

# MHD copper-water nanofluid flow and heat transfer through convergent-divergent channel<sup>†</sup>

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# **Abstract**

This work is focused on the analytical solution of a nanofluid consisting of pure water with copper nanoparticle steady flow through convergent-divergent channel. The velocity and temperature distributions are determined by a novel method called Reconstruction of variational iteration method (RVIM). The effects of angle of the channel, Reynolds and Hartmann numbers on the nanofluid flow are then investigated. The influences of solid volume fraction and Eckert number upon the temperature distribution are discussed. Based on the achieved results, Nusselt number enhances with increment of solid volume fraction of nanoparticles, Reynolds and Eckert numbers. Also the fourth order Runge-Kutta method, which is one of the most relevant numerical techniques, is used to investigate the validity and accuracy of RVIM and good agreement is observed between the solutions obtained from RVIM and some known numerical results.

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*Keywords*: Convergent-divergent channel; Nanofluid flow; MHD; Heat transfer enhancement; Analytical approximate solution; RVIM

## **1. Introduction**

The study of Magneto-hydrodynamics (MHD) focuses on the interactions between the dynamics of electrically conducting fluids and the electromagnetic forces. Alfvén initiated the research field of magneto-hydrodynamics and received the Nobel Prize of physics in 1970 [1]. However, incompressible fluid magneto-hydrodynamics was initiated in 1937 by Hartmann [2] who studied the effect of a lateral magnetic field, which was considered to be external and uniform, upon the flow field of a viscous incompressible electrically conducting fluid between infinite parallel fixed plates (with the assumption of insulating properties).

One of the most important fields in power industries is fluid heating, which has also crucial role in manufacturing plants. There is an increasing demand for finding novel and effective cooling techniques to improve the efficiency of the cooling processes related to various types of high energy devices. In most cases, for this purpose, common fluids such as water, engine oil or ethylene glycol are used. But, because of many limitations in heat transfer capabilities of these fluids, it is better to find some alternative ways. Thermal conductivity values of most of metals are very high, and can be estimated to be around three-fold higher than the aforementioned fluids. Consequently, it might be desirable to use a uniform combination of metal and fluid to gain the benefits of both matters. Thus, by this technique one could achieve a proper heat transfer medium which could behave like a fluid and, at the same time, could have a high thermal conductivity (the same as metals).

Recently, a remarkable number of researches have been done in the field of nanofluids and their vast applications in industries have been studied. In addition, it has been demon strated that they have certain superiorities (as a heat transfer agent) in comparison with common conventional fluids like water or engine oil [3-6].

An investigation on the flow field and heat transfer specifications of nanofluid between two horizontal parallel plates in a rotating system has been done [7]. As reported [7], for suction and injection, the rate of heat transfer at the surface would enhance by increment of the solid nanoparticle volume fraction, Reynolds number, and the parameters related to the injection/suction process. However, it was demonstrated that [7] the rate of heat transfer at the surface would reduce with in crement in the power of rotation parameter, which represents the effect of rotation of system on the physics of the problem.

Azimi et al. [8] studied the effect of graphene oxide nanoparticle solid volume fraction, the moving parameter and the Eckert number on heat transfer characteristics of nanofluid flow between two moving parallel plates. In Azimi et al. [9], magneto-hydrodynamics Jeffery-Hamel flow of nanofluid containing graphene oxide nanoparticles for various Hartman number has been investigated. They concluded that the di-

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mensionless velocity for water-GO nanofluid is an increasing function of Re, in a divergent channel.

Heat transfer enhancement is an important achievement in heat transfer systems like heat exchangers because more heat transfer enhancement would lead to more heat fluxes and easier cooling processes [10].

Lihong and Hangming [11] investigated the distribution of thin copper wire in a chamber cross section (assuming the chamber to be isothermal) by employing topological techniques to achieve heat transfer enhancement from the wall to the chamber interior and to promote the isothermal specifications of the chamber in their study.

Moslehi and Saghafian [12] studied flow of a Newtonian electrically conducting fluid in laminar condition, in a vertical parallel micro-channel, considering the direct influence of an external uniform magnetic field as well as mixed convection heat transfer using a well known numerical method. Azimi and Riazi [13] used Galerkin optimal homotopy asymptotic method (GOHAM) to achieve an approximate solution of the  $J = \sigma(V \times B)$ , where V is the velocity vector. As a conseunsteady magneto-hydrodynamics squeezing flow between two parallel disks. Their investigation depicted that the aver-<br> $F_R = (\sigma(V \times B)) \times B$ . Based on these assumptions, the mass, age Nusselt number can be increased by using higher concentration of graphene-oxide particles in base fluid as the nanoparticle between plates. Their results show that the same manner can be obtained by increasing Rayleigh number, while their calculations show that Nusselt number would be decreased if higher magnetic field would be used. So, the aver age Nusselt number has a reverse relation with the Hartmann number. Hamad et al. [14] investigated analytically the steady free convection boundary layer flow over a vertical semiinfinite flat plate embedded within water (containing nano particles) considering the effects of magnetic field. Their results show that more heat transfer enhancement can be achieved by using copper and silver nanoparticles in base fluid. The CVFEM (Control volume based finite element method) was employed as a novel numerical technique to study the MHD natural convection heat transfer of copper water nan ofluid within a coaxial cold outer circular case together with a hot inner sinusoidal circular cylinder by Sheikholeslami et al. [15]. As reported, with negligible value of Hartman number, increment of Rayleigh number could lead to reduction of the enhancement ratio; however, in presence of a horizontal mag netic field, increase of the Rayleigh number could lead to in crement of the enhancement ratio (the Jeffery-Hamel problem).

Recently, a considerable number of researches have been performed regarding the possibility of using analytical approaches to achieve proper solutions for high-order nonlinear differential equations. Some of these analytical methods are Homotopy perturbation method (HPM) [18], Reconstruction of variational iteration method (RVIM) [19], Differential transformation method (DTM) [20] and others [21-23].

Our purpose was to gain the analytic approximate solutions of the two-dimensional magneto-hydrodynamics copper water nanofluid flow between converging/diverging channels using RVIM and investigating the effect of different parameters upon both the flow and heat transfer characteristics.

## **2. Problem description**

To investigate the problem of Jeffery-Hamel magneto hydrodynamics flow analytically, a 2-D flow field of an in compressible, electrically conducting viscous fluid, considering the influence of an external transverse homogeneous magnetic field (see Fig. 1) was studied in the current research. As indicated in Fig. 1, the steady 2-D flow of an incompressible, electrically conducting viscous fluid with respect to a sink or source located at the intersection of two non-parallel plane walls is considered. We assumed that the velocity would be purely radial and a function of  $r$  and  $\theta$  only. To control the flow field, we studied the influence of magnetic field on dynamic of flow. The generated electric field is assumed to be negligible, which may lead to the reduction of Ohm's law to *J Zyma* and myestigating the errect of direction parameters pron both the flow and heat transfer characteristics.<br> **2. Problem description** of Jeffry-Hamel magneto-To investigate the problem of Jeffry-Hamel magne quence, the Lorentz force would be simplified to **2. Problem description**<br> *To* investigate the problem of Jeffery-Hamel magneto-<br>
sydrodynamics flow analytically, a 2-D flow field of an in-<br> *p* sydrodynamics indivertically conducting viscous fluid, consider-<br> *ng* the momentum and energy relations in polar coordinates could be written as: solynamics now analytically conducting viscous fluid, consider-<br>pressible, electrically conducting viscous fluid, consider-<br>he influence of an external transverse homogeneous mag-<br>field (see Fig. 1) was studied in the cur the influence of an external transverse homogeneous mag-<br>ic field (see Fig. 1) was studied in the current research. As<br>icated in Fig. 1, the steady 2-D flow of an incompressible,<br>teritrally conducting viscous fluid with r matering viscous fitted with respect to a sink or<br>lat the intersection of two non-parallel plane<br>dered. We assumed that the velocity would be<br>and a function of r and  $\theta$  only. To control<br>we studied the influence of magne (see Fig. 1) was studied in the current research. As<br>
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rely radial and a function of characteric fie *n*c of thow. The generated electric field is assumed to be  $h(r \times B)$ , where *V* is the reduction of Ohm's law to  $(r \times B)$ , where *V* is the velocity vector. As a conse-<br>
e, the Lorentz force would be simplified to  $\sigma(V \times B)$ 

gligible, which may lead to the reduction of Ohm's law to  
\n
$$
= \sigma(V \times B)
$$
, where V is the velocity vector. As a conse-  
\nence, the Lorentz force would be simplified to  
\n $= (\sigma(V \times B)) \times B$ . Based on these assumptions, the mass,  
\nmentum and energy relations in polar coordinates could be  
\nritten as:  
\n
$$
\frac{\rho_{\text{w}}}{r} \frac{\partial (r u(r,\theta))}{\partial r} = 0
$$
\n
$$
u(r,\theta) \frac{\partial u(r,\theta)}{\partial r} = -\frac{1}{\rho_{\text{w}}}\frac{\partial P}{\partial r}
$$
\n
$$
+v_{\text{w}} \left( \frac{\partial^2 u(r,\theta)}{\partial r^2} + \frac{1}{r} \frac{\partial u(r,\theta)}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u(r,\theta)}{\partial \theta^2} - \frac{u(r,\theta)}{r^2} \right)
$$
\n
$$
- \frac{\sigma B_0^2}{\rho_{\text{w}} r^2} u(r,\theta)
$$
\n
$$
- \frac{1}{\rho_{\text{w}} r} \frac{\partial P}{\partial \theta} + \frac{2\mu_{\text{w}}}{\rho_{\text{w}} r^2} \frac{\partial u(r,\theta)}{\partial \theta} = 0
$$
\n
$$
u(r,\theta) \frac{\partial T(r,\theta)}{\partial r} = \alpha_{\text{w}} \left( \frac{\partial^2 T(r,\theta)}{\partial r^2} + \frac{1}{r} \frac{\partial T(r,\theta)}{\partial r} + \frac{1}{r^2} \frac{\partial^2 T(r,\theta)}{\partial \theta^2} \right)
$$
\n(4)

$$
\begin{array}{ccc}\n\sqrt{r} \eta & \partial r & r^2 & \partial \theta^2 & r^2\n\end{array}
$$
\n
$$
\begin{array}{ccc}\n-\frac{\sigma B_0^2}{\rho_{\eta f}r^2} u(r,\theta) & & \\
& & \\
\end{array}
$$

$$
-\frac{1}{\rho_{\eta f}r}\frac{\partial P}{\partial \theta} + \frac{2\mu_{\eta f}}{\rho_{\eta f}r^2}\frac{\partial u(r,\theta)}{\partial \theta} = 0
$$
 (3)

Hence, the Lorentz force would be simplified to  
\n<sub>g</sub> = (σ(V×B))×B. Based on these assumptions, the mass,  
\nomentum and energy relations in polar coordinates could be  
\nritten as:  
\n
$$
\frac{\rho_{\pi}}{r} \frac{\partial (ru(r,\theta))}{\partial r} = 0
$$
\n(1)  
\n
$$
u(r,\theta) \frac{\partial u(r,\theta)}{\partial r} = -\frac{1}{\rho_{\pi}} \frac{\partial P}{\partial r}
$$
\n+
$$
v_{\pi} \left( \frac{\partial^2 u(r,\theta)}{\partial r^2} + \frac{1}{r} \frac{\partial u(r,\theta)}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u(r,\theta)}{\partial \theta^2} - \frac{u(r,\theta)}{r^2} \right)
$$
\n(2)  
\n
$$
-\frac{\sigma B_0^2}{\rho_{\pi} r^2} u(r,\theta)
$$
\n
$$
-\frac{1}{\rho_{\pi} r} \frac{\partial P}{\partial \theta} + \frac{2\mu_{\pi}}{\rho_{\pi} r^2} \frac{\partial u(r,\theta)}{\partial \theta} = 0
$$
\n(3)  
\n
$$
u(r,\theta) \frac{\partial T(r,\theta)}{\partial r} = \frac{\alpha_{\pi} \left( \frac{\partial^2 T(r,\theta)}{\partial r^2} + \frac{1}{r} \frac{\partial T(r,\theta)}{\partial r} + \frac{1}{r^2} \frac{\partial^2 T(r,\theta)}{\partial \theta^2} \right)}
$$
\n(4)  
\n+
$$
\frac{\mu_{\pi}}{\left( \rho C_{\mu} \right)_{\pi}}
$$
\n
$$
\left( 2 \left( \frac{\partial u(r,\theta)}{\partial r} \right)^2 + 2 \left( \frac{u(r,\theta)}{r} \right)^2 + \frac{1}{r^2} \left( \frac{\partial u(r,\theta)}{\partial \theta} \right)^2 \right).
$$
\nDue to the symmetric geometry, the boundary conditions  
\nwill be:  
\n
$$
\left( At the Channel Centerline):
$$
\n
$$
\left( \frac{\partial u(r,\theta)}{\partial \theta} \right) = 0, \frac{\partial T(r,\theta)}{\partial \theta} = 0, u(r,\theta) = U_{\text{max}}
$$
\n(5)

Due to the symmetric geometry, the boundary conditions will be:

$$
\left( At the Channel Centerline \right):
$$
\n
$$
\left( \frac{\partial u(r, \theta)}{\partial \theta} \right) = 0, \frac{\partial T(r, \theta)}{\partial \theta} = 0, u(r, \theta) = U_{\text{max}} \tag{5}
$$

Table 1. Thermophysical properties of water and copper nanoparticle.

Material	Copper	Water
$\rho$ [kg/m <sup>3</sup> ]	8933	997.1
$c_{n}$ [J/(kg·K)]	385	4179
$k$ [W/(m·K)]	1.67	21.0
$\beta$ [K <sup>-1</sup> ] $\times$ 10 <sup>5</sup>	401	0.613



Fig. 1. Geometry of problem.

 $T = T_{\alpha}$ ,  $u(r, \theta) = 0$ . :

Here  $B_0$  is the electromagnetic induction,  $u(r)$  is the velocity along radial direction,  $P$  is the fluid pressure,  $\sigma$  is the conductivity of the fluid,  $\rho_{nf}$  is the density of fluid and  $v_{nf}$  is the coefficient of kinematic viscosity. The physical properties of Cu-water nanofluid are provided in Table 1.

By assuming  $\phi$  as the solid volume fraction, the density of fluid, dynamic viscosity, the fluid kinematic viscosity, thermal diffusivity and thermal conductivity of nanofluid could be considered as the following relations [13]:

where 
$$
Pr = \frac{f(x,y)}{k_x}
$$
 is the Prandtl number,  $Re = \frac{dG_{\text{max}}}{\nu}$  is  
\n $T = T_w$ ,  $u(r, \theta) = 0$ .  
\nHere  $B_n$  is the electromagnetic induction,  $u(r)$  is the  $v_c$   
\nHence  $\frac{dG}{dr_w}$  is the Hartmann number. With the following  
\nHence  $B_n$  is the diud,  $P_w$  is the fluid,  $P_w$  is the fluid,  $P_w$  is the fluid,  $P_w$  is the chiral derivative of the fluid,  $P_w$  is the density of fluid and  $v_w$  is  
\ncoefficient of kinematic viscosity. The physical properties  
\nBy assuming  $\phi$  as the solid volume fraction, the density of  
\nBy assuming  $\phi$  as the solid volume fraction, the density of  
\n $Q(w)$  is the fluid volume fraction, the density of  
\n $Q(w)$  is the fluid volume fraction, the density of  
\n $Q(w)$  is the fluid volume fraction, the density of  
\n $Q(w)$  is the fluid volume fraction, the density of  
\n $Q(w)$  is the direction of the fluid,  $Q(w)$  is the  
\n $Q(w) = 1$ ,  $F(1) = 0$ ,  $F'(0) = 0$ .  
\nHence, the following relations [13]:  
\n $Q_w = \frac{\mu_r}{(\mu - \phi)^{25}}$   
\n $Q_w = \frac{\mu_r}{(\mu - \phi)^{25}}$   
\n $Q_w = \frac{\mu_r}{(\mu - \phi)^{25}}$   
\n $Q_w = \frac{k_w}{(\mu - \phi)^{25}}$   
\n $Q_w =$ 

 $\eta = \frac{\theta}{\alpha}$  as the dimensionless degree, the dimensionless form of the velocity parameter can be obtained by dividing to its maximum values as  $F(\eta) = \frac{F(\theta)}{F_{\text{max}}}$  where  $F_{\text{max}} = rU_{\text{max}}$ . Intro-<br> $w(x,t)$  as  $\theta$  the number of  $\theta$ 

ducing  $\zeta = \frac{T}{T_w}$  as the dimensionless form of temperature, and substituting these dimensionless parameters into Eqs. (1)-(5) and eliminating the pressure term implies the following nonlinear third-order boundary value problems:

M. *1ztini and R. Rizat / Journal of Mechanical Science and Technology 30 (10) (2016) 4679–4686* 4681  
\n
$$
\frac{1}{\log n}
$$
\n
$$
\frac{1}{\log n
$$

where  $Pr = \frac{\mu_f (C_p)_f}{I}$  is the Prandtl number,  $Re = \frac{\alpha U_{max}}{I}$  is  $\left(\frac{C_p}{k_f}\right)$  is the Prandtl number, Re =  $\frac{\alpha U_{\text{max}}}{V}$  is  $=\frac{\mu_f (C_p)_f}{k_c}$  is the Prandtl number, Re  $=\frac{\alpha U_{\text{max}}}{V}$  is Reynolds number,  $Ec = \frac{U^2}{(C_p)_c T_w}$  is Eckert number and  $\frac{U^2}{\left(\frac{U^2}{\nu}\right)^2} = 0$  (8)<br>Prandtl number, Re =  $\frac{\alpha U_{\text{max}}}{\nu}$  is<br> $\frac{U^2}{\left(\frac{U^2}{\nu}\right)^2}$  is Eckert number and<br>n number. With the following  $Ec = \frac{c}{(c)}$  is Eckert number and  $H = \sqrt{\frac{\sigma B_0^2}{\rho V}}$  is the Hartmann number. With the following  $\frac{\partial f}{\partial x} \left( \frac{F}{f} + \frac{P F E C}{(1 - \phi)^{25}} \left( 4\alpha^2 F^2 + F'^2 \right) \right)$ <br>  $\left[ 1 - \phi + \phi \frac{(P C_p)_x}{(P C_p)_x} \right] = 0$  (8)<br>  $\left[ 1 - \phi + \phi \frac{(P C_p)_x}{(P C_p)_x} \right]$ <br>  $\therefore$  Pr =  $\frac{\mu_f (C_p)_x}{k_f}$  is the Prandtl number, Re =  $\frac{\alpha U_{\text{max}}}{V}$  is<br>
blds  $\frac{1}{2r_f}C^2 + \frac{1}{(1-\phi)^{2s}}(4\alpha^2 F^2 + F'^2)$ <br>  $\left[1-\phi+\phi\frac{(\rho C_p)_x}{(\rho C_p)_f}\right] = 0$  (8)<br>  $\frac{\mu_f(C_p)_f}{k_f}$  is the Prandtl number,  $Re = \frac{\alpha U_{\text{max}}}{v}$  is<br>
olds number,  $Ec = \frac{U^2}{(C_p)_f T_w}$  is Eckert number and<br>  $\sqrt{\frac{\sigma B_0^2}{\rho v}}$  is  $\left[\frac{k_{\pi}}{k_{f}}\zeta'' + \frac{\text{Pr } Ec}{(1-\phi)^{25}}(4\alpha^{2}F^{2} + F^{2})\right]$ <br>  $= 0$  (8)<br>  $\left[1-\phi+\phi\frac{(\rho C_{p})}{(\rho C_{p})_{f}}\right]$ <br>
ere Pr $=\frac{\mu_{f}(C_{p})_{f}}{k_{f}}$  is the Prandtl number, Re $=\frac{\alpha U_{\text{max}}}{v}$  is<br>
ynolds number,  $Ec = \frac{U^{2}}{(C_{p})_{f}T_{w}}$  is  $\left[\frac{k_{\pi}}{k_{f}}\zeta'' + \frac{\text{Pr} E c}{(1-\phi)^{25}}(4\alpha^{2}F^{2} + F^{2})\right]$ <br>  $= 0$  (8)<br>  $\left[1 - \phi + \phi\left(\frac{\rho C_{p}}{\rho C_{p}}\right) \right]$ <br>
here  $\Pr = \frac{\mu_{f}(C_{p})}{k_{f}}$  is the Prandtl number,  $\text{Re} = \frac{\alpha U_{\text{max}}}{v}$  is<br>
ynolds number,  $Ec = \frac{U^{2}}{(C_{p})_{f}T_{$ mber,  $Ec = \frac{U^2}{(C_p)_f T_w}$  is Eckert number and<br>
s the Hartmann number. With the following<br>
ditions:<br>  $F(1) = 0$ ,  $F'(0) = 0$ , (9)<br>  $F'(0) = 0$ .<br>
the case of  $\alpha = 0$ , the flow acts very much like<br>
ne Poiseuille flow between two molds number,  $Ec = \frac{U^2}{(C_p)_f T_w}$  is Eckert number and<br>  $\sqrt{\frac{\sigma B_0^2}{\rho V}}$  is the Hartmann number. With the following<br>
dary conditions:<br>  $V(0) = 1$ ,  $F(1) = 0$ ,  $F'(0) = 0$ , (9)<br>  $(1) = 1$ ,  $\zeta'(0) = 0$ . (9)<br>
(1) = 1,  $\zeta'(0) =$ ynolds number,  $Ec = \frac{U^2}{(C_p)_f}$  is Eckert number and<br>  $= \sqrt{\frac{\sigma B_0^2}{\rho V}}$  is the Hartmann number. With the following<br>
undary conditions:<br>  $F(0) = 1$ ,  $F'(1) = 0$ ,  $F'(0) = 0$ , (9)<br>  $\zeta(1) = 1$ ,  $\zeta'(0) = 0$ . (9)<br>
Note that in olds number,  $Ec = \frac{U^2}{(C_p)_f T_w}$  is Eckert number and<br>  $\frac{GB_0^2}{\rho v}$  is the Hartmann number. With the following<br>
lary conditions:<br>
0) = 1,  $F(1) = 0$ ,  $F'(0) = 0$ , (9)<br>
1) = 1,  $\zeta'(0) = 0$ .<br>
(9)<br>
te that in the case of  $\$ 

boundary conditions:

$$
F(0) = 1, F(1) = 0, F'(0) = 0,
$$
  
\n
$$
\zeta(1) = 1, \zeta'(0) = 0.
$$
\n(9)

Note that in the case of  $\alpha = 0$ , the flow acts very much like that of a plane Poiseuille flow between two parallel plates. The skin friction coefficient, local Nusselt number, heat transfer rate and shear stress can be defined as:

Reynolds number, 
$$
Ec = \frac{U}{(C_p) f_w}
$$
 is Eckert number and  
\n $H = \sqrt{\frac{\sigma B_0^2}{\rho V}}$  is the Hartmann number. With the following  
\nboundary conditions:  
\n $F(0) = 1$ ,  $F(1) = 0$ ,  $F'(0) = 0$ , (9)  
\n $\zeta(1) = 1$ ,  $\zeta'(0) = 0$ .  
\nNote that in the case of  $\alpha = 0$ , the flow acts very much like  
\nthat of a plane Poiseuille flow between two parallel plates.  
\nThe skin friction coefficient, local Nusselt number, heat trans-  
\nfer rate and shear stress can be defined as:  
\n $c_f = \frac{\tau_w}{\rho_f U^2}$ ,  $Nu = \frac{rq_w|_{\theta = \alpha}}{k_f T_w}$ ,  
\n $q_w = -k_w \nabla T$ ,  $\tau_w = \mu_w \left( \frac{1}{r} \left( \frac{\partial u(r, \theta)}{\partial \theta} \right) \right)$ .  
\nSubstitution of Eq. (10) into Eqs. (8) and (9), gives:  
\n $c_f = \frac{1}{\text{Re}(1 - \phi)^{2s}} F'(1)$ ,  $Nu = -\frac{1}{\alpha} \frac{k_{u'}}{k_f} \zeta'(1)$ . (11)  
\n3. Solution procedure  
\nTo recognize the best value of the Lagrange multiplier, the  
\nprocedure of Laplace transform can be employed.  
\nConsider  $x, t$  as two independent variables, where  $x, t$  are  
\nthe principal and secondary variables, respectively. Assuming  
\n $w(x, t)$  as a function of two variables (i.e.,  $x$  and  $t$ ), the

Substitution of Eq. (10) into Eqs. (8) and (9), gives:

$$
c_f = \frac{1}{\text{Re}(1-\phi)^{2s}} F'(1), \quad Nu = -\frac{1}{\alpha} \frac{k_{nf}}{k_f} \zeta'(1).
$$
 (11)

### **3. Solution procedure**

To recognize the best value of the Lagrange multiplier, the procedure of Laplace transform can be employed.

the principal and secondary variables, respectively. Assuming

Laplace transform can be defined as:

( ) ( ) 0 æ ö - ç ÷ <sup>=</sup> è ø <sup>ò</sup> (12) *t t* ¥ æ ö ¶ è ø ¶

We can use some preliminary information as follows:

$$
L\left(\frac{\partial w}{\partial t};s\right) = \int_{0}^{\infty} e^{-st} \frac{\partial w}{\partial t} dt = sW(x,s) - w(x,0)
$$
 will achieve, (13)

$$
L\left(\frac{\partial^2 w}{\partial t^2};s\right) = s^2 W(x,s) - sW(x,s) - w_t(x,0) \qquad (14)
$$

$$
W(x,s) = L\bigg(w(x,t) \; ;s\bigg). \tag{15}
$$

*M. Azimi and R. Riazi / Journal of Mechanical Science and Technology 30 (10) (2016) 4679–4686*<br>
place transform can be defined as:<br>  $L\left(w(x,t): s\right) = \int_{0}^{x} e^{-x} w(x,t) dt$ .<br>
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W *M. Azimi and R. Riazi / Journal of Mechanical Science and Technology 30 (10) (2016) 4679–468<br>
nsform can be defined as:<br>*  $W(x, s) = \frac{L\left[h\{(x, t, w)\}\right]}{B(s)}$ *.<br>*  $w(x, t)dt$ *.<br>
(12)<br>
sue some preliminary information as follows:<br> \begin* There are certain functions that could not be considered as the transform of some known functions but, at the same time, they could possibly be assumed as a product of two functions.  $L\left(w(x, t): s\right) = \int_{0}^{1} e^{-x} w(x, t) dt.$  (12)<br>
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We can use some preliminary information as follows:<br>  $L\left(\frac{\partial w}{\partial t}, s\right) = \int_{0}^{3} e^{-x} \frac{\partial w}{\partial t} dt = sW(x, s) - w(x, 0)$  (13)<br>  $L\left(\frac{\partial w}{$ *L*(*w*(*x,t*) :*s*) =  $\int_0^{\infty} e^{-x} w(x,t) dt$ . (12)<br>
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Leglace function on right<br>
Leglace functions  $L\left(\frac{\partial^2 w}{\partial t^2}; s\right) = \int_0^x e^{-x} \frac{\partial w}{\partial t} dt = sW(x, s) - w(x, 0)$  (13)<br>  $L\left(\frac$ Suppose that  $D(s) = 1/\mu(s)$ ; we can use the convolution<br>
We can use some preliminary information as follows:<br>  $L\left(\frac{\partial w}{\partial t},s\right) = \int_0^{\pi} e^{-u} \frac{\partial w}{\partial t} dt = sW(x,s) - w(x,0)$ <br>  $L\left(\frac{\partial^2 w}{\partial t^2},s\right) = s^2W(x,s) - sW(x,s) - w(x,0)$ <br>  $W(x,s) = L\left(w(x$ the Laplace Transform of  $\int_{0}^{1} w(x,t-\varepsilon)z(x,\varepsilon) d\varepsilon$ : :  $s = s^2W(x,s) - sW(x,s) - w, (x, 0)$  (14)<br>  $\int_0^{1} s^2 dx = 0.$  (x, s) -  $\int_0^{1} K(x,s) - W(x,s) dx = 0.$ <br>  $\int_0^{1} s^2 dx = 0.$  (x, s) -  $\int_0^{1} K(x,s) dx = 0.$ <br>  $\int_0^{1} (x, t) dx = 0.$ <br>  $\int_0$  $t^2$   $(\partial_t^{x,y}) = \int_0^{x} \partial_t^{x} dx = 3x/4x, y - h(x, y)$ <br>  $h(x, t) = w_0(x, t) + \int_0^1 d(t - \varepsilon)h(x, \varepsilon, w) d\varepsilon$ .<br>  $\left(\frac{\partial^2 w}{\partial t^2}, s\right) = s^2W(x, s) - sW(x, s) - w_1(x, 0)$ <br>
(14)  $W(x, t) = w_0(x, t) + \int_0^1 d(t - \varepsilon)h(x, \varepsilon, w) d\varepsilon$ .<br>
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the turasform of Some known functions but, at the same time, and using initial guess as  $f_n(\eta) = a\eta^2 + 1$  where a is considered as the transform of the functions *y* could possibly be assumed as a product of two functions.<br>
the following relation can be obtaine<br> *L* and  $Z(s)$  are considered as the transform of the func-<br> *L* and  $Z(s)$  are considered as the transform of the func-<br>

$$
L^{-1}(W(x,s),Z(x,s)) = \int_{0}^{t} w(x,t-\varepsilon)z(x,\varepsilon)d\varepsilon.
$$
 (16) Using Eq. (22) the analytical solutions can be achieved.

To explain the difference between classical variational iteration method and Reconstruction of variational iteration method (RVIM), we introduce the novel nonlinear or linear function

$$
L(w(t,x)) = h(t,x,w).
$$
\n(17)

Using a novel idea based on Laplace transform theorem and applying the mentioned transform to the both sides of Eq. (17), we can implement the correctional function of variational iteration method; therefore, the artificial initial conditions can be fixed to zero for the current problem and the left hand side of Eq. (17), after applying Laplace transformation, might be rewritten as follows: *L* (*N*),  $-q$  (*L*),  $\sqrt{h(x,t)} = f(W(x,t)) = f(W(x,t))$  and  $\sqrt{h(x,t)} = \sqrt{h(x,t)} = \sqrt{h(x,t)}$  and  $\sqrt{h(x,t)} = \sqrt{h(x,t)} = \sqrt{h(x,t$ explain the difference between classical variational itera-<br>
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M), we introduce the novel nonlinear or linear function tween convergin explain the difference between classical variational itera-<br>
method and Reconstruction of variational iteration method<br>
(M), we introduce the novel nonlinear or linear function<br>
(W(x,t)) = q(x,t) – N(w(x,t)) and supposing In the book and Note (Substituted) of Variational relation incernal relation the book and variables in the book and variables in the solution, write  $h(w(x,t)) = q(x,t) - N(w(x,t))$  and supposing the novel amounts of solid volume<br>  $L(w(t$ 

$$
L\big[L\big\{w(x,t)\big\}\big]=W\big(x,s\big)B\big(s\big)\,.
$$
 (18)

trary function is the highest order derivative of linear operator, which can be seen as follows:

$$
L\left[L\left\{w(x,t)\right\}\right] = W(x,s)B(s) = L\left[h\left\{(x,t,w)\right\}\right]
$$
 (19)

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\n
$$
W(x,s) = \frac{L\left[h\{(x,t,w)\}\right]}{B(s)}.
$$
\nSuppose that  $D(s) = 1/B(s)$ ; we can use the convolution  
eorem to find the initial solution. By applying the inverse  
nplace function on right side and left side of Eq. (19), we

<sup>22</sup><br> *M. Azimi and R. Riazi / Journal of Mechanical Science and Technology 30 (10) (2016) 4679-4686*<br>
place transform can be defined as:<br>  $L\left(w(x,t):s\right) = \int_{0}^{\infty} e^{-st} w(x,t) dt.$ <br>
(12)<br>
We can use some preliminary information 2 <br>
2 *M. Azimi and R. Riazi / Journal of Mechanical Science and Technology 30 (10) (2016) 4679-4686*<br>
Dlace transform can be defined as:<br>  $L\left(w(x,t):s\right) = \int_{0}^{\pi} e^{-u} w(x,t) dt.$ <br>
(12)<br>
We can use some preliminary information a *M. Azimi and R. Riazi / Journal of Mechanical Science and Technology 30 (10) (2016) 4679-4686*<br>
ace transform can be defined as:<br>  $\left(w(x, t) : s\right) = \int_0^{\infty} e^{-st} w(x, t) dt.$ <br>
(and use some preliminary information as follows:<br>  $\$ *M. Azimi and R. Riazi / Journal of Mechanical Science and Technology 30 (10) (2016) 4679-4686*<br>
transform can be defined as:<br>  $W(x,s) = L\left[h\{(x,t,w)\}\right]$ .<br>  $x,t$   $s$ ,  $s$ ) =  $\int_{0}^{\pi} e^{-\alpha} w(x,t) dt$ .<br>
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Suppose that  $D(s) = 1/B(s)$ *L*  $\left(\frac{\partial w}{\partial t}, s\right) = \int_0^s e^{-st} \frac{\partial w}{\partial t} dt = sW(x, s) - w(x, 0)$ <br> *L*  $\left(w(x, t) \right)$ ;  $\left(\frac{\partial w}{\partial t}, s\right) = \int_0^s e^{-st} w(x, t) dt.$ <br> *L*  $\left(\frac{w(x, t)}{w(x, t)}\right) = \int_0^s e^{-st} w(x, t) dt.$ <br> *L*  $\left(\frac{\partial w}{\partial t}, s\right) = \int_0^s e^{-st} \frac{\partial w}{\partial t} dt = sW(x, s) - w(x, 0)$ <br> M. Azimi and R. Riazi / Journal of Mechanical Science and Technology 30 (10) (2016) 4679-4686<br>
ace transform can be defined as:<br>  $\begin{aligned}\nw(x,t) : s^2 &= \int_0^x e^{-x} w(x,t) dt. \\
\text{We can use some preliminary information as follows:} \\
\left(\frac{\partial w}{\partial t}, s\right) &= \int_0^x e^{-x} \frac{\partial w}{\partial t} dt = sW(x,s)$ bechnology 30 (10) (2016) 4679-4686<br>  $\begin{aligned}\ns(s) &= \frac{L\left[h\{(x,t,w)\}\right]}{B(s)}.\n\end{aligned}$ (20)<br>
ose that  $D(s) = 1/B(s)$ ; we can use the convolution<br>
1 to find the initial solution. By applying the inverse<br>
1 to find the initial solution. *and Technology 30 (10) (2016) 4679-4686*<br> *W*  $(x, s) = \frac{L[h\{(x, t, w)\}]}{B(s)}$ . (20)<br>
Suppose that  $D(s) = 1/B(s)$ ; we can use the convolution<br>
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(*s*) = 1/*B*(*s*); we can use the convolution<br>
the initial solution. By applying the inverse<br>
on right side and left side of Eq. (19), we nology 30 (10) (2016) 4679-4686<br>  $=\frac{L\left[h\{(x,t,w)\}\right]}{B(s)}$ . (20)<br>
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Suppose that  $D(s) = 1/B(s)$ ; we can use the convolution<br>
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place function on right side and l theorem to find the initial solution. By applying the inverse Laplace function on right side and left side of Eq. (19), we will achieve, Fechnology 30 (10) (2016) 4679-4686<br>  $(x, s) = \frac{L[h\{(x, t, w)\}]}{B(s)}$ . (20)<br>
Dose that  $D(s) = 1/B(s)$ ; we can use the convolution<br>
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place functi and Technology 30 (10) (2016) 4679-4686<br>
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Suppose that  $D(s) = 1/B(s)$ ; we can use the convolution<br>
theorem to find the initial solution. By applying the inverse<br>
Laplace function on right side and left side of Eq. (19), we<br>
will (*s*); we can use the convolution<br>solution. By applying the inverse<br>side and left side of Eq. (19), we<br> $-\varepsilon h(x,\varepsilon,w) d\varepsilon$ . (21)<br>itial solution and it could contain<br>it. Without unknown parameters, the<br>must be satisfied by

$$
w(x,t) = w_0(x,t) + \int_0^t d(t-\varepsilon)h(x,\varepsilon,w)d\varepsilon.
$$
 (21)

unknown parameters or not. Without unknown parameters, the

and using initial guess as  $f_0(\eta) = a\eta^2 + 1$  where a is constant, the following relation can be obtained:

, , *<sup>t</sup> w x t z x d* - <sup>e</sup> <sup>e</sup> <sup>e</sup> <sup>ò</sup> ( ) ( ) ( ) ( ) ( ( ) ) ( ) 1 0 2.5 2 0 1.25 <sup>2</sup> 2 Re 1 1 . <sup>2</sup> 4 1 *n s s <sup>f</sup> f f ff <sup>s</sup> ds H f* <sup>h</sup> <sup>h</sup> <sup>r</sup> <sup>a</sup> <sup>j</sup> <sup>j</sup> <sup>j</sup> <sup>h</sup> <sup>r</sup> <sup>j</sup> <sup>a</sup> <sup>+</sup> = æ ö é ù æ ö ç ÷ ê ú ç ÷ - + - ¢ - + × ê ú ë û è ø + - - ¢ è ø ò (22)

#### **4. Results and discussion**

The obtained results of copper-water nano-fluid flow between converging-diverging plates considering various amounts of solid volume fraction, Eckert, Reynolds and Hartman numbers is studied in this section.

The effect of increment of Reynolds number on fluid velocity is demonstrated in Fig. 2(a), assuming a constant Hartmann  $f_{n+1}(\eta) = f_0(\eta)$ <br>  $+ \int_{\eta}^{2} 2\alpha \text{Re}\left[ \left( (1-\varphi) + \frac{\rho_*}{\rho_f} \varphi \right) (1-\varphi)^{2s} \right] d\eta'$ <br>  $+ \left( 4 - (1-\varphi)^{1.5} H \right) \alpha^2 f'$ <br>
Using Eq. (22) the analytical solutions can be achieved.<br> **4. Results and discussion**<br>
The obtained r that the occurrence of back flow could be possible in large Reynolds numbers, as depicted in Fig. 2(a), for the case of diverging channels.

 $L[x(x, x)] = h(t, x, w)$ .<br> *Livi* is demonstrated in Fig. 2(a), assuming a constant Hampy<br>  $L[\text{w}(x, x)] = h(t, x, w)$ .<br>
Using a novel idea based on Laplace transform theorem and<br>
that the occurrence of back flow could be possible in<br>
c ( $w(t,x)$ ) =  $h(t,x,w)$ .<br>
(17) ity is demonstrated in Fig. 2(a), assuming a constant Hartmar<br>
ing a novel idea based on Laplace transform theorem and that the occurrence of hack flow could be possible in la<br>
infigure mentioned Fig. 2(b) illustrates the effect of variation of Hartmann number on velocity profile for a diverging channel. Based on the results of Fig. 2(b), one could suggest that by increment of Hartmann number the rate of momentum transport would considerably be decreased. This is because the variation of Hartmann number would lead to the change of the Lorentz force (considering the effect of magnetic field) and, as a con sequence, the modified Lorentz force may result in a higher resistance to the transport of flow. number of  $H = 500$  along with  $\alpha = \pi / 18$ ,  $\phi = 0.1$ . Note<br>that the occurrence of back flow could be possible in large<br>Reynolds numbers, as depicted in Fig. 2(a), for the case of<br>diverging channels.<br>Fig. 2(b) illustrates

Furthermore, the parameter of nanoparticle volume fraction could play a key role on behavior of the flow field. Particularly, it has a significant effect on both the velocity and temperature fields. The effect of variation of solid volume fraction for the copper nanoparticles upon temperature profile, considering the





Fig. 3. Effect of variation in the volume fraction of Nanoparticle upon



Fig. 4. Influence of change of angle between plates on Velocity profile channel; (b) diverging channel.

indicated in Fig. 3.

By addition of solid volume fraction of nanofluid the ther mal boundary layer thickness would reduce. Hence, the in crease of Cu-nanoparticles volume fraction could result in reduction of dimensionless temperature due to increase of the heat transfer rate. Two considerable properties of nanofluids are usually noticed by the energy related communities. The first characteristic is the higher thermal conductivity of nan ofluids, which can lead to increment of heat transfer. The other important property of nanofluids is their absorption characteristic. In this study, the absorption properties of Cu- Water nanofluid have been assumed to be negligible.

By keeping the Reynolds and Hartman numbers constant, the influence of channel half-angle upon velocity profile for (a) converging channel and (b) diverging channel is illustrated in Figs. 4(a) and (b), respectively. It is obvious that the dimen-



Fig. 5. Effect of change of Eckert number upon the temperature profile

sionless velocity is a decreasing function of  $\alpha$ , whereas this dimensionless variable (dimensionless velocity) grows when  $\alpha$  is added in convergent channel. So, by increment of the channel half-angle (for converging channels) due to the in crease of the effect of favorable pressure gradient, the fluid elements near the wall would accelerate. The influence of Eckert number variation upon dimensionless temperature profiles is indicated in Fig. 5. Based on the results (see Fig. 5), one could suggest that by increment of Eckert number, due to the related effects of frictional heating, the heat energy would be stored in the liquid and, consequently, the temperature would be increased.

The variation of Nusselt number and the skin friction coefficients with the parameters such as solid volume fraction,  $H = 250$ ,  $Re = 25$ ,  $\alpha = \pi/36$ ,  $\phi = 0.0$ . Eckert number, Reynolds and Hartman numbers are presented in Tables 2 and 3, respectively.

Based on the calculations discussed earlier, (Eq. (6)) and Table 2, one can thoroughly consider that generally, by addition of nanoparticles to the working fluid, the value of the Nusselt number would be increased. Moreover, the other result from Table 2 is that the variation in the magnitude of Eckert number has certain influences on the change of Nusselt number. Note that the viscous dissipation effects (related to the increase of Eckert number) would lead to the increment of fluid temperature between the two nonparallel plates. Consequently, by increase of the Eckert number, the magnitude of<br>the Nusselt number would be enhanced.<br>( $\phi = 0.1$ ,  $\phi = 0.2$ ) are employed in the current investigation. the Nusselt number would be enhanced.

The effects of channel half-angle, Reynolds and Hartmann numbers upon the coefficient of skin friction are given in Ta ble 3. The results show that by addition of Reynolds number and the amount of opening angle, the coefficient of skin friction enhances. In contrast, increment of the Hartmann number would result in reduction of the coefficient of skin friction. To study the effect of concentration of nanoparticle upon the in creased heat transfer performance of nanofluid, the Cu-water nanofluid with two different particle volume fractions



	nce and Technology 30 (10) (2016) 4679~4686		
		Table 2. Nusselt number for the case of $H = 50$ and $\alpha = 15^\circ$ .	
Solid volume			
fraction	Eckert number	Reynolds number	Nusselt number
$0.1\,$	0.1	50	4.9010
0.2	0.1	50	7.0706
0.1	0.2	50	9.8024
$0.2\,$	$0.2\,$	50	14.141
$0.1\,$	0.1	100	9.4166
$0.2\,$	0.1	100	13.8571
0.1	0.2	100	18.8331

Table 3. Skin friction coefficient in case  $\phi = 0.15$ .

	Angle between plates	Hartmann number	Reynolds Skin friction number coefficient		
	5 degree	50	25		$-0.1771$
	10 degree	50	25		$-0.2173$
	100 5 degree		25		$-0.1802$
10 degree		100	25		$-0.2282$
5 degree		50	50		$-0.1049$
	10 degree	50	50		$-0.1377$
	5 degree	100	50		$-0.1063$
	10 degree	100	50		$-0.1424$
		Table 4. Comparison between RVIM, DTM and NM (Ganji, Azimi, 2013) regarding the calculation of velocity for the case of $H = 250$ , Re = 25, $\alpha = \pi/36$ , $\phi = 0.0$ .			
$\eta$	Numerical solution	<b>RVIM</b>	DTM [17]	%Error (DTM)	$%$ Error (RVIM)
$\boldsymbol{0}$	1.0000	1.0000	1.0000	0.00	0.00
02	0.9547	0.9502	0.9412	142	0.45

Table 4. Comparison between RVIM, DTM and NM (Ganji, Azimi, 2013) regarding the calculation of velocity for the case of



The relationship between Eckert number and Nusselt number cannot be generally formulated. This may be due to the com plications of the proposed model. Nevertheless, the present study provides a good base for further research.

The following relation introduces the percentage of error as:

$$
\%Error = \left| \frac{F(\eta)_{_{NM}} - F(\eta)_{_{RVM}}}{F(\eta)_{_{NM}}}\right| \times 100 \,. \tag{23}
$$

Table 4 provides the comparison of numerical results, con sidering the DTM (Ganji, and, Azimi, 2013) and RVIM solutions, regarding the calculation of velocity for different values of  $\eta$ . Table 4 shows that the results of reconstruction of  $\eta$ itteration of variational method are in good agreement with  $\theta$ those of the numerical method. This demonstrates the capa- $\rho$ bility of RVIM for dealing with such problems and solving  $\phi$ them in engineering and related fields. Based on the error  $\mu$ analysis, RVIM can be more useful to find better solutions  $\nu$ than DTM.

#### **5. Conclusions**

This investigation deals with the analysis of heat transfer and MHD viscous copper water nanofluid flow between two  $\infty$ non-parallel walls for both converging/ diverging cases.

Based on the achieved results, increment of the intensity of f magnetic field could lead to a considerable stabilizing effect S on the growth of boundary layer for both geometries of diverging and converging channels.

The results show that the non-dimensional parameters have strong influences on the temperature profile. The main findings are summarized below:

- Increase of the solid volume fraction of nanofluid could lead to reduction of the thickness of thermal boundary layer (due to the higher heat transfer rate that is created).

- Nusselt number is enhanced by increment of Reynolds number, *Ec* (the Eckert number) and the amount of solid volume fraction.

- Skin friction coefficient would increase with addition of Reynolds number and the amount of opening angle. However, by increment of Hartmann number, the skin friction coefficient would be reduced. - Comparing the analytical results with numerical calcula-

tions (which were achieved by fourth order Runge-Kutta method), one could suggest that the RVIM could be considered as a simple, powerful and efficient technique that can be employed regarding the analytical solutions of non-linear differential equations in various scientific and engineering related applications.

# Nomenclature---

- *B<sup>0</sup>* : Magnetic field  $\lceil \text{wb/m}^2 \rceil$
- *Ec* : Eckert number
- *F(η)* : Dimensionless velocity
- *Ha* : Hartmann number
- P : Pressure term
- Pr : Prandtl number
- Re : Reynolds number
- *r, θ* : Cylindrical coordinates
- *T* : Temperature
- *T<sup>w</sup>* : Wall temperature
- *Umax* : Maximum value of velocity
- *u, v* : Velocity components along x, y

#### *Greek symbols*

- $\alpha$  : Semi-Angle between two plates
- : Dimensionless angle
- : Angle
- : Density
- : Nanoparticle volume fraction
- : Dynamic viscosity
- : Kinematic viscosity
- $\zeta$  : Dimensionless temperature
- $\beta$  : Thermal expansion coefficient

#### *Subscript*

- : Condition at infinity
- *nf* : Nanofluid
- *f* : Base fluid
- : Solid particles

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