### **RESEARCH ARTICLE**



# **Chaotic Social Group Optimization for Structural Engineering Design Problems**

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#### **Abstract**

Till now, several novel metaheuristic algorithms are proposed for global search. But only specifc algorithms have become popular or attracted researchers, who are efficient in solving global optimization problems as well as real-world application problems. The Social Group Optimization (SGO) algorithm is a new metaheuristic bioinspired algorithm inspired by human social behavior that attracted researchers due to its simplicity and problem-solving capability. In this study, to deal with the problems of low accuracy and local convergence in SGO, the chaos theory is introduced into the evolutionary process of SGO. Since chaotic mapping has certainty, ergodicity, and stochastic property, by replacing the constant value of the self-introspection parameter with chaotic maps, the proposed chaotic social group optimization algorithm increases its convergence rate and resulting precision. The proposal chaotic SGO is validated through 13 benchmark functions and after that 9 structural engineering design problems have been solved. The simulated results have been noticed as competent with that of state-of-art algorithms regarding convergence quality and accuracy, which certifes that improved SGO with chaos is valid and feasible.

**Keywords** Chaos · Bionic algorithm · Constrained optimization · SGO · Design problem

# **1 Introduction**

For simplicity and gradient-free mechanism, metaheuristic optimization algorithms are becoming popular among researchers globally. According to the no-free lunch (NFL) theorem [\[1](#page-23-0)], a single metaheuristic optimization algorithm cannot solve all optimization problems. It may solve some problems with high performance and some problems with low performance. Hence, researchers have invented many optimization algorithms, and every year new algorithms are being proposed. At the same time, the existing algorithms are also improved.

Till now, several novel metaheuristic algorithms are proposed for global search. These algorithms reveal improved performances in comparison to traditional optimization techniques, especially when applied to solve non-convex optimization problems [\[2](#page-23-1)]. Satapathy et al. have developed a promising metaheuristic algorithm, called social group

 $\boxtimes$  Anima Naik animanaik@vignaniit.edu.in optimization (SGO) in year 2016, which is inspired by humans social behavior to solve complex problems [\[3](#page-23-2)]. Preliminary studies suggest that the SGO demonstrates superior results when compared with other metaheuristics algorithms  $[4, 5]$  $[4, 5]$  $[4, 5]$  $[4, 5]$ .

The metaheuristic algorithms consist of two essential steps exploration and exploitation. Exploration refers to searching the whole search space of the algorithm. This factor shows the capability of a method in global search. Exploitation is the capability to fnd local optimum around diferent feasible solutions It has been seen that if an optimization algorithm has good exploration capability, then it will be lacking in good exploitation capability and vice versa [\[6](#page-23-5)]. Previously, researchers were using random walks and gradient descent methods for improving exploration and exploitation, respectively. But, increasing the overall computational cost of the algorithm, researchers are using chaotic maps to improve diversifcation and local exploitation of search space to find the optimal solutions [[7,](#page-23-6) [8](#page-23-7)]. The interesting property of the systems is that when there is a minor change in the system, the whole system gets affected [[9\]](#page-23-8).

In the past, various metaheuristic optimization algorithms have been used together with chaotic sequences

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such as Artificial Bee Colony (ABC) optimization [[10](#page-23-9)], Harmony Search (HS) [\[11\]](#page-23-10), Particle Swarm Optimization (PSO) [[12\]](#page-23-11), genetic algorithm (GA) [\[13](#page-23-12)], diferential evolution (DE)  $[14]$ , simulated annealing (SA)  $[15]$  $[15]$ , firefly algorithm (FA) [\[16\]](#page-23-15), krill herd (KH) [\[17](#page-23-16)], imperialist competitive algorithm (ICA)[[18\]](#page-23-17), biogeography-based optimization (BBO) [[19](#page-23-18)], bat algorithm (BA) [\[20\]](#page-23-19), gravitational search algorithm (GSA) [[8\]](#page-23-7), Bird swarm algorithms (BSA) [[21](#page-23-20)], league championship algorithms (LCA) [\[22](#page-23-21)], and farmland fertility (FF) [[23\]](#page-23-22).

Based on the SGO algorithm, in this paper, a family of the chaotic algorithm is proposed, called Chaotic SGO (CSGO). The insertion of chaotic maps in the structure of the CSGO algorithm is motivated by the following arguments: (1) the SGO functions with various dimensions and characteristics (unimodal, multimodal, composite) [[5\]](#page-23-4). Thus, it is expected that in the case of structural engineering problems this efficiency will be maintained. (2) Consulting several databases, we found that the SGO algorithm equipped with various chaotic maps has not been used in solving the structural engineering problem (3). In addition, CSGO algorithms are easy to implement and have the ability to maintain a good balance between exploration and exploitation, thus being able to generate promising solutions during the iterative process. Again to evaluate the proposed family of CSGO algorithms, 13 benchmark functions are utilized and their performances are compared: with 10 metaheuristics optimization algorithms.

Normally, metaheuristic algorithms show good results on benchmark functions, but they perform poorly on realworld problems. The practical problem is an actual test for checking the problem-solving capabilities of an optimization algorithm. Therefore, to further evaluate the validity of the proposed family of CSGO algorithms in real-world applications, these are used to solve nine structural engineering design problems. The results reveal that there is an improvement in the performance of the proposed algorithms due to the application of deterministic chaotic signals.

The rest of the paper is organized as follows. Section [2](#page-1-0) presents the description of SGO. Section [3](#page-2-0) outlines the chaotic maps that generate chaotic sequences in the SGO. Section [4](#page-10-0) presents the proposed family of CSGO algorithms. Simulations and result analysis are presented in Sect. [5.](#page-10-1) Finally, the conclusions and directions for further research are drawn in Sect. [6.](#page-22-0)

# <span id="page-1-0"></span>**2 Social Group Optimization (SGO) Algorithm**

The SGO algorithm is based on human behavior towards society in solving complex problems. The person is a candidate solution and the person's knowledge is the ftness value of the problem. The human traits are designated as the design variable of the problem which corresponds to the dimension of the problem. The SGO algorithm goes through two phases, namely the improving and acquiring phases. In the group, each individual's knowledge level is improved based on the best individual infuence in the improving phase. The best candidate solution is the one having the highest knowledge level and the ability to solve the problem under concern. The mutual interaction between individuals in the group and at the same time interaction with the best person through the acquiring phase improved each person's knowledge. For a detailed description of the SGO algorithm, please refer to the paper [[3,](#page-23-2) [24\]](#page-23-23). The SGO algorithm, in short, is given as follows:

Let  $P_i$ ,  $i = 1, 2, 3, \ldots, N$ , be the *N* persons of the social group and each person  $P_i$  is defined by  $P_i = (p_{i1}, p_{i2}, p_{i3}, \dots, p_{iD})$ where  $D$  is the number of traits assigned to a person and  $f_i$ 's are their corresponding ftness value, respectively. For every iteration, each person has to undergo the "improving" and "acquiring" phase in the hope of fnding a better solution.

#### **2.1 Improving Phase**

Find best<sub>*P*</sub> = *P<sub>i</sub>* such that  $f_i$  isminmum in social group (1)

$$
Pnew_i = c * P_i + rand * (best_p - P_i)
$$

Accept *P*new if it gives better ftness than *P*

where rand is a random number, rand  $\sim U(0, 1)$ , and *c* is known as a self-introspection parameter in (0,1).

#### **2.2 Acquiring Phase**

 $\text{best}_P = P_i \text{ such that } f_i \text{ is minimum in social group } (2)$ 

Randomly select one person  $P_r$ , where  $i \neq r$ If  $f(P_i) < f(P_r)$ 

$$
Pnew_i = P_i + rand_1 * (P_i - P_r) + rand_2 * (best_P - P_i)
$$

Else

$$
Pnewi = Pi + rand1 * (Pr - Pi) + rand2 * (bestP - Pi)
$$

#### End If

Accept *P*new if it gives better fitness than  $P$  where  $rand_1$  and rand<sub>2</sub> are two independent random numbers, rand<sub>1</sub> ∼  $U(0, 1)$ , and rand<sub>2</sub>  $\sim U(0, 1)$ . These random numbers are used to affect the stochastic nature of the algorithm.

### <span id="page-2-0"></span>**3 Chaotic Map**

Variety of chaotic maps are available in the optimization feld [[25](#page-23-24)]. In this study, 10 most widely used uni-dimensional chaotic maps have been employed [[26](#page-23-25)]. The mathematical forms of chaotic maps employed are represented as follows:

Chebyshev map

 $x_{k+1} = \cos(k\cos^{-1}(x_k))$  (3)

Circle map

$$
x_{k+1} = x_k + b - (P/2\pi)\sin(2\pi x_k) \mod{1}
$$
 (4)

where  $P=0.5$  and  $b=0.2$ .

Gauss map

$$
x_{k+1} = \begin{cases} 0 & x_k = 0\\ \frac{1}{x_k \mod(1)} & \text{otherwise} \end{cases} \tag{5}
$$

$$
\frac{1}{x_k \mod (1)} = \frac{1}{x_k} - \left[\frac{1}{x_k}\right] \tag{6}
$$

Iterative map

$$
x_{k+1} = \sin\left(\frac{P\pi}{x_k}\right) \tag{7}
$$

where  $P \in (0, 1)$  is a suitable parameter.

Logistic map

 $x_{k+1} = Px_k(1 - x_k)$  (8)

*P*=4 is used for the experiments.

Piecewise map

$$
x_{k+1} = \begin{cases} \frac{x_k}{p} & 0 \le x_k \le P\\ \frac{x_k - P}{0.5 - P} & 0 \le x_k \le 0.5\\ \frac{1 - P - x_k}{0.5 - P} & 0.5 \le x_k \le 1 - P\\ \frac{1 - x_k}{P} & 1 - P \le x_k \le 1 \end{cases}
$$
(9)

where  $0 \le P \le 0.5$ .

.

Sine map

$$
x_{k+1} = \sin(\pi x_k) \tag{10}
$$

Singer map

$$
x_{k+1} = P(7.86x_k - 23.31x_k^2 + 28.75x_k^3 - 13.302875x_k^4)
$$
 (11)  
where  $P \in (0.9, 1.08)$ .

Sinusoidal map

<span id="page-2-1"></span>
$$
x_{k+1} = Px_k^2 \sin(\pi x_k) \tag{12}
$$

where  $P=2.3$ .

Tent map

$$
x_{k+1} = \begin{cases} \frac{x_k}{0.7} & x_k < 0.7\\ \frac{10}{3} \left( 1 - x_k \right) & x_k \ge 0.7 \end{cases} \tag{13}
$$

# **4 The Proposed Chaotic Social Group Optimization Algorithms**

On consulting several databases (Scopus, Springer, Elsevier), it can be seen much latest research work has been done through the SGO algorithm. The SGO algorithm has been successfully applied to many research areas such as in the medical feld [\[27](#page-23-26), [28\]](#page-23-27), civil engineering [\[29](#page-23-28)], optimization engineering [\[30\]](#page-23-29), communication engineering [[31\]](#page-23-30), operation management [[32,](#page-23-31) [33\]](#page-24-0), and many more.

In metaheuristic algorithms, randomness is achieved through some probability distributions. Such randomness can be replaced with a chaotic map due to similar properties of randomness with better statistical and dynamic properties. Such dynamical mixing helps the algorithm to diverse enough to reach every mode in the multimodal objective landscape. Due to the ergodicity and mixing properties of chaos, algorithms perform the iterative search at higher speeds than standard stochastic searches with standard probability distributions.

While going through the literature on the SGO algorithm, we have found that there is only a single paper on SGO which is combined with chaotic concepts [\[34](#page-24-1)]. In this paper, the self-inspection parameter 'C' value is replaced by two chaotic strategies as Chaotic decreasing inertia weight and Chaotic random inertia weight where logistic maps are aggregated with two popular techniques i.e., liner decreasing inertia weight and random inertia weight. Here,

authors proved that the chaotic maps do not signifcantly afect the convergence of SGO. Again the authors replaced the '*C*' value with another adaptive chaotic inertia weight to adjust the weight with logistic maps to introduce chaotic sequence into iterations and proved that SGO with adaptive chaotic inertia weight performs better for some benchmark functions.

In the SGO algorithm, the self-introspection parameter  $C = 0.2$  is made constant for all the persons in all generations, and this parameter is responsible for a person to improve his/her knowledge level from the current position towards the optimum position. In order to increase the searchability of the algorithm, the parameter *C* should be changed or redefned in a manner such that the improvement of the person should be done at a higher speed than the standard speed. This can be achieved by selecting diferent *C* values according to the chaotic function, as the insertion of chaotic maps in the structure of metaheuristic algorithms can increase the efficiency of the new algorithm  $[20, 35]$  $[20, 35]$  $[20, 35]$  $[20, 35]$ . Equipping the SGO algorithm with chaotic maps aims to improve the capacity of the CSGO algorithm to avoid local minimums, increase stability and strengthen the global search. Hence if replacement happens the potential benefts of *C* are retained by chaotic numbers.

When the '*C*' value in SGO is replaced by chaotic maps, then the CSGO can be an algorithm-specifc parameter-free algorithm. Then, when we compared CSGO with other algorithms that have diferent parameter settings, we can declare for the CSGO algorithm no need to bother with parameter settings. The selected chaotic maps that produce chaotic numbers in  $(0, 1)$  have been listed in Sect. [3.](#page-2-0) The family of CSGO algorithms maybe simply classifed and described as follows:

In Chaotic SGO1 (CSGO1), Chaotic SGO2 (CSGO2), Chaotic SGO3 (CSGO3), Chaotic SGO4 (CSGO4), Chaotic SGO5 (CSGO5), Chaotic SGO6 (CSGO6), Chaotic SGO7 (CSGO7), Chaotic SGO8 (CSGO8), Chaotic SGO9 (CSGO9), and Chaotic SGO10 (CSGO10) algorithm, the self-introspection parameter C is replaced by a chaotic number generated by the Chebyshev map, circle map, gauss map, iterative map, logistic map, piecewise map, sine map, singer map, sinusoidal map, and tent map, respectively.

Now, it can be said that both original SGO and chaotic SGOs algorithms have the same structure; the only diference between them is the self-introspection parameter that is replaced by chaotic maps in chaotic SGOs and all other conditions remain the same. If we carefully see, four random numbers have been used in SGO: the random numbers in the initialization phase, the improving phase, and two in acquiring phase, and these are not replaced by any chaotic maps in CSGOs. It can be seen from the literature that the chaotic maps replace the random numbers of the chaotic-based stochastic algorithm and even in population initialization.

From paper [[36\]](#page-24-3), the author has experimentally proven that logistic map-based initialization is able to generate more uniformly distributed particles in the allowable search space to enhance the stability of the algorithm. Not replacing random numbers of the CSGO algorithm with any of the chaotic maps create uniqueness in the algorithm. Although there is no mathematical proof for enhancing the stability of the SGO algorithm still, it has been proved through our experiments that the proposed CSGO algorithms increase their convergence rate and the resulting precision than the SGO algorithm.

### **5 Simulation, Experimental Results, and Discussion**

Every novel optimization algorithm must be subjected to well-defned benchmark functions to measure and test the performance. There are many benchmark functions available; however, there is no standardized set of benchmark functions that are agreed upon for validating new algorithms. To validate and benchmark the performance of the proposed CSGO family of algorithms, simulations on 13 benchmark functions are conducted. One of the main reasons for selecting these functions is that they are utilized in many papers [[37–](#page-24-4)[41](#page-24-5)]. Out of 13, 7 are unimodal benchmark functions and 6 are multimodal benchmarks. Detailed descriptions of these benchmark functions are given in papers [[37](#page-24-4)[–41](#page-24-5)]. After that, nine structural engineering design problems are considered, and the detailed descriptions of these design problems are given in their respective cited papers. All algorithms are implemented using MATLAB 2016a, under Microsoft Windows 10 operating system. Simulations are carried out on an Intel Core i5, 8 GB memory laptop.

### **5.1 Algorithm Validation**

For validating the performance of the CSGO family of algorithms, 13 benchmarks are employed as described above and the results are compared with 10 diferent metaheuristics algorithms such as GSA [[42\]](#page-24-6), Whale Optimization Algorithm (WOA) [[37](#page-24-4)], Henry Gas Solubility Optimization (HGSO) [[43\]](#page-24-7), Seagull Optimization Algorithm (SOA) [\[44](#page-24-8)], Marine Predators Algorithm (MPA) [[45](#page-24-9)], Tunicate Swarm Algorithm (TSA) [\[46\]](#page-24-10), Slime Mould Algorithm (SMA) [[47](#page-24-11)], Sooty Term Optimization Algorithm (STOA) [[48](#page-24-12)], Harris Hawks Optimization (HHO) [[38\]](#page-24-13), and Ground-Tour Algorithm (GTA) [[49](#page-24-14)]. In experiment 1, the CSGO family of algorithms is compared with each other, and Table [2](#page-5-0) illustrates the comparative results. Similar to experiment 2, the performance of the CSGO family is compared with the other ten algorithms and Table [3](#page-7-0) illustrates the comparative results. In the experiments, the parameters max\_FEs have been kept fxed at 10,000. Hence, the number of iterations and population size may vary for diferent algorithms. The algorithmic parameter settings are based on the parameters widely used by various researchers and these are mentioned in Table [1](#page-4-0).

### **5.1.1 Experiment 1: The Performance Comparison of the CSGO Family of Algorithms**

In this experiment, the performance of the proposed CSGO family of algorithms such as CSGO1, CSGO2, CSGO3, CSGO4, CSGO5, CSGO6, CSGO7, CSGO8, CSGO9, and CSGO10 are compared with each other. Statistical results of 30 repetitions in terms of the best (BEST), worst (WORST), average (MEAN), and standard deviation (SD) of ftness solutions are determined and reported in Table [2](#page-5-0) to ensure stability and statistical signifcance with the best results are highlighted in bold. In the tables, the symbol '∥' represents that its value is equal to the value of the above column.

It is seen from Table [2](#page-5-0) that the CSGO3 algorithm reaches the global optimum for all the functions except F5–F7, F10, F12, and F13, and in 10 cases out of 13 fnds the best solutions than others. CSGO4 in 6 cases, CSGO7 in 5 cases, and other algorithms except for CSGO9 in 4 cases out of 13 fnd the best solutions, whereas CSGO9 in 3 cases fnds the best solutions. For the F10 function, all algorithms fnd an equivalent solution but not an optimal solution. Hence, it can be said that the CSGO3 algorithm outperformed all other CSGO family algorithms.

### **5.1.2 Experiment 2: The Performance Comparison with Other Metaheuristics Algorithms**

From experiment 1, it can be examined that CSGO3 has shown superior performance in comparison to all algorithms of the CSGO family in terms of ftness function evaluation. Therefore, in this experiment, CSGO3 is compared with the other ten algorithms for performance validation. Statistical results of 30 repetitions in terms of the best (BEST), worst (WORST), average (MEAN), and standard deviation (SD) of ftness solutions are determined and reported in Table [3](#page-7-0) to ensure stability and statistical signifcance with the best

<span id="page-4-0"></span>

<span id="page-5-0"></span>





**Table 2** (continued)

results are highlighted in bold. Table [4](#page-9-0) reports *p* values of the WRS test [[50](#page-24-15)] obtained at a 5% signifcance level of CSGO3 vs. other approaches. The *p* values less than 0.05 indicate that the null hypothesis is rejected, and *p* values that are 'NaN' mean both the input values are the same in Table [4](#page-9-0), "−", "+", and "≈" denote that the performance of other approaches is worse, better, and similar to CSGO3, respectively.

Table [3](#page-7-0) illustrates that the CSGO3 algorithm has the best results in most of the cases than the other compared algorithms for the analyzed benchmarks. As can be seen from Table [4,](#page-9-0) out of 130 cases, only in 7 cases, CSGO3 fnds equivalent results, in 9 cases, CSGO3 fnds the same solution, in 4 cases, CSGO3 fnds a worse solution and in 110 cases, CSGO3 fnds best results than others.

## **5.2 Structural Engineering Design Optimization Problems and Result Analysis**

In structural engineering, design optimization problems are Constrained Optimization Problem (COP) which are highly nonlinear and design variables are involved under complex constraints. Such nonlinearity often results in multimodal response landscape. Subsequently, metaheuristic global optimization algorithms are used to obtain optimal solutions.

#### **5.2.1 Constrained Optimization**

A COP comprises of an objective function together with some equality and inequality constraints. Lower and upper bounds of design variables are often specifed. Considering

<span id="page-7-0"></span>



### **Table 3** (continued)



Algo/functions		F8	F9	F10	F11	F12	F13
<b>STOA</b>	<b>BEST</b>	$-5.8237e+03$	2.1453	0.7407	0.0921	0.0968	1.9846
	<b>WORST</b>	$-4.4813e+03$	89.1702	19.9626	0.9397	2.2575	4.7258
	<b>MEAN</b>	$-5.0923e+03$	42.6491	19.3197	0.5811	0.9978	3.2201
	<b>SD</b>	307.5817	23.9185	3.5090	0.2239	0.5344	0.7318
	$p$ value	$3.0199e - 11$	$1.2118e - 12$	$1.2118e - 12$	$1.2118e - 12$	$3.0199e - 11$	$3.0199e - 11$
HHO	<b>BEST</b>	$-1.2569e + 04$	$\bf{0}$	8.8818e-16	$\bf{0}$	$1.8057e - 09$	$2.2821e - 06$
	<b>WORST</b>	$-1.2566e + 04$	$\bf{0}$	8.8818e-16	$\bf{0}$	$6.7745e - 05$	$4.6801e - 04$
	<b>MEAN</b>	$-1.2568e + 04$	$\bf{0}$	8.8818e-16	$\bf{0}$	$2.0373e - 05$	$1.1551e - 04$
	<b>SD</b>	1.1436	$\bf{0}$	0	$\bf{0}$	$2.1029e - 05$	1.3780e-04
	$p$ value	0.0773	NaN	<b>NaN</b>	<b>NaN</b>	$4.9980e - 09$	$5.5727e - 10$
<b>GTA</b>	<b>BEST</b>	$-6.0633e+03$	$\mathbf{0}$	$1.8652e - 14$	$\mathbf{0}$	0.5241	2.2501
	<b>WORST</b>	$-2.3456e+03$	5.6843e-14	5.8771e-12	$4.7184e - 14$	1.3979	3.1935
	<b>MEAN</b>	$-1.3501e+03$	1.8948e-15	8.8386e-13	$7.4533e - 15$	0.9688	2.9359
	<b>SD</b>	$1.1853e + 03$	$1.0378e - 14$	1.3506e-12	$1.2642e - 14$	0.2434	0.1828
	$p$ value	$3.0199e - 11$	0.3337	1.2088e-12	$1.9280e - 09$	$3.0199e - 11$	$3.0199e - 11$

**Table 3** (continued)

<span id="page-9-0"></span>

"−", "+", and "≈" denote that the performance of other approaches are worse, better, and similar to CSGO3, respectively

that there are *n* design variables, then COP can be written in following form:

Minimize : 
$$
f(X)
$$
  
\nSubjectto :  $g_i(X) \le 0$ ,  $i = 1, 2, ..., m$   
\n $h_k(X) = 0$   $k = 1, 2, ..., p$   
\n $a_j \le x_j \le b_j$   $j = 1, ..., n$   
\n $X = (x_1, x_2, ..., x_n)$  (14)

where the function  $f(X)$  is objective function which is to be minimized. The functions  $g_i(X)$  and  $h_k(X)$  are inequality and equality constraint functions, respectively. There are m inequality constraints and p equality constraints in the above problem. This problem is a nonlinear optimization problem if at least one of the functions  $f(X)$ ,  $g_i(X)$  or  $h_k(X)$ is nonlinear.

Most metaheuristic algorithms are normally designed to work on unconstrained search spaces. Solving COPs using metaheuristic algorithms requires additional mechanisms to incorporate the efects of constraints into their objective function. While solving COPs, it has become necessary to deal with both feasible and infeasible solutions, dealing with the latter having more concerns. It may be possible to ignore all the infeasible solutions but as metaheuristic algorithms are stochastic search methods, completely discarding the infeasible solutions may results in a loss of information about some promising regions of the function landscape.

To remove this confusion and to solve this problem, there is a traditional approach that imposes a penalty [[51\]](#page-24-16) for the infeasible solutions. A constraint violation is included for the penalized candidate solutions. Then, the penalized candidate solutions are handled as an unconstrained objective function that can be optimized using the unconstrained optimizing technique.

#### **5.2.2 Constraint Violation**

The constraint violation  $V(X)$  is the measure that indicates by how much a candidate solution *X* violates the given constraints:

$$
V(X) = 0; \quad \text{if } X \in F \\ V(X) > 0; \quad \text{if } X \notin F \end{cases}
$$
, where *F* is the feasible region (15)

Generally, evaluation of constraint violation in the COP is done using the following two equations:

$$
V(X) = \max\left\{\max_{i} \{0, g_i(X)\}, \max_{k} |h_k(X)|\right\}
$$
 (16)

$$
V(X) = \sum_{i} \max\{0, g_i(X)\}^{m} + \sum_{k} \{|h_k(X)\}^{m}
$$
 (17)

In our study, we have used the approach  $(17)$  with m = 2.

#### **5.2.3 Constraint Handling**

In COP, the constraint handling technique is a necessary criterion to reach the optimal solution within the feasible region (if exists). This is mainly to exploit the infeasible candidate solutions and extract efective information for the stochastic search process. Depending on the constraint violation and the objective function value, Deb's rules [[52\]](#page-24-17) have been chosen for handling constraints.

While solving a COP, it is very difficult to handle the situation if some active constraint is present. All equality constraints are active constraints and for the inequality constraints those satisfy  $g_i(X) = 0$  at the global optimum solution are called active constraints. Therefore, the problems with equality constraint should be handled evasively for a high-quality solution. The equality constraints can be altered into the inequality form and can easily be combined with the inequality constraint. Lots of techniques have been used for this particular operation. Here, we use a tolerance parameter  $(t_p)$  to for converting the equality constraints into inequality form. Therefore, the constraints of Eq.  $(14)$  $(14)$  can be written as

$$
G_{ineq}(X) = \begin{cases} max\{g_i(X), 0\}, & i = 1, ..., m \\ max\{|h_i(X)| - t_p, 0\}, & i = 1, ..., p \end{cases}
$$
 (18)

where  $G_{\text{ineq}}(X)$  is the inequality constraints, and  $t_p$  is a tolerance parameter for the equality constraints.

Thus, the objective is to minimize the ftness function  $f(X)$  such that the optimal solution obtained satisfies all the inequality constraints  $G_{\text{ineq}}(X)$ .

#### **5.2.4 Structural Engineering Design Problems**

The performance of the family of CSGO algorithms are demonstrated in this paper through solving nine structural engineering design problems and the performances are compared with many state-of-the-art as well as latest metaheuristic bionic algorithm algorithms of literature.

#### <span id="page-10-0"></span>**5.2.4.1 Parameter Settings and Evaluation Criterion**

- *Stopping criterion:* Maximum number of function evaluations 20,000.
- *Runs*: 30 independent runs
- *Statistical results*: best (BEST), mean (MEAN), worst (WORST), and standard deviation (SD)
- *Constraints handling*: Deb's rules [[52\]](#page-24-17)
- Initial point in chaos theory set to 0.7 for all chaos maps

The parameter settings for all the algorithms considered for statistical results comparisons are kept the same as mentioned in their respective papers.

Here, we have applied a rule that the infeasible solutions containing slight violation of the constraints (from 0.01 in the frst iteration to 0.001 in the last iteration) are considered as feasible solutions. For most structural optimization problems, the global minimum locates on or close to the boundary of a feasible design space. By applying this rule, the candidate solutions approach the boundaries and can reach the global minimum with a higher probability  $[53]$  $[53]$ .

<span id="page-10-1"></span>**5.2.4.2 Tension/Compression Spring Design Problem** The objective is the minimization of the fabrication cost of spring with three parameters and four constrains such as wire diameter  $(x_1)$ , spring coil diameter  $(x_2)$ , and a number of active coils  $(x_3)$ , and deflection  $(g_1(X))$ , shear stress  $(g_2(X))$ , surge frequency  $(g_3(X))$ , and outer diameter limit  $(g_4(X))$ . The spring design pattern is shown in Fig. [1](#page-11-0) and formulated optimization problem is referred from [[54\]](#page-24-19).

The optimization results and the statistical results are given in Tables [5](#page-11-1) and [6,](#page-12-0) respectively. The result of the PO, EO, PRO, CSA, MFO and Emperor Penguin Optimizer (EPO) algorithms are imported from  $[55-59]$  $[55-59]$  $[55-59]$  $[55-59]$  $[55-59]$  and  $[46]$  $[46]$  $[46]$ , respectively. The result for the HGSO, MPA, TSA, and STOA algorithms are reported from [\[43](#page-24-7), [45,](#page-24-9) [46\]](#page-24-10), and [\[48](#page-24-12)], respectively. For SHO, SCA, GWO, PSO, MVO, GSA, GA, and DE, the results are imported from [[44\]](#page-24-8). For CS, WOA, EHO (elephant herbing behavior), and SA, the results are imported from [[43](#page-24-7)]. The results for the CSGO family are achieved by us. In the tables, "−" represents "not given"



<span id="page-11-0"></span>**Fig. 1 a** Schematic of the spring; **b** stress distribution evaluated at the optimum design and **c** displacement distribution evaluated at the optimum design

<span id="page-11-1"></span>**Table 5** Optimum results of tension/compression spring design problem by diferent algorithms



for that particular algorithm. The best result is highlighted in bold. From Tables [5](#page-11-1) and [6](#page-12-0), it can be inferred that the CSGO family has found better optimal results than other. Again in CSGO family, CSGO5 fnds better optimal result than others.

**5.2.4.3 The Welded Beam Design Problem** The objective is to minimize the manufacturing cost of the welded beam with four optimized variables and seven constrains such as thickness of the weld  $(x_1)$ , length of clamped bar  $(x_2)$ , the height of the bar  $(x_3)$ , and thickness of the bar  $(x_4)$ , and <span id="page-12-0"></span>**Table 6** Statistical results of tension/compression spring design problem by diferent algorithms





<span id="page-12-1"></span>**Fig. 2** Welded beam design problem: **a** Schematic of the weld, **b** stress distribution evaluated at the optimum design, **c** displacement distribution at the optimum design

<span id="page-13-0"></span>



shear stress  $(\tau)$ , and bending stress in the beam  $(\theta)$ , buckling load (Pc), end deflection of beam ( $\delta$ ), normal stress ( $\sigma$ ), and boundary. The design of welded beam is shown in Fig. [2](#page-12-1) and formulated optimization problem is referred from [\[54](#page-24-19)].

The optimization results and statistical results are given in Tables [7](#page-13-0) and [8,](#page-14-0) respectively. The result of the PO, EO, PRO, CSA, MFO and Emperor Penguin Optimizer (EPO) algorithms are imported from [[55](#page-24-20)[–59](#page-24-21)] and [\[56](#page-24-22)], respectively. The result for the HGSO, SOA, MPA, TSA, and STOA algorithms are imported from [[43–](#page-24-7)[46](#page-24-10)], and [[48\]](#page-24-12), respectively. For SMA, SSA the result is imported from [[57](#page-24-23)]. For SHO, GWO, PSO, MVO, SCA, GSA, GA, and DE, the results are imported from [\[44](#page-24-8)]. For CS, WOA, EHO (elephant herbing behavior), and SA, the results are imported from [[43\]](#page-24-7). The results for the CSGO family are achieved by us. In the tables, "−" represents "not given" for that particular algorithm. The best result is highlighted in bold. From Tables [7](#page-13-0) and [8,](#page-14-0) it can be stated that the CSGO family of algorithms outperforms all other algorithms. Here, all algorithms of the CSGO family perform equally well in fnding optimal results.

**5.2.4.4 Cantilever Beam Design Problem** It is made up of fve hollow square cross-sections as Fig. [3](#page-14-1) [\[54](#page-24-19)]. Regarding this problem, detailed description and formulated optimization problem is referred from [\[54](#page-24-19)].

The optimization results and the statistical results of algorithms are given in Tables [9](#page-15-0) and [10](#page-15-1), respectively. The result SMA, MFO, SOS (Symbiotic Organisms Search), CS,

<span id="page-14-0"></span>**Table 8** Statistical results of welded beam design problem by diferent algorithms







<span id="page-14-1"></span>**Fig. 3** Cantilever beam design

MMA (Method of Moving Asymptotes), and GCA (Generalised Convex Approximation) are imported from [\[47](#page-24-11)]. The results for the CSGO family are achieved by us. The "−" represents "not given" for that particular algorithm. The best result is highlighted in bold. From Tables [9](#page-15-0) and [10](#page-15-1), it can be inferred that the CSGO family of algorithm outperform all other algorithms. Among the CSGO family of algorithms, CSGO1 fnds the best optimal solution, whereas CSGO8 fnds the best solution in terms of BEST, WORST, MEAN, and SD solution among others.

<span id="page-15-0"></span>**Table 9** Optimum results of cantilever beam design problem by diferent algorithms

Algorithms	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	Optimal result
<b>SMA</b>	6.017757	5.310892	4.493758	3.501106	2.150159	1.339957* 1.339957 <sup>c</sup>
<b>MFO</b>	5.9830	5.3167	4.4973	3.5136	2.1616	1.33998* 1.33998 <sup>c</sup>
SOS	6.0188	5.3034	4.4959	3.4990	2.1556	1.33996* $13.3996^c$
<b>CS</b>	6.0089	5.3049	4.5023	3.5077	2.1504	1.33999* $13.3999^c$
<b>MMA</b>	6.0100	5.3000	4.4900	3.4900	2.1500	$1.3400*$ $13.400^{\circ}$
<b>GCA</b>	6.0100	5.3000	4.4900	3.4900	2.1500	$1.3400*$ $13.400^{\circ}$
CSGO1	6.0143069125645	5.3080639580584	4.4936917574974	3.5006821291728	2.1518561741050	13.3620572197022
CSGO <sub>2</sub>	6.0150727517961	5.3073755398209	4.4931808855624	3.5006393848484	2.1523324379117	13.3620572623622
CSGO3	6.0145326449192	5.3076950955757	4.4931185679383	3.5011268561112	2.1521279556988	13.3620573372395
CSGO <sub>4</sub>	6.0138874235950	5.3079214693168	4.4932750108494	3.5013219117263	2.1521954499936	13.3620574276354
CSGO5	6.0149990750964	5.3075027372209	4.4934538417099	3.5002586185344	2.1523867492680	13.3620572759868
CSGO <sub>6</sub>	6.0151106132899	5.3084991455319	4.4926672877461	3.5003628791237	2.1519613721669	13.36205744778727
CSGO7	6.0142224790303	5.3079146553709	4.4931574308163	3.5008169029355	2.1524895464754	13.36205727150465
CSGO <sub>8</sub>	6.0148823577978	5.3072968983588	4.4933942605634	3.5007556408336	2.1522719285524	13.36205731599240
CSGO9	6.0145090595848	5.3071963634624	4.4935926982223	3.5007769877979	2.1525259502884	13.36205729934305
CSGO <sub>10</sub>	6.0140122013280	5.308292289245	4.4935032881358	3.5002309588785	2.1525624547352	13.36205738210221

\* Represents wrongly put

c Represents corrected value

<span id="page-15-1"></span>**Table 10** Statistical results of cantilever beam design problem by diferent algorithms

Algorithms	<b>BEST</b>	<b>WORST</b>	<b>MEAN</b>	<b>SD</b>
<b>SMA</b>				
<b>MFO</b>				
<b>SOS</b>				
CS				
<b>MMA</b>				
<b>GCA</b>				
CSGO1	13.362057219702205	13.362060325929614	13.362058423000358	8.593615875833658e-07
CSGO <sub>2</sub>	13.362057262362285	13.362061867644758	13.362058785952119	1.299590279055970e-06
CSGO <sub>3</sub>	13.362057337239426	13.362061311531937	13.362058932062419	9.909115197252335e-07
CSGO <sub>4</sub>	13.362057427635454	13.362060428644744	13.362058414070182	8.861240402167021e-07
CSGO <sub>5</sub>	13.362057275986803	13.362061591038888	13.362058600135557	1.028567170707533e-06
CSGO <sub>6</sub>	13.362057447787276	13.362061960283475	13.362058518321360	9.275908881267436e-07
CSGO7	13.362057271504650	13.362061236823928	13.362058766562427	1.103333599646931e-06
CSGO <sub>8</sub>	13.362057315992399	13.362060253167591	13.362058364060077	7.399711676054027e-07
CSGO <sub>9</sub>	13.362057299343050	13.362060339061168	13.362058575093503	9.682425313271179e-07
CSGO10	13.362057382102218	13.362063301098216	13.362058788800560	1.304095221610504e-06



<span id="page-16-0"></span>**Fig. 4** Three-bar truss design

<span id="page-16-1"></span>**Table 11** Optimum results of three-bar truss design with constraint values by diferent

algorithms

**5.2.4.5 Three‑Bar Truss Design Problem** The objective is to design a truss with a minimum weight that does not violate constraints. Regarding this problem, detailed description is given in [\[54](#page-24-19)]. Figure [4](#page-16-0) [\[54](#page-24-19)] shows the structural parameters of this problem. The formulated design problem is referred from [\[42](#page-24-6)].

The optimization result of algorithms with constraint function values is given in Table [11](#page-16-1), and the statistical result is given in Table [12](#page-17-0). The result PRO (Poor and Rich Optimization), GOA, MFO, PSO-DE, ALO, and MVO are imported from [\[57\]](#page-24-23), and for CSA, the result is imported from [[58](#page-24-24)].

The results for the CSGO family are achieved by us. The constraint value in Table [13](#page-17-1) is calculated by us using optimization results as imported by the authors in their respective papers. The "−" represents "not given" for that particular algorithm. The best result is highlighted in bold. From Tables [11](#page-16-1) and [12,](#page-17-0) it can be stated that the CSGO family of algorithms outperforms all other algorithms. Among the CSGO family of algorithms, CSGO4 fnds the best optimal solution, whereas CSGO1 fnds the best solution in terms of worst, mean, and standard deviation solution among others.

**5.2.4.6 I-Beam Design Problem** The objective is to minimize the vertical defection of an I-beam with four optimization variables and two optimization constraints such as cross-section area  $(g_1(X))$ , and bending stress  $(g_2(X))$  as Fig. [5](#page-17-2) [\[59](#page-24-21)]. This case is modifed from the original problem reported in [[60\]](#page-24-25). The formulated optimization problem is referred from [\[59](#page-24-21)].

The optimization result of algorithms with constraint function values is given in Table [13,](#page-17-1) and the statistical result is given in Table [14](#page-18-0). The result of ARSM, Improved ARSM, and CS are imported from [\[59](#page-24-21)]. The results for the CSGO family are achieved by us. "−" represents "not given" for that particular algorithm. The best result is highlighted in bold From Tables [13](#page-17-1) and [14](#page-18-0), it can be deduced that the CSGO family of algorithms outperforms all other algorithms. Here, all algorithms of CSGO family fnd equivalent results. Hence, all CSGO algorithm fnds the best optimal solution



<span id="page-17-0"></span>



<span id="page-17-2"></span>**Fig. 5** I-beam design problem





<span id="page-17-1"></span>**Table 13** Optimum results of I-beam design problem with value of constraints function by diferent algorithms

Algorithms	$x_1$	$x_2$	$x_3$	$x_4$	Optimal result
<b>ARSM</b>	80	37.05	1.71	2.31	0.0157
<b>Improved ARSM</b>	79.99	48.42	0.90	2.40	0.0131
<b>CS</b>	80	50	0.9000	2.3216715	0.0130747
CSGO <sub>1</sub>	80	50	1.764718360707903	5	0.006620471665250
CSGO <sub>2</sub>	80	50	1.764718360707903	5	0.006620471665250
CSGO <sub>3</sub>	80	50	1.764718360707903	5	0.006620471665250
CSGO <sub>4</sub>	80	50	1.764718360707903	5	0.006620471665250
CSGO <sub>5</sub>	80	50	1.764718360707903	5	0.006620471665250
CSGO <sub>6</sub>	80	50	1.764718360707903	5	0.006620471665250
CSGO <sub>7</sub>	80	50	1.764718360707903	5	0.006620471665250
CSGO <sub>8</sub>	80	50	1.764718360707903	5	0.006620471665250
CSGO <sub>9</sub>	80	50	1.764718360707903	5	0.006620471665250
CSGO10	80	50	1.764718360707903	5	0.006620471665250

<span id="page-18-0"></span>**Table 14** Statistical results of I-beam design problem by diferent algorithms

Algorithms	<b>BEST</b>	<b>WORST</b>	<b>MEAN</b>	<b>STD</b>
ARSM				
<b>Iproved ARSM</b>				
CS	0.0130747	0.01353646	0.0132165	0.0001345
CSGO1	0.006620471665250	0.006620471665250	0.006620471665250	3.528758033802314e-18
CSGO <sub>2</sub>	0.006620471665250	0.006620471665250	0.006620471665250	3.528758033802314e-18
CSGO <sub>3</sub>	0.006620471665250	0.006620471665250	0.006620471665250	3.528758033802314e-18
CSGO <sub>4</sub>	0.006620471665250	0.006620471665250	0.006620471665250	3.528758033802314e-18
CSGO <sub>5</sub>	0.006620471665250	0.006620471665250	0.006620471665250	3.528758033802314e-18
CSGO <sub>6</sub>	0.006620471665250	0.006620471665250	0.006620471665250	3.528758033802314e-18
CSGO7	0.006620471665250	0.006620471665250	0.006620471665250	3.528758033802314e-18
CSGO <sub>8</sub>	0.006620471665250	0.006620471665250	0.006620471665250	3.528758033802314e-18
CSGO <sub>9</sub>	0.006620471665250	0.006620471665250	0.006620471665250	3.528758033802314e-18
CSGO <sub>10</sub>	0.006620471665250	0.006620471665250	0.006620471665250	3.528758033802314e-18



<span id="page-18-1"></span>**Fig. 6** The tabular column design

as well as the best solution in terms of mean and standard deviation solution among others.

**5.2.4.7 Tabular Column Design** The objective of the tabular column design problem is to minimize the cost of designing a uniform column of the tabular section that includes material and construction costs as Fig. [6](#page-18-1) [[59\]](#page-24-21). The column is made of material of length (L) with a yield stress (S), a modulus of elasticity (E), and a density (D) carry a compressive load (P). This optimization problem has two optimized variables such as mean diameter of the column  $(x_1)$ 

<span id="page-18-2"></span>**Table 15** Optimum results of tabular column design problem by different algorithms

Algorithms	$x_1$	$x_2$	Optimal result
<b>Fuzzy PDCOE</b>	5.4507	0.292	$25.5316^*$ $26.49912312^{\circ}$
Rao	5.44	0.293	26.5323
CS	5.45139	0.29196	26.53217
CSGO <sub>1</sub>	5.451941	0.29174226	26.4913864882
CSGO <sub>2</sub>	5.451941	0.29174226	26.4913864882
CSGO <sub>3</sub>	5.451941	0.29174226	26.4913864882
CSG <sub>O4</sub>	5.451941	0.29174226	26.4913864884
CSGO <sub>5</sub>	5.451941	0.29174226	26.4913864882
CSGO <sub>6</sub>	5.451941	0.29174227	26.4913864882
CSGO7	5.451941	0.29174227	26.4913864881
CSGO <sub>8</sub>	5.451942	0.29174222	26.4913864884
CSGO <sub>9</sub>	5.451941	0.29174228	26.4913864882
CSGO10	5.451941	0.29174227	26.4913864882

The best results of the experiments are represented in bold

\*Represents wrongly put

c Represents corrected value

and tube thickness  $(x_2)$ , and six constraints such as the stress included in the column should be less then the buckling stress  $((g_1(X))$ , and the yield stress  $(g_2(X))$ , the mean diameter of the column is restricted between 2 and 14 cm  $(g_3(X))$ and  $g_4(X)$ , and columns with thickness outside the range 0.2–0.8 cm is not commercially available ( $g_5(X)$ ) and  $g_6(X)$ ). The formulated optimization problem is referred from [[59\]](#page-24-21).

The optimization result of algorithms with constrains value is given in Table [15,](#page-18-2) and the statistical result is given in Table [16](#page-19-0). The result of Rao, fuzzy proportional-derivative

Algorithms	<b>BEST</b>	WORST	<b>MEAN</b>	<b>SD</b>
<b>Fuzzy PDCOE</b>				
Rao	-	-	-	$\overline{\phantom{0}}$
CS	26.53217	26.53972	26.53504	0.00193
CSGO1	26.491386488153360	26.491386495333025	26.491386490856410	2.363396596882364e-09
CSGO <sub>2</sub>	26.491386488165571	26.491386498136841	26.491386490233214	2.281681440373964e-09
CSGO <sub>3</sub>	26.491386488158895	26.491386497496833	26.491386490513413	2.511529340998990e-09
CSGO <sub>4</sub>	26.491386488390233	26.491386498026579	26.491386490660908	2.452381904843001e-09
CSGO <sub>5</sub>	26.491386488172985	26.491386501565771	26.491386490788571	3.436161611017448e-09
CSGO <sub>6</sub>	26.491386488156394	26.491386496288538	26.491386489778495	1.843842257939578e-09
CSGO7	26.491386488145615	26.491386509030100	26.491386492059771	4.395248054678416e-09
CSGO <sub>8</sub>	26.491386488359122	26.491386503520090	26.491386492538890	4.499242203936305e-09
CSGO <sub>9</sub>	26.491386488150628	26.491386497031133	26.491386490765663	2.795759587125070e-09
CSGO <sub>10</sub>	26.491386488156930	26.491386507603700	26.491386491513428	4.242503751531444e-09

<span id="page-19-0"></span>**Table 16** Statistical results of tabular column design problem by diferent algorithms

controller optimization engine (fuzzy PDCOE) and CS are reported from [\[60](#page-24-25), [61](#page-24-26)] and [\[59\]](#page-24-21), respectively. The results for the CSGO family are achieved by us. The "−" represents "not given" for that particular algorithm. The best result is highlighted in bold. From Tables [15](#page-18-2) and [16,](#page-19-0) it can be stated that the CSGO family of algorithms outperforms all other algorithms. Among the CSGO family of algorithms, CSGO7 fnds the best optimal solution, whereas CSGO6 fnds the best solution in terms of mean and standard deviation among others.

**5.2.4.8 Piston Lever Design Problem** The objective is to minimize the oil volume when the lever of the piston is lifted up from 0<sup>o</sup> to 45<sup>o</sup> as shown in Fig. [7](#page-19-1) [\[59](#page-24-21)]. This problem has four optimization variables and four constraints such as force equilibrium, maximum bending moment of the lever,



<span id="page-19-1"></span>**Fig. 7** Piston problem

minimum piston stroke, and geographical conditions. The formulated optimization problem is referred from [[59\]](#page-24-21).

The optimization result of algorithms is given in Table [17](#page-20-0), and the statistical result is given in Table [18.](#page-20-1) The result of PSO, DE, GA, HPSO, HPSO with Q-learning, and CS are reported from [\[59](#page-24-21)]. The results for the CSGO family of algorithms are achieved by us. "−" represents "not given" for that particular algorithm. The best result is highlighted in bold. From Tables [17](#page-20-0) and [18,](#page-20-1) it can be stated that the CSGO1 algorithm fnds the best optimal solution as well as worst solution and CS algorithm achieve best mean solution among others.

**5.2.4.9 Multi‑plate Disc Clutch Brake Design Problem** The objective is to minimize the total weight of the multi-plate disc clutch brake as Fig.  $8 \times 10^{-1}$  $8 \times 10^{-1}$ . This problem has five optimized variables as driving force  $F(x_4)$ , inner redius ri $(x_1)$ , outer redius ro( $x_2$ ), friction surface number  $Z(x_5)$ , and disc thickness  $t(x_3)$ . Since the problem contains eight different constraints, the feasible region in the solution space only accounts for 70%, which makes it more difficult to solve the problem. The formulated optimization problem is referred from [\[61](#page-24-26)].

The optimization results of algorithms are given in Table [19](#page-21-0), and the statistical results are given in Table [20.](#page-21-1) The result of HHO, PVS, WCA, TLBO, and WSOA are reported from [[38,](#page-24-13) [62–](#page-24-27)[65\]](#page-24-28), respectively. Similarly, the result of hHHO–SCA, NSGA-II, and AMDE are reported from [[66\]](#page-24-29) and for teaching learning-based pathfnder algorithm (TLPFA), the result is reported from [[67\]](#page-24-30). The results for the CSGO family are achieved by us. "−" represents "not given" for that particular algorithm. The best result is highlighted in bold. From Tables [19](#page-21-0) and [20,](#page-21-1) it can be stated that the TLPFA, CSGO1-CSGO6, CSGO9 and CSGO10 algorithms

<span id="page-20-0"></span>**Table 17** Optimum results of piston lever design problem by diferent algorithms



The best results of the experiments are represented in bold

<span id="page-20-1"></span>



The best results of the experiments are represented in bold



<span id="page-20-2"></span>**Fig. 8** Multi-plate disc clutch brake problem

fnd the best optimal solution than all other algorithms. Here, CSGO1 and CSGO4 algorithm outperforms all other algorithms and fnds the best optimal solution in terms of best (BEST), mean (MEAN), worst (WORST) and standard deviation (SD) solution among others.

**5.2.4.10 Corrugated Bulkhead Design Problem** The objective is to minimize the weight of the corrugated bulkhead for a tanker [\[68](#page-24-31)]. This problem has four optimized variables such as width  $(x_1)$ , depth  $(x_2)$ , length  $(x_3)$ , and plate thickness  $(x_4)$  and six constraints. The formulated optimization problem is referred from [\[67](#page-24-30)].

<span id="page-21-0"></span>**Table 19** Optimum results of multi-plate disc clutch brake design by diferent algorithms



The best results of the experiments are represented in bold

\*Represents wrongly put

c Represents corrected value

<span id="page-21-1"></span>



<span id="page-22-2"></span>**Table** 22

Algorithms  $x_1$   $x_2$   $x_3$   $x_4$  Optimal result CSGO1 57.644819523344992 34.150109951178024 57.644939799015262 1.049257917114013 6.839596279899362 CSGO2 57.644820772896942 34.150109887652107 57.644939345910650 1.049257917252038 6.839596279826666 CSGO3 57.644819962796369 34.150109901928758 57.644939421910124 1.049257916614736 6.839596279845521 CSGO4 57.644820464996570 34.150109692435414 57.644937754918580 1.049257912968599 6.839596279822398 CSGO5 57.644818850940318 34.150109536692320 57.644936416305917 1.049257907999835 6.839596279986681 CSGO6 57.644820863171816 34.150109774692190 57.644938438225104 1.049257915078914 6.839596279813460 CSGO7 57.644820566162814 34.150109615000055 57.644937135495880 1.049257911534023 6.839596279859407 CSGO8 57.644819703038927 34.150109750974714 57.644938190258316 1.049257913273896 6.839596279825124

CSGO9 57.644819026305839 34.150109700474118 57.644937749466969 1.049257911489912 6.839596279881082 CSGO10 57.644819123092731 34.150110099522784 57.644940980144021 1.049257919679909 6.839596280080818

<span id="page-22-1"></span>**Table 21** Optimum results of corrugated bulkhead design problem by diferent algorithms



The optimization result of CSGO family algorithms is given in Table [21](#page-22-1) and the statistical result is given in Table [22](#page-22-2). For this problem, Ravindran et al. [\[69](#page-25-0)] reported the minimum value of 6.84241 using the random search method. A comparison of the results clearly shows that the CSGO family notably improves the results were obtained by the random search method.

In the present study, the CSGO family of algorithms performance is compared against other state-of-art as well as latest metaheuristic algorithms in solving structural optimization problems. The extensive comparative study conducted reveals that the CSGO family performs superior to diferent existing algorithms. This is partly due to the fact that there is one parameter, i.e., self-introspection parameter is replaced by the chaotic maps than in other algorithms. Other algorithms such as GA, DE, PSO, MBA, and CS require the tuning of at least one specifc algorithm parameter. While simpler and more robust than competing algorithms, the CSGO family is able to resolve a wide variety of problems. Moreover, it avoids the risk of compromised performance due to proper parameter tuning.

### <span id="page-22-0"></span>**6 Conclusion**

In this paper, the family of CSGO algorithms is proposed as an improved version of the SGO algorithm to solve optimization problems. The family of ten CSGO algorithms is designed using ten chaotic maps in place of self-introspection parameters which improves the performance of the SGO algorithm. The performance of the CSGO family of algorithms is validated through 13 benchmark functions and to evaluate effectiveness, extensive experiments are conducted using 9 structural engineering problems and results are compared with many popular optimization algorithms. The extensive experiment and the promising results indicate the superiority of the proposed CSGO family for providing acceptable results in a wide range of problems. Again, although not yet mathematically proven, these experimental studies have shown that using chaotic maps is generally more useful than a constant value of 0.2 for the selfintrospection parameter in SGO. Since in CSGO, any of the random numbers are not replaced by a chaotic map, then replacing random numbers with a chaotic map in SGO is further research. Furthermore, the mapping strategies can also be used to generate a high-quality initial population

for obtaining rapid and better solutions. Proposing diferent hybridizing methods for chaotic mapping, and solving the problem of clustering or classifcation, large-scale optimizations and multiobjective optimizations using these chaotic concepts with SGO can be further researched.

**Data Availability Statement** Data sharing not applicable to this article as no datasets were generated or analyzed during the current study.

#### **Declarations**

**Conflict of Interest** The author declares that she has no confict of interest in the publication of this paper.

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