ORIGINAL PAPER



# New performance guarantees for the greedy maximization of submodular set functions

Jussi Laitila $^1$  · Atte Moilanen $^2$ 

Received: 3 June 2015 / Accepted: 2 May 2016 / Published online: 10 May 2016 © Springer-Verlag Berlin Heidelberg 2016

**Abstract** We present new tight performance guarantees for the greedy maximization of monotone submodular set functions. Our main result first provides a performance guarantee in terms of the overlap of the optimal and greedy solutions. As a consequence we improve performance guarantees of Nemhauser et al. (Math Program 14:265–294, 1978) and Conforti and Cornuéjols (Discr Appl Math 7:251–274, 1984) for maximization over subsets, which are at least half the size of the problem domain. As a further application, we obtain a new tight approximation guarantee in terms of the cardinality of the problem domain.

Keywords Approximation  $\cdot$  Cardinality  $\cdot$  Convex optimization  $\cdot$  Greedy algorithm  $\cdot$  Maximization  $\cdot$  Steepest ascent

## **1** Introduction

Let *X* be a finite set,  $X = \{x_1, ..., x_n\}$ , and let *T* be an integer such that  $0 < T \le n$ . We consider the cardinality-constrained maximization problem

$$\max\{f(S) \colon |S| = T, S \subset X\},\tag{1}$$

<sup>☑</sup> Jussi Laitila jussi.laitila@helsinki.fi

<sup>&</sup>lt;sup>1</sup> Department of Mathematics and Statistics, University of Helsinki, P.O. Box 68, 00014 Helsinki, Finland

<sup>&</sup>lt;sup>2</sup> Department of Biosciences, University of Helsinki, P.O. Box 65, 00014 Helsinki, Finland

where  $f: 2^X \to \mathbb{R}_+$  is a submodular set function. Recall that f is submodular if

$$f(S) + f(R) \ge f(S \cup R) + f(S \cap R) \tag{2}$$

for all  $S, R \subset X$ ; see, e.g., [1]. We further assume that f is nondecreasing;  $f(S) \leq f(R)$  for all  $S \subset R$ , and, without loss of generality, that  $f(\emptyset) = 0$ . We consider the following well-known greedy algorithm for solving problem (1):

#### Algorithm A

Step 0: Set  $S_0 = \emptyset$ . Go to Step 1. Step t  $(1 \le t \le T)$ : Select any  $x_t \in S_{t-1}$  such that

$$f(S_{t-1} \cup \{x_t\}) = \max\{f(S_{t-1} \cup \{x\}) \colon x \in X \setminus S_{t-i}\}.$$

Set  $S_t = S_{t-1} \cup \{x_t\}$ . Go to step t + 1. Step T + 1: Set  $S_{gr} = S_T$ . Stop.

Algorithm A has been extensively studied in the literature. It is well known [2,3], that it finds an optimal solution when f is an additive set function, i.e., when (2) holds with an equality for all  $S, R \subset X$ . Nemhauser et al. [1] (see also [4,5]) gave the following performance guarantee for Algorithm A for nonadditive functions f:

$$\frac{f(S_{gr})}{f(S_{opt})} \ge 1 - \left(1 - \frac{1}{T}\right)^T =: G_{NWF}(T),\tag{3}$$

where  $S_{opt}$  is an optimal solution to problem (1). Conforti and Cornuéjols [2] improved (3) to

$$\frac{f(S_{gr})}{f(S_{opt})} \ge \frac{1}{\alpha} \left( 1 - \left(1 - \frac{\alpha}{T}\right)^T \right) =: G_{CC}(T, \alpha), \tag{4}$$

for  $\alpha \in (0, 1]$ , where  $\alpha \in (0, 1]$  is the total curvature

$$\alpha = \max\left\{1 - \frac{f(X) - f(X \setminus \{x\})}{f(\{x\}) - f(\emptyset)} \colon x \in X, f(\{x\}) \neq f(\emptyset)\right\}.$$

It is known that  $\alpha \in (0, 1]$  if and only if f is nonadditive [2]. We also clearly have  $G_{NWT}(T) = G_{CC}(T, 1)$  and  $G_{CC}(T, \alpha) \rightarrow 1$  as  $\alpha \rightarrow 0^+$ . The above performance guarantees further satisfy the estimates

$$G_{CC}(T,\alpha) \ge \max\left\{G_{NWF}(T), \frac{1-e^{-\alpha}}{\alpha}\right\} \ge 1-e^{-1},$$

for all  $\alpha$  and T. The guarantees (3) and (4) are tight for suitable choices of parameters T and  $\alpha$ . For example, for all  $\alpha \in (0, 1]$  and  $T \ge 1$  there is a problem of the type (1) and the corresponding greedy solution  $S_{gr}$  such that  $f(S_{gr}) = G_{CC}(T, \alpha) f(S_{opt})$  [2].

Submodular optimization has played a central role in operations research and combinatorial optimization [6]. By now it has applications in various fields, including computer science [7], economics [8] and, more recently, ecology [9–11]. Problem (1) and the above performance guarantees have been extended to various other settings and problem structures, related to, for example, matroid [2, 12] and knapsack [13, 14] constraints, continuous algorithms [15, 16], nonmonotone functions [17], nonsubmodular functions [18] and supermodular minimization [19, 20].

To authors' knowledge, previously presented performance guarantees either do not depend on *T* or *n*, or, like (3) and (4), they are decreasing in *T*. However, when T = n, it is clear that  $S_{opt} = S_{gr}$ , so the greedy algorithm returns the optimal solution. This suggests that any performance guarantee should in fact be improving when *T* approaches and is close enough to *n*. We show that this is indeed the case. More generally, we show that increasing degree of overlap  $m = |S_{opt} \cap S_{gr}|$  between the sets  $S_{opt}$  and  $S_{gr}$  improves the approximation guarantees. While in applications the overlap *m* may not be known, we can give this quantity a useful lower bound. In fact, when T > n/2, we have  $m \ge 2T - n > 0$ . Our results thus have particular relevance for optimization problems where the maximum is sought over subsets of cardinality larger than n/2.

Let

$$G(T, \alpha, m) = \frac{1}{\alpha} \left( 1 - \left( 1 - \frac{\alpha m}{T} \right) \left( 1 - \frac{\alpha}{T} \right)^{T-m} \right)$$

and  $\widetilde{G}(T, \alpha, n) = G(T, \alpha, \max\{0, 2T - n\})$ . Our main result is the following.

**Theorem 1** Let  $\alpha \in (0, 1]$ , let  $1 \leq T \leq n$  and let  $S_{opt}$  and  $S_{gr}$  be an optimal, respectively a greedy, solution to problem (1) and let  $m = |S_{opt} \cap S_{gr}|$ . Then

$$\frac{f(S_{gr})}{f(S_{opt})} \ge G(T, \alpha, m) \ge \widetilde{G}(T, \alpha, n).$$
(5)

Moreover, these bounds are tight in the following sense: for every  $\alpha \in (0, 1]$  and numbers *n* and *T* such that  $1 \le T \le n$ , there is a problem of the type (1) and its greedy solution  $S_{gr}$  such that  $\max\{0, 2T - n\} = |S_{opt} \cap S_{gr}|$  and

$$\frac{f(S_{gr})}{f(S_{opt})} = \tilde{G}(T, \alpha, n).$$

We postpone the proof of Theorem 1 to Sect. 2.

*Remark 1* Theorem 1 strictly improves (4) and provides further examples of cases where the performance guarantee equals one. Indeed, for all *T* and *n* such that T > n/2, we have the strict inequality

$$G(T, \alpha, n) > G_{CC}(T, \alpha).$$

For T = n, we get  $\widetilde{G}(n, \alpha, n) = 1$ . Note that, by (4),  $\lim_{\alpha \to 0^+} \widetilde{G}(T, \alpha, n) = 1$ . Moreover, in the case m = T, we again get  $G(T, \alpha, T) = 1$ . Note also that  $G(T, \alpha, m)$  is decreasing in  $\alpha$ , so (5) can be substituted by a weaker but simpler approximation guarantee

$$\frac{f(S_{gr})}{f(S_{opt})} \ge 1 - \left(1 - \frac{m}{T}\right) \left(1 - \frac{1}{T}\right)^{T-m}$$

Using Theorem 1, one can derive other new performance guarantees for the greedy algorithm. As an example of independent interest, we present the following performance guarantee in terms of n only.

**Corollary 1** Let  $\alpha \in (0, 1]$ ,  $1 \le T \le n$ , and let  $S_{opt}$  and  $S_{gr}$  be an optimal, respectively a greedy, solution to problem (1). Then

$$\frac{f(S_{gr})}{f(S_{opt})} \ge \frac{1}{\alpha} \left( 1 - \left( 1 - \frac{\alpha}{\lfloor \frac{n}{2} \rfloor} \right)^{\lfloor \frac{n}{2} \rfloor} \right) \ge \frac{1}{\alpha} \left( 1 - \left( 1 - \frac{2\alpha}{n} \right)^{n/2} \right), \quad (6)$$

where  $\lfloor x \rfloor$  denotes the largest integer not greater than x. The left-hand estimate is tight in the following sense: for every  $\alpha \in (0, 1]$  and  $n \ge 2$ , there is a problem of the type (1) and its greedy solution  $S_{gr}$  such that

$$\frac{f(S_{gr})}{f(S_{opt})} = \frac{1}{\alpha} \left( 1 - \left( 1 - \frac{\alpha}{\lfloor \frac{n}{2} \rfloor} \right)^{\lfloor \frac{n}{2} \rfloor} \right).$$

*Proof* If *n* is an odd integer, it is easy to check that the minimum of  $\widetilde{G}(T, \alpha, n)$  over all integers *T* with  $0 \le T \le n$  is  $\widetilde{G}((n-1)/2, \alpha, n)$ . Moreover, when treated as a continuous function of *T*,  $\widetilde{G}(T, \alpha, n)$  attains its minimum at T = n/2. Together with Theorem 1 this yields (6). Tightness of the left-hand inequality in (6) follows from Theorem 1 with the choice  $T = \left|\frac{n}{2}\right|$ .

### 2 Proof of Theorem 1

In this section we present a proof of Theorem 1. We first prove (5). Note that the right-hand inequality in (5) follows directly from  $m = |S_{opt} \cap S_{gr}| \ge \max\{0, 2T - n\}$  and the fact that  $G(T, \alpha, m)$  is increasing in m.

We next prove the left-hand inequality in (5). We may assume that 0 < m < T. Indeed, if m = T, then  $S_{gr} = S_{opt}$  and the claim is trivial. If m = 0, the claim follows from (4).

Let  $S_0 = \emptyset$  and  $S_t = \{y_1, \dots, y_t\} \subset X$  be the successive sets chosen by the greedy algorithm for  $t = 1, \dots, T$ , so that  $S_0 \subset S_1 \subset \dots \subset S_T$ . Let

$$a_t = \frac{f(S_t) - f(S_{t-1})}{f(S_{opt})}$$

🖄 Springer

for t = 1, ..., T. Because f is nondecreasing, each  $a_t$  is nonnegative and

$$\frac{f(S_{gr})}{f(S_{opt})} = \sum_{i=1}^{T} a_i.$$

Let  $1 \le j_1 \le \cdots \le j_m \le T$  denote the indices for which  $S_{gr} \cap S_{opt} = \{y_{j_1}, \dots, y_{j_m}\}$ . Denote  $j_0 = 0$  and  $j_{m+1} = T$ . We will use the following lemma from [2].

Lemma 1 ([2, Lemma 5.1]) We have

$$\alpha \sum_{\{i: y_i \in S_{t-1} \setminus S_{opt}\}} a_i + \sum_{\{i: y_i \in S_{t-1} \cap S_{opt}\}} a_i + (T - |S_{t-1} \cap S_{opt}|)a_t \ge 1,$$

for t = 1, ..., T.

Using Lemma 1, we get

$$\frac{f(S_{gr})}{f(S_{opt})} \ge B(J),\tag{7}$$

where  $J = \{j_1, ..., j_m\}$  and, for  $U \subset \{1, ..., T\}$ , B(U) denotes the minimum of the linear program

minimize 
$$\sum_{i=1}^{T} b_i$$
  
s.t.  $\alpha \sum_{i \in V_{t-1} \setminus U} b_i + \sum_{i \in U \cap V_{t-1}} b_i + (T - |U \cap V_{t-1}|)b_t \ge 1, \quad t = 1, \dots, T$   
 $b_t \ge 0, \qquad t = 1, \dots, T,$ 
(8)

where  $V_t = \{1, ..., t\}$ . The following lemma refines [2, Lemma 5.2].

**Lemma 2**  $B(J) \ge B(\{T - m + 1, T - m + 2, ..., T\}).$ 

*Proof* Fix  $1 \le r \le m$  and consider  $q = j_r \in J$ . We first show that  $b_q \le b_{q+1}$  for some optimal solution to (8) with U = J. To this end, assume that this does not hold for some optimal solution  $b = (b_1, \ldots, b_T)$ . Then  $\varepsilon := b_q - b_{q+1} > 0$ . The constraints q and q + 1 are

$$\alpha \sum_{i \in V_{q-1} \setminus J} b_i + \sum_{i \in J \cap V_{q-1}} b_i + (T-r+1)b_q \ge 1;$$
  
$$\alpha \sum_{i \in V_q \setminus J} b_i + \sum_{i \in J \cap V_q} b_i + (T-r)b_{q+1} \ge 1.$$

Deringer

Because  $V_q \setminus J = V_{q-1} \setminus J$  and  $J \cap V_q = (J \cap V_{q-1}) \cup \{q\}$ , the constraint q + 1 is equivalent to

$$\alpha \sum_{i \in V_{q-1} \setminus J} b_i + \sum_{i \in J \cap V_{q-1}} b_i + b_q + (T-r)b_{q+1} \ge 1.$$

Therefore

$$\alpha \sum_{i \in V_{q-1} \setminus J} b_i + \sum_{i \in J \cap V_{q-1}} b_i + (T-r+1)b_q \ge 1 + \varepsilon(T-r) > 1,$$

which shows that the constraint q is not tight. Form a new solution  $b' = (b'_1, \ldots, b'_T)$  by setting  $b'_i = b_i$  for  $1 \le i \le q - 1$ ,  $b'_q = b_q - \varepsilon(T - r)/(T - r + 1)$  and  $b'_i = b_i + \varepsilon/(T - r + 1)$  for  $q + 1 \le i \le T$ . It is easy to check that b' is feasible. Moreover,

$$b'_q - b'_{q+1} = b_q - \frac{\varepsilon(T-r)}{T-r+1} - b_{q+1} - \frac{\varepsilon}{T-r+1} = 0$$

and

$$\sum_{i=1}^{T} b'_{i} = \sum_{i=1}^{T} b_{i} + \frac{\varepsilon(T-q)}{T-r+1} - \frac{\varepsilon(T-r)}{T-r+1} \le \sum_{i=1}^{T} b_{i},$$

because  $r \leq q$ . Hence b' is an optimal solution with  $b'_q \leq b'_{q+1}$ .

Assume next that  $q = j_r \in J$  and  $q + 1 \notin J$  for some r. Let  $b = (b_1, \ldots, b_T)$  be a feasible solution to (8) with U = J, so that

$$\alpha \sum_{i \in V_{t-1} \setminus J} b_i + \sum_{i \in J \cap V_{t-1}} b_i + (T - |J \cap V_{t-1}|) b_t \ge 1,$$
(9)

for  $1 \le t \le T$ . Assume also that  $b_q \le b_{q+1}$ . Let  $J' = \{j_1, \ldots, j_{r-1}, q + 1, j_{r+1}, \ldots, j_m\}$ . We will show that b is a feasible solution to (8) with U = J'. Consider first  $1 \le t \le q$ . Then  $V_{t-1} \setminus J' = V_{t-1} \setminus J$  and  $J' \cap V_{t-1} = J \cap V_{t-1}$ , so

$$\alpha \sum_{i \in V_{t-1} \setminus J'} b_i + \sum_{i \in J' \cap V_{t-1}} b_i + (T - |J' \cap V_{t-1}|)b_t \ge 1,$$

Deringer

by (9). Consider next t = q + 1. Then  $V_{t-1} \setminus J' = (V_{t-1} \setminus J) \cup \{q\}$  and  $J' \cap V_{t-1} = (J \cap V_{t-1}) \setminus \{q\}$ . By (9) and using  $b_q \leq b_{q+1}$ , we get

$$\alpha \sum_{i \in V_q \setminus J'} b_i + \sum_{i \in J' \cap V_q} b_i + (T - |J' \cap V_q|)b_{q+1}$$
  
=  $\alpha \sum_{i \in V_q \setminus J} b_i + \alpha b_q + \sum_{i \in J \cap V_q} b_i - b_q + (T - |J \cap V_q| + 1)b_{q+1}$   
 $\geq 1 + \alpha b_q - b_q + b_{q+1} \geq 1.$ 

Finally, consider t = q + k for  $k \ge 2$ . Then  $V_{t-1} \setminus J' = ((V_{t-1} \setminus J) \cup \{q\}) \setminus \{q+1\}$ and  $J' \cap V_{t-1} = ((J \cap V_{t-1}) \setminus \{q\}) \cup \{q+1\}$ . By (9) and using  $b_q \le b_{q+1}$ , we get similarly as above

$$\alpha \sum_{i \in V_{q+k-1} \setminus J'} b_i + \sum_{i \in J' \cap V_{q+k-1}} b_i + (T - |J' \cap V_{q+k-1}|)b_{q+k}$$
  

$$\geq 1 + (b_{q+1} - b_q)(1 - \alpha) \geq 1.$$

This shows that *b* is a feasible solution to (8) with U = J'. By combining the above results, we get

$$B(J) \ge B(J').$$

The proof of Lemma 2 is completed by repeating this argument sufficiently many times.  $\hfill \Box$ 

Lemma 2 and (7) now imply

$$\frac{f(S_{gr})}{f(S_{opt})} \ge B(\{T - m + 1, T - m + 2, \dots, T\}).$$

By the weak duality theorem, we get

$$\frac{f(S_{gr})}{f(S_{opt})} \ge \sum_{i=1}^{T} c_i^*,\tag{10}$$

D Springer

where  $c^* = (c_1^*, \dots, c_T^*)$  is an optimal solution to the dual problem of (8):

maximize 
$$\sum_{i=1}^{T} c_i$$
 (11)

s.t. 
$$Tc_t + \alpha \sum_{i=t+1}^{T} c_i \le 1,$$
  $1 \le t \le T - m$  (12)

$$(2T - m + 1 - t)c_t + \sum_{i=t+1}^{T} c_i \le 1, \quad T - m + 1 \le t \le T \quad (13)$$

$$c_i \ge 0, \qquad \qquad i = 1, \dots, T. \tag{14}$$

Define the vector  $c = (c_1, \ldots, c_T)$  by

$$c_{t} = \begin{cases} \frac{1}{T} \left( 1 - \frac{\alpha m}{T} \right) \left( 1 - \frac{\alpha}{T} \right)^{T - m - t}, & 1 \le t \le T - m, \\ \frac{T - m}{(2T - m + 1 - t)(2T - m - t)}, & T - m + 1 \le t \le T. \end{cases}$$

We will need the following two straightforward indentities:

$$\sum_{i=s}^{T-m} c_i = \frac{1}{\alpha} \left( 1 - \frac{\alpha m}{T} \right) \left( 1 - \left( 1 - \frac{\alpha}{T} \right)^{T-m-s+1} \right), \qquad 1 \le s \le T - m; \tag{15}$$

$$\sum_{i=k}^{T} c_i = \frac{T-k+1}{2T-m-k+1}, \qquad T-m+1 \le k \le T+1.$$
(16)

**Lemma 3** The vector c is a feasible solution to problem (11).

*Proof* Consider first  $1 \le t \le T - m - 1$ . By (15) and (16),

$$\sum_{i=s}^{T} c_i = \sum_{i=s}^{T-m} c_i + \sum_{i=T-m+1}^{T} c_i = \frac{1}{\alpha} \left( 1 - \frac{\alpha m}{T} \right) \left( 1 - \left( 1 - \frac{\alpha}{T} \right)^{T-m-s+1} \right) + \frac{m}{T},$$

for  $1 \le s \le T - m$ . Hence

$$Tc_{t} + \alpha \sum_{i=t+1}^{T} c_{i} = \left(1 - \frac{\alpha m}{T}\right) \left(1 - \frac{\alpha}{T}\right)^{T-m-t} + \left(1 - \frac{\alpha m}{T}\right) \left(1 - \left(1 - \frac{\alpha}{T}\right)^{T-m-t}\right) + \frac{\alpha m}{T}$$
$$= 1,$$

so  $c_t$  satisfies the constraint (12).

By (16),

$$Tc_{T-m} + \alpha \sum_{i=T-m+1}^{T} c_i = \left(1 - \frac{\alpha m}{T}\right) + \frac{\alpha m}{T} = 1,$$

so  $c_{T-m}$  also satisfies the constraint (12).

For  $T - m + 1 \le t \le T$ , we get from (16) that

$$(2T - m + 1 - t)c_t + \sum_{i=t+1}^{T} c_i = 1,$$

so  $c_t$  satisfies the constraint (13).

Finally, it is clear from the definition that each  $c_t$  satisfies the constraint (14). This completes the proof of Lemma 3.

Lemma 3 and (10) imply

$$\frac{f(S_{gr})}{f(S_{opt})} \ge \sum_{i=1}^{T} c_i.$$

Moreover, by (15) and (16),

$$\sum_{i=1}^{T} c_i = \frac{1}{\alpha} \left( 1 - \frac{\alpha m}{T} \right) \left( 1 - \left( 1 - \frac{\alpha}{T} \right)^{T-m} \right) + \frac{m}{T} = G(T, \alpha, m),$$

which yields the desired estimate

$$\frac{f(S_{gr})}{f(S_{opt})} \ge G(T, \alpha, m)$$

and completes the proof of (5).

We next show the tightness of  $\widetilde{G}(T, \alpha, n)$  by modifying the proof of [2, Theorem 5.4]. Let  $1 \leq T < n$  be any positive numbers. Pick any number  $1 \leq r \leq n/2$ , let  $X = \{a_1, \ldots, a_r, b_1, \ldots, b_{n-r}\}$  and let  $f : 2^X \to \mathbb{R}_+$  be the set function

$$f(\{a_{i_1},\ldots,a_{i_s},b_{j_1},\ldots,b_{j_u}\}) = u + \left(1 - \frac{\alpha u}{T}\right) \sum_{k=1}^s \left(1 - \frac{\alpha}{T}\right)^{i_k - 1}$$

defined for all subsets  $\{a_{i_1}, \ldots, a_{i_s}, b_{j_1}, \ldots, b_{j_u}\} \subset X$ . Then  $f(\emptyset) = 0$ . For any  $S = \{a_{i_1}, \ldots, a_{i_s}, b_{j_1}, \ldots, b_{j_u}\} \subsetneq X$ , where s < r and  $u \le n - r$ , and  $a_i \in X \setminus S$ , we have

$$f(S \cup \{a_i\}) - f(S) = \left(1 - \frac{\alpha u}{T}\right) \left(1 - \frac{\alpha}{T}\right)^{i-1} \ge 0.$$

For any  $S = \{a_{i_1}, \ldots, a_{i_s}, b_{j_1}, \ldots, b_{j_u}\} \subsetneq X$ , where  $s \le r$  and u < n - r, and  $b_j \in X \setminus S$ , we have

$$f(S \cup \{b_j\}) - f(S) = 1 - \frac{\alpha}{T} \sum_{k=1}^{s} \left(1 - \frac{\alpha}{T}\right)^{i_k - 1} \ge 0.$$

By recalling that a set function  $g: 2^X \to \mathbb{R}_+$  is submodular if and only if

$$g(S \cup \{x\}) - g(S) \ge g(R \cup \{x\}) - g(R),$$

for all  $S \subset R \subsetneq X$  and  $x \in X \setminus R$  (e.g., [1]), these inequalities show that f is submodular and nondecreasing. Moreover,

$$\max\left\{1 - \frac{f(X) - f(X \setminus \{x\})}{f(\{x\})} : x \in X, f(\{x\}) \neq 0\right\}$$
$$= 1 - \frac{f(X) - f(X \setminus \{a_i\})}{f(\{a_i\})} = \alpha,$$

for any  $1 \le i \le r$ , so *f* has total curvature  $\alpha$ .

Consider next the case where T > n/2. Set r = n - T, so that r < n/2 < Tand n - r = T. It is easy to verify that  $S_{opt} = \{b_1, \ldots, b_T\}$  is an optimal solution to problem (1) with  $f(S_{opt}) = T$ . Since  $f(\{a_1\}) = f(\{b_j\}) = 1$ , for any  $1 \le j \le T$ , the greedy algorithm can choose the element  $a_1$  at the first iteration. Assume next that the greedy algorithm has chosen  $S_{t-1} = \{a_1, \ldots, a_{t-1}\}$  for some  $t \le n - T$ . Using the fact

$$\sum_{k=1}^{l} \left(1 - \frac{\alpha}{T}\right)^{k-1} = \frac{T}{\alpha} \left(1 - \left(1 - \frac{\alpha}{T}\right)^{l}\right)$$

it is easy to see that

$$f(S_{t-1} \cup \{a_t\}) = f(S_{t-1} \cup \{b_j\}) = \sum_{i=1}^t \left(1 - \frac{\alpha}{T}\right)^{i-1},$$

so the greedy algorithm can choose  $a_t$  at the *t*th iteration. We therefore can have  $S_{gr} = \{a_1, \ldots, a_{n-T}, b_1, \ldots, b_{2T-n}\}$ . This solution has the value

$$f(S_{gr}) = \frac{T}{\alpha} \left( 1 - \left(1 - \frac{\alpha m}{T}\right) \left(1 - \frac{\alpha}{T}\right)^{n-T} \right)$$

The claim follows because  $m = |S_{opt} \cap S_{gr}| = 2T - n$ , whence we obtain n - T = T - m.

The proof of case  $T \le n/2$  is easier, so we omit its proof.

Acknowledgements J.L. and A.M were supported by the ERC-StG Grant 260393. A.M. was supported by the Academy of Finland Centre of Excellence programme 2012–2017, Grant 250444, and the Finnish Natural Heritage Services (Metsähallitus).

## References

- Nemhauser, G.L., Wolsey, L.A., Fisher, M.L.: An analysis of approximations for maximizing submodular set functions I. Math. Program. 14, 265–294 (1978)
- Conforti, M., Cornuéjols, G.: Submodular set functions, matroids and the greedy algorithm: tight worst-case bounds and some generalizations of the Rado–Edmonds theorem. Discr. Appl. Math. 7, 251–274 (1984)
- 3. Edmonds, J.: Matroids and the greedy algorithm. Math. Program. 1, 127-136 (1971)
- Cornuéjols, G., Fisher, M.L., Nemhauser, G.L.: Location of bank accounts to optimize float: an analytic study of exact and approximate algorithms. Manag. Sci. 23, 789–810 (1977)
- Nemhauser, G.L., Wolsey, L.A.: Best algorithms for approximating the maximum of a submodular set function. Math. Oper. Res. 3, 177–188 (1978)
- Goundan, P.R., Schulz, A.S.: Revisiting the greedy approach to submodular set function maximization. Working Paper, Massachusetts Institute of Technology (2007). http://www.optimization-online.org/ DB\_HTML/2007/08/1740.html
- Krause, A., Golovin, D.: Submodular function maximization. In: Bordeaux, L., Hamadi, Y., Kohli, P. (eds.) Tractability: Practical Approaches to Hard Problems, pp. 71–104. Cambridge University Press, Cambridge (2014)
- 8. Topkis, D.M.: Supermodularity and Complementarity. Princeton University Press, Princeton (1998)
- Bordewich, M., Semple, C.: Budgeted nature reserve selection with diversity feature loss and arbitrary split systems. J. Math. Biol. 64, 69–85 (2012)
- Golovin, D., Krause, A., Gardner, B., Converse, S.J., Morey, S.: Dynamic resource allocation in conservation planning. In: Proceeding of the 25th AAAI Conference on Artificial Intelligence, pp. 1331–1336 (2011)
- Moilanen, A.: Landscape Zonation, benefit functions and target-based planning: unifying reserve selection strategies. Biol. Conserv. 134, 571–579 (2007)
- Fisher, M.L., Nemhauser, G.L., Wolsey, L.A.: An analysis of approximations for maximizing submodular set functions II. Math. Program. Study 8, 73–87 (1978)
- Kulik, A., Shachnai, H., Tamir, T.: Approximations for monotone and non-monotone submodular maximization with knapsack constraints. Math. Oper. Res. 38, 729–739 (2013)
- Sviridenko, M.: A note on maximizing a submodular set function subject to a knapsack constraint. Oper. Res. Lett. 32, 41–43 (2004)
- Calinescu, G., Chekuri, C., Pál, M., Vondrák, J.: Maximizing a submodular set function subject to a matroid constraint. SIAM J. Comput. 40, 1740–1766 (2011)
- Vondrák, J.: Submodularity and curvature: the optimal algorithm. RIMS Kôkyûroku Bessatsu B23, 253–266 (2010)
- Feige, U., Mirrokni, V.S., Vondrák, J.: Maximizing non-monotone submodular functions. SIAM J. Comput. 40, 1133–1153 (2011)
- Wang, Z., Moran, B., Wang, X., Pan, Q.: Approximation for maximizing monotone non-decreasing set functions with a greedy method. J. Comb. Optim. 31, 29–43 (2016)
- Il'ev, V.: An approximation guarantee of the greedy descent algorithm for minimizing a supermodular set function. Discr. Appl. Math. 114, 131–146 (2001)
- Il'ev, V., Linker, N.: Performance guarantees of a greedy algorithm for minimizing a supermodular set function on comatroid. Eur. J. Oper. Res. 171, 648–660 (2006)