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Aerodynamic improved design and optimization for the rear stage of a High‑load axial compressor

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Abstract

This paper proposes and discusses the aerodynamic retroft design schemes for a multistage high pressure axial compressor. A high hub/tip ratio mixed-fow compressor is designed and analyzed to replace the rear stage of the axial compressor. In order to minimize the axial dimension and maximize the load capacity, three unconventional types of combined compressors equipped with the high hub/tip ratio mixed-fow compressor are explored. Further, the efects of blade number, splitter blades and dimensionless geometric parameters on the mixed-fow compressor performance are investigated by an improved loss model. A full-surface parameterization control method is introduced and adopted for blade optimizations of the mixed-fow impeller and the tandem stator. The results indicate that after aerodynamic improved design and optimization, the total pressure ratio is relatively improved by 3.71% and the adiabatic efficiency is improved by 0.95 percent point for the mixed-flow compressor at the near design point. Based on this, the retroft schemes for the axial compressor are benefcial to improve the load capacity and reduce the axial dimension with a slight impact on efficiency and surge margin. These show the potential application prospects of high hub/tip ratio mixed-fow compressors.

Keywords Axial compressor · Mixed-fow compressor · Hub/tip ratio · Retroft design · Full-surface parameterization · Optimization

Abbreviations

- AR Aspect ratio
- HR Hub/tip ratio
- LE Leading edge
- Opt Optimal
- Ori Original
- PS Pressure side

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- SS Suction side
- TE Trailing edge

1 Introduction

At present, high load, high efficiency, wide operating range and dimension minimization are the goals of advanced high pressure compressor designs. In high pressure multistage axial compressors with small and medium dimensions, blades of rear stages are usually very short and thin. Thus, problems of insufficient compression work capacity, low efficiency and difficult machining may appear in axial compressor rear stages. In the condition that the axial compressor load has reached its limit, one of the common retroft solutions is the axial-centrifugal compressor in which the rear axial stages are replaced with a centrifugal compressor. Both the load capacity of rear stages and the overall surge margin can be improved. However, a large flow path turning is usually inevitable to turn outlet radial channel into axial channel in order to connect the combustion chamber inlet in a centrifugal compressor designed for aero-engines. The radial dimension is increased, and the fow capacity is

weakened. Hence, the axial-centrifugal compressor scheme may not meet the design requirements for a high pressure compressor with a limited radial dimension, an axial outlet channel and larger fow rate.

The mixed-fow compressor works with a higher mass flow and a higher efficiency than centrifugal compressors. Meanwhile, it has a higher load capacity: than axial compressors. This type of machine possesses advantages of both axial and centrifugal compressors. At present, one of hot researches for combined compressors in small and medium-sized aero-engines is designing high-performance mixed-fow compressors to replace axial or centrifugal compressor stages. Mixed-fow stages were adopted to replace front stages of multistage compressors in most compressor modifcation design processes according to previous researches. One of retroft compressor confgurations is the mixed-fow-co-centrifugal compressor that can replace axial-centrifugal or twin-stage centrifugal compressors in turboshaft engines $[1-3]$ $[1-3]$. The compressor axial dimension can be reduced, but the fow capacity is still weak on account of the complex fow path structure. The other confguration is the mixed-fow-co-axial compressor. The mixed-fow stage is connected to the axial-fow stage forepart [[4](#page-19-2), [5](#page-19-3)]. This kind of configuration has higher flow capacity and simpler fow path structure. However, larger hub radial dimensions of rear axial stages are adverse to the structure weight reduction.

The axial-co-mixed-fow compressor is an unconventional compressor confguration, in which a mixed-fow compressor stage is adopted to replace the axial compressor rear stages. The load capacity can be improved, and the axial dimension can be reduced compared with that of the multistage axial compressors. On the other hand, the axialco-mixed-fow compressor possesses higher fow capacity, smaller radial dimension and smoother fow path than axial-centrifugal compressors. In order to minimize the axial length, the fow path transition section between the front axial stages and the fnal mixed-fow stage in this kind of compressor is extremely short or even negligible. Thus, the corresponding mixed-fow impeller usually has a high inlet hub/tip ratio and a low aspect ratio.

Some researchers have investigated the structure particularities of high hub/tip ratio centrifugal compressors. Groh et al. [\[6](#page-19-4)] presented the design and test results of an unusual high hub/tip ratio centrifugal compressor with a pressure ratio of 2.0. It was designed as a substitute of the last stages of a multistage axial compressor. Rodgers and Brown [[7\]](#page-19-5) summarized and compared various existing high hub/tip ratio centrifugal compressor designs. Sun [[8](#page-19-6)] illustrated special considerations for the aerodynamic designs of high inlet hub ratio centrifugal compressors. Long and Wang [\[9\]](#page-19-7) analyzed and improved a high hub/tip ratio centrifugal compressor as a retroft design for a common centrifugal compressor. In general, adopting a high hub/tip ratio centrifugal compressor design to an axial-centrifugal compressor is conducive to the structure compaction and the performance improvement of the axial compressor stage. However, relative Mach number at the centrifugal compressor stage inlet rises with increasing hub/tip ratio, which may increase the impeller difusion load and afect the centrifugal stage efficiency. $[11]$ Hence, the high hub/tip ratio impeller confguration is a kind of compromise design in comprehensive consideration of overall dimensions and performance of each stage. It is applicable to the aerodynamic design schemes for the combined compressors with specifc performance indexes and dimensional limit. Further, the high hub/tip ratio mixed-fow compressor confgurations are more unconventional and there are few relevant researches on detailed designs and analyses for now. The only similar research on this compressor type is a mixed-fow compressor with a high inlet hub/tip ratio of 0.686 and a low aspect ratio proposed by Musgrave and Plehn [[10\]](#page-19-9) in 1987. Two types of mixedflow compressors, respectively, investigated by Huang et al. [[11\]](#page-19-8), and Liu and Yu [\[12](#page-19-10)] were also adopted to connect the axial compressor stages outlet. However, the hub/tip ratios of the two compressors are relatively low so that the structure particularities are not obvious. In consideration of the special geometric features of high hub/tip ratio mixed-fow impellers, usual radial impeller design experience such as the performance prediction models and the selection methods of blade number and splitter blade length may be unsuitable. Hence, design criterions and aerodynamic optimizations are necessary to be improved and performed to achieve higher performances.

In this research, targeting the load capacity improvement and the axial dimension reduction, the aerodynamic retrofit design schemes for a four-stage high-load axial compressor are compared and screened. The high hub/tip ratio mixed-fow compressor is the decisive part in the retroft design process. The optimal blade number and splitter blade length of the mixed-fow impeller are selected based on an improved loss model. A full-surface parameterization control method and the multi-island genetic algorithm are applied to blade optimizations for the mixed-fow compressor. The performance of the axial-co-mixed-fow compressor (as the principal retroft design) is numerically simulated and analyzed. In addition, in order to further reduce the axial dimension and improve the load capacity, the preliminary designs of a twin-stage mixed-fow compressor and a twinstage counter-rotating mixed-fow compressor, respectively, equipped with the high hub/tip ratio mixed-fow compressor are also proposed and explored.

Fig. 1 Comparisons among various retroft design schemes and the original design

Table 1 Design index parameters

Parameters	Unit	Value
Inlet total temperature	K	288.15
Inlet total pressure	Pa	101325
Mass flow rate	kg/s	18
Total pressure ratio		6.3
Rotate speed	rpm	14500
Outlet absolute Mach number		< 0.3
Overall axial length	m	< 0.3
Radial dimension		Least possible
Inlet and outlet flow direction		Axial

2 Discussion on retroft design schemes

The original high pressure compressor is a four-stage axial compressor (A-A-A-A) with an average stage pressure ratio of 1.585, as shown in Fig. [1.](#page-2-0) According to the design index parameters presented in Table [1](#page-2-1), the axial and radial dimensions are limited to reduce the structure weight. The direction and magnitude of the outlet velocity are also limited. Reducing stage number is the most efective way to meet the requirements for the axial dimension since the rotate speed is relatively low for high pressure compressors and there is a high demand for the stage load capacity. Five novel types of flow path retrofit configurations are conceived to reduce the stage number and raise the average stage load:

•axial-co-mixed-fow-co-axial compressor (A-M-A)

•mixed-fow-co-axial compressor (M-A-A) •twin-stage mixed-fow compressor (M-M) •twin-stage counter-rotating mixed-flow compressor (M-CR-M)

Figure [1](#page-2-0) shows the flow path configurations and the axial dimensions of various design schemes. Stage loading levels of each scheme are evaluated based on Smith diagram and Cordier line, respectively, as shown in Figs. [2](#page-2-2) and [3.](#page-3-0)

Figure [2](#page-2-2) locates the efficiency zone positions of each stage in the axial compressor Smith diagram given by Hall [\[13](#page-19-11)]. Based on this load evaluation criterion, the third stage of A-A-M has very high Ψ and its location is beyond the efficiency border. It means the third stage has a weak flow capacity and a high load which a single axial compressor stage can hardly achieved. It is suitable to apply the mixed-fow compressor stage in the third stage to raise the load. Ψ and ϕ for Smith diagram are calculated by Equation [\(1](#page-2-3)).

$$
\Psi = \Delta H / U_1^2 \quad \phi = 4Q_1 / \pi D_1^2 U_1 \tag{1}
$$

However, Smith diagram is just appropriate for the axial turbomachinery. It can be only used as a reference for load evaluation of the mixed-fow compressor, while Balje line or Cordier line is normally adopted for the load evaluation and selection of the radial compressors. Figure [3](#page-3-0) shows the load levels of the mixed-fow compressor stages of each retroft confguration in a modifed Cordier diagram given by Casey [\[14\]](#page-19-12). The locations of the axial compressor stages are also presented. Apparently, the modifed Cordier diagram is applicable to the mixed-fow compressors rather than the axial

Fig. 2 Load locations of each stage of A-A-A-A and A-A-M in axial compressor Smith diagram; contour increment: 1%, peak contour: 95%

[•]axial-co-mixed-fow compressor (A-A-M)

Table 2 Main geometric parameter comparisons of the retroft confgurations and the original design

compressors. The load levels of the axial compressor stages are out of the efficient boundary. Definitions of Ψ and $φ$ for the Cordier line are diferent from that for Smith diagram, as described by Equation ([2\)](#page-3-1).

$$
\Psi = \Delta H / U_1^2 \quad \phi = 4Q_1 / \pi D_1^2 U_1 \tag{2}
$$

Considering the inlet flow path connection and the outlet dimensions of the mixed-fow stage, the load position can hardly reach the best efficiency line in the condition of the design index. The location of the high hub/tip ratio mixed-fow compressor in A-A-M is the closest to the peak efficiency zone among the mixed-flow stages of all the schemes. Ψ of the mixed-flow compressor at the last stage locates at a relatively low level, which indicates the mixedflow compressor possesses greater load-carrying potential. Hence, using mixed-fow compressors to decrease the stage number is an applicable solution for the retroft designs of multistage axial compressors. As demonstrated in Fig. [1,](#page-2-0) M-A-A has a larger axial length and the rear two axial compressor stages with extremely high hub/tip ratios can hardly

achieve the required efficiency and pressure ratio, while the middle mixed-fow stage of A-M-A has more serious interstage matching problems with the front and rear axial stages. Thus, this research only discusses A-A-M, M-M and M-CR-M. Main geometric parameters of the three modifcations and the original compressor are compared in Table [2](#page-3-2). The axial length is defned as the distance from the leading edge at the hub of the frst rotor to the trailing edge at the hub of the last stator. Although the rear radial dimension enlarges, reductions of the axial and inlet radial dimensions as well as the row number are signifcant.

Two types of twin-stage mixed-fow compressors (M-M and M-CR-M) are also proposed to further explore the application of the high hub/tip ratio mixed-fow compressor. Based on the same design index presented in Table [1](#page-2-1), the axial dimension needs to be least possible. The twin-stage mixed-fow compressor with no return channel is a novel combined compressor type which has a smoother fow path and a lower axial length. The second stage is the high hub/tip ratio mixed-fow compressor studied in this research. Both inlet and outlet fow directions are axial.

The current study only presents two preliminary design results for twin-stage mixed-fow compressors, as contrasts to A-A-M. The geometries of A-A-M, M-M and M-CR-M are shown and compared in Table [2](#page-3-2) and Fig. [4.](#page-4-0) Their performances at $1.0R_n$, $0.9R_n$ and $0.8R_n$ are simulated by CFD software NUMECA. As presented in Fig. [5](#page-4-1), only A-A-M can work stably at low rotate speeds for now. Obviously, the surge margins of M-M and M-CR-M are lower than that of A-A-M. There is a performance gap between M-M and A-A-M, while M-CR-M has much poorer performance. The main cause of performance degradation is the interstage matching problem between the front and the rear stages in twin-stage mixed-fow compressors. Nonetheless, the structures with no return channel of the three novel combined compressors are all benefcial for the reduction in dimension and cost, which

Fig. 4 3D geometries of the three kinds of combined compressor confgurations with no return channel: **a** axial-co-mixed-fow compressor, **b** twin-stage mixed-fow compressor, **c** twin-stage counter-rotating mixed-fow compressor

Fig. 5 CFD simulated performance comparisons of the three combined compressor confgurations: **a** total pressure ratio, **b** adiabatic efciency

shows the potential application prospects of high hub/tip ratio mixed-fow compressors.

For A-A-M, in order to take the furthest advantage of high flow capacity and high efficiency of the axial compressors, the axial compressor confguration is used in the front two stages which have better flow conditions. The IGV and the rotor of the frst stage remain unchanged. The hub line rises from the stator inlet of the frst stage, as demonstrated in Fig. [1.](#page-2-0) The loss caused by the mixed-fow confguration in the final stage can be offset. On the other hand, the mixedflow stage strengthens the compression work capacity and has a wide stable operating scope to cope with a worse flow

condition. Hence, A-A-M can improve the compressor load capacity with slight impact on the efficiency and the surge margin. Beyond that, A-A-M has a simpler flow path structure and moderate axial and radial sizes. It is benefcial to reduce the cost of structure dimension and manufacture. Above all, A-A-M is selected to be the principal retroft scheme.

Increasing the outlet diameter can reduce Ψ, but *𝜙* declines more quickly. Conversely, decreasing the outlet diameter can increase ϕ and benefit the through flow. However, the centrifugal force does less work and Ψ raises. It is easier to cause the insufficient compression work and the flow separation. The mutual contradiction enhances the design difficulties of the high hub/tip ratio mixed-flow compressor. Advanced design methods and comprehensive **Table 3** The mixed-fow impeller design parameters (mean streamline)

*means the total parameter

considerations of various factors are needed to achieve the performance requirements.

3 Improved design and optimization for the high hub/tip ratio Mixed‑fow compressor

3.1 Analysis of Mixed‑fow impeller dimensionless parameter

Table [3](#page-5-0) presents the design parameters of the mixedfow impeller without splitter blades. Detailed geometric descriptions are demonstrated in Fig. [6,](#page-5-1) including the meridional fow path, the blade chord length estimation and the defnition of blade height/pitch ratio in cascades.

In this study, the dimensionless splitter blade length is defned as the length ratio of splitter blade and principal blade, as formulated by Equation (3) (3) .

$$
\zeta = L_{\rm s}/L_{\rm B} \tag{3}
$$

An improved loss model [[15](#page-19-13)] that introduces blade number (Z) and dimensionless splitter blade length (ζ) is applied to select the optimal blade number and the optimal splitter blade length for the minimum head loss of the mixed-fow impeller. In the improved model, the splittered impeller is assumed to be divided into two tandem normal impellers: "1-S" and "S-2" to utilize existing normal impeller performance prediction models, as illuminated in Fig. [6.](#page-5-1) "S" means the splitter blade inlet. "S-1" is a no-splittered section with truncated principal blades, and "S-2" contains double splitter blades. The loss model modifcation for the splittered impellers refers to

Fig. 6 Geometric parameters of the mixed-fow impeller

the performance prediction models proposed by Aungier [[16](#page-19-14)] in consideration of incidence, skin friction, loading, clearance leakage and wake mixing. Krain impeller was adopted for model verifcation. The optimum blade number and splitter blade length are studied at the design fow rate. Detailed description of the improved loss model can be referred in Reference [[15](#page-19-13)].

At present, the defnition of the mixed-fow compressor impeller is broad and vague. Case (a) [\[17\]](#page-19-15) and Case (b) [[18\]](#page-19-16) presented in Fig. [7](#page-6-0) can be both seen as mixed-fow confgurations ('mixed-fow compressor' was what they were called by the authors in their papers). However, the former is more similar to the axial compressor, while the latter is more similar to the centrifugal compressor. The blade profles of these two cases also indicate that Case (a) was designed with axial compressor design methods, while Case (b) was designed with centrifugal compressor design methods. Hence, the magnitude of fow path lean angle and the diference of inlet and outlet diameters determine the design reference for the mixed-fow impellers.

There have been several previous mixed-fow compressor design researches [[19,](#page-19-17) [20](#page-19-18)] that adopted the centrifugal compressor design methods and experience. These mixed-fow impellers were seen as the centrifugal impeller modifcations. This research object can also be treated as a centrifugal impeller retroft design, as shown in Fig. [7](#page-6-0) (c). Centrifugal impeller design methods are more suitable for this research object since the diference of inlet and outlet diameters and **Fig. 7** Various mixed-fow impeller cases: **a** confguration similar to axial rotors [[17](#page-19-15)], **b** configuration similar to centrifugal impellers [\[18\]](#page-19-16), **c** this research object as a retroft design for centrifugal impeller

Fig. 8 Adiabatic efficiency distributions with respect to principal blade number and dimensionless splitter blade length

the fow path lean angle are relatively large. Meanwhile, high inlet hub/tip ratio and low aspect ratio cause the blade height of the mixed-fow compressor impeller to be comparatively low. Aerodynamic and geometric parameters vary moderately along the radial direction. Thus, the high hub/tip ratio mixed-fow impeller is peculiar and typical and it is more appropriate for the 1D mean streamline loss analysis. On the other hand, greater friction loss and clearance leakage loss may be caused by the increase in the relative blade surface area and the relative tip clearance, since the fow path is narrow and blade height is low.

Based on the improved 1D loss model, the distribution of impeller adiabatic efficiency at design flow rate with respect to Z and ζ is shown in Fig. [8](#page-6-1). Variable ranges are $Z = 30-50$ and $\zeta = 0$ to 1.0 (particularly, $\zeta = 1.0$ means double principal blade numbers). High efficiency region locates where $Z = 40-42$ and $\zeta = 0$ to 0.2. The overall maximum efficiency is 0.91 and (Z, ζ) for the maximum efficiency is (42, 0.2). When Z and ζ are over-high or over-low, Efficiency declines rapidly. (Z, ζ) for overall minimum efficiency point is $(50, 1)$. Two black lines that intersect in the $Z - \zeta$ plane represent the distributions of maximum efficiency points with respect to invariable and invariable ζ , respectively. Their intersection is the overall maximum efficiency point. ζ is approximatively linear with Z. On account of data range restriction, the vertical occurs at the left line end, but a linear extension can be predicted if data increase. The horizontal at the right line end demonstrates that splitter blades are unsuitable for the mixed-fow impeller design if blade number is overmuch.

Several previous models for selecting recommended blade number $[15]$ are presented in Equation (4) (4) (4) as contrasts to the new model.

$$
Z = \begin{cases} k_z \frac{d_1 + d_2}{d_2 - d_1} \sin \quad \text{(Galvas/Pfleiderer)}\\ \frac{2\pi \sin \beta_m}{0.4 \ln(d_2/d_1)} & (Ec \text{ker } t)\\ 25 \sin \beta_2 / N_s & \text{(Rodgers)}\\ (90 - \beta_2) / 2 & (Xu) \end{cases} \tag{4}
$$

As illustrated in Fig. [6](#page-5-1), the average blade chord length is estimated by:

$$
Lc_m \approx \frac{r_2 - r_1}{\sin \gamma \sin \beta_m} \tag{5}
$$

The average solidity is estimated by:

$$
\tau_m \approx \frac{Lc_m}{s_m} \approx \frac{(r_2 - r_1)}{\sin \gamma \sin \beta_m} / \frac{2\pi (r_1 + r_2)}{2Z}
$$
(6)

where s_m is average pitch.

The meridional streamline slope angle γ is 90 \degree for radial impellers with no inducers. According to the cascade optimum solidity theory, the mixed-fow impeller can be regarded as an axially elongated radial impeller with no inducer. The optimum blade number is barely afected by γ. Hence, γ is set to 90° in the following discussion. $\tau_{m_{1-s}}$ and $\tau_{m_{s-2}}$ are obtained by applying Equation [\(6](#page-7-0)) to "1-S" and "S-2" parts of the mixed-flow impeller, as shown in Fig. [6.](#page-5-1) Equation [\(7\)](#page-7-1) presents the formulas of τ_m , $\tau_{m_{1-s}}$ and $\tau_{m_{s-2}}$. Specifically, $\tau_m = \tau_{m_{1-s}}$ when $\zeta = 0$.

$$
\begin{cases}\n\tau_m = \frac{Z}{\pi \left(\frac{r_1 + r_2}{r_2 - r_1}\right) \sin \beta_m} \\
\tau_{m_{1-s}} = \frac{Z(1-\zeta)}{\pi \left(\frac{r_1 + r_2}{r_2 - r_1}\right) \sin \beta_m} \\
\tau_{m_{s-2}} = \frac{Z}{\pi \left(\frac{2r_2}{r_2 - r_1} - \zeta\right) \sin \beta_m}\n\end{cases} (7)
$$

Figure [9](#page-7-2) shows the distributions of $\tau_{m_{1-s}}$ and $\tau_{m_{s-2}}$ with respect to Z and ζ . $\tau_{\rm m}$ corresponding to the maximum adiabatic efficiency is approximately equal to 2 for no-splittered impeller configurations ($\zeta = 0$). The data contours also indicate that maximum efficiency points approximately locate at the region where $\tau_{m_{1-s}} + \tau_{m_{s-2}} = 2.25$. Thus, for the overall maximum efficiency point,

$$
Z = 2\pi \left(\frac{r_1 + r_2}{r_2 - r_1}\right) \sin \beta_m
$$

$$
\pi \left(\frac{r_1 + r_2}{r_2 - r_1} - \zeta\right) \sin \beta_m + \pi \left(\frac{2r_2}{r_2 - r_1} - \zeta\right) \sin \beta_m = 2.25
$$
 (8)

Define $\overline{R} = (r_1 + r_2) / (r_2 - r_1)$ and ζ for maximum efficiency can be solved by Equation [\(9](#page-7-3)).

$$
\frac{1-\zeta}{\overline{R}-\zeta} + \frac{2\zeta}{1+\overline{R}-\zeta} = \frac{1.125}{\overline{R}}
$$
(9)

The new blade number empirical model in Equation [\(7](#page-7-1)) has the same form with Galvas' model [[15\]](#page-19-13) except that $k_z = 2\pi$. When the splitter blade is not considered, i.e., $\zeta = 0$, the new model will degenerate into Galvas' model. This model combines the cascade optimum solidity theory and the loss analysis. For the frst time, the new model

Fig. 9 Distributions of the average solidity and the maximum efficiency points

Fig. 10 Distributions of the average solidity and the maximum efficiency points

evaluates the splitter blade length quantitatively in detail and gives the analytical solutions of the blade number and the splitter blade length simultaneously. The adiabatic efficiencies of the no-splittered impeller configurations ($\zeta = 0$)

and corresponding maximum efficiencies for the optimum blade numbers calculated by the above models are shown in Fig. [10](#page-7-4). It can be observed that blade number calculated by the new model is the closest to the high efficiency region among all the model results.

This study also investigates dimensionless cascade geometric parameters as a reference to select Z and ζ in consideration of the impeller geometric particularities of high hub/tip ratio and low aspect ratio. There are several typical dimensionless geometric parameters corresponding to diferent stream surfaces: hub/tip ratio (HR = r_h/r_t , S2 surface), aspect ratio ($AR = h/L = (r_t - r_h)/L$, quasi-S2 surface) and solidity ($\tau = L/s$, S1 surface). However, the dimensionless geometric parameter corresponding to S3 surface has not been investigated in the previous studies. It can be defned as the blade height/pitch ratio (h/s_t) . According to Fig. [6](#page-5-1):

$$
h/s_t = (r_t - r_h)/(2\pi r_t/Z) = (1 - HR)Z/2\pi = \tau \cdot AR
$$
 (10)

This parameter illustrates the relationship among blade number, hub/tip ratio, aspect ratio and solidity. Figure [11](#page-8-0) presents distributions of h/s_t and HR at ζ =0, 0.1, 0.2, 0.3, 0.4 and 0.5. Blade number needs to increase with higher HR for an invariable h/s_t . HR is higher, and h/s_t is lower than the inlet values in the impeller rear channel, which means more blades are needed to maintain h/s_t value and weaken the flow separation. Splitter blades are preferred in this case. There is an optimal h/s_t to determine blade number and the leading edge position of splitter blade for each impeller configuration.

The off-design conditions and other additional losses such as supersonic loss have not been considered in the improved 1D loss model yet. The universality of the above models that describe the relation between Z and ζ still needs to be verifed by more other impellers and experimental data.

Fig. 11 Distributions of blade height/pitch ratio and hub/tip ratio

3.2 Aerodynamic optimization for the Mixed‑fow compressor using Full‑surface parameterization method

The three-dimensional aerodynamic optimization for compressors is a typical problem with the characteristics of high-dimension, elapsed time and black box (HEB). In order to solve this problem, the number of the optimization control parameters should be reduced on the premise that the optimal solution of the original design space remains unchanged. Hence, it is necessary to construct a parameterization technique with fewer control parameters and

Fig. 12 Principle of the full-surface parameterization method

Fig. 13 Flowchart of parameterization

a better performance for compressor blade geometries. A full-surface parameterization control method is applied for blade optimization of the mixed-fow compressor. The principle and the fowchart of parameterization are presented in Figs. [12](#page-9-0) and [13](#page-9-1), respectively. In order to realize one-to-one mapping between physical domain points and calculation domain points, parametric arc lengths for the original surface points are calculated by:

$$
\xi_{i,j} = \frac{\sum_{m=1}^{i} l_m}{L_j} \quad \eta_{i,j} = \frac{\sum_{n=1}^{j} l l_n}{L L_i}
$$
\n(11)

where $\xi_{i,j}$ and $\eta_{i,j}$ are horizontal and vertical coordinates in the unit mesh plane, as shown in Fig. [12.](#page-9-0)

Displacement variations of calculation domain points for the original blade surface can be calculated by Bezier surface functions given by Equation [\(12](#page-10-0)).

$$
\begin{cases}\n\vec{R} = \sum_{k=0}^{n} \left\{ \sum_{l=0}^{m} P_{k,l} B_{l}^{m}(v) \right\} B_{k}^{n}(u) \\
B_{k}^{n}(u) = C_{k}^{n} u^{k} (1 - u)^{n-k} \\
C_{k}^{n} = \begin{cases}\n\frac{n!}{(n-k)!k!} if 0 \le k \le n \\
0 \quad \text{if not}\n\end{cases}
$$
\n(12)

where \vec{R} is the normal displacement of each point in the calculation domain. P_{k1} represents the control points of the Bezier surface and the number of control points is $(m + 1) \times (n + 1)$. $B_l^m(v)$ and $B_k^n(u)$ are the Bernstein basis functions. C_k^n is combination number.

Burguburu and le Pape [\[21\]](#page-19-19) Cheng [[22\]](#page-19-20), respectively, adopted the Bezier surface to control deformations of suction surfaces and pressure surfaces of axial compressor blades. The innovation point of full-surface parameterization control method is that the pressure surface and suction surface can be seen as one whole surface. As illustrated in Fig. [12,](#page-9-0) the Bezier surface is covered over the whole blade surface form leading edge to trailing edge and back to the original points. The trailing edge is the middle position of the whole surface. Displacements of the Bezier surface points correspond to the displacements of the original blade surface points. The smoothness of leading and trailing edges can be maintained, and optimization control variables can be reduced.

The multi-island genetic algorithm (population size 10, algebra 10 and population number 10) is adopted in the aerodynamic optimization of the mixed-fow compressor. There are three blade rows in the mixed-fow compressor stage. Each blade has twelve control points. As shown in Fig. [13](#page-9-1), the red points are variable active control points and they can be moved along the surface normal direction. The green points are fxed control points, and they remain stationary to ensure the smoothness of the leading and trailing edge. The scopes of all variable are set to [-6, 6]. The optimization targets are the efficiencies of the near design point and the near stall point, respectively. The relative variation in flow rate is $\pm 5\%$, and the pressure ratio is not less than the initial value. The optimization target function is given by:

 $\max f = \omega_{nd} * f_{nd} + \omega_{ns} * f_{ns}$ (13)

The constraint conditions are given by:

$$
\begin{cases}\nf_{nd} = eff_{nd}; & if \left\{ \left| \frac{m_{nd} - m_{nd_{ori}}}{m_{nd_{ori}}} \right| \le 5\% \right\} \\
P_{nd}^* - P_{nd_{ori}} \ge 0 \\
f_{ns} = eff_{ns}; & if \left\{ \left| \frac{m_{ns} - m_{ns_{ori}}}{m_{ns_{ori}}} \right| \ge 5\% \right\} \\
else & f_{nd} = \min us f_{ns} = \min us\n\end{cases}
$$
\n(14)

At present, CFD approach represented by the numerical solution for RANS equation has been widely applied in the feld of compressor aerodynamic designs. The infuence of the random pulsation term in a unsteady flow is replaced by Reynolds stress, and turbulence models are introduced to enclose the equation. The computation load is greatly reduced compared with LES and DNS. However, boundary layer transition, turbulence model, losses of tip clearance, endwall, blade leading and trailing edge flow, and unsteady flow, etc., may increase the calculation error and uncertainty. The simulation should be verifed with the test data as much as possible to maintain credibility and accuracy.

NUMECA software is adopted for 3D viscous steady turbulence simulations. The Spalart–Allmaras turbulence model is selected to simulate the compressor internal flow field. The space is discretized by the central difference scheme. Fourth-order Runge–Kutta method is used to solve the time derivative terms. The grids of single blade channel are generated by AutoGrid5 module of NUMECA. The mesh confgurations of both the impeller and the tandem stator have H&I topologies. In order to ensure that the value of near-wall Y plus is less than 5, the frst-layer grid spacing near the wall is set to 0.001 mm. Three kinds of grid densities are adopted to check mesh independence. The mesh confgurations and grid numbers of no-splittered and splittered impeller confgurations are presented in Table [4](#page-11-0). The conditions of total temperature and pressure are imposed at the inlet boundary. Meanwhile, a condition of averaged static pressure is imposed at the outlet boundary. The inlet boundary conditions of the mixed-fow compressor and the A-A-M can refer to Tables [3](#page-5-0) and [1](#page-2-1) severally. The values

Table 4 Mesh confgurations and grid numbers of diferent impeller confgurations

Fig. 14 Mesh independence verifcation: **a** characteristics comparison of total pressure ratio, **b** characteristics comparison of adiabatic efciency

of outlet pressure are set to 600000Pa and 650000Pa corresponding to the near design point and the near stall point, respectively. The initial fow solution requires estimating the static pressure at the inlet, outlet and each rotor-stator interface. Considering the strong adverse pressure gradient flow in the compressor, the initial static pressure in front and rear of each blade usually needs to be estimated according to the blade load or calculated by the radial equilibrium control equation of the meridional fow surface. In the process of calculating a whole constant speed characteristic line, various operating points are calculated by changing the outlet back pressure. The calculation result of the adjacent previous operating point can be used as the initial condition for the current calculation. Figure [14](#page-11-1) shows the performance comparisons of the original impeller simulated with diferent mesh confgurations. The performance characteristics of Mesh_2 confguration and Mesh_3 confguration approach. Hence, Mesh₂ configuration is used for CFD numerical simulations in consideration of calculation accuracy and speed.

A cloud supercomputing service was used for the parallel calculation of this aerodynamic optimization. A thousand sample points with diferent blade geometries of the mixedflow compressor were calculated on the supercomputing platform. Each calculation was executed with 6 CPU threads in about 15 minutes. The optimization process had taken about 31 hours in total using a 32-core x64-thread processor $-$ AMD EpycTM 7452.

Fig. 15 Distribution of the sample points in the multi-objective optimization process

Figure [15](#page-12-0) presents the distribution of sample points in this multi-objective optimization process. The green point represents the optimal mixed-fow compressor confguration which achieves the maximum adiabatic efficiency at both the near design point and the near stall point. The geometry comparisons of the optimal result and the original compres-sor are shown in Fig. [16](#page-13-0). It can be seen that major geometric changes occur at leading edges of each blade row. Geometric variations are obvious at impeller tip and hub, the former stator hub and the rear stator tip. As indicated in Fig. [17](#page-14-0), after optimization, the total pressure ratio increases by 3.71% relatively and the adiabatic efficiency increases by 0.95% absolutely at the near design point, while at the near stall point, the total pressure ratio and the adiabatic efficiency, respectively, increase by 5.55% relatively and 2.93% absolutely. There is a signifcant improvement on the performance of the mixed-fow compressor, especially at the near stall point.

The operation condition with a back pressure of 620000 Pa which is near the design point is selected to a benchmark to compare the fow feld before and after the optimization. As shown in Fig. [18,](#page-15-0) the main flow loss occurs in the tandem cascade channel. The low kinetic energy fow exists in the front cascade of the tandem stator at the blade tip. Meanwhile, in the rear cascade channel, the mismatching of the inlet fow angle and the curve blade profle cause apparent separations at the leading edge of the pressure side and the trailing edge of the suction side. According to the static pressure distribution on the blade surface, it is observed that the optimization has improved the fow angle matching between the front and rear blade of the tandem stator. The large positive attack angle at the rear blade inlet has been eliminated. After the optimization, the region where the low kinetic energy fow and the separation fow occur are signifcantly reduced, especially at the blade tip and the midsection main flow region.

4 Performance of the Axial‑co‑mixed‑fow compressor

The performances of the axial-co-mixed-fow compressor $(A-A-M)$ at 1.0 R_n , 0.9 R_n and 0.8 R_n are calculated by 3D numerical simulation. In addition, the performances of the single mixed-fow compressor stage and the single mixedflow impeller are also simulated.

The blade tip gap is 0.3 mm, and 17 mesh control volumes were put into the tip gap region. The distance from the frst-layer grid to the wall is also set to 0.001 m to meet the requirement of the value of Y plus. The meshes and the values of near-wall $Y+$ of the three stages in A-A-M are

presented in Fig. [19](#page-16-0). The total grid number of three stages of A-A-M is 2288014. The minimum skewness angle is 22.179°. The maximum aspect ratio is 5835.2. The maximum expansion ratio is 3.183. The values of Y + near the wall are all lower than 5, which is appropriate for the S-A turbulence model.

Figure [20](#page-16-1) presents the performances of the impeller, the mixed-fow compressor stage and A-A-M at three rotate speeds. The performance of the original four-stage axial compressor (A-A-A-A) is also presented as a comparison. As the rotate speed decreases, the total pressure ratio of A-A-M declines uniformly while the pressure ratios of the mixed-fow stage and the impeller decline more slowly. This indicates that the mixed-fow stage has a wider stable operation range and still carries a relatively higher load at the off-design conditions. Hence, the mixed-flow stage maintains a relatively higher load capacity than the front axial-fow stages. The peak pressure ratio of A-A-M is higher than that of A-A-A-A at 1.0 R_n and 0.9 R_n . At 0.8 R_n , the peak pressure ratio of A-A-M approaches that of

Fig. 17 Performances comparisons of the optimized and the original mixed-flow compressor: **a** total pressure ratio, **b** adiabatic efficiency

A-A-A-A with a slight decline. On the other hand, the fow rate declines after modification, especially at $0.8 \, \text{R}_n$. In general, A-A-M has a higher load capacity than A-A-A-A, while the flow capacity of A-A-M is lower than that of A-A-A-A.

The efficiency of A-A-M maintains a relatively high level at 0.9 R_n and 1.0 R_n. However, the efficiency declines significantly and the efficiency characteristic curve steepens at 0.8 R*̇* , which indicates the stability margin declines. The efficiency characteristic curves of the mixed-flow stage and A-A-M approach. Therefore, the efficiency performance of A-A-M is mainly infuenced by the mixedflow stage, while the efficiency of the impeller is still at a relatively high level at $0.8 \, \text{R}_n$, which indicates that the tandem stator is the main factor that restricts the overall efficiency promotion. There is a slight efficiency difference between A-A-M and A-A-A-A. Although the peak efficiency of A-A-M is slightly lower than that of A-A-A-A, the load capacity improvement is much more obvious. Thus, the axial-co-mixed-fow compressor combination scheme may have some reference signifcance for dimension reductions and performance improvements of high pressure axial compressors.

At the near design point, the near choke point and the near stall point, the comparisons of blade angle and airflow angle at each blade row inlet in the mixedflow compressor stage are shown in Fig. [21.](#page-17-0) Figure [21a](#page-17-0) shows that the flow angles at the hub and the middle of the impeller match relatively well. The negative attack angle exists near the tip region. The attack angle declines gradually as the stage load increases. The negative attack angle near the tip region is weakened. The positive attack angle appears at the hub and the middle of the impeller. As demonstrated in Fig. [21b](#page-17-0), the positive attack angle exists from the hub to the tip of the former stator and rises gradually with the stage load increasing, which may cause flow separation at the suction surface. The maximum positive attack angle locates near the tip region. Fig. [21c](#page-17-0) shows that the flow angle at the rear stator inlet changes slightly along the radial direction due to low blade height. The negative attack angle exists from the hub to the tip. As the stage load increases, the attack angle variation is not apparent.

Figure [22](#page-18-0) demonstrates that there is no obvious flow separation in the impeller cascade channel at the near design point. Main separation occurs in the hub region of the suction surface tail of the rear stator. A strong fow acceleration caused by the large positive attack angle occurs at the suction surface leading edge of the former stator, which corresponds to the positive attack angle region shown in Fig. [21](#page-17-0)b.

The geometric and the fow matchings with the former axial stages is the principal difficulty for the application of the mixed-fow compressor. The drastic curvature change of the mixed-fow impeller fow path is an important factor that causes fow losses. The impeller inlet and outlet relative positions and the axial-oblique turning angles of the flow path have direct effects on the flow path curvature. Therefore, interstage and rotor-stator fow path matchings are of vital importance. The impeller inlet axial transition is benefcial for the fow conditions at the axial-fow stage outlet and the mixed-fow stage inlet. However, a

Fig. 18 Comparisons of the relative Mach number of S1 surface and static pressure on the blade surface

Fig. 19 The meshes and the near-wall Y+ of A-A-M

greater curvature change of the fow path is generated at the impeller inlet. Similarly, the impeller outlet axial transition may causes a large flow path turning and a curvature variation.

5 Conclusion

A high hub/tip ratio mixed-fow compressor and three novel retroft design schemes for a high pressure axial compressor are proposed and investigated. The performance of the mixed-fow compressor and the axial-co-mixed-fow compressor has been improved using a full-surface parametric optimization approach. The conclusions are as follows.

- (1) The high hub/tip ratio mixed-flow compressor can greatly promote the load capacity with slight impact on efficiency and surge margin. Meanwhile, simpler structures are beneficial for the reduction in axial dimension. The structures with no return channel of various high pressure compressor retroft schemes demonstrate the potential application prospects of high hub/tip ratio mixed-fow compressors.
- (2) The mixed-fow impeller confguration equipped with 42 principal blades and splitter blades with a ffth of principal blade length achieves the maximum adiabatic efficiency at the design flow rate. Blade height/pitch ratio which illustrates the relation among blade number, hub/tip ratio, aspect ratio and solidity can also be adopted as a reference for the selections of blade number and splitter blade.

Fig. 20 Performances of impeller, mixed-fow stage and combined compressor: **a** characteristics of total pressure ratio, **b** characteristics of adiabatic efficiency

(3) Compared with the traditional optimization parametric methods, the full-surface parametric method can efectively decrease the control parameters and shrink the variation space of the variables in the optimization process. At the near design point, the total pressure ratio and the isentropic efficiency, respectively, increase by 3.71% relatively and 0.95% absolutely. At the near stall point, they, respectively, increase by 5.55% relatively and 2.93% absolutely, which shows a more signifcant performance enhancement. These improvements demonstrate the approach efectiveness in the reduction in the time as well as the dimensionality of the optimization control parameter space mapping. It is benefcial to

Fig. 21 Radial distributions of blade angle and airfow angle at each blade row inlet: **a** rotor, **b** front row of stator, **c** rear row of stator

solve the HEB frontier issue in the feld of the compressor aerodynamic optimization.

(4) The axial-co-mixed-fow compressor is a considerable retroft design scheme for high pressure axial compressors, which can meet the requirements of high load capacity and compact dimensions. It has some reference signifcance for dimension reductions and performance improvements of high pressure axial compressors. Further, the twin-stage (counter-rotating) mixed-fow compressor possesses even greater potential advantages in stage load capacity promotion and axial dimension reduction. The subsequence work is to further explore detailed aerodynamic designs and verify the feasibility of twin-stage mixed-fow compressors.

Fig. 22 Near-wall limit streamlines at the near design point

Appendix

Appendix: Springer‑Author Discount

List of symbols

- *b* Append Hub-to-shroud passage width *D* Diameter
- *D* Diameter
- *f* Optimized objective function
- *h* Blade height
- *L* Blade length
- *Lc* Blade chord length
- \dot{m} Mass flow
- *P*∗ Total pressure
- *Q* Volume flow
- R_n Design rotate speed
 R_n Design rotate speed
- Design rotate speed

 $\overline{R}(r_1 + r_2) / (r_2 - r_1)$

- *r* Radius
- *s* Pitch
- *T*∗ Total temperature
- *U* Blade tangential velocity
- *U* Blade tangential velocity
- *Z* Main blade number
- β Blade angle with respect to tangent
- *γ* Meridional streamline slope angle
- Δ*H* Total enthalpy increase
- δ Tip clearance
- *𝜁* Dimensionless splitter blade length
- η Adiabatic efficiency, vertical coordinate
- η Adiabatic efficiency, vertical coordinate
- *𝜉* Horizontal coordinate
- π_r^* Total pressure ratio
- *τ* Solidity
Ψ Loading
- Loading coefficient
- *ψ* Flow coefficient
- ω Weight coefficient

Subscripts

- *B* Principal blade parameter
- *h* Hub
- *m* Meridional, mean
- *nd* Near design point
- *ns* Near stall point
- *ori* Original parameters (before optimization)
- *out* Outlet
- *s* Splitter blade (inlet)
- *t* Tip
- *z* Axial
- *1* Inlet
- *2* Outlet

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