



RESEARCH PAPER

WELL-POSEDNESS OF TIME-FRACTIONAL
ADVECTION-DIFFUSION-REACTION EQUATIONS

William McLean¹, Kassem Mustapha², Raed Ali³, Omar Knio⁴

Abstract

We establish the well-posedness of an initial-boundary value problem for a general class of linear time-fractional, advection-diffusion-reaction equations, allowing space- and time-dependent coefficients as well as initial data that may have low regularity. Our analysis relies on novel energy methods in combination with a fractional Gronwall inequality and properties of fractional integrals.

MSC 2010: Primary 26A33; Secondary 35A01, 35A02, 35B45, 35D30, 35K57, 35Q84, 35R11.

Key Words and Phrases: fractional PDE, weak solution, Volterra integral equation, fractional Gronwall inequality, Galerkin method

1. Introduction

The main scope of this paper is to investigate the existence and uniqueness of the weak solution of a linear, time-fractional problem of the form

$$\partial_t u - \nabla \cdot (\kappa \nabla \partial_t^{1-\alpha} u - \vec{F} \partial_t^{1-\alpha} u - \vec{G} u) + a \partial_t^{1-\alpha} u + bu = g \quad (1.1)$$

for $x \in \Omega$ and $0 < t \leq T$. The parameter α in the fractional derivative lies in the range $0 < \alpha < 1$, and the spatial domain $\Omega \subseteq \mathbb{R}^d$ ($d \geq 1$) is bounded and Lipschitz. The transport coefficients \vec{F} and \vec{G} , the reaction coefficients a and b , as well as the source term g , are assumed to be known functions of x and t , whereas the generalized diffusivity $\kappa = \kappa(x)$ may depend only on x but is permitted to be a real, symmetric positive-definite

matrix. In (1.1), $-\nabla \cdot (\kappa \nabla \partial_t^{1-\alpha} u)$ is the non-local diffusion term, whereas $\nabla \cdot (\vec{F} \partial_t^{1-\alpha} u + \vec{G} u)$ is the non-local/local advection term, and $a \partial_t^{1-\alpha} u + bu$ is the non-local/local reaction term.

We impose homogeneous Dirichlet boundary conditions,

$$u(x, t) = 0 \quad \text{for } x \in \partial\Omega \text{ and } 0 \leq t \leq T, \tag{1.2}$$

and the initial condition

$$u(x, 0) = u_0(x) \quad \text{for } x \in \Omega. \tag{1.3}$$

The Riemann–Liouville fractional *derivative* [33] of order $1 - \alpha$ is defined via the fractional *integral* of order α : with $\mathcal{I}^\alpha(t) = t^{\alpha-1}/\Gamma(\alpha)$ we have

$$\partial_t^{1-\alpha} v(x, t) = \partial_t \mathcal{I}^\alpha v(x, t) \quad \text{where} \quad \mathcal{I}^\alpha v(x, t) = \int_0^t \mathcal{I}^\alpha(t-s)v(x, s) ds.$$

We denote by $W_p^k(\Omega)$ the usual Sobolev space of functions whose partial derivatives of order k or less belong to $L_p(\Omega)$. The following regularity assumptions on the coefficients will be used:

$$\begin{aligned} \kappa \in L^\infty(\Omega)^{d \times d}, \quad \vec{F}, \vec{G} \in C^2([0, T]; W^1(\Omega)^d), \\ a, b \in C^1([0, T]; L^\infty(\Omega)). \end{aligned} \tag{1.4}$$

In addition, to ensure that the spatial operator $v \mapsto -\nabla \cdot (\kappa \nabla v)$ is uniformly elliptic on Ω , we assume that the minimal eigenvalue of $\kappa(x)$ is bounded away from zero, uniformly for $x \in \Omega$.

Based on physical models of various subdiffusive transport processes, different classes of time-fractional PDEs arise as special cases of (1.1), including

- fractional Fokker–Planck equations [4, 10, 16, 30], when $\vec{G} = \mathbf{0}$, $a = b = 0$ and $g = 0$;
- fractional reaction-diffusion equations [11, 12], when $\vec{F} = \vec{G} = \mathbf{0}$;
- fractional cable equations [19], when $\vec{F} = \vec{G} = \mathbf{0}$;
- fractional advection-dispersion (or fractional convection-diffusion) equations [25], when $\vec{F} = \vec{F}(x)$, $\vec{G} = \mathbf{0}$ and $a = b = 0$.

Consider the simplest non-trivial case, when κ is the identity matrix with $\vec{F} = \vec{G} = \mathbf{0}$, $a = b = 0$ and $g = 0$, so that (1.1) reduces to the fractional subdiffusion equation: $\partial_t u - \nabla^2 \partial_t^{1-\alpha} u = 0$. Let β denote a Dirichlet eigenfunction of the Laplacian on Ω , with corresponding eigenvalue $\lambda > 0$, that is, $-\nabla^2 \beta = \lambda \beta$ in Ω with $\beta|_{\partial\Omega} = 0$. For the special choice of initial data $u_0 = \beta(x)$, the solution of the initial-boundary value problem (1.1)–(1.3) has the separable form $u(x, t) = E_\alpha(-\lambda t^\alpha)\beta(x)$, where $E_\alpha(z) = \sum_{n=0}^\infty z^n / \Gamma(1+n\alpha)$ is the Mittag–Leffler function [33]. Notice that $\partial_t^m u = O(t^{\alpha-m})$ as $t \rightarrow 0$. Moreover, we can extend the classical method of separation of variables for the heat equation to construct a series solution

for arbitrary initial data $u_0 \in L_2(\Omega)$, and the regularity properties of the solution u follow from this representation [28].

Such an explicit construction is no longer possible for the solution of the general equation (1.1). Instead, we proceed by formally integrating (1.1) in time, multiplying both sides by a test function v , and applying the first Green identity over Ω to arrive at the weak formulation

$$\begin{aligned}
 u(t), v + \int_0^t \kappa \nabla \partial_s^{1-\alpha} u(s) - \vec{F}(s) \partial_s^{1-\alpha} u(s) - \vec{G}(s) u(s), \nabla v \, ds \\
 + \int_0^t a(s) \partial_s^{1-\alpha} u(s) + b(s) u(s), v \, ds = u_0, v + \int_0^t g(s), v \, ds \quad (1.5)
 \end{aligned}$$

for all $v \in H_0^1(\Omega)$, where we have suppressed the dependence of the functions on x , and where \cdot, \cdot denotes the inner product in $L_2(\Omega)$ or $L_2(\Omega)^d$.

Numerical methods for particular cases of (1.1) were extensively studied over the last two decades, see for example [1, 18, 23, 36, 38] for finite differences, [14, 20, 31] for continuous and discontinuous finite elements, and also see [8, 13] for more references. However, due to various types of mathematical difficulties, proof of the well-posedness of the continuous problem is almost missing despite its importance, apart from the case [28] when $\vec{F} = \vec{G} = \mathbf{0}$ and $a = b = 0$. In this paper, we address these fundamental questions. A related paper [21] treats the fractional Fokker–Planck equation (that is, the case $\vec{G} = \mathbf{0}$ and $a = b = 0$) via a different, and somewhat simpler, chain of estimates that, for instance, does not use the quadratic operator \mathcal{Q}_1^μ defined below in Section 2.

If the coefficients \vec{F} and a are independent of t , and if $\vec{G} = \mathbf{0}$ and $b = 0$, then by applying the fractional integration operator $\mathcal{I}^{1-\alpha}$ to both sides of (1.1) we obtain

$${}^C \partial_t^\alpha u - \nabla \cdot (\kappa \nabla u - \vec{F} u) + au = g, \quad (1.6)$$

where ${}^C \partial_t^\alpha u = \mathcal{I}^{1-\alpha} \partial_t u$ denotes the Caputo fractional derivative [33] and where $g = \mathcal{I}^{1-\alpha} g$. Existence and uniqueness results for (1.6) were studied by several authors, including Zacher [39], Alikhanov [2], Sakamoto and Yamamoto [34] and Kubica and Yamamoto [17]. Further, the reader can refer to [15, 22, 27, 35]. Some of these papers include results for time-dependent coefficients, but in that case (1.6) is no longer equivalent to (1.1).

To recast the weak formulation (1.5) as a Volterra integral equation, we introduce two bounded linear operators, firstly $K_1(t) : H_0^1(\Omega) \rightarrow H^{-1}(\Omega)$ defined by

$$\begin{aligned}
 K_1(t)v, w = \kappa \nabla v, \nabla w - \vec{F}(t)v, \nabla w + a(t)v, w \quad \text{for } v, w \in H_0^1(\Omega), \\
 \text{and secondly } K_2(t) : L_2(\Omega) \rightarrow H^{-1}(\Omega) \text{ by}
 \end{aligned}$$

$$K_2(t)v, w = b(t)v, w - \vec{G}(t)v, \nabla w \quad \text{for } v \in L_2(\Omega) \text{ and } w \in H_0^1(\Omega).$$

The variational problem (1.5), subject to the initial condition (1.3), can then be written more succinctly as

$$u(t) + \int_0^t K_1(s) \partial_s^{1-\alpha} u(s) + K_2(s)u(s) \, ds = f(t) \quad u_0 + \int_0^t g(s) \, ds. \quad (1.7)$$

Assuming u is sufficiently regular that $(\mathcal{I}^\alpha u)(0) = 0$, and using a dash to indicate a derivative in time, integration by parts leads to

$$\begin{aligned} \int_0^t K_1(s) \partial_s^{1-\alpha} u(s) \, ds &= K_1(t) \mathcal{I}^\alpha u(t) - \int_0^t K_1(s) \mathcal{I}^\alpha u(s) \, ds \\ &= \int_0^t \alpha(t-s) K_1(t) - \int_s^t \alpha(z-s) K_1(z) \, dz \quad u(s) \, ds, \end{aligned}$$

with $K_1(t) : H_0^1(\Omega) \rightarrow H^{-1}(\Omega)$ given by $K_1(t)v, w = - \vec{F}(t)v, \nabla w + a(t)v, w$.

Thus, u satisfies

$$u(t) + \int_0^t K(t, s)u(s) \, ds = f(t) \quad \text{for } 0 \leq t \leq T, \quad (1.8)$$

where $K(t, s) : H_0^1(\Omega) \rightarrow H^{-1}(\Omega)$ is the weakly-singular, operator-valued kernel

$$K(t, s) = \alpha(t-s)K_1(t) + K_2(s) - \int_s^t \alpha(z-s)K_1(z) \, dz. \quad (1.9)$$

Following some technical preliminaries in Section 2, we apply the Galerkin method in Section 3 to project the problem (1.8) to a finite dimensional subspace $X \subseteq H_0^1(\Omega)$, thereby obtaining an approximate solution $u_X : [0, T] \rightarrow X$. Using delicate energy arguments and a fractional Gronwall inequality, we prove *a priori* estimates for u_X that are uniform with respect to the dimension of X , allowing us in Section 4 (Theorems 4.1 and 4.2) to establish the existence and uniqueness of a weak solution u to the original problem (1.1)–(1.3), provided (1.4) holds.

The regularity of the weak solution u will be studied in a companion paper [29].

2. Preliminaries and notations

Our subsequent analysis makes frequent use of two quadratic operators defined, for $\mu \geq 0$ and $0 \leq t \leq T$, by

$$\mathcal{Q}_1^\mu(\cdot, t) = \int_0^t \cdot, \mathcal{I}^\mu \cdot \, ds \quad \text{and} \quad \mathcal{Q}_2^\mu(\cdot, t) = \int_0^t \mathcal{I}^{\mu-2} \cdot \, ds.$$

These operators coincide when $\mu = 0$ because $\mathcal{I}^0 = \mathcal{I}$, and so we write $\mathcal{Q}^0 = \mathcal{Q}_1^0 = \mathcal{Q}_2^0$. If we put $\varphi(t) = 0$ for $t > T$, then the Laplace transform $\varphi(z) = \int_0^T e^{-zt} \varphi(t) dt$ is an entire function and $\mathcal{I}^\mu \varphi(z) = z^{-\mu} \varphi(z)$, so it follows by the Plancherel Theorem that

$$\mathcal{Q}_1^\mu(\varphi, T) = \frac{\cos(\mu/2)}{0} \int_0^\infty y^{-\mu} |\varphi(iy)|^2 dy \geq 0, \tag{2.1}$$

assuming that φ is real-valued; see also [32, Theorem 2]. Note that because $\mu \in L_1(0, T)$, the fractional integral defines a bounded linear operator

$$\mathcal{I}^\mu : L_p((0, T); L_2(\Omega)) \rightarrow L_p((0, T); L_2(\Omega)) \text{ for } 1 \leq p \leq \infty. \tag{2.2}$$

Also, $\mathcal{I}^{\mu+\beta} = \mathcal{I}^\mu \mathcal{I}^\beta$ because $\int_0^t \int_0^s \varphi = \int_0^t \varphi_{\mu+\beta}$ for $\mu > 0$ and $\beta > 0$; here, $\varphi_{\mu+\beta}$ denotes the Laplace convolution.

The next four lemmas establish key inequalities satisfied by \mathcal{Q}_1^μ and \mathcal{Q}_2^μ .

LEMMA 2.1. *If $0 < \alpha < 1$ and $\varphi > 0$, then*

$$\int_0^t \varphi, \mathcal{I}^\alpha \varphi ds \leq \frac{\mathcal{Q}_1^\alpha(\varphi, t)}{4(1-\alpha)^2} + \mathcal{Q}_1^\alpha(\varphi, t), \tag{2.3}$$

$$\mathcal{Q}_2^\alpha(\varphi, t) \leq \frac{2t^\alpha}{1-\alpha} \mathcal{Q}_1^\alpha(\varphi, t), \tag{2.4}$$

$$\mathcal{Q}_1^\alpha(\varphi, t) \leq 2t^\alpha \mathcal{Q}^0(\varphi, t), \tag{2.5}$$

$$\int_0^t \varphi, \mathcal{I}^\alpha \varphi ds \leq \frac{t^\alpha \mathcal{Q}^0(\varphi, t)}{2(1-\alpha)^2} + \mathcal{Q}_1^\alpha(\varphi, t). \tag{2.6}$$

P r o o f. The first three inequalities are proved by Le, McLean and Mustapha [20, Lemma 3.2]. The fourth inequality follows from (2.3) and (2.5). □

For the next result, note that if $\varphi \in W_1^1((0, T); X)$ for a normed space X , then $\varphi : [0, T] \rightarrow X$ is absolutely continuous and

$$(\partial_t \mathcal{I}^\alpha \varphi - \mathcal{I}^\alpha \partial_t \varphi)(t) = \varphi(0)_{1-\alpha}(t) \text{ for } 0 < t \leq T. \tag{2.7}$$

LEMMA 2.2. *If $0 < \alpha \leq 1$, then for $\varphi \in L_2((0, t), L_2(\Omega))$,*

$$\mathcal{Q}_2^\alpha(\varphi, t) \leq 2 \int_0^t \varphi_{1-\alpha}(t-s) \mathcal{Q}_1^\alpha(\varphi, s) ds.$$

P r o o f. Assume first that $\varphi \in W_1^1((0, T), L_2(\Omega))$ and let $\varphi = \mathcal{I}^\alpha \psi$. Since $\varphi(0) = 0$, the Caputo fractional derivative of φ is

$${}^C \partial_t^\alpha \varphi = \mathcal{I}^{1-\alpha}(\psi) = (\mathcal{I}^{1-\alpha} \psi) - \varphi(0)_{1-\alpha} = (\mathcal{I}^1 \psi) = \psi.$$

Recalling an identity of Alikhanov [3, Corollary1],

$$2 \quad (t), {}^C\partial_t^\alpha (t) = {}^C\partial_t^\alpha (\quad^2)(t) + \frac{\alpha}{2(1-\alpha)} \int_0^t \frac{1}{(t-s)^{1-\alpha}} \int_0^s \frac{(q) dq}{(t-q)^\alpha} \quad^2 ds,$$

we see that

$$2 \quad , \mathcal{I}^\alpha \quad = 2 \quad {}^C\partial_t^\alpha \quad , \quad \geq {}^C\partial_t^\alpha (\quad^2) = \mathcal{I}^{1-\alpha} (\mathcal{I}^\alpha \quad^2), \quad (2.8)$$

and thus

$$\begin{aligned} \mathcal{I}^1 (\mathcal{I}^\alpha \quad^2) &= \mathcal{I}^2 (\mathcal{I}^\alpha \quad^2) = \mathcal{I}^{1+\alpha} \mathcal{I}^{1-\alpha} (\mathcal{I}^\alpha \quad^2) \\ &\leq 2\mathcal{I}^{1+\alpha} (\quad, \mathcal{I}^\alpha \quad) = 2\mathcal{I}^\alpha \mathcal{I}^1 (\quad, \mathcal{I}^\alpha \quad), \end{aligned}$$

which is equivalent to the desired inequality.

Now let $\eta \in L_2((0, T), L_2(\Omega))$, and choose $\eta_n \in W_1^1((0, T), L_2(\Omega))$ such that $\int_0^T \eta_n(t) - \eta(t) \quad^2 dt \rightarrow 0$ as $n \rightarrow \infty$. Using (2.2) with $\mu = \alpha$ and $p = 2$, it follows that $\mathcal{Q}_1^\alpha(\eta_n, t) \rightarrow \mathcal{Q}_1^\alpha(\eta, t)$ and $\mathcal{Q}_2^\alpha(\eta_n, t) \rightarrow \mathcal{Q}_2^\alpha(\eta, t)$, uniformly for $t \in [0, T]$, which implies the result in the general case. \square

The next lemma will eventually enable us to establish pointwise (in time) estimates for $u(t)$.

LEMMA 2.3. *Let $0 \leq \mu < \alpha \leq 1$. If the function $\eta : [0, T] \rightarrow L_2(\Omega)$ is continuous with $\eta(0) = 0$, and if its restriction to $(0, T]$ is differentiable with $|\eta'(t)| \leq Ct^{-\mu}$ for $0 < t \leq T$, then $|\eta(t)| \quad^2 \leq 2 \int_0^t (t-s)^{\alpha-\mu} \mathcal{Q}_1^\alpha(\eta, s) ds$.*

P r o o f. For $\alpha = 1$, equality holds:

$$2 \quad \eta_1(t) \mathcal{Q}_1^1(\eta, t) = 2 \int_0^t \eta'(s) ds = \eta(t) \quad^2.$$

For $0 < \alpha < 1$, put $\eta(t) = \mathcal{I}^\alpha \eta_1(t)$ and note that $|\eta_1'(t)| \leq Ct^{\alpha-\mu}$. By following similar arguments, one can show that (2.8) holds with η_1 in place of η , that is $2 \quad \eta_1, \mathcal{I}^\alpha \quad = \mathcal{I}^{1-\alpha} (\mathcal{I}^\alpha \quad^2)$, for almost all $t > 0$. Now, applying the operator \mathcal{I}^1 to both sides, and using $\mathcal{I}^\alpha \eta_1(0) = \eta(0) = 0$, we observe that

$$\mathcal{I}^{1-\alpha} (\mathcal{I}^\alpha \quad^2)(t) = 2\mathcal{Q}_1^\alpha(\eta, t) \quad \text{for } t > 0. \quad (2.9)$$

Since $\eta = \mathcal{I}^1 \eta_1 = \mathcal{I}^{1-\alpha} \eta_1$,

$$\begin{aligned}
 (t)^2 &\leq \int_0^t (t-s)^{1-\alpha} (s)^2 ds \\
 &\leq \int_0^t (t-s)^{1-\alpha} ds \int_0^t (t-s)^{1-\alpha} (s)^2 ds \\
 &= {}_2^{-\alpha}(t) \mathcal{I}^{1-\alpha} \mathcal{I}^\alpha (t)^2,
 \end{aligned}$$

and hence the desired result follows immediately after using (2.9). □

LEMMA 2.4. *If $0 \leq \mu \leq \beta \leq 1$, then $Q_2^\beta(\cdot, t) \leq 2t^{2(\beta-\mu)} Q_2^\mu(\cdot, t)$.*

P r o o f. See Le, McLean and Mustapha [20, Lemma 3.1]. □

We will make essential use of the following fractional Gronwall inequality.

LEMMA 2.5. *Let $\alpha > 0$ and $T > 0$. Assume that \mathbf{a} and \mathbf{b} are non-negative, non-decreasing functions on the interval $[0, T]$. If $\mathbf{q} : [0, T] \rightarrow \mathbb{R}$ is an integrable function satisfying*

$$0 \leq \mathbf{q}(t) \leq \mathbf{a}(t) + \mathbf{b}(t) \int_0^t (t-s)\mathbf{q}(s) ds \quad \text{for } 0 \leq t \leq T,$$

then

$$\mathbf{q}(t) \leq \mathbf{a}(t)E(\mathbf{b}(t)t^\alpha) \quad \text{for } 0 \leq t \leq T.$$

P r o o f. See Dixon and McKee [9, Theorem 3.1]. □

Let \mathcal{M} denote the operator of pointwise multiplication by t , that is, $(\mathcal{M} \mathbf{u})(t) = t \mathbf{u}(t)$, and note the commutator property

$$\mathcal{M}\mathcal{I}^\mu - \mathcal{I}^\mu\mathcal{M} = \mu\mathcal{I}^{\mu+1}, \tag{2.10}$$

for any real $\mu \geq 0$. We will need the following estimates involving the linear operator B^μ defined (for suitable \mathbf{u} and \mathbf{v}) by

$$(B^\mu \mathbf{u})(t) = (\mathcal{M} \mathbf{u})(t) \mathcal{I}^\mu \mathbf{v}(t) - \int_0^t (s) \mathcal{I}^\mu (\mathbf{u})(s) ds. \tag{2.11}$$

LEMMA 2.6. *If $\mathbf{u} \in W^1((0, T); L^\infty(\Omega)^d)$ and $\mathbf{v} \in W_1^1((0, T); L_2(\Omega))$, then there is a constant C (depending only on α, μ and T) such that for $0 \leq t \leq T$,*

$$\mathcal{Q}^0(B^\mu, t) \leq C \mathcal{Q}_2^\mu(\cdot, t), \tag{2.12}$$

$$\mathcal{Q}^0(\mathcal{M}B^\mu, t) + \mathcal{Q}^0(\mathcal{I}^1 B^\mu, t) \leq Ct^2 \mathcal{Q}_2^\mu(\cdot, t), \tag{2.13}$$

$$\mathcal{Q}^0((\mathcal{M}B^\mu), t) \leq C \mathcal{Q}_2^\mu((\mathcal{M}), t) + C \mathcal{Q}_2^\mu(\mathcal{M}, t) + C \mathcal{Q}_2^\mu(\cdot, t). \tag{2.14}$$

P r o o f. The assumption on \mathcal{M} implies that

$$(B^\mu)(t)^2 \leq C (\mathcal{I}^\mu)(t)^2 + C \int_0^t (\mathcal{I}^\mu)(s)^2 ds,$$

and (2.12) follows after integrating in time. By the Cauchy–Schwarz inequality,

$$(\mathcal{M}B^\mu)(t)^2 + (\mathcal{I}^1 B^\mu)(t)^2 \leq t^2 (B^\mu)(t)^2 + t \int_0^t (B^\mu)(s)^2 ds,$$

and (2.13) follows after integrating in time. The third identity in (2.10) implies that

$$\mathcal{M}B^\mu = (\mathcal{I}^\mu \mathcal{M} + \mu \mathcal{I}^{\mu+1}) - \mathcal{M} \mathcal{I}^1(\mathcal{I}^\mu)$$

and therefore, differentiating with respect to t ,

$$(\mathcal{M}B^\mu)' = (\mathcal{I}^\mu \mathcal{M}' + \mu \mathcal{I}^{\mu+1}) + ((\mathcal{I}^\mu \mathcal{M})' + \mu \mathcal{I}^\mu)' - (\mathcal{I}^1 + \mathcal{M})(\mathcal{I}^\mu)'.$$

Thus, noting that $(\mathcal{I}^\mu \mathcal{M})' = \mathcal{I}^\mu(\mathcal{M})'$ by (2.7), with

$$\mathcal{I}^{\mu+1}(t)^2 = \mathcal{I}^1(\mathcal{I}^\mu)(t)^2 \leq t \mathcal{Q}_2^\mu(\cdot, t)$$

and $\mathcal{I}^1(\mathcal{I}^\mu)(t)^2 \leq Ct \mathcal{Q}_2^\mu(\cdot, t)$, we have

$$\begin{aligned} (\mathcal{M}B^\mu)'(t)^2 &\leq C (\mathcal{I}^\mu(\mathcal{M})'(t))^2 + C (\mathcal{I}^\mu(\mathcal{M})'(t))^2 \\ &\quad + C (\mathcal{I}^\mu)'(t)^2 + Ct \mathcal{Q}_2^\mu(\cdot, t), \end{aligned}$$

so (2.14) follows after integrating in time. □

3. The projected equation

Suppose that X is a finite-dimensional subspace of $H_0^1(\Omega)$, equipped with the induced norm: $\|v\|_X = \|v\|_{H_0^1(\cdot)}$. We define a bounded linear operator $K_X(t, s) : X \rightarrow X$ in terms of $K(t, s)$ in (1.9) by

$$K_X(t, s)v, w = K(t, s)v, w \quad \text{for } v, w \in X \text{ and } 0 \leq s \leq t \leq T,$$

and let $f_X(t)$ denote the L_2 -projection onto X of $f(t)$ from (1.7), that is,

$$f_X(t), w = f(t), w \quad \text{for } w \in X \text{ and } 0 \leq t \leq T.$$

In this way, we arrive at a finite dimensional reduction of the Volterra equation (1.8),

$$u_X(t) + \int_0^t K_X(t,s)u_X(s) ds = f_X(t) \quad \text{for } 0 \leq t \leq T. \quad (3.1)$$

In the next theorem, we outline a self-contained proof of existence and uniqueness under relaxed assumptions on the coefficients in the fractional PDE (1.1). Similar results for scalar-valued kernels are shown by Linz [24, §3.4], Becker [5], and Brunner [6].

Henceforth, C will denote a generic constant that may depend on the coefficients in (1.1), the spatial domain Ω , the time interval $[0, T]$, the fractional exponent α , the parameter ν , and the integer m in (1.4). However, any dependence on the subspace X is indicated explicitly by writing C_X . We let $Y = C([0, T]; X)$ with the norm $\|v\|_Y = \max_{0 \leq t \leq T} \|v(t)\|_X$.

THEOREM 3.1. *Assume that the coefficients in (1.1) satisfy*

$$\begin{aligned} \kappa \in L^\infty(\Omega)^{d \times d}, \quad \vec{F} \in W^1((0, T); L^\infty(\Omega)^d), \quad \vec{G} \in L^\infty((0, T); L^\infty(\Omega)^d), \\ a \in W^1((0, T); L^\infty(\Omega)), \quad b \in L^\infty((0, T); L^\infty(\Omega)). \end{aligned}$$

Assume, in addition, that the source term $g : (0, T] \rightarrow L_2(\Omega)$ is a measurable function satisfying

$$|g(t)| \leq Mt^{-1} \quad \text{for } 0 < t \leq T, \quad (3.2)$$

where M and ν are positive constants, and that the initial data $u_0 \in L_2(\Omega)$. Then, the weakly-singular Volterra integral equation (3.1) has a unique solution $u_X \in Y$, and moreover $\|u_X\|_Y \leq C_X \|f_X\|_Y \leq C_X (\|u_0\| + M)$.

P r o o f. Our assumptions on u_0 and g ensure that $f_X \in Y$. The kernel (1.9) has the form

$$K(t, s) = \nu^\alpha(t - s)G(t, s) + H(t, s),$$

where

$$G(t, s) = K_1(t) - \nu^\alpha(t - s) \int_0^1 \nu^\alpha(y)K_1(s + (t - s)y) dy$$

and $H(t, s) = K_2(s)$ for $0 \leq s \leq t \leq T$. Our assumptions on the coefficients of the fractional PDE (1.1) ensure that G and H are continuous mappings from the closed triangle $\Delta = \{(t, s) : 0 \leq s \leq t \leq T\}$ into the space of bounded linear operators $H_0^1(\Omega) \rightarrow H^{-1}(\Omega)$. Likewise,

$$K_X(t, s) = \nu^\alpha(t - s)G_X(t, s) + H_X(t, s),$$

where $G_X(t, s) : X \rightarrow X$ and $H_X(t, s) : X \rightarrow X$ are defined by

$$G_X(t, s)v, w = G(t, s)v, w \quad \text{and} \quad H_X(t, s)v, w = H(t, s)v, w$$

for $(t, s) \in J \times J$ and $v, w \in X$. Since X is finite dimensional, G_X and H_X are continuous functions from $J \times J$ into the space of bounded linear operators $X \rightarrow X$. Hence, there is a positive constant K_X such that

$$K_X(t, s)v \leq K_X^{-\alpha}(t-s) \|v\|_X \quad \text{for } (t, s) \in J \times J \text{ and } v \in X,$$

so we can define the Volterra operator $\mathcal{K}_X : Y \rightarrow Y$ by

$$\mathcal{K}_X v(t) = \int_0^t K_X(t, s)v(s) ds \quad \text{for } 0 \leq t \leq T \text{ and } v \in Y.$$

We see that $\|\mathcal{K}_X v\|_Y \leq K_X^{-1+\alpha}(T) \|v\|_Y$. In fact, using the semigroup property,

$$\int_0^t K_X^\alpha(t-s) K_X(s) ds = K_X^{\alpha+1}(t),$$

we obtain the following estimate for the operator norm of the n th power of \mathcal{K}_X ,

$$\|\mathcal{K}_X^n\|_{Y \rightarrow Y} \leq K_X^n \max_{0 \leq t \leq T} \int_0^t n\alpha(t-s) ds = K_X^n^{-1+n\alpha}(T) \quad \text{for } n \geq 1.$$

It follows that the sum $\mathcal{R}_X = \sum_{n=1}^{\infty} (-1)^{n+1} \mathcal{K}_X^n$ defines a bounded linear operator with

$$\|\mathcal{R}_X\|_{Y \rightarrow Y} \leq K_X^{-1+n\alpha}(T) = E_\alpha(K_X T^\alpha) - 1.$$

The existence and uniqueness of $u_X \in Y$ is seen by noting

$$u_X + \mathcal{K}_X u_X = f_X \quad \text{if and only if} \quad u_X = f_X - \mathcal{R}_X f_X,$$

from which we also deduce the *a priori* estimate claimed in the theorem. □

For a scalar, weakly-singular, second-kind Volterra equation, it is known that if f_X admits an expansion in powers of t and t^α , then so does the solution u_X ; see Lubich [26, Corollary 3], and also Brunner, Pedaş and Vainikko [7, Theorem 2.1] (with $\alpha = 1 - \alpha$). To outline a proof that a similar result holds for *systems* of Volterra equations, let $C_\alpha^m = C_\alpha^m([0, T]; X)$ denote the space of continuous functions $v : [0, T] \rightarrow X$ that are C^m on the half-open interval $(0, T]$ and for which the seminorm

$$|v|_{j,\alpha} = \sup_{0 < t \leq T} t^{j-\alpha} \|v^{(j)}(t)\|_X \quad \text{is finite for } 1 \leq j \leq m.$$

We make C_α^m into a Banach space by defining the obvious norm:

$$\|v\|_{m,\alpha} = \|v\|_Y + \sum_{j=1}^m |v|_{j,\alpha}.$$

THEOREM 3.2. *Let $m \geq 1$, and strengthen the assumptions (1.4) by requiring*

$$\vec{F}, \vec{G} \in C^{m+1}([0, T]; W^1(\Omega)^d) \quad \text{and} \quad a, b \in C^m([0, T]; L^2(\Omega)).$$

If $u_0 \in L_2(\Omega)$ and $g : (0, T] \rightarrow X$ is C^m with $g^{(i-1)}(t) \leq Mt^{\alpha-i}$ for $1 \leq i \leq m$, then $u_X \in C_\alpha^m$ and $\|u_X\|_{m,\alpha} \leq C_X \|f_X\|_{m,\alpha} \leq C_X (\|u_0\| + M)$.

P r o o f. Our assumptions on u_0 and g imply that $f_X \in C_\alpha^m$. Using the substitution $z = s + (t - s)y$ in (1.9), we find that if $j + k \leq m$ and $0 \leq s < t \leq T$, then

$$\partial_t^k (\partial_t + \partial_s)^j K(t, s)v \in H^{-1}(\Omega) \leq C_X (t - s)^{\alpha-1-k} \|v\|_{H_0^1(\Omega)} \quad \text{for } v \in H_0^1(\Omega),$$

and, since X is finite dimensional,

$$\partial_t^k (\partial_t + \partial_s)^j K_X(t, s)v \in X \leq C_X (t - s)^{\alpha-1-k} \|v\|_X \quad \text{for } v \in X.$$

Hence, the Volterra operator $\mathcal{K}_X : C_\alpha^m \rightarrow C_\alpha^m$ is compact [37, Theorem 6.1]. Theorem 3.1 implies that the homogeneous equation, $u_X + \mathcal{K}_X u_X = 0$, has only the trivial solution $u_X = 0$, and therefore the inhomogeneous equation $u_X + \mathcal{K}_X u_X = f_X$ is well-posed not only in Y but also in C_α^m . \square

Our goal in the remainder of this section is to obtain bounds for $\|u_X(t)\|$ and $\|\nabla u_X(t)\|$ with constants that are independent of X . Our proof relies on a sequence of technical lemmas. To simplify our estimates, we rescale the time variable, if necessary, so that the minimal eigenvalue of κ is bounded below by unity:

$$\min(\kappa(x)) \geq 1 \quad \text{for } x \in \Omega. \tag{3.3}$$

In this way, $\kappa \nabla v, \nabla v \geq \|\nabla v\|^2$ for $v \in H_0^1(\Omega)$, and we see from (2.1) that for (real-valued) $\psi \in C([0, T]; H_0^1(\Omega))$,

$$\begin{aligned} \int_0^t \kappa \mathcal{I}^\mu \nabla \psi, \nabla \psi \, ds &= \int_0^t \frac{\cos(\mu/2)}{y^{-\mu}} \kappa \nabla \psi(iy), \overline{\nabla \psi(iy)} \, dy \\ &\geq \int_0^t \frac{\cos(\mu/2)}{y^{-\mu}} \|\nabla \psi(iy)\|^2 \, dy, \end{aligned}$$

so

$$\int_0^t \kappa \mathcal{I}^\mu \nabla \psi, \nabla \psi \, ds \geq \int_0^t \mathcal{I}^\mu \nabla \psi, \nabla \psi \, ds = \mathcal{Q}_1^\mu(\nabla \psi, t). \tag{3.4}$$

Since (1.7) is equivalent to (1.8), if $v \in X$ then

$$\begin{aligned} & \int_0^t K_X(t,s)u_X(s) ds, v \\ &= \int_0^t K_1(s)\partial_s^{1-\alpha}u_X, v ds + \int_0^t K_2(s)u_X(s), v ds \\ &= \kappa(\mathcal{I}^\alpha \nabla u_X)(t), \nabla v - (B_1 u_X)(t), \nabla v + (B_2 u_X)(t), v, \end{aligned}$$

where

$$\begin{aligned} \vec{B}_1(t) &= \int_0^t \vec{F}(s)\partial_s^{1-\alpha}(s) + \vec{G}(s)(s) ds, \\ B_2(t) &= \int_0^t a(s)\partial_s^{1-\alpha}(s) + b(s)(s) ds. \end{aligned} \tag{3.5}$$

Assuming $\in C^1_\alpha([0, T]; X)$, we may integrate by parts and use the notation (2.11) to write

$$\vec{B}_1 = B_F^\alpha + B_G^1 \quad \text{and} \quad B_2 = B_a^\alpha + B_b^1. \tag{3.6}$$

Thus, the solution of (3.1) satisfies

$$\begin{aligned} u_X(t), v + \kappa \nabla \mathcal{I}^\alpha u_X(t), \nabla v - (\vec{B}_1 u_X)(t), \nabla v + (B_2 u_X)(t), v \\ = f_X(t), v \quad \text{for } v \in X, \end{aligned} \tag{3.7}$$

which yields the following estimates (with C independent of X).

LEMMA 3.1. *For $0 \leq t \leq T$, the solution u_X of the Volterra equation (3.1) satisfies the a priori estimates*

$$\mathcal{Q}_1^\alpha(u_X, t) + \mathcal{Q}_2^\alpha(\nabla u_X, t) \leq Ct^\alpha \mathcal{Q}^0(f_X, t)$$

and

$$\mathcal{Q}^0(u_X, t) + \mathcal{Q}_1^\alpha(\nabla u_X, t) \leq C \mathcal{Q}^0(f_X, t).$$

P r o o f. From (3.7),

$$\begin{aligned} u_X(t), v + \kappa \nabla \mathcal{I}^\alpha u_X(t), \nabla v \leq \frac{1}{2} \|\nabla v\|^2 + \frac{1}{2} \|\vec{B}_1 u_X(t)\|^2 + \frac{1}{2} \|B_2 u_X(t)\|^2 \\ + \frac{1}{2} \|v\|^2 + f_X(t), v. \end{aligned}$$

Choosing $v = \mathcal{I}^\alpha u_X(t)$ we have $\kappa \nabla \mathcal{I}^\alpha u_X(t), \nabla v = \kappa \nabla v, \nabla v \geq \|\nabla v\|^2$ because of (3.3). Thus, after canceling the term $\frac{1}{2} \|\nabla v\|^2$ and integrating in time, we see that

$$\begin{aligned} \mathcal{Q}_1^\alpha(u_X, t) + \frac{1}{2} \mathcal{Q}_2^\alpha(\nabla u_X, t) \leq \frac{1}{2} \mathcal{Q}^0(\vec{B}_1 u_X, t) + \frac{1}{2} \mathcal{Q}^0(B_2 u_X, t) + \frac{1}{2} \mathcal{Q}_2^\alpha(u_X, t) \\ + \int_0^t f_X(s), \mathcal{I}^\alpha u_X(s) ds. \end{aligned} \tag{3.8}$$

Using the representation (3.6) and the achieved estimate (2.12),

$$\begin{aligned} \mathcal{Q}^0(\vec{B}_1 u_X, t) &\leq 2\mathcal{Q}^0(B_F^\alpha u_X, t) + 2\mathcal{Q}^0(B_G^1 u_X, t) \\ &\leq C\mathcal{Q}_2^\alpha(u_X, t) + C\mathcal{Q}_2^1(u_X, t) \leq C\mathcal{Q}_2^\alpha(u_X, t), \end{aligned}$$

where, in the final step, we used Lemma 2.4. In the same way,

$$\mathcal{Q}^0(B_2 u_X, t) \leq C\mathcal{Q}_2^\alpha(u_X, t).$$

Using (2.6) with $\phi = f_X$, $\psi = u_X$ and $\theta = 1/2$, we deduce that

$$\mathcal{Q}_1^\alpha(u_X, t) + \frac{1}{2}\mathcal{Q}_2^\alpha(\nabla u_X, t) \leq C\mathcal{Q}_2^\alpha(u_X, t) + Ct^\alpha \mathcal{Q}^0(f_X, t) + \frac{1}{2}\mathcal{Q}_1^\alpha(u_X, t).$$

Hence, applying Lemma 2.2 with $\psi = u_X$, we can show that the function $q(t) = \mathcal{Q}_1^\alpha(u_X, t) + \mathcal{Q}_2^\alpha(\nabla u_X, t)$ satisfies

$$q(t) \leq Ct^\alpha \mathcal{Q}^0(f_X, t) + C \int_0^t \alpha(t-s) \mathcal{Q}_1^\alpha(u_X, s) ds.$$

Since $\mathcal{Q}_1^\alpha(u_X, s) \leq q(s)$, Lemma 2.5 implies the first estimate.

To show the second estimate, use $v = (\vec{B}_1 u_X)(t), \nabla v = \nabla \cdot \vec{B}_1 u_X(t), v$ in (3.7) to obtain

$$\begin{aligned} u_X(t), v + \kappa \nabla \mathcal{I}^\alpha u_X(t), \nabla v &\leq \frac{1}{2} \|v\|^2 + \frac{3}{2} \|\nabla \cdot (\vec{B}_1 u_X)(t)\|^2 \\ &\quad + \frac{3}{2} \|(B_2 u_X)(t)\|^2 + \frac{3}{2} \|f_X(t)\|^2. \end{aligned}$$

Choosing $v = u_X(t)$, integrating in time, and using (3.4), we have

$$\frac{1}{2}\mathcal{Q}^0(u_X, t) + \mathcal{Q}_1^\alpha(\nabla u_X, t) \leq C\mathcal{Q}^0(\nabla \cdot \vec{B}_1 u_X, t) + C\mathcal{Q}^0(B_2 u_X, t) + C\mathcal{Q}^0(f_X, t).$$

Since

$$\begin{aligned} \nabla \cdot (B_F^\alpha u_X)(t) &= (\nabla \cdot \vec{F}(t))\mathcal{I}^\alpha u_X(t) + \vec{F}(t) \cdot \mathcal{I}^\alpha \nabla u_X(t) \\ &\quad - \int_0^t (\nabla \cdot \vec{F}(s))\mathcal{I}^\alpha u_X(s) + \vec{F}(s) \cdot \mathcal{I}^\alpha \nabla u_X(s) ds \quad (3.9) \end{aligned}$$

it follows that

$$\begin{aligned} \nabla \cdot (B_F^\alpha u_X)(t) &\leq C \|\mathcal{I}^\alpha u_X(t)\|^2 + C \|\mathcal{I}^\alpha \nabla u_X(t)\|^2 \\ &\quad + C \int_0^t \|\mathcal{I}^\alpha u_X(s)\|^2 + \|\mathcal{I}^\alpha \nabla u_X(s)\|^2 ds, \end{aligned}$$

implying that $\mathcal{Q}^0(\nabla \cdot B_F^\alpha u_X, t) \leq C\mathcal{Q}_2^\alpha(u_X, t) + C\mathcal{Q}_2^\alpha(\nabla u_X, t)$. In the same way, $\mathcal{Q}^0(\nabla \cdot B_G^1 u_X, t) \leq C\mathcal{Q}_2^1(u_X, t) + C\mathcal{Q}_2^1(\nabla u_X, t)$ and therefore, by Lemma 2.4,

$$\mathcal{Q}^0(\nabla \cdot \vec{B}_1 u_X, t) \leq C\mathcal{Q}_2^\alpha(u_X, t) + C\mathcal{Q}_2^\alpha(\nabla u_X, t).$$

Recall $\mathcal{Q}^0(B_2u_X, t) \leq C\mathcal{Q}_2^\alpha(u_X, t)$ and let $\mathfrak{q}(t) = \mathcal{Q}^0(u_X, t) + \mathcal{Q}_1^\alpha(\nabla u_X, t)$. It follows using Lemma 2.2 and (2.5) that

$$\begin{aligned} \mathfrak{q}(t) &\leq C\mathcal{Q}_2^\alpha(u_X, t) + C\mathcal{Q}_2^\alpha(\nabla u_X, t) + C\mathcal{Q}^0(f_X, t) \\ &\leq C\mathcal{Q}^0(f_X, t) + C \int_0^t \alpha(t-s) \mathcal{Q}_1^\alpha(u_X, s) + \mathcal{Q}_1^\alpha(\nabla u_X, s) \, ds \\ &\leq C\mathcal{Q}^0(f_X, t) + Ct^\alpha \int_0^t \alpha(t-s)\mathfrak{q}(s) \, ds. \end{aligned}$$

We may now apply Lemma 2.5 to complete the proof. □

The function $\mathcal{M}u_X(t) = tu_X(t)$ satisfies a similar estimate to the first one in Lemma 3.1, but with an additional factor t^2 on the right-hand side.

LEMMA 3.2. *The solution u_X of (3.1) satisfies*

$$\mathcal{Q}_1^\alpha(\mathcal{M}u_X, t) + \mathcal{Q}_2^\alpha(\mathcal{M}\nabla u_X, t) \leq Ct^{2+\alpha}\mathcal{Q}^0(f_X, t) \quad \text{for } 0 \leq t \leq T.$$

P r o o f. Multiplying both sides of (3.7) by t , and applying the third identity in (2.10), we find that (since κ is independent of t)

$$\begin{aligned} \mathcal{M}u_X, v + \kappa(\mathcal{I}^\alpha\mathcal{M} + \alpha\mathcal{I}^{\alpha+1})\nabla u_X, \nabla v \\ = \mathcal{M}\vec{B}_1u_X, \nabla v + \mathcal{M}(f_X - B_2u_X), v, \end{aligned} \tag{3.10}$$

whereas integrating (3.7) in time gives

$$\kappa\mathcal{I}^{\alpha+1}\nabla u_X, \nabla v = \mathcal{I}^1\vec{B}_1u_X, \nabla v + \mathcal{I}^1(f_X - u_X - B_2u_X), v,$$

so, after eliminating $\kappa\mathcal{I}^{\alpha+1}\nabla u_X, \nabla v$,

$$\begin{aligned} \mathcal{M}u_X, v + \kappa\mathcal{I}^\alpha\mathcal{M}\nabla u_X, \nabla v &= (\mathcal{M} - \alpha\mathcal{I}^1)\vec{B}_1u_X, \nabla v \\ &\quad + (\mathcal{M} - \alpha\mathcal{I}^1)(f_X - B_2u_X) + \alpha\mathcal{I}^1u_X, v \\ &\leq \frac{1}{2} \nabla v^2 + \frac{1}{2} \vec{B}_3u_X^2 + \frac{1}{2} B_4u_X^2 + \frac{1}{2} v^2 + (\mathcal{M} - \alpha\mathcal{I}^1)f_X + \alpha\mathcal{I}^1u_X, v, \end{aligned}$$

where $\vec{B}_3 = (\mathcal{M} - \alpha\mathcal{I}^1)\vec{B}_1$ and $B_4 = (\mathcal{M} - \alpha\mathcal{I}^1)B_2$. By choosing $v = \mathcal{I}^\alpha\mathcal{M}u_X$, we have $\kappa\mathcal{I}^\alpha\mathcal{M}\nabla u_X, \nabla v = \kappa\nabla v, \nabla v \geq \nabla v^2$ so, after canceling the term $\frac{1}{2} \nabla v^2$ and integrating in time,

$$\begin{aligned} \mathcal{Q}_1^\alpha(\mathcal{M}u_X, t) + \frac{1}{2}\mathcal{Q}_2^\alpha(\mathcal{M}\nabla u_X, t) \\ \leq \frac{1}{2}\mathcal{Q}^0(B_3u_X, t) + \frac{1}{2}\mathcal{Q}^0(B_4u_X, t) + \frac{1}{2}\mathcal{Q}_2^\alpha(\mathcal{M}u_X, t) \\ + \int_0^t (\mathcal{M} - \alpha\mathcal{I}^1)f_X, \mathcal{I}^\alpha\mathcal{M}u_X \, ds + \alpha \int_0^t \mathcal{I}^1u_X, \mathcal{I}^\alpha\mathcal{M}u_X \, ds. \end{aligned}$$

Using (2.6), we find that

$$\int_0^t (\mathcal{M} - \alpha \mathcal{I}^1) f_X, \mathcal{I}^\alpha \mathcal{M} u_X \, ds \leq Ct^\alpha \mathcal{Q}^0((\mathcal{M} - \alpha \mathcal{I}^1) f_X, t) + \frac{1}{4} \mathcal{Q}_1^\alpha(\mathcal{M} u_X, t)$$

and

$$\int_0^t \mathcal{I}^1 u_X, \mathcal{I}^\alpha \mathcal{M} u_X \, ds \leq Ct^\alpha \mathcal{Q}^0(\mathcal{I}^1 u_X, t) + \frac{1}{4} \mathcal{Q}_1^\alpha(\mathcal{M} u_X, t),$$

so

$$\begin{aligned} \mathcal{Q}_1^\alpha(\mathcal{M} u_X, t) + \mathcal{Q}_2^\alpha(\mathcal{M} \nabla u_X, t) &\leq \mathcal{Q}^0(B_3 u_X, t) + \mathcal{Q}^0(B_4 u_X, t) \\ &+ 2\mathcal{Q}_2^\alpha(\mathcal{M} u_X, t) + Ct^\alpha \mathcal{Q}^0((\mathcal{M} - \alpha \mathcal{I}^1) f_X, t) + Ct^\alpha \mathcal{Q}^0(\mathcal{I}^1 u_X, t). \end{aligned}$$

Since

$$\vec{B}_3 = (\mathcal{M} - \alpha \mathcal{I}^1) B_F^\alpha + (\mathcal{M} - \alpha \mathcal{I}^1) B_G^1$$

and

$$B_4 = (\mathcal{M} - \alpha \mathcal{I}^1) B_a^\alpha + (\mathcal{M} - \alpha \mathcal{I}^1) B_b^1,$$

the estimate (2.13) gives

$$\begin{aligned} \mathcal{Q}^0(\vec{B}_3 u_X, t) + \mathcal{Q}^0(B_4 u_X, t) &\leq Ct^2 \mathcal{Q}_2^\alpha(u_X, t) + Ct^2 \mathcal{Q}_2^1(u_X, t) \\ &\leq Ct^2 \mathcal{Q}_2^\alpha(u_X, t), \end{aligned}$$

where, in the last step, we used Lemma 2.4 with $\mu = \alpha$ and $\nu = 1$. We easily verify that

$$\mathcal{Q}^0((\mathcal{M} - \alpha \mathcal{I}^1) f_X, t) \leq Ct^2 \mathcal{Q}^0(f_X, t),$$

and by Lemma 2.4 with $\mu = 0$ and $\nu = 1$,

$$\mathcal{Q}^0(\mathcal{I}^1 u_X, t) = \mathcal{Q}_2^1(u_X, t) \leq t^2 \mathcal{Q}^0(u_X, t).$$

Thus, the function $q(t) = \mathcal{Q}_1^\alpha(\mathcal{M} u_X, t) + \mathcal{Q}_2^\alpha(\mathcal{M} \nabla u_X, t)$ satisfies

$$q(t) \leq Ct^2 \mathcal{Q}_2^\alpha(u_X, t) + 2\mathcal{Q}_2^\alpha(\mathcal{M} u_X, t) + Ct^{2+\alpha} \mathcal{Q}^0(f_X, t) + Ct^{2+\alpha} \mathcal{Q}^0(u_X, t).$$

By (2.4) and Lemma 3.1,

$$t^2 \mathcal{Q}_2^\alpha(u_X, t) + t^{2+\alpha} \mathcal{Q}^0(u_X, t) \leq Ct^{2+\alpha} \mathcal{Q}^0(u_X, t) \leq Ct^{2+\alpha} \mathcal{Q}(f_X, t),$$

and therefore, using Lemma 2.2 with $\eta = \mathcal{M} u_X$,

$$q(t) \leq Ct^{2+\alpha} \mathcal{Q}^0(f_X, t) + C \int_0^t \alpha(t-s) q(s) \, ds,$$

The result now follows by applying Lemma 2.5. □

LEMMA 3.3. *The solution u_X of (3.1) satisfies, for $0 \leq t \leq T$,*
 $\mathcal{Q}_1^\alpha((\mathcal{M} u_X), t) + \mathcal{Q}_2^\alpha((\mathcal{M} \nabla u_X), t) \leq Ct^\alpha \mathcal{Q}^0(f_X, t) + Ct^\alpha \mathcal{Q}^0((\mathcal{M} f_X), t).$

P r o o f. By differentiating (3.10) with respect to t , we have

$$\begin{aligned}
 (\mathcal{M}u_X), v + \kappa \nabla(\mathcal{I}^\alpha \mathcal{M}u_X), \nabla v &= \vec{B}_5 u_X - \alpha \kappa \mathcal{I}^\alpha \nabla u_X, \nabla v \\
 &+ (\mathcal{M}f_X) - B_6 u_X, v, \quad (3.11)
 \end{aligned}$$

where $\vec{B}_5 = (\mathcal{M}\vec{B}_1)$ and $B_6 = (\mathcal{M}B_2)$. Hence,

$$\begin{aligned}
 (\mathcal{M}u_X), v + \kappa \nabla(\mathcal{I}^\alpha \mathcal{M}u_X), \nabla v &\leq \frac{1}{2} \nabla v^2 + \vec{B}_5 u_X^2 + \frac{1}{2} B_6 u_X^2 \\
 &+ \frac{1}{2} v^2 + C \mathcal{I}^\alpha \nabla u_X^2 + (\mathcal{M}f_X), v.
 \end{aligned}$$

Putting $v = \mathcal{I}^\alpha(\mathcal{M}u_X)$, we can cancel $\frac{1}{2} \nabla v^2$ because $v = (\mathcal{I}^\alpha \mathcal{M}u_X)$ by (2.7). Thus, by integrating in time and using (2.6) to show

$$\int_0^t (\mathcal{M}f_X), \mathcal{I}^\alpha(\mathcal{M}u_X) \, ds \leq Ct^\alpha \mathcal{Q}^0((\mathcal{M}f_X), t) + \frac{1}{2} \mathcal{Q}_1^\alpha((\mathcal{M}u_X), t),$$

and using (3.4), we arrive at the estimate

$$\begin{aligned}
 \mathcal{Q}_1^\alpha((\mathcal{M}u_X), t) + \mathcal{Q}_2^\alpha((\mathcal{M}\nabla u_X), t) &\leq 2\mathcal{Q}^0(\vec{B}_5 u_X, t) + \mathcal{Q}^0(B_6 u_X, t) \\
 &+ \mathcal{Q}_2^\alpha((\mathcal{M}u_X), t) + C\mathcal{Q}_2^\alpha(\nabla u_X, t) + Ct^\alpha \mathcal{Q}^0((\mathcal{M}f_X), t).
 \end{aligned}$$

Since

$$\vec{B}_5 u_X = (\mathcal{M}B_F^\alpha u_X) + (\mathcal{M}B_G^1 u_X)$$

and

$$B_6 u_X = (\mathcal{M}B_a^\alpha u_X) + (\mathcal{M}B_b^1 u_X),$$

it follows from (2.14) that

$$\begin{aligned}
 \mathcal{Q}^0(\vec{B}_5 u_X, t) + \mathcal{Q}^0(B_6 u_X, t) &\leq C\mathcal{Q}_2^\alpha((\mathcal{M}u_X), t) + C\mathcal{Q}_2^\alpha(\mathcal{M}u_X, t) \\
 &+ C\mathcal{Q}_2^\alpha(u_X, t).
 \end{aligned}$$

By Lemmas 2.4, 3.1 and 3.2,

$$\begin{aligned}
 \mathcal{Q}_2^\alpha(\mathcal{M}u_X, t) + \mathcal{Q}_2^\alpha(u_X, t) &\leq Ct^\alpha \mathcal{Q}_1^\alpha(\mathcal{M}u_X, t) + Ct^\alpha \mathcal{Q}_1^\alpha(u_X, t) \\
 &\leq C(t^{2+2\alpha} + t^{2\alpha})\mathcal{Q}^0(f_X, t)
 \end{aligned}$$

and $\mathcal{Q}_2^\alpha(\nabla u_X, t) \leq Ct^\alpha \mathcal{Q}^0(f_X, t)$. Hence, the function

$$\mathfrak{q}(t) = \mathcal{Q}_1^\alpha((\mathcal{M}u_X), t) + \mathcal{Q}_2^\alpha((\mathcal{M}\nabla u_X), t)$$

satisfies

$$\mathfrak{q}(t) \leq Ct^\alpha \mathcal{Q}^0(f_X, t) + Ct^\alpha \mathcal{Q}^0((\mathcal{M}f_X), t) + C\mathcal{Q}_2^\alpha((\mathcal{M}u_X), t).$$

Finally, by Lemma 2.2,

$$\mathcal{Q}_2^\alpha((\mathcal{M}u_X), t) \leq C \int_0^t \alpha(t-s)\mathcal{Q}_1^\alpha((\mathcal{M}u_X), s) \, ds \leq C \int_0^t \alpha(t-s)\mathfrak{q}(s) \, ds,$$

and the desired estimate follows by Lemma 2.5. □

LEMMA 3.4. The solution u_X of (3.1) satisfies, for $0 \leq t \leq T$,

$$\mathcal{Q}^0((\mathcal{M}u_X), t) + \mathcal{Q}_1^\alpha((\mathcal{M}\nabla u_X), t) \leq C\mathcal{Q}^0(f_X, t) + C\mathcal{Q}^0((\mathcal{M}f_X), t)$$

P r o o f. Using $-\vec{B}_5 u_X, \nabla v = \nabla \cdot \vec{B}_5 u_X(t), v$ in (3.11), we obtain

$$(\mathcal{M}u_X), v + \kappa \mathcal{I}^\alpha(\mathcal{M}\nabla u_X), \nabla v \leq \frac{1}{2} v^2 + 2 \nabla \cdot \vec{B}_5 u_X^2 + 2 B_6 u_X^2 + (\mathcal{M}f_X)^2 - \alpha \kappa \mathcal{I}^\alpha \nabla u_X, \nabla v .$$

Choosing $v = (\mathcal{M}u_X)$, integrating in time, and using (3.4) yields

$$\begin{aligned} \frac{1}{2} \mathcal{Q}^0((\mathcal{M}u_X), t) + \mathcal{Q}_1^\alpha((\mathcal{M}\nabla u_X), t) &\leq 2\mathcal{Q}^0(\nabla \cdot \vec{B}_5 u_X, t) + 2\mathcal{Q}^0(B_6 u_X, t) \\ &\quad + \mathcal{Q}^0((\mathcal{M}f_X), t) - \alpha \int_0^t (\mathcal{M}\nabla u_X)(s), \kappa \mathcal{I}^\alpha \nabla u_X(s) ds. \end{aligned}$$

Recall from (3.9) that $\nabla \cdot B_F^\alpha = B_{.F}^\alpha + B_{F.}^\alpha \nabla$, where we have used the notation

$$B_{F.}^\alpha \nabla = \vec{F}(t) \cdot \mathcal{I}^\alpha \nabla - \int_0^t \vec{F}(s) \cdot \mathcal{I}^\alpha \nabla(s) ds.$$

Thus,

$$\begin{aligned} \nabla \cdot \vec{B}_5 u_X &= \nabla \cdot (\mathcal{M}\vec{B}_1 u_X) = (\mathcal{M}\nabla \cdot \vec{B}_1 u_X) \\ &= (\mathcal{M}\nabla \cdot B_F^\alpha u_X) + (\mathcal{M}\nabla \cdot B_G^1 u_X) \\ &= (\mathcal{M}B_{.F}^\alpha u_X) + (\mathcal{M}B_{F.}^\alpha \nabla u_X) \\ &\quad + (\mathcal{M}B_{.G}^1 u_X) + (\mathcal{M}B_{G.}^1 \nabla u_X), \end{aligned}$$

and so, by (2.14),

$$\begin{aligned} \mathcal{Q}^0(\nabla \cdot \vec{B}_5 u_X, t) + \mathcal{Q}^0(B_6 u_X, t) &\leq C\mathcal{Q}_2^\alpha((\mathcal{M}u_X), t) + C\mathcal{Q}_2^\alpha(\mathcal{M}u_X, t) \\ &\quad + C\mathcal{Q}_2^\alpha(u_X, t) + C\mathcal{Q}_2^\alpha((\mathcal{M}\nabla u_X), t) + C\mathcal{Q}_2^\alpha(\mathcal{M}\nabla u_X, t) + C\mathcal{Q}_2^\alpha(\nabla u_X, t). \end{aligned}$$

By (2.3),

$$\int_0^t (\mathcal{M}\nabla u_X)(s), \kappa \mathcal{I}^\alpha \nabla u_X(s) ds \leq \frac{1}{2} \mathcal{Q}_1^\alpha((\mathcal{M}\nabla u_X), t) + C\mathcal{Q}_1^\alpha(\nabla u_X, t),$$

and thus the function $q(t) = \mathcal{Q}^0((\mathcal{M}u_X), t) + \mathcal{Q}_1^\alpha((\mathcal{M}\nabla u_X), t)$ satisfies

$$\begin{aligned} q(t) &\leq C\mathcal{Q}_2^\alpha((\mathcal{M}u_X), t) + C\mathcal{Q}_2^\alpha(\mathcal{M}u_X, t) + C\mathcal{Q}_2^\alpha(u_X, t) \\ &\quad + C\mathcal{Q}_2^\alpha((\mathcal{M}\nabla u_X), t) + C\mathcal{Q}_2^\alpha(\mathcal{M}\nabla u_X, t) + C\mathcal{Q}_2^\alpha(\nabla u_X, t) \\ &\quad + C\mathcal{Q}^0((\mathcal{M}f_X), t) + C\mathcal{Q}_1^\alpha(\nabla u_X, t) \\ &\leq C\mathcal{Q}_2^\alpha((\mathcal{M}u_X), t) + Ct^\alpha \mathcal{Q}_1^\alpha(\mathcal{M}u_X, t) + Ct^\alpha \mathcal{Q}_1^\alpha(u_X, t) \\ &\quad + C\mathcal{Q}_2^\alpha((\mathcal{M}\nabla u_X), t) + Ct^{2+\alpha} \mathcal{Q}^0(f_X, t) + Ct^\alpha \mathcal{Q}^0(f_X, t) \\ &\quad + C\mathcal{Q}^0((\mathcal{M}f_X), t) + C\mathcal{Q}^0(f_X, t), \end{aligned}$$

where, in the second step, we used Lemmas 2.2, 3.1 and 3.2. A further application of Lemmas 3.1 and 3.2 yields

$$q(t) \leq C\mathcal{Q}^0((\mathcal{M}f_X), t) + C\mathcal{Q}^0(f_X, t) + C\mathcal{Q}_2^\alpha((\mathcal{M}u_X), t) + C\mathcal{Q}_2^\alpha((\mathcal{M}\nabla u_X), t).$$

Lemma 2.2 implies that $\mathcal{Q}_2^\alpha((\mathcal{M}u_X), t) + \mathcal{Q}_2^\alpha((\mathcal{M}\nabla u_X), t)$ is bounded by

$$C \int_0^t \alpha(t-s) \mathcal{Q}_1^\alpha((\mathcal{M}u_X), s) + \mathcal{Q}_1^\alpha((\mathcal{M}\nabla u_X), s) ds \leq C \int_0^t \alpha(t-s)q(s) ds,$$

where we used $\mathcal{Q}_1^\alpha((\mathcal{M}u_X), s) \leq Ct^\alpha \mathcal{Q}^0((\mathcal{M}u_X), s)$, which follows by Lemma 2.4. Finally, Lemma 2.5 implies the desired estimate. \square

The preceding lemmas yield the main result for this section.

THEOREM 3.3. *Assume that the coefficients satisfy (1.4), that the initial data $u_0 \in L_2(\Omega)$ and that the source term satisfies (3.2). Then, the solution u_X of the projected Volterra equation (3.1) satisfies (with C independent of X)*

$$\|u_X(t)\|^2 + t^\alpha \|\nabla u_X(t)\|^2 \leq C(\|u_0\|^2 + M^2 t^2) \quad \text{for } 0 \leq t \leq T.$$

P r o o f. The function $u_X = \mathcal{M}u_X$ satisfies $\|u_X(t)\| \leq Ct^\alpha$ by Theorem 3.2 so, applying Lemma 2.3 with $\mu = 0$, we see that Lemma 3.3 gives

$$\|u_X(t)\|^2 = \|\mathcal{M}u_X(t)\|^2 \leq Ct^{1-\alpha} \mathcal{Q}_1^\alpha((\mathcal{M}u_X), t) \leq Ct\mathcal{Q}^0(f_X, t) + Ct\mathcal{Q}^0((\mathcal{M}f_X), t).$$

Define $g_X : [0, T] \rightarrow X$ by $g_X(t), v = g(t), v$ for $v \in X$, and observe that $f_X = u_0 + \mathcal{I}^1 g_X$ and $(\mathcal{M}f_X) = f_X + \mathcal{M}f_X = f_X + \mathcal{M}g_X$. We find using (3.2) that

$$\mathcal{Q}^0(f_X, t) + \mathcal{Q}^0((\mathcal{M}f_X), t) \leq C \int_0^t \|u_0\|^2 + \|\mathcal{I}^1 g\|^2 + \|Mg\|^2 ds \leq Ct(\|u_0\|^2 + M^2 t^2), \tag{3.12}$$

so the estimate for the first term $\|u_X(t)\|^2$ follows at once. Similarly, applying Lemma 2.3 with $u_X = \mathcal{M}\nabla u_X$ followed by Lemma 3.4, we have

$$t^{2+\alpha} \|\nabla u_X(t)\|^2 = t^\alpha \|\mathcal{M}\nabla u_X(t)\|^2 \leq Ct\mathcal{Q}_1^\alpha((\mathcal{M}\nabla u_X), t) \leq Ct\mathcal{Q}^0(f_X, t) + Ct\mathcal{Q}^0((\mathcal{M}f_X), t),$$

implying the estimate for the second term $t^\alpha \|\nabla u_X(t)\|^2$. \square

4. The weak solution

We will now establish that the weak formulation (1.5) of the initial-boundary value problem (1.1)–(1.3) is well-posed. The proof relies on our estimates from Section 3 and also the following local Hölder continuity properties of u_X .

LEMMA 4.1. *If $0 < t_1 < t_2 \leq T$, then*

$$|u_X(t_2) - u_X(t_1)|^2 \leq C t_2^{-2} (u_0^2 + M^2 t_2^2) (t_2 - t_1)$$

and

$$|\mathcal{I}^\alpha \nabla u_X(t_2) - \mathcal{I}^\alpha \nabla u_X(t_1)| \leq C (u_0 + M t_2)^{\alpha-2} (t_2 - t_1)^{-\alpha/2} (t_2 - t_1)^\alpha .$$

P r o o f. The Cauchy–Schwarz inequality implies that

$$|u_X(t_2) - u_X(t_1)|^2 = \int_{t_1}^{t_2} |u_X(s)|^2 ds \leq (t_2 - t_1) \int_{t_1}^{t_2} |u_X(s)|^2 ds,$$

and by the second inequality of Lemma 3.1, together with Lemma 3.4,

$$\begin{aligned} \int_{t_1}^{t_2} |u_X(s)|^2 ds &= \int_{t_1}^{t_2} s^{-2} |(\mathcal{M}u_X)(s) - u_X(s)|^2 ds \\ &\leq 2^{-2} \int_{t_1}^{t_2} (|\mathcal{M}u_X|^2 + |u_X|^2) ds \\ &= 2^{-2} \mathcal{Q}^0((\mathcal{M}u_X), t_2) + \mathcal{Q}^0(u_X, t_2) \\ &\leq C^{-2} \mathcal{Q}^0(\mathcal{M}f_X, t_2) + \mathcal{Q}^0(f_X, t_2) . \end{aligned}$$

The first result now follows from (3.12). To prove the second, we write

$$\begin{aligned} \mathcal{I}^\alpha \nabla u_X(t_2) - \mathcal{I}^\alpha \nabla u_X(t_1) &= \int_0^{t_1 - /2} \alpha(t_2 - s) - \alpha(t_1 - s) \nabla u_X(s) ds \\ &+ \int_{t_1 - /2}^{t_1} \alpha(t_2 - s) - \alpha(t_1 - s) \nabla u_X(s) ds + \int_{t_1}^{t_2} \alpha(t_2 - s) \nabla u_X(s) ds, \end{aligned}$$

and deduce from Theorem 3.3 that

$$|\mathcal{I}^\alpha \nabla u_X(t_2) - \mathcal{I}^\alpha \nabla u_X(t_1)| \leq C (u_0 + M t_2) (I_1 + I_2 + I_3),$$

where

$$\begin{aligned}
 I_1 &= \int_0^{t_1 - \tau/2} \left(\alpha(t_1 - s) - \alpha(t_2 - s) \right) s^{-\alpha/2} ds, \\
 I_2 &= \int_{t_1 - \tau/2}^{t_1} \left(\alpha(t_1 - s) - \alpha(t_2 - s) \right) s^{-\alpha/2} ds, \\
 I_3 &= \int_{t_1}^{t_2} \alpha(t_2 - s) s^{-\alpha/2} ds.
 \end{aligned}$$

By the mean value theorem,

$\alpha(t_1 - s) - \alpha(t_2 - s) = (t_2 - t_1) | \alpha_{-1}(\xi) |$ with $t_1 - s < \xi < t_2 - s$, and if $0 < s < t_1 - \tau/2$ then $t_1 - s > \tau/2$ so

$$\begin{aligned}
 I_1 &\leq (t_2 - t_1) | \alpha_{-1}(\tau/2) | \int_0^{t_1 - \tau/2} \frac{ds}{s^{\alpha/2}} \\
 &\leq \frac{2^{2-\alpha}}{1 - \alpha/2} \frac{1 - \alpha}{(\alpha)} \frac{(t_1 - \tau/2)^{1-\alpha/2}}{(\alpha)} (t_2 - t_1).
 \end{aligned}$$

Moreover,

$$\begin{aligned}
 I_2 &\leq (\tau/2)^{-\alpha/2} \int_{t_1 - \tau/2}^{t_1} \left(\alpha(t_1 - s) - \alpha(t_2 - s) \right) ds \\
 &= (2/\tau)^{\alpha/2} \left(\alpha_{+1}(t_2 - t_1) + \alpha_{+1}(\tau/2) - \alpha_{+1}(t_2 - t_1 + \tau/2) \right) \\
 &\leq (2/\tau)^{\alpha/2} \alpha_{+1}(t_2 - t_1)
 \end{aligned}$$

and $I_3 \leq \int_{t_1}^{t_2} \alpha(t_2 - s) ds = \alpha_{+1}(t_2 - t_1)$. □

Our existence theorem is stated as follows. Note the weak continuity at $t = 0$ asserted in part 5; we show in the companion paper [29] that the solution u is continuous on the closed interval $[0, T]$ provided $u_0 \in H^\mu(\Omega)$ for some $\mu > 0$.

THEOREM 4.1. *Assume that the coefficients satisfy (1.4), that the source term satisfies (3.2), and that the initial data $u_0 \in L_2(\Omega)$. Then, the initial-boundary value problem (1.1)–(1.3) has a weak solution u . More precisely, there exists a function $u : [0, T] \rightarrow L_2(\Omega)$ with the following properties:*

- (1) *The restriction $u : (0, T] \rightarrow L_2(\Omega)$ is continuous.*
- (2) *If $0 < t \leq T$, then $u(t) \in H_0^1(\Omega)$ with*

$$\|u(t)\| + t^{\alpha/2} \|\nabla u(t)\| \leq C(\|u_0\| + Mt).$$

(3) The functions $\mathcal{I}^\alpha u$ and $B_2 u$ are continuous from the closed interval $[0, T]$ to $L_2(\Omega)$. Likewise, $\mathcal{I}^\alpha \nabla u$ and $\vec{B}_1 u$ are continuous from $[0, T]$ to $L_2(\Omega)^d$.

(4) At $t = 0$ we have $\mathcal{I}^\alpha u = B_2 u = 0$, $\mathcal{I}^\alpha \nabla u = \vec{B}_1 u = 0$ and $u(0) = u_0$.

(5) If $t > 0$, then $(u(t), v) = (u(0), v)$ for each $v \in L_2(\Omega)$.

(6) For $0 \leq t \leq T$ and $v \in H_0^1(\Omega)$,

$$u(t), v + \kappa(\mathcal{I}^\alpha \nabla u)(t), \nabla v - (\vec{B}_1 u)(t), \nabla v + (B_2 u)(t), v = f(t), v. \tag{4.1}$$

P r o o f. Let $\phi_1, \phi_2, \phi_3, \dots$ be a sequence of functions spanning a dense subspace of $H_0^1(\Omega)$. For each integer $n \geq 1$, let $X_n = \text{span}\{\phi_1, \phi_2, \dots, \phi_n\}$ and for brevity denote the solution of (3.7) with $X = X_n$ by $u_n = u_X$, and likewise write $f_n = f_X$, so that

$$u_n(t), v + \kappa(\mathcal{I}^\alpha \nabla u_n)(t), \nabla v - (B_1 u_n)(t), \nabla v + (B_2 u_n)(t), v = f_n(t), v \tag{4.2}$$

for $v \in X_n$ and $0 < t \leq T$. We see from Theorem 3.3 and Lemma 4.1 that, whenever $0 < \epsilon < T$, the sequence of functions u_n is bounded and equicontinuous in $C([\epsilon, T]; L_2(\Omega))$. By choosing a sequence of values of ϵ tending to zero we can select a subsequence, again denoted by u_n , such that $u_n(t)$ converges in $L_2(\Omega)$ for $0 < t \leq T$. We may therefore define

$$u(t) = \lim_n u_n(t) \quad \text{for } 0 < t \leq T,$$

and this function satisfies Property 1 because, given any fixed $\epsilon \in (0, T)$, the limit is uniform for $t \in [\epsilon, T]$. Similarly, the functions $\mathcal{I}^\alpha \nabla u_n$ are bounded and equicontinuous in $C([\epsilon, T]; L_2(\Omega)^d)$ so $\mathcal{I}^\alpha \nabla u : (0, T] \rightarrow L_2(\Omega)^d$ is continuous. In fact, it will follow from (4.4) below that $\mathcal{I}^\alpha \nabla u(t) = 0$ as $t \rightarrow 0$, so $\mathcal{I}^\alpha \nabla u : [0, T] \rightarrow L_2(\Omega)^d$ is continuous.

By Theorem 3.3,

$$|u_n(t)| \leq C(u_0 + Mt) \quad \text{for } 0 < t \leq T,$$

so by sending $n \rightarrow \infty$ we conclude that $|u(t)| \leq C(u_0 + Mt)$. Also, for $0 < t \leq T$,

$$|u_n(t), v| \leq C |u_n(t)|_{H_0^1(\Omega)} |v|_{H^{-1}(\Omega)} \leq Ct^{-\alpha/2} (u_0 + Mt) |v|_{H^{-1}(\Omega)}$$

and sending $n \rightarrow \infty$ it follows that

$$|u(t), v| \leq Ct^{-\alpha/2} (u_0 + Mt) |v|_{H^{-1}(\Omega)} \quad \text{for all } v \in L_2(\Omega),$$

so $u(t) \in H_0^1(\Omega)$ with $|u(t)|_{H_0^1(\Omega)} \leq Ct^{-\alpha/2} (u_0 + Mt)$, establishing Property 2.

Since $u(t)$ is bounded, $\mathcal{I}^\alpha u$ is continuous on $[0, T]$ with

$$\begin{aligned}
 \mathcal{I}^\alpha u(t) &\leq \int_0^t (t-s)^{\alpha-1} u(s) \, ds \\
 &\leq C \int_0^t (t-s)^{\alpha-1} (u_0 + Ms) \, ds \leq C(u_0 + Mt)t^\alpha,
 \end{aligned}
 \tag{4.3}$$

and similarly

$$\mathcal{I}^\alpha \nabla u(t) \leq C \int_0^t (t-s)^{\alpha-1} s^{-\alpha/2} (u_0 + Ms) \, ds \leq C(u_0 + Mt)t^{\alpha/2}.
 \tag{4.4}$$

Likewise, for $n \geq 1$,

$$\mathcal{I}^\alpha u_n(t) \leq C(u_0 + Mt)t^\alpha \quad \text{and} \quad \mathcal{I}^\alpha \nabla u_n(t) \leq C(u_0 + Mt)t^{\alpha/2}.
 \tag{4.5}$$

Continuity of $\vec{B}_1 u$ and $B_2 u$ follow from (2.11) and (3.6), completing the proof of property 3, with

$$\begin{aligned}
 (\vec{B}_1 u)(t) + (B_2 u)(t) &\leq C(\mathcal{I}^\alpha u)(t) + C \int_0^t ((\mathcal{I}^\alpha u)(s) + u(s)) \, ds \\
 &\leq C(u_0 + M)t^\alpha.
 \end{aligned}
 \tag{4.6}$$

Property 4 follows from the estimates (4.3), (4.4) and (4.6).

If $0 \leq t \leq T$, then

$$\begin{aligned}
 (\mathcal{I}^\alpha u_n)(t) - (\mathcal{I}^\alpha u)(t) &\leq \int_0^t (t-s)^{\alpha-1} (u_n(s) - u(s)) \, ds \\
 &\leq C \int_0^t (t-s)^{\alpha-1} (u_0 + Ms) \, ds + \int_0^t (t-s)^{\alpha-1} |u_n(s) - u(s)| \, ds \\
 &\leq C^\alpha (u_0 + M) + \alpha^{-1} (t-)^{\alpha} \max_{s \in [0, t]} |u_n(s) - u(s)|,
 \end{aligned}$$

showing that $\mathcal{I}^\alpha u_n(t) \rightarrow \mathcal{I}^\alpha u(t)$ in $L_2(\Omega)$, uniformly for $t \in [0, T]$. In fact, the convergence is uniform for $t \in [0, T]$, owing to the estimates (4.3) and (4.5). Therefore, we see using (2.11) and (3.6) that, for $v \in H_0^1(\Omega)$,

$$(\vec{B}_1 u_n)(t), \nabla v \rightarrow (\vec{B}_1 u)(t), \nabla v \quad \text{and} \quad (B_2 u_n)(t), v \rightarrow (B_2 u)(t), v.$$

Since $f_n, j = f, j$ for $j \leq n$, we have

$$\lim_n f_n(t), j = f(t), j \quad \text{for all } j \geq 1 \text{ and } 0 \leq t \leq T,$$

and therefore $f_n(t), v \rightarrow f(t), v$ for all $v \in L_2(\Omega)$. Thus, by sending $n \rightarrow \infty$ in (4.2), it follows that (4.1) holds for $v \in H_0^1(\Omega)$ and $0 < t \leq T$. In light of (4.6) and (4.4), the variational equation (4.1) is satisfied when $t = 0$ if and only if $u(0), v = u_0, v$ for all $v \in H_0^1(\Omega)$, which is the case if and only if we define $u(0) = u_0$. Moreover, if $t = 0$ then $u(t), v = f(0), v =$

u_0, v , for each $v \in H_0^1(\Omega)$, and hence by density for each $v \in L_2(\Omega)$, establishing Properties 5 and 6. \square

REMARK 4.1. Since our estimates rely on Lemma 2.1, the constant C in part 2 of Theorem 4.1 becomes unbounded as $\alpha \rightarrow 1$. However, this behavior appears to be an artifact of our method of proof. In the limiting case when $\alpha = 1$ and (1.1) reduces to a parabolic PDE, a simple energy argument combined with the classical Gronwall inequality yields the *a priori* estimate

$$u(t) \leq C \left(u_0 + \int_0^t g(s) \, ds \right) \quad \text{for } 0 \leq t \leq T;$$

see also the alternative analysis [21] of the fractional Fokker–Planck equation.

THEOREM 4.2. *The weak solution of the initial-boundary value problem (1.1)–(1.3) is unique. More precisely, under the same assumptions as Theorem 4.1, there is at most one function u that satisfies (4.1) and is such that u and $\mathcal{I}^\alpha u$ belong to $L_2((0, T); L_2(\Omega))$, and $\mathcal{I}^\alpha \nabla u$ belongs to $L_2((0, T); L_2(\Omega)^d)$.*

P r o o f. The problem is linear, so it suffices to show that if $u_0 = 0$ and $g(t) = 0$ then $u(t) = 0$. Thus, suppose that

$$u(t), v + \kappa(\mathcal{I}^\alpha \nabla u)(t), \nabla v - (\vec{B}_1 u)(t), \nabla v + (B_2 u)(t), v = 0$$

for $0 < t \leq T$ and $v \in H_0^1(\Omega)$. Proceeding as in the proof of (3.8), we have

$$\begin{aligned} \mathcal{Q}_1^\alpha(u, t) + \frac{1}{2} \mathcal{Q}_2^\alpha(\nabla u, t) &\leq \frac{1}{2} \mathcal{Q}^0(\vec{B}_1 u, t) + \frac{1}{2} \mathcal{Q}^0(B_2 u, t) + \frac{1}{2} \mathcal{Q}_2^\alpha(u, t) \\ &\leq C \mathcal{Q}_2^\alpha(u, t), \end{aligned}$$

where the final step used (2.11), (2.12) and Lemma 2.4. Thus, applying Lemma 2.2, the function $\mathbf{q}(t) = \mathcal{Q}_1^\alpha(u, t) + \mathcal{Q}_2^\alpha(\nabla u, t)$ satisfies

$$\mathbf{q}(t) \leq C \mathcal{Q}_2^\alpha(\nabla u, t) \leq C \int_0^t \alpha(t-s) \mathbf{q}(s) \, ds,$$

and therefore $\mathbf{q}(t) = 0$ for $0 \leq t \leq T$ by Lemma 2.5. In particular, $\mathcal{Q}_1^\alpha(u, T) = 0$, so if we put $u(t) = 0$ for $t > T$ then the Laplace transform of u satisfies $u(iy) = 0$ for $-\infty < y < \infty$ by (2.1), implying that $u(t) = 0$ for $0 \leq t \leq T$. \square

Acknowledgements

The authors thank the University of New South Wales (Faculty Research Grant Efficient numerical simulation of anomalous transport phenomena), the King Fahd University of Petroleum and Minerals (project No. KAUST005) and the King Abdullah University of Science and Technology.

References

- [1] E. A. Abdel-Rehim, Implicit difference scheme of the space-time fractional advection diffusion equation. *Fract. Calc. Appl. Anal.* **18**, No 6 (2015), 1452–1469; DOI: 10.1515/fca-2015-0084; <https://www.degruyter.com/view/j/fca.2015.18.issue-6/issue-files/fca.2015.18.issue-6.xml>.
- [2] A. A. Alikhanov, A priori estimates for solutions of boundary value problems for fractional-order equations. *Di er. Equ.* **46** (2010), 660–666; DOI: 10.1134/S0012266110050058.
- [3] A. A. Alikhanov, Boundary value problems for the diffusion equation of the variable order in differential and difference settings. *Appl. Math. Comput.* **219** (2012), 3938–3946; DOI: 10.1016/j.amc.2012.10.029.
- [4] C. N. Angstmann, B. I. Henry, B. A. Jacobs, and A. V. McGann, A time-fractional generalised advection equation from a stochastic process. *Chaos, Solitons and Fractals* **102** (2017), 175–183; DOI: 10.1016/j.chaos.2017.04.040.
- [5] L. C. Becker, Resolvents and solutions of weakly singular linear Volterra integral equations. *Nonlinear Anal.* **74** (2011), 1892–1912; DOI: 10.1016/j.na.2010.10.060.
- [6] H. Brunner, *Volterra Integral Equations: an Introduction to Theory and Applications*. Cambridge University Press (2017); DOI: 10.1017/9781316162491.
- [7] H. Brunner, A. Pedaş, and G. Vainikko, The piecewise polynomial collocation method for nonlinear weakly singular Volterra equations. *Math. Comp.* **68** (1999), 1079–1095; DOI: 10.1090/S0025-5718-99-01073-X.
- [8] J. Cao, Ch. Li, and Y.-Q. Chen, High-order approximation to Caputo derivatives and Caputo-type advection-diffusion equations (ii). *Fract. Calc. Appl. Anal.* **18**, No 3 (2015), 735–761; DOI: 10.1515/fca-2015-0045; <https://www.degruyter.com/view/j/fca.2015.18.issue-3/issue-files/fca.2015.18.issue-3.xml>.
- [9] J. Dixon and S. McKee, Weakly singular Gronwall inequalities. *ZAMM Z. Angew. Math. Mech.* **66** (1986), 535–544; DOI: 10.1002/zamm.19860661107.

- [10] B. I. Henry, T. A. M. Langlands, and P. Straka, Fractional Fokker–Planck equations for subdiffusion with space- and time-dependent forces. *Phys. Rev. Lett.* **105** (2010), 170602; DOI: 10.1103/PhysRevLett.105.170602.
- [11] B. I. Henry, T. A. M. Langlands, and S. L. Wearne, Anomalous diffusion with linear reaction dynamics: From continuous time random walks to fractional reaction-diffusion equations. *Phys. Rev. E* **74** (2006), 031116; DOI: 10.1103/PhysRevE.74.031116.
- [12] B. I. Henry and S. L. Wearne, Fractional reaction-diffusion. *Phys. A* **276** (2000), 448–455; DOI: 10.1016/S0378-4371(99)00469-0.
- [13] B. Jin, B. Li, and Z. Zhou, Discrete maximal regularity of time-stepping schemes for fractional evolution equations. *Numer. Math.* **138** (2018), 101–131; DOI: 10.1007/s00211-017-0904-8.
- [14] S. Karaa and A. K. Pani, Error analysis of a FVEM for fractional order evolution equations with nonsmooth initial data. *ESAIM: M2AN* **52**, No 2 (2018), 773–801; DOI: 10.1051/m2an/2018029.
- [15] J. Kemppainen, Existence and uniqueness of the solution for a time-fractional diffusion equation. *Fract. Calc. Appl. Anal.* **14**, No 3 (2011), 411–417; DOI: 10.2478/s13540-011-0025-5; <https://www.degruyter.com/view/j/fca.2011.14.issue-3/issue-files/fca.2011.14.issue-3.xml>.
- [16] J. Klafter and I. M. Sokolov, *First Steps in Random Walks*. Oxford University Press (2011); DOI: 10.1093/acprof:oso/9780199234868.001.0001.
- [17] A. Kubica and M. Yamamoto, Initial-boundary value problems for fractional diffusion equations with time-dependent coefficients. *Fract. Calc. Appl. Anal.* **21**, No 2 (2018), 276–311; DOI: 10.1515/fca-2018-0018; <https://www.degruyter.com/view/j/fca.2018.21.issue-2/issue-files/fca.2018.21.issue-2.xml>.
- [18] T. A. M. Langlands and B. I. Henry, The accuracy and stability of an implicit solution method for the fractional diffusion equation. *J. Comput. Phys.* **205**, No 2 (2005), 719–736; DOI: 10.1016/j.jcp.2004.11.025.
- [19] T. A. M. Langlands, B. I. Henry, and S. L. Wearne, Fractional cable equation models for anomalous electrodiffusion in nerve cells. *SIAM J. Appl. Math.* **71**, No 4 (2011), 1168–1203; DOI: 10.1137/090775920.
- [20] Kim Ngan Le, W. McLean, and K. Mustapha, A semidiscrete finite element approximation of a time-fractional Fokker–Planck equation with non-smooth initial data. *SIAM J. Sci. Comput.* **40**, No 6, (2018), A3831–3852; DOI: 10.1137/17M1125261.
- [21] Kim Ngan Le, W. McLean, and M. Stynes, Existence, uniqueness and regularity of the solution of the time-fractional Fokker–Planck equation

- with general forcing. *Commun. Pure Appl. Anal.* (to appear); DOI: 10.13140/RG.2.2.30053.24801.
- [22] Y. Li and Q. Zhang, Blow-up and global existence of solutions for a time fractional diffusion equation. *Fract. Calc. Appl. Anal.* **21**, No 6 (2018), 1619–1640; DOI: 10.1515/fca-2018-0085; <https://www.degruyter.com/view/j/fca.2018.21.issue-6/issue-files/fca.2018.21.issue-6.xml>.
- [23] H.-L. Liao, D. Li, and J. Zhang, Sharp error estimate of the nonuniform 11 formula for linear reaction-subdiffusion equations. *SIAM J. Numer. Anal.* **66**, No 2 (2018), 1112–1133; DOI: 10.1137/17M1131829.
- [24] P. Linz, *Analytical and Numerical Methods for Volterra Equations*. Ser. Studies in Applied and Numerical Mathematics, SIAM, Philadelphia (1985); DOI: 10.1137/1.9781611970852.
- [25] F. Liu, V. V. Anh, I. Turner, and P. Zhuang, Time fractional advection-dispersion equation. *J. Appl. Math. Computing* **13** (2003), 233–245; DOI: 10.1007/BF02936089.
- [26] Ch. Lubich, Runge–Kutta theory for Volterra and Abel integral equations of the second kind. *Math. Comp.* **41** (1983), 87–102; DOI: 10.1090/S0025-5718-1983-0701626-6.
- [27] Y. Luchko and M. Yamamoto, General time-fractional diffusion equation: some uniqueness and existence results for the initial-boundary-value problems. *Fract. Calc. Appl. Anal.* **19**, No 3 (2016), 676–695; DOI: 10.1515/fca-2016-0036; <https://www.degruyter.com/view/j/fca.2016.19.issue-3/issue-files/fca.2016.19.issue-3.xml>.
- [28] W. McLean, Regularity of solutions to a time-fractional diffusion equation. *ANZIAM J.* **52** (2010), 123–138; DOI: 10.1017/S1446181111000617.
- [29] W. McLean, K. Mustapha, R. Ali, and O. M. Knio, Regularity theory for time-fractional advection–diffusion–reaction equations. *Comput. Math. Appl.* (2019), Available online Aug. 2019 (In press); DOI: 10.1016/j.camwa.2019.08.008.
- [30] R. Metzler, E. Barkai, and J. Klafter, Deriving fractional Fokker–Planck equations from a generalised master equation. *Europhys. Lett.* **46** (1999), 431–436; DOI: 10.1209/epl/i1999-00279-7.
- [31] K. Mustapha, Time-stepping discontinuous Galerkin methods for fractional diffusion problems. *Numer. Math.* **130**, No 3 (2015), 497–516; DOI: 10.1007/s00211-014-0669-2.
- [32] J. A. Nohel and D. F. Shea, Frequency domain methods for Volterra equations. *Adv. Math.* **22** (1976), 278–304; DOI: 10.1016/0001-8708(76)90096-7.

- [33] I. Podlubny, *Fractional Differential Equations*. Academic Press, San Diego (1999).
- [34] K. Sakamoto and M. Yamamoto, Initial value/boundary value problems for fractional diffusion-wave equations and applications to some inverse problems. *J. Math. Anal. Appl.* **382**, No 1 (2011), 426–447; DOI: 10.1016/j.jmaa.2011.04.058.
- [35] C.-S. Sin and L. Zheng, Existence and uniqueness of global solutions of Caputo-type fractional differential equations. *Fract. Calc. Appl. Anal.* **19**, No 3 (2016), 765–774. DOI: 10.1515/fca-2016-0040; <https://www.degruyter.com/view/j/fca.2016.19.issue-3/issue-files/fca.2016.19.issue-3.xml>.
- [36] M. Stynes, E. O Riordan, and J. Luis Gracia, Error analysis of a finite difference method on graded meshes for a time-fractional diffusion equation. *SIAM J. Numer. Anal.* **55**, No 2 (2017), 1057–1079; DOI: 10.1137/16M1082329.
- [37] G. Vainikko, *Weakly Singular Integral Equations*. Lecture Notes, University of Tartu, Helsinki University of Technology (2006–2007).
- [38] S. B. Yuste and L. Acedo, An explicit finite difference method and a new von Neumann stability analysis for fractional diffusion equations. *SIAM J. Numer. Anal.* **42**, No 5 (2005), 1862–1874; DOI: 10.1137/030602666.
- [39] R. Zacher, Weak solutions of abstract evolutionary integro-differential equations in Hilbert spaces. *Funkcial. Ekvac.* **52** (2009), 1–18; DOI: 10.1619/fesi.52.1.

¹ *School of Mathematics and Statistics, The University of New South Wales Sydney 2052, AUSTRALIA*

e-mail: w.mclean@unsw.edu.au

Received: November 15, 2018

² *Department of Mathematics and Statistics KFUPM, Dhahran 31261, SAUDI ARABIA*

e-mail: kassem@kfupm.edu.sa

³ *Al-Quds Open University, Tubas Branch, PALESTINE*

e-mail: g201305090@kfupm.edu.sa

³ *Computer, Electrical, Mathematical Sciences and Engineering Division KAUST, Thuwal 23955, SAUDI ARABIA*

e-mail: Omar.Knio@kaust.edu.sa

Please cite to this paper as published in:

Fract. Calc. Appl. Anal., Vol. **22**, No 4 (2019), pp. 918–944,

DOI: 10.1515/fca-2019-0050; at <https://www.degruyter.com/view/j/fca>.