ORIGINAL PAPER

A new damage model accounting the effect of joint orientation for the jointed rock mass

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Received: 1 August 2019 / Accepted: 3 March 2020 /Published online: 25 March 2020 \odot Saudi Society for Geosciences 2020

Abstract

Damage accumulation in the rock mass leading to failure is influenced by the properties of pre-existing discontinuities. In order to simulate rock mass behaviour realistically, many damage models have been proposed. Amongst them, limited damage models consider joint orientation, one of the significant properties of discontinuities impacting the rock mass failure, in the strongly anisotropic rock masses. In this study, we propose a statistical damage model using the Weibull distribution which takes into account joint orientation by incorporating the Jaeger's and modified Hoek-Brown failure criteria for jointed rock masses. The proposed statistical damage model is validated using experimental results. Furthermore, verification of the proposed model is conducted by distinct element method using Particle Flow Code (PFC). To investigate the influence of the shape parameter (m) and scale parameter (F_0) of the Weibull distribution on the statistical damage model predictions, a sensitivity analysis is carried out. It is found that the parameter m only depends on strain parameter k. On the other hand, the parameter F_0 is indirectly related to the failure strength of the jointed rock mass in the proposed damage model. Considerable influence of joint stiffness on the damage variable D , damage evolution rate D_r and rock mass responses are also identified.

Keywords Damage model .Joint orientation .Jointed rock mass . Bonded particle model

Abbreviations

Responsible Editor: Zeynal Abiddin Erguler

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Introduction

The deformation behaviour of rock material is a fundamental topic in rock engineering (Li et al. [2012;](#page-11-0) Peng et al. [2015\)](#page-11-0). Accurate estimation of rock strength and deformation properties is critical for the stability analysis of rock engineering applications such as rock slopes, rock tunnels and underground excavations. In nature, the rock mass consists of intact rock and discontinuities such as bedding planes, joints and cleavages. The strength and the mechanical properties of the rock mass are controlled by the mechanical and geometrical properties of the discontinuities and intact rocks (Guo et al. [2017;](#page-11-0) Jin et al. [2016](#page-11-0); Tiwari and Rao [2006](#page-11-0); Wasantha et al. [2015;](#page-11-0) Yang et al. [1998](#page-11-0); Zhou et al. [2014](#page-12-0)). In this study, the rock mass is defined as the intact rock separated by the joints, bedding planes, folds etc. at the lab- or in-situ-scale. Therefore, the deformation behaviours of the rock mass can be largely influenced by the geometrical and mechanical properties of joints, especially for anisotropic rock mass.

Many experimental investigations (Chen et al. [2016](#page-11-0); Donath [1961](#page-11-0); Hoek [1964](#page-11-0); Jiang et al. [2014;](#page-11-0) Jin et al. [2016](#page-11-0); Mclamore and Gray [1967;](#page-11-0) Prudencio and Van Sint Jan [2007](#page-11-0); Ramamurthy et al. [1988](#page-11-0); Yang et al. [1998\)](#page-11-0) published characterized deformation properties and failure mechanisms in anisotropic rock masses. The results from these studies indicate that the failure strength and deformation are closely associated with joint orientation or bedding orientation (see Fig. 1). The corresponding joint orientation is also demonstrated in Fig. 1. The failure strength reaches its maximum value at $\beta = 90^{\circ}$, while its minimum value located around $\beta = 60^{\circ}$. Three failure modes are observed in the experimental results (Tien and Tsao [2000\)](#page-11-0): sliding mode along the discontinuity or joint, shearing mode along the intact rock and mixed-mode. These laboratory results lay the foundation for failure analysis of anisotropic rock masses.

To describe the stress-strain relationship for rock materials, the statistical damage model (SDM) has been widely employed for different applications based on the statistical theory and continuum damage mechanics. The SDM was first proposed by Krajcinovic and Silva [\(1982\)](#page-11-0) to reflect the process of micro-crack initiation, propagation, and coalescence and was employed to explore the damage process of concretes. Later, the concept of SDM was adopted and extended to grasp the complicated behaviours of rocks (Cao et al. [2018;](#page-11-0) Cao et al. [2010;](#page-11-0) Deng and Gu [2011;](#page-11-0) Li et al. [2012](#page-11-0); Liu

Fig. 1 Behaviour of rock-like materials with different joint orientation (after Jin et al. [2016](#page-11-0))

and Yuan [2015;](#page-11-0) Tang et al. [1998](#page-11-0)). The initial damage (crack closure stage) was identified and modelled by introducing initial voids (Cao et al. [2018](#page-11-0)) and dissipated energy corresponding to the initial damage (Yang et al. [2015](#page-12-0)). The residual strength of rocks induced by the confining pressure was further considered by different researchers. For example, a coefficient C_n was introduced by Wang et al. [\(2007\)](#page-11-0) to improve the description of residual strength. Zhao et al. ([2016](#page-12-0)) adopted the damage tolerance principle to reflect the residual strength of the rocks. The impact on the mechanical properties of rocks was captured by the SDM using the coefficient of viscosity (Li et al. [2015](#page-11-0)) and over-stress model (Zhao et al. [2014\)](#page-12-0).

To address the anisotropic characteristics of the jointed rock mass, which may be vital to the stability of slopes and caverns (Hudson and Harrison [2000](#page-11-0); Jia et al. [2012;](#page-11-0) Kostić [2017\)](#page-11-0), the damage tensors were employed in SDM in most cases. Kawamoto et al. ([1988\)](#page-11-0) and Swoboda et al. [\(1998](#page-11-0)) adopted a second-order damage tensor to reflect rock mass anisotropy due to pre-existing joints. In their damage models, geometrical parameters of joints such as orientation, length and density were used to describe the anisotropic characteristics of the jointed rock mass. Recently, based on these works, Yang et al. [\(2019\)](#page-12-0) employed the normal vector and area of joints to describe the joints based on damage mechanics. However, in strongly anisotropic materials, these models do not correctly describe the failure modes: shear failure in the intact rock matrix and sliding failure along the joint and thus they may underestimate the strength of the rock mass (Liu and Yuan [2015\)](#page-11-0). Therefore, it is still necessary to develop a new damage model for the jointed rock mass considering the joint orientation and failure modes.

In this paper, inspired by the previous studies mentioned above, a new statistical damage model for a rock mass considering joint orientation is derived based on the Weibull distribution. Fundamentals of the statistical damage model and its derivation are explained in "[Statistical damage model](#page-2-0)"

section. Validation and verification of the proposed damage model are presented in "[Validation and verification of the](#page-5-0) [proposed damage model](#page-5-0)" section. Particle Flow Code used for verification is explained in "[Validation and verification](#page-5-0) [of the proposed damage model](#page-5-0)" section. Finally, a sensitivity analysis for the damage distribution parameters and rock mass response is carried out in "[Sensitivity analysis of damage dis](#page-6-0)[tribution parameters and the damage variables and rock mass](#page-6-0) [response](#page-6-0)" section.

Statistical damage model

Damage model development

Conceptually, a rock is composed of a large number of microscopic elements. When the rock is subjected to external loading, microscopic elements will fail, and defects or microcracks are created, which then coalesce to form macro-cracks. This is basically the damage accumulation process taking place in the rock as a response to an external load. Statistically, the strength of these microscopic elements can follow a certain type of distribution with the most commonly suggested ones as power function distribution and Weibull distribution. Therefore, a statistical approach may better describe the mechanical behaviour of rocks at the micro-level (Deng and Gu [2011\)](#page-11-0).

The Weibull distribution used to describe the distribution of the strength of microscopic elements in the damage model can be written as:

$$
P(F) = \frac{m}{F_0} \left(\frac{F}{F_0}\right)^{m-1} \exp\left[-\left(\frac{F}{F_0}\right)^m\right] \tag{1}
$$

where F is the element strength parameter depending on the failure criterion used, which can be regarded as stress level when strength criterion (Zhou et al. [2017\)](#page-12-0) is used or strain when maximum strain criterion (Liu and Yuan [2015](#page-11-0)) is adopted; m is the shape parameter or a homogeneous index of Weibull distribution; F_0 is the scale parameter of the Weibull distribution.

Assuming N is the number of all microscopic elements within the rock and n denotes the number of failed microscopic elements under a certain external load, the damage variable D (between 0 and 1) can be directly defined as (Tang and Kaiser [1998](#page-11-0)):

$$
D = \frac{n}{N} \tag{2}
$$

If all microscopic elements are subjected to the same local stress of F , the total failed microscopic elements n can be calculated as:

$$
n = N \int_0^F P(F) dF = N \left\{ 1 - \exp \left[- \left(\frac{F}{F_0} \right)^m \right] \right\}
$$
 (3)

i.e., the damage variable D can be expressed as:

$$
D = 1 - \exp\left[-\left(\frac{F}{F_0}\right)^m\right] \tag{4}
$$

Under biaxial compression, two effective stresses (σ_1 , σ_3) of the rock mass can be expressed using nominal stresses (σ_1 , σ_3):

$$
\sigma_i^* = \sigma_i / (1 - D) \tag{5}
$$

with $i = 1, 3$.

According to the generalized Hooke's law and the damage, the strain can be expressed as:

$$
\varepsilon_1 = \frac{1}{E} \left(\sigma_1^* - \nu \sigma_3^* \right) = \frac{1}{E(1-D)} \left(\sigma_1 - \nu \sigma_3 \right) \tag{6}
$$

where ν is the Poisson's ratio of the material. Substituting Eq. (4) into Eq. (6), the stress-strain relationship is obtained on the major principal stress direction:

$$
\sigma_1 = E \varepsilon_1 \exp\left[-\left(\frac{F}{F_0}\right)^m\right] + \nu \sigma_3 \tag{7}
$$

As an example to demonstrate this model, the damage variable D, $E = 50$ GPa, $\sigma_3 = 0$ MPa and $F_0 = 0.01$ with maximum strain criterion were adopted here and the results are plotted in Fig. [2](#page-3-0) for different m values. As can be seen, a higher value of *corresponds to narrower distribution of the element* strengths, hence greater variation in damage variable D against strain and a sharper decrease of the stress after the peak load. In other words, when *m* value is increased, the rock behaves in a more brittle fashion, and its strength increases accordingly.

Next, the strength of the microscopic elements must be determined. As shown in Fig. [2,](#page-3-0) the maximum strain criterion can be used to describe the microscopic element strength. However, it could not reflect the influence of complicated stress state of the microscopic element. Therefore, many studies (Deng and Gu [2011](#page-11-0); Li et al. [2012](#page-11-0); Xu and Karakus [2018](#page-11-0)) tried to consider the rock failure criterion for a microscopic element in stress space and proposed new expressions for the microscopic element. In general, the failure criterion of the microscopic element can be expressed in the following form:

$$
f(\sigma^*) - k_0 = 0 \tag{8}
$$

where k_0 is a constant value related to the cohesion and internal friction angle of the rock. $F = f(\sigma^*) = f(\sigma)/(1 - D)$ reflects the strength of microscopic element, depending on the failure criteria adopted in the damage model.

Fig. 2 Microscopic damage variable and the strength of intact rock. a Damage variable vs. strain. b Corresponding stress-strain response

Rearranging Eq. ([6\)](#page-2-0), one can obtain:

$$
1-D = \frac{(\sigma_1 - \nu \sigma_3)}{E \varepsilon_1} \tag{9}
$$

Then substituting in Eq. [8,](#page-2-0) the following equation can be obtained:

$$
F = \frac{f(\sigma)}{\sigma_1 - \nu \sigma_3} E \varepsilon_1 \tag{10}
$$

To derive the rock mass response and calculate damage variable D , the damage parameters m and F_0 should be determined. In this process, the 'Extremum method' was used in previous studies (Cao et al. [2010;](#page-11-0) Deng and Gu [2011](#page-11-0)), where the peak point of the measured stress-strain curve can be used. At the peak point, the derivative of σ_1 with corresponding ε_1 should be zero, i.e.:

$$
\varepsilon_1 = \varepsilon_{1f}, \sigma_1 = \sigma_{1f} \tag{11}
$$

$$
\frac{d\sigma_1}{d\varepsilon_1} = 0\tag{12}
$$

where σ_{1f} and ε_{1f} are stress and strain corresponding to the peak point. Based on the Eq. (12), one can obtain:

$$
m\varepsilon_1 \left(\frac{F}{F_0}\right)^{m-1} \frac{1}{F_0} \frac{dF}{d\varepsilon_1} = 1
$$
\n(13)

From Eq. (9), one can easily obtain the following equation:

$$
\frac{dF}{d\varepsilon_1} = \frac{f(\sigma)}{\sigma_1 - \nu \sigma_3} E = \frac{F}{\varepsilon_1} \tag{14}
$$

Then the distribution parameter m and F_0 can be calculated by substituting Eqs. (13) and (11) into Eq. (7) (7) (7) :

$$
m = \frac{1}{\ln(E\varepsilon_{1f}/(\sigma_{1f} - \nu \sigma_3))}
$$
(15)

$$
F_0 = \sqrt[m]{m} F_f, \varepsilon_1 = \varepsilon_{1f} \tag{16}
$$

Implementation of failure criteria into the proposed damage model

Appropriate failure criterion should be determined for the microscopic elements in the damage model (Xu and Karakus [2018\)](#page-11-0). Due to the pre-existing joint, the commonly used failure criteria should be modified to account for the influence of joint orientation. In nature, the anisotropic rock masses demonstrated the anisotropic characteristics due to various forms of weakness and generally can be divided into two groups: the rock masses with a strong discontinuity or a set of parallel joints and the inherently anisotropic rock masses. Therefore, two failure criteria including Jaeger's criterion and Hoek-Brown criterion are integrated into the proposed damage model.

Jaeger's failure criterion

We used Jaeger's failure criterion to derive the damage parameters for the Weibull damage model:

$$
\sigma_1 = \begin{cases}\n\frac{1 + \sin\phi}{1 - \sin\phi} \sigma_3 + \frac{2c \cos\phi}{1 - \sin\phi}, & \beta < \phi_j \text{ or } \beta = 90^\circ \\
\sigma_3 + \frac{2c_j + 2\sigma_3 \tan\phi_j}{\sin 2\beta \left(1 - \tan\phi_j \tan\beta\right)}, & \phi_j \le \beta < 90^\circ\n\end{cases} \tag{17}
$$

where c and ϕ are cohesion and internal friction angle of the rock; c_j and ϕ_j are joint cohesion and friction angle, respectively, and β is the joint orientation (the angle of the joint from the plane perpendicular to the loading direction). Then the strength of microscopic element in stress space can be expressed in the following equation:

We can derive the stress-strain relationship by substituting Eq. [\(18\)](#page-3-0) into Eq. [\(7](#page-2-0)):

$$
\sigma_1 = \begin{cases} E\varepsilon_1 \exp\left[-\left(\frac{F_1}{F_0}\right)^m\right] + \nu \sigma_3, \beta < \phi_j \text{ or } \beta = 90^\circ\\ E\varepsilon_1 \exp\left[-\left(\frac{F_2}{F_0}\right)^m\right] + \nu \sigma_3, \ \ \phi_j \leq \beta < 90^\circ \end{cases} \tag{19}
$$

where F_1 and F_2 are the expression of microscopic strength derived in Eq. ([18\)](#page-3-0).

Modified Hoek-Brown criterion

Here, the modified Hoek-Brown model proposed by Saroglou and Tsiambaos (Saroglou and Tsiambaos [2008\)](#page-11-0) incorporating the anisotropic parameter $k_β$ of rock mas is used:

$$
\sigma_1 = \sigma_3 + \sigma_c \left(k_\beta m_i \frac{\sigma_3}{\sigma_c} + 1 \right)^{0.5} \tag{20}
$$

where m_i is a Hoek-Brown constant, depending on the rock type (texture and mineralogy) (Shen and Karakus [2014](#page-11-0)), σ_c is the uniaxial compressive strength of the intact rock. Then failure strength of microscopic element using the Hoek-Brown criterion can be expressed in the following equation:

$$
F = \frac{\sqrt{(\sigma_1 - \sigma_3)^2 - k_\beta m_i \sigma_c \sigma_3}}{\sigma_1 - \nu \sigma_3} E \varepsilon_1
$$
 (21)

Accordingly, the stress-strain relationship can be expressed as:

$$
\sigma_1 = E\varepsilon_1 \exp\left[-\left(\frac{\frac{\sqrt{(\sigma_1-\sigma_3)^2 - k\beta m_i \sigma_c \sigma_3}}{T_0}}{F_0}\right)^m\right] + \nu \sigma_3 \qquad (22)
$$

Damage model implementation

In order to implement the proposed damage model for further analysis, the basic material parameters such as cohesion (c), internal friction angle (ϕ), joint cohesion (c_i), joint friction angle (ϕ_i) and joint orientation (β) should be identified first. Then the failure stress σ_{1f} , deformation modulus E_β and failure strain ε_{1f} should be determined to derive the damage distribution parameters m and F_0 . We can estimate the failure stress σ_{1f} from Eqs. [\(17\)](#page-3-0) and (20). However, the deformation modulus $E_β$ of the jointed rock mass is influenced by the joint orientation, which can be estimated through the following equation (Gao et al. [2016\)](#page-11-0):

$$
\frac{1}{E_{\beta}} = \frac{1}{E} + \cos^2 \beta \left(\frac{\cos^2 \beta}{\delta k_n} + \frac{\sin^2 \beta}{\delta k_s} \right)
$$
 (23)

where δ is a mean vertical spacing interval in rock that contains a single set of joints; k_n and k_s are the normal stiffness and shear stiffness on the weak planes, respectively. On the other hand, the failure strain ε_{1f} is related to the failure stress σ_{1f} and the deformation modulus E_{β} :

$$
\varepsilon_{1f} \propto \frac{\sigma_{1f}}{E_{\beta}} \tag{24}
$$

Due to the existing crack closure and unstable crack growth stages, the failure strain is larger than $\frac{\sigma_{1f}}{E_{\beta}}$. Therefore, to better estimate the failure strain, a strain parameter k is introduced here, and the failure strain can be estimated using the following equation:

$$
\varepsilon_{1f} = (1+k)\frac{\sigma_{1f}}{E_{\beta}}\tag{25}
$$

where k depends on the plastic strain of the material, which will be discussed in "[Sensitivity analysis of damage distribu](#page-6-0)[tion parameters and the damage variables and rock mass re](#page-6-0)[sponse](#page-6-0)" section.

The implementation procedure for the proposed damage model is summarized as follows, see Fig. [3:](#page-5-0)

- (1) Obtain the basic material parameters: rock cohesion c, internal friction angle ϕ , joint cohesion c_j , joint friction angle ϕ_i and joint orientation β for the damage model incorporating Jaeger's criterion; anisotropic parameter k_{β} and Hoek-Brown constantm_i for the damage model incorporating the modified Hoek-Brown criterion;
- (2) Estimate failure stress σ_{1f} , deformation modulus E_β and failure strain ε_{1f} through Eqs. [\(17](#page-3-0)) or (20), (23) and (25), respectively;
- (3) Obtain damage distribution parameters m and F_0 through Eqs. (15) (15) and (16) (16) ;
- (4) Substitute damage distribution parameters m and F_0 into Eq. (19) or (22) to obtain the stress-strain response.

Fig. 3 Flow chart for damage model implementation

Validation and verification of the proposed damage model

Validation of the proposed damage model

To validate the proposed damage model, the damage model is applied to a group of published experimental data on jointed basalt (Jin et al. [2016\)](#page-11-0) using modified Hoek-Brown criterion. In the experimental test, rock-like material, a mixture of water, river sand and gypsum, was prepared to model the columnar jointed basalt. The joint orientation varies while the joint roughness is kept smooth in the experimental study. The results of the damage model, obtained from Eq. ([7\)](#page-2-0), with different joint orientation is presented in Fig. 4, and the corresponding experimental results are also shown for comparison purpose. One can see that the proposed model is capable of describing the main deformation and strength properties of the jointed rock mass, especially the pre-peak region. However, the rock mass responses from the proposed damage model cannot capture the rock compaction characteristics in the initial stage of rock mass response when joint orientation <30°. The rock compaction in the initial stage of rock mass response relates to the crack closure when joint orientation <30°. The damage variable D may be modified in future study to capture this phenomenon.

Verification of the proposed damage model by PFC

The proposed damage model is verified by comparison of the stress-strain response of a rock mass from the proposed model and results are obtained from the bonded particle model, PFC in this study. The synthetic rock mass (SRM) model consists

b Joint orientation 45° , 60° , 75° and 90° .

Fig. 4 Comparison of the proposed damage model and experimental results (Jin et al. [2016\)](#page-11-0) for the jointed rock mass with various joint orientations. a Joint orientation 0°, 15° and 30°. b Joint orientation 45°, 60°, 75° and 90°

of two components to represent intact rock and discontinuities (Mas Ivars et al. [2011](#page-11-0)). Intact rock can be represented by bonded particle model (BPM) (Potyondy and Cundall [2004\)](#page-11-0) material which is non-uniform circles or particles assembly connected through contacts. For the current study, the flat joint model (FJM) is employed to simulate a more realistic intact rock, especially for brittle rocks (Vallejos et al. [2016](#page-11-0); Zhou et al. [2019,](#page-12-0) [2018](#page-12-0)). On the other hand, the smooth joint model (SJM) is implemented into the flat joint contacts to represent joint in PFC.

Intact rock representation

In this study, the Hawkesbury sandstone was chosen for the verification study. A rectangular numerical model of 54 mm \times 108 mm containing random non-uniform particles assembly was subjected to uniaxial compression tests to obtain macroproperties for calibration. The loading rate is set to small enough (0.02 m/s) to ensure the quasi-static loading condition (Zhang and Wong [2014,](#page-12-0) [2013\)](#page-12-0).

The PFC parameters calibrated using experimental data reported by Wasantha et al. ([2013](#page-11-0)), and are given in Table 1. A good agreement between experimental and PFC model results was achieved, where the coefficient of variation (COV) was found to be less 1%. The calibrated micro-parameters for Hawkesbury sandstone are summarized in Table [2](#page-7-0). Figure [5](#page-7-0) shows the intact rock response of UCS tests conducted in PFC.

Joint representation

To simulate the behaviour of the joint within a rock mass, the smooth joint contact model was proposed by Pierce et al. [\(2007\)](#page-11-0) and explored in detail by Mas Ivars et al. [\(2008\)](#page-11-0). The smooth joint model provides the behaviour of a planar interface with dilation regardless of the local particle contact orientations along with the interface. The two particles using a smooth joint contact model may slide past each other instead of moving around each other of FJM.

Generally, these macro-properties include normal stiffness, shear stiffness, cohesion and friction angle, and are governed by smooth joint micro-parameters such as bond normal stiffness, bond shear stiffness, bond cohesion and friction angle at the particle level. Bahaaddini et al. ([2013](#page-11-0)) proposed a twostage calibration procedure: normal deformability test for normal stiffness calibration and direct shear test for the shear

stiffness and coefficient of friction calibration, and using the ISRM suggested method (Ulusay [2014](#page-11-0)) (see Fig. [6](#page-8-0)).

In this study, normal stiffness and shear stiffness are set large to minimise their effect on mechanical properties, and the only direct shear test was carried out to match the cohesion and friction angle of Hawkesbury sandstone, which is 2.2 MPa and 32°. The corresponding calibrated cohesion and joint friction angle are 2.19 MPa and 31.79°, respectively. And the calibrated micro-parameters for the smooth-joint model are summarized in Table [3](#page-8-0).

Simulation of a single-jointed rock mass by PFC

In order to verify the proposed damage model, the PFC models with different joint orientations using 0°, 40°, 50°, 60° and 90° are subjected to the uniaxial compression tests. The correctness and robustness of the numerical model were confirmed in our previous study (Zhou et al. [2019](#page-12-0)). The comparison of the proposed Weibull damage model and the results from the PFC analysis are shown in Fig. [7.](#page-9-0)

The failure stress of rock mass model when joint orientation $\beta = 0^{\circ}$ drops to 46.88 MPa, which is consistent with the experimental results (Wasantha et al. [2013\)](#page-11-0) when one persistent joint exists in the intact specimen. The comparison shows that the proposed damage model is in good agreement with the PFC results at both the pre-peak and post-peak regions. As can be seen from Fig. [7](#page-9-0), the proposed damage model can capture the stress-strain response better at pre-peak region than the post-peak region.

Sensitivity analysis of damage distribution parameters and the damage variables and rock mass response

The damage variables in the proposed damage model are largely influenced by the joint orientation based on the analysis presented in "[Statistical damage model](#page-2-0)" section. Taking the stress-strain in the direction of the major principal strain as an example, we considered $E = 11.00 \text{ GPa}$, $\sigma_{(90)} = 46.88$ MPa, $\sigma_3 = 0.00$ MPa, $\nu = 0.20$, $k = 0.2$, $c_i =$ 6.00 MPa and $\phi_i = 0^\circ$ as the reference parameters for sensitivity analysis.

Table 1 Mechanical properties of Hawkesbury sandstone (Wasantha et al. [2013](#page-11-0)) and calibrated BPM material

Table 2 Basic calibrated microparameters for Hawkesbury sandstone (Zhou et al. [2018\)](#page-12-0)

Damage distribution parameters

Damage distribution parameter m

As mentioned in "[Statistical damage model](#page-2-0)" section, the damage distribution parameter m is an indicator of material brittleness: more brittle as the damage distribution parameter m becomes larger. Substituting Eq. (25) (25) into Eq. (15) (15) , we can see that the damage distribution parameter only depends on parameter k:

$$
m = \frac{1}{\ln(1+k)}\tag{26}
$$

The result (see Fig. [8\)](#page-9-0), shows that damage distribution parameter m is nonlinear and indirectly proportional to the strain parameter k for the jointed rock mass. As the parameter k is directly proportional to the increase of the failure strain, we confirm that the material becomes more brittle as the failure strain becomes smaller. The parameter k should be

Fig. 5 Intact rock behaviour under uniaxial compression in PFC

carefully chosen according to the material brittleness when the failure strain data is not available.

Damage distribution parameter F_0

The influence of the model parameters listed as the reference parameters previously on the damage distribution parameter $F₀$ is analysed by changing one of the corresponding parameters and leaving the other parameters constant.

The effects of confining stress, joint cohesion and joint friction angle on the damage distribution parameter F_0 is demonstrated in Fig. [9a, b, and c](#page-9-0), respectively. The results show that the damage distribution parameter F_0 follows the 'U' shape with various joint orientation, reaching the minimum value when joint orientation equals to $45 + \phi_i/2$.

The confining stress can increase the level of damage distribution parameter as confining stress increases from 0 to 20 MPa (see Fig. [9a](#page-9-0)). However, it has a larger influence on F_0 when joint orientation $\beta = 0^\circ$ and $\beta = 90^\circ$ but smaller influence when joint orientation $0^{\circ} < \beta < 90^{\circ}$. This is due to the fact that two failure modes occur: shear failure when joint orientation $\beta = 0^{\circ}$ and $\beta = 90^{\circ}$ and sliding failure when joint orientation 0 $^{\circ}$ < β < 90 $^{\circ}$.

The joint cohesion effect on F is investigated by increasing cohesion from 2 to 10 MPa (see Fig. [9b\)](#page-9-0). The maximum value of F_0 is independent with different joint cohesion as the maximum failure strength keeps unchanged with a certain confining condition. On the other hand, joint cohesion can increase the values of F_0 when it is less than the maximum value of F_0 . As joint cohesion increases, the F_0 gradually reaches its maximum value when joint orientation approaching to horizontal and vertical directions.

The joint friction angle effect on F_0 is analysed by varying from 0 to 40° (see Fig. [9c](#page-9-0)). Similarly, the joint friction angle has no influence on the maximum value of F_0 . The interval of 'U' shape narrows from smaller joint orientation as joint

Fig. 6 Calibration of smooth-joint micro-parameters for PFC analysis. (a) Uniaxial compression test. (b) Direct shear test

friction angle increases. At the same time, the joint friction angle can increase the value of F_0 when it is less than the maximum value. Overall, the F_0 can be regarded as a strength parameter, indirectly related to the failure strength of the jointed rock masses.

Influence of joint stiffness on the damage variable and rock mass response

Based on derived damage distribution parameters m and F_0 , the rock mass response will be influenced by the joint orientation. However, as pointed out earlier in "[Damage model](#page-4-0) [implementation](#page-4-0)" section, the joint stiffness may have effects on the rock mass response, which was ignored by the previous studies (Liu and Yuan [2015;](#page-11-0) Zhang et al. [2015\)](#page-12-0).

Invoking Eq. (23) (23) , the deformation modulus of the rock masses varies with joint orientation. When the δ and stiffness ratio (normal stiffness/shear stiffness) are set to 1 m and 0.5, respectively, we plot the deformation modulus versus joint orientation as the normal stiffness increases from 10 to 200 GPa (see Fig. [10\)](#page-10-0). The results show that the deformation modulus decreases as the joint orientation becomes smaller. The joint stiffness has a larger influence on the deformation modulus when the jointed rock mass with small joint orientation than those with larger joint orientation, even has no influence when the joint orientation equals to 90°.

To better investigate the joint stiffness effect, based on the theoretical analysis, using the parameters of the reference, the rock mass response, damage variable D and damage evolution rate D_r curves with and without considering the joint stiffness are plotted in Fig. [11](#page-10-0). When the joint stiffness effect on the D , D_r and rock mass response is ignored, the deformation modulus of the jointed rock mass equals to Young's modulus of intact rock. The results reveal that all the damage variable D, damage evolution rate D_r and rock mass response curves of the model with 0°. 10°, 20°, 30° and 40° overlap with those models with 90°, 80°, 70°, 60° and 50°, respectively. The failure strength varies with varying joint orientation when deformation modulus is kept constant. The damage variable D curve becomes steeper, and the starting damage point appears earlier as joint orientation approaching 40° and 50°. Correspondingly, the maximum value of D_r becomes smaller as the joint orientation approaching 40[°] and 50[°].

The joint normal stiffness is set to 50 GPa when considering the joint stiffness. One can easily see that the deformation modulus varies from the stress-strain curves, consisting of the experimental results given in "[Validation](#page-5-0) [of the proposed damage model](#page-5-0)" section. The results demonstrate that damage variable D curve becomes steeper, and the starting point of damage variable D appears earlier as the joint stiffness increases. Additionally, the peak value of damage evolution rate D_r becomes larger with

Table 3 Calibrated microparameters for the smooth-joint model

b Joint orientation 60° and 90°.

Fig. 7 Comparison of the proposed damage model and PFC model predictions for the jointed rock mass with various joint orientation. a Joint orientation 0°, 40° and 50°. b Joint orientation 60° and 90°

Fig. 8 Damage distribution parameter m versus parameter k

Fig. 9 Influence of a confining stress, b cohesion and c joint friction angle on the damage distribution parameter F_0

increasing joint stiffness. Therefore, the proposed damage model considering joint stiffness can better capture the deformation and strength behaviours compared with the damage model without considering joint stiffness.

Conclusions

In this paper, we proposed a new damage model which uses the Jaeger's and modified Hoek-Brown criteria. The damage distribution parameters m and F_0 were modified to reflect the

Fig. 10 Influence of joint stiffness on the deformation modulus of the rock masses

effect of joint orientation on the rock mass failure behaviour. This way, we can simulate the jointed rock mass behaviours with various joint orientations realistically. Additionally, the deformation modulus variation caused by the joint stiffness can be considered in the damage model by introducing the deformation modulus from Eq. [\(23](#page-4-0)). Based on this research, the following conclusions are obtained:

- (1) The shape parameter m was only related to the introduced strain parameter k , reflecting the brittleness of the anisotropic rock mass;
- (2) The damage variable D and rock mass response demonstrated an anisotropic characteristic for the damage model with various joint orientations. The damage variables and stress-strain curves for with the orientations of 0°, 10°, 20°, 30° and 40° coincided with those of 90°, 80°, 70°, 60° and 50°, respectively, when joint stiffness was ignored in the proposed damage model.
- (3) The proposed damage model can reflect the failure modes of the jointed rock mass if the Jaeger's criterion was employed. Therefore, it improves the prediction of

Fig. 11 Influence of joint stiffness on rock mass response, damage variable D and damage evolution rate D_r for rock masses with different joint orientation

rock mass response significantly; thus, the proposed model can be used to simulate anisotropic rock mass behaviour accurately.

Acknowledgments The PhD scholarship provided by the China Scholarship Council (CSC) to the first author is gratefully acknowledged.

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