



An Interactive Intuitionistic Fuzzy Method for Multilevel Linear Programming Problems

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Abstract: In this paper, we propose an interactive method for solving the multilevel linear programming problems based on the intuitionistic fuzzy set theory. Firstly, the membership function and the non-membership function are introduced to describe the uncertainty of the decision makers. Secondly, a satisfactory solution is derived by updating the minimum satisfactory degrees with considerations of the overall satisfactory balance among all levels. In addition, the steps of the proposed method are given in this paper. Finally, numerical examples illustrate the feasibility of this method.

Key words: intuitionistic fuzzy; multilevel linear programming; interactive method; satisfying degree

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0 Introduction

Multilevel programming (MP) was first proposed by Candler and Norton^[1] in 1977. It is identified as mathematical programming which has a special hierarchical structure. There are multiple decision makers (DMs) in this structure and every DM has his/her objective function, decision variables and constraints, respectively. MP is very practical in the field of economic systems, engineering, transportation and so on. A lot of scholars have taken on this research since 1970s which leads to a rapid development in the theories, algorithms and applications of MP (Refs.[2-5]).

When taking into account some cooperation among the DMs, it is not appropriate to develop an algorithm for obtaining a Stackelberg solution to a multilevel programming problem. Then the interactive fuzzy methods have been developed in consideration of fuzziness of human judgment^[6-12]. Sakawa *et al*^[8] presented interactive fuzzy goal programming for multilevel linear programming problems. Wan *et al*^[10] introduced an interactive fuzzy decision making method for bilevel programming with a common decision variable. Other fuzzy methods for solving multilevel programming problems can refer to Refs.[13-16].

The concept of intuitionistic fuzzy sets (IFS) developed by Atanassov^[17,18] is a generalization of the fuzzy set theory. There have been some algorithms for the intuitionistic fuzzy optimization (IFO). Angelov^[19] introduced a frame to solve optimization problems in intuitionistic fuzzy environment; Li^[20] investigated mul-

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tiattribute decision making using IFS theory; Liu and Wang [21] proposed an approach to multi-criteria decision making based on IFS; Mahapatra [22] used the IFO technique to solve multi-objective nonlinear programming problems.

There is no means to incorporate the lack of information with the membership degree in fuzzy sets, but IFS can be viewed as an approach to overcome the shortcoming of fuzzy set theory. In addition, IFO can reduce DMs' subjective consciousness as much as possible thus the practical problems can be reflected objectively. In this paper, we present an interactive method for multilevel linear programming based on IFS theory under the assumption of cooperative relationship among the DMs. Here, we consider the following multilevel linear programming:

$$\left\{ \begin{array}{l} \min_{x_1, \dots, x_t} z_1(\mathbf{x}) = \sum_j c_{1j} x_j \\ \min_{x_2, \dots, x_t} z_2(\mathbf{x}) = \sum_j c_{2j} x_j \\ \vdots \\ \min_{x_t} z_t(\mathbf{x}) = \sum_j c_{tj} x_j \\ \text{s.t.} \quad \sum_{k=1}^t A_k \mathbf{x}_k \leq b \\ \quad \quad x_j \geq 0, j = 1, 2, \dots, n \end{array} \right. \quad (1)$$

where, \mathbf{x}_k and $z_k(\mathbf{x})$ are DM_{*i*}'s decision variable and objective function, respectively. DM_{*i*} denotes the DM at *i*th level. $\cup_k \{\mathbf{x}_k | k = 1, 2, \dots, t\} = \{x_1, x_2, \dots, x_n\}$, A_k is $m \times n_k$ coefficient matrix, b is m -dimensional column vector, $k = 1, 2, \dots, t$ and $n_1 + n_2 + \dots + n_t = n$.

The rest of this paper is organized as follows. Section 1 briefly introduces the basic concepts of IFS. The interactive intuitionistic fuzzy method for problem (1) is established afterwards. Furthermore, numerical examples are given in Section 2 to illustrate the feasibility of this method. The last section gives a short conclusion for this paper.

1 Algorithm Formulation

1.1 Definitions and Properties of IFS

Definition 1 [17, 23] Let X be a nonempty set of the universe. An intuitionistic fuzzy set (IFS) A in X is an object having the form $A = \{ \langle \mathbf{x}, \mu_A(\mathbf{x}), \nu_A(\mathbf{x}) \rangle | \mathbf{x} \in X \}$, where $\mu_A(\mathbf{x}): X \rightarrow [0, 1]$ and $\nu_A(\mathbf{x}): X \rightarrow [0, 1]$ define the degree of membership and non-membership, respectively, and for every $\mathbf{x} \in X$, $0 \leq \mu_A(\mathbf{x}) + \nu_A(\mathbf{x}) \leq 1$.

Definition 2 [17] $\pi_A(\mathbf{x}) = 1 - \mu_A(\mathbf{x}) - \nu_A(\mathbf{x})$ is called the degree of non-determinacy (or hesitancy) of the element $\mathbf{x} \in X$ to the IFS A . Obviously, for every $\mathbf{x} \in X$, $0 \leq \pi_A(\mathbf{x}) \leq 1$.

Definition 3 [18, 24] The intuitionistic fuzzy number (IFN) is defined as $\alpha = (\mu_\alpha, \nu_\alpha, \pi_\alpha)$, where $\mu_\alpha \in [0, 1]$, $\nu_\alpha \in [0, 1]$, $0 \leq \mu_\alpha(\mathbf{x}) + \nu_\alpha(\mathbf{x}) \leq 1$. Moreover, the function $s(\alpha) = \mu_\alpha(\mathbf{x}) - \nu_\alpha(\mathbf{x})$ is also defined to evaluate the degree of suitability that an alternative satisfies the DM's requirement.

Notice that maximization of the score function $s(\alpha)$ can decrease the DMs' hesitancy and their subjective consciousness can be reduced. Sakawa *et al* [8] proposed that taking fuzzy goals of the objective function and the decision variables may generate inconsistency between them, so we only consider that DMs have fuzzy goals for their objectives. If $z_i(\mathbf{x})$ is less than or equal to a value, the result is satisfied for DM_{*i*}; On the contrary, if $z_i(\mathbf{x})$ is greater than or equal to a value, DM_{*i*} can't accept the result completely. Due to Ref.[22], we can elicit the membership function and non-membership function for every fuzzy objective by the following steps:

Step 1: For all $i = 1, 2, \dots, t$, DM_{*i*} solves the following problem (2),

$$\left\{ \begin{array}{l} \min_{\mathbf{x}} z_i(\mathbf{x}) = \sum_{j=1}^n c_{ij} x_j \\ \text{s.t.} \quad \sum_{k=1}^t A_k \mathbf{x}_k \leq b \\ \quad \quad x_j \geq 0, j = 1, 2, \dots, n \end{array} \right. \quad (2)$$

Suppose that \mathbf{x}_i^* is the optimal solution of problem (2), we call \mathbf{x}_i^* the ideal solution of $z_i(\mathbf{x})$.

Step 2: DMs calculate the value of every objective function at the ideal point \mathbf{x}_i^* , $i, j = 1, 2, \dots, t$, denote

$$L_i^a = z_i(\mathbf{x}_i^*) = \min_{j=1, 2, \dots, t} z_i(\mathbf{x}_j^*), U_i^a = \max_{j=1, 2, \dots, t} z_i(\mathbf{x}_j^*) \quad (3)$$

Moreover, we can assume that L_i^r and U_i^r are lower bound and upper bound of the non-membership function, respectively:

$$L_i^r = L_i^a + \varepsilon_i, U_i^r = U_i^a \quad (4)$$

where $\varepsilon_i = t_i(U_i^a - L_i^a)$, $0 < t_i < 1$, and ε_i is determined by DM_{*i*}, $i = 1, 2, \dots, t$.

Step 3: We use the following linear membership function $\mu_i(z_i(\mathbf{x}))$ and non-membership function $\nu_i(z_i(\mathbf{x}))$ to describe the fuzzy goals of the DMs, respectively:

$$\mu_i(z_i(\mathbf{x})) = \begin{cases} 1, & z_i(\mathbf{x}) \leq L_i^a \\ \frac{U_i^a - z_i(\mathbf{x})}{U_i^a - L_i^a}, & L_i^a \leq z_i(\mathbf{x}) \leq U_i^a \\ 0, & z_i(\mathbf{x}) \geq U_i^a \end{cases} \quad (5)$$

$$\nu_i(z_i(\mathbf{x})) = \begin{cases} 0, & z_i(\mathbf{x}) \leq L_i^r \\ \frac{z_i(\mathbf{x}) - L_i^r}{U_i^r - L_i^r}, & L_i^r \leq z_i(\mathbf{x}) \leq U_i^r \\ 1, & z_i(\mathbf{x}) \geq U_i^r \end{cases} \quad (6)$$

Rough sketch of the membership function and non-membership function for minimization type objective function are shown in Fig. 1. We can denote the score functions of DMs after eliciting membership and non-membership function according to the definition.

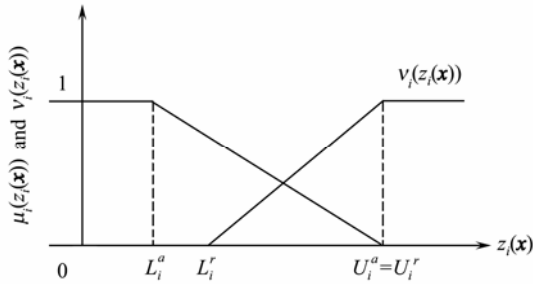


Fig. 1 Membership and non-membership functions of objective function

1.2 Interactive Intuitionistic Fuzzy Method

After eliciting the membership and non-membership function, DM_t specifies a minimal satisfactory level $\delta_i \in [0,1]$ for the score function $s_i(z_i(\mathbf{x}))$. DM_t maximizes $s_i(z_i(\mathbf{x}))$ under the existing constraints after getting the requirement of $t-1$ DMs at upper level, that is, DM_t solves the following problem:

$$\left\{ \begin{array}{l} \max_x s_t(z_t(\mathbf{x})) \\ \text{s.t. } \sum_{k=1}^t A_k \mathbf{x}_k \leq b \\ x_j \geq 0, j=1,2,\dots,n \\ s_i(z_i(\mathbf{x})) \geq \delta_i, i=1,2,\dots,t-1 \\ \nu_i(z_i(\mathbf{x})) \geq 0, i=1,2,\dots,t \\ \mu_i(z_i(\mathbf{x})) \geq \nu_i(z_i(\mathbf{x})), i=1,2,\dots,t \\ \mu_i(z_i(\mathbf{x})) + \nu_i(z_i(\mathbf{x})) \leq 1, i=1,2,\dots,t \end{array} \right. \quad (7)$$

If an optimal solution to problem (7) exists, it shows that DMs at upper level can obtain a satisfactory solution which has a satisfactory degree larger than or equal to the minimal satisfactory level specified by DMs. However, the larger the minimal satisfactory level of the upper level is, the smaller the satisfactory degree of DMs at lower level becomes. This may cause that the DM's sat-

isfaction at each level is of great difference. Considering the overall satisfactory balance and the stability of decision, the DMs at upper level compromise with the lower DMs. So we define

$$\lambda = \lambda(\mathbf{x}) = \min(s_1(z_1(\mathbf{x})), s_2(z_2(\mathbf{x})), \dots, s_t(z_t(\mathbf{x})))$$

then problem (7) convert to the problem (8):

$$\left\{ \begin{array}{l} \max_{\mathbf{x}, \lambda} \lambda \\ \text{s.t. } \sum_{k=1}^t A_k \mathbf{x}_k \leq b \\ x_j \geq 0, j=1,2,\dots,n \\ s_i(z_i(\mathbf{x})) \geq \delta_i \geq \lambda, i=1,2,\dots,t-1 \\ s_t(z_t(\mathbf{x})) \geq \lambda \\ \lambda \in [0,1] \\ \nu_i(z_i(\mathbf{x})) \geq 0, i=1,2,\dots,t \\ \mu_i(z_i(\mathbf{x})) \geq \nu_i(z_i(\mathbf{x})), i=1,2,\dots,t \\ \mu_i(z_i(\mathbf{x})) + \nu_i(z_i(\mathbf{x})) \leq 1, i=1,2,\dots,t \end{array} \right. \quad (8)$$

The auxiliary problem of (8) is:

$$\left\{ \begin{array}{l} \max_{\mathbf{x}, \lambda} \lambda \\ \text{s.t. } \sum_{k=1}^t A_k \mathbf{x}_k \leq b \\ x_j \geq 0, j=1,2,\dots,n \\ s_i(z_i(\mathbf{x})) \geq \lambda, i=1,2,\dots,t \\ \lambda \in [0,1] \\ \nu_i(z_i(\mathbf{x})) \geq 0, i=1,2,\dots,t \\ \mu_i(z_i(\mathbf{x})) \geq \nu_i(z_i(\mathbf{x})), i=1,2,\dots,t \\ \mu_i(z_i(\mathbf{x})) + \nu_i(z_i(\mathbf{x})) \leq 1, i=1,2,\dots,t \end{array} \right. \quad (9)$$

Sakawa *et al* [8] defined $\Delta_i = \frac{\mu_{i+1}(z_{i+1}(\mathbf{x}))}{\mu_i(z_i(\mathbf{x}))}$ to

measure the overall interests, here we define the ratio of neighboring levels' score function value

$$\sigma_i = \frac{s_{i+1}(z_{i+1}(\mathbf{x}))}{s_i(z_i(\mathbf{x}))}. \text{ For } DM_i \text{ and } DM_{i+1}, s_i(z_i(\mathbf{x})) >$$

$$s_{i+1}(z_{i+1}(\mathbf{x})), \sigma_i \in [0,1].$$

DM_i sets the acceptable interval $[\sigma_i^L, \sigma_i^U]$ for σ_i , if $\sigma_i < \sigma_i^L$, it means that the lower level's satisfactory degree is low because the upper level's demand is too high. Then, DM_i reduces his/her minimal satisfactory level δ_i ; If $\sigma_i > \sigma_i^U$, DM_i increases δ_i .

The algorithm terminates if the solution \mathbf{x}^* of problem (9) meets the following conditions:

- ① $s_i(z_i(\mathbf{x}^*)) \geq \delta_i$, for all $i=1,2,\dots,t-1$.
- ② $\sigma_i \in [\sigma_i^L, \sigma_i^U]$, for all $i=1,2,\dots,t-1$.

If \mathbf{x}^* can not satisfy both of the above conditions for some DM_i , then DM_i needs to update the minimal satisfactory level of relevant objective function in accordance with the following criteria:

- 1) If condition ① is not satisfied, DM_i decreases the minimal satisfactory level δ_i ;
- 2) If $\sigma_i > \sigma_i^U$, DM_i increases δ_i ; If $\sigma_i < \sigma_i^L$, DM_i decreases δ_i .

Note: If some DMs can not meet the termination conditions, update the DM's minimal satisfactory degree who located at the lowest level. So, the DMs at upper level can update their strategy according to the lower level's reaction such that a satisfactory solution can be obtained.

Suppose DM_q is located at the lowest level among the DMs who don not satisfy the termination conditions, DM_q adjusts the minimal satisfactory degree to δ'_q , then we solve (10) with the updated δ'_q :

$$\left\{ \begin{array}{l} \max_{\mathbf{x}, \lambda} \lambda \\ \text{s.t. } \sum_{k=1}^t A_k \mathbf{x}_k \leq b \\ x_j \geq 0, j=1, 2, \dots, n \\ s_i(z_i(\mathbf{x})) \geq \lambda, i=1, 2, \dots, q-1, q+1, \dots, t \\ s_q(z_q(\mathbf{x})) \geq \delta'_q \\ \lambda \in [0, 1] \\ v_i(z_i(\mathbf{x})) \geq 0, i=1, 2, \dots, t \\ \mu_i(z_i(\mathbf{x})) \geq v_i(z_i(\mathbf{x})), i=1, 2, \dots, t \\ \mu_i(z_i(\mathbf{x})) + v_i(z_i(\mathbf{x})) \leq 1, i=1, 2, \dots, t \end{array} \right. \quad (10)$$

Next, we test whether the solution to (10) satisfies the termination conditions or not. If not, the relevant DMs update the minimal satisfactory level until satisfactory solution is obtained. The above-mentioned algorithm is summarized as follows:

Step 1: For all $i=1, 2, \dots, t$, DM_i elicits the membership function and non-membership function of the fuzzy goal of DM_i in turn.

Step 2: DM_i specifies the minimal satisfactory level δ_i , the lower and the upper bounds of σ_i , $i=1, 2, \dots, t-1$.

Step 3: DM_i solves the problem (9), that is, it obtains the optimal solution \mathbf{x}^* by maximizing the score functions of all the DMs. Then DMs calculate the value of $s_i(z_i(\mathbf{x}^*))$ and $\sigma_i(z_i(\mathbf{x}^*))$, $i=1, 2, \dots, t-1$.

Step 4: If the solution \mathbf{x}^* satisfies the termination conditions, the algorithm terminates; Otherwise, go to Step 5.

Step 5: If DM_q is located at the lowest level among

the DMs who don't satisfy the termination conditions, updates δ_q according to the procedure of updating minimal satisfactory level and then solves problem (10).

Step 6: If the solution to (10) satisfies the termination conditions, the algorithm terminates; Otherwise, return to Step 5.

2 Numerical Examples

Example 1^[10]:

$$\left\{ \begin{array}{l} \min_{x_1} z_1 = 18x_1 - 10x_2 - 11x_3 + 11x_4 - 23x_5 - 40x_6 \\ \min_{x_2} z_2 = 35x_1 + 9x_2 - 20x_3 + 44x_4 - 10x_5 - 7x_6 \\ \text{s.t. } 47x_1 - 14x_2 - x_3 + 4x_4 + x_5 - 49x_6 \leq 1.5 \\ -23x_1 + 2x_2 + 45x_3 - 35x_4 + 12x_5 + 41x_6 \leq 13.5 \\ -9x_1 - 18x_2 + 12x_3 + 13x_4 + 37x_5 - 11x_6 \leq 5.5 \\ 6x_1 - 19x_2 - x_3 - 2x_4 - 49x_5 - 11x_6 \leq -43.5 \\ -31x_1 - 8x_2 + 2x_3 + 17x_4 + 47x_5 - 25x_6 \leq 6.3 \\ 46x_1 + 3x_2 - 28x_3 + 17x_4 - 36x_5 - 3x_6 \leq 22.5 \\ -45x_1 + 34x_2 - 44x_3 + 44x_4 + 16x_5 - 2x_6 \leq 17 \\ 29x_1 - 13x_2 + 38x_3 + 19x_4 - 2x_5 + 7x_6 \leq 39 \\ 13x_1 + 10x_2 + 27x_3 - 29x_4 - 49x_5 - 38x_6 \leq -38 \\ x_i \geq 0, i=1, 2, \dots, 6 \end{array} \right. \quad (11)$$

where $\mathbf{x}_1 = (x_1, x_2, x_3)'$, $\mathbf{x}_2 = (x_4, x_5, x_6)'$.

In our algorithm, we choose $\varepsilon_1 = 3, \varepsilon_2 = 4, \delta_1 = 0.5$, $[\sigma_1^L, \sigma_1^U] = [0.75, 0.9]$. The solution of problem (9) is $\mathbf{x} = (0.881520, 1.122045, 0, 0.066176, 1.040567, 0.520981)'$, $\lambda = 0.252975$, $z_1 = -39.397442$, $z_2 = 29.810803$, $\sigma_1 = 1$, $s_1(z_1) = 0.252975$, $s_2(z_2) = 0.252975$.

While $s_1(z_1) = 0.252975 < 0.5$ doesn't satisfy the termination condition (1), DM_1 changes $\delta_1 = 0.5$ to $\delta'_1 = 0.27$. Then a problem corresponding to (10) is formulated as problem (12).

The solution of problem (12) is:

$\mathbf{x} = (0.890311, 1.125337, 0, 0.071434, 1.044841, 0.528990)'$, $\lambda = 0.228208$, $z_1 = -39.632923$, $z_2 = 30.280680$, $s_1(z_1) = 0.27 = \delta'_1$, $s_2(z_2) = 0.228208$, $\sigma_1 = 0.845215$.

$$\left\{ \begin{array}{l} \max_{\mathbf{x}, \lambda} \lambda \\ \text{s.t. } \sum_{k=1}^t A_k \mathbf{x}_k \leq b \\ x_j \geq 0, j=1, 2, \dots, 6 \\ s_1(z_1(\mathbf{x})) \geq 0.27 \\ s_1(z_1(\mathbf{x})) \geq \lambda \\ \lambda \in [0, 1] \\ v_i(z_i(\mathbf{x})) \geq 0, i=1, 2 \\ \mu_i(z_i(\mathbf{x})) \geq v_i(z_i(\mathbf{x})), i=1, 2 \\ \mu_i(z_i(\mathbf{x})) + v_i(z_i(\mathbf{x})) \leq 1, i=1, 2 \end{array} \right. \quad (12)$$

The above solution satisfies all the termination conditions, so DMs obtain the satisfactory solution and the algorithm terminates.

$$\mathbf{x} = (0.890\ 311, 1.125\ 337, 0, 0.071\ 434, 1.044\ 841, 0.528\ 990)', \lambda = 0.228\ 208, z_1 = -39.632\ 923, z_2 = 30.280\ 680, s_1(z_1) = 0.27 = \delta'_1, s_2(z_2) = 0.228\ 208, \sigma_1 = 0.845\ 215.$$

The above solution satisfies all the termination conditions, so DMs obtain the satisfactory solution and the algorithm terminates.

To demonstrate the feasibility of our method, we compare the results in Table 1. Our method is denoted by Method 1, the method of Wan *et al* [10] is Method 2, and

the method of Zheng *et al* [11] is Method 3.

According to the Table 1, all the DMs' score function values obtained by Method 3 are better than that of Method 2; Though DM₁'s score function value obtained by Method 3 is better than that of Method 1, DM₂'s score function value is not ideal as that of Method 1. Furthermore, $\sigma = 0.722\ 429$ is not in $[0.75, 0.9]$ of Method 3, it means that there is a big difference between two DMs' satisfactory degree. By contrast, the parameter σ in Method 1 is much closer to 0.9. This guarantees not only the upper DM's advantage but also the satisfaction of both DMs. Consequently, our method is feasible.

Table 1 Comparisons of the results of Example 1

Method	(z_1, z_2)	$(s_1(z_1), s_2(z_2))$	σ
1	(-39.632 923, 30.280 680)	(0.270 000, 0.228 208)	0.845 215
2	(-39.613 400, 30.620 500)	(0.268 589, 0.210 059)	0.782 084
3	(-39.788 800, 30.591 800)	(0.293 190, 0.211 809)	0.722 429

Example 2 [8].

$$\begin{cases} \min_{x_1, x_2, x_3} z_1 = c_1 x_1 + c_2 x_2 + c_3 x_3 \\ \min_{x_2, x_3} z_2 = c_4 x_1 + c_5 x_2 + c_6 x_3 \\ \min_{x_3} z_3 = c_7 x_1 + c_8 x_2 + c_9 x_3 \\ \text{s.t. } A_1 x_1 + A_2 x_2 + A_3 x_3 \leq b \\ x_j \geq 0, j = 1, 2, \dots, 15 \end{cases} \quad (13)$$

where $\mathbf{x}_1 = (x_1, \dots, x_5)'$, $\mathbf{x}_2 = (x_6, \dots, x_{10})'$, $\mathbf{x}_3 = (x_{11}, \dots, x_{15})'$. In addition, $c_1, \dots, c_9, A_1, A_2, A_3, b$ are showed in Table 5 of Ref.[8].

We choose $\varepsilon_1 = 10, \varepsilon_2 = 6, \varepsilon_3 = 2, \delta_1 = 0.95, \delta_2 = 0.85, [\sigma_1^L, \sigma_1^U] = [\sigma_2^L, \sigma_2^U] = [0.75, 0.9]$. The solution of problem (9) is

$$\mathbf{x} = (2.580\ 710, 0, 0.967\ 857, 2.285\ 659, 2.146\ 568, 1.675\ 894, 3.217\ 242, 0, 0, 1.019\ 755, 1.667\ 012, 0, 0, 1.273\ 604, 0.095\ 182)', \lambda = 0.581\ 152, z_1 = -516.220\ 154, z_2 = -451.706\ 332, z_3 = -371.453\ 935, s_1(z_1) = 0.803\ 765 < \delta_1 = 0.95, s_2(z_2) = 0.595\ 763 > \delta_2 = 0.85, s_3(z_3) = 0.581\ 152, \sigma_1 = 0.741\ 215, \sigma_2 = 0.975\ 475.$$

DM₁ and DM₂ are both not satisfied with the above solution, DM₂ changes $\delta_2 = 0.85$ to $\delta'_2 = 0.65$. Then a problem corresponding to (10) is formulated as:

$$\begin{cases} \max_{x, \lambda} \lambda \\ \text{s.t. } \sum_{k=1}^t A_k x_k \leq b \\ x_j \geq 0, j = 1, 2, \dots, 15 \\ s_1(z_1(\mathbf{x})) \geq \lambda \end{cases}$$

$$\begin{cases} s_2(z_2(\mathbf{x})) \geq 0.65 \\ s_3(z_3(\mathbf{x})) \geq \lambda \\ \lambda \in [0, 1] \\ v_i(z_i(\mathbf{x})) \geq 0, i = 1, 2, \dots, 15 \\ \mu_i(z_i(\mathbf{x})) \geq v_i(z_i(\mathbf{x})), i = 1, 2, \dots, 15 \\ \mu_i(z_i(\mathbf{x})) + v_i(z_i(\mathbf{x})) \leq 1, i = 1, 2, \dots, 15 \end{cases} \quad (14)$$

The solution of problem (14) is $\mathbf{x} = (2.595\ 286, 0, 0.964\ 740, 2.266\ 238, 2.173\ 129, 1.664\ 712, 3.272\ 815, 0, 0, 1.010\ 653, 1.694\ 636, 0, 0, 1.265\ 663, 0.059\ 115), \lambda = 0.558\ 775, z_1 = -519.092\ 639, z_2 = -453.212\ 020, z_3 = -371.350\ 523, s_1(z_1) = 0.865\ 072 < \delta_1 = 0.95, s_2(z_2) = 0.65, s_3(z_3) = 0.558\ 775, \sigma_1 = 0.751\ 382, \sigma_2 = 0.859\ 653.$

The value of $s_1(z_1)$ does not satisfy the termination condition (1), DM₁ changes $\delta_1 = 0.95$ to $\delta'_1 = 0.91$ and solve the problem (15):

$$\begin{cases} \max_{x, \lambda} \lambda \\ \text{s.t. } \sum_{k=1}^t A_k x_k \leq b \\ x_j \geq 0, j = 1, 2, \dots, 15 \\ s_1(z_1(\mathbf{x})) \geq 0.91 \\ s_2(z_2(\mathbf{x})) \geq 0.65 \\ s_3(z_3(\mathbf{x})) \geq \lambda \\ \lambda \in [0, 1] \\ v_i(z_i(\mathbf{x})) \geq 0, i = 1, 2, \dots, 15 \\ \mu_i(z_i(\mathbf{x})) \geq v_i(z_i(\mathbf{x})), i = 1, 2, \dots, 15 \\ \mu_i(z_i(\mathbf{x})) + v_i(z_i(\mathbf{x})) \leq 1, i = 1, 2, \dots, 15 \end{cases} \quad (15)$$

The solution of problem (15) is $\mathbf{x} = (2.608\ 886, 0, 0.961\ 929, 2.248\ 116, 2.197\ 912, 1.654\ 278, 3.324\ 670, 0, 0, 1.002\ 161, 1.720\ 411, 0, 0, 1.258\ 253, 0.025\ 461)$, $\lambda = 0.537\ 895$, $z_1 = -521.772\ 923$, $z_2 = -454.616\ 942$, $z_3 = -371.254\ 030$, $s_1(z_1) = 0.91$, $s_2(z_2) = 0.700\ 608$, $s_3(z_3) = 0.537\ 894$, $\sigma_1 = 0.778\ 453$, $\sigma_2 = 0.767\ 755$.

By now, $s_1(z_1) = 0.91 = \delta_1'$, $s_2(z_2) = 0.700\ 608 > 0.65 = \delta_2'$, moreover $\sigma_1 = 0.778\ 453$, $\sigma_2 = 0.767\ 755$ are all in the interval $[0.75, 0.9]$. That is to say, all the termination conditions of the proposed algorithm are satisfied, the DMs obtain the satisfactory solution.

3 Conclusion

This paper proposes an interactive intuitionistic fuzzy method for solving multilevel linear programming problems under the assumption of DMs' cooperative relationship. Considering the overall satisfactory balance, the DMs at upper level update the minimal satisfactory level continuously until a satisfactory solution is obtained. The numerical examples illustrate that not only the bilevel but also the multilevel linear programming problems can be solved by our proposed method.

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