**RESEARCH PAPER**



# **Risk Assessment of Three‑Dimensional Bearing Capacity of a Circular Footing Resting on Spatially Variable Sandy Soil**

**Kouseya Choudhuri1 · Debarghya Chakraborty<sup>1</sup>**

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#### **Abstract**

The present study investigates the probabilistic assessment of the three-dimensional bearing capacity of a circular footing resting on spatially variable sandy soil. The random fnite-diference method and Monte Carlo simulation (MCS) technique are utilized to execute all numerical analyses. Three different combinations of friction and dilation angles ( $\phi = 30^\circ$ ,  $\psi = 0^\circ$ ; *ϕ*=35°, *ψ*=*ϕ*/6; and *ϕ*=40°, *ψ*=*ϕ*/3) are considered in this study. The tangent of friction angle (tan*ϕ*) is assumed as the lognormally distributed random field. The variations in mean bearing capacity  $(\mu_q)$  and failure probability  $(p_f)$  are presented with respect to normalized horizontal scales of fluctuation  $(\theta_x/D = \theta_y/D)$  for different friction and dilation angles ( $\phi$  and  $\psi$ ), coefficients of variation of tan $\phi$  (*COV*<sub>tan $\phi$ </sub>), normalized vertical scales of fluctuation ( $\theta_z/D$ ), and footing diameters (*D*). The effect of negative cross-correlation between *c* and tan $\phi$  is explored. The changes in  $p_f$  for different factors of safety (*FOS*),  $COV<sub>tan</sub>$ , and  $\theta<sub>x</sub>/D = \theta<sub>y</sub>/D$  are also illustrated in this study. Based on this observation, the target failure probability ( $p<sub>f~tot</sub>$ ) is plotted against the required factor of safety ( $FOS_{\text{red}}$ ). The variations in the allowable bearing capacity ( $q_{ad}$ ) in the design of the footing are also illustrated for different reliability indices ( $\beta$ ),  $COV_{\text{tan}\phi}$ , and  $\theta_x/D = \theta_y/D$ .

**Keywords** Circular footing · Bearing capacity · Sandy soil · Spatial variability · Failure probability

# **1 Introduction**

The uncertainty associated with geotechnical structures can be broadly classifed into three categories: (1) the inherent variability associated with the soil properties, (2) the variability in sampling and testing processes, and (3) the uncertainty related to the model transformation (Phoon and Kulhawy [1999](#page-17-0)). To incorporate these uncertainties into the structure, engineers have historically used the conventional deterministic-based approach, considering the factor of safety (*FOS*). However, this concept does not ensure that the structure is completely safe against failure, and it often leads to the under-prediction or over-prediction of the responses of the structure (Gong et al. [2015\)](#page-16-0). The rationality of using the failure probability concept in the structure can be justifed

 $\boxtimes$  Debarghya Chakraborty debarghya@civil.iitkgp.ac.in Kouseya Choudhuri kousheyo1995@iitkgp.ac.in

<sup>1</sup> Department of Civil Engineering, Indian Institute of Technology Kharagpur, Kharagpur, West Bengal 721302, India

as it helps in considering the inherent variability associated with the soil parameters using the probabilistic statistics and distribution type of these parameters (Cherubini [2000](#page-16-1); Mollon et al. [2009;](#page-17-1) Nazeeh and Sivakumar Babu [2021](#page-17-2); Luo and Luo [2022](#page-17-3)). The concept of soil spatial variability has been incorporated into several geotechnical problems (Fenton and Grifths [2002;](#page-16-2) Grifths et al. [2002;](#page-16-3) Grifths and Fenton [2004;](#page-16-4) Haldar and Sivakumar Babu [2008;](#page-16-5) Luo et al. [2012](#page-17-4); Kasama and Whittle [2016;](#page-17-5) Halder and Chakraborty [2020\)](#page-16-6) using the random feld theory introduced by Vanmarcke ([1983\)](#page-17-6). Several studies on the shallow foundation have taken into account the efect of soil spatial variability (Fen-ton and Griffiths [2003;](#page-16-7) Griffiths et al. [2006;](#page-16-8) Cho and Park [2010;](#page-16-9) Johari and Sabzi [2017](#page-17-7); Wu et al. [2019](#page-17-8); Johari et al. [2019;](#page-17-9) Krishnan and Chakraborty [2022](#page-17-10)). However, these studies were restricted to two-dimensional strip footings. Reliability-based studies on three-dimensional shallow foundations (e.g., rectangular, square) considering soil spatial variability are limited, as the analyses of these foundations are computationally expensive. Nevertheless, such probabilistic analyses are essential, because these foundations are constructed to carry massive super-structural loads, and the failure associated with them must be appropriately assessed



(Kawa and Puła  $2020$ ). Fenton and Griffiths  $(2005)$  $(2005)$  produced the pioneering work on the probabilistic assessment of individual and two closely spaced square footings considering the spatial variability efect of the elastic modulus to determine the total and diferential settlements, respectively. Al-Bittar and Soubra ([2014\)](#page-16-11) carried out a reliability-based study on the bearing capacity of square footing, considering cohesion and friction angle as the spatially variable random felds. Ahmed and Soubra ([2014\)](#page-16-12) conducted probabilitybased analyses of a three-dimensional circular footing under inclined loading. Their study aimed to determine the reliability index and the correlated failure modes under ultimate and serviceability limit states. However, the spatial variability efect was not taken into account in their study. Kawa and Pula ([2020\)](#page-17-11) studied the spatial variability effect of cohesion and friction angle on the load-carrying capacity of a square footing resting on cohesive-frictional  $(c-\phi)$  soil. The aim of their paper was to study the efect of the horizontal scale of fuctuation on the probabilistic characteristics of the load-carrying capacity. Several other researchers (Simões et al. [2013;](#page-17-12) Kawa and Puła [2020;](#page-17-11) Chwała and Kawa [2021\)](#page-16-13) have explored the effect of spatial variability on the threedimensional bearing capacity of strip footing, considering the modeled length in the out-of-plane direction. Recently, Choudhuri and Chakraborty [\(2022](#page-16-14)) conducted probabilitybased analyses of the three-dimensional bearing capacity of a circular footing resting on a spatially variable two-layer *c*-*ϕ* soil system.

Circular footing on sandy soil is a classical geotechnical problem which has been used worldwide over the decades. Several researchers (Manoharan and Dasgupta [1995](#page-17-13); Erickson and Drescher [2002;](#page-16-15) Loukidis and Salgado [2009\)](#page-17-14) have conducted deterministic analyses on the bearing capacity of circular footing on sandy soil, exploring the efect of both associativity and non-associativity. Erickson and Drescher ([2002\)](#page-16-15) carried out a two-dimensional axisymmetric analysis of a circular footing having  $D = 12$  m for  $\phi$ =20°, 35°, 40°, and 45° and corresponding  $\psi$ =0°,  $\phi$ /2, and  $\phi$ , considering mass density  $(\rho_m) = 1500 \text{ kg/m}^3$ , cohesion (*c*) = 0.1 kPa and  $\rho_m = 2500 \text{ kg/m}^3$ , *c* = 100 kPa. The ultimate bearing capacity of the circular footing was found to increase with the increase in dilation angle for a particular *ϕ* value. Ornek et al. [\(2012\)](#page-17-15) carried out a numerical study

using fnite-element software to predict the scale efect of circular footing supported by partially replaced granular fll on natural clay deposits. A two-dimensional axisymmetric model was generated in their study, and the numerical analysis results were validated with small-scale feld tests. It was observed that the ultimate bearing capacity increased with the increase in footing diameter. The present study compares the results obtained by Erickson and Drescher [\(2002](#page-16-15)) for the cases of  $\phi = 20^{\circ}$ , 35°, and 40° and corresponding  $\psi = 0^{\circ}$ ,  $\phi/2$ , and  $\phi$ , considering  $\rho_m = 1500 \text{ kg/m}^3$ , and  $c = 0.1 \text{ kPa}$ , and the comparison is presented in Table [1.](#page-1-0) Similarly, this study compares the feld test results obtained by Ornek et al. [\(2012\)](#page-17-15), considering the diameter of the footing,  $D=0.12$  m, and the thickness of the granular layer,  $H_{or} = 0.333D$ . The comparison is illustrated in Fig. [1.](#page-1-1) It can be seen that the results obtained from the present study closely resemble those in the literature.

From the extensive literature survey, it is found that no reliability-based study is available on the three-dimensional circular surface footing resting on sandy soil, considering the spatial variability efect of the soil friction angle. Hence, the present study tries to provide a general perspective of the problem. The primary objective of this paper is to study the variations in  $\mu_q$  and  $p_f$  of the system for different  $\theta_x/D = \theta_y/D$ . In this study, the friction angle  $(\phi)$  is characterized as the



<span id="page-1-1"></span>**Fig. 1** Comparison of bearing pressure versus settlement ratio curve for the circular footing between the present study and Ornek et al. ([2012\)](#page-17-15)

<span id="page-1-0"></span>



<sup>a</sup>Axisymmetric model in FLAC<sup>2D</sup>

<sup>b</sup>Three-dimensional model in FLAC<sup>3D</sup>



spatially variable random feld. Since the dilation angle (*ψ*) is assumed to be the function of friction angle, it is also simulated as the random feld. The soil cohesion is assumed to be a non-random parameter in the study. However, the efect of cross-correlation between cohesion and friction angle ( $\rho_{c\text{-tan}\phi}$ ) is also explored in the present study as a representative case where the soil cohesion is characterized as a random field. The changes in  $p_f$  for different *FOS* and  $\theta_x/D = \theta_y/D$  are explored in the study. Design charts are provided, illustrating the variations in the  $FOS_{req}$  for different  $p_{f \, \text{fgt}}$ . The  $q_{ad}$  of the footing is evaluated based on a few standard reliability indices ( $β$ ), and the variations in  $q_{ad}$ are also shown for different coefficients of variation of tan  $(COV_{\text{tand}})$  and  $\theta_x/D = \theta_y/D$ .

# **2 Details of Finite‑Diference Numerical Modeling**

A three-dimensional rigid circular footing with a rough base placed on the surface of sandy soil is represented by a schematic diagram shown in Fig. [2a](#page-2-0). The diameter of the footing is represented by  $D$ . FLAC<sup>3D</sup> software (Itasca [2012\)](#page-16-16) is used to model the footing and the soil domain and to execute all the numerical analyses. In the probabilistic analysis, a full model domain is considered where the stretch of the model domain in both horizontal directions is assumed to be 10*D*, whereas the stretch of the model in the vertical direction is considered to be 5*D*. The model domain is chosen after several trials to avoid boundary effects. The horizontal and vertical movements are restricted at the bottom boundary, whereas only the vertical movement is allowed at the outer side boundaries by the provision of the lateral restriction. Radially graded mesh around a cylindrical tunnel with a solid core is incorporated for discretization of the soil domain. Finer mesh is generated adjacent to the footing area where the high-stress gradient is expected, whereas the mesh size becomes coarser as it approaches the boundary. Total elements of the domain are selected as 18,144 to maintain the balance between efficiency and accuracy. The finite-difference discretized mesh is shown in Fig. [2](#page-2-0)b. The sandy soil is assumed to obey the elastic-perfectly plastic Mohr–Coulomb yield criterion. Three different friction angles ( $\phi$ =30°, 35°, and 40°) are considered in the present study. As per Sloan ([2013\)](#page-17-16), the  $\psi$  of the soil varies from 0<sup>°</sup> to  $\phi$ /3. Hence, three different dilation angles,  $\psi = 0^{\circ}$ ,  $\phi/6$ , and  $\phi/3$ , are considered in this study to correspond to  $\phi = 30^{\circ}$ ,  $35^{\circ}$ , and  $40^{\circ}$ , respectively. Young's modulus (*E*) and Poisson's ratio (*υ*) of the soil are assumed to be 30 MPa and 0.3, respectively (as per Johari and Sabzi [2017](#page-17-7)). After mesh generation and allocation of soil properties to all the elements, the whole model is analyzed under gravity loading. The footing roughness is ensured by providing lateral resistance to the footing nodes.



<span id="page-2-0"></span>**Fig. 2** Circular footing on sandy soil: **a** schematic diagram, **b** fnitediference discretization

An optimum and very small amount of controlled downward displacement of magnitude  $5 \times 10^{-6}$  m (per step) is applied at the specifed nodes. Then the model undergoes a certain number of steps until the limiting value of bearing capacity is achieved (Halder and Chakraborty [2020](#page-16-6); Kawa and Puła 2020). It should be noted that a small amount of cohesion  $(c=0.5 \text{ kPa})$  is considered in all the analyses to achieve numerically stable results. For this reason, the results are presented using the ultimate bearing capacity of footing (*qu*) instead of the bearing capacity factor, *Nγ*.

#### **3 Deterministic Analysis**

Deterministic analyses are carried out for three diferent combinations of friction and dilation angles (i.e.,  $\phi = 30^{\circ}$ ,  $\psi = 0^\circ$ ;  $\phi = 35^\circ$ ,  $\psi = \phi/6$ ; and  $\phi = 40^\circ$ ,  $\psi = \phi/3$ ) and three different diameters  $(D=0.5 \text{ m}, 1 \text{ m}, \text{ and } 2 \text{ m})$  of the circular



footing. The importance of deterministic analyses is justifed as the results obtained can be used as a reference to calculate the  $p_f$  of the system. Both  $\phi$  and  $\psi$  are considered to be spatially constant during the deterministic analyses. The bearing pressure–settlement ratio (*q* versus *s*/*D*) curves for three different  $\phi$ ,  $\psi$ , and *D* are illustrated in Fig. [3a](#page-3-0), b, and c. The bearing capacity of the footing increases with the increase in  $\phi$  and  $\psi$ , which is a very intuitive observation. In the present study, the  $q_{ud}$  of the footing is expressed as the footing pressure for a particular settlement ratio (*s*/*D*) of 6%. However, in the case of  $\phi = 40^{\circ}$ ,  $\psi = \phi/3$  for  $D = 0.5$  m and 1 m, and for all the combinations of  $\phi$  and  $\psi$  for  $D=2$  m, the stable value of footing pressure has yet to be reached. According to Eurocode 7 (CEN [2013\)](#page-16-17), the permissible settlement of a typical footing for a normal residential building can be considered as 75–135 mm, and the settlement value of 6% of *D* (even for  $D=2$  m) falls within this range. Hence, the  $q_{ud}$  of the footing is defned based on the settlement criterion. The  $q_{ud}$  of the footing corresponding to  $s/D = 6\%$  for different  $\phi$ , *ψ*, and *D* is shown in Fig. [3](#page-3-0)d, where it is observed that the *qud*

of the footing (at  $s/D = 6\%$ ) increases as the footing diameter increases, irrespective of the change in  $\phi$  and  $\psi$ .

## **4 Probabilistic Analyses**

#### **4.1 Random Fields for** *ϕ* **and** *ψ*

Generally, soil is highly complex in nature, depending on its mineralogical components, physicomechanical behavior, and loading history. Hence, layer-wise variations in soil properties may be observed in nature, in which the variation can also be observed within a single layer of soil (Johari et al. [2017](#page-17-17)). In the present study,  $\phi$  is characterized by a random field. Since the dilation angle for  $\phi = 35^\circ$  and 40° is a function of  $\phi$ , the dilation angles for these two friction angles can also be defned by the random felds. However, due to the very small cohesion value (i.e.,  $c = 0.5$  kPa), it is considered homogeneous throughout the study. Similarly, this study considers *E* and *υ* as spatially constant. The random



<span id="page-3-0"></span>**Fig. 3** Bearing pressure versus settlement ratio curves for circular footing with **a**  $D=0.5$  m, **b**  $D=1$  m, **c**  $D=2$  m, and **d** variation in  $q_{ud}$  with respect to *D* corresponding to  $s/D = 6\%$ 



field for tan $\phi$  is assumed to be lognormally distributed, as it always gives non-negative random numbers. The tan $\phi$  is chosen as a random field instead of  $\phi$ , as it ensures that the randomly initiated  $\phi$  values are between 0° and 90° (Griffiths et al. [2011](#page-16-18); Krishnan and Chakraborty [2022](#page-17-10)).

In the present study, a three-dimensional Markov exponential autocorrelation function,  $\rho(\varsigma)$ , is used to define the correlation structure of the randomly generated friction feld. The three-dimensional Markov function uses the scales of fluctuation (SOFs) in both the horizontal  $(\theta_x, \theta_y)$  and vertical  $(\theta_z)$  directions and can be expressed as follows:

$$
\rho(\varsigma_x, \varsigma_y, \varsigma_z) = \exp\left(\frac{-2|\varsigma_x|}{\theta_x} + \frac{-2|\varsigma_y|}{\theta_y} + \frac{-2|\varsigma_z|}{\theta_z}\right) \tag{1}
$$

In the above equation,  $\zeta_x = (x_k - x_l)$ ,  $\zeta_y = (y_k - y_l)$ , and  $\varsigma_z = (z_k - z_l)$  are the centroidal distances between the *k*th and *l*th elements, where  $k = 1, 2, 3, ..., E_n$ , and  $l = 1, 2, 3$ ,  $..., E_n$  ( $E_n$  is the total number of elements in the generated mesh).  $\theta_x$ ,  $\theta_y$ , and  $\theta_z$  are the SOFs in the *x*, *y*, and *z* directions, respectively. The SOF defnes the distance over which the randomly generated values of a soil parameter are strongly correlated with each other. Lower SOF values defne ragged fields, whereas higher SOF values define smoothly varying random felds (Grifths et al. [2002](#page-16-3)). The present study considers the SOFs in the *x* and *y* directions as equal (i.e.,  $\theta_x = \theta_y$ ), following the literature (Kawa and Puła [2020](#page-17-11); Choudhuri and Chakraborty [2021\)](#page-16-19). Considering the soil deposition process in nature,  $\theta_x = \theta_y$  is generally assumed to be greater than  $\theta$ <sub>z</sub> (Jamshidi Chenari and Mahigir [2014](#page-17-18)). Hence, the anisotropic random feld is considered in the present study where  $\theta_x = \theta_y > \theta_z$ . However, it should be noted that there are a few cases where  $\theta$ <sub>z</sub> is considered to be greater than  $\theta_x = \theta_y$  to explore the effect of  $\theta_z$  on the probabilistic characteristics of bearing capacity. The parameters used in the probabilistic study are outlined in Table [2.](#page-4-0)

The spatially variable random field of  $\phi$  is generated using the Cholesky decomposition method (Haldar and Sivakumar Babu [2008](#page-16-5); Kasama and Whittle [2016](#page-17-5)). Since the obtained autocorrelation matrix  $\rho(\zeta)$  is positive definite, the matrix can be factorized into the lower triangular matrix (*Q*) and its transpose ( $Q^T$ ), as follows:

$$
\rho(\zeta) = QQ^{\mathrm{T}} \tag{2}
$$

The spatially correlated standard normal random feld for friction angle  $(G<sub>ln tan</sub>_{\phi})$  can be evaluated using the lower triangular matrix (*Q*) as follows:

$$
G_{\ln \tan \overline{\phi}} = \sum_{j=1}^{i} Q_{ij} (G_{\ln \tan \phi})_j, i = 1, 2, 3, ..., E_n
$$
 (3)

where  $G_{\ln \tan \phi}$  denotes the column vector of the uncorrelated standard normal variable with zero mean and unit standard deviation. As tan $\phi$  of the soil is assumed to be lognormally distributed, the spatially varied random fields for  $\phi$  can be expressed as follows:

$$
\phi(\xi) = \tan^{-1} \left[ \exp\{ \mu_{\ln \tan \phi} + \sigma_{\ln \tan \phi} G_{\ln \tan \overline{\phi}} \} \right] \tag{4}
$$

In the above equation,  $\xi = \xi(x, y, z)$  denotes the spatial location of a point where the friction feld is required. The underlying normal distribution parameters  $\mu_{\text{ln tan } \phi}$  and  $\sigma_{\text{ln tan } \phi}$ are evaluated using the following transformations:

$$
\sigma_{\ln \tan \phi}^2 = \ln \left( 1 + \frac{\sigma_{\tan \phi}^2}{\mu_{\tan \phi}^2} \right) = \ln(1 + \text{COV}_{\tan \phi}^2)
$$
 (5)

$$
\mu_{\ln \tan \phi} = \ln \mu_{\tan \phi} - \frac{1}{2} \sigma_{\ln \tan \phi}^2 \tag{6}
$$

To extract the centroidal coordinates of all the elements of the discretized mesh as a text fle, an in-house FISH subroutine is written in FLAC<sup>3D</sup>. After extracting those coordinates into the text fles, the fles are loaded into MATLAB (The MathWorks Inc. [2020\)](#page-17-19). The spatially varied random felds for *ϕ* and *ψ* are generated in MATLAB using the parameters provided in Table [2.](#page-4-0) Then the obtained random felds are taken back to FLAC<sup>3D</sup> as the text file and assigned to each

<span id="page-4-0"></span>**Table 2** Parameters used in probabilistic analyses

Fixed parameters	
Cohesion, $c$ (kPa)	0.5
Normalized horizontal scales of fluctuation, $\theta$ ,/D = $\theta$ ,/D	1.25, 2.5, 5, 10
Number of Monte Carlo realizations	300
Variable parameters	
Mean of tan $\phi$ ( $\mu_{tan\phi}$ ) and dilation angle ( $\psi$ )	$tan(30^{\circ}) (\psi = 0^{\circ})$ , $tan(35^{\circ}) (\psi = \phi/6)$ , $tan(40^{\circ}) (\psi = \phi/3)$ $(COV_{\text{tand}} = 20\%, D = 1 \text{ m}, \theta/D = 1)$
Coefficients of variation of the tangent of friction angle, $COV_{\text{tand}}$	5%, 10%, 20% ( $\mu_{tan\phi} = \tan(30^\circ)$ , $\psi = 0^\circ$ , D = 1 m, $\theta_z/D = 1$ )
Normalized vertical scales of fluctuation, $\theta$ <sub>-</sub> /D	1, 2, 4, 8 ( $\mu_{tan\phi}$ = tan(35°), $\psi = \phi/6$ , $COV_{tan\phi}$ = 20%, D = 1 m, $\theta_z/D$ = 1)
Footing diameter, D	0.5 m, 1 m, 2 m ( $\mu_{tan\phi}$ = tan(30°), $\psi$ = 0°, $COV_{tan\phi}$ = 20%, $\theta_z/D$ = 1)



element of the discretized mesh using the FISH subroutine. The exemplary random fields for different  $\phi$  for the constant values of  $\theta_x/D = \theta_y/D$ ,  $\theta_z/D$ ,  $COV_{tan\phi}$ , and *D* are illustrated in Fig. [4](#page-5-0). Cross-sectional views of the friction feld along the centroid of the footing are also depicted in that fgure. It should be noted that the illustrated felds correspond to a particular Monte Carlo realization. The  $\mu_q$  and  $COV_q$  of  $q_u$ for the given sets of probabilistic parameters are evaluated



**(c)**

<span id="page-5-0"></span>**Fig.** 4 Spatially variable random fields of friction angle ( $\phi$ ) for **a**  $\phi = 30^\circ$ , **b**  $\phi = 35^\circ$ , and **c**  $\phi = 40^\circ$ 





<span id="page-6-0"></span>**Fig. 5** Variations in **a**  $p_f$  and **b**  $COV_{pf}$  of the footing with respect to MCS for different  $COV_{\text{tan}\phi}$ 

using the Monte Carlo simulation (MCS) technique. In addition, the probabilistic  $q_u$  is evaluated at  $s/D = 6\%$ . The coefficient of variation of the failure probability  $(COV_{pf})$  of the footing is evaluated to check the performance of the MCS (Cheng et al. [2018\)](#page-16-20). This is essential, because as the number of MCS increases, the numerical accuracy increases. However, the probabilistic analyses of the three-dimensional problem under the MCS framework require substantial computational effort. Hence, a trade-off between the computational efficiency and accuracy of the obtained solution should be established. Following the central limit theorem, the estimated  $p_f$  can be used to determine the accuracy of the chosen MCS. The  $COV_{pf}$  is evaluated using the following equation:

$$
COV_{pf} = \sqrt{\frac{1 - p_{\rm f}}{N_{\rm mcs} p_{\rm f}}}
$$
(7)

In the above equation,  $N_{\text{mes}}$  denotes the number of Monte Carlo simulations. As per the literature (Cheng et al. [2018](#page-16-20)), the reasonable value of the  $COV_{pf}$  can be set as 10%. The variations in  $p_f$  and  $COV_{pf}$  for different MCS and  $COV_{tan\phi}$ are illustrated in Fig. [5.](#page-6-0) It is observed that the  $p_f$  of the system is almost stable after 300 Monte Carlo realizations. The obtained  $COV_{pf}$  values for different  $COV_{tan\phi}$  are also well below 10% after the 300 MC realizations. Hence, all the probabilistic analyses are carried out for the 300 MC realizations. All analyses were performed on a PC with 12 GB RAM and a single Intel Core i5 processor with a clock speed of 1.80 GHz, and around 22 h of computational time was required to complete the 300 MCSs for a particular set of probabilistic input statistics.

#### **4.2 Failure Probability**

A footing is said to fail under the ultimate limit state of collapse when the stress applied to the footing (i.e.,  $q_{amp}$ ) exceeds the  $q_u$  of the underlying soil. Following the exist-ing literature (Griffiths et al. [2002](#page-16-3); Haldar and Sivakumar Babu [2008](#page-16-5); Krishnan and Chakraborty 2022), the present study considers the  $q_{ud}$  as the stress applied to the footing. Since  $tan\phi$  is assumed to be lognormally distributed, the distribution of the probabilistic ultimate bearing capacity  $(q_u)$ will most likely follow the lognormal distribution. However, the actual distribution of  $q_u$  is compared with the assumed hypothetical cumulative lognormal distribution having the parameters  $\mu_q$  and  $COV_q$  (Fig. [6a](#page-7-0)). The plot is constructed for the case of  $\phi = 30^{\circ}$ ,  $\psi = 0^{\circ}$ ,  $D = 1$ ,  $\theta_x/D = \theta_y/D = 2.5$ ,  $\theta_z/D = 1$ , and  $COV_{\text{tan}\phi}$  = 20%. The observed distribution of  $q_u$  closely matches the theoretical distribution. The distribution of *qu* is further confrmed using the Kolmogorov–Smirnov test (Massey [1951](#page-17-20)), which is performed for three diferent significance levels (i.e.,  $\alpha = 1\%$ , 5%, and 20%). For each significance level, the maximum absolute diference between the actual and theoretical distribution is well below the critical value. Thus, the lognormal distribution is acceptable at the given signifcance levels. Along with this cumulative distribution function (*CDF*) plot, the actual distribution of  $q_u$ is expressed through the histogram illustrated in Fig. [6b](#page-7-0). It is observed that the histogram of  $q_u$  closely resembles the lognormal fit. Hence, the  $p_f$  of the system can be estimated as the probability for which the evaluated  $q_u$  is less than the *qud*, as follows:

$$
p_{\rm f} = P(q_u < q_{\rm app}) = P(q_u < q_{\rm ud}) = \Phi\left(\frac{\ln(q_{\rm ud}) - \mu_{\ln q_u}}{\sigma_{\ln q_u}}\right) = \Phi(-\beta) \tag{8}
$$

where  $\Phi(.)$  is the cumulative normal distribution function.  $\mu_{\ln q_u}$  and  $\sigma_{\ln q_u}$  are the transformed normal distribution

<span id="page-6-1"></span>



<span id="page-7-0"></span>**Fig. 6** a Comparison of actual distribution with the assumed theoretical lognormal distribution of  $q_u$ , **b** histogram of  $q_u$  with lognormal fit for  $D=1$  m,  $\phi = 30^{\circ}$ ,  $\psi = 0^{\circ}$ ,  $c=0.5$  kPa,  $COV_{tan\phi} = 20\%$ ,  $\theta_x/D = \theta_x/D = 2.5$ , and  $\theta_x/D = 1$ 

parameters, and  $\beta$  defines the reliability index. It should be noted that in this section, the obtained  $p_f$  is for  $FOS = 1$ .

## **5 Results Obtained from the Probabilistic Analyses**

This section is devoted to the detailed discussion on the variation in  $\mu_q$  and  $p_f$  with respect to different  $\theta_x/D = \theta_y/D$ . The effect of  $\theta_z/D$  on  $\mu_q$  and  $p_f$  is also scrutinized in this section for the particular values of  $\phi$  and  $\psi$ ,  $COV_{tan\phi}$ , and *D*. The next sub-section illustrates the failure mechanism of the spatially variable random soil under the footing for diferent *ϕ* and  $\psi$ . Then, the changes in *CDF* and *PDF* of  $q_u$  for different  $COV_{\text{tan}\phi}$ ,  $\theta_x/D = \theta_y/D$ , and  $\theta_z/D$  are discussed. The impacts of different *FOS* on the  $p_f$  for different  $COV_{\text{tan}\phi}$  and  $\theta_x/D = \theta_y/D$ are also discussed in this section, and based on this, the plots of  $p_{f_{\text{f}}_{\text{g}}}/p_{\text{f}_{\text{g}}}/p_{\text{g}}$  are provided for different  $COV_{\text{tan}\phi}$  and  $\theta_x/D = \theta_y/D$ . Finally, the  $q_{ad}$  of the footing is evaluated for different  $\beta$ ,  $COV_{\text{tan}\phi}$ , and  $\theta_x/D = \theta_y/D$ .

### 5.1 Variations in  $\mu_q$  and  $p_f$  for Different  $\theta_x/D = \theta_y/D$ , *ϕ***, and** *ψ*

The variations in  $\mu_a$  for different  $\theta_x/D = \theta_y/D$ ,  $\phi$ , and  $\psi$  with constant values of  $D=1$  m,  $COV_{tan\phi} = 20\%$ , and  $\theta_z/D = 1$  are illustrated in Fig. [7a](#page-7-1). Similarly, the variations in  $p_f$  for the same set of parameters are shown in Fig. [7](#page-7-1)e. For  $\phi = 30^{\circ}$ ,  $\psi = 0^{\circ}$  and  $\phi = 35^{\circ}$ ,  $\psi = \phi/6$ , the  $\mu_q$  increases as  $\theta_x/D = \theta_y/D$ increases, whereas for  $\phi = 40^{\circ}$ ,  $\psi = \phi/3$ ,  $\mu_a$  decreases with an increase in  $\theta_x/D = \theta_y/D$ . However, the variation in  $\mu_a$ with respect to  $\theta_x/D = \theta_y/D$  is restricted to a very small



<span id="page-7-1"></span>Fig. 7 Variations in  $\mu_q$  with respect to  $\theta_x/D = \theta_y/D$  corresponding to different **a**  $\phi$  and  $\psi$ , **b**  $COV_{\text{tan}\phi}$ , **c**  $\theta_z/D$  and **d** D; variations in  $p_f$  with respect to  $\theta_x/D = \theta_y/D$  corresponding to different **e**  $\phi$  and  $\psi$ , **f**  $COV_{\text{tan}\phi}$ , **g**  $\theta_z/D$ , and **h** *D* 



range. The  $p_f$  of the system decreases with the increase in  $\theta_x/D = \theta_y/D$  irrespective of the change in magnitude of  $\phi$  and *ψ*. For a particular value of  $θ_x/D = θ_y/D$ , the  $p_f$  of the system increases remarkably as  $\phi$  increases from 30° to 35°, and  $\psi$ increases from  $0^{\circ}$  to  $\phi/6$ . However, a marginal increase in  $p_f$ is observed as  $\phi$  increases from 35 $^{\circ}$  to 40 $^{\circ}$ , and  $\psi$  increases from *ϕ*/6 to *ϕ*/3. It is also observed that the rate of change in both  $\mu_q$  and  $p_f$  with respect to  $\theta_x/D = \theta_y/D$  decreases as  $\theta_x/D = \theta_y/D$  increases. Halder and Chakraborty ([2020](#page-16-6)) and Kawa and Pula [\(2020](#page-17-11)) reported a similar observation.

# 5.2 Variations in  $\mu_q$  and  $p_f$  for Different  $\theta_x/D = \theta_y/D$ **and** *COV***tan***<sup>ϕ</sup>*

Figure [7b](#page-7-1) and f illustrate the variations in  $\mu_q$  and  $p_f$ , respectively, for different  $\theta_x/D = \theta_y/D$  and  $COV_{tan\phi}$  corresponding to the constant values of  $\phi = 30^{\circ}$ ,  $\psi = 0^{\circ}$ ,  $D = 1$  m, and  $\theta$ <sub>/</sub> $D = 1$ . The  $\mu_a$  of the footing decreases as the  $COV_{\text{tan}\phi}$  increases, whereas the  $p_f$  increases with an increase in  $COV_{\text{tan}\phi}$ . These observations can be attributed to the increase in the randomness of generated  $\phi$  values with the increase in  $COV_{\text{tand}}$ . Hence, the chances of producing weaker strength zones under the footing increase as the  $COV_{tan\phi}$  increases, which leads to failure of the soil under the footing when the load is applied to the footing. It is also observed that the rate of change in  $\mu_q$  with respect to  $\theta_x/D = \theta_y/D$  decreases as the *COV*tan*<sup>ϕ</sup>* decreases.

## 5.3 Variations in  $\mu_q$  and  $p_f$  for Different  $\theta_x/D = \theta_y/D$ and  $\theta$ <sub>*z</sub>*/*D*</sub>

Figure [7c](#page-7-1) and g illustrate the variations in  $\mu_q$  and  $p_f$ , respectively, for different  $\theta_x/D = \theta_y/D$  and  $\theta_z/D$  corresponding to the constant values of  $\phi = 35^{\circ}$ ,  $\psi = \phi/6$ ,  $COV_{\text{tan}\phi} = 20\%$ , and  $D=1$  m. The  $\mu_q$  and  $p_f$  of the system increase and decrease, respectively, as  $\theta$ */D* increases, irrespective of  $\theta$ *<sub>i</sub>*/*D*= $\theta$ *<sub>i</sub>*/*D*. Krishnan and Chakraborty [\(2022\)](#page-17-10) reported a similar observation when the mean bearing capacity factor  $(\mu N_y)$  is varied with  $\theta$ <sub>z</sub>D. Similarly, for each set of  $\theta$ <sub>z</sub>D, the  $\mu$ <sub>a</sub> of the system increases as  $\theta_x/D = \theta_y/D$  increases. However, the  $p_f$  of the system decreases as  $\theta_x/D = \theta_y/D$  increases.

## 5.4 Variations in  $\mu_q$  and  $p_f$  for Different  $\theta_x/D = \theta_y/D$ **and** *D*

Figure [7d](#page-7-1) and h illustrate the variations in  $\mu_q$  and  $p_f$ , respectively, for different  $\theta_x/D = \theta_x/D$  and *D* corresponding to constant values of  $\phi = 30^{\circ}$ ,  $\psi = 0^{\circ}$ ,  $COV_{\text{tan}\phi} = 20\%$ , and  $\theta_z/D = 1$ . For  $D = 0.5$  m and 1 m, the  $\mu_q$  of the system increases as  $\theta_x/D = \theta_y/D$  increases, whereas for  $D = 2$  m,  $\mu_a$  decreases as  $\theta_x/D = \theta_y/D$  increases. In the case of  $p_f$  it increases with the increase in *D* for constant values of  $\theta_x/D = \theta_y/D$ . However, the  $p_f$  of the system decreases as  $\theta_x/D = \theta_y/D$  increases, irrespective of the change in *D*. It should be noted that the results obtained for diferent *D* are based on non-dimensionalized parameters such as  $\theta_x/D = \theta_x/D$  and  $\theta_x/D$ , and the domain of the model is also considered based on the footing diameter. Hence, a particular value of  $\theta_r/D = \theta_r/D$  and  $\theta_r/D$ provides the different values of  $\theta_x = \theta_y$  and  $\theta_z$  for different *D*, which can be attributed to the decreasing trend of  $\mu_a$  with respect to  $\theta_r/D = \theta_r/D$  for  $D = 2$  m.

#### **5.5 Efect of Cross‑Correlation Between** *c* **and tan***ϕ*

The soil shear strength parameters (i.e.,  $c$  and  $\phi$ ) show the degree of interdependence between them. The present study considers the cross-correlation between  $c$  and tan $\phi$  instead of  $\phi$ , and it is represented as the cross-correlation coefficient  $\rho_{c\text{-tand}}$ . For this reason, the soil cohesion is characterized as the lognormally distributed random feld with a mean  $(\mu_c)$  = 0.5 kPa and coefficient of variation  $(COV<sub>c</sub>)$  = 50%. In general, the soil cohesion and friction angle are negatively correlated, and the cross-correlation coefficient varies from −0.70 to −0.24 (Cherubini [2000](#page-16-1); Johari et al. [2017](#page-17-17)). The typical value of  $\rho_{c\text{-tan}\phi}$  is considered as  $-0.5$  for this study following Johari et al. ([2017\)](#page-17-17), to generate the cross-correlated random fields for *c* and tan $\phi$ . The obtained  $\mu_q$  and  $p_f$  of the system for  $\rho_{c\text{-tan}\phi}$ =−0.5 are compared with the results for  $\rho_{c\text{-tan}\phi}=0$ .

The cross-correlation between  $c$  and tan $\phi$  can be described using the following matrix:

$$
A_{\rm cr} = \begin{bmatrix} 1 & \rho_{\rm c-tan\phi} \\ \rho_{\rm c-tan\phi} & 1 \end{bmatrix}
$$
 (9)

Since the cross-correlation matrix is positive defnite, it can be decomposed into lower and upper triangular matrices using the Cholesky decomposition method given in the following equation:

$$
A_{\rm cr} = \overline{QQ}^{\rm T} \tag{10}
$$

Hence, the cross-correlated standard normal random fields for  $c$  and tan $\phi$  can be evaluated using the following expression:

$$
\begin{pmatrix} G_{\text{intan}\overline{\phi}}^{\text{cr}} \\ G_{\text{ln}\overline{c}}^{cr} \end{pmatrix} = \left[ \frac{\overline{Q}}{\overline{Q}_{21}} \frac{0}{\overline{Q}_{22}} \right] \begin{pmatrix} G_{\text{intan}\overline{\phi}} \\ G_{\text{ln}\overline{c}} \end{pmatrix}
$$
(11)

Here,  $G_{\ln \overline{c}}$  is the auto-correlated standard normal field for cohesion which can be evaluated using the following equation:

$$
G_{\ln \bar{c}} = \sum_{j=1}^{i} Q_{ij} (G_{\ln c})_j, i = 1, 2, 3, ..., E_n
$$
 (12)



where  $G_{\ln c}$  is the uncorrelated standard normal random field for cohesion with zero mean and unit standard deviation.

Since the lognormal distribution is considered for both *c* and tan $\phi$ , the cross-correlated random fields for *c* and  $\phi$  can be evaluated using the following equations:

$$
\phi(\xi) = \tan^{-1} \left[ \exp(\mu_{\ln \tan \phi} + \sigma_{\ln \tan \phi} G_{\ln \tan \overline{\phi}}^{cr} \right] \tag{13}
$$

$$
c(\xi) = \tan^{-1}[\exp(\mu_{\text{inc}} + \sigma_{\text{inc}} G_{\text{inc}}^{cr})]
$$
 (14)

The underlying normal distribution parameters for cohesion, i.e.,  $\mu_{\text{ln }c}$  and  $\sigma_{\text{ln }c}$  are evaluated using the following transformations:

$$
\sigma_{\ln c}^2 = \ln \left( 1 + \frac{\sigma_c^2}{\mu_c^2} \right) = \ln(1 + \text{COV}_c^2)
$$
 (15)

$$
\mu_{\text{ln}c} = \ln \mu_c - \frac{1}{2}\sigma_{\text{ln}c}^2 \tag{16}
$$

<span id="page-9-1"></span>Figure [8a](#page-9-0), b, and c illustrate the respective variations in  $\mu_q$ , *COV<sub>q</sub>*, and  $p_f$  with respect to  $\theta_x/D = \theta_y/D$  for  $\rho_{c\text{-tan}\phi} = 0$ and  $-0.5$  corresponding to constant values of  $\phi = 30^{\circ}$ ,  $\psi = 0^\circ$ ,  $COV_{\text{tand}} = 20\%, \theta/D = 1$ , and  $D = 1$  m. The  $\mu_a$  of the footing for  $\rho_{c\text{-tan}\phi}$  = −0.5 shows higher values as compared to that for  $\rho_{c\text{-tand}} = 0$ , whereas the  $COV_q$  of the footing for  $\rho_{c\text{-tand}}$  = −0.5 is observed to be less than that for  $\rho_{c\text{-tand}}$  = 0. The negative cross-correlation between  $c$  and tan $\phi$  indicates that the increase in the tan $\phi$  value is associated with the decrease in *c* value and vice versa. Hence, the averaging effect is present, which increases the  $\mu_a$  and reduces the  $COV_q$  for  $\rho_{c\text{-tan}\phi}$  = -0.5. The  $p_f$  of the system is also found to be smaller for  $\rho_{c\text{-tan}\phi}$  = −0.5. However, the difference between  $p_f$  for  $\rho_{c\text{-tan}\phi} = 0$  and  $-0.5$  is only marginal for  $\theta$ <sub>x</sub>/*D*= $\theta$ <sub>x</sub>/*D*=1.25 and 2.5, and an observable difference is present for  $\theta$ <sub>x</sub>/*D* =  $\theta$ <sub>x</sub>/*D* > 2.5.



<span id="page-9-0"></span>**Fig.** 8 Variations in **a**  $\mu_q$ , **b**  $COV_q$ , and **c**  $p_f$  of the circular footing with respect to  $\theta_x/D = \theta_y/D$  for  $\rho_{c\text{-tan}\phi} = 0$  and  $-0.5$ 



## **5.6 Failure Patterns**

This study illustrates the failure mechanisms of the underlying spatially variable soil using the maximum shear strain rate contour plots. The comparisons of these failure patterns for different  $\phi$  and  $\psi$  corresponding to the constant values of  $COV_{\text{tan}\phi} = 10\%$ ,  $\theta_x/D = \theta_y/D = 10$ ,  $\theta$ <sub>i</sub> $/D = 1$ , and  $D = 1$  m are shown in Fig. [9.](#page-10-0) For a better



<span id="page-10-0"></span>**Fig. 9** Maximum shear strain rate (Max. SSR) contour plots of the underlying spatially variable soil for  $\mathbf{a} \phi = 30^\circ$ ,  $\psi = 0^\circ \mathbf{b} \phi = 35^\circ$ ,  $\psi = \phi/6$ , and  $c \phi = 40^{\circ}, \psi = \phi/3$ 



understanding of the failure mechanism of the soil under the footing, the cross-sectional views of the failure patterns along the centroidal point of the footing in the *x*–*z* plane are illustrated in Fig. [9.](#page-10-0) Despite having identical probabilistic statistics of underlying soil friction angle (for a particular value of  $\phi$ ), different spatial orientations of *ϕ* are expected for different Monte Carlo realizations. Therefore, different bearing pressure–settlement responses are achieved for different realizations, where the bearing capacities reach their ultimate state for some of the realizations but they have yet to reach their limiting values for other realizations. Hence, the failure patterns illustrated in the figure correspond to a particular Monte Carlo realization. It is evident from the figure that the developed plastic regions are asymmetric for all the cases, as the generated  $\phi$  (as well as  $\psi$  except  $\phi = 30^{\circ}$ ) values are different at different spatial coordinates. It is also observed that the plastic regions are well developed and reach the ground surface for all  $\phi$ , indicating that the system is failing under the general shear failure mechanism in that particular realization. It is also evident from the figures that both *ϕ* and *ψ* have profound effects on the failure pattern. With the increase in  $\phi$  and  $\psi$ , the resistance offered by the underlying soil increases, and the *ϕ* and *ψ* of the large volume of soil mass get mobilized during load transfer. Hence, the extent of the plastic zones in the depth direction as well as beyond the edge of the footing increase with the increase in  $\phi$  and  $\psi$ . For example, the maximum depths of the bottom of the asymmetric failure zone (from the ground surface) are found to be 0.84 m, 1.2 m, and 1.71 m for (1)  $\phi = 30^{\circ}$ ,  $\psi = 0^{\circ}$ , (2)  $\phi = 35^{\circ}$ ,  $\psi = \phi/6$ , and (3)  $\phi = 40^{\circ}$ ,  $\psi = \phi/3$ , respectively (for the particular realization). It is also observed that the maximum shear strain rate value increases with the increase in *ϕ* and *ψ*.

# **5.7 Variations in** *CDF* **and** *PDF* **for Diferent** *COV***tan***ϕ***,**  *θx***/***D***=***θy***/***D***, and** *θz***/***D*

The variations in *CDF* and *PDF* for diferent values of *COV*<sub>tan</sub><sup> $\phi$ </sup> corresponding to the specific values of  $\phi = 30^{\circ}$ ,  $\psi = 0^\circ$ ,  $\theta_x/D = \theta_y/D = 10$ ,  $\theta_x/D = 1$ , and  $D = 1$  m are presented in Fig. [10](#page-11-0)a and d, respectively. It is clear from the *CDF* plot that for the lower values of the probabilistic  $q_u$ , the cumulative probability or the  $p_f$  of the system increases with the increase in  $COV_{\text{tan}\phi}$ . Similarly, at the  $q_{ud}$ , the  $p_f$ also increases with the increase in  $COV_{\text{tan}\phi}$ , although for higher values of  $q_u$ ,  $p_f$  decreases as the  $COV_{\text{tan}\phi}$  increases. The *PDF* plot clearly shows that the  $q_u$  of the footing at the maximum probability of occurrence is less than the *qud*, and it decreases as the  $COV_{\text{tan}\phi}$  increases, suggesting that when the  $COV_{\text{tand}}$  value increases, a significant reduction in  $q_u$ occurs as compared to *qud*. It is also observed that the maximum probability of occurrence decreases as the  $COV_{\text{tan}\phi}$ 



<span id="page-11-0"></span>Fig. 10 Variations in CDF of  $q_u$  for different values of a COV<sub>tan $\phi$ </sub>, b  $\theta_x/D = \theta_y/D$ , and c  $\theta_z/D$ ; variations in PDF of  $q_u$  for different values of d *COV*<sub>tan $\phi$ </sub>, **e**  $\theta_x/D = \theta_y/D$  and **f**  $\theta_z/D$ 



increases, whereas the skewness of the *PDF* curve increases as the  $COV_{\text{tand}}$  increases.

The variations in *CDF* and *PDF* for different  $\theta$ <sub>*,</sub>* $D = \theta$ <sub>*,*</sub> $D$ </sub> corresponding to the particular values of  $\phi = 30^{\circ}$ ,  $\psi = 0^{\circ}$ ,  $COV_{\text{tan}\phi}$ =20%,  $\theta_z/D$ =1, and *D* = 1 m are illustrated in Fig. [10](#page-11-0)b and e, respectively. Similarly, the variations in cumulative and probability density plots for different  $\theta$ <sub>i</sub> $/D$  corresponding to the particular values of  $\phi = 30^{\circ}$ ,  $\psi = 0^{\circ}$ ,  $COV_{\text{tand}} = 20\%$ ,  $\theta_x/D = \theta_y/D = 10$  $\theta_x/D = \theta_y/D = 10$ , and  $D = 1$  m are represented in Fig. 10c and f, respectively. It is observed from the *CDF* plot that for the lower values of  $q_{\mu}$ , the cumulative probability increases as  $\theta_x/D = \theta_y/D$  increase. However, at the  $q_{ud}$  and for higher values of  $q_u$ , the cumulative probability decreases as  $\theta_x/D = \theta_x/D$ increases. From the *PDF* plot, it can be clearly stated that the maximum probability of occurrence decreases as  $\theta$ <sub>*i*</sub> $D = \theta$ <sub>*i*</sub> $D$ increases, and at  $q_{ud}$ , the probability of occurrence also decreases as  $\theta_x/D = \theta_x/D$  increases. However, for the lower and higher values of  $q_{\mu}$ , the probability of occurrence increases as  $\theta$ <sub>x</sub>/*D*= $\theta$ <sub>x</sub>/*D* increases. A similar observation is observed for the variations in *CDF* and *PDF* with respect to *θz*/*D*. However, for the lower values of *qu*, the segments of *CDF* and *PDF* curves fall within a very tight band for  $\theta$ <sub>/</sub>*D*.

# **5.8 Variation in** *p<sup>f</sup>*  **with Respect to** *FOS*

The signifcance of probabilistic analyses is justifed in the Introduction section as it helps calculate the  $p_f$ , which is found to be a more robust concept as compared to the *FOS*. However,  $p_f$  and  $FOS$  are strongly correlated, which can be defned using the following expression:

$$
p_{\rm f} = P(q_u < q_{\rm ud}/\text{FOS}) = \Phi\left(\frac{\ln(q_{\rm ud}/\text{FOS}) - \mu_{\ln q_u}}{\sigma_{\ln q_u}}\right) = \Phi(-\beta) \tag{17}
$$

Figure [11](#page-12-0)a, b demonstrate the variations in  $p_f$  with respect to the *FOS* for different  $COV_{\text{tan}\phi}$  and  $\theta_x/D = \theta_y/D$ , respectively. Both figures show a drastic reduction in  $p_f$  with the increase in *FOS*. However, the observed trend is very obvious. For  $COV_{\text{tan}\phi} = 5\%$ , the  $p_f$  of the system tends to zero



<span id="page-12-0"></span>Fig. 11 Variations in  $p_f$  with respect to FOS for different values of a COV<sub>tan</sub>, b  $\theta_x/D = \theta_y/D$ ; variations in  $p_{f\_tgt}$  with respect to FOS<sub>req</sub> for different values of **c**  $COV_{\text{tan}\phi}$ , **d**  $\theta_x/D = \theta_y/D$ 



when the *FOS* approaches 1.7. Similarly, for  $COV_{\text{tand}} = 10\%$ , the *pf* of the system tends to zero when the *FOS* approaches 2.3, whereas for  $COV_{\text{tan}\phi}$  = 20%, the system is not completely safe at  $FOS = 3$ , as  $p_f$  is found to be 1.5% at  $FOS = 3$ . Hence, designing a typical footing considering *FOS*=3 can overestimate the allowable bearing capacity ( $q_a$ ) for  $COV_{\text{tan}\phi} = 5\%$ and 10%, whereas it can underestimate  $q_a$  for  $COV_{\text{tan}\phi} = 20\%$ . It is found that for  $FOS = 1$ , the  $p_f$  of the system decreases as the  $\theta_x/D = \theta_y/D$  increases, although the variation is very small. However, for the *FOS* values  $\geq 1.1$ ,  $p_f$  increases as  $\theta_x/D = \theta_y/D$  increases. The significant variation in  $p_f$  for different  $\theta_x/D = \theta_y/D$  is observed as the *FOS* increases from 1.3 to 2.5. As the *FOS* increases beyond 2.5, the variation in  $p_f$  for different  $\theta_x/D = \theta_y/D$  decreases. It is also observed that for  $\theta_x/D = \theta_y/D = 1.25$ ,  $p_f$  tends to zero when the *FOS* approaches 2.6, whereas the system  $p_f$  is found to be 1.5% for  $\theta_x/D = \theta_y/D = 10$  at  $FOS = 3$ . Hence, at  $FOS = 3$ ,  $q_a$  is slightly overestimated for  $\theta_x/D = \theta_y/D = 1.25$ , whereas it is underestimated for  $\theta_r/D = \theta_r/D = 10$ . Based on these observations, Fig. [11c](#page-12-0) and d are plotted, estimating the required factor of safety (*FOS<sub>req</sub>*) to achieve a specific target failure probability ( $p_f$ <sub>tgt</sub>). The  $FOS_{req}$  corresponding to a specific  $p_f$ <sub>tgt</sub> can be evaluated by rearranging Eq. ([17](#page-9-1)) as follows:

$$
FOS_{\text{req}} = \frac{q_{\text{ud}}}{\exp[\mu_{\ln q_u} + \sigma_{\ln q_u} \{ \Phi^{-1}(p_{f_{\text{-tgt}}}) \}]} \tag{18}
$$

Figure [11c](#page-12-0), d represents  $p_{f_{t}}$  versus  $FOS_{req}$  for different *COV*<sub>tan $\phi$ </sub> and  $\theta_x/D = \theta_y/D$ , respectively. For a given  $p_{f \text{tgt}}$ (say  $p_{f_{\perp} t g t} = 0.1\%$ ), the  $FOS_{req}$  increases with the increase in

*COV*<sub>tanφ</sub>. A similar trend is observed for  $\theta_x/D = \theta_y/D$ . For example,  $FOS_{req}$  increases from 1.53 to 4.45 as the  $COV_{tan\phi}$ increases from 5 to 20% to achieve a  $p_f$ <sub>tet</sub>=0.1% for the particular values of  $\phi = 30^\circ$ ,  $\psi = 0^\circ$ ,  $\theta_x/D = \theta_y/D = 10$ ,  $\theta_z/D = 1$ , and  $D = 1$  m. Similarly, the  $FOS_{\text{rea}}$  is observed to increase from 2.75 to 4.45 as  $\theta_x/D = \theta_y/D$  increases from 1.25 to 10 for the particular values of  $\phi = 30^{\circ}$ ,  $COV_{\text{tand}} = 20\%$ ,  $\theta_z/D = 1$ , and  $D=1$  m.

# **5.9 Variations in** *qad* **of Footing for Diferent** *β***,**  *COV*<sub>tan $\phi$ </sub>, and  $\theta$ <sub>*x</sub></sub>/<i>D* =  $\theta$ <sub>v</sub>/*D*</sub>

The present study also attempts to evaluate the  $q_{ad}$  of the footing by modifying Eq. ([8\)](#page-6-1) as follows:

$$
\Phi\left(\frac{\ln(q_{\text{ad}}) - \mu_{\ln q_{\text{u}}}}{\sigma_{\ln q_{\text{u}}}}\right) = \Phi(-\beta)
$$
\n(19)

By rearranging the above equation, the  $q_{ad}$  of the footing can be obtained directly as follows:

$$
q_{\rm ad} = \exp(\mu_{\ln q_u} - \beta \sigma_{\ln q_u}) \tag{20}
$$

Four diferent reliability indices are used in this study to obtain  $q_{ad}$ : (1)  $\beta$  = 3.0902, corresponding to the target failure probability ( $p_{f~tot}$ ) of 0.1%; (2)  $\beta$  = 3.8, which corresponds to the RC2 reliability class structures (residential and office buildings and their typical foundations) having medium consequences of failure, and 50 years of design working life (CEN [2002\)](#page-16-21); (3)  $\beta$  = 3.0 for the average performance and (4)



<span id="page-13-0"></span>**Fig. 12** Variations in  $q_{ad}$  of the footing with respect to  $\beta$  for different values of **a**  $COV_{tand}$ , **b**  $\theta_x/D = \theta_x/D$ 



 $\beta$ =4.0 for the good performance of the geotechnical struc-tures provided by USACE ([1997\)](#page-17-21). The variations in  $q_{ad}$  with respect to  $\beta$  for different  $COV_{\text{tan}\phi}$  and  $\theta_x/D = \theta_y/D$  are shown in Fig. [12](#page-13-0)a and b, respectively. As illustrated in the fgures, the  $q_{ad}$  decreases with the increase in  $\beta$ . Similarly, a drastic decrease in  $q_{ad}$  is also seen with the increase in  $COV_{tan\phi}$  for the constant values of  $\beta$  and  $\theta_x/D = \theta_y/D$  (Fig. [12a](#page-13-0)). Likewise, a lower value of  $\theta_r/D = \theta_r/D$  provides a higher value of  $q_{ad}$ , whereas for higher values of  $\theta_x/D = \theta_y/D$ , the  $q_{ad}$  obtained is quite low (Fig. [12](#page-13-0)b). However, the  $q_{ad}$  values approach stable solutions as  $\theta$ <sub>*/D*</sub> =  $\theta$ */D* increases. Kawa and Pula [\(2020\)](#page-17-11) observed a similar trend.

# **6 Remarks**

The present study primarily estimates the probabilistic bearing capacity of circular footing. However, while estimating the bearing capacity of the footing, it is also necessary to calculate the probabilistic allowable settlement of the foundation. For this reason, the elastic modulus (*E*) and Poisson's ratio (*υ*) of the foundation soil need to be considered as the random feld. Hence, the cross-correlated random felds for the elastic modulus (*E*) and Poisson's ratio (*υ*) are generated, and the probabilistic allowable foundation settlement  $(\delta_{all})$  is evaluated corresponding to an allowable bearing pressure  $(q_a)$  of 150 kPa, considering both *E* and *υ* as lognormally distributed, with  $\mu_F = 30$  MPa,  $\mu_p = 0.3$ ,  $COV_E$ =30%,  $COV_p$ =5%, and  $\rho_{E-p}$ =−0.5 (following Johari and Sabzi [2017](#page-17-7)). As a representative case, the *CDF* and histogram ft of probabilistic allowable settlements are plotted for  $\theta_r/D = \theta_r/D = 10$  and  $\theta_r/D = 1$  (Fig. [13\)](#page-14-0). It is clear from Fig. [13](#page-14-0) that the probabilistic allowable settlement of the foundation follows the Weibull distribution. The distribution of the probabilistic allowable settlement is further confrmed using the Kolmogorov–Smirnov goodness-of-ft test. It is also found that the obtained absolute diference between the actual distribution and the theoretical Weibull distribution is well below the critical value of the diference for the given significance levels (i.e.,  $\alpha = 1\%$ , 5%, and 20%). Hence, the assumed theoretical distribution is acceptable at those given significance levels, and the  $p_f$  of the system in terms of the allowable settlement can be estimated as the probability for which the evaluated  $\delta_{all}$  is greater than the deterministic allowable settlement ( $\delta_{all\text{ det}}$ ), as follows:

$$
p_f = P(\delta_{\text{all}} > \delta_{\text{all\_det}}) = 1 - P(\delta_{\text{all}} \le \delta_{\text{all\_det}})
$$
  
= 
$$
1 - \left(1 - e^{-\left(\frac{\delta_{\text{all\_det}}}{A}\right)^B}\right) = e^{-\left(\frac{\delta_{\text{all\_det}}}{A}\right)^B}
$$
(21)

In the above equation, *A* and *B* denote the respective scale and shape parameters for the Weibull distribution.



<span id="page-14-0"></span>**Fig. 13 a** Comparison of actual distribution with the assumed theoretical Weibull distribution of  $\delta_{all}$ , **b** histogram of  $\delta_{all}$  with the Weibull-distribution fit for  $D=1$  m,  $\phi=30^{\circ}$ ,  $\psi=0^{\circ}$ ,  $c=0.5$  kPa,  $\mu_E$ =30 MPa,  $\mu_v$ =0.3, *COV*<sub>E</sub>=30%, *COV*<sub>v</sub>=5%,  $\rho_{E_v}$ =-0.5,  $\theta_x/D = \theta_y/D = 10$ , and  $\theta_x/D = 1$ 

The variations in the mean, coefficient of variation of allowable settlement ( $\mu \delta_{all}$  and  $COV_{ol}$ ), and the failure probability  $(p_f)$  of the footing in terms of allowable settlement for different  $\theta_x/D = \theta_y/D$  are presented in Fig. [14a](#page-15-0), b, and c, respectively. The  $\mu \delta_{all}$  of the footing decreases with the increase in  $\theta_r/D = \theta_r/D$ . However, the variation in  $\mu \delta_{all}$ is very insignificant beyond  $\theta_x/D = \theta_y/D = 2.5$ . In contrast to  $\mu \delta_{all}$ , the *COV\_* $\delta_{all}$  increases with the increase in  $\theta_x/D = \theta_y/D$ because of the averaging efect. The failure probability of the system is found to be decreasing with the increase in  $\theta_x/D = \theta_y/D$ .

## **7 Conclusions**

The present study explores the spatial variability effect of soil friction and dilation angles on the bearing capacity of a three-dimensional circular surface footing resting on sandy soil. Deterministic analyses are carried out for





<span id="page-15-0"></span>**Fig. 14** Variations in **a**  $\mu \delta_{all}$ , **b**  $COV_{-} \delta_{all}$ , and **c**  $p_f$  of the circular footing with respect to  $\theta_x/D = \theta_y/D$  for  $D = 1$  m,  $\theta_z/D = 1$ ,  $\phi = 30^\circ$ ,  $\psi = 0^\circ$ , *c*=0.5 kPa

three different combinations of  $\phi$  and  $\psi$  ( $\phi$  = 30°,  $\psi$  = 0°;  $\phi = 35^{\circ}$ ,  $\psi = \phi/6$ ; and  $\phi = 40^{\circ}$ ,  $\psi = \phi/3$ ) and three different  $D$  ( $D = 0.5$  m, 1 m, and 2 m). In the case of probabilistic analyses, the tan $\phi$  is assumed to be lognormally distributed instead of *ϕ*. The main focus of the study is to investigate the effect of  $\theta_x/D = \theta_y/D$  on the  $\mu_q$  and  $p_f$  of the system for different values of  $\phi$ ,  $\psi$ ,  $COV_{tan\phi}$ ,  $\theta_z/D$ , and *D*. The probabilistic allowable settlement of the footing corresponding to the allowable bearing pressure of 150 kPa is also evaluated considering the *E* and *υ* as the lognormally distributed cross-correlated random felds. The essential conclusive remarks drawn from the present study are listed below:

(1) Higher values of  $\phi$ ,  $\psi$ ,  $COV_{\text{tan}\phi}$ , and *D* have a notable impact on the  $\mu_q$  and the  $p_f$  of the system.  $\phi = 40^\circ$ ,  $ψ = φ/3$  (for  $D = 1$  m,  $COV_{tan φ} = 20\%$ ,  $θ_z/D = 1$ , and  $FOS = 1$ ) shows the opposite trend of  $\mu_a$  (with respect to  $\theta_x/D = \theta_y/D$ ) which is observed for  $\dot{\phi} = 30^\circ$ ,  $\psi = 0^\circ$ 

and  $\phi = 35^\circ$ ,  $\psi = \phi/6$ . Similarly,  $D = 2$  m (for  $\phi = 30^\circ$ ,  $\psi = 0^\circ$ , *COV*<sub>tan</sub><sub>*j*</sub> = 20%,  $\theta_z/D = 1$ , and *FOS* = 1) shows the opposite trend of  $\mu_a$  which is observed for  $D=0.5$  m and 1 m. Additionally,  $\phi = 40^{\circ}$ ,  $\psi = \phi/3$ , and  $D = 2$  m give the highest value of  $p_f$  as compared to the other cases.

- (2) The negative cross-correlation between *c* and tan*ϕ* shows higher values of  $\mu_a$  and lower values of  $COV_a$ and  $p_f$  than the case without cross-correlation, irrespective of the change in  $\theta_x/D = \theta_y/D$ . In the case of  $p_f$ , the change in it is only marginal up to  $\theta_x/D = \theta_x/D = 2.5$ , beyond which there is an observable diference.
- (3) The use of the *FOS* concept may overestimate the  $q_a$  of the footing for lower values of  $COV_{\text{tan}\phi}$ , whereas it may underestimate the  $q_a$  for higher values of  $COV_{\text{tan}\phi}$ . Similarly, the  $q_a$  gets overestimated for lower  $\theta_x/D = \theta_y/D$ and underestimated for higher  $\theta_r/D = \theta_r/D$ .
- (4) Estimating the  $FOS_{rea}$  is essential, as higher values of *FOS* do not ensure that the system is entirely safe



against failure. Hence, the  $FOS_{rea}$  is calculated based on the fundamental concept of failure probability to achieve a target  $p_f$  of the system. It is found that to achieve a  $p_{f \text{tgt}}$  of 0.1%, the  $FOS_{req}$  increases as the *COV*<sub>tan*ϕ*</sub> and  $\theta_x$ /*D* =  $\theta_y$ /*D* increase.

- (5) The  $q_{ad}$  of the footing decreases significantly as  $\beta$ ,  $COV_{\text{tan}\phi}$ , and  $\theta_x/D = \theta_y/D$  increase. However, the variation in  $q_{ad}$  decreases as  $\theta_x/D = \theta_x/D$  approaches a higher value.
- (6) The probabilistic allowable settlement  $(\delta_{all})$  is observed to follow the Weibull distribution. The  $\mu \delta_{all}$  and  $p_f$ associated with the allowable settlement is found to decrease with the increase in  $\theta_x/D = \theta_y/D$ , whereas  $COV_{\phi}$ <sup>*a<sub>dl</sub>*</sub> increases with the increase in  $\theta$ <sub>*i</sub>* $D = \theta$ *j* $D$ .</sup></sub>
- (7) The primary focus of the present study is on estimating the probabilistic bearing capacity of circular footing. The probabilistic allowable settlement of the footing corresponding to a specifc allowable bearing pressure is also evaluated. However, it is also essential to evaluate the probabilistic allowable diferential settlement of two closely spaced circular footings, which is beyond the scope of the study and can be considered in a future study.

The trend of using the spatial variability concept in the geotechnical felds has grown rapidly over the past few decades. The present analysis of the probabilistic bearing capacity of circular footing, considering the inherent spatial variability of the soil shear strength parameters under vertical loading, provides a general perspective of the problem. The risk associated with the potential failure of the footing is also discussed in the study. Hence, the authors hope the present study will help engineers working on this type of problem.

#### **Declarations**

**Conflict of interest** The authors declare that there are no competing interests.

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