

Nanofluid thin film flow and heat transfer over an unsteady stretching elastic sheet by LSM†

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Abstract

This study is carried out on the unsteady flow and heat transfer of a nanofluid in a stretching flat plate. Least square method is implemented for solving the governing equations. It also attempts to demonstrate the accuracy of the aforementioned method compared with a numerical one, Runge-Kutta fourth order. Furthermore, the impact of some physical parameters like unsteadiness parameter (S), Prandtl number (Pr) and the nanoparticles volume fraction (ϕ) on the temperature and velocity profiles is scrutinized carefully. Accordingly, the results obtained from this study reveal that the temperature enhances by means of augmenting the nanoparticles volume fraction. At $\eta \in$ $\{0, 0.5\}$, the velocity decreases as a result of a rise in nanoparticles volume fraction and at $\eta \in \{0.5, 1\}$, an opposite treatment takes place. Moreover, velocity distribution augments by raising the S value, however an inverse trend is observed in temperature values. Moreover, the local skin friction coefficient indicated a notable rise by increasing the S parameter as well as a steady decrease by rising ϕ . Finally, water-Alumina nanofluid demonstrated better heat transfer enhancement compared to other types of nanofluids.

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Keywords: Least square method (LSM); Nanofluid volume fraction; Thin film nanofluid; Unsteady stretching elastic sheet

1. Introduction

Enhancement of heat transfer by the addition of nanosized particles to a base fluid is a fast-growing field of interest and its application in various industries from microchannel cooling and floor heating to heat recovery systems has thrived during the recent years. The nano-scaled particles have evoked specific attention as a consequence of barriers in pressure drop or making the mixture homogenous for all particle dimensions. Since these particles are approximately in the same size of the base fluid molecules, they highly perceive stable suspensions during a long period of time. Convective heat transfer characteristic of nanofluids depends on flow pattern, nanofluid volume fraction and geometrical configuration of the particles [1].

Initially, the term "nanofluid" was presented by Choi [2] who described the fluid consisted of nanoparticles dispersing in a fluid. Thereupon, Masuda et al. [3] pursued the concept of this analysis and eventually a substantial number of researches were remarkably implemented in this field of study. During recent years, nanofluids have been brought into service by

many industries and its analytical and numerical methods have inspired researchers in various fields of study [4-8].

For instance, Sheikholeslami et al. [9] looked over the performance of nanofluids between two rotating plates. They demonstrated that during injection and suction process, the rate of heat transfer could be improved by enhancing the volume fraction of nanoparticles. Furthermore, Hatami and Ganji [8] used the analytical Least square method (LSM) to study the role of Cu-water nanofluid flow in Microchannel heat sink (MCHS) cooling. Their proposed analytical method was then exerted in other heat transfer problems as well [10-13], by means of its simplicity and high accuracy. Consequently, Hatami and Ganji [13] probed the impact of variable magnetic field on the nanofluid flow behavior between two parallel disks. Besides, Domairry and Hatami [14] analyzed the impact of squeezing film of Cu-water nanofluid between parallel plates. In another investigation by Akbar and Nadeem [15], Homotopy Perturbation Method was applied to realize the motion of a MHD Jeffrey nanofluid in a channel. They [16] also took the initiative to employ the mentioned method to simulate the Phan-Thien-Tanner (PTT) nanofluid in a cylindrical coordinate system. Then, Nadeem et al. [17] reported a boundary layer formation when the velocity of viscid free-

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Fig. 1. The schematic diagram of the physical model.

stream is higher than stretching velocity.

Further studies are presented by Akbar et al. [18-22]. They added more complexity into the current nvestigations by considering the external magnetic field on nanofluids passing through a vertical stretching sheet. They studied different aspects including the effect of nanoparticle aggregation [18], exponential temperature-dependent viscosity [19] thermal radiation [20], double-diffusive natural convective boundarylayer flow [21] and permeable wall [22] in their models.

During the recent years, the wide application of Weighted residuals methods (WRMs) [23] including collocation, Galerkin and Least square method (LSM) attracted the researchers' attention looking for more reliable methods for solving the nonlinear differential equations. Stern and Rasmussen [24] solved the third order differential equation via the collocation method. Vaferi et al. [25] conducted an investigation into the practicability of resolving the diffusivity phenomenon in the transient flow passing the radial coordinates with the the Orthogonal collocation method. Latterly, Hatami et al. [26] made use of LSM for the porous fin problems with transverse magnetic field. Hatami and Ganji [27] detected that LSM is the most suitable analytical approach for nonlinear equations.

In the present study, the unsteady flow and the heat transfer of a nanofluid moving on a flat plate are studied and the nonlinear differential equations governing the presented system are solved by Least square method. Besides the impact of physical factors such as unsteadiness parameter (S), Prandtl number (Pr) and the volume fraction of nanofluids (ϕ) on the temperature and velocity distributions is explored thoroughly. *n* are solved by Least square method. Besides the impact of

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2. Problem description

In this research, it is considered that a nano-liquid film is flowing through a thin elastic sheet. The related physical model is outlined in Fig. 1.

It is assumed that the surface at $y = 0$ is stretched with the following velocity profile as:

$$
U_w = \frac{bx}{1 - \alpha t}.\tag{1}
$$

In the above equation, b and $α$ are constants. Finally, the profile of temperature on the sheet is formulated as follows:

$$
T_s = T_0 - T_r \left(\frac{bx^2}{2\nu_f}\right) (1 - \alpha t)^{-3/2}.
$$
 (2)

In Eq. (2), T_0 , T_r and v_f are the slit temperature, the reference temperature and kinematic viscosity of the base fluid. It is presumed that the gravitational effect is negligible and the film is stable and uniform. Therefore, according to the proposed mathematical model by Tiwari and Das [28], the differential equations governing are expressed as below: *d* Technology 32 (1) (2018) 177-183

Eq. (2), T₀, T_r and v_r are the slit temperature, the refer-

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ble and uniform.

$$
\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0.
$$
\n(3)

$$
\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial y} = \frac{\mu_{nf}}{\rho_{nf}} \frac{\partial^2 u}{\partial y^2}.
$$
 (4)

$$
\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} = \alpha_{w} \frac{\partial^{2} T}{\partial y^{2}}.
$$
 (5)

where the velocity components in *x* and *y* directions are shown by u and v, respectively. α_{nf} , ρ_{nf} and μ_{nf} are the thermal diffusivity, density and viscosity of nanofluid defined as: *n* $\frac{\partial x}{\partial t} + u \frac{\partial y}{\partial x} + v \frac{\partial y}{\partial y} = \alpha_{nf} \frac{\partial^2 T}{\partial y^2}$. (5)
 ne the velocity components in *x* and *y* directions are shown

and *v*, respectively. α_{nf} , ρ_{nf} and μ_{nf} are the thermal diffusion, density a

$$
\alpha_{n f} = \frac{k_{n f}}{(\rho C_p)_{n f}}, \rho_{n f} = (1 - \phi) \rho_f + \phi \rho_s, \mu_{n f} = \frac{\mu_{n f}}{(1 - \phi)^{2.5}}.
$$
 (6)

Afterwards:

d) (3)
\n
$$
\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0.
$$
 (3)
\n
$$
\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial y} = \frac{\mu_{sf}}{\rho_{sf}} \frac{\partial^2 u}{\partial y^2}.
$$
 (4)
\n
$$
\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} = \alpha_{sf} \frac{\partial^2 T}{\partial y^2}.
$$
 (5)
\nwhere the velocity components in *x* and *y* directions are shown
\nby u and v, respectively. α_{sf} , ρ_{sf} and μ_{sf} are the thermal diffi-
\nsivity, density and viscosity of nannfluid defined as:
\n
$$
\alpha_{sf} = \frac{k_{sf}}{(\rho C_{p})_{sf}}, \rho_{sf} = (1 - \phi)\rho_{f} + \phi \rho_{s}, \mu_{sf} = \frac{\mu_{sf}}{(1 - \phi)^{2s}}.
$$
 (6)
\nAfterwards:
\n
$$
(\rho C_{p})_{sf} = (1 - \phi)(\rho C_{p}) + \phi(\rho C_{p})
$$
,
\n
$$
\frac{k_{sf}}{k_{f}} = \frac{(k_{s} + 2k_{f}) - 2\phi(k_{f} - k_{s})}{(k_{s} + 2k_{f}) + \phi(k_{f} - k_{s})}.
$$
 (7)
\nwhere ϕ , k_{sf} and $(\rho C_{p})_{sf}$ are the volume fraction, thermal
\nconductivity and the heat capacitance of the manifold, respectively. Then, the related boundary conditions for the differential equation governing the mentioned system are defined as:
\nwhen $y = 0 \rightarrow u = U_{w}$, $v = 0$, $T = T_{s}$. (8)
\nSubsequently:
\nwhen $y = h(t) \rightarrow \frac{\partial u}{\partial y} = 0$, $\frac{\partial T}{\partial y} = 0$, $v = \frac{\partial T}{\partial y}$. (9)
\nIn the above equation, the thickness of the film is shown by *h(t)*. Based on the Schlichting and Gersten [29], the thickness
\nof boundary-layer δ(x) is proportional to $(x_{f}/U_{w})^{0.5}$, hence the
\nvariable η is defined as follows:

where ϕ , k_{nf} and $(\rho C_p)_{nf}$ are the volume fraction, thermal conductivity and the heat capacitance of the nanofluid, respectively. Then, the related boundary conditions for the differential equation governing the mentioned system are defined as:

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$$
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$$
, $v = 0$, $T = T_s$. (8)

Subsequently:

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$$
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Then, the related boundary conditions for the e ϕ , k_{nf} and $(\rho C_p)_{nf}$ are the volume fraction, thermal
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quation governing the mentioned syste

$$
\eta = y \sqrt{\frac{U_w}{x v_f}} = y \sqrt{\frac{b}{(1 - \alpha t) v_f}}.\tag{10}
$$

solved by Least square method. Besides the impact of
factors such as unsearching sparameter (S), Prandtl

(Pr) and the volume fraction of nanofluids (ϕ) on the
ture and velocity distributions is explored thoroughly.
 and the heat capacitance of the nanofluid, respec-

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governing the mentioned system are defined as:
 $\rightarrow u = U_w$, $v = 0$, $T = T_x$. (8)

(8)

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 $0 \rightarrow u = U_w$, $v = 0$, $T = T_s$. (8)
 $0 \rightarrow u = U_w$, $v = 0$, $T = T_s$. (8)
 $h(t) \rightarrow \frac{\partial u}{\partial y} = 0$, $\frac{\partial T}{\partial y} = 0$, $v = \$ It is necessary to mention that the above equation can be achieved by the expressions presented by Görtler [29]. In accordance to this explanation and substituting $U(x) = U_w$, it is possible to define ξ , η and ψ (x, y), which is brought completely in Ref. [30]. Regarding the above explanations, the following new variables are introduced as [30]:

$$
\psi = \beta \left[\frac{v_j b}{1 - \alpha t} \right]^{1/2} x f(\eta). \tag{11}
$$

$$
W. Fakour et al. /Journal of Mechanical Science and Technology 32 (1) (2018) 177-183
$$

\n
$$
\psi = \beta \left[\frac{v_f b}{1-\alpha t} \right]^{1/2} x f(\eta).
$$

\nIn the above equation, the heat f
\nsurface are defined in the following
\n
$$
T = T_0 - T_r \left(\frac{bx^2}{2v_f} \right) (1-\alpha t)^{3/2} \theta(\eta).
$$

\n(12)
$$
\tau_w = \mu_{\eta f} \left(\frac{\partial u}{\partial y} \right)_{y=0}, q_w = -k_{\eta f} \left(\frac{\partial T}{\partial y} \right)_{y=0}
$$

\n
$$
\eta = \frac{1}{\beta} \left[\frac{b}{v_f (1-\alpha t)} \right]^{1/2} y.
$$

\n(13) Therefore, after substituting Eq.

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\n
$$
\psi = \beta \left[\frac{v_{f}b}{1-\alpha t} \right]^{1/2} xf(\eta).
$$
\nIn the above equation, the heat flux and s surface are defined in the following form:
\n
$$
T = T_{0} - T_{r} \left(\frac{bx^{2}}{2v_{f}} \right) (1-\alpha t)^{3/2} \theta(\eta).
$$
\n(12)
$$
\tau_{w} = \mu_{w} \left(\frac{\partial u}{\partial y} \right)_{y=0}, q_{w} = -k_{w} \left(\frac{\partial T}{\partial y} \right)_{y=0}.
$$
\n
$$
\eta = \frac{1}{\beta} \left[\frac{b}{v_{f}(1-\alpha t)} \right]^{1/2} y.
$$
\n(13) Therefore, after substituting Eq. (23) into have the final form of the physical quantities
\nwhere $\psi(x, y)$ is the stream function explained in the usual

M. Fakour et al. / Journal of Mechanical Science and Technology 32 (1) (2018) 177-
 $\left[\frac{bx^2}{2v_f}\right]^{1/2}$ *f* (*n*). (11) In the above equation, the h

surface are defined in the follow
 $\left[\frac{bx^2}{2v_f}\right](1 - \alpha t)^{3/2} \theta(\eta$ *M. Fakour et al. / Journal of Mechanical Science and Technology 32 (1) (2018) 17
* $\beta \left[\frac{v_1 b}{1-\alpha t} \right]^{1/2} x f(\eta)$ *.* (11) In the above equation, the
 $T_0 - T_r \left(\frac{bx^2}{2v_f} \right) (1-\alpha t)^{3/2} \theta(\eta)$. (12) $\tau_w = \mu_w \left(\frac{\partial u}{\partial y}$ *M. Fakour et al. / Journal of Mechanical Science and Technology 32 (1) (2018) 177-1.

=* $\beta \left[\frac{v_1 b}{1-\alpha t} \right]^{1/2} x f(\eta)$ *.* In the above equation, the he

surface are defined in the follow
 $= T_0 - T_r \left(\frac{bx^2}{2v_f} \right) (1-\alpha t$ where $\psi(x, y)$ is the stream function explained in the usual way, for example, $u = \partial \psi / \partial y$, $v = -\partial \psi / \partial x$ and $\beta > 0$ is the non-dimensional film thickness parameter given by $β =$ $(hb/v_f)(1 - \alpha t)^{-1/2}$. For the limiting cases $\beta = 0$ and $\beta = \infty$, this transformation is no longer effective and particular approaches are needed to give solutions as shown in Wang [31]. As a result, the velocity components u and v can be defined as: $\left[\frac{b}{\alpha x}\right]^{1/2} x f(\eta).$ (11) In the above equation, the heat flu

surface are defined in the following for
 $\left[\frac{bx^2}{2v_f}\right](1-\alpha t)^{3/2}\theta(\eta).$ (12) $\tau_w = \mu_w\left(\frac{\partial u}{\partial y}\right)_{y=0}$, $q_w = -k_w\left(\frac{\partial T}{\partial y}\right)_{y=0}$

is the stream $\left[\frac{v}{1-\alpha t}\right]$ *xf(n).* (11) surface are defined in the following $-\frac{r}{\sqrt{2v_{f}}}\left[\frac{bx^{2}}{2v_{f}}\right](1-\alpha t)^{3/2}\theta(\eta)$. (12) $\tau_{w} = \mu_{w}\left(\frac{\partial u}{\partial y}\right)_{y=0}$, $q_{w} = -k_{w}$
 $\left[\frac{b}{v_{f}(1-\alpha t)}\right]^{1/2}$ *y*. (13) Therefore, af $=\int_{0}^{2\pi} \left[\frac{v_x b}{1-\alpha t}\right]^{1/2} x f(\eta)$.
 $= T_0 - T_2 \left(\frac{\hbar x^2}{2v_f}\right) (1-\alpha t)^{3/2} \theta(\eta)$.
 $= \int_{0}^{2\pi} \left[\frac{v_x}{v_x(1-\alpha t)}\right]^{1/2} y$.
 $\left[\frac{1}{v_x(1-\alpha t)}\right]^{1/2} y$.

(12) $r_x = \mu_g \left(\frac{\partial u}{\partial v}\right)_{y=0}$, $q_x = -k_g \left(\frac{\partial T}{\partial v}\right)_{y=0}$.
 $=\frac{1}{\beta}\left[\frac{bx^3}{2v_f}\right](1-\alpha t)^{3/2}\theta(\eta)$. (12) $\tau_w = \mu_w \left(\frac{\partial u}{\partial y}\right)_{y=0}$, $q_w = -k_w \left(\frac{\partial T}{\partial y}\right)_{y=0}$
 $=\frac{1}{\beta}\left[\frac{b}{v_f(1-\alpha t)}\right]^{\alpha/2}$ y. (13) Therefore, after substituting Eq. (2)

therefore, after substituting Eq. (2) *e* $\psi(x, y)$ is the stream function explained in the usual

fine means) and $\sinh(\theta)$, $y = -\partial \psi/\partial x$ and $\beta > 0$ is the $\cosh(\theta)$

fine means and $\sinh(\theta)$ is $\cosh(\theta)$ is $\theta = \pi/2$ is $\pi/2$ is $\theta = 0$ and $\beta = \pi/2$. However, ere $\psi(x, y)$ is the stream function explained in the usual

or, for casmple, $u = \frac{\partial \psi}{\partial x}$, $v = -\frac{\partial \psi}{\partial x}$ or ϕ . x_0 and β o is the

an-dimensional film thickness parameter given by β

an-dimensional film t (a) is the stream function explained in the usual

only C_{β} Re_x⁺² = $\frac{1}{\beta(1-\phi)^{3.5}}f''(0)$.

(b) $e^{(1-\phi)^3/2}$ For the limiting cases $\beta = 0$ and $\beta = \alpha$, this

only $e^{3.2}$ For the limiting cases $\beta = 0$ and $\mathbf{v}(\mathbf{x}, \mathbf{y})$ is the stream function explained in the usual

or example, u – $\partial \mathbf{w}$ (\mathbf{x} and β > 0 is the $C_R \text{Re}_z^{1/2} = \frac{1}{\beta(1-\phi)^{2.5}} f^*(0)$.

(1 – αt)⁻¹². For the limiting cases β = 0 and β = ∞, thi mple, $u = \partial \psi' \partial y$, $v = -\partial \psi' \partial x$ and $\beta > 0$ is the

solution thickness parameter given by $\beta = \frac{1}{\beta(1-\phi)^{23}} f''(0)$.
 $\frac{1}{\beta} \frac{d}{dt} \int u = \frac{1}{\beta} \frac{d}{dt} \int v(0)$.

is no longer effective and particular approaches

or gi dimensional intime unceded to give solutions and the momentum and
 $\frac{\partial \psi}{\partial t} = -\beta \left(\frac{v_b}{1-\alpha t} \right)^{t/2}$ (f) = 0.

Solutions is no longer effective and particular approaches

this notable that in Eqs. (24) and (25)

nee (v_i)(1 – at)^{-1/2}. For the limiting cases $\beta = 0$ and $\beta = \infty$, this

subscriming in longer effective and particular approaches

needed to give solutions as shown in Wang [31]. As a

let, the velocity components u and From Showar IIIm tunckeness parameter given by p =
 For the limiting cases $\beta = 0$ and $\beta = \infty$, this
 Nu_s $Re_z^{1/2} = -\frac{k_y}{k_y} \theta'(0)$.
 f or $\theta = \frac{1}{2}$ for the limiting cases $\beta = 0$ and $\beta = \infty$, this
 nut, the

$$
u = \frac{\partial \psi}{\partial y} = \left(\frac{bx}{1 - \alpha t}\right) f'(\eta).
$$

$$
v = -\frac{\partial \psi}{\partial x} = -\beta \left(\frac{v_f b}{1 - \alpha t} \right)^{1/2} f(\eta).
$$
 (15) **3. Analyti**

Inserting the similarity variables into the momentum and energy equations results in:

$$
\varepsilon_1 f''' + \beta^2 \left[ff'' - (f')^2 - S \left(f' + \frac{\eta}{2} f'' \right) \right] = 0. \tag{16}
$$

$$
\frac{\varepsilon_2}{2}\theta'' - \beta^2 \left[\frac{S}{2} (3\theta + \eta \theta') + 2\theta f' - f\theta' \right] = 0.
$$
 (17)

where the relevant boundary conditions can be rewritten as:

at
$$
\eta = 0 \rightarrow f(0) = 0, f'(0) = 1, \theta(0) = 1.
$$
 (18)

at
$$
\eta = 1 \rightarrow f(1) = \frac{S}{2}, \ \theta'(1) = 0.
$$
 (19)

 $u = \frac{2v}{dy} = \left[\frac{1}{1-\alpha t}\right] f'(\eta).$
 $v = -\frac{\partial v}{\partial x} = -\beta \left(\frac{v_1 b}{1-\alpha t}\right)^{1/2} f(\eta).$
 $v = -\frac{\partial v}{\partial x} = -\beta \left(\frac{v_1 b}{1-\alpha t}\right)^{1/2} f(\eta).$
 $v = -\frac{\partial v}{\partial x} = -\beta \left(\frac{v_1 b}{1-\alpha t}\right)^{1/2} f(\eta).$

(14) lem occurred by an unsteady stretching su $\frac{dy}{dy} = \left(\frac{y}{1 - \alpha t}\right)f'(\eta)$.
 $\frac{dy}{dx} = -\beta \left(\frac{y}{1 - \alpha t}\right)^{1/2} f(\eta)$.
 $\frac{dy}{dx} = -\beta \left(\frac{y}{1 - \alpha t}\right)^{1/2} f(\eta)$.
 $\frac{dy}{dx} = -\beta \left(\frac{y}{1 - \alpha t}\right)^{1/2} f(\eta)$.

(15)

S. Analytical and numerical methods
 $\frac{3.1 \text{ Least square method (LSM)}}{\text{is one of the WRM$ In the afore-mentioned equations, $Pr = (v_f / \alpha_f)$ and $S = (\alpha / \alpha_f)$ b) are the Prandtl number and unsteadiness parameter, respectively. Finally, ε_1 and ε_2 are two constants explained in the following form: $- B^2$ $\left[\frac{1}{2}(3\theta + \eta \theta') + 2\theta J' - J\theta'\right] = 0.$ (11)
 $f(\eta) = \eta + C_1(200\eta^2 + \eta)$

the relevant boundary conditions can be rewritten as:
 $C_1(400\eta^4 + \eta) + C_4(500\eta^3 + \eta)$
 $= 0 \rightarrow f(0) = 0, f'(0) = 1, \theta(0) = 1.$ (18)
 $C_8(\eta - 1/4\eta$

$$
\varepsilon_1 = \frac{1}{(1-\phi)^{2.5} \left[(1-\phi) + \phi \rho_s / \rho_f \right]}.
$$
 (20)

$$
\varepsilon_{2} = \frac{\left(k_{\eta} / k_{f}\right)}{\left[\left(1-\phi\right) + \phi(\rho C_{p})_{s} / (\rho C_{p})_{f}\right]}.
$$
\n(21)

The physical quantities for this problem are the Nusselt number Nu and skin friction coefficient C_f as follows:

$$
C_f = \frac{\tau_w}{\rho_f (U_w)^2}, \quad Nu = \frac{q_w x}{k_f (T_s - T_0)}.
$$
 (22) **4. Res**
In the

 (11) surface are defined in the following form: In the above equation, the heat flux and skin friction at the

and Technology 32 (1) (2018) 177–183
\nIn the above equation, the heat flux and skin friction at the
\nurface are defined in the following form:
\n
$$
\tau_w = \mu_{wf} \left(\frac{\partial u}{\partial y} \right)_{y=0}, \quad q_w = -k_{wf} \left(\frac{\partial T}{\partial y} \right)_{y=0}.
$$
\n(23)
\nTherefore, after substituting Eq. (23) into Eq. (22), we will
\nave the final form of the physical quantities as follows:
\n
$$
C_{fs} \text{ Re}_x^{-1/2} = \frac{1}{\beta (1-\phi)^{2.5}} f''(0).
$$
\n(24)
\n
$$
Nu_x \text{ Re}_x^{-1/2} = -\frac{k_{wf}}{k_f \beta} \theta'(0).
$$
\n(25)
\nIt is notable that in Eqs. (24) and (25) Re_x = U_{wx}/v_f is the lo-
\nale
\nReynolds number. Wang [31] calculated that the solutions

Therefore, after substituting Eq. (23) into Eq. (22), we will have the final form of the physical quantities as follows:

$$
C_{f_x} \operatorname{Re}_x^{-1/2} = \frac{1}{\beta \left(1 - \phi\right)^{2.5}} f''(0). \tag{24}
$$

$$
\tau_{w} = \mu_{w} \left(\frac{\partial u}{\partial y} \right)_{y=0}, \quad q_{w} = -k_{w} \left(\frac{\partial T}{\partial y} \right)_{y=0}.
$$
\n(23)

\nTherefore, after substituting Eq. (23) into Eq. (22), we will
\nwe the final form of the physical quantities as follows:

\n
$$
C_{f_{x}} \text{Re}_{x}^{-1/2} = \frac{1}{\beta (1 - \phi)^{2.5}} f''(0).
$$
\n
$$
N u_{x} \text{Re}_{x}^{-1/2} = -\frac{k_{w}}{k_{f} \beta} \theta'(0).
$$
\n(24)

\nIt is notable that in Eqs. (24) and (25) Re_x = U_{wx}/v_f is the lo-

bove equation, the heat flux and skin friction at the

defined in the following form:
 $\left(\frac{\partial u}{\partial y}\right)_{y=0}$, $q_w = -k_w \left(\frac{\partial T}{\partial y}\right)_{y=0}$. (23)

ore, after substituting Eq. (23) into Eq. (22), we will

final form of the p It is notable that in Eqs. (24) and (25) $Re_x = U_{wx}/v_f$ is the local Reynolds number. Wang [31] calculated that the solutions are available in the range of $0 \le S \le 2$ for a liquid film problem occurred by an unsteady stretching surface.

a **3. Analytical and numerical methods**

3.1 Least square method (LSM)

(16) function must satisfy the boundary conditions and equations, mesonar num tankness parameter given by $p = -p$
 $\frac{dy}{dx} = -p \left[\frac{f}{2}(3\theta + \eta \theta') + 2\theta f' - f \theta' \right] = 0.$ (17)
 $\theta = -p \left[\frac{S}{2}(3\theta + \eta \theta') + 2\theta f' - f \theta' \right] = 0.$ (18)
 $\theta = -p \left[\frac{f}{2}(3\theta + \eta \theta') + 2\theta f' - f \theta' \right] = 0.$ (18)
 $\theta = -p \left[\frac{$ at Reynolds number. Wang [31] calculated that the are available in the range of 0 \leq S \leq 2 for a liquid finite in the material methods in the material methods in the material methods $v = -\frac{\partial w}{\partial x} = -\beta \left(\frac{v_1 b}{1 -$ Sheikholeslami, Hatami and Ganji [32] expressed that LSM is one of the WRMs constructed for minimizing the residuals of the trial function. It is important to mention that the trial hence, the trial function can be considered as: $u_x \text{Re}_x^{-1/2} = -\frac{u_y}{k_f} \theta'(0).$ (25)

is notable that in Eqs. (24) and (25) $\text{Re}_x = \text{U}_{w_x}/\text{V}_f$ is the lo-

exprolos number. Wang [31] calculated that the solutions

ivaliable in the range of $0 \le S \le 2$ for a liquid f s notable that in Eqs. (24) and (25) $Re_x = U_{wx}/v_f$ is the lo-
eynolds number. Wang [31] calculated that the solutions
vailable in the range of $0 \le S \le 2$ for a liquid film prob-
ecurred by an unsteady stretching surface.
 Nu_x $Re_x^{-1/2} = -\frac{n_{ef}}{k_f B} \theta'(0)$. (25)
 i is notable that in Eqs. (24) and (25) $Re_x = U_{ww}/v_f$ is the lo-
 Reynolds number. Wang [31] calculated that the solutions

available in the range of $0 \le S \le 2$ for a liquid fi $u_x \text{Re}^{-1/2} = -\frac{v_{xf}}{k_f \beta} \theta'(0).$ (25)

s notable that in Eqs. (24) and (25) $\text{Re}_x = \text{U}_{\text{w}}/\text{v_f}$ is the lo-

eynolds number. Wang [31] calculated that the solutions

vailable in the range of $0 \le S \le 2$ for a liquid table that in Eqs. (24) and (25) Re_s = U_{wx}/v_f is the lo-

blds number. Wang [31] calculated that the solutions

ble in the range of $0 \le S \le 2$ for a liquid film prob-

red by an unsteady stretching surface.
 tical $e_x^{-1/2} = -\frac{n_{eff}}{k_f B} \theta'(0).$ (25)

otable that in Eqs. (24) and (25) Re_x = U_{wy}/v_f is the lo-

ololds number. Wang [31] calculated that the solutions

lable in the range of $0 \le S \le 2$ for a liquid film prob-
 arrow b the that in Eqs. (24) and (25) Re_x = U_{wx}/v_f is the lo-

sumber. Wang [31] calculated that the solutions

in the range of $0 \le S \le 2$ for a liquid film prob-

by an unsteady stretching surface.

al and numerical met is notable that in Eqs. (24) and (25) $Re_x = U_{w_x}/v_f$ is the lo-
Reynolds number. Wang [31] calculated that the solutions
vailable in the range of $0 \le S \le 2$ for a liquid film prob-
occurred by an unsteady stretching surface eynolds number. Wang [31] calculated that the solutions
vailable in the range of $0 \le S \le 2$ for a liquid film prob-
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nalytical and numerical methods
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e It is notable that in Eqs. (24) and (25) Re_x = U_{svs}/v_r is the lo-
Reynolds number. Wang [31] calculated that the solutions
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noccurred by an unsteady stretc eynolds number. Wang [31] calculated that the solutions
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lable in the range of $0 \le S \le 2$ for a liquid film prob-
urred by an unsteady stretching surface.
yi nolds number. Wang [31] calculated that the solutions

lable in the range of $0 \le S \le 2$ for a liquid film prob-

ured by an unsteady stretching surface.
 ytical and numerical methods

st square method (LSM)

holeslami,

$$
f(\eta) = \eta + C_1(200\eta^2 + \eta) + C_2(300\eta^3 + \eta) + C_3(400\eta^4 + \eta) + C_4(500\eta^5 + \eta) + C_5(600\eta^6 + \eta).
$$
 (26)

$$
\theta(\eta) = 1 + C_6(\eta - 1/2\eta^2) + C_7(\eta - 1/3\eta^3) + \tag{27}
$$

$$
C_8(\eta - 1/4\eta^4) + C_9(\eta - 1/5\eta^5) + C_{10}(\eta - 1/6\eta^6).
$$
 (27)

By introducing this equation into Eqs. (16) and (17), the residual function can be extracted and by substituting them into Eqs. (26) and (27), a set of ten equations and ten unknown coefficients C1-C10 will be determined.

3.2 Numerical method (NUM)

 $\varepsilon_r f'' + \beta^2 \left[f'' - (f')^2 - S \left[f' + \frac{\gamma}{2} f'' \right] \right] = 0.$ (16) function must satisfy the boundary conditione.
 $\frac{\varepsilon_r}{2} \theta^r - \beta^2 \left[\frac{S}{2} (3\theta + \eta \theta) + 2\theta f' - f \theta \right] = 0.$ (17) $f(\eta) = \eta + C_1 (200\eta^2 + \eta) + C_2 (300\eta^3 + \eta)$

are the $\beta^2 \left[f'' - (f')^3 - S \left(f' + \frac{\pi}{2} f'' \right) \right] = 0.$ (16) function must satisfy the boundary
hence, the trial function can be contributed by the set of β^2 $\left[\frac{1}{2}(3\theta + \eta \theta') + 2\theta \right] = 0.$ (17)
 $\left[\frac{1}{2}(3\theta + \eta \theta') + 2\theta \right] = 0.$ (17)
 $\left[\frac{1}{2}(30\eta^2 + \eta) + C_4(300\eta^2 + \eta) + C_5(300\eta^2 + \eta) + C_6(600\eta^2 + \eta) + C_7(600\eta^2 + \eta) + C_8(600\eta^2 + \eta) + C_9(600\eta^2 + \eta) + C_9(600\eta^2 + \eta) + C_9$ *nhence, the trail function can be contended to* $f(\eta) = \eta + C_1(200\eta^2 + \eta) + C_2(200\eta^3 + \eta)$ *.

boundary conditions can be rewritten as:
* $C_3(400\eta^4 + \eta) + C_4(500\eta^5 + \eta)$ *.
* $\theta(\eta) = 1, \theta(0) = 1$ *.

(18)
* $D = \frac{S}{2}, \theta'(1) = 0$ *.
 The p* $f(\eta) = \eta + C_1(200\eta^2 + \eta) + C_2(300\eta^3 + \eta)$

bundary conditions can be rewritten as:
 $C_1(400\eta^4 + \eta) + C_4(500\eta^3 + \eta) + C_5(600\eta^3 + \eta) + C_1(600\eta^3 + \eta) + C_2(600\eta^3 + \eta) + C_2(600\eta^3 + \eta) + C_2(600\eta^3 + \eta) + C_2(600\eta^3 + \eta) +$ $\left[\frac{1}{2}(3b^2 + 7b^2) + 2(b^2 - b^2)^2\right] = 0.$ (11)

Evant boundary conditions can be rewritten as:
 $G_1(400\eta^4 + \eta) + C_4(500\eta^5 + \eta) + C_5(300\eta^5 + \eta) + C_6(500\eta^5 + \eta) + C_7(600\eta^5 + \eta) + C_7(600\eta^5 + \eta) + C_8(600\eta^5 + \eta) + C_9(70 - 1/3)\$ (21) value (B-V) problem procedure. This algorithm is based on at $n = 1 \rightarrow f(1) = \frac{S}{2}$, $\theta'(1) = 0$.
 ignum in the afore-mentioned equations, Pr = ($v_f \langle \alpha_f \rangle$ and $S = (\alpha /$ Eqs. (26) and (27), a set of ten equation

sidual function can be extracted and by st

letter the Paradul numb *V* $U = \frac{1}{2}$, *V* (*U* = 0.
 U **Example 10 Example 12 E** The above system of non-linear ordinary differential equations along with the boundary conditions is solved numerically using the algebra package Maple 16.0 with a boundary ourth-fth order Runge-Kutta-Fehlberg procedure which im proves the Euler method by adding a midpoint in the step which increases the accuracy by one order. Thus, the midpoint method is used as a suitable numerical technique.

4. Results and discussion

In this research, LSM method was adopted to achieve an

Fig. 2. A comparison between the obtained results by LSM and Numerical solution in terms of varying $f(\eta)$ for different values of unsteadiness parameter (S) (Water - Copper).

Fig. 3. A comparison between the obtained results by LSM and Numerical solution in terms of varying $\theta(\eta)$ for different values of unsteadiness parameter (S) (Water - Copper).

Fig. 4. The variation of velocity profile for some values of unsteadiness parameter (Water - Copper).

Fig. 5. Temperature distributions for four different values of volume

Fig. 6. Variation of velocity for four different values of volume frac-

Fig. 7. Variation of $θ(η)$ in terms of various amounts of Prandtl number (Water - Copper).

Fig. 8. Variation of local skin friction coefficient in terms of four different amounts of S (Water - Copper).

Fig. 9. Effect of (ϕ) on the local Nusselt number in the specified domain (Water - Copper).

explicit analytical solution of the unsteady flow and the related heat transfer of a nanofluid passing through a horizontal plate. (Fig. 1). Copper-water nanofluid passes through the horizontal plate and the impact of some physical parameter (Pr, S and ϕ), as well as various types of nanofluids on the temperature and velocity profiles is studied in this research.

Figs. 2 and 3 indicate that S had an impact on the temperature and $f(\eta)$ profiles. Accordingly, it is concluded that $f(\eta)$ increases by a rise in the S parameter. On the contrary, an opposite trend is seen in temperature values, where the value of temperature profile decreases by increasing the parameter S. Moreover, it can be inferred from these figures. that the obtained results from the LSM demonstrate a great compatibility with the data achieved from the numerical model.

Fig. 4 shows that with a rise in η, the velocity will steadily increase. It is worth noting that the rate of the velocity would augment with growth in S parameter. Since the parameter S depends on α and β, it can be deduced that the stretching velocity of wall is a vital factor to specify the velocity profile. The variation of temperature with various volume fractions of

Fig. 10. Effect of different types of nanofluids on $f(\eta)$.

Fig. 11. Effect of different types of nanofluids on θ(η).

nanofluids is shown in Fig. 5. As stated in this figure, increasing the nanoparticles volume leads to the rise of temperature value due to more heat transfer caused by the nanoparticles. This case implies that the nanofluid has a very important and vital impact on the properties of the heat transfer.

Moreover the impact of the nanofluid volume fraction on the velocity is displayed in Fig. 6. An overall observation of Fig. 6 reveals that when $\eta \in \{0, 0.5\}$, the velocity decreases due to the enhancement in nanoparticles volume fraction and when $\eta \in \{0.5, 1\}$, the opposite trend occurs. Furthermore, the effect of Pr number on $\theta(\eta)$ is completely investigated in Fig. 7. As a result, the temperature distribution has a considerable decline due to the increase of Pr number and such a decrease in temperature distribution in free surface $(\eta = 1)$ will be vanished for larger values of Pr. Thus, it is clear that the surface temperature is equal to ambient temperature.

The variations of local skin friction coefficient and Nusselt number with ϕ are displayed in Figs. 8 and 9. It can be seen that the local skin friction coefficient increases significantly and decreases steadily by increasing the S and ϕ parameters,

respectively. From this figure, it can be inferred that the local Nusselt number faces a steady and considerable enhancement by increasing the ϕ and S parameters.

Figs. 10 and 11 show the impact of different structure of nanofluids on $f(\eta)$ and $\theta(\eta)$. According to the figures, it can be observed that the maximum amount of $f(η)$ and $θ(η)$ occurs when the water-Alumina and water-Lead nanofluids are used. The results indicate that nanoparticles in working fluid mainly cause the increase of the heat transfer rate at any given value of S and the Pr in a thin film nanofluid over a stretching plate.

5. Conclusion

In this study, the LSM is implemented to solve the unsteady flow problem and the related heat transfer of a nanofluid over a horizontal plate. The accuracy of the LSM is checked with the numerical model. The comparison indicates that the LSM has a good compatibility with the numerical data. After validating the model, the impact of physical parameters such as S, Pr and the nanoparticles volume fraction on the temperature and velocity behaviors has been studied in details. It is observed that the values of $f(\eta)$ increase as the S parameter augments. However, a reverse trend is observed in which an en hancement in the S value leads to reduction in the temperature profile and by increasing the η, the velocity will increase steadily. Regarding the role of nanofluid volume fraction, it is concluded that the overall convective heat transfer coefficient enhances by adding the nanoparticles into the pure working fluid. Among different types of nanofluid, water-Alumina nanofluid showed better improvement in terms of boosting the velocity and heat transfer in the considered geometry. How ever, the velocity profile experienced a turning point at $\eta = 0.5$.

Nomenclature-

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