

ON MINIMAL ISOTROPIC TORI IN $\mathbb{C}P^3$

M. S. Yermentay

UDC 514.763.47

Abstract: We show that one of the classes of minimal tori in $\mathbb{C}P^3$ is determined by the smooth periodic solutions to the sinh-Gordon equation. We also construct examples of such surfaces in terms of Jacobi elliptic functions.

DOI: 10.1134/S0037446618030047

Keywords: minimal isotropic torus, sinh-Gordon equation

1. Introduction

Isotropic submanifolds in a symplectic space are a natural generalization of Lagrange submanifolds. A surface $\Sigma \subset \mathbb{C}P^3$ is called *isotropic* if $\omega|_{\Sigma} = 0$, where ω is the Fubini–Study symplectic form on $\mathbb{C}P^3$. We will define isotropic surfaces as the image of the composition $\mathcal{H} \circ r : \mathbb{R}^2 \rightarrow \mathbb{C}P^3$, where $r : \mathbb{R}^2 \rightarrow S^7 \subset \mathbb{C}^4$ is the horizontal mapping into the unit sphere, and $\mathcal{H} : S^7 \rightarrow \mathbb{C}P^3$ is the Hopf projection. Assume moreover that, in the coordinates (x, y) , the metric on the surface has the conformal form $ds^2 = 2e^{v(x,y)}(dx^2 + dy^2)$. The isotropy of Σ , the horizontality of the metric r , and the conformality of the metric imply that

$$\langle r_x, r \rangle = \langle r_y, r \rangle = \langle r_x, r_y \rangle = 0, \quad \langle r_x, r_x \rangle = \langle r_y, r_y \rangle = 2e^{v(x,y)};$$

moreover, $|r| = 1$, where $\langle \cdot, \cdot \rangle$ is the Hermitian product in \mathbb{C}^4 . Thus, the unit vectors $r, \frac{r_x}{|r_x|}, \frac{r_y}{|r_y|} \in \mathbb{C}^4$ are pairwise orthogonal in the Hermitian sense. Complement this collection of vectors by the normal vector $n(x, y)$ to the Hermitian frame

$$R = \begin{pmatrix} r \\ \frac{r_x}{|r_x|} \\ \frac{r_y}{|r_y|} \\ n \end{pmatrix} \in SU(4).$$

Introduce matrices $A, B \in su(4)$ such that

$$R_x = AR, \quad R_y = BR. \tag{1}$$

In what follows, we assume that the image of $\mathcal{H} \circ r$ is a minimal immersed torus; i.e., $\mathcal{H} \circ r$ is a doubly periodic mapping with some lattice of periods.

Lemma 1. *The matrices $A, B \in su(4)$ have the form*

$$A = \begin{pmatrix} 0 & \sqrt{2}e^{\frac{v}{2}} & 0 & 0 \\ -\sqrt{2}e^{\frac{v}{2}} & \frac{k_1}{2}ie^{-v} & \frac{1}{2}(ik_2e^{-v} - v_y) & e^{-\frac{v}{2}}(V_1 + iV_3) \\ 0 & \frac{1}{2}(ik_2e^{-v} + v_y) & -\frac{k_1}{2}ie^{-v} & e^{-\frac{v}{2}}(V_2 + iV_4) \\ 0 & -e^{-\frac{v}{2}}(V_1 - iV_3) & -e^{-\frac{v}{2}}(V_2 - iV_4) & 0 \end{pmatrix},$$

$$B = \begin{pmatrix} 0 & 0 & \sqrt{2}e^{\frac{v}{2}} & 0 \\ 0 & \frac{k_2}{2}ie^{-v} & \frac{1}{2}(-ik_1e^{-v} + v_x) & e^{-\frac{v}{2}}(V_2 + iV_4) \\ -\sqrt{2}e^{\frac{v}{2}} & -\frac{1}{2}(ik_1e^{-v} + v_x) & -\frac{k_2}{2}ie^{-v} & -e^{-\frac{v}{2}}(V_1 + iV_3) \\ 0 & -e^{-\frac{v}{2}}(V_2 - iV_4) & e^{-\frac{v}{2}}(V_1 - iV_3) & 0 \end{pmatrix},$$

The author was supported by the Russian Science Foundation (Grant 14–11–00441).

$k_1, k_2 \in \mathbb{R}$, $V_i(x, y)$ are some real doubly periodic functions. The compatibility condition

$$A_y - B_x + [A, B] = 0 \quad (2)$$

for (1) is equivalent to the system of equations:

$$-V_2V_3 + V_1V_4 = 0, \quad (3)$$

$$4e^v - e^{-2v}(k_1^2 + k_2^2) - 2e^{-v}(V_1^2 + V_2^2 + V_3^2 + V_4^2) + \Delta v = 0, \quad (4)$$

$$k_2V_3 - k_1V_4 + e^v(V_{1y} - V_{2x}) = 0, \quad (5)$$

$$-k_2V_1 + k_1V_2 + e^v(V_{3y} - V_{4x}) = 0, \quad (6)$$

$$-k_1V_3 - k_2V_4 + e^v(V_{2y} + V_{1x}) = 0, \quad (7)$$

$$k_1V_1 + k_2V_2 + e^v(V_{4y} + V_{3x}) = 0. \quad (8)$$

We can distinguish two natural cases when this system amounts to a single equation. If $V_i = 0$ then $v(x, y)$ satisfies the Tzitzeica equation

$$\Delta v + 4e^{v(x,y)} - (k_1^2 + k_2^2)e^{-2v(x,y)} = 0.$$

In this case, the vector n is constant and the surface Σ lies in some complex projective plane $\mathbb{C}P^2 \subset \mathbb{C}P^3$. Thus, Σ is a Lagrange surface in $\mathbb{C}P^2$. This case was studied particularly in many works (see, for example, [1–8]), and we will not address it here.

The second natural case is distinguished by the conditions

$$k_1 = k_2 = 0, \quad V_i = p_i = \text{const}, \quad i = 1, 2, \quad p_3 = p_4 = 0. \quad (9)$$

Then $v(x, y)$ satisfies the sinh-Gordon equation

$$\Delta v + 4e^{v(x,y)} - 2(p_1^2 + p_2^2)e^{-v(x,y)} = 0. \quad (10)$$

Equation (10) appears, for example, in the theory of surfaces of constant mean curvature in \mathbb{R}^3 [9] and also in mathematical physics (see, for example, [10]). Smooth periodic and quasiperiodic solutions to (10) were studied in [11].

Give an example of an isotropic minimal surface corresponding to (10). Let $c > 0$ and p_1 and p_2 be real numbers such that $c^2 > 2(p_1^2 + p_2^2)$, $p_1 \neq 0$. Put

$$\gamma_1 = \frac{c + \sqrt{c^2 - 2(p_1^2 + p_2^2)}}{2}, \quad \gamma_2 = \frac{c - \sqrt{c^2 - 2(p_1^2 + p_2^2)}}{2}.$$

Let $\pm\alpha_1$ and $\pm\alpha_2$ be the roots of the equation

$$\frac{\alpha^4}{2} - c\alpha^2 + p_2^2 = 0, \quad (11)$$

where $\alpha_1 > \alpha_2 > 0$.

We have

Theorem 1. *The mapping $\mathcal{H} \circ r$, where*

$$r = (F_1(x)e^{i(G_1(x)+\alpha_1y)}, F_1(x)e^{-i(G_1(x)+\alpha_1y)}, F_2(x)e^{i(G_2(x)+\alpha_2y)}, F_2(x)e^{-i(G_2(x)+\alpha_2y)}), \quad (12)$$

defines a minimal isotropic immersion of \mathbb{R}^2 in $\mathbb{C}P^3$. Here

$$F_1 = \sqrt{\frac{2e^{v(x)} - \alpha_2^2}{2(\alpha_1^2 - \alpha_2^2)}}, \quad F_2 = \sqrt{\frac{\alpha_1^2 - 2e^{v(x)}}{2(\alpha_1^2 - \alpha_2^2)}}, \quad (13)$$

$$G_1 = 2p_1p_2 \int_0^x \frac{dz}{\alpha_1(\alpha_2^2 - 2e^{v(z)})}, \quad G_2 = 2p_1p_2 \int_0^x \frac{dz}{\alpha_2(\alpha_1^2 - 2e^{v(z)})}, \quad (14)$$

$$e^{v(x)} = \gamma_1 - (\gamma_1 - \gamma_2)sn^2\left(\sqrt{2\gamma_1}x, \sqrt{\frac{\gamma_1 - \gamma_2}{\gamma_1}}\right),$$

$sn(z, k)$ is a Jacobi elliptic function.

Note that $\mathcal{H} \circ r : \mathbb{R}^2 \rightarrow \mathbb{C}P^3$ is periodic in y for $\frac{\alpha_2}{\alpha_1} \in \mathbb{Q}$. Let τ be the period of $v(x)$. Then $\mathcal{H} \circ r$ is periodic in x if $G_1(\tau), G_2(\tau) \in \pi\mathbb{Q}$.

2. Proofs of Lemma 1 and Theorem 1

Equations (1) and the condition $A, B \in su(4)$ imply that A and B look as

$$A = \begin{pmatrix} 0 & \sqrt{2}e^{\frac{v}{2}} & 0 & 0 \\ -\sqrt{2}e^{\frac{v}{2}} & if_1 & a_1 + ib_1 & a_2 + ib_2 \\ 0 & -a_1 + ib_1 & if_2 & a_3 + ib_3 \\ 0 & -a_2 + ib_2 & -a_3 + ib_3 & -i(f_1 + f_2) \end{pmatrix},$$

$$B = \begin{pmatrix} 0 & 0 & \sqrt{2}e^{\frac{v}{2}} & 0 \\ 0 & ig_1 & c_1 + id_1 & c_2 + id_2 \\ -\sqrt{2}e^{\frac{v}{2}} & -c_1 + id_1 & ig_2 & c_3 + id_3 \\ 0 & -c_2 + id_2 & -c_3 + id_3 & -i(g_1 + g_2) \end{pmatrix},$$

where $a_i(x, y)$, $b_i(x, y)$, and $c_i(x, y)$ are real functions. Furthermore, from (1) we obtain the equalities

$$r_{xx} = \sqrt{2}e^{\frac{v}{2}}(a_2 + ib_2)n + \left(\frac{v_x}{2} + if_1\right)r_x + (a_1 + ib_1)r_y - 2e^v r,$$

$$r_{yy} = \sqrt{2}e^{\frac{v}{2}}(c_3 + id_3)n + (id_1 - c_1)r_x + \left(\frac{v_y}{2} + ig_2\right)r_y - 2e^v r,$$

$$r_{xy} = \sqrt{2}e^{\frac{v}{2}}(a_3 + ib_3)n + (-a_1 + ib_1)r_x + \left(\frac{v_x}{2} + if_2\right)r_y,$$

$$r_{xy} = \sqrt{2}e^{\frac{v}{2}}(c_2 + id_2)n + \left(\frac{v_y}{2} + ig_1\right)r_x + (c_1 + id_1)r_y.$$

Consequently, $c_2 = a_3$, $d_2 = b_3$, $b_1 = g_1$, $a_1 = -\frac{v_y}{2}$, $c_1 = \frac{v_x}{2}$, $d_1 = f_2$,

$$\Delta r = i(f_1 + f_2)r_x + i(g_1 + g_2)r_y - 4e^v r + \sqrt{2}e^{\frac{v}{2}}(a_2 + c_3 + i(b_2 + d_3))n. \quad (15)$$

Since the image of $\mathcal{H} \circ r : \mathbb{R}^2 \rightarrow \mathbb{C}P^3$ is a minimal surface, its horizontal lifting $r : \mathbb{R}^2 \rightarrow S^7$ is minimal in S^7 . The mapping r defines a minimal surface if and only if $\Delta_{LB}r = -2r$, where Δ_{LB} is the Laplace–Beltrami operator for the induced metric $ds^2 = 2e^{v(x,y)}(dx^2 + dy^2)$ on the surface (see, for example, [12]) or, equivalently, $\Delta r = -4e^v r$. Consequently, from (15) we obtain $f_2 = -f_1$, $g_2 = -g_1$, $c_3 = -a_2$, and $d_3 = -b_2$. Thus, A and B take the form

$$A = \begin{pmatrix} 0 & \sqrt{2}e^{\frac{v}{2}} & 0 & 0 \\ -\sqrt{2}e^{\frac{v}{2}} & if_1 & ig_1 - \frac{v_y}{2} & a_2 + ib_2 \\ 0 & ig_1 + \frac{v_y}{2} & -if_1 & a_3 + ib_3 \\ 0 & -a_2 + ib_2 & -a_3 + ib_3 & 0 \end{pmatrix},$$

$$B = \begin{pmatrix} 0 & 0 & \sqrt{2}e^{\frac{1}{2}v} & 0 \\ 0 & ig_1 & -if_1 + \frac{v_x}{2} & a_3 + ib_3 \\ -\sqrt{2}e^{\frac{v}{2}} & -f_1 - \frac{v_x}{2} & -ig_1 & -a_2 - ib_2 \\ 0 & -a_3 + ib_3 & a_2 - ib_2 & 0 \end{pmatrix}.$$

Relation (2) implies the equations

$$f_{1y} + f_1v_y - g_{1x} - g_1v_x = 0, \quad g_{1y} + g_1v_y + f_{1x} + f_1v_x = 0,$$

which are equivalent to

$$\partial_y(f_1e^v) - \partial_x(g_1e^v) = 0, \quad \partial_y(g_1e^v) + \partial_x(f_1e^v) = 0.$$

Since f_1, g_1 , and v are doubly periodic, we have

$$f_1 = \frac{k_1}{2}e^{-v}, \quad g_1 = \frac{k_2}{2}e^{-v}, \quad k_1, k_2 \in \mathbb{R}.$$

Introduce the notations:

$$V_1 = a_2e^{\frac{v}{2}}, \quad V_2 = a_3e^{\frac{v}{2}}, \quad V_3 = b_2e^{\frac{v}{2}}, \quad V_4 = b_3e^{\frac{v}{2}}.$$

Then the matrices A and B take the form of Lemma 1, and (2) is equivalent to (3)–(8). Lemma 1 is proved.

Turn to proving Theorem 1. We will assume that (9) and (10) are fulfilled, the function v depends only on x , and put $p_3 = p_4 = 0$. It follows from (10) that v satisfies the equation

$$(v')^2 = -8e^v - 4e^{-v}(p_1^2 + p_2^2) + 8c, \quad (16)$$

where c is a real constant. We will search for r_j and n_j in the form

$$r_j = R_j(x)e^{i\beta_j y}, \quad n_j = N_j(x)e^{i\beta_j y},$$

where $R_j(x)$ and $N_j(x)$ are complex-valued functions, $\beta_j \in \mathbb{R}$. Relation (1) implies the equalities

$$-4p_1N_j + \sqrt{2}(2R_j'' + 4e^vR_j - R_j'v') = 0, \quad (17)$$

$$4p_2N_j - \beta_j i\sqrt{2}(2R_j' - R_jv') = 0, \quad (18)$$

$$\sqrt{2}ip_2\beta_jR_j + 2e^vN_j' + \sqrt{2}p_1R_j' = 0, \quad (19)$$

$$4p_1N_j + \sqrt{2}(R_j(4e^v - 2\beta_j^2) + R_j'v') = 0, \quad (20)$$

$$2ie^v\beta_jN_j - \beta_j i\sqrt{2}p_1R_j + \sqrt{2}p_2R_j' = 0. \quad (21)$$

Put $R_j(x) = F_j(x)e^{iG_j(x)}$, where $F_j(x)$ and $G_j(x)$ are real functions. Then from (18) and (21) we obtain

$$F_j(x) = s_j\sqrt{p_2^2 - \beta_j^2e^{v(x)}}, \quad G_j'(x) = \frac{\beta_j p_1 p_2}{p_2^2 - \beta_j^2e^{v(x)}},$$

$$N_j(x) = \frac{\beta_j p_1 R_j(x) + ip_2 R_j'(x)}{\beta_j \sqrt{2}e^{v(x)}},$$

where s_j and β_j are some constants. Straightforward calculations can show that (17), (19), and (20) hold if and only if β_j satisfy the equality

$$\frac{\beta_j^4}{2} - c\beta_j^2 + p_2^2 = 0.$$

Put $\beta_1 = \alpha_1, \beta_2 = -\alpha_1, \beta_3 = \alpha_2, \text{ and } \beta_4 = -\alpha_2$, where $\pm\alpha_1$ and $\pm\alpha_2$ are the roots of (11). The equalities

$$|r| = 1, \quad \langle r, r_x \rangle = \langle r, r_y \rangle = \langle r_x, r_y \rangle = 0$$

give the following relations on the constants $s_k, k = 1, \dots, 4, \alpha_j, j = 1, 2$:

$$(s_1^2 + s_2^2)\alpha_1^2 + (s_3^2 + s_4^2)\alpha_2^2 = 0,$$

$$(p_2^2 + p_4^2)(s_1^2 + s_2^2 + s_3^2 + s_4^2) = \frac{\alpha_1^2 \alpha_2^2}{2}(s_1^2 + s_2^2 + s_3^2 + s_4^2) = 1,$$

$$(s_1^2 - s_2^2)\alpha_1 + (s_3^2 - s_4^2)\alpha_2 = 0, \quad (s_1^2 - s_2^2)\alpha_1^3 + (s_3^2 - s_4^2)\alpha_2^3 = 0.$$

The last system implies that $s_2 = \pm s_1$ and $s_4 = \pm s_3$. We will assume that $s_2 = s_1$ and $s_4 = s_3$ (the other cases are reduced to this by means of an automorphism of $\mathbb{C}P^3$). This yields

$$s_1 = \pm \frac{1}{\alpha_1 \sqrt{\alpha_2^2 - \alpha_1^2}}, \quad s_3 = \pm \frac{i}{\alpha_2 \sqrt{\alpha_2^2 - \alpha_1^2}},$$

and so (13) and (14). Straightforward calculations show that, for r defined by (12), the matrix R belongs to $SU(4)$. Find smooth periodic solutions to (16). Perform the change $h(x) = e^{v(x)}$; then (16) takes the form

$$(h')^2 + 8h(h - \gamma_1)(h - \gamma_2) = (h')^2 + 8h^3 - ch^2 + 4h(p_1^2 + p_2^2) = 0, \quad (22)$$

where γ_1 and γ_2 are the roots of the equation $\gamma^2 - c\gamma + \frac{1}{2}(p_1^2 + p_2^2) = 0$. The identity $(sn(x, k))' = (1 - sn^2(x, k))(1 - k^2 sn^2(x, k))$ (see [13]), where $sn(x, k) = \sin \varphi$, φ is the inverse function to

$$\omega(\varphi) = \int_0^\varphi \frac{dt}{\sqrt{1 - k^2 \sin^2 t}}, \quad 0 < k < 1,$$

implies that (22) has a solution of the form

$$h(x) = e^{v(x)} = \gamma_1 - \left(\gamma_1 - \gamma_2 \right) sn^2 \left(\sqrt{2\gamma_1} x, \sqrt{\frac{\gamma_1 - \gamma_2}{\gamma_1}} \right).$$

The function $v(x)$ is periodic with period $\tau = \frac{1}{\sqrt{2\gamma_1}} \int_0^{2\pi} \frac{dt}{\sqrt{1 - k^2 \sin^2 t}}$.

Note that $\alpha_1^2 > 2\gamma_1 \geq 2e^{v(x)} \geq 2\gamma_2 > \alpha_2^2$. Therefore, $\alpha_2^2 - 2e^{v(x)} \neq 0$, $\alpha_1^2 - 2e^{v(x)} \neq 0$, and so G_1 and G_2 are smooth functions. Theorem 1 is proved.

References

1. Sharipov R. A., "Minimal tori in the five-dimensional sphere in \mathbb{C}^3 ," Theoret. and Math. Phys., vol. 87, no. 1, 363–369 (1991).
2. Castro I. and Urbano F., "New examples of minimal Lagrangian tori in the complex projective plane," Manuscripta Math., vol. 85, no. 1, 265–281 (1994).
3. Ma H. and Ma Y., "Totally real minimal tori in $\mathbb{C}P^2$," Math. Z., Bd 249, Heft 2, 241–267 (2005).
4. Carberry E. and McIntosh I., "Minimal Lagrangian 2-tori in $\mathbb{C}P^2$ come in real families of every dimension," J. London Math. Soc., vol. 69, no. 2, 531–544 (2004).
5. Mironov A. E., "The Novikov–Veselov hierarchy of equations and integrable deformations of minimal Lagrangian tori in $\mathbb{C}P^2$," Sib. Electron. Math. Rep., vol. 1, 38–46 (2004).
6. Mironov A. E., "New examples of Hamilton-minimal and minimal Lagrangian manifolds in \mathbb{C}^n and $\mathbb{C}P^n$," Sb. Math., vol. 195, no. 1, 85–96 (2004).
7. Haskins M., "The geometric complexity of special Lagrangian T^2 -cones," Invent. Math., vol. 157, no. 1, 11–70 (2004).
8. Joyce D., "Special Lagrangian submanifolds with isolated conical singularities. V. Survey and applications," J. Differ. Geom., vol. 63, no. 2, 279–347 (2003).
9. Wentz H. C., "Counterexample to a conjecture of H. Hopf," Pacific J. Math., vol. 121, no. 1, 193–243 (1986).
10. Grinevich P. G. and Novikov S. P., "Real finite-zone solutions of the sine-Gordon equation: a formula for the topological charge," Russian Math. Surveys, vol. 56, no. 5, 980–981 (2001).
11. Babich M. V., "Smoothness of real finite-gap solutions of equations connected with the sine-Gordon equation," St. Petersburg Math. J., vol. 3, no. 1, 45–52 (1992).
12. Lawson H. B., *Lectures on Minimal Submanifolds*. Vol. 1, Publish or Perish, Berkeley (1980).
13. Akhiezer N. I., *Elements of the Theory of Elliptic Functions* [Russian], Nauka, Moscow (1970).

M. S. YERMENTAY
 SOBOLEV INSTITUTE OF MATHEMATICS, NOVOSIBIRSK, RUSSIA
 E-mail address: ermentay.m@gmail.com