

The Hopf–Cole Transformation and Multidimensional Representations of Solutions to Evolution Equations

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Abstract—We consider some new identities and representations of solutions to the second-order partial differential equations connected with the Hopf–Cole transformation.

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In this paper, we present some new identities and representations for solutions to the second-order differential equations that generalize those available [1–3] and go on with the study of the general problem (formulated in [2]) of the constructive construction of partial differential equations from a given class of functions determining the solutions of these equations (see also [1–7]).

Theorems 1–3 of the article are directly related to the Hopf–Cole transformation which makes it possible to obtain some multidimensional representations of the solutions and coefficients of Burgers-type nonlinear equations. Theorem 4 is a new version of the application of a fundamental system of solutions to a second-order linear ordinary differential equation with variable parameter for obtaining a representation of the solution and the coefficients of a second-order multidimensional equation with considerable arbitrariness.

We first give results for a Burgers-type multidimensional equation with parameter p applying the Hopf–Cole transformation and its generalization. As is known [8, 9], the Hopf–Cole transformation consists in that if a function $F(y, t, p) \neq 0$ is a solution to the parabolic equation with parameter p

$$\frac{\partial F}{\partial t} = p \frac{\partial^2 F}{\partial y^2}$$

then the function $w(y, t, p) = -2p \frac{\partial F}{\partial y} / F$ satisfies the nonlinear Burgers equation

$$\frac{\partial w}{\partial t} = p \frac{\partial^2 w}{\partial y^2} - w \frac{\partial w}{\partial y}$$

with the same parameter p . Note that the variable parameter makes it possible to obtain, as $p \rightarrow 0$, solutions to the classical Hopf equation

$$\frac{\partial w}{\partial t} + w \frac{\partial w}{\partial y} = 0,$$

which is important for applications.

Suppose that $a_{ij}(x, t)$, $a_{ij} = a_{ji}$, are continuous functions $i, j = 1, 2, \dots, n$, $x \in D \subset \mathbb{R}^n$, and $t_0 < t < t_1$, where D is a domain in the real Euclidean space \mathbb{R}^n .

A generalization of the Hopf–Cole transformation to the multidimensional case is given by

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Theorem 1. Let $F(y, t, p) \neq 0$ be a solution to the parabolic equation with parameter p

$$\frac{\partial F}{\partial t} = p \frac{\partial^2 F}{\partial y^2}, \quad y \in \mathbb{R}^n, \quad t_0 < t < t_1,$$

and let $v(x, t)$ be a twice continuously differentiable function such that

$$\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \neq 0,$$

which is arbitrary in all other respects. Then

$$w(x, t, p) = -2p \frac{\partial F}{\partial y} \Big/ F \Big|_{y=v(x,t)}$$

satisfies the following equation independent of F :

$$\begin{aligned} \left(\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \right) \frac{\partial w}{\partial t} &= p \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial^2 w}{\partial x_i \partial x_j} - w \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial w}{\partial x_i} \frac{\partial v}{\partial x_j} \\ &+ \left[\frac{\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial v}{\partial t} - p \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial^2 v}{\partial x_i \partial x_j}}{\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j}} \right] \sum_{k,l=1}^n a_{kl}(x, t) \frac{\partial w}{\partial x_k} \frac{\partial v}{\partial x_l}. \end{aligned} \quad (1)$$

The proof is immediate from the following relations obtained by the representation

$$w(y, t, p) = -2p \frac{\partial F}{\partial y} \Big/ F \Big|_{y=v(x,t)}$$

with account taken of the equation $\frac{\partial F}{\partial t} = p \frac{\partial^2 F}{\partial y^2}$ and the equalities

$$\frac{\partial w}{\partial t} = -2p \left(\frac{\partial^2 F}{\partial y^2} \frac{\partial v}{\partial t} + \frac{\partial^2 F}{\partial y \partial t} \right) \Big/ F + 2p \left(\frac{\partial F}{\partial y} \frac{\partial v}{\partial t} + \frac{\partial F}{\partial t} \right) \frac{\partial F}{\partial y} \Big/ F^2,$$

$$\frac{\partial w}{\partial x_i} = \left(-2p \frac{\partial^2 F}{\partial y^2} \Big/ F + 2p \left(\frac{\partial F}{\partial y} \right)^2 \Big/ F^2 \right) \frac{\partial v}{\partial x_i},$$

$$w \frac{\partial w}{\partial x_i} = -\frac{2p}{F} \frac{\partial F}{\partial y} \left(-2p \frac{\partial^2 F}{\partial y^2} \Big/ F + 2p \left(\frac{\partial F}{\partial y} \right)^2 \Big/ F^2 \right) \frac{\partial v}{\partial x_i},$$

$$\begin{aligned} \frac{\partial^2 w}{\partial x_i \partial x_j} &= \frac{\partial^2 v}{\partial x_i \partial x_j} \left(-2p \frac{\partial^2 F}{\partial y^2} \Big/ F + 2p \left(\frac{\partial F}{\partial y} \right)^2 \Big/ F^2 \right) \\ &+ \left(-2p \frac{\partial^3 F}{\partial y^3} \Big/ F + 6p \frac{\partial^2 F}{\partial y^2} \frac{\partial F}{\partial y} \Big/ F^2 - 4p \left(\frac{\partial F}{\partial y} \right)^3 \Big/ F^3 \right) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j}. \end{aligned}$$

For $a_{ij} = \delta_{ij}$, $n = 1$, and $v(x, t) = x$, from equation (1) we obtain the one-dimensional Burgers equation. Assume in what follows that

$$\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \neq 0, \quad x \in D \subset \mathbb{R}^n, \quad t_1 < t < t_2,$$

without further specification. Of interest are the more general solutions w ; namely, if we suppose that $w(x, t, p)$ is the root of the equation

$$g(w(x, t, p), p) = -2p \frac{\partial F}{\partial y} \Big|_{y=v(x,t)},$$

where $g(z, p)$ is a twice continuously differentiable function, $\frac{\partial g}{\partial z}(z, p) \neq 0$, and F is three times continuously differentiable then equation (1) has a substantially nonlinear and more general form which is convenient for applications.

We have

Theorem 2. *Suppose that $g(z, p)$ and $v(x, t)$ are twice continuously differentiable functions, while $F(y, t, p) \neq 0$ is an arbitrary three times continuously differentiable function,*

$$\alpha < p < \beta, \quad z \in \mathbb{R}^1, \quad y \in \mathbb{R}^1, \quad x \in D \subset \mathbb{R}^n, \quad t_1 < t < t_2.$$

Then the function $w(x, t, p)$ that is the root of the equation

$$g(w(x, t, p), p) = -2p \frac{\partial F}{\partial y} \Big|_{y=v(x,t)}$$

satisfies the equation

$$\begin{aligned} \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial w}{\partial t} &= p \frac{g''_{zz}(w, p)}{g'_z(w, p)} \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial w}{\partial x_i} \frac{\partial w}{\partial x_j} \\ &+ p \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial^2 w}{\partial x_i \partial x_j} - g(w, p) \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial w}{\partial x_i} \frac{\partial v}{\partial x_j} \\ &+ \left[\frac{\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial v}{\partial t} - p \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial^2 v}{\partial x_i \partial x_j}}{\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j}} \right] \sum_{k,l=1}^n a_{kl}(x, t) \frac{\partial w}{\partial x_k} \frac{\partial v}{\partial x_l} \\ &- \frac{2p}{g'_z(w, p)} \left[\frac{\partial}{\partial y} \left(\frac{\partial F}{\partial t} - p \frac{\partial^2 F}{\partial y^2} \right) \Big/ F - \frac{\partial F}{\partial y} \left(\frac{\partial F}{\partial t} - p \frac{\partial^2 F}{\partial y^2} \right) \Big/ F^2 \right] \Big|_{y=v(x,t)} \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j}. \end{aligned} \quad (2)$$

Proof. Differentiating $g(w(x, t, p), p) = -2p \frac{\partial F}{\partial y} \Big|_{y=v(x,t)}$, we infer

$$g'_z \frac{\partial w}{\partial t} = -2p \left(\frac{\partial^2 F}{\partial y^2} \Big/ F - \left(\frac{\partial F}{\partial y} \right)^2 \Big/ F^2 \right) \frac{\partial v}{\partial t} - 2p \left(\frac{\partial^2 F}{\partial y \partial t} \Big/ F - \frac{\partial F}{\partial y} \frac{\partial F}{\partial t} \Big/ F^2 \right), \quad (3)$$

$$g'_z \frac{\partial w}{\partial x_i} = -2p \left(\frac{\partial^2 F}{\partial y^2} \Big/ F - \left(\frac{\partial F}{\partial y} \right)^2 \Big/ F^2 \right) \frac{\partial v}{\partial x_i}, \quad (4)$$

$$\begin{aligned} g'_z \frac{\partial^2 w}{\partial x_i \partial x_j} + g''_{zz} \frac{\partial w}{\partial x_i} \frac{\partial w}{\partial x_j} &= -2p \left(\frac{\partial^3 F}{\partial y^3} \Big/ F - 3 \frac{\partial^2 F}{\partial y^2} \frac{\partial F}{\partial y} \Big/ F^2 + 2 \left(\frac{\partial F}{\partial y} \right)^3 \Big/ F^3 \right) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \\ &- 2p \left(\frac{\partial^2 F}{\partial y^2} \Big/ F - \left(\frac{\partial F}{\partial y} \right)^2 \Big/ F^2 \right) \frac{\partial^2 v}{\partial x_i \partial x_j}. \end{aligned} \quad (5)$$

Inserting (3)–(5) into (2), we prove Theorem 2. □

Theorem 2 obviously implies

Theorem 3. Suppose that $g(z, p)$ and $v(x, t)$ are twice continuously differentiable functions, $g'_z(z, p) \neq 0$, and $F(y, t, p) \neq 0$ is a solution to the parabolic equation $\frac{\partial F}{\partial t} = p \frac{\partial^2 F}{\partial y^2}$. Then the function $w(x, t, p)$ that is the root of the equation

$$g(w(x, t, p), p) = -2p \frac{\partial F}{\partial y} \Big|_{y=v(x,t)},$$

satisfies the following equation with the coefficients independent of F :

$$\begin{aligned} \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial w}{\partial t} &= p \frac{g''_{zz}(w, p)}{g'_z(w, p)} \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial w}{\partial x_i} \frac{\partial w}{\partial x_j} \\ &+ p \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial^2 w}{\partial x_i \partial x_j} - g(w, p) \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial w}{\partial x_i} \frac{\partial v}{\partial x_j} \\ &+ \left[\frac{\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial v}{\partial t} - p \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial^2 v}{\partial x_i \partial x_j}}{\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j}} \right] \sum_{k,l=1}^n a_{kl}(x, t) \frac{\partial w}{\partial x_k} \frac{\partial v}{\partial x_l}. \end{aligned}$$

Now, consider the questions of using the fundamental systems of solutions for representing the solutions and coefficients of the second-order multidimensional evolution equations. To this end, consider the second-order linear ordinary differential equation with meromorphic coefficients and variable parameter $p \geq 0$:

$$F''(z) + b(z)F' + (pa(z) + c(z))F(z) = 0. \tag{6}$$

Let $Z_1(z, p), Z_2(z, p)$ be a fundamental system of solutions to (6). Give an example of constructing $Z_1(z, p)$ and $Z_2(z, p)$. Consider the hypergeometric equation

$$z(1-z)F'' + (\gamma - (\alpha + \beta + 1)z)F' - \alpha\beta F(z) = 0, \quad \gamma > 0, \tag{7}$$

with the fundamental system of solutions Z_1 and Z_2 [10]:

$$Z_1(\alpha, \beta, \gamma, z) = \frac{\Gamma(\gamma)}{\Gamma(\alpha)\Gamma(\beta)} \sum_{k=0}^{\infty} \frac{\Gamma(\alpha+k)\Gamma(\beta+k)}{\Gamma(\gamma+k)} \frac{z^k}{k!}, \quad |z| < 1,$$

$$Z_2(\alpha, \beta, \gamma, z) = z^{1-\gamma} Z_1(\alpha - \gamma + 1, \beta - \gamma + 1, 2 - \gamma, z), \quad |z| < 1.$$

If in equation (7) we assume the parameters $\gamma = a_0 > 0$ and $-(\alpha + \beta + 1) = b_0$ to be fixed and the values $-\alpha\beta = p \geq 0$ to be variable then, for $z \neq 0$ and $|z| < 1$, equation (7) can be rewritten as

$$F'' + \frac{a_0 + b_0 z}{z(1-z)} F' + \frac{p}{z(1-z)} F(z) = 0$$

for

$$b(z) = \frac{a_0 + b_0 z}{z(1-z)}, \quad a(z) = \frac{1}{z(1-z)}, \quad c(z) = 0$$

with the explicitly computed $Z_1(z, p)$ and $Z_2(z, p)$.

As above, denote by $a_{ij}(x, t), v(x, t), a_{ij} = a_{ji}, x \in D \subset \mathbb{R}^n$, and $t_1 < t < t_2$ respectively the continuously differentiable functions with the condition

$$\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \neq 0,$$

and designate as $Q(p)$ and $R(p)$ with $p \geq 0$ the integrable functions decreasing at infinity rapidly enough. We have

Theorem 4. *Suppose that the function*

$$w(x, t) = \int_0^\infty [Q(p)Z_1(v(x, t), p) + R(p)Z_2(v(x, t), p)]e^{-pt} dp, \quad x \in D \subset \mathbb{R}^n, \quad t_1 < t < t_2,$$

twice differentiable under integral is well defined. Then it satisfies the equation

$$\begin{aligned} a(v) \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial w}{\partial t} &= \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial^2 w}{\partial x_i \partial x_j} + c(v) \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} w \\ &+ \left[\frac{a(v) \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial v}{\partial t} - \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial^2 v}{\partial x_i \partial x_j}}{\sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j}} + b(v) \right] \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial w}{\partial x_i} \frac{\partial v}{\partial x_j}. \end{aligned} \quad (8)$$

Proof. Let $F(z, p)$ be an arbitrary solution to (6) with parameter $p, 0 \leq p < \infty$, and let $\alpha(p)$ be a suitable function. Consider the function

$$u(x, t) = \int_0^\infty \alpha(p)F(v(x, t), p)e^{-pt} dp$$

and show that it satisfies (8). We have

$$\begin{aligned} \frac{\partial u}{\partial t} &= \int_0^\infty \alpha \left[F' \frac{\partial v}{\partial t} - Fp \right] e^{-pt} dp, & \frac{\partial u}{\partial x_i} &= \int_0^\infty \alpha F' \frac{\partial v}{\partial x_i} e^{-pt} dp, \\ \frac{\partial^2 u}{\partial x_i \partial x_j} &= \int_0^\infty \alpha \left[F'' \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} + F' \frac{\partial^2 v}{\partial x_i \partial x_j} \right] e^{-pt} dp. \end{aligned}$$

Hence,

$$\begin{aligned} a(v) \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial v}{\partial t} &\int_0^\infty \alpha F' \frac{\partial v}{\partial t} e^{-pt} dp - a(v) \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \int_0^\infty \alpha F p e^{-pt} dp \\ &- \left\{ \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \int_0^\infty \alpha F'' e^{-pt} dp + \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial^2 v}{\partial x_i \partial x_j} \int_0^\infty \alpha e^{-pt} dp \right. \\ &\left. + c(v) \sum_{i,j=1}^n a_{ij}(x, t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \int_0^\infty \alpha F(v(x, t), p) e^{-pt} dp \right. \end{aligned}$$

$$\begin{aligned}
& + \left[\frac{a(v) \sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial v}{\partial t} - \sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial^2 v}{\partial x_i \partial x_j}}{\sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j}} + b(v) \right] \\
& \quad \times \sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \int_0^\infty \alpha F' e^{-pt} dp \Big\} \\
& = \sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \int_0^\infty \alpha(p) [F''(z,p) + b(z)F'(z,p) + (pa(z) + c(z))F(z,p)] \Big|_{z=v(x,t)} e^{-pt} dp.
\end{aligned}$$

Choosing $Q(p)$ and $R(p)$ as $\alpha(p)$ and Z_1 and Z_2 as F , we completely prove Theorem 4. \square

In view of the representation of a solution $w(x, t)$ to (6) by the formula of Theorem 4

$$w = \int_0^\infty [Q(p)Z_1(v(x, t), p) + R(p)Z_2(v(x, t), p)]e^{-pt} dp,$$

a possibility opens for applying the theory of second-order linear differential equations with some constant parameters. We confine ourselves to just one example.

Suppose that $b(z) = 0$, $a(z) = 1$, and $c(z) = 0$ in (6); i.e., $F'' + pF = 0$. We have

$$Z_1(z, p) = \sin \sqrt{p} z, \quad Z_2(z, p) = \cos \sqrt{p} z.$$

Assume that

$$R(p) = \sum_{k=0}^\infty R_k \delta(p - k), \quad Q(p) = \sum_{k=0}^\infty Q_k \delta(p - k),$$

R_k and Q_k are constant, $|R_k| \leq 1/k^\alpha$, and $|Q_k| \leq 1/k^\alpha$ with $\alpha > 1$. Then

$$w(x, t) = \sum_{k=0}^\infty [R_k \sin \sqrt{k} v(x, t) + Q_k \cos \sqrt{k} v(x, t)] e^{-kt}, \quad (10)$$

series (10) converges for $t \geq 0$, and equation (8) has the form

$$\begin{aligned}
\sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial w}{\partial t} &= \sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial^2 w}{\partial x_i \partial x_j} \\
& + \left[\frac{\sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} \frac{\partial v}{\partial t} - \sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial^2 v}{\partial x_i \partial x_j}}{\sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j}} \right] \sum_{i,j=1}^n a_{ij}(x,t) \frac{\partial w}{\partial x_i} \frac{\partial v}{\partial x_j}.
\end{aligned}$$

As was observed many times [4–7], the representations of solutions and coefficients found here can be used in the direct and inverse problems of mathematical physics.

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