#### **ORIGINAL PAPER**



# An accurate and reliable mathematical analytic solution procedure for the EOQ model with non-instantaneous receipt under supplier credits

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#### Abstract

Recently, Huang and Hsu (J Oper Res Soc Jpn 50:1–13, 2007) investigated the retailer's optimal replenishment policy with non-instantaneous receipt under trade credit and cash discount. Basically, their inventory model is correct and interesting. However, they ignored explorations of interrelations of functional behaviors of the annual total cost to locate the optimal solutions so much so that the accuracy and reliability of the process of the proof of their solution procedure are questionable. The main purpose of this paper is to provide accurate and reliable mathematical analytic solution procedures to improve the findings in the aforementioned work of Huang and Hsu (J Oper Res Soc Jpn 50:1–13, 2007). Some related recent works on the subject-matter of this investigation are also cited with a view to providing incentive and motivation for making further advances along the lines of the supply chain management and associated inventory problems which we have discussed in this article.

**Keywords** Mathematical analytic solution procedure  $\cdot$  Inventory model  $\cdot$  Retailer's optimal replenishment policy  $\cdot$  Economic order quantities (EOQ)  $\cdot$  Trade credits  $\cdot$  Cash discounts  $\cdot$  Permissible delay in payment  $\cdot$  Cash discount

**Mathematics Subject Classification** Primary 26A06 · 26A24 · 91B24 · 93C15; Secondary 26D10 · 90B30.

# **1 Introduction**

In the year 1998, Borde and McCarty [1] pointed out that, in inventory management, economic order quantities (EOQ) may be affected as a result of the payment delays associated with trade credit, which implies that interactions may occur between trade credit and other operational considerations. From a retailer's viewpoint, not accepting the discount and paying later may be advantageous in the presence of rapid inflation in which case a finite fund would become worthless in real terms. On the other hand, from the supplier's perspective, Hill and Riener [8] identified several benefits and costs which are associated with cash discounts. Cash discounts

Extended author information available on the last page of the article

typically induce some customers to pay early in exchange for a pre-specified discount. To the supplier, cash is received sooner, thereby reducing the need to borrow. An early payment discount is, in effect, a price reduction. If retailers are price elastic, cash discounts may generate greater demand for the firm's products. Thus, cash discount can be used as a tool in the process of fine tuning the product's price. Early payment may reduce the possibility of bad debt losses as less time would be available for buyers to develop and resolve the paymentrelated problems. However, on the negative side, a cash discount may directly reduce total sales revenue if unit sales volume does not increase sufficiently to offset the unit revenue loss. This may occur if buyers are price inelastic and, therefore, are not induced to buy proportionally more units of the product in response to a price reduction.

Given the importance of trade credit and the fact that some features of the firm's cash discount problem, a lot of published articles can be found in the literature such as those by (for example) Borde and McCarty [1], Rashid and Mitra [19], Huang and Chung [9], Stokes [22], Sarker and Kindi [20], Huang and Hsu [10], Chung et al. (see [3,5,6]), Liao et al. (see [12,14,15]), and Srivastava et al. [21]. In particular, Huang and Hsu's model in [10] is correct and interesting. However, they seem to have ignored or missed explorations of interrelations of functional behaviors of the annual total cost to locate the optimal solutions. This means that their arguments about the solution procedure are not complete. The main purposes of this paper is to present accurate and reliable mathematical analytic solution procedures to provide the complete proof of, and thereby improve, the findings in the above-mentioned work of Huang and Hsu [10]. Finally, in Sect. 7 on concluding remarks and further observations, we have chosen to include citations of a number of related recent works on the subject-matter of our present investigations with the hope to provide incentive and motivation for making further advances along the lines of the supply chain management and associated inventory problems which we have discussed in this article.

# 2 Model formulation

### 2.1 Notation

Α	Cost of placing one order
С	Unit purchasing price per item
D	Demand rate per year
h	Unit stock holding cost per item per year excluding interest charges
$I_e$	Interest which can be earned per \$ per year
$I_k$	Interest charges per \$ investment in inventory per year
$M_1$	The period of cash discount in years
$M_2$	The period of trade credit in years, $M_1 < M_2$
P	Replenishment rate per year, $P > D \rho = 1 - \frac{D}{P} > 0$
r	Cash discount rate, $0 \le r < 1$
S	Unit selling price per item
Т	The cycle time in years (decision variable)
	• • • • •

Policy I.The retailer accepts the cash discount and makes the full payment within<br/> $M_1$ .Policy II.The retailer does not accept the cash discount and makes the full payment<br/>within  $M_2$ .

$$= \begin{cases} TVC_{11}(T) \text{ if } PM_1/D \leq T\\ TVC_{12}(T) \text{ if } M_1 \leq T \leq PM_1/D\\ TVC_{13}(T) \text{ if } 0 < T \leq M_1 \end{cases}$$

 $TVC_2(T)$  = the annual total relevant cost when the retailer adopts Policy II and T > 0

$$= \begin{cases} TVC_{21}(T) \text{ if } PM_2/D \leq T \\ TVC_{22}(T) \text{ if } M_2 \leq T \leq PM_2/D \\ TVC_{23}(T) \text{ if } 0 < T \leq M_2 \end{cases}$$

TVC(T) = the annual total relevant cost when T > 0

 $= \begin{cases} TVC_1(T) & \text{if the retailer adopts Policy I} \\ TVC_2(T) & \text{if the retailer adopts Policy II.} \end{cases}$ 

 $T^*$  = the optimal cycle time of TVC(T).

# 2.2 Assumptions

- (1) Demand rate, D, is known and constant.
- (2) Replenishment rate, P, is known and constant.
- (3) Shortages are not allowed.
- (4) Time horizon is infinite.
- (5)  $s \ge c$  and  $I_k \ge I_e$ .
- (6) Supplier offers a cash discount after settlement of an order if payment is paid within  $M_1$ , otherwise the full payment is paid within  $M_2$ . The account is settled when the payment is paid.
- (7) During the time the account is not settled, generated sales revenue is deposited in an interest-bearing account. At the end of the period, the retailer pays off all units sold and keeps his/her profits, and starts paying for the higher interest charges on the items in stock.

# 2.3 Mathematical model

According to Assumption (6), the retailer has the following two policies (Policy I and Policy II) to choose from:

Policy I.The retailer accepts the cash discount and makes the full payment within<br/> $M_1$ .Policy II.The retailer does not accept the cash discount and makes the full payment<br/>within  $M_2$ .

Huang and Hsu [10] divided the annual total relevant cost into two cases to be discussed as follows:

**Case 1.** The retailer adopts Policy I.

$$\begin{cases} TVC_{11}(T) & \text{if } \frac{PM_1}{D} \leq T \end{cases}$$
(1a)

$$TVC_1(T) = \begin{cases} TVC_{12}(T) & \text{if } M_1 \leq T \leq \frac{PM_1}{D} \end{cases}$$
(1b)

$$\begin{bmatrix} TVC_{13}(T) & \text{if } 0 < T \leq M_1, \end{bmatrix}$$
(1c)

where

$$TVC_{11}(T) = \frac{A}{T} + \frac{DTh\rho}{2} + c(1-r)D + \frac{cI_k(1-r)\rho}{T} \left(\frac{DT^2}{2} - \frac{PM_1^2}{2}\right) - \frac{sI_e}{T} \left(\frac{DM_1^2}{2}\right),$$
(2)
$$TVC_{12}(T) = \frac{A}{T} + \frac{DTh\rho}{2} + c(1-r)D + \frac{cI_k(1-r)}{T} \left(\frac{D(T-M_1)^2}{2}\right) - \frac{sI_e}{T} \left(\frac{DM_1^2}{2}\right)$$
(3)

and

$$TVC_{13}(T) = \frac{A}{T} + \frac{DTh\rho}{2} + c(1-r)D - \frac{sI_e}{T} \left(\frac{DT^2}{2} + DT(M_1 - T)\right).$$
(4)

Case 2. The retailer adopts Policy II.

$$\left\{ TVC_{21}(T) \quad \text{if} \quad \frac{PM_2}{D} \leq T \right.$$
(5a)

$$TVC_{2}(T) = \begin{cases} TVC_{22}(T) & \text{if } M_{2} \leq T \leq \frac{PM_{2}}{D} \\ TVC_{23}(T) & \text{if } 0 \leq T \leq M_{2}, \end{cases}$$
(5b)  
(5c)

$$(TVC_{23}(T) \quad \text{if} \quad 0 \leq T \leq M_2,$$

where

$$TVC_{21}(T) = \frac{A}{T} + \frac{DTh\rho}{2} + cD + \frac{cI_k\rho}{T} \left(\frac{DT^2}{2} - \frac{PM_2^2}{2}\right) - \frac{sI_e}{T} \left(\frac{DM_2^2}{2}\right), \quad (6)$$

$$TVC_{22}(T) = \frac{A}{T} + \frac{DTh\rho}{2} + cD + \frac{cI_k}{T} \left(\frac{D(T - M_2)^2}{2}\right) - \frac{sI_e}{T} \left(\frac{DM_2^2}{2}\right)$$
(7)

and

$$TVC_{23}(T) = \frac{A}{T} + \frac{DTh\rho}{2} + cD - \frac{sI_e}{T} \left(\frac{DT^2}{2} + DT(M_2 - T)\right).$$
 (8)

Combining Cases 1 and 2, the annual total relevant cost can be expressed as follows:

$$TVC(T) = \begin{cases} TVC_1(T) \text{ if the retailer adopts Policy I} \\ TVC_2(T) \text{ if the retailer adopts Policy II.} \end{cases}$$
(9a)  
(9b)

# 3 The Convexity of $TVC_{ij}(T)$ (*i* = 1, 2; *j* = 1, 2, 3)

For convenience, we treat all  $TVC_{ij}(T)$  (i = 1, 2; j = 1, 2, 3) are defined on T > 0. Equations (2), (3), (6), (7), (8) and (10) yield

$$TVC'_{11}(T) = -\left(\frac{2A - M_1^2[cI_k(1-r)P\rho + sI_eD]}{2T^2}\right) + \frac{D\rho[h + cI_k(1-r)]}{2},$$
(10)

$$TVC_{11}''(T) = \frac{2A - M_1^2[cI_k(1-r)P\rho + sI_eD]}{T^3} \frac{2A - cM_1^2PI_k(1-r) + DM_1^2[cI_k(1-r) - sI_e]}{T^3},$$
(11)

$$TVC_{12}'(T) = -\left(\frac{2A + DM_1^2[cI_k(1-r) - sI_e]}{2T^2}\right) + \frac{D[h\rho + cI_k(1-r)]}{2};$$
(12)

and

$$TVC_{12}''(T) = \frac{2A + DM_1^2[cI_k(1-r) - sI_e]}{T^3},$$
(13)

$$TVC'_{13}(T) = -\frac{A}{T^2} + \frac{D(h\rho + sI_e)}{2},$$
(14)

$$TVC_{13}''(T) = \frac{2A}{T^3} > 0, (15)$$

$$TVC'_{21}(T) = -\left(\frac{2A - M_2^2(cI_k P\rho + sI_e D)}{2T^2}\right) + \frac{D\rho(h + cI_k)}{2},$$
(16)

$$TVC_{21}''(T) = \frac{2A - M_2^2(cI_k\rho P + sI_e D)}{T^3} = \frac{2A - cM_2^2PI_k + DM_2^2(cI_k - sI_e)}{T^3},$$
(17)

$$TVC'_{22}(T) = -\left(\frac{2A + DM_2^2[cI_k - sI_e]}{2T^2}\right) + \frac{D(h\rho + cI_k)}{2},$$
(18)

$$TVC_{22}''(T) = \frac{2A + DM_2^2(cI_k - sI_e)}{T^3},$$
(19)

$$TVC'_{23}(T) = -\frac{A}{T^2} + \frac{D(h\rho + sI_e)}{2}$$
(20)

and

$$TVC_{23}''(T) = \frac{2A}{T^3} > 0.$$
 (21)

Let

$$G_1 = 2A - cM_1^2 P I_k(1-r) + DM_1^2 [cI_k(1-r) - sI_e],$$
(22)

$$H_1 = 2A + DM_1^2 [cI_k(1-r) - sI_e],$$
(23)

$$G_2 = 2A - cM_2^2 P I_k + DM_2^2 (cI_k - sI_e)$$
<sup>(24)</sup>

and

$$H_2 = 2A + DM_2^2(cI_k - sI_e)$$
(25)

**Remark 1** Equations (22)–(25) imply that  $H_1 > G_1$ ,  $H_2 > G_2$  and  $G_1 > G_2$ . Equations (11), (13), (15), (17), (19) and (21) imply the results asserted by Theorem 1 below.

#### **Theorem 1** Each of the following assertions hold true:

- (i)  $TVC_{11}(T)$  is convex on T > 0 if  $G_1 > 0$  and concave on T > 0 if  $G_1 \leq 0$ . Furthermore,  $TVC'_{11}(T) > 0$  and  $TVC_{11}(T)$  is increasing on T > 0 if  $G_1 \leq 0$ .
- (ii)  $TVC_{12}(T)$  is convex on T > 0 if  $H_1 > 0$  and concave on T > 0 if  $H_1 \leq 0$ . Furthermore,  $TVC'_{12}(T) > 0$  and  $TVC_{12}(T)$  is increasing on T > 0 if  $H_1 \leq 0$ .
- (iii)  $TVC_{13}(T)$  is convex on T > 0.
- (iv)  $TVC_{21}(T)$  is convex on T > 0 if  $G_2 > 0$  and concave on T > 0 if  $G_2 \leq 0$ . Furthermore,  $TVC'_{21}(T) > 0$  and  $TVC_{21}(T)$  is increasing on T > 0 if  $G_2 \leq 0$ .

(vi)  $TVC_{23}(T)$  is convex on T > 0.

Letting

$$TVC'_{ij}(T) = 0$$
  $(i = 1, 2; j = 1, 2, 3)$  (26)

and solving Eq. (26), we obtain

$$T_{11}^* = \sqrt{\frac{2A - cM_1^2 P I_k(1-r) + DM_1^2 [cI_k(1-r) - sI_e]}{D\rho[h + cI_k(1-r)]}}, \text{ if } G_1 > 0$$
(27)

$$T_{12}^* = \sqrt{\frac{2A + DM_1^2 [cI_k(1-r) - sI_e]}{D[h\rho + cI_k(1-r)]}} \quad \text{if} \quad H_1 > 0,$$
(28)

$$T_{13}^* = \sqrt{\frac{2A}{D(h\rho + sI_e)}},$$
(29)

$$T_{21}^{*} = \sqrt{\frac{2A + DM_{2}^{2}(cI_{k} - sI_{e}) - cM_{2}^{2}PI_{k}}{D\rho(h + cI_{k})}} \quad \text{if} \quad G_{2} > 0$$
(30)

$$T_{22}^* = \sqrt{\frac{2A + DM_2^2(cI_k - sI_e)}{D(h\rho + cI_k)}} \quad \text{if } H_2 > 0, \tag{31}$$

$$T_{23}^* = \sqrt{\frac{2A}{D(h\rho + sI_e)}},$$
(32)

which provide the respective solution of Eq. (26). We also have

$$TVC'_{i}(T) \begin{cases} < 0 \text{ if } 0 < T < T_{i3}^{*} \\ -0 \text{ if } T - T_{i3}^{*} \end{cases}$$
(33*a*)  
(33*b*)

$$\left\{ \begin{array}{l} = 0 \text{ if } T = T_{i3}^{*} \\ > 0 \text{ if } T > T_{i3}^{*} \end{array} \right.$$
(33b)  
(33c)

for i = 1 and 2. Furthermore, we also have

$$TUC'(T) \begin{bmatrix} < 0 \text{ if } 0 < T < T_{1j}^* \\ 0 \text{ if } T = T^* \end{bmatrix}$$
(34a)

$$TVC'_{1j}(T) \begin{cases} = 0 \text{ if } T = T^*_{1j} \\ > 0 \text{ if } T > T^*_{1j} \end{cases}$$
(34b)  
(34c)

if  $G_1 > 0$  for j = 1 and  $H_1 > 0$  for j = 2, and

$$TVC'_{2j}(T) \begin{cases} < 0 & \text{if } 0 < T < T_{2j} \\ = 0 & \text{if } T = T_{2j}^{*} \\ < 0 & \text{if } T = T_{2j}^{*} \end{cases}$$
(35b)

$$l > 0 \text{ if } T > T_{2j}^*$$
 (35c)

if  $G_2 > 0$  for j = 1 and  $H_2 > 0$  for j = 2.

# 4 Mathemsatical Analytic Solution Procedure Used by Huang and Hsu [10]

Let  $T_i^*$  denote the optimal solution of  $TVC_i(T)$  for i = 1 and i = 2. Huang and Hsu [10] recorded their conclusions as follows:

Conclusion (A):  $T_1^* = T_{11}^*$  if  $T_{11}^* \ge \frac{PM_1}{D}$ . Conclusion (B):  $T_1^* = T_{12}^*$  if  $M_1 \le T_{12}^* \le \frac{PM_1}{D}$ . Conclusion (C):  $T_1^* = T_{13}^*$  if  $0 < T_{13}^* \le M_1$ . Conclusion (D):  $T_2^* = T_{21}^*$  if  $T_{21}^* \ge \frac{PM_2}{D}$ . Conclusion (E):  $T_2^* = T_{22}^*$  if  $M_2 \le T_{22}^* \le \frac{PM_2}{D}$ . Conclusion (F):  $T_2^* = T_{23}^*$  if  $0 < T_{23}^* \le M_2$ .

We just need to discuss Conclusion (A). The same arguments in Conclusion (A) can be applied to Conclusions (B) to (F). About Conclusion (A), the following inequality:

$$T_{11}^* \geqq \frac{PM_1}{D}$$

only means that the optimal solution  $T_{11}^*$  of  $TVC_{11}(T)$  lies in the interval  $\left\lfloor \frac{PM_1}{D}, \infty \right)$ . Basically, the equations 1(a, b, c) reveal the fact that the graph of  $TVC_1(T)$  consists of those of  $TVC_{11}(T)$ ,  $TVC_{12}(T)$  and  $TVC_{13}(T)$  on the respective domain of  $TVC_1(T)$ . In fact, if

$$T_{11}^* \ge \frac{PM_1}{D},$$

we can only conclude that  $T_{11}^*$  is the optimal solution of  $TVC_1(T)$  on the interval  $\left[\frac{PM_1}{D},\infty\right)$ , but  $T_{11}^*$  is not necessarily the optimal solution  $T_1^*$  of  $TVC_1(T)$  on the whole domain T > 0. The function  $TVC_{11}(T)$  can not solely determine the optimal solution of  $TVC_1(T)$ , since the graphs of  $TVC_{11}(T)$  and  $TVC_1(T)$  are different. It should explore the functional behaviors of  $TVC_{11}(T)$ ,  $TVC_{12}(T)$  and  $TVC_{13}(T)$  on the following intervals:

$$\left[\frac{PM_1}{D},\infty\right), \quad \left[M_1,\frac{PM_1}{D}\right] \quad \text{and} \quad (0,M_1],$$

respectively, to jointly decide whether  $T_{11}^*$  is the optimal solution  $T_1^*$  of  $TVC_1(T)$  on the whole domain T > 0.

In spite of the above observation, Huang and Hsu [10] ignores the explorations of the interrelations of the functional behaviors of  $TVC_{11}(T)$ ,  $TVC_{12}(T)$  and  $TVC_{13}(T)$  on the respective domain of  $TVC_1(T)$  so much so that their arguments about the solution procedure are not reliable. So, their processes of proof of Conclusion (A) are questionable. The above arguments about Conclusion (A) can be applied to Conclusions (B) to (F). Thus, clearly, the processes of proof of Theorem 1 in the work of Huang and Hsu [10] are not complete.

## 5 Theorems for the Optimal Cycle Time $T^*$ of TVC(T)

Case 1. The retailer adopts Policy I.

In this case, we recall from the equations 1(a,b,c) that

$$\begin{cases} TVC_{11}(T) \text{ if } \frac{PM_1}{D} \leq T \end{cases}$$
(1a)

$$TVC_1(T) = \begin{cases} TVC_{12}(T) \text{ if } M_1 \leq T \leq \frac{PM_1}{D} \end{cases}$$
(1b)

$$TVC_{13}(T) \text{ if } 0 < T \leq M_1.$$

$$(1c)$$

We then find that

$$TVC_{11}(PM_1/D) = TVC_{12}\left(\frac{PM_1}{D}\right)$$
 and  $TVC_{12}(M_1) = TVC_{13}(M_1)$ 

Hence the function  $TVC_1(T)$  is continuous and well-defined. All of the functions  $TVC_{11}(T)$ ,  $TVC_{12}(T)$ ,  $TVC_{13}(T)$  and  $TVC_1(T)$  are defined on T > 0. Furthermore, we have

$$TVC'_{11}(\frac{PM_1}{D}) = TVC'_{12}\left(\frac{PM_1}{D}\right)$$
$$= \frac{-2A + \frac{M_1^2}{D}[cI_k(1-r)(P^2 - D^2) + sI_eD^2 + hP(P - D)]}{2\left(\frac{PM_1}{D}\right)^2}$$
(36)

and

Т

$$TVC'_{12}(M_1) = TVC'_{13}(M_1) = \frac{-2A + DM_1^2(h\rho + sI_e)}{2M_1^2}$$
(37)

Case 2. The retailer adopts Policy II.

In this case, we recall from the equations 5(a,b,c) that

$$\left\{ TVC_{21}(T) \text{ if } \frac{PM_2}{D} \leq T \right.$$
(5a)

$$VC_2(T) = \begin{cases} TVC_{22}(T) \text{ if } M_2 \leq T \leq \frac{PM_2}{D} \end{cases}$$
(5b)

$$TVC_{23}(T) \text{ if } 0 \leq T \leq M_2 \tag{5c}$$

We then find that

$$TVC_{21}\left(\frac{PM_2}{D}\right) = TVC_{22}\left(\frac{PM_2}{D}\right)$$
 and  $TVC_{22}(M_2) = TVC_{23}(M_2).$ 

Hence the function  $TVC_2(T)$  is continuous and well-defined. All of the functions  $TVC_{21}(T)$ ,  $TVC_{22}(T)$ ,  $TVC_{23}(T)$  and  $TVC_2(T)$  are defined on T > 0. Furthermore, we have

$$TVC_{21}'\left(\frac{PM_2}{D}\right) = TVC_{22}'\left(\frac{PM_2}{D}\right) = \frac{-2A + \frac{M_2^2}{D}\left[cI_k(P^2 - D^2) + sI_eD^2 + hP(P - D)\right]}{2\left(\frac{PM_2}{D}\right)^2}$$
(38)

and

$$TVC'_{22}(M_2) = TVC'_{23}(M_2) = \frac{-2A + DM_2^2(h\rho + sI_e)}{2M_2^2}$$
(39)

Let

$$\Delta_1 = -2A + \frac{M_1^2}{D} \left[ cI_k (1-r)(P^2 - D^2) + sI_e D^2 + hP(P - D) \right]$$
(40)

$$\Delta_2 = -2A + DM_1^2(h\rho + sI_e)$$
(41)

$$\Delta_3 = -2A + \frac{M_2^2}{D} \left[ cI_k (P^2 - D^2) + sI_e D^2 + hP(P - D) \right]$$
(42)

and

$$\Delta_4 = -2A + DM_2^2(h\rho + sI_e) \tag{43}$$

Equations(40)–(43) reveal that

$$\Delta_3 > \Delta_1 > \Delta_2 \tag{44}$$

and

$$\Delta_3 > \Delta_4 > \Delta_2 \tag{45}$$

We then have the following results.

**Theorem 2** If  $H_1 \leq 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{13}), TVC_2(T^*_{23})\}\$$

and  $T^* = T^*_{13}$  or  $T^*_{23}$  are associated with the least cost. Furthermore, there are three cases to occur:

- (A) If  $sI_e(M_1 M_2) + cr > 0$ , then  $T^* = T_{13}^*$  and Policy I is better.
- (B)  $TVC_{12}(T)$  is convex on T > 0 if  $H_1 > 0$  and concave on T > 0 if  $H_1 \leq 0$ . Furthermore,  $TVC'_{12}(T) > 0$  and the function  $TVC_{12}(T)$  is increasing on T > 0 if  $H_1 \leq 0$ .
- (C) If  $sI_e(M_1 M_2) + cr < 0$ , then  $T^* = T_{23}^*$  and Policy II is better.

**Proof** If  $H_1 \leq 0$ , then  $\Delta_2 > 0$ . Equations (44) and (45) reveal that  $\Delta_1 > 0$ ,  $\Delta_2 > 0$ ,  $\Delta_3 > 0$  and  $\Delta_4 > 0$ . Thus, together with Theorem 1, we can arrive at the following observations:

- (i)  $TVC_{13}(T)$  is decreasing on  $(0, T_{13}^*]$  and increasing on  $[T_{13}^*, M_1]$ .
- (ii)  $TVC_{12}(T)$  is increasing on  $\left[M_1, \frac{PM_1}{D}\right]$ . (iii)  $TVC_{11}(T)$  is increasing on  $\left[\frac{PM_1}{D}, \infty\right)$ .
- (iv)  $TVC_{23}(T)$  is decreasing on  $[0, T_{23}^*]$  and increasing on  $[T_{23}^*, M_2]$ .
- (v)  $TVC_{22}(T)$  is increasing on  $\left[M_2, \frac{PM_2}{D}\right]$ . (vi)  $TVC_{21}(T)$  is increasing on  $\left[\frac{PM_2}{D}, \infty\right)$ .

Now, by combining the equations 1(a, b, c), 5(a, b, c) and (i) to (vi), we conclude that  $T_1^* = T_{13}^*$  and  $T_2^* = T_{23}^*$ . Equations 9(a, b) imply that

$$TVC(T^*) = \min\{TVC_1(T_1^*), TVC_2(T_2^*)\}.$$

So,  $T^* = T^*_{13}$  or  $T^*_{23}$  is associated with the least cost.

Equations (30) and (32) reveal that  $T_{13}^* = T_{23}^*$ . On the other hand, the equations (1c) and (5c) imply that

$$TVC_{23}(T) - TVC_{13}(T) = D[sI_e(M_1 - M_2) + cr],$$

so that

$$TVC_{23}(T_{23}^*) - TVC_{13}(T_{13}^*) = D[sI_e(M_1 - M_2) + cr].$$

There are the following three cases to occur:

(A) If  $sI_e(M_1 - M_2) + cr > 0$ , then

$$TVC_2(T_2^*) = TVC_{23}(T_{23}^*) > TVC_{13}(T_{13}^*) = TVC_1(T_1^*),$$

so  $T^* = T_{13}^*$  and Policy I is better.

(B) If  $sI_e(M_1 - M_2) + cr = 0$ , then

$$TVC_2(T_2^*) = TVC_{23}(T_{23}^*) = TVC_{13}(T_{13}^*) = TVC_1(T_1^*),$$

so  $T^* = T^*_{13} = T^*_{23}$  and Policy I and Policy II are not different.

(C) If  $sI_e(M_1 - M_2) + cr < 0$ , then

$$TVC_2(T_2^*) = TVC_{23}(T_{23}^*) < TVC_{13}(T_{13}^*) = TVC_1(T_1^*),$$

so  $T^* = T^*_{23}$  and Policy II is better.

Incorporating the above arguments, we have completed the proof of Theorem 1. 

**Remark 2** If  $H_1 \leq 0$ , then  $0 > G_1 > G_2$ . Equations (28), (29), (31) and (31) reveal that  $T_{11}^*$ ,  $T_{12}^*$  and  $T_{21}^*$  do not exist. Therefore, the assertions of Theorem 1(B, C, D, E, F) in Huang and Hsu [10] do not hold true.

**Theorem 3** Suppose that  $H_1 > 0$ ,  $G_1 \leq 0$  and  $H_2 \leq 0$ . The following assertions hold true:

(A) If  $\Delta_2 > 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{13}), TVC_2(T^*_{23})\}$$

and  $T^* = T^*_{13}$  or  $T^*_{23}$  is associated with the least cost. Furthermore, there are the following three cases to occur:

- (i) If  $sI_e(M_1 M_2) + cr > 0$ , then  $T^* = T_{13}^*$  and Policy I is better. (ii) If  $sI_e(M_1 M_2) + cr = 0$ , then  $T^* = T_{13}^* = T_{23}^*$  and Policy I and Policy II are not different.
- (iii) If  $sI_e(M_1 M_2) + cr < 0$ , then  $T^* = T^*_{23}$  and Policy II is better.
- (B) If  $\Delta_2 \leq 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{12}), TVC_2(T^*_{23})\}$$

and  $T^* = T_{12}^*$  or  $T_{23}^*$  is associated with the least cost.

**Proof** If  $G_1 \leq 0$  and  $H_2 \leq 0$ , then  $TVC'_{11}(T) > 0$ ,  $TVC'_{21}(T) > 0$  and  $TVC'_{22}(T) > 0$ . Equations (40), (42) and (43) reveal that  $\Delta_1 > 0$ ,  $\Delta_3 > 0$  and  $\Delta_4 > 0$ . Therefore, in view of Theorem 1, we can get

- (A) If  $\Delta_2 > 0$ , the proof of (A) is the same as that of Theorem 2.
- (B) If  $\Delta_2 \leq 0$ , we have
- (i)  $TVC_{13}(T)$  is decreasing on  $(0, M_1]$ .
- (ii)  $TVC_{12}(T)$  is decreasing on  $[M_1, T_{12}^*]$  and increasing on  $\left|T_{12}^*, \frac{PM_1}{D}\right|$ . (iii)  $TVC_{11}(T)$  is increasing on  $\left[\frac{PM_1}{D},\infty\right)$ . (iv)  $TVC_{23}(T)$  is decreasing on  $[0, T_{23}^*]$  and increasing on  $[T_{23}^*, M_2]$ . (v)  $TVC_{22}(T)$  is increasing on  $\left[M_2, \frac{PM_2}{D}\right]$ . (vi)  $TVC_{21}(T)$  is increasing on  $\left[\frac{PM_2}{D}, \infty\right]$ .

By combining the equations 1(a,b,c), 5(a,b,c) and (i) to (vi), we conclude that  $T_1^* = T_{12}^*$ and  $T_2^* = T_{23}^*$ . Equations 9(a,b) imply that

$$TVC(T^*) = \min\{TVC_1(T_1^*), TVC_2(T_2^*)\},\$$

so  $T^* = T_{12}^*$  or  $T_{23}^*$  is associated with the least cost.

Incorporating the above arguments, we have completed the proof of Theorem 3. 

**Remark 3** If  $H_2 \leq 0$  and  $G_1 \leq 0$ , then  $G_2 \leq 0$ . Equations (27), (30) and (31) reveal that  $T_{11}^*$ ,  $T_{21}^*$  and  $T_{22}^*$  do not exist. Therefore, the assertions of Theorem 1(C, D, E, F) in Huang and Hsu [10] are not valid.

**Theorem 4** Suppose that  $H_1 > 0$ ,  $G_1 \leq 0$ ,  $H_2 > 0$  and  $G_2 \leq 0$ . The following assertions hold true:

(A) If  $\Delta_2 > 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{13}), TVC_2(T^*_{23})\}\$$

and  $T^* = T^*_{13}$  or  $T^*_{23}$  is associated with the least cost. Furthermore, there are the following three cases to occur:

- (i) If  $sI_e(M_1 M_2) + cr > 0$ , then  $T^* = T^*_{13}$  and Policy I is better. (ii) If  $sI_e(M_1 M_2) + cr = 0$ , then  $T^* = T^*_{13} = T^*_{23}$  and Policy I and Policy II are not different.
- (iii) If  $sI_e(M_1 M_2) + cr < 0$ , then  $T^* = T^*_{23}$  and Policy II is better.

(B) If  $\Delta_4 > 0$  and  $\Delta_2 \leq 0$ , then

 $TVC(T^*) = \min\{TVC_1(T_{12}^*), TVC_2(T_{23}^*)\}$ 

and  $T^* = T^*_{12}$  or  $T^*_{23}$  is associated with the least cost. (C) If  $\Delta_4 \leq 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{12}), TVC_2(T^*_{22})\}\$$

and  $T^* = T^*_{12}$  or  $T^*_{22}$  is associated with the least cost.

**Proof** If  $G_1 \leq 0$  and  $G_2 \leq 0$ , then  $TVC'_{11}(T) > 0$  and  $TVC'_{21}(T) > 0$ . Equations (40) and (42) reveal that  $\Delta_1 > 0$  and  $\Delta_3 > 0$ . Thus, in light of Theorem 1, we can get

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- (A) If  $\Delta_2 > 0$ , then  $\Delta_4 > 0$ . So, the proof of is the same as that of Theorem 2.
- (B) If  $\Delta_4 > 0$ , then  $\Delta_2 \leq 0$ , then the proof of (B) is the same as that of Theorem 3(B).
- (C) If  $\Delta_4 \leq 0$ , then  $\Delta_2 < 0$ . We have the following cases:
  - (i)  $TVC_{13}(T)$  is decreasing on  $(0, M_1]$ .
  - (ii)  $TVC_{12}(T)$  is decreasing on  $[M_1, T_{12}^*]$  and increasing on  $\left|T_{12}^*, \frac{PM_1}{D}\right|$ .
  - (iii)  $TVC_{11}(T)$  is increasing on  $\left[\frac{PM_1}{D},\infty\right)$ . (iv)  $TVC_{23}(T)$  is decreasing on  $(0, M_2)$ . (v)  $TVC_{22}(T)$  is decreasing on  $[M_2, T_{22}^*]$  and increasing on  $\left|T_{22}^*, \frac{PM_2}{D}\right|$ . (vi)  $TVC_{23}(T)$  is increasing on  $\left[\frac{PM_2}{D},\infty\right)$ .

Thus, if we combine the equations 1(a,b,c), 5(a,b,c) and (i) to (vi), we conclude that  $T_1^* = T_{12}^*$  and  $T_2^* = T_{22}^*$ . Equations 9(a, b) imply that

$$TVC(T^*) = \min\{TVC_1(T_1^*), TVC_2(T_2^*)\},\$$

so  $T^* = T_{12}^*$  or  $T_{22}^*$  is associated with the least cost.

Incorporating the above arguments, we have completed the proof of Theorem 4. 

**Remark 4** If  $G_1 \leq 0$  and  $G_2 \leq 0$ , then  $TVC'_{11}(T) > 0$  and  $TVC'_{21}(T) > 0$ . Equations (27) and (30) reveal that  $T_{11}^*$  and  $T_{21}^*$  do not exist. Therefore, the assertions of Theorem 1(D, E, F) in Huang and Hsu [10] do not hold true.

**Theorem 5** Suppose that  $G_1 > 0$  and  $H_2 \leq 0$ . The following assertions hold true:

(A) If  $\Delta_2 > 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{13}), TVC_2(T^*_{23})\}\$$

and  $T^* = T^*_{13}$  or  $T^*_{23}$  is associated with the least cost. Furthermore, there are the following three cases to occur:

- (i) If  $sI_e(M_1 M_2) + cr > 0$ , then  $T^* = T_{13}^*$  and Policy I is better. (ii) If  $sI_e(M_1 M_2) + cr = 0$ , then  $T^* = T_{13}^* = T_{23}^*$  and Policy I and Policy II are not different.
- (iii) If  $sI_e(M_1 M_2) + cr < 0$ , then  $T^* = T^*_{23}$  and Policy II is better.

(B) If  $\Delta_1 > 0$  and  $\Delta_2 \leq 0$ , then

$$TVC(T^*) = \min\{TVC_1(T_{12}^*), TVC_2(T_{23}^*)\}$$

and  $T^* = T^*_{12}$  or  $T^*_{23}$  is associated with the least cost. (C) If  $\Delta_1 \leq 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{11}), TVC_2(T^*_{23})\}\$$

and  $T^* = T_{11}^*$  or  $T_{23}^*$  is associated with the least cost.

**Proof** If  $H_2 \leq 0$  and  $G_2 \leq 0$ , we have  $TVC'_{21}(T) > 0$  and  $TVC'_{22}(T) > 0$ . Equations (42) and (43) reveal that  $\Delta_3 > 0$  and  $\Delta_4 > 0$ . Together with Theorem 1, we can get

(A) If  $\Delta_2 > 0$ , then  $\Delta_1 > 0$ . So, the proof of (A) is the same as that of Theorem 2.

- (C) If  $\Delta_1 \leq 0$ , then  $\Delta_2 < 0$ . We have
  - (i)  $TVC_{13}(T)$  is decreasing on  $(0, M_1]$ . (ii)  $TVC_{12}(T)$  is decreasing on  $\left[M_1, \frac{PM_1}{D}\right]$ . (iii)  $TVC_{11}(T)$  is decreasing on  $\left[\frac{PM_1}{D}, T_{11}^*\right]$  and increasing on  $[T_{11}^*, \infty)$ . (iv)  $TVC_{23}(T)$  is decreasing on  $[0, T_{23}^*]$  and increasing on  $[T_{23}^*, M_2]$ . (v)  $TVC_{22}(T)$  is increasing on  $\left[M_2, \frac{PM_2}{D}\right]$ . (vi)  $TVC_{21}(T)$  is increasing on  $\left[\frac{PM_2}{D},\infty\right]$ .

Upon combining the equations 1(a,b,c), 5(a,b,c) and (i) to (vi), we conclude that  $T_1^* = T_{11}^*$ and  $T_2^* = T_{23}^*$ . Equations 9(a,b) imply that

$$TVC(T^*) = \min\{TVC_1(T_1^*), TVC_2(T_2^*)\}$$

so  $T^* = T^*_{11}$  or  $T^*_{23}$  is associated with the least cost.

Incorporating the above arguments, we have completed the proof of Theorem 5. 

**Remark 5** If  $H_2 \leq 0$  and  $G_2 \leq 0$ , then Eqs. (30) and (31) reveal that  $T_{21}^*$  and  $T_{22}^*$  do not exist. Therefore, the assertions of Theorem 1(C, E, F) in Huang and Hsu [10] is not true.

**Theorem 6** Suppose that  $G_1 > 0$ ,  $H_2 > 0$  and  $G_2 \leq 0$ . The following assertions hold true:

(A) If  $\Delta_2 > 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{13}), TVC_2(T^*_{23})\}\$$

and  $T^* = T^*_{13}$  or  $T^*_{23}$  is associated with the least cost. Furthermore, there are the following three cases to occur:

- (i) If  $sI_e(M_1 M_2) + cr > 0$ , then  $T^* = T^*_{13}$  and Policy I is better. (ii) If  $sI_e(M_1 M_2) + cr = 0$ , then  $T^* = T^*_{13} = T^*_{23}$  and Policy I and Policy II are not different.
- (iii) If  $sI_e(M_1 M_2) + cr < 0$ , then  $T^* = T^*_{23}$  and Policy II is better.
- (B) If  $\Delta_4 > 0$ ,  $\Delta_1 > 0$  and  $\Delta_2 \leq 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{12}), TVC_2(T^*_{23})\}\$$

and  $T^* = T^*_{12}$  or  $T^*_{23}$  is associated with the least cost. (C) If  $\Delta_4 \leq 0$  and  $\Delta_1 > 0$ , then

$$TVC(T^*) = \min\{TVC_1(T_{12}^*), TVC_2(T_{22}^*)\}$$

and  $T^* = T^*_{12}$  or  $T^*_{22}$  is associated with the least cost. (D) If  $\Delta_4 > 0$  and  $\Delta_1 \stackrel{22}{\leq} 0$ , then

 $TVC(T^*) = \min\{TVC_1(T^*_{11}), TVC_2(T^*_{23})\}\$ 

and  $T^* = T^*_{11}$  or  $T^*_{23}$  is associated with the least cost.

(E) If  $\Delta_4 \leq 0$  and  $\Delta_1 \leq 0$ , then

$$TVC(T^*) = \min\{TVC_1(T_{11}^*), TVC_2(T_{22}^*)\}\$$

and  $T^* = T_{11}^*$  or  $T_{22}^*$  is associated with the least cost.

**Proof** If  $G_2 \leq 0$ , then  $TVC'_{21}(T) > 0$ . Equation (42) reveals that  $\Delta_3 > 0$ . So, together with Theorem 1, we can get

- (A) If  $\Delta_2 > 0$ , then  $\Delta_1 > 0$  and  $\Delta_4 > 0$ . The proof of (A) is the same as that of Theorem
- (B) If  $\Delta_4 > 0$ ,  $\Delta_1 > 0$  and  $\Delta_2 \leq 0$ , then the proof of (B) is the same as that of Theorem 3(B).
- (C) If  $\Delta_4 \leq 0$  and  $\Delta_1 > 0$ , then  $\Delta_2 < 0$ . The proof of (C) is the same as that of Theorem 4(C).
- (D) If  $\Delta_4 > 0$  and  $\Delta_1 \leq 0$ , then  $\Delta_2 < 0$ . The proof of (D) is the same as that of Theorem 5(C).
- (E) If  $\Delta_4 \leq 0$  and  $\Delta_1 \leq 0$ , then  $\Delta_2 < 0$ . We have the following cases:

(i) 
$$TVC_{13}(T)$$
 is decreasing on  $(0, M_1]$ 

- (ii)  $TVC_{12}(T)$  is decreasing on  $\left[M_1, \frac{PM_1}{D}\right]$ .
- (iii)  $TVC_{11}(T)$  is decreasing on  $\left[\frac{PM_1}{D}, T_{11}^*\right]$  and increasing on  $[T_{11}^*, \infty)$ .
- (iv)  $TVC_{23}(T)$  is decreasing on  $[0, M_2]$ .

(iv  $TVC_{22}(T)$  is decreasing on  $[M_2, T_{22}^*]$  and increasing on  $\left[T_{22}^*, \frac{PM_2}{D}\right]$ . (vi)  $TVC_{21}(T)$  is increasing on  $\left[\frac{PM_2}{D},\infty\right)$ .

Combining the equations 1(a,b,c), 5(a,b,c) and (i) to (vi), we conclude that  $T_1^* = T_{11}^*$  and  $T_2^* = T_{22}^*$ . Equations 9(a, b) imply that

$$TVC(T^*) = \min\{TVC_1(T_1^*), TVC_2(T_2^*)\},\$$

so  $T^* = T_{11}^*$  or  $T_{22}^*$  is associated with the least cost.

Incorporating the above arguments, we have completed the proof of Theorem 6. 

**Remark 6** If  $G_2 \leq 0$ , Eq. (30) reveals that  $T_{21}^*$  does not exist. Therefore, the assertions of Theorem 1(F) in Huang and Hsu [10] are not true.

**Theorem 7** Suppose that  $G_2 > 0$ . The following assertions hold true:

(A) If  $\Delta_2 > 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{13}), TVC_2(T^*_{23})\},\$$

so  $T^* = T^*_{13}$  or  $T^*_{23}$  is associated with the least cost. Furthermore, there are the following three cases to occur:

- (i) If  $sI_e(M_1 M_2) + cr > 0$ , then  $T^* = T_{13}^*$  and Policy I is better. (ii) If  $sI_e(M_1 M_2) + cr = 0$ , then  $T^* = T_{13}^* = T_{23}^*$  and Policy I and Policy II are not different.
- (iii) If  $sI_e(M_1 M_2) + cr < 0$ , then  $T^* = T^*_{23}$  and Policy II is better.

(B) If  $\Delta_1 > 0$ ,  $\Delta_2 \leq 0$  and  $\Delta_4 > 0$ , then

 $TVC(T^*) = \min\{TVC_1(T^*_{12}), TVC_2(T^*_{23})\},\$ 

so  $T^* = T^*_{12}$  or  $T^*_{23}$  is associated with the least cost. (C) If  $\Delta_1 > 0$  and  $\Delta_4 \leq 0$ , then

 $TVC(T^*) = \min\{TVC_1(T_{12}^*), TVC_2(T_{22}^*)\},\$ 

so  $T^* = T_{12}^*$  or  $T_{22}^*$  is associated with the least cost. (D) If  $\Delta_1 \leq 0$  and  $\Delta_4 > 0$ , then

 $TVC(T^*) = \min\{TVC_1(T^*_{11}), TVC_2(T^*_{23})\}$ 

so  $T^* = T^*_{11}$  or  $T^*_{23}$  is associated with the least cost. (E) If  $\Delta_1 \leq 0$ ,  $\Delta_3 > 0$  and  $\Delta_4 \leq 0$ , then

 $TVC(T^*) = \min\{TVC_1(T^*_{11}), TVC_2(T^*_{22})\},\$ 

so  $T^* = T_{11}^*$  or  $T_{22}^*$  is associated with the least cost. (F) If  $\Delta_3 \leq 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{11}), TVC_2(T^*_{21})\},\$$

so  $T^* = T_{11}^*$  or  $T_{21}^*$  is associated with the least cost.

**Proof** We consider the following situations:

- (A) If  $\Delta_2 > 0$ , then  $\Delta_1 > 0$ ,  $\Delta_3 > 0$  and  $\Delta_4 > 0$ . The proof of (A) is the same as that of Theorem 2.
- (B) If  $\Delta_1 > 0$ ,  $\Delta_2 \leq 0$  and  $\Delta_4 > 0$ , then  $\Delta_3 > 0$ . The proof of (B) is the same as that of Theorem 3(B).
- (C) If  $\Delta_1 > 0$  and  $\Delta_4 \leq 0$ , then  $\Delta_3 > 0$  and  $\Delta_2 < 0$ . The proof of (C) is the same as that of Theorem 4(C).
- (D) If  $\Delta_1 \leq 0$  and  $\Delta_4 > 0$ , then  $\Delta_2 < 0$  and  $\Delta_3 > 0$ . The proof of (D) is the same as that of Theorem 5(C).
- (E) If  $\Delta_1 \leq 0$ ,  $\Delta_3 > 0$  and  $\Delta_4 \leq 0$ , then  $\Delta_2 < 0$ . The proof of (E) is the same as that of Theorem 6(E).
- (F) If  $\Delta_3 \leq 0$ , then  $\Delta_1 < 0$ ,  $\Delta_2 < 0$  and  $\Delta_4 < 0$ . Thus, together with Theorem 1, we can get

Combining the equations 1(a,b,c), 5(a,b,c) and the items (i) to (vi), we conclude that  $T_1^* = T_{11}^*$  and  $T_2^* = T_{21}^*$ . Equations 9(a,b) imply that

$$TVC(T^*) = \min\{TVC_1(T_1^*), TVC_2(T_2^*)\}.$$

Consequently,  $T^* = T_{11}^*$  or  $T_{21}^*$  is associated with the least cost. Incorporating the above arguments, we have completed the proof of Theorem 7. 

**Remark 7** By combining all of the arguments of Theorems 2–7, we are led to the complete proof of Theorem 1 in Huang and Hsu [10]. We thus obtain the following result.

**Theorem 8** Each of the following assertions hold true:

(A) If  $\Delta_2 > 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{13}), TVC_2(T^*_{23})\}\$$

and  $T^* = T^*_{13}$  or  $T^*_{23}$  is associated with the least cost. There are three cases to occur in this case.

- (i) If  $sI_e(M_1 M_2) + cr > 0$ , then  $T^* = T_{13}^*$  and Policy I is better. (ii) If  $sI_e(M_1 M_2) + cr = 0$ , then  $T^* = T_{13}^* = T_{23}^*$  and Policy I and Policy II are not different.
- (iii) If  $sI_e(M_1 M_2) + cr < 0$ , then  $T^* = T^*_{23}$  and Policy II is better.
- (B) If  $\Delta_1 > 0$ ,  $\Delta_2 \leq 0$  and  $\Delta_4 > 0$ , then

$$TVC(T^*) = \min\{TVC_1(T^*_{12}), TVC_2(T^*_{23})\}\$$

and  $T^* = T^*_{12}$  or  $T^*_{23}$  is associated with the least cost. (C) If  $\Delta_1 > 0$  and  $\Delta_4 \leq 0$ , then

 $TVC(T^*) = \min\{TVC_1(T_{12}^*), TVC_2(T_{22}^*)\}$ 

and  $T^* = T^*_{12}$  or  $T^*_{22}$  is associated with the least cost. (D) If  $\Delta_1 \leq 0$  and  $\Delta_4 > 0$ , then

 $TVC(T^*) = \min\{TVC_1(T^*_{11}), TVC_2(T^*_{23})\}\$ 

and  $T^* = T^*_{11}$  or  $T^*_{23}$  is associated with the least cost.

(E) If  $\Delta_1 \leq 0$ ,  $\overline{\Delta_3} > 0$  and  $\Delta_4 \leq 0$ , then

 $TVC(T^*) = \min\{TVC_1(T_{11}^*), TVC_2(T_{22}^*)\}$ 

and  $T^* = T^*_{11}$  or  $T^*_{22}$  is associated with the least cost. (F) If  $\Delta_3 \leq 0$ , then

 $TVC(T^*) = \min\{TVC_1(T_{11}^*), TVC_2(T_{21}^*)\}$ 

and  $T^* = T^*_{11}$  or  $T^*_{21}$  is associated with the least cost.

**Remark 8** Basically, Theorem 8 is consistent with Theorem 1 in the work of Huang and Hsu [10]. Furthermore, Theorem  $\mathcal{B}(A)$  above simplifies Theorem 1(A) in this paper by Huang and Hsu [10].

#### 6 Numerical Examples

Forty-two numerical examples are used here to explain and illustrate all of the results in the paper. The necessary parameters and the optimal solutions of the forty-two examples are presented in Tables 1 and 2. All dimensions of the parameters involved in this paper are the same as those in Huang and Hsu [10]. The optimal policies adopted by all examples in Huang and Hsu [10] are included in Policy I. However, the optimal policies adopted by all examples in this paper consist of Policy I as well as Policy II. Therefore, all of results presented in Table 2 are more informative and more meaningful than those in Huang and Hsu [10]. In Table 2 above, the following abbreviations and conventions have been used: Theorem: Which Theorem is applied? N: No, it does not exist. Y: Yes, it exists.

(\*): The optimal solution. ( $\alpha$ ): Which policy is adopted: Policy I or Policy II.?

#### 7 Concluding remarks and further observations

According to the facts that  $H_1 > H_2$ ,  $H_2 > G_2$  and  $G_1 > G_2$ , Theorem 1 characterizes the familiar convexity and concavity properties of  $TVC_{ij}(T)$  (i = 1, 2; j = 1, 2, 3) into six situations (see, for details, [25]). These six situations represent six different types of graphs of  $TVC_{ij}(T)$  (i = 1, 2; j = 1, 2, 3). Although Theorem 1 in the investigation by Huang and Hsu [10] is correct, Huang and Hsu [10] ignored explorations of interrelations of the functional behaviors of  $TVC_{ij}(T)$  (i = 1, 2; j = 1, 2, 3) on the respective domain of  $TVC_{ij}(T)$  (i = 1, 2; j = 1, 2, 3) such that the accuracy and reliability of the process of the proof of Theorem 1 in Huang and Hsu [10] to specify the optimal solution are questionable. This paper removes all of these drawbacks and presents a complete mathematical analytic proof for Theorem 1 in Huang and Hsu [10]. Numerical examples illustrate all of the results which are presented in this paper.

Finally, with a view to providing incentive and motivation for making further advances along the lines of the supply chain management and associated inventory problems which we have discussed in our present investigation, we choose to cite several related recent works including (for example) those by Cárdenas-Barrón et al. [2], Chung et al. (see [4,7]), Khan et al. [11], Liao et al. (see [13], [16,17]), Modak et al. [18], Tiwari et al. [23], Udayakumar and Geetha [24], and Wójtowicz [26].

Example No.	Α	D	с	Р	r	h	Ie	$I_k$	$M_1$	$M_2$	S
1	50	500	50	800	0.9	20	0.15	0.2	0.1	0.15	200
2	50	500	50	800	0.1	20	0.15	0.2	0.1	0.2	400
3	50	500	50	800	0.4	20	0.15	0.2	0.3	0.4	60
4	7	500	150	800	0.05	20	0.15	0.2	0.14	0.4	200
5	40	500	50	800	0.1	20	0.15	0.2	0.1	0.4	80
6	40	500	50	800	0.1	20	0.15	0.2	0.1	0.4	120
7	85	500	50	1200	0.1	20	0.15	0.2	0.1	0.4	147
8	300	500	50	1200	0.1	20	0.15	0.2	0.2	0.4	120
9	85	500	50	1200	0.1	20	0.15	0.2	0.12	0.2	100
10	85	500	50	1200	0.02	20	0.15	0.2	0.12	0.2	100
11	85	500	50	1200	0.02	20	0.15	0.2	0.11	0.2	100
12	300	500	50	1200	0.1	20	0.15	0.2	0.2	0.3	120
13	300	500	70	1200	0.02	20	0.15	0.2	0.18	0.2	120
14	350	500	70	2500	0.01	20	0.15	0.2	0.15	0.2	120
15	150	500	50	800	0.1	20	0.15	0.2	0.12	0.16	240
16	155	500	50	800	0.02	20	0.15	0.2	0.12	0.16	240
17	150	500	50	800	0.1	20	0.15	0.2	0.1	0.15	250
18	150	500	50	800	0.02	20	0.15	0.2	0.1	0.15	250
19	200	500	50	800	0.1	20	0.15	0.2	0.1	0.2	250
20	200	500	50	800	0.02	20	0.15	0.2	0.1	0.2	200
21	150	500	50	800	0.1	20	0.15	0.2	0.12	0.15	240
22	153	500	50	800	0.02	20	0.15	0.2	0.12	0.15	240
23	160	500	50	800	0.1	20	0.15	0.2	0.1	0.15	250
24	160	500	50	800	0.02	20	0.15	0.2	0.1	0.15	250
25	160	500	50	1300	0.1	20	0.15	0.2	0.1	0.11	250
26	160	500	50	1300	0.005	20	0.15	0.2	0.1	0.11	250
27	150	500	50	800	0.1	20	0.15	0.2	0.05	0.15	140
28	150	500	50	800	0.01	20	0.15	0.2	0.05	0.15	140
29	150	500	50	800	0.1	10	0.15	0.2	0.1	0.17	100
30	150	500	50	800	0.01	10	0.15	0.2	0.1	0.17	100
31	120	500	10	800	0.1	20	0.15	0.2	0.15	0.16	100
32	120	500	10	800	0.01	20	0.15	0.2	0.15	0.16	100
33	160	500	50	800	0.1	20	0.15	0.2	0.1	0.12	250
34	160	500	50	800	0.02	20	0.15	0.2	0.1	0.12	250
35	160	500	50	800	0.1	20	0.15	0.2	0.1	0.11	250
36	160	500	50	800	0.003	20	0.15	0.2	0.1	0.11	250
37	160	500	50	800	0.1	20	0.15	0.2	0.1	0.15	140
38	160	500	50	800	0.01	20	0.15	0.2	0.1	0.15	140
39	160	500	50	800	0.1	10	0.15	0.2	0.1	0.17	100
40	160	500	50	800	0.01	10	0.15	0.2	0.1	0.17	100
41	150	500	50	800	0.1	20	0.15	0.2	0.05	0.1	100
42	150	500	50	800	0.003	20	0.15	0.2	0.05	0.1	100

solution
optimal
The
Table 2

Table 2 The optimal solutions	timal solutions																
Example No.	Theorem	$G_1$	$H_1$	$G_2$	$H_2$	$\bigtriangleup_1$	$\Delta_2$	$\Delta_3$	$\Delta_4$	$T_{11}^{*}$	$T_{12}^{*}$	$T_{13}^{*}$	$T_{21}^{*}$	$T_{22}^{*}$	$T^{*}_{23}$	$T^*$	(α)
1	2	<0>	<0>	<0>	0>	>0	>0	>0	>0	Z	Z	(*)	Z	Z	Υ	0.073	(I)
2	2	0>	0>	0>	0>	0<	0<	0<	0<	z	z	Υ	z	z	(*)	0.054	E
3	2	0>	0>	0>	0>	0 <	0 <	0<	0<	z	z	(*)	z	Y	Y	0.110	(I)
4	2	0>	0>	0>	0>	0 <	0 <	0<	>0	z	z	Y	z	Y	(*)	0.027	(II)
5	3(A)	0>	0<	0>	0>	0 <	0 <	0<	0<	z	Υ	(*)	z	z	Y	0.091	(I)
9	3(A)	0>	0<	0>	0>	0 <	0 <	0<	0<	z	Y	Y	z	z	(*)	0.079	(II)
7	3(B)	0>	>0	0>	$^{0}$	~0	0 >	0<	>0	z	Y	Y	z	z	(*)	0.100	E
8	3(B)	0>	>0	0>	0>	~0	0>	>0	>0	z	(*)	Y	Z	z	Y	0.202	Ð
6	4(A)	0>	>0	0>	~0~	0 <	0 <	0<	>0	z	Υ	(*)	z	Y	Y	0.113	Ð
10	4(A)	0>	>0	0>	>0	~0	~0	>0	>0	z	Y	Y	z	Y	(*)	0.113	(II)
11	4(B)	0>	>0	0>	>0	~0	0>	>0	>0	z	Υ	Y	Z	Y	(*)	0.113	E
12	4(B)	0>	>0	0>	~0	~0	0 >	0<	>0	z	(*)	Y	z	Y	Y	0.202	Ð
13	4(C)	0>	>0	0>	>0	>0	0>	0<	0>	z	(*)	Y	Z	Y	Y	0.204	Ð
14	4(C)	0>	0<	0>	>0	~0	0~	0<	0>	z	Υ	Y	Z	(*)	Y	0.203	E
15	5(A)	>0	>0	0>	0>	~0	~0	>0	>0	Y	Y	(*)	z	z	Y	0.117	Ð
16	5(A)	>0	0<	0>	0>	~0	~0	0<	>0	Y	Υ	Υ	Z	z	(*)	0.119	E
17	5(B)	>0	>0	0>	0>	~0	0>	0<	0<	Y	(*)	Υ	z	z	Y	0.138	Ð
18	5(B)	>0	>0	0>	0>	>0	0>	0<	>0	Y	Υ	Υ	z	z	(*)	0.115	(II)
19	5(C)	>0	>0	0>	0>	0>	0>	0<	0<	(*)	Y	Υ	z	z	Y	0.185	Ð
20	5(C)	~	~	0>	0>	0>	0>	0<	0<	Y	Y	Y	z	z	(*)	0.133	E

	ncn																
Example No.	Theorem	$G_1$	$H_1$	$G_2$	$H_2$	$\bigtriangleup_1$	$\Delta_2$	$\triangle_3$	$\Delta_4$	$T_{11}^*$	$T_{12}^{*}$	$T_{13}^{*}$	$T_{21}^{*}$	$T^{*}_{22}$	$T_{23}^{*}$	$T^*$	$(\alpha)$
21	6(A)	>0	>0	0>	~0	>0	>0	>0	>0	Υ	Υ	Υ	N	N	Υ	0.117	(]]
22	6(A)	0<	0<	0>	0<	0<	0<	0<	0<	Y	Y	Y	z	Y	(*)	0.119	E
23	6(B)	0<	0<	0>	0<	0<	0>	0<	0<	Y	(*)	Y	z	Y	Υ	0.147	(I)
24	6(B)	>0	>0	0>	>0	0<	0>	0<	0 <	Υ	Υ	Υ	z	Y	(*)	0.119	(]]
25	6(C)	0<	0<	0>	0<	0<	0>	0<	0>	Y	(*)	Y	z	Y	Υ	0.129	Ξ
26	6(C)	0<	0<	0>	0<	0<	0>	0<	0>	Y	Y	Y	z	(*)	Υ	0.117	(II)
27	6(D)	0<	0<	$\overset{0}{\scriptscriptstyle >}$	0<	0>	0>	0<	0 <	(*)	Y	Y	z	Y	Y	0.222	Ξ
28	6(D)	0<	0<	0>	0<	0>	0>	0<	0<	Y	Y	Y	z	Y	(*)	0.145	(II)
29	6(E)	0<	0<	$\overset{0}{\scriptscriptstyle >}$	0<	0>	0>	0<	0>	(*)	Y	Y	z	Y	Y	0.236	Ξ
30	6(E)	>0	>0	0>	0<	0>	0>	0<	0>	Y	Υ	Y	z	(*)	Y	0.182	(II)
31	7(A)	0<	0<	0<	0<	0<	0<	0<	0<	Y	Y	(*)	Y	Y	Υ	0.146	Ξ
32	7(A)	>0	>0	>0	0<	>0	0<	0<	~0	Υ	Υ	Υ	Y	Y	(*)	0.146	(II)
33	7(B)	>0	>0	>0	>0	>0	0>	0<	0 <	Y	(*)	Y	Y	Y	Y	0.147	Ξ
34	7(B)	0<	0<	0<	0<	0<	0>	0<	0 <	Y	Y	Y	Y	Y	(*)	0.119	E
35	7(C)	>0	>0	>0	~0	>0	0>	>0	0>	Υ	(*)	Υ	Y	Y	Y	0.147	Ξ
36	7(C)	>0	>0	>0	0<	>0	$^{0}_{>}$	0<	0 >	Y	Y	Y	Y	(*)	Y	0.133	(II)
37	7(D)	>0	>0	>0	>0	0>	0>	>0	~0	(*)	Y	Y	Y	Y	Y	0.150	Ξ
38	7(D)	0~	>0	0<	0<	0~	0~	0<	0 <	Y	Y	Y	Y	Y	(*)	0.150	(II)
39	7(E)	>0	>0	>0	0<	0>	0>	>0	0>	(*)	Y	Y	Y	Y	Y	0.247	Ξ
40	7(E)	>0	>0	>0	~0	0>	0>	>0	0>	Υ	Υ	Υ	Y	(*)	Y	0.190	(II)
41	7(F)	>0	>0	>0	0<	0>	0>	0>	0>	(*)	Υ	Υ	Y	Y	Y	0.225	Ξ
42	7(F)	0<	0<	0<	0<	0>	0>	0>	0>	Y	Y	Y	(*)	Y	Υ	0.186	(II)

#### **Compliance with ethical standards**

Conflict of interest The authors declare no conflicts of interest

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