**TECHNICAL PAPER**



# **Efects of soil small strain nonlinearity on the dynamic behavior of foating column structures considering soil‑structure interaction**

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### **Abstract**

Past seismic events reveal that soil and structural responses are interdependent, not independent. The seismic behavior of irregular structures, considering soil-structure interaction (SSI) efects, signifcantly increases the structural vulnerability compared to traditional fxed-base structures. The study on the impact of SSI on irregular structures, especially those with foating columns, is currently limited. Hence, this study primarily examines the infuence of nonlinear soil structure interactions on the dynamic response of mid-rise reinforced foating column structures resting on diferent soil mediums. A three-dimensional fnite element programming tool is used to simulate the seismic response of structures with and without foating columns. This study explores the use of elastoplastic hinges to study the inelastic behavior of structural components. The isotropic hardening elastoplastic hysteretic soil model is used to account for the nonlinear behavior of the soil. The nonlinear time history analysis is used to perform and evaluate structural demand parameters subjected to selected ground motions. Moreover, the seismic structural response parameters, such as storey displacement, peak storey drift, peak horizontal acceleration, base shear, and member forces, are compared for both fxed and SSI bases. The analysis results show that the presence of foating columns in structures signifcantly alters the dynamic response of buildings compared to those without floating column structures. The incorporation of SSI effects increases the flexibility of the foundation and increases the seismic structural response of storey displacement and inter-storey drift ratio while reducing the base shear value.

**Keywords** Floating column · Soil structure interaction · HSS constitutive model · PLAXIS 3D · Nonlinear time history analysis · Inter storey drift

# **Introduction**

Soil-structure interaction (SSI) is a phenomenon in which the response of the soil afects the motion of the structure, and the response of the structure afects the motion of the soil [[1\]](#page-21-0). Due to seismic events, the interaction between soil response and structural response demonstrates that their responses are interdependent rather than independent. However, the standards for structural design recommended either ignoring the efects of SSI or concession a reduction in the seismic coefficient when accounting for SSI effects. Seismic design guidelines for SSI [\[2](#page-21-1), [3](#page-21-2)] show that consensus and

Palani Jagan jagan.p2020@vitstudent.ac.in recommend reducing base shear when SSI has to be taken into account. According to IS: 1893 (Part 1-2002) [\[4](#page-21-3)], it is not recommended to incorporate soil-structure interaction (SSI) in the seismic design of structures built on rock-type materials. Moreover, the presence of tall buildings on soft soil can signifcantly alter the seismic response of the struc-ture due to SSI effects during an earthquake event [[5\]](#page-21-4).

Several researchers [\[6](#page-21-5)–[8\]](#page-21-6) have examined seismic structural behavior incorporation of SSI effects due to earthquakes. SSI has signifcantly afected dynamic structural responses and it is crucial to consider this during the design process. Also, the dynamic responses of multi-story reinforced concrete frame buildings resting on raft foundations, considering SSI effects, have been investigated [[9](#page-21-7)–[11](#page-21-8)]. These studies have revealed that factors such as the number of stories, soil type, soil damping, stifness degradation, distinctive foundation behaviors, and ground motion characteristics play a signifcant role in infuencing seismic structural behavior. Many researchers [[12](#page-21-9)[–15](#page-21-10)] have performed

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the nonlinear dynamics analysis by using fnite element programming tools to evaluate the seismic structural response. The fndings of these studies concluded that the stifness of the soil, and frequency content of the ground motions are the most important factors afecting SSI. Also, if the rigidity of the soil is reduced, structural foor-level displacement increases.

Due to global urbanization, irregular structures are becoming more widespread. The shapes and orientations of structures are modifed due to functional, aesthetic, and usage requirements. Several codes [[4,](#page-21-3) [16–](#page-21-11)[18\]](#page-21-12) provided recommendations and guidelines for earthquake-resistant design of irregular structures, and it is periodically revised due to increased demand and emerging difficulties. Vertical irregularity relates to the varying structural characteristics over the height of structures. This variation incorporates changes in the geometrical shape, mass distribution, strength, and stifness along the structural height. In the past seismic events, such as the earthquakes in Mexico (2017), Kobe (1995), and Northridge (1994), have demonstrated the adverse efects of vertical irregularities in structures when subjected to seismic forces. Several researchers [[19](#page-21-13)[–21\]](#page-21-14) have performed static and dynamic inelastic analyses to evaluate the seismic response of vertical irregular structures. Ghoozhdi et al. [\[22\]](#page-21-15) studied the seismic behavior of tall ground-storied structures with irregular confgurations, considering the efects of SSI. They concluded that accounting for SSI is crucial for reducing seismic demand, especially in soft soil conditions.

The column is supported by a beam or transfer slab and not directly attached to the foundation is called a foating column. The presence of discontinuities in column elements leads to a defciency in load transmission paths during lateral forces, resulting in poor performance of structures. Various researchers [[23](#page-21-16)[–26](#page-22-0)] conducted a comparative analysis of the seismic performance of structures with and without foating structures. The results showed that foating column structures modify the spectral acceleration and base shear, extend the time period, and increase storey displacement. Singala and Rahaman [\[24\]](#page-21-17) conducted static and dynamic analyses on a structure with foating columns, as depicted in Fig. [1](#page-1-0). This evaluation aimed to assess the seismic efects of foating column structures in multistoried RC buildings. The study concluded that the presence of foating column structures signifcantly alters the dynamic response of buildings. Additionally, lower-level stories of structures experienced increased vulnerability to earthquake forces. Several authors [[27–](#page-22-1)[30\]](#page-22-2) reported that foating column structures and the variation in lateral stifness on each foor of the building greatly infuence the structural vulnerability during earthquakes. Consequently, this leads to increased structural lateral displacement. Jagan and Visuvasam [[31\]](#page-22-3) performed an analysis of the inelastic seismic behaviors of reinforced



<span id="page-1-0"></span>**Fig. 1** Structure with foating columns

concrete buildings with and without foating columns. The study results reveal that the presence of foating columns increases the inter-storey drift ratio and structure damage probability. Bhosle et al. [\[32](#page-22-4)] have investigated the seismic response of vertical irregular structures. The fndings show that structures with open-ground stories and foating column structures demonstrate increased vulnerability in comparison to regular structures. However, urban development has led to the construction of these irregular structures, which are difficult to control. Modern construction techniques enable the creation of fexible structures with unique shapes and aesthetics. At the same time challenge traditional principles and raise safety concerns due to their unconventional design.

From the previous literature studies, foating column structures are more vulnerable to earthquake forces compared to conventional structures. Therefore, suitable retroftting methods are required to minimize the structural vulnerability of foating column structures in seismic-prone areas. Several researchers [[33](#page-22-5)–[36\]](#page-22-6) have studied diferent retroftting techniques to mitigate the seismic vulnerability of foating column structures. For example, lateral loadresisting systems such as moment-resisting frames, shear wall structures, and structures with various bracing systems (including diagonal, X, K, V, and inverted V) are widely used retroftting techniques in foating column structures. Saeed et al. [\[37\]](#page-22-7) conducted a recent numerical study on the seismic performance of shear walls in buildings with regular and staggered openings. The dynamic analysis was performed to assess the seismic response parameters and compare the performance of shear walls with regular and staggered openings in buildings. The authors concluded that openings have a signifcant efect on the seismic behavior of shear walls, emphasizing the necessity of considering them during the construction design phase. Additionally, various authors [[38](#page-22-8), [39](#page-22-9)] have focused on enhancing the mechanical strength and shear performance of reinforced concrete beams. The fndings of the studies contribute to the development of stronger building materials and structural elements, enhancing seismic resistance.

Based on the literature studies, it is indicated that seismic responses of irregular structures considering SSI efects are more susceptible. Previous studies have mainly focused on the seismic behavior of structures with foating columns, neglecting the impact of SSI effects. However, there is limited research on the inelastic seismic response of foating columns considering nonlinear dynamic soil-structure interaction. Hence, further investigations are necessary to understand the comprehension of the vulnerability of foating column structures considering SSI efects. This study aims to provide valuable insights into the response of reinforced concrete foating column structures under seismic loading, considering nonlinear dynamic soil-structure interactions. The five-storied structures rest on a raft foundation embedded in diferent soil mediums. Nonlinear time history analysis (NLTHA) is performed to assess the structural responses for both fxed and SSI (fexible) bases. The present study involves, fnding the seismic structural response parameters such as peak lateral storey displacement, peak storey drift, peak horizontal acceleration, base shear, and member forces. The numerical results aid in comparing the structural response characteristics of various soil strata in a moderate seismic zone.

### **Description of structure properties**

The five-storied reinforced moment-resistant concrete frame structures are used in this numerical study. The ground foor height is 4.5 m and the remaining floor height is 3.5 m. The total height of the building is 18.5 m. The plan dimensions of the structure at ground floor level are  $16 \text{ m} \times 15 \text{ m}$ . The structure comprises four bays in the longitudinal direction, each with equal intervals of 4 m, and three bays in the lateral direction, with intervals of 5 m. This study involves four diferent types of structural models. One of the models represents a regular structure without foating columns (Fig. [2](#page-3-0)a), while the other three models incorporate foating columns oriented in diferent directions such as X (Fig. [2](#page-3-0)b), Y (Fig. [2](#page-3-0)c), and XY (Fig. [2d](#page-3-0)). In addition to the regular structures, a 1.5 m bay width is extended from the outer columns of the structure at the frst-foor level. The foating columns are positioned at the end of these extended bays. Furthermore, the foating columns begin at the frst-foor level and extend up to the roof level. These types of foating columns are not supported by the ground. The dimensions of the structural elements are provided in Table [1](#page-4-0). A uniform slab thickness of 15 cm was utilized for all models. The used concrete properties are compressive strength  $(f<sub>ck</sub>)$ , unit weight (γ) and the Poisson ratio are 30 N/mm<sup>2</sup>, 25 kN/m<sup>3</sup>, and 0.2 respectively [\[40](#page-22-10)].

The value of modulus elasticity is 27386 MPa, calculated using the relationship of 5000√*fck* as per IS 456-2000 [\[40](#page-22-10)].

The yield strength of steel  $(fy)$  is 500 N/mm<sup>2</sup>. According to IS 875 [\[41\]](#page-22-11) the gravity loads are taken into account. The dead load is considered as the self-weight of structural elements and addition floor finish  $(1.0 \text{ kN/m}^2)$  and live load  $(3.0 \text{ kN/m}^2)$ .

The structural ductility in a moment-resisting frame relies on the bending capacity of beams. Components with ductile behavior can undergo plastic deformation without a signifcant reduction in strength. Consequently, these components absorb and dissipate the energy from seismic forces. Thus, the elastoplastic hinge element (nonlinear fexure/bending spring) was utilized at beam ends to simulate the nonlinear behavior of the building [[42,](#page-22-12) [43](#page-22-13)]. The bending stifness (*EI*) at the end of the beam, and the plastic moment  $(M_n = M_p)$ are defned as follows

$$
E_c I_{\text{eff}} = 0.35 E_c I_g \text{for beams}
$$
 (1)

$$
M_n = M_p = A\sigma_{y, y_g}
$$
  
\n
$$
E_c I_{eff} = M_n / 2\epsilon_y
$$
 for columns (2)

where,  $E_c$  = concrete elastic modulus,  $I_g$  = gross moment of inertia,  $A =$  sectional area,  $y_g =$  distance between centroid of tensioned or concrete zones of cross section and neutral axis,  $\varepsilon_{v}$  = yield strain of steel reinforcement,  $\sigma_{v}$  = compressive strength of concrete (assumed to equal to compressive strength of concrete,  $f'_{c}$ ). The cracking effects are taken into consideration by assuming the cracked column and beam were 0.7 and 0.35 times the bending stifness of uncracked components, respectively. It is assumed that the structural models are located in Chennai. Based on the guidelines provided by IS 1893-2016 [\[44](#page-22-14)] the Chennai site location falls within Zone III and is categorized as a moderate seismic zone. The seismic design characteristics of the site include the zone factor (Z), response reduction factor, importance factor, and damping, which are adapted to be 0.16, 5, 1.5, and 5%, respectively. The analysis and design of superstructural elements using structural analysis programming (SAP 2000) [\[45](#page-22-15)]. The structures are analyzed by using both equivalent static and response spectrum analyses. As per IS 456-2000 [[40\]](#page-22-10) the permissible storey drift due to lateral forces is 0.4% of the storey height. The analysis results for all models ensured that the lateral storey drift values were within the permissible limits.

# **Finite element modelling of the soil–raft– structure system**

The fnite element programming tool is utilized to simulate the interaction between the soil and structure in the direct analysis approach. This study examined the seismic response



16 m @ 4 m each



<span id="page-3-0"></span>**Fig. 2** Typical plan and sectional elevations of structures. **a** Ground foor plan for without foating column structure, **b** sectional elevation view for without foating column, **c** frst-foor plan view for foating in X direction, **d** sectional elevation view for foating in X direction,

**e** frst-foor plan view for foating in Y direction, **f** sectional elevation view for foating in Y direction, **g** frst-foor plan view for foating in XY direction, **h** three-dimensional view of foating XY structures

<span id="page-4-0"></span>



of fve-story reinforced concrete structures with and without foating columns resting on raft foundations supported by diferent soil mediums. The foundation is embedded at a depth of 1.5 meters below ground level. A raft foundation with a thickness of 450 mm and a plan dimension of 19 m by 18 m has been adopted. The model depicts a beam and column with six-node beam elements made of linear elastoplastic materials. Additionally, slab and raft components are represented by 6-noded plate elements with linear elastic properties, whereas soil elements are represented by 10-noded tetrahedral elements. Previous studies [[46,](#page-22-16) [47](#page-22-17)] suggested that the geometric soil model boundaries are seven times raft width to minimize boundary efects and wave reflection. The schematic diagram in Fig. [3](#page-5-0) depicts the soil-foundation-structure system without foating column models and a similar approach used for foating column structures. The hardening soil with small strain (HSS) constitutive model is used to simulate the nonlinear dynamic behavior of structures during earthquakes.

#### **Soil properties**

The majority of soil standards classify the state of the soil condition according to shear wave velocity. This study aims to examine three diferent soil types, as classifed according to the International Building Code (IBC) [\[48\]](#page-22-18). The basic properties of diferent soil mediums utilized in this study such as hard, stiff, and soft are presented in Table [2](#page-5-1). This study assumes subsoil homogeneity and constant shear wave velocity throughout depth. The water table is assumed much below ground level. The well-defned empirical correlation proposed by Maheswari et al. [[49](#page-22-19)] for all soil conditions in the Chennai zone, as depicted in Eq. [3,](#page-4-1) is employed in this study to determine the SPT-N value for various soil mediums. Additionally, the structural models utilized in this study are assumed to be located in Chennai. Therefore, this correlation is very helpful in deriving the soil properties for diferent soil mediums in this present study. It is important to note that the SPT-N values were determined using this correlation in Eq. [3](#page-4-1) for various soil conditions in this study fall within the range of Indian soil types specified in IS 1893-2016 [[44\]](#page-22-14), as listed in Table [2.](#page-5-1) According to Bowels [\[50](#page-22-20)], the bulk density (ρ) of diferent soil mediums concerning SPT (N) value was considered for this study. Additionally, the initial shear modulus was determined using linear elasticity, as shown in Eq. [4](#page-4-2). The plastic parameter angle of friction in various soil types is taken from Peck et al. [[51\]](#page-22-21).

<span id="page-4-1"></span>
$$
V_S = 95.64N^{0.420} (r^2 = 0.84) [\text{All type soil}] \tag{3}
$$

<span id="page-4-2"></span>
$$
G_o = \rho \cdot \left(V_s\right)^2\tag{4}
$$

where,  $V<sub>S</sub>$  is the shear wave velocity of soil, *N* is standard penetration number, and  $(G<sub>o</sub>)$  is initial shear modulus.

## <span id="page-4-3"></span>**Hardening soil model with small strain stifness (HSS) model**

The nonlinearity of soil behaviors is essential to understanding the ground response during an earthquake. In this study, the nonlinear analysis of the soil structure system is carried out using the hardening soil model with a small strain stifness (HSS) constitutive model. To simulate the nonlinear behaviors of soil, the hardening soil (HS) model is one of the advanced constitutive models, which is derived based on the theory of plasticity [[52](#page-22-22)]. The HSS model is an extended version of the hardening soil model



<span id="page-5-0"></span>**Fig. 3** Modeling of the soil-raft-structure system (without foating column structure). **a** plan and **b** sectional elevation

Soil type	Soil profile as per (IBC)	Shear wave velocity, (Vs)(m/s)	Average shear wave velocity, $(Vs)(m/s)$	Standard penetration number $(N)$	Soil type (According to IS 1893–2016 based on SPT-N value
C	Hard soil	$360 < V_s < 750$	564	> 50	$N > 30$ (Hard soil)
D	Stiff soil	$180 < V_s < 360$	260	28	$10 < N < 30$ (Stiff soil)
E	Soft soil	$V_s < 180$	160	<sub>(</sub>	$10 < N$ (Soft soil)

<span id="page-5-1"></span>**Table 2** Properties of diferent soil mediums

and has almost similar properties to the hardening soil model. In addition, two additional parameters were added to the HSS model, namely the small-strain shear modulus

 $(G_0)$  and the shear strain level  $\gamma_{0.7}$ , at which the secant shear modulus  $(G_s)$  is 70% of  $G_0$  [\[53](#page-22-23)]. The HSS model accurately accounts for small strain stifness and nonlinear

strain dependence. This characteristic represents a strength of the HSS model in comparison to other models [[54\]](#page-22-24). The derivation of the variation in the reduced shear modulus curve is shown in Eq. [5](#page-6-0), can be achieved by utilizing the hyperbolic law, which was originally proposed by Hardin and Drnevich [\[55\]](#page-22-25) in Eq. [5](#page-6-0).

$$
\frac{G_S}{G_0} = \frac{1}{1 + 0.385 \frac{\gamma}{\gamma_{0.7}}}
$$
\n(5)

The relationship between shear modulus reduction and strain leads to the determination of the tangent shear modulus  $(G_t)$ , which is constrained by a lower limit at high levels of strain.

$$
G_t = \frac{1}{\left(1 + 0.385 \frac{r}{r_{0.7}}\right)^2} \tag{6}
$$

The lower cut-off of  $G_t$  is called the unloading–reloading shear modulus  $(G_{ur})$ , which can be correlated with the unloading–reloading elastic modulus (*Eur)* and Poisson's ratio (*υ*).

$$
G_t \ge G_{ur} = \frac{E_{ur}}{2(1 + v_{ur})} \tag{7}
$$

The shear modulus, a stress dependency parameter, increases with soil depth and it can be determined by the Eq. [8](#page-6-1) [[53](#page-22-23)].

$$
G_0 = G_0^{ref} \left( \frac{c' \cos \varphi' - \sigma_3' \sin \varphi'}{c' \cos \varphi' + p^{ref} \sin \varphi'} \right)^m
$$
 (8)

Based on Eq. [8](#page-6-1), the initial shear modulus at a certain stress level or depth is a function of strength parameter *C* and φ at the reference pressure of 100 kPa, confning pressure  $\sigma_3$  and power for stress-level dependency  $(m)$ . Equation [8](#page-6-1) shows the stress dependence of the shear modulus, which is similar to the stress dependency observed in Young's modulus during unloading and reloading stress paths  $(E_{ur})$ , the secant modulus  $(E_{50})$ , and the tangent modulus  $(E_{\text{oed}})$ . The parameter  $E_{50}$  represents the stiffness modulus for primary loading, which is dependent on the confning stress. It can be calculated using the following Eq. [9.](#page-6-2)

<span id="page-6-2"></span>
$$
E_{50} = E_{50}^{ref} \left( \frac{c'cos\varphi' - \sigma_3' sin\varphi'}{c'cos\varphi' + p^{ref} sin\varphi'} \right)^m
$$
(9)

The  $E_{50}$  value of the soil was calculated in this study by using the SPT-*N* values and shear strength parameters by the established correlations (Eqs. [10](#page-6-3) and [11\)](#page-6-4) for coarse-grained soil (GW-Well graded gravel and S-normal consolidated sand) [[50\]](#page-22-20).

<span id="page-6-3"></span><span id="page-6-0"></span>
$$
E_{50} = 1200(N+6) \text{ for GW}
$$
 (10)

<span id="page-6-4"></span>
$$
E_{50} = 500(N + 15) \text{ for S}
$$
 (11)

According to previous literature studies [\[56](#page-22-26), [57](#page-22-27)] in the absence of laboratory data, the following relationship  $(E_{50}^{ref} = E_{oed}^{ref} = 3E_{ur}^{ref})$  is used to determine the soil stiffness values of  $E_{ur}^{ref}$  and  $E_{oed}^{ref}$ . The soil properties and HSS model parameters utilized in this study are described in Table [3.](#page-6-5)

The dynamic properties of soil, including the damping ratio and shear modulus, are signifcant factors for assessing ground response during an earthquake [\[57\]](#page-22-27). Therefore, it is essential to consider the nonlinear characteristics of soil during the evaluation of structural seismic response. To enhance the accuracy of predicting the response of soilfoundation-structure systems, the authors Amorosi et al. [[58\]](#page-22-28) recommended the utilization of viscous damping in fnite element analysis and the incorporation of the Rayleigh formulation. In this approach, the formation of the damping matrix involves combining the mass and stifness matrices by the linear relationship described in Eq. [12](#page-6-6).

<span id="page-6-6"></span><span id="page-6-1"></span>
$$
\lceil C \rceil = \alpha_R \lceil M \rceil + \beta_R \lceil K \rceil \tag{12}
$$

The damping, mass, and stifness matrices are represented by  $[C]$ ,  $[M]$ , and  $[K]$ , respectively. Additionally, the damping coefficients are denoted as  $\alpha_R$  and  $\beta_R$ . The damping coefficients are determined by evaluating the damping ratio associated with two distinct vibration modes occurring at their respective natural frequencies shown in Eq. [13.](#page-6-7)

<span id="page-6-7"></span>
$$
\begin{pmatrix} \alpha_R \\ \beta_R \end{pmatrix} = \frac{2\xi}{\omega_i + \omega_j} \begin{bmatrix} \omega_i \omega_j \\ 1 \end{bmatrix}
$$
 (13)

where  $\omega_i$  and  $\omega_j$  are two natural modes and their respective frequencies. *ξ* assumed damping value for the natural mode. The structural seismic response is most signifcantly

<span id="page-6-5"></span>**Table 3** Soil properties and HSS model parameters used in the analysis

Soil type	$\gamma$ (kN/m <sup>3</sup> )	$c$ (kPa)	$\varphi'$	$E_{50}^{ref}$ (MPa)	$E_{\alpha e d}^{ref}$ (MPa)	$E_{ur}^{ref}$ (MPa)	$Go_{ref}$ (MPa)	$\gamma_{0.7(%)}$	$\nu_{ur}$	m
Hard soil (Soft rock)			39	127.2	127.2	381.6	713.4	0.0079	0.2	0.5
Stiff soil (Dense sand)	18		36	21.5	21.5	64.5	130.1	0.0162	0.2	0.5
Soft soil (Loose sand)	15		30	10.5	10.5	31.5	39.1	0.0164	0.2	0.5

$$
f_n = \frac{V_s}{4H}(2n - 1)
$$
 (14)

where,  $f_n$  = natural frequency of the corresponding mode,  $V<sub>s</sub>$  = sheare wave velocity, H = depth of soil deposit, and  $n =$  mode number. Here, the first and second vibration modes of soil deposits with a specifc target damping ratio of 5% were selected. The determined damping coefficients are presented in Table [4](#page-7-0), where the corresponding values remain constant with depths.

The present study incorporates the consideration of a nonlinear soil model to accurately characterize the dynamic behavior of soil during analysis. The rate at which cyclic shear strain increases has the effect of reducing the tangent shear modulus and increasing the damping ratio during an earthquake. Hence, the consideration of strain, shear modulus, and damping relationships is crucial. The backbone curve is utilized to represent the hysteresis damping. Furthermore, the DEEPSOIL [[61\]](#page-22-31) program was utilized to obtain ftting curves, considering the relevant soil parameters that were chosen in this study. The recommended curvature of the backbone for sand layers, as proposed by Seed and Idriss (Mean) [\[62\]](#page-22-32) is shown in Fig. [4](#page-7-1) (as an example of soft soil).

<span id="page-7-0"></span>**Table 4** Raylieghs damping coefficients

Soil Type		Natural frequency (rad/s)	Damping coefficients		
	$\omega_1$	$\omega_{2}$	$\alpha_{R}$	$\beta_R$	
Hard soil	31.08	93.25	2.333	0.0008	
Stiff soil	13.56	40.69	1.018	0.0018	
Soft soil	8.35	25.05	0.627	0.0029	

<span id="page-7-1"></span>**Fig. 4**  $\alpha$  G/G<sub>max</sub>—strain relationship and **b** damping—strain relationship

# **Details on boundaries, meshing, and interface characteristics**

The foremost and crucial step in numerical simulation involves establishing the boundaries for a geometric model. Also, it is of utmost importance to carefully position and efectively eliminate wave refection from the boundaries of the model. The distance between the lateral boundaries of soil models was adopted based on previous studies [[46,](#page-22-16) [47](#page-22-17)]. The authors suggested the lateral boundaries be seven times the dimensions of the raft from its center, efectively minimizing wave refection from the boundaries. Therefore, in this study, the longitudinal and lateral dimensions of the soil boundaries were adopted as 133 m and 126 m, respectively as shown in Fig. [5](#page-8-0). The appropriate boundary conditions replicate the far-feld behavior of the soil medium by absorbing stress increments and preventing the refection of waves. Hence, employing free-feld and interface elements was recommended for the dynamic analysis [[63\]](#page-22-33). This study utilized free-feld boundaries with viscous dampers at the lateral boundaries of the soil mediums to mitigate wave refection and replicate energy dissipation. Lysmer and Kuhlmeyer [\[64\]](#page-22-34) described the dependence of normal and shear stress at the boundaries on pressure and shear wave velocities as shown in Eqns. [15](#page-7-2) and [16.](#page-7-3)

<span id="page-7-2"></span>
$$
\sigma_{x,y} = C_1 \rho V_p u_{x,y} \tag{15}
$$

<span id="page-7-3"></span>
$$
\tau = C_2 \rho V_s u_z \tag{16}
$$

where,  $\sigma_{x,y}$ =normal stress in the x or y direction, respectively,  $\tau$  = shear stress in zx or zy plane,  $\rho$  = density of soil,  $V_p$  and  $V_s$ =pressure and shear wave velocities, respectively,  $u_x$  and  $u_y$  are the nodal velocities at the boundaries in x and y directions respectively, and  $C_1$  and  $C_2$  are the relaxation coefficients were employed to formulate the absorbent boundaries at the calculation stage. Additionally, dimensionless relaxation coefficients ( $C_1$  and  $C_2$ ) were utilized to





<span id="page-8-0"></span>**Fig. 5 a** Three-dimensional view structure foating column presents in XY directions, **b** solid element modeling using fnite element method (PLAXIS 3D)

improve the efficiency of the wave-absorbing boundaries in the calculation phase. However, Brinkgreve et al. [\[65](#page-22-35)] recommended setting these coefficients as  $C_1 = 1$  and  $C_2 = 0.25$ to maintain rational shear wave transmissivity at the boundaries for dynamic SSI behavior. The bedrock level was represented by incorporating a compliant base at the bottom of the soil medium. The compliant base is combined between the viscous boundaries to mitigate the refection of waves and enable the application of earthquake records through prescribed surface displacement. According to FEMA-273 [\[66](#page-22-36)], local site characteristics in the top 30 m of the soil profle stimulate earthquake amplifcation. Hence in this study depth of the bedrock level is considered to be 30 m below ground level.

The optimal number of elements was ascertained by conducting a mesh independence study (MIS). An MIS was conducted to investigate how the predicted response varies with the number of elements. The test was initiated with a very coarse mesh and progressed to a very fne mesh. Consequently, there is little to no signifcant diference in the structural response subjected to RSN-6 (Imperial Valley-02) ground motion when using a very fne mesh compared to a fne mesh. Thus, the decision was made to employ fne mesh elements for all analyses, ensuring accurate prediction of the structures dynamic response. The divided mesh comprises a total of 23,746 soil elements and 58,504 nodes, which is the highest value among all the meshed model structures. Seismic records are applied through prescribed surface displacement at the bottom of the soil model. The waves propagate through the soil medium and reach the foundation, inducing vibrations in the structure. Large concentrations of stress or deformation are expected during the analysis, especially at the soil and foundation interaction locations. Therefore, the mesh size is reduced and locally refned around the raft foundation (with a local element refne factor of 0.125) [\[63](#page-22-33)], as depicted in Fig. [5b](#page-8-0) to improve structural response results. The PLAXIS three-dimensional meshing perspective for modeling soil-structure systems with foating columns in the XY directions is shown in Fig. [5.](#page-8-0) To replicate the interaction between the foundation and the surrounding soil, a strength reduction factor  $(R<sub>inter</sub>)$  was utilized within the framework of the Mohr–Coulomb failure criterion. Soil characteristics are utilized to calculate the strength reduction factor (*Rinter*) for interfaces between structures and soil, enabling the representation of their lateral behaviors [[63\]](#page-22-33).

$$
C_i = R_{inter} C_{soil} \tag{17}
$$

$$
tan \phi_i = R_{inter} \ tan \phi_{soil} \le tan \phi_{soil}
$$
 (18)

$$
\psi_i = 0 \text{ for } R_{inter} < 1, \text{ other wise } \psi_i = \psi_{soil} \tag{19}
$$

where,  $C_i$  and  $\phi_i$  are cohesion and friction angle of the interface. The strength reduction factor  $(R<sub>inter</sub>)$  defines the roughness between the soil and the foundation. It describes the reduced shear strength at the interface between soil and foundation materials. Belinchnon et al. [[67\]](#page-22-37) and Nor et al. [[68](#page-23-0)], conducted numerical analyses using the PLAXIS fnite element program to investigate interface characteristics between foundations and diferent soil conditions. They performed direct shear interface tests with varying strength reduction factors ( $R<sub>inter</sub>$ ) ranging from 0.12 to 1 to simulate the foundation-soil interaction. Test results showed that decreasing the strength reduction factor increased soil

displacement. Thus, variations in the  $R<sub>inter</sub>$  value can signifcantly impact the distribution of shear stress between the foundation and soil, directly affecting soil displacement. The authors, Kim et al. [[69](#page-23-1)] and Fatahi and Tabatabaiefar [[70\]](#page-23-2) documented the utilization of a strength reduction factor of 0.75, a value commonly adopted in geotechnical practice, and found that it improved outcomes in numerical analysis. Therefore, a  $R_{inter}$  value of 0.75 is used in this study to achieve realistic results in the dynamic analysis.

# **Non‑linear time history analysis approach (NLTHA)**

The nonlinear time-history analysis is widely regarded as the most comprehensive approach to conducting seismic analysis. At the bedrock level, the seismic force is applied by inputting an acceleration time history. The structural response is calculated continuously throughout the entire duration of an earthquake, on every second. The governing equations of motion of a structure, including its base interaction, and their solution are complicated. Hence, in this study, the direct analysis method is used to simulate the interaction of soil-raft-structure systems and solve these equations in a complex system. The direct method involves the simultaneous modeling of the soil and structures system, and it solves the dynamic equilibrium equation, as depicted in Eq. [20](#page-9-0), in a single step.

$$
[M]{\n{ii} + [C]{\n{ii} + [K]}{\n{ii} = -[M]{\n{ii}_g} + {F_{vb}} \n{ (20)}}
$$

where, *[M], [C]*, and *[K]* represent the matrices for mass, viscous damping, and stifness respectively. The vectors {*ü*} *,* {*u̇* } and *{u}* refer to the acceleration, velocity, and displacement of the nodes concerning the underlying foundation. The vector  ${F_{vb}}$  denoted as a force vector associated with the viscous damping boundaries. Additionally,  $\{\ddot{u}_g\}$  represents the induced acceleration by seismic activity at the bedrock level [[71\]](#page-23-3). In this study, the aim is to conduct a dynamic time history analysis that incorporates the nonlinearity of soil material behaviors, the inelastic behaviors of structural systems, and the consideration of cracked sections for reinforced concrete. This approach is used to evaluate the reliable response of soil-structure systems due to seismic events.

The nonlinearity of the soil material and its characteristics have been discussed in Sect. "[Hardening soil model](#page-4-3) [with small strain stifness \(HSS\) model"](#page-4-3). The geometric and material nonlinearity of structures was taken into consideration during the analysis and design of rigid-based structures. The dynamic analysis incorporated the cracking efects by assuming that cracked beams and columns were 0.35 and 0.7 times the bending stifness of uncracked components, respectively [[44](#page-22-14)]. Also, the nonlinear behavior of beam and

column structural components with lumped plasticity is taken into account by putting plastic hinges on both ends. In this study, the plastic hinge characteristics were determined by utilizing the default auto hinge properties provided by ASCE (41–17) [\[72\]](#page-23-4). The modes of dynamic response in which approximately 90% of the mass is involved. The damping coefficients of structures are determined by utilizing Eq. [21](#page-9-1) and taking into account a damping ratio of 5% as described by Chopra et al. [[73\]](#page-23-5). The structural characteristics and damping coefficients for all modeled structures are presented in Table [5.](#page-9-2)

<span id="page-9-1"></span>
$$
\xi_i = \frac{1}{2} \left( \left( \frac{a}{\omega_i} \right) + \beta \omega_i \right) \tag{21}
$$

where  $\alpha$ ,  $\beta$ , and  $\xi$  are mass proportional coefficient, stiffness proportional damping coefficient, and critical damping ratio respectively.

### **Ground motion details**

The suitable ground motion records were selected based on the following factors, such as a magnitude  $(M_w)$  range of 4.5–7.5, a source-to-site distance of 5–50 km, and the dominating frequencies according to the Indian subcontinent during the past two decades, which ranged from 0.1 to 8 Hz. The PEER (Pacifc Earthquake Engineering Research) [[74\]](#page-23-6) database was used to collect the real strong ground motion records. This study performed the dynamic analysis incorporating a set of fve acceleration time histories of earthquakes with a magnitude of above 6. The characteristics of the selected ground motion records are listed in Table [6](#page-10-0). The selected ground motion for analysis has been appropriately scaled to IS 1893 to meet the specifed pga value of 0.16 g for a moderate seismic zone.

<span id="page-9-0"></span>This scaling process has been carried out using the seismomatch software  $[75]$ . According to ASCE/SEI (7-16) [[2\]](#page-21-1), the standard scaling procedure prevents scaled average response spectra from falling below the target spectrum over the period range of 0.2–1.5 T. Where T is the fundamental

<span id="page-9-2"></span>**Table 5** Structural characteristics for all models

Type of structure	Fundamental mode frequencies (rad/s)		Rayleighs damping coefficients	
	$\omega_1$	$\omega_2$	$\alpha$	
Without floating structure	5.13	14.30	0.3778	0.0051
$F$ loating- $X$	5.40	14.27	0.3920	0.0050
Floating-Y	5.70	15.40	0.4167	0.0047
Floating-XY	4.48	13.52	0.3369	0.0054



<span id="page-10-0"></span>**Table 6** Characteristics of selected ground motion

period of fxed-base structures. Over that time range, this study used a scaled ground motion average response spectrum that was not allowed to be less than the design spectrum. Bracketed duration is a common engineering way of quantifying strong ground motion. Bracket duration is the period between the frst and last ground acceleration exceeding 0.05 g [[76\]](#page-23-8). The bracket duration of the ground motions is applied at the rock level to perform the dynamic analysis. Figure [6](#page-10-1) displays the unscaled and scaled response spectrum while Fig. [7](#page-11-0) displays the scaled acceleration time history for selected ground motions.

# **Validation**

The validation study involved a comparison between the results obtained from experimental and numerical simulation to evaluate the efectiveness of the nonlinear simulation.

Design spectrum

<span id="page-10-1"></span>





<span id="page-11-0"></span>**Fig. 7** Scaled acceleration time history data for selected ground motion. **a** RSN-6 imperial valley-02, **b** RSN 57-san fernando, **c** RSN 93-san fernando, **d** RSN 122-fruiliitaly-01, and **e** RSN 456-morgan hill

El Hoseny et al. [\[77](#page-23-9)] conducted an experimental and numerical study on the seismic response of multistory buildings, considering SSI efects under diferent ground motions. For this validation investigation, a nonlinear time history analysis was performed on a prototype building frame model subjected to the Kobe earthquake of 1995. The prototype structure is composed of seven-story concrete frames supported by a raft foundation. The building frame consists of a double bay confguration with a bay width of 4 m and a floor height of 3 m. The prototype model has a total height of 21 m. The sectional dimensions of the beam and column are  $300 \times 600$  mm and  $800 \times 800$  mm, respectively, and the slab thickness is 160 mm. The compressive strength of concrete (*fck*) is 30 MPa, and the modulus of elasticity (*E*) is 25,742.96 MPa. The prototype model rests on both fexible and fxed bases. The soil-foundation-structure interaction of a real model system is shown in Fig. [8](#page-12-0)a. The soil type is silty clay with a unit weight of  $17.8 \text{ kN/m}^3$ , and the shear wave velocity  $(V<sub>s</sub>)$  is 220 m/s. The longitudinal and lateral boundaries of the soil model are 70 m and 50 m, respectively, and the depth soil model is 40 m. The frequency of the soil layer is 1.375 Hz. The HSS model parameters for silty clay are detailed in Table [7.](#page-13-0)

The procedure used in modeling the soil-raft-interface system remains consistent, with the same boundary conditions and interface characteristics as discussed earlier in the HSS constitutive model section. In Fig. [8](#page-12-0)b, the numerical analysis results show absolute displacement values at the roof level for structures with fxed and fexible bases. The numerical results are 94.2 mm for fxed bases and 103.9 mm for fexible bases, while the experimental study by El Hoseny et al. [\[77](#page-23-9)] recorded 92.5 mm for fxed bases and 102.5 mm for fexible bases. The comparison between roof level displacement values in the numerical and experimental



<span id="page-12-0"></span>**Fig. 8 a** Three-dimensional meshing view of the experimental model, **b** absolute displacement at roof level from numerical analysis, and **c** results of experimental and numerical analysis

<span id="page-13-0"></span>



data reveals a lower percentage of errors. The comparison of relative displacement distribution between structures with fxed and fexible bases in the numerical analysis and the experimental study, as shown in Fig. [8](#page-12-0)c, demonstrates good agreement in the lateral displacement of the building.

# **Result and discussion**

According to the International Building Code (IBC) [[48](#page-22-18)], soil C is classifed as very dense and soft-rock soil. Soil C exhibits signifcantly greater shear wave velocity and stifness properties. Analyzing the structural response of the soil C model in comparison to the fxed base model. The fndings from both cases indicate whether the SSI (soil C) model can serve as a suitable replacement for the fxed base model. The structure foating in the XY direction was utilized to assess the seismic response of both SSI (soil C) and fxed bases subjected to RSN-6 ground motions in this check (as an example). The roof displacement of fxed and SSI (soil C) structures are compared in Fig. [9.](#page-13-1) Small diferences were found between fxed and SSI (soil C) models. Thus, the soil C (SSI) model is considered a fxed base condition. In this numerical study, fve-story buildings are modeled with and without foating columns located in diferent soil conditions, considering the soil structure interaction efect. This dynamic analysis study employed the constitutive HSS model to simulate soil nonlinear behavior and perform nonlinear time history analysis. The assessment of structural response to earthquakes involved a comparison between structures with and without foating columns incorporating the SSI efects. The results are presented in terms of the average structural responses subjected to selected fve ground motions.

#### **Lateral storey displacement**

The relative lateral displacement is determined by subtracting the movement at the foundation level from the movement at the storey level to assess the soil-structure interaction (SSI) effect. This section discusses the average relative lateral displacement of storey levels for all modeled structures resulting from fve ground motions under diferent soil conditions. The structural models in this study modeled structures are considered, structures with foating columns in the X direction as FX, Y direction as FY, X, and Y directions as FXY, and without foating column structures as WOF. Figure [10](#page-14-0) shows the absolute and relative roof level displacement of structure FXY under the San Fernando (RSN-93) ground motion in diferent soil conditions (as an example). The hard soil condition is considered a fxed base in Fig. [10a](#page-14-0), the maximum absolute displacement time history at the roof level is subtracted from the foundation base to obtain a relative lateral displacement time history at the roof level. It is observed that the maximum relative displacement is −47 mm, and the maximum absolute roof and foundation displacement of  $-117$  mm and  $-94$  mm respectively.

In stiff soil, Fig. [10](#page-14-0)b displays the maximum absolute displacement of the roof and foundation as −135 mm and −103 mm, respectively, and the relative lateral displacement at the roof level as  $-57$  mm. Figure [10](#page-14-0)c shows that on soft soil, the roof and foundation exhibited maximum absolute displacements of −142 mm and −106 mm, respectively. Also, the maximum relative lateral displacement was observed at  $+68$  mm. Comparing Fig. [10](#page-14-0)a–c, the amplifcation ratio of maximum relative lateral displacement at the roof level is the relative lateral displacement of fexible bases (stiff and soft soil) divided by fixed base (hard soil). The amplifcation ratio of 1.21 (57/47) is determined under

<span id="page-13-1"></span>**Fig. 9** Roof displacement of foating column structures in XY direction due to 'RSN-6' ground motion



<span id="page-14-0"></span>**Fig. 10** Absolute and relative displacement time histories for the FXY model at the roof level under 'RSN-93'. **a** Hard soil, **b** stif soil, and **c** soft soil



stif soil conditions. In the case of soft soil conditions, it is observed that the amplifcation ratio is 1.45 (68/47). Figure [11](#page-15-0) shows the shape of the structural maximum displacement for the soil-foundation-structure system subjected to 'RSN 93' ground motion.

Figure [12](#page-16-0) shows the average relative lateral displacement profle for structures with and without foating columns on diferent soil conditions subjected to applied ground motions at the bedrock level. The structural average relative lateral displacement at the roof level in hard soil was obtained from the analysis as shown in Fig. [12a](#page-16-0). It is observed that the roof displacement values for diferent confgurations such as 18 mm for WOF, 24 mm for FX, 21 mm for FY, and 29 mm for FXY structures. Roof displacements increased 1.33 times for FX, 1.17 times for FY, and 1.61 times for FXY structures compared to without floating column structure. In stiff soil conditions, WOF, FX, FY, and FXY roof displacement values were 23 mm,

33 mm, 28 mm, and 40 mm respectively (Fig. [12b](#page-16-0)). The roof displacement of structures with foating columns FX, FY, and FXY is 1.43, 1.22, and 1.74 times greater compared to structures without a foating column.

In the case of soft soil conditions, the roof displacement values for WOF, FX, FY, and FXY structures are 32 mm, 44 mm, 39 mm, and 52 mm, respectively as shown in Fig. [12](#page-16-0)c. The roof displacement values exhibit an increase of 1.37 times for FX, 1.22 times for FY, and 1.62 times for FXY in comparison to the WOF structure. The structural seismic response for both fxed and soil-structure interaction (SSI) base conditions has been significantly infuenced by changes in the geometry of structures. Also, the displacement of storey levels experienced signifcant changes as a result of variations in the stifness of buildings [\[78\]](#page-23-10). The location of foating columns in structures modifes the structural geometry and varies the structural stifness along the height of the building. Hence, during



<span id="page-15-0"></span>**Fig. 11** Structural maximum displacement shape for a soil-foundation-structure system subjected to 'RSN 93' ground motion. **a** Hard soil, **b** stif soil, and **c** soft soil

the evaluation of structural seismic responses, one should consider the efects of structural shape under diferent soil conditions.

An enhanced lateral displacement occurs due to the fexibility of the soil-structure interaction. The interaction between the building and the surrounding soil allows for greater movement and deformation, resulting in increased relative lateral displacement along the height of the structure. The displacement values at the roof level in fexible bases such as stif soil and soft soil are signifcantly higher than in the fxed base (hard soil) condition. The amplifed value of roof displacement in stif soil, as compared to hard soil conditions, is 1.27 times for WOF structures, 1.37 times for FX structures, 1.33 times for FY structures, and 1.38 times for FXY structures. However, in the case of soft soil condition as compared to hard soil, the observed amplifed values were 1.78 times for WOF, 1.83 times for FX, 1.85 times for FY, and 1.79 times for FXY structure. Based on the analysis results, the incorporation of SSI efects enhanced the structural displacement. Specifcally, structures with foating columns in the XY direction resting on soft soil deposits signifcantly increase the roof displacement, which may afect building performance.

#### **Inter‑storey drift ratio (IDR)**

Storey drift ratio is the maximum relative displacement of each foor divided by its height. According to Standard Australia [\[79](#page-23-11)], the maximum inter-storey drift ratio is calculated using the following equation.

Inter storey drift = 
$$
\frac{(d_{(i+1)} - d_i)}{h}
$$
 (22)

where,  $d_{(i+1)}$ = deflection at the  $(i+1)$  level,  $d_i$ = deflection at the  $i$  level, and  $h$  = storey height. The inter-storey drift ratio is an essential structural response parameter that plays a signifcant role in evaluating the seismic performance of structures. It is calculated for each level, taking into account all time steps during the earthquake. The inter-storey drift ratio of the structures is supported by the fxed base (hard soil) and flexible bases (stiff and soft soil), as shown in



<span id="page-16-0"></span>**Fig. 12** Distribution of average relative lateral storey displacement. **a** Hard soil, **b** stif soil, and **c** soft soil

Fig. [13a](#page-17-0)–c. The orientation of foating columns in structures has been found to alter the inter-storey drift ratio when compared to those without foating column structures. Table [8](#page-17-1) provides a summary of the maximum inter-storey drift ratios for both types of structures.

The analysis results reveal that foating column structures have an increasing inter-storey drift ratio in fxed base (hard soil) conditions, with values increasing by 7% for FX and FY structures and 28% for FXY structures compared to WOF structures. In fexible bases, the structures foating columns (FX, FY, and FXY) have higher values in stiff soil conditions (29%, 12%, and 41%), and soft soil conditions (27%, 18%, and 40%) compared to without foating column structures. In addition, it is important to note the signifcant increase in IDR values for structures with foating columns (FX, FY, and FXY) compared to those without foating column structures.

When SSI effects are incorporated into flexible base models instead of fxed base models, the inter-story drift values of structures are amplifed. In stif soil conditions, fexible base structures have an increasing percentage of IDR values are 21%, 46%, 26%, and 33% for structures WOF, FX, FY, and FXY, respectively, compared to fxed base structures. Additionally, compared to fxed base structures, soft soil conditions have a greater efect on structures with WOF, FX, FY, and FXY by 57%, 86%, 73%, and 72%, respectively. These findings reveal that the presence of SSI effects signifcantly amplifes the inter-story drift values of structures, particularly in soft soil conditions. The decreasing dynamic characteristics of the subsoil conditions, which increase the



<span id="page-17-0"></span>**Fig. 13** Distribution of storey drift. **a** Hard soil, **b** stif soil, **c** soft soil

<span id="page-17-1"></span>**Table 8** Maximum inter storey drift values of structures resting on diferent soil medium

Soil type		Inter storey drift (IDR) values					
	Without floating column structures (WOF)	direction $(FX)$	Floating columns structure in X Floating columns structure in Y Floating columns direction $(FY)$	structure in XY direction (FXY)			
Hard soil	0.0014	0.0015	0.0015	0.0018			
Stiff soil	0.0017	0.0022	0.0019	0.0024			
Soft soil	0.0022	0.0028	0.0026	0.0031			

lateral displacement of buildings, are the cause of fuctuating inter-storey drift ratios between fxed and fexible bases.

This study has shown that the presence of SSI can lead to an uneven distribution of inter-storey drift ratios, with higher values observed in the middle stories compared to the top and bottom levels. In addition, the inter-storey height, defned as the ratio between ground and typical ground storey height, is 1.285 (4.5 /3.5). However, the variations in height between floor levels affect the stiffness and strength of each storey. An increased ground storey height increases the drift ratio above the changed storey, while top story drift decreases. It is evident, according to the Ghoozhdi et al. [\[22\]](#page-21-15)

study, that changing the ground foor height increases the drift ratio immediately above modifed storey levels and decreases at top levels.

#### **Peak horizontal acceleration (PHA)**

The horizontal acceleration response at the roof level of structures with foating columns oriented in the XY direction (FXY) resting on various soil types subjected to ground motion "RSN 57" (as an example) is shown in Fig. [14.](#page-18-0) Peak horizontal acceleration at the level of FXY buildings is 4.81 m/s<sup>2</sup>, 3.81 m/s<sup>2</sup>, and 3.70 m/s<sup>2</sup> for hard, stiff, and soft soil conditions, respectively. The study reveals that the peak horizontal acceleration at the roof level decreases by 21% and 23% in stiff and soft soil conditions compared to hard soil conditions. The fndings of the study indicate that buildings resting on hard soil conditions experience higher peak horizontal acceleration at roof level compared to those on stiff and soft soil conditions. This decrease in peak horizontal acceleration at the roof level suggests that the stifness of the soil has a signifcant impact on the structural response.

Figure [15](#page-19-0), shows the highest horizontal acceleration amplification ( $\text{PHA}_{\text{store}}$ / $\text{PHA}_{\text{bedrock}}$ ) occurs at the roof level for all structural models in diferent soil conditions. For WOF, FX, FY, and FXY structures, the roof level amplifcation is 5.10, 5.5, 5.32, and 5.80 times higher than the bedrock acceleration in hard soil conditions, as shown in Fig. [15a](#page-19-0). In stiff soil conditions, the amplified values are 3.99, 4.28, 4.10, and 4.74, respectively, as shown in Fig. [15b](#page-19-0). In the case of soft soil conditions, the roof acceleration amplifcations are 2.71, 2.98, 2.83, and 3.16, respectively as shown in Fig. [15](#page-19-0)c.

In comparing the fxed base model on hard soil to fexible base models in stif and soft soil conditions, it was found that the amplifcation ratio was higher for the fxed base model. However, the interaction models showed that incorporating the nonlinear behavior of soil in the model led to more consistent changes in the building height compared to the fxed base model. It was evident that the incorporation of SSI effects in moment-resisting frame buildings significantly

5

This study examines a comprehensive numerical analysis of the seismic response of mid-rise reinforced concrete structures, both with and without foating columns,

<span id="page-18-0"></span>**Fig. 14** Comparison of roof level acceleration history of FXY structures under diferent soil conditions subjected to ground motion "RSN 57"



lowered horizontal acceleration values at the roof level as compared to fxed-base model structures [\[80](#page-23-12), [81\]](#page-23-13).

### **Base shear value and internal forces in members due to seismic load**

The ultimate response of the base shear in each model is calculated by combining the maximum shear force in the ground foor columns during fve earthquake excitations [\[43](#page-22-13)]. The results regarding the ultimate response of the base shear under the fve selected seismic records are presented in Table [9](#page-19-1). The result of the time history analysis of models reveals that incorporating the SSI efect reduced the base shear value of structures. When compared to models with fixed bases (hard soil), the flexible bases (stiff and soft soil) in each model signifcantly reduced the base shear value. In comparison to fxed base models, the reduction in base shear for all models with fexible bases ranges from 46 to 60% for stiff soil conditions to 66 to 75% for soft soil conditions.

The envelope in Table [10](#page-20-0) shows the maximum bending moment values for the selected beams highlighted in Fig. [16.](#page-20-1) Comparing envelopes, fexible base models exhibit higher bending moments than fxed base models. Bending moments caused by varying base settlement due to soil-structure interaction decrease from the bottom to the top of structures. The ultimate response of axial forces and moments in the studied column (Fig.  $16$ ) when subjected to five ground motions is presented in Table [11.](#page-20-2) Comparing these envelopes reveals notably higher axial forces in the fexible base model under both stif and soft soil conditions compared to the fxed base (hard soil) model. Conversely, there was a decrease in bending moment values in the beams of fexible base models compared to fxed base models.

### **Conclusion**



<span id="page-19-0"></span>**Fig. 15** Ratio of structure PHA to bedrock PHA. **a** Hard soil, **b** stif soil, **c** soft soil

<span id="page-19-1"></span>**Table 9** Ultimate response of base shear response to fve selected earthquake motions

Soil type	Base shear (t) Structure type					
	WOF	FX	FY	FXY		
Hard soil	119.8	174.3	152.6	184.1		
Stiff soil	64.0	72.5	68.2	73.3		
Soft soil	40.6	42.8	42.4	51.3		

taking into account the efects of soil-structure interaction (SSI). Structures with foating columns were considered in diferent confgurations (X, Y, and XY). Three diferent types of soil conditions (hard, stif, and soft) were taken into account in this study. The PLAXIS 3D fnite element programming tool was used to simulate the interaction between soil and structure, employing the direct method. Nonlinear time history analysis was conducted to assess the seismic response of structures subjected to selected ground motions. The study assesses key seismic response parameters such as peak lateral displacement, peak interstorey drift ratio, peak horizontal acceleration, base shear, and member forces for different structural configurations and soil conditions. The fndings from the nonlinear dynamic analysis of this study can be summarized as follows.

<span id="page-20-0"></span>**Table 10** The ultimate response of the bending moment in the chosen beam





<span id="page-20-1"></span>**Fig. 16** Locations of studied columns and beams

(a) The incorporation of soil-structure interaction in nonlinear dynamic analysis results for fexible base structures (stiff and soft soil) reveals that lateral storey displacement signifcantly increases compared to fxed base (hard soil) structures. In stif soil conditions, peak lateral displacement increases by 1.27 to 1.38 times for all modeled structures. In soft soil conditions, this efect is even more pronounced, with increases ranging from 1.78 to 1.85 times. Specifcally, structures with floating columns in an XY configuration resting on soft soil deposits exhibit the highest roof displacement when subjected to earthquake excitation.

- (b) The orientation of foating columns in structures signifcantly infuences the structural seismic response, enhancing it through variations in geometry and structural stifness across the building height. Notably, in structures with foating columns (FX, FY, and FXY) resting on soft soil deposits, the lateral roof displacement increased by 1.22 to 1.62 times compared to structures without foating columns.
- (c) The incorporation of soil-structure interaction (SSI) efects in the analysis results in amplifed inter-story drift values in fexible base structures (stif and soft soil) compared to fxed base (hard) structures. In stif soil conditions, inter-story drift increases by 21% to 46% for all modeled structures. In soft soil conditions, this efect is even more pronounced, with increases ranging from 57 to 86%. It is noteworthy that structures with foating columns consistently exhibit higher inter-story drift ratios in all soil mediums compared to those without foating column structures.
- (d) The amplifed peak horizontal acceleration in all structural models reached its maximum at the roof level. The ratio of peak horizontal acceleration at the storey level to peak horizontal acceleration at the bedrock was higher in hard soil conditions compared to stiff and soft soil conditions.
- (e) Incorporating soil-structure interaction (SSI) efects in the analysis results in a significant reduction in base shear values. Flexible base models (stif and soft soil) demonstrate a substantial decrease in base shear compared to fxed base models (hard). The reduction

<span id="page-20-2"></span>



obtained ranges from 46 to 60% in stif soil and from 66 to 75% in soft soil.

(f) Bending moments in the studied beams and axial forces in columns show signifcant increases in fexible base models during earthquakes.

This numerical study fnding reveals that the incorporation of soil-structure interaction afects soil foundation fexibility and signifcantly infuences building seismic demand. Neglecting the SSI effects may result in underestimated responses and increased seismic risks. The foating column structures located in seismic-prone areas are more vulnerable especially structures resting on soft soil deposits. Hence, it is important to ensure the safety of foating column structures, even in moderately seismic areas, needs proper attention and the implementation of efective retroftting methods to prevent potential failures. The current study focuses solely on the seismic response of foating column structures outside regular buildings on homogeneous soil conditions. The authors suggest further studies incorporating the SSI efects on the dynamic behaviors of foating column structures with diferent heights and shapes of buildings resting on heterogeneous multilayered soil conditions. Additionally, exploring the impact of foating columns inside buildings at diferent foor levels is recommended. Adopting suitable retroftting methods to mitigate the seismic vulnerability of structures is also suggested.

**Author contributions** PJ: conceptualization, methodology, numerical investigation, validation, writing, and original draft preparation JAV: conceptualization, supervision, writing, reviewing, and editing. All authors have read and agreed to the published version of the manuscript.

### **Declarations**

**Conflict of interest** The authors declare that they have no known competing fnancial interests or personal relationships that could have appeared to infuence the work reported in this paper.

**Ethical approval** This article does not contain any studies with human participants or animals performed by any of the authors.

**Informed consent** For this type of study, no informed consent is required.

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