

## BRIEF COMMUNICATIONS

### Description of the Real von Neumann Algebras with Abelian Skew-Symmetric Part

Sh. A. Ayupov

Received May 7, 2001

**ABSTRACT.** In this note we describe (up to isomorphism) the real von Neumann algebras  $R$  with Abelian skew-symmetric part  $R_k = \{x \in R : x^* = -x\}$ , i.e., such that  $xy - yx = 0$  for any  $x, y \in R_k$ .

**KEY WORDS:** real von Neumann algebra, symmetric element, skew-symmetric element,  $JW$ -algebra, spin factor.

Consider the  $*$ -algebra  $B(H)$  of all bounded linear operators on a complex Hilbert space  $H$ . Recall [1, 2] that a weakly closed real  $*$ -subalgebra  $R$  in  $B(H)$  is called a *real von Neumann algebra* if it contains the identity operator  $\mathbb{I}$  and satisfies the condition  $R \cap iR = \{0\}$ . There is a close relationship between the real von Neumann algebras and the involutive (i.e., period two)  $*$ -antiautomorphisms of (complex) von Neumann algebras (for details, see [1, 2]).

For a real von Neumann algebra  $R$ , the set  $R_s = \{x \in R : x^* = x\}$  of all symmetric elements of  $R$  forms a weakly closed Jordan algebra of self-adjoint operators (a  $JW$ -algebra [3]) with respect to the symmetrized product  $x \circ y = \frac{1}{2}(xy + yx)$ . The set  $R_k = \{x \in R : x^* = -x\}$  of all skew-symmetric elements in  $R$  is a Lie algebra with respect to the commutator  $[x, y] = xy - yx$ .

It follows from the results in [4] that if a real von Neumann algebra  $R$  is Abelian, then it is isomorphic to the direct sum of algebras of the form  $L^\infty(\Omega, \mu, \mathbb{R})$  and  $L^\infty(\Omega, \mu, \mathbb{C})$ , i.e., algebras of essentially bounded measurable (real or complex) functions on a measure space  $(\Omega, \mu)$ . This result was generalized in [5], where it was proved that if  $R$  is a real von Neumann algebra with Abelian symmetric part  $R_s$ , then, along with the above summands,  $R$  can have a direct summand of the form  $L^\infty(\Omega, \mu, \mathbb{Q})$ , where  $\mathbb{Q}$  is the quaternion skew field.

In the present note we describe the real von Neumann algebras  $R$  with Abelian skew-symmetric part  $R_k$ , i.e., such that  $[x, y] = 0$  for any  $x, y \in R_k$ . Namely, we prove the following result.

**Theorem.** *Let  $R$  be a real von Neumann algebra whose skew-symmetric part  $R_k$  is Abelian. Then  $R$  is isomorphic to the direct sum of algebras of the following types:*

- (i)  $L^\infty(\Omega, \mu, \mathbb{R})$ ;
- (ii)  $L^\infty(\Omega, \mu, \mathbb{C})$ ;
- (iii)  $L^\infty(\Omega, \mu, M_2(\mathbb{R})) = L^\infty(\Omega, \mu, \mathbb{R}) \otimes M_2(\mathbb{R})$ ,

where  $M_2(\mathbb{R})$  denotes the algebra of  $2 \times 2$  real matrices.

Before passing to the proof of the theorem we present several preliminary results.

**Lemma 1** (Putnam [6]). *Let  $a, x \in B(H)$ , where  $a$  is normal, i.e.,  $a^*a = aa^*$ . Then  $[a, [a, x]] = 0$  implies  $[a, x] = 0$ .*

**Lemma 2.** *Under the assumptions of the theorem, for any  $x, y \in R_k$ , the product  $xy$  is a central element of  $R$ , i.e., it commutes with every element of  $R$ .*

**Proof.** Since  $R_k$  is Abelian, we have  $(xy)^* = xy \in R_s$ , and  $xy$  commutes with every element of  $R_k$ . Further, since  $xy \in R_s$ , it follows that  $[a, xy] \in R_k$  for any  $a \in R_s$ , and therefore  $[a, xy]$  commutes with  $x$  and with  $y$ , and thus with  $xy$ , i.e.,  $[[a, xy], xy] = 0$ . Since the symmetric element  $xy$  is normal, it follows from Lemma 1 that  $[a, xy] = 0$  for any  $a \in R_s$ . Therefore,  $xy$  commutes with any element in  $R = R_s + R_k$ .

**Lemma 3.** *Under the assumptions of the theorem, if the  $JW$ -algebra  $R_s$  is Abelian, then the real von Neumann algebra  $R$  is commutative.*

**Proof.** By assumption,  $[x, y] = 0$  for any  $x, y \in R_k$ , and  $[a, b] = 0$  for any  $a, b \in R_s$ . Therefore, it suffices to prove that  $[a, x] = 0$  for  $a \in R_s$  and  $x \in R_k$ . Indeed,  $[a, x]^* = [a, x] \in R_s$ , and thus  $[a, [a, x]] = 0$ . Since  $a = a^*$  is normal, it follows from Lemma 1 that  $[a, x] = 0$ .

**Lemma 4.** *Under the assumptions of the theorem, any family of mutually orthogonal pairwise equivalent projections in the  $JW$ -algebra  $R_s$  has at most two elements.*

**Proof.** Suppose the converse, i.e., let there exist three mutually orthogonal and pairwise equivalent projections  $e = e_1, e_2, e_3$ . By [3, Proposition 10] they are conjugate by symmetries, i.e.,  $e_2 = s_2 e s_2$  and  $e_3 = s_3 e s_3$  for some symmetries  $s_2, s_3 \in R_s$  (recall that  $s_2^2 = s_3^2 = \mathbb{I}$ ). Consider the element  $x = s_2 e s_3 - s_3 e s_2 \in R_k$ . Since the projections  $e, e_2$ , and  $e_3$  are orthogonal, it can readily be calculated that  $x^2 = -e_2 - e_3$ . By Lemma 2, the element  $x^2$  is central in  $R$ . On the other hand, consider the element  $a = e s_2 + s_2 e \in R_s$ . Using the orthogonality of  $e, e_2$ , and  $e_3$  again and the relations between them via symmetries, we can readily see that

$$[a, x^2] = -[e s_2 + s_2 e, e_2 + e_3] = s_2 e - e s_2.$$

Therefore,

$$[a, x^2]^2 = (s_2 e - e s_2)^2 = -e_2 - e \neq 0,$$

which contradicts the condition that the element  $x^2$  is central, i.e.,  $[a, x^2] = 0$  for any  $a \in R$ . A contradiction.

**Proof of the theorem.** By Lemma 4, there exists a central projection  $z$  in  $R_s$  such that  $zR_s$  is of type  $I_1$  (i.e., an Abelian  $JW$ -algebra) and  $(\mathbb{I} - z)R_s$  is a type  $I_2$   $JW$ -algebra. The central element  $z$  in  $R_s$  is automatically central in  $R$ . Indeed, for  $x \in R_k$ , the commutator  $[z, x]$  is in  $R_s$ , and therefore  $[z, [z, x]] = 0$ , and Lemma 1 implies that  $[z, x] = 0$ , i.e.,  $z$  commutes with each element of  $R_k$  as well. Thus,  $R = zR \oplus (\mathbb{I} - z)R$ , where the real von Neumann algebra  $zR$  has the Abelian symmetric part  $zR_s$  and the Abelian skew-symmetric part  $(zR)_k = zR_k$ . By Lemma 3, the real von Neumann algebra  $zR$  is Abelian, and, by [4],  $zR$  is isomorphic to the direct sum of algebras of the form (i) and (ii). Therefore, it remains to consider the case in which  $R_s$  is a  $JW$ -algebra of type  $I_2$ .

Since  $a_1 \cdots a_n + a_n a_{n-1} \cdots a_1 \in R_s$  for any  $a_1, \dots, a_n \in R_s$ , it follows that the  $JW$ -algebra  $R_s$  is a *reversible*  $JW$ -algebra of type  $I_2$ . As is known [7], any  $JW$ -algebra of type  $I_2$  can be decomposed into a direct sum of  $JW$ -algebras of the form

$$\sum_{m=3}^{\infty} L^{\infty}(\Omega_m, \mu_m, V_m),$$

where  $\Omega_m$  is a locally compact Hausdorff space,  $\mu_m$  is a Radon measure on  $\Omega_m$ , and  $V_m$  is a spin factor (i.e., a  $JW$ -factor of type  $I_2$ ) of dimension  $m \geq 3$ . On the other hand, if the original  $JW$ -algebra is reversible, then all spin factors  $V_m$  are reversible as well, which is possible only if  $m = 3, 4$ , or  $6$  (see [8]), i.e., if  $V_3 \cong M_2(\mathbb{R})_s$ ,  $V_4 \cong M_2(\mathbb{C})_s$ , or  $V_6 \cong M_2(\mathbb{Q})_s$ . As is known [9, Theorem 3],  $M_k = [M_s, M_s]$  for any real factor  $M$  except for  $\mathbb{Q}$ , i.e., any skew-symmetric element of  $M$  is a finite sum of commutators of symmetric elements in  $M$ . In particular, the skew-symmetric matrices in  $M_2(\mathbb{F})$  are algebraically generated by  $M_2(\mathbb{F})_s$  (where  $\mathbb{F} = \mathbb{R}, \mathbb{C}$  or  $\mathbb{Q}$ ). Therefore, if the reversible  $JW$ -algebra  $R_s$  contains direct summands of the form  $L^{\infty}(\Omega, \mu, M_2(\mathbb{F})_s)$ , then  $R$  contains direct summands of the form  $L^{\infty}(\Omega, \mu, M_2(\mathbb{F}))$ . However, for  $\mathbb{F} = \mathbb{C}$  or  $\mathbb{Q}$ , the algebra  $M_2(\mathbb{F})$  has skew-symmetric matrices which do not commute, and this contradicts the assumption of the theorem. Therefore, the only possible case is  $R_s = L^{\infty}(\Omega, \mu, M_2(\mathbb{R})_s)$ .

As noted above, in this case the algebra  $R$  contains the algebra  $R^0 = L^{\infty}(\Omega, \mu, M_2(\mathbb{R}))$ . We claim that  $R = R^0$ . Indeed,  $R_s = R_s^0$ . Let  $x \in R_k$ . Consider an arbitrary invertible skew-symmetric element  $u \in R_k^0$ , for instance, the function on  $\Omega$  identically equal to the matrix  $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$  in  $M_2(\mathbb{R})$ .

Then  $xu$  is a symmetric element of  $R_s = R_s^0$ , and therefore  $x = (xu)u^{-1} \in R_s^0 R_k^0 \subset R^0$ . Thus,  $R_k = R_k^0$  and  $R = R_s + R_k = R_s^0 + R_k^0 = R^0$ , which proves that if the  $JW$ -algebra  $R_s$  is of type  $I_2$ , then  $R = L^\infty(\Omega, \mu, M_2(\mathbb{R}))$ , i.e., case (iii) takes place. This completes the proof of the theorem.

### References

1. Sh. Ayupov, A. Rakhimov, and Sh. Usmanov, Jordan, Real and Lie Structures in Operator Algebras, Kluwer Acad. Publ., Dordrecht, 1997.
2. E. Størmer, Pacific J. Math., **21**, No. 2, 349–370 (1967).
3. D. M. Topping, Mem. Amer. Math. Soc., **53** (1965).
4. Li Minli and Li Bingren, Acta Math. Sinica, **14**, No. 1, 85–90 (1998).
5. Sh. A. Ayupov, A. A. Rakhimov, and A. Kh. Abduvaitov, Dokl. AN RUz, No. 4–5, 3–6 (2001).
6. C. R. Putnam, Amer. J. Math. **73**, 357–362 (1951).
7. P. J. Stacey, Quart J. Math. Oxford Ser. 2, **33**, No. 129, 115–127 (1982).
8. A. G. Robertson, Quart. J. Math. Oxford Ser. 2, **34**, No. 133, 87–96 (1983).
9. Sh. A. Ayupov and N. A. Azamov, Comm. Algebra, **24**, No. 4, 1501–1520 (1996).

INSTITUTE OF MATHEMATICS, UZBEKISTAN ACAD. SCI.  
 e-mail: e\_ayupov@hotmail.com, ayupov@im.tashkent.su

*Translated by Sh. A. Ayupov*