**ORIGINAL RESEARCH** 



# A comprehensive framework towards segmenting and classifying breast cancer patients using deep learning and Aquila optimizer

Hossam Magdy Balaha<sup>1</sup> · Esraa Raffik Antar<sup>1</sup> · Mahmoud M. Saafan<sup>1</sup> · Eman M. El-Gendy<sup>1</sup>

Received: 22 March 2022 / Accepted: 27 March 2023 / Published online: 7 April 2023 © The Author(s) 2023

### Abstract

Breast cancer is among the major frequent types of cancer worldwide, causing a significant death rate every year. It is the second most prevalent malignancy in Egypt. With the increasing number of new cases, it is vital to diagnose breast cancer in its early phases to avoid serious complications and deaths. Therefore, routine screening is important. With the current evolution of deep learning, medical imaging became one of the interesting fields. The purpose of the current work is to suggest a hybrid framework for both the classification and segmentation of breast scans. The framework consists of two phases, namely the classification phase and the segmentation phase. In the classification phase, five different CNN architectures via transfer learning, namely MobileNet, MobileNetV2, NasNetMobile, VGG16, and VGG19, are applied. Aquila optimizer is used for the calculation of the optimal hyperparameters of the different TL architectures. Four different datasets representing four different modalities (i.e., MRI, Mammographic, Ultrasound images, and Histopathology slides) are used for training purposes. The framework can perform both binary- and multi-class classification. In the segmentation phase, five different structures, namely U-Net, Swin U-Net, Attention U-Net, U-Net++, and V-Net, are applied to identify the region of interest in the ultrasound breast images. The reported results prove the efficiency of the suggested framework against current state-of-the-art studies.

**Keywords** Breast Cancer (BC)  $\cdot$  Convolutional Neural Network (CNN)  $\cdot$  Deep Learning (DL)  $\cdot$  Meta-heuristic Optimization  $\cdot$  Aquila Optimizer (AO)

# 1 Introduction

Breast cancer affects a huge bulk of women yearly around the world, and it causes fatalities among women. As per the World Health Organization (WHO), breast cancer is an extremely popular sort of cancer worldwide in 2020 (Organization WH 2022) as indicated in Fig. 1. The survival rates vary among different countries, from 80% in North America,

Mahmoud M. Saafan saafan2007@mans.edu.eg

Hossam Magdy Balaha hossam.m.balaha@mans.edu.eg

Esraa Raffik Antar esraa96@mans.edu.eg

Eman M. El-Gendy eman\_elgendy@mans.edu.eg

<sup>1</sup> Computers and Control Systems Engineering Department, Faculty of Engineering, Mansoura University, Mansoura, Egypt 60% in Japan and Sweden, to 40% in low-income nations (Masud et al. 2020). The rates of occurrence shown in Fig. 2 and mortality shown in Fig. 3 differ per country, depending on many circumstances including the environment, the availableness of modern medical care, socioeconomic levels, and so on Francies et al. (2020). As shown in Fig. 4, the mortality rates in nations with a bigger "low to middle" income population are rising every year due to the inability to obtain profitable resources. Several affluent countries, such as Australia, are also seeing an increase in the number of cases. Therefore, raising awareness about breast cancer and encouraging women to be screened is critical because early detection and diagnosis can save lives (Zuluaga-Gomez et al. 2021). As shown in Fig. 5, Egypt is one of the top countries having new cases of breast cancer in Africa in 2020. Breast cancer is the second most prevalent malignancy in Egypt in 2020 as shown in Fig. 6.

Breast cancer is a disease in which the cells of the breast uncontrollably multiply (For Disease Control 2022). The main elements of the breast are the (1) ducts, (2) lobules, **Fig. 1** Approximate number of novel patients of different types of cancer in 2020 (Organization WH 2022)

Fig. 2 Approximate number of

novel breast cancer patients dis-

tributed by continents in 2020

(Organization WH 2022)

Estimated age-standardized incidence and mortality rates (World) in 2020, worldwide, both sexes, all ages



Estimated number of incident cases all cancers, females, all ages



# **Fig. 3** Approximate number of deaths due to breast cancer distributed by continents in 2020 (Organization WH 2022)





Estimated number of incident cases and deaths all cancers, females, all ages



Fig. 5 Approximate number of novel breast cancer patients distributed by countries in Africa in 2020 (Organization WH 2022)







and (3) connective tissues. A duct is a tube that transports breast milk to the nipple. Lobules are the glands responsible for making milk. Connective tissues consist of fiber and fatty tissues and connect the entire components of the breast (Lawrence 2022). Breast cancer is more commonly found in the lobules or the ducts of the breast (Charishma et al. 2020). It begins in the breast tissue. Like other malignant tumors, they can enter and spread to the tissues around the breast. It may also propagate to other organs of the body, leading to the formation of additional tumors, a process called metastasis (Clinic 2022). It is vital to keep in mind that the predominant of breast lumps are not cancerous (i.e., malignant). Non-cancerous breast tumors are irregular masses that remain locally in the breast. Benign breast lipomas are rarely dangerous. However, they do increase the risk of breast cancer in women (Society 2022).

Symptoms of breast cancer can vary according to the affected patient. The majority of people are completely oblivious to any indicators (Melekoodappattu et al. 2022). The frequently obvious sign of breast cancer is a new tumor or mass in the breast tissue (Bakker et al. 2019). A lump in the breast or armpit is the most prevalent symptom. Skin changes, soreness, a nipple that pushes inward, and unusual discharge from the nipple are among the other symptoms (Benson et al. 2020). The risks of acquiring breast cancer rise with age. Every year, more than 80% of women with breast cancer are above 45 years old, with around 43% of women being 65 years old or older (Duffy et al. 2020).

Mammography is the gold standard for routine screening. It is critical to examine the screening data and deliver a diagnosis as correctly and fast as possible after collecting it (Zuluaga-Gomez et al. 2021; Melekoodappattu and Subbian 2020). Experts use mammography and ultrasound pictures to discover malignancies, which necessitate the use of specialist radiologists (Indra and Manikandan 2021). The most commonly used characteristics, such as shape, texture, density, and other characteristics, are characteristics manually configured according to the experience of the physician, that is, subjective characteristics. Although the traditional diagnosis approach is widely utilized, its accuracy can still be improved (Wang et al. 2019). Consequently, computeraided diagnosis systems (CADs) are now widely employed to assist radiologists in making decisions when diagnosing malignancies (Ahmed et al. 2020). CAD systems can reduce radiologists' workload and decrease the amount of false-positive and false-negative diagnoses (Elter and Horsch 2009).

With deep learning's exceptional performance in detecting and recognizing visual items, as well as other applications, deep learning techniques to aid radiologists providing increased accuracy of interpreting mammographic scans have piqued people's curiosity (Kim et al. 2018; Hamidinekoo et al. 2018). According to recent research, deep learning-based CAD systems perform the same goes for radiation in the standalone mode and even improve radiologists' performance in the assisted mode (Shen et al. 2019). The Convolutional Neural Network (CNN) is a deep learning algorithm frequently applied in solving challenging problems. It is a representative learning algorithm that can automatically extract meaningful information from the original image without manually designing function descriptors (Khan et al. 2020). It solves the drawbacks of classic machine learning techniques. Traditional machine learning algorithms necessitate feature extraction, which necessitates the assistance of a domain expert (Zheng et al. 2014). In addition, choosing the right function for a specific situation is a daunting task. However, deep learning technology solves the feature selection problem by automatically extracting relevant features from the original input without the need for pre-selected features (Indolia et al. 2018). Due to recent performance improvements in image segmentation, detection, and classification, CNN has been successfully applied in medical imaging challenges (Sohail et al. 2021).

In the present work, a novel hybrid framework for the segmentation and classification of breast cancer images is proposed. The framework is composed of two phases, namely the classification phase and the segmentation phase. In the classification phase, the model is used to classify breast images into two categories (i.e., benign or malignant). To train the framework, four different datasets representing different modalities (i.e., MRI, Mammographic, Ultrasound images, and Histopathology slides) are used. The variety of data types ensures that the model can be used with all image types. Each of these datasets is classified into a different number of classes, hence the framework can perform both binary- and multi-class classification. Five pre-trained CNN architectures, namely MobileNet, MobileNetV2, NasNet-Mobile, VGG16, and VGG19, are used in the classification phase. To refine the performance of the different models, Aquila Optimizer (AO) is used to tune the hyperparameters of the different CNN architectures. During the segmentation phase, five different segmentation models are used, namely U-Net, Swin U-Net, Attention U-Net, U-Net++, and V-Net, to identify the region of interest in the ultrasound breast images.

#### 1.1 Paper contributions

The key contributions of the current study are:

- Proposing a novel hybrid framework for classification and segmentation of breast cancer images.
- Using four different datasets for training purposes.
- The proposed model can be used for MRI, Mammographic, Ultrasound images, and Histopathology slides.
- The use of five pretrained CNN architectures for breast image classification.

- AO is used to tune the hyperparameters of the different CNN architectures.
- Using five models for the segmentation of ultrasound breast cancer images.

#### 1.2 Paper organization

The remaining of the article is divided into six sections. Section 2 gives a survey of the current studies about the use of CNN for detecting breast cancer and the different segmentation techniques. Section 3 presents background about the necessary techniques used in the proposed framework. Section 4 explains in detail the proposed framework for the classification and segmentation of breast cancer images while section 5 gives the experimental results and their discussions. Section 6 is the conclusion, limitations of the current study, and trends for future work.

# 2 Related studies

This section presents a state-of-the-art survey about the use of CNN in the diagnosis of breast cancer. Then, a survey about the different segmentation techniques applied to breast cancer images is presented.

#### 2.1 Related studies using CNN

Melekoodappattu et al. (2022) developed a system for diagnosing breast cancer using CNN and image texture attribute extraction. They could achieve accuracies of 98% and 97.9% on the MIAS and DDSM repositories, respectively. Wang et al. (2021) proposed a boosted EfficientNet CNN architecture for automatically detecting cancer cells in breast cancer pathology tissue as a solution to low image resolution. Sharma and Kumar (2021) created a deep learning system to identify breast cancer using histopathology photographs. They used the DenseNet201 CNN model for extracting features. Malignant and benign classification tasks are the two categories of classification tasks. Salama and Aly (2021) used images from three different datasets, namely Digital Database for Screening Mammography (DDSM), Mammographic Image Analysis Society (MIAS), and the Curated Breast Imaging Subset of DDSM (CBIS-DDSM). These images are classified as benign and malignant using various models such as DenseNet121, InceptionV3, VGG16, ResNet50, and MobileNetV2. The best-achieved accuracy is 88.87% using InceptionV3 with data augmentation. Chorianopoulos et al. (2020) applied three CNN models, namely MobileNet, VGG16, and AlexNet on two different datasets i.e., ultrasounds and histopathological images. The best accuracy was 96.82% achieved by VGG16 on the ultrasounds dataset. MobileNet achieved the best accuracy of 91.04% on the Invasive Ductal Carcinoma dataset. Hameed et al. (2020) used four distinct CNN models based on the pre-trained VGG16 and VGG19 structures, namely VGG16 Fully Trained, VGG16 Refined, VGG19 Fully Trained, and VGG19 Refined trained to classify histopathological images of noncancerous and cancerous breast cancers using their collected dataset. They found that the best accuracy was 92% achieved by VGG19 Fine Tuned model.

Dabeer et al. (2019) used CNN to identify breast cancer cells into benign or malignant classes. They obtained an accuracy of 99.86%. Alghodhaifi et al. (2019) experimented with two CNN models using depthwise separable convolution (IDCDNet) and standard convolution (IDCNet). Several types of activation functions were investigated, including Sigmoid, TanH, and ReLU. The best achieved accuracy was 87.13% achieved by standard convolution (IDCNet) with ReLU activation function. Saikia et al. (2019) compared multiple fine-tuned transfer learning classification approaches based on CNN to diagnose cell samples. Their suggested method was examined on a dataset containing 212 images of which 113 images are malignant. This dataset was extended to 2120 images of which 1130 images are malignant. Four CNN architectures, namely ResNet50, VGG16, VGG19, and GoogLeNetV3, were used in training. The Fine-tuned GoogLeNetV3 achieved the best accuracy of 96.25%. Ismail et al. (2019) compared the identification of breast cancer using two deep learning model networks, namely VGG16 and ResNet50, and applied the models on the IRMA dataset for classifying benign and malignant tumors. In terms of accuracy, VGG16 outperforms ResNet50 with a score of 94% compared to 91.7% for ResNet50. Mehra (2018) used three popular CNN models, namely ResNet50, VGG16, and VGG19, for both full training and forward learning for classifying histological images of breast cancer. Their best accuracy was 92.60% achieved by VGG16 with Logistic Regression (LR). Gao et al. (2018) proposed a Shallow-Deep CNN to classify patients as benign or cancer from mammography images. The shallow CNN is used to find the recombined images from low-energy images, while a deep CNN is applied to extract the unique features from these images. Their best-achieved accuracy was 90% using their proposed technique.

#### 2.2 Related studies using segmentation

Salama and Aly (2021) used a modified U-Net model for segmentation of breast cancerous area from mammographic images. There proposed model could do both segmentation and classification with an accuracy of 98.87% using InceptionV3 plus a modified U-Net model with data augmentation. Byra et al. (2020) proposed a deep learning method using U-Net for breast mass segmentation in ultrasonography. They achieved an overall accuracy of 97.6%. El Adoui et al. (2019) created two CNN using SegNet and U-Net to suggest two deep learning algorithms for automatic segmentation of breast tumors in dynamic contrast-enhanced magnetic resonance imaging. The Seg-Net architecture achieved a mean intersection over union (i.e., accuracy) of 68.88%, whereas the U-Net architecture achieved 76.14%. Li et al. (2019) used the segmentation of masses for enhancing the accuracy of diagnosing breast cancer and lowering the mortality rate because breast mass is one of the most characteristic markers for the diagnosis of breast cancer. In their experiments, they used U-Net, attention U-Net, and DenseNet for segmentation and could achieve accuracy of 74.37%, 74.83%, and 77.93%, respectively. Alom et al. (2018) applied the Recurrent Residual U-Net for Nuclei segmentation from high-resolution histopathology images to extract the fine features from nuclear morphometrics. They could achieve a dice coefficient of 92.15% segmentation accuracy. Dalmia et al. (2018) compared the accuracy of different algorithms, namely VGG-Net, U-Net, and V-Net. They could prove that a larger dataset combined with parameter adjustment would allow the model to generalize to previously unseen examples more efficiently, resulting in better training and validation outcomes. They could achieve an accuracy of 81.6%, 99.5%, and 99.6% for the different models respectively.

# 3 Background

This section presents background about the techniques used in the proposed framework.

# 3.1 Convolutional Neural Networks (CNN)

CNN is a class of deep learning used in handling image data (Bingli et al. 2021). It is inspired by the visual cortex in animals (Jogin et al. 2018). It is designed for automatic and adaptive learning of structures, hierarchical and spatial characteristics, and low-level to high-level patterns (Balaha et al. 2021).

#### 3.1.1 CNN layers

CNN is usually made up of three types of layers: convolution layer, pooling layer, and fully connected layer. The earlier two layers (i.e. the convolutional and pooling layers) extract features. On the other hand, the last layer (i.e., fully connected layer) maps the extracted objects to the final output space (Balaha et al. 2021).

#### 3.1.2 Parameters optimization

The choice of the right optimization method and the efficient tuning of the hyperparameters strongly influences the training speed and the final performance of the learned model (Zhang et al. 2021). The current study uses the Adam, AdaGrad, NAdam, AdaDElta, AdaMax, RMSProp, and SGD optimizers. Adaptive Moment Estimation (Adam) Optimizer effective when dealing with a huge problem containing multiple parameters (Kingma and Ba 2014). AdaGrad Optimizer adjusts the learning ratio based on the settings, making smaller updates for settings related to common features and huge updates for settings related to non-features regularly (Luo et al. 2019). Nesterov Adaptive Momentum (NAdam) calculates the velocity before the gradient (Dozat 2016) AdaDelta Optimizer extends AdaGrad as a trial to decrease the rate of excessive and monotonous learning rather than assembling the entire past squared gradients (Dogo et al. 2018). AdaMax Optimizer represents the updated version of Adam (Vani and Rao 2019). RMSProp Optimizer was proposed simultaneously to address Adagrad's plummeting learning rate. RMSprop is the same as Adadelta's first update vector (Wu et al. 2016). Stochastic Gradient Descent (SGD) Optimizer is a repetitive technique used for the optimization of the objective function with appropriate regularity properties. Otherwise, it updates the parameter for each input (Bottou 2012).

### 3.2 Aquila Optimizer (AO)

Aquila's behavior in the wild while capturing victims is the main inspiration for the AO algorithm. Therefore, the optimization methods of the AO algorithm are presented in 4 methods. The first method is to select a search area by navigating up with vertical tilt. The second method is to explore inside a disparate search area by contour flight with a small glide attack. The third method is to explore inside a convergent search area by low-level flight with a sinking attack for slow prays. The fourth method is walking and grabbing the victim (AlRassas et al. 2021). The selection between the four methods is done based on specific parameters.

#### 3.3 Image segmentation

Image segmentation is one class of digital image processing including splitting an image into various parts on the basis of the image's properties and qualities (Singh and Singh 2010). The fundamental reason behind image segmentation is to simplify the image for ease in analysis (Norouzi et al. 2014). In diagnosing patients with cancer, the form of cancer cells is important in determining the severity of the cancer disease. The use of image segmentation technologies has had a significant impact in this area so that cancer cells can be correctly and accurately identified (Senthil Kumar et al. 2019).

Segmentation using U-Net Model: U-Net model was created for biological-image segmentation (Ronneberger et al. 2015). The U-Net architecture is essentially a network of encoders followed by a network of decoders (Habijan et al. 2019). Segmentation using Swin U-Net Model: The use of transformers (Vaswani et al. 2017) has extended from natural language processing (NLP) tasks to vision-related and segmentation tasks. Swin U-Net (Cao et al. 2021) implants pure transformer structure into the U-Net architecture for segmentation tasks. Segmentation using Attention U-Net Model: is almost built upon the well-known U-Net (Vaswani et al. 2017). The network consists of a reduced path for extracting features of locality and an extension path for resampling the image map using contextual information (Abraham and Khan 2019). Segmentation using U-Net++ *Model*: U-Net++ is a general-purpose image segmentation architecture that tries to address the shortcomings of U-Net (Zhou et al. 2019). The U-Net++ is made up of multiple U-Nets of different depths, with the decoders firmly coupled at the same resolution via a revised skip connection (Lu et al. 2021). Segmentation using V-Net Model: The V-Net method consists of two main parts, i.e. left and right sections. The left section contains the compressed path and is divided into various stages that operate at other resolutions with each stage having 1 to 3 convolution layers. On the other hand, the right section compresses the input until an initial size is reached (Abdollahi et al. 2020).

# 3.4 Performance metrics

All learning algorithms require a metric to evaluate performance (Balaha et al. 2021b). The most commonly used performance metrics are TN, TP, FN, FP, Accuracy, Recall (Sensitivity), Precision, F1-score, Specificity, AUC (Area under the curve), IoU Coefficient, Dice Coefficient, Cosine similarity, Hinge, and SquaredHinge (Balaha and Saafan 2021; Abdulazeem et al. 2021). These metrics are: *TN* is the rightly estimated negative values so that the actual class value is false and the estimated class value is also false. *TP* is the rightly estimated positive values so that the actual class value is true and the estimated class value is also true. *FN* is the actual class value is true but the estimated class value is false. *FP* is the actual class value is false and the estimated class value is true.

Accuracy is the ratio of rightly estimated observations to overall observations. *Precision* is the ratio of the rightly estimated positive observations to the overall estimated positive observations. *Sensitivity (or Recall)* is the ratio of rightly estimated positive observations to overall observations. *F1-score* is the weighted ratio of Recall and Precision. *Specificity* is the number of cases identified as negative from all the real negative cases. Area Under Curve (AUC) is the area under the Receiver Operating Characteristics Curve (ROC Curve). Intersection over Union (IoU) is also known as the Jaccard index. Dice Coefficient is a measure of similarity of the objects. Cosine Similarity is a similarity measure using Euclidean distance. Hinge Loss is a similarity measure using the loss function. Squared Hinge Loss is a square of the output of the hinge.

# 4 Methodology

The suggested approach is trained on four different types from four different modalities for versatility. This is important to guarantee the robustness of the model for all types of images. Each type of dataset has a variable number of classes. For this reason, the proposed framework can perform both binary and multi-class classification. The purpose of the current work is to suggest a novel hybrid framework for the classification and segmentation of breast cancer images. The phases of the proposed framework are presented in Fig. 7. The phases of the proposed framework are described in the next subsections.

#### 4.1 Datasets acquisition phase

In the current work, four different datasets with different modalities (i.e., MRI, mammographic, Ultrasound images, and histopathology slides) are used to train the models. Magnetic Resonance Imaging (MRI) is recommended when soft tissue imaging is required. So, it is used for expose lesioned regions (Yurttakal et al. 2020). On the other hand, Mammography is the most commonly used technique for breast cancer diagnosis. It is an accurate technique that uses lowdose X-Ray to display the inner texture of the breast (Maitra et al. 2012). The ultrasound image is preferred due to many advantages including low cost and acceptable accuracy (Feng et al. 2017). On the other hand, the biopsy is defined as the process of extracting a sample or portion of a mass in the human body, usually called the biopsy sample, for further examination (Preetha and Jinny 2021). Histopathology means to analyze the biopsy sample by the specialist, usually called the pathologist. Therefore, histopathology images are microscopic images of the tissues of masses taken from the human body (Aswathy and Jagannath 2017).

The first used dataset is "Breast Cancer Patients MRI's" from Kaggle which can be retrieved from https://www.kaggle.com/uzairkhan45/breast-cancer-patients-mris. This dataset contains 1,480 MRI images classified into Healthy (Benign) and Sick (Malignant). The second dataset is "Breast Cancer Dataset" from Kaggle which can be retrieved from https:// www.kaggle.com/anaselmasry/breast-cancer-dataset. This dataset contains histopathology slides. The third dataset is



Fig. 7 The hybrid framework for the classification and segmentation of breast cancer images

Dataset\_BCD\_mammography\_images\_out downloaded from Kaggle from https://www.kaggle.com/anwarsalem/datas et-bcd-mammography-images-out. This dataset consists of 8 classes representing the severity of breast cancer. The fourth dataset is *Breast Ultrasound Images Dataset* (Al-Dhabyani et al. 2020) containing ultrasound images of 600 female patients with 780 images classified into normal, benign, and malignant. It can be downloaded from https://www.kaggle. com/aryashah2k/breast-ultrasound-images-dataset. Table 1 presents a summary of the datasets used in the current study. Samples from the acquired datasets are displayed in Fig. 8.

# 4.2 Pre-processing phase

The used datasets are not found with the same size and hence the *datasets are resized* equally to the size of (100, 100, 3) for classification and (256, 256, 3) for segmentation in RGB mode. The present work uses 4 distinct *scaling techniques*. They are (1) normalization, (2) standardization, (3) min–max scaler, and (4) max–abs scaler. The equations for them are shown in Eqs. 1 to 4 respectively where  $X_{input}$  is the input image,  $X_{scaled}$  is the scaled output image,  $\mu$  is the mean of the input image,  $\sigma$  is the standard deviation of the input image. The used datasets are not balanced as shown in Table 1. To overcome this problem, *data balancing using data augmentation* approach is employed. The present work uses rotation, shifting, shearing, zooming, flipping, and brightness changing augmentation techniques. Table 2 shows the different augmentation techniques and the corresponding configurations.

$$X_{scaled} = \frac{X_{input}}{\max(X)} \tag{1}$$

$$X_{scaled} = \frac{X_{input} - \mu}{\sigma} \tag{2}$$

$$X_{scaled} = \frac{X_{input} - \min(X)}{\max(X) - \min(X)}$$
(3)

$$X_{scaled} = \frac{X_{input}}{|\max(X)|} \tag{4}$$

# 4.3 Segmentation phase

Segmentation is important to label the area of the tumor (i.e., the region of interest) to facilitate the diagnosis for the physician. Hence, the first processing phase of the framework is to apply segmentation. In the segmentation phase, five different segmentation models (i.e., U-Net Ronneberger et al. 2015, Swin U-Net Cao et al. 2021, Attention U-Net Abraham and Khan 2019, U-Net++ Zhou et al. 2019, and V-Net Abdollahi et al. 2020) are used to identify the region of interest in the ultrasound breast images.

# 4.4 Classification and hyperparameters optimization phase

Classification of medical images into their correct class helps physicians in their diagnosis. Hence, the second processing phase of the framework is to classify breast images into either benign or malignant. Medical data always suffers from scarcity. Therefore, five different pre-trained architectures (i.e., MobileNet Howard et al. 2017, MobileNetV2 Sandler et al. 2018, NasNetMobile Addagarla et al. 2020,

lable I Summary of the dataset	s used in the cur	rrent work					
Dataset	Image format	Modality	No. of classes	Classes	No. of images	No. of images per category	Classification or segmentation
"Breast Cancer Patients MRI's"	ipg	MRI	5	Healthy (Benign) and Sick (Malignant)	1480	740 per categort	Classification
"Breast Cancer Dataset"	guq.	Histopathological	5	Healthy (Benign) and Sick (Malignant)	8053	2749 Benign and 5,304 Malig- nant	Classification
"Dataset_BCD_ mammogra- phy_images_out"	gud.	Mammography	×	Density 1Benign, Density 1Ma- lignant, Density2Benign, Density2Malignant, Densi- ty3Benign, Density3Malig- nant, Density4Benign, and Density4Malignant	7632	864 Density1Benign, 288 Density2Benign, 936 Density3Benign, 432 Density4Benign, 2160 Density1Malignant, 2304 Density2Malignant, and 72 Density4Malignant	Classification
Breast Ultrasound Images Dataset	guq.	Ultrasound	б	Normal, Benign, and Malignant	780	133 Normal, 437 Benign and 210 Malignant	Classification and Segmentation

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$$\theta_{t+1} = \theta_t - \frac{\eta}{\nu + \epsilon} \times m_t \tag{5}$$

$$\theta_{t+1} = \theta_t - \frac{\eta}{\nu + \epsilon} \times \left(\beta_1 \times m_t + \frac{(1 - \beta_1) \times g_t}{1 - \beta_1^t}\right) \tag{6}$$

$$\theta_{t+1} = \theta_t - \frac{\eta}{G_t + \epsilon} \odot g_t \tag{7}$$

$$\theta_{t+1} = \theta_t - \frac{RMS[\Delta\theta]_{t-1}}{RMS[g]_t} \times g_t \tag{8}$$

$$\theta_{t+1} = \theta_t - \frac{\eta}{\max(\beta \times \gamma_{x-1}, g_t)} \times m_t \tag{9}$$

$$\theta_{t+1} = \theta_t - \frac{\eta}{\sqrt{E[g^2]_t + \epsilon}} \times g_t \tag{10}$$

$$\theta_{t+1} = \theta_t - \eta \times \nabla_\theta \times J(\theta; x^{(i)}; y^{(i)})$$
(11)

where  $m_t$  is the mean, v is the uncentered variance of the gradients,  $\eta$  is the step size, e is a small quantity used to prevent the division by zero,  $G_t \in \mathbb{R}^{(d \times d)}$  is a diagonal matrix, *RMS* is the root mean squared,  $g_t$  is the gradient of loss function,  $E[g^2]_t$  is the average of squared gradients,  $\beta_1$  and  $\beta_2$  are hyperparameters,  $\gamma_{x-1}$  is the average of squared past gradient, and  $x^{(i)}$  and  $y^{(i)}$  are the input and output pair respectively.

For better selection of the different hyperparameters, AO is introduced at the learning phase. As mentioned in Sect. 3.2, it depends on 4 updating methods. They are expanded exploration  $(X_1)$ , narrowed exploration  $(X_2)$ , expanded exploitation  $(X_3)$ , and narrowed exploitation  $(X_4)$ . For the expanded exploration  $(X_1)$  method, Eq. 12 is used.  $X_M(t)$  is calculated using Eq. 13. where  $X_{best}(t)$ is the best location,  $X_M(t)$  is the average location of the entire Aquila's in the ongoing iteration, t is the number of the ongoing iteration, T is the total count of iterations, N is the population size, and  $r_1$  is an arbitrary number in the range of 0 to 1. For the narrowed exploration  $(X_2)$  method, Eq. 14 is used where  $X_R(t)$  is any arbitrary chosen location of Aquila, D is the size of the dimension, and  $r_2$  is an arbitrary value in the range of 0 to 1. LF(D) is the Levy's flight



and is calculated as shown in Eqs. 15 and 16 where *s* and  $\beta$  are fixed as 0.01 and 1.5, respectively, *v* and *u* are arbitrary number in the range of 0 to 1, and *x* and *y* represents the helix movement during the search and can be calculated function as shown in Eqs. 17 to 20 where  $r_3$  is the count of search cycles in the range from 1 to 20,  $D_1$  consists of

integers in the range from 1 to *D*, and *w* is 0.005. For the expanded exploitation  $(X_3)$  method, Eq. 21 is used where  $\alpha$  and  $\delta$  are adapting parameters set at 0.1, *LB* and *UB* are the lower and upper limits of the problem, and  $r_4$  and  $r_5$  are arbitrary values in the range of 0 to 1. For the narrowed exploitation  $(X_4)$  method, Eq. 22 is used. QF(t) is

Table 2The differentaugmentation techniquesand the correspondingconfigurations

Technique	Value
Rotation	20°
Width shift ratio	15%
Height shift ratio	15%
Shear ratio	15%
Zoom ratio	15%
Brightness change	[0.8 : 1.2]
Vertical flip	1
Horizontal flip	1

calculated using Eq. 23,  $G_1$  is calculated using Eq. 24, and  $G_2$  is calculated using Eq. 25 where  $r_6$ ,  $r_7$ , and  $r_8$  are arbitrary values in the range of 0 to 1, X(t) is the current location, QF(t) is the value of the quality function used to stabilize the search technique,  $G_1$  is an arbitrary value in the range of -1 to 1 expressing Aquila's movement during victim pursuit, and  $G_2$  is linearly reduced from 2 to 0 and represents the slope of flight when hunting victim.

$$X_1(t+1) = X_{best}(t) \times \left(1 - \frac{t}{T}\right) + \left(X_M(t) - X_{best}(t) \times r_1\right)$$
(12)

$$X_M(t) = \frac{\sum_{i=1}^N X_i(t)}{N} \tag{13}$$

$$X_2(t+1) = X_{best}(t) \times LF(D) + X_R(t) + (y-x) \times r_2$$
(14)

$$LF(D) = s \times \frac{u \times \sigma}{|v|^{\frac{1}{\beta}}}$$
(15)

$$\sigma = \frac{r \times (1+\beta) \times \sin\left(\frac{\pi \times \beta}{2}\right)}{0.5 \times r \times (1+\beta) \times \beta \times 2^{\frac{\beta-1}{2}}}$$
(16)

 $x = r \times \sin(\theta) \tag{17}$ 

 $y = r \times \cos(\theta) \tag{18}$ 

 Table 3
 The segmentation phase experiments configurations

Configuration	Specifications
Input shape	$(256 \times 256 \times 3)$
Loss function	Binary crossentropy
Parameters optimizer	Adam
Batch size	4
Train to test ratio	85 to 15%
Number of epochs	25
Patience	5

segmentation model	Loss	Accuracy (%)	F1 (%)	Precision (%)	Recall (%)	Specificity (%)	AUC (%)	Sensitivity (%)	IoU (%)	Dice (%)
ention U-Net	0.115	95.58	62.88	87.02	60.36	99.36	96.08	60.36	96.48	96.70

 Table 4
 The segmentation phase experiments results

Squared Hinge (%)

Hinge (%)

95.33

96.38 95.33 98.05 96.70 94.24

94.71

95.84 94.80

95.69 94.58

69.16 18.54 34.50 87.62

92.53 90.65 92.37

99.72

18.54 34.50 87.62

98.97 66.41

18.83

97.37

69.16

67.00 84.24 74.89

57.48 25.98 36.60 27.39

94.13 93.74 93.22 67.89

0.175

0.166

Swin U-Net U-Net++

V-Net

U-Net

0.182 0.619

91.55 80.32

91.24 80.17

87.65

97.03 95.33 94.64  $r = r_3 + 0.00565 \times D_1 \tag{19}$ 

 $\theta = -w \times D_1 + 1.5 \times \pi \tag{20}$ 

$$X_{3}(t+1) = (X_{best}(t) - X_{M}(t)) \times \alpha - r_{4} + ((UB - LB) \times r_{5} + LB) \times \delta$$
(21)

$$X_4(t+1) = QF(t) \times X_{best}(t) - (G_1 \times X(t) \times r_6) - G_2 \times LF(D) + r_7 \times G_1$$
(22)

$$QF(t) = t^{\frac{2 \times rond - 1}{(1 - T)^2}}$$
(23)

$$G_1 = 2 \times r_8 - 1 \tag{24}$$

$$G_2 = 2 \times \left(1 - \frac{1}{T}\right) \tag{25}$$

# 4.5 System evaluation phase

Different performance metrics are used in the current study as mentioned in Sect. 3.4. The corresponding equations for them are accuracy (Eq. 26), (2) precision (Eq. 27), (3) recall (i.e., sensitivity) (Eq. 29), (4) specificity (Eq. 28), (5) F1-score (Eq. 30), (6) AUC, (7) IoU (Eq. 31), (8) dice coef. (Eq. 32), and (9) cosine similarity.

$$Accuracy = \frac{TP + TN}{TP + TN + FP + FN}$$
(26)

$$Precision = \frac{TP}{TP + FP}$$
(27)

Specificity = 
$$\frac{TN}{TN + FP}$$
 (28)

Recall = Sensitivity = 
$$\frac{TP}{TP + FN}$$
 (29)

$$F1-score = \frac{2 \times Precision \times Recall}{Precision + Recall}$$
(30)

$$IoU = \frac{TP}{TP + FP + FN}$$
(31)

Dice = 
$$\frac{2 \times TP}{2 \times TP + FP + FN}$$
 (32)

#### 4.6 Pseudocode of the proposed framework

The learning and optimization steps are calculated repeatedly for a predefined number of iterations  $T_{max}$ . After the learning iterations are executed, the finest combined configuration can be reported and used in any further systems. Algorithm 1 presents a summary of the introduced overall parameters learning and AO hyperparameters optimization approach.

Algorithm 1: The suggested learning and AO optimization fi	amework pesudocode
Input: model, dataset	// The required model to optimize and the target dataset (See Table 1).
<b>Output:</b> bestScore, bestCombinations	<pre>// The best overall score and the corresponding combinations.</pre>
1 trainX, validationX, testX, trainY, validationY, testY = Split	tDatasetTrainValTest(dataset) // Split the dataset into training,
testing, and validation subset concerning the split size	(0.85 in the current study).
2 model = CreateCompileModel() // Create a	nd compile the pre-trained model using the ImageNet pre-trained weights.
<b>3</b> solutions = <b>GenerateInitialSolutions</b> ()	// Generate the initial AO solutions (10 in the current study).
// Execute the learning and AO hyperparameters optimizatio	n processes for $T_{max}$ iterations.
4 $t = 1$	// Initialize the iterations' counter where $t \leq T_{max}$ .
s while $(t \leq T_{max})$ do	
// Calculate the scores for each solution in the popul	ation.
<b>6</b> i = 1	// Initialize the counter where $i \leq N_{max}$ .
7 $ $ scoresList = [] /	/ Initialize the scores list that will hold the score for each solution.
8 while $(i \leq N_{max})$ do	
9 $ $ score = CalculateFitnessScore (model, solutions[i])	<pre>,trainX,trainY,validationX,validationY,textX,textY) // Calculate the</pre>
fitness score (i.e., accuracy) for the selected s	olution.
10 Append(score, scoresList)	<pre>// Append the retrieved score into the scores list.</pre>
$11 \qquad \qquad \qquad i=i+1$	// Increment the counter.
// Update the population using the AO meta-heuristic o	ptimizer.
12 solutions = UpdateSolutionsViaAO(solutions, scoresL	<i>ist</i> )
13 $\lfloor t = t + 1$	// Increment the iterations counter.
14 return bestScore, bestCombinations	// Return the best score and the corresponding commbinations

# 5 Experiments and discussions

This section presents the results of experiments applied to the proposed framework. Python is the used scripting language. The major used packages are Tensorflow, Keras, keras-unet-collection, NumPy, OpenCV, and Matplotlib. The working environment is Google Colab with GPU (i.e., Intel(R) Xeon(R) CPU @ 2.00GHz, Tesla T4 16 GB GPU, CUDA v.11.2, and 12 GB RAM).

# 5.1 Segmentation phase experiments and discussion

Table 3 summarizes the common configurations of the segmentation experiments. Table 4 summarizes the segmentation phase experiments results. It is clear that the "Attention U-Net" is better than other models concerning the loss, accuracy, F1-score, precision, specificity, AUC, IoU coef., and dice coef. However, the "V-Net" is better than others concerning the recall (i.e., sensitivity). Figure 9 summarizes the segmentation phase experiments results graphically. Figure 10 shows the result of applying the Attention U-Net on a sample image. It shows that the region of interest from the predicted mask is relatively comparable with the original mask region of interest.

## 5.2 Classification phase experiments and discussion

Table 5 summarizes the classification phase experiments configurations. The finest associations for every model applied on "Breast Cancer Dataset" dataset are documented in Table 6. It is clear that the Categorical Crossentropy loss is the best choice using two models. The SGD and SGD Nesterov parameters optimizers are the best choice by two models each. Standardization is the best choice using two models. The finest associations for every model applied on "Dataset BCD mammography images out" dataset are documented in Table 7. It is clear that the KLDivergence loss is the best choice using three models. The SGD and AdaMax parameters optimizers are the best choice by two models each. The min-max scaler is the best choice using three models. The finest associations for every model applied on "Breast Cancer Patients MRI's" dataset are documented in Table 8. It is clear that the Categorical Crossentropy and KLDivergence losses are the best choice by two models each. The AdaGrad and SGD Nesterov parameters optimizers are the best choice by two models each. The standardization and min-max scaling are the best choice by two models each. This presents multiple performance indices concerning the "Breast Cancer Dataset" dataset in Table 9. From them, the VGG19 pre-trained model gives the topmost results over other models. This presents multiple





Fig. 9 The segmentation phase experiments graphical summarization



Fig. 10 The result of applying the Attention U-Net on a sample image

Configuration	Specifications
Apply dataset random shuffling?	Yes
Input shape	$(100 \times 100 \times 3)$
Train to test ratio	85 to 15%
Output activation function	SoftMax
Number of epochs	5
Pre-trained parameters initializers	ImageNet
Hyperparameters metaheuristic optimizer	Aquila Optimizer (AO)
AO population size	10
AO iterations number	10
Pre-trained models	InceptionV3, Xception, EfficientNetB7, NASNetLarge, VGG19, SeNet154, DenseNet201, and ResNet152V2
Losses range	Categorical Hinge, Categorical Crossentropy, KLDivergence, Poisson, Hinge, and Squared Hinge
Parameters optimizers range	Adam, AdaGrad, AdaMax, NAdam, RMSProp, AdaDelta, SGD, SGD Nesterov, RMSProp Centered, Ftrl, and Adam AMSGrad
Scaling techniques	Standardization, Normalization, Max-Absolute, and Min-Max
Dropout range	$[0\% \to 60\%]$
Batch size range	$4 \rightarrow 48 \text{ (step = 4)}$
Pre-trained model learn ratio range	$1 \rightarrow 100 \text{ (step = 1)}$
Apply data augmentation (DA)	[Yes, No]
DA rotation range	$0^{\circ} \rightarrow 45^{\circ} \text{ (step = } 1^{\circ}\text{)}$
DA width shift range	$[0\% \rightarrow 25\%]$
DA height shift range	$[0\% \rightarrow 25\%]$
DA shear range	$[0 \to 0.25]$
DA zoom range	$[0\% \rightarrow 25\%]$
DA horizontal flip range	[Yes, No]
DA vertical flip range	[Yes, No]
DA brightness range	$[0.5 \rightarrow 2.0]$

 Table 5
 The classification phase experiments configurations

performance indices concerning the "Dataset\_BCD\_mammography\_images\_out" dataset in Table 10. From them, the MobileNet pre-trained model gives the topmost results over other models. This presents multiple performance indices concerning the "Breast Cancer Patients MRI's" dataset in Table 11. From them, the MobileNet, VGG16, and VGG19 pre-trained models are the best model compared to others. Figures 11, 12, and 13 present graphical summarization of the performance metrics concerning the "Breast Cancer Dataset", "Dataset\_BCD\_ mammography\_images\_out", and "Breast Cancer Patients MRI's" datasets respectively.

# 5.3 Comparative study

The results of the proposed framework against the related studies are shown in Table 12. As seen from these results, BCSF could achieve a 100% classification accuracy on MRI data, which is higher than the recorded accuracy. For segmentation, the achieved accuracy is better than most of the recent studies.

# 6 Conclusion and future work

This study introduced a hybrid framework for both classification and segmentation of breast images to diagnose breast cancer using CNN. The framework included two phases. The first phase is the segmentation phase. During this phase, the area of the tumor is detected to facilitate the diagnosis for the physician. Five different segmentation models are used, namely U-Net, Swin U-Net, Attention U-Net, U-Net++, and V-Net, to identify the region of interest in the ultrasound breast images. The used performance metrics are Accuracy, Recall, Precision, Specificity, F1-score, AUC, Sensitivity, IoU coef., dice coef., Hinge, and Squared Hinge. The second phase is the classification phase, in which breast images are classified. Five pretrained CNN architectures, namely MobileNet, MobileNetV2, NasNetMobile, VGG16, and VGG19 are applied. The choice of the different parameters for the used CNN architectures is done using seven different optimizers, namely Adam, AdaGrad, NAdam, AdaMax, AdaDelta, RMSProp, and SGD optimizers. On the other hand, Aquila

<b>Table 6</b> the	s finest combi	ined configur	ations cor	cerning the	"Breast Can	cer Dataset'	' dataset								
Model	Loss	Batch size	Dropout	TF learn ratio	Optimizer	Scaler	Apply augmen- tation	Rotation range	Width shift range	Height shift range	Shear range	Zoom range	Horizontal flip	Vertical flip	Brightness range
VGG16	Categori- cal cros- sentropy	20	0.19	52	SGD	Normalize	Yes	33	0.14	0.19	0.01	0.07	Yes	Yes	0.7–1.55
VGG19	Poisson	36	0.12	44	AdaDelta	Standard- ize	No	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
MobileNet	Cat- egorical Hinge	32	0.25	98	SGD Nes- terov	MaxAbs	Yes	4	0.19	0.19	0.23	0.12	No	Yes	0.55-1.73
Mobile- NetV2	Categori- cal Cros- sentropy	36	0.08	LL	SGD	Standard- ize	Yes	14	0.15	0.21	0.02	0.22	Yes	No	0.89—1.15
NASNet- Mobile	Squared Hinge	32	0.42	55	SGD Nes- terov	MinMax	No	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
Table 7	; finest combi	ined configur	ations cor	cerning the	"Dataset_BC	CD_ mammo	graphy_ima	tges_out" da	taset						
Model	Loss	Batch size	Dropout	TF learn ratio	Optimizer	Scaler	Apply augmen- tation	Rotation range	Width shift range	Height shift range	Shear range	Zoom range	Horizontal flip	Vertical flip	Brightness range
VGG16	KLDiver- gence	8	0.45	94	SGD	MinMax	No	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
VGG19	Cat- egorical Hinge	16	0.45	26	FTRL	Standard- ize	Yes	4	0.19	0.17	0.1	0.16	Yes	No	0.79–1.84
MobileNet	Poisson	20	0.5	35	AdaMax	MaxAbs	No	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
Mobile- NetV2	KLDiver- gence	8	0.23	52	SGD	MinMax	Yes	37	0.14	0.08	0.03	0.13	No	No	1.22–1.25
NASNet- Mobile	KLDiver- gence	48	0.12	49	AdaMax	MinMax	Yes	42	0.25	0.23	0.01	0.03	No	No	1.05–1.21

7911

	200	Datch Size	Dropout	TF learn ratio	Optimizer	Scaler	Apply augmen- tation	range	wıdun shift range	Height shift range	Shear range	Zoom range	Horizo flip	ntal Vert flip	lical I	krightnes ange
VGG16 K	LDiver- gence	40	0.07	78	AdaGrad	Standard- ize	No	N/A	N/A	N/A	N/A	N/A	N/A	N/A		I/A
VGG19 C	ategori- cal Cros- sentropy	24	0.35	76	AdaGrad	MinMax	No	N/A	N/A	N/A	N/A	N/A	N/A	N/A	-	ΥA
MobileNet C	ategori- cal Cros- sentropy	40	0.12	76	SGD Nes- terov	MinMax	Yes	11	0.18	0.06	0.14	0.01	No	Yes	C	.93–1.47
Mobile- Sc NetV2 1	quared Hinge	20	0.01	42	SGD Nes- terov	MaxAbs	Yes	9	0.11	0.05	0.23	0.05	Yes	No	U	.61–0.81
NASNet- K Mobile	LDiver- gence	12	0.39	6	AdaMax	Standard- ize	No	N/A	N/A	N/A	N/A	N/A	N/A	N/A	2	I/A
Model	Loss	Accuracy	(%) F1 (	%) Precisi	on (%) Re	e meuros call (%) S	pecificity (%)	AUC (%)	Sensitivit	y (%) Ic	(%) U(	Dice (%)	Cosine similarity	ΤΡ	N	FP
Table 9 The "J	Breast Ca	ncer Datasei	," dataset c	experiments	performance	e metrics										
VGG16	0.080	97.27	97.2	7 97.27	97.	.27 9	7.27	09.60	97.27	6.0	5.65	96.55 26.25	97.68	10,311	10,311	289 2
VGG19 MabilaNot	070.0	C4.84	2.07 0	C6.86 C	98	2 CV. 2 D	C6.0	99.12 09.66	C6.86 79 70	οč	0.8U 0.11	98.99 00 10	80.62 07.07	10,475	10,475	ר אנג 111
MobileNetV2	0.089	97.66	97.6 97.6	6 97.66	.79	60 90	7.66	90.00 99.49	97.66	r Q	0.41 7.69	90.40 98.02	98.06	10.336	10.336	248 248
NASNetMobil	e 0.648	92.40	92.4	10 92.40	92.	40 9	2.40	96.54	92.40	6	3.80	94.38	93.24	9787	9787	805

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Table 10 The ".	Dataset_	BCD_ mammog.	raphy_im	uges_out" dataset	experiments	s performance n	netrics									
Model	Loss	Accuracy (%)	F1 (%)	Precision (%) Re	ecall (%) S	pecificity (%)	AUC (%)	Sensitivity (%)	IoU (%)	Dice (%)	Cosine similarit. (%)	dT y	NT	E	FN	1
VGG16	0.809	70.32	61.64	80.52 53	3.65 9	8.39	95.82	53.65	63.78	68.65	75.33	9889	126,95	3 2071	8543	
VGG19 MohileNet	1.000 0.143	22.56 95 78	0.00 95 81	0.00 0.0 96.08 95	00 1 5 58 9	00 9 45	50.00 99.60	0.00 95 58	39.13 96 19	41.67 96.62	35.37 96 34	0 17.606	129,02	4 0 7 713	18,43 814	32
MobileNetV2	0.224	92.29	91.86	93.99 90	.59 9	9.20	99.62	90.59	89.59	91.34	93.53	16,698	127,98	9 1035	1734	
NASNetMobile	0.896	68.10	67.74	72.11 64	4.17 9	6.59	94.81	64.17	73.92	76.29	73.38	11,828	124,62	3 4401	6604	
Table 11 The " Model	Breast C. Loss	ancer Patients <u>N</u> Accuracy (%)	<i>IRI's</i> " da F1 (%)	taset experiments I	performance Recall (%)	metrics Specificity (	%) AUC	(%) Sensitivity	, (%) Iol	J (%) D	ice (%) 0	Cosine	dT	NI	FP	Z
VGG16	0.013	100	100	100	100	100	100	100	86	79 96	).16 9	(%) 99.89	1480	1480	0	Ι.
VGG19	0.004	100	100	100	100	100	100	100	.66	.71 99	9.78 9	9.92	1464	1464	0 0	
MobileNet	0.005	100	100	100	100	100	100	100	.66	.60 <u>0</u> 9.	9.71 9	16.91	1480	1480	0 0	_
MobileNetV2	0.511	99.80	99.80	99.80	99.80	99.80	66.66	99.80	.66	.26 99	9.43 9	9.71	1477	1477	33	
NASNetMobile	0.068	98.04	98.04	98.04	98.04	98.04	99.73	98.04	96	.46 97	7.17 9	98.02	1447	1447	29 29	6



Fig. 11 Graphical summarization of the performance metrics concerning the "Breast Cancer Dataset" dataset



Fig. 12 Graphical summarization of the performance metrics concerning the "Dataset\_BCD\_mammography\_images\_out" dataset



THE "BREAST CANCER PATIENTS MRI'S" PERFORMACE METRICS GRAPHICALSUMMARIZATION

Fig. 13 Graphical summarization of the performance metrics concerning the "Breast Cancer Patients MRI's" dataset

Optimizer is used for the choice of the different hyperparameters of the various CNN architectures. For training purposes, three different datasets with different modalities are used to allow the diagnosis of breast cancer. Due to the differences in the datasets, a different number of classes for each type is available. Therefore, the suggested framework can perform both binary- and multi-class classification. The used performance metrics are Accuracy, Recall, Precision, Specificity, F1-score, AUC, Sensitivity, IoU coef., dice coef., TP, TN, FP, FN, and cosine similarity. the proposed framework can achieve a classification accuracy of 100% on MRI images. From the different segmentation methods, the best-recorded segmentation accuracy is 95.58% using Attention U-Net. However, the main limitations of the current work are: (1) limitation of data for training and (2) segmentation was applied to

Table 12 A Comparative study among the proposed framework and the related studies

Study	Year	Dataset	Approach	Best accuracy (%)
Mehra (2018)	2018	BreakHis	VGG-16 with LR	92.60
Gao et al. (2018)	2018	A dataset from Mayo Clinic and a dataset from INbreast	Shallow-Deep CNN	90
Dabeer et al. (2019)	2019	BreakHis	CNN	99.86
Alghodhaifi et al. (2019)	2019	Kaggle Breast Histopathology Images dataset	IDCNet with ReLU	87.13
Saikia et al. (2019)	2019	FNAC cell sample images of 20 patients in India	Fine tuned GoogLeNetV3	96.25
Ismail et al. (2019)	2019	Mammography images from IRMA database	VGG16	94
Chorianopoulos et al. (2020)	2020	Breast Cancer Ultrasounds Dataset, Invasive Ductal Carci- noma (IDC) Dataset 1, and IDC Dataset 2	VGG16	96.82
Hameed et al. (2020)	2020	Histopathology images collected from 80 patients	Fine tuned VGG19	92
Salama and Aly (2021)	2021	MIAS, DDSM, and CBIS-DDSM	InceptionV3	93.85
Wang et al. (2021)	2021	Rectified Patch Camelyon (RPCam) dataset	Boosted EfficientNet-B3	97.96
Sharma and Kumar (2021)	2021	BreakHis	DenseNet201	95.58
Melekoodappattu et al. Mele- koodappattu et al. (2022)	2022	MIAS and DDSM	CNN and image texture attribute extraction	98
Current study	2022	Breast Cancer Dataset	Hybrid (Classification)	98.95
Current study	2022	Dataset_BCD_ mammography_images_out	Hybrid (Classification)	95.78
Current study	2022	Breast Cancer Patients MRI's	Hybrid (Classification)	100
Alom et al. Alom et al. (2018)	2018	Dataset from the 2018 Data Science Bowl Grand Challenges	Recurrent Residual U-Net	92.15
Dalmia et al. (2018)	2018	Anonymized data of 180 subjects	V-Net	99.6
El Adoui et al. (2019)	2019	MRI database collected by their institution	U-Net	76.14
Li et al. (2019)	2019	DDSM of X-ray mammography	DenseNet	77.93
Byra et al. (2020)	2020	Dataset of 882 breast mass US images	U-Net	97.6
Salama and Aly (2021)	2021	MIAS, DDSM, and CBIS-DDSM	Modified U-Net model	N/A
Current study	2022	Breast Ultrasound Images Dataset	Hybrid (Segmentation)	95.58

ultrasonic data only. As future work, we will apply the segmentation techniques to other types of images, namely MRI images. We also hope to apply other different optimization techniques such as the Red Deer algorithm (RDA) and Sine Cosine Algorithm (SCA). We also aim to use the suggested hybrid framework in other different medical imaging problems.

**Funding** Open access funding provided by The Science, Technology & Innovation Funding Authority (STDF) in cooperation with The Egyptian Knowledge Bank (EKB).

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