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Ensemble of subspace discriminant classifers for schistosomal liver fbrosis staging in mice microscopic images

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Abstract

Schistosomiasis is one of the dangerous parasitic diseases that afect the liver tissues leading to liver fbrosis. Such disease has several levels, which indicate the degree of fbrosis severity. To assess the fbrosis level for diagnosis and treatment, the microscopic images of the liver tissues were examined at their diferent stages. In the present work, an automated staging method is proposed to classify the statistical extracted features from each fbrosis stage using an ensemble classifer, namely the subspace ensemble using linear discriminant learning scheme. The performance of the subspace/discriminant ensemble classifer was compared to other ensemble combinations, namely the boosted/ trees ensemble, bagged/trees ensemble, subspace/KNN ensemble, and the RUSBoosted/trees ensemble. The simulation results established the superiority of the proposed subspace/discriminant ensemble with 90% accuracy compared to the other ensemble classifers.

Keywords: Liver fbrosis, Schistosomiasis, Ensemble classifer, Statistical features

Introduction

Schistosomiasis is a serious disease triggered by parasitic fatworms called Schistosomes, which are widely spread in the developing countries due to the contaminated water. Early diagnosis saves the patient's life, which is identifed by the existence parasite's eggs in the stool/ urine of the individual and can be confrmed by discovering antibodies in the blood $[1]$ $[1]$. This disease causes liver fbrosis that can be assessed quantitatively and automatically using microscopic image analysis for detecting the liver fbrosis stage and minimizing the inter-observation variations [\[2](#page-8-1)]. For automated quantitative assessment of liver fbrosis, Sun et al. [[3\]](#page-8-2) used nonlinear optical microscopy. Mabey et al. [[4\]](#page-8-3) used the tissue and cellular information to identify the fbrosis progression based on the microscopic images.

Recently, for liver tissues classifcation, the artifcial intelligence procedures were employed for image

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processing and computer-aided diagnosis. From the histological images, Mahmoud-Ghoneim [\[5](#page-8-4)] optimized the computerized features of the liver fbrosis by inspecting the three color spaces at diferent resolutions for texture classifcation, where classifcation is a supervised remarkable machine learning process. Several techniques can be used for classifcation, including the k-nearest neighbor (KNN), neural network, support vector machine (SVM), and the decision tree $[6]$ $[6]$.

A standard practice for confrming the fbrosis level and screening is to examine the microscopic images of the liver tissue samples. From optical microscopy images, Saito et al. [[7\]](#page-8-6) implemented an automated approach for intestinal parasites based on a pattern classifer using active learning procedures. In order to achieve accurate diagnosis, the ensemble methodology that weighs and combines some individual classifers can be applied to attain a classifer, which outperforms the individual classifers included in the ensemble. Rathore et al. [\[8\]](#page-8-7) implemented an ensemble classifcation procedure using the discriminatory abilities of information rich hybrid feature spaces in colon biopsy microscopic images. Based on majority voting, an ensemble classifer, including linear,

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sigmoid SVM, and radial basis function, was applied to classify the microscopic images using the selected features. Early detection and diagnosis of liver fbrosis are still challenging tasks. Worldwide, several researchers are inspired to efectively determine the liver fbrosis stage. However, according to the previous studies, very few automated image-based classifers have been reported. Furthermore, there is no such ensemble methodology has not been included for liver fbrosis staging.

Consequently, the current work applied an ensemble of subspace and discriminant classifers on the microscopic images from mice as animal model liver samples of the different fibrosis stages for liver fibrosis staging. The proposed ensemble classifer used the extracted statistical features. Moreover, a comparative study of diferent ensembles, namely the boosted/trees ensemble, bagged/ trees ensemble, subspace/KNN ensemble, and the RUS-Boosted/trees ensemble, was also included.

The structure of the remaining sections is as follows. Section [2](#page-1-0) includes the methodology and the proposed method in the present work. Section [3](#page-2-0) reports the obtained results with comparative studies. Finally, Sect. [4](#page-8-8) concludes the proposed study.

Methodology

The proposed staging system consists of the following phases: (i) preprocess the acquired microscopic liver images for normal and diferent fbrosis levels, (ii) extract the statistical features, and (iii) apply the ensemble classifer to classify the liver image to any of the four cases, namely normal liver tissue, cellular granuloma, fbrocellular granuloma, or fbrotic granuloma.

Image preprocessing

The captured samples from the normal liver tissues as well as the three fibrosis levels are preprocessed. The preprocessing and segmentation steps were performed using ImageJ software tools. Initially, the colored microscopic images are converted to grayscale image. Then, the thresholding is used to identify the fbrosed regions, and then the watershed of the Euclidian distance map (EDM) segmentation method is applied to the microscopic images. During the segmentation process, the EDM is measured and the ultimate eroded points (UEPs) are located, and then dilates each UEPs. Afterwards, the statistical features are extracted from the segmented images.

Statistical features

In the present work, the statistical features of the diferent samples at the diferent fbrosis levels are extracted which are the area, perimeter, circularity, mean, median, mode, Feret, and the IntDen of the fbrosis regions in the microscopic images. The most prominent features are selected to distinguish the four classes for further classifcation process. These selected features are namely the (i) the 'minor', which is the secondary axis of the best ftting ellipse of the fbrosis region, (ii) the 'Feret', which is the Feret's diameter defned as the longest distance between any two points on the boundary of the selected fbrosis region, (iii) the 'area', which is the area of fbrosis/selected region in square pixels based on the calibration unit, and (iv) the 'RawIntDen', which is the integrated density defned as the sum of the pixel values within the fbrosis selected region. Subsequently, the ensemble of the subspace and discriminant classifers is deployed to classify the normal liver case and the diferent fbrosis stages.

Ensemble classifer based liver fbrosis staging

A classifcation process based on the features similarity is used to classify the liver fbrosis stages. In the current work, an ensemble of classifers is proposed for labeling each microscopic liver image as normal or one of the fbrosis levels according to the selected statistical features.

Typically, the multiple-classifer techniques or the ensemble-based techniques are more desirable compared to their single-classifer counterparts as they reduce the poor selection possibility $[7]$ $[7]$. The ensemble classifier combines a set of classifers that might produce superior classifcation performance compared to each individual classifier. The ensemble of classifiers is categorized generally into (i) classifer selection, where only the output of the classifer with the preeminent performance is selected as the fnal output, or (ii) classifer fusion, where the outputs of the individual classifers are combined to determine the fnal decision as the individual classifers are trained in parallel [\[8](#page-8-7)]. To select the fnal class label from the individual ones, precise predefned rules are applied. The most combination rules include the weighted majority voting, majority voting, Borda count, and behavior knowledge space common $[9]$ $[9]$. The selection of the ensemble size (number of classifers in the ensemble) involves a balance between the accuracy and speed of the classifer, where over-trained classifcation may occur with too large ensembles and larger ensembles take longer training time for prediction.

Ensemble learning combines several models for improving the prediction performance, which has several approaches, such as (i) random subspace, which randomizes the learning algorithm by selecting a subset of features randomly (chosen subspace) before performing the training algorithm, and then the models' outputs are combined by majority vote, (ii) bagging (Bootstrap Aggregation), which creates a set of models that trained on a random data, then the predictions are aggregated/ combined for fnal prediction using averaging, and (iii)

boosting is based on averaging/voting of multiple models, where it weights the constructed models based on their performance. In the current work, the majority voting rule is used with the subspace ensemble through linear discriminant.

Subspace discriminant ensemble

Subspace learning techniques have a signifcant role; especially with the linear discriminant analysis (LDA) scheme that engaged to determine a specifc discriminant subspace of low-dimension [[10–](#page-9-1)[12](#page-9-2)]. Several studies were conducted to study efect of the diferent subspacing, weighting, and resampling techniques on the classification performance in the ensemble learning $[13-15]$ $[13-15]$ $[13-15]$. Ho [[16\]](#page-9-5) used random subspaced feature arrangements using the random subspace method (RSM) using a random sample of features to construct each learner for decreasing the error rates [\[17\]](#page-9-6). Nevertheless, this random selection of the features in the subspaces is considered the main shortcoming of the RSM, where poor discrimination ability may occur due to the random selection of the subsets in some cases. In this case, the fnal ensemble decision becomes poor. To decrease this drawback of the RSM, a majority voting (MV) method is used. Generally, a single classifer in the ensemble might use only a small part of the features from the feature space. In addition, each classifer has the ability to classify any new/ unknown instance. The MV method uses each classifier to separately predict the new/unknown instance's class. Afterwards a majority vote between the predictions is employed to adopt the fnal class of the instance (fnal classifcation result). In this work, a framework based on the discriminant learning is applied to classify the fbrosis levels and the normal case using subspaces, which are the main elements of the learning algorithm.

The RSM ensemble construction methods using a modifed feature space is considered to build the ensembles of learners, unlike boosting and bagging ensemble methods [\[18\]](#page-9-7). Typically, the individual classifers are constructed using the subset of features. In the present work, the steps of the used RSM technique are illustrated as follows.

The classifiers' outputs in the proposed procedure are combined with the MV method. In the MV, unlabeled (new/unknown) instance classifcation is performed based on the class that has the most frequent vote (the highest number of votes) from the classifers in the ensemble. The description of the MV is as follows:

$$
Class(a) = \underset{c_i \in dom(y)}{\arg \max} \left(\sum_{\nu} h(y_{\nu}(a), c_i) \right) \tag{1}
$$

where $y_v(a)$ is the classification of the classifier 'v' and $h(y_v(a), c_i)$ represents an indicator function, which is given by:

$$
h(y_v(a), c_i) = \begin{cases} 1 & y = c \\ 0 & y \neq c \end{cases}
$$
 (2)

Experimental results and discussion

In the present work, Schistosoma mansoni cercariae was used to infect the mice in the Parasitology Department, Faculty of Medicine, Tanta University, Egypt. Afterwards 60 microscopic images of liver sections at diferent fbrosis levels were captured (15 images from each class), namely (i) level 1 (cellular granuloma), (ii) level 2 (fbrocellular granuloma), and (iii) level 3 (fbrotic granuloma) along with normal samples. Figure [1](#page-3-0) illustrates samples from each fbrosis level and the steps mentioned previously in order to extract the statistical features.

Performance evaluation of the proposed subspace discriminant

The subspace discriminant ensemble was designed using the majority voting rule, where the random subspace ensemble method was used with linear discriminant learner type of 30 learners and two subspace dimension. The confusion matrix is illustrated in Fig. [2](#page-3-1). The ROC curves are demonstrated in Fig. [3](#page-5-0)a through d for the normal and three fbrosis levels; respectively.

Figure [3](#page-5-0) illustrates the ROC curve that represents (i) the false positive rate (FPR), which indicates the number of the incorrect positive results with respect to all the negative instances during the test and (ii) the true positive rate (TPR), which represents the number of correct positive results with respect to all positive instances. Typically, the classifcation accuracy is measured by AUC curve. Figure [3](#page-5-0) reports that the proposed classifer achieved perfect classifcation with both the normal and fbrosis at level 3, while good classifcation with $AUC = 0.94$ during the classification of fibrosis cases at levels 1 and 2. These results are owing to the absence of the fbrosis and granulomas in the normal cases and the very big area of the fbrosis granuloma, while, in level 1

and 2 cellular- and fbrocellular- granuloma exist; respectively. The preceding results reported 90% accuracy, where the prediction speed was 68 observation/second.

Comparative study with diferent classifers of ensemble and neural network

A comparative study is conducted on diferent ensemble classifers in terms of the classifers' accuracies as follows.

Bagged trees ensemble

The weight average rule uses the bag ensemble method with Decision tree learner type and 30 learners. The achieved results established 81.7% accuracy with prediction speed of 110 observation/second. The confusion

(See fgure on next page.)

Fig. 2 Confusion matrix of the proposed subspace discriminant ensemble **a** true positive rates/false negative rates, and **b** positive predictive values/false discovery rates

matrix results showing the true positive rates/false negative rates and the positive predictive values/false discovery rates are illustrated in Fig. [4](#page-5-1). In addition, the ROC curves are demonstrated in Fig. [5](#page-7-0)a through d for the normal and three fbrosis levels; respectively.

Subspace KNN ensemble

Subspace KNN, where the training parameters in this study are based on the simple Majority Vote rule with the Subspace ensemble method as in the proposed method. However, the learner type is Nearest Neighbor of 30 numbers of learners and 2 subspace dimensions. The performance of

(See fgure on next page.)

Fig. 4 Confusion matrix of the bagged trees ensemble **a** true positive rates/false negative rates, and **b** positive predictive values/false discovery rates

this classifer is 73.3% accuracy with prediction speed of 44 observation/second.

of this classifer is 25% accuracy with prediction speed of 870 observation/second.

Boosted trees ensemble

Boosted Trees, where the training parameters in this study are based on the Weighted Majority vote rule with the AdaBoost ensemble method. The learner type is Decision tree with maximum number of splits is 20, number of learners 30 and learning rate is 0.1. The performance

RUSBoosted trees ensemble

RUSBoosted trees, where the training parameters in this study are Combined RUS and standard boosting procedure of AdaBoost with RUSBoost ensemble method. The learner type is the decision tree with maximum number of splits is 20 and number of learners 30 and learning rate

is 0.1. The performance of this classifier is 25% accuracy with prediction speed of 1200 observation/second.

Multi‑layer perceptron neural network

In addition, a comparison is conducted with the neural network of multi-layer perceptron neural network (MLP-NN) of one hundred hidden neurons. The NN realized accuracy of 88.3% to classify the diferent liver fbrosis levels as well as the normal case.

Comparative study evaluation

The reporting of the accuracy percentages of the preceding classifers to discriminate between the normal case and the three liver levels staging is illustrated in Table [1](#page-8-9).

Table [1](#page-8-9) reports that both the boosted trees ensemble and the RUSBoosted trees ensemble classifers failed to classify the fbrosis levels. However, the MLP-NN accomplished 83% accuracy, which is superior to the subspace KNN ensemble and the bagged trees ensemble. Generally, the proposed random subspace discriminant ensemble achieved the best accuracy of 90% value. These results illustrated that bagging provides better performance than boosting, and the RSM outperforms them both and the MLP-NN. Additionally, in terms of the computational time, the subspace KNN ensemble took the least computational time as it has prediction speed of 44 observation/second, while the RUSBoosted trees ensemble took the longest computational time as it has prediction speed of 1200 observation/sec. However, the proposed subspace discriminant ensemble took reasonable computational time as it has prediction speed was 68 observation/second. The superiority of the RSM classifcation is due to its ability to handle small dataset (samples) size due to its random subspaces process. However, bagging suffers from a shifting effect on the generalization error on small training sample sizes, also boosting failed to classify the small size dataset as it handles only large training

Table 1 Accuracy percentage of the diferent classifers compared to the proposed ensemble

General classifier type	Classifier	Accuracy %
Neural network	MI P-NN	83
Fnsembles	Boosted/trees	25
	RUSBoosted/trees	25
	Subspace/KNN	73.3
	Bagged/trees	81.7
	Subspace/discriminant (proposed)	90

sample sizes $[19]$ $[19]$. Thus, it is recommended to conduct a comparative study on larger dataset with diferent classifer types.

Conclusions

This work offers significant contribution for liver fibrosis staging in schistosomiasis. The microscopic image analysis based on the statistical features was followed by using diferent ensemble of classifers as well as the MLP-NN techniques and employed an ensemble of subspace discriminant classifiers for liver fibrosis staging. The results proved that the proposed random subspace discriminant ensemble realized the best accuracy of 90% compared to the other classifers. In future, it is recommended to employ other ensemble rules and to increase the dataset size of the microscopic images. Furthermore, the morphological features can combined with the statistical features to realize better staging performance. In addition, the conventional neural network [\[20](#page-9-9), [21\]](#page-9-10) can be employed and compared with the proposed method.

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