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# Ground state solution and multiple solutions to asymptotically linear Schrödinger equations

Xiang-Dong Fang<sup>1,2\*</sup> and Zhi-Qing Han<sup>1\*</sup>

\*Correspondence:

fangxd0401@gmail.com;  
hanzhiq@dlut.edu.cn

<sup>1</sup>School of Mathematical Sciences,  
Dalian University of Technology,  
Dalian, 116024, P.R. China

<sup>2</sup>State Key Laboratory of Structural  
Analysis for Industrial Equipment,  
Department of Engineering  
Mechanics, Dalian University of  
Technology, Dalian, 116024,  
P.R. China

## Abstract

In this paper, we consider the Schrödinger equation  $-\Delta u + V(x)u = f(x, u)$ ,  $x \in \mathbb{R}^N$ , where  $V$  and  $f$  are periodic in  $x_1, \dots, x_N$ , asymptotically linear and satisfies a monotonicity condition. We use the generalized Nehari manifold methods to obtain a ground state solution and infinitely many geometrically distinct solutions when  $f$  is odd in  $u$ .

**Keywords:** Schrödinger equation; ground state solution; multiplicity of solutions; asymptotically linear

## 1 Introduction

We consider the problem

$$-\Delta u + V(x)u = f(x, u), \quad u \in H^1(\mathbb{R}^N), \quad (1.1)$$

where  $f$  and  $V$  are periodic in  $x_1, \dots, x_N$ , asymptotically linear and satisfies a monotonicity condition. In the case that the nonlinear term is asymptotically linear at infinity, there are some results in the literature [1–12] and the references therein, where multiplicity results are considered in [1–3, 9, 10, 12]. As far as we know, there are only a few papers concerned with the existence of infinitely many solutions for the asymptotically linear case when  $f$  and  $V$  are also periodic in  $x_1, \dots, x_N$ ; e.g. see [2]. Except for [5], there seem to be few results on the existence of a ground state solution in the asymptotically linear case. Motivated by [13], this paper is to present a different approach involving the critical point theory with the discreteness property of the Palais-Smale in search for a ground state solution and multiple solutions for the asymptotically linear Schrödinger equations. It should be pointed out that in [2], they cannot make sure the existence of a ground state solution. Our results can be regarded as complements or different attempts of the results in [2, 5].

Setting  $F(x, u) := \int_0^u f(x, s) ds$ , we suppose that  $V$  and  $f$  satisfy the following assumptions:

(V)  $V$  is continuous, 1-periodic in  $x_i$ ,  $1 \leq i \leq N$ , and there exists a constant  $a_0 > 0$  such that  $V(x) \geq a_0$  for all  $x \in \mathbb{R}^N$ .

(f<sub>1</sub>)  $f$  is continuous, 1-periodic in  $x_i$ ,  $1 \leq i \leq N$ .

(f<sub>2</sub>)  $f(x, u) = o(u)$  as  $u \rightarrow 0$ , uniformly in  $x$ .

(f<sub>3</sub>) There is  $q(x) > V(x), \forall x \in \mathbb{R}^N$ , such that  $f(x, u)/u \rightarrow q(x)$ , as  $|u| \rightarrow \infty$ , where  $q$  is continuous, 1-periodic in  $x_i, 1 \leq i \leq N$ .

(f<sub>4</sub>)  $u \mapsto f(x, u)/|u|$  is strictly increasing on  $(-\infty, 0)$  and  $(0, \infty)$ .

Let  $*$  denote the action of  $\mathbb{Z}^N$  on  $H^1(\mathbb{R}^N)$  given by

$$(k * u)(x) := u(x - k), \quad k \in \mathbb{Z}^N. \tag{1.2}$$

It follows from (V) and (f<sub>1</sub>) that if  $u_0$  is a solution of (1.1), then so is  $k * u_0$  for all  $k \in \mathbb{Z}^N$ . Set

$$\mathcal{O}(u_0) := \{k * u_0 : k \in \mathbb{Z}^N\}.$$

$\mathcal{O}(u_0)$  is called *the orbit* of  $u_0$  with respect to the action of  $\mathbb{Z}^N$ , and it is called *a critical orbit* for a functional  $F$  if  $u_0$  is a critical point of  $F$  and  $F$  is  $\mathbb{Z}^N$ -invariant, i.e.,  $F(k * u) = F(u)$  for all  $k \in \mathbb{Z}^N$  and all  $u$  (then of course all points of  $\mathcal{O}(u_0)$  are critical). Two solutions  $u_1, u_2$  of (1.1) are said to be *geometrically distinct* if  $\mathcal{O}(u_1) \neq \mathcal{O}(u_2)$ .

**Theorem 1.1** *Suppose that (V), (f<sub>1</sub>)-(f<sub>4</sub>) are satisfied. Then (1.1) has a ground state solution. In addition, if  $f$  is odd in  $u$ , then (1.1) admits infinitely many pairs  $\pm u$  of geometrically distinct solutions.*

**Notation**  $C, C_1, C_2, \dots$  will denote different positive constants whose exact value is inessential. The usual norm in the Lebesgue space  $L^p(\Omega)$  is denoted by  $\|u\|_{p, \Omega}$ , and by  $\|u\|_p$  if  $\Omega = \mathbb{R}^N$ .  $E$  denotes the Sobolev space  $H^1(\mathbb{R}^N)$  and  $S$  is the unit sphere in  $E$ . It follows from (V) that

$$\|u\| := \left( \int_{\mathbb{R}^N} (|\nabla u|^2 + V(x)u^2) \right)^{1/2}$$

is an equivalent norm in  $E$ . It is more convenient for our purposes than the standard one and will be used henceforth. For a functional  $I$ , as in [14], we put

$$I^d := \{u : I(u) \leq d\}, \quad I_c := \{u : I(u) \geq c\}, \quad I_c^d := \{u : c \leq I(u) \leq d\}.$$

## 2 Preliminary results

Consider the functional

$$I(u) := \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 + \frac{1}{2} \int_{\mathbb{R}^N} V(x)u^2 - \int_{\mathbb{R}^N} F(x, u). \tag{2.1}$$

Then  $I$  is well defined on  $E$  and  $I \in C^1(E, \mathbb{R})$  under the hypotheses (V), (f<sub>1</sub>)-(f<sub>3</sub>). Note also that (V), (f<sub>1</sub>) imply  $I$  is invariant with respect to the action of  $\mathbb{Z}^N$  given by (1.2). It is easy to see that

$$\langle I'(u), v \rangle = \int_{\mathbb{R}^N} \nabla u \nabla v + \int_{\mathbb{R}^N} V(x)uv - \int_{\mathbb{R}^N} f(x, u)v \tag{2.2}$$

for all  $u, v \in E$ .

Let

$$\mathcal{M} := \{u \in E \setminus \{0\} : \langle I'(u), u \rangle = 0\}. \tag{2.3}$$

Recall that  $\mathcal{M}$  is called the Nehari manifold. We do not know whether  $\mathcal{M}$  is of class  $C^1$  under our assumptions and therefore we cannot use minimax theory directly on  $\mathcal{M}$ . To overcome this difficulty, we employ the arguments developed in [13, 15, 16].

We assume that (V) and  $(f_1)$ - $(f_4)$  are satisfied from now on. First,  $(f_2)$  and  $(f_3)$  imply that for each  $\varepsilon > 0$  there is  $C_\varepsilon > 0$  such that

$$|f(x, u)| \leq \varepsilon|u| + C_\varepsilon|u|^{p-1} \quad \text{for all } u \in \mathbb{R}, \tag{2.4}$$

where  $2 < p < 2^*$ ,  $2^* := 2N/(N - 2)$  if  $N \geq 3$ ,  $2^* := \infty$  if  $N = 1$  or  $2$ .

For  $t > 0$ , let

$$h(t) := I(tu) = \frac{t^2}{2} \int_{\mathbb{R}^N} |\nabla u|^2 + V(x)u^2 - \int_{\mathbb{R}^N} F(x, tu).$$

Let

$$\mathcal{E} := \left\{ u \in E : \int_{\mathbb{R}^N} |\nabla u|^2 + V(x)u^2 < \int_{\mathbb{R}^N} q(x)u^2 \right\}.$$

It follows from  $q(x) - V(x) > 0, \forall x \in \mathbb{R}^N$ , that  $\mathcal{E} \neq \emptyset$ .

**Lemma 2.1**  $F(x, u) > 0$  and  $\frac{1}{2}f(x, u)u > F(x, u)$  if  $u \neq 0$ .

This follows immediately from  $(f_2)$  and  $(f_4)$ .

**Lemma 2.2**

- (1) For each  $u \in \mathcal{E}$  there is a unique  $t_u > 0$  such that  $h'(t) > 0$  for  $0 < t < t_u$  and  $h'(t) < 0$  for  $t > t_u$ . Moreover,  $tu \in \mathcal{M}$  if and only if  $t = t_u$ .
- (2) If  $u \notin \mathcal{E}$ , then  $tu \notin \mathcal{M}$  for any  $t > 0$ .

*Proof* (1) For each  $u \in \mathcal{E}$ , due to the Lebesgue dominated convergence theorem and  $(f_2)$ ,  $(f_3)$ , we get

$$\begin{aligned} \lim_{t \rightarrow \infty} \frac{I(tu)}{t^2} &= \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 + V(x)u^2 - \lim_{t \rightarrow \infty} \int_{u \neq 0} \frac{F(x, tu)}{t^2 u^2} u^2 \\ &= \frac{1}{2} \left[ \int_{\mathbb{R}^N} |\nabla u|^2 + V(x)u^2 - \int_{\mathbb{R}^N} q(x)u^2 \right] < 0 \end{aligned}$$

and

$$\begin{aligned} \lim_{t \rightarrow 0} \frac{I(tu)}{t^2} &= \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 + V(x)u^2 - \lim_{t \rightarrow 0} \int_{u \neq 0} \frac{F(x, tu)}{t^2 u^2} u^2 \\ &= \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 + V(x)u^2 > 0. \end{aligned}$$

Hence  $h$  has a positive maximum. The condition  $h'(t) = 0$  is equivalent to

$$\|u\|^2 = \int_{u \neq 0} \frac{f(x, tu)}{tu} u^2.$$

By (f<sub>4</sub>), the first conclusion holds. The second conclusion follows from  $h'(t) = t^{-1} \langle I'(tu), tu \rangle$ .

(2) If  $tu \in \mathcal{M}$  for some  $t > 0$ , then  $\langle I'(tu), u \rangle = 0$  and therefore using (f<sub>3</sub>) and (f<sub>4</sub>)

$$\|u\|^2 = \int_{u \neq 0} \frac{f(x, tu)}{tu} u^2 < \int_{\mathbb{R}^N} q(x) u^2.$$

Hence  $u \in \mathcal{E}$ . □

**Lemma 2.3**

(1) *There exists  $\rho > 0$  such that  $c := \inf_{\mathcal{M}} I \geq \inf_{S_\rho} I > 0$ .*

(2)  *$\|u\|^2 \geq 2c$  for all  $u \in \mathcal{M}$ .*

*Proof* (1) Using (2.4) and the Sobolev inequality we have  $\inf_{S_\rho} I > 0$  if  $\rho$  is small enough. The inequality  $\inf_{\mathcal{M}} I \geq \inf_{S_\rho} I$  is a consequence of Lemma 2.2 since for every  $u \in \mathcal{M}$  there is  $s > 0$  such that  $su \in S_\rho$  (and  $I(t_u u) \geq I(su)$ ).

(2) For  $u \in \mathcal{M}$ , by Lemma 2.1 we have

$$c \leq \frac{1}{2} \|u\|^2 - \int_{\mathbb{R}^N} F(x, u) \leq \frac{1}{2} \|u\|^2. \quad \square$$

We do not know whether  $I$  is coercive on  $\mathcal{M}$ . However, we can prove the following.

**Lemma 2.4** *All Palais-Smale sequences  $(u_n) \subset \mathcal{M}$  are bounded.*

*Proof* Arguing by contradiction, suppose there exists a sequence  $(u_n) \subset \mathcal{M}$  such that  $\|u_n\| \rightarrow \infty$  and  $I(u_n) \leq d$  for some  $d \in [c, \infty)$ . Let  $v_n := u_n / \|u_n\|$ . Then  $v_n \rightharpoonup v$  and  $v_n(x) \rightarrow v(x)$  a.e. in  $\mathbb{R}^N$  after passing to a subsequence. Choose  $y_n \in \mathbb{R}^N$  so that

$$\int_{B_1(y_n)} v_n^2 = \max_{y \in \mathbb{R}^N} \int_{B_1(y)} v_n^2. \quad (2.5)$$

Since  $I$  and  $\mathcal{M}$  are invariant with respect to the action of  $\mathbb{Z}^N$  given by (1.2), we may assume that  $(y_n)$  is bounded in  $\mathbb{R}^N$ . If

$$\int_{B_1(y_n)} v_n^2 \rightarrow 0 \quad \text{as } n \rightarrow \infty, \quad (2.6)$$

then it follows that  $v_n \rightarrow 0$  in  $L^r(\mathbb{R}^N)$  for  $2 < r < 2^*$  by Lions' lemma (cf. [17], Lemma 1.21), and therefore (2.4) implies that  $\int_{\mathbb{R}^N} F(x, sv_n) \rightarrow 0$  for every  $s \in \mathbb{R}$ . Lemma 2.2 implies that

$$d \geq I(u_n) \geq I(sv_n) = \frac{s^2}{2} - \int_{\mathbb{R}^N} F(x, sv_n) \rightarrow \frac{s^2}{2}.$$

Taking a sufficiently large  $s$ , we get a contradiction. Hence (2.6) cannot hold and, since  $v_n \rightarrow v$  in  $L^2_{loc}(\mathbb{R}^N)$ ,  $v \neq 0$ . Hence  $|u_n(x)| \rightarrow \infty$  if  $v(x) \neq 0$ .

Let  $\varphi \in C_0^\infty(\mathbb{R}^N)$ . Then  $\langle I'(u_n), \varphi \rangle \rightarrow 0$  and hence

$$\int_{\mathbb{R}^N} \nabla v_n \nabla \varphi + V(x)v_n \varphi - \int_{\mathbb{R}^N} \frac{f(x, u_n)}{u_n} v_n \varphi \rightarrow 0.$$

By the Lebesgue dominated convergence theorem we therefore have

$$\int_{\mathbb{R}^N} \nabla v \nabla \varphi + V(x)v \varphi = \int_{\mathbb{R}^N} q(x)v \varphi.$$

So  $v \neq 0$  and  $-\Delta v + V(x)v = q(x)v$ . This is impossible because  $-\Delta + V - q$  has only an absolutely continuous spectrum. The proof is complete.  $\square$

**Lemma 2.5** *If  $\mathcal{V}$  is a compact subset of  $\mathcal{E}$ , then there exists  $R > 0$  such that  $I \leq 0$  on  $(\mathbb{R}^+ \mathcal{V}) \setminus B_R(0)$ .*

*Proof* We may assume without loss of generality that  $\mathcal{V} \subset S$ . Arguing by contradiction, suppose there exist  $u_n \in \mathcal{V}$  and  $w_n = t_n u_n$ , where  $u_n \rightarrow u$ ,  $t_n \rightarrow \infty$  and  $I(w_n) \geq 0$ . We have

$$\begin{aligned} 0 &\leq \frac{I(t_n u_n)}{t_n^2} = \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u_n|^2 + V(x)u_n^2 - \int_{u_n \neq 0} \frac{F(x, t_n u_n)}{t_n^2 u_n^2} u_n^2 \\ &\rightarrow \frac{1}{2} \int_{\mathbb{R}^N} |\nabla u|^2 + V(x)u^2 - \frac{1}{2} \int_{\mathbb{R}^N} q(x)u^2 < 0. \end{aligned} \quad \square$$

Let  $U := \mathcal{E} \cap S$  and define the mapping  $m : U \rightarrow \mathcal{M}$  by setting

$$m(w) := t_w w,$$

where  $t_w$  is as in Lemma 2.2.

**Lemma 2.6**  *$U$  is an open subset of  $S$ .*

*Proof* Obvious because  $\mathcal{E}$  is open in  $E$ .  $\square$

**Lemma 2.7** *Assume  $u_n \in U$ ,  $u_n \rightarrow u_0 \in \partial U$ , and  $t_n u_n \in \mathcal{M}$ , then  $I(t_n u_n) \rightarrow \infty$ .*

*Proof* Since  $u_0 \in \partial U$ ,  $\int_{\mathbb{R}^N} |\nabla u_0|^2 + V(x)u_0^2 = \int_{\mathbb{R}^N} q(x)u_0^2$ . Using this, we have

$$\begin{aligned} I(tu_0) &= \frac{1}{2} t^2 \int_{\mathbb{R}^N} |\nabla u_0|^2 + V(x)u_0^2 - t^2 \int_{\mathbb{R}^N} \frac{F(x, tu_0)}{t^2 u_0^2} u_0^2 \\ &= \frac{1}{2} t^2 \int_{\mathbb{R}^N} \left( q(x) - \frac{2F(x, tu_0)}{t^2 u_0^2} \right) u_0^2 \\ &= \frac{1}{2} t^2 \int_{\mathbb{R}^N} \left( q(x) - \frac{f(x, tu_0)}{tu_0} \right) u_0^2 \\ &\quad + \int_{\mathbb{R}^N} \frac{1}{2} f(x, tu_0) tu_0 - F(x, tu_0). \end{aligned}$$

Note that by  $(f_4)$ , we have for large enough  $s$ , there is  $\delta > 0$  such that

$$\frac{1}{2} f(x, s)s - F(x, s) \geq \delta$$

(see [4], Remark 1.5). So  $I(tu_0) \rightarrow \infty$ , as  $t \rightarrow \infty$  (we have used Fatou's lemma). Given  $C > 0$ , choose  $t > 0$  such that  $I(tu_0) \geq C$ . Since  $u_n \rightarrow u_0$ ,

$$\lim_{n \rightarrow \infty} I(t_n u_n) \geq \lim_{n \rightarrow \infty} I(tu_n) = I(tu_0) \geq C$$

and hence  $I(t_n u_n) \rightarrow \infty$ . □

The following lemmas are taken from [13, 15].

Below we shall use the notations

$$K := \{w \in S : \Psi'(w) = 0\},$$

$$K_d := \{w \in K : \Psi(w) = d\}.$$

Since  $f$  is odd in  $u$ , we can choose a subset  $\mathcal{F}$  of  $K$  such that  $\mathcal{F} = -\mathcal{F}$  and each orbit  $\mathcal{O}(w) \subset K$  has a unique representative in  $\mathcal{F}$ . We must show that the set  $\mathcal{F}$  is infinite. Arguing indirectly, assume

$$\mathcal{F} \text{ is a finite set.} \tag{2.7}$$

**Lemma 2.8** *The mapping  $m$  is a homeomorphism between  $U$  and  $\mathcal{M}$ , and the inverse of  $m$  is given by  $m^{-1}(u) = \frac{u}{\|u\|}$ .*

We consider the functional  $\Psi : U \rightarrow \mathbb{R}$  given by

$$\Psi(w) := I(m(w)).$$

**Lemma 2.9**

(1)  $\Psi \in C^1(U, \mathbb{R})$  and

$$\langle \Psi'(w), z \rangle = \|m(w)\| \langle I'(m(w)), z \rangle \quad \text{for all } z \in T_w(U).$$

- (2) If  $(w_n)$  is a Palais-Smale sequence for  $\Psi$ , then  $(m(w_n))$  is a Palais-Smale sequence for  $I$ . If  $(u_n) \subset \mathcal{M}$  is a bounded Palais-Smale sequence for  $I$ , then  $(m^{-1}(u_n))$  is a Palais-Smale sequence for  $\Psi$ .
- (3)  $w$  is a critical point of  $\Psi$  if and only if  $m(w)$  is a nontrivial critical point of  $I$ . Moreover, the corresponding values of  $\Psi$  and  $I$  coincide and  $\inf_U \Psi = \inf_{\mathcal{M}} I$ .
- (4)  $\Psi$  is even (because  $I$  is).

By (2.4), the following lemma also holds.

**Lemma 2.10** *Let  $d \geq c$ . If  $(v_n^1), (v_n^2) \subset \Psi^d$  are two Palais-Smale sequences for  $\Psi$ , then either  $\|v_n^1 - v_n^2\| \rightarrow 0$  as  $n \rightarrow \infty$  or  $\limsup_{n \rightarrow \infty} \|v_n^1 - v_n^2\| \geq \rho(d) > 0$ , where  $\rho(d)$  depends on  $d$  but not on the particular choice of Palais-Smale sequences.*

It is well known that  $\Psi$  admits a pseudo-gradient vector field  $H : U \setminus K \rightarrow TU$  (see e.g. [18], p.86). Moreover, since  $\Psi$  is even, we may assume  $H$  is odd. Let  $\eta : \mathcal{G} \rightarrow U \setminus K$  be the

flow defined by

$$\begin{cases} \frac{d}{dt}\eta(t, w) = -H(\eta(t, w)), \\ \eta(0, w) = w, \end{cases} \tag{2.8}$$

where

$$\mathcal{G} := \{(t, w) : w \in U \setminus K, T^-(w) < t < T^+(w)\}$$

and  $(T^-(w), T^+(w))$  is the maximal existence time for the trajectory  $t \mapsto \eta(t, w)$ . Note that  $\eta$  is odd in  $w$  because  $H$  is and  $t \mapsto \Psi(\eta(t, w))$  is strictly decreasing by the properties of a pseudogradient.

Let  $P \subset U$ ,  $\delta > 0$  and define  $U_\delta(P) := \{w \in U : \text{dist}(w, P) < \delta\}$ .

**Lemma 2.11** *Let  $d \geq c$ . Then for every  $\delta > 0$  there exists  $\varepsilon = \varepsilon(\delta) > 0$  such that*

- (a)  $\Psi_{d-\varepsilon}^{d+\varepsilon} \cap K = K_d$  and
- (b)  $\lim_{t \rightarrow T^+(w)} \Psi(\eta(t, w)) < d - \varepsilon$  for  $w \in \Psi^{d+\varepsilon} \setminus U_\delta(K_d)$ .

Part (a) is an immediate consequence of (2.7) and (b) has been proved in [15]; see Lemmas 2.15 and 2.16 there. The argument is exactly the same except that  $S$  should be replaced by  $U$ . We point out that an important role in the proof of Lemma 2.11 is played by the discreteness property of the Palais-Smale sequences expressed in Lemma 2.10.

### 3 Proof of Theorem 1.1

*Proof of Theorem 1.1* Taking a similar argument as in the proof of Theorem 1.1 in [15], it is easy to get a ground state solution. Noting that by Lemma 2.7 and Ekeland’s variational principle, it can make sure the existence of a  $(PS)_c$  sequence belonging to  $U$ .

For the multiplicity the argument is the same as in Theorem 1.2 (cf. [15]). However, there are details which need to be clarified.

Let  $\eta$  be the flow given by (2.8). If  $T^+(w) < \infty$ , then  $\lim_{t \rightarrow T^+(w)} \eta(t, w)$  exists (cf. [15], Lemma 2.15, Case 1) but unlike the situation in [15], this limit may be a point  $w_0 \in \partial U$ . This possibility is ruled out by Lemma 2.7.

Finally, we need to show that  $U$  contains sets of arbitrarily large genus. Since the spectrum of  $-\Delta + V - q$  in  $L^2(\mathbb{R}^N)$  is absolutely continuous,  $\mathcal{E} \cup \{0\}$  contains an infinite-dimensional subspace  $E_0$ . Hence  $E_0 \cap S \subset U$  and  $\gamma(E_0 \cap S) = \infty$ . □

**Remark 3.1** There is a small gap in the proof of Theorem 1.2 in [13]. Lemma 4.6 as stated there does not exclude the possibility of  $\eta(t, w)$  approaching the boundary as  $t \rightarrow T^+(w)$  (because we only know that  $\eta(t, w)$  goes to infinity). But it is easy to prove that  $I(\eta(t, w))$  goes to infinity as well in [13]. In Lemma 2.7 of this paper we make some proper modifications which also apply to [13] and were proposed by Andrzej Szulkin.

#### Competing interests

The authors declare that they have no competing interests.

#### Authors’ contributions

All authors contributed equally to the writing of this paper. All authors read and approved the final manuscript.

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