

Bi-Integrable Couplings Associated with $\mathfrak{so}(3, \mathbb{R})$

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Abstract By a class of zero curvature equations over a non-semisimple matrix loop algebra, we generate a new hierarchy of bi-integrable couplings for a soliton hierarchy associated with $\mathfrak{so}(3, \mathbb{R})$. The bi-Hamiltonian structures are found by the associated variational identity, which imply that all the presented coupling systems possess infinitely many commuting symmetries and conserved functionals and, thus, are Liouville integrable.

Keywords Integrable coupling · Matrix loop algebra · Hamiltonian structure

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1 Introduction

The study of solitons in regard to integrable systems has facilitated a deeper understanding of mathematics and physics. Many well-known nonlinear partial differential equations have been found to have soliton solutions, for example, the Korteweg–de Vries equation and the sine-Gordon equation. It is known that zero curvature equations associated with simple Lie algebras generate classical integrable systems [1], and semisimple Lie algebras generate non-coupled systems of classical integrable systems. It is our business to further develop the study of non-semisimple Lie algebras in relation to integrable couplings. Soliton hierarchies, and specifically, integrable couplings and bi-integrable couplings, provide valuable new insights into the classification of multi-component integrable systems [2–6].

It is known that zero curvature equations on semidirect sums of matrix loop algebras generate integrable couplings [7, 8], and the associated variational identity [9, 10] is used to furnish Hamiltonian structures and bi-Hamiltonian structures of the resulting integrable couplings and bi-integrable couplings [11–17]. An important step in generating Hamiltonian structures is to search for non-degenerate, symmetric, and ad-invariant bilinear forms on the underlying loop algebras [13, 18] as the trace identity proposed by Gui-Zhang Tu [18, 19] is ineffective for non-semisimple Lie algebras which possess a degenerate Killing form. Semidirect sums of loop algebras bring various interesting integrable couplings and bi-integrable couplings [20–24], including higher-dimensional local bi-Hamiltonian integrable couplings [25–29], greatly enriching multi-component integrable systems. Recently, it has been of interest to study new integrable couplings and bi-integrable couplings generated from spectral problems associated with $\mathfrak{so}(3, \mathbb{R})$ [14].

Integrable couplings enlarge an original integrable system and often times retain its properties [2, 4]. Bi-integrable couplings then take the integrable coupling system and enlarge that system. Again, the original properties frequently are maintained. An important feature is if a soliton hierarchy has infinitely many commuting symmetries and conserved densities, the integrable coupling and then bi-integrable coupling generally will too [14–17, 30, 31]. A bi-integrable coupling system is a natural way of extending a well-behaved integrable system. We show that the bi-integrable couplings of an original spectral problem associated with $\mathfrak{so}(3, \mathbb{R})$ will preserve bi-Hamiltonian structures, i.e., Liouville integrability, of the integrable couplings associated with the same spectral problem [32].

A zero curvature representation of a system of the form

$$u_t = K(u) = K(x, t, u, u_x, u_{xx}, \dots), \quad (1)$$

where u is a column vector of dependent variables and means there exists a Lax pair [33] $U = U(u, \lambda)$ and $V = V(u, \lambda)$ in a matrix loop algebra such that the zero curvature equation,

$$U_t - V_x + [U, V] = 0, \quad (2)$$

will generate system (1) [19]. The integrable coupling of system (1) is an integrable system of the form ([25,26] for definition):

$$\bar{u}_t = \bar{K}_1(\bar{u}) = \begin{bmatrix} K(u) \\ S(u, u_1) \end{bmatrix}, \quad \bar{u} = \begin{bmatrix} u \\ u_1 \end{bmatrix}, \tag{3}$$

where u_1 is a new column vector of dependent variables. An integrable system of the form

$$\bar{u}_t = \bar{K}_1(\bar{u}) = \begin{bmatrix} K(u) \\ S_1(u, u_1) \\ S_2(u, u_1, u_2) \end{bmatrix}, \quad \bar{u} = \begin{bmatrix} u \\ u_1 \\ u_2 \end{bmatrix}, \tag{4}$$

is called a bi-integrable coupling of (1). Note that in (4), S_2 depends on u_2 , but S_1 does not. Now, we use zero curvature equations in order to generate bi-integrable couplings and associated Hamiltonian structures, through appropriate variational identities.

We will proceed with Sects. 2 through 6. In Sect. 2, we recall a soliton hierarchy presented in [32] for a matrix spectral problem in $so(3, \mathbb{R})$. In Sect. 3, we construct bi-integrable couplings from the results in Sect. 2 using an enlarged matrix loop algebra. We then use the corresponding variational identity to present the Hamiltonian structure of the bi-integrable coupling system in Sect. 4. In Sect. 5, infinitely many symmetries and conserved functionals are discussed. We finish the paper with a couple open questions.

2 A Soliton Hierarchy Associated with $so(3, \mathbb{R})$

Let us recall the a soliton hierarchy [32] given by the spectral problem

$$\phi_x = U\phi, \quad U = U(u, \lambda) = \begin{bmatrix} 0 & q & \lambda \\ -q & 0 & -p \\ -\lambda & p & 0 \end{bmatrix} \in \bar{so}(3), \tag{5}$$

where

$$u = \begin{bmatrix} p \\ q \end{bmatrix}, \quad \phi = \begin{bmatrix} \phi_1 \\ \phi_2 \end{bmatrix},$$

λ is a spectral parameter, $p = p(x, t)$, $q = q(x, t)$, and $\bar{so}(3)$ is the special matrix loop algebra, i.e.,

$$\bar{\mathfrak{g}} = \bar{so}(3) = \{A \in so(3) | \text{entries of } A \text{ are Laurent series in } \lambda\}. \tag{6}$$

Under the assumption that W is of the form

$$W = \begin{bmatrix} 0 & c & a \\ -c & 0 & -b \\ -a & b & 0 \end{bmatrix} = \sum_{i \geq 0} \begin{bmatrix} 0 & c_i & a_i \\ -c_i & 0 & -b_i \\ -a_i & b_i & 0 \end{bmatrix} \lambda^{-i} = \sum_{i \geq 0} W_i \lambda^{-i}, \tag{7}$$

then the stationary zero curvature equation,

$$W_x = [U, W], \tag{8}$$

determines the system of equations

$$\begin{cases} a_x = pc - qb, \\ b_x = -\lambda c + qa, \\ c_x = -pa + \lambda b. \end{cases} \tag{9}$$

After setting a, b, c to appropriate Laurent expansions, system (9) equivalently generates

$$\begin{cases} b_{i+1} = pa_i + c_{i,x}, \\ c_{i+1} = -b_{i,x} + qa_i, \\ a_{i+1,x} = pc_{i+1} - qb_{i+1}, \end{cases} \quad i \geq 0. \tag{10}$$

Next, we set the initial conditions as $\{a_0 = -1, b_0 = 0 = c_0\}$ and take all constants of integration to be zero. We can present for $1 \leq i \leq 4$:

$$\begin{aligned} a_1 &= 0, & c_1 &= -q, & b_1 &= -p, \\ a_2 &= \frac{1}{2}(p^2 + q^2), & c_2 &= p_x, & b_2 &= -q_x, \\ a_3 &= pq_x - p_xq, & c_3 &= q_{xx} + \frac{1}{2}p^2q + \frac{1}{2}q^3, & b_3 &= p_{xx} + \frac{1}{2}p^3 + \frac{1}{2}pq^2, \\ a_4 &= -\frac{3}{4}p^2q^2 - \frac{3}{8}p^4 + \frac{1}{2}p_x^2 - pp_{xx} - \frac{3}{8}q^4 + \frac{1}{2}q_x^2 - qq_{xx}, \\ b_4 &= q_{xxx} + \frac{1}{2}(3p^2 + 3q^2)q_x, & c_4 &= -p_{xxx} - \frac{1}{2}(3p^2 + 3q^2)p_x. \end{aligned}$$

All functions $\{a_i, b_i, c_i | i \geq 0\}$ are differential polynomials of u with respect to x .

The zero curvature equations are

$$U_{t_m} - V_x^{[m]} + [U, V^{[m]}] = 0 \quad \text{with} \quad V^{[m]} = (\lambda^m W)_+, \tag{11}$$

where $m \geq 0$, and, therefore, provide a hierarchy of soliton equations, i.e.,

$$u_{t_m} = K_m = \begin{bmatrix} -c_{m+1} \\ b_{m+1} \end{bmatrix} = \Phi^m \begin{bmatrix} q \\ -p \end{bmatrix} = J \frac{\delta \mathcal{H}_m}{\delta u}, \tag{12}$$

where $m \geq 0$. The Hamiltonian operator J , the hereditary recursion operator Φ , and the Hamiltonian functions are defined as follows:

$$J = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}, \quad \Phi = \begin{bmatrix} q\partial^{-1}p & \partial + q\partial^{-1}q \\ -\partial - p\partial^{-1}p & -p\partial^{-1}q \end{bmatrix}, \quad \mathcal{H}_m = \int -\frac{a_{m+2}}{m+1} dx, \tag{13}$$

in which $m \geq 0$ and $\partial = \frac{\partial}{\partial x}$. The first nonlinear example is

$$u_{t_2} = K_2 = \begin{bmatrix} -q_{xx} - \frac{1}{2}p^2q - \frac{1}{2}q^3 \\ p_{xx} + \frac{1}{2}p^3 + \frac{1}{2}pq^2 \end{bmatrix} = J \begin{bmatrix} p_{xx} + \frac{1}{2}p^3 + \frac{1}{2}pq^2 \\ q_{xx} + \frac{1}{2}p^2q + \frac{1}{2}q^3 \end{bmatrix} = J \frac{\delta \mathcal{H}_2}{\delta u}. \tag{14}$$

3 Bi-Integrable Couplings

We construct Hamiltonian bi-integrable couplings for the soliton hierarchy by using a matrix loop Lie algebra. Define a triangular block matrix

$$M(A_1, A_2, A_3) = \begin{bmatrix} A_1 & A_2 & A_3 \\ 0 & A_1 & \alpha A_2 \\ 0 & 0 & A_1 \end{bmatrix}. \tag{15}$$

It is known that block matrices of this form are closed under multiplication, i.e., constitute a Lie algebra [34]. The associated loop matrix Lie algebra $\tilde{\mathfrak{g}}(\lambda)$ is formed by all block matrices of the type

$$\tilde{\mathfrak{g}}(\lambda) = \{M(A_1, A_2, A_3) | M \text{ defined by (15), entries of } A \text{ are Laurent series in } \lambda\}. \tag{16}$$

A spectral matrix is chosen from $\tilde{\mathfrak{g}}(\lambda)$ as

$$\tilde{U} = \tilde{U}(\tilde{u}, \lambda) = M(U, U_1, U_2), \quad \tilde{u} = (p, q, r, s, v, w)^T, \tag{17}$$

where U is defined as in (5) and the supplementary spectral matrices U_1 and U_2 are

$$U_1 = U_1(u_1) = \begin{bmatrix} 0 & s & 0 \\ -s & 0 & -r \\ 0 & r & 0 \end{bmatrix}, \quad u_1 = \begin{bmatrix} r \\ s \end{bmatrix}, \tag{18}$$

$$U_2 = U_2(u_2) = \begin{bmatrix} 0 & w & 0 \\ -w & 0 & -v \\ 0 & v & 0 \end{bmatrix}, \quad u_2 = \begin{bmatrix} v \\ w \end{bmatrix}. \tag{19}$$

In order to solve the enlarged stationary zero curvature equation,

$$\bar{W}_x = [\tilde{U}, \bar{W}], \tag{20}$$

we take the solution to be of the following form:

$$\bar{W} = \bar{W}(\tilde{u}, \lambda) = M(W, W_1, W_2) \in \tilde{\mathfrak{g}}(\lambda), \tag{21}$$

where W is defined by (7) and solves $W_x = [U, W]$, and W_1 and W_2 are assumed to be

$$W_1 = W_1(u, u_1, \lambda) = \begin{bmatrix} 0 & g & e \\ -g & 0 & -f \\ -e & f & 0 \end{bmatrix} \in \bar{so}(3), \tag{22}$$

and

$$W_2 = W_2(u, u_1, u_2, \lambda) = \begin{bmatrix} 0 & g' & e' \\ -g' & 0 & -f' \\ -e' & f' & 0 \end{bmatrix} \in \bar{so}(3). \quad (23)$$

Equation (20) is equivalent to satisfying the following matrix equations:

$$\begin{cases} W_x = [U, W], \\ W_{1,x} = [U, W_1] + [U_1, W], \\ W_{2,x} = [U, W_2] + [U_2, W] + \alpha[U_1, W_1]. \end{cases} \quad (24)$$

The second and third equations in (24) generate

$$\begin{cases} e_x = pg - qf + rc - sb, \\ f_x = -\lambda g + qe + sa, \\ g_x = -pe + \lambda f - ra, \end{cases} \quad (25)$$

and

$$\begin{cases} e'_x = -fs\alpha + gra - qf' + pg' - wb + vc, \\ f'_x = qe' - \lambda g' + wa + sea, \\ g'_x = -pe' + \lambda f' - rea - va, \end{cases} \quad (26)$$

respectively. Plugging into recursion relations (25) and (26) into the Laurent expansions,

$$\begin{cases} e = \sum_{i \geq 0} e_i \lambda^{-i}, & f = \sum_{i \geq 0} f_i \lambda^{-i}, & g = \sum_{i \geq 0} g_i \lambda^{-i}, \\ e' = \sum_{i \geq 0} e'_i \lambda^{-i}, & f' = \sum_{i \geq 0} f'_i \lambda^{-i}, & g' = \sum_{i \geq 0} g'_i \lambda^{-i}, \end{cases} \quad (27)$$

we have

$$\begin{cases} f_{i+1} = g_{i,x} + pe_i + ra_i, \\ g_{i+1} = -f_{i,x} + qe_i + sa_i, \\ e_{i+1,x} = pg_{i+1} - qf_{i+1} + rc_{i+1} - sb_{i+1}, \\ f'_{i+1} = g'_{i,x} + pe'_i + va_i + \alpha rc_i, \\ g'_{i+1} = -f'_{i,x} + qe'_i + wa_i + \alpha sc_i, \\ e'_{i+1,x} = pg'_{i+1} - qf'_{i+1} - \alpha sf_{i+1} + \alpha rg_{i+1} - wb_{i+1} + vc_{i+1}, \end{cases} \quad (28)$$

where $i \geq 0$. We take the initial data as $\{e_0 = -1, f_0 = g_0 = 0; e'_0 = -1, f'_0 = g'_0 = 0\}$ and suppose that the integration constants are zero. Then, recursion relation (28) uniquely generates $\{e_i, f_i, g_i, e'_i, f'_i, g'_i | i \geq 1\}$. We obtain

$$\left\{ \begin{aligned} e_1 &= 0, \\ f_1 &= -p - r, \\ g_1 &= -q - s; \\ e_2 &= \frac{1}{2}p^2 + \frac{1}{2}q^2 + rp + sq, \\ f_2 &= -q_x - s_x, \\ g_2 &= p_x + r_x; \\ e_3 &= q_x p - qp_x - sp_x + rq_x + s_x p - r_x q, \\ f_3 &= p_{xx} + \frac{1}{2}p^3 + \frac{1}{2}pq^2 + \frac{3}{2}rp^2 + psq + \frac{1}{2}rq^2 + r_{xx}, \\ g_3 &= q_{xx} + \frac{1}{2}q^3 + \frac{1}{2}qp^2 + \frac{3}{2}sq^2 + qrp + \frac{1}{2}sp^2 + s_{xx}; \\ e_4 &= (-p - r)p_{xx} + (-q - s)q_{xx} - pr_{xx} - qs_{xx} - \frac{1}{2}p_x^2 + p_x r_x + \frac{1}{2}q_x^2 + q_x s_x \\ &\quad - \frac{3}{8}(p^2 + q^2)(p^2 + 4pr + q(q + 4s)), \\ f_4 &= q_{xxx} + s_{xxx} + \frac{1}{2}(3p^2 + 6pr + 3q^2 + 6qs)q_x + \frac{1}{2}(3p^2 + 3q^2)s_x, \\ g_4 &= -p_{xxx} - r_{xxx} + \frac{1}{2}(-3p^2 - 6pr - 3q^2 - 6qs)p_x + \frac{1}{2}(-3p^2 - 3q^2)r_x; \end{aligned} \right.$$

and

$$\left\{ \begin{aligned} e'_1 &= 0, \\ f'_1 &= -p - \alpha r - v, \\ g'_1 &= -q - \alpha s - w; \\ e'_2 &= \frac{1}{2}p^2 + \frac{1}{2}q^2 + \alpha rp + \alpha sq + vp + wq + \frac{1}{2}\alpha s^2 + \frac{1}{2}\alpha r^2, \\ f'_2 &= -q_x - \alpha s_x - w_x, \\ g'_2 &= p_x + \alpha r_x + v_x; \\ e'_3 &= q_x p - qp_x - \alpha sp_x + \alpha rq_x + \alpha s_x p - r_x q - wp_x + vq_x + w_x p - \alpha qr_x \\ &\quad - v_x q + \alpha s_x r - \alpha sr_x, \\ f'_3 &= p_{xx} + \frac{1}{2}p^3 + \frac{1}{2}pq^2 + \alpha \frac{3}{2}rp^2 + \alpha psq + \alpha \frac{1}{2}rq^2 + r_{xx} + \alpha \frac{3}{2}pr^2 + \alpha rsq \\ &\quad + pqw + \frac{3}{2}vp^2 + \frac{1}{2}vq^2 + \frac{1}{2}\alpha ps^2 + \alpha r_{xx} + v_{xx}, \\ g'_3 &= q_{xx} + \frac{1}{2}q^3 + \frac{1}{2}qp^2 + \alpha \frac{3}{2}sq^2 + \alpha qrp + \alpha \frac{1}{2}sp^2 + s_{xx} + \alpha \frac{3}{2}qs^2 + \alpha srp \\ &\quad + pvq + \frac{3}{2}wq^2 + \frac{1}{2}wp^2 + \frac{1}{2}\alpha pr^2 + \alpha s_{xx} + w_{xx}; \\ e'_4 &= (-\alpha r - p - v)p_{xx} + (-\alpha s - q - w)q_{xx} - \alpha(p + r)r_{xx} - \alpha(q + s)s_{xx} \\ &\quad - v_{xx}p - w_{xx}q + \frac{1}{2}p_x^2 + (\alpha r_x + v_x)p_x \\ &\quad + \frac{1}{2}q_x^2 + (\alpha s_x + w_x)q_x + \frac{1}{2}\alpha r_x^2 + \frac{1}{2}\alpha s_x^2 - \frac{3}{8}p^4 + \frac{3}{2}(-\alpha r - v)p^3 \\ &\quad + \frac{1}{8}(-6q^2 + (-12\alpha s - 12w)q - 18\alpha r^2 - 6\alpha s^2)p^2 \\ &\quad - \frac{3}{2}q((\alpha r + v)q + 2\alpha rs)p - \frac{3}{2}q^2\left(\frac{1}{4}q^2 + (\alpha s + w)q + \frac{1}{2}\alpha(r^2 + 3s^2)\right), \\ f'_4 &= q_{xxx} + \alpha s_{xxx} + w_{xxx} + \frac{1}{2}(3p^2 + (6\alpha r + 6v)p + 3q^2 + (6\alpha s + 6w)q \\ &\quad + 3\alpha r^2 + 3\alpha s^2)q_x + \frac{1}{2}(3\alpha p^2 + 6\alpha pr + 3\alpha q^2 + 6\alpha qs)s_x \\ &\quad + \frac{1}{2}(3p^2 + 3q^2)w_x, \\ g'_4 &= -p_{xxx} - \alpha r_{xxx} - v_{xxx} + \frac{1}{2}(-3p^2 - (6\alpha r + 6v)p - 3q^2 - (6\alpha s + 6w)q \\ &\quad - 3\alpha r^2 - 3\alpha s^2)p_x + \frac{1}{2}(-3\alpha p^2 - 6\alpha pr - 3\alpha q^2 - 6\alpha qs)r_x \\ &\quad - \frac{1}{2}(3p^2 + 3q^2)v_x. \end{aligned} \right.$$

These functions are differential polynomials in the variables $p, q, r, s, v,$ and w .

Similar to [35], for each integer $m \geq 0$, we further introduce an enlarged Lax matrix

$$\bar{V}^{[m]} = (\lambda^m \bar{W})_+ = M \left(V^{[m]}, V_1^{[m]}, V_2^{[m]} \right) \in \tilde{\mathfrak{g}}(\lambda), \tag{29}$$

where $V^{[m]}$ is defined by (11) and $V_i^{[m]} = (\lambda^m W_i)_+, i = 1, 2$. The enlarged zero curvature equation,

$$\bar{U}_{t_m} - \bar{V}_x^{[m]} + [\bar{U}, \bar{V}^{[m]}] = 0, \tag{30}$$

gives the following matrix equations:

$$\begin{cases} U_{1,t_m} - V_{1,x}^{[m]} + [U, V_1^{[m]}] + [U_1, V^{[m]}] = 0, \\ U_{2,t_m} - V_{2,x}^{[m]} + [U, V_2^{[m]}] + [U_2, V^{[m]}] + \alpha [U_1, V_1^{[m]}] = 0, \end{cases} \tag{31}$$

along with the system in (11). The above equations then present the additional systems

$$\bar{v}_{t_m} = S_m = S_m(\bar{v}) = \begin{bmatrix} S_{1,m}(u, u_1) \\ S_{2,m}(u, u_1, u_2) \end{bmatrix}, \quad m \geq 0, \tag{32}$$

where $\bar{v} = (r, s, v, w)^T$ and

$$S_{1,m}(u, u_1) = \begin{bmatrix} -g_{m+1} \\ f_{m+1} \end{bmatrix},$$

and

$$S_{2,m}(u, u_1, u_2) = \begin{bmatrix} -g'_{m+1} \\ f'_{m+1} \end{bmatrix}.$$

Then the enlarged zero curvature equation generates a hierarchy of bi-integrable couplings,

$$\bar{u}_{t_m} = \begin{bmatrix} p \\ q \\ r \\ s \\ v \\ w \end{bmatrix}_{t_m} = \begin{bmatrix} -c_{m+1} \\ b_{m+1} \\ -g_{m+1} \\ f_{m+1} \\ -g'_{m+1} \\ f'_{m+1} \end{bmatrix} = \bar{K}_m(\bar{u}), \quad m \geq 0, \tag{33}$$

for soliton hierarchy (12).

In particular, when $m = 2$, we have $u_{t_2} = \bar{K}_2$, i.e.,

$$\begin{aligned}
 & \begin{bmatrix} p \\ q \\ r \\ s \\ v \\ w \end{bmatrix}_{t_2} \\
 &= \begin{bmatrix} -q_{xx} - \frac{1}{2}p^2q - \frac{1}{2}q^3 \\ p_{xx} + \frac{1}{2}p^3 + \frac{1}{2}pq^2 \\ -q_{xx} - \frac{1}{2}q^3 - \frac{1}{2}qp^2 - \frac{3}{2}sq^2 - qrp - \frac{1}{2}sp^2 - s_{xx} \\ p_{xx} + \frac{1}{2}p^3 + \frac{1}{2}pq^2 + \frac{3}{2}rp^2 + psq + \frac{1}{2}rq^2 + r_{xx} \\ -q_{xx} - \frac{1}{2}q^3 - \frac{1}{2}qp^2 - \alpha\frac{3}{2}sq^2 - \alpha qrp - \alpha\frac{1}{2}sp^2 - s_{xx} - \alpha\frac{3}{2}qs^2 - \alpha srp \\ -pvq + \frac{3}{2}wq^2 - \frac{1}{2}wp^2 - \frac{1}{2}\alpha ps^2 - \alpha s_{xx} - w_{xx} \\ p_{xx} + \frac{1}{2}p^3 + \frac{1}{2}pq^2 + \alpha\frac{3}{2}rp^2 + \alpha psq + \alpha\frac{1}{2}rq^2 + r_{xx} + \alpha\frac{3}{2}pr^2 + \alpha rsq \\ +pqw + \frac{3}{2}vp^2 + \frac{1}{2}vq^2 + \frac{1}{2}\alpha ps^2 + \alpha r_{xx} + v_{xx} \end{bmatrix}.
 \end{aligned}
 \tag{34}$$

4 Hamiltonian Structures

We have a systematic approach for generating Hamiltonian structures for the bi-integrable coupling in (33) using the variational identity over the enlarged matrix loop algebra $\tilde{\mathfrak{g}}(\lambda)$ [13, 18]. The variational identity is as follows:

$$\frac{\delta}{\delta \bar{u}} \int \langle \bar{W}, \bar{U}_\lambda \rangle dx = \lambda^{-\gamma} \frac{\partial}{\partial \lambda} \lambda^\gamma \langle \bar{W}, \bar{U}_\lambda \rangle, \quad \gamma = \text{constant}.
 \tag{35}$$

As seen in [35], there is a convenient method to constructing a symmetric and ad-invariant bilinear form on $\tilde{\mathfrak{g}}(\lambda)$ by rewriting the semidirect sum $\tilde{\mathfrak{g}}(\lambda)$ into a vector form. First, we define a mapping

$$\sigma : \tilde{\mathfrak{g}}(\lambda) \mapsto \mathbb{R}^9, A \mapsto (a_1, \dots, a_9)^T,
 \tag{36}$$

where

$$A = M(A_1, A_2, A_3) \in \tilde{\mathfrak{g}}(\lambda), \quad A_i = \begin{bmatrix} 0 & a_{3i} & a_{3i-2} \\ -a_{3i} & 0 & -a_{3i-1} \\ -a_{3i-2} & a_{3i-1} & 0 \end{bmatrix}, \quad 1 \leq i \leq 3.
 \tag{37}$$

The map σ induces a Lie algebra structure on \mathbb{R}^9 isomorphic to the enlarged matrix loop algebra $\tilde{\mathfrak{g}}(\lambda)$. Thus, the corresponding Lie bracket $[\cdot, \cdot]$ on \mathbb{R}^9 is generated by letting

$$[a, b]^T = a^T R(b), \tag{38}$$

where $a = (a_1, \dots, a_9)^T, b = (b_1, \dots, b_9)^T \in \mathbb{R}^9$ and

$$R(b) = M(R_1, R_2, R_3), \tag{39}$$

with

$$R_i = \begin{bmatrix} 0 & -b_{3i} & b_{3i-1} \\ b_{3i} & 0 & -b_{3i-2} \\ -b_{3i-1} & b_{3i-2} & 0 \end{bmatrix}, \quad 1 \leq i \leq 3. \tag{40}$$

There is an Lie isomorphism, σ , between the Lie algebra $(\mathbb{R}^9, [\cdot, \cdot])$ with the enlarged matrix loop algebra $\tilde{\mathfrak{g}}(\lambda)$.

We may find a bilinear form on \mathbb{R}^9 by

$$\langle a, b \rangle = a^T F b, \tag{41}$$

where F is a constant matrix and the symmetric property of $\langle \cdot, \cdot \rangle$ requires that

$$F^T = F. \tag{42}$$

The symmetric condition along with the ad-invariance property

$$\langle a, [b, c] \rangle = \langle [a, b], c \rangle,$$

provides the condition

$$F(R(b))^T = -R(b)F, \quad b \in \mathbb{R}^9. \tag{43}$$

Upon solving the derived system of equations from (43) for an arbitrary vector $b \in \mathbb{R}^9$, we find

$$F = \begin{bmatrix} \eta_1 & \eta_2 & \eta_3 \\ \eta_2 & \alpha\eta_3 & 0 \\ \eta_3 & 0 & 0 \end{bmatrix} \otimes F_0, \tag{44}$$

where

$$F_0 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \tag{45}$$

and $\eta_i, 1 \leq i \leq 3$, are arbitrary constants. Thus, the bilinear form on the semidirect sum $\tilde{\mathfrak{g}}(\lambda)$ of the two Lie subalgebras $\tilde{\mathfrak{g}}$ and $\tilde{\mathfrak{g}}_c$ is defined as

$$\begin{aligned} \langle A, B \rangle_{\tilde{\mathfrak{g}}(\lambda)} &= \langle \sigma(A), \sigma(B) \rangle_{\mathbb{R}^9} \\ &= (a_1, \dots, a_9)F(b_1, \dots, b_9)^T \\ &= (a_1b_1 + a_2b_2 + a_3b_3)\eta_1 + (a_1b_4 + a_2b_5 + a_3b_6 + a_4b_1 + a_5b_2 \\ &\quad + a_6b_3)\eta_2 + (\alpha a_4b_4 + \alpha a_5b_5 + \alpha a_6b_6 + a_1b_7 + a_2b_8 + a_3b_9 \\ &\quad + a_7b_1 + a_8b_2 + a_9b_3)\eta_3, \end{aligned} \tag{46}$$

where A and B are two matrices in $\tilde{\mathfrak{g}}(\lambda)$ presented by

$$\begin{cases} A = \sigma^{-1}((a_1, \dots, a_9)^T) \in \tilde{\mathfrak{g}}(\lambda), \\ B = \sigma^{-1}((b_1, \dots, b_9)^T) \in \tilde{\mathfrak{g}}(\lambda). \end{cases} \tag{47}$$

Bilinear form (46) is symmetric and ad-invariant due to the isomorphism σ . A bilinear form, defined by (46), is non-degenerate iff the determinant of F is not zero, i.e.,

$$\det(F) = -\eta_3^9 \alpha^3 \neq 0. \tag{48}$$

Therefore, we choose $\eta_3 \neq 0$ to obtain a non-degenerate, symmetric, and ad-invariant bilinear form over the enlarged matrix loop algebra $\tilde{\mathfrak{g}}(\lambda)$.

Now, we compute

$$\langle \bar{W}, \bar{U}_\lambda \rangle_{\tilde{\mathfrak{g}}(\lambda)} = a\eta_1 + e\eta_2 + e'\eta_3 \tag{49}$$

and

$$\langle \bar{W}, \bar{U}_{\bar{u}} \rangle_{\tilde{\mathfrak{g}}(\lambda)} = \begin{bmatrix} b\eta_1 + f\eta_2 + f'\eta_3 \\ c\eta_1 + g\eta_2 + g'\eta_3 \\ b\eta_2 + \alpha f\eta_3 \\ c\eta_2 + \alpha g\eta_3 \\ b\eta_3 \\ c\eta_3 \end{bmatrix}. \tag{50}$$

In addition, the formula $\gamma = -\frac{\lambda}{2} \frac{d}{d\lambda} \ln |\text{tr}(W^2)|$ [19] yields that the constant $\gamma = 0$, and thus, the corresponding variational identity is

$$\frac{\delta}{\delta \bar{u}} \int \frac{-a_{m+1}\eta_1 - e_{m+1}\eta_2 - e'_{m+1}\eta_3}{m} dx = \begin{bmatrix} b_m\eta_1 + f_m\eta_2 + f'_m\eta_3 \\ c_m\eta_1 + g_m\eta_2 + g'_m\eta_3 \\ b_m\eta_2 + \alpha f_m\eta_3 \\ c_m\eta_2 + \alpha g_m\eta_3 \\ b_m\eta_3 \\ c_m\eta_3 \end{bmatrix}, \quad m \geq 1. \tag{51}$$

We consequently obtain a Hamiltonian structure for hierarchy (33) of bi-integrable couplings,

$$\bar{u}_{t_m} = \bar{J} \frac{\delta \bar{\mathcal{H}}_m}{\delta \bar{u}}, \quad m \geq 0, \tag{52}$$

with the Hamiltonian functionals,

$$\bar{\mathcal{H}}_m = \int \frac{-a_{m+2}\eta_1 - e_{m+2}\eta_2 - e'_{m+2}\eta_3}{m + 1} dx, \tag{53}$$

and the Hamiltonian operator,

$$\bar{J} = \begin{bmatrix} 0 & \eta_1 & 0 & \eta_2 & 0 & \eta_3 \\ -\eta_1 & 0 & -\eta_2 & 0 & -\eta_3 & 0 \\ 0 & \eta_2 & 0 & \alpha\eta_3 & 0 & 0 \\ -\eta_2 & 0 & -\alpha\eta_3 & 0 & 0 & 0 \\ 0 & \eta_3 & 0 & 0 & 0 & 0 \\ -\eta_3 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}^{-1}, \tag{54}$$

and note that $\det(\bar{J}) \neq 0$. In particular, when $m = 2$, the Hamiltonian functional is

$$\bar{\mathcal{H}}_2 = \int \frac{1}{3} (-a_4\eta_1 - e_4\eta_2 - e'_4\eta_3) dx, \tag{55}$$

where

$$\begin{aligned} -a_4\eta_1 - e_4\eta_2 - e'_4\eta_3 &= ((\eta_1 + \eta_2 + \eta_3)p + (\alpha\eta_3 + \eta_2)r + \eta_3v) p_{xx} \\ &+ ((\eta_1 + \eta_2 + \eta_3)q + (\alpha\eta_3 + \eta_2)s\eta_3w) q_{xx} \\ &+ ((\alpha\eta_3 + \eta_2)p + \eta_3\alpha r) r_{xx} ((\alpha\eta_3 + \eta_2)q + \eta_3\alpha s) s_{xx} \\ &+ \eta_3 p v_{xx} \eta_3 q w_{xx} - \frac{1}{2}(\eta_1 + \eta_2 + \eta_3) p_x^2 \\ &+ ((-\alpha\eta_3 - \eta_2)r_x - \eta_3 v_x) p_x - (\eta_1 + \eta_2 + \eta_3) q_x^2 \\ &+ ((-\alpha\eta_3 - \eta_2)s_x - \eta_3 w_x) q_x - \frac{1}{2}\eta_3 \alpha r_x^2 - \frac{1}{2}\eta_3 \alpha s_x^2 \\ &+ \frac{3}{8}(\eta_1 + \eta_2 + \eta_3) p^4 \frac{3}{2} ((\alpha\eta_3 + \eta_2)r + \eta_3v) p^3 \\ &+ \frac{1}{8} \left(6(\eta_1 + \eta_2 + \eta_3) q^2 + ((12\alpha\eta_3 + 12\eta_2)s + 12\eta_3w) q \right. \\ &+ 18\eta_3 \left(r^2 + \frac{1}{3}s^2 \right) \alpha \left. \right) p^2 + \frac{3}{2}(((\alpha\eta_3 + \eta_2)r + \eta_3v)q \\ &+ 2\eta_3\alpha r s) p q + \frac{3}{8}q^2((\eta_1 + \eta_2 + \eta_3)q^2 + ((4\alpha\eta_3 \\ &+ 4\eta_2)s + 4\eta_3w)q + 2\alpha\eta_3(r^2 + 3s^2)). \end{aligned} \tag{56}$$

5 Symmetries and Conserved Functionals

We may solve the recursion relation of symmetries

$$\bar{K}_m = \bar{\Phi} \bar{K}_{m-1}, \quad m \geq 0, \tag{57}$$

for a recursion operator, $\bar{\Phi}$, to obtain

$$\bar{\Phi} = \begin{bmatrix} \Phi & 0 & 0 \\ \Phi_1 & \Phi & 0 \\ \Phi_2 & \alpha\Phi_1 & \Phi \end{bmatrix}, \tag{58}$$

where Φ is given by (13) and

$$\Phi_1 = \begin{bmatrix} q\partial^{-1}r + s\partial^{-1}p & q\partial^{-1}s + s\partial^{-1}q \\ -p\partial^{-1}r - r\partial^{-1}p & -p\partial^{-1}s - r\partial^{-1}q \end{bmatrix}, \tag{59}$$

and

$$\Phi_2 = \begin{bmatrix} q\partial^{-1}v + w\partial^{-1}p + \alpha s\partial^{-1}r & q\partial^{-1}w + w\partial^{-1}q + \alpha s\partial^{-1}s \\ -p\partial^{-1}v - v\partial^{-1}p - \alpha r\partial^{-1}r & -p\partial^{-1}w - v\partial^{-1}q - \alpha r\partial^{-1}s \end{bmatrix}. \tag{60}$$

It can be shown by a symbolic computation that $\bar{\Phi}$ is a hereditary operator [36,37]. Therefore,

$$\bar{\Phi}'(\bar{u})[\bar{\Phi}\bar{T}_1]\bar{T}_2 - \bar{\Phi}\bar{\Phi}'(\bar{u})[\bar{T}_1]\bar{T}_2$$

is symmetric with respect to \bar{T}_1 and \bar{T}_2 , and the two operators \bar{J} and $\bar{M} = \bar{\Phi}\bar{J}$ make a Hamiltonian pair [38], i.e., \bar{J} , \bar{M} , and $\bar{J} + \bar{M}$ are all Hamiltonian operators. Thus, the hierarchy (33) of bi-integrable couplings possesses a bi-Hamiltonian structure [38,39] and is Liouville integrable. It follows that there are infinitely many symmetries and conserved functionals:

$$[\bar{K}_m, \bar{K}_n] = 0, \quad m, n \geq 0, \tag{61}$$

and

$$\{\bar{\mathcal{H}}_m, \bar{\mathcal{H}}_n\}_{\bar{J}} = \{\bar{\mathcal{H}}_m, \bar{\mathcal{H}}_n\}_{\bar{M}} = 0, \quad m, n \geq 0. \tag{62}$$

6 Concluding Remarks

We have obtained a new class of bi-integrable couplings (33) for the soliton hierarchy (12) using on non-semisimple Lie algebra (16). We showed the resulting hierarchy of bi-integrable couplings possesses a bi-Hamiltonian structure and is Liouville integrable. It remains an open question how to generate a Hamiltonian structure for matrix loop algebra (15) when $\alpha = 0$ as the bilinear form presented in Sect. 4 is degenerate.

Some enlarged matrix loop algebras do not possess any non-degenerate, symmetric, and ad-invariant bilinear forms required in the variational identity. In the following example of a bi-integrable coupling,

$$\begin{cases} u_t = K(u) \\ v_t = K'(u)[v] \\ w_t = K'(u)[w]. \end{cases} \quad (63)$$

where $K'(u)$ denotes the Gateaux derivative, is there any Hamiltonian structure for this specific bi-integrable coupling?

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