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Chemical potential formalism for polymer entropic forces

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The entropic force is one of the most elusive interactions in macromolecules. It is clearly defined theoretically, but practically difficult to evaluate, thus restricting our knowledge of it often to a qualitative level. Here, we propose a formula for entropic force, $f = f^\circ + T \ln(\alpha)$, for confined polymers and demonstrate its mathematical equivalence to the widely used chemical potential formula for solutions, $\mu = \mu^\circ + RT \ln(a)$. A systematic analysis based on this formalism clarifies the force magnitudes obtained in several recent experiments on polymers and granular chains and elucidates the common force scales for polymers studied in nanoscience and biological systems. This work provides a practical tool for instantaneously evaluating the entropic forces in polymer science and indicates the possibility of using a reference-based strategy to tackle general entropic problems beyond chemical solutions.

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A wire threaded through a hole might be one of the simplest models one can imagine in physics, which, captures the core scenario in numerous polymer systems in laboratories, industrial applications, and real biological environments. This model has been studied intensively over decades, for polymer translocation and confined polymers in microfluidics, nanotechnology, and single-molecule experiments^{1–4}. Although entropic effects are significant for systems scaled down to that size and were already formulated in the earlier theories in this field^{5–7}, the estimation of their strength is challenging, because analytically or numerically solving partition functions is difficult^{8,9}. Thus, qualitative judgments on entropic effects are more frequently reported than quantitative characterizations.

In contrast to these direct approaches, here we derive an entropic force formula for confined polymers and demonstrate its correspondence to the well-known chemical potential formula for solutions (Fig. 1)¹⁰. The advantage of the latter formula is that one can calculate the chemical potential of a desired solution by summing an easily calculable correction term with a known reference value. In the same spirit, the convenience of the derived force formula is that it can be readily calculated based on the knowledge of the entropic force of a known reference system. The formalism is elucidated in several numerical experiments, including a polymer pulled by an optical tweezer into a two-dimensional (2D) channel and a polymer straddling a 2D channel undergoing a tug-of-war. Different types of entropic forces in those systems are calculated by the Jarzynski equality (JE)¹¹ and a recursion formula (RF) for counting the exact configuration numbers. The highly coincident force magnitudes extracted from

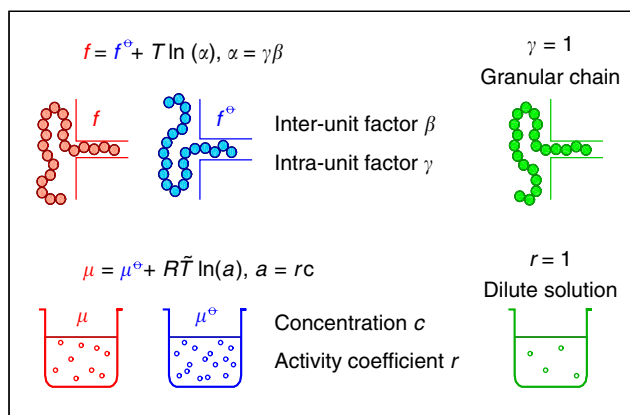


Fig. 1 A correspondence between polymer physics and physical chemistry. Owing to a correspondence between the chemical potentials for solutions and the entropic forces for partly confined polymers, solving these two problems is mathematically equivalent. The chemical potential formula for a solution of activity $a = rb$ is $\mu = \mu^o + R\tilde{T}\ln(a)$, with the standard chemical potential μ^o , gas constant R , Kelvin temperature \tilde{T} , activity coefficient r , and concentration b of the solution. With this expression one can calculate the μ of a desired solution by summing an easily calculable correction term $R\tilde{T}\ln(a)$ with a known reference value μ^o . The entropic force formula for a polymer partly confined in a channel is $f = f^o + T\ln(\alpha)$, with a reference force f^o and a dimensionless temperature T . Here, the “activity” $\alpha = \gamma\beta$ depends on the channel width and stiffness, as well as the polymer persistence length and excluded volume. Therein, the “concentration” β is decided by the configuration number of the basic unit to coarse-grain the polymer, such as the commonly adopted beads, rods, or blobs, whereas the “activity coefficient” γ reflects the change in internal freedom in that basic unit when it enters or leaves the channel. If all the basic units along the polymer chain are identical in shape and internal freedom, such as those in a granular chain, then $\gamma = 1$ and $\alpha = \beta$, which corresponds to the ideal case of dilute solutions with $r = 1$ and $a = c$ in μ

these two independent approaches justify the accuracy of the force formula. On the basis of this consistency, the analysis is extended to three-dimensional (3D) circular tubes and slits. The estimated force magnitudes are very close to the experimentally observed ones in 2D strips¹², pillar arrays¹³, and 3D nanoslits¹⁴, and follow the same scaling behavior observed in granular chains¹⁵. More general studies on several polymers threaded through various natural and artificial pores unravel a common force range between femto- and piconewton and indicate a special ratio between the forces of different confinements. The proposed force formula reduces the complex evaluation of partition functions to a simple textbook-level calculation. This allows us to estimate the entropic effects on polymers algebraically by hand without resorting to elaborate computational efforts and perform a systematic analysis on the force scales for a broad class of confined-polymer systems.

Results

Configurational entropies. Let us consider a polymer partly confined in a channel. Suppose the polymer segment inside (outside) the channel is coarse-grained as a chain of basic unit (BU) C_I (C_O), where C_I and C_O do not need to be the same (Fig. 2a). For instance, C_I could be a rod in the Odijk regime and C_O could be a Kuhn segment in a free space, or C_I and C_O could have the same shape but different numbers of monomer microstates inside them. The chain can be a non-self-avoiding chain (NSC) or a self-avoiding chain (SC). The channel is assumed to be narrow with respect to C_I . If C_I and C_O are identical beads of size l in a bead-spring model (Fig. 2b, c), let n_I (n_O) be the number of beads inside (outside) the channel and Ω_{n_I} (Ω_{n_O}) denote the configuration number of the chain segment of C_I (C_O) inside (outside) the channel. Then the configurational entropy of the whole chain is $S = k_B \ln(\Omega_{n_I} \Omega_{n_O})$, with k_B being the Boltzmann constant.

Entropic recoiling forces. The entropic recoiling force describes the tendency of a chain to escape from a channel (Fig. 2b). It is the negative of the change in the entropic free energy, $-\tilde{T}S$, per shifted distance out of the channel, where \tilde{T} is the Kelvin temperature. If the distance is l , this force is given by $\tilde{f}_R = (k_B \tilde{T}/l) \ln[(\Omega_{n_I-1} \Omega_{n_O+1})/(\Omega_{n_I} \Omega_{n_O})]$. Taking the dimensionless temperature $T \equiv \tilde{T}/\tilde{T}_{\text{room}}$ with respect to the room temperature $\tilde{T}_{\text{room}} = 298$ K, it yields a dimensionless entropic force $f_R \equiv \tilde{f}_R l/\epsilon$, or

$$f_R = T \ln \left(\frac{\Omega_{n_I-1} \Omega_{n_O+1}}{\Omega_{n_I} \Omega_{n_O}} \right) = T \ln \left(\frac{\Phi_{n_O}}{\Phi_{n_I-1}} \right), \quad (1)$$

with $\epsilon \equiv k_B \tilde{T}_{\text{room}}$. Here, $\Phi_{n_I} \equiv \Omega_{n_I+1}/\Omega_{n_I}$ ($\Phi_{n_O} \equiv \Omega_{n_O+1}/\Omega_{n_O}$) is the excess configuration number caused by an added bead inside (outside) the channel. As Φ_{n_O} outside the channel is always larger than Φ_{n_I-1} inside the channel, we have $f_R > 0$. The positive sign indicates that the force points to the same direction as an outward-moving bead. If the channel is so narrow that only one straight configuration is allowed inside it, the force will degenerate to $f_R = T \ln(\Phi_{n_O})$, because $\Omega_{n_I-1} = \Omega_{n_I} = 1$ implies $\Phi_{n_I-1} = 1$.

Let f'_R be the force of a second chain of the same form as Eq. (1), with Φ_{n_O} , Φ_{n_I} , and l there replaced by Φ'_{n_O} , Φ'_{n_I} and l' . For a

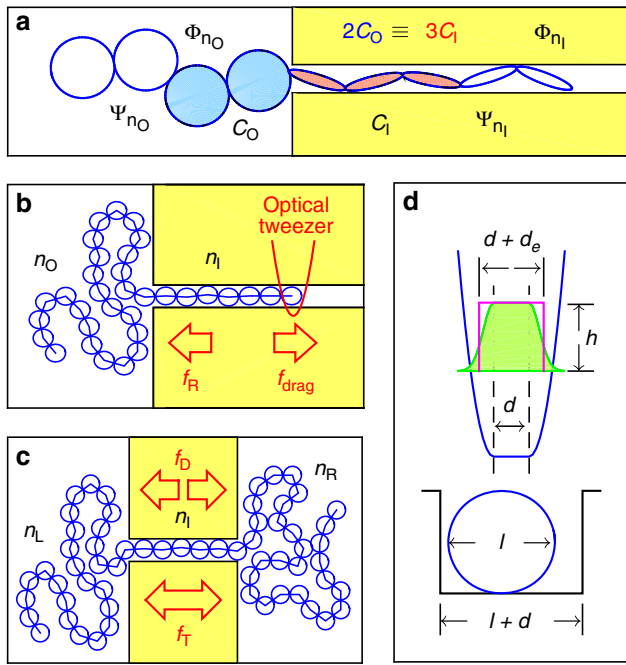


Fig. 2 Three kinds of entropic forces for partly confined polymers. **a** A chain partly confined by a channel, for which three basic units of C_I (red) appear inside the channel when two basic units of C_O (blue) move into the channel. Φ_{n_i} (Φ_{n_o}) is the excess configuration number inside (outside) the channel in Eq. (1), whereas Ψ_{n_i} and Ψ_{n_o} reflect the changes of internal freedoms in basic units in Eq. (3). **b** The entropic recoiling force f_R for a chain escaping from a two-dimensional (2D) channel is counterbalanced by the drag force f_{drag} of an optical tweezer. n_i (n_o) is the number of basic unit C_I inside (C_O outside) the channel. **c** The entropic drift force f_D and tension force f_T for polymer tug-of-war. n_L (n_R) is the number of basic unit C_O in the left (right) space. **d** A bead (blue circle) of size l is in a channel (black) of width $w = l + d$, where the lateral free space d is the distance the bead can freely move without touching the boundary. The potential well (blue curve) above the channel describes the bead-wall interaction versus the location of the bead center. The well boundary $V(\eta) = \kappa\eta^2/2$ is a function of the penetration depth η and stiffness κ . The probability density of finding the bead in the lateral direction of the channel (green area) has the same area as a uniform probability density of an effective width $d + d_e$ (magenta rectangle). The bead confined by the blue soft potential is analogous to being restricted to a hard potential of an effective width $d + d_e$.

given (n_b, n_o), f'_R is related to f_R by

$$f_R = f'_R + T \ln \left(\frac{\Phi'_{n_i-1} \Phi_{n_o}}{\Phi_{n_i-1} \Phi'_{n_o}} \right) = f'_R + T \ln(\alpha_R), \quad (2)$$

with $\alpha_R \equiv \alpha_i \alpha_o$, where $\alpha_i \equiv \Phi'_{n_i-1} / \Phi_{n_i-1}$ and $\alpha_o \equiv \Phi_{n_o} / \Phi'_{n_o}$. Generally, the bead sizes l for f_R and l' for f'_R in Eq. (2) are not the same. Therefore, even when the values of f_R and f'_R of the two systems are identical, the real forces $\tilde{f}_R = f_R \epsilon / l$ and $\tilde{f}'_R = f'_R \epsilon / l'$ may be different.

If C_I and C_O do not have identical shapes or internal freedom, such as those in Fig. 2a, let $\tilde{\Phi}_{n_i}$ ($\tilde{\Phi}_{n_o}$) be the excess “microstate” number caused by an added BU C_I inside (C_O outside) the channel. The “microstates” here include the allowed configurations of C_I and C_O considered in Eq. (1) and the internal freedom inside each individual BU, which are generally hybridized and cannot be decoupled. When a chain segment of length l moves into (out of) a channel, suppose n_i (n_o) BUs of C_I (C_O) appear inside (outside) it. Then, the total excess microstate number of n_i

(n_o) added BUs would be $(\tilde{\Phi}_{n_i-1})^{n_i} ((\tilde{\Phi}_{n_o})^{n_o})$, for which the entropic recoiling force in Eq. (1) is generalized to

$$f_R = T \ln \left(\frac{(\tilde{\Phi}_{n_o})^{n_o}}{(\tilde{\Phi}_{n_i-1})^{n_i}} \right), \quad (3)$$

with $\tilde{\Phi}_{n_i} \equiv g_{n_i+1} \Omega_{n_i+1} / (g_{n_i} \Omega_{n_i}) = \Psi_{n_i} \Phi_{n_i}$ and $\tilde{\Phi}_{n_o} \equiv g_{n_o+1} \Omega_{n_o+1} / (g_{n_o} \Omega_{n_o}) = \Psi_{n_o} \Phi_{n_o}$. Therein, Φ_{n_i} (Φ_{n_o}) is the excess configuration of C_I (C_O) defined in Eq. (1), while g_{n_i} and g_{n_o} as well as $\Psi_{n_i} \equiv g_{n_i+1} / g_{n_i}$ and $\Psi_{n_o} \equiv g_{n_o+1} / g_{n_o}$ are correction terms reflecting the difference between the shapes, or internal freedoms, of C_I and C_O . Notice that n_o and n_o as well as n_i and n_i in Eq. (3) have different meanings.

Two forces of the same form as Eq. (3) are related as Eq. (2) with α_R there replaced by $\tilde{\alpha}_R = G \tilde{\alpha}_R$ where

$$G \equiv \frac{g'_{n_i-1} n_i g_{n_o}^{n_o}}{g_{n_i-1} n_i g'_{n_o}} \text{ and } \tilde{\alpha}_R \equiv \frac{\Phi'_{n_i-1} n_i \Phi_{n_o}^{n_o}}{\Phi_{n_i-1} n_i \Phi'_{n_o}}. \quad (4)$$

That is, $\tilde{\alpha}_R$ is related to the α_R in Eq. (2) by $\tilde{\alpha}_R = \gamma \alpha_R$ with $\gamma \equiv G \tilde{\alpha}_R / \alpha_R$. Therefore, for general C_I and C_O , Eq. (2) is extended to the form

$$f = f^\ominus + T \ln(\alpha), \text{ with } \alpha = \gamma \beta, \quad (5)$$

with $\beta = \alpha_R$. Specifically, if the microstates of a polymer can be decomposed as those inside and outside C_I (C_O), then g_{n_i} (g_{n_o}) is exactly the number of microstates inside (C_O). This decomposition is similar to that in the de Gennes blob, where the Flory statistics inside a blob is independent of the chain properties outside the blob. If C_I and C_O are identical, then $n_i = n_o = g_{n_i} = g_{n_o} = 1$ for all n_i and n_o . In this case, $\gamma = 1$ and α is reduced to the $\beta = \alpha_R$ of an “ideal” confined chain in Eq. (2). Therefore, α , β , and γ play the same role as the activity $a = rc$, the concentration c , and the activity coefficient r , respectively, in the chemical potential formula $\mu = \mu^\ominus + T \ln(a)$ of a non-ideal solution. Notice that the mathematical equivalence between Eq. (5) and the chemical potential formula for solutions does not mean the former is aimed at understanding polymer solutions.

Entropic drift forces. The above formalism also applies to other entropic forces. For polymer tug-of-war in Fig. 2c, the chain straddling the channel is unstable and will gradually move out of a channel either rightward or leftward. The entropic drift force

$$f_D = T \ln \left(\frac{\Omega_{n_R-1} \Omega_{n_L+1}}{\Omega_{n_R} \Omega_{n_L}} \right) = T \ln \left(\frac{\Phi_{n_L}}{\Phi_{n_R-1}} \right) \quad (6)$$

represents the tendency of the drift of the whole chain from the right to the left space. Here, n_L (n_R) denotes the number of beads in the left (right) space and $\Phi_{n_L} \equiv \Omega_{n_L+1} / \Omega_{n_L}$ ($\Phi_{n_R} \equiv \Omega_{n_R+1} / \Omega_{n_R}$) stands for the excess configuration number caused by an added bead in the left (right) space. Φ_{n_L} and Φ_{n_R} are the same function as Φ_{n_o} in Eq. (1). Since the configuration of an outside segment with fewer beads is more constrained by the half-plane boundary, such segment cannot have a larger excess number, which implies $\Phi_{n-1} \leq \Phi_n$ for $n \in \{n_o, n_L, n_R\}$ (see a discrete example in Fig. 3). Hence, $n_L > n_R - 1$ ($n_L < n_R - 1$) in Eq. (6) implies $\Phi_{n_L} > \Phi_{n_R-1}$ ($\Phi_{n_L} < \Phi_{n_R-1}$) and $f_D > 0$ ($f_D < 0$), for

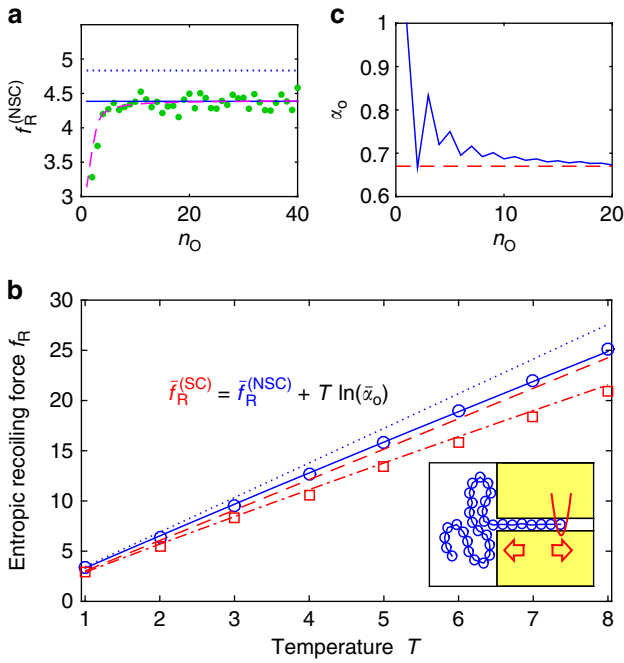


Fig. 3 Relations between the entropic recoiling forces of different kinds of polymer. **a** If a non-self-avoiding chain is pulled into a channel by an optical tweezer (as shown in the inset of **b**), the entropic recoiling forces $f_R^{(NSC)}$ calculated by the Jarzynski equality at $d = 0.05l$, $\kappa/\epsilon = 10^4$, $T = 1$, and different bead numbers outside the channel, n_O , are depicted by the green points. Increasing the number of systems in the ensemble of the Jarzynski equality approach, the green points will become more concentrated onto the magenta dashed curve. The curve saturates at the maximum magnitude $\bar{f}_R^{(NSC)}$ when $n_O > 10$. The blue dotted (solid) line denotes the force $\bar{f}_R^{(NSC)}$ calculated by the recursion formula, without (with) the penetration effect, for which the lateral free space in Fig. 2d is d (is $d + d_e$). **b** For $d = 0.2l$ at different temperatures, the circles (squares) are the force $\bar{f}_R^{(NSC)}$ ($\bar{f}_R^{(SC)}$) of the non-self-avoiding chain (self-avoiding chain) measured via the Jarzynski equality. The dotted (dashed) line denotes the $\bar{f}_R^{(NSC)}$ ($\bar{f}_R^{(SC)}$) calculated by the recursion formula without the penetration effect, while the solid (dash-dotted) line represents the $\bar{f}_R^{(NSC)}$ ($\bar{f}_R^{(SC)}$) calculated by the recursion formula with that effect, which agrees with the circles (squares). The forces $\bar{f}_R^{(NSC)}$ and $\bar{f}_R^{(SC)}$ are related by a specific version of formula (5) written in the plot. **c** The function α_O (blue curve) in Eq. (2) converges to 0.66 (red dashed line). It has a zigzag shape, because α_O behaves differently at even and odd n_O in a lattice space. The error bars in the Jarzynski equality approach vary with the selected ensemble size and are, therefore, not emphasized in **b**

which the chain tends to move leftward (rightward). For $n_L = n_R - 1$, one has $\Phi_{n_L} = \Phi_{n_R-1}$ and $f_D = 0$, for which the chain movement does not have a biased direction. The drift force in Eq. (6) can be decomposed as a difference $f_D = f_{R,(n_L,n_L)} - f_{R,(n_L,n_R-1)}$ between a leftward recoiling force, $f_{R,(n_L,n_L)}$, and a rightward recoiling force, $f_{R,(n_L,n_R-1)}$, with $f_{R,(n,n')} \equiv T \ln [(\Omega_{n-1}\Omega_{n'+1})/(\Omega_n\Omega_{n'})]$ being a generalized expression of Eq. (1). Interestingly, the statistical forces f_D and f_R based on counting configurations also comply with the above subtraction rule as normal non-statistical forces in mechanics. Two drift forces of the same form as Eq. (6) are related as Eq. (2) with α_R there replaced by $\alpha_D \equiv \alpha_l/\alpha_r$, where $\alpha_l \equiv \Phi_{n_L}/\Phi_{n_L}$ and $\alpha_r \equiv \Phi_{n_R-1}/\Phi'_{n_R-1}$ are the same function as the α_O below Eq. (2).

Entropic tension forces. The entropic tension force in Fig. 2c characterizes the tendency of polymer stretching inside a channel.

Table 1 The upper and lower bounds of various entropic forces

Force range	Strip (2D)	Tube (3D)	Slit (3D)
$\begin{bmatrix} \bar{f}_R^{(NSC)} \\ \underline{f}_L^{(NSC)} \end{bmatrix}$	$\begin{bmatrix} T \ln(\frac{2\pi l}{d}) \\ T \ln(\frac{\pi l}{d}) \end{bmatrix}$	$\begin{bmatrix} T \ln(\frac{16l^2}{d^2}) \\ T \ln(\frac{8l^2}{d^2}) \end{bmatrix}$	$\begin{bmatrix} T \ln(\frac{2lq}{d}) \\ T \ln(\frac{lq}{d}) \end{bmatrix}$
$\begin{bmatrix} \bar{f}_D^{(NSC)} \\ \underline{f}_D^{(NSC)} \end{bmatrix}$	$\begin{bmatrix} T \ln 2 \\ -T \ln 2 \end{bmatrix}$	$\begin{bmatrix} T \ln 2 \\ -T \ln 2 \end{bmatrix}$	$\begin{bmatrix} T \ln 2 \\ -T \ln 2 \end{bmatrix}$
$\begin{bmatrix} \bar{f}_T^{(NSC)} \\ \underline{f}_T^{(NSC)} \end{bmatrix}$	$\begin{bmatrix} T \ln(\frac{4\pi l}{d}) \\ T \ln(\frac{2\pi l}{d}) \end{bmatrix}$	$\begin{bmatrix} T \ln(\frac{32l^2}{d^2}) \\ T \ln(\frac{16l^2}{d^2}) \end{bmatrix}$	$\begin{bmatrix} T \ln(\frac{4lq}{d}) \\ T \ln(\frac{2lq}{d}) \end{bmatrix}$

The maxima (minima) of the entropic recoiling, drift, and tension forces of a non-self-avoiding chain are denoted by the upper (lower) components in the column vectors, where $d > 1/\rho$, with ρ the linear density of the bead configurations (Supplementary Note 1). The parameter $q \in [1, \infty)$ characterizes the angle $2\pi/q$ a bead in a stretched chain segment inside a quasi-2D slit can rotate. Because the force $f^{(NSC)}$ of the non-self-avoiding chain is smaller than the force $f^{(SC)}$ of the self-avoiding chain, $|f^{(NSC)}| < |f^{(SC)}|$, the maximum $\bar{f}^{(NSC)}$ of $f^{(NSC)}$ is an upper bound of the maximum $\bar{f}^{(SC)}$ of $f^{(SC)}$.

The simplest version of that force describes the tendency of moving one bead from the channel into the left or the right space,

$$f_T = T \ln \left(\frac{\Omega_{n_L+1}\Omega_{n_R-1}\Omega_{n_R} + \Omega_{n_L}\Omega_{n_R-1}\Omega_{n_R+1}}{\Omega_{n_L}\Omega_{n_L}\Omega_{n_R}} \right) = T \ln \left(\frac{\Phi_{n_L} + \Phi_{n_R}}{\Phi_{n_L-1}} \right). \tag{7}$$

Since $\Phi_{n_L}, \Phi_{n_R} > \Phi_{n_L-1}$, f_T is always positive, indicative of a spontaneous trend of stretching, rather than compression, in that system. This trend will eventually be counterbalanced by the increased free energy during stretching caused by other mechanisms, such as bead deformation. Two tension forces of the same form as Eq. (7) can be related as Eq. (2), with α_R there replaced by $\alpha_T \equiv \alpha_l\alpha_r$, where $\alpha_{lr} \equiv (\Phi_{n_L} + \Phi_{n_R})/(\Phi'_{n_L} + \Phi'_{n_R})$ and $l = l'$ is not required, as in Eq. (2). For large n_L and n_R , $\Phi_{n_L}, \Phi_{n_R}, \Phi'_{n_L}$, and Φ'_{n_R} are approximately the same as Φ_{n_O} at large n_O , which implies $f_T \approx T \ln(2\Phi_{n_O}/\Phi_{n_L})$ and $\alpha_T \approx \alpha_l\alpha_r = \alpha_R$.

If C_I and C_O are different, in analogy to Eq. (3), the generalized tension force is $f_T = T \ln \left(\frac{[\tilde{\Phi}_{n_L}]^{n_O} + [\tilde{\Phi}_{n_R}]^{n_O}}{[\tilde{\Phi}_{n_L-1}]^{n_L}} \right)$. It is related to another tension force of the same form again by Eq. (5) with a slightly different α . For those C_I and C_O , the drift force f_D in Eq. (6) does not need to be generalized, because C_I is absent in that equation and C_O in the left and right spaces are identical. The upper and lower limits of the above forces for NSCs and SCs in various confinements are derived in Supplementary Note 1 and summarized in Table 1), which serve as good candidates for the values of f° in Eq. (5).

Optical tweezer experiments. To illustrate the above formulas and the analytical results in Table 1, let us carry out the following numerical experiments, with the Hamiltonian described in the Methods section. First, suppose an NSC is pulled into a 2D channel of width w by the drag force f_{drag} of an optical tweezer, which moves slowly rightward with a constant speed (Fig. 2b, d). The work done by f_{drag} is converted to the entropic recoiling force $f_R^{(NSC)}$ via the JE (Methods section), as depicted by the magenta dashed curve in Fig. 3a. This curve shows that for $n_O > 10$, $f_R^{(NSC)}$ has almost saturated at its maximum value $\bar{f}_R^{(NSC)}$ on a plateau (blue solid line), which is independent of the tail length $n_O l$ outside the channel. In contrast to other studies in experiments¹³ and simulations^{16,17}, this tail length independent force is, to our

knowledge, first time determined by the JE. For $n_O < 10$, the curve falls monotonically and drastically with a decreasing n_O to its minimum. The sharp kink around $n_O = 5$ reveals that after most beads have been pulled into the channel, the rest beads in the tail will surrender and give up to resist, which behaves like a first order phase transition¹⁶. In Fig. 3a, the maximum force $\bar{f}_R^{(NSC)}$ is also calculated by the RF (blue dotted line) (Methods section), which is slightly larger than the magenta dashed curve calculated via the JE.

To inspect the cause of this slight difference, we raise the temperature from $T = 1$ ($\tilde{T} = 298$ K) up to a physically extreme value $T = 8$ ($\tilde{T} = 2384$ K) in Fig. 3b. At that T , the $\bar{f}_R^{(NSC)}$ evaluated by the RF (blue dotted line) has deviated 10% from that calculated by the JE (blue circles). However, taking into account the penetration effect by enlarging the channel width $w = l + d$ in the RF approach to $w_e = l + d + d_e$ with d_e being the mean penetration depth in Eq. (8) in the Methods section, the blue dotted line is reduced to the blue solid line in the same plot. The latter passes precisely through all blue circles evaluated by the JE, which justifies the crucial role of the penetration effect and the accuracy of formula (8). Subtracting this effect, the plateau of the magenta dashed curve in Fig. 3a is shifted to the blue dotted line, which is rather close to the magnitude $\bar{f}_R^{(NSC)} = T \ln(2\pi l/d)$ predicted in Table 1. Although that analytical magnitude is derived under the strict assumption of $n_O \gg 1$, the simulation in Fig. 3a shows its correctness even for $n_O > 10$.

If the chain is an SC, the maximum values $\bar{f}_R^{(SC)}$ of the recoiling force $f_R^{(SC)}$ of that chain are calculated by the JE at different T and depicted by the red squares in Fig. 3b. To determine those values from an NSC by Eq. (2), one needs to evaluate $\bar{\alpha}_0$, which is the α_0 at $n_O \gg 1$. For a 2D half-lattice, our Monte Carlo simulation (Fig. 3c) shows that α_0 has almost saturated at its minimum $\bar{\alpha}_0 \approx 0.66$ after $n_O = 10$, which is slightly smaller than that, $\hat{\alpha}_R \approx 0.78$, observed in a 3D half-lattice¹⁸. If f_R and f'_R in formula (2) represent the $\bar{f}_R^{(SC)}$ of an SC and the $\bar{f}_R^{(NSC)}$ of an NSC, respectively, partly confined in the same channel, $\bar{\alpha}_R$ there should be equal to $\bar{\alpha}_R = \bar{\alpha}_i \bar{\alpha}_0 \approx 0.66$, where $\bar{\alpha}_i = 1$ due to identical channels (Supplementary Note 1). Using this formula, $\bar{f}_R^{(NSC)}$ (blue dotted line) in Fig. 3b is converted to $\bar{f}_R^{(SC)}$ (red dashed line), which is the RF calculated force for the SC without the penetration effect. Taking into account that effect by enlarging d to $d + d_e$, the red dashed line is further shifted down to the red dash-dotted line. The latter is very close to the JE calculated red squares, which confirms the specific version of formula (5) written in Fig. 3b.

In Fig. 4a, the maximum recoiling force $\bar{f}_R^{(NSC)}$ for a channel of width $w = l + d$ at different d is calculated by the RF and depicted by the blue solid curve. It deviates from the force evaluated by the JE when the channel has stiffness $\kappa = 10^3 \epsilon$ (diamonds) and $10^4 \epsilon$ (triangles). However, after considering the penetration effect by replacing d by $d + d_e$ as before for $\kappa/\epsilon = 10^3$ ($\kappa/\epsilon = 10^4$), the blue solid curve is shifted to the red dash-dotted (dashed) curve, which precisely passes through the diamonds (triangles) and again justifies the significance of formula (8). All force magnitudes on the blue solid curve agree very well with the analytical results in Table 1, which validates those results at least up to $d = 0.6l$, far beyond the ideal condition $d \ll l$. In Fig. 4b, the stiffness dependent $\bar{f}_R^{(NSC)}$ calculated by the JE at two different T (squares and circles) coincide precisely with those evaluated by the RF (dashed and solid curves). Both curves show a kink around $\kappa/\epsilon = 10^3$, indicative of a separation between the stiffness effect dominant regime ($\kappa/\epsilon < 10^3$) and the width effect dominant regime ($\kappa/\epsilon > 10^3$) for the force. A similar stiffness analysis on a

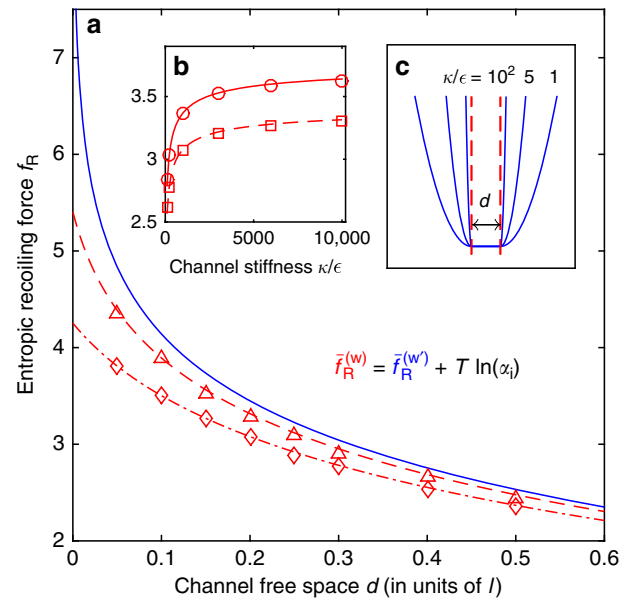


Fig. 4 Relations between the entropic recoiling forces of different channel sizes and stiffnesses. **a** The recoiling forces $\bar{f}_R^{(NSC)}$ of a non-self-avoiding chain for $\kappa/\epsilon = 10^3$ and 10^4 at $T = 1$ and different d measured by the Jarzynski equality approach are depicted by the diamonds and triangles, respectively. The same force for a hard-wall channel ($\kappa = \infty$) calculated by the recursion formula is depicted by the blue solid curve. The divergence of this curve is bounded by a maximum value when d falls into the small area ($0, 1/\rho$), which is the degenerate force explained below Eq. (1). **b** The squares (circles) are the $\bar{f}_R^{(NSC)}$ measured by the Jarzynski equality approach, at $d = 0.2l$, $T = 1.1$, and different stiffnesses κ scaled by ϵ . The dashed (solid) curve denotes those forces calculated by the recursion formula for the effective channel width $w_e = l + d + d_e$, in units of l . **c** The potentials of three different stiffnesses studied in **b** are plotted on the same length scale. The error bars in the Jarzynski equality approach vary with the selected ensemble size and are, therefore, not emphasized in **a, b**

linear channel potential can be found in ref. 19. In Fig. 4c, the potentials of three different stiffnesses are plotted. The force magnitudes calculated in Fig. 4a, b confirm the specific version of formula (5) written in Fig. 4a.

Tug-of-war experiments. In Fig. 5a, the drift forces $f_D^{(NSC)}$ of an NSC of N' beads straddling a channel are calculated by the RF, where the translocation ratio $\xi \equiv n_l/N$, with $N = N' - n_l$, is the fraction of the chain segment in the left space. The left (right) ends of the force curves of different N approach their minimum, $-T \ln 2$, (maximum, $T \ln 2$), as derived in Table 1. These force curves are insensitive to the penetration depth and channel size, in consistent with the absence of Ω_{n_l} and Φ_{n_l} in Eq. (6). Integrating these curves leads to the free energy profiles $F(\xi)$ in Fig. 5b. The barriers of $F(\xi)$ can be used to calculate Kramers' escape rate for polymer translocation, if the process is quasi-equilibrium and ergodicity is preserved²⁰. The curves in Fig. 5b will converge to an invariant shape at large N . In Fig. 5c, the tension forces $f_T^{(NSC)}$ of different N start from some initial values close to $T \ln(3\pi l/d)$ at $\xi = 0$, increase monotonically to their maxima below $T \ln(4\pi l/d)$, and then fall back to their initial values when $\xi = 1$. For larger (smaller) N , the maxima (minima) of the forces will approach $T \ln(4\pi l/d)$ ($T \ln(2\pi l/d)$). All these numerical observations agree with the analytical bounds of $f_T^{(NSC)}$ predicted in Table 1 and Supplementary Note 1.

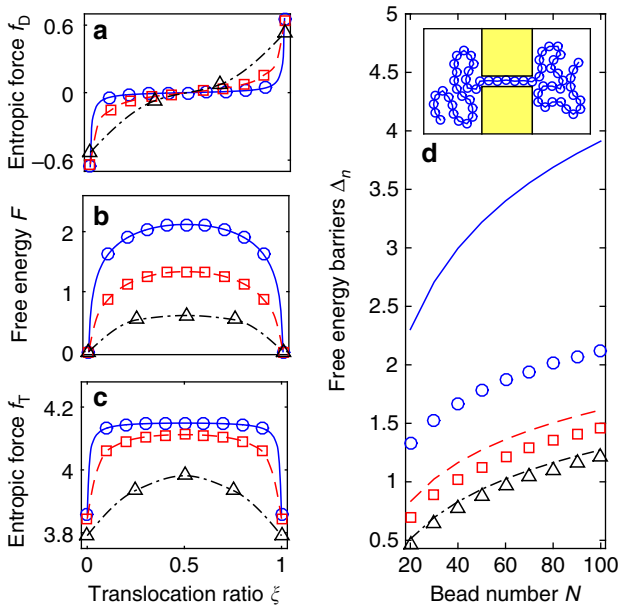


Fig. 5 Entropic drift and tension forces at different chain lengths and translocation ratios. **a** The drift forces $f_D^{(NSC)}$ of a non-self-avoiding chain of $N = 4, 20,$ and 100 are calculated by the recursion formula at different ξ , and fitted by the black dash-dotted, red dashed, and blue solid curves, respectively. When the chain is pulled leftward to increase its n_L starting from $n_L = 0$, it will be resisted by a rightward force, $f_D^{(NSC)}(\xi) < 0$, when $\xi < 0.5$, but assisted by a leftward force, $f_D^{(NSC)}(\xi) > 0$, when $\xi > 0.5$. **b** The free energy profiles $F(\xi)$ are integrated from the curves in **a**, where the two ends of those profiles are set to zero. The integration is carried out along the real length $n_L l$, and then reexpressed as a function of ξ . Therefore, $F(\xi)$ rises with N , although the areas bounded by the curves $f_D^{(NSC)}(\xi)$ in Fig. 5a decrease with N . **c** The tension forces $f_T^{(NSC)}$ calculated by the recursion formula are fitted by the black dash-dotted, red dashed, and blue solid curves for $N = 4, 20,$ and 100 , respectively. **d** The free-energy barrier Δ_n measured from the energy profiles in Fig. 5b gives the blue circles, red squares, and black triangles for $n = 1, 2,$ and 3 , respectively, where $n_1 \gg 1$. The Δ_n calculated by the scaling formula in the main text are the blue solid, red dashed, and black dash-dotted curves, respectively

Let Δ_n be the difference between the entropic free energies of a chain at $n_L = n$ and $N/2$, where the latter is the position of the maximum of the $F(\xi)$ in Fig. 5b. The value of Δ_n reveals the free energy barrier for a chain translocation starting from $n_L = n$. According to a scaling argument, the entropic free energy of a chain of $n_L = n$ is $F_n/k_B \tilde{T} = (1-r) \ln(n) + (1-r) \ln(N-n)$ when n and $N-n \gg 1$ ^{21,22}, where $r = 1/2$ for NSCs. It implies $\Delta_n = (F_{N/2} - F_n)/(k_B \tilde{T}) = (1/2) \ln[(N/2)^2/(n(N-n))]$ for an NSC. In Fig. 5d, the Δ_n calculated by that scaling argument are found to overestimate those measured from the $F(\xi)$ in Fig. 5b. The discrepancy is especially significant in Δ_1 between the solid curve and circles. This is ascribed to the overestimated difficulty of pulling the first few beads into the left space by the scaling formula. It is in echo with the finding in Fig. 3a that $f_R^{(NSC)}$ is weaker than expected for chains with few beads outside the channel.

Applications. Suppose we have a double-stranded DNA (dsDNA) of persistence length $l_p \approx 53$ nm partly confined in a 2D strip (Fig. 2b, c), a 3D circular tube, or a 3D slit of size $w = 110$ nm and stiffness $\kappa = \infty$ pN nm⁻¹ at $\tilde{T} = 298$ K. If this system is modeled by an SC of beads of Kuhn length l_k , then

$l = l_k \approx 2l_p \approx 106$ nm. According to Eq. (5) (Supplementary Note 2), the maximum real forces are $(\hat{f}_R^{(SC)}, \hat{f}_D^{(SC)}, \hat{f}_T^{(SC)}) \approx (0.18, 0.01, 0.21)$ pN for the strip, $(0.35, 0.02, 0.38)$ pN for the tube, $(0.16, 0.02, 0.19)$ pN for the slit when n_1 is so large that an added bead in the slit can freely rotate 2π , and $(0.28, 0.02, 0.31)$ pN if n_1 is so small during strong stretching that an added bead can only rotate a small angle around $2\pi/q = \pi/16$ for $q = 32$.

In an experiment¹², a dsDNA recoiling from a 90-nm-wide and 100-nm-deep channel is estimated to encounter a force $\hat{f}_R^{(exp)} \approx 0.22$ pN. It is slightly larger than the value $\hat{f}_R^{(SC)} \approx 0.18$ pN for a strip of a slightly greater width 110 nm calculated above. In an experiment¹³, a T2 phage dsDNA recoils from an array of nanopillars 35 nm in diameter with a center-to-center spacing of 160 nm. The experimentally estimated recoiling force $\hat{f}_R^{(exp)} \approx 0.04$ pN in that array was bounded by the force $\hat{f}_R^{(SC)} \approx 0.12$ pN in a 2D channel of the same width estimated by formula (5) (Supplementary Note 2). This upper bound is reasonable because the confinement of an array is much weaker than that of a channel of the same size. In an experiment¹⁵, a granular chain above a vibrating platform escapes from a channel. The recorded recoiling force follows exactly the same relation $f_R \sim -\ln(w-l)$ as in Fig. 4a. In another experiment¹⁴, when a dsDNA straddling a nanoslit is entropically pulled out of the slit, it undergoes (i) a tug-of-war scenario, followed by (ii) a recoiling-retraction scenario. The force, $\hat{f}_i^{(exp)}$, in (i) is similar to the above $\hat{f}_T^{(SC)}$, which is counterbalanced by the entropic elasticity of the stretched dsDNA strand inside the nanoslit. The force, $\hat{f}_{ii}^{(exp)}$, in (ii) is closer to our $\hat{f}_R^{(SC)}$, which are dragged by the friction force and the optical tweezer (Fig. 2b), respectively. For a slit 110 nm in height, the forces extracted from the experiment, $(\hat{f}_{ii}^{(exp)}, \hat{f}_{i}^{(exp)}) \approx (0.17, 0.30)$ pN, are not far from $(\hat{f}_T^{(SC)}, \hat{f}_R^{(SC)}) \approx (0.31, 0.28)$ pN of a tightened chain estimated in the previous paragraph. The relation $\hat{f}_{ii}^{(exp)} \approx \hat{f}_R^{(SC)}$ indicates that the allowed rotational angle for beads inside the slit is around $\pi/16$. The ordering $\hat{f}_{ii}^{(exp)} < \hat{f}_T^{(SC)}$ suggests the existence of a non-configurational-entropy effect in $\hat{f}_{ii}^{(exp)}$. Indeed, in addition to increasing the configurational entropy, strong chain stretching may also decrease the microstate number inside a bead or deform the bead. The subsequent increase of free energy will weaken $\hat{f}_{ii}^{(exp)}$, but not $\hat{f}_T^{(SC)}$, leading to $\hat{f}_{ii}^{(exp)} < \hat{f}_T^{(SC)}$. Despite that discrepancy, these two forces are of the same order.

More generally, if a single-stranded DNA (ssDNA) of $l_p \approx 0.75$ nm²³, partly confined in a 2D nanochannel or a 3D circular nanotube of width 1.6 nm and $\kappa = \infty$ pN nm⁻¹, is modeled by an SC comprising beads of three nucleotide bases²⁴, one obtains $l = l_k \approx 1.5$ nm and $d \approx 0.1$ nm. This yields $\hat{f}_R^{(SC)} \approx 11.32$ pN for the nanochannel and 21.76 pN for the nanotube (Supplementary Note 2), which are even larger than the drag force, 5 ~ 6 pN, of a myosin. The increase in the force magnitude from dsDNA to ssDNA is a consequence of the shortened Kuhn length and the narrowed channel width. Owing to the physical limits on these two lengths, 20 pN seems to be close to the maximum entropic force one can observe in nature for a recoiling polymer. For the examples of soft channels, consider a 120-nt ssDNA oligomer²⁵ threaded through an α -hemolysin, which is 10 nm long and has an inner size varying between 1.4 and 4.1 nm¹. If this system is modeled by an NSC of 40 Kuhn segments of $l \approx 1.5$ nm²⁴ and threaded through a circular tube of the same width as l , with a

hypothesized effective stiffness $\kappa = 1 \sim 10^2$ pN nm⁻¹, then the maximum tension force is $\hat{f}_T \approx 1.47 \sim 14.12$ pN (Supplementary Note 2). This analysis provides an instantaneous check for the consistency between the hypothesized d , κ , and forces.

Discussion

The experimental measurement of polymer entropic forces is challenging. The currently reported “measured” force magnitudes are all indirectly inferred from certain force-velocity or force-extension relations. The observed velocity and extension can be affected by several factors, including interfacial friction, Debye length, osmotic force, dye and salt concentrations, and nature of solvent. Even for the more fundamental polymer characteristics, such as persistence length or width of DNA and RNA, the experimentally measured values are often not unique. Thus, some experimentally measured entropic force was considered an “effective” one¹³. With these technical difficulties and system varieties, a coincidence close to 100% between a theoretically predicted force and an experimentally measured one could be accidental, when these forces are as small as a few piconewtons. However, if coincidences of the same order occur concurrently in several systems, as in the above-mentioned examples, the actual force magnitudes are probably not much different from the experimentally and theoretically determined ones.

The formalism proposed in this work overcomes the problem of directly solving partition functions and provides a less-time-consuming reference-based algorithm to assess entropic contributions. This approach is especially simple when a polymer system can be modeled by an ideal confined chain with $\gamma = 1$. Beyond that regime, such as in the de Gennes or Odijk regime, the forces obtained from Eqs. (3) and (5) are as complex as those extracted by other half-analytical approaches (Supplementary Note 3). If other specific interactions, such as the angular and dihedral force-fields, are not coarse-grained in the BUs of a chain model, their entropic contribution has to be derived case by case, as reflected in the widened channel width in Eq. (8), or empirically measured, as the α_o in Fig. 3c. Nevertheless, the forces of a nearby system with $\gamma = 1$, calculated by Eq. (5), can readily provide an upper or a lower bound for the desired systems with $\gamma \neq 1$, as the pillar array discussed above. To sharpen these force bounds, the current formalism further serves as a proper framework, for instance, for selecting more sophisticated UBs C_1 and C_0 or for performing perturbation approaches on Eq. (5) around $\gamma = 1$.

Methods

Hamiltonian. For a chain of N identical beads in the bead-spring model in Fig. 2b, let m and l be the mass and the size of a bead, respectively, whereas \mathbf{x}_i and $\dot{\mathbf{x}}_i$ be the position and the velocity of the i th bead, respectively. The Hamiltonian of the chain is $H = E_K + E_C + E_V + E_O + E_W$, with the kinetic energy $E_K = \sum_{i=1}^N m \dot{\mathbf{x}}_i^2 / 2$, the interaction between consecutive beads $E_C = \sum_{i=1}^{N-1} k_C (|\mathbf{x}_i - \mathbf{x}_{i+1}| - l)^2 / 2$, the excluded volume interaction between non-consecutive beads $E_V = \sum_{i,j=1}^N (i > j) k_V (|\mathbf{x}_i - \mathbf{x}_j| - l)^2 \sigma_{ij} / 2$, the bead-channel interaction $E_W = \sum_{i=1}^N V(\eta_i)$, and the interaction between the last bead and the optical tweezer $E_O = k_O |\mathbf{x}_N - \mathbf{z}|^2 / 2$. Here, the natural length of the spring between two consecutive beads is the same as the bead size l . The value $\sigma_{ij} = 1$ for $|\mathbf{x}_i - \mathbf{x}_j| \leq l$ and 0 for $|\mathbf{x}_i - \mathbf{x}_j| > l$. The position \mathbf{z} denotes the location of the optical tweezer. The potential $V(\eta_i) = \kappa \eta_i^2 / 2$ when the i th bead penetrates a distance η_i into a channel wall (Fig. 2d). Therein, k_C , k_V , k_O , and κ are the force constants in E_C , E_V , E_O , and E_W , respectively. In this system, there is no facial friction and the diffusion coefficient is position independent. For an SC, the bending angle formed by three consecutive beads lies within $[0, 2\pi/3]$.

Penetration effects. Since the channel is narrow, the slight lateral motion of a bead is less affected by its motion along the channel axis. Therefore, the probability density of finding a bead at some lateral position y follows the Boltzmann distribution $e^{-U(y)/k_B T}$, which is depicted by the green area in the upper part of Fig. 2d.

Here, the potential well $U(y)$ consists of a zero-potential area flanked by two walls of the form of the above $V(\eta)$. If that distribution has the same area as an effective uniform distribution (magenta rectangle) of the same height h and of a larger width $d + d_e$, the equality in area implies $2 \int_0^\infty h \exp(-\kappa \eta^2 / (2k_B T)) d\eta + hd = h(d + d_e)$. In analogy, for a 3D circular tube, the equality in volume leads to $\int_0^\infty 2\pi(\eta + d/2)h \exp(-\kappa \eta^2 / (2k_B T)) d\eta + h(d/2)^2 \pi = h(d/2 + d_e/2)^2 \pi$. Therein, d_e is the mean penetration depth into two strip walls in Fig. 2b, c or into the circular tube wall, which is given by

$$d_e = \begin{cases} \sqrt{2\pi T \epsilon / \kappa}, & \text{for 2D strips;} \\ \sqrt{d^2 + B} - d, & \text{for 3D circular tubes,} \end{cases} \quad (8)$$

with ϵ defined in Eq. (1) and $B \equiv 8\epsilon T / \kappa + 2d\sqrt{2\pi T \epsilon / \kappa}$. Although the above soft potential U can generally be interpreted as a soft channel or a soft bead, the latter requires a more subtle model with a varying bead shape during bead-wall collision, which is not considered here.

Langevin dynamics. With the above Hamiltonian H , the i th bead follows a Langevin equation $m \ddot{\mathbf{x}}_i = -\nabla_{\mathbf{x}_i} H - \Xi \dot{\mathbf{x}}_i + \zeta_i$, where $\nabla_{\mathbf{x}_i} H$ is the derivative of H with respect to \mathbf{x}_i , Ξ denotes the friction coefficient, and ζ_i stands for a random force²⁴. That force is Gaussian and white and satisfies the fluctuation-dissipation theorem, with $\langle \zeta_i(t) \rangle = 0$ and $\langle \zeta_i(t) \zeta_j^T(t') \rangle = 4\Xi k_B T \delta(t - t') \delta(i - j)$, where the superscript T represents the transpose. Since the strength of the above random force changes with temperature, the diffusion of beads is temperature dependent as well. To study general real systems, the above equation can be reduced to a dimensionless one, $\tilde{m} \ddot{\tilde{\mathbf{x}}}_i = -\nabla_{\tilde{\mathbf{x}}_i} \tilde{H} - \tilde{\Xi} \dot{\tilde{\mathbf{x}}}_i + \tilde{\zeta}_i$, with the dimensionless quantities: $\tilde{m} \equiv m/M$, $\tilde{\mathbf{x}} \equiv \mathbf{x}/l$, $\tilde{t} \equiv t/\tau$, $\tilde{H} \equiv (\tau^2 / (Ml^2)) H$, $\tilde{k}_C \equiv (\tau^2 / M) k_C$, $\tilde{k}_V \equiv (\tau^2 / M) k_V$, $\tilde{\kappa} \equiv (\tau^2 / M) \kappa$, $\tilde{\Xi} \equiv (\tau / M) \Xi$, and $\tilde{\zeta} \equiv (\tau^2 / (Ml)) \zeta$ in units of some convenient mass M and time τ ²⁴. However, to test the consistency between the force formula (5), the JE and RF approaches, and the analytical results in Table 1, it is sufficient to consider some simple parameter values for the original Langevin equation. In this study, we take $(l, m, \Xi, k_C, k_V, k_O, \kappa / \epsilon) = (1, 1, 1, 10^4, 10^4, 10^4, 0 \sim 10^4)$, where units are not specified.

Jarzynski equality. Let \tilde{W} be the work done by f_{drag} to pull a bead of length l into the channel in Fig. 2b. Owing to fluctuations, the \tilde{W} in different pulling realizations will be different, which form a work distribution. According to the JE¹¹, the free energy change, $\Delta \tilde{F}$, per shifted l is related to \tilde{W} by $e^{-\Delta \tilde{F} / k_B T} = \langle e^{-\tilde{W} / k_B T} \rangle$, where the ensemble mean $\langle \cdot \rangle$ is averaged over the whole work distribution. Therefore, the mean force to counterbalance f_{drag} is the free energy change per shifted bead $\tilde{f} = -\Delta \tilde{F} / l = (k_B T / l) \ln \langle e^{-\tilde{W} / k_B T} \rangle$, which has a dimensionless version $f = \tilde{f} l / \epsilon = T \ln \langle e^{-W / T} \rangle$, with the dimensionless work $W = \tilde{W} / \epsilon$, where ϵ is defined in Eq. (1). The f measured in our numerical recoiling experiments should be the $f_R^{(\text{NSC})}$ derived in Eq. (1) if the change of internal energy is negligible during pulling, which occurs when the channel has a hard-wall or its soft wall is replaced by an effective hard-wall.

Recursion formulas. A recursion formula can be used to count the configuration number of a chain of n beads based on that of a chain of $n - 1$ beads. For a one-dimensional NSC consisting of n rods of unit length, let N_x^n be the configuration number when one end of the chain is anchored to the origin and the other end is located at x between $-n$ and $+n$, where x is an integer. It follows a simple recursion relation $N_x^n = N_{x-1}^{n-1} + N_{x+1}^{n-1}$ for $x = -n, -n + 1, \dots, n - 1, n$, where $N_x^n = 0$ for $|x| > n$. The solutions of this equation are the binomial coefficients $N_x^n = C_{(n+x)/2}^n$ when $x = -n, -n + 2, \dots, n - 2, n$ and $N_x^n = 0$ elsewhere. With those N_x^n , the total number of the chain configurations of n rods is $\Omega_n = \sum_{x=-n}^n N_x^n = 2^n$ and the corresponding configurational entropy is $S = k_B \ln \Omega_n = nk_B \ln 2$. For a chain of n beads of size l in a high-dimensional off-lattice space, the above RF can be generalized to $N_{\mathbf{r}}^n = \int N_{\mathbf{r}'}^{n-1} \delta(|\mathbf{r}' - \mathbf{r}| - l) d\mathbf{r}'$, for which the total number of the chain configurations, $\Omega_n = \int N_{\mathbf{r}}^n d\mathbf{r}$, is an integration over all end-to-end displacement vectors \mathbf{r} of a chain of n beads. To count the configurations of a macrostate of a chain, specified by some (n_1, n_0) , in Fig. 2b, first calculate the configuration number $\Omega_{n_1}(\Omega_{n_0})$ of a chain segment of n_1 (n_0) beads inside (outside) the channel when one segment end is anchored to a point on the cross-section of the channel opening. Summing up the product $\Omega_{n_1} \Omega_{n_0}$ over all different points on that cross-section yields the total configuration number needed for calculating the entropy of the whole chain. Notice that although the RF is able to count the chain configurations within a channel, it cannot reflect the stiffness effect of the channel, unless we use Eq. (8) to replace a soft channel by an effective wider hard channel.

Data availability

All data generated or analyzed during this study are included in this published article (and its Supplementary Information file).

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Author contributions

H.-Q.X. constructed the theory and carried out the analytical and numerical calculations. C.-H.C. initiated the problem, constructed the theory, carried out the analytical calculations, and wrote the paper.

Additional information

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