# On Some Properties of Nash Equilibrium Points in Two-Person Games

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Abstract—In modern game theory, a lot of attention is paid to the concept of Nash equilibrium. The paper is devoted to the study of some properties of the set  $\mathfrak{A}$  of Nash equilibrium points in two-person games. In particular, the character of possible complexity of the set  $\mathfrak{A}$  is investigated, and the stability of the set  $\mathfrak{A}$  under small perturbations of payoff functions is analyzed.

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Denote by  $\mathbb{R}^k$   $(k \ge 1)$  the k-dimensional Euclidean real arithmetic space with standard inner product and with elements identified with ordered sets (columns) of k real numbers. For a nonempty set  $M \subset \mathbb{R}^k$ , denote by comp(M) the set of nonempty compact sets that belong to M. We will use the notions of a set-valued map (s.m.), an upper semicontinuous set-valued map (u.s.c. s.m.), a lower semicontinuous set-valued map, and a continuous set-valued map (see, for example, [1]). If a scalar function h(a) is defined and continuous on a nonempty compact set  $A \subset \mathbb{R}^k$ , then we denote by  $\operatorname{Arg} \max_{a \in A} h(a)$  and  $\operatorname{Arg} \min_{a \in A} h(a)$  the set of maximizers and the set of minimizers of the function h(a) on the set A.

Consider the following two-person (two-player) game (see, for example, [2–6]). Let X and Y be nonempty compact sets in  $\mathbb{R}^p$  and  $\mathbb{R}^q$ , respectively. Put  $Z = X \times Y$ . Suppose that continuous scalar functions f(x, y) and g(x, y) are fixed on Z.

The aim of the first player is to maximize the function f(x, y) by choosing  $x \in X$ , and the aim of the second player is to maximize the function g(x, y) by choosing  $y \in Y$ . So the functions f(x, y) and g(x, y) represent the criteria corresponding to the first and second player, respectively.

**Definition.** A point  $(x_0, y_0) \in Z$  is called a *Nash equilibrium point* if the following two conditions are satisfied simultaneously:

- (1) the inequality  $f(x, y_0) \leq f(x_0, y_0)$  holds for all  $x \in X$ ;
- (2) the inequality  $g(x_0, y) \leq g(x_0, y_0)$  holds for all  $y \in Y$ .

Denote the set of all Nash equilibrium points in the game by  $\mathfrak{A}$ . It is known that in the general case the set  $\mathfrak{A}$  may be empty. There is a well-known general theorem (see, for example, [2, Theorem 7.2.2]) that gives sufficient conditions for  $\mathfrak{A}$  to be nonempty. Below (see Theorem 2), we present other known sufficient conditions under which the set  $\mathfrak{A}$  is nonempty.

To find and study the set  $\mathfrak{A}$ , it is useful to consider two marginal maps

$$\Omega_1(y) = \operatorname*{Arg\,max}_{x \in X} f(x, y), \qquad y \in Y, \tag{1}$$

$$\Omega_2(x) = \operatorname*{Arg\,max}_{y \in Y} g(x, y), \qquad x \in X.$$
(2)

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It is clear that  $\Omega_1(y) \neq \emptyset$  for  $y \in Y$  and  $\Omega_2(x) \neq \emptyset$  for  $x \in X$  and that  $\Omega_1(y) \in \text{comp}(X)$  for  $y \in Y$ and  $\Omega_2(x) \in \text{comp}(Y)$  for  $x \in X$ . Thus, the game under consideration is assigned two s.m.'s

 $\Omega_1: Y \to \operatorname{comp}(X)$  and  $\Omega_2: X \to \operatorname{comp}(Y).$ 

It is easy to show that the s.m.  $\Omega_1$  is u.s.c. on Y and the s.m.  $\Omega_2$  is u.s.c. on X. Next, we put

$$\operatorname{Gr} \Omega_1 = \{ (x, y) \colon x \in \Omega_1(y), \ y \in Y \} \quad \text{and} \quad \operatorname{Gr} \Omega_2 = \{ (x, y) \colon x \in X, \ y \in \Omega_2(x) \}.$$

Using the fact that the s.m.  $\Omega_1(y)$  is u.s.c. on Y and s.m.  $\Omega_2(x)$  is u.s.c. on X, one can easily check that the sets  $\operatorname{Gr} \Omega_1$  and  $\operatorname{Gr} \Omega_2$  are compact.

Let  $\mathfrak{B} = \operatorname{Gr} \Omega_1 \cap \operatorname{Gr} \Omega_2$ . The following theorem is well-known in game theory.

**Theorem 1.** The equality  $\mathfrak{A} = \mathfrak{B}$  holds.

The following lemma may be useful in studying the properties of the s.m.'s  $\Omega_1(y)$  and  $\Omega_2(x)$ .

**Lemma 1.** Suppose that  $P \subset \mathbb{R}^k$   $(k \ge 1)$  and  $Q \subset \mathbb{R}^l$   $(l \ge 1)$  are nonempty compact sets and  $\Omega: P \to \operatorname{comp}(Q)$  is an s.m. If  $\Omega$  is u.s.c. at a point  $\xi \in P$  and  $\Omega(\xi)$  is a one-point set, then the s.m.  $\Omega$  is continuous at the point  $\xi$ .

**Proof.** It suffices to prove the lower semicontinuity of the s.m.  $\Omega$  at the point  $\xi$ . This fact is proved by contradiction.  $\Box$ 

**Remark 1.** Note that if the hypothesis of Lemma 1 holds for all  $\xi \in P$ , then the single-valued function  $\omega(\xi) = \Omega(\xi)$  is continuous (in the ordinary sense) on P.

Using this remark and the well-known theorem of Brouwer (see, for example, [7]), we arrive at the following well-known theorem (see, for example, [6]).

**Theorem 2.** Suppose that the marginal maps  $\Omega_1(y)$  and  $\Omega_2(x)$  (see (1) and (2)) in the game are single-valued for all  $y \in Y$  and  $x \in X$ , respectively, and the compact sets X and Y are convex. Then the set  $\mathfrak{A}$  in the game is nonempty.

**Remark 2.** This theorem is interesting because it imposes no explicit requirements on the concavity of the function f(x, y) with respect to  $x \in X$  for  $y \in Y$  and on the concavity of the function g(x, y) with respect to  $y \in Y$  for  $x \in X$  (here X and Y are convex compact sets), as is usually done in the literature (see, for example, [2, Theorem 7.2.2]).

In connection with Theorem 1, a question arises as to what extent the compact set  $\mathfrak{A}$  may be arbitrary, provided that  $\mathfrak{A} \neq \emptyset$ , as a function of the pair of continuous payoff functions f and g defined on the compact set  $Z = X \times Y$ .

**Theorem 3.** In the nonempty compact set Z, we fix an arbitrary nonempty compact subset  $M_1$  with the following property: for every  $y \in Y$ , the intersection of the set  $\bigcup_{x \in X} \{(x, y)\}$  with  $M_1$  is nonempty. Then there exists a continuous scalar function f(x, y) on Z such that  $\operatorname{Gr} \Omega_1 = M_1$ .

**Proof.** According to the recipe from [7, Ch. 2, Sect. 3, Theorem 1], one can explicitly construct a smooth scalar function F(x, y) on  $\mathbb{R}^p \times \mathbb{R}^q$  such that F(x, y) = 0 for  $(x, y) \in M_1$  and F(x, y) < 0for  $(x, y) \notin M_1$ . As the sought function f(x, y), one can take the restriction of the function F(x, y)to Z.  $\Box$ 

The next theorem can be proved in a similar way.

**Theorem 4.** In the nonempty compact set Z, let  $M_2$  be an arbitrary fixed compact subset with the following property: for every  $x \in X$ , the intersection of the set  $\bigcup_{y \in Y} \{(x, y)\}$  with  $M_2$  is nonempty. Then there exists a continuous scalar function g(x, y) on Z such that  $\operatorname{Gr} \Omega_2 = M_2$ .

The following theorem is related to Theorems 3 and 4.

**Theorem 5.** Suppose that an arbitrary nonempty compact subset M is fixed in the nonempty compact set Z. Then there exist continuous scalar functions f(x,y) and g(x,y) on Z such that  $\mathfrak{A} = M$ .

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**Proof.** Fix a point  $(\xi, \eta) \in M$ , where  $\xi \in X$  and  $\eta \in Y$ . Consider the sets  $\mathfrak{M}_1 = M \cup L_1$  and  $\mathfrak{M}_2 = M \cup L_2$  with

$$L_1 = \{(x, y) \in Z : x = \xi, y \in Y\}$$
 and  $L_2 = \{(x, y) \in Z : x \in X, y = \eta\}$ 

One can easily prove that  $\mathfrak{M}_1$  and  $\mathfrak{M}_2$  are compact sets; moreover,

$$\mathfrak{M}_1 \cap \mathfrak{M}_2 = M. \tag{3}$$

According to Theorem 3, for the set  $\mathfrak{M}_1$  one can construct a continuous function f(x, y) such that

$$\operatorname{Gr} \Omega_1 = \mathfrak{M}_1. \tag{4}$$

According to Theorem 4, for the set  $\mathfrak{M}_2$  one can construct a continuous function g(x, y) such that

$$\operatorname{Gr}\Omega_2 = \mathfrak{M}_2. \tag{5}$$

Taking into account relations (3)–(5) and using Theorem 1, we find that the equality  $\mathfrak{A} = M$  is satisfied for the functions f(x, y) and g(x, y).  $\Box$ 

Now, we examine separately the case of a two-person zero-sum game with

$$g(x,y) = -f(x,y) \quad \text{for} \quad (x,y) \in Z.$$
(6)

Here we are interested in the saddle points of the game. It is known that when the functions f(x, y) and g(x, y) are continuous on the compact set  $Z = X \times Y$  and condition (6) is satisfied, the concept of a Nash equilibrium point is equivalent to the concept of a saddle point. Therefore, the equality  $\mathfrak{A}_1 = \mathfrak{A}$  holds, where  $\mathfrak{A}_1$  is the set of saddle points in the game. The specific feature of a zero-sum game is that if  $\mathfrak{A}_1$  is nonempty, it is a rectangular set, i.e.,  $\mathfrak{A}_1 = K_1 \times K_2$ , where  $K_1$  is a nonempty compact set in X and  $K_2$  is a nonempty compact set in Y; moreover,

$$K_1 = \operatorname*{Arg\,max}_{x \in X} \left( \min_{y \in Y} f(x, y) \right) \quad \text{and} \quad K_2 = \operatorname*{Arg\,min}_{y \in Y} \left( \max_{x \in X} f(x, y) \right).$$

**Theorem 6.** Suppose that an arbitrary nonempty rectangular compact subset M in the nonempty compact set Z is fixed; i.e.,  $M = M_1 \times M_2$ , where  $M_1$  is a nonempty compact subset of Xand  $M_2$  is a nonempty compact subset of Y. Then there exists a continuous scalar function f(x, y)on Z such that the equality  $\mathfrak{A}_1 = M$  holds for the corresponding zero-sum game (see (6)).

**Proof.** Using the arguments from [7, Ch. 2, Sect. 3, Theorem 1], we construct a continuous function  $f_1(x)$  on X such that

$$\operatorname*{Arg\,max}_{x \in X} f_1 = M_1$$

Using the same arguments, we construct a continuous function  $f_2(y)$  on Y such that

$$\underset{y \in Y}{\operatorname{Arg\,min}} f_2 = M_2.$$

After constructing the functions  $f_1(x)$  and  $f_2(y)$ , one can take the function  $f(x,y) = f_1(x) + f_2(y)$ as the sought function f(x,y).  $\Box$ 

To study further the set  $\mathfrak{A}$ , consider the function

$$\Delta(p,q) = \left( f(x,\widetilde{y}) - f(\widetilde{x},\widetilde{y}) \right) + \left( g(\widetilde{x},y) - g(\widetilde{x},\widetilde{y}) \right),\tag{7}$$

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where  $x, \tilde{x} \in X, y, \tilde{y} \in Y, p = (x, y)$ , and  $q = (\tilde{x}, \tilde{y})$ , and introduce the function

$$L(q) = \max_{p \in Z} \Delta(p, q).$$
(8)

Note that under the assumptions made above, the function L(q) is continuous on Z. It is easy to show (see (7)) that

$$L(q) \ge 0 \qquad \forall q \in Z. \tag{9}$$

Note that functions of the type (8) have been considered in some previous studies in N-person game theory (see, for example, [8]).

Lemma 2. Let

$$\min_{q \in Z} L(q) = 0. \tag{10}$$

Then  $\mathfrak{A} \neq \emptyset$ .

**Proof.** Suppose that a point  $q_0 = (x_0, y_0)$  in Z is such that (see (10))

 $L(q_0) = 0.$ 

Then (see (7), (8), (10))

$$(f(x, y_0) - f(x_0, y_0)) + (g(x_0, y) - g(x_0, y_0)) \le 0 \qquad \forall (x, y) \in \mathbb{Z}.$$

Substituting successively  $y = y_0$  and  $x = x_0$  into this inequality, we obtain

$$f(x, y_0) \le f(x_0, y_0) \quad \forall x \in X, \qquad g(x_0, y) \le g(x_0, y_0) \quad \forall y \in Y,$$
 (11)

i.e.,  $q_0 \in \mathfrak{A}$ .  $\Box$ 

**Lemma 3.** If  $\mathfrak{A} \neq \emptyset$ , then relation (10) is satisfied.

**Proof.** Let  $q_0 = (x_0, y_0) \in \mathfrak{A}$ . Then relations (11) hold. Hence (see (7)),

$$\Delta(p, q_0) \le 0 \qquad \forall p \in Z. \tag{12}$$

Relations (8), (9), and (12) imply equality (10).  $\Box$ 

The following lemma is a corollary to Lemmas 2 and 3.

**Lemma 4.** 1. The set  $\mathfrak{A}$  coincides with the set of points  $q \in Z$  that (see (8)) satisfy the equality L(q) = 0.

2. The set  $\mathfrak{A}$  coincides with the set of points  $\operatorname{Arg\,min}_{q\in \mathbb{Z}} L(q)$  provided that relation (10) is valid.

3. The set  $\mathfrak{A}$  is empty if and only if  $\min_{q \in \mathbb{Z}} L(q) > 0$ .

Lemma 4 opens up certain possibilities for calculating the points of the set  $\mathfrak{A}$  on the basis of the calculation of the roots of the function L(q) (see (8)) on the set Z (see [9]). Note that in view of formulas (7) and (8), the analytic properties of L(q) may deteriorate compared with the analytic properties of the function  $\Delta(p,q)$  due to the presence of a maximum-type operation. Note also that there are a fairly large number of publications devoted to the numerical aspects of calculating the points of the set  $\mathfrak{A}$ . We mention [10] among these publications.

In conclusion, we examine how the set  $\mathfrak{A}$  depends on perturbations of the functions f(x, y) and g(x, y). To this end, we consider a two-person game with payoff functions  $f(x, y, \varepsilon)$  and  $g(x, y, \varepsilon)$  that are defined and continuous on  $X \times Y \times \mathcal{E}$ , where the sets  $X \subset \mathbb{R}^p$ ,  $Y \subset \mathbb{R}^q$ , and  $\mathcal{E} \subset \mathbb{R}^r$  are

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nonempty and compact and the point 0 is an interior point of the set  $\mathcal{E}$ . For a fixed  $\varepsilon \in \mathcal{E}$ , we have an ordinary two-player game considered above. To every such game, there corresponds a set of Nash equilibrium points  $\mathfrak{A}(\varepsilon)$ . By analogy with formulas (7) and (8), we define functions  $\Delta(p, q, \varepsilon)$  and  $L(q, \varepsilon)$ . These functions are continuous on  $Z \times Z \times \mathcal{E}$  and  $Z \times \mathcal{E}$ , respectively. Suppose that  $\min_{q \in \mathbb{Z}} L(q, 0) > 0$ , i.e.,  $\mathfrak{A}(0) = \emptyset$ . Then, for sufficiently small  $|\varepsilon|$ , we have  $\min_{q \in \mathbb{Z}} L(q, \varepsilon) > 0$ ; i.e.,  $\mathfrak{A}(\varepsilon) = \emptyset$  for such  $\varepsilon$ . Now, suppose that  $\mathfrak{A}(\varepsilon) \neq \emptyset$  in a neighborhood  $V \subset \mathcal{E} \subset \mathbb{R}^r$  of the point  $0 \in \mathcal{E} \subset \mathbb{R}^r$ . Then, according to the aforesaid, in this neighborhood V the set  $\mathfrak{A}(\varepsilon)$  consists of those points  $q \in \mathbb{Z}$  for which

$$L(q,\varepsilon) = 0$$

Hence, the s.m.  $\mathfrak{A}(\varepsilon)$  is u.s.c. at the point  $\varepsilon = 0$ . If  $\mathfrak{A}(0)$  is a one-point set, then (see Lemma 1) the s.m.  $\mathfrak{A}(\varepsilon)$  is continuous at the point  $\varepsilon = 0$ . Thus, in this case, the set  $\mathfrak{A}(0)$  is stable under small perturbations of the payoff functions.

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