#### **ORIGINAL PAPER**



# A new transfer learning approach to detect cardiac arrhythmia from ECG signals

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#### Abstract

Deep Learning (DL) has turned into a subject of study in different applications, including medical field. Finding the irregularities in Electrocardiogram (ECG) is a critical part in patients' health monitoring. ECG is a simple, non-invasive procedure used in the prediction and diagnosis of Cardiac Arrhythmia. This paper proposes a new transfer learning-based end to end approach to automate the cardiac arrhythmia classification. The proposed approach begins with gathering ECG Dataset and extracting beats after ECG beat segmentation. Developing a Model from scratch is time-consuming, so the concept of transfer learning is used. For transferring the knowledge to our ECG classification domain, the last layers of the model are fine-tuned such that model becomes more domain-specific to our target ECG data. Three pre-trained Convolutional Neural Networks (CNNs), AlexNet, Resnet18, GoogleNet are explored, and then, our model is designed by block wise fine-tuning each layer with different model training parameters. To update the weights and offsets, Adaptive moment estimation, Root means square propagation and Stochastic gradient descent with momentum (SGDM) are three different optimizers used. Investigating the results obtained by training fine-tuned models, we select the model which gives the system's best accuracy. MIT-BIH arrhythmia database is considered in this study. Performance of each Fine-tuned Model is evaluated by calculating Precision, Recall, Specificity,*F*-score and Accuracy. Moreover, our proposed fine-tuned Deep-CNN Model is effective and outperformed the existing models in the literature with accuracy of 99.56%.

**Keywords** Deep learning  $\cdot$  Convolutional neural network (CNN)  $\cdot$  Fine-tuned deep-CNN  $\cdot$  Transfer learning  $\cdot$  Electrocardiogram (ECG)

## **1** Introduction

Heart attacks are the significant reason for death all around the world. 17.9 million individuals are deceased every year because of cardiac anomalies, assessing 31% of overall deaths [1]. Major part of cardiovascular deaths is due to cardiac arrhythmia. Cardiologists regularly prescribe patients with Arrhythmia to wear Holter for ceaseless observing of ECG for 24 h. As this recorded data are enormous, there is a need to arrange kind of every heartbeat naturally utilizing the computer-aided diagnosis tools [2]. The development and adoption of deep learning (DL) have flooded over the most recent couple of years. Conventional Machine learning procedures or kernel-based neural network (NN) needs domain experts to recognize significant features for investigation of abnormalities in ECG [2, 3]. Artificial Intelligence (AI) techniques have emerged as a boon in the advancement of technologies.

Various Scholars in the literature have proposed various techniques for cardiac arrhythmia classification [4]. Machine learning methods needs features for classification. Hence, significant features need to be extracted, which without a doubt needs a domain expert. DL models learn features in a gradual manner without the need of experts. These are the layered architecture that learns various significant features at various layers. All the initial input layers extract features, and these features are classified by output layers. Convolutional neural networks (CNN) are preferred in DL approaches for extracting significant features and classification [5, 6]. The Deep-CNN model comprises of at least one convolution layers. The convolution layer performs convolution by sliding the kernel or filter over the data. Each receptive field gener-

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ates a feature map, which is added to obtain output feature maps.

Many approaches for classifying ECG beats utilizing CNN have been proposed. Kiranyaz et al. [7] proposed CNN to classify ECG beats utilizing time series data and further modified it to 2-D CNN. Rajendra et al. [8] solved dataset imbalance problem and did a five-class classification utilizing a nine-layer CNN. Zhai et al. [9] designed a CNN architecture with just seven convolution layers. Sellami and Hwang [10] introduced CNN with batch-weighted loss which gave incredible results while training but failed to produce a better accuracy. Wenhan liu et al. [11] used a patient specific approach and developed CNN to learn intrinsic features. The CNN proposed by Li [12] performed well for five class classification but the model has some cons while training from scratch. W. Yin et al. [13] proposed an integrated UW radarbased CNN. This model classified ECG data even in moving state. Using the concept of transfer learning CNN model was proposed by Salem [14]. The model performed well, but only four classes of arrhythmia were considered.

A DL model learns the basic features adaptively and creates end to end DL framework. It takes the ECG signal, extracts intrinsic features and the predicts cardiac arrhythmia [15–18]. The effect of noise when DL model is used was studied using a nine-layer CNN [19]. Results show that when DL models are trained from scratch the effect on noisy signal do not have much impact on classification results. For extracting significant feature maps time-frequency spectral entropy can be used [20]. Real time detection of abnormal cardiac rhythms using a robust CNN [21] may help cardiologist in early diagnosis. Detection myocardial infraction at an early stage can save life of diseases [22, 23]. When the dataset is large the performance of model is improved [24, 25]. The major challenge is to collect patients' data, which can be time-consuming and expensive. In the absence of real-time data, most widely used public database is MIT-BIH arrhythmia database [26].

In this study, our main motto is to detect cardiac arrhythmia from ECG signals. Noise is removed from signals using discrete wavelet transform (DWT) [27, 28]. ECG beats are segmented and labelled according to the annotations mentioned in database [29]. This labeled database is used for further processing. Using concept of transfer learning, deep learning models are adapted to our ECG signal database. These models are fine-tuned with different model training parameters. Further, these fine-tuned models are validated by testing for detection of cardiac arrhythmia.

The rest of work is systematized as follows. Section 2 defines our proposed methodology which includes preprocessing data extraction of feature maps and classification with fine-tuned models. In Sect. 3, investigative results are presented and compared with existing state-of-the-art model. Section 4 concludes our work.

## 2 Methodology

Transfer learning approach helps us to transfer the learned knowledge of pre-trained models and helps us to collect information required to handle new data. In this study, we explored DL models like AlexNet, ResNet18 and GoogleNet, utilizing MIT-BIH datasets and extract intrinsic features by applying a block-wise fine-tuning strategy to each layer. Utilizing a fully-connected layer along with SoftMax layer, classification of these features is done. Figure 1 represents the block diagram of proposed methodology. The proposed strategy begins with gathering signals from MIT-BIH Dataset, preprocessing the data to extract ECG beats, Feature extraction using Fine-tuned Deep Learning Models and Classification of ECG beats.

#### 2.1 Pre-processing

Signals are taken from MIT-BIH Arrhythmia Database [1]. It consists of 48 records, each with a duration of 30 min. All records together contain 16 types of beats; of which one is normal, 14 are arrhythmia classes and one unclassified beat. Among all, Records 102, 104, 106, 107, 109, 111, 118, 124, 200, 207, 208, 212, 214, 217, 223, 231, 232, 233 are considered. These 18 Records (captured from 18 different patients) are sufficient to extract required type of ECG beats. Beats considered in these records are Normal Beats (N), Left Bundle Branch Block Beats (L), Right Bundle Branch Block Beats (R), Premature Ventricular contraction Beats (V), Paced Beats (P), Atrial Premature Beats (A) and Fusion of Normal and Paced Beats (F).

In this work, Noise removal is done using Discrete wavelet Transform (DWT) filters. DWT decomposed signal into low- and high-frequency components commonly known as approximation and detailed coefficients. Let z(j) be the signal which decomposes as follows

$$z(j) = z_{l_0}(j) + \sum_{l=\infty}^{l_0} d_l(j)$$
(1)

where  $z_{l_0}(j)$  denotes approximated coefficients,  $l_0$  is the scaling factor and  $d_l(j)$  are the detailed coefficients.

For finding approximation coefficients of next higher level of decomposition, we iterate as

$$z_l(j) = z_{l+1}(j) + d_{l+1}(j)$$
(2)

each level of decomposition, input coefficients given is approximation coefficients obtained by previous level. Daubechies wavelet 6 (db6) is used to decompose signal into six levels. Coefficients are obtained from third level to sixth level and retained and signal is reconstructed using these coefficients.





Noise-free ECG Signals are considered to extract ECG beats. Pan Tompkins algorithm is used to find R peaks [31]. Subtracting the consecutive R peaks gives us the RR interval. For segmenting ECG beats 30 s signal is considered at a time and average RR interval is found. An onset duration of one-third of average RR interval and offset duration of two-third of average RR interval is selected to segment one ECG beat.

Results obtained after Removal of Noise and Beat segmentation is shown in Sect. 3.1.

## 2.2 Feature extraction and classification through deep learning

DL models extracts features by using Convolutional Layers. These filters in these layers convolved with different kernels to generate a tensor of features. The filter will move from one point to next point depending on stride. In order to cover the entire beat, we use zero padding to filters. These tensor of features generated are activated using Rectified Linear Unit (ReLU) function. Let the convolution be defined as

$$x_{k}^{l} = f\left(\sum_{i \in M_{k}} x_{i}^{l-1} * w_{ik} + b_{k}\right)$$
(3)

 $M_K$  denotes the kernels used with different kernel size of 5 or 3. At layerl,  $x_k^l$  denotes output of  $k^{th}$  neuron,  $b_k$  is the bias of neuronk,  $w_{ik}$  is the weight kernel between neuron *i* at layer l - 1 and neuron *k* at layer *l*. f(.) denotes ReLU activation.

The model is trained until the loss function is minimized. The loss function is defined as

$$L = -\frac{1}{N} \sum_{n=1}^{N} \left[ y_n \log(\widehat{y_n}) + (1 - y_n) \log(1 - \widehat{y_n}) \right]$$
(4)

*N* denotes total neurons,  $y_n$  is the actual beat,  $\hat{y_n}$  is the predicted beat. To fine-tune the model, best hyper-parameter values and along with some regularization tricks is used to obtain ideal results. A batch of beats is given for training utilizing gradient descent algorithm. It optimizes the objective function  $J(\theta)$  with model constraint  $\theta \in \mathbb{R}^d$ . Gradient is defined as

$$g = \frac{1}{m} \nabla_{\theta} \sum_{i} L\left(f\left(x^{(i)}; \theta\right), y^{(i)}\right)$$
(5)

where *m* denotes batch size,  $\theta$  denotes the updating parameter,  $f(x^{(i)}; \theta)$  is predicted beat,  $y^{(i)}$  is actual beat and L(.) is the Loss function.

SGDM, ADAMs and RMSprop are optimizers used to update weights and offsets. SGDM accelerates a descent inappropriate path to reduce the oscillation. This is done by adding previous step update vector  $\gamma$  with learning rate  $\eta$ .

$$v_t = \gamma v_{t-1} + \eta \nabla_{\theta} J(\theta)$$
  

$$\theta_{t+1} = \theta_t - v_t$$
(6)



Fig. 2 Removal of Noise from ECG signal

where  $v_t$  is the momentum to be updated and  $\theta_{t+1}$  is updated parameter.

RMSprop adaptively uses exponential decaying average to converge and is given as

$$E\left|g^{2}\right|_{t} = \gamma E\left|g^{2}\right|_{t-1} + (1-\gamma)g_{t}^{2}$$
  

$$\theta_{t+1} = \theta_{t} - \frac{\eta}{\sqrt{E\left|g^{2}\right|_{t}} + \epsilon}g_{t}$$
(7)

where  $E|g^2|_t$  is the running average,  $g_t = \nabla_{\theta} J(\theta)$  and  $\theta_{t+1}$  is updated parameter.

Adams optimizer calculates adaptive learn rates. First moment (mean)  $m_t$  and second moment (variance)  $v_t$  estimates are updated as

$$m_{t} = \beta_{1}m_{t-1} + (1 - \beta_{1})g_{t}$$
  

$$v_{t} = \beta_{2}v_{t-1} + (1 - \beta_{2})g_{t}^{2}$$
(8)

Corrections made to  $m_t$  and  $v_t$  to get exact mean  $\widehat{m_t}$  and variance  $\widehat{v_t}$  is given as

$$\widehat{m_t} = \frac{m_t}{(1 - \beta_1^t)}$$

$$\widehat{v_t} = \frac{v_t}{(1 - \beta_2^t)}$$
(9)

Using mean  $\widehat{m_t}$  and variance  $\widehat{v_t}$  the parameter  $\theta$  is updated with step  $\in$  as

$$\theta_{t+1} = \theta_t - \frac{1}{\sqrt{\widehat{v_t}} + \epsilon} \widehat{m_t} \tag{10}$$

The final layer is the fully connected layer (FC) associated along with SoftMax layer. Three CNN architectures AlexNet, Resnet18 and GoogleNet are explored with different model training parameters. AlexNet model contains five convolutional layers and three fully connected layers. GoogleNet Model introduced a new inception layer that concatenated



Fig. 3 ECG peak detection and RR interval



Fig. 4 Segmented ECG beat

different filters into a single filter. It has two convolutional layers, nine inception layers and one fully connected layer. Resnet18 model has one convolution layer, eight Residual blocks and one fully connected layer. Each residual block internally has two convolution layers, i.e., ResNet18 has a total of 18 layers.

## **3 Results and discussions**

The proposed model is simulated and tested on a system with Intel core i7-9<sup>th</sup> Gen, 3.6 GHz CPU, 16 GB RAM, and NVIDIA GeForce GTX 1060 8 GB GPU.

#### 3.1 Pre-processing data

Noises that affect most frequently are baseline drifts, motion artifacts, power line interference and electromyography (EMG) noise. Noise is removed using DWT as mentioned in Sect. 2.1. Simulated result of noise removal is shown in Fig. 2.

For segmenting ECG beats 30 s signal is considered at a time and average RR interval is found (Fig. 3). An onset duration of one-third of average RR interval and offset duration of two-third of average RR interval is selected to segment one ECG beat as shown in Fig. 4.

A total of 40,213 ECG beats are extracted of which 27,344 beats are training beats, 4826 beats are validation beats and 8,043 beats are testing beats. Table 1 depicts the summary of total beats.

 Table 1
 Total beats extracted

 from MIT-BIH Arrhythmia

Database

Arrhythmia	Beat Type	Total Beats	Training Beats	
	N	10,838	7370	
	L	8075	5491	
	R	7259	4935	
	V	4334	2947	
	Р	7028	4779	
	А	1697	1154	

982

40,213

668

27,344

Table 2 Model training parameters considered

Parameters	Values
Optimizers	SGDM, RMSprop, ADAMs
Pooling method	Maximum pooling and average pooling
Mini batch size	32,64,128
Initial learn rate	0.0001, 0.001, 0.01
Drop factor of learn rate	0.1,0.2,0.5
Maximum epochs	6,8,10

F

Total ECG Beats

#### Table 3 Investigative results of fine-tuning AlexNet Model

Tested parameter	Optimizers	Optimizers				
	SGDM	Adam	RMSprop			
Batch size	32	32	32			
Maximum epochs	10	10	10			
Initial learn rate	0.0001	0.0001	0.0001			
Drop factor	0.2	0.2	0.2			
Training time	37 min 10 s	40 min 8 s	36 min 58 s			
Validation accuracy	98.47%	97.78%	97.14%			

Validation Beats

1300

969

872

520

843

204

118

4826

#### 3.2 Fine-tuning CNN models

The Fine-tuned DL models are considered for identifying normal ECG beats and ECG beats with cardiac Arrhythmia. Pre-trained Model AlexNet, ResNet18, GoogleNet are fine-tuned to get system's best accuracy. Table 2 represents various model training parameters considered to fine-tune a model to achieve best outcome.

The optimum network configuration parameter is found by block wise fine-tuning with various model training parameters. The performance changes which occur due to change in batch size was observed. High batch sizes take less time to train but are very prone to overfitting. Low batch sized takes more time to train but improves performance. A batch size of 128 was considered, and then, it was slowly reduced to check performance improvement. Reduction in batch size beyond 32 did not show any significant improvement in performance. Hence, a batch size of 32 is considered. Different initial learn rate like 0.01, 0.001, 0.0001 were considered while fine-tuning. Lower the initial learn rate, higher the performance. So, an initial learn rate of 0.0001 is considered. Sharp features are not identified by average pooling. So, we here used maximum pooling in fine-tuning. Different drop factor of 0.1, 0.2 and 0.5 were considered. Increasing the drop factor more than 0.5 did not improve performance of model. Hence drop factor of 0.5 with initial learn rate 0.0001 is fixed for GoogleNet, ResNet18. As AlexNet has a few layers a drop factor of 0.2 is sufficient. So a drop factor of 0.2 is considered for AlexNet with initial learn rate 0.0001.

Table 4 Investigative results of fine-tuning ResNet18 Model

Tested parameter	Optimizers				
	SGDM	Adam	RMSprop		
Batch size	32	32	32		
Maximum epochs	10	10	10		
Initial learn rate	0.0001	0.0001	0.0001		
Drop factor	0.5	0.5	0.5		
Training time	64 min 58 s	70 min 3 s	73 min 52 s		
Validation Accuracy	97.24%	99.09%	99.50%		

The CNN Models-AlexNet, ResNet18 and GoogleNet converged with firm accuracy after 10 epochs. So, 10 epochs have been considered for training models. Considering these parameters, Model was trained with different optimizers like SGDM, RMSprop and Adam.

Investigative Results obtained after fine-tuning the models are shown in Tables 3, 4 and 5 CNN Model-AlexNet achieved best training accuracy of 98.47% with training time of 37 min 10 s using SGDM optimizer. CNN Model-Resnet18 achieved best training accuracy of 99.50% with training time of 73 min 52 s using RMSprop optimizer. CNN Model-GoogleNet achieved best training accuracy of 98.57% with training time of 53 min 16 s using ADAMs optimizer. Figure 5 shows the training progress and loss function of the best Fine-tuned Models. This projected systems performance is evaluated by testing process using Test ECG beats.

Testing Beats

2168

1615

1452

867

1406

339

196

8043

Table 5	Investigative res	ults of fine-tuning	GoogleNet Model
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Tested parameter	Optimizers				
	SGDM	Adam	RMSprop		
Batch size	32	32	32		
Maximum epochs	10	10	10		
Initial learn rate	0.0001	0.0001	0.0001		
Drop factor	0.5	0.5	0.5		
Training time	86 min 0 s	77 min 16 s	99 min 3 s		
Validation accuracy	96.97%	98.57%	97.70%		

Table 6 Confusion matrix for N classes

True Class	Predicted Class						
	class 1	class 2		class N			
Class 1	<i>c</i> <sub>11</sub>	<i>c</i> <sub>12</sub>		$c_{1N}$			
Class 2	c <sub>21</sub>	<i>c</i> <sub>22</sub>		$c_{11}$			
:	÷	:	÷	÷			
Class N	$c_{N1}$	$c_{N1}$		$c_{NN}$			

#### 3.3 Confusion matrix and performance measures

Confusion matrix represents the performance of model. For a N class classification the confusion matrix obtained is of  $N \ge N$  dimensions as shown in Table 6.

Figure 6 shows the confusion matrices obtained by our fine-tuned models. To evaluate the performance, performance measures like precision, recall. Specificity, F-score and Accuracy are calculated. Formulae for calculating performance measures are listed below

$$Precision(class i) = \frac{c_{ii}}{\sum_{j=1}^{N} c_{ji}}$$
(11)

$$Recall(class i) = \frac{c_{ii}}{\sum_{j=1}^{N} c_{ij}}$$
(12)

$$Specificity (class i) = \frac{\left(\sum_{j=1}^{N} c_{jj} - c_{ii}\right)}{\left(\sum_{j=1}^{N} c_{ji} - c_{ii}\right) + \left(\sum_{j=1}^{N} c_{jj} - c_{ii}\right)}$$
(13)

$$F - Score(class i) = \frac{2 \times c_{ii}}{\sum_{j=1}^{N} c_{ij} + \sum_{j=1}^{N} c_{ji}}$$
(14)

$$OverallAccuracy = \frac{\sum_{i=1}^{N} c_{ii}}{\sum_{i=1}^{N} \sum_{j=1}^{N} c_{ij}}$$
(15)

where Tp gives True positives, Tn gives True negatives, Fp gives False positives and Fn gives False negatives.

Performance measures of all the fine-tuned models is summarized in Tables 7, 8 and 9. From the tabulated results it is



Fig. 5 Training process and loss of Fine-tuned CNN Model



(a) Confusion Chart using Fine-tuned CNN Model-AlexNet



(b) Confusion Chart using Fine-tuned CNN Model-ResNet18



(c) Confusion Chart using Fine-tuned CNN Model-GoogleNet

Fig. 6 Illustrations of Confusion Charts of Fine-tuned CNN Models. a Fine-tuned AlexNet Model. b Fine-tuned ResNet18 Model. c Finetuned GoogleNet Model

obvious that fine-tuned ResNet18 has attained highest test accuracy of 99.56%, while Fine-tuned AlexNet, GoogleNet, attained test accuracy of 99.09%, 98.98%.

 Table 7 Performance Measures using Fine-tuned AlexNet Model

ECG beat type	Precision (%)	Recall (%)	Specificity (%)	F score (%)
N	99.45	100	100	99.22
L	99.69	99.44	99.86	99.56
R	98.63	99.31	99.84	98.97
V	99.08	100	100	99.54
Р	99.64	99.50	99.92	99.57
А	100	89.38	99.57	94.39
F	99.46	94.38	97.74	96.85
Average	99.27	97.43	99.56	98.30

Overall test accuracy of model is 99.09%

Table 8 Performance Measures using Fine-tuned ResNet18 Model

ECG beat type	Precision (%)	Recall (%)	Specificity (%)	F score (%)
N	98.81	100	100	99.40
L	99.81	99.93	99.98	99.87
R	100	98.82	99.74	99.41
V	99.85	100	100	99.94
Р	100	99.43	99.91	99.71
А	100	99.23	99.92	99.10
F	97.47	98.46	97.67	97.97
Average	99.42	99.26	99.60	99.34

Overall test accuracy of model is 99.56%

 Table 9 Performance Measures using Fine-tuned GoogleNet Model

ECG Beat Type	Precision (%)	Recall (%)	Specificity (%)	F score (%)
N	98.50	100	100	99.24
L	100	96.26	99.07	98.10
R	100	100	100	100
V	95.69	100	100	97.80
Р	100	99.36	99.09	99.67
А	98.20	97.05	99.88	97.62
F	97.97	98.46	97.71	98.21
Average	98.62	98 73	99 39	98.66

Overall Test Accuracy of Model is 98.98%

## 3.4 Comparisons of state-of-the-art techniques

Performance measures achieved by several state-of-the-art studies in the literature is given in Table 10. Our proposed fine-tuned ResNet18 model outperformed existing models in the literature with an accuracy of 99.56%.

Study	No. of beats	ECG classes	methods	Precision (%)	Recall (%)	Specificity (%)	F Score (%)	Accuracy (%)
Mousavi et al. [6]	750	5	CNN-LSTM	79.31	93.88	92.05	85.98	92.50
Wu et al. [16]	8,582	4	CNN	-	-	-	86.00	-
Acharya et al. [22]	50,728	5	CNN	-	93.71	92.83	-	93.53
Manish et al. [15]	50,977	5	DNN	94.85	85.63	98.27	89.65	98.10
Li et al. [17]	94,031	5	ResNet	_	99.38	98.14	_	99.38
Oh et al. [18]	83,648	5	Modified U-Net	_	-	_	_	97.32
Ozal et al. [24]	7,326	5	LSTM-WS	_	-	_	_	99.39
Yildirim et al. [25]	1000	13	Deep-CNN	92.52	93.52	99.61	92.45	95.20
Yildirim et al. [25]	1000	15	Deep-CNN	90.48	88.57	99.39	89.28	92.51
Yildrim et.al. [30]	10,436	7	DNN	80.31	80.15	98.72	80.04	92.24
Yildrim et al. [30]	10,588	4	DNN	95.78	95.43	95.43	95.57	96.13
Proposed	40,213	7	Fine-tuned AlexNet	99.27	97.43	99.56	98.30	99.09
Models			Fine-tuned ResNet18	99.42	99.26	99.60	99.34	<b>99.56</b>
			Fine-tuned GoogleNet	98.62	98.73	99.39	98.66	98.98

Table 10 Comparison of State-of-the-art Models

# **4** Conclusions

In this Paper, AI-based fine-tuned CNN Models have been proposed to classify ECG beats. Pre-trained CNN Models AlexNet, ResNet18, GoogleNet are considered as backbone models in our work. We introduced a block-wise tuning strategy to optimize these backbone models and transfer learned knowledge to classify ECG beats. While fine-tuning each block it has been observed that the type of optimizer used while training has a large impact on the Performance of the Model. The time taken for training a Model depends on the depth of fine-tuned layers and the number of parameters considered while fine-tuning. It is observed that among all Models fine-tuned AlexNet has taken a minimum training time of 37 min 10 s using SGDM optimizer and produced test accuracy of 99.09%. Fine-tuned ResNet18 accomplished the highest accuracy of 99.56% using RMSprop optimizer with a Training time of 73 min 52 s. In future work, an Inference Model/working proof Hardware Model can be built considering real-time ECG Signals to detect abnormalities in ECG signals.

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