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# Cooling/Lubrication Performance of Dry and Supercritical CO<sub>2</sub>-Based **Minimum Quantity Lubrication in Peripheral Milling Ti‑6Al‑4V**

**Chongyan Cai1 · Xu Liang1 · Qinglong An[1](http://orcid.org/0000-0001-5023-7258) · Zhengrui Tao1 · Weiwei Ming<sup>1</sup> · Ming Chen1**

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#### **Abstract**

Cryogenic environments are often adopted in machining difficult-to-cut materials such as Ti-6Al-4V alloy to control its cutting heat and improve machinability. This paper aims to study the machinability of Ti-6Al-4V in fnish milling process under four green cutting environments (CEs), i.e. dry, supercritical carbon dioxide ( $\sec O_2$ ), supercritical CO<sub>2</sub>-based minimum quantity lubrication with water-based cutting fluid (scCO<sub>2</sub>-WMQL), supercritical  $CO<sub>2</sub>$ -based minimum quantity lubrication with oil-on-water droplets cutting fluid ( $\text{scCO}_2$ -OoWMQL). Peripheral finish-milling of Ti-6Al-4V was conducted under various cutting speeds, feed rates, radial depth of cut and CEs. The cutting force, cutting temperature, surface morphology and surface roughness were analysed. The experiment results show that the minimum cutting force and its coefficients, cutting temperature and surface roughness are obtained in  $\text{scCO}_2$ -OoWMQL environment because of its excellent cooling/ lubrication and chip evacuation performance, whereas the worst friction in the tool-workpiece interface leads to the worst performance under scCO<sub>2</sub> CE. Additionally, the machined surface profile, cutting force and their spectrums under four CEs were studied. The fundamental frequency of machined surface profle is equal to that of cutting force envelope under dry and  $\secO_2$  CEs, which is also called beat frequency, therefore  $\secO_2$ -WMQL and  $\secO_2$ -OoWMQL CEs can improve the milling stability. The results indicate that scCO<sub>2</sub>-OoWMQL provides the best performance with regard to cutting force, cutting temperature, surface fnish and clean production.

**Keywords** Supercritical CO<sub>2</sub> · Minimum quantity lubrication · Oil-on-water · Beat vibration · Cutting force coefficients · Peripheral milling

# **1 Introduction**

Ti-6Al-4V alloy has many advantages such as high specifc strength, good thermal strength, corrosion resistance and abundant resources. It has a wide range of applications in aerospace, defence industry and medical felds [\[1,](#page-14-0) [2](#page-14-1)]. However, the high chemical activity and the low thermal conductivity greatly afect the machinability of the titanium alloy  $[3]$  $[3]$ . In order to effectively control the rise of cutting temperature and cutting force, improve the friction state of the tool-work interface, suppress tool wear and improve the quality of the machined surface, it is necessary to apply cooling/lubrication conditions in machining Ti-6Al-4V.

 $\boxtimes$  Qinglong An qlan@sjtu.edu.cn

Although cutting fuids have been widely used in food cooling system in manufacturing process, traditional cutting fuids also have their disadvantages, such as high cost, serious environmental pollution, difficulty in waste fluid treatment and threat to the health of operators. Amiril et al. [[4\]](#page-14-3) and Gajrani et al. [[5\]](#page-14-4) pointed out that in high productivity manufacturing enterprises, the cost of cutting fuid supply, maintenance and recycling together accounts for 17% of the manufacturing cost of the workpiece, while the cost of cutting tools only accounts for 2–4%. Moreover, the poor permeability of cutting fuid in food cooling process often leads to lubricant flm rupture and lubrication failure, due to the excessive temperature of the cutting zone [[6](#page-14-5)]. Therefore, according to the requirements of environmental protection and sustainable development, it is necessary to improve and reduce the environmental pollution caused by cutting fuid, so as to realize cleaner production. Cleaner production requires green cutting technology in manufacturing process [[7\]](#page-14-6). At present, green cutting technology can

 $1$  School of Mechanical Engineering, Shanghai Jiao Tong University, Shanghai 200240, People's Republic of China

be divided into two categories: one is dry cutting technology without lubrications at all; the other is quasi-dry cutting technology, which requires a very small amount of cutting fuid that is degradable and harmless to the human body, such as steam cooling, liquid nitrogen cooling, MQL and cryogenic minimum quantity lubrication (CMQL). Although dry cutting can protect the environment and reduce costs to a large extent, the inevitable large cutting force and high cutting temperature in dry cutting will have an impact on the machinability. Complete dry cutting has a narrow range of applications due to the harsh requirements on cutting tools, process selection principles and other conditions. Quasi-dry combines the advantages of dry and flood cooling, which can not only meet the processing requirements, but also reduce the cost of cutting fuid to the lowest level and meet the same requirements as dry cutting  $[8, 9]$  $[8, 9]$  $[8, 9]$  $[8, 9]$  $[8, 9]$ .

Yuan et al. [\[10](#page-15-1)] found that MQL condition cannot produce evident efect on cutting performance of Ti-6Al-4V, because oil mists cannot penetrate the contact layer to lubricate the cutting zone efectively due to the high temperature and load in tool-chip and tool-workpiece interfaces. Bordin et al. [[9\]](#page-15-0) pointed out that cryogenic semi-fnish turning Ti-6Al-4V signifcantly reduces tool wear, improves surface fnish and chip fragmentation compared with dry and wet cutting. Cryogenic machining is a sustainable manufacturing process for titanium alloy surgical prostheses. CMQL combines the efficient cooling of cryogenic machining with the lubrication effect of MQL, and solves the problem of insufficient cooling performance such as lubrication flm breakdown caused by excessive temperature in cutting zone. CMQL technology has become a research hotspot of scholars.

There is extensive review on the application of MQL and CMQL techniques for machining titanium alloys [\[11](#page-15-2)]. Pereira et al.  $[11]$  $[11]$  optimized the  $CO<sub>2</sub>$  flow outlet diameter and velocity by utilizing computational fuid dynamics during CMQL machining and designed two nozzle adaptors to obtain best cooling/lubrication performance. Li et al. [[2\]](#page-14-1) pointed out that the addition of graphite nanoparticles in cutting fuid can signifcantly improve the cooling/lubrication performance of oil flm in milling Ti-6Al-4V under MQL condition. Bai et al. [[12\]](#page-15-3) compared the cooling/lubrication performance of different nanofluids by dispersing  $Al_2O_3$ ,  $SiO<sub>2</sub>$ , MoS<sub>2</sub>, CNTs, SiC, and graphite particles in cutting fluids, results showed that  $Al_2O_3$  and  $SiO_2$ -based MQL obtained the lowest cutting force and surface roughness. Krolczyk et al. [[7\]](#page-14-6) found that compared with dry turning, the use of mineral oil-based cooling-lubricant can reduce the tool life by nearly 65% in duplex stainless turning process, they also found that when the cutting speed is high and the feed rate is small, the cutting force of dry turning is smaller than that under food cooling condition, which means dry turning can achieve cleaner production for high cutting speed and low feed rate. Mia et al. [[13](#page-15-4)] established a sustainability evaluation model under three sustainable processing technologies, i.e. dry cutting, MQL, solid lubrication system with compressed air cooling and traditional food cooling by Pugh matrix environment method, results showed that MQL provides environment friendliness, cleaner production and helps to improve the desirable machinability characteristics. Krolczyk et al. [\[14](#page-15-5)] studied the parametric and non-parametric description of the machined surface after dry cutting and CMQL conditions. Results showed that the application of CMQL method can lead to the reduction of 3D surface roughness parameters compared to values reached after the dry machining, and the surface wear resistance was improved by CMQL. Bagherzadeh and Budak [[15](#page-15-6)] proposed a new cooling technology in turning experiments of Ti-6Al-4V and Inconel 718 to improve the cooling effect of MQL and cryogenic  $CO<sub>2</sub>$ , results showed that CMQL increase machinability and fnal product quality with low cooling rate consumption. Based on response surface methodology and Taguchi signal-to-noise ratio method, Mia [\[16\]](#page-15-7) established a statistical model for the infuence of feed rate, cutting speed and MQL fow rate on the cutting energy and surface roughness in end milling AISI 4140 steel. Behera et al. [[17](#page-15-8)] studied the cutting force, tool wear, surface integrity and chip morphology of Inconel 718 under high-pressure jet, cryogenic, MQL and MQL with nanofuid CEs. They concluded that the cryogenic environment results in better surface integrity and reduced tool wear. Mia and Dhar [[18](#page-15-9)] studied the cutting zone temperature, machinability of material and tool wear pattern by applying highpressure coolant into tool-chip and tool-workpiece interfaces respectively. Results showed that high pressure coolant jet can signifcantly reduce cutting temperature, cutting force and surface roughness, and improve tool life. Faga et al. [[19\]](#page-15-10) investigated the process productivity and environmental impact in turning of Ti-6Al-4V under dry, MQL, emulsion mist and wet CEs. Wang et al. [[6\]](#page-14-5) proposed using cryogenic air with OoW droplets as an environmentally friendly cooling/lubrication method to reduce tool wear in turning compacted graphite cast iron.  $\text{scCO}_2$ -OoWMQL environment was also used in machining 316L stainless steel, under which the cutting force was reduced  $[20]$  $[20]$  $[20]$ .

Although there are lots of studies on the performance of different cooling/lubrication conditions in machining hard-to-cut materials, the comprehensive analysis of machinability of Ti-6Al-4V peripheral fnish-milling under sustainable green CEs, i.e. dry,  $\text{scCO}_2$ ,  $\text{scCO}_2$ -WMQL,  $\text{scCO}_2$ -OoWMQL, is rarely reported. This paper investigates the cutting force and its coefficients, cutting temperature, surface morphology, surface roughness and milling stability under various cutting parameters and CEs. The mechanism of beat vibration in dry and  $\sec O_2$  CEs under specific cutting parameters is also studied, and the dependence of surface profle on milling force envelope is quantifed. Finally, it is concluded that  $\text{scCO}_2$ -OoWMQL is the most suitable CE for the sustainability and green fnish-milling of Ti-6Al-4V, and can promote cleaner production.

# **2 Experiment**

#### **2.1 Cooling/Lubrication Methods**

Figure [1](#page-2-0) shows the schematic diagram of the CMQL generator. The device has two separate oil-based and water-based cutting fuid storage tanks, two separate cutting fuid-air mixing chambers and two separate atomizing nozzles. Two diferent cutting fuids are transported to the mixing chamber through an oil pump, then atomized by high-pressure and high-speed air jet from the air compressor, and then entered the nozzle. Due to the expansion of oil molecules, they are adsorbed at the water-molecule interface, forming oil-onwater (OoW) droplets. Under the Joule–Thomson effect, the mixture of OoW droplets and air mixes with high-pressure, high-speed and normal-temperature  $CO<sub>2</sub>$  at the nozzle to form a cryogenic (approximately − 78℃) mixed jet of gaseous  $CO_2$ /solid- $CO_2$ / $O$ oW droplets. It penetrates into the cutting zone at a high speed, resulting in a signifcant reduction in the temperature of the cutting zone and the surrounding environment for powerful cryogenic cooling and lubrication. Different cooling/lubrication methods, namely,  $\text{scCO}_2$ ,  $\text{scCO}_2$ -WMQL and  $\text{scCO}_2$ -OoWMQL, can be obtained when controlling diferent valves. The diameter of the droplet particles is about  $100 \sim 200 \mu$ m. The cooling/lubrication methods and their parameters are shown in Table [1](#page-2-1).

#### **2.2 Experiment Parameter**

Figure [2a](#page-3-0) shows the photograph of experimental set-up. The peripheral milling was carried out on HURCO VMX42 three-axis vertical CNC machining centre with a positioning accuracy of 0.01 mm. The workpiece was Ti-6Al-4V alloy block with a shape of  $50 \times 50 \times 20$  mm and a hardness of 30-45HRC, and the chemical composition of Ti-6Al-4V is: Al 6.5%, V 4.25%, Fe 0.04%, C 0.02%, N 0.015%, O 0.16%, H 0.0018%, Ti, Bal [\[10\]](#page-15-1). The tool was a 4-edge cemented carbide end mill with a 1-4 μm diamond coating by CVD, a diameter of 6 mm, a blade length of 20 mm, a rake angle of



<span id="page-2-0"></span>**Fig. 1** Schematic diagram of CMQL generator

<span id="page-2-1"></span>





<span id="page-3-0"></span>**Fig. 2 a** Experimental set-up **b** CMQL system **c** Nozzle arrangement diagram—main view **d** Nozzle arrangement diagram—top view **e** scCO<sub>2</sub> jet with lubricant particles

5° and a helix angle of 35°. The cutting force was measured by Kistler 9272 piezoelectric dynamometer, amplifed by Kistler 5070A multi-channel charge amplifer and recorded by data acquisition card. The milling force acquisition frequency was 2 kHz. The milling temperature was measured using an infrared camera model FLIR A615, which has a resolution of  $640 \times 480$  temperature points per frame and acquires 60 frames per second. The distance between infrared camera and cutting zone was 800 mm. An emissivity value of 0.5 was used for the Ti-6Al-4 V. The maximum cutting zone temperature at a machining length of 16.7 mm was taken as the characteristic temperature for each trial.

The temperature feld in the cutting zone during milling is shown in Fig. [3](#page-3-1). The atomizing nozzle with an inner diameter of 1.4 mm was mounted on the machining centre through a connecting plate, the gas/liquid two-phase  $CO<sub>2</sub>$ was delivered to the nozzle through a metal pipe having an inner diameter of about 5 mm, while the gas/liquid twophase mixture of the cutting fuid droplets and air was delivered to the nozzle through a plastic pipe having an inner diameter of about 3 mm. Figure [2](#page-3-0)b shows the ARMORINE  $scCO<sub>2</sub>-$ OoWMQL cooling/lubrication system and liquid  $CO<sub>2</sub>$  storage tank. As shown in Fig. [2c](#page-3-0) and d, distances





<span id="page-3-1"></span>**Fig. 3** Temperature feld measured by infrared camera

between the centres of No. 1 and No. 2 nozzles to the tool centre are approximately 52 mm and 53 mm, respectively. Angles between the axes of No. 1 and No. 2 nozzles and the feed direction are 3° and 25°, respectively.

Milling parameters are shown in Table [2](#page-4-0). The cutting speed  $v_c$ , the feed per tooth  $f<sub>z</sub>$  and the radial depth of cut  $a_e$ were single factor variables, each factor took three levels,



and nine experiments under each CE were performed using one end mill. Three passes are performed under each milling parameter. The axial depth of cut of each pass is  $a_p = 3$  mm, the machined surface length left under each parameter was 16.7 mm. The machining schematic is shown in Fig. [2c](#page-3-0).

After the experiment, the machined surface morphology was taken using Keyence VHX-500 FE 3D microscopy system. The surface profle and roughness parameters were measured by Mitutoyo SJ-210 Portable Surface Roughness Tester based on the ISO 4288–1997 standards, the GAUSS filter was used with cut-off length  $\lambda_c = 0.8$  mm and evaluation length  $l_n = 5$  *l* = 4.0 mm. During the measurement, the surface roughness was repeatedly measured 5 times on the machined surface of the frst pass, and the average value was taken under each milling parameter.

### **3 Results and Discussion**

## **3.1 Milling Force**

<span id="page-4-0"></span>**Table 2** Milling parameters

During the down milling process, the thickness of the cutting layer is periodically reduced from maximum to zero, so the cutting force also changes periodically. The average resultant milling force over a period of time during the frst pass is calculated by Eq. ([1\)](#page-4-1) under each cutting parameter and CE.

$$
\overline{F} = \frac{\int_{t_1}^{t_2} \sqrt{F_x^2 + F_y^2 + F_z^2} dt}{t_2 - t_1}
$$
\n(1)

 $(a)$ 

 $200$ 

Resultant cutting force  $\frac{1}{2}$ <br>b  $\frac{1}{2}$   $\frac{1$ 

 $\mathbf 0$ 

 $0.02$ 

dry

 $0.03$ 

where  $\overline{F}$  is the average resultant milling force,  $F_x$ ,  $F_y$ ,  $F_z$ are the instantaneous milling force components in the feed *x*, normal *y*, and axial *z* direction, respectively,  $t_2$  and  $t_1$  are the upper and lower limits of the integral, respectively, and the integration time period is  $t_2-t_1=4$  s.

For each CE, the average reduction *r* of the cutting force relative to that under dry cutting condition is calculated by Eq. ([2\)](#page-4-2) [[17](#page-15-8)].

<span id="page-4-2"></span>
$$
r(\%) = \frac{1}{n} \sum_{i=1}^{n} r_i
$$
 (2)

where,  $r_i$  is the amount of reduction of the cutting force in the *i*-th test under  $\sec O_2$ ,  $\sec O_2$ -WMQL and  $\sec O_2$ -OoWMQL with respect to that under dry cutting, and *n* represents the number of tests.

For  $v_c = 40$  m/min,  $a_e = 0.3$  mm and  $a_p = 3$  mm, the variation of cutting force with feed rate under each CE is shown in Fig. [4](#page-4-3)a, and the changes of cutting force in different cooling/lubrication environments relative to that in dry cutting environment are shown in Fig. [4b](#page-4-3). The cutting force increases with increasing feed rate regardless of CEs, which is also observed by Behera et al. [\[17](#page-15-8)]. and Mia [\[21](#page-15-12)]. This rise can be attributed to the increased cutting layer area for higher feed rate. The order of cutting force under different CEs is  $\text{scCO}_2$ >dry> $\text{scCO}_2$ -WMQL> $\text{scCO}_2$ -OoW-MQL. The average changes of cutting force under  $\text{scCO}_2$ ,  $scCO<sub>2</sub>-WMQL$ ,  $scCO<sub>2</sub>-OoWMQL$  CEs with respect to that under dry cutting are 49.0%, -20.4% and -28%, respectively. Surprisingly, the utilization of  $\sec O_2$  condition significantly increases the cutting force. In particular, when feed

<span id="page-4-1"></span>

<span id="page-4-3"></span>**Fig. 4 a** Cutting force vs. feed rate **b** Percentage changes of cutting force under cooling/ lubrication environments relative to that under dry cutting

rate is very small  $(f<sub>z</sub>=0.025$  mm/min), the cutting force increases by 60.1%. This can be attributed to the fact that the strength and hardness of Ti-6Al-4V alloys increase with the decrease of temperature  $[22]$  $[22]$ , under scCO<sub>2</sub> condition, the cutting deformation resistance increases, and the friction in tool-workpiece interface deteriorates. However, when cutting fluid is mixed into cryogenic  $CO<sub>2</sub>$ , the cutting forces decrease signifcantly relative to dry cutting. Particularly, for small feed rate  $(f<sub>z</sub>=0.025$  mm/min), the reductions of cutting forces of  $\text{scCO}_2$ -WMQL and  $\text{scCO}_2$ -OoWMQL are the largest with respect to dry cutting, which are  $-27.7\%$ , − 35.9%, respectively. Although the cryogenic environment increases the strength of the workpiece material, high speed liquid  $CO<sub>2</sub>$  and lubricant jets can lift the chip and reduce the contact length between chip and tool rake face, and the presence of lubricant reduces the friction coefficients of toolchip and tool-workpiece interfaces, so in view of this, the cutting forces of  $\text{scCO}_2$ -WMQL and  $\text{scCO}_2$ -OoWMQL are still reduced relative to that of dry cutting. The cutting force of  $\text{scCO}_2$ -OoWMQL is smaller than that of  $\text{scCO}_2$ -WMQL, which can be ascribed to the larger viscosity and better lubricating performance of OoW droplets than those of water droplets.

For  $f_z = 0.045$  mm/rev,  $a_e = 0.3$  mm and  $a_p = 3$  mm, the variation of cutting force with  $v_c$  under each CE is shown in Fig. [5a](#page-5-0), and the changes of cutting force in diferent cooling/ lubrication environments relative to that in dry cutting are shown in Fig. [5](#page-5-0)b. The cutting force increases as  $v_c$  increases regardless of CEs, which is also observed by Korkut and Donertas [[23](#page-15-14)]. In diferent cutting speed ranges, the variation trend of cutting force with cutting speed is diferent. The cutting force decreases with the increase of cutting speed for high speed. Because when  $v_c$  increases, the chip flow speed increases, and the friction coefficients of toolchip and tool-workpiece interfaces decrease [\[7](#page-14-6), [17](#page-15-8), [18](#page-15-9)], the temperature in the cutting zone increases, which softens the material and make it easier to be removed  $[18, 23, 24]$  $[18, 23, 24]$  $[18, 23, 24]$  $[18, 23, 24]$  $[18, 23, 24]$  $[18, 23, 24]$ , the chips become thinner and the cutting thickness decreases [\[17,](#page-15-8) [25](#page-15-16)]. However, the cutting speed of this experiment is low enough to produce sufficient cutting temperature to soften the material. Moreover, the built-up edge (BUE) is prone to be induced for low  $v_c$  range, the BUE first reaches a peak followed by a decrease with the increase of  $v_c$  [[23\]](#page-15-14). As the  $v_c$  increases, the built-up edge dissipates and the actual rake angle  $\gamma_0$  decreases, resulting in an increase in cutting force. As shown in Fig. [5b](#page-5-0), for intermediate cutting speed  $(v_c=60 \text{ m/min})$ , the changes of cutting forces of scCO<sub>2</sub>,  $scCO<sub>2</sub>$ -WMQL and  $scCO<sub>2</sub>$ -OoWMQL with respect to dry cutting are  $8.0\%$ ,  $-3.4\%$  and  $-20.8\%$ , respectively, whereas they are 22.8%, 19.7% and  $-10.3%$  respectively for low cutting speed ( $v_c$  = 40 m/min). This means that the application of cooling/lubrication CE increases the cutting force (the reduction in cutting force is reduced for  $\mathrm{scCO_{2}}$ -OoWMQL due to its best lubrication performance), which is precisely because cooling/lubrication CEs inhibit the generation of BUE then reduce the actual rake angle, resulting in a higher cutting force compared to dry cutting.

As shown in Fig. [6a](#page-6-0), for  $f_z = 0.045$  mm/rev,  $v_c = 40$  m/min and  $a_p = 3$  mm, the cutting force increases with radial cutting depth  $a_e$  regardless of CEs. It can be accredited to the increased cutting layer thickness per rotation cycle of tool for higher  $a_e$ . The order of cutting force under different CEs is  $\text{scCO}_2$  > dry >  $\text{scCO}_2$ -WMQL >  $\text{scCO}_2$ -OoWMQL. Correspondingly, the average percentage changes compared to dry cutting are 37.8%, 0, − 0.9%, − 18.8%, − 27.0%, respec-tively. It can be seen from Fig. [6](#page-6-0)b that as  $a_e$  increases, the percentage change in cutting force decreases because the tool-workpiece contact time per rotation cycle increases and the cooling/lubrication efect is reduced.

It can be concluded that under different CEs,  $scCO<sub>2</sub>-$ OoWMQL is the best way to reduce cutting force due to its best cooling/lubrication performance, whereas simply using cryogenic  $CE$  (scCO<sub>2</sub>) will increase the cutting force.  $scCO<sub>2</sub>-$ OoWMQL CE can also promote chip cleaning and inhibit formation of BUE.

#### **3.2 Milling Force Coefficients**

The force diagram of the milling cutter is shown in Fig. [7.](#page-6-1) The total milling force can be decomposed into the plough

 $-v_c=20$ 

 $v_c = 40$ 

 $-v<sub>s</sub>=60$ 

100%

 $\leftarrow$  - Avg.

<span id="page-5-0"></span>**Fig. 5 a** Cutting force vs. cutting speed **b** Percentage changes of cutting force under cooling/ lubrication environments relative to that under dry cutting





<span id="page-6-0"></span>







<span id="page-6-1"></span>**Fig. 7** The force diagram of the milling cutter

force component and the cutting force component. The plough force is generated by the existence of the blunt radius of tool edge and the friction between tool and workpiece, and the cutting force is generated due to shear deformation of the material [[26\]](#page-15-17). The diferential milling forces in the tangential,  $dF_t$ , radial,  $dF_t$ , and axial,  $dF_a$ , directions are shown in Eq.  $(3)$  $(3)$   $[27]$  $[27]$ .

$$
dF_{ij}(\Phi, z) = [K_{te} + K_{tc}h_j(\Phi, z)]dz
$$
  
\n
$$
dF_{rj}(\Phi, z) = [K_{re} + K_{rc}h_j(\Phi, z)]dz
$$
  
\n
$$
dF_{qj}(\Phi, z) = [K_{ae} + K_{ac}h_j(\Phi, z)]dz
$$
\n(3)

where, *Φ* is tool immersion angel, *z* is the axial height of a point of the tooth, j is the tooth number.  $K_{te}$ ,  $K_{re}$  and  $K_{ae}$  are tangential, radial and axial plough force coefficients, respectively, which relate the total cutting force and the ploughing and friction effect of cutting edge.  $K_{\text{tc}}$ ,  $K_{\text{rc}}$ , and  $K_{\text{ac}}$  are the tangential, radial, and axial cutting force coefficients, respectively, which relate the total cutting force and shearing action of the cutting layer [[28\]](#page-15-19).

The milling force components in feed direction  $x, F<sub>x</sub>$ , normal direction *y*,  $F_v$ , axial direction *z*,  $F_z$  can be expressed as a function of  $F_t$ ,  $F_r$  and  $F_a$ .

$$
\begin{pmatrix} F_x \\ F_y \\ F_z \end{pmatrix} = \begin{pmatrix} \cos \Phi & \sin \Phi & 0 \\ -\sin \Phi & \cos \Phi & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} F_t \\ F_r \\ F_a \end{pmatrix}
$$
(4)

The cutting force data of the frst pass is used to calculate the milling force coefficient to avoid the ploughing and friction efect of the tool on the previous machined surface during the second and third passes. According to the method proposed by Budak  $[28]$  $[28]$ , the milling force coefficients are calculated by Eq. [\(5\)](#page-6-3).

<span id="page-6-3"></span>
$$
K_{te} = -\frac{\overline{F}_{xe} \frac{aN}{2\pi} [\sin \phi]_{\phi_{st}}^{\phi_{ex}} + \overline{F}_{ye} \frac{aN}{2\pi} [\cos \phi]_{\phi_{st}}^{\phi_{ex}}}{\left(\frac{aN}{2\pi} [\sin \phi]_{\phi_{st}}^{\phi_{ex}}\right)^{2} + \left(\frac{aN}{2\pi} [\cos \phi]_{\phi_{st}}^{\phi_{ex}}\right)^{2}}
$$
  
\n
$$
K_{tc} = 4 \frac{\overline{F}_{xc} \frac{aN}{2\pi} [\cos 2\phi]_{\phi_{st}}^{\phi_{ex}} + \overline{F}_{yc} \frac{aN}{2\pi} [2\phi - \sin 2\phi]_{\phi_{st}}^{\phi_{ex}}}{\left(\frac{aN}{2\pi} [\cos 2\phi]_{\phi_{st}}^{\phi_{ex}}\right)^{2} + \left(\frac{aN}{2\pi} [2\phi - \sin 2\phi]_{\phi_{st}}^{\phi_{ex}}\right)^{2}}
$$
  
\n
$$
K_{re} = -\frac{K_{te} \frac{aN}{2\pi} [\sin \phi]_{\phi_{st}}^{\phi_{ex}} + \overline{F}_{xe}}{\frac{aN}{2\pi} [\cos \phi]_{\phi_{st}}^{\phi_{ex}}}
$$
  
\n
$$
K_{rc} = \frac{K_{tc} \frac{aN}{2\pi} [\cos 2\phi]_{\phi_{st}}^{\phi_{ex}} - 4\overline{F}_{xc}}{\frac{aN}{2\pi} [2\phi - \sin 2\phi]_{\phi_{st}}^{\phi_{ex}}}
$$
  
\n(5)

<span id="page-6-2"></span>where,  $\Phi_{\text{ex}}$  is the tool cut-out angle,  $\Phi_{\text{st}}$  is the tool cut-in angle, for down milling,  $\Phi_{\text{ex}} = \pi$  and  $\Phi_{\text{st}} = \pi \text{-cos}^{-1}(1 - a_e/\text{R})$ . *a* is axial depth of cut, *N* is the number of teeth.  $F_{xe}$ ,  $F_{ye}$ ,  $F_{xc}$ ,  $F_{xc}$ ,  $F_{yc}$  are the algebraic mean of cutting forces, which can be fitted by Eq. ([6\)](#page-6-4). The correlation coefficients  $R^2$  of the fitting under four CEs are shown in Fig.  $8. R^2$  $8. R^2$  is very close to 1 in each CE, indicating that the ftting results are reliable.

<span id="page-6-4"></span>
$$
\overline{F}_q = \overline{F}_{qe} + f_z \overline{F}_{qc} \quad (q = x, y)
$$
\n(6)



<span id="page-7-0"></span>**Fig. 8** Correlation coefficients  $R^2$  of the fitting

The edge force coefficients and the cutting force coeffcients under four CEs are shown in Fig. [9](#page-7-1)a, b respectively. For edge force coefficients,  $K_{\text{re}}$  is always greater than  $K_{\text{te}}$ regardless of CE, particularly in  $\sec O_2$  CE,  $K_{\text{re}}$  is 350% larger than  $K_{te}$ . This is because the spring-back phenomenon in machining Ti-6Ak-4V is very serious. The rankings of  $K_{te}$  and  $K_{re}$  under different CEs are scCO<sub>2</sub>>dry > scCO<sub>2</sub>- $WMQL > scCO<sub>2</sub>$ -OoWMQL which is identical with the ranking of cutting force (Figs. [4](#page-4-3), [5](#page-5-0) and [6](#page-6-0)), therefore, it can be inferred that ploughing force accounts for a large part of total cutting force.  $K_{te}$  and  $K_{re}$  can represent the friction between the tool-workpiece and the tool-chip interfaces. In  $\mathrm{scCO}_2$ CE,  $K_{te}$  and  $K_{re}$  increases by 31.3% and 113.0%, respectively, compared to those under dry CE, which indicates that the friction between tool and workpiece/chip is deteriorated under  $\sec 0$ , CE during finish-milling of Ti-6Al-4V, and accounts for the increased cutting force under  $\sec 0<sub>2</sub>$  CE compared to dry CE (Figs. [4,](#page-4-3) [5](#page-5-0) and [6\)](#page-6-0). After the addition of lubricants to  $\sec O_2$  jet, the friction is greatly improved. In scCO<sub>2</sub>-OoWMQL CE,  $K_{te}$  and  $K_{re}$  are reduced by  $-49.5\%$ 

and − 39.4%, respectively, relative to those under dry cutting. The reduction of  $K_{te}$  and  $K_{re}$  in scCO<sub>2</sub>-OoWMQL are larger than those in scCO<sub>2</sub>-WMQL ( $-$  42.4% and  $-$  3.6%, respectively), it can be ascribed to fact that the OoW droplet has a higher viscosity than water, and the tool-workpiece interface is easier to form a lubricating flm, which is benefcial to reduce the friction.

It can be seen from Fig. [9b](#page-7-1) that  $K_{\text{rc}}$  is less than  $K_{\text{tc}}$  in the three cooling/lubricating environments, which is different from dry cutting. The tangential cutting force coeffcient does not change much in the cooling/lubrication environment. For scCO<sub>2</sub> CE,  $K_{\text{tc}}$  is slightly increased by 1.8% compared with dry cutting, and only reduced by  $-4.7\%$  and  $-13.2\%$  respectively in scCO<sub>2</sub>-WMQL and  $scCO<sub>2</sub>-OoWMQL$  CEs, which indicates that the effect of cooling/lubrication on shear of cutting layer is not significant. However, the radial cutting force coefficients are greatly reduced by  $-28.5\%$ ,  $-40.5\%$  and  $-43.5\%$  under  $\rm scCO_2$ ,  $\rm scCO_2$ -WMQL and  $\rm scCO_2$ -OoWMQL CEs, respectively, which suggests that the application of cooling/lubrication reduces the spring-back of Ti-6Al-4V in milling process.

#### **3.3 Cutting Temperature**

The average value of the maximum cutting temperature  $\bar{T}_{\text{CE}}$ for diferent CEs is calculated by Eq. [\(7\)](#page-7-2).

<span id="page-7-2"></span>
$$
\overline{T}_{CE} = \frac{1}{n} \sum_{i=1}^{n} \overline{T}_{CE\_i} \tag{7}
$$

where, CE is cutting environment,  $\overline{T_{\text{CE}\_\text{i}}}$  represents the maximum cutting temperature measured under the *i*-th trial in specific CE, and *n* represents the number of tests. The effect of cutting parameters on cutting temperature under diferent CEs is shown in Fig. [10.](#page-8-0)

For  $f_z = 0.045$  mm/rev,  $a_e = 0.3$  mm and  $a_p = 3$  mm, the variation of cutting temperature with  $v_c$  under each CE is

<span id="page-7-1"></span>



<span id="page-8-0"></span>

shown in Fig. [10a](#page-8-0). The cutting temperature increases with increasing  $v_c$  regardless of CEs, because the amount of metal removal per unit time, the work done by tool and the heat generated by shear and friction increase with the increase of  $v_c$ . As shown in Fig. [10](#page-8-0)b, c, the cutting temperature increases with increasing  $f_z$  or  $a_e$  regardless of CEs, the increased material removal and heat generated in the cutting zone for higher  $f<sub>z</sub>$  or  $a<sub>e</sub>$  account for this phenomenon. However, the increase in cutting temperature with the increase in  $f<sub>z</sub>$  or  $a<sub>e</sub>$ is not as significant as  $v_c$ . This can be attributed to the fact that although the heat generation per unit time increases as  $f<sub>z</sub>$  or  $a<sub>e</sub>$  increases, the tool-chip contact length also increases, and the heat dissipation improves. Due to the application of  $\mathrm{scCO}_{2}$  and lubricants, the cutting temperatures under  $scCO<sub>2</sub>-WMQL$  and  $scCO<sub>2</sub>$ -OoWMQL change slower with cutting parameters compared to dry cutting.

As shown in Fig. [10](#page-8-0)d, the cutting temperature under different CEs in descending order is:  $\text{dry} > \text{scCO}_2 > \text{scCO}_2$ - $WMQL > scCO<sub>2</sub>-OoWMQL.$   $scCO<sub>2</sub>$  significantly reduces the cutting temperature, which is 44.4% lower than dry cutting. Four reasons accounts for this: (1) High-pressure high-speed cryogenic  $\sec O_2$  jet realizes forced convection heat transfer. (2) After the  $\sec O_2$  droplets are sprayed into the cutting zone, the droplets undergo vaporization, taking away part of the cutting heat. (3) The use of  $\sec O_2$  jet can promote chip evacuation, thereby promoting the release of cutting heat from chips. (4)  $\sec O_2$  jet can even cause chip breaking or chip lifting, reducing contact length between chip and rake face, thereby reducing friction heat.

By adding a minimum quantity of lubricant to  $\text{scCO}_2$ , the cutting temperature is further reduced. As shown in Fig. [10](#page-8-0)d, the cutting temperatures in the  $\mathrm{scCO}_2$ -WMQL and  $scCO<sub>2</sub>-$ OoWMQL are further reduced by 37.9% and 49.3%, respectively, relative to the temperature in the  $\sec O_2$  environment. This is because the lubricants in  $\text{scCO}_2\text{-}WMQL$ and  $\text{scCO}_2$ -OoWMQL CEs reduce the friction coefficients between tool-chip and tool-workpiece interfaces, resulting in lower cutting force then friction heat, and the vaporization of the lubricant particles also carry away a part of the heat.  $scCO<sub>2</sub>-$ OoWMQL shows better performance with regard to cutting temperature than  $\text{scCO}_2\text{-}WMQL$ , this can be accredited to the higher viscosity of OoW particles than that of water molecules, making it easier to form a lubricating flm in the cutting zone.

#### <span id="page-8-2"></span>**3.4 Surface Roughness**

The average value of the surface roughness  $\overline{Ra}_{CE}$  for different CEs is calculated by Eq. ([8\)](#page-8-1).

$$
\overline{Ra}_{ce} = \frac{1}{n} \sum_{i=1}^{n} \overline{Ra}_{ce,i} \tag{8}
$$

where,  $\overline{Ra_{\text{CE}\_i}}$  represents the surface roughness measured under the *i*-th trial in specific CE. The effect of cutting parameters on surface roughness under diferent CEs is shown in Fig. [11.](#page-9-0)

<span id="page-8-1"></span>her Kant

<span id="page-9-0"></span>**Fig. 11** Surface roughness vs. **a** cutting speed **b** feed rate **c** radial depth of cut **d** cutting environments



As shown in Fig. [11a](#page-9-0), for  $f_z = 0.045$  mm/rev,  $a_e = 0.3$  mm and  $a_p = 3$  mm, the surface roughness increases with increasing  $v_c$  regardless of CEs, this is because the cutting force and the cutting temperature also increase for higher cutting speed, resulting in worse surface quality. It can be found from Fig. [11a](#page-9-0) that when the cutting speed is  $v_c = 60$  m/min, the surface roughness is 2.22 μm and 3.28 μm in dry and  $\sec CO_2$  CEs, respectively, which is much larger than that in the  $\sec O_2$ -WMQL and  $\sec O_2$ -OoWMQL CEs (0.95 µm and 0.65 μm, respectively). Observation of the machined surface shows that beat vibration of tool occurs, which will be discussed in more detail in Sect. [3.4.](#page-8-2) As shown in Fig. [11b](#page-9-0), for  $v_c$ =40 m/min,  $a_e$ =0.3 mm and  $a_p$ =3 mm, the surface roughness increases with feed rate regardless of CEs, which can be attributed to the higher theoretical residual contour for the increased feed rate. As shown in Fig. [11c](#page-9-0), radial depth of cut has little effect on surface roughness, which is also observed by Mia et al. [[13](#page-15-4)].

There is a certain error in measuring the surface roughness using the probe type roughness measuring instrument, and the surface roughness diference is small under diferent CEs during fnish-milling process. So the average surface roughness of nine experiments under each CEs will be used to compare the infuence of CE on surface roughness. As shown in Fig. [11d](#page-9-0), the surface roughness  $R_a$  is in the range of 0.55–1.0 μm,  $R<sub>a</sub>$  under different CEs in descending order is  $scCO_2$  > dry >  $scCO_2$ -WMQL >  $scCO_2$ -OoWMQL, which is consistent with ranking of the edge force coefficients under four CEs (Fig. [9a](#page-7-1)). This indicates that friction property is a direct factor affecting  $R_a$  in different CEs. Surprisingly, although  $\sec O_2$  jet promotes chip evacuation and cleans chippings on the tool and machined surface,  $R_a$  of  $\rm{scCO}$ , CE is still 22% greater than that of dry cutting. This is because the edge force coefficients of  $\mathrm{scCO}_2$  are the largest, which indicates that the friction between tool and workpiece deteriorates.  $R_a$  in scCO<sub>2</sub>-WMQL and scCO<sub>2</sub>-OoWMQL CEs is less than that in  $\sec O_2$  CE, because water molecules and OoW particles improve the lubrication of toolworkpiece interface. The better lubrication performance of OoW particle is accredited with the better surface fnish of  $\text{scCO}_2$ -OoWMQL than that of  $\text{scCO}_2$ -WMQL.

## **3.5 Beat Vibration**

When  $v_c = 60$  m/min,  $f_z = 0.045$  mm/r,  $a_e = 0.3$  mm (Experiment No. 3), the machined surface topography of four CEs is shown in Fig. [12](#page-10-0) (The machined surface magnifed 20 times is in the left side and that of the third tool path magnifed 200 times is in the right side). The surface waviness caused by tool vibration is clearly observed in dry and  $\sec O_2$  CEs, but not found in  $\text{scCO}_2$ -WMQL and  $\text{scCO}_2$ -OoWMQL CEs. The direction of the surface waviness is along the tool axis, perpendicular to the feed direction. The direction of the surface waviness is consistent after three passes of tool, which indicates that the defection and vibration of tool are most severe during the third pass of tool, covering the ripples generated during the frst and second passes. Only abrasive sliding grooves parallel to the direction of cutting speed and



<span id="page-10-0"></span>**Fig. 12** Machined surface topography of experiment No. 3  $\bf{a}$  dry  $\bf{b}$  scCO<sub>2</sub>  $\bf{c}$  scCO<sub>2</sub>-WMQL  $\bf{d}$  scCO<sub>2</sub>-OoWMQL



feed marks are observed on the machined surfaces under  $scCO_2$ -WMQL and  $scCO_2$ -OoWMQL CEs.

The machined surface profle and its spectrum of the third tool pass of experiment No. 3 are shown in Fig. [13.](#page-11-0) When only the relative motion of tool and workpiece is considered, the machined surface topography is only a copy of the tool geometry. Theoretically, the distance between adjacent peaks of surface profile is  $f_z = 45 \mu m$ ,



<span id="page-11-0"></span>**Fig. 13** Machined surface profile and its spectrum of experiment No. 3 **a** dry **b** scCO<sub>2</sub> **c** scCO<sub>2</sub>-WMQL **d** scCO<sub>2</sub>-OoWMQL

however, the mean width of the profle elements *RSm* under four CEs is greater than  $f_z$ , which is 935, 809, 202.5 and 158.4 μm, respectively. This is because the tool-workpiece system will vibrate during milling process, which has a much greater efect on the surface topography than the efect of feed on that. *RSm* under diferent CEs in descending order is  $\text{dry} > \text{scCO}_2 > \text{scCO}_2$ -WMQL $> \text{scCO}_2$ -OoW-MQL, which is identical with the order of cutting force (Fig. [5](#page-5-0)a), indicating that cutting force has a great infuence on surface morphology. The *RSm* values of scCO<sub>2</sub>-WMQL and  $\sec O_2$ -OoWMQL are 202.5 and 158.4  $\mu$ m, respectively, which are approximately four times of  $f<sub>z</sub>$ , namely the feed length in a tool rotation cycle. The manufacturing error or radial run-out of the tool is accredited with this phenomenon. However, under dry and  $\sec O_2$  CEs, the *RSm* values are 935 and 809 μm respectively, which are approximately 20 times of  $f_z$ , indicating that the tool is signifcantly vibrating during milling process.

The vibration of tool under dry and  $\sec O_2$  CEs can be confrmed from the spectrum of surface profle in the spatial frequency domain, which is obtained by the Fast Fourier Transform (FFT) and shown in Fig. [13](#page-11-0). Theoretically, the spectrum of machined surface profle in the spatial frequency domain consists of the tooth passing frequency  $s_{\text{tn}}$  due to feed and the spindle frequency  $s_{\text{sn}}$  due to manufacturing error or radial run-out of tool. According to the octave property, the spectrum will appear at the fundamental frequency and its integer multiple, as shown in Eq. ([9](#page-12-0)).

$$
\begin{cases}\ns_{tp} = \frac{k}{f_z}, & k = 1, 2, 3.... \\
s_{sp} = \frac{k}{z f_z}, & k = 1, 2, 3....\n\end{cases}
$$
\n(9)

where, *z* is the number of teeth, in this experiment  $z = 4$ . *k* is a positive integer, which represents the fundamental frequency when  $k = 1$ , and represents the frequency multiplication when  $k = 2, 3, 4...$  When  $v_c = 60$  m/min,  $f<sub>z</sub>=0.045$  mm/r,  $a<sub>e</sub>=0.3$  mm (Experiment No. 3), the fundamental frequency of  $s_{tp}$  and  $s_{sp}$  in the spatial domain are 22.2 mm<sup>-1</sup> and 5.55 mm<sup>-1</sup>, respectively.

In accordance with expectations, the tooth passing frequency  $s_{\text{tp}}$  and spindle frequency  $s_{\text{sp}}$  in spatial domain are not observed in the spectrum of dry and  $\sec O_2$  CEs due to tool vibration. The spectrum of surface profle moves to low frequency band obviously in dry and  $\sec O<sub>2</sub>$  CEs compared with that in  $\text{scCO}_2\text{-}WMQL$  and  $\text{scCO}_2\text{-}OoWMQL$ CEs, which means an increase in the peak-to-peak distance of the surface profle. The main frequency of surface profile in the  $\text{scCO}_2$ -WMQL and  $\text{scCO}_2$ -OoWMQL environments is only close to  $s_{sp}$  (5.55 mm<sup>-1</sup>), which is 4.75 mm<sup> $-1$ </sup> and 7 mm<sup> $-1$ </sup>, respectively. This phenomenon may be ascribed to lateral fow of materials during milling process, Nieslony et al. [[29](#page-15-20)] pointed out that it may also be due to errors of probe surface proflometer.

The tooth pass frequency  $f_{\text{tp}}$  and spindle frequency  $f_{\text{sp}}$  in the time domain are calculated by Eq.  $(10)$  $(10)$ .

<span id="page-12-1"></span>
$$
\begin{cases}\nf_{\mathbf{tp}} = \frac{knz}{60}, & k = 1, 2, 3.... \\
f_{\mathbf{sp}} = \frac{kn}{60_z}, & k = 1, 2, 3....\n\end{cases}
$$
\n(10)

where *n* is spindle speed in r/min, which is calculated by Eq.  $(11)$ . Under experiment No. 3,  $n = 3183$ r/min and  $f_{\text{tn}}$ =212.21 Hz are obtained.

<span id="page-12-2"></span>
$$
v_c = \frac{\pi dn}{1000} \tag{11}
$$

When the vibration frequency  $f_c$  of the tool in the time domain is less than  $f_{\text{tp}}/2$ , vibration waviness will be generated on machined surfaces [\[30](#page-15-21)].

$$
y_t(x) = \sum_{n=0}^{\infty} a_n(A) \sin\left(2\pi n \frac{f_c}{f_s f_{\mathbf{p}}} x\right)
$$
 (12)

where, *A* is the vibration amplitude of the tool in normal direction,  $f_c/(f_r * f_{\text{tn}})$  is the fundamental frequency of machined surface profle in spatial domain. Therefore, it can be determined that the vibration frequency  $f_c$  of tool is 11.94 Hz in dry and  $\sec O_2$  CEs, as shown in Eq. [\(13](#page-12-3)).

<span id="page-12-3"></span>
$$
f_c = f_z f_{tp} \times 1.25 = 11.94 Hz \tag{13}
$$

<span id="page-12-0"></span>The octave of machined surface spectrum under  $\sec 0<sub>2</sub>$ CE proves that tool vibration does occur, although the machine surface spectrum of dry CE does not exhibit octave property, which is because chips scratch or adhere to the machined surface due to bad chip evacuation performance of dry CE, causing the waviness generated by tool vibration to be destroyed.

In order to analyse the cause of surface waviness of dry and  $\sec O_2$  CEs under experiment No. 3 ( $v_c$ =60 m/min,  $f<sub>z</sub>=0.045$  mm/r,  $a<sub>e</sub>=0.3$  mm), it is necessary to investigate the milling force characteristics. For experiment No. 3, the dynamic milling force in normal direction  $(F_v)$  and its envelops varying with cutting length under each CE is shown in Fig. [14.](#page-13-0) The spectrums of  $F<sub>v</sub>$  and its upper envelop are also obtained by FFT as shown in Fig. [14](#page-13-0). Under dry and  $\sec O_2$ CEs, the amplitude of  $F_y$  varies periodically and slowly with cutting length (the upper and lower envelopes of  $F<sub>v</sub>$  are shown in the fgure), as if the amplitude of high-frequency tooth passing signal is modulated by the low-frequency carrier signal, which indicates that the beat vibration of toolworkpiece system occurs during milling process. Beat vibration occurs when there are two sources of vibration at closely spaced frequencies and amplitudes, which can be verifed by



<span id="page-13-0"></span>**Fig. 14** Dynamic milling force in normal direction and its spectrum of experiment No. 3 **a** dry **b** scCO<sub>2</sub> **c** scCO<sub>2</sub>-WMQL **d** scCO<sub>2</sub>-OoWMQL

observing the spectrum of  $F_v$ . As shown in Fig. [14](#page-13-0)a, b, an excitation signal ( $s_w$  = 20.72 mm<sup>-1</sup>) near the tooth passing frequency  $(s_{\text{tp}} = 22.22^{-1})$  appears under dry and scCO<sub>2</sub> CEs, which is the cause of beat vibration. The distance between two adjacent beats of cutting force is approximately equal to the mean width of the profle elements *RSm* (Fig. [13a](#page-11-0), b). The fundamental frequency (in spatial frequency domain) of upper envelope of cutting force that is also called beat frequency is  $1.50 \text{ mm}^{-1}$ , which is approximately equal to that of machined surface profle (Fig. [13a](#page-11-0), b). No beat vibration occurs in milling process under  $\text{scCO}_2\text{-}WMQL$ and  $\sec O_2$ -OoWMQL CEs, spectrum of  $F_v$  has only two distinct tooth passing frequency  $s_{\text{tp}}$  (22.22 mm<sup>-1</sup>) and spindle frequency  $s_{\rm sn}$  (5.49 mm<sup>-1</sup>). The distance between two adjacent peaks of the milling force envelope is  $4f<sub>z</sub>$ , and the fundamental frequency of upper envelope is equal to  $s_{\rm sn}$ , which is caused by radial run-out of tool.

# **4 Conclusion**

The present article investigates the cutting force and its coefficients, cutting temperature, surface roughness, surface morphology and beat vibration phenomenon in peripheral milling of Ti-6Al-4V under various cutting parameters and four green CEs (dry,  $\text{scCO}_2$ ,  $\text{scCO}_2$ -wCMQL,  $scCO<sub>2</sub>-OoWCMQL$ ). The following conclusions are drawn from this study:

- (1) Cutting force increases by 273.6% on average with  $v_c$  increasing from 20 to 60 m/min regardless of CEs due to formation of BUE. The lowest cutting force is obtained under  $\sec O_2$ -OoWCMQL CE owing to its excellent cooling/lubrication, chip evacuation, chip reduction and tool-chip contact length reducing efect. Cutting force increases by  $8-64\%$  under  $\sec O_2$  because of the increased strength and hardness of material and deteriorated friction of tool-workpiece interface.
- (2) The maximum and minimum edge force coefficients  $K_{\text{te}}$ and  $K_{\text{re}}$  are obtained for  $\text{scCO}_2$ -OoWMQL and  $\text{scCO}_2$ , respectively. OoW droplets in cryogenic  $\mathrm{scCO}_2$  significantly improve the friction of tool-workpiece interface, whereas only applying  $\sec O_2$  without lubricants will worsen friction. CE has a marginal effect on  $K_{\text{tc}}$ , which means that the cooling/lubrication environment does not change the shearing of cutting layer.  $K_{\text{rc}}$  is reduced under  $\sec O_2$ -WMQL and  $\sec O_2$ -OoWMQL CEs, indicting the spring-back of material is inhibited
- (3) Lowest cutting temperature and best surface fnish are obtained under  $\text{scCO}_2$ -OoWCMQL CE owing to the forced convection heat transfer, vaporization, chip evacuation promoting of  $\sec O_2$  and lubrication of OoW particles. Cutting temperature increases with  $v_c$ ,

 $f_z$  and  $a_e$ . Surface roughness increase with  $v_c$  and  $f_z$ ,  $a_e$ shows little infuence on it.

- (4) For  $v_c = 60$  m/min,  $f_z = 0.045$  mm/r,  $a_e = 0.3$  mm, beat vibration occurs under dry and  $\sec O_2$ , vibration waviness is left on the machined surface, the radial vibration frequency of tool is 11.94 Hz. The fundamental frequency of machined surface profle is equal to that of cutting force envelope (beat frequency,  $1.5 \text{ mm}^{-1}$ ), indicting cutting force directly affects surface topography.  $\sec O_2$ -WMQL and  $\sec O_2$ -OoWMQL CEs can improve milling stability.
- (5) From the aspects of cutting force, cutting temperature, surface quality, milling stability and cleaner production, the optimum CE for peripheral finish-milling Ti-6Al-4V is  $\text{scCO}_2$ -OoWMQL.

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# **Compliance with Ethical Standards**

**Conflict of interest** No confict of interest exists for all participating authors.

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**Chongyan Cai** is a Ph.D. candidate in Shanghai Jiao Tong University. His main direction of scientifc activity is modelling and improvement of manufacturing processes. His current research interests include green manufacturing, surface engineering and surface morphology modelling in high-speed machining of aerospace difficult-to-cut materials such as titanium alloy and carbon fibre reinforced plastics.



**Xu Liang** is a master degree candidate in Shanghai Jiao Tong University. He studies cutting and process technology through experiments and numerical methods. In addition, he focuses on green cutting technology such as supercritical  $CO<sub>2</sub>$ , oils on water (OoW) and minimum quantity lubrication (MQL).



**Qinglong An** is an associate professor in Shanghai Jiao Tong University. He received his doctorate from the Nanjing University of Aeronautics and Astronautics. His research interests mainly include the high-efficiency machining of carbon fbre reinforced plastics, high-speed cutting/high-efficiency grinding theory and application, green manufacturing of the difficult-tocut materials. He has published many academic papers in the peer-reviewed journals as the first or corresponding author,

such as IJMTM, ASME-JMSE, IJPEM, Composite Structures, etc. He ever won the second prize of National Scientifc and Technological Progress Award (3/10) in 2017.



**Zhengrui Tao** is currently pursuing an M.Sc. in Mechanical Engineering at the Shanghai Jiao Tong University. He researched on data-driven intelligent predictive maintenance, with a focus on diagnosis, prognostics, and remaining useful life prediction. Most recently, he has been working on the virtual machining system focusing on chatter stability analysis and feed rate optimization. He ever was rewarded as the National scholarship for Graduates.



**Weiwei Ming** is an assistant research fellow in Shanghai Jiao Tong University. He received Ph.D. from the same university. His current research interests include high-efficiency machining of aerospace difficult-to-cut materials and big data technology.



ciency grinding theory and application, green manufacturing of the difficult-to-cut materials. He ever won the second prize of National Scientifc and Technological Progress Award of China (1/10) in 2017.

**Ming Chen** is a Professor, Director of Institute of Manufacturing Technology and Equipment Automation, Shanghai Jiao Tong University. He has published about 300 scientifc papers and 8 books. He is a member of the International Abrasive Technology Committee, and he is also an

editorial board member of some of the well-known journals. His research interests mainly include the high-efficiency machining of carbon fbre reinforced plastics, high-speed cutting/high-effi-