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Effect of process parameter on wire cut EDM using RSM method

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Abstract

The article aims to estimate the importance of machining parameters for the performance measure material removal rate (MRR) in the Wire Electrical Discharge Machining (WEDM) processing of MONEL 400 K. Wire feed, Time On and Time Off (downtime) have been discovered to be more impactful in deciding the MRR criterion substantially. The significant contribution of relevant input parameters varies according to the objective response behaviour of the parameter. The effect of Time off is the inverse of Pulse on Time, and it leads to the increased MRR as Time off increases, but surface roughness decreases. The material was flushed away effectively during higher Time off, leading to good-quality machined components. It endeavoured to recognize the most significant machining factors for experimentation, and the response surface methodology (RSM) strategy tracks down the best arrangement of boundaries for increasing the MRR. Parametric evaluation on WEDM of MONEL 400 K stands new in this study which many researchers fail to explore in detail followed by response surface methodology to analyse the results. The conformity tests were completed to assess the RSM strategy's expected outcome, proving promising. The results confirmed that the increased MRR of 0.06938 gm/min is obtained at the optimal level of pulse On Time of 10 μs, down Time of 2 μs, and wire feed rate of 4 m/min.

Keywords WEDM · Time on · Down Time · MRR · RSM

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Abbreviations

1 Introduction

WEDM is a pulsating direct flow technique that pulverizes and removes material by transforming plasma formed by electric flashes between two conductive materials (such as terminal and workpiece) into heat energy [\[1\]](#page-11-0). An electric flash can occur between a small hole in a dielectric liquid and the anode, which is detrimental to the material. When the pulsating flow stops, the plasma splits, causing a temperature drop so that the broken material is removed with the help of a dielectric liquid [\[2](#page-11-1)[–4\]](#page-11-2). There is a range of 15–30° for a 100 mm thick cut surface material [\[5\]](#page-11-3). Water is deionized by passing it through a pitch tank, which removes the conducting components of water. This deionized water circulates the siphon after the machining process [\[6\]](#page-11-4). The Pulse on Time, margin time, communication between dielectric tension and margin time, and collaboration between the heartbeat on Time and Free Time are all essential elements influencing the WEDM flash gap. To get the smallest flash hole, it is possible to use a low value of Pulse On Time (20 μ s), a high value of dielectric pressure (15 kef/cm²), a high value of margin time (50 s), and a voltage of 50 V. If the Pulse on and off periods are adjusted to result in wire breakage and increased machining time, the model will correspond to the compliance findings [\[6\]](#page-11-4). An objective of the study is to involve Taguchi's L18 symmetrical cluster to streamline process boundaries for single reaction improvement was studied. H-21 pass-on device steel was utilized as the workpiece cathode, and zinc-covered metal wire was used as the apparatus anode in the examinations [\[7\]](#page-11-5). The responses are cut-rate, surface roughness, and kick-the-bucket width. Overseeing different execution qualities as limitations improves the most impressive strategy instead of other techniques. The consequences of the investigation are then changed over into a sign-to-noise ratio (S/N) proportion. The S/N proportion can decide how far the presentation qualities are from the objective worth. The interaction boundary's ideal level has the most elevated S/N proportion. To determine if process boundaries are measurably critical, a factual investigation of change (ANOVA) is utilized [\[8\]](#page-11-6). Taguchi designs of trials were used to rationalize surface roughness, kerf, and MRR [\[9\]](#page-11-7). Analysis of Variance (ANOVA) identifies the optimal value and the key factor affecting surface roughness, kerf, and material removal rate [\[10\]](#page-11-8). The completed wire EDM utilizes the L16 Orthogonal exhibit, using steel and Molybdenum wire as work materials [\[11\]](#page-11-9). Taguchi strategy-based grey investigation to test WEDM of Mg parts considering various quality measures, including material evacuation rate and surface severity [\[12\]](#page-11-10). Wire feed rate, Pulse on Time, Pulse off Time, no heap voltage, servo voltage, and wire strain are among the muddled connections in WEDM [\[13\]](#page-11-11). Different machining factors will influence the surface quality and MRR of the machined surface utilizing wire EDM [\[14\]](#page-11-12). The WEDM process is typically completed in a lowered state in a tank loaded with dielectric liquid, even though it can likewise be done in a dry form.

Based on the above literature review, the present work focuses on the conditions where the WEDM of the work specimens (MONEL 400 K) with three parameters varied at three levels is conducted. The novelty of the current work deals with the WEDM of MONEL 400K for the evaluation of the material removal rate (MRR) by varying the input parameters (Wire feed, Time On and Time Off (downtime)) at three different levels. Minimal researchers worked on the parametric optimization of WEDM of MONEL 400K's performance evaluation experimentally and statistically. The use of response surface methodology (RSM) for response prediction and analysis (through interaction and surface plots) would become more useful and advantageous for the researchers and industrialists to choose the optimal level for machining. The statistical result from the present study would also stand more promising in its implementation in the current industrial sector.

2 WEDM response variables and process parameters

WEDM's primary objectives are to achieve excellent dependability and productivity. As new and more exceptional materials are created, and more complex shapes are required, conventional machining operations will continue to reach its limits, and the use of WEDM in manufacturing will increase rapidly. However, because WEDM procedures involve numerous variables, optimal execution is challenging. The most effective approach to this problem is establishing a relationship between the interaction's reaction elements and regulated information bounds.

2.1 Experiment work and measurement

The experiment is designed and conducted at the sprint cut wire cut electro discharge machine shown in Fig. [1.](#page-2-0) The primary objective of this research is to determine how changing the input machining parameters influences theMRR response for obtaining the optimal and desired values.

2.2 Theoretical investigation of WEDM machining factors

Many components are involved in the WEDM process, making it exceedingly complicated and affecting performance. As a result, a thorough understanding of the machining factors is required. WEDM machining factors are divided into two categories.:

i. Pulse on Time, downtime, peak current, and servo voltage are all electrical considerations [\[15\]](#page-11-13).

the current investigation

Table 1 Varying process parameters and its levels

ii. Wire tension, wire feed rate, dielectric pressure, type of dielectric, dielectric flow rate, dielectric conductivity, wire diameter and material, workpiece thickness, and workpiece characteristics are non-electrical parameters.

The right combination of these elements must be chosen to obtain optimal machining performance [\[16\]](#page-11-14).

2.3 Machining process

The WEDM process has several machining characteristics that must be tuned for improved performance and economy. Table [1](#page-2-1) contains the process parameters and levels used in the present study. Various machining features were investigated in this study. These are discussed in the following order:

2.3.1 Material removal rate (MRR)

Material removal rate refers to the rate at which material is removed from the workpiece. It determines the economics and output rate of WEDM machining. In this study, the MRR is calculated using the following formula.MRR $=$ *Weight of material removed* am/min The world to f the material

Time taken in min gm/min The weight of the material

removed may be estimated by weighing the workpiece before and after cutting. The workpiece's weight is determined using a weighing scale with a minimum count of 0.01 g [\[17\]](#page-11-15).

2.3.2 Kerf width (KW)

WEDM makes use of kerf width as one of its primary exhibition indicators. The material determines the accuracy of the finished product wasted during the manufacturing process. Additionally, the kerf width restricts the inside corner radius produced by a WEDM method. When selecting machining parameters, the primary objective is to maximize MRR while minimizing Kerf width.

3 Results and discussion

The most efficient use of the WEDM process is carefully choosing the correct machining parameters combinations. Because the approach is multidimensional and stochastic, this can be accomplished by accepting the link between many elements affecting the process and determining the best cutting conditions. As a result, testing on a specific machine is required to assess the impact of machining parameters on performance characteristics such as material removal rate (MRR), kerf width, overcut, dimensional deviation, and recast layer thickness [\[18\]](#page-11-16).

3.1 Experimental results

The WEDM experiments are carried out with the help of a randomization tool to investigate the impacts of process

Table 2 Machining parameters

parameters on the output characteristics of the process parameters and interactions assigned to the columns. The same has been tabulated in Table [2.](#page-3-0) In an experiment, randomization refers to the assignment of trials at random. This way, any potential biases in the analysis will be eliminated. In an investigation, randomization is significant since it reduces biased responses.

Table [3](#page-4-0) shows the results of experiments on kerf width and MRR at four distinct places on the workpiece. Taguchi's design of experiments is used to conduct the tests, and each process is repeated three times to produce S/N ratios [\[19\]](#page-11-17). Because kerf width influences dimensional accuracy and a very smooth surface finish is needed, the lower-the-better (LTB) characteristic is used to compute the S/N ratio of these characteristics. Still, the higher-the-better (HTB) characteristic is used to calculate the S/N ratio of MRR because we need more productivity. Minitab statistical software was utilized for this study's designs, plots, and analyses. Images of the specimen before and after machining and specimens cut out from it are given in Figs. [2](#page-4-1) and [3.](#page-4-2)

3.2 Process parameter optimization of WEDM by RSM

Response Surface Methodology (RSM) is valuable for managing multi-variable reactions. It's intended to assist with process enhancement and tracking down the best blend of boundaries for a specific response. Compared with a full factorial plan of investigations, this methodology enormously decreases the number of preliminaries expected to show the reaction capability [\[20\]](#page-11-18).

The essential advantage of this strategy is that it allows you to discover potential interactions between variables. The signal-to-noise ratio is used to investigate the experimental results and aid in selecting the best process design. This method worked well for analyzing the wear behaviour of composite materials and used the "smaller the better" quality criteria to calculate the MRR under various EDM process parameters [\[21\]](#page-11-19). The significance and forecast were examined using DOE's RSM, a sophisticated statistical method with 95% confidence limit as an uncertainty test condition to check the correctness of the obtained results. The following are the input parameters for this WED project: Ton, Toff, Wire feed, Voltage, Current. The responses are machining time, Kerf width, and MRR (output parameters) [\[22\]](#page-11-20).

3.3 Material removal rate by RSM analysis

The Sum of squares is Type III - Partial

The F-value of 12.72 for the model shows that it is essential. An F-value of this model has a 0.29 per cent chance of happening because of commotion, and the same has been tabulated in Table [4.](#page-5-0)

Model terms with P-esteems under 0.0500 are critical. B and BC are significant model terms in this situation with results falling within the 95% confidence interval. The model terms are insignificant, assuming the worth is more significant than 0.1000. The model decrease might work on your

Table 3 WEDM factors and responses	Run order	Pulse on time (μs)	Downtime (μs)	Wire feed rate (m/min)	Kerf width (mm)	MRR (gm/min)
	16	7	$\overline{\mathcal{A}}$	2	0.339	0.05165
	11	8	3	2	0.346	0.05291
	6	9	\overline{c}	2	0.343	0.04471
		10		2	0.324	0.05825
	15	7	3	4	0.338	0.05264
	12	8	4	4	0.336	0.04325
	5	9		4	0.339	0.05871
	\overline{c}	10	2	4	0.346	0.06938
	9	8		6	0.342	0.06346
	8	9	$\overline{4}$	6	0.345	0.01592
	3	10	3	6	0.344	0.04825
	13	7	1	8	0.337	0.05698
	14	7	2	8	0.335	0.05864
	10	8	\overline{c}	8	0.339	0.05268
	7	9	3	8	0.347	0.02864
	4	10	4	8	0.349	0.00851

Fig. 2 a Before machining, **b** After Machining

Fig. 3 Samples after machining

model, assuming there are numerous immaterial model terms (excluding those expected to help order) [\[23\]](#page-11-21).

3.4 Fit statistics

The Adjusted \mathbb{R}^2 of 0.8755 isn't as close to the Predicted $R²$ of 0.3902 as one would suspect; the thing that matters is more prominent than 0.2. This could indicate a considerable block impact or an issue with your model or information. Model decreases, reaction changes, anomalies, and different variables should be considered. Affirmation runs ought to be utilized to test every experimental model, and the fit statistics results are given in Table [5.](#page-5-1)

Adeq Precision estimates the sign-to-commotion proportion. Having a proportion of more than four is ideal. Your sign strength is satisfactory, as shown by your proportion of 13.474. The planned space can be explored utilizing this idea.

3.4.1 Coefficients in terms of coded factors

When any remaining elements are consistent, the coefficient gauge gives the normal change per unit change in factor esteem. In a symmetrical plan, the capture is the typical general reaction of various runs. The coefficients are changes in light of the variable settings around that normal. The Variance Inflation Factor (VIFs) are 1 when the elements are symmetrical; VIFs more than 1 infer multi-collinearity; the 2962 International Journal on Interactive Design and Manufacturing (IJIDeM) (2024) 18:2957–2968

Table 5 Fit statistics

higher the VIF, the more serious the component connection. VIFs of less than ten are viewed as average. The co-efficient obtained for these results is given in Table [6.](#page-5-2)

3.4.2 Final equation in terms of coded factors

 $MRR = 0.0526 + +0.0026$ A $-$ 0.0148 B $-$ 0.0022 C 0.0093 AB − 0.0003 AC − 0.0158 BC + 0.0068 A² − 0.0078 $B^2 - 0.0071 C^2$

The reaction may be predicted using the coded factor equation for a given set of element values. By default, 1 is assigned to a factor's highest level, while -1 is assigned to its lowest. It is possible to assess the relative significance of the variables in the encoded equation by contrasting their factor coefficients.

3.4.3 Final equation in terms of actual factors

 $MRR = 0.106823 - 0.038611$ Pulse on Time $+ 0.060000$ Downtime + 0.016624 Wire Feed Rate − 0.004128 Pulse on Time * Downtime − 0.000076 Pulse on Time * Wire Feed Rate − 0.003514 Downtime * Wire Feed Rate + 0.003004 Pulse on time² − 0.003447 Downtime² − 0.000792 Wire Feed Rate2

It is possible to produce predictions about the response by using the equation expressed in terms of actual factors for a set of element values that have already been determined. It is important to indicate the levels of each element in its respective initial units. This equation should not be used to evaluate the relative influence of each factor because the coefficients

Table 6 Coefficients in terms of coded factors

Run Number

are scaled to suit the units of each element, and the intercept is not at the centre of the design space. Instead, a more appropriate equation should be used to do so [\[24\]](#page-11-22).

The graphical depiction of the predicted vs actual value for MRR is shown in Fig. [4.](#page-6-0) Based on the graph provided, the predicted values are lying closer to the actual values, proving the chosen input parameter levels are correct for a better result. The values were generally more relative to the projected value. Figure [5](#page-6-1) shows the graphical representation of residual vs run values of MRR. In most cases, the values are in the normal range except the 4th and 13th values are some deviations that occurred. Figure [6](#page-7-0) shows the graphical representation of DFFITS vs run values for MRR; the values

A: Pulse on time

are mostly nearer to the predicted range, and the lowest value is from 0.00851 to 0.06938.

Figure [7](#page-7-1) demonstrates the graphical representation of the Contour plot of Pulse on Time and Downtime for MRR; if the Pulse on Time is more than 8.5, the MRR is increased by more than 0.6 mm. Figures [8](#page-8-0) and [9](#page-8-1) give the Contour plot of Pulse on Time, wire feed rate for MRR and the Contour plot of Downtime, Wire feed rate for MRR, respectively. Results proved that higher Pulse ON time, downtime and wire feed rate result in better MRR. The error report obtained during this MRR analysis is given in Table [7.](#page-9-0)

The Response Surface Methodology arrangement was utilized in this experimental study. The created RSM model predicts the Wire feed rate, Downtime, and Pulse on Time, on MRR response. The images of all the Response surface plots (RSM plot of Downtime, Pulse on Time with MRR,

RSM plot of Wire feed rate, Pulse on Time with MRR, RSM plot of Wire feed rate, Downtime with MRR) are given in Figs. [10,](#page-9-1) [11](#page-10-0) and [12,](#page-10-1) respectively. The following inferences are made based on the response plots obtained above.

- Downtime, Pulse on Time, and Wire feed rate are varied to obtain the response named MRR for effective machinability.
- For the decrease in Downtime, Pulse on Time, and Wire feed rate, the most crucial output response, MRR, is reduced.

Table 7 Error Report of MRR Analysis

Fig. 10 RSM plot of downtime, pulse on time with MRR

Factor Coding: Actual

 0.00851

 $X1 = A$ $X2 = B$

 $C = 5$

4 Conclusions

Based on the WEDM experiments conducted on the MONEL 400K material in the present investigation, the following observations are made:

• Wire feed, Time on, and Time off have been found to affect MRR considerably. Taguchi's methodology tracks down the best settings for boosting the material removal rate during the machining of MONEL 400 K.

- The process parameters significantly impact the output response material removal rate—the proportion of significant parameters changes with the output objective response changes.
- Downtime has the opposite impact as a pulse on Time. Removed debris was flushed away during downtime leading to an increased MRR of 0.06938 gm/min.
- The best material removal is obtained at the optimal level of 10 μs of Pulse On Time, 2 μs of Down Time, and 4 m/min of wire feed rate. The higher the Pulse on Time, higher the amount of material removal takes place on the work piece material and thus leading to the higher MRR on the work material.

• The RSM analysis proposes a mathematical model for the Analysis of MRR, confirming the relative value proportion of deviation.

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