



Investigation of dimensional accuracy of material extrusion build parts using mathematical modelling and artificial neural network

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Abstract

Dimensional accuracy of fabricated parts made through material extrusion process is an important parameter to decide the part's quality. Since a 3D model part is produced in layered form, the deposited layers are subjected to heat for multiple times. Also, deposited layers form bonds with adjacent layers and roads. It leads to shrinkage and distortion in fabricated parts. Process variables are also significant parameters to decide the final part dimension. Accuracy of the parts can be improved if the dimensions are predicted in an earlier stage. So, for the prediction of accurate result various mathematical models have been formulated by the researchers. Use of soft computing techniques can be one method which may also be used for prediction. Since the experiments are performed at various combination of process variables. RSM uses different mathematical models for each set of experiment, but ANN can be use at same parameters. Thus, in this paper ANN model is compared with the developed models of the selected existing literatures. Also, these models are used to find and compare the effect of process variables on dimensional accuracy. The results show that ANN model predicts the results with very less error in comparison of existing models.

Keywords Material extrusion · Modelling · Soft computing · Dimensional accuracy · ANN · Additive manufacturing

1 Introduction

Nowadays, material extrusion additive manufacturing (MEAM) is one of the most used techniques utilized for prototyping, rapid tooling and inhouse fabrication. The MEAM process can be divided into three types: first is fused filament fabrication, second is screw based pellets extrusion (SBPE) and last is plunger-based extrusion process. In these types of MEAM process, FFF and SBPE are most commonly used techniques [1, 2]. Figure 1 (a and b) shows the schematic of FFF and SBPE methods. MEAM techniques are used to fabricate 3D parts by depositing materials layer-by-layer. Mostly, thermoplastic polymers are used as filaments and pellets to produce 3D parts [3].

One of the important quality characteristics in the printed objects using FFF and SBPE is dimensional accuracy. Dimensional accuracy must be studied in FFF and SBPE processes to produce accurate individual parts' dimensions.

Since a product consists of several parts which are assembled in the last stage of product finishing. The assembly of the parts needs accurate dimensions because if the fabricated individual parts do not meet specifications, then the problems in assembly may arise. Volumetric or dimensional error is a well-known error in produced parts using MEAM methods. Surface roughness is also a major drawback of MEAM methods.

Various researchers have worked on the improvement of dimensional accuracy of parts fabricated using MEAM processes by considering different process parameters and optimization methods. Also, various authors have studied the effects process variables on the dimensional accuracy of the parts. Very few of them used soft computing techniques to predict the results. Some related works are presented in the next section.

Budzik et al. [5] discussed the strategies for quality enhancement of additively manufactured parts using polymer form materials. On the basis of the state of the process, quality control process is categories in three levels namely quality control during data generation, quality control during manufacturing, quality control during post processing. In this study visual prototype assessment technique was used in

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Fig. 1 Schematic of (a) fused filament fabrication (b) screw-based pellets extrusion [4]

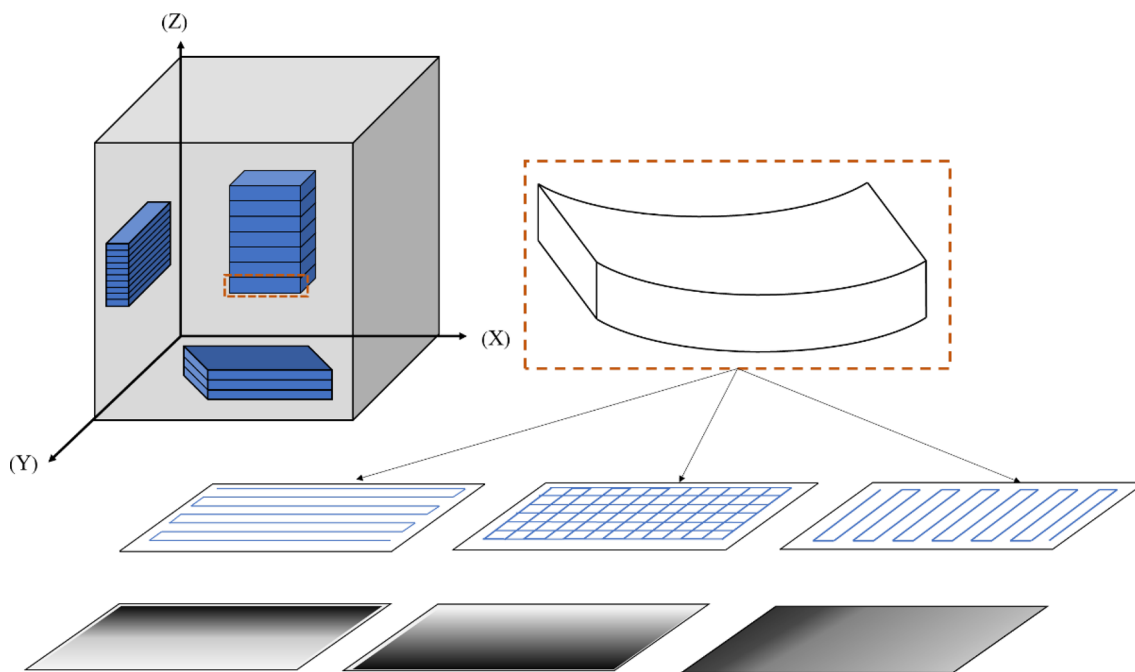
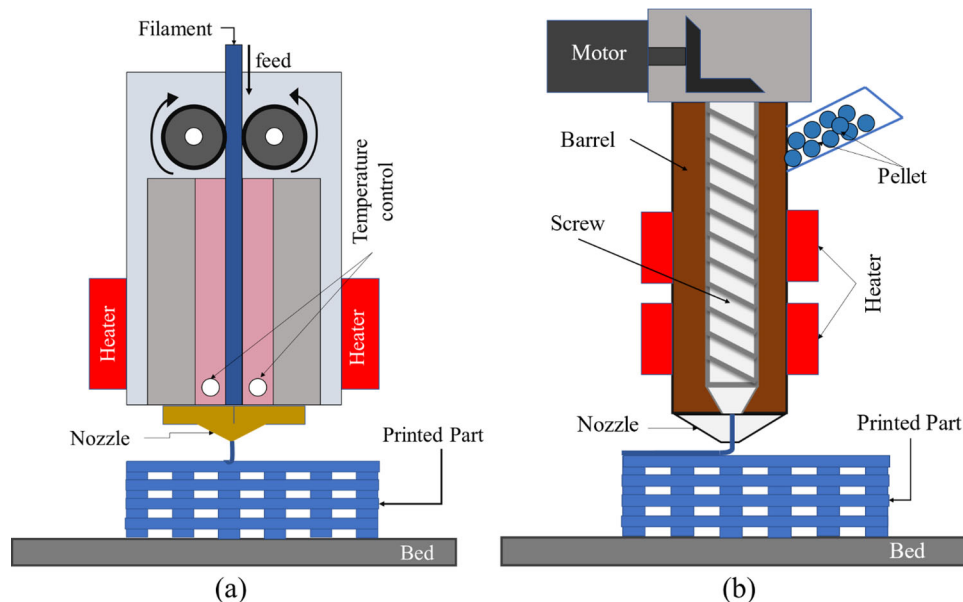
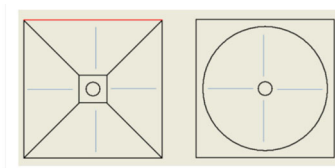
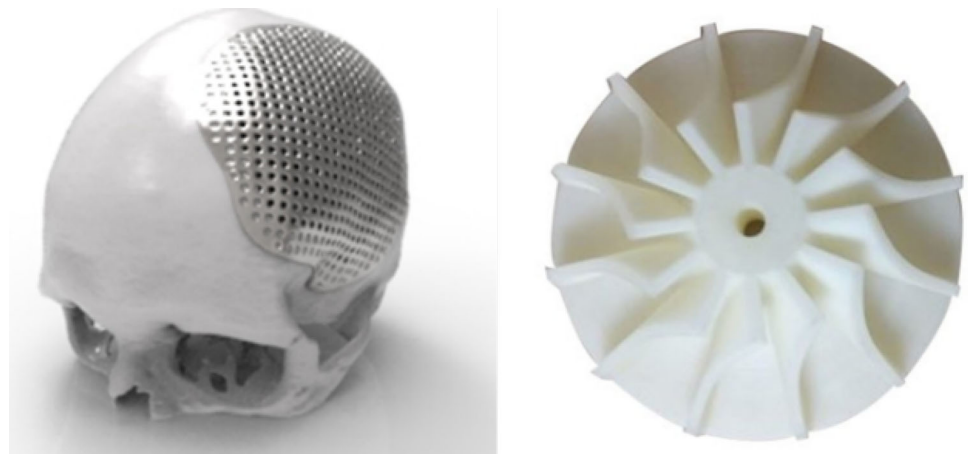


Fig. 2 Variation of stress concentration at different raster patterns

41 quality control and it was found that the MEM method was
 42 less accurate among other processes like FDM, polyjet, DLP,
 43 etc. methods. Chen et al. [6] proposed a low-cost approach to
 44 characterize the rheological properties in AM. In this study
 45 melt flow behavior of polymers and pressure drop in nozzle
 46 was computed. Nieto et al. [7] presented a case study to
 47 develop a prototype of a large format pellet-based AM
 48 system to extrude the polymers for industrial use. The poly-
 49 mers PLA and ABS were selected to extrude and fabricate
 50 layered parts. Masood et al. [8] formulated a mathematical

51 model that can be suitable to compute the volumetric error
 52 for any build orientation. This model was applied to vari-
 53 ous shapes (like cylinder, cube, pyramid, and sphere) and
 54 the calculated error of these shapes was compared with the exper-
 55 imental results. The accuracy of the developed model was
 56 significant, and the authors concluded that this mathematical
 57 model can be further extended to calculate the volumetric
 58 error of complex shapes. Garg et al. [9] analyzed the effect
 59 of build orientation on the dimensional accuracy and surface
 60 roughness of parts printed using FDM process. The printed

Fig. 3 Practical use of AM in medical and aerospace sectors [14, 15]



(a)



(b)

Fig. 4 Test Specimens [17]

raster angle bead is deposited along the length. So, long raster pattern is obtained which generated the stress concentration at the adjacent previous layer. Since the stress is concentrated at a specific location this can generate the bending and distortion in the parts.

As the material extrusion AM processes are being rapidly used for prototyping and producing medical models. In such applications a very high order of dimensional accuracy is being needed [13]. Figure 3 shows an example of the various practical use where a very high accuracy of the parts is necessary. The dimensional accuracy of the produced models varies for different materials and processes, or technologies used. The accuracy can be enhanced if it is estimated at the earlier stage.

In this work, a unique method using an ANN modelling is developed for the prediction of dimensional accuracy of the parts printed using extrusion based additive manufacturing process. The ANN methodology provides the modelling of complex relationships, spatially non-linear activation functions that can be investigated without complicated expressions. Due to flexibility with the number of experimental data, ANN makes it possible to use more familiar experimental designs. Also, ANN models may have better prediction power than regression models. So, the purpose of this work is to predict the accuracy of printed parts by using a soft computing technique (artificial neural network). Also, the mathematical models used by the authors in their literature are compared with the ANN models for the prediction of accuracy of printed parts. Thus, this research shows an integrated approach for part design and manufacturing with the involvement of ANN based computing technique for the modelling and predictive analysis of dimensional accuracy for additively manufactured discrete artefacts.

This paper is organized as follows: Sect. 2 introduces some useful information part design and measurement of dimensional accuracy. Section 3 represents the DoE based

parts are also post processed by using cold vapor treatment to enhance the surface finish and dimensional accuracy. Thaisa et al. [10] presented a review study on the use of AM in dental implants. Custom implants like dental implants need microscopic resolution and sufficient bone height and thickness. So, in the individualized implants AM has significant potential to replace older processes if the parts made using AM processes reach up to desired surface finish and dimensional accuracy. Perez et al. [11] studied the surface roughness and dimensional accuracy of FFF fabricated parts. It was found that at lower layer height good surface finish can be achieved but this increases fabrication time. Zhang and Chou [12] investigated the heat and mass transfer phenomena in the FDM process. Figure 2 shows that the effect of the various tool path on the stress concentration directions. In this study simulation was performed at various tool path strategies. It was found that principal stress generated due to heat accumulated at the location of starting point of deposition. At the 90°

Table 1 Process variables and their level used by various authors

Literature	Process Variables	Levels
Mohamed et al. [16]	Layer height	0.254; 0.178; 0.127
	Orientation	30; 15; 0
	Raster angle	60; 30, 0
	Raster width	0.5064; 0.4564; 0.4064
	Air gap	0.008; 0.004; 0
Vyavahare et al. [17]	Barrel temperature	100, 110, 120
	Bed temperature	30, 40, 50
	Build orientation	0, 45, 90
	Raster angle	0, 45, 90
	No. of Contours	1, 2, 3
Jung et al. [18]	Outlet Size	50, 57.32, 75, 93.68, 100
	Hopper angle	30, 37.32, 55, 72.68, 80

115 mathematical modelling. Section 4 proposes the ANN archi-
 116 tecture and modelling. Section 5 discusses the comparison
 117 of developed model with existing models, and conclusions
 118 are made in Sect. 6.

119 2 Part design and measurement 120 of dimensional accuracy

121 In the literature, various techniques have been used by the
 122 researcher for the measurement of the dimensional accu-
 123 racy or percentage error in dimensions of FFF and SBME
 124 manufactured parts. Researchers have adopted the various
 125 test specimens as per their CAD modelling packages and at
 126 the basis of precision of the 3D printer. The CAD model
 127 and the fabricated parts are shown in the Fig. 4. Mohamed
 128 et al. [16] followed the Eq. 1, Vyavahare et al. [17] followed
 129 Eq. 2 to measure the percentage difference of fabricated
 130 test specimens. In the Eq. 1, ΔD is the percentage differ-
 131 ence in diameter, D_{EXP} , and D_{CAD} are the dimeter of parts
 132 fabricated and CAD model file. Jung et al. [18] measured
 133 the discharge time. To measure the dimension of the parts
 134 Mohamed et al. [16] used Mitutoyo Precision Micrometer
 135 (precision of 0.01 mm), Vyavahare et al. [17] used the caliper
 136 (gauging range of 0 mm–150 mm and precision of 0.01 mm)
 137 and Jung et al. [18] used a high-speed camera with time
 138 stamping records to measure the discharge time.

$$139 \Delta D = \left| \frac{D_{EXP} - D_{CAD}}{\frac{D_{EXP} + D_{CAD}}{2}} \right| \times 100 \quad (1)$$

$$140 \Delta L(\%) = \frac{\text{Length of CAD model} - \text{Length of fabricated model}}{\text{Length of CAD model}} \times 100 \quad (2)$$

143 3 DOE based mathematical modelling

Mathematical modelling is the best tool to formulate the
 relationship between process parameters and the output vari-
 ables. The response surface methodology (RSM) is one of
 such as tool that is useful to formulate an analytical model
 for the targeted output variables. In this work dimensional
 accuracy (percentage change in various dimensions) and dis-
 charge time were selected as the output variables based on
 the available literatures. Equation 3 shows a generalized full
 quadratic response surface model used to obtain mathemati-
 cal relation [16]–[18].

$$y = \beta_0 + \sum_{i=1}^k \beta_i X_i + \sum_{i=1}^k \beta_{ii} X_i X_i + \sum_{i < j} \beta_{ij} X_i X_j + \varepsilon \quad (3)$$

where y : output function; X_i, X_j : independent variables; β_0 :
 regression constants for intercept; β_i : regression constants
 for linear term; β_{ii} , and β_{ij} : regression constants for quadratic
 term.

144 Researchers can select any of the DOE techniques as per
 145 their need and suitability, out of various techniques available
 146 in the literature. Box-Behnken, Taguchi orthogonal array,
 147 central composite design etc. are the generally used DOE
 148 methods. Mohamed et al. [16] used IV-optimal RSM design,
 149 Vyavahare et al. [17] implemented the central composite
 150 design (CCD) and Jung et al. [18] implemented central com-
 151 posite rotatable design (CCRD) to perform the experiments.
 152 Table 1 shows parameters level used by various authors for
 153 evaluating the effects on dimensional accuracy of the fabri-
 154 cated parts.
 155

156 For the description of process parameters and dimen-
 157 sional accuracy, a mathematical relationship between them
 158 is required. By formulating an approximate expression, in
 the fitness problem the response surface methodology has

been used in place of controllable factors. Mohamed et al. [16], Vyavahare et al. [17] and Jung et al. [18] applied the least square method for generating the functional expression. The generated functional expressions are shown in Eqs. (2–9). Many authors also evaluate the significance of process parameters and formulated expressions, using the analysis of variance. The ANOVA test is mostly performed using the software such as MINITAB, STATISTICA and Design Expert [16, 17]. The process parameters and expressions are assumed to be significant if the low probability (P-value) is lower than 0.05.

$$\begin{aligned} \Delta D (\%) = & -9.52 - 28.18 \times \text{layer thickness} - 0.735 \\ & \times \text{airgap} - 0.003274 \times \text{raster angle} \\ & + 0.00376 \times \text{orientation} + 51.4 \\ & \times \text{raster width} - 0.0511 \times \text{No. of contours} \\ & - 6.675 \times \text{layer thickness} \times \text{air gap} \\ & + 0.03629 \times \text{layer thickness} \\ & \times \text{orientation} + 17.39 \times \text{layer thickness} \\ & \times \text{road width} + 0.3804 \times \text{layer thickness} \\ & \times \text{no. of contours} - 0.01486 \times \text{airgap} \\ & \times \text{raster angle} - 0.01405 \times \text{airgap} \\ & \times \text{orientation} - 3.4 \times 10^{-5} \times \text{raster angle} \\ & \times \text{orientation} + 58.04 \times \text{layer thickness}^2 \\ & + 4.861 \times \text{airgap}^2 - 5.9 \times 10^{-5} \\ & \times \text{orientation}^2 - 53.2 \times \text{no. of contours}^2 \end{aligned} \quad (4)$$

$$\begin{aligned} \Delta \text{Length} = & 115.77 - 58.1 \times \text{Layer thickness} + 0.051 \\ & \times \text{Print speed} + 0.029 \times \text{Build orientation} \\ & + 23.2 \times \text{wall thickness} - 1.029 \\ & \times \text{Extrusion temperature} + 0.016 \\ & \times \text{Layer thickness} \times \text{Print speed} - 0.019 \\ & \times \text{Layer thickness} \times \text{Build orientation} \\ & - 1.99 \times \text{Layer thickness} \times \text{wall thickness} \\ & + 0.068 \times \text{Layer thickness} \\ & \times \text{Extrusion temperature} + 0.00002 \\ & \times \text{Print speed} \times \text{Build orientation} \\ & + 0.013 \times \text{Print speed} \times \text{wall thickness} \\ & - 0.0003 \times \text{Print speed} \\ & \times \text{Extrusion temperature} - 0.011 \\ & \times \text{Build orientation} \times \text{wall thickness} \\ & - 0.00004 \times \text{Build orientation} \\ & \times \text{Extrusion temperature} - 0.005 \\ & \times \text{wall thickness} \times \text{Extrusion temperature} \\ & + 111.13 \times \text{Layer thickness}^2 \end{aligned}$$

$$\begin{aligned} & - 0.00002 \times \text{Print speed}^2 \\ & - 0.00003 \times \text{Build orientation}^2 \\ & - 9.54 \times \text{wall thickness}^2 \\ & + 0.0022 \times \text{Extrusion temperature}^2 \end{aligned} \quad (5)$$

$$\begin{aligned} \Delta \text{width} = & 44.16 - 6.061 \times \text{Layer thickness} + 0.021 \\ & \times \text{Print speed} + 0.004 \times \text{Build orientation} \\ & + 2.93 \times \text{wall thickness} - 0.36 \\ & \times \text{Extrusion temperature} + 0.0019 \\ & \times \text{Layer thickness} \times \text{Print speed} - 0.041 \\ & \times \text{Layer thickness} \times \text{Build orientation} \\ & - 0.46 \times \text{Layer thickness} \times \text{wall thickness} \\ & + 0.0013 \times \text{Layer thickness} \\ & \times \text{Extrusion temperature} + 1.85E - 06 \\ & \times \text{Print speed} \times \text{Build orientation} + 0.0012 \\ & \times \text{Print speed} \times \text{wall thickness} - 0.00009 \\ & \times \text{Print speed} \times \text{Extrusion temperature} \\ & - 0.001 \times \text{Build orientation} \times \text{wall thickness} \\ & - 3.47E - 06 \times \text{Build orientation} \\ & \times \text{Extrusion temperature} - 0.016 \\ & \times \text{wall thickness} \times \text{Extrusion temperature} \\ & - 8.2 \times \text{Layer thickness}^2 \\ & - 0.00001 \times \text{Print speed}^2 - 4.7E \\ & - 06 \times \text{Build orientation}^2 \\ & - 0.36 \times \text{wall thickness}^2 \\ & + 0.0007 \times \text{Extrusion temperature}^2 \end{aligned} \quad (6)$$

$$\begin{aligned} \Delta \text{Height} = & -141.06 - 26.23 \times \text{Layer thickness} + 0.12 \\ & \times \text{Print speed} + 0.04 \times \text{Build orientation} \\ & - 31.27 \times \text{wall thickness} + 1.3 \\ & \times \text{Extrusion temperature} + 0.05 \\ & \times \text{Layer thickness} \times \text{Print speed} - 0.013 \\ & \times \text{Layer thickness} \times \text{Build orientation} \\ & + 0.26 \times \text{Layer thickness} \times \text{wall thickness} \\ & + 0.028 \times \text{Layer thickness} \\ & \times \text{Extrusion temperature} + 0.00005 \\ & \times \text{Print speed} \times \text{Build orientation} \\ & - 0.02 \times \text{Print speed} \times \text{wall thickness} \\ & - 0.0003 \times \text{Print speed} \\ & \times \text{Extrusion temperature} - 0.0075 \\ & \times \text{Build orientation} \times \text{wall thickness} \\ & + 0.00001 \times \text{Build orientation} \end{aligned}$$

$$\begin{aligned}
& \times \textit{Extrusion temperature} \\
& - 0.053 \times \textit{wall thickness} \\
& \times \textit{Extrusion temperature} \\
& + 32.12 \times \textit{Layer thickness}^2 \\
& - 0.0004 \times \textit{Print speed}^2 \\
& - 0.0002 \times \textit{Build orientation}^2 \\
& + 9.35 \times \textit{wall thickness}^2 \\
& - 0.0028 \times \textit{Extrusion temperature}^2
\end{aligned} \tag{7}$$

$$\begin{aligned}
(\Delta \textit{diameter})^{0.5} = & -32.14 - 3.03 \times \textit{Layer thickness} \\
& - 0.005 \times \textit{Print speed} + 0.012 \\
& \times \textit{Build orientation} + 1.9 \\
& \times \textit{wall thickness} + 0.27 \\
& \times \textit{Extrusion temperature} + 0.03 \\
& \times \textit{Layer thickness} \times \textit{Print speed} \\
& - 0.007 \times \textit{Layer thickness} \\
& \times \textit{Build orientation} - 0.89 \\
& \times \textit{Layer thickness} \times \textit{wall thickness} \\
& + 0.008 \times \textit{Layer thickness} \\
& \times \textit{Extrusion temperature} \\
& + 0.00001 \times \textit{Print speed} \\
& \times \textit{Build orientation} + 0.0009 \\
& \times \textit{Print speed} \times \textit{wall thickness} \\
& + 0.00009 \times \textit{Print speed} \\
& \times \textit{Extrusion temperature} \\
& + 0.0007 \times \textit{Build orientation} \\
& \times \textit{wall thickness} - 0.00004 \\
& \times \textit{Build orientation} \\
& \times \textit{Extrusion temperature} \\
& - 0.0334 \times \textit{wall thickness} \\
& \times \textit{Extrusion temperature} \\
& + 4.41 \times \textit{Layer thickness}^2 \\
& - 0.0002 \times \textit{Print speed}^2 \\
& - 0.00002 \times \textit{Build orientation}^2 \\
& + 2.8 \times \textit{wall thickness}^2 \\
& - 0.0005 \times \textit{Extrusion temperature}^2
\end{aligned} \tag{8}$$

$$\begin{aligned}
y_{case1} = & 15.7781 - 0.2499 \times \textit{outlet size} - 0.0792 \\
& \times \textit{hopper angle} + 0.0008 \times \textit{outlet size} \\
& \times \textit{hopper angle} + 0.0011 \times \textit{outlet size}^2 \\
& - 0.0001 \times \textit{hopper angle}^2
\end{aligned} \tag{9}$$

$$\begin{aligned}
y_{case2} = & 20.1556 - 0.2499 \times \textit{outlet size} - 0.3163 \\
& \times \textit{hopper angle} - 0.1112 \times \textit{outlet size} \\
& \times \textit{hopper angle} + 0.0013 \times \textit{outlet size}^2 \\
& - 0.0001 \times \textit{hopper angle}^2
\end{aligned} \tag{10}$$

$$\begin{aligned}
y_{case3} = & 22.4699 - 0.3785 \times \textit{outlet size} - 0.1055 \\
& \times \textit{hopper angle} - 0.0013 \times \textit{outlet size} \\
& \times \textit{hopper angle} + 0.0016 \times \textit{outlet size}^2 \\
& - 0.0002 \times \textit{hopper angle}^2
\end{aligned} \tag{11}$$

4 Artificial neural network (ANN)

Process time, surface integrity, strength, dimensional accuracy, etc. are the common responses in many of the manufacturing process. The controllable and uncontrollable process parameters affect these responses [19]. Hence, to achieve the desired response, the process parameters are required to be required. To handle large amount of data generated from process monitoring, failure mechanisms, and experimental data necessitates the implementation of artificial intelligence (AI). The Large data are better handled by ANN algorithms [20][21].

There are some basic terms in ANN, such as number of layers, and various functions such as activation function and loss function. A typical neural network contains mainly three layers that are named as input layer, hidden layer, and output layer. Out of these three layers, neurons from hidden can only be altered. From the literature [23] it has been observed that one hidden layer with 5–10 neurons shows a better performance with lesser iteration time. The work of activation function is to determine the transformation of weighted some of inputs into an output through the nodes of the ANN network. Binary step, linear, and non-linear are the main three activation function. In these activation functions only, non-linear functions can be used for backpropagation because the derivative functions are related to the inputs. Further, non-linear activation function can be classified into ten various types. Most commonly used linear and non-linear activation functions are tansig, logsig, and purelin. Tansig function is also commonly known as hyperbolic tangent function. In tansig function, the output is ‘Zero’ centered, hence it indicates the output values to be highly negative, neutral, or highly positive. Logsig (sigmoid) is also known as logistic activation function. Sigmoid function accepts any real number as an input and output is in the range of 0 to 1. As the figure shown in Table 2 corresponding to logsig, it can be observed that this function returns one for larger number input and

Table 2 Activation functions used in ANN

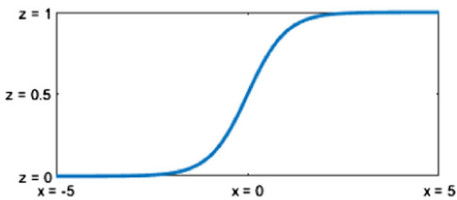
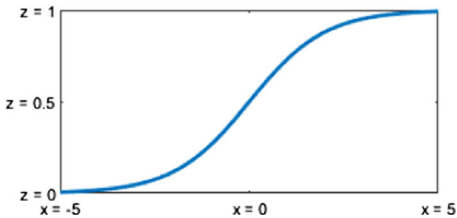
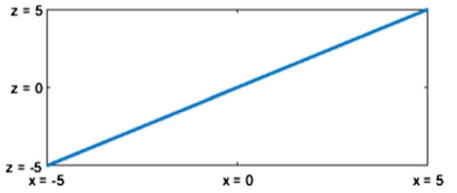
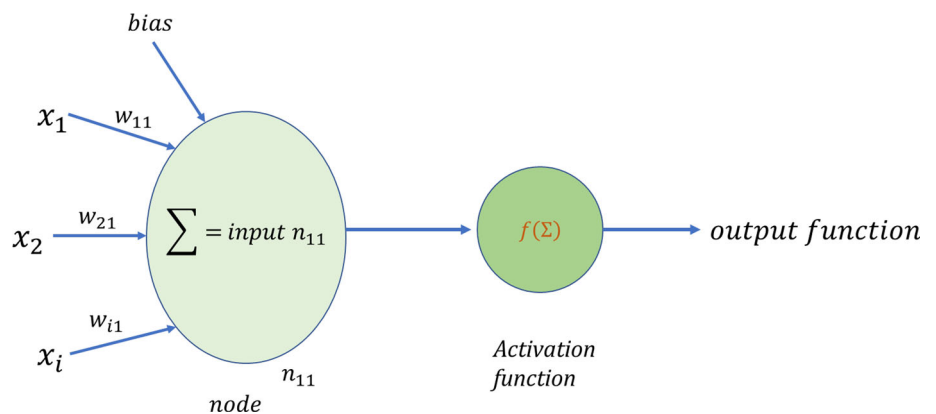
Tansig	$Z(x) = \frac{2}{1+e^{-x}} - 1$	
Logsig	$Z(x) = \frac{1}{1+e^{-x}}$	
Purelin	$Z(x) = x$	

Fig. 5 Schematic of an ANN architecture [22]



zero for smaller value inputs. It is mostly used for the models where probability prediction used as an output. Purelin function is a type of linear activation function. A schematic of the weighted sum in the neural network has been illustrated in Fig. 5. In the Eq. 10: ‘i’ is number of input (or process variables), ‘j’ is no. of neurons in hidden layer, ‘k’ is training cases, ‘g’ is the activation function, some frequently used activation functions are given in Table 2, ‘w’ and ‘B’ is weight assigned to each input neurons and bias respectively.

$$F_{jk} = g \left(\sum (w_{ji}x_{ik}) + B_j \right) \tag{12}$$

BPNN algorithm with the single hidden layer. As depicted In the Fig. 6, a correlation has been formulated between the experimental and predicted values has been developed for three sets (i.e., training, validation, test). Figure 6 also shows the overall performance of the optimal ANN structure. The R value for response (i.e., percentage error in dimension) for the literature Mohamed et al. [16] is 0.98072. The R value for percentage error in length, width, diameter, and height for the literature Vyavahare et al. [17] are 0.94918, 0.97395, 0.87413 and 0.90175 respectively. The R value for response (i.e., discharge time for all cases) for the literature are 0.99924, 0.99977 and 0.99758.

In this study the optimum ANN model has been generated by implementing a trial and error method for deciding the number of hidden layer neurons. Each ANN architecture is trained at least three times for to get minimum MSE and maximum R value. The developed model considered feed forward

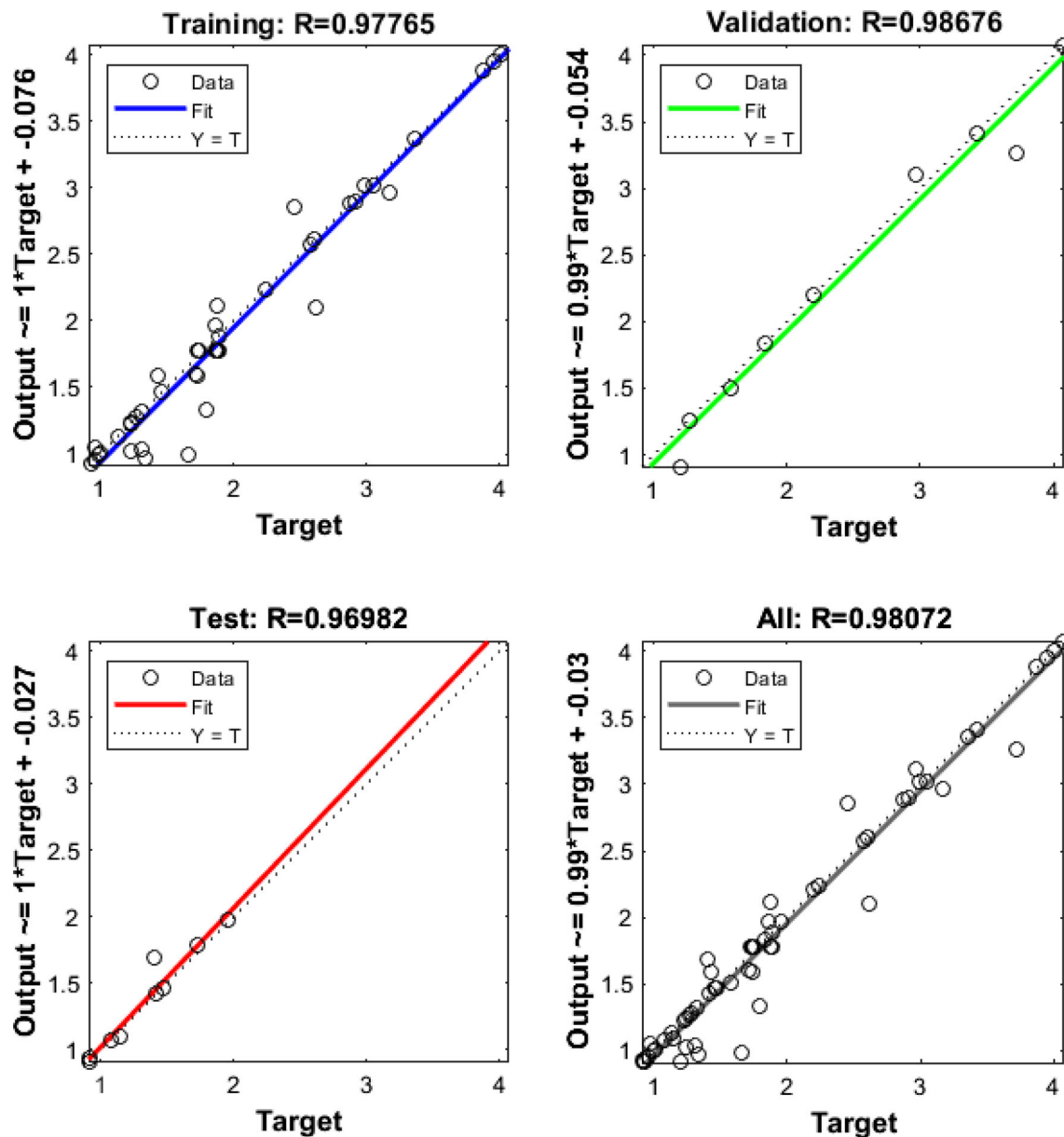


Fig. 6 Linear regression analysis for experimental and estimation made using ANN for Mohamed et al. [16]

5 Accuracy prediction of existing models through ANN

In general, several mathematical modelling techniques have been used for the material extrusion processes. Among these mathematical modelling RSM is commonly used for the prediction and to formulate an expression between process parameters and responses. The accuracy of the fitness model used by the authors is either not significant or prediction is not accurate. Nevertheless, new challenges have to be overcome when predicting the response at various combinations of process parameters. Thus, in this study, to find the consequence of the process variables on the response, first the

developed model is used and later it is compared with the ANN model.

In the paper (Mohamed et al. [16]), error percentage in dimension was selected as a response by the authors. Higher the error percentage in the dimension, higher will be error in printed part with respect to 3D digital model. So, for getting the accurate and less error in the part, response taken in this paper should be minimum. The accuracy estimation for the conducted experiments using ANN and RSM have been illustrated in the Fig. 7. From the Fig. 7, it can be concluded that the performance of both models is upright.

In this section, the effect of the process variables is quantified based on the developed RSM and trained ANN

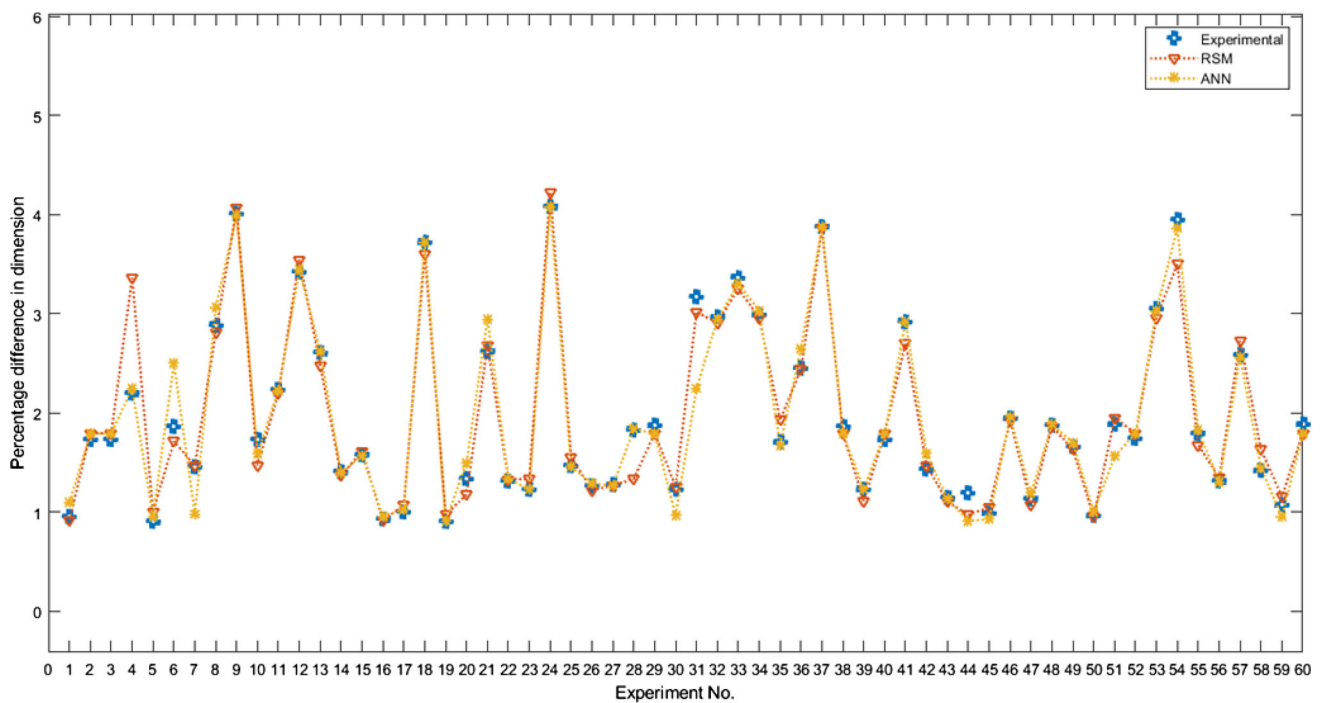


Fig. 7 Comparison plot of RSM and ANN with experimental value

212 mathematical model. The effect of the considered process
 213 variables by the authors on the percentage difference in
 214 dimension are shown in Fig. 8 (a) to (f). It is observed from
 215 Fig. 8(a) and (f) that on increasing the layer thickness and
 216 no. of contours, as can be seen in RSM and ANN mod-
 217 els the increment in the error percentage also taking place.
 218 In the case of layer thickness, worst dimensional accuracy
 219 is obtained at higher layer thickness (i.e., at 0.3302 mm)
 220 because higher layer thickness develops voids and internal
 221 stress that leads to deformation, it can be observed from
 222 microscopic images (Fig. 9). As the air gap increases, there
 223 is a prominent increase in dimensional accuracy (Fig. 8e)
 224 because when the air gap is small, it restricts heat dissipation
 225 rate so that instability generates in the part and leads to per-
 226 manent deformation up to a certain level of air gap. At the
 227 smaller raster angles (upto 45°), a very little change in dimen-
 228 sional accuracy is obtained but further increase in the raster
 229 angle dimensional accuracy is enhanced because at larger
 230 raster angles shorter lengths of rasters and sharp corners will
 231 be deposited in internal part of the specimen. Increasing the
 232 angle of build direction, percentage error in dimension first
 233 decreases and then increases. At the 0° build orientation part
 234 is printed parallel to X-direction (i.e., along part's length),
 235 thus long-long rasters are deposited which leads to deflection
 236 in the printed part, whereas in case of 90° build orientation,
 237 the shorter rasters are deposited which leads to non-uniform
 238 temperature distribution. On the basis of analysis of variation
 239 performed by the authors and Fig. 8 (a-f) it can be concluded
 240 that only layer thickness, raster angle air gap, and number of

contours are significant factors while road width and build
 orientation are insignificant factors.

For the validation of ANN model with the given model,
 literature by Vyavahare et al. [17] is chosen. In the paper
 Vyavahare et al. [17] dimensional accuracy of the outer
 region (i.e., length, width, height, and thickness) as well as
 inner region (i.e., diameter) of fabricated parts was investi-
 gated. The CAD 3D model and the fabricated parts are shown
 in Fig. 4.

The error in dimensions was calculated by using the Eq. 2.
 Figure 10 shows the prediction plot for the percentage dimen-
 sional error along length, diameter, width, and height. From
 the Fig. 10 it can be extracted that the ANN model predicts
 the response more accurately than the model used in the lit-
 erature. The main effect plot for each response with respect
 to considered process variables (layer height, printing speed,
 road width, build orientation, and print temperature) is collec-
 tively shown in the Fig. 11. To find the deviation in responses
 at a single set of variables one experiment was repeated for 5
 times. By repeating the experiments, there is 0.5% fluctuation
 in the response is observed. So, if the process variable does
 not change the responses more than the 0.5% then it is con-
 sidered as a dead process variable. Figure 11 (a) to (d) show
 the variation of the percentage error in length, width, diam-
 eter, and height with process variables based on the existing
 mathematical modelling equation and proposed ANN model.
 From the Fig. 11 (a-d) it can be observed that layer thickness
 is a significant factor for all the responses. Print speed is
 an insignificant factor for the percentage error along width,

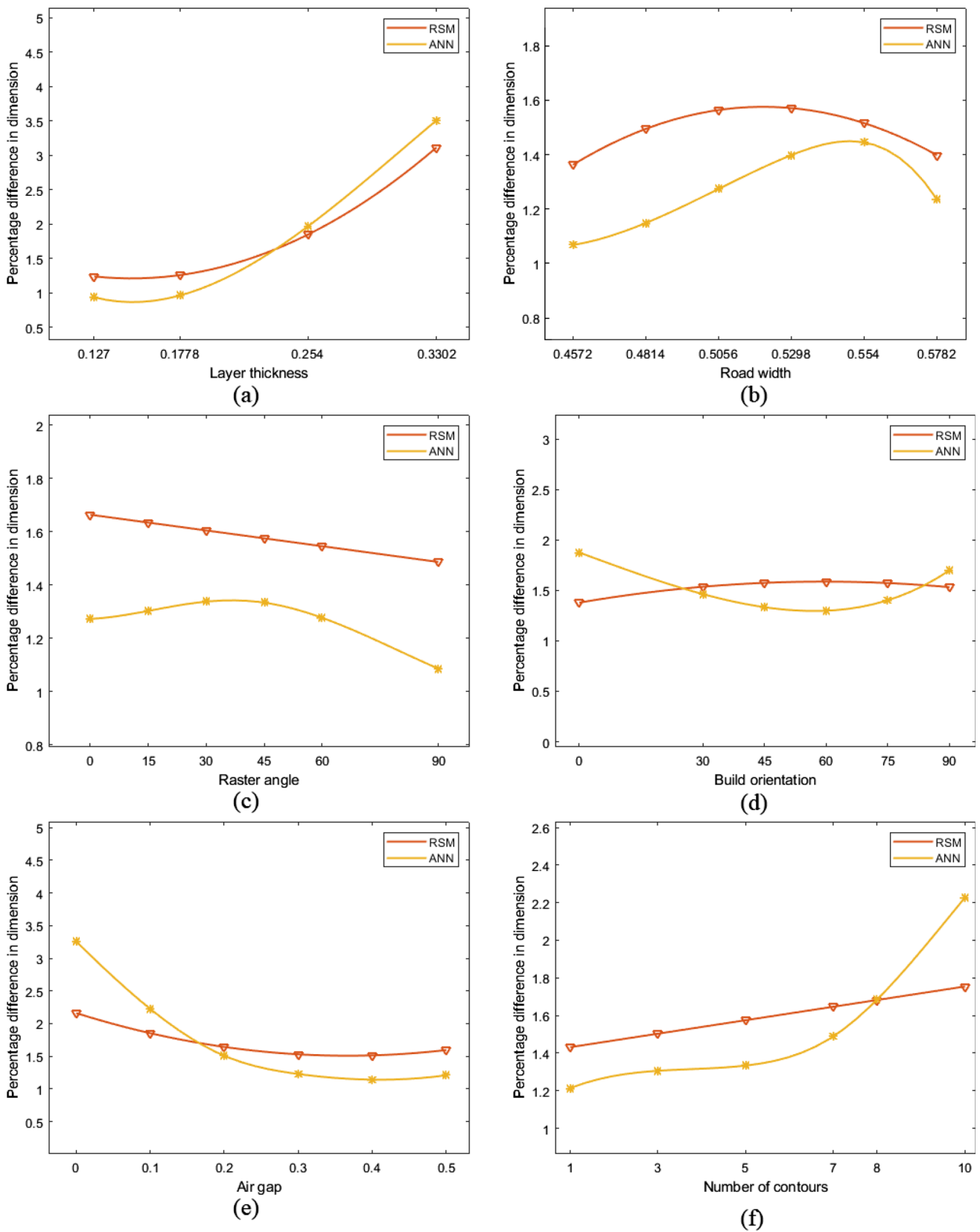


Fig. 8 Variation of percentage difference in dimension as per RSM and ANN model with respect to (a) Layer height, b road width, c raster angle, d build orientation, e air gap and f no. of contours

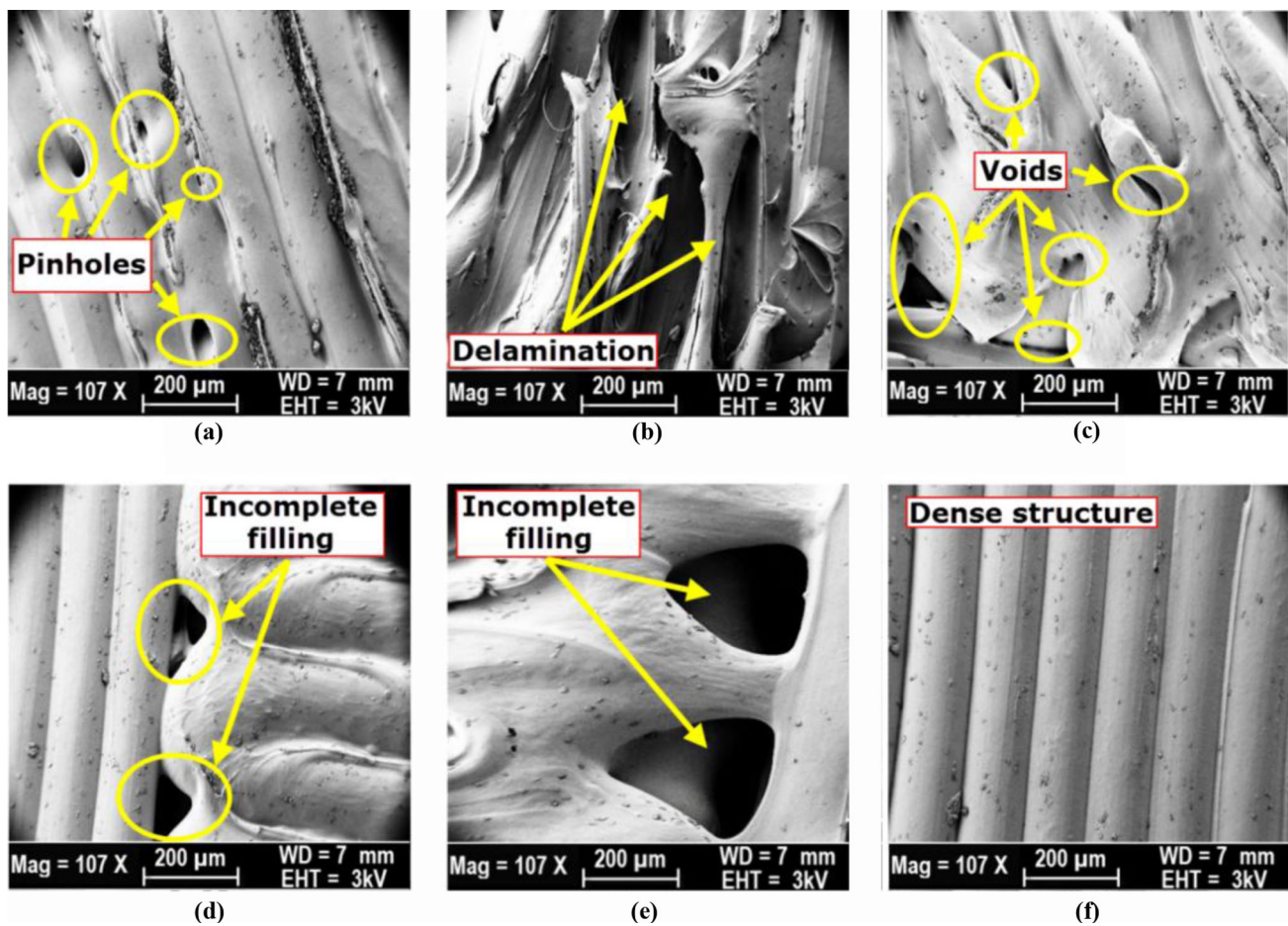


Fig. 9 Scanning electron microscopic images of various parts [16]

length, and diameter but it contributes significantly to dimension along height. Orientation is not a significant factor for the dimension along length and width while it affects the dimension along diameter and height. Wall thickness is the only parameter which has a significant effect on all the responses measured. Extrusion temperature is an insignificant factor for the percentage error along length, width but it can be considered as a significant factor for the percentage error along diameter and height. It is clear from the Fig. 11 that approximate estimation using RSM is quite same, but ANN prediction is much closer to experimental results.

In the paper Jung et al. [18] discharge time is measured by varying the outlet size (i.e., nozzle diameter) and hopper angle. Three cases are considered for different pellet sizes. In the first case 100% pellets are of the size of 12 mm diameter, in the second of 50% pellets are of 12 mm in diameter and 50% are 20 mm diameter and in the third case 100% pellets are of 20 mm diameters. Discharge time is an important factor which affects dimensional accuracy. If discharge is lower or higher than the desired value, then the lack of flow or over-flow may occur which leads to instability in the dimensional

accuracy. For the prediction of response (i.e., discharge time) given mathematics is compared with the ANN. Figure 12 shows the prediction of the response for all three cases. From the Fig. 12 it is clearly visible that ANN prediction is more accurate than the RSM model prediction. The variation of discharge time with respect to the size of outlet and hopper angle, has been shown in Fig. 13. In each case as the values of both process variables increases discharge time decreases according to both models. But the only difference in both prediction models are the types of curves. In the case of RSM prediction mostly responses vary linearly while in ANN prediction responses vary in quadratic manner. The decrease in the discharge time with the increase in hopper angle is because pressure generation is lower at greater hopper angle. Also, discharge time decreases with outlet size because as the outlet size increases the area of the nozzle increases, so that lesser velocity of flow (i.e., low flow rate) is obtained.

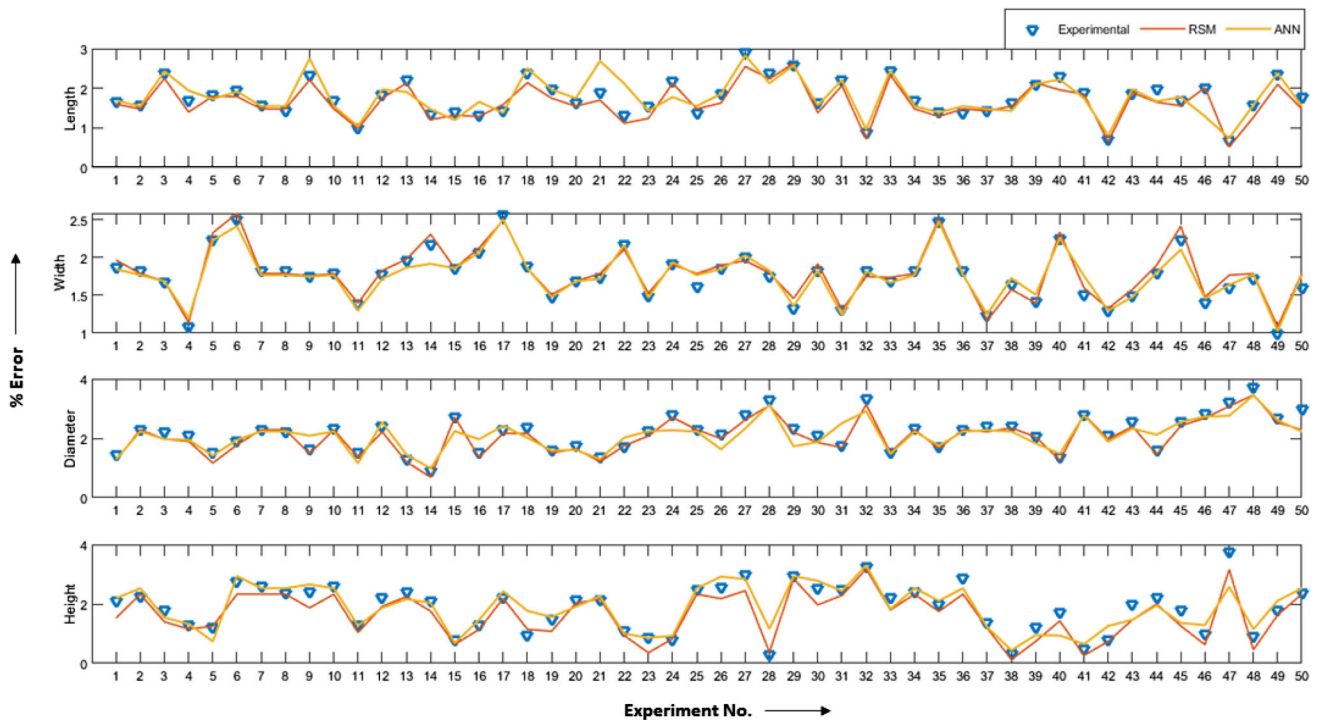


Fig. 10 Comparison plot of RSM and ANN with experimental value

5.1 Root mean square error (RMSE)

RMSE provides data on short-term efficiency, which is defined as the difference between actual and predicted values. The lower the RMSE, the more precise the assessment. The RMSE value for the performed analysis is calculated using Eq. 13 [24].

$$RMSE = \sqrt{\frac{1}{N} \sum_{i=1}^N \left((X_i^{actual} - X_i^{predicted})^2 \right)} \quad (13)$$

The lesser average RMSE for the developed ANN indicates that it has better performance than the models available in the literature. As shown in Fig. 14, the implemented ANN network can predict a lower average error value of 0.49, under the conditions such as materials, machines and processing conditions. While the average error estimated by existing models is higher even in the literature. These models are only useful for a limited set of process parameters, materials,

and machines. Above discussion validate that the developed ANN model can estimate accurate results under random situations, which also ensure the robustness of the developed model.

6 Conclusion and future scope

Part dimensional accuracy in the extrusion-based AM processes is the one of the major factors to decide part quality. To enhance the dimensional accuracy of the components fabricated by fused filament fabrication and screw-based pellet extrusion processes, mathematical modelling of the percentage difference on the dimension is applied. Previously available empirical modelling is not sufficient to predict dimensional accuracy. Therefore, in this study the experimental data has been extracted from the existing literature and ANN techniques is implemented on it. Following outcomes is obtained from the presented study.

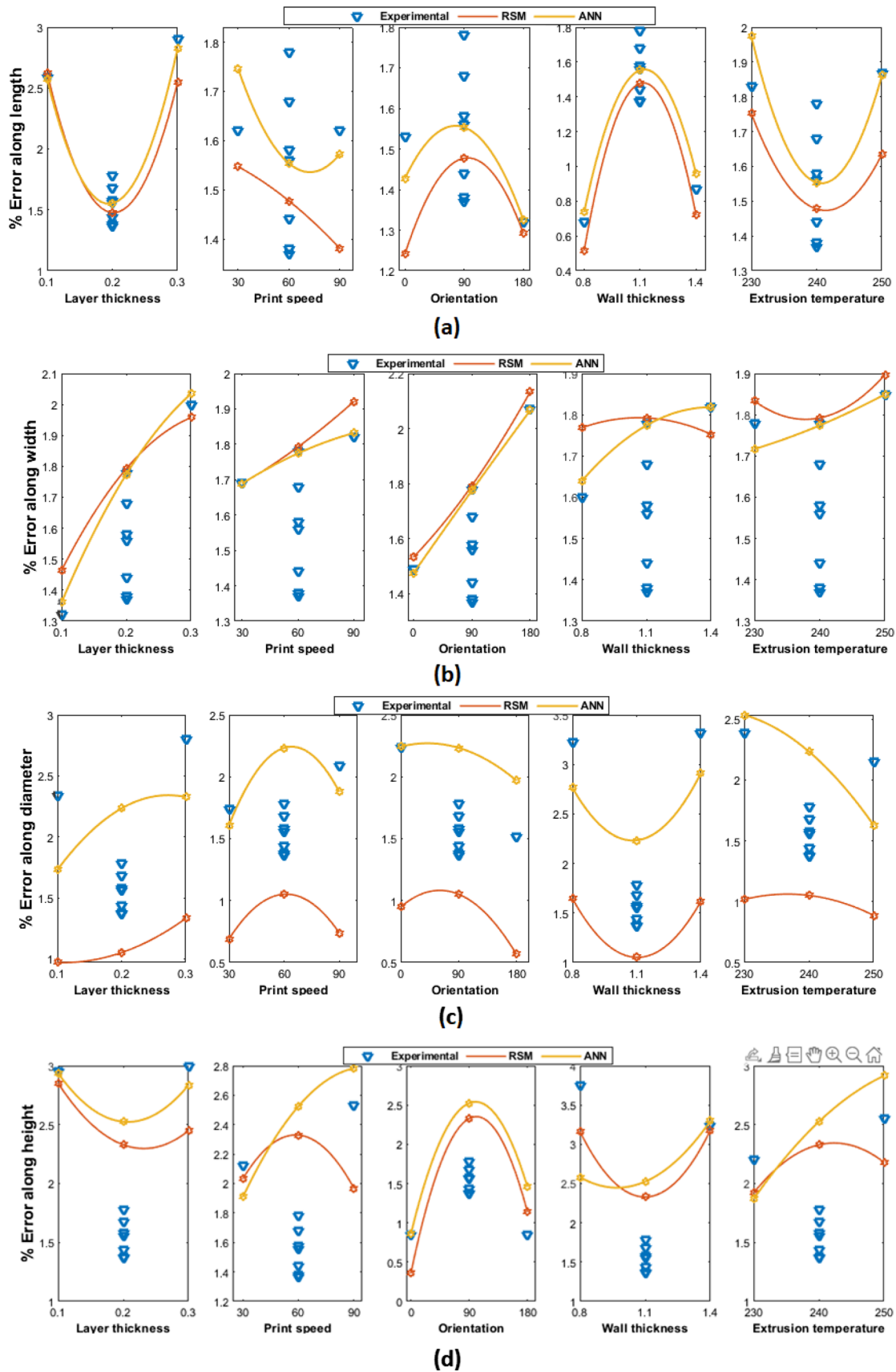


Fig. 11 Effect of process variables (a) on diemnsional percentage error in length (b) on dimensional error percentage in width (c) diemnsional error percentage in diameter (d) on percentage difference in height

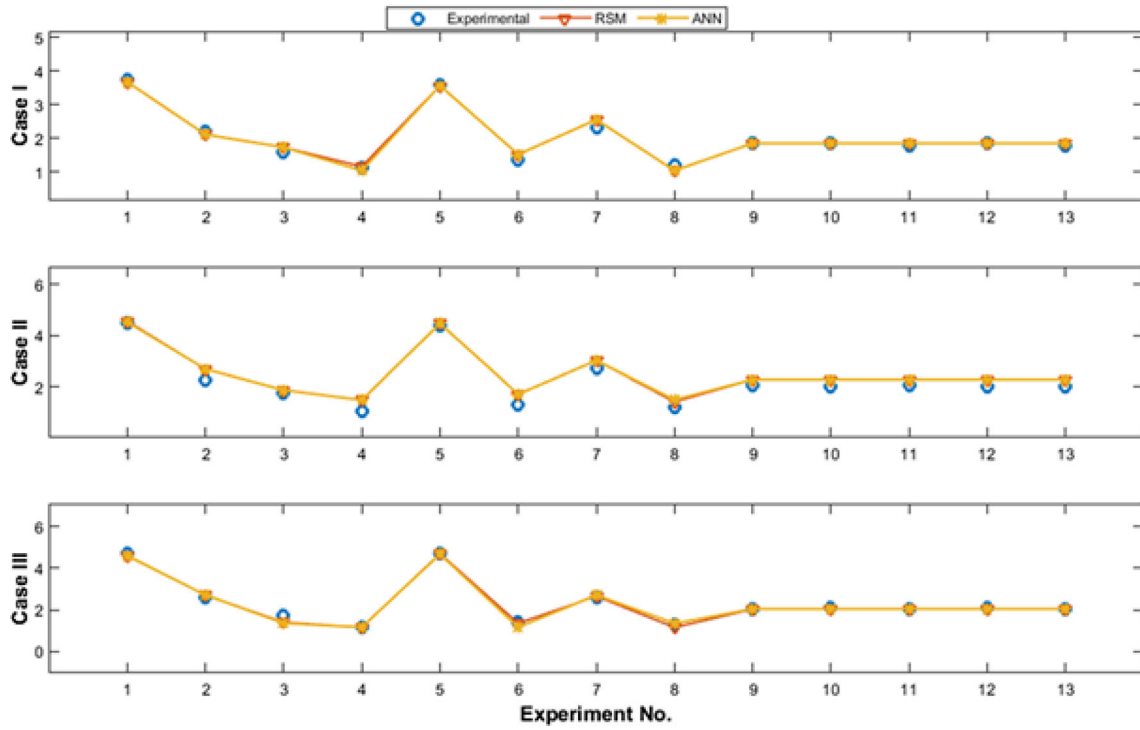
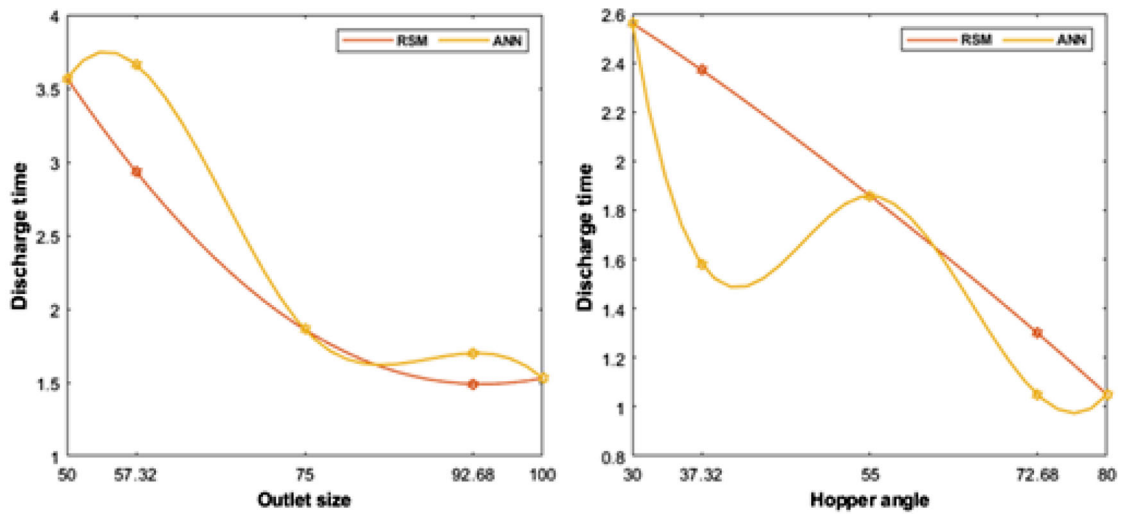
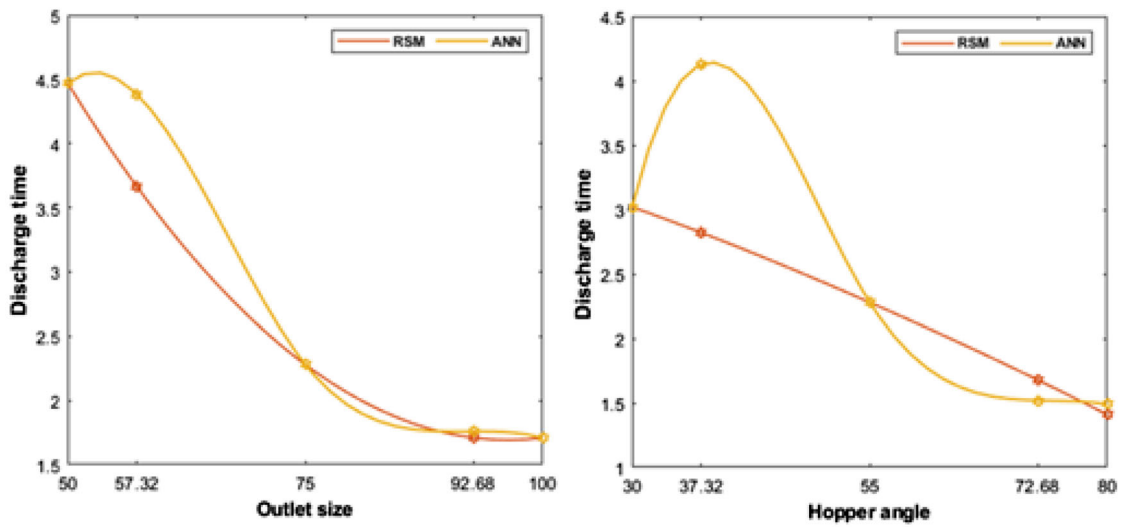


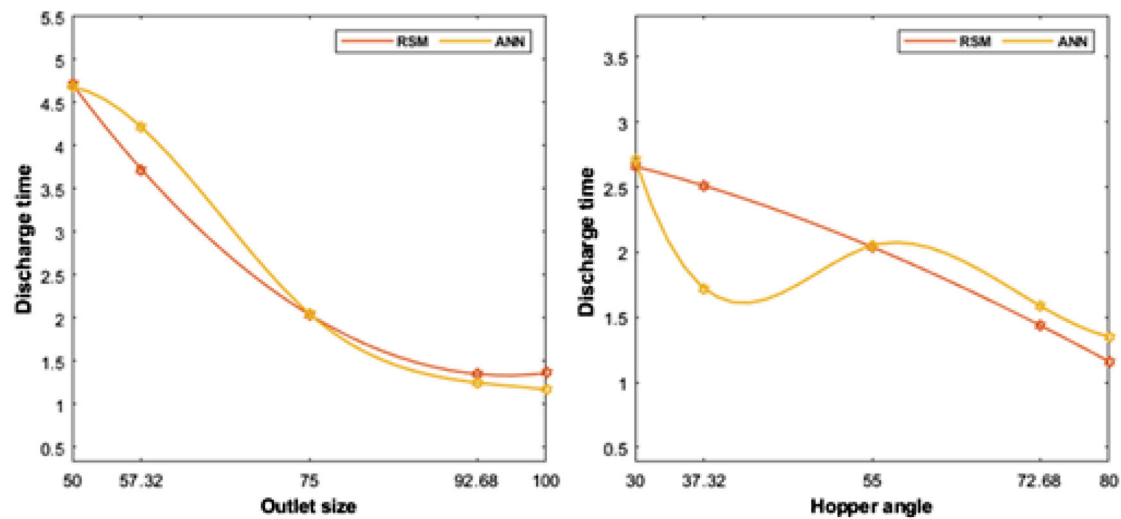
Fig. 12 Comparison plot of RSM and ANN with experimental value



(a)



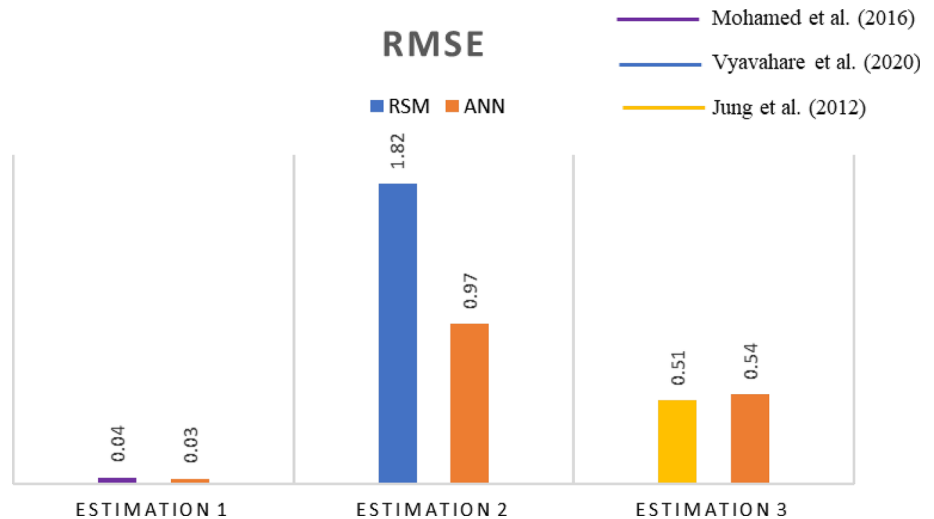
(b)



(c)

Fig. 13 Effect of process variables on discharge time

Fig. 14 Comparison plot of RMSE for the RSM and ANN



- The ANN estimation accuracy is dependent on the ANN variables, therefore, to ensure better performance, the formulated model has been trained several times.
- The precision in most of the experiments is about 0.5% of average value. Thus, only that parameter is needed to be studied which changes the dimension greater or lower than the value obtained at the previous level of that parameter.
- The sum of RMSE for RSM and ANN model is 2.27 and 1.54 respectively. So, the estimation of ANN is more acceptable than the existing used model.
- Although ANN is time taking technique, hence it should be used for large data set and more accuracy. The presented study states that RSM and ANN are suitable for optimization of MEAM process. It is also helpful to eliminate complications and a large number of experimental trials.

Despite improving the proposed model's dimensional accuracy, future directions of this work could include investigating the tensile behavior, compression behavior, buckling behavior, and failure mechanism of material extrusion additive manufactured thermoplastic polymer parts using finite element analysis.

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Declarations

Conflict of interest The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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