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Quantitative prediction model of water inrush quantities from coal mine roofs based on multi‑factor analysis

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Abstract

Accurately and efectively predicting the quantity of water inrush from the roof of coal mines is important for the safety of coal mine production. There is a complex and nonlinear relationship between the water inrush quantities from the coal roof and its infuencing factors. To improve the precision and reliability in predicting the water inrush quantity, this paper establishes a water inrush quantity quantitative prediction model for coal seam roof aquifers based on the partial least squares regression (PLSR) and radial basis function (RBF) neural network coupling methods. First, the infuencing factors of the coal roof water inrush quantity in the study area are determined, and then PLSR is used to reduce the dimensions of the original data by extracting the principal components with the best interpretation function for the system. The principal components are then used as input to the RBF neural network to model and predict the coal roof water inrush quantity, which efectively overcomes the multicollinearity problem between variables, optimizes the network structure, and improves the learning efficiency and robustness of the network. Finally, the reliability of the method is verified through simulation testing and comparison with other prediction methods. The results show that: compared with the PLSR model, the multiple linear regression (MLR) model, the RBF neural network model, the SVM model, and the FA-RBF neural network model, the ftting and prediction capabilities of the coal roof water inrush quantity prediction model based on the PLSR and the RBF neural network are better than the other models. The average absolute error of fitting of this model is $6.07E-4 \text{ m}^3/\text{h}$, and the average relative error of ftting is 6.07E-3%; the average absolute error and the average relative error of prediction of this model for new samples are 1.9967 m³/h and 9.8730% respectively. The model combines the unique advantages of the PLSR and the RBF neural network and can deal with the correlation and nonlinear problems between variables, which is very practicable and provides a new way for predicting water inrush quantities from coal roofs.

Keywords Coal seam roof · Water inrush quantity · Nonlinear · Multicollinearity · PLSR · RBF neural network

Introduction

As China's main energy source, coal plays a crucial role in energy structure (Li et al. [2018](#page-13-0); Zeng et al. [2018](#page-14-0)). In recent years, due to the application of comprehensive mechanized coal mining technology, as well as an increase in the scale of mining, mining depth, and mining intensity, the problem

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² School of Earth and Environment, Anhui University of Science and Technology, Huainan 232001, China of water inrush from the roof of the coal mines has become ever more serious (LaMoreaux et al. [2014;](#page-13-1) Xu et al. [2018](#page-14-1); Yin et al. [2018,](#page-14-2) [2019](#page-14-3)). Roof water inrush accidents caused a large number of casualties and huge economic losses, which seriously afected and restricted safe production in the coal industry (Shi et al. [2017;](#page-13-2) Zhang and Yang [2018](#page-14-4); Ju and Hu [2021](#page-13-3)). Efective water inrush prediction is an important tool to curb frequent water inrush accidents in coal mines by guiding the mine in taking preventive measures to ensure safe production and the safety of employees. It can also be used to accurately predict the water inrush quantity once a water inrush accident occurs in a mine (Oin et al. [2013](#page-13-4)). Fast and accurate methods for predicting the water inrush quantities in coal mines are therefore very important to mine safety.

The occurrence of water inrush from the roof and floor of the coal seam is the result of the joint action of multiple factors (Liu et al. [2021;](#page-13-5) Zhang and Yang [2021\)](#page-14-5), and the factors that affect the water inrush quantity are complex, non-linear, and uncertain. The quantitative prediction of the water inrush quantities in mines is, therefore, a very complex and non-linear dynamic problem and there are certain dif-ficulties in prediction (Xiao et al. [2012;](#page-14-6) Qin et al. [2013](#page-13-4); Liu and Li [2019](#page-13-6)). At present, the prediction and analysis of mine water inrush are mostly limited to qualitative research, and fnally, get the grade division of the water inrush quantity in mines. Most of these studies analyze water inrush from the coal foor, while there is limited quantitative research on the actual water inrush quantities from coal roofs (Cao and Zhao [2011\)](#page-12-0). The methods for predicting water inrush from mine foor mainly include multiple linear regression (Gong et al. [2012\)](#page-13-7), support vector machine (SVM) (Gao and Wang [2012](#page-13-8); Ma et al. [2018](#page-13-9)), distance discriminant analysis theory (Chen et al. [2009\)](#page-13-10), multiple information fusion methods (Han et al. [2009](#page-13-11)), and back propagation (BP) neural network prediction (Yang et al. [2013](#page-14-7)). Although the above methods have achieved good prediction results, due to the complexity and uncertainty of the mine water inrush problem, as well as the nonlinear and fuzzy relationship between the water inrush infuencing factors and the water inrush quantity, these methods have certain limitations (Jiang and Liang [2005](#page-13-12); Cheng et al. [2014](#page-13-13)). For example, the multiple linear regression model sometimes does not provide a satisfactory ft, resulting in low prediction accuracy (Chen et al. [2005](#page-12-1)). The blind selection of model parameters in the training process is problematic when the SVM model is used to predict the water inrush quantity alone (Gao and Wang [2012\)](#page-13-8), and compared with neural network algorithms, there are no special advantages in its prediction accuracy (Wei et al. [2015](#page-14-8)). BP neural networks require more stringent modeling conditions, it is difficult to determine the network structure, it has parameters that must be adjusted, has a slow learning speed, and easily fall into local minimums and fail to obtain a globally optimal solution (Wu et al. [2017](#page-14-9)). The radial basis function (RBF) neural network is a typical forward modeling neural network (Liang et al. [2020](#page-13-14)). Because it has the characteristics of the only best approximation, no local minimum problem, simple structure, convenient training, and fast convergence speed of the learning process, it overcomes the above shortcomings of a BP network. It can approximate any nonlinear continuous function with high precision, and can better reveal the actual structure of a complex nonlinear system (Chen et al. [2010;](#page-13-15) Dai et al. [2014;](#page-13-16) Wu et al. [2017](#page-14-9)). It is therefore a suitable tool to analyze and predict water inrush quantities from the roof and foor of coal seams. In addition, the mine roof water inrush is afected by many factors such as geological structural conditions, hydrogeo-logical conditions, and mining activities (Liu et al. [2021](#page-13-5)),

and it is therefore almost impossible to comprehensively and accurately consider the impact of all the diferent factors. The multi-variable model proposed for some of the main infuencing factors will inevitably be afected by overlapping information (Liu and Liang [2011\)](#page-13-17) because there are often multicollinearity problems among the various factors, which will exaggerate the position of some factors in the system analysis. This will result in a less objective analysis, which is not conducive to the correct judgment of the model, and will affect the accuracy of prediction results. At the same time, due to the high-dimensional complexity brought about by multiple factors, the structure of the prediction model will be very large and the calculation process will be very complicated. To solve these problems, previous studies have introduced principal component analysis (PCA) and factor analysis (FA) methods with strong data compression capabilities (Liu and Liang [2011;](#page-13-17) Wen et al. [2017\)](#page-14-10), but PCA and FA do not consider dependent variables at all during its component extraction, and only consider independent variables. Although the components obtained in this way have strong generalizability for the independent variable system, they lack the explanatory ability for the dependent variable. PLSR is superior to PCA and FA in this respect, in that it considers the infuence of independent variables and dependent variables during principal component extraction. This method integrates the advantages of multiple linear regression, principal component analysis and canonical correlation analysis (Gong [2021\)](#page-13-18). The best interpretation function for the system is extracted by decomposing and fltering data and information from the variable system to reduce the dimensions of the multidimensional data space, eliminate the noise interference in the system, and efectively solve the modeling problems such as serious multicollinearity between independent variables, the availability of a small number of samples, and model instability (Yan et al. [2021](#page-14-11)).

Given the above, to accurately and quantitatively predict the water inrush quantity of coal seam roof aquifer, this paper proposes a water inrush quantity quantitative prediction model based on the coupling of the PLSR and the RBF neural networks, explaining their respective advantages, aiming to improve the model prediction speed and accuracy while improving the generalizability of the model. Firstly, the infuencing factors of the water inrush quantity from the coal seam roof were analyzed and selected, and the original data was reduced by PLSR to extract several components which can best describe the system. The extracted components were then used as input to the RBF neural network to model and predict water inrush quantities from the coal seam roof. Finally, the reliability of the method was verifed by the simulation test and a comparison with various other prediction methods.

Materials and methods

Overview of the study area

The Xuzhuang Coal Mine is located close to Datun Town, Pei County, Jiangsu Province, and Xiping Town, Weis-han County, Shandong Province, China (see Fig. [1](#page-2-0)a). The mining area is about 10.0 km long from east to west and 3.84 km wide from north to south, with an area of about 38.4 km^2 . The coal-bearing strata in the mining area include the Taiyuan Formation, the Shanxi Formation, and the Xiashihezi Formation, which contains more than 20 layers of coal that has an average total thickness of about 13.43 m. There are four minable coal seams, of which No.7 coal seam with an average thickness of 4.87 m (variable between 1.13 m \sim 7.97 m) is the main coal seam in the Xuzhuang Coal Mine. At present, the No. 7 and No. 8 coal seams of the Shanxi Formation have been mined at the − 400 m level. In the eastern part, mining has begun at the − 750 m level, while the west is still being developed. The mine area is located in the centralsouthern part of the Tengpei synclinorium. Most of the area is a monoclinic structure with a strike 45°N ~ 70°E and a northwestern slope, with a dip angle of $10^{\circ} \sim 36^{\circ}$. According to the actual measurement data revealed by

exploration and mining, the fault structure in the mining area is relatively developed. There are more than 400 faults with a drop of ≥ 2 m, of which there are 209 faults with a drop of \geq 5 m, 149 faults with a drop of 5 m ~ 20 m, and 60 faults with a drop of \geq 20 m. Due to the influence of multiple tectonic movements, many folds have developed in the central and western parts of the mining area. The eastern part of the mining area is not well developed, with only a few obvious wide and gentle folds, small folds, and fault drag folds. The fold types are medium. The structural outline of the Xuzhuang Coal Mine is shown in Fig. [1b](#page-2-0). From top to bottom, the main aquifers in the mining area include the pore aquifer of the bottom sand layer of the Quaternary system, the bottom conglomerate aquifer of the Lower Cretaceous-Upper Jurassic system, the bottom sandstone aquifer of the Lower Shihezi Formation of the lower Permian system, the sandstone aquifer of the coal seam roof of the Shanxi Formation of the lower Permian system (see Fig. [1c](#page-2-0)), the limestone of the Taiyuan Formation of the upper Carboniferous system and the karst limestone aquifer of the thick limestone of the Ordovician system. Among them, the No.7 coal seam roof sandstone aquifer is the direct source of water for the No.7 coal seam, which greatly impacts the safe mining of the No.7 coal seam. The comprehensive histogram of the roof of the No.7 coal seam is shown in Fig. [1](#page-2-0)d. Since the mine was

Fig. 1 The location of the Xuzhuang Coal Mine, the outline of the geological structure, the profle of the exploration line and the comprehensive histogram of the roof of the No. 7 coal seam

put into operation, many roof water inrush accidents have occurred, and the high frequency of water inrushes into the No.7 coal seam roof has seriously threatened the safe production of the mine. It is very important to accurately predict the water inrush quantities of the No. 7 coal seam roof sandstone aquifer to ensure safe mining.

Data source and index selection

Water inrush from the coal roof of a mine is a very complex systemic problem infuenced by many factors, including hydrogeological conditions (such as aquifer thickness), geological conditions (such as faults, fold structures, and the development of cracks in the roof overlying rock), mining conditions (such as mining depth) and other aspects. Of them, the geological structure is the main factor controlling roof water inrush (Cheng et al. [2021](#page-13-19)). The geological fault structure not only destroys the integrity of the roof, but also reduces the strength of the rock mass, weakening the resistance of the roof aquiclude to deformation, and leading to the formation of fault fracture zones. The displacement of the upper and lower walls of the fault zone shortens the distance between the aquifer and the coal seam, which causes part of the aquifuge to lose its water resistance, causing water inrush accidents (Das et al. [2018;](#page-13-20) Wang et al. [2021\)](#page-14-12). In the axial part of the fold (syncline or anticline), the stratum is subject to strong tensile or extrusion pressures, and the fractures are often quite developed, which not only means good aquifer storativity but also serves as pathways for water transport. The existence of an aquifer above the coal roof is a prerequisite for coal roof water inrush (Zhang and Yang [2018](#page-14-4)). A thick aquifer is usually water-rich and can store and transport large volumes of groundwater. The thicker the aquifer, the more water it can store leading to greater water inrush quantities once the coal roof is breached (Zeng et al. [2018;](#page-14-0) Zhang et al. [2021a\)](#page-14-13). The sandstone-mudstone ratio mainly used to characterize the sedimentary facies of regional geological strata, and describes the relative content of sandstone and mudstone in the strata. If the sandstone content of the strata is large, the storativity and permeability of the aquifer are better, and the thinner the water barrier within the coal roof, the greater the risk of water inrush (Zeng et al. [2018\)](#page-14-0). The drilling core recovery rate of the roof is an index refecting the degree of rock fragmentation and the degree of rock fracture intersections (Zhang et al. [2021a\)](#page-14-13). The lower the drilling core recovery rate of the roof, the poorer the rock integrity of the roof (Zeng et al. [2018](#page-14-0)). Coupled with the more sandstone fractures and larger storativity, this leads to greater water inrush quantities upon breaching of the roof (Wu et al. [2016](#page-14-14); Ji [2019\)](#page-13-21). Drilling fuid consumption is an important parameter refecting the permeability of the rock formation (Liu and Li [2019\)](#page-13-6). When the borehole passes through the aquifer, the drilling fuid will be consumed to a certain extent. If the drilling fuid consumption is large, it indicates that the degree of connectivity between fractures in the rock stratum is better, the permeability coefficient is larger, and the aquifer contains large volumes of water (Wu et al. [2016;](#page-14-14) Zeng et al. [2018\)](#page-14-0). Mining depth plays an important role in the original stress state of the coal seam and its roof and foor strata. Within a certain range, mining depth has a great infuence on the change in mine pressure and also has a certain infuence on the development height of water flowing fractured zone (Hu et al. [2012](#page-13-22); Gao et al. [2018](#page-13-23)), which affects the occurrence of water inrush accidents.

Taking into account the adaptability, accuracy, conciseness, and desirability of the factor indicators, the drilling core recovery rate of the roof, the drilling fuid consumption, the aquifer thickness, the sandstone-mudstone ratio, the fault fractal dimension, the fold plane deformation coefficient, the fault strength, and the mining depth were selected as the main factors afecting the water inrush quantity from the roof aquifer of the No. 7 coal seam in Xuzhuang Coal Mine. They are represented by $X_1, X_2, X_3, X_4, X_5, X_6, X_7, X_8$, respectively. Based on the actual water inrush data of the mine, 24 groups of typical water inrush cases were selected to predict and analyze the water inrush quantity from the roof aquifer of No. 7 coal seam, and the training samples (No. 1–21) and simulation samples (No. 22–24) are randomly determined according to the principle of 7:1, as shown in Table [1](#page-4-0)

Research methods

Partial least squares regression analysis

The Partial least squares regression method is a widely applied multivariate statistical analysis method, similar to principal component analysis, canonical correlation analysis, and linear regression analysis. It can efectively solve the problem of multiple collinear variables (Gong [2021](#page-13-18)). PLSR adopts the method of component extraction but difers from the traditional PCA. The PLSR method reorganizes information instead of removing variables. When extracting variables, the linear relationship between the dependent variable and the independent variable is considered, the comprehensive variable with the strongest explanatory effect on the independent variable and the dependent variable is selected, and noise interference is eliminated. Therefore, it not only ensures the elimination of the multicollinearity problem but also ensures the stability of the model (Yan et al. [2021\)](#page-14-11). The principle is as follows:

Suppose there are *q* dependent variables $\{y_1, y_2, \dots, y_q\}$ and *p* independent variables $\{x_1, x_2, \dots, x_p\}$. To study the statistical relationship between the dependent variable and the independent variable, *n* sample points are observed,

Table 1 Original data of water inrush cases in the study area

which constitute the data tables $X = \{x_1, x_2, \dots, x_p\}_{n \times p}$ and $Y = \{y_1, y_2, \dots, y_q\}_{n \times q}$ of independent variables and dependent variables. PLSR extracts components t_1 and u_1 from X and Y respectively. To meet the needs of regression analysis, t_1 and u_1 should carry as much of the variation information in their respective data tables as possible and the correlation between t_1 and u_1 should be maximized. After the first component is extracted, PLSR implements the regression of *X* to t_1 and the regression of *Y* to u_1 respectively. If the regression equation has reached a satisfactory accuracy, the algorithm terminates; otherwise, the residual information after *X* that is explained by t_1 and the residual information after *Y* that is explained by u_1 will be used for the second round of component extraction. This process is repeated until a satisfactory accuracy is achieved.

If *h* components t_1, t_2, \dots, t_h are finally extracted from *X*, PLSR will perform the regression of $y_k(k = 1, 2, \dots, q)$ on t_1, t_2, \dots, t_h , and then express it as the regression equation of y_k on the original independent variable x_1, x_2, \dots, x_p (Shi et al. [2013;](#page-13-24) Wang et al. [2014](#page-14-15)). Based on the number of dependent variables, partial least squares regression analysis can be divided into multiple dependent variable partial least squares regression analysis and single dependent

variable partial least squares regression analysis. In this study, only partial least squares regression analysis of single dependent variables is performed, and the specifc modeling steps are as follows (Wang et al. [2014;](#page-14-15) Gong [2021\)](#page-13-18):

(1) To eliminate the infuence of diferent dimensions of input parameters on the calculation results, the original data are standardized according to formula [\(1](#page-4-1)), and the standardized dependent variable matrix F_0 and independent variable matrix E_0 are obtained, which are recorded as, $F_0 = Y, E_0 = X$ respectively.

$$
\hat{z}_{ij} = \frac{z_{ij} - \bar{z}_j}{S_j} (i = 1, 2, \cdots, n; j = 1, 2, \cdots, p)
$$
 (1)

where z_{ii} is the actual value of the sample; \overline{z} is the mean value of the sample z_j ; S_j is the standard deviation of the sample z_j ; \hat{z} is the standardized sample value.

(2) Extraction of the first component t_1

It is known that F_0 and E_0 can be used to extract the first component t_1 , $t_1 = E_0 W_1$, where W_1 is the first axis of E_0 , which is the combination coefficient and $||W_1|| = 1$. At the same time, the first component u_1 is extracted from F_0 to meet $u_1 = F_0 C_1$, where C_1 is the first axis of F_0 and $||C_1|| = 1$.

Here it is required that t_1 and u_1 should better express the data variation information in X and Y respectively, and t_1 can better explain u_1 . In the principal component analysis and canonical correlation analysis, these conditions can be satisfied by taking $W_1 = E_0^T F_0 / ||E_0^T F_0||$. After W_1 is obtained, the component t_1 can be obtained, and the regression equations of E_0 and F_0 to t_1 are respectively calculated as:

$$
E_0 = t_1 p_1^T + E_1, F_0 = t_1 r_1 + F_1
$$
\n(2)

where $p_1 = E_0^T t_1 / ||t_1||^2$, vector $r_1 = F_0^T / ||t_1||^2$, and E_1 and F_1
are the residual matrix of the regression equation are the residual matrix of the regression equation.

(3) Extraction of the second component t_2

Here E_1 is substituted for E_0 and F_1 for F_0 . The above method is used to find the second axis W_2 and the second component *t*₂, then $W_2 = E_1^T F_1 / ||E_1^T F_1||$, $t_2 = E_1 W_1$. Similarly, E_1 and F_1 are regressed to t_2 and $E_1 = t_2 p_2^T + E_2, F_1 = t_2 r_2 + F_2$ are obtained.

The same applies to the extraction of the *hth* component. The number can be identifed by the principle of cross-validity, and *h* is less than the rank of *X*.

(4) Cross-validity principle

The principle of cross validity is used to determine the number of extracted components *h* for modeling. Recorded as the original data as y_i ($i = 1, 2, ..., n$), \hat{y}_{hi} is the fitting value of the *ith* sample after modeling using all the samples and extracting the component $t₁$, then the sum of squared fitting errors of \hat{y}_{hi} is $SS_h = \sum_{i=1}^n (y_i - \hat{y}_{hi})^2$. If $\hat{y}_{h(-i)}$ is the fitting value of y_i calculated after deleting the sample point *i* during modeling and extracting the component t_1 after regression modeling, then the sum of squared ftting errors y_i is $PRESS_h = \sum_{i=1}^n (y_i - \hat{y}_{h(-i)})^2$.

If the error of the regression equation is large, *PRESSh* will be very sensitive to changes in the sample points, and its value will increase. Therefore, when *PRESS_h* reaches the minimum value, the corresponding *h* is the number of components. Generally, *PRESS_h* is greater than SS_h , and SS_h is less than *SSh*−1. Therefore, when extracting components, it is always hoped that the ratio $PRESS_h/SS_h$ is as small as possible. Generally, the limit value can be set to 0.05, that is, when $PRESS_h/SS_{h-1}$ ≤ $(1 - 0.05)^2 = 0.95^2$, increasing the component t_h is beneficial and improves the accuracy of the model. The cross-validity of the component t_h is defined as $Q_h^2 = 1 - PRESS_h/SS_{h-1}$ so that the cross-validity test is performed before the calculation of each step of PLSR modeling. If Q_h^2 < (1 − 0.95²) = 0.0975 in the *hth* step, the model has reached the accuracy requirement and the component extraction can be stopped. If $Q_h^2 \ge 0.0975$, it means that the marginal contribution of the component t_h extracted in step h is signifcant, and the calculation of the component extracted in step $h + 1$ should be continued (Gong [2021\)](#page-13-18).

(5) Establish a partial least squares regression model

Based on the above analysis, a partial least squares regression model can be obtained, as shown in formula [\(3](#page-5-0)).

$$
Y = XWR + F_2 \tag{3}
$$

Where $W = [W_1, W_2, \cdots, W_h], R = [r_1, r_2, \cdots, r_h], F_2$ is the residual matrix.

Radial basis function neural network analysis

The Radial basis function neural network is an efficient feedforward neural network designed by using a multivariate interpolation radial basis function. It transforms the lowdimensional input vector into the high-dimensional space so that the linear inseparability in the low-dimensional space becomes linearly separable in the high-dimensional space. Therefore, it can approximate various nonlinear continuous functions with high precision and has the best approximation performance and global optimal characteristics compared to other forward networks (Kou and Zhang [2015](#page-13-25); Su et al. [2020](#page-13-26); Zhang et al. [2020;](#page-14-16) Tao et al. [2021](#page-14-17)). There is also no need for the data to conform to the normal distribution characteristics, and there are few prior knowledge requirements for the modeling of an object. Generally, it is not necessary to have knowledge about the structure, parameters, and dynamic characteristics of the object for it to be modeled in advance. Only input and output data of the object must be provided, and the input and output can be fully consistent through the self-learning function of the network itself, which avoids the complex algorithm to complete the calculation and prediction accurately (Tong et al. [2013;](#page-13-27) Zheng et al. [2013](#page-14-18)). This makes RBF suitable for the prediction of water inrush quantities from coal seam roofs.

The RBF neural network consists of three layers, and its network topology is shown in Fig. [2.](#page-6-0) The frst layer is the input layer, which is composed of input nodes connected to the external environment and only transmits the input signal to the second linear layer, which is hidden. The second layer is composed of radial basis functions (such as Gaussian functions) to complete the nonlinear change from the input space to the hidden layer. In most applications, the hidden layer space is high-dimensional, and the entire RBF neural network has only one hidden layer. The third layer is the

Fig. 2 Topological structure diagram of RBF neural network

output layer and the nodes of the output layer are usually simple linear functions that respond to excitation patterns or signals added to the entire network (Peng et al. [2020](#page-13-28); Montoya-Chairez et al. [2021](#page-13-29); Yang et al. [2021](#page-14-19)).

The activation function of the hidden layer node in the RBF neural network is a radial basis function, and the distance between the input vector and the node center is used as an independent variable, and the input vector is directly mapped to the hidden layer. The action function of the output layer node is linear, and the output information of the hidden layer node is linearly weighted and then output is given. Because the Gaussian function has the advantages of rotational symmetry, good practicability, simple form, and existing any order derivative, and its local response characteristics are very consistent with the RBF neural network, the Gaussian function is often used as the basis function of the RBF neural network. The general expression of the Gaussian function is shown in formula ([4\)](#page-6-1) (Peng et al. [2020](#page-13-28)).

$$
f(x_i - c_i) = e^{-\frac{1}{2\sigma^2} ||x_i - c_i||}
$$
\n(4)

where ‖∗‖ is the European paradigm and *𝜎* is the variance of Gaussian function.

When the number of neurons in the hidden layer is large enough, it can approximate any n-element continuous function, and when the network is fully trained, a highly accurate ftting result can be obtained (Zhang et al. [2021b](#page-14-20)). During RBF neural network training, it is necessary to fnd the center vector and standardization constant of the Gaussian function according to the location distribution of the data. Finally, after the weight learning stage, the recursive least squares method is used to obtain the weight value matrix of the output layer after the hidden layer parameters are determined. The output function is shown in formula (5) (5) (Guan et al. [2021](#page-13-30)).

$$
Y = \sum_{i=1}^{m} \varepsilon_i f(x_i - c_i)
$$
\n(5)

where *Y* is the output variable; x_i is the input variable; c_i is the center of the Gaussian function; *m* is the number of variables; $f(x_i - c_i)$ is the basis function; ϵ_i is the weight from the hidden layer node to the output layer.

Partial least squares regression‑ radial basis function neural network algorithm

Considering the relationship between multiple infuencing factors, adopting appropriate forecasting methods is important for optimizing forecasting accuracy and operational efficiency. Based on the PLSR-RBF neural network coupling method, a data fusion model that integrates the PLSR and RBF neural networks are constructed to address the fact that the original data has many dimensions and is difficult to handle simultaneously. Firstly, PLSR is used to reduce the dimensionality of the original data. By refning and condensing the useful information in the original data, several components that best describe the system, are extracted. These components not only contain most of the useful information but also eliminate the noise and useless information in the original data. The extracted components are then used as the input data of the RBF neural network to establish a suitable neural network structure through learning and training and calculate the predicted result value.

PLSR reduces the dimensionality of the original data, eliminates the infuence of multicollinearity between diferent factors, reduces the amount of data input into the RBF neural network, and also optimizes the structure of the determined neural network to ensure faster convergence speed, which increases the operability of the model simulation. The flow chart of the prediction model based on the PLSR-RBF neural network coupling method is shown in Fig. [3](#page-7-0).

Results and analysis

Correlation analysis

Selected water inrush data of 21 sets of training samples were used in the Origin 2021 software to analyze the correlation of the eight main control factors that affect the water inrush quantity, and draw the correlation heat map of the main controlling factors, as shown in Fig. [4](#page-7-1). It can be seen from Fig. [3](#page-7-0) that the Pearson correlation coefficients between the variables are not equal to 0, indicating that the variables have diferent degrees of correlation. For example, the correlations between X_1 and X_7 , X_8 , between X_3 and X_4 , between X_7 and X_4 , between X_6 and X_5 , and between X_7 and X_8 are all

Fig. 3 Flow chart of establishing PLSR-RBF neural network coupling model

Fig. 4 Correlation heat map between main controlling factors

greater than 0.50. Among them, the maximum correlation coefficient between X_3 and X_4 is 0.93, indicating that there is a certain multicollinearity relationship between these variables, and the multicollinearity problem between independent variables may lead to instability of the prediction model (Yan et al. [2021](#page-14-11)). Therefore, to eliminate the mutual infuence between the indicators, PLSR was used to eliminate the linear correlation between the variables.

Extracting components using the PLSR method

After the original data of 21 sets of training samples were standardized according to formula [\(1](#page-4-1)), MATLAB software was used to carry out PLSR analysis on the calculation model $Y = f(X_1, X_2, X_3, X_4, X_5, X_6, X_7, X_8)$. Judging by the principle of cross-validity, when the two components are extracted, the accuracy requirements have been met at this time, that is, the two components t_1 and t_2 can be extracted. According to the aforementioned PLSR principle, t_1 and t_2 are orthogonal to each other, which eliminates the correlation or multicollinearity between the original data, and reduces the dimensionality of the independent variable from eight to two. At the same time, these two components also contain the information of the original data to the maximum extent. The expressions of the two components of t_1 and t_2 are shown in formula (6) .

$$
\begin{bmatrix} t_1 \\ t_2 \end{bmatrix} = \begin{bmatrix} -0.4628 & 0.0206 \\ -0.3706 & -0.6032 \\ -0.3956 & -0.0229 \\ -0.3481 & 0.2726 \\ 0.3121 & 0.4729 \\ 0.4526 & 0.3812 \\ -0.0631 & 0.3980 \\ -0.2541 & 0.3755 \end{bmatrix} \begin{bmatrix} \hat{X}_2 \\ \hat{X}_2 \\ \hat{X}_3 \\ \hat{X}_4 \\ \hat{X}_5 \\ \hat{X}_6 \\ \hat{X}_8 \end{bmatrix}
$$
 (6)

where $\hat{X}_1, \hat{X}_2, \hat{X}_3, \hat{X}_4, \hat{X}_5, \hat{X}_6, \hat{X}_7, \hat{X}_8$ are the standardized values of $X_1, X_2, X_3, X_4, X_5, X_6, X_7, X_8$ respectively.

PLSR is introduced in this study because the independent variables extracted by PLSR are those that best correlate with dependent variable *Y*. PLSR is also more accurate and stable than other principal component analysis methods when processing multicollinear, high redundancy, and multinoise data. Therefore, PLSR is the frst choice in dimension reduction (Chen et al. [2015\)](#page-12-2). In this study, two independent variable components were extracted from eight factors that afect the water inrush quantity through PLSR analysis, and these two-component inputs were used to replace eight independent variable inputs in the subsequent RBF neural network model to achieve the optimized network.

Establishment of PLS‑RBF neural network prediction model

Determine the network and training

The two components t_1 and t_2 extracted by PLSR were used as the input of the RBF neural network, expressed by the vector $T = \{t_1, t_2\}$, \hat{Y} (standardized value of *Y*) as the output. An RBF neural network with two input neurons and one output neuron was established and the network was trained by using 21 groups of training samples. The radial basis function network is designed with *newrb* function by using MATLAB. When it is used as a function approximation, the hidden layer

Fig. 5 Trend of mean square error with the increase of the number of neurons

neurons of the radial basis function network can automatically be increased until the requirement of mean square error is reached (Chen et al. [2010](#page-13-15)). The format is shown in Eq. [\(7](#page-8-0)).

net = *newrb*(*input*, *output*, *GOAL*, *SPREAD*, *MN*, *DF*) (7)

where *net* is the radial basis function network object; *newrb* is the radial basis function; *input* is the network input sample vector; *output* is the target vector; *GOAL* is the mean square error; *SPREAD* is the radial basis function distribution density; *MN* is the maximum number of neurons; and *DF* is the display frequency of the training process.

In this network training, *GOAL* is set to 0; *MN* is set to 30;*DF* is set to 2. After continuous experiments, when *SPREAD* is 0.20, the RBF neural network has the smallest error and the best approximation efect. The obtained RBF network training error curve is shown in Fig. [5.](#page-8-1) The mean square error of the target setting is 0, and the mean square error of actual network training is 8.03388e-33, and it is considered that the network error has reached the ideal requirements. At this time, after neural network training and testing, the predicted values of 21 groups of training samples are obtained. After de-standardization, the comparison between the measured values and the predicted values is made, as shown in Fig. [6](#page-8-2). It can be seen from Fig. [6](#page-8-2) that the predicted values of water inrush in the 21 groups of training sample data are very close to the actual values, and the errors between them are very small. The average relative error of the training set sample is 6.07E-3%, and the correlation coefficient of the linear fitting line between them is 1, which indicates that the ftting accuracy of the water inrush quantity prediction model based on the PLSR-RBF neural network is very high.

Fig. 6 Comparison between the predicted value and the actual value of the training sample

Simulation test

To verify the prediction ability of the water inrush quantity prediction model of coal seam roof aquifer based on PLS and RBF neural network for new samples, the reserved three groups of test sample data were processed according to the principle of standardized processing of training sample data, and then substituted the standardized data into formula ([6\)](#page-7-2) to obtain two PLSR components $\{t_1, t_2\}$ of each test sample, which were substituted into the trained PLSR-RBF neural network model for simulation prediction. Finally, the network output value of each test sample was de-standardized to obtain the water inrush quantity prediction value of the test sample. The results are shown in Table [2](#page-9-0). It can be seen from Table [2](#page-9-0) that the relative errors between the simulation sample data prediction results and the actual values are small, and the average relative error is 9.8730%, which is less than 10%, indicating that the model has a good prediction efect for new sample inputs.

Comparison among diferent prediction models

Comparison with other models' ftting ability

To further verify the model fitting accuracy of the water inrush quantity prediction model of coal seam roof aquifer based on the coupled PLS and RBF neural networks, based on 21 groups of training samples data, the multiple linear regression(MLR) model, the PLSR prediction model, the RBF neural network prediction model, the SVM prediction model and the FA-RBF neural network model were developed, and their model fitting results were compared with that of the PLS-RBF neural network prediction model. Among them, SVM is a machine learning method based on statistical learning theory. It realizes the minimization of empirical risk and confidence range, so as to obtain good statistical laws and generalization ability in the case of a small number of samples. For nonlinear mapping problems, it can be mapped to a high-dimensional feature space through a kernel function, and linear regression is performed on this nonlinear relationship in the high-dimensional feature space (Roushangar and Koosheh [2015](#page-13-31); Dhiman et al. [2019](#page-13-32)). Because

Table 2 Prediction results of simulation samples	Number of simulation samples	The actual value (m^3/h)	The predicted Absolute value (m^3/h)	error (m^3/h)		Relative error $\%$ Average relative error $\%$
	22	15.0000	17.1695	2.1695	14.4633	9.8730
	23	20,0000	19.2234	0.7766	3.8832	
	24	27.0000	23.9561	3.0439	11.2736	

Fig. 7 Comparison of ftting results of the diferent models on training samples

Table 3 Comparison of ftting efects of the diferent models

on training samples

SVM has unique advantages in solving problems such as small samples, nonlinear and high-dimensional data analysis, they have been widely used in various prediction problems in many fields (Zhao and Wu [2018](#page-14-21)) and some scholars have used this method to predict the water inrush from coal seam floor (Qin et al. [2013;](#page-13-4) Ma et al. [2018\)](#page-13-9). The results of various models are shown in Fig. [7](#page-9-1). When evaluating the fitting of the prediction model, this study mainly considers the three indicators—the coefficient of determination (R^2) , the average absolute error, and the average relative error, as shown in Table [3.](#page-10-0) The absolute error is the difference between the predicted value and the true value. For the convenience of analysis, this study takes the absolute value of the difference between the predicted value and the true value.

It can be seen from Fig. [7](#page-9-1) and Table [3](#page-10-0) that between the six models, the PLSR prediction model and the multiple linear regression prediction model have the worst fit. Although the PLSR model can solve the multicollinearity problem between independent variables, like the linear analysis method used in the multiple linear regression analysis, it has a poor ability to deal with nonlinear problems. The SVM and the RBF neural network can effectively deal with nonlinear problems and have shown a better fit for nonlinear problems. The fit of the RBF neural network model is better than that of the SVM model, which reflects the advantages of the RBF neural network compared with the SVM. After implementing FA or PLSR analysis to reduce the dimensions of the original data, the redundant information between variables

is eliminated, and the structure of the neural network is optimized, so that the fit of the FA-RBF neural network prediction model and PLSR-RBF neural network prediction model is better than that of the RBF neural network prediction model alone. The fitting accuracy of the FA-RBF neural network prediction model is further improved compared to that of the RBF neural network model alone, but the PLSR-RBF neural network prediction model is not further improved compared to the RBF neural network model in terms of fitting accuracy.

Comparison with other models' predictive ability

Because the established prediction model may have over the ftting phenomenon, that is, the prediction accuracy of the model near the training samples is very high, but the prediction accuracy of new samples is very low. Such a prediction model is not a good model that can be applied to solve practical problems. Therefore, judging the quality of a prediction model mainly depends on the prediction ability of the model for new samples (Chu et al. [2021](#page-13-33)). The ability of the coupled PLSR-RBF neural network model of the coal seam roof aquifer to predict water inrush quantities for new samples were further verifed by processing the three reserved groups of simulation sample data according to the principle of training sample data standardization. Thereafter, the processed sample data were substituted into both the MLR prediction model, the PLSR prediction model, the RBF neural network prediction model, the SVM prediction model, and the FA-RBF neural network model. To further analyze

Table 4 Comparison of the prediction results of the diferent models for simulation samples

Fig. 8 Comparison of ftting results of the diferent models based on simulation samples

the applicability and rationality of diferent methods, the prediction effects of the PLSR-RBF neural network model were compared with the other five models (see Table [4](#page-10-1) and Fig. [8\)](#page-11-0). This study mainly considered four indicators for evaluating the predictive ability of the PLSR-RBF neural network model, including the maximum absolute error, the average absolute error, the maximum relative error, and the average relative error(see Table [4](#page-10-1)).

The prediction effect of the PLSR prediction model and the MLR prediction model are the worst of the six models (see Fig. [8,](#page-11-0) Table [4\)](#page-10-1), which indicates that both of these methods are used as methods to deal with linear problems, and their predictive ability and ftting ability for non-linear problems are both poor. The RBF neural network model and the SVM model have almost the same predictive capabilities for new sample data, and both are signifcantly better than the PLSR prediction model and the MLR prediction model. This means that the RBF neural network model and the SVM model have better generalizability, but their predictive accuracy must still be improved compared with the FA-RBF neural network prediction model and the PLSR-RBF neural network prediction model after dimension reduction. The PLSR-RBF neural network prediction model has the highest prediction accuracy for new samples among the six models and this indicates that the PLSR-RBF neural network model has a strong generalization ability and high prediction accuracy, and it can be more practicable and accurate to predict the water inrush quantities of coal seam roof aquifers.

Discussion

Compared with other models, the PLSR-RBF neural network prediction model proposed in this paper has a good ftting ability for training samples, and more importantly, it shows better prediction accuracy for new samples. The reasons for this result may be due to three factors. First, the RBF neural network can approximate arbitrary nonlinear continuous functions with high precision, and can better reveal the actual structure of complex nonlinear systems. Second, the PLSR not only considers the generalizability of the independent variable system but also focuses on explaining dependent variables and the components that were extracted using the PLSR can better explain the whole system than the principal components that were extracted by FA. The application of PLSR efectively realizes the dimensionality reduction processing of high-dimensional data, eliminates noise interference, and efectively solves the problems of serious multicollinearity between independent variables. Third, the prediction model based on PLSR-RBF neural network proposed in this paper integrates the unique advantages of these two methods and it can not only eliminate the infuence of repeated information among various infuencing factors on the prediction results but also simplify the structure of the neural network model, which greatly improves the convergence speed, learning ability and prediction ability of the model. Therefore, from the perspective of obtaining a good

model ft and the ability to make accurate predictions, the PLSR-RBF neural network model can reasonably efectively model water inrush quantities of coal seam roof aquifers and is very practicable.

In addition, although the PLSR-RBF neural network model can efectively handle the complex nonlinear coupling system required to model coal seam roof water inrushes, where water inrushes are afected by many factors (Liu and Li [2019\)](#page-13-6), including hydrogeological conditions, geological structure, and mining conditions (Xiao et al. [2012;](#page-14-6) Qin et al. [2013](#page-13-4); Liu et al. [2021](#page-13-5)). Therefore, it is necessary to comprehensively consider the various factors that affect the coal roof water inrush and their interrelationships, efectively use the existing geological and hydrological parameters, and analyze the potential changes in depth (Chen et al. [2021](#page-12-3)). This study was limited in that it only considered eight of these variables, and the number of modeling samples is relatively small. For the prediction accuracy of the model, the number of infuencing factors selected and the richness and reliability of data resources will have impact on the accuracy of the prediction results. As many variables as possible and more sample data would be considered in the future to further improve the prediction ability of the PLSR-RBF model, so that it can predict coal seam roof water inrush quantities more accurately.

Conclusions

Based on the geological and hydrogeological conditions of the Xuzhuang Coal Mine, a quantitative prediction model of the water inrush quantities from the coal seam roof based on PLSR and RBF neural network was proposed in this study. Through this study, the following conclusions can be obtained:

- (1) Water inrushes from coal seam roofs are the result of many complex and nonlinear factors. In this study, the drilling core recovery rate of the roof, the drilling fuid consumption, the aquifer thickness, the sandstonemudstone ratio, the fault fractal dimension, the fold plane deformation coefficient, the fault strength, and the mining depth were the main factors that controlled the water inrush quantity from the roof aquifer of the No. 7 coal seam in the Xuzhuang Coal Mine. Correlation analysis showed that there is certain multicollinearity among the independent variables which will make prediction models unstable.
- (2) The PLSR and RBF neural networks were used to develop a prediction model of the water inrush quantities from coal seam roof. PLSR was used to extract two main variables from the eight independent variables which strongly explain the water inrush quantities.

These two variables were then used as an input layer to the RBF neural network, which reduced the input dimensions of the RBF neural network and optimized the network structure.

- (3) Compared with the PLSR model, the MLR model, the RBF neural network model, the SVM model, and the FA-RBF neural network model, the coupled PLSR-RBF neural network prediction model of coal seam roof water inrush has better ftting accuracy and the best prediction accuracy. The average absolute error of fitting of this model is $6.07E-4$ m³/h, and the average relative error of ftting is 6.07E-3%; while the average absolute error of prediction of this model for new samples is $1.9967 \text{ m}^3/\text{h}$, and the average relative error of prediction for new samples is 9.873%, which is less than 10%.
- (4) This model not only solves the multicollinearity problem among multiple variables but also improves the stability and prediction accuracy of the model while avoiding the phenomenon of overftting. It has good engineering application value and can meet the needs of the water inrush quantity quantitative prediction of coal seam roof aquifer.

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Declarations

Conflict of interest The authors declare no confict of interest.

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