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The stability of solutions for the Fornberg–Whitham equation in $L^1(\mathbb{R})$ space

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Abstract

The $L^2(\mathbb{R})$ conservation law of solutions for the nonlinear Fornberg–Whitham equation is derived. Making use of the Kruzkov's device of doubling the space variables, the stability of the solutions in $L^1(\mathbb{R})$ space is established under certain assumptions on the initial value.

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1 Introduction

In this article, we investigate the Fornberg–Whitham(FW) equation

$$V_t - V_{txx} - V_x + \frac{3}{2}VV_x = \frac{9}{2}V_xV_{xx} + \frac{3}{2}VV_{xxx}, \quad (1)$$

which was first written down in Whitham [1]. The numerical and theoretical analysis of solutions for Eq. (1) are made in Fornberg and Whitham [2] in which the peakon solution

$$V(t, x) = \frac{8}{9}e^{-\frac{1}{2}|x - \frac{4}{3}t|} \quad (2)$$

is found.

Recently, Holmes and Thompson [3] have established the existence and uniqueness of the FW equation in the Besov space in both non-periodic and periodic cases and discussed the sharpness of continuity on the data-to-solution map. A Cauchy–Kowalewski type result, which guarantees the existence and uniqueness of real analytic solutions for Eq. (1), is given and the blow-up criterion for solutions is obtained in [3]. Haziot [4] employs the estimates derived from the FW equation itself and some conclusions in [5] to derive sufficient conditions on the initial value which lead to wave breaking of solutions. For the detailed discussion about the discovery of wave breaking, we refer the reader to [2, 5–8].

We know that the dynamic properties of the Fornberg–Whitham equation are related to those of the Camassa–Holm (CH) [9], Degasperis–Procesi (DP) [10], and Novikov equations [11]. The four types of equations possess the peakon solutions. Here, we recall several works on the study of the CH, DP, and Novikov equations. The well-posedness of the Cauchy problem for a generalized CH equation is established in Himonas and Holliman [12]. The nonuniform dependence of the periodic CH equation and the well-posedness

of the DP equation are discussed in [13] and [14], respectively. The continuity properties of the data-to-solution map for the periodic b-family equation including the CH and DP equations are obtained in [15]. Coclite and Karlsen [16] discuss the existence and stability of the entropy solution for the DP equation. The existence and uniqueness of global solutions for the DP equation are studied in Liu and Yin [17] in the case that the initial data satisfy the sign condition. Escher et al. [18] investigate the global weak solutions and blow-up structure for the DP model under certain assumptions. Matsuno [19] finds out the multisoliton solutions of the DP equation and analyzes their peakon limits. The uniform stability of peakons for the Camassa–Holm model is established in Constantin and Strauss [7]. Using the conservation law and assuming that the initial data satisfy the sign condition, Lin and Liu [20] obtain the stability of peakons for the Degasperis–Procesi equation. The Cauchy problem for the Novikov equation is considered in [21]. A generalized Novikov model with peakon solutions is studied in [22]. For other studies of the CH, DP, and Novikov equations, the reader is referred to [21–29] and the references therein.

Motivated by the works made in Coclite and Karlsen [16], the aim of this article is to investigate the stability of local strong solutions for the Fornberg–Whitham equation (1). We find out the L^2 conservation law to the FW model. Assuming that the initial data belong to the space $L^1(\mathbb{R}) \cap H^s(\mathbb{R})$ with $s > \frac{3}{2}$, we obtain the stability of local strong solution in the space $L^1(\mathbb{R})$. We state that the L^1 stability for Eq. (1) has never been established in the previous literature works. The main technique used in this work is the device of doubling the space variables presented in [30].

The structure of this paper is that several lemmas are given in Sect. 2 and the proof of our main result is presented in Sect. 3.

2 Several lemmas

Consider the Cauchy problem of Eq. (1)

$$\begin{cases} V_t - V_{txx} - V_x + \frac{3}{2}VV_x = \frac{9}{2}V_xV_{xx} + \frac{3}{2}VV_{xxx}, \\ V(0, x) = V_0(x). \end{cases} \tag{3}$$

Letting $\Lambda^2 = 1 - \partial_x^2$ and noting the expression $VV_{xxx} = \frac{1}{2}(V^2)_{xxx} - 3V_xV_{xx}$, multiplying both sides of the first equation of problem (3) by Λ^{-2} , we obtain the nonlocal form of problem (3) in the form

$$\begin{cases} V_t + \frac{3}{2}VV_x - (1 - \partial_x^2)^{-2}V_x = 0, \\ V(0, x) = V_0(x), \end{cases} \tag{4}$$

where $\Lambda^{-2}g = \frac{1}{2} \int_{\mathbb{R}} e^{-|x-y|} g \, dy$ for any $g \in L^\infty$ or $g \in L^p(\mathbb{R})$ with $1 \leq p \leq \infty$.

Lemma 1 *If $V_0(x) \in H^s(\mathbb{R})$, $s > \frac{3}{2}$ and $V(t, x)$ is the solution of problem (4), then*

$$\int_{\mathbb{R}} V^2(t, x) \, dx = \int_{\mathbb{R}} V_0^2(x) \, dx. \tag{5}$$

Proof Setting $(1 - \partial_x^2)^{-2}V = W$, we get $W - W_{xx} = V$ and

$$\int_{\mathbb{R}} V(1 - \partial_x^2)^{-2}V_x \, dx = \int_{\mathbb{R}} VW_x \, dx = \int_{\mathbb{R}} (W - W_{xx})W_x \, dx = 0, \tag{6}$$

from which we have

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \int_R V^2 dx &= \int_R V V_t dx \\ &= \int_R \left[-\frac{3}{2} V^2 V_x + V(1 - \partial_x^2)^{-2} V_x \right] dx \\ &= 0 + \int_R [V(1 - \partial_x^2)^{-2} V_x] dx \\ &= 0, \end{aligned}$$

which completes the proof. □

Lemma 2 ([3, 4, 23]) *Assume $V(0, x) = V_0(x) \in H^s(\mathbb{R})$, $s > \frac{3}{2}$. Then problem (3) or (4) has a unique strong solution V satisfying*

$$V \in C([0, T]; H^s(\mathbb{R})) \cap C^1([0, T]; H^{s-1}(\mathbb{R})),$$

where $T = T(V_0) > 0$ is the maximal existence time.

Consider the ordinary differential equation

$$\begin{cases} p_t = \frac{3}{2} V(t, p), & t \in [0, T], \\ p(0, x) = x. \end{cases} \tag{7}$$

Lemma 3 *Assume that $V_0 \in H^s$, $s \geq 3$, and $T > 0$ is the maximal existence time of the solution for problem (7). Then there exists a unique solution $p \in C^1([0, T] \times \mathbb{R})$ to problem (7) and the map $p(t, \cdot)$ is an increasing diffeomorphism of \mathbb{R} with $p_x(t, x) > 0$ for $(t, x) \in [0, T] \times \mathbb{R}$.*

Proof Using Lemma 2, we have $V \in C^1([0, T]; H^{s-1}(\mathbb{R}))$ and $H^s \in C^1(\mathbb{R})$. Therefore, we know that functions $V(t, x)$ and $V_x(t, x)$ are bounded, Lipschitz in space, and C^1 in time. Making use of the existence and uniqueness theorem of ordinary differential equations, we conclude that problem (7) has a unique solution $p \in C^1([0, T] \times \mathbb{R})$.

We differentiate (7) about the variable x and get

$$\begin{cases} \frac{d}{dt} p_x = \frac{3}{2} V_x(t, p) p_x, & t \in [0, T], \\ p_x(0, x) = 1, \end{cases} \tag{8}$$

which results in

$$p_x(t, x) = e^{\int_0^t \frac{3}{2} V_x(\tau, p(\tau, x)) d\tau}. \tag{9}$$

For every $T' < T$, applying the Sobolev imbedding theorem gives rise to

$$\sup_{(\tau, x) \in [0, T'] \times \mathbb{R}} |V_x(\tau, x)| < \infty, \tag{10}$$

from which we know that there exists a constant $K_0 > 0$ to satisfy $p_x(t, x) \geq e^{-K_0 t} > 0$ for $(t, x) \in [0, T) \times \mathbb{R}$. The proof is finished. \square

Lemma 4 *Suppose that T is the maximal existence time of the solution V to problem (4) and $V_0 \in H^s(\mathbb{R})$, $s > \frac{3}{2}$. Then*

$$\|V(t, x)\|_{L^\infty} \leq t\|V_0\|_{L^2} + \|V_0\|_{L^\infty}, \quad \forall t \in [0, T], \tag{11}$$

$$|\Lambda^{-2}V_x| \leq \|V_0\|_{L^2}, \quad \forall t \in [0, T]. \tag{12}$$

Proof Using the density argument presented in [17], we only need to consider the case $s = 3$ to prove Lemma 4. If the initial value $V_0 \in H^3(\mathbb{R})$, we obtain $V \in C([0, T), H^3(\mathbb{R})) \cap C^1([0, T), H^2(\mathbb{R}))$. From (4), we have

$$\begin{aligned} V_t + \frac{3}{2}V V_x &= \frac{1}{2} \int_{-\infty}^{\infty} e^{-|x-y|} \frac{\partial}{\partial y} V(t, y) dy \\ &= \frac{1}{2} \int_{-\infty}^x e^{-x+y} \frac{\partial}{\partial y} V(t, y) dy + \frac{1}{2} \int_x^{\infty} e^{-y+x} \frac{\partial}{\partial y} V(t, y) dy \\ &= -\frac{1}{2} \int_{-\infty}^x e^{-x+y} V(t, y) dy + \frac{1}{2} \int_x^{\infty} e^{-y+x} V(t, y) dy \end{aligned} \tag{13}$$

and

$$\begin{aligned} \frac{dV(t, p(t, x))}{dt} &= V_t(t, p(t, x)) + V_x(t, p(t, x)) \frac{dp(t, x)}{dt} \\ &= \left(V_t + \frac{3}{2}V V_x \right)(t, p(t, x)). \end{aligned} \tag{14}$$

Using the identity $\int_{-\infty}^{\infty} e^{-2|x-y|} dy = 1$ and $\|V\|_{L^2} = \|V_0\|_{L^2}$ (see Lemma 1), we have

$$\begin{aligned} &\left| -\frac{1}{2} \int_{-\infty}^x e^{-x+y} V(t, y) dy + \frac{1}{2} \int_x^{\infty} e^{-y+x} V(t, y) dy \right| \\ &\leq \frac{1}{2} \int_{-\infty}^x e^{-x+y} |V(t, y)| dy + \frac{1}{2} \int_x^{\infty} e^{-y+x} |V(t, y)| dy \\ &\leq \left(\int_{-\infty}^{\infty} e^{-2|x-y|} dy \right)^{\frac{1}{2}} \left(\int_{-\infty}^{\infty} V^2(t, y) dy \right)^{\frac{1}{2}} \\ &\leq \|V\|_{L^2(\mathbb{R})} \\ &= \|V_0\|_{L^2(\mathbb{R})}, \end{aligned} \tag{15}$$

from which together with (13) we derive that (12) holds.

From (13)–(15), we derive that

$$\begin{aligned} \left| \int_0^t \frac{dV(t, p(t, x))}{dt} dt \right| &\leq \frac{1}{2} \int_0^t \left| \int_{-\infty}^{\infty} e^{-|p(t,x)-y|} \frac{\partial}{\partial y} V(t, y) dy \right| dt \\ &\leq t\|V_0\|_{L^2(\mathbb{R})}, \end{aligned} \tag{16}$$

from which we obtain

$$|V(t, p(t, x))| \leq \|V(t, p(t, x))\|_{L^\infty} \leq t \|V_0\|_{L^2(\mathbb{R})} + \|V_0\|_{L^\infty}. \tag{17}$$

Using Lemma 3, for every $t \in [0, T')$, $T' < T$, we get that there exists a function $K(t) > 0$ such that

$$e^{-K(t)} \leq p_x(t, x) \leq e^{K(t)}, \quad x \in \mathbb{R}. \tag{18}$$

We deduce from (18) that the function $p(t, \cdot)$ is strictly increasing on \mathbb{R} with $\lim_{x \rightarrow \pm\infty} p(t, x) = \pm\infty$ as long as $t \in [0, T')$. Applying (17) produces

$$\|V(t, x)\|_{L^\infty} = \|V(t, p(t, x))\|_{L^\infty} \leq t \|V_0\|_{L^2(\mathbb{R})} + \|V_0\|_{L^\infty}.$$

The proof is finished. □

Lemma 5 *Suppose that $V_1(t, x)$ and $V_2(t, x)$ are two solutions of problem (4) with initial data $V_{1,0}(x), V_{2,0}(x) \in H^s(\mathbb{R})$ ($s > \frac{3}{2}$), respectively. Assume $f(t, x) \in C_0^\infty([0, \infty) \times (-\infty, \infty))$. Then*

$$\begin{aligned} & \int_{-\infty}^{\infty} \left| \Lambda^{-2} \frac{\partial}{\partial x} V_1(t, x) - \Lambda^{-2} \frac{\partial}{\partial x} V_2(t, x) \right| |f(t, x)| \, dx \\ & \leq c_0 \int_{-\infty}^{\infty} |V_1(t, x) - V_2(t, x)| \, dx, \end{aligned} \tag{19}$$

where $c_0 > 0$ depends on f .

Proof We have

$$\begin{aligned} & \int_{-\infty}^{\infty} \left| \Lambda^{-2} \frac{\partial}{\partial x} V_1(t, x) - \Lambda^{-2} \frac{\partial}{\partial x} V_2(t, x) \right| |f(t, x)| \, dx \\ & \leq \int_{-\infty}^{\infty} |\partial_x \Lambda^{-2}(V_1 - V_2)| |f(t, x)| \, dx \\ & \leq \int_{-\infty}^{\infty} \left| \int_{-\infty}^{\infty} e^{-|x-y|} \operatorname{sign}(x-y) (V_1(t, y) - V_2(t, y)) \, dy \right| |f(t, x)| \, dx \\ & \leq \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-|x-y|} |V_1(t, y) - V_2(t, y)| |f(t, x)| \, dy \, dx \\ & \leq c_0 \int_{-\infty}^{\infty} |V_1 - V_2| \, dy, \end{aligned}$$

in which we have applied the Tonelli theorem. The proof is completed. □

Assume that $\delta(\sigma)$ is a function which is infinitely differentiable on $(-\infty, +\infty)$ such that $\delta(\sigma) \geq 0$, $\delta(\sigma) = 0$ for $|\sigma| \geq 1$ and $\int_{-\infty}^{\infty} \delta(\sigma) \, d\sigma = 1$. For an arbitrary $h > 0$, set $\delta_h(\sigma) = \frac{\delta(h^{-1}\sigma)}{h}$. We conclude that $\delta_h(\sigma)$ is a function in $C^\infty(-\infty, \infty)$ and

$$\begin{cases} \delta_h(\sigma) \geq 0, & \delta_h(\sigma) = 0 \quad \text{if } |\sigma| \geq h, \\ |\delta_h(\sigma)| \leq \frac{c}{h}, & \int_{-\infty}^{\infty} \delta_h(\sigma) \, d\sigma = 1. \end{cases} \tag{20}$$

Suppose that the function $W_1(x)$ is locally integrable in $(-\infty, \infty)$. The approximation function of W_1 is defined by

$$W_1^h(x) = \frac{1}{h} \int_{-\infty}^{\infty} \delta\left(\frac{x-y}{h}\right) W_1(y) dy, \quad h > 0. \tag{21}$$

We call x_0 a Lebesgue point of function $W_1(x)$ if

$$\lim_{h \rightarrow 0} \frac{1}{h} \int_{|x-x_0| \leq h} |W_1(x) - W_1(x_0)| dx = 0.$$

We introduce notation about the concept of a characteristic cone. For any $M > 0$, we define $M > N = \max_{t \in [0, T]} \|V\|_{L^\infty} < \infty$. Let \mathcal{U} designate the cone $\{(t, x) : |x| < M - Nt, 0 \leq t \leq T_0 = \min(T, MN^{-1})\}$. We let S_τ designate the cross section of the cone \mathcal{U} by the plane $t = \tau, \tau \in [0, T_0]$.

Let $K_{r+2\rho} = \{x : |x| \leq r + 2\rho\}$ where $r > 0, \rho > 0$ and $\zeta_T = [0, T] \times \mathbb{R}$. The space of all infinitely differentiable functions $f(t, x)$ with compact support in $[0, T] \times \mathbb{R}$ is denoted by $C_0^\infty(\zeta_T)$.

Lemma 6 ([30]) *Let the function $U(t, x)$ be a bounded and measurable function in some cylinder $\Omega_T = [0, T] \times K_r$. If for some $\rho \in (0, \min[r, T])$ and any number $h \in (0, \rho)$, then the following function*

$$U_h = \frac{1}{h^2} \iiint_{\substack{|t-\tau| \leq h, \rho \leq \frac{t+\tau}{2} \leq T-\rho, \\ |\frac{x-y}{2}| \leq h, |\frac{x+y}{2}| \leq r-\rho}} |U(t, x) - U(\tau, y)| dx dt dy d\tau$$

satisfies $\lim_{h \rightarrow 0} U_h = 0$.

Lemma 7 ([30]) *If the function $G(U)$ satisfies a Lipschitz condition on the interval $[-N, N]$, then the function*

$$G_1(U_1, U_2) = \text{sign}(U_1 - U_2)(G(U_1) - G(U_2))$$

satisfies the Lipschitz condition in U_1 and U_2 , respectively.

Lemma 8 *Suppose that V is the strong solution of problem (4), $f(t, x) \in C_0^\infty(\zeta_T)$ and $f(0, x) = 0$. Then*

$$\iint_{\zeta_T} \left\{ |V - k| f_t + \frac{3}{4} \text{sign}(V - k) [V^2 - k^2] f_x + \text{sign}(V - k) \Lambda^{-2} V_x f \right\} dx dt = 0, \tag{22}$$

where k is an arbitrary constant.

Proof Here we mention that the method to prove this lemma comes from [30]. We assume that $\Phi(V)$ is an arbitrary twice differentiable function on the line $-\infty < V < \infty$. We multiply the first equation of Eq. (4) by the function $\Phi'(V)f(t, x)$, where $f(t, x) \in C_0^\infty(\zeta_T)$. Integrating over ζ_T and integrating by parts (transferring the derivatives with respect to t and x to function f), for any constant k , we have

$$\int_{-\infty}^{\infty} \left[\int_k^V \Phi'(z) z dz \right] f_x dx = - \int_{-\infty}^{\infty} [f \Phi'(V) V V_x] dx$$

and

$$\iint_{\zeta_T} \left\{ \Phi(V)f_t + \frac{3}{2} \left[\int_k^V \Phi'(z)z dz \right] f_x - \Phi'(V)\Lambda^{-2}V_x f \right\} dx dt = 0. \tag{23}$$

Integration by parts yields

$$\begin{aligned} \int_{-\infty}^{\infty} \left[\int_k^V \Phi'(z)z dz \right] f_x dx &= \int_{-\infty}^{\infty} \left[\frac{1}{2} \Phi'(V)V^2 - \frac{1}{2} \Phi'(k)k^2 \right. \\ &\quad \left. - \frac{1}{2} \int_k^V (z^2 - k^2) \Phi''(z) dz \right] f_x dx. \end{aligned} \tag{24}$$

Choosing that $\Phi^h(V)$ is an approximation of the function $|V - k|$, setting $\Phi(V) = \Phi^h(V)$, and making use of the properties of the $\text{sign}(V - k)$, (23), (24) and sending $h \rightarrow 0$, we notice that the last term in (24) becomes zero. Thus, we have

$$\iint_{\zeta_T} \left\{ |V - k|f_t + \frac{3}{4} \text{sign}(V - k)[V^2 - k^2]f_x + \text{sign}(V - k)\Lambda^{-2}V_x f \right\} dx dt = 0. \tag{25}$$

The proof is finished. □

3 Main result

Now, we give the main result of this work.

Theorem 1 *Assume that V_1 and V_2 are two local strong solutions of Eq. (1) with initial data $V_{1,0}(x), V_{2,0}(x) \in L^1(\mathbb{R}) \cap H^s(\mathbb{R})$, $s > \frac{3}{2}$. Let T be the maximal existence time of the solutions. Then*

$$\|V_1(t, \cdot) - V_2(t, \cdot)\|_{L^1(\mathbb{R})} \leq c_0 e^{c_0 t} \int_{-\infty}^{\infty} |V_{10}(x) - V_{20}(x)| dx, \quad t \in [0, T), \tag{26}$$

where $c_0 > 0$ is a constant.

Proof From Lemma 2, we know the existence of local strong solutions for Eq. (1). Let $f(t, x) \in C_0^\infty(\zeta_T)$. Assume $f(t, x) = 0$ outside the cylinder

$$\mathfrak{U} = \{(t, x)\} = [\rho, T - 2\rho] \times K_{r-2\rho}, \quad 0 < 2\rho \leq \min(T, r). \tag{27}$$

We let

$$\xi = f\left(\frac{t+\tau}{2}, \frac{x+y}{2}\right) \delta_h\left(\frac{t-\tau}{2}\right) \delta_h\left(\frac{x-y}{2}\right) = f(\dots)\lambda_h(*), \tag{28}$$

where $(\dots) = (\frac{t+\tau}{2}, \frac{x+y}{2})$ and $(*) = (\frac{t-\tau}{2}, \frac{x-y}{2})$. The function $\delta_h(\sigma)$ is defined in (20). We obtain

$$\xi_t + \xi_\tau = f_t(\dots)\lambda_h(*), \quad \xi_x + \xi_y = f_x(\dots)\lambda_h(*). \tag{29}$$

We apply the technique of Kruzkov’s device of doubling the space variables [30]. In (22), we set $k = V_1(\tau, y)$ and $f = \xi(t, x, \tau, y)$ for a fixed point (τ, y) . We note that $V_1(\tau, y)$ is defined

almost everywhere in $\zeta_T = [0, T] \times \mathbb{R}$. We integrate (22) over ζ_T for variable (τ, y) and then get

$$\begin{aligned} & \iiint\limits_{\zeta_T \times \zeta_T} \left\{ |V_1(t, x) - V_2(\tau, y)| \xi_t \right. \\ & + \frac{3}{4} \operatorname{sign}(V_1(t, x) - V_2(\tau, y)) \left(\frac{V_1^2(t, x)}{2} - \frac{V_2^2(\tau, y)}{2} \right) \xi_x \\ & \left. + \operatorname{sign}(V_1(t, x) - V_2(\tau, y)) \Lambda^{-2} \partial_x (V_1(t, x)) \xi \right\} dt dx dy d\tau = 0. \end{aligned} \tag{30}$$

Similarly, it has

$$\begin{aligned} & \iiint\limits_{\zeta_T \times \zeta_T} \left\{ |V_2(\tau, y) - V_1(t, x)| \xi_\tau \right. \\ & + \frac{3}{4} \operatorname{sign}(V_2(\tau, y) - V_1(t, x)) \left(\frac{V_2^2(\tau, y)}{2} - \frac{V_1^2(t, x)}{2} \right) \xi_y \\ & \left. + \operatorname{sign}(V_2(\tau, y) - V_1(t, x)) \Lambda^{-2} \partial_y (V_2(\tau, y)) \xi \right\} dx dt dy d\tau = 0. \end{aligned} \tag{31}$$

Using (30) and (31), we acquire the inequality

$$\begin{aligned} 0 & \leq \iiint\limits_{\zeta_T \times \zeta_T} \left\{ |V_1(t, x) - V_2(\tau, y)| (\xi_t + \xi_\tau) \right. \\ & + \frac{3}{4} \operatorname{sign}(V_1(t, x) - V_2(\tau, y)) \left(\frac{V_1^2(t, x)}{2} - \frac{V_2^2(\tau, y)}{2} \right) (\xi_x + \xi_y) \left. \right\} dx dt dy d\tau \\ & + \left| \iiint\limits_{\zeta_T \times \zeta_T} \operatorname{sign}(V_1(t, x) - V_2(t, x)) \right. \\ & \quad \left. \times (\Lambda^{-2} \partial_x V_1(t, x) - \Lambda^{-2} \partial_y V_2(\tau, y)) \xi dx dt dy d\tau \right| \\ & = L_1 + L_2 + \left| \iiint\limits_{\zeta_T \times \zeta_T} L_3 dx dt dy d\tau \right|. \end{aligned} \tag{32}$$

We claim that the following inequality

$$\begin{aligned} 0 & \leq \iint\limits_{\zeta_T} \left\{ |V_1(t, x) - V_2(t, x)| f_t \right. \\ & + \frac{3}{4} \operatorname{sign}(V_1(t, x) - V_2(t, x)) \left(\frac{V_1^2(t, x)}{2} - \frac{V_2^2(t, x)}{2} \right) f_x \left. \right\} dx dt \\ & + \left| \iint\limits_{\zeta_T} \operatorname{sign}(V_1(t, x) - V_2(t, x)) \Lambda^{-2} \partial_x [V_1(t, x) - V_2(t, x)] f dx dt \right| \end{aligned} \tag{33}$$

holds.

In fact, for the choice of ξ , the first two terms in the integrand of (32) can be represented in the form

$$D_h = D(t, x, \tau, y, V_1(t, x), V_2(\tau, y)) \lambda_h(*).$$

From Lemma 4, we know $\|V_1\|_{L^\infty} < C_T$ and $\|V_2\|_{L^\infty} < C_T$; from Lemma 7, we know D_h satisfies the Lipschitz condition in V_1 and V_2 , respectively. By the choice of ξ , we derive that $D_h = 0$ outside the region

$$\{(t, x; \tau, y)\} = \left\{ \rho \leq \frac{t + \tau}{2} \leq T - 2\rho, \frac{|t - \tau|}{2} \leq h, \right. \\ \left. \frac{|x + y|}{2} \leq r - 2\rho, \frac{|x - y|}{2} \leq h \right\}. \tag{34}$$

Furthermore, we get

$$\iiint_{\xi_T \times \xi_T} D_h dx dt dy d\tau \\ = \iiint_{\xi_T \times \xi_T} [D(t, x, \tau, y, V_1(t, x), V_2(\tau, y)) \\ - D(t, x, t, x, V_1(t, x), V_2(t, x))] \lambda_h(*) dx dt dy d\tau \\ + \iiint_{\xi_T \times \xi_T} D(t, x, t, x, V_1(t, x), V_2(t, x)) \lambda_h(*) dx dt dy d\tau \\ = B_{11}(h) + B_{12}. \tag{35}$$

Noticing $|\lambda(*)| \leq \frac{c}{h^2}$ and the definition of D_h gives rise to

$$|B_{11}(h)| \\ \leq c \left[h + \frac{1}{h^2} \right. \\ \left. \times \iiint_{\substack{|t-\tau| \leq h, \rho \leq \frac{t+\tau}{2} \leq T-2\rho, \\ |\frac{x-y}{2}| \leq h, |\frac{x+y}{2}| \leq r-\rho}} |V_1(t, x) - V_2(\tau, y)| dx dt dy d\tau \right], \tag{36}$$

where the constant c does not depend on h . Using Lemma 6, we get $B_{11}(h) \rightarrow 0$ as $h \rightarrow 0$. The integral B_{12} does not depend on h . Substituting $t = \alpha$, $\frac{t-\tau}{2} = \beta$, $x = \eta$, $\frac{x-y}{2} = \mu$ and noting the identity

$$\int_{-h}^h \int_{-\infty}^{\infty} \lambda_h(\beta, \mu) d\mu d\beta = 1, \tag{37}$$

we derive that

$$B_{12} = 2^2 \iint_{\xi_T} D_h(\alpha, \eta, \alpha, \eta, V_1(\alpha, \eta), V_2(\alpha, \eta)) \left\{ \int_{-h}^h \int_{-\infty}^{\infty} \lambda_h(\beta, \mu) d\mu d\beta \right\} d\eta d\alpha \\ = 4 \iint_{\xi_T} D_h(t, x, t, x, V_1(t, x), V_2(t, x)) dx dt. \tag{38}$$

Thus, we have

$$\lim_{h \rightarrow 0} \iiint_{\xi_T \times \xi_T} D_h dx dt dy d\tau = 4 \iint_{\xi_T} D(t, x, t, x, V_1(t, x), V_2(t, x)) dx dt. \tag{39}$$

We write

$$\begin{aligned}
 L_3 &= \text{sign}(u(t, x) - v(\tau, y))(\Lambda^{-2}\partial_x V_1(t, x) - \Lambda^{-2}\partial_y V_2(\tau, y))f(\dots)\lambda_h(*) \\
 &= \overline{L}_3(t, x, \tau, y)\lambda_h(*)
 \end{aligned}
 \tag{40}$$

and

$$\begin{aligned}
 \iiint_{\zeta_T \times \zeta_T} L_3 \, dx \, dt \, dy \, d\tau &= \iiint_{\zeta_T \times \zeta_T} [\overline{L}_3(t, x, \tau, y) - \overline{L}_3(t, x, t, x)]\lambda_h(*) \, dx \, dt \, dy \, d\tau \\
 &\quad + \iiint_{\zeta_T \times \zeta_T} \overline{L}_3(t, x, t, x)\lambda_h(*) \, dx \, dt \, dy \, d\tau \\
 &= B_{21}(h) + B_{22},
 \end{aligned}
 \tag{41}$$

from which we have

$$\begin{aligned}
 &|B_{21}(h)| \\
 &\leq c \left(h + \frac{1}{h^2} \iiint_{\substack{|t-\tau| \leq h, \rho \leq \frac{t+\tau}{2} \leq T-\rho, \\ |\frac{x-y}{2}| \leq h, |\frac{x+y}{2}| \leq r-\rho}} |\Lambda^{-2}\partial_x V_1(t, x) \right. \\
 &\quad \left. - \Lambda^{-2}\partial_y V_2(\tau, y)| \, dx \, dt \, dy \, d\tau \right).
 \end{aligned}
 \tag{42}$$

Using Lemmas 5 and 6, we have $B_{21}(h) \rightarrow 0$ as $h \rightarrow 0$. Using (37), we have

$$\begin{aligned}
 B_{22} &= 2^2 \iint_{\zeta_T} \overline{L}_3(\alpha, \eta, \alpha, \eta, V_1(\alpha, \eta), V_2(\alpha, \eta)) \left\{ \int_{\mathbb{R}} \int_{-h}^h \lambda_h(\beta, \mu) \, d\mu \, d\beta \right\} \, d\eta \, d\alpha \\
 &= 4 \iint_{\zeta_T} \overline{L}_3(t, x, t, x, V_1(t, x), V_2(t, x)) \, dx \, dt \\
 &= 4 \iint_{\zeta_T} \text{sign}(V_1(t, x) - V_2(t, x))(\Lambda^{-2}\partial_x [V_1(t, x) - V_2(t, x)])f(t, x) \, dx \, dt.
 \end{aligned}
 \tag{43}$$

From (36), (37), (42), and (43), we prove that inequality (33) holds.

Set

$$X(t) = \int_{-\infty}^{\infty} |V_1(t, x) - V_2(t, x)| \, dx.
 \tag{44}$$

Let

$$\gamma_h = \int_{-\infty}^{\sigma} \delta_h(\tau) \, d\tau \quad (\gamma'_h(\sigma) = \delta_h(\sigma) \geq 0)
 \tag{45}$$

and choose two numbers ρ and $\tau \in (0, T_0), \rho < \tau$. In (33), we choose

$$f = [\gamma_h(t - \rho) - \gamma_h(t - \tau)]\chi(t, x), \quad h < \min(\rho, T_0 - \tau),
 \tag{46}$$

where

$$\chi(t, x) = \chi_\varepsilon(t, x) = 1 - \gamma_\varepsilon(|x| + Nt - M + \varepsilon), \quad \varepsilon > 0.
 \tag{47}$$

We know that the function $\chi(t, x) = 0$ outside the cone \mathcal{U} and $f(t, x) = 0$ outside the set \mathcal{M} . If $(t, x) \in \mathcal{U}$, we get the relations

$$0 = \chi_t + N|\chi_x| \geq \chi_t + N\chi_x. \tag{48}$$

Applying (46)–(48) and (33), we have

$$\begin{aligned} 0 \leq & \int_0^{T_0} \int_{-\infty}^{\infty} \{[\delta_h(t - \rho) - \delta_h(t - \tau)]\chi_\varepsilon |V_1(t, x) - V_2(t, x)|\} dx dt \\ & + \int_0^{T_0} \int_{-\infty}^{\infty} [\gamma_h(t - \rho) - \gamma_h(t - \tau)] |(\Lambda^{-2} \partial_x [V_1(t, x) - V_2(t, x)] \chi(t, x))| dx dt. \end{aligned} \tag{49}$$

Using Lemma 5 and letting $\varepsilon \rightarrow 0$ and $M \rightarrow \infty$, we obtain

$$\begin{aligned} 0 \leq & \int_0^{T_0} \left\{ [\delta_h(t - \rho) - \delta_h(t - \tau)] \int_{-\infty}^{\infty} |V_1(t, x) - V_2(t, x)| dx \right\} dt \\ & + c_0(1 + T_0) \int_0^{T_0} [\gamma_h(t - \rho) - \gamma_h(t - \tau)] \int_{-\infty}^{\infty} |V_1(t, x) - V_2(t, x)| dx dt. \end{aligned} \tag{50}$$

Using the properties of the function $\delta_h(\sigma)$ for $h \leq \min(\rho, T_0 - \rho)$ yields

$$\begin{aligned} \left| \int_0^{T_0} \delta_h(t - \rho) X(t) dt - X(\rho) \right| &= \left| \int_0^{T_0} \delta_h(t - \rho) |X(t) - X(\rho)| dt \right| \\ &\leq c \frac{1}{h} \int_{\rho-h}^{\rho+h} |X(t) - X(\rho)| dt \rightarrow 0 \quad \text{as } h \rightarrow 0, \end{aligned} \tag{51}$$

where c is independent of h . Denoting

$$L(\rho) = \int_0^{T_0} \gamma_h(t - \rho) X(t) dt = \int_0^{T_0} \int_{-\infty}^{t-\rho} \delta_h(\sigma) d\sigma X(t) dt, \tag{52}$$

we get

$$L'(\rho) = - \int_0^{T_0} \delta_h(t - \rho) X(t) dt \rightarrow -X(\rho) \quad \text{as } h \rightarrow 0, \tag{53}$$

and

$$L(\rho) \rightarrow L(0) - \int_0^\rho X(\sigma) d\sigma \quad \text{as } h \rightarrow 0. \tag{54}$$

Similarly, we obtain

$$L(\tau) \rightarrow L(0) - \int_0^\tau X(\sigma) d\sigma \quad \text{as } h \rightarrow 0. \tag{55}$$

It follows from (54) and (55) that

$$L(\rho) - L(\tau) \rightarrow \int_\rho^\tau X(\sigma) d\sigma \quad \text{as } h \rightarrow 0. \tag{56}$$

Send $\rho \rightarrow 0$, $\tau \rightarrow t$, and note that

$$\begin{aligned} |V_1(\rho, x) - V_2(\rho, x)| &\leq |V_1(\rho, x) - V_{10}(x)| \\ &\quad + |V_2(\rho, x) - V_{20}(x)| + |V_{10}(x) - V_{20}(x)|. \end{aligned} \quad (57)$$

Thus, from (50), (51), (56)–(57), we have

$$\begin{aligned} \int_{-\infty}^{\infty} |V_1(t, x) - V_2(t, x)| dx &\leq \int_{-\infty}^{\infty} |V_{10} - V_{20}| dx \\ &\quad + c_0 \int_0^t \int_{-\infty}^{\infty} |V_1(t, x) - V_2(t, x)| dx dt. \end{aligned} \quad (58)$$

Using the Gronwall inequality and (58), we complete the proof. \square

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Authors' contributions

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