



Assessment of New Vector Intensity Measures for the Seismic Evaluation of Low-rise Frames by Considering Near-field Aftershock Effects

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Abstract

There are not enough as recorded aftershock time histories. Therefore, intensity measures (IMs) can be used to reduce the number of necessary records. Previous studies have not dealt with the determination of a suitable IM by considering aftershock impacts. $S_a(T_1)$ has been considered as an efficient and sufficient IM in many cases. Several vector IMs of structures other than $S_a(T_1)$ were defined. The $S_a(T_1)$ of the mainshock was denoted as IM1 (the first component) in all proposed IMs. IM2s were selected such that they could be derived from the response spectrum. Therefore, the main purpose of this study is to introduce and assess several IMs considering near-field aftershock influences. For the purpose of the research, three RC frames (a one-story frame, a three-story frame, and a five-story frame) were considered. The buildings were assumed to be built in 1980s. The 2-D model of each structure was built in Opensees. Fifty-six near-field records from FEMA P-695 were selected as mainshock and aftershock records. The frames were analyzed under repeated mainshock and aftershock effects until they collapsed. Finally, the best IM was proposed. The results are valid for assessing collapse damage states, but the present study does not include other damage levels. The present investigation showed that the ratio of summation of the first mode spectral acceleration value of aftershocks on summation of the area of aftershock $S_a(T_1)$ plot as the second part of vector IM can lead to efficiency and sufficiency of the IM.

Keywords Vector intensity measure · Aftershock · Near-field · Low-rise frame · Collapse

1 Introduction

The Pacific Earthquake Engineering Research Center (PEER 2021) has developed a methodology for assessing structures. The process has been broken down into several elements (Moehle and Deierlein 2004). The mean annual frequency of collapse which shows the probability of collapse considering different levels of IMs for a specific IM is calculated by integrating collapse fragility curve with the hazard curve (Cornell et al. 2002; Krawinkler, et al. 2006):

$$\lambda_c = \int_{im} P(C|im) |d\lambda_{IM}(im)| \quad (1)$$

In which $P(C|im)$ and $d\lambda_{IM}(im)$ are the probability of collapse given im and the probability of exceedance of IM from a specific level, respectively. An IM is an intermediate variable between ground motion hazard and the response of a structure. Efficiency and sufficiency are two factors that practitioners use to evaluate what IM is suitable for use in performance assessments (Baker and Cornell 2008).

Efficiency denotes a dispersion of the demand of a structure, while sufficiency signifies the dependency of structural responses to earthquake properties (Baker and Cornell 2008). Hazard curves for peak ground acceleration (PGA) and spectral acceleration at the fundamental period of the structure, $S_a(T_1)$, are easily accessible. Therefore, they are commonly used to assess the performance of structures.

IMs are categorized as either scalar or vector IMs. Over the past decade, a large volume of published studies has

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introduced new IMs (e.g., Yakut and Yılmaz 2008; Jayaram et al. 2010; Zhou et al. 2017; Suzuki and Iervolino 2019). Factors thought to influence IMs have been explored in several studies. For instance, many published papers describe the role of near-field impacts on structural behavior and IM determination. For example, inelastic spectral displacement has been considered as an IM in some research works (Luco and Cornell 2007; Tothong and Luco 2007). This IM can be combined with other parameters to incorporate period elongation and high mode effects. An IM has also been proposed by the second author of the paper for applying near-field shocks (Yahyaabadi and Tehranizadeh 2012).

Most studies in the field of IM have focused only on mainshocks. Preliminary work on the effects of aftershocks on the seismic demand of structures was undertaken by (Yeo and Cornell 2005). In the same vein, many studies have proposed methods for examining aftershock effects in the seismic evaluation of buildings and have considered repeated mainshock time histories as aftershocks (e.g., Bazzurro et al. 2004; Hatzigeorgiou and Beskos 2009; Luco et al. 2011; Nazari Khanmiri 2015). While a great number of investigations have also been done on the seismic evaluation of structures considering aftershocks (e.g., Iervolino et al. 2014; Jeon et al. 2015; Raghunandan et al. 2015), none have suggested building regulations that can be used for the long-term assessment of structures.

Some researchers have done by Jalayer in this field (e.g., Jalayer, et al. 2010; Ebrahimian, et al. 2014; Jalayer and Ebrahimian 2016). They proposed the most applicable method for considering aftershock effects on the seismic response and behavior of buildings. They also investigated the importance of aftershock input and concluded that aftershock sequences significantly affect structural responses (Jalayer et al. 2015). However, their studies have been concentrated mostly on the short-term effects of aftershocks. Other researchers have examined the relationship between repeating real shocks as aftershocks and the responses of buildings. Garcia, for example, claimed that the responses of structures under artificial sequences are very different from their responses under real sequences (García and Manriquez 2011; Ruiz-García 2012). Goda has published several papers in which he has investigated the effects of real aftershocks on the response of structures (e.g., Goda et al. 2015). In another study, the average horizontal components of PGA, peak ground velocity (PGV), and 5% damped pseudo spectral acceleration (PSA) at different spectral periods of aftershock earthquakes were estimated for tectonically active crustal regions as a function of the aftershock-to-mainshock magnitude ratio, distance ratio, and time-averaged shear-wave velocity in the upper 30 m of soil deposits (VS30) (Kim and Shin 2017).

To determine the effects of aftershocks, Elenas et al. investigated the interrelation between seismic intensity parameters and the post-seismic damage state of structures. Several peak, energy, and spectral intensity parameters were implemented. Analytical examinations showed that both the energy and the spectral seismic intensity parameters have a strong correlation with the overall structural damage indices (Elenas et al. 2017). In 2018, Muderrisoglu et al. proposed a conditional aftershock hazard assessment method by considering the microseismic indicators of mainshocks observed at the site (Muderrisoglu and Yazgan 2018). A novel formulation for the joint probability of the mainshock and aftershock spectral accelerations was proposed (Hu et al. 2019). The model can be used for mainshock-aftershock sequences. In 2019, Salami et al. investigated the influences of different types of mainshock-aftershock sequences on the seismic fragility of low-rise RC frames. They selected $S_a(T_1)$ as the IM, and ground motion data from other seismic regions were utilized. It was found that, for crustal ground motions, considering aftershocks increased the probability of the exceedance of damage to extensive and complete damage. Meanwhile, for slab and interface records, the structure experienced less damage. If the damage of the mainshock was slight or moderate, the structure was not affected by major aftershocks (Salami et al. 2019).

A review of previous proposed intensity measures, methods of aftershock collapse assessment, and some researches about near field earthquake parameters have been discussed. The study needs to consider all previously discussed parameters. This study aims to investigate the efficiency and sufficiency of vector IMs for predicting the collapse capacity of structures under near-field aftershock sequences. As $S_a(T_1)$ is not sufficient with respect to distance, 14 vector IMs were selected, among which IM1 is considered $S_a(T_1)$ of the mainshock, and IM2 is a combination of aftershock spectral properties. Three RC moment frames based on designs from the 1980s have been used, and 56 near-field records from FEMA P-695 have been used as mainshocks and aftershocks.

2 Considered Intensity Measures

First, the efficiency and sufficiency of $S_a(T_1)$ were evaluated. In the following sections, it is shown that the efficiency of vector-valued IM determined by degree of scatter about regression in Eq. 2. According to Table 1, $S_a(T_1)$ is

Table 1 Standard deviation of $S_a(T_1)$ main shock

No. Stories	1	3	5
Standard deviation	0.226	0.161	0.151

Table 2 P-values obtained from investigating the sufficiency of $S_a(T_1)$ with respect to magnitude, Distance assuming F-test for the slope of the linear regression of $S_a(T_1)$ and M and LnR. source-to-site

No. Stories	M(Mainshock)	R(Mainshock)	$M_{Average}$ (Aftershock)	$R_{Average}$ (Aftershock)
1	0	0	0.16	0
3	0.018	0	0.079	0
5	0.006	0.003	0	0.003

an efficient IM, as it has a small standard deviation. Table 1 illustrates the amount of standard deviation of one, three, and five story frames. This result corroborates that observed in Jalayer’s paper (Jalayer, et al. 2010).

In order to evaluate sufficiency of $S_a(T_1)$ with respect to magnitude (M) and distance (D), it is necessary to use a unique M and D. As each aftershock sequence is made up of several earthquake records, there is not a unique M and D for each chain of earthquake records. So as to use one parameter

for M and D, the average of M and D of aftershocks in each sequence were considered. If an IM is sufficient with respect to the magnitude or distance of each aftershock, it would be sufficient respect to summation of M or D. There for, the amount of average of M and D were considered for evaluation of sufficiency. Table 2 shows that $S_a(T_1)$ is not sufficient with respect to magnitude and distance. Therefore, time history properties should be considered during record selection and seismic assessment.

Table 3 Defined vectored IMs

No	IM2	No	IM2
1	$\sum_{i=1}^n PGA_i \times S_a(T_1)_{Structure}$	8	$\sum_{i=1}^n (\int S_v(t)^2 \cdot dt)_i \times S_a(T_1)_{Structure}$
2	$\sum_{i=1}^n S_a(T_1)_i \times S_a(T_1)_{Structure}$	9	$\sum_{i=1}^n (\int S_a(t) \cdot S_v(t) \cdot dt)_i \times S_a(T_1)_{Structure}$
3	$\sum_{i=1}^n S_v(T_1)_i \times S_a(T_1)_{Structure}$	10	$\sum_{i=1}^n (\int \frac{S_a(t)}{t} \cdot dt)_i \times S_a(T_1)_{Structure}$
4	$\sum_{i=1}^n S_a(T_1)_i \cdot S_v(T_1)_i \times S_a(T_1)_{Structure}$	11	$\frac{\sum_{i=1}^n S_a(T_1)_i}{\sum_{i=1}^n (\int S_a(t) \cdot dt)_i}$
5	$\sum_{i=1}^n (\int S_a(t) \cdot dt)_i \times S_a(T_1)_{Structure}$	12	$\frac{\sum_{i=1}^n S_a(T_1)_i}{\sum_{i=1}^n (\int S_v(t) \cdot dt)_i}$
6	$\sum_{i=1}^n (\int S_a(t)^2 \cdot dt)_i \times S_a(T_1)_{Structure}$	13	$\frac{\sum_{i=1}^n S_a(T_1)_i}{\sum_{i=1}^n PGA_i}$
7	$\sum_{i=1}^n (\int S_v(t) \cdot dt)_i \times S_a(T_1)_{Structure}$	14	$\frac{(\sum_{i=1}^n S_a(T_1)_i)^2}{\sum_{i=1}^n (\int S_a(t) \cdot dt)_i}$

Table 4 Definition of second part of IMs

No	IM2	Definition
1	$\sum_{i=1}^n PGA_i$	Summation of PGA of all aftershock records in each chain of main shock-aftershock
2	$\sum_{i=1}^n S_a(T_1)_i$	Summation of Sa(T1) of all aftershock records in each chain of main shock-aftershock
3	$\sum_{i=1}^n S_v(T_1)_i$	Summation of Sv(T1) of all aftershock records in each chain of main shock-aftershock
5	$\sum_{i=1}^n (\int S_a(t) dt)_i$	Summation of integral of Sa spectrum of all records in in each chain of main shock-aftershock
7	$\sum_{i=1}^n (\int S_v(t) dt)_i$	Summation of integral of Sv spectrum of all records in in each chain of main shock-aftershock

Several vector IMs of structures other than Sa(T1) were defined such that aftershocks' influences can be considered. The $S_a(T_1)$ of the mainshock was denoted as IM1 (the first component) in all proposed IMs. The aftershock response spectrum can be determined through aftershock probabilistic seismic hazard analysis (APSHA) according to Yeo and Cornell (Yeo and Cornell 2005). Some possible IM2s were investigated by the author of the paper. The IM2s were selected such that they could be derived from the response spectrum. IM2 values are given in Table 3. Table 4 provides the definitions of second components (1, 2, 3, 5, and 7). Other IM2s are produced by combining the aforementioned components, either with one another or with the $S_a(T_1)$ of the structure of mainshock records. $S_v(T_i)$ is a spectrum defined in this article by the authors of this paper and is derived by multiplying the $S_a(T_1)$ of aftershock by T_i .

3 The Structures, Ground Motions and Analysis

In order to consider the effect of height on the results of this study, the case study buildings are selected three four-bay 2-dimensional RC frames consisting of a one-story, three-story, and five-story structure. Table 5 shows the periods of the three frames. The structures are considered to be constructed based on building code in 1980s in California. The structures are designed by author of the paper. The nonlinear behavior of RC beams and columns was modeled by utilizing the concentrated plasticity element in OpenSees. Table 5 illustrates the strength of the concrete and steel used. The dimensions of the beams and columns are shown in Tables 6 and 7, respectively.

Some researchers have concentrated on determining aftershock records (e.g., (Goda, et. al 2015)) In some research works, aftershock records are considered similar to the mainshock records, while in others, aftershocks are considered a factor of the mainshock (Lee and Foutch 2004). Li and Ellingwood utilized the Gutenberg-Richter relationship, together with the magnitude density function. They determined a factor that can be multiplied by the mainshock time history to produce the strongest aftershock (Li and Ellingwood 2007). In 2009, Hatzigeorgiou and Beskos utilized attenuation relationships to specify the PGA of aftershocks

Table 5 Concrete and Steel strength (Mpa)

Building	Concrete (Mpa)	Steel (Mpa)
1Story	17	455
3, and 5 Story	24	

Table 6 Dimension and reinforcement of beams

Building	Story number (mm)	Dimension	Top	Bot	Shear
1 Story	1	300*250	3Φ16	3 Φ 16	Φ8 @ 150
3 Story	1, 2, and 3	300*300			
5 Story	1, 2, and 3	350*350			
	4, and 5	300*250			

(Hatzigeorgiou and Beskos 2009). Then, they changed the records to obtain specified PGA values. Goda et al. investigated the effects of earthquake types, magnitudes, and hysteretic behavior on the peak and residual ductility demands of an inelastic single-degree-of-freedom system. An extensive dataset of real mainshock-aftershock sequences for Japanese earthquakes was developed. The records were categorized into mainshocks and aftershocks according to the time-space window (Goda et al. 2015).

In this study, 56 earthquake ground motions from FEMA P-695 were used as mainshocks and aftershocks. The properties of earthquake records are illustrated in Table 8 and this table exists in FEMA P-695. For each structure, some mainshock records may lead to a collapse or instability. Moreover, it is not logical to consider the aftershock effects for records, which cause a great maximum inter-story drift ratio. According to ASCE 07-13, the maximum inter-story drift ratios for life safety and collapse prevention are 0.01 and 0.02, respectively. In this study, 0.015 was considered the limit for record purification. As such, records that cause responses greater than 0.015 were omitted. Furthermore, dynamic instability is also used for determining the collapse capacity of the structures. Dynamic instability shows that the structure will collapse under the main shock and aftershock analysis is meaningless (Figs. 1, 2).

The results for one, and three-story frames are illustrated in Fig. 3. Earthquake records are categorized in two groups including pulse like and non-pulse like. The earthquakes with inter-story drift ration greater than 0.015 or earthquakes which lead to dynamic instability were omitted. The remain records were utilized for aftershock analysis. Each of the

Table 7 Dimension and reinforcement of columns

Building	Story number	Dimension	Longitudinal	Shear
1 Story	1	300*300	8Φ16	Φ8 @ 250
3 Story	1, and 2	350*350	12Φ20	
	3		8Φ16	
5 Story	1, and 2	400*400	12Φ20	
	3, 4, and 5	350*350	8Φ16	

Table 8 Properties of Earthquake records (FEMA P-695)

ID No	Name	M	Year	NEHRP Class	V30	Fault Type	Epicentral	Campbell	Joyner-Boore
Pulse Record									
1	Imperial Valley-06	6.5	1979	D	203	Strike-slip	27.5	3.5	0
2	Imperial Valley-06	6.5	1979	D	211	Strike-slip	27.5	3.6	0.6
3	Irpinia, Italy-01	6.5	1980	B	1000	Normal	30.4	10.8	6.8
4	Superstition Hills-02	6.5	1987	D	349	Strike-slip	16	3.5	1
5	Loma Prieta	6.9	1989	C	371	Strike-slip	27.2	8.5	7.6
6	Erzican, Turkey	6.7	1992	D	275	Strike-slip	9	4.4	0
7	Cape Mendocino	7	1992	C	713	Trust	4.5	8.2	0
8	Landers	7.3	1992	C	685	Strike-slip	44	3.7	2.2
9	Northridge-01	6.7	1994	D	282	Trust	10.9	6.5	0
10	Northridge-01	6.7	1994	C	441	Trust	16.8	5.3	1.7
11	Kocaeli, Turkey	7.5	1999	B	811	Strike-slip	5.3	7.4	3.6
12	Chi-Chi, Taiwan	7.6	1999	D	306	Trust	26.7	6.7	0.6
13	Chi-Chi, Taiwan	7.6	1999	C	714	Trust	45.6	7.7	1.5
14	Duzce, Turkey	7.1	1999	D	276	Strike-slip	1.6	6.6	0
No Pulse Record									
15	Gazli, USSR	6.8	1979	C	660	Trust	12.8	5.5	3.9
16	Imperial Valley-06	6.5	1979	D	223	Strike-slip	6.2	4	0.5
17	Imperial Valley-06	6.5	1979	D	275	Strike-slip	18.9	8.4	7.3
18	Nahanni, Canada	6.8	1985	C	660	Trust	6.8	9.6	2.5
19	Nahanni, Canada	6.8	1985	C	660	Trust	6.5	4.9	0
20	Loma Prieta	6.9	1989	C	376	Strike-slip	9	10.7	3.9
21	Loma Prieta	6.9	1989	C	462	Strike-slip	7.2	3.9	0.2
22	Cape Mendocino	7	1992	C	514	Trust	10.4	7	0
23	Northridge-01	6.7	1994	C	380	Trust	8.5	8.4	0
24	Northridge-01	6.7	1994	D	281	Trust	3.4	12.1	0
25	Kocaeli, Turkey	7.5	1999	D	297	Strike-slip	19.3	5.3	1.4
26	Chi-Chi, Taiwan	7.6	1999	C	434	Trust	28.7	6.5	0.6
27	Chi-Chi, Taiwan	7.6	1999	C	553	Trust	8.9	11.2	0
28	Denali, Alaska	7.9	2002	C	553	Strike-slip	7	8.9	0

frame under a specific main shock will collapse with different numbers of sequential aftershocks. Fig. 2 illustrates the number of aftershock records that leads to collapse of each frame. It shows that for the one-story frame, the number of aftershocks for collapse of structure is approximately less than 10 records. This number is five for three and five story frames. According to Fig. 2. The shorter a building, the greater number of aftershock records need to collapse.

4 Efficiency of IMs for Collapse Capacity Prediction

The efficiency of a scalar IM indicates a lower dispersion among the capacity values. For a vector IM, efficiency is defined as the degree of scattering of capacity concerning the regression in Eq. 2. The scattering in Eq. 2 can be

determined through Eq. 3. Therefore, a vector IM is more efficient if it has a lower standard deviation according to Eq. 3. From another viewpoint, efficiency illustrates whether there is a high correlation between IM_1 and IM_2 . Equation 4 can be utilized to determine the correlation coefficient in which $cov()$ represents the convenience between variables, and $\sigma_{\ln IM_1}$ and $\sigma_{\ln IM_2}$ are the standard deviation of $\ln IM_1$ and $\ln IM_2$, respectively. The correlation between $\ln IM_1$ and $\ln IM_2$ is shown for some IM_2 s for a one-story building in Fig. 4. The period of frames are available in Table 9.

The correlation coefficient and standard deviation are available for three frames in Tables 10, 11, and 12. The maximum values of the correlation coefficient for the one-, three-, and five-story buildings were obtained from $IM_2(11)$, $IM_2(12)$, and $IM_2(12)$, respectively. Figure 4 shows the correlation between $\ln Sa$ and IM_2 considering the $IM_2(11)$ and $IM_2(12)$ parameters for the one-story structure.

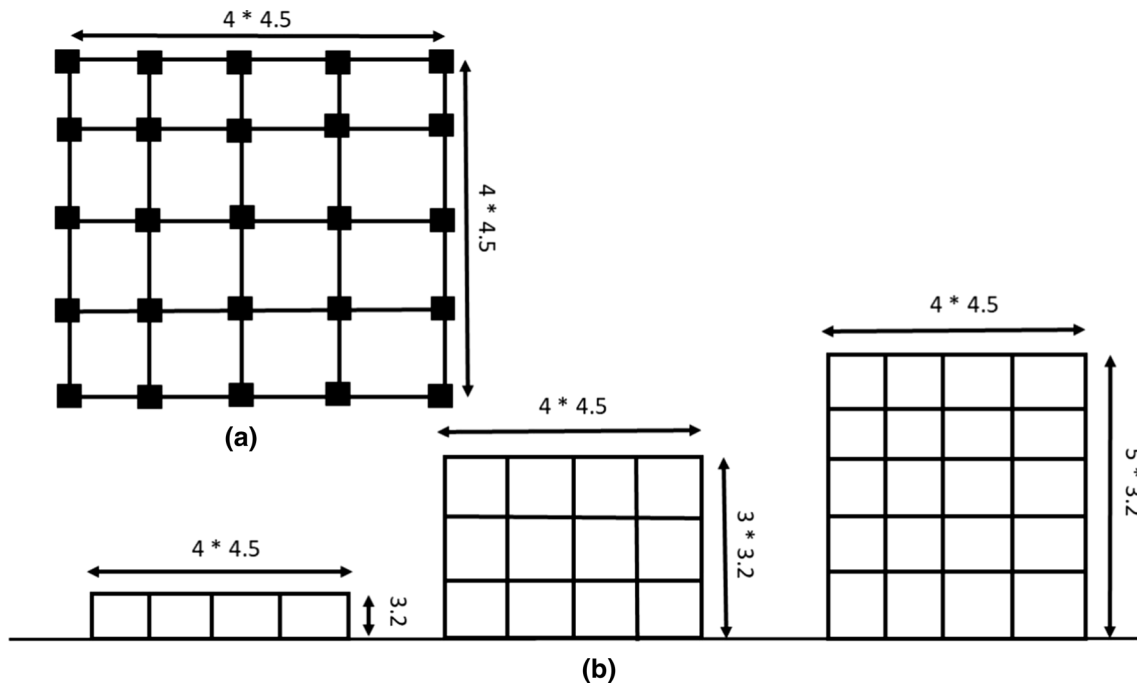


Fig. 1 a Plan and, b Elevation of considered buildings

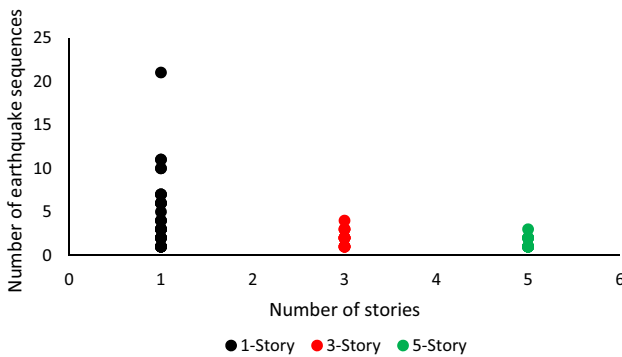


Fig. 2 The number of aftershocks needed for collapse of the frames

Using an efficient vector IM leads to a reduction in the number of earthquakes required for the estimation of a structural response. Equation 5 can be used to calculate the standard error of capacity associated with a sample size of n_s . Table 10 shows the standard error of all IM_2 s for each building as percentages.

$$\mu_{\ln IM_1 | IM_2 = im_2} = \alpha_0 + \alpha_1 \ln IM_2 \tag{2}$$

$$\sigma_{\ln IM_1 | IM_2} = \left[\sum_{i=1}^n (\ln IM_{1i} - \overline{\ln IM_{1i}})^2 / (n - 2) \right]^{1/2} \tag{3}$$

$$\rho = \frac{\text{cov}(\ln IM_1, \ln IM_2)}{\sigma_{\ln IM_1} \sigma_{\ln IM_2}} \tag{4}$$

$$SE = \frac{\sigma_{\ln IM_1 | IM_2}}{\sqrt{n_s}} \tag{5}$$

5 Sufficiency of IMs for Collapse Capacity Prediction Considering the Magnitude and Source to Site Distance

A sufficient IM has an independent distribution of the ground motion properties (e.g., magnitude and distance). In scalar IMs, sufficiency, with respect to M and R, is determined through a linear regression between the properties and observed capacity through Eq. 6, in which coefficients β_0 and β_1 can be determined from the linear regression, and x can be M or $\ln R$. The student-t distribution can be assumed for β_1 , and an F-test can be utilized to determine the significance of β_1 . A p-value of less than 0.05 shows insufficiency. It can be seen that IM_1 is insufficient with respect to M and $\ln R$. To determine the sufficiency of Vectors-M, the residual capacity of Eq. 1 for $\ln R$ or M is used in Eq. 6 instead of collapse capacity Tables 13 and 14.

$$\mu_{\ln IM_1} = \beta_0 + \beta_1 x \tag{6}$$

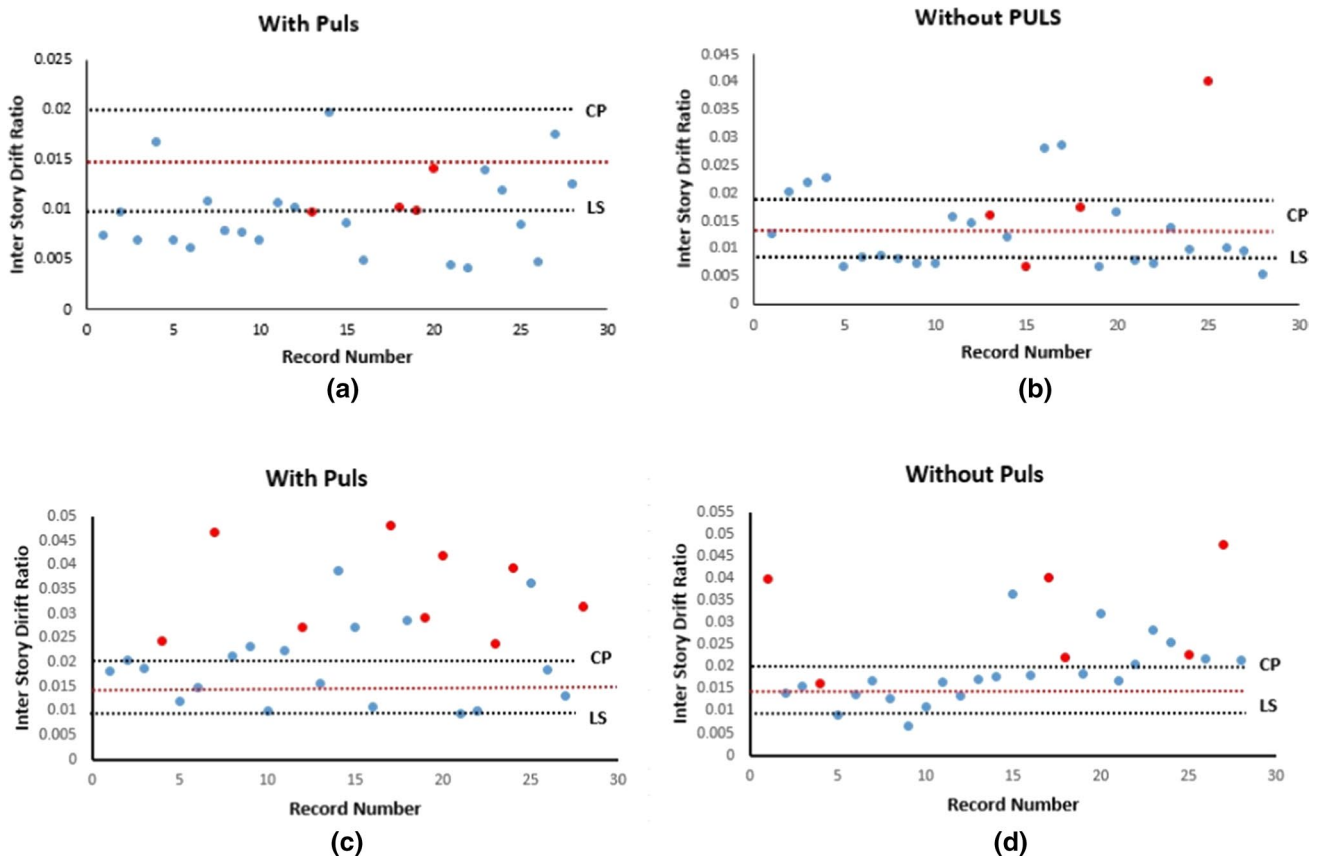


Fig. 3 Purification of earthquake records

Other research studies have used this method to determine sufficiency (Luco and Cornell 2007), (Baker and Cornell 2008), (Tothong and Cornell 2008), and (Bradley, et al. 2009). Figure 6 illustrates the results. Regarding the relationship between IM_1 as a scalar IM with respect to M and LnR for a one-story building. It can be concluded that IM_1 is insufficient with respect to M and LnR , as the p-values from the F-test are less than 0.05. Therefore, it is necessary to consider the magnitude and distance of the earthquake record. A unique magnitude and distance cannot be dedicated to a chain of sequences from an earthquake, as it is made up of several time histories. Distance and magnitude were considered as the average of all earthquakes in each series. The p-values for M and R for all vector IMs are available in Tables 15 and 16, respectively. Figures 5 and 6 illustrate the results for the one-story frame. $IM_2(11)$ shows the best sufficiency of all IM_2 s.

In order to calculate collapse probability, 46 main shock records were considered where each main shock was followed by 50 chains of aftershock (Fig. 7). The Fig. 7 illustrates the procedure which was proposed in this study. Thus, in this study n and m are 28 and 50 respectively. Variable n shows the number of earthquakes that were used as the main

shocks and variable m denotes to the number of chains that follow each mainshock. In total there is (28×150) 1400 main shock- aftershock sequences. Collapse probability for a vector IM can be calculated via logistic regression according to the Eq. 7. Note that the return period is considered to be equal to a specific measure and all the main shock records are scaled to have $IM_1 = S_a(T_1)$ mainshock, after which unscaled records were imposed to the frames as aftershock. In order to calculate collapse probability, im_1 , im_2 , a , and b should be determined. im_1 is $S_a(T_1)$ of main shock. This parameter depends on the considered return period and is extract from main shock spectrum of the region. All main shocks are scaled to have $IM_1 = im_1$. Unscaled main shocks are utilized as aftershock and imposed to the structure until the collapse happens. There for there are 1400 amin shock-aftershock sequences. The parameter ($IM_2(11)$) which is the ratio of summation of the first mode spectral acceleration value of aftershocks on summation of the area of aftershocks $S_a(T_1)$ plot of each chain is calculated. According to the results of logistic regression the mount of a , and b are extract. In order to obtain im_2 , the amount Eq. 8 should be determined.

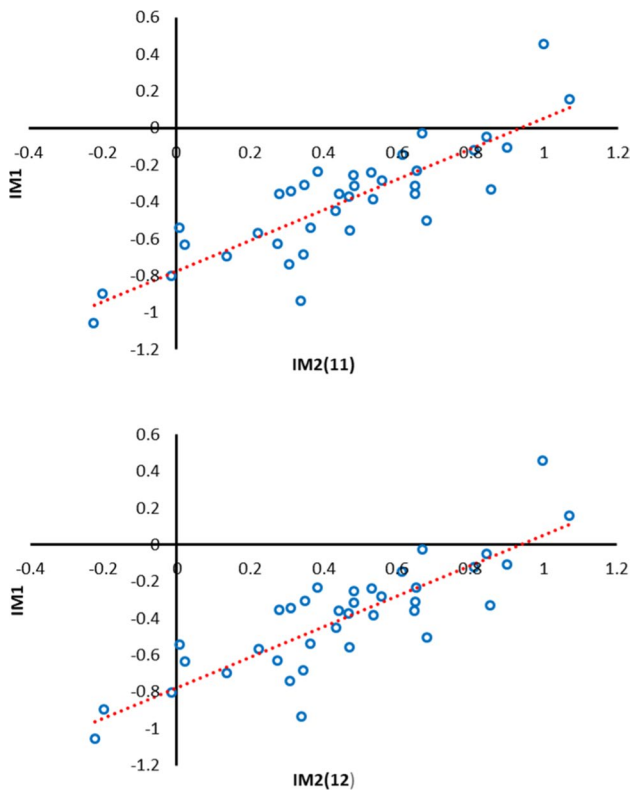


Fig. 4 Correlation between the collapse capacity of the 1-story structure and different IM2(11) and IM2(12)

Table 9 Period of the structures

Number of stories	Fundamental period (s)
1	0.454
3	0.93
5	1.238

Table 10 Correlation, P-value, and standard deviation of 1-story frame

Parameter	1	2	3	4	5	6	7	8	9	10	11	12	13	14
Correlation	0.452	0.453	0.453	0.4431	0.455	0.447	0.526	0.568	0.572	0.451	0.839	0.671	0.604	0.437
P-value	0.017	1E-07	2E-15	8E-16	0.477	0.295	0.001	9E-23	2E-24	8E-11	2E-27	6E-24	9E-12	5E-16
STD	1.044	0.91	0.91	0.9957	1.006	1.205	0.812	0.821	0.869	1.047	0.302	0.423	0.396	0.838

Table 11 Correlation, P-value, and standard deviation of 3-story frame

Parameter	1	2	3	4	5	6	7	8	9	10	11	12	13	14
Correlation	0.55	0.399	0.399	-0.001	0.565	-0.137	0.568	0.307	-0.05	0.572	0.751	0.87	0.399	0.131
P-value	0.134	0.017	1E-10	2E-10	6E-04	0.111	5E-09	9E-14	2E-13	3E-05	0.002	2E-12	0.161	0.295
STD	0.828	0.553	0.553	0.6396	0.647	0.792	0.561	0.583	0.632	0.702	0.34	0.347	0.414	0.58

$$P(\text{Collapse}|IM_1 = im_1, IM_2 = im_2) = \frac{1}{1 + e^{-(a+bm_2)}} \quad (7)$$

$$\frac{\sum_{i=1}^{i=na} S_a(T_1)}{\sum_{i=1}^{i=na} \int S_a(T_1)} \quad (8)$$

In which na is the number of aftershocks that follow each mainshock. The expected number of aftershocks with a specific magnitude can be determined through Epidemic-Type Aftershock Sequence (ETAS) (N_{ETAS}) (Tavakolietal.2018). Therefore, na is equal to the N_{ETAS} for each earthquake magnitude, as Eq. 8 is a fraction, the amount of N_{ETAS} in the face and dominator are omitted. Therefore, im_2 can be derived by Eq. 9.

$$im_2 = S_a(T_1) / \int S_a(T_1) \quad (9)$$

The amount of $S_a(T_1)$ of aftershock can be determined by Aftershock spectrum for a specific return period. $\int S_a(T_1)$ is the area under the aftershock spectrum which obtained by aftershock probabilistic hazard analysis. Knowing im_2 , collapse probability can be calculated through Eq. 7. In order to illustrate the procedure, the collapse probability of 1,3 and 5 story frames in Sect. 3 are determined. The results are as below. It should be mentioned that the return period is considered to be 10% in 50 years. Table 13 and 14 show the results.

It can be concluded the number of stories doesn't have consider effect on probability of collapse.

6 Results

An overview of the results is provided in Table 18. The correlation coefficient has been categorized into four groups according to (Rumsey 2016) (Table 17). According to the

Table 12 Correlation, P-value, and standard deviation of 5-story frame

Parameter	1	2	3	4	5	6	7
Correlation	0.583	0.626	0.626	0.2888	0.633	0.502	0.0
P-value	0.005	1E-07	3E-15	7E-14	4E-06	5E-04	8E
STD	0.923	0.449	0.449	0.6344	1.119	1.119	0.2

Table 13 im_1, b, a of frames

Number of Stories	im_1	a	b
1	0.8425	1.4089	-2.3462
3	0.5012	2.0897	-4.7194
5	0.4539	2.0833	-11.1019

Table 14 $im_2, a, and b$ of frames

Number of stories	$S_a(T_1)$	$\int S_a(T_1)$	im_2	P(collapse) (%)
1	1.036	2.6697	0.3879	62.2
3	0.896	2.6697	0.3357	62.3
5	0.7262	2.6697	0.272	71.8

previous sections, an efficient IM assumes that a t-test will yield a p-value of less than 0.05, while a sufficient IM (using the F-test) should yield a p-value of above 0.05. Considering this, an acceptable and unacceptable p-value has been shown with A and No, respectively. According to the data in Table 18, IM2(11) and IM2(12) have the best correlation

Table 15 P-value of IM2 respect to M

St No	1	2	3	4	5	6	7	8	9	10	11	12	13	14
IM2														
1	0.207	0.296	0.275	0.128	0.102	0.012	0.344	0.075	3E-09	2E-07	0.0541	4E-05	0.01	2E-10
3	2E-05	0.002	0.002	3E-04	3E-04	3E-05	0.001	1E-03	0.0004	1E-04	0.0971	0.0851	0.024	0.001
5	0.015	2E-06	2E-06	2E-04	0.001	0.079	3E-05	5E-04	0.0176	0.003	2E-06	1E-05	4E-05	1E-06

Table 16 P-Value of IM2s respect to LnR

St No	1	2	3	4	5	6	7	8	9	10	11	12	13	14
IM2														
1	0.184	0.45	0.45	0.252	0.238	0.039	0.3	0.319	0.461	0.175	1E-08	2E-05	8E-06	0.365
3	0.063	0.41	0.41	0.687	0.347	0.144	0.495	0.487	0.411	0.248	0.1794	0.209	0.3983	0.271
5	0.041	0.162	0.162	0.404	0.181	0.008	0.451	0.232	0.028	0.114	0.1909	0.2831	0.4988	0.14

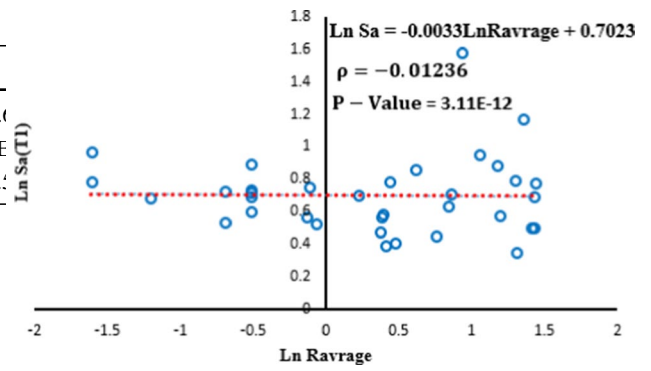


Fig. 5 Testing the sufficiency of $S_a(T_1)$ with respect to M and R for collapse capacity prediction of the 1-story structure: M

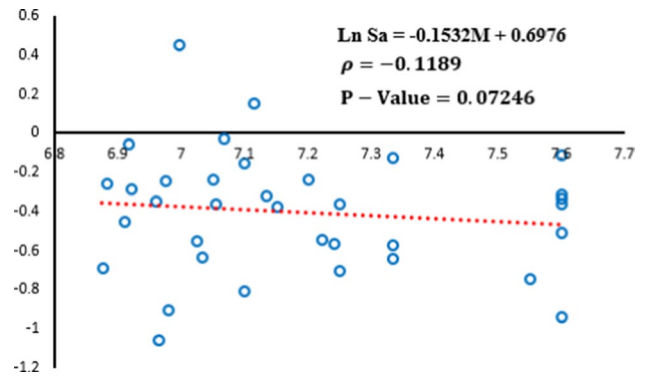


Fig. 6 Testing the sufficiency of $S_a(T_1)$ with respect to M and R for collapse capacity prediction of the 1-story structure: LnR

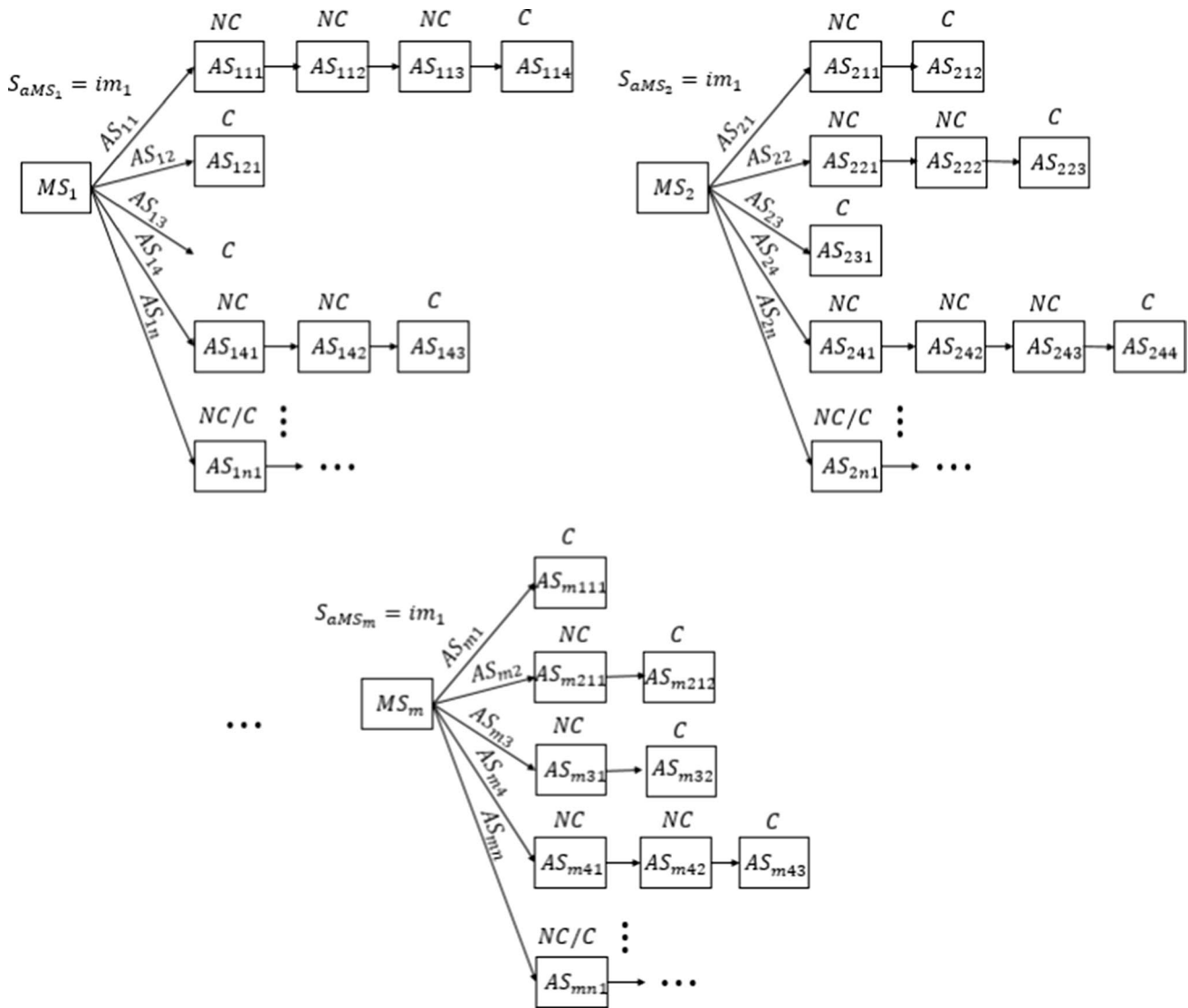


Fig. 7 Chemotic diagram of the sequential analysis procedure

of any two IM2s. However, it seems that IM2(12) is not sufficient with respect to magnitude. IM2(14) has the lowest level of correlation with the other IM2s. Other IM2s were also found not to be sufficient with respect to M. Therefore, IM2(11) is the best candidate for the second main IM. As a result, $(S_a(T_1), IM(11))$ is the most likely acceptable IM for the seismic evaluation of short buildings when aftershock impacts are considered.

7 Conclusions

The aim of this study is to investigate several new vector IMs in order to compare the proposed IMs.

Three low-rise RC frames were considered and analyzed under the 56 near-field earthquake record situations taken

Table 17 Categorization of correlation coefficient

Correlation Coef	Group	Abbreviation
0.3	Weak	W
0.5	Moderate	M
0.7	Strong	S
1	Excellent	E

from FEMA P-695. The results show that the $S_a(T_1)$ of the mainshock was insufficient with respect to M. Therefore, new vector records were introduced. The $S_a(T_1)$ of the mainshock was considered the first component in all the new IMs.

The present investigation showed that $(S_a(T_1), IM_2(11))$ is the most suitable case among other proposed IMs, as it is

Table 18 Summary of the results

	Correlation			Standard Deviation			P-Value IM1 & IM2			P-Value Maverage			P-Value Raverage		
	1	3	5	1	3	5	1	3	5	1	3	5	1	3	5
1	M	S	S	1.044	0.828	0.923	A	NO	A	A	NO	NO	A	A	A
2	M	M	S	0.91	0.553	0.449	A	NO	A	A	NO	NO	A	A	A
3	M	M	S	0.91	0.553	0.449	A	A	A	A	NO	NO	A	A	A
4	M	W	W	0.996	0.64	0.634	A	A	A	A	NO	NO	A	A	A
5	M	S	S	1.006	0.647	1.119	NO	A	A	A	NO	NO	A	A	A
6	M	W	S	1.205	0.792	1.119	NO	NO	A	A	NO	A	A	A	A
7	S	S	S	0.812	0.561	0.548	A	A	A	A	NO	NO	A	A	A
8	S	M	S	0.869	0.583	0.679	A	A	A	A	NO	NO	A	A	A
9	S	W	M	0.869	0.632	0.936	A	A	A	NO	NO	A	A	A	A
10	M	S	S	1.047	0.702	0.79	A	A	A	NO	NO	NO	A	A	A
11	E	E	E	0.302	0.34	0.455	A	A	NO	A	A	NO	NO	A	A
12	S	E	E	0.423	0.347	0.512	A	A	A	NO	A	NO	NO	A	A
13	S	M	W	0.396	0.414	0.559	A	NO	A	A	A	NO	NO	A	A
14	M	W	W	0.838	0.58	0.442	A	NO	A	NO	NO	NO	A	A	A

both efficient and sufficient $IM_2(11)$ is the ratio of summation of the first mode spectral acceleration value of aftershocks on summation of the area of aftershock spectrum $S_a(T_1)$ plots. Thus, by utilizing this IM, the number of analyses needed to estimate the structural response of a building can be decreased. Also, earthquake records can be considered independently of their magnitude and distance from the building. Furthermore, the efficiency and sufficiency of the proposed IMs can increase the reliability of seismic assessments.

The current study has examined only RC frames. The research does not consider all damage states and evaluates only the structures at a collapse damage level.

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