METHODS OF THEORETICAL PHYSICS

Overview of Knot Invariants at Roots of Unity

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We discuss different invariants of knots and links that depend on a primitive root of unity. We clarify the definitions of existing invariants with the Reshetikhin–Turaev method, present the generalization of ADO invariants to $U_a(sl_N)$ and highlight the connections between different invariants.

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1. INTRODUCTION

Celebrated Jones polynomial $J^{\mathcal{K}}(q)$ discovered in 1984 by V. Jones [1] is a one-variable polynomial invariant of knots and links. It was originally defined with skein-relations, which offer a constructive method of calculation of Jones polynomials. Skein relations (1) connect Jones polynomials of three knots that differ in one crossing (2):

$$J^{\mathcal{K}}(q) - q^{-2} J^{\mathcal{K}}(q) = (q - q^{-1}) J^{\mathcal{K}''}(q), \qquad (1)$$

$$\mathcal{K} = \mathcal{K}, \quad \mathcal{K}' = \mathcal{K}, \quad \mathcal{K}'' = \mathcal{K}'' = \mathcal{K}''$$
 (2)

Shortly after the definition of Jones polynomial two important discoveries were made by E. Witten and N. Reshetikhin and V. Turaev. E. Witten [2] found a quantum field theory-Chern-Simons theory with gauge group SU_2 —that allowed one to construct observables (Wilson loop averages) that coincide with Jones polynomials; i.e., he offered a physical definition of a mathematical object. N. Reshetikhin [3] and V. Turaev [4] on the other hand discovered a new method of calculation of knot invariants with special operators called \mathcal{R} -matrices. They connected Jones polynomials with universal \mathcal{R} -matrix in fundamental representation of quantized universal enveloping algebra $\mathcal{U}_{a}(sl_{2})$. The Reshetikhin–Turaev (RT) method also allowed to define colored Jones polynomials calculated with \mathcal{R} -matrices in other representations of $\mathcal{U}_{a}(sl_{2}).$

These results were later generalized to HOMFLY-PT polynomials [5, 6], Chern–Simons theory with gauge group SU_N and universal \mathcal{R} -matrix in representations of $\mathcal{U}_a(sl_N)$.

 $U_q(sl_N)$ is an associative algebra with generators E_i , F_i , $K_i = q^{h_i}$ (i = 1, ..., N - 1) that satisfy the relations

$$K_{i}E_{j} = q^{-s}E_{j}K_{i}, \quad [K_{i}, K_{j}] = 0,$$

$$K_{i}F_{j} = q^{-a_{ij}}F_{j}K_{i}, \quad [E_{i}, F_{j}] = \delta_{ij}\frac{K_{i} - K_{i}^{-1}}{q - q^{-1}}.$$
(3)

The universal \mathcal{R} -matrix is the following:

$$\mathcal{R}_{u} = Pq^{i,j} \prod_{\beta \in \Phi^{+}}^{a_{i,j}^{-1}h_{i} \otimes h_{j}} \prod_{\beta \in \Phi^{+}} \exp_{q}\left((q-q^{-1})E_{\beta} \otimes F_{\beta}\right), \quad (4)$$

where $P(x \otimes y) = y \otimes x$, Φ^+ are positive roots, $\exp_q A = \sum_{m=0}^{\infty} \frac{A^m}{[m]_q!} q^{m(m-1)/2}$, and $[m]_q = (q^m - q^{-m})/((q - q^{-1}))$.

Chern–Simons theory is the three-dimensional quantum field theory with the action

$$S_{CS} = \frac{k}{4\pi} \int_{\mathcal{M}} \mathrm{Tr} \Big(\mathcal{A} \wedge d\mathcal{A} + \frac{2}{3} \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A} \Big).$$
(5)

Nonzero correlators in Chern–Simons theory are Wilson loop averages, which are correlators of a special type. When the gauge group of the theory is SU_N , they coincide with HOMFLY-PT polynomials $H_{\nu}^{K}(q, A)$

$$H_{R}^{\mathcal{K}}(q,A) = \frac{1}{d_{R}(N)} \left\langle \operatorname{Tr}_{R} P \exp\left(\oint_{\mathcal{K}} \mathcal{A} \right) \right\rangle_{CS(N,k)}.$$
 (6)

They depend on a contour \mathcal{K} (a knot or a link), the rank N-1 of the gauge group SU_N , its representation (corresponding to a Young diagram) R, on quantum dimension $d_R(N)$ and the Chern–Simons coupling



Fig. 1. Correspondence between the invariants at roots of unity.

constant k. This average is a polynomial in variables $q = \exp\left(\frac{2\pi i}{N+k}\right)$ and $A = q^N$. It was shown [7] that Chern–Simons theory is gauge invariant when the coupling constant k is an integer, which means that q is a root of unity. That is why invariants at roots of unity attract additional attention.

The obvious approach to get invariants at roots of unity is to substitute variables in HOMFLY-PT $H_R^{\mathcal{K}}(q, A)$ and Jones $J_{[r]}^{\mathcal{K}}(q)$ polynomials.

There also exist the invariant $\langle K \rangle_{m,N}$ defined by R. Kashaev [8–10] with \mathcal{R} -matrix that depends on a variable ω (that is a primitive *N*th root of unity) and an integer parameter *m*. The Kashaev invariants are not connected with quantum algebras, but they coincide with colored Jones polynomials.

Another possibility to construct invariants at roots of unity emerges when we consider representations of $\mathcal{U}_q(sl_N)$ when the parameter of quantization is a root of unity. In this case new types of representations with parameters λ emerge, which allow one to construct \mathcal{R} -matrices with parameters and to define new invariants of knots and links at roots of unity. The resulting invariants are ADO [11] or colored Alexander invariants [12] $\Phi_m^{\mathcal{L}}(q,\lambda)$ for $\mathcal{U}_q(sl_2)$. In this case, q is 2mth root of unity and λ is an arbitrary parameter. ADO invariants coincide with Alexander polynomials $\mathcal{A}(q) = H_{[1]}^{\mathcal{K}}(q, A = 1)$ when q is the fourth root of unity. They are also connected with Jones polynomials.

The new result that we want to highlight in this work is the generalization of ADO invariants to $\mathcal{U}_q(sl_N)$. These are the invariants $\mathcal{P}_{m,N}^{\mathcal{L}}(q,\lambda_i)$ (29) [13] of knots and links, which are associated with nilpotent representations with parameters of $\mathcal{U}_q(sl_N)$ at roots of unity $(q^{2m} = 1)$. They depend on a set of parameters $\{\lambda_1, \dots, \lambda_{N-1}\}$ and are connected with Alexander and HOMFLY-PT polynomials. ADO invariants and



Fig. 2. Different types of crossings and turning points.

invariants $\mathcal{P}_{m,N}^{\mathcal{L}}(q,\lambda_i)$ are defined with the modified version of the RT method, which requires the introduction of a special normalization coefficient (27) that we present in this work.

The schematic correspondence between invariants described above is shown in Fig. 1.

The aim of this work is to clarify the definition of different invariants at roots of unity and establish relations between them. The structure of the work is the following. We start with the RT method (Section 2) that is used to define all invariants considered in this work. Then we discuss the representation structure of $U_q(sl_2)$ for different values of q (Section 3). We define ADO invariants (Section 4) and their generalization (Section 5) and discuss the modifications of the RT method that are necessary in order to define them. Finally, we consider the notion of long knots and define Kashaev invariant (Section 6). The new results that we present in this work are in Section 5.

2. RESHETIKHIN-TURAEV METHOD

The RT method [9, 14, 15] allows one to define colored invariants of knots and links [16], [17]. There are also modifications of this method that allow to conduct the calculations more efficiently in some cases [18, 19]. In this section we discuss the most general version of the RT method and follow the description from [15].

The RT method is based on the use of a twodimensional oriented projection of a knot or a link on a plane with a fixed direction, which is a diagram of a knot or a link. The diagram shows which thread is above the other in each crossing. Then a diagram is broken down into the elements that play the role in the construction of knot invariant: crossings and turning points (relative to the selected direction). There are eight types of crossings and four types of turning points (Fig. 2).

All turning points and crossings can be expressed just with the operators \mathcal{R} , \mathcal{M} , and $\overline{\mathcal{M}}$:

 $= \mathcal{R} \qquad = \mathcal{M} \qquad = \overline{\mathcal{M}}.$ (7)

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Fig. 3. Reidemeister moves.

Operators \mathcal{R} , \mathcal{M} and $\overline{\mathcal{M}}$ satisfy the equations that come from Reidemeister moves (Fig. 3):

$$\mathrm{Tr}_{2}(I\otimes\mathcal{W})\mathcal{R}=q^{\Omega}I,\qquad(8)$$

$$\mathcal{R}_1 \mathcal{R}_2 \mathcal{R}_1 = \mathcal{R}_2 \mathcal{R}_1 \mathcal{R}_2, \tag{9}$$

where $\mathcal{R}_1 = \mathcal{R} \otimes I$, $\mathcal{R}_2 = I \otimes \mathcal{R}$, $\mathcal{W} = \mathcal{M}\overline{\mathcal{M}}$, and Iis the identity operator. Equations (8) and (9) fix only \mathcal{R} and \mathcal{W} operators, so there is some freedom in definition of \mathcal{M} and $\overline{\mathcal{M}}$. Different choices of operators \mathcal{R} and \mathcal{W} can produce different types of invariants. Colored Jones and HOMFLY-PT polynomials are associated with universal \mathcal{R} -matrix (4) in representations of $\mathcal{U}_q(sl_2)$ and $\mathcal{U}_q(sl_N)$, respectively, ADO invariants and their generalization are associated with universal \mathcal{R} matrix in nilpotent representation with parameters of $\mathcal{U}_q(sl_2)$ and $\mathcal{U}_q(sl_N)$ at roots of unity. The Kashaev invariant is based on a different \mathcal{R} -matrix (37).

The coefficient q^{Ω} in Eq. (8) is called the framing coefficient. It emerges when we consider a knot made out of a ribbon. In this case the first Reidemeister move resolves with a coefficient. In topological framing, which we use in definition of ADO invariants, matrices \mathcal{R} and \mathcal{W} satisfy the equation:

$$\mathrm{Tr}_{2}(I \otimes \mathcal{W})\mathcal{R} = I. \tag{10}$$

The polynomial invariant of a knot or a link is defined as a contraction of all operators associated with elements of a particular diagram.

If we choose universal \mathcal{R} -matrix calculated for representation R of $\mathcal{U}_q(sl_N)$, this method gives us unreduced HOMFLY-PT polynomial $\mathcal{H}_R^{\mathcal{K}}$. We can also define reduced polynomials $H_R^{\mathcal{K}} = \mathcal{H}_R^{\mathcal{K}}/\mathcal{H}_R^{\circ}$, where \mathcal{H}_R° is the unreduced polynomial of unknot.

It is convenient to use diagrams of knots and links in the form of braids (Fig. 4), that exist for any knot or link. In this case the definition of invariants can be reformulated in terms of Markov trace Tr_q (quantum trace) and operator $\mathcal{W} = \mathcal{M}\overline{\mathcal{M}}$, which is known as the weight matrix.

$$\mathcal{H}_{R}^{\mathcal{K}} = \mathrm{Tr}_{q} \prod_{i} \mathcal{R}_{i} = \mathrm{Tr} \overline{\mathcal{W} \otimes \ldots \otimes \mathcal{W}} \prod_{i} \mathcal{R}_{i}, \quad (11)$$

where *s* is a number of strands in a braid, the product includes all crossings in the braid.

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Fig. 4. Diagrams of the Hopf link and trefoil knot in the braid form.

3. REPRESENTATIONS OF $U_q(sl_2)$ AT ROOTS OF UNITY

 $U_q(sl_2)$ is generated by elements $e, f, k = q^h$ and $k^{-1} = q^{-h}$ that satisfy the relations

$$kk^{-1} = k^{-1}k = 1, \quad kek^{-1} = q^2e,$$
 (12)

$$kfk^{-1} = q^{-1}f$$
, $[e, f] = ef - fe = \frac{k - k^{-1}}{q - q^{-1}}$.

The universal \mathcal{R} -matrix is the following

$$\mathcal{R} = Pq^{h \otimes h/2} \sum_{m=0}^{\infty} \frac{q^{m(m+1)/2} (1-q^{-2})^m}{[m]_q!} e^m \otimes f^m \quad (13)$$

and the corresponding weight matrix coincides with operator k: W = k.

When *q* is not a root of unity the irreducible finite dimensional representations L_r of the algebra $\mathcal{U}_q(sl_2)$ are symmetric representations enumerated with Young diagrams that consist of one row [*r*]. L_r are the representations with the highest and the lowest weights, which act on a vector space \mathcal{V}_{r+1} of dimension r + 1 with basis vectors v_i , $i = \{0, ..., r\}$, where v_0 and v_r are the highest and lowest weight vectors, respectively,

$$L_{r}(k)v_{i} = q^{r-2i}v_{i},$$

$$L_{r}(e)v_{i} = [i]_{q}[r-i+1]_{q}v_{i-1}, \quad L_{r}(e)v_{0} = 0, \quad (14)$$

$$L_{r}(f)v_{i} = v_{i+1}, \quad L_{r}(f)v_{r} = 0,$$

where $[x]_q = (q^x - q^{-x})/(q - q^{-1})$ is a quantum number and δ_{ij} is the Kronecker delta. In this case the highest weight $L_r(k)v_0 = \lambda v_0$ is fixed $\lambda = q^r$. The condition that fixes the weight emerges when one builds a Verma module starting with an eigenvector v_0 of operator *k* that satisfies $ev_0 = 0$. One gets the other vectors of the Verma module acting on v_0 with the operator *f*: $fv_0 = v_1, f^2v_0 = v_2, ..., f^nv_0 = v_n$. Then we look for

an invariant subspace with the condition $ev_{r+1} = 0$, which is the following:

$$[r+1]_{q}(\lambda q^{-r} - \lambda^{-1} q^{r}) = 0.$$
(15)

This condition fixes the weight λ only if $[r+1] \neq 0$, which means that when *q* is a root of unity, there exist representations, where the weight is arbitrary.

Let q be a primitive root of unity of degree 2m, which means that there is no p < 2m so that $q^p = 1$. In this case operators e^m , f^m and k^m are central, which comes directly from the defining relations (12). The centrality of k^m results in the fact that the weight of representations of dimension m is not fixed and is a parameter of representations. The fact that e^m and f^m are central is the reason why new types of representations emerge in this case: cyclic and semicyclic.

There are four types of irreducible representations (any irreducible representation of $U_q(sl_2)$ is finitedimensional at roots of unity):

(1) representations L_r (14) for $r \le m - 2$;

(2) cyclic $U_m^{a,b,\lambda}$;

(3) semicyclic
$$V_m^{a,\lambda} = U_m^{a,0,\lambda}$$
 or $V_m^{b,\lambda} = U_m^{0,b,\lambda}$;

(4) nilpotent representations $W_m^{\lambda} = U_m^{0,0,\lambda}$.

The last three representations have the same dimension *m* and can be described with the following operators acting on a *m*-dimensional vector space V_m with basis v_i , i = 0, 1, ..., m - 1,

$$U_{m}^{\lambda,a,b}(k)v_{i} = q^{-2i}\lambda v_{i}, \qquad (16)$$

$$U_{m}^{\lambda,a,b}(e)v_{i} = \left(ab + [i]_{q} \frac{\lambda q^{1-i} - \lambda^{-1}q^{i-1}}{q - q^{-1}}\right)v_{i-1}, \quad i > 0,$$

$$U_{m}^{\lambda,a,b}(e)v_{0} = av_{m-1},$$

$$U_{m}^{\lambda,a,b}(f)v_{i} = v_{i+1}, \quad i < m-1,$$

$$U_{m}^{\lambda,a,b}(f)v_{m-1} = bv_{0},$$

where *a*, *b*, and $\lambda \neq 0$ are arbitrary complex numbers. One can check that these operators satisfy the defining relations (12) of $U_a(sl_2)$.

Representations W_m^{λ} produce non-trivial \mathcal{R} -matrices and allow one to define invariants of knots and links that are known as ADO or colored Alexander invariants.

4. ADO OR COLORED ALEXANDER INVARIANTS

ADO invariants of links were defined by Akutsu, Deguchi, and Ohtsuki [11]. ADO invariants of knots and links can be defined with the RT method, which is



Fig. 5. (1, 1)-tangles of the Hopf link and trefoil knot.

applied to (1,1)-tangles—knot and links with one cut line (Fig. 5). The consideration of tangles instead of knots and links is possible because of the existing oneto-one correspondence between them [20]. It is an important step that allows one to calculate nonzero invariants. Invariants, that are calculated with knots and links directly are all equal to zero, because of the

properties of Markov trace in representations W_m^{λ} .

Let us now define ADO invariants. Two important modifications of the RT method have to be made. First of all, we have to redefine Markov trace in the following way:

$$\operatorname{Tr}_{q}^{*} \dots = \operatorname{Tr} I \otimes \overbrace{\mathcal{W} \otimes \dots \otimes \mathcal{W}}^{s-1} \dots \dots \dots (17)$$

i.e., omit one weight matrix, that is associated with a cut line. Then the normalization coefficient of polynomials (unreduced polynomial of unknot) equals a classical dimension of a representation.

This procedure makes one choose the line to cut and brings asymmetry into the definition of the invariant. That is why one also needs to introduce a normalization coefficient. The coefficient that was calculated

in [11] up to normalization coefficient q^m is the following

$$\Xi_m^{sl_2}(\lambda_1) = \prod_{i=0}^{m-2} \{\lambda_1 q^{-i}\},$$
(18)

where $\{x\} = x - x^{-1}$, λ_1 is a color of an open component.

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Now we can define ADO invariant $\Phi_m^{\mathcal{L}}(\lambda_1,...)$:

$$\Phi_m^{\mathcal{L}}(\lambda_1,\ldots) = \frac{\operatorname{Tr} I \otimes \overline{\mathcal{W}} \otimes \ldots \otimes \overline{\mathcal{W}} \prod_i \mathcal{R}_i}{\Xi_m^{sl_2}(\lambda_1)}.$$
 (19)

In this definition \mathcal{R} is the universal \mathcal{R} -matrix, calculated for representation W_m^{λ} of $\mathcal{U}_q(sl_2)$ at roots of unity. In general, it depends on two colors $\lambda_1 = q^{\mu_1}$ and $\lambda_2 = q^{\mu_2}$:

$$\mathcal{R}_{m}(v_{i}^{\mu_{1}} \otimes v_{j}^{\mu_{2}})$$

$$= \sum_{n=0}^{m-1} q^{\mu_{2}(m-1-i+n)-\mu_{1}(j+n)+2(i-n(j+n)+\frac{n(n-1)}{2})}$$
(20)

$$\times \frac{(q-q^{-1})^n}{[n]!} [i-n+1;n] [\mu_1-i+n;n] (v_{j+n}^{\mu_2} \otimes v_{i-n}^{\mu_1})$$

and

$$\mathcal{W}_{m}v_{i}^{\mu} = q^{-\mu(m-1)-2i}v_{i} = q^{-\mu m}kv_{i}^{\mu}.$$
 (21)

ADO invariants $\Phi_m^{\mathcal{L}}$ are connected with Alexander and Jones polynomials. For simplicity let us define ADO polynomials of knots and one-colored links:

$$\hat{\Phi}_{m}^{\mathcal{L}}(\lambda) = \Phi_{m}^{\mathcal{L}}(\lambda) \Xi_{m}^{sl_{2}}(\lambda)$$
(22)

then

$$\hat{\Phi}_{2}^{\mathcal{K}}(\lambda) = \mathcal{A}^{\mathcal{K}}(q = \lambda), \qquad (23)$$

i.e., ADO polynomials for fourth root of unity coincide with Alexander polynomials of knots and ADO invariants for fourth root of unity coincide with multivariable Alexander polynomials of links

$$\Phi_2^{\mathcal{L}}(\lambda_1,\ldots) = \Delta^{\mathcal{L}}(\lambda_1,\ldots), \qquad (24)$$

and that is why ADO invariants are also called colored Alexander invariants.

The connection with Jones polynomials is the following:

$$\hat{\Phi}_{m}^{\mathcal{L}}(\lambda = q^{m-1}) = J_{[m-1]}^{\mathcal{L}}(q)\Big|_{q^{2m}=1},$$
(25)

where $J_{[m-1]}^{\mathcal{L}}(q)$ are reduced Jones polynomials in representation L_{m-1} . It follows from the fact that representations W_m^{λ} coincide with representations L_{m-1} when we choose the correct value of the weight $\lambda = q^{m-1}$.

Recent study by S. Willetts [21] showed that ADO invariants and colored Jones polynomials can be generalized with the unified knot invariant that contains both invariants: ADO and Jones. And there exists a map that allows one to get ADO invariants from colored Jones polynomials.

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5. GENERALIZATION OF ADO INVARIANTS
TO
$$U_q(sl_N)$$

Jones polynomials were generalized to HOMFLY-PT, and similarly ADO invariants can be generalized to invariants $\mathcal{P}_{m,N}^{\mathcal{L}}(\lambda_i^{(j)})$ associated with representations of $\mathcal{U}_q(sl_N)$ (3) at roots of unity.

Let *q* be a primitive root of unity of degree 2m. In this case the representation structure of $\mathcal{U}_q(sl_N)$ [22] is very similar to representation structure of $\mathcal{U}_q(sl_2)$, that we discussed before. The operators K_i^m are central and there exist nilpotent representations $W_{m,N}^{\lambda_i}$ of dimension $m^{N(N-1)/2}$ with N-1 parameters λ_i and arbitrary weights. There are also cyclic and semicyclic representations because E_i^m and F_i^m are central, but these representations do not produce non-trivial invariants of knots and links [13]. Representations $W_{m,N}^{\lambda_i}$ are associated with non-trivial invariants that we denote $\mathcal{P}_{m,N}^{\mathcal{L}}(\lambda_i^{(j)})$.

The definition of invariants $\mathcal{P}_{m,N}^{\mathcal{L}}(\lambda_i^{(j)})$ repeats the definition of ADO invariants. We color components of a link with *l* representations $W_{m,N}^{\lambda_i^{(j)}}$ (j = 1,...,l) with sets of parameters λ_i (i = 1,...,N-1), make a projection of the link and cut one line of the projection. We then apply RT method to (1, 1)-tangles and get polynomials $P_{m,N}^{\mathcal{L}}(\lambda_i^{(j)})$. As the operators \mathcal{R} and \mathcal{W} in the RT method we use the universal \mathcal{R} -matrix (4) and the operator \mathcal{W} , calculated for representations $W_{m,N}^{\lambda_i}$. The operator \mathcal{W} is the following:

$$\mathcal{W} = q^{2h_{\rm p}}, \quad h_{\rm p} = \frac{1}{2} \sum_{\alpha \in \Phi^+} h_{\alpha}. \tag{26}$$

We also need to normalize the polynomials $P_{m,N}^{\mathcal{L}}(\lambda_i^{(j)})$ in order to restore the symmetry between all threads in a link. If the color of an open component is $\lambda^{(1)}$ (Fig. 6) the normalization coefficient $\Xi_{m,N}(\lambda^{(1)})$ is the following:

$$\Xi_{m,N}(\lambda^{(1)}) = \prod_{\alpha \in \Phi_N^+} \xi_m(\lambda_\alpha^{(1)} q^{|\alpha|}), \qquad (27)$$

where α are positive roots Φ_N^+ of sl_N , $\alpha = \sum_{k=i}^{j} \alpha_k$ $(i \le j < N)$, where α_k are simple roots of sl_N , $|\alpha| = j - i$. Definition of $\xi_m(\lambda)$ repeats the definition of normalization coefficient of ADO invariants (18):

$$\xi_m(\lambda) = \prod_{i=0}^{m-2} \{\lambda q^{-i}\}.$$
(28)



Fig. 6. Colored (1, 1)-tangle corresponding to the Hopf link.

Now we can define invariants $\mathcal{P}_{m,N}^{\mathcal{L}}(\lambda_i^{(j)})$ at roots of unity with parameters $\lambda_i^{(j)}$ (i = 1, ..., N - 1, j = 1, ..., l, l is the number of components in a link), $\lambda_i^{(1)}$ is the color of an open component:

$$\mathcal{P}_{m,N}^{\mathcal{L}}(\lambda_i^{(j)}) = \frac{P_{m,N}^{\mathcal{L}}(\lambda_i^{(j)})}{\Xi_{m,N}(\lambda_i^{(1)})}.$$
(29)

Invariants $\mathcal{P}_{m,N}^{\mathcal{L}}(\lambda_i^{(j)})$ coincide with HOMFLY-PT polynomials in representations $R_{m,N}$ corresponding to the Young diagrams $[(N-1)(m-1), (N-2)(m-1), \dots, (m-1)]$ when the parameters $\lambda_i^{(j)}$ coincide with the highest weights of representation $R_{m,N}$:

$$P_{m,N}^{\mathcal{L}}(\lambda_i^{(j)} = q^{m-1})\Big|_{q^{2m} = 1} = H_{R_{m,N}}^{\mathcal{L}}(A = q^N, q)\Big|_{q^{2m} = 1}.$$
 (30)

They are also connected with Alexander polynomials, but these connections are not as simple as in case of ADO invariants. They are listed in [13]. For example, for N = 3:

$$P_{2,3}^{\mathcal{K}}(\lambda_1,\lambda_2=1) = \mathcal{A}^{\mathcal{K}}(\lambda_1^2), \qquad (31)$$

$$P_{3,3}^{\mathcal{K}}(q,\lambda_1,\lambda_2=1) = \mathcal{A}^{\mathcal{K}}(\lambda_1)\mathcal{A}^{\mathcal{K}}(\lambda_1^3).$$
(32)

Invariants $\mathcal{P}_{m,N}^{\mathcal{L}}(\lambda^{(j)})$ coincide with ADO invariants $\Phi_m^{\mathcal{L}}(\lambda^{(1)},...)$ when N = 2.

6. KASHAEV INVARIANT

There exists another type of knot invariant, defined specifically for a root-of-unity variable, which is not based on representations of quantum algebras. In this section, we discuss the Kashaev knot invariant $\langle K \rangle_{m,N}$.

The Kashaev invariant of knots was defined by Rinat Kashaev in [10] for long knots. It is based on \mathcal{R} -matrix, obtained from solutions of pentagon identity, which depends on a root-of-unity variable ω and two integer spectral parameters (*m* and *n*) that are associated with two colors of two strands in a crossing. For the definition of the invariant Kashaev uses the RT method applied to (1,1)-tangles, which are twodimensional projections of long knots. Long knots are 3-dimensional analogs of (1, 1)-tangles. By definition long knot is an embedding $f: \mathbb{R} \to \mathbb{R}^3$ and there exist $a, b \in \mathbb{R}$ such that f(t) = (0, 0, t) for any t < a or t > b. Calculating invariants of long knots allows to avoid the problem with normalization coefficient.

The steps to define the Kashaev invariant are the following. First of all, we fix a primitive root of unity ω of order *N*, color the threads with integer numbers $n_i: 0 \le n_i < N$, make a two-dimensional projection, place \mathcal{R} -matrices and turning point operators according to the rules below and sum over all indices (the invariance of the resulting sum was shown in [9]).

$$\begin{array}{ccc}
j & i \\
m & n \\
k & l
\end{array} = \langle i, j | r (m, n) | k, l \rangle, \quad (33)$$

$$\sum_{i \in n} j = i \int_{j}^{n} j = \delta_{i,j}, \qquad (34)$$

$$i \xrightarrow{n} j \longrightarrow j \xrightarrow{n} i = \omega^{-n} \delta_{i, [j+1]_N},$$
 (35)

$$\bigvee_{i \atop n} j \rightarrow j \bigvee_{n} i = \omega^{n} \delta_{i, [j+1]_{N}}, \qquad (36)$$

$$\langle i, j | r(m,n) | k, l \rangle = V_{i,j-m,k-n,l}(\omega) \omega^{k-l-n+(k-i-n)m}, \quad (37)$$

where

$$V_{i,j,k,l}(\omega) := \frac{N\Theta_N([j-i-1]_N + [l-k]_N)\Theta_N([i-l]_N + [k-j]_N)}{(\overline{\omega})_{[j-i-1]_N}(\omega)_{[i-l]_N}(\overline{\omega})_{[l-k]_N}(\omega)_{[k-j]_N}}$$
(38)

and $[k]_n = k \mod n$, $\theta_n(k) = \delta_{k, [k]_n}$, $(x)_n = \prod_{k=1}^n (1 - x^k)$.

As said above, to define the Kashaev invariant we base our calculations on (1, 1)-tangle and it is a matrix invariant, which is equal to identity matrix $N \times N$ multiplied with Jones polynomial colored with

(m+1)-dimensional representation L_m (14) (corresponding to the Young diagram [m]) evaluated at a point $q = \omega$:

$$\langle K \rangle_{N,m} = J_{[m]}(\omega) I_N. \tag{39}$$

This result is the conjecture based on calculations of different examples. Even though Kashaev constructed

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 \mathcal{R} -matrix that is not based on representations of $\mathcal{U}_q(sl_2)$ the resulting polynomial coincides with Jones polynomial.

7. CONCLUSIONS

In this work, we have considered different invariants of knots and links at roots of unity. Among them are colored Jones and HOMFLY-PT polynomials (11) evaluated at roots of unity, ADO or colored Alexander invariants and their generalization and the Kashaev invariants.

All these invariants can be defined and calculated with the RT method; however, to define invariants at roots of unity, one needs to modify the RT method: consider (1, 1)-tangles instead of knots and links and introduce the normalization coefficient (18), (27).

We defined ADO or colored Alexander invariants (19). They depend on a root-of-unity variable and correspond to nilpotent representations with parameters of $U_q(sl_2)$ at roots of unity. They are connected with Jones (25) and Alexander (22) polynomials and according to the recent study are equivalent to Jones polynomials [21].

We also discussed Kashaev invariants, that are defined with \mathcal{R} -matrix with integer parameters that depends on a root-of-unity variable and is not defined with representations of $\mathcal{U}_q(sl_N)$. The resulting polynomial conjecturally coincides with colored Jones polynomial (39).

This work also contains a brief summary of definition of invariants $\mathcal{P}_{m,N}^{\mathcal{L}}(\lambda_i^{(j)})$ (30) that are the generalization of ADO invariants. They are a new type of invariants, defined for nilpotent representations with parameters $W_{m,N}^{\lambda_i}$ of $\mathcal{U}_q(sl_N)$ at roots of unity. They are connected with HOMFLY-PT (30) and Alexander

connected with HOMFLY-PT (30) and Alexander polynomials (31) and (32) [13]. The question remains whether these invariants are independent or they are equivalent to colored HOMFLY-PT polynomials.

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CONFLICT OF INTEREST

The author declares that he has no conflicts of interest.

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