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Estimation of Population Mean Using Imputation Methods for Missing Data Under Two-Phase Sampling Design

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Abstract

This manuscript emphasizes the estimation procedure of population mean in twophase sampling when non-response occurs during survey in both phases of sample data. To cope with the problem of missing data, some new imputation methods have been suggested for estimating the population mean which utilize the information on two auxiliary variables. The properties of the resultant estimators are studied which are followed by empirical and simulation studies accomplished on real as well as on artificial data sets which justify the suggested imputation methods. Results are significantly analyzed, and appropriate suggestions are made to the survey practitioners.

Keywords Non-response \cdot Auxiliary variable \cdot Imputation \cdot Bias \cdot Mean square error \cdot Sampling design

Mathematics Subject Classification 62D05

1 Introduction

Missing data are the most frequent occurring feature in sample surveys, and recognizing its stochastic nature is of utmost importance in order to use appropriate methodology for handling the data sets. Failure in recognition of its nature may distort the inferences about population characteristics/parameters; therefore, the assiduous attempt is needed for handling of the data sets with missing values. A fundamental query appears in this regard that what assumptions to be considered while justifying the ignorability of the complete mechanism. Rubin [1] discussed

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this fundamental query for missing data by establishing ignorability conditions under the classical and Bayesian approach for statistical inference. Further, [2, 3] subsequently generalized the [1] model to include other forms of incompleteness. Initially, [1] addressed three key concepts related to missing pattern of the data sets: missing at random (MAR), observed at random (OAR) and parameter distribution (PD). He mentioned "The data are MAR if the probability of the observed missingness pattern, given the observed and unobserved data, does not depend on the values of the unobserved data. The data are OAR, if for every possible value of the missing data, the probability of the observed missingness pattern, given the observed and unobserved data, does not depend on the values of observed data." Later, the combination of MAR and OAR is called missing completely at random (MCAR). Heitain and Basu [4] have differentiated MAR and MCAR mechanism with series of examples. Based on these works, the pattern of the missing mechanism of data sets is recognized and inference related to population parameter is made under some strategies according to their obtained pattern. These methods are termed as "imputation methods." Imputation is the procedure of replacing missing data with fabricated values. Abundant of works have been carried out based on imputation methods, such as [5-17].

The information related to the auxiliary variable may be used either at the planning stage or at design stage or survey stage or at estimation stage to get the improved precision of the estimates. When the information on auxiliary variable correlated with study variable is readily available, ratio, regression and their transformed and improved methods have been widely used to obtain efficient estimates, anticipating the information on the population mean of the auxiliary variable. In spite of that, the knowledge of the population mean of the auxiliary variable is not always available. In such circumstances, two-phase sampling or double scheme is a widely used sampling scheme to obtain the reliable estimates of unknown population mean of auxiliary variable in survey studies. The presence of missing data during survey sampling under two-phase sampling design enforces the researchers to implement the imputation methods for obtaining trustworthy conclusion regarding population parameters. Several researchers like [18–21] and others have suggested some imputation methods for compensating existence of the missing data with the assumption that the complete response may not be available on the study variable as well as on the auxiliary variable in second-phase sample. It is worth to be mentioned that very limited attention has been paid to deal with the situations, when the complete response is not available in the first-phase sample as well.

Following the aforementioned arguments and motivated with the work of [9], authors have proposed some effective imputation methods under missing completely at random (MCAR) response mechanism, which result in the point estimators of the population mean of study variable in two-phase sampling design. The properties of the proposed estimators have been discussed. Empirical and simulation studies are accomplished to authenticate the propositions of the suggested imputation methods and resultant estimators. Suitable recommendations have been made to the survey practitioners for real-life applications.

2 Sampling Design and Notations

Let $P = (P_1, P_2 \dots P_N)$ be a finite population of size N indexed by triplet characters (y, x, z). It is assumed that y is the study variable and (x and z) are the (first and second) auxiliary variables, respectively, such that y is positively correlated with x and z, while in comparison with x, it is remotely correlated with z. When the population mean \bar{X} of the first auxiliary variable is not known but information on the second auxiliary variable z is available for all the units of the population, the following two-phase sampling scheme has been designed for making inference about the population parameters.

Let s' be the first-phase sample of size n' drawn using simple random sampling without replacement (SRSWOR) scheme from the population and surveyed for the auxiliary variable x to estimate its population mean \bar{X} . The second-phase sample of size n < n' is drawn to measure the study characteristic y under the following design:

Design I The second-phase sample *s* is drawn from the first-phase sample *s' Design II* The second-phase sample *s* is independently drawn from the entire population.

We have assumed that non-response occurs in the first- and second-phase samples where r' and r are the number of responding units in the first- and second-phase samples of sizes n' and n, respectively. The corresponding sets of responding units are denoted by $(R_1 \text{ and } R_2)$ and the sets of non-responding units by $(R_1^c \text{ and } R_2^c)$, respectively. We have also assumed that sample units in the second-phase sample s have been drawn from the responding set R_1 .

3 Proposed Methods of Imputation and Subsequent Estimators

In this section, using the compromised method of imputation in the first-phase sample, we have proposed some new compromised imputation methods under MCAR response mechanism in the second-phase sample for missing data on the study variable *y*. The proposed imputation methods and resultant estimators are given below:

3.1 Imputation for Missing Data in the First-Phase Sample

To compensate the missing values on auxiliary variable x in the first-phase sample, we considered the ratio method of imputation; hence, after imputation, the sample data in x take the following form:

$$x_{i} = \begin{cases} \frac{\alpha n' x_{i}}{r'} + (1 - \alpha) \hat{b}' z_{i} & \text{if } i \in R_{1} \\ (1 - \alpha) \hat{b}' z_{i} & \text{if } i \in R_{1}^{c} \end{cases}$$
(1)

where $\hat{b'} = \frac{\sum_{i=1}^{r'} x_i}{\sum_{i=1}^{r'} z_i}$ and α is an unknown constant. Under the imputation method

described in Eq. (1), the point estimator of the population mean \bar{X} in the first-phase sample is derived as

$$\bar{x}' = \frac{1}{n'} \left\{ \sum_{i \in R_1} x_{,i} + \sum_{i \in R_1^c} x_{,i} \right\}$$

which produces the point estimator of the population mean \bar{X} in the first-phase sample as

$$\bar{x}' = \alpha \bar{x}_{r'} + (1 - \alpha) \bar{x}_{r'} \frac{\bar{z}_{n'}}{\bar{z}_{r'}}$$
(2)

where $\bar{x}_{r'} = \frac{\sum_{i \in R_1} x_i}{r'}$, $\bar{z}_{r'} = \frac{\sum_{i \in R_1} z_i}{r'}$ and $\bar{z}_{n'} = \frac{\sum_{i=1}^{n'} z_i}{n'}$.

3.2 Imputation for Missing Data in the Second-Phase Sample

To derive the reliable substitutes for missing values in the second-phase sample, we suggest two new compromised imputation methods which are presented below:

First Imputation Method Under this method of imputation, sample data take the following forms

$$y_{i} = \begin{cases} \frac{\alpha_1 n y_i c}{r} + (1 - \alpha_1) \hat{b} z_i c & \text{if } i \in R_2\\ (1 - \alpha_1) c \hat{b} z_i & \text{if } i \in R_2^c \end{cases}$$
(3)

where $c = \frac{1}{\bar{x}_n} \alpha \bar{x}_{r'} + (1 - \alpha) \bar{x}_{r'} \frac{\bar{z}_{n'}}{\bar{z}_{r'}}, \ \hat{b} = \frac{\sum_{i=1}^r y_i}{\sum_{i=1} z_i}$ and α_1 is suitably chosen constant

such that the mean square error of resultant estimator is minimum.

Under the imputation method described in Eq. (3), the point estimator of the population mean \bar{Y} takes the following form

$$\zeta_{1} = \frac{\left\{\alpha_{1}\bar{y}_{r} + (1 - \alpha_{1})\bar{y}_{r}\frac{\bar{z}_{n}}{\bar{z}_{r}}\right\}}{\bar{x}_{n}} \left\{\alpha\bar{x}_{r'} + (1 - \alpha)\bar{x}_{r'}\frac{\bar{z}_{n'}}{\bar{z}_{r'}}\right\}.$$
(4)

Second Imputation Method Under this method of imputation, sample data take the following forms

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$$y_{,i} = \begin{cases} \frac{\alpha_2 n y_i}{r} + (1 - \alpha_2) \hat{b}_{z_i} & \text{if } i \in R_2 \\ (1 - \alpha_2) \hat{b}_{z_i} + \frac{1}{n - r} \hat{b}_{yx}(r) \left\{ \alpha \bar{x}_{r'} + (1 - \alpha) \bar{x}_{r'} \frac{\bar{z}_{n'}}{\bar{z}_{r'}} - \bar{x}_n \right\} & \text{if } i \in R_2^c \end{cases}$$
(5)

where $\hat{b}_{yx}(r) = \frac{s_{yx}}{s_x^2}$ and α_2 is suitably chosen constant such that the mean square error

of resultant estimator is minimum.

Under the imputation method described in Eq. (5), the point estimator of the population mean \bar{Y} takes the following form

$$\zeta_{2} = \left\{ \alpha_{2} \bar{y}_{r} + (1 - \alpha_{2}) \bar{y}_{r} \frac{\bar{z}_{n}}{\bar{z}_{r}} \right\} + \hat{b}_{yx}(r) \left\{ \alpha \bar{x}_{r'} + (1 - \alpha) \bar{x}_{r'} \frac{\bar{z}_{n'}}{\bar{z}_{r'}} - \bar{x}_{n} \right\}.$$
(6)

4 Properties of Estimators ζ_1 and ζ_2

The properties of the proposed estimators ζ_1 and ζ_2 have been explored under two different types of two-phase sampling design opted for MCAR response mechanism. Large sample approximations have been used in order to obtain the expressions of biases and mean square errors of the proposed estimators using the following transformations:

$$\begin{split} \bar{y}_r &= \bar{Y} \left(1 + e_0 \right), \bar{x}_r = \bar{X} \left(1 + e_1 \right), \bar{x}_{r'} = \bar{X} \left(1 + e_1' \right), \bar{x}_n = \bar{X} (1 + e_2), \bar{x}_{n'} = \bar{X} (1 + e_2'), \\ \bar{z}_{r'} &= \bar{Z} (1 + e_3'), \bar{z}_n = \bar{Z} (1 + e_4), \bar{z}_{n'} = \bar{Z} (1 + e_4'), s_{yx}(r) = S_{YX} (1 + e_5), s_x^2(r) = S_X^2 (1 + e_6), \\ \text{such that } E(e_i') &= E(e_i) = 0, |e_i'| \le 1 \text{ and } |e_i| \le 1 \forall i, i' = 0, 1, 2, 3, 4, 5, 6. \end{split}$$

Under the above transformations, the estimators ζ_1 and ζ_2 take the following forms:

$$\zeta_1 = \bar{Y} \left\{ \alpha_1 (1+e_0) + (1+\alpha_1)(1+e_0) \frac{1+e_4}{1+e_3} \right\} \frac{(1+e_1')}{(1+e_2)} \frac{(1+e_4')}{(1+e_3')}$$
(7)

and

$$\begin{aligned} \zeta_2 &= \bar{Y}(1+e_0) \left\{ \alpha_2 + (1-\alpha_2) \frac{(1+e_4)}{(1+e_3)} \right\} \\ &+ \beta_{YX} \frac{(1+e_5)}{(1+e_6)} \bar{X} \left[(1+e_1') \left\{ \alpha + (1-\alpha) \frac{(1+e_4')}{(1+e_3')} \right\} - (1+e_2) \right] \end{aligned} \tag{8}$$

where $\beta_{YX} = \frac{S_{YX}}{S_X^2}$.

4.1 Biases and Mean Square Errors of Estimators ζ_1 and ζ_2

Let $B(.)_d$ and MSE(.)_d be the bias and mean square error, respectively, of an estimator under a given two-phase sampling design d(= I, II).

Theorem 4.1 The biases of the estimators ζ_1 and ζ_2 are given by

$$B(\zeta_1)_I = \bar{Y} \Big[\delta_2 (C_X^2 - \rho_{YX} C_Y C_X) + \{ \delta_3 (1 - \alpha_1) + \delta_4 (1 - \alpha) \} (C_Z^2 - \rho_{YZ} C_Y C_Z) \Big]$$
(9)

$$B(\zeta_1)_{II} = \bar{Y} \left[f_1 (C_X^2 - \rho_{YX} C_Y C_X) + \delta_3 (1 - \alpha_1) (C_Z^2 - \rho_{YZ} C_Y C_Z) + \delta_4 (1 - \alpha) (C_Z^2 - \rho_{XZ} C_X C_Z) \right]$$
(10)

$$B(\zeta_2)_I = \bar{Y}\delta_3(1-\alpha_2)(C_Z^2 - \rho_{YZ}C_YC_Z) + \beta_{YX}\bar{X}\Big[\delta_4(1-\alpha)(C_Z^2 - \rho_{XZ}C_XC_Z)\Big] + \beta_{YX}\bar{X}\bigg[\frac{\delta_2}{\bar{X}}\bigg(\frac{\mu_{030}}{\mu_{020}} - \frac{\mu_{120}}{\mu_{110}}\bigg) + \frac{(1-\alpha)(\delta_4)}{\bar{Z}}\bigg(\frac{\mu_{021}}{\mu_{020}} - \frac{\mu_{111}}{\mu_{110}}\bigg)\bigg]$$
(11)

$$B(\zeta_2)_{II} = \bar{Y}\delta_3(1 - \alpha_2)(C_Z^2 - \rho_{YZ}C_YC_Z) + \beta_{YX}\bar{X} \left[\delta_4(1 - \alpha)(C_Z^2 - \rho_{XZ}C_XC_Z)\right] + \beta_{YX}\bar{X}\frac{f_1}{\bar{X}} \left(\frac{\mu_{120}}{\mu_{110}} - \frac{\mu_{030}}{\mu_{020}}\right)$$
(12)

where

$$\delta_1 = \left(\frac{1}{r} - \frac{1}{N}\right), \delta_2 = \left(\frac{1}{n} - \frac{1}{r'}\right), \delta_3 = \left(\frac{1}{r} - \frac{1}{n}\right), \delta_4 = \left(\frac{1}{r'} - \frac{1}{n'}\right), \delta_5 = \left(\frac{1}{n'} - \frac{1}{N}\right), \delta_6 = \left(\frac{1}{r'} - \frac{1}{N}\right) \text{ and } f_1 = \left(\frac{1}{n} - \frac{1}{N}\right).$$

Proof The bias of the estimator ζ_1 is derived as

$$B(\zeta_1)_d = E(\zeta_1 - \bar{Y})$$

= $E\left[\bar{Y}\left\{\alpha_1(1+e_0) + (1+\alpha_1)(1+e_0)\frac{1+e_4}{1+e_3}\right\}\frac{(1+e_1')}{(1+e_2')}\frac{(1+e_4')}{(1+e_3')} - \bar{Y}\right]$ (13)

Now, expanding the right-hand sides of Eq. (13) binomially, taking expectation under the sampling designs I and II, respectively, and retaining the terms up to the

first order of approximations, we get the expression of the bias of the proposed estimator ζ_1 under sampling designs I and II as obtained in Eqs. (9)–(10).

In similar fashion, we derive the expression of bias of the proposed estimator ζ_2 under sampling designs I and II as obtained in Eq. (11)–(12).

Theorem 4.2 The mean square errors of the estimators ζ_1 and ζ_2 are given by

$$MSE(\zeta_1)_I = \bar{Y}^2 \Big[\delta_1 C_Y^2 + \delta_2 (C_X^2 - 2\rho_{YX} C_Y C_X) + \delta_3 \{ (1 - \alpha_1)^2 C_Z^2 - 2(1 - \alpha_1)\rho_{YZ} C_Y C_Z \} + \delta_4 \{ (1 - \alpha)^2 C_Z^2 - 2(1 - \alpha)\rho_{YZ} C_Y C_Z \} \Big]$$
(14)

$$MSE(\zeta_1)_{II} = \bar{Y}^2 \left[\delta_1 C_Y^2 + \delta_6 C_X^2 + f_1 (C_X^2 - 2\rho_{YX} C_Y C_X) + \delta_3 \{ (1 - \alpha_1)^2 C_Z^2 - 2(1 - \alpha_1)\rho_{YZ} C_Y C_Z \} + \delta_4 \{ (1 - \alpha)^2 C_Z^2 - 2(1 - \alpha)\rho_{XZ} C_X C_Z \} \right]$$
(15)

$$MSE(\zeta_{2})_{I} = \bar{Y}^{2} \Big[(\delta_{1} - \delta_{2}\rho_{YX}^{2})C_{Y}^{2} + \delta_{3} \{ (1 - \alpha_{2})^{2}C_{Z}^{2} - 2(1 - \alpha_{2})\rho_{YZ}C_{Y}C_{Z} \} \Big] + \delta_{4} \Big[(1 - \alpha)^{2}\beta_{YX}^{2}\bar{X}^{2}C_{Z}^{2} - 2(1 - \alpha)\bar{Y}\bar{X}\beta_{YX}\rho_{YZ}C_{Y}C_{Z}) \Big]$$
(16)

and

$$MSE(\zeta_2)_{II} = \bar{Y}^2 \Big[(\delta_1 - f_1 \rho_{YX}^2) C_Y^2 + \delta_3 \{ (1 - \alpha_2)^2 C_Z^2 - 2(1 - \alpha_2) \rho_{YZ} C_Y C_Z \} \Big] \\ + \beta_{YX}^2 \bar{X}^2 \Big[\delta_4 \{ (1 - \alpha)^2 C_Z^2 - 2(1 - \alpha) \rho_{XZ} C_X C_Z \} \} + \delta_6 C_X^2 \Big].$$
(17)

Proof The mean square error of the estimator ζ_1 is derived as

$$\begin{split} \text{MSE}(\zeta_1)_d &= E(\zeta_1 - \bar{Y})^2 \\ &= E \left[\bar{Y} \left\{ \alpha_1 (1 + e_0) + (1 + \alpha_1)(1 + e_0) \frac{1 + e_4}{1 + e_3} \right\} \frac{(1 + e_1')}{(1 + e_2)} \frac{(1 + e_4')}{(1 + e_3')} - \bar{Y} \right]^2 \end{split}$$
(18)

Now, expanding the right-hand sides of Eq. (18) binomially, taking expectation under the sampling designs I and II, respectively, and retaining the terms up to the first order of approximations, we get the expressions of the mean square error of the proposed estimator ζ_1 under sampling designs I and II as obtained in Eqs. (14)–(15). In similar fashion, we derive the expression of mean square error of the proposed estimator ζ_2 under sampling designs I and II as obtained in Eqs. (16)–(17).

4.2 Minimum Biases and Mean Square Errors of the Estimators ζ_1 and ζ_2

Since the mean square errors of estimators ζ_1 and ζ_2 under two types of sampling designs mentioned in Eqs. (14)–(17) are the functions of unknown scalars α , α_1 and α_2 , the optimum choices of α , α_1 and α_2 are obtained by minimizing the mean square errors given in Eqs. (14)–(17) with respect to α , α_1 and α_2 as

$$\alpha_{1(\text{opt})_{I}} = \alpha_{1(\text{opt})_{II}} = 1 - \rho_{YZ} \frac{C_Y}{C_Z}$$
(19)

$$\alpha_{2(\text{opt})_{I}} = 1 - \rho_{YZ} \frac{C_Y}{C_Z} \quad \text{and} \quad \alpha_{2(\text{opt})_{II}} = 1 - \rho_{YZ} \frac{C_Y}{C_Z}$$
(20)

For estimator ζ_1 , we have

$$\alpha_{(\text{opt})_I} = 1 - \rho_{YZ} \frac{C_Y}{C_Z} \quad \text{and} \quad \alpha_{(\text{opt})_{II}} = 1 - \rho_{XZ} \frac{C_X}{C_Z}$$
(21)

For estimator ζ_2 , we have

$$\alpha_{(\text{opt})_I} = 1 - \frac{\rho_{YZ}C_X}{\rho_{YX}C_Z} \quad \text{and} \quad \alpha_{(\text{opt})_{II}} = 1 - \rho_{XZ}\frac{C_X}{C_Z}$$
(22)

The optimum biases of the proposed estimators ζ_1 and ζ_2 have been obtained by putting the optimum choices of α , α_1 and α_2 from Eqs. (19)–(22) in Eqs. (9)–(12). The optimum biases of the proposed estimators ζ_1 and ζ_2 under two types of two-phase sampling designs are given as

$$B^{*}(\zeta_{1})_{I} = \bar{Y} \Big[\delta_{2} (C_{X}^{2} - \rho_{YX} C_{Y} C_{X}) + (\delta_{3} + \delta_{4}) (\rho_{YZ} C_{Y} C_{Z} - \rho_{YZ}^{2} C_{Y}^{2}) \Big]$$
(23)

$$B^{*}(\zeta_{1})_{II} = \bar{Y} \Big[f_{1}(C_{X}^{2} - \rho_{YX}C_{Y}C_{X}) + \delta_{3}(\rho_{YZ}C_{Y}C_{Z} - \rho_{YZ}^{2}C_{Y}^{2}) + \delta_{4}(\rho_{XZ}C_{X}C_{Z} - \rho_{XZ}^{2}C_{X}^{2}) \Big]$$
(24)

$$B^{*}(\zeta_{2})_{I} = \bar{Y}\delta_{3}(\rho_{YZ}C_{Y}C_{Z} - \rho_{YZ}^{2}C_{Y}^{2}) + \beta_{YX}\bar{X}\left[\delta_{4}\frac{\rho_{YZ}}{\rho_{YX}}(C_{X}C_{Z} - \rho_{XZ}C_{X}^{2})\right] + \beta_{YX}\bar{X}$$

$$\left[\frac{\delta_{2}}{\bar{X}}\left(\frac{\mu_{030}}{\mu_{020}} - \frac{\mu_{120}}{\mu_{110}}\right) + \frac{(1 - \alpha)(\delta_{4})}{\bar{Z}}\left(\frac{\mu_{021}}{\mu_{020}} - \frac{\mu_{111}}{\mu_{110}}\right)\right]$$
(25)

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$$B^{*}(\zeta_{2})_{II} = \bar{Y}\delta_{3}(\rho_{YZ}C_{Y}C_{Z} - \rho_{YZ}^{2}C_{Y}^{2}) + \beta_{YX}\bar{X}\left[\delta_{4}(\rho_{XZ}C_{X}C_{Z} - \rho_{XZ}^{2}C_{Z}^{2})\right] + \beta_{YX}f_{1}\left(\frac{\mu_{120}}{\mu_{110}} - \frac{\mu_{030}}{\mu_{020}}\right).$$
(26)

The minimum mean square errors of the proposed estimators ζ_1 and ζ_2 have been obtained by putting the optimum choices of α , α_1 and α_2 from Eqs. (19)–(22) in Eqs. (14)–(17). The optimum mean square errors of the proposed estimators ζ_1 and ζ_2 under two types of two-phase sampling designs are denoted by $M(\zeta_1)_d$ and $M(\zeta_1)_d$, respectively, and given as

$$M(\zeta_1)_I = \bar{Y}^2 \left[\{ \delta_1 - (\delta_3 + \delta_4) \rho_{YZ}^2 \} C_Y^2 + \delta_2 (C_X^2 - 2\rho_{YX} C_Y C_X) \right]$$
(27)

$$M(\zeta_1)_{II} = \bar{Y}^2 \left[(\delta_1 - \delta_3 \rho_{YZ}^2) C_Y^2 + (\delta_6 - \delta_4 \rho_{XZ}^2) C_X^2 + f_1 (C_X^2 - 2\rho_{YX} C_Y C_X) \right]$$
(28)

$$M(\zeta_2)_I = \bar{Y}^2 \left[(\delta_1 - \delta_2 \rho_{YX}^2) C_Y^2 - (\delta_3 + \delta_4) \rho_{YZ}^2 \right]$$
(29)

and

$$M(\zeta_2)_{II} = \bar{Y}^2 \Big[(\delta_1 - f_1 \rho_{YX}^2) - \delta_3 \rho_{yz}^2 \Big] C_Y^2 + \beta_{yx}^2 \bar{X}^2 C_X^2 \Big(\delta_6 - \delta_4 \rho_{xz}^2 \Big).$$
(30)

5 Some Well-Known Methods of Imputation

In the single-phase sampling design when the sample of size n is selected from the population under SRSWOR scheme and the non-response occurs in the sample data, some classical methods of imputation are presented in this section under the assumption that information on the auxiliary variable x is available for each and every units of the population.

5.1 Mean Method of Imputation

The mean method of imputation gives the data as:

$$y_{i} = \begin{cases} y_{i} & \text{if } i \in R \\ \bar{y}_{r} & \text{if } i \in R^{c} \end{cases}$$
(31)

Under the imputation method discussed in Eq. (31), the corresponding point estimator of the population mean \bar{Y} is derived as

$$\bar{y}_m = \frac{1}{r} \sum_{i=1}^r y_{,i} = \bar{y}_r.$$
 (32)

The variance of the estimator \bar{y}_m is obtained as

$$v(\bar{y}_m) = \delta_1 \bar{Y}^2 C_Y^2. \tag{33}$$

5.2 Ratio Method of Imputation

The ratio method of imputation gives the data as:

$$y_{i} = \begin{cases} y_{i} & \text{if } i \in R \\ \hat{b}x_{i} & \text{if } i \in R^{c} \end{cases}$$
(34)

where $\hat{b} = \frac{\sum_{i \in R}^{\cdot} y_i}{\sum_{i \in R}^{\cdot} x_i}$.

Under the imputation method discussed in Eq. (34), the corresponding point estimator of the population mean \bar{Y} is derived as

$$\bar{y}_{\text{rat}} = \frac{1}{n} \sum_{i=1}^{n} y_{.i} = \bar{y}_r \frac{\bar{x}_n}{\bar{x}_r}.$$
(35)

The mean square error of the estimator \bar{y}_{rat} up to the first order of approximations is obtained as

$$M(\bar{y}_{rat}) = \bar{Y}^2 \left[\delta_1 C_Y^2 + \delta_3 (C_X^2 - 2\rho_{YX} C_Y C_X) \right].$$
(36)

5.3 Regression Method of Imputation

The regression method of imputation gives the data as

$$y_{,i} = \begin{cases} y_i & \text{if } i \in R\\ \hat{a} + \hat{b}_{yx} x_i & \text{if } i \in R^c \end{cases}$$
(37)

where $\hat{b}_{yx} = \frac{s_{yx}(r)}{s_x^2(r)}$ and $\hat{a} = (\bar{y}_r - \hat{b}_{yx}\bar{x}_r)$. Under the imputation method discussed in

Eq. (37), the corresponding point estimator of the population mean \bar{Y} is derived as

$$\bar{y}_{\text{reg}} = \frac{1}{n} \sum_{i=1}^{n} y_{,i} = \bar{y}_r + \hat{b}_{yx} (\bar{x}_n - \bar{x}_r).$$
(38)

The mean square of the estimator $\bar{y}_{\rm reg}$ up to the first order of approximations is obtained as

$$M(\bar{y}_{\rm reg}) = \bar{Y}^2 C_Y^2 \Big[\delta_1 - \delta_3 \rho_{yx}^2 \Big].$$
(39)

6 Analytical Comparison

In this section, we compare the suggested estimators with existing classical estimators \bar{y}_m , \bar{y}_{rat} and \bar{y}_{reg} .

Lemma 6.1

(i) The proposed estimator ζ_1 under first-phase design is more efficient than \bar{y}_m if

$$M(\zeta_1)_I - \nu(\bar{y}_m) < 0 \Rightarrow \frac{1 - 2\rho_{YX}}{\rho_{YZ}^2} < \frac{\delta_3 + \delta_4}{\delta_2}.$$

(ii) The proposed estimator ζ_1 under second--phase design is more efficient than \bar{y}_m if

$$M(\zeta_1)_{II} - v(\bar{y}_m) < 0 \Rightarrow 1 - 2\rho_{YX} < \frac{\delta_3 \rho_{YZ}^2 + \delta_4 \rho_{XZ}^2 - \delta_6}{f_1}.$$

(iii) The proposed estimator ζ_2 under first-phase design is more efficient than \bar{y}_m if $M(\zeta_2)_I - v(\bar{y}_m) < 0 \Rightarrow \delta_2 \rho_{YZ}^2 + (\delta_3 + \delta_4) \rho_{YZ}^2 > 0$

which is always true.

(iv) The proposed estimator ζ_2 under second-phase design is more efficient than \bar{y}_m if

 $M(\zeta_2)_{II} - v(\bar{y}_m) < 0 \Rightarrow \bar{Y}^2(f_1 \rho_{YX}^2 + \delta_3 \rho_{YZ}^2) > \bar{X}^2 \beta_{YX}^2(\delta_6 - \delta_4 \rho_{XZ}^2)$

Lemma 6.2

(i) The proposed estimator ζ_1 under first-phase design is more efficient than \bar{y}_{rat} if

$$M(\zeta_1)_I - M(\bar{y}_{\text{rat}}) < 0 \Rightarrow \frac{1 - 2\rho_{YX}}{\rho_{YZ}^2} < \frac{\delta_3 + \delta_4}{\delta_2 - \delta_3}.$$

(ii) The proposed estimator ζ_1 under second-phase design is more efficient than \bar{y}_{rat} if

$$M(\zeta_1)_{II} - M(\bar{y}_{rat}) < 0 \Rightarrow 1 - 2\rho_{YX} < \frac{\delta_3 \rho_{YZ}^2 + \delta_4 \rho_{XZ}^2 - \delta_6}{f_1 - f_3}.$$

- (iii) The proposed estimator ζ_2 under first-phase design is more efficient than \bar{y}_{rat} if
- $$\begin{split} M(\zeta_2)_I M(\bar{y}_{\rm rat}) < 0 \Rightarrow \delta_2 \rho_{YX}^2 + (\delta_3 + \delta_4) \rho_{YZ}^2 + \delta_3 (1 2\rho_{YX}) > 0 \\ which is always true if \rho_{YX} > \frac{1}{2}. \end{split}$$
- (iv) The proposed estimator ζ_2 under second-phase design is more efficient than \bar{y}_{rat} if

$$M(\zeta_{2})_{II} - M(\bar{y}_{rat}) < 0 \Rightarrow 1 - 2\rho_{YX} > \frac{\beta_{YX}^{2} \bar{X}^{2} (\delta_{6} - \delta_{4} \rho_{XZ}^{2}) - (\delta_{3} \rho_{YZ}^{2} + f_{1} \rho_{YX}^{2}) \bar{Y}^{2}}{\delta_{3} \overline{Y}^{2}}.$$

Lemma 6.3

(i) The proposed estimator ζ_1 under first-phase design is more efficient than \bar{y}_{reg} if

 $M(\zeta_1)_I - M(\bar{y}_{\rm reg}) < 0 \Rightarrow \delta_3 \rho_{YX}^2 + \delta_2 (1 - 2\rho_{YX}) < (\delta_3 + \delta_4) \rho_{YZ}^2.$

(ii) The proposed estimator ζ_1 under second-phase design is more efficient than \bar{y}_{reg} if

 $M(\zeta_1)_{II} - M(\bar{y}_{\rm reg}) < 0 \Rightarrow \delta_3 \rho_{YX}^2 + f_1(1 - 2\rho_{YX}) < (\delta_4 \rho_{XZ}^2 + \delta_3 \rho_{YZ}^2) - \delta_6.$

(iii) The proposed estimator ζ_2 under first-phase design is more efficient than \bar{y}_{reg} if

 $M(\zeta_2)_I - M(\bar{\mathbf{y}}_{\mathrm{reg}}) < 0 \Rightarrow (\delta_3 - \delta_2) \rho_{YX}^2 < (\delta_3 + \delta_4) \rho_{YZ}^2$

(iv) The proposed estimator ζ_2 under second-phase design is more efficient than \bar{y}_{reg} if

$$M(\zeta_2)_{II} - M(\bar{y}_{reg}) < 0 \Rightarrow \bar{Y}^2 \left\{ (\delta_3 - f_1) \rho_{YX}^2 - \delta_3 \rho_{YZ}^2 \right\} + \bar{X}^2 \beta_{YX}^2 (\delta_6 - \delta_4 \rho_{XZ}^2) < 0.$$

Remark 6.1 It may be assumed that $C_Y \approx C_X \approx C_Z$ in the population.

7 Efficiency Comparison

In this section, empirical and simulation studies have been carried out to demonstrate the accomplishment of the proposed methods of imputation and resultant estimators over mean, ratio and regression methods of imputation.

7.1 Empirical Study

To show the practicability of the proposed methods of imputation in the real-life scenario, four natural populations from various survey studies have been chosen for empirical study. The optimum mean square errors of proposed estimators are taken under consideration in empirical study. The percent relative efficiencies of the proposed methods with respect to the classical methods of imputations (mean, ratio and regression) are obtained as

$$E_{11} = \frac{v(\bar{y}_m)}{M(\zeta_1)} \times 100, \quad E_{12} = \frac{M(\bar{y}_{rat})}{M(\zeta_1)} \times 100, \quad E_{13} = \frac{M(\bar{y}_{reg})}{M(\zeta_1)} \times 100;$$
$$E_{21} = \frac{v(\bar{y}_m)}{M(\zeta_2)} \times 100, \quad E_{22} = \frac{M(\bar{y}_{rat})}{M(\zeta_2)} \times 100 \quad \text{and} \quad E_{23} = \frac{M(\bar{y}_{reg})}{M(\zeta_2)} \times 100.$$

The detailed information of populations is given below: *Population I [Source* [22]] (*Page No. 58*)

Y: Head length of second son *X*: Head length of first son *Z*: Head breadth of first son N = 25, n' = 18, r' = 11, n = 9, r = 7.

Population II [Source: [23]] (Page No. 399)

Y: Area under wheat in 1964 *X*: Area under wheat in 1963 *Z*: : Cultivated area in 1961 N = 34, n' = 22, r' = 14, n = 11, r = 8.

Population III [Source: [24]] (Page No. 182)

Y: Number of 'placebo' children *X*: Number of paralytic polio cases in the placebo group *Z*: Number of paralytic polio cases in the 'not inoculated' group N = 33, n' = 22, r' = 18, n = 12, r = 8.

Population IV [Source: [25] (Page No. 349)

Y: Volume *X*: Diameter *Z*: Height N = 31, n' = 22, r' = 16, n = 10, r = 7.

Table 1 Percent relative efficiencies of the proposed	Population	Design I		Design II	
methods of imputation with respect to mean method of		$\overline{E_{11}}$	E ₂₁	<i>E</i> ₁₁	E ₂₁
imputation	Ι	166.7263	120.0599	170.2578	151.791
	II	344.1896	347.9319	344.3223	336.9121
	III	153.1210	197.6898	204.4901	197.8982
	IV	170.9074	103.5229	166.3121	159.7961
Table 2 Percent relativeefficiencies of the proposed	Population	Design I		Design II	
methods of imputation with respect to ratio method of		<i>E</i> ₁₂	<i>E</i> ₂₂	$\overline{E_{12}}$	E ₂₂
imputation	Ι	143.9904	103.6878	147.0403	131.0918
	II	226.3443	228.8053	226.4315	221.5584
	III	123.7454	95.73043	133.0007	130.4266
	IV	127.7331	147.7498	152.8322	147.9056
Table 3Percent relativeefficiencies of the proposed	Population	Design I		Design II	
methods of imputation with respect to regression method of		<i>E</i> ₁₃	E ₂₃	<i>E</i> ₁₃	E ₂₃
imputation	Ι	140.7310	101.3406	143.7118	128.1244
	II	226.2768	228.7371	226.3640	221.4924
	III	102.8689	79.58021	110.5628	108.4229
	IV	108.9643	126.0398	130.3755	126.1727

The percent relative efficiencies are computed for the above-mentioned populations under both sampling designs I and II and shown in Tables 1, 2 and 3.

7.2 Simulation Study

A computer simulation is an endeavor to model a real-life or hypothetical scenarios on a computer so that it may be studied to see how the proposed system, strategies or methods works. The inference may be made about the behavior of the proposed system, strategies or methods by changing parameters in the simulation study. It is a tool to virtually investigate the behavior of the method or system under study. Inspired by this argument, we have run simulation study to investigate the behavior of the proposed imputation methods with respect to classical methods of imputation. The simulation studies have been performed on three artificial computer generated data sets to know the percent relative efficiencies and losses of proposed estimators due to the presence of non-response in the population. The description of artificial data sets is given as:

Population V Source: [Artificially Generated Data Set]

A population of size N = 2000 are generated from the multivariate normal distribution in R software. The study variable y is positively correlated with auxiliary variables with fixed correlations $\rho_{YX} = 0.7$, $\rho_{YZ} = 0.6$ and $\rho_{XZ} = 0.5$. The parameters used for this population are n' = 800, r' = 640, n = 256, r = 204.

Population VI Source: [Artificially Generated Data Set]

The triplet (y, x, z) is generated of size N = 200. The study variable y is highly correlated with auxiliary variables with fixed correlations $\rho_{YX} = 0.93$, $\rho_{YZ} = 0.87$ and $\rho_{XZ} = 0.95$. We have taken n' = 80, r' = 64, n = 50, r = 40.

Population VII Source: [Artificially Generated Data Set]

The triplet (y, x, z) is generated of size N = 1000 such that $x \sim gamma(4, 2.5), e \sim N(0, 1), z = 1.5x^{0.5} + e, y = 8x + 7z + e$ where $\rho_{YX} > \rho_{Yz}$. We have taken n' = 400, r' = 320, n = 128, r = 102.

In this simulation studies, the following steps have been followed:

Step I Draw a random sample s' of size n' from population size N.

Step II Take out (n' - r') sample units randomly from the first-phase sample each time. Impute dropped units using imputation method contemplated for the first-phase sample.

Step III Draw a random subsample of size n from s' for design I and independent random sample n from N for design II.

Step IV Take out (n - r) sample units randomly from the second-phase sample each time. Impute dropped units using proposed method of imputation contemplated for the second-phase sample.

Step V Compute relevant statistics.

Step VI Repeat the above steps $\binom{N}{n=M}$ (say) times.

The simulated variance and mean square errors of the existing and proposed estimators are obtained as:

$$\begin{aligned} \operatorname{var}^*(\bar{Y}_M) &= \frac{1}{M} \sum_{j=1}^M ((\bar{y}_m)_j - \bar{Y})^2, M^*(\bar{y}_{rat}) = \frac{1}{M} \sum_{j=1}^M (\bar{y}_{rat})_j - \bar{Y})^2, M^*(\bar{y}_{reg}) \\ &= \frac{1}{M} \sum_{j=1}^M ((\bar{y}_{reg})_j - \bar{Y})^2, \\ M^*(\zeta_1)_d &= \frac{1}{M} \sum_{j=1}^M ((\zeta_1)_{dj} - \bar{Y})^2 \quad \text{and} \quad M^*(\zeta_2)_d = \frac{1}{M} \sum_{j=1}^M ((\zeta_1)_{dj} - \bar{Y})^2 \end{aligned}$$

The simulated percent-related efficiencies are given as

$$E'_{11} = \frac{\operatorname{var}^*(\bar{y}_m)}{M^*(\zeta_1)_d} \times 100, \quad E'_{12} = \frac{M^*(\bar{y}_{rat})}{M^*(\zeta_1)_d} \times 100, \quad E'_{13} = \frac{M^*(\bar{y}_{reg})}{M^*(\zeta_1)_d} \times 100;$$
$$E'_{21} = \frac{\operatorname{var}(\bar{y}_m)}{M^*(\zeta_2)_d} \times 100, \quad E'_{22} = \frac{M^*(\bar{y}_{rat})}{M^*(\zeta_2)_d} \times 100 \quad \text{and} \quad E'_{23} = \frac{M^*(\bar{y}_{reg})}{M^*(\zeta_2)_d} \times 100.$$

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Population	$B(\xi_1)_I$	$B(\xi_2)_I$	$B(\xi_1)_{II}$	$B(\xi_2)_{II}$	$B(\bar{y}_m)$	$B(\bar{y}_{\rm rat})$	$B(\bar{y}_{reg})$
I	- 0.0035	- 0.0185	0.0224	0.0170	- 0.0071	- 0.0158	- 0.0069
II	- 0.7398	- 0.3272	- 0.8430	- 0.5335	0.0920	- 0.0525	0.0915
III	0.2768	0.2418	0.2661	0.2195	0.0665	0.2234	- 0.0359
IV	- 0.2358	- 0.0651	- 0.1998	- 0.0664	- 0.0034	- 0.0913	- 0.0613

Table 4 Bias of proposed, mean, ratio and regression estimators under imputation method

Population	E'_{11}	E'_{12}	E'_{13}	E'_{21}	E'_{22}	E'_{23}
V	94.79711	111.2117	172.9588	242.4857	284.4733	442.419
VI	202.5033	167.5122	204.283	131.2021	108.5314	132.3552
VII	198.655	151.9309	202.3274	124.9503	95.56174	127.2602

 Table 6
 Percent relative efficiencies of proposed method with respect to mean, ratio and regression methods of imputation under design II

Population	E'_{11}	E'_{12}	E'_{13}	E'_{21}	E'_{22}	E'_{23}
V	-	-	-	166.4769	295.3405	226.3282
VI	110.6395	91.0507	111.6266	132.9174	109.3844	134.1034
VII	165.2897	127.6943	167.7603	135.1092	104.3784	137.1287

The percent relative losses in efficiencies due to non-response of the estimators ζ_1 and ζ_2 are obtained with respect to the similar estimators when non-response has not observed in any phase. The estimators T_1 and T_2 are defined under the similar circumstances as the estimators ζ_1 and ζ_2 , respectively, but under complete response. The simulated percent relative losses in efficiencies of the proposed estimators ζ_1 and ζ_2 with respect to T_1 and T_2 , respectively, under their respective design are given as

$$l_1 = \frac{M'(\zeta_1)_d - \text{MSE}(T_1)_d}{M'(\zeta_1)_d} \times 100 \text{ and } l_2 = \frac{M'(\zeta_2)_d - \text{MSE}(T_2)_d}{M'(\zeta_1)_d} \times 100$$

where

$$MSE(T_1)_d = \frac{1}{M} \sum_{j=1}^M ((T_1)_{dj} - \bar{Y})^2 \text{ and } MSE(T_2)_d = \frac{1}{M} \sum_{j=1}^M ((T_1)_{dj} - \bar{Y})^2.$$

In this study, M = 50,000 has been taken for convenience in calculation. The values of $E'_{ii}(i = 1, 2,), (j = 1, 2, 3)$ and $l_k(k = 1, 2)$ are calculated based on the above proce-

dures and presented in Tables 5, 6, 7, 8, 9 and 10.

Following the above-mentioned simulation study, we have also calculated the biases of the resultant estimators ζ_1 , ζ_2 and existing estimators \bar{y}_m , \bar{y}_{rat} and \bar{y}_{reg} for populations I-IV and shown in Table 4.

8 Interpretations of Empirical and Simulation Results

The following interpretation may be read out form Tables 1, 2, 3, 4, 5, 6, 7, 8, 9 and 10:

- (i) From Tables 1, 2 and 3, it is seen that the percent relative efficiencies of proposed estimators ζ_1 and ζ_2 with respect to the estimators \bar{y}_m , \bar{y}_{rat} and \bar{y}_{reg} are more than 100 in almost cases when percent relative efficiencies have been obtained using the large sample approximations. This reflects the dominance nature of the proposed method of imputations and resultant estimators over the classical method of imputations.
- (ii) From Tables 5 and 6, it is observed that simulated percent relative efficiencies of proposed estimators ζ_1 and ζ_2 with respect to the estimators \bar{y}_m , \bar{y}_{rat} and \bar{y}_{reg} are more than 100 in most of the cases when simulation studies are performed on artificial data sets.
- (iii) From Tables 7, 8, 9 and 10, it is indicated that the percent relative losses in efficiencies l_1 and l_2 of the estimators ζ_1 and ζ_2 under two types of two-phase sampling designs are not more than 30% for both artificial and real populations.
- (iv) From Tables 7 and 8, the negative percent relative losses in efficiencies are observed for some cases under two-phase sample design I which indicates the gain in the precision of estimate.
- (v) From Tables 8, 9 and 10, it is also seen that the percent relative losses in efficiencies l_1 and l_2 are decreasing as the values of r increase for fixed values of N, n', r' and n under both types of two-phase sampling designs. This shows that the percent relative losses in efficiencies are decreasing as percentage of non-response in the second-phase sample decreases.

In Tables 7 and 8, the impact of percent relative losses in efficiencies of the proposed estimators is observed very closely taking into consideration of minor change in percentage of non-response in the second-phase sample and results are shown graphically in Figs. 1, 2, 3, 4, 5 and 6 to get more visible pattern under sampling designs I and II separately.

Non-	r	Design I		Design II	
response in %		<i>l</i> ₁	l_2	l ₁	<i>l</i> ₂
20.3	204	- 5.78817	18.37585	9.91844	22.05380
19.9	205	- 6.31469	18.92934	9.78423	22.37468
19.5	206	- 5.99639	17.22236	10.37980	21.97567
19.1	207	- 6.44455	17.85349	9.99347	21.88525
18.8	208	- 6.25436	16.28825	9.78489	21.35387
18.4	209	- 6.44913	16.77161	9.70870	21.05562
18.0	210	- 6.86914	16.30936	10.00350	20.77964
17.6	211	- 7.01849	15.29330	9.81893	20.39861
17.2	212	- 7.70971	15.23885	9.63560	19.20669
16.8	213	- 6.02526	15.57119	9.45744	19.39193
16.4	214	- 7.16053	14.64099	9.57376	18.67739
16.0	215	- 7.52787	13.78702	9.46119	19.30768
15.6	216	- 7.04825	14.22896	9.38657	18.36987
15.2	217	- 7.09088	13.32298	9.12777	17.94182
14.8	218	- 7.64929	13.68114	9.22407	17.84795
14.5	219	- 7.83837	13.46266	9.19650	17.82550
14.1	220	- 7.45660	12.21393	8.91465	16.92621
13.7	221	- 7.39892	11.83445	9.06312	16.69474
13.3	222	- 8.33907	11.31900	9.54730	16.56260
12.9	223	- 8.10236	11.96917	9.03036	15.71908
12.5	224	- 8.25863	11.31934	9.14293	16.08700
12.1	225	- 7.81661	11.24739	9.04696	15.42324
11.7	226	- 8.40448	10.23890	8.74597	14.73185
11.3	227	- 7.98930	10.33325	8.79993	15.01819
10.9	228	- 8.76567	8.98472	9.08217	14.12681
10.5	229	- 8.45887	9.25380	8.48976	13.52911
10.2	230	- 8.50701	9.03267	8.75179	13.04728
9.8	231	- 9.09961	8.03963	9.19510	13.53535
9.4	232	- 9.10836	7.93695	8.73893	13.19960
9.0	233	- 8.44382	7.93043	8.75542	12.76529
8.6	234	- 9.17175	7.76826	8.41679	12.15552
8.2	235	- 9.96900	7.02693	8.81511	11.55354
7.8	236	- 8.82106	7.28959	8.72726	11.69547
7.4	237	- 8.60567	7.07465	8.59408	11.36768
7.0	238	- 9.49687	5.97648	8.64117	11.28274
6.6	239	- 9.05269	5.69001	8.10258	10.63448
6.3	240	- 9.99699	4.80093	8.57878	10.74080
5.9	241	- 9.53311	5.08852	8.59809	10.46995
5.5	242	- 9.63400	4.76279	8.51161	9.71565
5.1	243	- 9.42295	4.44962	8.53528	9.47632
4.7	244	- 10.00734	3.71636	8.34055	9.10798
4.3	245	- 10.48103	3.39492	8.15473	8.24409

Table 7	Percent relative loss
in efficie	encies of T_1 and T_2 for
populati	on V

Table 7 (continued)

Non-	r	Design I		Design II		
response in %		$\overline{l_1}$	l_2	l_1	l_2	
3.9	246	- 9.88941	3.38665	8.16975	8.46270	
3.5	247	- 10.06214	3.29086	8.04340	7.55059	
3.1	248	- 10.14132	2.57034	8.20028	7.52925	
2.7	249	- 10.46531	2.45727	8.01292	7.55005	
2.3	250	- 10.15615	1.52099	7.69954	7.04355	
2.0	251	- 10.54069	1.41321	8.54029	7.05718	
1.6	252	- 11.12250	1.11616	8.16445	6.66917	
1.2	253	- 10.53713	0.20925	7.92645	5.82650	
0.8	254	- 10.27741	0.14196	7.95137	5.64613	
0.4	255	- 10.39877	- 0.24243	7.94458	5.42982	
0.0	256	- 10.94064	- 0.27996	7.60032	4.94298	

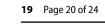
Table 8	Percent relative loss
in efficie	encies of T_1 and T_2 for
populati	on VI

Non-	r	Design I		Design II		
response in %		$\overline{l_1}$	<i>l</i> ₂	$\overline{l_1}$	l_2	
20	40	0.38499	3.22463	20.39023	4.10889	
18	41	- 0.50571	2.65795	19.58656	3.69353	
16	42	- 0.98140	2.63887	19.85537	3.05953	
14	43	- 1.62884	1.97126	19.52627	2.68474	
12	44	- 2.40481	1.53769	19.07874	2.46456	
10	45	- 2.94636	1.15623	18.81600	1.88539	
8	46	- 3.93481	0.73010	18.34428	1.44364	
6	47	- 4.59481	0.31150	18.46878	1.18639	
4	48	- 4.98863	- 0.07682	17.29139	0.69541	
2	49	- 5.69632	- 0.49788	17.29067	0.33158	
0	50	- 6.27116	- 0.81286	16.90846	0.00644	

Table 9	Percent relative loss
in efficie	encies of T_1 and T_2 for
populati	on II

Non-	r	Design I		Design II		
response in %		$\overline{l_1}$	l_2	$\overline{l_1}$	l ₂	
33.3	8	36.95582	14.83099	41.03305	12.51196	
25.0	9	30.64520	8.46692	34.14653	8.73106	
16.7	10	23.86985	7.58180	27.67686	5.44361	
08.3	11	17.51420	3.97377	21.32365	2.58095	
00.0	12	15.93921	0.00102	15.31889	0.00006	

Table 10Percent relative lossin efficiencies of T_1 and T_2 forpopulation VII	Non-	r	Design I		Design II	
	response in %		$\overline{l_1}$	<i>l</i> ₂	l_1	l_2
	0.195	103	26.81336	7.73479	29.08972	8.33188
	0.188	104	26.24445	7.42685	28.39203	7.63929
	0.180	105	26.23111	7.57448	28.12601	7.05548
	0.172	106	25.03845	6.62386	26.57549	7.06049
	0.164	107	24.07782	6.23184	26.92988	6.30257
	0.156	108	22.02978	6.14109	25.23823	6.22763
	0.148	109	22.86167	5.88638	25.19880	5.47770
	0.141	110	21.85859	5.56049	24.44542	5.28713
	0.133	111	20.30682	5.20738	24.28342	5.20218
	0.125	112	20.31858	4.73168	23.29412	4.91795
	0.117	113	19.25704	4.37953	22.84402	4.29005
	0.109	114	18.74893	4.29919	22.22405	4.03677
	0.102	115	17.83962	4.10569	21.72554	3.62004
	0.094	116	17.08092	3.48148	21.07267	3.56363
	0.086	117	16.17240	3.34654	20.96048	3.25696
	0.078	118	15.21242	2.96510	20.23740	2.76381
	0.070	119	14.06151	2.70694	19.59230	2.46887
	0.063	120	13.79710	2.45448	19.47380	2.18053
	0.055	121	13.94238	2.43216	18.36667	2.11684
	0.047	122	11.94824	1.80634	17.72348	1.67985
	0.039	123	10.74092	1.53694	17.81411	1.41050
	0.031	124	10.49605	1.29132	17.09411	1.06919
	0.023	125	10.02008	1.20352	16.58742	0.83095
	0.016	126	9.02589	0.89909	15.76101	0.56016
	0.008	127	7.42204	0.63633	15.51021	0.20878
	0.000	128	7.52170	0.36594	14.21055	0.02435



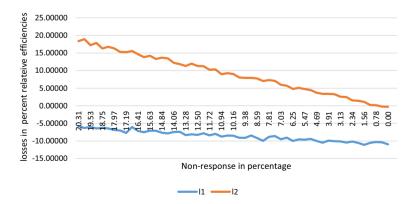


Fig. 1 Losses in percent relative efficiencies under design I for population ${\rm V}$

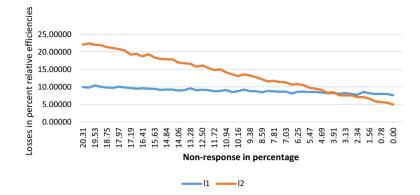


Fig. 2 Losses in percent relative efficiencies under design II

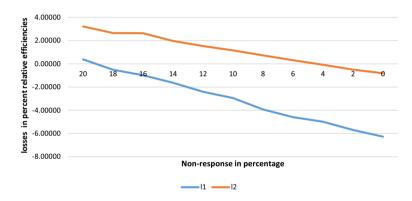


Fig. 3 Losses in percent relative efficiencies under design I for population VI

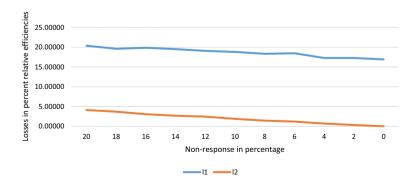


Fig. 4 Losses in percent relative efficiencies under design II for population VI

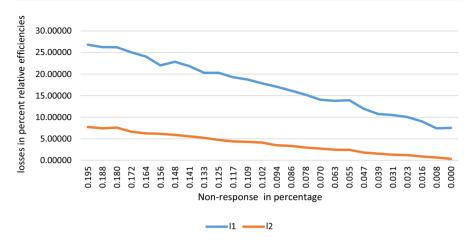


Fig. 5 Losses in percent relative efficiencies under design I for Population VII

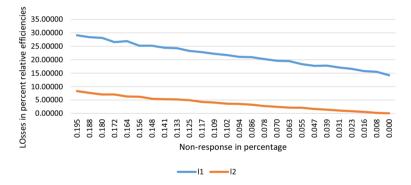


Fig. 6 Losses in percent relative efficiencies under design II for Population VII

From Figs. 1, 2, 3, 4, 5 and 6, it is easily seen that the percent relative losses in efficiencies of proposed estimators are decreasing as the percentage of non-response decreases under both types of sampling designs.

9 Conclusions and Recommendations

When the proposed methods of imputation under study have implemented in real-life scenario, proposed methods are remunerating in terms of percent relative efficiencies. These strategies are also showing their superiority in terms of percent relative efficiencies over classical imputation methods namely mean, ratio and regression methods of imputation when simulation studies have been performed over artificial data sets. The percent relative losses in efficiency of proposed estimators are less than 30% whenever non-response occurs 20% or

less of sample size. These results support that the proposed methods of imputations described in this study are appreciatively favorable in diminishing the pessimistic effect of non-response on inference to a greater extend as compared to the classical methods of imputation. Hence, looking on the persuaded behavior of the suggested imputation methods, survey practitioner may be encouraged for their practical applications, whenever non-response is inescapable in the survey data.

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