Approximate series solution of singular boundary value problems with derivative dependence using Green's function technique

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Abstract In this work, we propose an effective approach for solving singular boundaryvalue problems with derivative dependence. The present approach is based on a modification of the Adomian decomposition method (ADM) which combines with Green's function. In fact, it depends on constructing Green's function before establishing the recursive scheme for the solution components. In contrast to the existing recursive schemes based on ADM, the proposed method avoids solving a sequence of transcendental equations for the undetermined coefficients. The approximations of the solution are obtained in the form of series with easily computable components. Additionally, the convergence analysis and error estimation of the proposed method is discussed under quite general conditions. Moreover, the numerical examples are included to demonstrate the accuracy, applicability, and generality of the proposed scheme. The numerical results reveal that the proposed method is very effective and simple.

Keywords Singular boundary value problems · Adomian decomposition method · Adomian polynomials · Green's function · Approximations

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1 Introduction

Two-point singular boundary value problems for ordinary differential equations arise very frequently in many branches of applied mathematics and physics such as gas dynamics, chemical reactions, nuclear physics, atomic structures, atomic calculations, electrical potential theory, study of positive radial solutions of nonlinear elliptic equations and physiological studies. Therefore, it has been studied extensively in recent years. However, such nonlinear singular boundary value problems cannot be solved analytically in general. So these must be tackled by various numerical or approximate methods. However, the numerical treatment of the singular boundary value problems has always been far from trivial due to the singularity.

The aim of this paper is to propose an effective recursive scheme for solving nonlinear derivative-dependent singular boundary value problems (SBVPs). This scheme is based on Adomian decomposition method (ADM) and the Green's function technique. We consider the SBVPs with derivative dependence (Bobisud 1990; Verma and Pandey 2011)

$$(p(x)u'(x))' = q(x)f(x, u(x), p(x)u'(x)), x \in (0, 1], u(0) = \alpha_1, \beta_1 u(1) + \gamma_1 u'(1) = \eta_1,$$

$$(1.1)$$

where α_1 , $\beta_1 > 0$, γ_1 and η_1 are any finite real constants. The condition p(0) = 0 says that the Eq.(1.1) is singular and if q(x) is allowed to be discontinuous at x = 0 then the Eq.(1.1) is called doubly singular (Bobisud 1990). Throughout the paper the following conditions are assumed on p(x), q(x) and f(x, u(x), p(x)u'(x))

- (E₁) $p(x) \in C[0, 1] \cap C^{1}(0, 1]$ with p(x) > 0 in (0, 1] and $\frac{1}{p(x)} \in L^{1}(0, 1]$.
- (E₂) q(x) > 0 in (0, 1], $q(x) \in L^{1}(0, 1]$ and q(x) is not identically zero.
- (E₃) Assume f(x, u, pu') is continuous on $D_1 = \{(0, 1] \times (0, \infty) \times \mathbb{R}\}$ and is not identically zero.
- (E₄) The nonlinear function f(x, u, pu') is locally Lipschitz continuous such that

$$|f(x, u, pu') - f(x, v, pv')| \le L_1 |u - v| + L_2 |p(u' - v')|,$$
(1.2)

where L_1 and L_2 are Lipschitz constants.

There has been much interest devoted in the study of singular two point boundary value problems, Bobisud (1990), Verma and Pandey (2011), Wazwaz et al. (2013), Singh and Kumar (2013b), Chawla and Katti (1982), Inc and Evans (2003), Kumar and Aziz (2006), Ebaid (2011), Khuri and Sayfy (2010), Kumar and Singh (2010), Singh et al. (2012), Ravi Kanth and Aruna (2010), Wazwaz and Rach (2011), Cen (2007), Öztürk and Gülsu (2013) and many of the references therein. The main difficulty of (1.1) is that the singularity behavior occurs at x = 0. Bobisud (1990) and Verma and Pandey (2011) discussed the existence and uniqueness of solution of the problem (1.1). Recently, a great deal of numerical methods have been used to solve the particular case of (1.1). For example, the cubic spline, B-spline and finite difference methods were carried out in Chawla and Katti (1982), Kanth and Bhattacharya (2006), Çağlar et al. (2009) and Kumar and Aziz (2006). Although, these numerical methods have many advantages, but an immense amount of computational work is involved that combines some root-finding techniques to obtain accurate numerical solution especially for nonlinear problems.

Furthermore, some newly developed numerical-approximate methods have also been applied to handle (1.1). Such as, the ADM and modified Adomian decomposition method (MADM) were employed in Khuri and Sayfy (2010), Kumar and Singh (2010), Inc and Evans (2003), Ebaid (2011). The homotopy analysis method (HAM) was introduced in Danish et al. (2012). It is well known that solving (1.1) by using ADM or MADM is always a

computationally involved task as it requires the computation of undetermined coefficients in a sequence of nonlinear algebraic or more difficult transcendental equations which increases the computational work (for details see Kumar and Singh 2010; Khuri and Sayfy 2010; Danish et al. 2012; Bataineh et al. 2009). Moreover, the undetermined coefficients may not be uniquely determined in some cases. This may be the major disadvantage of these methods for solving nonlinear two-point BVPs. Furthermore, the variational iteration method (VIM) and its modified versions have been employed in Wazwaz and Rach (2011) and Ravi Kanth and Aruna (2010). Wazwaz and Rach (2011) showed that VIM gives good approximations only when the problem is linear or weakly nonlinear with nonlinearity of the form u^n , $uu' \dots$ etc. However, the VIM suffers when the nonlinearity is of the form e^u , $\ln(u)$, $\sin u$, $\sinh u \dots$ etc. This may be one of the major drawbacks of VIM for solving difficult nonlinear problems.

In this paper, we present a modification of the ADM which combines with Green's function to overcome the difficulties occurring in the ADM or MADM for solving nonlinear SBVPs (1.1). In fact, we propose an efficient recursive scheme which does not require any computation of undetermined coefficients, that is, without solving a sequence of growingly higher order polynomials or difficult transcendental equations for obtaining undetermined coefficients (Kumar and Singh 2010; Khuri and Sayfy 2010; Inc and Evans 2003; Wazwaz and Rach 2011). The main advantage of proposed method is that it provides a direct recursive scheme for solving the SBVP. Moreover, the convergence analysis and error estimation of the proposed method is discussed. In addition, the numerical examples are included to demonstrate the accuracy of the proposed method.

1.1 Review of ADM

In this subsection, we shall briefly describe ADM for nonlinear second order differential equation of the form (1.1).

It is well-known that ADM allows us to solve both nonlinear IVPs and BVPs without unphysical restrictive assumptions such as linearization, discretization, perturbation and guessing the initial term or a set of basis function. In recent years, many authors Singh and Kumar (2013a,b), Wu et al. (2009), Duan and Rach (2011), Singh et al. (2012, 2013), Ebaid (2011), Wazwaz and Rach (2011), Khuri and Sayfy (2010), Kumar and Singh (2010), Benabidallah and Cherruault (2004), Inc and Evans (2003), Adomian (1994), Adomian and Rach (1983), Wazwaz (2001), Al-Khaled and Allan (2005), El-Kalla (2012), El-Sayed et al. (2013) and Duan et al. (2013) have shown interest in the study of ADM for different scientific models. According to the ADM, the operator form of (1.1) can be written as

$$\mathcal{L}u(x) = Ru(x) + Nu(x), \quad x \in (0, 1],$$
(1.3)

where $\mathcal{L} = \frac{d^2}{dx^2}$ is linear second-order differential operator, $Ru(x) = -\frac{p'(x)}{p(x)}u'(x)$ is remainder operator and $Nu(x) = \frac{q(x)}{p(x)}f(x, u(x), p(x)u'(x))$ represents the nonlinear function. The inverse operator of \mathcal{L} is defined as

$$\mathcal{L}^{-1}[\cdot] = \int_{0}^{x} \int_{0}^{x} [\cdot] \, \mathrm{d}x \, \mathrm{d}x.$$
 (1.4)

Operating the inverse operator $\mathcal{L}^{-1}[\cdot]$ on both sides of (1.3) and using the boundary condition $u(0) = \alpha_1$ we obtain

$$u(x) = \alpha_1 + cx + \mathcal{L}^{-1}[Ru(x) + Nu(x)], \qquad (1.5)$$

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where $c = u'(0) \neq 0$ is unknown constant, and it will be determined later using boundary conditions at x = 1.

The solution u(x) and the nonlinear function Nu(x) are decomposed by infinite series

$$u(x) = \sum_{n=0}^{\infty} u_n(x), \quad Nu(x) = \sum_{n=0}^{\infty} A_n,$$
(1.6)

where A_n are Adomian's polynomials that can be constructed for various classes of nonlinear functions with the formula given by Adomian and Rach (1983)

$$A_n = \frac{1}{n!} \frac{\mathrm{d}^n}{\mathrm{d}\lambda^n} \left[N\left(\sum_{k=0}^{\infty} u_k \lambda^k\right) \right]_{\lambda=0}, \quad n = 0, 1, 2, \dots$$
(1.7)

Substituting the series (1.6) into (1.5), we obtain

$$\sum_{n=0}^{\infty} u_n(x) = \alpha_1 + cx + \mathcal{L}^{-1} \left[R \sum_{n=0}^{\infty} u_n(x) + \sum_{n=0}^{\infty} A_n \right].$$
 (1.8)

Upon comparing both sides of (1.8), the ADM admits the following recursive scheme

$$u_0(x,c) = \alpha_1 + cx, u_j(x,c) = \mathcal{L}^{-1}[Ru_{j-1} + A_{j-1}], \quad j \ge 1,$$
 (1.9)

that will lead to the complete determination of components $u_j(x, c)$, j = 0, 1, 2, ..., of the solution u. Hence the *n*-term truncated approximate series solution can be obtained as

$$\phi_n(x,c) = \sum_{j=0}^n u_j(x,c).$$
(1.10)

One can note that the approximate solution $\phi_n(x, c)$ depends on the unknown constant *c*. This constant *c* will be determined approximately by imposing the boundary condition at x = 1 on $\phi_n(x, c)$, which leads to a sequence of transcendental equations $\phi_n(1, c) = 0$, n = 1, 2, 3, ...

Recently, in Wazwaz (2001), Inc and Evans (2003), Benabidallah and Cherruault (2004), Khuri and Sayfy (2010) and Kumar and Singh (2010) authors applied ADM for solving nonlinear two-point BVPs. However, solving such BVPs using ADM is always a computationally involved task because it requires the computation of undetermined coefficients in a sequence of difficult transcendental equations that increases the computational work. For example, consider

$$u''(x) = -e^{u(x)}, \quad u(0) = 0, \quad u(1) = 0,$$
 (1.11)

According to the ADM (1.9), the (1.11) can be transformed into the recursive scheme as

$$u_0(x,c) = cx, \quad u_j(x,c) = -\mathcal{L}^{-1}[A_{j-1}], \quad j \ge 1.$$
 (1.12)

Using the formula (1.7), the Adomian's polynomials for $f(u) = e^u$ about $u_0 = cx$ are

$$A_0 = e^{cx}, \quad A_1 = u_1 c e^{cx}, \quad A_2 = u_2 c e^{cx} + \frac{1}{2} u_1^2 c^2 e^{cx}, \dots$$
 (1.13)

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Using (1.12) and (1.13), we obtain the components as

$$u_{0}(x, c) = cx,$$

$$u_{1}(x, c) = \frac{1}{c^{2}} - \frac{e^{cx}}{c^{2}} + \frac{x}{c},$$

$$u_{2}(x, c) = -\frac{5}{4c^{4}} + \frac{e^{cx}}{c^{4}} + \frac{e^{2cx}}{4c^{4}} - \frac{x}{2c^{3}} - \frac{e^{cx}x}{c^{3}},$$

$$u_{3}(x, c) = \frac{11}{6c^{6}} - \frac{5e^{cx}}{4c^{6}} - \frac{e^{2cx}}{2c^{6}} - \frac{e^{3cx}}{12c^{6}} + \frac{x}{2c^{5}} + \frac{3e^{cx}x}{2c^{5}} + \frac{e^{2cx}x}{2c^{5}} - \frac{e^{cx}x^{2}}{2c^{4}},$$

$$\vdots$$

Consequently, the *n*-term truncated series solution is obtained

$$\phi_n(x,c) = \sum_{j=0}^n u_j(x,c).$$
(1.14)

By imposing the boundary condition at x = 1 on $\phi_n(x, c)$, which leads to a sequence of transcendental equations $\phi_n(1, c) = 0, n = 1, 2, 3, ...$

$$\begin{aligned}
\phi_{1}(1,c) &\equiv c + \left(\frac{1}{c^{2}} - \frac{e^{c}}{c^{2}} + \frac{1}{c}\right) = 0 \\
\phi_{2}(1,c) &\equiv c + \left(\frac{1}{c^{2}} - \frac{e^{c}}{c^{2}} + \frac{1}{c}\right) + \left(-\frac{5}{4c^{4}} + \frac{e^{c}}{c^{4}} + \frac{e^{2c}}{4c^{4}} - \frac{1}{2c^{3}} - \frac{e^{c}}{c^{3}}\right) = 0 \\
\phi_{3}(1,c) &\equiv c + \left(\frac{1}{c^{2}} - \frac{e^{c}}{c^{2}} + \frac{1}{c}\right) + \left(-\frac{5}{4c^{4}} + \frac{e^{c}}{c^{4}} + \frac{e^{2c}}{4c^{4}} - \frac{1}{2c^{3}} - \frac{e^{c}}{c^{3}}\right) \\
&\quad + \left(\frac{11}{6c^{6}} - \frac{5e^{c}}{4c^{6}} - \frac{e^{2c}}{2c^{6}} - \frac{e^{3c}}{12c^{6}} + \frac{1}{2c^{5}} + \frac{3e^{c}}{2c^{5}} + \frac{e^{2c}}{2c^{5}} - \frac{e^{c}}{2c^{4}}\right) = 0 \end{aligned}$$

$$(1.15)$$

In order to obtain unknown constant c, we need some root finding techniques and these techniques require additional computational work. However, solving a sequence of transcendental equations (1.15) for c is difficult task in general. Moreover, in some cases the undetermined coefficient c may not be uniquely determined. This may be the major drawback of ADM for solving nonlinear boundary value problems. In order to avoid solving such types of a sequence of transcendental equations for unknown constant c, in next section we shall propose a new recursive scheme which does not involve any undetermined coefficient to be determined.

2 ADM with Green's function technique

In this section, we propose an efficient recursive scheme which is based on the Green's function technique and ADM for solving nonlinear derivative-dependent singular two point boundary value problems of the form (1.1). To this end, we first consider the following homogeneous SBVP:

$$\begin{array}{l} (p(x)v(x))' = 0, \quad x \in (0,1], \\ v(0) = \alpha_1, \quad \beta_1 v(1) + \gamma_1 v'(1) = \eta_1. \end{array}$$

$$(2.1)$$

Note that the unique solution of (2.1) is given by

$$v(x) = \alpha_1 + \frac{1}{\mu} (\eta_1 - \alpha_1 \beta_1) h(x), \qquad (2.2)$$

where $h(x) = \int_0^x \frac{ds}{p(s)}$, $\mu = \beta_1 h(1) + \gamma_1 h'(1)$, $h(1) = \int_0^1 \frac{ds}{p(s)}$ and $h'(1) = \frac{1}{p(1)}$.

In order to construct the Green's function, we now consider the linear SBVP as

$$\begin{aligned} &(p(x)u'(x))' = q(x)F(x), \quad x \in (0, 1], \\ &u(0) = 0, \quad \beta_1 u(1) + \gamma_1 u'(1) = 0. \end{aligned}$$
 (2.3)

Integrating the Eq. (2.3) twice first from x to 1 and then from 0 to x, changing the order of integration, and applying the boundary conditions, we obtain

$$\begin{split} u(x) &= -\frac{1}{\mu} \int_{0}^{1} \beta_{1}h(x)h(\xi)q(\xi)F(\xi) \,\mathrm{d}\xi + \int_{0}^{x} h(\xi)q(\xi)F(\xi) \,\mathrm{d}\xi + \int_{x}^{1} h(x)q(\xi)F(\xi) \,\mathrm{d}\xi, \\ u(x) &= -\frac{1}{\mu} \int_{0}^{x} \beta_{1}h(x)h(\xi)q(\xi)F(\xi) \,\mathrm{d}\xi - \frac{1}{\mu} \int_{x}^{1} \beta_{1}h(x)h(\xi)q(\xi)F(\xi) \,\mathrm{d}\xi \\ &+ \int_{0}^{x} h(\xi)q(\xi)F(\xi) \,\mathrm{d}\xi + \int_{x}^{1} h(x)q(\xi)F(\xi) \,\mathrm{d}\xi, \\ u(x) &= \int_{0}^{x} h(\xi) \left(1 - \frac{\beta_{1}h(x)}{\mu}\right)q(\xi)F(\xi) \,\mathrm{d}\xi + \int_{x}^{1} h(x) \left(1 - \frac{\beta_{1}h(\xi)}{\mu}\right)q(\xi)F(\xi) \,\mathrm{d}\xi, \\ u(x) &= \int_{0}^{1} G(x,\xi)q(\xi)F(\xi) \,\mathrm{d}\xi, \end{split}$$

where the Green's function of the problem (2.3) is given by

$$G(x,\xi) = \begin{cases} h(x) \left(1 - \frac{\beta_1 h(\xi)}{\mu}\right), & 0 \le x \le \xi \le 1, \\ h(\xi) \left(1 - \frac{\beta_1 h(x)}{\mu}\right), & 0 \le \xi \le x \le 1. \end{cases}$$
(2.4)

It is easy to check that the function $G(x, \xi)$ satisfies all the properties of Green's function.

Making use of (2.2) and (2.4), we transform original SBVP (1.1) into the integral equation as

$$u(x) = \alpha_1 + \frac{1}{\mu} (\eta_1 - \alpha_1 \beta_1) h(x) + \int_0^1 G(x, \xi) q(\xi) f(\xi, u(\xi), p(\xi) u'(\xi)) \, \mathrm{d}\xi.$$
(2.5)

It should be noted that the (2.5) does not involve any undetermined coefficients to be determined.

We now decompose the solution u(x) by a series as follows

$$u(x) = \sum_{n=0}^{\infty} u_n(x),$$
 (2.6)

and the nonlinear function f(x, u(x), p(x)u'(x)) by a series as

$$f(x, u(x), p(x)u'(x)) = \sum_{n=0}^{\infty} A_n,$$
(2.7)

where A_n are Adomian's polynomials (Adomian and Rach 1983). Recently, in Duan (2010a,b) Duan developed several new efficient algorithms for rapid computer-generation of the one-variable and the multi-variable Adomian polynomials. El-Kalla (2012) deduced another programmable formula for Adomian polynomials

$$A_n = f(x, \chi_n, p\chi'_n) - \sum_{j=0}^{n-1} A_j,$$
(2.8)

where $\chi_n = \sum_{j=0}^n u_j$ is partial sum of the series solution $\sum_{j=0}^{\infty} u_j$. Substituting the series (2.6) and (2.7) into (2.5), we obtain

$$\sum_{n=0}^{\infty} u_n(x) = \alpha_1 + \frac{1}{\mu} (\eta_1 - \alpha_1 \beta_1) h(x) + \int_0^1 G(x, \xi) q(\xi) \sum_{n=0}^{\infty} A_n \, \mathrm{d}\xi.$$
(2.9)

Comparing both sides of (2.9), we obtain a new recursive scheme as

$$u_{0}(x) = \alpha_{1},$$

$$u_{1}(x) = \frac{1}{\mu}(\eta_{1} - \alpha_{1}\beta_{1})h(x) + \int_{0}^{1}G(x,\xi)q(\xi)A_{0} d\xi,$$

$$u_{j}(x) = \int_{0}^{1}G(x,\xi)q(\xi)A_{j-1} d\xi, \quad j \ge 2.$$
(2.10)

Using the recursive scheme (2.10), we can determine the solution components $u_j(x)$ and hence, the *n*-term truncated series solution can be obtained as

$$\chi_n = \sum_{j=0}^n u_j(x).$$
 (2.11)

Unlike ADM or MADM, the proposed recursive scheme (2.10) does not involve any undetermined coefficients to be determined. In other words, it avoids solving the sequence of transcendental equations for the undetermined coefficients.

3 Convergence analysis

In this section, we shall discuss the convergence analysis and the error estimation of the proposed scheme (2.10). To do this, let $\mathbb{X} = C[0, 1] \bigcap C^1(0, 1]$ be a Banach space with the norm

$$\|u\| = \max\{\|u\|_0, \|u\|_1\}, \quad u \in \mathbb{X},\tag{3.1}$$

where, $||u||_0 = \max_{x \in [0,1]} |u(x)|$ and $||u||_1 = \max_{x \in [0,1]} |p(x)u'(x)|$. It is well known that X is Banach space with norm (3.1) (see Bobisud 1990). The operator equation form of (2.5) is given by

$$u = \mathcal{N}(u), \tag{3.2}$$

where $\mathcal{N}: \mathbb{X} \to \mathbb{X}$ is a nonlinear operator given by

$$\mathcal{N}(u) = \alpha_1 + \frac{1}{\mu} (\eta_1 - \alpha_1 \beta_1) h(x) + \int_0^1 G(x, \xi) q(\xi) f(\xi, u(\xi), p(\xi) u'(\xi)) \, \mathrm{d}\xi.$$
(3.3)

We next discuss the existence of the unique solution of the Eq. (3.2). To do this, we first prove the following lemma.

Lemma 3.1 Let the assumptions (E_1) and (E_2) hold, then

(i) $M_1 := \max_{x \in [0,1]} \int_0^1 |G(x,\xi)q(\xi) d\xi| < \infty,$ (ii) $M_2 := \max_{x \in [0,1]} \int_0^1 |p(x)G_x(x,\xi)q(\xi) d\xi| < \infty, \text{ where } G_x(x,\xi) = \frac{\partial G(x,\xi)}{\partial x}.$

Proof (i) The maximum value of Green's function (2.4) is given by

$$C_1 = \max_{x,\xi \in [0,1]} |G(x,\xi)| = \frac{\mu}{4\beta_1}.$$
(3.4)

Using the assumption (E_2) and (3.4), we obtain

$$\int_{0}^{1} |G(x,\xi)q(\xi) \, \mathrm{d}\xi| \le \max_{x,\xi \in [0,1]} |G(x,\xi)| \int_{0}^{1} |q(\xi)| \, \mathrm{d}\xi = C_1 \int_{0}^{1} |q(\xi)| \, \mathrm{d}\xi < \infty.$$

Hence, $M_1 := \max_{x \in [0,1]} \int_0^1 |G(x,\xi)q(\xi) d\xi| < \infty.$ (ii) From (2.4), we see that

$$p(x)G_x(x,\xi) = \begin{cases} 1 - \frac{\beta_1 h(\xi)}{\mu}, & 0 \le x \le \xi \le 1, \\ \frac{-\beta_1 h(\xi)}{\mu}, & 0 \le \xi \le x \le 1. \end{cases}$$
(3.5)

Hence, we obtain $C_2 = \max_{x,\xi \in [0,1]} |p(x)G_x(x,\xi)| < \infty$.

Again using (E_2) , we have

$$\int_{0}^{1} |p(x)G_{x}(x,\xi)q(\xi) \,\mathrm{d}\xi| \le \max_{x,\xi\in[0,1]} |p(x)G_{x}(x,\xi)| \int_{0}^{1} |q(\xi)| \,\mathrm{d}\xi = C_{2} \int_{0}^{1} |q(\xi)| \,\mathrm{d}\xi < \infty.$$
(3.6)

Hence it follows that $M_2 := \max_{x \in [0,1]} \int_0^1 |p(x)G_x(x,\xi)q(\xi) d\xi| < \infty$.

Theorem 3.1 Let X be Banach space with norm given by (3.1). Also, assume that the nonlinear function f(x, u, pu') satisfies the Lipschitz condition (E_4) . Let $M = \max\{M_1, M_2\}$ and $L = \max\{L_1, L_2\}$, where the constants M_1 and M_2 given as in Lemma 3.1 and L_1 and L_2 are Lipschitz constants. If $\delta = 2LM < 1$, then the equation (3.2) has a unique solution in X.

Proof Using the Lemma 3.1 and the Lipschitz continuity of f, we have for any $u, v \in \mathbb{X}$,

$$\begin{split} \|\mathcal{N}u - \mathcal{N}v\|_{0} &= \max_{x \in [0,1]} \left| \int_{0}^{1} G(x,\xi)q(\xi) \left[f(\xi, u, pu') - f(\xi, v, pv') \right] d\xi \right|, \\ &\leq \max_{x \in [0,1]} \int_{0}^{1} |G(x,\xi)q(\xi) d\xi| \left| f(\xi, u, pu') - f(\xi, v, pv') \right|, \\ &\leq M_{1} \max_{x \in [0,1]} [L_{1}|u - v| + L_{2}|p(u' - v')|], \\ &\leq 2LM_{1} \max\{ \|u - v\|_{0}, \|u - v\|_{1} \} = 2LM_{1}\|u - v\|, \end{split}$$

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where $L = \max\{L_1, L_2\}$. Thus we have

$$\|\mathcal{N}u - \mathcal{N}v\|_0 \le 2LM_1 \|u - v\|.$$
(3.7)

Similarly, we have

$$\begin{split} \|\mathcal{N}u - \mathcal{N}v\|_{1} &= \max_{x \in [0,1]} \left| \int_{0}^{1} p(x)G_{x}(x,\xi)q(\xi)[f(\xi,u,pu') - f(\xi,v,pv')] \,\mathrm{d}\xi \right|, \\ &\leq \max_{x \in [0,1]} \int_{0}^{1} |p(x)G_{x}(x,\xi)q(\xi) \,\mathrm{d}\xi||f(\xi,u,pu') - f(\xi,v,pv')|, \\ &\leq M_{2} \max_{x \in [0,1]} \{L_{1}|u-v| + L_{2}|p(u'-v')|\}, \\ &\leq 2LM_{2} \max\{\|u-v\|_{0}, \|u-v\|_{1}\} = \leq 2LM_{2}\|u-v\|. \end{split}$$

Hence

$$\|\mathcal{N}u - \mathcal{N}v\|_1 \le 2LM_2 \|u - v\|.$$
(3.8)

Combining the estimates (3.7) and (3.8), we obtain

$$\|\mathcal{N}u - \mathcal{N}v\| = \max\{\|\mathcal{N}u - \mathcal{N}v\|_{0}, \|\mathcal{N}u - \mathcal{N}v\|_{1}\}, \\ \leq \max\{2LM_{1}\|u - v\|, 2LM_{2}\|u - v\|\}, \\ = \delta\|u - v\|,$$
(3.9)

where $\delta = 2LM$ and $M = \max\{M_1, M_2\}$. If $\delta < 1$, then $\mathcal{N} : \mathbb{X} \to \mathbb{X}$ is contraction mapping and hence by the Banach contraction mapping theorem, the Eq. (3.2) has a unique solution in \mathbb{X} .

Now let $\{\chi_n = \sum_{j=0}^n u_j\}$ be a sequence of partial sums of the series solution $\sum_{j=0}^{\infty} u_j$. Using (2.10) and (2.11), we have

$$\chi_n = u_0 + \sum_{j=1}^n u_j = \alpha_1 + \frac{1}{\mu} (\eta_1 - \alpha_1 \beta_1) h(x) + \sum_{j=1}^n \left[\int_0^1 G(x, \xi) q(\xi) A_{j-1} \, \mathrm{d}\xi \right],$$

= $\alpha_1 + \frac{1}{\mu} (\eta_1 - \alpha_1 \beta_1) h(x) + \int_0^1 G(x, \xi) q(\xi) \sum_{j=0}^{n-1} A_j \, \mathrm{d}\xi.$ (3.10)

Using (2.8) in (3.10), it follows that

$$\chi_n = \alpha_1 + \frac{1}{\mu} (\eta_1 - \alpha_1 \beta_1) h(x) + \int_0^1 G(x, \xi) q(\xi) f(x, \chi_{n-1}, p \chi'_{n-1}) \, \mathrm{d}\xi.$$
(3.11)

which is equivalent to the following operator equation

$$\chi_n = \mathcal{N}(\chi_{n-1}), \quad n = 1, 2, \dots$$
 (3.12)

In following theorem, we give the convergence of the sequence χ_n to the exact solution *u* of (3.2).



Theorem 3.2 Let $\mathcal{N}(u)$ be the nonlinear operator defined by (3.3) is contractive that is $\|\mathcal{N}(u) - \mathcal{N}(v)\| \le \delta \|u - v\|$, for all $u, v \in \mathbb{X}$ with $0 < \delta < 1$. If $\|u_1\| < \infty$, then the sequence χ_n defined by (2.11) converges to the exact solution u of (3.2).

Proof Using the relation (3.12) and the estimate (3.9), we have

$$\|\chi_{m+1} - \chi_m\| = \|\mathcal{N}(\chi_m) - \mathcal{N}(\chi_{m-1})\| \le \delta \|\chi_m - \chi_{m-1}\|.$$

Thus we have

$$\|\chi_{m+1} - \chi_m\| \le \delta \|\chi_m - \chi_{m-1}\| \le \delta^2 \|\chi_{m-1} - \chi_{m-2}\|, \le \cdots \le \delta^m \|\chi_1 - \chi_0\|.$$

For all $n, m \in \mathbb{N}$, with n > m, consider

$$\begin{aligned} \|\chi_n - \chi_m\| &= \|(\chi_n - \chi_{n-1}) + (\chi_{n-1} - \chi_{n-2}) + \dots + (\chi_{m+1} - \chi_m)\|, \\ &\leq \|\chi_n - \chi_{n-1}\| + \|\chi_{n-1} - \chi_{n-2}\| + \dots + \|\chi_{m+1} - \chi_m\|, \\ &\leq [\delta^{n-1} + \delta^{n-2} + \dots + \delta^m]\|\chi_1 - \chi_0\|, \\ &= \delta^m [1 + \delta + \delta^2 + \dots + \delta^{n-m-1}]\|\chi_1 - \chi_0\|, \\ &= \delta^m \left(\frac{1 - \delta^{n-m}}{1 - \delta}\right) \|u_1\|. \end{aligned}$$

Since $0 < \delta < 1$ so, $(1 - \delta^{n-m}) < 1$, and $||u_1|| < \infty$, it follows that

$$\|\chi_n - \chi_m\| \le \frac{\delta^m}{1 - \delta} \|u_1\|,$$
 (3.13)

which converges to zero, that is, $\|\chi_n - \chi_m\| \to 0$, as $m \to \infty$. This implies that there exits a χ such that $\lim_{n\to\infty} \chi_n = \chi$. Since, we have $u = \sum_{n=0}^{\infty} u_n = \lim_{n\to\infty} \chi_n$, that is, $u = \chi$ which is exact solution of (3.2).

In the following theorem we obtain the error bounds for the approximate solution χ_n .

Theorem 3.3 Let u(x) be the exact solution of (3.2). Let χ_m be the sequence of approximate series solution defined by (3.2). Then there holds

$$\max_{x \in [0,1]} \left| u(x) - \sum_{j=0}^{m} u_j(x) \right| \le \frac{\delta^m}{(1-\delta)} \max_{x \in [0,1]} |u_1|.$$

Proof Using the estimate (3.13), for $n \ge m$, $n, m \in \mathbb{N}$, we have

$$\|\chi_n-\chi_m\|\leq \frac{\delta^m}{1-\delta}\|u_1\|$$

Since $\lim_{n\to\infty} \chi_n = u$, fixing *m* and letting $n \to \infty$, we obtain

$$\|u - \chi_m\| \le \frac{\delta^m}{1 - \delta} \max_{x \in [0, 1]} |u_1|.$$
(3.14)

Hence, we have

$$\max_{x \in [0,1]} \left| u(x) - \sum_{j=0}^{m} u_j(x) \right| \le \frac{\delta^m}{(1-\delta)} \max_{x \in [0,1]} |u_1|.$$

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4 Numerical illustrations

In this section, the proposed recursive scheme (2.10) is applied to solve SBVP of form (1.1). In order to check the efficiency of proposed scheme (2.10), we shall consider one linear and two strongly nonlinear singular problems.

Example 4.1 We first consider linear SBVPs with derivative dependence

$$\begin{cases} (x^{\alpha}u')' = x^{\alpha+\beta-2}(\beta xu' + \beta(\alpha+\beta-1)u), & x \in (0,1], \\ u(0) = 1, & u(1) = e, \end{cases}$$

$$(4.1)$$

with the exact solution $u(x) = e^{x^{\beta}}$, $0 \le \alpha < 1$ and $\beta > 0$ are any real constants.

According to proposed scheme (2.10), the (4.1) can be converted into following recursive scheme

$$u_{0} = 1, u_{1} = (e - 1)x^{1-\alpha} + \int_{0}^{1} G(x, \xi)\xi^{\alpha+\beta-2}A_{0} d\xi, u_{j} = \int_{0}^{1} G(x, \xi)\xi^{\alpha+\beta-2}A_{j-1} d\xi, \quad j \ge 2.$$

$$(4.2)$$

where,

$$A_j = (\beta x u'_j + \beta (\alpha + \beta - 1) u_j).$$

$$(4.3)$$

For the demonstration purpose, we pick some specific values of α and β .

For $\alpha = 0.5$, $\beta = 1$, using (4.2) and (4.3), we obtain the components u_n as:

$$u_{0} = 1,$$

$$u_{1} = 0.718282x^{0.5} + x,$$

$$u_{2} = -0.978855x^{0.5} + 0.478855x^{1.5} + 0.5x^{2},$$

$$u_{3} = 0.294361x^{0.5} - 0.65257x^{1.5} + 0.191542x^{2.5} + 0.166667x^{3},$$

$$u_{4} = -0.0316058x^{0.5} + 0.196241x^{1.5} - 0.261028x^{2.5} + 0.0547262x^{3.5} + 0.0416667x^{4},$$

$$\vdots$$

For $\alpha = 0.5$, $\beta = 2.5$, using (4.2), the components u_n are obtained as:

$$u_{0} = 1,$$

$$u_{1} = 0.718282x^{0.5} + x^{2.5},$$

$$u_{2} = -1.09857x^{0.5} + 0.598568x^{3} + 0.5x^{5},$$

$$u_{3} = 0.47673x^{0.5} - 0.915473x^{3} + 0.272076x^{5.5} + 0.166667x^{7.5},$$

$$u_{4} = -0.107842x^{0.5} + 0.397275x^{3} - 0.416124x^{5.5} + 0.0850239x^{8} + 0.0416667x^{10},$$

$$\vdots$$

Note that all above components are computed by computer algebra system, such as 'MATH-EMATICA'. Now, we define absolute error function as $E_n(x) = |\chi_n(x) - u(x)|, n = 1, 2, ...$ and the maximum absolute errors as

$$E^{n} = \max_{x \in (0,1]} E_{n}(x)$$
(4.4)

where u(x) is exact solution and $\chi_n(x)$ is *n*-term approximate series solution. In order test efficiency and accuracy of the proposed recursive scheme (2.10), we exhibit the maximum

α	<i>E</i> ⁽⁴⁾	<i>E</i> ⁽⁵⁾	E ⁽⁶⁾	<i>E</i> ⁽⁷⁾	E ⁽⁸⁾	E ⁽⁹⁾	E ⁽¹⁰⁾
0.25	9.466E-04	1.593E-04	3.093E-05	3.981E-06	9.456E-07	9.533E-08	1.907E-08
0.5	6.549E-04	1.412E-04	6.265E-05	1.215E-05	1.467E-06	3.584E-07	3.261E-08
0.75	8.356E-04	2.321E-04	3.615E-05	1.792E-05	3.860E-06	2.674E-07	8.044E-08

Table 1 Maximum absolute error estimate for Example 4.1, when $\beta = 1$

Table 2 Maximum absolute error estimate for Example 4.1, when $\beta = 2.5$

α	$E^{(4)}$	$E^{(5)}$	$E^{(6)}$	$E^{(7)}$	$E^{(8)}$	E ⁽⁹⁾	$E^{(10)}$
0.25	9.211E-04	1.749E-04	8.364E-05	2.083E-05	5.112E-06	5.560E-07	6.880E-08
0.50	8.654E-04	2.141E-04	6.139E-05	1.397E-05	5.946E-06	9.377E-07	6.738E-08
0.75	6.549E-04	1.412E-04	6.265E-05	1.215E-05	1.538E-06	4.065E-07	4.379E-08

absolute error estimate for various values of α and β in Tables 1 and 2. From these numerical results, it is observed that as the number of iterations increases the maximum absolute error decreases. Furthermore, the comparison between our approximate series solutions χ_2 , χ_3 and the exact solution is plotted in Fig. 1, it is shown that our three terms approximate solution χ_3 is coincides with the exact solution.

Example 4.2 Consider the nonlinear SBVPs with derivative dependence

$$\begin{aligned} & (x^{\alpha}u')' = x^{\alpha-1}(-xu'e^u - \alpha e^u), \quad x \in (0,1], \\ & u(0) = \ln\left(\frac{1}{2}\right), \quad u(1) = \ln\left(\frac{1}{3}\right), \end{aligned}$$

$$(4.5)$$

and the exact solution is $u(x) = \ln\left(\frac{1}{2+x}\right)$, where $0 \le \alpha < 1$.

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According to proposed scheme (2.10), where $p(x) = x^{\alpha}$, $q(x) = x^{\alpha-1}$, $\alpha_1 = \ln(\frac{1}{2})$, $\beta_1 = 1$, $\gamma_1 = 0$ and $\eta_1 = \ln(\frac{1}{3})$, we have the recursive scheme:



Fig. 1 Comparison of the approximate series χ_2 , χ_3 and the exact *u* solutions of Example 4.1, when $\mathbf{a} \alpha = 0.5$ and $\beta = 1$ **b** $\alpha = 0.5$ and $\beta = 2.5$

α	$E^{(4)}$	<i>E</i> ⁽⁵⁾	E ⁽⁶⁾	<i>E</i> ⁽⁷⁾	E ⁽⁸⁾	E ⁽⁹⁾	$E^{(10)}$
0.25	5.790E-04	2.181E-04	5.069E-05	8.737E-06	2.240E-06	6.142E-07	5.882E-08
0.50	9.709E-04	3.531E-04	4.566E-05	2.136E-05	4.025E-06	1.290E-06	3.344E-07
0.75	7.733E-04	3.486E-04	8.713E-05	2.483E-05	8.272E-06	1.146E-06	4.819E-07

 Table 3
 Maximum absolute error estimate for Example 4.2

1 (1)

$$u_{0} = \ln\left(\frac{1}{2}\right),$$

$$u_{1} = \left[\ln\left(\frac{1}{3}\right) - \ln\left(\frac{1}{2}\right)\right] x^{1-\alpha} + \int_{0}^{1} G(x,\xi)\xi^{\alpha-1}A_{0} \,\mathrm{d}\xi,$$

$$u_{j} = \int_{0}^{1} G(x,\xi)\xi^{\alpha-1}A_{j-1} \,\mathrm{d}\xi, \quad j \ge 2.$$

$$(4.6)$$

h

Using the formula (1.7), the Adomian's polynomials for $f = -(xe^{u}u' + e^{u}\alpha)$ about $u_0 = \ln(\frac{1}{2})$ are calculated as:

$$A_{0} = -e^{u_{0}}(xu'_{0} + \alpha),$$

$$A_{1} = -e^{u_{0}}(xu'_{1} + u_{1}\alpha),$$

$$A_{2} = -e^{u_{0}}\left(x(u'_{2} + u_{1}u'_{1}) + \left(u_{2} + \frac{u^{2}_{1}}{2}\right)\alpha\right),$$

$$A_{3} = -e^{u_{0}}\left(x\left(u'_{3} + u'_{2}u_{1} + u'_{1}\left(\frac{u^{2}_{1}}{2} + u_{2}\right)\right) + \left(u_{3} + u_{1}u_{2} + \frac{u^{3}_{1}}{6}\right)\alpha\right),$$

$$\vdots$$

$$(4.7)$$

For $\alpha = 0.5$, using (4.6) and (4.7), we obtain the successive solution components u_n as: $u_0 = -0.693147$, $u_1 = 0.0945349x^{0.5} - 0.5x$, $u_2 = -0.0934884x^{0.5} - 0.0315116x^{1.5} + 0.125x^2$, $u_3 = -0.00413483x^{0.5} + 0.0311628x^{1.5} - 0.00111711x^2 + 0.0157558x^{2.5} - 0.0416667x^3$, $u_4 = 0.00321966x^{0.5} + 0.00137828x^{1.5} + 0.00220948x^2 - 0.0156096x^{2.5} + 0.00105504x^3 - 0.00787791x^{3.5} + 0.015625x^4$, :

In similar manner as we did in last example Table 3 shows the maximum absolute error estimate for various values of α . From these results, one can observe that as the number of iterations increases, the maximum absolute error decreases. Furthermore, we plot the approximate series solutions χ_1 , χ_3 with the exact solution in Fig.2. It is clear from the figure that only three term approximate series solution χ_3 is almost identical to the exact solution u(x).

Example 4.3 Consider the nonlinear SBVP

$$\begin{aligned} & (x^{\alpha}u')' = -x^{\alpha+\beta-2}(\beta x e^{u}u' + \beta(\alpha+\beta-1)e^{u}), \quad x \in (0,1], \\ & u(0) = \ln\left(\frac{1}{4}\right), \quad u(1) = \ln\left(\frac{1}{5}\right), \end{aligned}$$

$$(4.8)$$

with exact solution $u(x) = \ln\left(\frac{1}{4+x^{\beta}}\right)$.

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Fig. 2 Comparison of the approximate series χ_1 , χ_3 and the exact *u* solutions of Example 4.2, when **a** $\alpha = 0.5$ and $\beta = 1$



According to proposed scheme (2.10), where $p(x) = x^{\alpha}$, $q(x) = x^{\alpha+\beta-2}$, $\alpha_1 = \ln\left(\frac{1}{4}\right)$, $\beta_1 = 1$, $\gamma_1 = 0$, and $\eta_1 = \ln\left(\frac{1}{5}\right)$, we obtain:

$$u_{0} = \ln\left(\frac{1}{4}\right), u_{1} = \left[\ln\left(\frac{1}{5}\right) - \ln\left(\frac{1}{4}\right)\right] x^{1-\alpha} + \int_{0}^{1} G(x,\xi)\xi^{\alpha+\beta-2}A_{0} \,\mathrm{d}\xi, u_{j} = \int_{0}^{1} G(x,\xi)\xi^{\alpha+\beta-2}A_{j-1} \,\mathrm{d}\xi, \quad j \ge 2.$$

$$(4.9)$$

Using the formula (1.7) the Adomian's polynomials for $f = -(\beta x e^u u' + \beta (\alpha + \beta - 1)e^u)$ about u_0 are obtained as:

$$A_{0} = -\beta e^{u_{0}} (xu_{0}' + (\alpha + \beta - 1)) A_{1} = -\beta e^{u_{0}} (xu_{1}' + u_{1}(\alpha + \beta - 1)), A_{2} = -\beta e^{u_{0}} \left(x(u_{2}' + u_{1}u_{1}') + (u_{2} + \frac{u_{1}^{2}}{2})(\alpha - \beta + 1) \right), A_{3} = -\beta e^{u_{0}} \left(x \left(u_{3}' + u_{2}'u_{1} + u_{1}' \left(\frac{u_{1}^{2}}{2} + u_{2} \right) \right) + \left(u_{3} + u_{1}u_{2} + \frac{u_{1}^{3}}{6} \right) (\alpha + \beta - 1) \right),$$

:
$$(4.10)$$

As we did before we pick some specific values of α and β .

For $\alpha = 0.5$, $\beta = 1$, using (4.9) and (4.10), we obtain the components u_n as

$$u_{0} = -1.38629436,$$

$$u_{1} = 0.0268564x^{0.5} - 0.25x,$$

$$u_{2} = -0.0267739x^{0.5} - 0.00447607x^{1.5} + 0.03125x^{2},$$

$$u_{3} = -0.0003279x^{0.5} + 0.0044623x^{1.5} - 0.000045079x^{2} + 0.00111902x^{2.5} - 0.0052083x^{3},$$

$$u_{4} = 0.00025327x^{0.5} + 0.0000546545x^{1.5} + 0.0000898816x^{2} - 0.0011159x^{2.5} + 0.0000212874x^{3} - 0.0002797x^{3.5} + 0.000976563x^{4},$$

$$\vdots$$

				-			
α	$E^{(4)}$	<i>E</i> ⁽⁵⁾	E ⁽⁶⁾	<i>E</i> ⁽⁷⁾	E ⁽⁸⁾	E ⁽⁹⁾	$E^{(10)}$
0.25	4.842E-05	1.112E-05	1.107E-06	1.228E-07	2.303E-08	2.156E-09	3.541E-10
0.50	9.426E-05	1.523E-05	1.523E-06	2.491E-07	2.687E-08	4.012E-09	5.403E-10
0.75	1.792E-04	1.164E-05	2.779E-06	3.102E-07	4.911E-08	6.759E-09	9.224E-10

Table 4 Maximum absolute error estimate for Example 4.3, when $\beta = 1$

Table 5 Maximum absolute error estimate for Example 4.3, when $\beta = 3.5$

α	$E^{(4)}$	$E^{(5)}$	$E^{(6)}$	$E^{(7)}$	$E^{(8)}$	E ⁽⁹⁾	$E^{(10)}$
0.25	1.881E-04	1.509E-05	3.038E-06	3.133E-07	4.782E-08	6.467E-09	1.127E-09
0.5	2.191E-04 2.377E-04	2.895E-05	3.757E-06	6.245E-07	6.926E-08	0.958E-09 1.299E-08	1.327E-09 1.386E-09

For $\alpha = 0.5$, $\beta = 3.5$, using (4.9) and (4.10), we have components u_n as follows:

$$\begin{split} &u_0 = -1.38629436, \\ &u_1 = 0. + 0.0268564x^{0.5} - 0.25x^{3.5}, \\ &u_2 = -0.0253752x^{0.5} - 0.00587485x^4 + 0.03125x^7, \\ &u_3 = -0.00174107x^{0.5} + 0.00555081x^4 - 0.000070123x^{4.5} + 0.00146871x^{7.5} \\ &-0.00520833x^{10.5}, \\ &u_4 = 0.000230726x^{0.5} + 0.000380859x^4 + 0.000132511x^{4.5} - 5.6497931825 \times 10^{-7}x^5 \\ &-0.0013877x^{7.5} + 0.0000347878x^8 - 0.000367178x^{11} + 0.000976563x^{14}, \\ &\vdots \end{split}$$

In similar fashion, Tables 4 and 5 show the maximum absolute error for different values of α and β . It is obvious from these results that the error decreases as one increases the terms in approximate solution. In addition, by plotting approximate solutions χ_2 , χ_3 and the exact solution in Fig. 3, we have shown that only few terms are required for acceptable solution.



Fig.3 Comparison of the approximate series χ_2 , χ_3 and the exact *u* solutions of Example 4.3, when $\mathbf{a} \alpha = 0.5$ and $\beta = 1$ **b** $\alpha = 0.5$ and $\beta = 3.5$



Remark It can be seen from the numerical results of all three examples discussed in this section that only three terms are sufficient for obtaining good approximations to the exact solution.

5 Conclusion

In this article, we have verified the proposed recursive scheme by solving one linear and two nonlinear singular two-point boundary value problems. The accuracy of the numerical results shows that the proposed method is suitable for solving such problems. Unlike ADM or MADM, the proposed method does not involve any undetermined coefficients to be determined. In fact, the proposed method provides a direct recursive scheme for obtaining the approximations of the exact solution.

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