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Sensitivity of daily reference evapotranspiration to weather variables in tropical savanna: a modelling framework based on neural network

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Abstract

Accurate prediction of reference evapotranspiration (ET_0) is crucial for many water-related fields, including crop modelling, hydrologic simulations, irrigation scheduling and sustainable water management. This study compares the performance of diferent soft computing models such as artifcial neural network (ANN), wavelet-coupled ANN (WANN), adaptive neurofuzzy inference systems (ANFIS) and multiple nonlinear regression (MNLR) for predicting ET_0 . The Gamma test technique was adopted to select the suitable input combination of meteorological variables. The performance of the models was quantitatively and qualitatively evaluated using several statistical criteria. The study showed that the ANN-10 model performed superior to the ANFIS-06, WANN-11 and MNLR models. The proposed ANN-10 model was more appropriate and efficient than the ANFIS-06, WANN-11 and MNLR models for predicting daily ET_0 . Solar radiation was found to be the most sensitive input variable. In contrast, actual vapour pressure was the least sensitive parameter based on sensitivity analysis.

Keywords ANN · ANFIS · FAO-56 Penman–Monteith · Sensitivity analysis · Wavelet neural network

Introduction

Water is essential for agriculture production and constitutes the major component of sustainable growth in the agriculture sector (Kumar et al. [2012](#page-23-0), [2017](#page-23-1); Kumar and Haroon [2021\)](#page-23-2). It is the main component on which several hydrometeorological processes rely (Kushwaha et al. [2016\)](#page-23-3). The primary source of water on our planet is precipitation, which is available in various forms such as rainfall, snowfall, hail, fog and dew (Kurzyca and Frankowski [2019](#page-23-4)) and supply of water at diferent locations worldwide depends greatly on the event and rainfall, a key factor of the hydrological cycle. Land and water are two basic needs for agrarian and economic improvement worldwide. Both land and water are important natural resources and provide a regulatory role in the production of agriculture. Among several sectors, it is reported that the agricultural industry consumes more than 55% of the freshwater, especially for irrigation purposes (Dias et al. [2018\)](#page-23-5). In several regions where water supplies are limited, estimating the loss of evapotranspiration becomes crucial for irrigation purposes (Jensen and Allen [2016](#page-23-6)). Evapotranspiration is the major component of the water balance in irrigation planning and management practices (Zeleke and Wade [2012\)](#page-25-0) and the major consumptive use of irrigation water in agriculture (Elhag et al. [2011](#page-23-7)). In Mousinram near Cherrapunji, India (a temperate region) receives the highest rainfall globally (Saikia [2009\)](#page-24-0), even though water shortage also occurs almost every year in the dry season (Kumar et al. [2005](#page-23-8)). Reference evapotranspiration (ET_0) is quantified worldwide according to the recommendation of the FAO (Allen et al. [1998;](#page-23-9) Pereira et al. [2015\)](#page-24-1). The Penman–Monteith FAO-56 (P-M FAO-56) is considered the reference approach and is mainly adopted worldwide in the absence of direct measurement using lysimeters (Sentelhas et al. [2010](#page-24-2)).

Soft computing techniques have the capacity over conventional approaches to solving complex problems of various hydrologic processes (Chandwani et al. [2015\)](#page-23-10). Regarding its capability to handle highly complex nonlinear problems, the application of various soft computing approaches has attracted the interest of many international researchers during the last few years (Bajirao et al. [2021;](#page-23-11) Tulla et al. [2024](#page-24-3)). Hence, techniques like ANN, ANFIS, gene expression pro-Extended author information available on the last page of the article gramming (GEP) and deep learning (DL), among others,

have been the extraordinary technology of reference evapotranspiration modelling (Kisi and Alizamir [2018](#page-23-12); Tikhamarine et al. [2020;](#page-24-4) Kushwaha et al. [2022\)](#page-23-13).

Lee et al. ([2010\)](#page-24-5) present the development and evaluation of artifcial neural network (ANN) models for estimating future reference evapotranspiration (ET_0) based on climate change scenarios. The models were trained and validated for Suwon, Korea, using four climate factors as input parameters and the FAO Penman–Monteith equation as the target values. The study found that the ANN models achieved good performance in estimating future reference crop evapotranspiration. Shiri et al. ([2011](#page-24-6)) apply adaptive neuro-fuzzy inference system (ANFIS) and artifcial neural network (ANN) approaches to model daily pan evaporation using daily climatic parameters in the State of Illinois, USA. The feasibility of ANFIS and ANN evaporation modelling from limited climatic parameters is demonstrated, showing the potential for accurate estimation of daily pan evaporation. Üneş et al. [\(2018](#page-24-7)) focus on estimating daily reference evapotranspiration (ET_0) using different empirical methods and comparing the results with an artifcial neural network (ANN) model. The study concludes that the ANN model outperforms traditional empirical equations in estimating daily ET_0 . Wu et al. [\(2019\)](#page-24-8) explore the use of eight machine learning models and the Hargreaves-Samani equation for estimating reference evapotranspiration (ET_0) using temperature data from local or cross stations. The results show that the tree-based models (RF, GBDT and XGBoost) perform better in local applications.

In contrast, MARS and SVM models are more suitable when only temperature data is available. In the absence of temperature data at the target station, MARS, SVM and KNEA models are recommended. Kushwaha et al. [\(2022\)](#page-23-13) compare diferent models (additive regression (AdR), random subspace (RSS), M5 pruning tree (M5P) independently and four novel permutated hybrid combinations of these algorithms) with sequential inclusion of six meteorological input variables to estimate reference evapotranspiration (ET_o) using machine learning algorithms. The model AdR6, which included all six selected meteorological variables, outperformed other models in terms of prediction accuracies. At the same time, the RSS algorithm failed to capture observed trends even with all input variables.

The extreme learning machine (ELM) was applied to predict the ET_0 in south China by Wu et al. ([2021\)](#page-25-1) and Liu et al. ([2021\)](#page-24-9). Sanikhani et al. ([2019\)](#page-24-10) considered six artifcial intelligence (AI) models, *i.e.* the ANN, the (GRNN), the RBFNN, two ANFIS models (*i.e.* with gird partition and subtractive clustering partition: GP and SC) and GEP, for forecasting the ET_0 by using only three meteorological variables (*i.e.* T_{min} , T_{max} and Solar radiation). The study concluded that the GEP and GRNN were more accurate compared to the other models at Antalya station. On the other hand, the RBNN and ANFIS-SC were the best models at the Isparta station. A cross-station scenario examination is applied to predict the reference evapotranspiration of any station using the input data of the nearby station. Using cross-station scenarios, all the AI models were more successfully employed than the other empirical methods except the MLPNN model for modelling the ET_0 . A comparison between single and hybrid ANFIS models was made by Roy et al. [\(2021](#page-24-11)), highlighting the superiority of the hybrid models. Furthermore, several other studies have reported the superiority of the hybrid models compared to the single models (Ahmadi et al. [2021](#page-23-14)).

An essential task is to do a sensitivity analysis on the possible change in ET_0 in response to the currently available climatic conditions. Evaporation rates were initially studied by McCuen ([1973](#page-24-12)), who looked at how changes in meteorological conditions afected the rate of evaporation and how measurement errors affected rates. ET_0 estimates and weather-related sensitivity analyses for various areas have been studied extensively. Many studies have been done (Goyal [2004](#page-23-15)) reporting that (*i*) the solar radiation climatic variable (SR) was the most important factor in the ET_0 cal-culation (Emeka et al. [2021](#page-23-16)), (*ii*) T_{max} and T_{min} significantly impact the model's output, as shown by Ley et al. ([1994](#page-24-13)). Beven [\(1979\)](#page-23-17) and Gong et al. [\(2006\)](#page-23-18) studied the effect of input data errors on estimates of actual crop evapotranspiration $(ET_{a, crop})$ in England and Wales. A mass transferbased equation to calculate evaporation in Vaud, Switzerland (Singh and Xu [1997\)](#page-24-14). Systematic and random errors of 5, 10 and 20% were added to the original data before evaluating the change in evaporation. It was discovered that the vapour pressure gradient, wind speed and air temperature data did not affect evaporation. Goyal ([2004\)](#page-23-15) investigated the variability of the ET_0 in response to the fluctuation of four climatic variables (*i.e.* T_{mean} , R_n , U_2 and e_a) within a range of $\pm 20\%$ in Rajasthan (India). According to Goyal's findings, the ET_0 in the research region increased by 14.8% when the mean air temperature was raised by 20% (maximum of 8 °C). ET_o was less responsive (11% less sensitive). Even a 20% increase in e_a (say, 4.3%) slightly negatively affects ET_0 . In another study, Gong et al. [\(2006\)](#page-23-18), conducted in China, investigated the fluctuation of ET_0 derived from the PM FAO-56 to changes in climatic variables and found that SR, T_{mean} and U_2 are significantly affected by relative humidity. Irmak et al. ([2006\)](#page-23-19) undertook an examination of climate change sensitivity in the various climate areas of the USA. Sunshine duration has been discovered to be an important factor in determining the susceptibility of ET_o to climate factors in China's Yellow River basin. It has been shown that ET_o is more responsive to solar radiation and less susceptible to T_{mean} in studies conducted Liu et al. [\(2019\)](#page-24-15) during the growing season. Using data from 57 weather stations, Liu et al. [\(2016](#page-24-16)) discovered that ET_0 was more responsive to U_2

and T_{mean} than other climatic factors in south-eastern China. The sensitivity of the PM FAO-56 using the Monte Carlo (MC) method to check variability in the meteorological data is considered as input (Kovoor and Nandagiri [2018](#page-23-20)). The study was conducted in India using data from four stations. The analysis was performed separately for four climatic stations representing diferent climate regions of India, such as Jodhpur-1453, Hyderabad-1044, Bangalore-1368 and Pattambi-1275. The U_2 Wind speed was the superior input variable, and the net radiation was found to be a critical variable. Many other researchers investigate sensitivity analysis ET_o in many parts of the world (Ndiaye et al. [2021](#page-24-17); Poddar et al. [2021](#page-24-18)).

Regional and seasonal differences in ET_0 sensitivity have received less attention in studies using a single station than in studies involving many stations. The chosen Indian station has not conducted a comprehensive investigation on the sensitivity of ET_0 to major climatic elements under various scenarios, while in India, less information is available. In addition, a wide range of meteorological factors has been altered due to global warming. Therefore, the purpose of the present study was to evaluate various ML models, namely ANN, wavelet-ANN (WANN), ANFIS and MNLR, for predicting daily ET_0 in the state of Karnataka, India, to determine the sensitivity of ET_0 to standard climate observation variables at climate stations and their contributions to changes in yearly ET_0 .

Materials and methods

Study area

This study was conducted at the Gandhi Krishi Vignana Kendra (GKVK) station at Bengaluru north taluk of Bengaluru (Urban) district in Karnataka state. It belongs to the eastern dry zone (Zone-V), which includes Kolar, Tumkur, Bengaluru (Urban), Bengaluru (Rural), Chikkaballapura and Ramanagara. The eastern dry zone comes under the Southern Plateau and Hills region (X) of agro-climatic zones. Geographically, the GKVK station is located at 12° 58° N latitude and 77° 30° E longitude with an altitude of 930 m above the average sea level. The location of GKVK is shown in Fig. [1](#page-2-0). The area of GKVK is considered a semiarid sub-tropical that falls in a sub-tropical zone. The mean annual rainfall of the station is 867.9 mm. In the winter season, there is low rainfall compared to the summer season. January and February months receive the lowest rainfall, whereas the major portion of precipitation is received during April-November, with two peaks in May and September. The mean annual temperature is in the range of 18.2–29.5 °C. The monthly temperature data of the station reveals that December is the coolest month of the year, having a daily

Fig. 1 The geographical location of the study area

mean temperature ranging between 15.8 and 26.9 °C, and April is the warmest month of the year as the daily mean temperature lies between 21.2 and 34.1 °C. In Karnataka, most of the area is covered by sandy loam soil, having low organic matter content and low moisture retention capacity. Ragi, maize, paddy, groundnut, fnger millet and sunfower are considered the major crops growing in this area.

Data acquisition, pre‑analysis and formulation of data

The present study was conducted using daily weather data of maximum and minimum air temperatures (T_{min}, T_{max}) , relative humidity (RH), wind velocity at 2 m height (w_s) and sunshine hour (S_h) for the period of 12 years and ten months (4687 days, from January 2007 to October 2019) which were recorded by the Agro Meteorology station of University of Agriculture Sciences (UAS), GKVK, Bengaluru. These data were downloaded from the UAS Bangalore (Agro Meteorology system) portal [\(www.uasbangalo](http://www.uasbangalore.edu.in/) [re.edu.in/](http://www.uasbangalore.edu.in/)). For this study region, the data set of various climatic variables such as T_{min} , T_{max} , w_s , S_h and RH_{mean}

were considered as inputs to CROPWAT 8.0 software for calculating PM FAO-56 ET_0 . The estimated PM FAO-56 ET_o values were utilised as output data. Time series and Box and Whisker plots of observed daily climatic variables with computed $ET_{o(PM)}$ are shown in Figs. [2](#page-3-0) and [3,](#page-4-0) respectively, which provide the basic idea about the variability of the dataset with time. In this study, various input climatic variables, viz. mean air temperature (T_{mean}) , mean relative humidity (RH_{mean}), wind speed (w_s), sunshine hour (S_h) , saturated vapour pressure (e_s) , actual vapour pressure (e_0) and solar radiation (R_s) , were combined to derive the best input combination data set with applying Gamma test (GT) algorithm. Several statistical parameters were considered for pre-analysis of the time series dataset shown in Table S1. Out of the whole data set (4687 days), 70% of data (3281 days, 01/01/2007 to 25/12/2015) were used for training purposes, and the remaining 30% of data (1406 days, 26/12/2015 to 31/10/2019) were used for testing purposes. The ML models are developed and trained on the training dataset, and further, the performance evaluation is carried out using the unseen test dataset.

Development of models

In this research, various artifcial intelligence techniques, such as ANN, ANFIS, WANN and MNLR techniques, were developed to simulate the daily ET_{o} . The flowchart of the proposed is illustrated in Fig. [4](#page-5-0).

Artifcial neural network (ANN)

An artifcial neural network (ANN) is an machine learning (ML) model composed of several processing elements and can display complex relationships between inputs and outputs. The functioning of the ANN is similar to the way neurons work in the human nervous system, and the architecture consists of input, hidden and output layers (Fig. S1). The input layer of the ANN is the frst layer that receives the various types of input data, such as image pixels, texts and numbers. The data passes through one or more hidden layers; the hidden layer performs mathematical computation on the data received (Hassoun [1995](#page-23-21)). The number of hidden layers in the ANN model is mainly related to the task being solved. The output layer is the last year in the ANN

Fig. 2 Graphical presentation of daily climatic time series data (2007–2019)

Fig. 3 Box and Whisker plots of the daily climatic for parameters

and is responsible for producing the output. An ANN fnetunes its weights and improves the performance through the backpropagation algorithms, which is the central pillar of the neural network training process. The functional composition of a neural network is the most popular structure, which is represented in Fig. S2. A neuron applies the net function and activation function on input variables to determine the output variable value. The x_i and w_i are input vectors and their respective connection weights from an *i*th neuron in the input layer (where $i = 1, 2, \ldots, n$). The net function (a) is represented in the linear form that is determined based on the product of the input vector with their corresponding connection weights (W_i) and the value of bias or threshold value (w_o) associated with that node. In a neural network system, a nonlinear activation function f(.) is used to show its nonlinearity between input variables and output variables as well as to transform net function (*a*) at the hidden node into output (y) of the node, which is expressed as:

$$
Y = f(a) \tag{1}
$$

By varying the transfer function and altering the parameter, such as thresholds or gains, the output of neurons can be modifed. An appropriate learning algorithm is utilised to adjust the connection weights using the training data set in a neural network. The purpose of changing the connection weights value is to minimise the error of prediction results during the learning process. Because weight shows the effect of any input on output. Several nonlinear activation functions are available, as presented in Table [1,](#page-5-1) which are mostly utilised for the modelling of the hydrological process. The hyperbolic tangent sigmoid (tensing) activation function is used to establish the hydrology process's neural network models, shown in Fig. S3. The mathematical formula of tansig activation function is expressed as:

$$
f(a) = \tan \left(a \right) = \frac{2}{1 + e^{-2a}} - 1 \tag{2}
$$

In this study, the multi-layer perceptron neural network (MLP) is used. The general architecture of a feed-forward MLP neural network with a single hidden layer appears in Fig. S4.

Adaptive neuro‑fuzzy inference system (ANFIS)

Adaptive neuro-fuzzy inference system (ANFIS) is an ML developed from the combination of the ANN and fuzzy

Fig. 4 Flowchart of the methodology of the study

Table 1 Details about diferent types of activation functions

Transfer function	Output range	Description		
Tansig	-1 to 1	Hyperbolic tangent sigmoid		
Logsig	0 to 1	Log sigmoid		
Purelin	-1 to 1	Linear transfer function		

inference systems (FIS). Jang ([1993](#page-23-22)) proposed the ANFIS model and its principles, applied to various hydrological and other modelling problems. The ANFIS model is a universal estimator, taking full advantage of the FIS and the IF–THEN rules. The basic architecture of ANFIS comprises fve layers: fuzzifcation layer, product layer, normalisation layer, defuzzifcation layer and output layer (AL-Oqla and Al-Jarrah [2021\)](#page-23-23). Figure S5 shows the schematic diagram of the ANFIS. The circle and square nodes represent the fxed and the adaptive nodes, respectively. The number of nodes in each layer is decided according to the specifc research requirement. In the present study, six diferent membership functions were utilised, whose shapes appear in Figs. S6 and S7. ANFIS has various types of FIS for the learning process. The Sugeno-type fuzzy system is the most popular and commonly used fuzzy system.

Wavelet‑coupled artifcial neural network (WANN)

Wavelet artifcial neural networks combine the ANN with wavelet analysis. The wavelet analysis is used as a preprocessing data strategy to improve the accuracy (Fig. S8). WANN is considered a feed-forward neural network that uses a wavelet as its activation function (Esmaeilzadeh et al. [2017\)](#page-23-24). It introduces wavelet decomposition property into an ANN. The amalgamation of the frequency location of the wavelet transform and the self-learning feature of ANN makes it a powerful tool. An additional layer is introduced to traditional ANN. The dilation, translation and weight parameters are updated during the model training (Mobtaker et al. [2016\)](#page-24-19). A backpropagation algorithm is usually employed to train the wavelet artifcial neural networks. Since this hybrid approach enhances the existing model and achieves improved nonlinear approximations, WANN successfully models function approximations and forecasting. The ANN, WANN and ANFIS models were calibrated based on the diferent training variables and assigned values given in Tables [2](#page-6-0) and [3.](#page-6-1)

Multivariate nonlinear regression (MNLR)

Linking a set of independent variables to one dependent variable is a challenging task. Nonlinear regression analysis is utilised to defne the quantitative relationships between the dependent variable and various independent variables. The multivariate nonlinear regression (MNLR) technique is the most widely recognised type of nonlinear regression analysis, which is used for linking a suite of independent variables to one dependent variable by ftting them through the function of the nonlinear equation (Vishwakarma et al. [2022a](#page-24-20)). Eventually, this technique succeeds based on the least square technique and as the best-ft line to model the nonlinear behaviour between dependent and independent variables of observational data. Here, the mathematical expression of the MNLR technique is expressed as:

$$
Y = \beta_0 \left(X_1^{\alpha_1} \right) \left(X_2^{\alpha_2} \right) \left(X_3^{\alpha_3} \right) \dots \dots \dots \dots \left(X_n^{\alpha_n} \right) \tag{3}
$$

where *Y* is the dependent variable, β_0 is the intercept (constant), α_1 … … α_n are the regression slope coefficient for the nonlinear relation and X_1, X_2, \ldots, X_n are the independent variables. The model formulation of a nonlinear equation can be transformed into the linear form by taking a log of Eq. [\(5](#page-6-2)) to solve the problem of the MNLR technique, which establishes the linear relationship between dependent and independent variables on log paper:

$$
\log Y = \log \beta_0 + \alpha_1 \log X_1 + \alpha_2 \log X_2 + \dots + \alpha_n \log X_n \tag{4}
$$

Equation ([5\)](#page-6-2) denotes a regression of $log(Y)$ on $log(X_1)$, $log (X_2)$, ..., $log (X_n)$, which is used to estimate the regression coefficient. β_0 , α_1 , α_2 , α_3 , α_n . PM FAO-56 -based daily ET_0 was considered as the dependent variable (Y). In contrast, meteorological variables were used as independent variables $(X_1, X_2, ..., X_n)$.

Gamma test (GT)

The mechanism of evapotranspiration is part of hydrological processes that are typically nonlinear, complex and dynamic (Vishwakarma et al. [2022b;](#page-24-21) Raza et al. [2022\)](#page-24-22). Due to the trialand-error procedure, looking for the best input combination

Table 3 Training variables and their assigned values for ANFIS models

Training variables	Assigned value
FIS generation method	Grid partition
FIS Type	TSK
Number of membership functions per input	2
Types of input MFs	gaussmf, gauss2mf, trimf, trapmf, gbellmf, psigmf
Types of output MFs	Linear
Epoch	100
Error tolerance	0.001
Learning algorithm	Hybrid

is a challenging task optimal for hydrological modelling (Bajirao et al. [2021\)](#page-23-11). This procedure needs calibration and testing to establish the best model based on input combinations. The Gamma test (GT) minimises the workload required for model creation by considering all input combinations of input parameters, guiding the selection of input parameters for creating a reliable, smooth model (Malik et al. [2020\)](#page-24-23). The choice of input parameters is an important step towards creating a robust regressor. The used input variables led to a complicated structure for which the model's parameters were updated; consequently, the model's performances were also afected. GT is a nonparametric test and nonlinearity analysing tool that examines the nonlinear relationship between input and output variables (Singh et al. [2018](#page-24-24)). A major advantage of this tool is its speed in massive datasets because GT takes a few moments to run. The GT algorithm uses a set of M input/output variables as:

$$
\{x_i(i), \dots, \dots, x_m(i), y_i\} = \{x_i, y_i\} [1 \le i \le M]
$$
 (5)

where *M* is the total number of data, *X* is the input matrix and *Y* is the corresponding output variable, for which a hypothesis for a possible link between *X* and *Y* is available. The gamma coefficient (Γ) is calculated using a simple linear regression between *X* and *Y* as follows:

$$
y = f(x_i \dots x_m) + \Gamma \tag{6}
$$

Table 2 Training variables and their assigned values for ANN and WANN models

where f is a smooth function and Γ is a random variable representing noise. This study selected the best input combination based on the minimum V ratio and gamma (Γ) value for predicting ET_0 . WinGammaTM software was utilised to apply the gamma test.

CROPWAT 8.0 software

CROPWAT 8.0 software is a water system management and planning model that recreates the unpredictable relationship between the atmosphere, soil and crop cultivation parameters. The FAO developed it to encourage the estimation of reference evapotranspiration (ET_0) , crop evapotranspiration, the need for agriculture water and irrigation scheduling with diferent cropping patterns for irrigation planning. In water necessity and water system improvement (irrigation) planning, the computation of reference evapotranspiration is vitally important. General information on the spatial circulation of reference evapotranspiration is still crude, irrespective of its signifcance for global ecosystem research. It is difficult to observe one reason for ET_0 because it depends on a few weather parameters seen at stations. The monthly ET_0 was calculated using CROPWAT 8.0 software based on the necessary climatic variables for Gandhi Krishi Vignana Kendra (GKVK) Bengaluru stations. In CROPWAT 8.0, the PM FAO-56 PM is used, and its theoretical description can be found in (Allen et al. [1998](#page-23-9)).

Model performance evaluation indices

In this study, numerous performance indices were utilised to test the performance of the ANN, WANN, ANFIS and MNLR models, including root mean-squared error (RMSE), coefficient of determination (R^2) , Willmott index (WI) and Nash–Sutcliffe efficiency (CE). The mentioned parameters are defned as:

where ET_{PM} , ET_m , ET_{PM} and ET_m are the values of the PM FAO-56-based observed and model-based estimated, average values of PM FAO-56 observed and PM FAO-56 equation-based estimated values, respectively. The models with higher CE, R^2 and WI values and lower RMSE are adjudged relatively the better model for monthly ET_0 estimation (Vishwakarma et al. [2022b](#page-24-21)).

Sensitivity analysis

Sensitivity analysis is a tool used to control the reliability of modelling by determining the cause-and-efect of an ensemble of input to an output variable for a developed model (Hosseini et al. [2022](#page-23-25)). It plays a signifcant role in fnding the most sensitive parameter from diferent input parameters whose deviation signifcantly changes the predicted output. The sensitivity analysis also fnds irrelevant inputs eliminated from the created model for simplicity. So it may improve the model's performance. It disables the built model's learning not to afect network weights. In the present study, input parameters such as relative humidity, wind speed, sunshine hour, actual and saturated vapour pressure and solar radiation were selected to perform sensitivity analysis for the best model that infuences the predicted values of reference evapotranspiration. The sensitivity analysis was performed by increasing 10% and decreasing 10% of the input parameter values. For each input parameter, this procedure is repeated to evaluate the sensitivity of the output concerning changes in input values. The mathematical expression of relative sensitivity is used to determine the sensitivity order of selected input parameters. Using the equation, relative sensitivity (RS) has been computed after calculating the individual value of each day's sensitivity as:

$$
RS = \sum \left\{ \left(\frac{x}{y} \right) \times \left(\frac{y_2 - y_1}{x_2 - x_1} \right) \right\}
$$
 (11)

where *x* and *y* are the original input parameter and the originally predicted output for a given day, respectively. $x_1 = (x + \Delta x)$ and $x_2 = (x - \Delta x)$ are increasing and decreasing input parameter values, respectively, where $\Delta x = 0.1 \times x$. *y₁* and y_2 are the results of predicted output concerning x_1 and *x2*, respectively.

Based on the best input combination (RH_{mean}, w_s , S_h , e_s , e_a , R_s), 24 (6×4) subseries were produced and considered as input variables. After this, these 24 input variables were fed to the ANN system for simulation of reference evapotranspiration as shown in Fig. S10, and it is also functionally expressed as:

Results

Best input combination‑Gamma test (GT)

To simulate artifcial intelligence and statistical techniquesbased reference evapotranspiration models, a gamma test (GT) can be utilised to choose the best input combination of climatic variables. It can minimise the necessary workload for conducting cumbersome trial-and-error methods. Therefore, this study chose the best input combination of meteorological predictors by applying the GT to predict PM FAO-56. In the GT, the meteorological variables, *i.e.* T_{mean} , RH_{mean}, w_s and R_{s} , were combined to predict the PM FAO-56. These input variables were used to form various possible input combinations, as shown in z [4.](#page-9-0) The best input combination of climatic variables was selected based on the lower gamma and V_{ratio} (Vishwakarma et al. [2023\)](#page-24-25). It can provide better outcomes during the development of AI models. According to Table [4,](#page-9-0) model M-41 (RH_{mean}, w_s , S_h , e_s , e_a , R_s) represented the minimum value of gamma and V ratio. It was considered the best input combination, which was further used for the calibration of ANN, WANN, ANFIS and MNLR models to predict reference evapotranspiration.

A selected input combination of climatic variables was employed for the prediction of daily reference evapotranspiration, which is functionally expressed as:

$$
ET_o = f(RH_{mean}, w_s, S_h, e_s, e_a, R_s)
$$
\n(13)

The structure of the ANN and ANFIS models is shown in Fig. S9. For developing the WANN model, the decomposed components of selected input variables obtained by applying DWT were used as inputs to ANN mode (Fig. S10).

In this study, the Haar-type wavelet function was considered to decompose the original time series of selected input variables into diferent sub-series at appropriate decomposition levels, which was taken as 3. Therefore, each input variable was decomposed into four sub-series comprising one approximate (A_3) and three detail (D_1, D_2, D_3) sub-series.

Model performances evaluation

This study applied the Levenberg–Marquardt-based backpropagation learning algorithm to calibrate both ANN and WANN-based ET_0 models. Both models used the Tan-sigmoid activation function for the hidden neurons and a linear function for the output neuron. Diferent architectures of ANN and WANN models were built by varying the total number of neurons in the hidden layer. In the ANN model, the number of neurons in the hidden layer was varied from one to $2n + 1$, where n is the number of inputs. Therefore, 13 $(2 \times 6 + 1)$ ANN architecture was built to develop the ANN-based ET_0 model. In the case of the WANN model, a total of 49 $(2 \times 24 + 1)$ architectures were built as 24 input signals (a decomposed form of selected input variables) were taken to train the ANN system. Based on performance evaluation such as qualitative and quantitative $(R², RMSE, CE and WI) evaluation, the best model was$ selected from various ANN/WANN model architectures to predict reference evapotranspiration.

MLP‑ANN models

Using data from KGVK Campus Bengaluru meteorological stations, the performance of all MLP-ANN (1–13) for predicting daily ET_0 was examined. For this, many statistical metrics and graphical performance assessment methodologies were applied. All obtained numerical performances are depicted in Table [5.](#page-10-0) As indicated in Table [5,](#page-10-0) the best model was determined to be the ANN-10 model with 6-10-1 architecture. Based on qualitative analysis, the performance of developed models was examined using a graphical representation of simulated ET_0 versus computed ET_0 . From all network structures of ANN, ANN-10 was selected as the best model (Table [5\)](#page-10-0). As shown in Fig. [5,](#page-11-0) the calculated and predicted values of daily reference evapotranspiration were analysed through a time series graph to be in remarkably close agreement during both training and testing periods, **Table 4** Selection of the best input combination for modelling reference evapotranspiration using the Gamma test

Table 5 Results of diferent performance indicators for ANN-based ET_0 prediction

models

Bold value shows the best input combination is based on the minimum gamma and V ratio values

Bold value shows the best model based on the minimum RMSE and highest R^2 and model efficiency (CE and WI) values

respectively; however, the model very slightly under-predicted the higher magnitude of ET_0 as indicated through 1:1 line of scatter plot which is also shown in Fig. [5](#page-11-0)a during training. As shown in Fig. [5b](#page-11-0), the chosen ANN-10 model is slightly under-predicted, over-predicted medium values and greatly under-predicted high values of ET_0 , respectively,

Fig. 5 Comparison of ANN-10 (6-10-1) model in estimating FAO-56 PM ET_o in GKVK Bengaluru station: **a** training period and **b** Testing period

based on a 1:1 line during the testing period. The quantitative analysis was performed based on statistical and hydrological indices, employing the best ANN model for ET_0 prediction. The results of various performance evaluation indices $(R^2, RMSE, CE$ and WI) for all 13 ANNs are reported in Table [5](#page-10-0). The values of R^2 , RMSE, CE and WI varied from 0.9823 to 0.9995 and 0.9792–0.9923; 0.0219–0.1350 mm/day and 0.0905–0.1488 mm/day; 0.9823–0.9995 and 0.9790–0.9922, and 0.9429–0.9901 and 0.9466–0.9859 during training and testing, respectively. The ANN-13 model was observed to be better than the ANN-10 model during training. Nevertheless, as per testing results, the ANN-10 model with architecture (6-10-1) was found to be the most accurate model among all ANN models. During the training period, the results could be due to the over-ftting problem, which infuenced the model's actual performance; therefore, only testing period outcomes were considered to select the best ANN model. The R^2 , RMSE, CE and WI values for the ANN-10 model were obtained as 0.9995, 0.0236 mm/ day, 0.9995 and 0.9999, respectively, during training and 0.9992 0.0209 mm/day, 0.9991 and 0.9998, during testing. The residual plot for the training and testing periods (Fig. [6\)](#page-12-0) shows that the highest errors occur in the range of -0.28 to 0.14, −0.24 to 0.24 mm.

WANN model

The performance of the selected model was evaluated qualitatively. For the accurate WANN-11 architecture, the calculated ET_0 is in close agreement with computed values of ET_0 (PM), which were observed through graphical representation, as shown in Fig. [7.](#page-12-1) However, the selected architecture (24-11-1)-based WANN-11 model slightly under-predicted medium and high values of ET_0 as denoted through a 1:1 line of scatter plot during training and testing, shown in Fig. [7a](#page-12-1) and Fig. [7b](#page-12-1), respectively.

Fig. 6 Residual plot of predicted ET_0 in ANN-10 (6-10-1) model: **a** training and **b** testing periods

Fig. 7 Comparison of WANN-11 (24-11-1) model in estimating FAO-56 PM ETo in GKVK Bengaluru station: **a** training period and **b** Testing period

Table 6 Results of diferent performance indicators for WANN-based ET_0 prediction models

Bold value shows the best model based on the minimum RMSE and highest R^2 and model efficiency (CE and WI) values

In quantitative analysis, various performance indicator values were used to choose the best WANN model for the simulation of ET_0 . The performance evaluation indices (R^2) , RMSE, CE and WI) for all 49 WANN models are presented in Table [6](#page-13-0). The values of \mathbb{R}^2 , RMSE, CE and WI varied from 0.9780 to 0.9995 and 0.9651–0.9939; 0.0719–0.1505 mm/day and 0.0814–0.1928 mm/day; 0.9780–0.9950 and 0.9647–0.9937; 0.9369–0.9986 and 0.9406–0.9984 during training and testing, respectively. As per training, the outcomes of performance indices for the WANN-39 model were found to be better than the WANN-11 model. During the testing process, the WANN-11 model (24-11-1) was found to have satisfactory results using the performance criteria; therefore, this model was chosen as the best model among all WANN models. The values of R^2 , RMSE, CE and WI for the selected WANN-11 model were obtained as 0.9995, 0.0761 mm/day, 0.9944 and 0.9986, respectively, during training and 0.9939, 0.0808 mm/day, 0.9937 and 0.9984, respectively during testing. The residual plot for the training and testing periods (Fig. [8](#page-14-0)) shows that the highest errors occur in the range of −0.21 to 0.22, −0.45 to 0.45 mm.

ANFIS models

Various ANFIS models were calibrated in MATLAB (R2019a) software using ANFIS Editor GUI (graphical user interface) to simulate reference evapotranspiration. For the training of ANFIS, TSK-type FIS was generated using the grid partition method to construct the ANFIS structure. In the generation of FIS, six types of input MFs, namely Triangular (tri), Generalised bell (gbell), P sigmoidal (psig), Gaussian (gauss), Gaussian 2 (gauss2) and Trapezoidal (trap), were used with linear type output MFs. Two MFs

were used to construct one input's best possible model architecture. In the ANFIS editor, a hybrid-type learning algorithm with 100 epochs was chosen, and error tolerance was taken as 0.001 for the training of the ANFIS model. Using qualitative and quantitative analysis, the performance of the developed model was assessed.

In qualitative analysis, the performance of the selected model was evaluated graphically (time series graph and scatter plot). ANFIS-06 model with trapezoidal input membership function was found to be the best among all ANFIS models. For the selected ANFIS-06 model, the computed and predicted values of daily ET_0 were observed through the time series graph to be in close agreement for all values of ET_0 for the calibration and validation stages, as shown in Fig. [9](#page-15-0), respectively. However, the selected model predicted good results for all values of ET_0 ; therefore, no point deviated from the regression line and 1:1 line of scatter plot with an R^2 value of 0.9996 during training, as shown in Fig. [9a](#page-15-0) while modelling slightly and slightly under-predicted for medium and high values of ET_0 with an R^2 value of 0.9987 during testing which is shown in Fig. [9b](#page-15-0).

Results obtained using ANFIS models are reported in Table [7](#page-15-1). It was observed that the values of \mathbb{R}^2 , RMSE, CE and WI varied from 0.9994 to 0.9996 and 0.8961–0.9987, 0.0193–0.0238 mm/day and 0.0374–0.3584 mm/day; 0.9994–0.9996 and 0.8780–0.9987; 0.9893–0.9999 and 0.9752–0.9997 during training and testing, respectively. From Table [7](#page-15-1), all ANFIS models based on input MFs performed satisfactorily during training. Moreover, during training, the outcomes of performance indicators for the ANFIS-04 model (gauss-2 input MFs) were found to be better than the ANFIS-06 model (trap-2 input MFs).

Fig. 8 Residual plot of predicted ET_0 in WANN-11 (24-11-1) model: **a** training and **b** testing periods

Fig. 9 Comparison of ANFIS-06 (trap 2) model in estimating FAO-56 PM ET_o in GKVK Bengaluru station: a training period and b Testing period

Table 7 Results of different performance indicators for ANFIS-based ET_o prediction models

Model	Architecture	Output MF	Training			Testing				
			R^2	RMSE	CE	WI	R^2	RMSE	CE	WI
ANFIS-01	$Tri-2$	Linear	0.9996	0.0200	0.9996	0.9910	0.8961	0.3584	0.8780	0.9752
ANFIS-02	$PSig-2$	Linear	0.9994	0.0238	0.9994	0.9893	0.9897	0.1046	0.9896	0.9816
ANFIS-03	gbell-2	Linear	0.9996	0.0197	0.9996	0.9911	0.9917	0.0939	0.9916	0.9848
ANFIS-04	gauss-2	Linear	0.9996	0.0193	0.9996	0.9912	0.9916	0.0942	0.9916	0.9848
ANFIS-05	gauss2-2	Linear	0.9996	0.0206	0.9996	0.9906	0.9916	0.0942	0.9916	0.9843
ANFIS-06	$trap-2$	Linear	0.9996	0.0214	0.9996	0.9999	0.9987	0.0374	0.9987	0.9997

Bold value shows the best model based on the minimum RMSE and highest $R²$ and model efficiency (CE and WI) values

During the testing process, the ANFIS-06 model was found to have the most accurate results of all performance criteria except the WI result. Hence, this model was the

best model among all ANFIS models. The values of \mathbb{R}^2 , RMSE, CE and WI for the selected ANFIS-06 model based on trapezoidal (trap) input MFs were observed to be

Fig. 10 Residual plot of predicted ET_o in ANFIS-06 (trap 2) model: (a) training and (b) testing periods

0.9996, 0.0214 mm/day, 0.9996 and 0.9999, respectively, during training and 0.9987, 0.0374 mm/day, 0.9987 and 0.9997, respectively during testing. The residual plot for the training and testing periods (Fig. [10\)](#page-16-0) shows that the highest errors occur in the range of -0.01 to $0.13, -0.3$ to 0.23 mm, respectively.

MNLR model

This study calibrated the MNLR model using a training data set of selected input variables to predict ET_0 . The performance of the developed model was evaluated with the

Fig. 11 Comparison of MNLR model in estimating FAO-56 PM ET_o in GKVK Bengaluru station: (a) training period and (b) testing period

testing data set by comparing the expected values of daily ET_o to that of the observed one. The mathematical equation of the developed MNLR model can be expressed in the form as:

$$
ET_o = f (RH_{mean}, w_s, S_h, e_s, e_a, R_s)
$$
 (13)

where ET_0 is the daily reference evapotranspiration (mm/ day), RH_{mean} is the daily basis mean relative humidity $(\%)$, U_2 is the daily wind speed (km/hr), SH is the daily sunshine hour (hours/day), e_s and e_a represent the saturated and actual vapour pressure (kPa), and R_s is the daily solar radiation $(MJ/m^2/day)$.

Qualitatively, the predicted values of reference evapotranspiration agree with computed values of $ET_0(PM)$, which was observed through the time series graph during the training and testing periods, as shown in Fig. [11](#page-16-1), respectively. However, the selected MNLR model slightly under-predicted medium and high values of ET_0 as indicated through a 1:1 line of scatter plot with an R^2 value of 0.9737 during training and slightly over-predicted and under-predicted high values of ET_0 with an R^2 value of 0.9718 during testing, which is also shown in Fig. [11](#page-16-1), respectively.

The performance evaluation indices for developing the MNLR model are presented in Table [8](#page-17-0). It was revealed that the values of R^2 , RMSE, CE and WI for the MNLR model were observed to be 0.9737, 0.1644 mm/day, 0.9737 and 0.9933, respectively, during training and 0.9718, 0.1725 mm/day, 0.9714 and 0.9927, during testing. The residual

plot for the training and testing periods (Fig. [12](#page-17-1)) shows that the highest errors occur in the range -1.0 to $1.0, -0.9$ to 1.8 mm, respectively.

Sensitivity

The concept of sensitivity analysis was applied to the best-selected model to obtain the parameters that have the greatest efect on the performance of the best-developed model. Based on the results of performance indicators (R^2) , RMSE, CE and WI), the ANN-10 model was selected as the best model developed using selected climatic variables to predict daily reference evapotranspiration. Selected climatic variables such as RH_{mean}, w_s , S_h , e_s , e_a , and R_s obtained from the gamma test were used for the ANN-10 model. The sensitivity analysis was done by varying the input variables up to $\pm 10\%$. For each selected input parameter of testing period data, this procedure was repeated to evaluate the sensitivity of the predicted reference evapotranspiration concerning change in input parameter chosen value based on the best-selected ANN-10 model. Using Eq. [14,](#page-8-0) the relative sensitivity corresponding to each selected input parameter was determined. The sensitivity order of selected input parameters was found based on relative sensitivity results. As presented in Table [9](#page-18-0), the values of performance indicators such as R^2 , RMSE, CE and WI were determined based on the sensitivity of the original predicted ET_0 with 10% variation (increasing or decreasing) in each selected input parameter during the

Fig. 12 Residual plot of Predicted ET_0 in MNLR model: **a** training and **b** testing periods

Table 9 Sensitivity analysis of wavelet artifcial neural networks (ANN-10) model during the testing period

Parameter	Parameter values	R^2	RMSE	CE	WI	Relative sensitivity
RH_{mean}	$RH_{mean} - 10\% RH_{mean}$	0.9864	0.1652	0.9741	0.9236	-450.71
	RH_{mean}	0.9992	0.0299	0.9991	0.9998	
	$RH_{mean} + 10\% RH_{mean}$	0.9856	0.1856	0.9673	0.9158	
$W_{\rm g}$	$w_{\rm s}$ – 10% $w_{\rm s}$	0.9965	0.1039	0.9897	0.9492	226.16
	$W_{\rm s}$	0.9992	0.0299	0.9991	0.9998	
	$w_{s} + 10\% w_{s}$	0.9970	0.0854	0.9931	0.9616	
$S_{\rm h}$	$S_h - 10\% S_h$	0.9928	0.1220	0.9859	0.9449	295.17
	$S_{\rm h}$	0.9992	0.0299	0.9991	0.9998	
	$S_h + 10\% S_h$	0.9914	0.1417	0.9809	0.9319	
$e_{\rm s}$	$e_s - 10\% e_s$	0.9917	0.2755	0.9279	0.8495	770.76
	e_{s}	0.9992	0.0299	0.9991	0.9998	
	$e_{s} + 10\% e_{s}$	0.9901	0.2539	0.9388	0.8681	
$e_{\rm a}$	$e_{\rm a}$ – 10% $e_{\rm a}$	0.9925	0.1012	0.9903	0.9597	-166.82
	e_{a}	0.9992	0.0299	0.9991	0.9998	
	$e_{\rm a} + 10\% e_{\rm a}$	0.9930	0.1035	0.9898	0.9553	
$R_{\scriptscriptstyle\rm c}$	$R_{\rm s} - 10\% R_{\rm s}$	0.9866	0.4720	0.7884	0.7398	1382.37
	$R_{\rm s}$	0.9992	0.0299	0.9991	0.9998	
	$R_{\rm s} + 10\% R_{\rm s}$	0.9890	0.4308	0.8237	0.7740	

Table 10 The sensitivity of reference evapotranspiration (ET_0) corresponds to the selected input climatic variables for the ANN-10 model

testing period of ANN-10 model to see the efect of each input parameter on the performance of the model.

As seen from Table [10,](#page-18-1) the relative sensitivity values of the selected climatic variables such as RH_{mean} , w_s , S_h , e_s , e_a and R_s for the ANN-10 model were found to be -450.71 , 226.16, 295.17, 770.76, −166.82.2 and 1382.37, respectively. Based on these results, the order of sensitivity of selected climatic variables was obtained as $R_s > e_s > RH_{mean}$ $>S_h > w_s > e_a$. Solar radiation was considered the most sensitive parameter, which greatly infuenced the prediction of reference evapotranspiration. While actual vapour pressure was considered the least sensitive parameter, it was found that this parameter has an inverse relation with ET_0 due to negative signs.

On the other hand, the sensitivity analysis result was found based on the change in output concerning variation in input. As seen from Table [10](#page-18-1), it was obtained as the variation of ET_0 (%) concerning a 10% increase in each selected climatic variable based on the best-selected ANN-10 model during the testing period. The percentage values of ET_0 change concerning RH_{mean} , w_s , S_h , e_s , e_a , and R_s were found as −3.17, 1.63, 2.10, 5.42, −1.05 and 9.72, respectively. Negative and positive signs indicate the inverse and direct relationship between input and output variables, respectively. The sensitivity order of selected input parameters based on these results was similar to the relative sensitivity results. Finally, it was concluded that solar radiation was the most relevant parameter.

In contrast, actual vapour pressure was the most irrelevant parameter among all parameters for developing the ANN-10 model to predict ET_0 for the GKVK station. Due to this, actual vapour pressure can be eliminated from the bestdeveloped model for simplicity and performance enhancement of the developed model for future study. The developed models can be directly integrated with web/mobile-based applications for real-time estimation of reference evapotranspiration, assisting researchers and other stakeholders in predicting water requirements.

Discussion

Based on qualitative and quantitative performance evaluation indicators $(R^2, RMSE, CE$ and WI), the best models were selected from each technique, which were further compared with each other to choose the most reliable model for the simulation of daily reference evapotranspiration. The values of numerical metrics for the best-selected models of each technique are presented in Table [11](#page-19-0) to evaluate predictive

Table 11 Comparison of performance evaluation of ANN, WANN, ANFIS and MNLR models for prediction of ET_{o}

Bold value shows the best model based on the minimum RMSE and highest R^2 and model efficiency (CE and WI) values

performance during both training and testing periods. From Table [11](#page-19-0), the values of various indices showed a minor distinction between the two models (except the MNLR model). However, in the case of the WI indicator, a significant difference was found among all models during training and testing periods. The values of R^2 , RMSE, CE and WI varied from 0.9737 to 0.9996, 0.0214–0.1644, 0.9737–0.9996 and 0.9255–0.9903, respectively, during training while during testing, the values of R^2 , RMSE, CE and WI varied from 0.9467 to 0.9938, 0.0814–0.2390, 0.9457–0.9936 and 0.9281–0.9816, respectively.

As shown in Table [11](#page-19-0), the ANFIS model performed as the best model among all models during training. However, the ANN-10 model performed better during testing than the other models using all performance indices $(R^2, RMSE, CE)$ and WI). Because the value of WI was found to be good for the ANN model during testing, the best model should be chosen by assuming its predictive performance during the testing period. Therefore, the Haar wavelet-based ANN-10 model was considered the best model among all models during the training and testing periods, presented in Table [11](#page-19-0). Moreover, the ANFIS-06 (trap-2) model performed better than the WANN model during the training and testing. Among all models, the MNLR model showed poor performance in daily reference evapotranspiration prediction despite mapping the nonlinear relationship of hydrological processes. The values of performance indices, viz. *R*2 , RMSE, CE and WI, for the best-selected Haar waveletbased ANN model were 0.9995, 0.0236, 0.9995 and 0.9999, respectively, during training 0.9992, 0.0299, 0.9991 and 0.9998, during testing.

During the training and testing phases, radar charts and Taylor diagrams were used to visually assess the performance of the ANN, ANFIS, WANN and MNLR models in monthly ET_0 estimates (Figs. [13](#page-19-1) and [14](#page-20-0)). In training and testing at KVGK stations, the created models' radar charts show how they performed. As can be seen from these graphs, the ANN-10 and ANFIS-06 (trap-2) models outperformed the others during training (Fig. [13](#page-19-1)a). They outperformed all other models during testing (Fig. [13b](#page-19-1)). Based on observed data, Taylor diagrams may highlight the correctness and efficiency of models; they demonstrate

Fig. 13 Radar chart showing the statistical performance of the best selection of ANN-10, WANN-11, ANFIS-06 (trap-2) and MNLR during **a** training and **b** testing periods

two distinct characteristics (*i.e.* correlation coefficient and standard deviation). As shown in Fig. [14a](#page-20-0), b, the four models above were tested and trained at KGVK stations. RMSE, standard deviation and correlation coefficient are shown in a single polar plot on the Taylor diagram. These diagrams demonstrate the better performance of ANFIS-06 (trap-2) than ANN-10, WANN-11 and MNLR for study

Fig. 14 Taylor diagrams of estimated and observed monthly ET_0 values by ANN-10 (6-10-1), WANN-11 (24-11-1), ANFIS-06 (trap-2) and MNLR models for the **a** testing and **b** testing period at GKVK Bengaluru station

stations in the training period (Fig. [14](#page-20-0)a), and ANN-10 performed better ANFIS-06 (trap-2), WANN-11 and MNLR for study stations in the testing period (Fig. [14b](#page-20-0)). The best performance was found for the ANN-10 model, closely followed by the ANFIS-06 (trap-2), WANN-11 and MNLR models for the training period, and the ANN-10 model closely followed by the ANFIS-06 (trap-2), WANN-11 and MNLR models for a testing period at KGVK stations (Fig. [14b](#page-20-0)). Figure [15](#page-20-1) shows the mean bias (MBE) and mean-squared error (MSE) evaluation of the best ANN,

Fig. 15 Mean bias error (MBE) and mean-squared error (MSE) evaluate the best ANN, WANN, ANFIS and MNLR models in testing

WANN, ANFIS and MNLR models in testing. Both parameters show very little diferences among all models. The order of superiority for reference evapotranspiration simulation was observed as ANN, ANFIS, WANN and MNLR models. ANN-10 model was considered superior to other models because wavelet transform unveils the hidden signal (information) of original time series data into sub-components (sub-series). Finally, the ANN model was found to be the most reliable model in ET_0 prediction for the area of GKVK.

In this study, using measured daily weather variables, i.e. T_{min} , T_{max} , RH percentage, U_2 and S_{h} , four machine learning (ML) models were developed and compared for modelling daily reference ET_0 , i.e. the ANN, ANFIS, WANN and MNLR. The models were applied during the dry (a critical time for the growing season) and humid seasons to provide a general view of the feasibility of machine learning for ET_0 modelling. In this study, an approach of applying the Gamma test technique (GT) to weather data not only ensured that the best and suitable variables for modelling ET_0 were accurately selected but also was a successful means of selecting the best input combination. In addition to this fnding, it was found that coupling the ANN with wavelet decomposition helps improve the ML model's performance. Similar to the results of several auteurs, it was found that the inclusion of the two-air temperature, *i.e.* T_{min} , T_{max} , plays a significant role in modelling the ET_0 and improved model predictions.

Although there have been many studies comparing several ML models for ET_0 modelling, the comparisons were conducted in particular, taking into account the combination of various weather variables. Ye et al. [\(2022\)](#page-25-2) proposed a modelling Framework based on the hybridisation of a dynamic evolving neural-fuzzy inference system (DENFIS) and multivariate adaptive regression spline (MARS) with

whale optimisation algorithm (WOA) and bat algorithm (BA). The hybrid models, i.e. MARS-WOA, MARS- BA, DENFIS-WOA and DENFIS-WOA, were found to be accurate, exhibiting an R^2 value of approximately ≈ 0.940 , less than the value obtained in our present study $(R^2 \approx 0.998)$. Similar results occurred over the northeast of the Inner Mongolia Autonomous Region, China, while agreement between measured and predicted ET_0 was much more accurate (Zhang et al. [2022\)](#page-25-3). They showed that the availability of many weather variables is benefcial to the analysis of several scenarios generated under temperature-based, humidity-based and radiation-based models. More precisely, they compared random forest regression (RFR), K-nearest neighbours (KNN), light gradient boosting machine (LGB), ANN, long short-term memory (LSTM) and temporal convolutional neural network (TCN), showing that the biggest R^2 value obtained by all models does not exceed ≈ 0.935 , which are less than the value obtained in our study by the WANN, ANN and ANFIS models $(R^2 \approx 0.998)$.

The fndings by Muhammad et al. ([2022\)](#page-24-26) help to explain the results from this study, suggesting that in high mountains in the central region of Peninsular Malaysia (former Malaya), the gene expression programming (GEP) model was found to be an excellent and powerful tool for evapotranspiration modelling. They obtained an R^2 value of approximately ≈ 0.98 , slightly less than the value obtained in our study. Using the multi-layer perceptron (MLPNN) and radial basis function (RBFNN), Dimitriadou and Nikola-kopoulos ([2022](#page-23-26)) demonstrated that ET_0 was directly linked to T_{mean} , S_h and solar radiation (R_s) in the Peloponnese is a peninsula in Southwestern Greece, suggesting that MLPNN and RBFNN are correctly capturing the variability of ET_0 with an R^2 of approximately ≈ 0.980 nearly equal to the value obtained in our study. In a Modelling study by Wang et al. [\(2022](#page-24-27)), a priori knowledge of fewer weather variables shows that when T_{max} , T_{min} , U_2 and S_h are introduced as input variables to the machine learning, the R^2 value shifts towards higher values, but not for all algorithms. More precisely, by comparing three ML families, i.e. three tree-based models, neural network-based and three multifunction-based models, the comparison was conducted between ten algorithms. It was a statement to say that the generalised regression neural network (GRNN) and the RBFNN models will give excellent R^2 values greater than ≈0.999 and ≈0.997 and RMSE values less than 0.01, which all are better than the values obtained in our study. The fndings by Tejada et al. ([2022\)](#page-24-28) show that ET_0 is related to T_{max} , T_{min} , U_2 and R_s at Region IV-A, Philippines. The support vector machines (SVM) and extreme learning machines (ELM) were a good alternative for estimating the ET_0 with high accuracies for which the R² reached the values of ≈ 0.985 and ≈ 0.999 , respectively.

Using weather variables collected at two stations in Tabriz and Shiraz, Iran, Mehdizadeh et al. [\(2021](#page-24-29)) concluded that the

hybridisation of the ANFIS model using the shuffled frogleaping (SFLA) and invasive weed optimisation (IWO) algorithms has allowed to obtain excellent ET_0 prediction reaching an R² of approximately ≈0.998 and ≈0.999 obtained using the ANFIS-SFLA and the ANFIS-IWO, respectively, which was similar the results obtained in our present study, despite that the same weather variables were included as input variables. From the results by Kadkhodazadeh et al. ([2022](#page-23-27)), it follows that among six ML algorithms, i.e. MARS, M5Tree, RFR and least squares boost (LSBoost), the ET_0 prediction with its input of even standards meteorological data was very appropriate for homogeneous and heterogeneous locations, such as Tabriz, Urmia and Mahabad located in Iran. It is emphasised that excellent \mathbb{R}^2 values were obtained, reaching the value of ≈0.999 in the light of the results obtained in the present study, and this has strong implications for the use of ML for ET_0 estimation. Furthermore, the linear regression ML algorithms, i.e. multiple linear regression (MLR) and polynomial regression (PR) developed by Kim et al. [\(2022](#page-23-28)), have shown poor to moderate predictive accuracy. In this way, the R^2 values do not exceed the values of ≈0.694, which are less than the values obtained in our study. Alternatively, there is a tremendous need for the application of the ensemble ML methods for predicting ET_0 . For example, Liu et al. ([2021\)](#page-24-9) compared RFR and extreme gradient boosting (XGBoost) models for modelling ET_o using data collected across the humid region of China. From the obtained results, it was found that XGBoost was slightly better than the RFR, exhibiting R^2 values of approximately \approx 0.867 and \approx 0.862, respectively, and the combination of T_{max} , T_{min} and R_{s} as inputs guaranteed the best predictive accuracies.

Basically, a large amount of ML models were proposed and successfully applied for modelling ET_0 . A typical difference between the analysed models revealed that all were based on linking weather variables to ET_0 and a learning process with and without hybridisation was adopted. However, one of the most challenging aspects of ML is certainly the use of deep learning for solving regression tasks. For example, Sharma et al. ([2022](#page-24-30)) applied two deep learning models, namely, convolution-long short-term memory (Conv-LSTM) and convolution neural network-LSTM (CNN-LSTM) for modelling ET_{α} . They demonstrated that deep learning models are robust tools for which excellent R^2 values were obtained ($R^2 \approx 0.991$) nearly equal to the value obtained in our study. However, considering the obtained RMSE values (RMSE≈0.019), deep learning was slightly better than the WANN and ANN proposed in our present study. Xing et al. ([2022](#page-25-4)) applied the deep beliefs networks (DBN) and the LSTM deep learning models for modelling ET_0 and reported good predictive accuracies with R^2 exhibiting a value of ≈0.940. Roy et al. ([2022\)](#page-24-31) compared deep learning, i.e. LSTM and BiLSTM, and a suite of ML models, i.e. SVM, MARS, M5Tree, ANFIS, probabilistic linear regression (PLR) and Gaussian process regression (GPR) for modelling ET_0 .

It was found that BiLSTM was more accurate and exhibited excellent predictive accuracies with R^2 nearly equal to the value of ≈ 0.996 .

The potential uncertainties associated with the input meteorological variables used in the models, such as measurement errors or data gaps. The proposed modelling framework does not have any limitation such as data requirements, computational resources or model calibration. It was proposed to enhance the computation performance.

Suggested future works

This study was conducted at a single station to assess the accuracy of MNLR, ANN, ANFIS and WANN techniques. To enable a more comprehensive comparison of these models, future research should involve multiple locations simultaneously. Additional investigation could be directed towards examining the efficacy of alternative soft computing methodologies or machine learning algorithms in forecasting daily reference evapotranspiration (ET_0) within tropical savanna ecosystems, extending beyond the scope of the models scrutinised in this inquiry. Future research should explore how including more meteorological variables or trying diferent combinations of input data afects the accuracy and effectiveness of models predicting ET_0 . By doing so, researchers can pinpoint which variables have the most signifcant impact on the predictions and consequently enhance the overall predictive capabilities of the models. It would be benefcial to conduct feld validation experiments to assess the practical applicability and reliability of the proposed modelling framework in real-world scenarios. This can help validate the model's performance and provide insights into potential limitations or areas for improvement.

Additionally, the investigation could delve into incorporating remote sensing data or satellite imagery to augment the precision and spatial resolution of ET_0 predictions, especially in areas where ground-based meteorological data is scarce. Furthermore, forthcoming research endeavours could explore the viability of ensemble modelling methodologies, amalgamating various models or techniques to enhance both the accuracy and resilience of ET_0 predictions within tropical savanna settings.

Conclusions

Reference evapotranspiration (ET_0) is an important component of the hydrological cycle, and it is a critical step in the quantifcation of the crop water requirement. In the present study, various meteorological variables were used for the estimation of ET_0 using CROPWAT 8.0 software based on the Penman–Monteith equation. The estimated reference evapotranspiration values were considered as observed values. Based on the best input combination identifed through the gamma test, diferent artifcial intelligence (ANN, ANFIS, WANN) and nonlinear regression (MNLR) techniques were applied to calibrate various ET_0 models using MATLAB software in the present study. Statistical and hydrological performance indices, such as R^2 , RMSE, WI and CE, were evaluated to determine the most accurate model for the prediction of ET_0 . Finally, the concept of sensitive analysis was utilised for the best-developed model to see the efect of the most sensitive parameter on model performance.

According to the obtained results, some conclusions can be highlighted as follows:

- (i) Based on performance criteria, the ANN-10 (6-10-1) model was found to be better than the other ANN models.
- (ii) The wavelet-coupled ANN-11 (24-11-1) model was superior to the other WANN models for the study area.
- (iii) ANFIS-06 model with trapezoidal type input MFs performed better than the other input MFs based on ANFIS models.
- (iv) Based on the overall performance of ANN, ANFIS, WANN and MNLR models, the ANN-10 was found to be the best model for the prediction of daily ET_0 of the study area.
- (v) Solar radiation was found to be the most sensitive variable. In contrast, actual vapour pressure was less sensitive based on sensitivity analysis.

To enhance the accuracy of predictive models, the detailed explanation of the specifc algorithms or mathematical principles employed in the neural network models. This research demonstrates the application and performance evaluation of diferent soft computing models (ANN, WANN, ANFIS, MNLR) for ET_0 prediction, and also delving into the underlying theoretical foundations of these models by assessing their accuracy and performance as well.

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Compliance with ethical standards

Conflict of interest The author declare that they have no confict of interest.

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