

RESEARCH

Open Access



Multiplicity of solutions for an anisotropic variable exponent problem

Leandro S. Tavares^{1*} 

*Correspondence:
leandro.tavares@ufca.edu.br
¹Center of Sciences and
 Technology, Federal University of
 Cariri, Juazeiro do Norte, Brazil

Abstract

In this manuscript an existence result for an anisotropic variable problem which is related to several applications is proved. By considering suitable hypotheses, the multiplicity of solutions is obtained. Examples of applicability of the results are also presented. The arguments are based on appropriated L^∞ estimates, sub-supersolutions, and the mountain pass theorem.

Keywords: Anisotropic problem; Variable exponents; Sub-supersolutions

1 Introduction and main results

$$\begin{cases} -\sum_{i=1}^N \frac{\partial}{\partial x_i} \left(\left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial u}{\partial x_i} \right) = a(x)u^{\alpha(x)-1} + \lambda f(x, u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (P)$$

where Ω , unless otherwise stated, is a bounded domain in $\mathbb{R}^N (N \geq 3)$ with smooth boundary $p_i \in C(\overline{\Omega}), 2 \leq p_i(x) \leq p_+(x) < \overline{p}^*(x), i = 1, \dots, N, p_+(x) := \max\{p_1(x), \dots, p_N(x)\}$ for any $x \in \overline{\Omega}$ with $\overline{p}(x) := N / \sum_{i=1}^N (1/p_i(x))$ and $\overline{p}^*(x) = N\overline{p}(x)/(N - \overline{p}(x))$ if $\overline{p}(x) < N$ and $\overline{p}(x) = +\infty$ if $N \geq p(x), \alpha \in C(\overline{\Omega})$ is a nonnegative function with $1 \leq \alpha(x)$ for all $x \in \overline{\Omega}$, $f : \Omega \times [0, +\infty) \rightarrow \mathbb{R}$ is a continuous function and

(H) $a \in L^\infty(\Omega)$ with $a(x) > 0$ a.e. in Ω ;

(f₁) There is $\delta > 0$ such that $f(x, t) \geq (1 - t^{\alpha(x)-1})a(x)$ for all $(x, t) \in \Omega \times [0, \delta]$;

(f₂) There exists $r \in C(\overline{\Omega})$ such that $1 < r(x)$ for any $x \in \overline{\Omega}$ and $|f(x, t)| \leq a(x)(1 + |t|^{r(x)-1})$ for all $(x, t) \in \Omega \times [0, +\infty)$.

We say that $u \in W_0^{1, \vec{p}(x)}(\Omega)$ is a weak solution for (P) if

$$\int_{\Omega} \sum_{i=1}^N \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial u}{\partial x_i} \frac{\partial \phi}{\partial x_i} = \int_{\Omega} a(x)u^{\alpha(x)-1} \phi + f(x, u)\phi$$

for all $\phi \in W_0^{1, \vec{p}(x)}(\Omega)$.

Denoting by $\|\cdot\|_\infty$ the norm in $L^\infty(\Omega)$, we obtain, by means of sub-supersolutions and minimization arguments, the result described below.

© The Author(s) 2022. This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article's Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit <http://creativecommons.org/licenses/by/4.0/>.

Theorem 1.1 *Consider that hypotheses (H), (f₁), and (f₂) hold. Then problem (P) has a solution for $\|a\|_\infty$ small enough.*

Define $p_\infty(x) = \max\{\bar{p}^+(x), p_+(x)\}, p_-(x) = \min\{p_1(x), \dots, p_n(x)\}, x \in \bar{\Omega}$ and denote $q^- := \inf_\Omega q$ and $q^+ := \sup_\Omega q$ for a function $q \in C(\bar{\Omega})$. Considering the Ambrosetti–Rabinowitz type condition:

(f₃) It holds that $\alpha^- > 1, \alpha^+, r^+ < p_\infty^-$ with $\alpha^+ < p_\infty^-$ or $p_+^+ < \alpha^-$, and there are $t_0 > 0$ and $\theta > p_+^+$ such that

$$0 < \theta F(x, t) \leq f(x, t)t, \quad \text{a.e. in } \Omega, \text{ for all } t \geq t_0,$$

we have the multiplicity result below.

Theorem 1.2 *Consider that hypotheses (H), (f₁)–(f₃) hold. Then problem (P) has two solutions for $\|a\|_\infty$ small enough.*

Consider $s_0 > 0$. The function

$$w(x, t) = \begin{cases} a(x)(1 - t^{\alpha(x)-1}), & 0 \leq t \leq s_0, \\ a(x)((1 - s_0^{\alpha(x)-1}) + (t - s_0)^{r(x)-1}), & t > s_0, \end{cases}$$

satisfies (f₁) and (f₂) for $\delta \in (0, s_0]$ and $r \in C(\bar{\Omega})$ with $r_- > 1$ for all $x \in \bar{\Omega}$. Note that (f₁)–(f₃) hold if $1 < \alpha^+ < p_\infty^-$ and $p_+^+ < r^-$ with $\alpha^+ < p_\infty^-$ or $p_+^+ < \alpha^-$.

Anisotropic partial differential equations have attracted the attention of several researchers in the last years due to their applicability in several areas of science. For example, in the classical paper [1] the authors considered a model which was applied for both image enhancement and denoising in terms of anisotropic PDEs as well as allowing the preservation of significant image features. In physics, anisotropic problems arise in models that describe the dynamics of fluids with different conductivities in different directions. We also point out that anisotropic equations can be applied in models that describe the spread of epidemic disease in heterogeneous environments. For more details regarding the mentioned applications, see for instance [2–4].

On the other hand, problems involving variable exponents can be also applied to consider several important models. A classical application is in the study of electrorheological fluids. The study of electrorheological fluids started when fluids that stop spontaneously, which are known in the literature as Bingham fluids, were discovered. We also mention the important work [5] due to W. Winslow, where the first major discovery regarding electrorheological fluids was presented. A notable fact is that under the presence of an electrical field, parallel and string-like formations arise in this kind of fluid. Such behavior is known as *Winslow effect*. As mentioned in the interesting paper [6], several experiments with such fluids have been considered in NASA due to their applicability in space technology and robotics.

We also mention that, from the mathematical viewpoint, anisotropic problems and equations with variable exponents are very interesting. For example, in the reference [7], regularity results for a system which arise in the study of electrorheological fluids are proved. In [8], the authors generalize several results of elliptic equations for the variable

exponents setting. In the classical manuscript [9] the author considers problems with an anisotropic operator with variable exponents. We also quote the interesting references [10–19] and the paper [20] which provides an overview of recent results concerning elliptic variational problems with nonstandard growth conditions and related to different kinds of nonuniformly elliptic operators. For a complete treatment of problems involving variable exponents, see [21, 22].

Problem (P) is motivated by [23], where the authors obtained versions of Theorems 1.1 and 1.2 with $\alpha \equiv 2$ for an anisotropic operator.

The rest of the manuscript is organized as follows: in Sect. 2 we present some preliminaries regarding spaces with variable exponents; in Sect. 3 we obtain an auxiliary L^∞ estimate which will play an important role in our arguments; in Sects. 5 and 6 the proofs of Theorems 1.1 and 1.2 are provided, respectively.

2 Preliminaries

Let $\Omega \subset \mathbb{R}^N (N \geq 1)$ be a bounded domain. Given $p \in C_+(\overline{\Omega}) := \{p \in C(\overline{\Omega}); \inf_{\Omega} p > 1\}$, we define the Lebesgue space

$$L^{p(x)}(\Omega) = \left\{ u : \Omega \rightarrow \mathbb{R} \text{ measurable; } \int_{\Omega} |u(x)|^{p(x)} < \infty \right\}$$

with the norm

$$\|u\|_{p(x)} := \inf \left\{ \lambda > 0; \int_{\Omega} \left| \frac{u(x)}{\lambda} \right|^{p(x)} \leq 1 \right\}.$$

It holds that $(L^{p(x)}(\Omega), \|\cdot\|_{p(x)})$ is a Banach space.

The results below, which can be found for example in [24], will be often used.

Proposition 2.1 Consider $p \in C_+(\overline{\Omega})$ and define $\rho(u) := \int_{\Omega} |u|^{p(x)} dx$. For $u, u_n \in L^{p(x)}(\Omega)$, $n \in \mathbb{N}$, the statements below hold.

- (i) If $u \neq 0$ in $L^{p(x)}(\Omega)$, then $\|u\|_{p(x)} = \lambda \Leftrightarrow \rho(\frac{u}{\lambda}) = 1$;
- (ii) If $\|u\|_{p(x)} < 1 (= 1; > 1)$, then $\rho(u) < 1 (= 1; > 1)$;
- (iii) If $\|u\|_{p(x)} > 1$, then $\|u\|_{p(x)}^{p^-} \leq \rho(u) \leq \|u\|_{p(x)}^{p^+}$;
- (iv) If $\|u\|_{p(x)} < 1$, then $\|u\|_{p(x)}^{p^+} \leq \rho(u) \leq \|u\|_{p(x)}^{p^-}$.

Theorem 2.2 Consider $p, q \in C_+(\overline{\Omega})$. The assertions below hold.

- (i) If $\frac{1}{q(x)} + \frac{1}{p(x)} = 1$ in Ω , then $|\int_{\Omega} uv dx| \leq (\frac{1}{p^-} + \frac{1}{q^-}) \|u\|_{p(x)} \|v\|_{q(x)}$;
- (ii) If $q(x) \leq p(x)$ in Ω and $|\Omega| < \infty$, then $L^{p(x)}(\Omega) \hookrightarrow L^{q(x)}(\Omega)$.

In what follows we recall some results on anisotropic variable exponents which can be found for example in [9]. Consider $p_i \in C_+(\overline{\Omega}), i = 1, \dots, N$. Denote

$$\vec{p}(x) := (p_1(x), \dots, p_N(x)) \in (C_+(\overline{\Omega}))^N$$

and define

$$p_+(x) := \max\{p_1(x), \dots, p_N(x)\} \quad \text{and} \quad p_-(x) := \min\{p_1(x), \dots, p_N(x)\}, \quad x \in \overline{\Omega}. \quad (2.1)$$

The anisotropic variable exponent Sobolev space given by

$$W^{1, \vec{p}(\cdot)}(\Omega) := \left\{ u \in L^{p_+(\cdot)}(\Omega); \frac{\partial u}{\partial x_i} \in L^{p_i(\cdot)}(\Omega), i = 1, \dots, N \right\}$$

is a Banach space with respect to the norm

$$\|u\|_{1, \vec{p}(\cdot)} := \|u\|_{p_+(\cdot)} + \sum_{i=1}^N \left\| \frac{\partial u}{\partial x_i} \right\|_{p_i(\cdot)}. \tag{2.2}$$

If $p_i^- > 1, i = 1, \dots, N$, then $W^{1, \vec{p}(\cdot)}(\Omega)$ is reflexive, see [9, Theorem 2.2].

By $W_0^{1, \vec{p}(\cdot)}(\Omega)$ we denote the Banach space defined by the closure of $C_0^\infty(\Omega)$ in $W^{1, \vec{p}(\cdot)}(\Omega)$ with respect to the norm (2.2).

Consider $\bar{p}(x) := N / \sum_{i=1}^N (1/p_i(x))$ and $\bar{p}^*(x) = N\bar{p}(x)(N - \bar{p}(x))$ if $\bar{p}(x) < N$ and $\bar{p}(x) = +\infty$ if $N \geq \bar{p}(x)$. If $p(x) < \bar{p}^*(x)$ for all $x \in \bar{\Omega}$, then the following Poincaré type inequality holds:

$$\|u\|_{p_+(\cdot)} \leq C \sum_{i=1}^N \left\| \frac{\partial u}{\partial x_i} \right\|_{p_i(\cdot)} \quad \text{for all } u \in W_0^{1, \vec{p}(\cdot)}(\Omega), \tag{2.3}$$

where C is a positive constant independent of $u \in W_0^{1, \vec{p}(\cdot)}(\Omega)$. Thus, the norm

$$\|u\| := \sum_{i=1}^N \left\| \frac{\partial u}{\partial x_i} \right\|_{p_i(\cdot)}, \quad u \in W_0^{1, \vec{p}(\cdot)}(\Omega)$$

is equivalent to the norm given in (2.2).

If $q \in C_+(\bar{\Omega})$ and $q(x) < p_\infty(x)$ for all $x \in \bar{\Omega}$, where $p_\infty(x) := \max\{\bar{p}^*(x), p_+(x)\}$, then there exists a compact embedding $W_0^{1, \vec{p}(\cdot)}(\Omega) \hookrightarrow L^{q(x)}(\Omega)$.

3 Auxiliary results

In what follows we present an existence result for a linear problem and a weak comparison principle which generalize Lemmas 2.1 and 2.2 of [23] respectively.

Lemma 3.1 Consider $a \in L^\infty(\Omega)$. The problem

$$\begin{cases} -\sum_{i=1}^N \frac{\partial}{\partial x_i} \left(\left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial u}{\partial x_i} \right) = a & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

has a unique solution in $W_0^{1, \vec{p}(\cdot)}(\Omega)$.

Proof The continuous nonlinear map $T : W_0^{1, \vec{p}(\cdot)}(\Omega) \rightarrow (W_0^{1, \vec{p}(\cdot)}(\Omega))'$ is defined by

$$\langle Tu, \phi \rangle = \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial u}{\partial x_i} \frac{\partial \phi}{\partial x_i}.$$

Since $p_i > 1, i = 1, \dots, N$, we have from the inequality (see for example [25, page 97])

$$\langle |x|^{l-2}x - |y|^{l-2}y, x - y \rangle \geq \frac{1}{2^{l-2}} |x - y|^l \tag{3.1}$$

for all $x, y \in \mathbb{R}^N$ and $l \geq 2$, where $\langle \cdot, \cdot \rangle$ denotes the usual inner product in \mathbb{R}^N , that

$$\langle Tu - Tv, u - v \rangle > 0 \quad \text{for all } u, v \in W_0^{1, \vec{p}(x)}(\Omega) \text{ with } u \neq v.$$

Consider $(u_n) \subset W_0^{1, \vec{p}(x)}(\Omega)$ a sequence with $\|u_n\| \rightarrow +\infty$. As in the proof of [21, Theorem 36], for each $i \in \{1, \dots, N\}$ and $n \in \mathbb{N}$, we define

$$\alpha_{i,n} := \begin{cases} p_i^+ & \text{if } \left\| \frac{\partial u_n}{\partial x_i} \right\|_{p_i(x)} \leq 1, \\ p_i^- & \text{if } \left\| \frac{\partial u_n}{\partial x_i} \right\|_{p_i(x)} > 1. \end{cases}$$

Since $(a_1 + \dots + a_N)^\beta \leq C(a_1^\beta + \dots + a_N^\beta)$ for $\beta \geq 1$ and $a_i \geq 0, i = 1, \dots, N$, for some constant C , we have

$$\begin{aligned} \int_{\Omega} \sum_{i=1}^N \left| \frac{\partial u_n}{\partial x_i} \right|^{p_i(x)} &\geq \sum_{i=1}^N \left\| \frac{\partial u_n}{\partial x_i} \right\|_{p_i(x)}^{\alpha_{i,n}} \\ &\geq C_1 \left(\sum_{\{i: \alpha_{i,n} = p_i^+\}} \left\| \frac{\partial u_n}{\partial x_i} \right\|_{p_i(x)} \right)^{p_i^+} \\ &\geq C_1 \left(\sum_{\{i: \alpha_{i,n} = p_i^+\}} \left\| \frac{\partial u_n}{\partial x_i} \right\|_{p_i(x)} \right)^{p_i^+} + C_2 \left(\sum_{\{i: \alpha_{i,n} = p_i^-\}} \left\| \frac{\partial u_n}{\partial x_i} \right\|_{p_i(x)} \right)^{p_i^-} \\ &\quad + C_2 \left(\sum_{\{i: \alpha_{i,n} = p_i^+\}} \left\| \frac{\partial u_n}{\partial x_i} \right\|_{p_i(x)} \right)^{p_i^-} - C_2 \left(\sum_{\{i: \alpha_{i,n} = p_i^-\}} \left\| \frac{\partial u_n}{\partial x_i} \right\|_{p_i(x)} \right)^{p_i^-} \\ &\geq C_3 \|u\|^{p_i^-} - N, \end{aligned} \tag{3.2}$$

where $C_1, C_2, C_3 > 0$ are constants that do not depend on $n \in \mathbb{N}$. Therefore

$$\lim_{n \rightarrow +\infty} \frac{\langle Tu_n, u_n \rangle}{\|u_n\|} = +\infty.$$

Thus, it follows from the Minty–Browder theorem [26, Theorem 5.16] that there is a unique function $u \in W_0^{1, \vec{p}(x)}(\Omega)$ such that $Tu = a$. □

Lemma 3.2 *Let $u, v \in W_0^{1, \vec{p}(x)}(\Omega)$ satisfy*

$$\begin{cases} -\sum_{i=1}^N \frac{\partial}{\partial x_i} \left(\left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial u}{\partial x_i} \right) \leq -\sum_{i=1}^N \frac{\partial}{\partial x_i} \left(\left| \frac{\partial v}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial v}{\partial x_i} \right) & \text{in } \Omega, \\ u \leq v & \text{on } \partial\Omega, \end{cases}$$

where $u \leq v$ on $\partial\Omega$ means that $(u - v)^+ := \max\{0, u - v\} \in W_0^{1, \vec{p}(x)}(\Omega)$. Then $u(x) \leq v(x)$ a.e. in Ω .

Proof Using the test function $\phi = (u - v)^+ := \max\{u - v, 0\} \in W_0^{1, \vec{p}(x)}(\Omega)$, it follows that

$$\int_{\Omega \cap \{u > v\}} \sum_{i=1}^N \left(\left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} - \left| \frac{\partial v}{\partial x_i} \right|^{p_i-2} \frac{\partial v}{\partial x_i} \right) \left(\frac{\partial u}{\partial x_i} - \frac{\partial v}{\partial x_i} \right) \leq 0$$

for $x, y \in \mathbb{R}^N$. Thus, it follows from (3.1) that

$$\int_{\Omega} \left| \frac{\partial}{\partial x_i} (u - v)^+ \right|^{p_i(x)} = 0$$

for $i = 1, \dots, N$, which allows to conclude that $\frac{\partial}{\partial x_i} (u - v)^+(x) = 0$ a.e. in Ω for $i = 1, \dots, N$. Applying (2.3) we obtain that $(u - v)^+(x) = 0$ a.e. in Ω , which finishes the proof of the result. \square

4 An auxiliary L^∞ estimate

Consider $\Omega \subset \mathbb{R}^N (N \geq 2)$ to be an admissible and bounded domain, that is, there exists a continuous embedding $W_0^{1,1}(\Omega) \hookrightarrow L^{\frac{N}{N-1}}(\Omega)$. The best constant of such an embedding will be denoted by C_0 , which depends on only Ω and N . Then it follows that

$$\|u\|_{W_0^{1,1}(\Omega)} \leq C_0 \|u\|_{L^{\frac{N}{N-1}}(\Omega)} \tag{4.1}$$

for all $u \in W_0^{1,1}(\Omega)$, where $\|u\|_{W_0^{1,1}(\Omega)} := \|\nabla u\|_{L^1}$. Adapting the ideas of [27, Lemma 4.1], we obtain an L^∞ estimate that will be applied in the construction of appropriate subsolutions, which is provided below.

Lemma 4.1 Consider $\lambda > 0$ and $u_\lambda \in W_0^{1, \vec{p}(x)}(\Omega)$ to be the unique solution of the problem

$$\begin{cases} -\sum_{i=1}^N \frac{\partial}{\partial x_i} \left(\left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial u}{\partial x_i} \right) = \lambda & \text{in } \Omega, \\ u = 0 & \text{on } \Omega. \end{cases} \tag{P_\lambda}$$

Consider $h := \frac{p^-}{2|\Omega|^{\frac{1}{N}}} C_0$. If $\lambda \geq h$, then $u \in L^\infty(\Omega)$ with $\|u\|_{L^\infty(\Omega)} \leq C^* \lambda^{\frac{1}{p^- - 1}}$ and $\|u\|_{L^\infty(\Omega)} \leq C_* \lambda^{\frac{1}{p^+ - 1}}$ when $\lambda < h$, where C^* and C_* are positive constants which depend only on Ω, N and $p_i, i = 1, \dots, N$.

Proof Note that u_λ is a nonnegative function with $u \not\equiv 0$. Consider $k \geq 0$ and define the set $A_k := \{x \in \Omega; u(x) > k\}$. Let $0 < \epsilon < 1$. Applying in (P_λ) the test function $(u - k)^+ \in W_0^{1, \vec{p}(x)}(\Omega)$, we obtain from (4.1) and Young's inequality that

$$\begin{aligned} & \int_{A_k} \sum_{i=1}^N \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)} dx \\ &= \lambda \int_{A_k} (u - k) dx \\ &\leq \lambda |A_k|^{\frac{1}{N}} \|(u - k)^+\|_{L^{\frac{N}{N-1}}(\Omega)} \end{aligned}$$

$$\begin{aligned}
 &\leq \lambda |A_k|^{\frac{1}{N}} C_0 \int_{A_k} |\nabla u| \, dx \\
 &\leq \lambda |A_k|^{\frac{1}{N}} C_0 \int_{A_k} \sum_{i=1}^N \left| \frac{\partial u}{\partial x_i} \right| \, dx \\
 &\leq \lambda |A_k|^{\frac{1}{N}} C_0 \sum_{i=1}^N \int_{A_k} \frac{(\epsilon |\frac{\partial u}{\partial x_i}|)^{p_i(x)}}{p_i(x)} \, dx + \lambda |A_k|^{\frac{1}{N}} C_0 \sum_{i=1}^N \int_{A_k} \frac{(\epsilon^{-1})^{(p_i(x))'}}{(p_i(x))'} \, dx. \tag{4.2}
 \end{aligned}$$

We have that

$$\begin{aligned}
 \lambda |A_k|^{\frac{1}{N}} C_0 \sum_{i=1}^N \int_{A_k} \frac{(\epsilon |\frac{\partial u}{\partial x_i}|)^{p_i(x)}}{p_i(x)} &\leq \frac{\lambda |A_k|^{\frac{1}{N}} C_0}{p_-} \sum_{i=1}^N \int_{A_k} \epsilon^{p_-} \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)} \, dx \\
 &\leq \frac{\lambda |\Omega|^{\frac{1}{N}} C_0}{p_-} \sum_{i=1}^N \int_{A_k} \epsilon^{p_-} \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)} \, dx,
 \end{aligned}$$

where p_- was defined in (2.1). Consider $h := \frac{p_-}{2|\Omega|^{\frac{1}{N}} C_0}$ and suppose that $\lambda \geq h$. Define

$$\epsilon := \left(\frac{p_-}{2\lambda |\Omega|^{\frac{1}{N}} C_0} \right)^{\frac{1}{p_-}}.$$

We have $\epsilon \leq 1$ and

$$\begin{aligned}
 \frac{\lambda |\Omega|^{\frac{1}{N}} C_0}{p_-} \sum_{i=1}^N \int_{A_k} \epsilon^{p_-} \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)} \, dx &\leq \frac{\lambda |\Omega|^{\frac{1}{N}} C_0 \epsilon^{p_-}}{p_-} \sum_{i=1}^N \int_{A_k} \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)} \, dx \\
 &= \frac{1}{2} \sum_{i=1}^N \int_{A_k} \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)} \, dx. \tag{4.3}
 \end{aligned}$$

Thus it follows from (4.2) and (4.3) that

$$\begin{aligned}
 \sum_{i=1}^N \int_{A_k} \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)} \, dx &\leq \frac{2\lambda |A_k|^{\frac{1}{N}} C_0}{(p_+)' } \sum_{i=1}^N \int_{A_k} \epsilon^{-(p_-)'} \, dx \\
 &\leq \gamma |A_k|^{1+\frac{1}{N}},
 \end{aligned}$$

where

$$\gamma := \frac{2N \epsilon^{-(p_-)'} C_0}{(p_+)' },$$

which provides that

$$\int_{A_k} (u - k) \, dx = \frac{1}{\lambda} \sum_{i=1}^N \int_{A_k} \left| \frac{\partial u}{\partial x_i} \right|^{p_i} \, dx \leq \gamma |A_k|^{1+\frac{1}{N}}.$$

From the L^∞ estimates in [28, Lemma 5.1-Chap. 2], we obtain that

$$\|u\|_{L^\infty(\Omega)} \leq \gamma (N + 1) |\Omega|^{\frac{1}{N}}$$

$$= C^* \lambda^{\frac{1}{p^--1}},$$

where C^* is a constant that does not depend on u_λ . If $\lambda < h$, then the result follows by applying the previous arguments with

$$\epsilon := \left(\frac{p^-}{2\lambda |\Omega|^{\frac{1}{N}} C_0} \right)^{\frac{1}{p^+}}. \quad \square$$

5 Proof of Theorem 1.1

Below we describe the notion of sub-supersolution that will be considered for (P) and a related result.

It will be considered that $(\underline{u}, \bar{u}) \in W_0^{1,p(\cdot)}(\Omega) \times W_0^{1,p(\cdot)}(\Omega)$ is a sub-supersolution pair for (P) if \underline{u} and \bar{u} belong to $L^\infty(\Omega)$, $0 < \underline{u}(x) \leq \bar{u}(x)$ a.e. in Ω and

$$\begin{aligned} \int_{\Omega} \sum_{i=1}^N \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial \underline{u}}{\partial x_i} \frac{\partial \varphi}{\partial x_i} &\leq \int_{\Omega} a(x) \underline{u}^{\alpha(x)-1} \varphi + \int_{\Omega} f(x, \underline{u}) \varphi, \\ \int_{\Omega} \sum_{i=1}^N \left| \frac{\partial \bar{u}}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial \bar{u}}{\partial x_i} \frac{\partial \varphi}{\partial x_i} &\geq \int_{\Omega} a(x) \bar{u}^{\alpha(x)-1} \varphi + \int_{\Omega} f(x, \bar{u}) \varphi \end{aligned} \tag{5.1}$$

for all $\varphi \in W_0^{1,p(\cdot)}(\Omega)$ with $\varphi(x) \geq 0$ a.e. in Ω .

Lemma 5.1 *Consider that hypotheses (H) and (f₁)–(f₂) hold. There is $\iota > 0$ such that if $\|a\|_{L^\infty(\Omega)} < \iota$, then (P) has a sub-supersolution pair $(\underline{u}, \bar{u}) \in (W_0^{1,p(\cdot)}(\Omega) \cap L^\infty(\Omega)) \times (W_0^{1,p(\cdot)}(\Omega) \cap L^\infty(\Omega))$ with $\|\underline{u}\|_\infty \leq \delta$, where δ is provided in (f₁).*

Proof From Lemmas 3.1 and 4.1, there are unique nonnegative solutions $\underline{u}, \bar{u} \in W_0^{1,p(\cdot)}(\Omega) \cap L^\infty(\Omega)$, respectively, for

$$\begin{cases} -\sum_{i=1}^N \frac{\partial}{\partial x_i} \left(\left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial \underline{u}}{\partial x_i} \right) = a(x) & \text{in } \Omega, \\ \underline{u} = 0 & \text{on } \partial\Omega, \end{cases} \tag{5.2}$$

and

$$\begin{cases} -\sum_{i=1}^N \frac{\partial}{\partial x_i} \left(\left| \frac{\partial \bar{u}}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial \bar{u}}{\partial x_i} \right) = 1 + a(x) & \text{in } \Omega, \\ \bar{u} = 0 & \text{on } \partial\Omega, \end{cases}$$

such that $\|\underline{u}\|_\infty \leq \max\{C^* \|a\|_\infty^{\frac{1}{p^--1}}, C_* \|a\|_\infty^{\frac{1}{p^+-1}}\}$, where $C^*, C_* > 0$ are the constants given in Lemma 4.1. Thus, there is $\eta > 0$, which depends only on C^* and C_* , such that $\|\underline{u}\|_\infty \leq \delta/2$ for $\|a\|_\infty < \eta$. From Lemma 3.2 we have $0 < \underline{u}(x) \leq \bar{u}(x)$ a.e. in Ω .

Let $\phi \in W_0^{1,p(\cdot)}(\Omega)$ be such that $\phi(x) \geq 0$ a.e. in Ω . Applying (f₁) and (5.2) we obtain that

$$\int_{\Omega} \sum_{i=1}^N \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial \underline{u}}{\partial x_i} \frac{\partial \phi}{\partial x_i} - \int_{\Omega} a(x) \underline{u}^{\alpha(x)-1} \phi - \int_{\Omega} f(x, \underline{u}) \phi$$

$$\begin{aligned} &\leq \int_{\Omega} a(x)\phi - \int_{\Omega} a(x)\underline{u}^{\alpha(x)-1}\phi - \int_{\Omega} (1 - \underline{u}^{\alpha(x)-1})a(x)\phi \\ &= 0. \end{aligned}$$

From (f₂) we have

$$\int_{\Omega} \sum_{i=1}^N \left| \frac{\partial \bar{u}}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial \bar{u}}{\partial x_i} \frac{\partial \phi}{\partial x_i} - \int_{\Omega} a(x)\bar{u}^{\alpha(x)-1}\phi - \int_{\Omega} f(x, \bar{u})\phi \geq \int_{\Omega} (1 - K\|a\|_{\infty})\phi,$$

where $K := \max\{\|\bar{u}\|_{\infty}^{\alpha^+}, \|\bar{u}\|_{\infty}^{\alpha^-}\} + \max\{\|\bar{u}\|_{\infty}^{\alpha^+-1}, \|\bar{u}\|_{\infty}^{\alpha^--1}\}$. Considering, if necessary, $\iota > 0$ smaller such that $K\|a\|_{\infty} \leq 1$ for $\|a\|_{\infty} < \iota$, it follows that the right-hand side in the last inequality is nonnegative, which provides the result. □

Proof of Theorem 1.1 Consider the functions $\underline{u}, \bar{u} \in W_0^{1, \vec{p}(x)}(\Omega)$ defined in Lemma 5.2. Define

$$w(x, t) = \begin{cases} a(x)\bar{u}^{\alpha(x)-1} + f(x, \bar{u}(x)), & t > \bar{u}(x), \\ a(x)t^{\alpha(x)-1} + f(x, t), & \underline{u}(x) \leq t \leq \bar{u}(x), \\ a(x)\underline{u}^{\alpha(x)-1} + f(x, \underline{u}(x)), & t < \underline{u}(x), \end{cases}$$

for $(x, t) \in \Omega \times \mathbb{R}$ and the problem

$$\begin{cases} -\sum_{i=1}^N \frac{\partial}{\partial x_i} \left(\left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial u}{\partial x_i} \right) = w(x, u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

whose solutions are the critical points of the C^1 functional defined by

$$J(u) := \int_{\Omega} \sum_{i=1}^N \frac{1}{p_i(x)} \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)} - \int_{\Omega} W(x, u) dx, \quad u \in W_0^{1, \vec{p}(x)}(\Omega), \tag{5.3}$$

where $W(x, t) := \int_0^t w(x, s) ds$. Note that J is coercive and sequentially weakly lower semi-continuous. We have that $K := \{u \in W_0^{1, \vec{p}(x)}(\Omega); \underline{u}(x) \leq u(x) \leq \bar{u}(x) \text{ a.e. in } \Omega\}$ is closed and convex and hence weakly closed in $W_0^{1, \vec{p}(x)}(\Omega)$. Thus, it follows that $J|_K$ attains its minimum at some $u_0 \in K$. Reasoning as in [29, Theorem 2.4], we get $J'(u_0) = 0$, which provides the result. □

6 Proof of Theorem 1.2

Consider $\underline{u} \in W_0^{1, \vec{p}(x)}(\Omega)$ given in Lemma 5.1 and the function

$$h(x, t) = \begin{cases} a(x)t^{\alpha(x)-1} + f(x, t), & t \geq \underline{u}(x), \\ a(x)\underline{u}(x)^{\alpha(x)-1} + f(x, \underline{u}(x)) & t < \underline{u}(x), \end{cases}$$

and the auxiliary problem

$$\begin{cases} -\sum_{i=1}^N \frac{\partial}{\partial x_i} \left(\left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial u}{\partial x_i} \right) = h(x, u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

whose solutions are given by the critical points of the C^1 functional

$$S(u) := \int_{\Omega} \sum_{i=1}^N \frac{1}{p_i(x)} \left| \frac{\partial u}{\partial x_i} \right|^{p_i(x)} - \int_{\Omega} H(x, u), \quad u \in W_0^{1, \vec{p}(x)}(\Omega),$$

where $H(x, t) := \int_0^t h(x, s) ds$.

Lemma 6.1 *The functional S satisfies the Palais–Smale condition.*

Proof Consider $(u_n) \subset W_0^{1, \vec{p}(x)}(\Omega)$ to be a sequence with $S'(u_n) \rightarrow 0$ and $S(u_n) \rightarrow c$ for some $c \in \mathbb{R}$.

We will start by considering the case $p_+^+ < \alpha^-$. Note that (f_3) holds for $\tilde{\theta} > 0$ such that $p_+^+ < \tilde{\theta} < \min\{\alpha^-, \theta\}$. Reasoning as in (3.2) and applying (f_2) – (f_3) , the boundedness of \underline{u} , and the continuous embedding $W_0^{1, \vec{p}(x)}(\Omega) \hookrightarrow L^1(\Omega)$, we obtain positive constants $C_1, C_2, C_3 > 0$ such that

$$\begin{aligned} C_1 + \|u_n\| &\geq S(u_n) - \frac{1}{\tilde{\theta}} S'(u_n) u_n \\ &\geq C_2 \|u_n\|^{p^-} + \int_{\{u_n \geq \underline{u}\}} \left(\frac{1}{\tilde{\theta}} - \frac{1}{\alpha(x)} \right) a(x) u_n^{\alpha(x)} - C_3 \|u_n\| \\ &\geq C_2 \|u_n\|^{p^-} - C_3 \|u_n\|, \end{aligned}$$

which provides the boundedness of (u_n) in $W_0^{1, \vec{p}(x)}(\Omega)$.

In the case $\alpha^+ < p_-^-$ we can apply (f_2) , (f_3) , Proposition 2.1, the boundedness of \underline{u} , and the continuous embedding $W_0^{1, \vec{p}(x)}(\Omega) \hookrightarrow L^1(\Omega)$ to obtain that

$$\begin{aligned} C_1 + \|u_n\| &\geq S(u_n) - \frac{1}{\theta} S'(u_n) u_n \\ &\geq C_2 \|u_n\|^{p^-} - C_4 \int_{\Omega} |u_n|^{\alpha(x)} - C_3 \|u_n\| \\ &\geq C_2 \|u_n\|^{p^-} - C_4 \max\{\|u_n\|_{\alpha(x)}^{\alpha^-}, \|u_n\|_{\alpha(x)}^{\alpha^+}\} - C_3 \|u_n\|, \end{aligned}$$

where $C_1, C_2, C_3, C_4 > 0$ are constants. Applying the embedding $W_0^{1, \vec{p}(x)}(\Omega) \hookrightarrow L^{\alpha(x)}(\Omega)$, we have

$$C_1 + \|u_n\| + C_3 \|u_n\| + C_5 \max\{\|u_n\|^{\alpha^+}, \|u_n\|^{\alpha^-}\} \geq C_2 \|u_n\|^{p^-}.$$

Since $\alpha^+ < p_-^-$, we obtain that (u_n) is bounded in $W_0^{1, \vec{p}(x)}(\Omega)$.

Thus, up to a subsequence, we get

$$\begin{cases} u_n \rightharpoonup u & \text{in } W_0^{1, \vec{p}(x)}(\Omega), \\ u_n(x) \rightarrow u(x) & \text{a.e. in } \Omega, \\ u_n \rightarrow u & \text{in } L^{\nu(x)}(\Omega), \end{cases} \tag{6.1}$$

for all $v \in C(\overline{\Omega})$ with $1 < v^- \leq v^+ < p_\infty^-$ and some $u \in W_0^{1,p(x)}(\Omega)$. Combining (6.1) and Lebesgue’s dominated convergence theorem it follows that

$$\int_{\Omega} \left(\left| \frac{\partial u_n}{\partial x_i} \right|^{p_i-2} \frac{\partial u_n}{\partial x_i} - \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} \right) \left(\frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right) \rightarrow 0,$$

which provides the result. □

Lemma 6.2 *Consider that (H), (f₁)–(f₃) hold. If $\|a\|_{L^\infty(\Omega)}$ is small enough, then the claims below hold.*

(i) *There are constants $R, \lambda > 0$ with $R > \|\underline{u}\|$ such that*

$$S(\underline{u}) < 0 < \lambda \leq \inf_{u \in \partial B_R(0)} S(u).$$

(ii) *There is $e \in W_0^{1,p(x)}(\Omega) \setminus \overline{B_{2R}(0)}$ with $S(e) < \lambda$.*

Proof From (5.1) and since $p_- > 1$, we have $S(\underline{u}) < 0$. Consider $u \in W_0^{1,p(x)}(\Omega)$ with $\|u\| \geq 1$. Arguing as in (3.2), applying Proposition 2.1 and the continuous embedding $W_0^{1,p(x)}(\Omega) \hookrightarrow L^{\alpha(x)}(\Omega)$, we obtain that

$$L(u) \geq K_1 \|u\|^{p_-} - K_2 \|u\| - K_3 \|a\|_\infty (\|u\|^{\alpha^+} + \|u\|^{r^+}) - K_4$$

for positive constants $K_1, K_2, K_3, K_4 > 0$. If necessary, decrease $\|a\|_\infty$ in such a way that $\|\underline{u}\| < 1$, which is possible by considering the test functions $\phi = \underline{u}$ in (5.1) and applying Lemma 4.1. Consider $\lambda > 0$ and fix $R > 1$ such that $K_1 R^{p_-} - K_2 R - K_4 \geq 2\lambda$. Considering $\|a\|_\infty$ small enough satisfying $K_3 \|a\|_\infty (R^{\alpha^+} + R^{r^+}) \leq \lambda$, it follows that $L(u) \geq \lambda$ for all $u \in W_0^{1,p(x)}(\Omega)$ with $\|u\| = R$, which finishes the proof of (i).

With respect to (ii), note that (f₃) implies the existence of constants $C_1, C_2, C_3, C_4 > 0$ and $t > 0$ such that $S(t\underline{u}) \leq C_1 t^{p^+} - C_2 t^{\alpha^-} - C_3 t^\theta + C_4 < 0$ with $\|t\underline{u}\| > 2R$. □

Proof of Theorem 1.2 Consider $\underline{u}, \bar{u} \in W_0^{1,p(x)}(\Omega)$ given in Lemma 5.1 and $u_1 \in W_0^{1,p(x)}(\Omega)$ the solution of (P) obtained in Theorem 1.1, which provides the minimum of $J|_K$, where

$$K := \{u \in W_0^{1,p(x)}(\Omega); \underline{u}(x) \leq u(x) \leq \bar{u}(x) \text{ a.e. in } \Omega\}$$

and J is the functional defined in (5.3). From Lemmas 6.1 and 6.2 we obtain that the hypotheses of the mountain pass theorem [30, Theorem 2.1] are satisfied by S . Therefore

$$c := \inf_{\gamma \in \Gamma} \max_{t \in [0,1]} S(\gamma(t)), \quad \text{where } \Gamma := \{\gamma \in C([0,1], W_0^{1,p(x)}(\Omega)); \gamma(0) = \underline{u}, \gamma(1) = e\},$$

is a critical value of S , that is, $S'(u_2) = 0$ and $L(u_2) = c$ for some $u_2 \in W_0^{1,p(x)}(\Omega)$. Note that $J(u) = S(u)$ for $u \in \{w \in W_0^{1,p(x)}(\Omega); 0 \leq w(x) \leq \bar{u}(x) \text{ a.e. in } \Omega\}$. Thus, $S(u_1) = \inf_{u \in K} J(u)$. If $u_2(x) \geq \underline{u}(x)$ a.e. in Ω , it follows that problem (P) has two weak solutions $u_1, u_2 \in W_0^{1,p(x)}(\Omega)$ with $S(u_1) \leq S(\underline{u}) < 0 < \lambda \leq c := S(u_2)$, where $\lambda > 0$ was provided in Lemma 6.2.

We claim that $u_2(x) \geq \underline{u}(x)$ a.e. in Ω . In fact, by considering the function $(\underline{u} - u_2)^+ \in W_0^{1,p(x)}(\Omega)$, we get

$$\begin{aligned} \int_{\Omega} \sum_{i=1}^N \left| \frac{\partial u_2}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial u_2}{\partial x_i} \frac{(\underline{u} - u_2)^+}{\partial x_i} &= \int_{\Omega} h(x, u_2)(\underline{u} - u_2)^+ \\ &= \int_{\Omega} (a(x)\underline{u}(x)^{\alpha(x)-1} + f(x, \underline{u}(x)))(\underline{u} - u_2)^+ \\ &\geq \int_{\Omega} \sum_{i=1}^N \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i(x)-2} \frac{\partial \underline{u}}{\partial x_i} \frac{\partial (\underline{u} - u_2)^+}{\partial x_i}. \end{aligned}$$

Thus, it follows from (3.1) that

$$\int_{\Omega} \left| \frac{\partial}{\partial x_i} (\underline{u} - u_2)^+ \right|^{p_i(x)} = 0$$

for $i = 1, \dots, N$, which implies that $\frac{\partial}{\partial x_i} (\underline{u} - u_2)^+(x) = 0$ a.e. in Ω for $i = 1, \dots, N$. From Proposition 2.1 and (2.3) we have $(\underline{u} - u_2)^+(x) = 0$ a.e. in Ω , which proves the claim. \square

Acknowledgements

The author would like to thank the referees for the comments which improved the manuscript.

Funding

No funding was received for this study.

Availability of data and materials

Not applicable.

Declarations

Competing interests

The author declares that they have no competing interests.

Authors' contributions

The author proved all the results of the paper and wrote the whole manuscript. He also read and approved the final version of the manuscript.

Publisher's Note

Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Received: 28 December 2021 Accepted: 9 February 2022 Published online: 24 February 2022

References

- Perona, P., Malik, J.: Scale-space and edge detection using anisotropic diffusion. *IEEE Trans. Pattern Anal. Mach. Intell.* **12**, 629–639 (1990)
- Antontsev, S.N., Diaz, J.I., Shmarev, S.: *Energy Methods for Free Boundary Problems*. Progress in Nonlinear Differential Equations and Their Applications, vol. 48. Birkhauser, Boston (2002)
- Bear, J.: *Dynamics of Fluids in Porous Media*. Elsevier, New York (1972)
- Bendahmane, M., Karlsen, K.H.: Renormalized solutions of an anisotropic reaction-diffusion advection system with L1 data. *Commun. Pure Appl. Anal.* **5**, 733–762 (2006)
- Winslow, W.: Induced fibrillation of suspensions. *J. Appl. Phys.* **20**, 1137–1140 (1949)
- Rădulescu, V.D.: Nonlinear elliptic equations with variable exponent: old and new. *Nonlinear Anal.* **121**, 336–369 (2015)
- Acerbi, E., Mingione, G.: Regularity results for stationary electro-rheological fluids. *Arch. Ration. Mech. Anal.* **164**, 213–259 (2002)
- Fan, X., Zhang, Q., Zhao, Y.: A strong maximum principle for $p(x)$ -Laplace equations. *Chin. J. Contemp. Math.* **21**, 1–7 (2000)
- Fan, X.: Anisotropic variable exponent Sobolev spaces and $\overrightarrow{p(x)}$ -Laplacian equations. *Complex Var. Elliptic Equ.* **56**, 623–642 (2011)

10. Benslimane, O., Aberqi, A., Bennouna, J.: Existence results for double phase obstacle problems with variable exponents. *J. Elliptic Parabolic Equ.* **7**, 875–890 (2021)
11. Benslimane, O., Aberqi, A., Bennouna, J.: The existence and uniqueness of an entropy solution to unilateral Orlicz anisotropic equations in an unbounded domain. *Axioms* **9**(3), 109 (2020)
12. Benslimane, O., Aberqi, A., Bennouna, J.: Existence and uniqueness of entropy solution of a nonlinear elliptic equation in anisotropic Sobolev–Orlicz space. *Rend. Circ. Mat. Palermo* **2**(70), 1579–1608 (2021)
13. Goodrich, C.S., Ragusa, M.A., Scapellato, A.: Partial regularity of solutions to $p(x)$ -Laplacian PDEs with discontinuous coefficients. *J. Differ. Equ.* **268**, 5440–5468 (2020)
14. Papageorgiou, N.S., Scapellato, A.: Nonlinear Robin problems with general potential and crossing reaction. *Rend. Lincei Mat. Appl.* **30**, 1–29 (2019)
15. Cencelj, M., Rădulescu, V.D., Repovš, D.: Double phase problems with variable growth. *Nonlinear Anal.* **177**, 270–287 (2018)
16. Ragusa, M.A., Tachikawa, A.: Partial regularity of the minimizers of quadratic functionals with VMO coefficients. *J. Lond. Math. Soc. (2)* **72**, 609–620 (2005)
17. Ragusa, M.A., Tachikawa, A.: Regularity for minimizers for functionals of double phase with variable exponents. *Adv. Nonlinear Anal.* **9**, 710–728 (2020)
18. Ragusa, M.A., Tachikawa, A.: On continuity of minimizers for certain quadratic growth functionals. *J. Math. Soc. Jpn.* **57**, 691–700 (2005)
19. Rădulescu, V.D., Saiedinezhad, R.: A nonlinear eigenvalue problem with $p(x)$ -growth and generalized Robin boundary value condition. *Commun. Pure Appl. Anal.* **17**, 39–52 (2018)
20. Mingione, G., Rădulescu, V.: Recent developments in problems with nonstandard growth and nonuniform ellipticity. *J. Math. Anal. Appl.* **501**, 125197 (2021)
21. Rădulescu, V., Repovš, D.: *Partial Differential Equations with Variable Exponents: Variational Methods and Qualitative Analysis*. CRC Press, Boca Raton (2015)
22. Růžička, M.: *Electrorheological Fluids: Modeling and Mathematical Theory*. Springer, Berlin (2000)
23. dos Santos, G.C.G., Figueiredo, G., Silva, J.R.S.: Multiplicity of positive solutions for an anisotropic problem via sub-supersolution method and mountain pass theorem. *J. Convex Anal.* **27**(4), 1363–1374 (2020)
24. Fan, X., Zhao, D.: On the spaces $L^{p(x)}(\Omega)$ and $W^{m,p(x)}(\Omega)$. *J. Math. Anal. Appl.* **163**, 424–446 (2001)
25. Lindqvist, P.: *Notes on the Stationary p-Laplace Equation*. SpringerBriefs in Mathematics. Springer, Cham (2019)
26. Brézis, H.: *Functional Analysis, Sobolev Spaces and Partial Differential Equations*. Springer, New York (2011)
27. dos Santos, G.C.G., Figueiredo, G., Tavares, L.S.: Existence of solutions for a class of nonlocal problems driven by an anisotropic operator via sub-supersolutions. *J. Convex Anal.* **29**(1), 291–320 (2022)
28. Ladyženskaya, O.A., Ural'tseva, N.N.: *Linear and Quasilinear Elliptic Equations*. Academic Press, New York (1968)
29. Struwe, M.: *Variational Methods. Applications to Nonlinear Partial Differential Equations and Hamiltonian Systems*, 2nd edn. *Ergebnisse der Mathematik und Ihrer Grenzgebiete*, vol. 34. Springer, Berlin (1996)
30. Ambrosetti, A., Rabinowitz, P.H.: Dual variational methods in critical point theory and applications. *J. Funct. Anal.* **14**, 349–381 (1973)

Submit your manuscript to a SpringerOpen[®] journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

Submit your next manuscript at ► [springeropen.com](https://www.springeropen.com)
