RESEARCH ARTICLE

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## Post-processing of ABS Replicas with Vapour Smoothing for Investment Casting Applications

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Abstract The need of customized products with tight dimensional tolerances, lower production cost and shorter lead times led to the development of additive manufacturing techniques like fused deposition modelling (FDM). The digitally fabricated ABS patterns prepared on FDM needs to be processed by vapour smoothing (VS) in order to reduce the surface roughness. The post-processing of FDM-based patterns/replicas with VS increases their density, which increases heat input and complexities in ash removal during burnout stage from ceramic shell in investment casting (IC). This study highlights the step-bystep procedure for controlling the density of master patterns/replicas after processing with VS for IC applications.

**Keywords** FDM · Vapour smoothing · ABS replicas · Investment casting · Density

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#### **1** Introduction

The additive manufacturing techniques have revolutionized the rapid investment casting (IC) process where complicated freeform replicas are directly manufactured from CAD model and are casted within few hours [1]. Traditional IC process has been employed for fabricating highly precise castings with intricate designs, but longer tooling process (using wax patterns) consumes major lead times. With the induction of rapid tooling, IC process has been accelerated and has been widely implemented in industries for ornamental, automotive, aerospace, military, and medical applications [2]. Fused deposition modelling (FDM) utilizes acrylonitrile butadiene styrene (ABS) as part material: a strong, non-toxic, biocompatible and chemical resistant and is replacement for wax patterns [3, 4]. FDM has a vital role among various freeform fabrication techniques due to advantages of easy material change, low maintenance cost, quick production, compact size, low-temperature operation, minimum supervision and tolerances within  $\pm 0.01$  mm [5].

In spite of these advantages, the poor surface finish comes out to be major disadvantage which is an inherent defect due to layer-by-layer deposition of semi-molten plastic beads. The peaks and valleys of surface profile of ABS replicas are adopted by ceramic mould and casting during investment casting process [6]. The poor surface finish casting needs post-finishing processes which may induce dimensional variability and restricts its application for medical implants. The minute surface irregularities or dimensional variation in implants may engender pain, discomfort and other post-operative complexities.

Baul and Kumar [7] reviewed various approaches to improve surface finish of FDM-based ABS parts (i.e. postprocessing, adaptive slicing, and optimization of FDM parameters, i.e. layer thickness, orientation angle, raster angle). The smaller layer thickness yielded minimum roughness but increased production time and cost. The adaptive slicing strategy requires nozzle with variable tip diameter which adds to equipment cost. Traditional surface finishing have been adopted as post-processing of ABS parts, but mechanical finishing actuated dimensional inaccuracy and edge cutting of small details. Chemical finishing using acetone bath (90% acetone and 10% water) has been reported [5] which proved to be economic and fast for freeform fabricated ABS products. The increase in average weight has been reported with shrinkage in volume due to absorption of chemical by ABS parts. The mechanical testing of chemically finished ABS parts showed lower tensile strength, greater ductility and increased flexural strength [4, 5].

In vapour smoothing (VS), the dedicated smoothing and cooling chambers treat the parts under controlled manner. The penetration of vapours causes temporary surface flattening and reflowing which results in glossy finish with minimum dimensional variation [8].

ABS replicas are finished using aforesaid process for IC applications, but the pilot experiments indicated comparatively higher heat input and burnout temperature as compared to untreated replicas. Generally, ABS replicas are flashed at 1120 °C, but vapour-treated replicas need additional 10 °C for higher density, vapour absorption, or bonding strength [9]. The higher burnout temperature of ABS may create internal cracks in ceramic shell [10] and may also result into problems related to ash removal in IC applications. During heating, the vapours trapped in ABS may cause blow holes on inner surface of ceramic shell which exit with high pressure and velocity [11].

The present study has been focused to investigate the reasons of higher heat consumption and selection of optimum set of parameters to minimize the energy input to achieve ultra smooth surface finish of ABS replicas with minimum hindrance to execute IC process. The various process parameters of combined FDM and VS process have been varied to access their impact on density change. As a practical application for biomedical field, the hip prosthesis has been selected as benchmark.

#### 2 Materials and Methods

The replica of hip prosthesis has been designed in Solid-Works 2014 and converted into STL format via CatalystEx. FDM apparatus uPrint SE has been selected with ABS-P400 plastic material for fabrication of replicas of hip prostheses. The vapour finishing has been performed by Finishing Touch Smoothing Station supplied by Stratasys, Inc., USA, which has cooling chamber and smoothing chamber  $(330 \times 406 \times 508 \text{ mm})$  as shown in Fig. 1.

Initially, the parts are hanged by cotton string in cooling chamber (precooling) for few minutes and thereafter in smoothing chamber for few seconds where parts are vapour-treated at constant temperature (65 °C) by inbuilt heaters [12]. After smoothing, the post-cooling is done for few minutes in cooling chamber at constant temperature (0 °C) which helps in the resettlement of reflowed layers. The smoothing fluid MCC-SSF01P (boiling point 43 °C) supplied by Microcare Corp., USA, is 30% decafluoropentane and 70% trans-dichloroethylene. It readily vaporizes and rises above smoothing chamber and is condensed by cooling coils running above the chambers and recirculated in smoothing chamber. Moreover, the opening and closing of smoothing camber are controlled by pneumatic lid operated by foot switch. The provision of exhaust of vapours to atmosphere has been made in cooling chamber where exhaust fan extracts the vapours from and within surface of parts. The whole precooling-smoothingpost-cooling is repeated till desired finish is achieved.

Based on the reported literature, it has been found that various FDM parameters such as layer thickness, orientation angle, raster angle and density significantly affect the surface finish, strength, raster arrangement of parts, but orientation angle and density has been selected as FDM control parameters for present experimentation. There are four control parameters of vapour smoothing apparatus (as shown in Table 1) as recommended by manufacturer, i.e. precooling time, smoothing time, post-cooling time and number of cycles, and their range has been decided as per operation manual [12].

The fluid pressure, fluid concentration, temperature of heaters and refrigeration system for cooling coils cannot be varied in the set up available and thus kept as fixed parameters. The Taguchi design of experiments approach



Fig. 1 Specimen of replica of hip prostheses

Parameters	Symbol	Level		
		1	2	3
FDM				
Orientation angle (°)	A	0	90	_
Density	В	Low	High	Solid
VS				
Precooling time (min)	С	10	15	20
Smoothing time (s)	D	10 10	15	20 20
Post-cooling time (min)	E		15	
Number of cycles F		1	2	3

Table 1 FDM and VS control parameters

has been implemented to minimize number of iterations and error keeping limited number of experimental runs, thus saving cost and time. To study impact of six factors,  $L_{18}$  orthogonal array has been formulated where one factor at two levels and five factors at three levels have been tested. The weight of replicas of hip prosthesis has been measured before and after vapour smoothing with Citizen digital weight-measuring machine having least count 0.0001 g and capacity up to 220 g. The density, being ratio of weight and volume, has been calculated by dividing weights of individual replica by constant volume (10.228 cm<sup>3</sup>). The percentage change in density has been taken as output parameter due to variation in initial weights of replicas manufactured at different densities.

The output is made robust against varying operating and environmental conditions at production stage by maximizing signal-to-noise (S/N) ratio. Thus, best levels of different parameters have been determined to minimize the noise effect. S/N ratios for six factors have been determined by selecting smaller the better characteristic to minimize the change in density. The ANOVA analysis based on S/Nratios has been performed for statistical validation of results and error calculations and to evaluate individual contribution of process parameters using Minitab 17. The signal-to-noise is calculated using the formula:

$$S/N = -10 \log_{10} \frac{1}{n} \sum y^2$$

where *y* is response.

### **3** Results and Discussion

The initial and final densities are calculated by dividing weights by part volume which showed varying density of parts manufactured at low, high, and solid density as shown in Table 2. This is attributed to internal raster arrangements extruded by machine head and gap between consecutive layers. The weight gain has been experienced in ABS patterns after vapour exposure similar to Galantucci et al. [5], where liquid acetone increased weight of test part. The observations of *S*/*N* ratios plot (see Fig. 2) reveals major contribution of smoothing time (*D*), precooling time (*E*) and number of cycles (*F*), while other parameters have least contribution for increasing the density ( $\%\Delta\rho$ ).

The smoothing time exerted maximum impact as larger exposure to vapours increased vapour absorption and bonding strength of internal raster's which further increased density of parts. The  $\%\Delta\rho$  is also controlled by increase in post-cooling time as fan extracts the vapours trapped on and inside surface with an increase in the cooling rate.

Similarly, larger number of cycles involves more vapour exposure (smoothing time) which increased  $\%\Delta\rho$ . The same trend has been endorsed by analysis of variance (ANOVA) results for *S/N* values calculated with 95% confidence level shown in Table 3.

The  $F_{0.05(1,6)}$  value from the standard table (critical values of *F*-distribution at 0.05 significance level) is 5.99, and thus, the parameters having *F* value more than value are significant, while remaining are insignificant. The orientation angle, initial density and precooling time do not significantly contribute to density change. The optimum combinations of parameters of FDM and VS retrieved from *S*/*N* plot are  $A_2B_2C_2D_1E_3F_1$ . The regression equation calculated by Minitab 17 software is given as:

S/N = 12.89 + 0.04A - 0.083B - 0.354C - 2.464D+ 1.869E - 2.347F

For parameters  $A_2B_2C_2D_1E_3F_1$ ,  $S/N_{opt} = 12.892$ 

The corresponding value response  $(\%\Delta\rho)$  is calculated using equation:

Replica no.	Run order	A	В	C	7.	D	Ε	F	Initial density (g/cm <sup>3</sup> )	Final density (g/cm <sup>3</sup> )	Percentage improvement in density $(\%\Delta\rho)$	S/N ratio
1	3	1	1	1		1	1	1	0.61441	0.61619	0.29	10.7520
2	7	1	1	2		2	2	2	0.61445	0.61697	0.41	7.7443
3	8	1	1	3		3	3	3	0.61444	0.61923	0.78	2.1581
4	16	1	2	1		1	2	2	0.82140	0.82526	0.47	6.5580
5	2	1	2	2		2	3	3	0.82145	0.82399	0.31	10.1728
6	10	1	2	3		3	1	1	0.82137	0.82663	0.64	3.8764
7	12	1	3	1		2	1	3	0.95563	0.96326	0.80	1.9382
8	5	1	3	2		3	2	1	0.95547	0.96120	0.67	3.4785
9	14	1	3	3		1	3	2	0.95559	0.95903	0.36	8.8739
10	17	2	1	1		3	3	2	0.61418	0.61793	0.61	4.2934
11	13	2	1	2		1	1	3	0.61412	0.61811	0.65	3.7417
12	18	2	1	3		2	2	1	0.61215	0.61655	0.39	8.1787
13	1	2	2	1		2	3	1	0.82086	0.82291	0.25	12.0412
14	15	2	2	2		3	1	2	0.82083	0.82722	0.78	2.1581
15	4	2	2	3		1	2	3	0.82092	0.82613	0.64	3.8764
16	6	2	3	1		3	2	3	0.93146	0.93901	0.81	1.8303
17	9	2	3	2		1	3	1	0.93130	0.93326	0.21	13.5556
18	11	2	3	3		2	1	2	0.93163	0.93620	0.49	6.1961

Table 2 Observations regarding percentage change in density with S/N ratio

Main effects plot for <u>S/N</u> Ratios



Fig. 2 S/N ratios plot at for different parameters and levels

 $y_{\rm opt}^2 = 1/10^{S/N_{\rm opt}/10}$ 

The percentage change in density predicted at set of optimum parameters is 0.2267%. The results of regression

equation has been confirmed by performing the vapour smoothing process again on three test replicas at optimum parameter levels  $(A_2B_2C_2D_1E_3F_1)$  which resulted in 0.2288% increase in density. The minimum variation

Source	DoF	Seq SS	Seq MS	F value	P value	Significance	Percentage contribution
A	1	0.006	0.0057	0.00	0.969	No	0.003
В	2	0.677	0.3384	0.10	0.909	No	0.286
С	2	4.948	2.4741	0.71	0.528	No	2.09
D	2	93.67	46.835	13.48	0.006	Yes	39.67
Ε	2	49.44	24.714	7.11	0.026	Yes	20.93
F	2	66.54	33.269	9.57	0.014	Yes	28.18
Error	6	20.85	3.4751				8.83
Total	17	236.119					

Table 3 ANOVA results for percentage change in density

between predicted and confirmatory experiments ensured robustness and consistency in VS process at optimum parameters.

The vapour smoothing process heats the plastic layers (beads), and they partially meltdown to fuse with adjacent layers which increased bonding strength and induced shrinkage. Similar structural changes have been experienced by Ahnet al. [13] when parts are heated at 170 °C to increase optical transmissvity. The time of vapour exposure has major influence on increasing density as heated plastic raster fuse together and air gaps are reduced inside the plastic replicas. The voids in internal surface are considerably reduced as vapour smoothing cycles are repeated. The internal raster arrangements also significantly vary

initial densities, and thus parts have different mechanical properties depending upon FDM process parameters [14]. Then parts manufactured at low-density settings saves material cost, fabrication time and energy input [15]. The material reflows and settles to give smooth surface and the surface finish increases with number of cycles. After vapour exposure, ABS parts are cooled which takes out the hot vapours and thus increases cooling rate.

The SEM micrograph (see Fig. 3) depicts surface modification after three vapour smoothing cycles through top and transverse view of upper surface of ABS replicas. An increase in road width can be distinguished in top view due fusion with adjacent roads. The peaks and valleys of surface roughness formed as consequence of layer



Fig. 3 SEM images of top view a before smoothing, b after smoothing and transverse view, c before smoothing, d after smoothing

manufacturing technique are visible in transverse view which is completely smoothed after three smoothing cycles. There has been slight increase in road width (Fig. 3a, b) while considerable reduction in layer height (Fig. 3c, d) when compared before and after three vapour smoothing cycles.

The material flows from peaks and settles down in valleys under surface tension forces to attain minimum surface area [16]. The selection of optimum parameters for minimum density change helps to reduce burnout complications of replicas and the minimum quantity of vapours in ceramic shell during IC. The results are in line with the observations made by other investigators [17–19].

#### 4 Conclusions

Based upon increased weight of FDM replicas after vapour smoothing cycles, the increase in density of parts has been noted which has been greatly influenced by smoothing time and post-cooling time. The post-cooling of parts extracts extra accumulated heat and vapours absorbed within surface which reduced density gain. The parts should have longer cooling time and minimum exposure to vapours to achieve controlled density but the smoothing cycles should be repeated depending upon required level of surface finish. Thus, it is recommended to maintain the minimum gap of 24 h between two consecutive smoothing cycles.

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