RESEARCH

Compact Three‑Channel Photonic Crystal Fiber Sensor Based on Surface Plasmon Resonance

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Abstract

In order to improve the integration of fber optic sensors, this paper designs a dual-core three-channel photonic crystal fber (PCF) optic sensor that can simultaneously measure the refractive index of a liquid, its temperature, and the ambient magnetic feld. Based on the PCF as well as SPR principles, the sensor has two D-planes, one coated with PDMS as well as a gold flm for detecting temperature and the other coated with a gold flm for detecting refractive index and coated with a gold flm over the air holes on the side of the core where the refractive index is measured and a magnetic fuid injected into the air holes to detect the magnetic feld. The results show a maximum sensitivity of 20,000 nm/RIU for refractive index, a linear sensitivity of 116 pm/Oe for magnetic feld, and 5300 pm/°C for temperature when the sample's refractive index is between 1.36 and 1.42, the temperature is between 0 $^{\circ}$ C and 50 $^{\circ}$ C, and the magnetic field is between 20 and 550 Oe. The sensitivity matrix of temperature versus refractive index is also given. The sensor is compact and simple to prepare, providing a new solution for miniaturization and integration of multifunctional photonic devices.

Keywords Photonic crystal fber · Surface plasmon resonance · Sensitivity matrix · Magnetic feld · Temperature · Refractive index

Introduction

Photonic crystal fber (PCF), with their periodically aligned pore structure, is an excellent platform for developing sensors with many sensing advantages. Recently, researchers have combined the surface plasmon resonance (SPR) effect with PCF sensing technology to construct PCF sensors that can excite the SPR efect. This type of sensor has good sensing characteristics, which makes it suitable for sensor development [[1\]](#page-8-0). SPR technology is based on the principle of total refection. When the incident light on the surface of the fber undergoes total refection, part of the light will return to the fber. The other part will propagate along the surface of the fber in the form of a swift wave, which is interfered with by the photons and undergoes a collective oscillation

 \boxtimes Xili Jing sljingxl@ysu.edu.cn to form a plasma wave, and the resonance of the surface plasma wave (SPW) with the evanescent wave occurs under a certain incident angle and wavelength to produce the SPR efect, which results in a corresponding Resonance Absorption Peak [[1](#page-8-0)]. At present, SPR technology has been used in the felds of biomonitoring analysis [\[2](#page-8-1)[–4](#page-8-2)]. PCF sensors based on the SPR effect are characterized by high sensitivity and fexible design [[5](#page-8-3), [6](#page-8-4)].

The optical phenomenon of SPR allows it to track the interactions between biomolecules in their natural state in real-time. In 2006, Hassani et al. designed a PCF based SPR sensor by combining SPR sensing with PCF for the frst time [[7](#page-8-5)]. This sensor has a stable structure and good sensing characteristics. However, fabricating is more difficult because its metal film and measurement channels are located in the air holes. In 2012, Ming Tian et al. proposed a D-type PCF [[8\]](#page-8-6). In this structure, a meta flm and a liquid are applied to the exterior of the cladding, making it easy to prepare. The above sensors can only measure one parameter, and the study of multi-parameter measurement is conducive to improving optical fber integration. In 2021, Xiao et al. designed a PCF-SPR sensor that can perform simultaneous three-parameter measurements. The air holes

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next to the fber core are flled with temperature-sensitive materials and magnetic fuids, respectively, and graphene and metal flms are coated on the side-throw surface of the fber, enabling simultaneous measurement of temperature, refractive index, and magnetic feld [\[9](#page-8-7)]. In 2022, Yin et al. designed a D-type dual-core PCF-SPR sensor. The upper throw surface is coated with temperature-sensitive material and a metal flm for temperature measurement, and the lower throw surface is coated with a metal flm for refractive index measurement [[10](#page-8-8)]. The reported SPR-PCF sensors achieve multifunctional detection but still have the disadvantages of complex preparation and low integration and do not meet the trend of device miniaturization and integration.

This paper proposes a three-parameter dual-core PCF-SPR sensor based on the above research background. Temperature and refractive index measurements are realized by applying a metal flm and temperature-sensitive material to the upper polished surface and a gold flm to the lower polished surface. Air holes next to the refractive index channel cores are filled with magnetic fluid for magnetic field measurements. This makes the three-parameter sensor easier to fabricate. The detection ranges chosen for this study were temperature 0–50 °C, refractive index 1.36–1.42, and magnetic feld strength 20–550 Oe. The results showed that the refractive index showed a maximum sensitivity of 20,000 nm/RIU, the linear sensitivity for temperature was 5.3 nm/°C, and the linear sensitivity for the magnetic feld was 116 pm/Oe.

Theoretical Foundations and Sensing Structures

The cross-section of the sensor is shown in Fig. [1](#page-1-0), from which it can be seen that the two sides are polished to different depths, with the upper polished depth being d_1 and the lower polished depth being d_2 . The radius of the air holes is r_1 , the radius of the magnetic field channel is r_2 , and the spacing between the nearest neighboring air holes is *c*.

Fig. 1 Cross-section of a multi-parameter PCF

Polydimethylsiloxane (PDMS) was coated immediately adjacent to the gold flm for temperature measurements. A layer of gold film with a thickness of t_2 on the lower polished surface is coated with gold for detecting the RI of the liquid, and one end of the fber core of the lower polished surface is flled with a magnetic fluid. A gold film of thickness t_2 was coated on the lower polished surface to detect the RI of the fuid, and the air holes at one end of the fber core on the lower polished surface were flled with magnetic fuid. The air holes were coated with a gold flm to detect the magnetic feld. The PDMS will be easily connected to other materials after heating. Based on the properties of PDMS as well as Si, temperature measurements can be realized [\[11](#page-8-9)]. Selection of $Fe₃O₄$ as a magnetic fluid to enable the detection of magnetic felds [[12\]](#page-8-10).

The following process can prepare the sensor: frst, PCF preforms are obtained by ultrasonic drilling [\[11,](#page-8-9) [12](#page-8-10)], sol-gel $[13]$ $[13]$, beam stacking $[14]$ $[14]$, or extrusion $[15, 16]$ $[15, 16]$ $[15, 16]$ $[15, 16]$ $[15, 16]$. After that, it is processed into PCF semi-fnished products [[17\]](#page-8-15). Double-sided polished photonic crystal fiber can be obtained by polishing [[18,](#page-8-16) [19\]](#page-8-17). Then, a gold flm is applied to the two polishing planes and the surface of the air holes at one end of the fber core (2) by magnetron sputtering. $[20, 21]$ $[20, 21]$ $[20, 21]$ $[20, 21]$ $[20, 21]$. Then, PDMS $[22]$ $[22]$ $[22]$ is applied to the gold film on the upper surface. Finally, $Fe₃O₄$ was injected into the air holes coated with gold flm using a micro syringe and plasticized. At this point, the fabrication of the sensor designed in this paper is complete, as shown in Fig. [2.](#page-2-0)

Silicon dioxide is commonly used as a material for making optical fber, and the equation for calculating its material dispersion is as follows [[23\]](#page-8-21):

$$
n^{2}(\lambda) = 1 + \sum_{i=1}^{3} \frac{a_{i} \lambda^{2}}{\lambda^{2} - b_{i}^{2}}
$$
 (1)

The dielectric constant of the gold flm can be expressed in terms of the Lorentz-Drude model as follows [[24\]](#page-8-22):

$$
\varepsilon_r(\omega) = 1 - \frac{\Omega_p^2}{\omega(\omega - i\tau_0)} + \sum_{j=1}^k \frac{f_j \omega_p^2}{\left(\omega_j^2 - \omega^2\right) + i\omega\tau_j} \qquad (2)
$$

Fig. 2 Three-dimensional modeling of the PCF-SPR sensor

We can also use expressions to characterize the refractive index of the PDMS used for detecting temperature as a function of temperature [[25](#page-8-23)].

$$
n_{PDMS} = -4.5 \times 10^{-4} \cdot T + 1.4176 \tag{3}
$$

A magnetofuid is a colloidal solution. The Langevin function expresses its dependence on temperature and magnetic feld strength [[26–](#page-8-24)[29\]](#page-8-25). The magnetic fuid used in this simulation is Fe₃ O_4 . The following expression can represent its material detection expression [\[30](#page-9-0)].

$$
n_{MF} = 1.3592 - 2.4 \times 10^{-4} \cdot T + 4.98 \times 10^{-5} \cdot H
$$
 (4)

Sensitivity is an essential index for evaluating the performance of photonic crystal fber optic sensors, and it can be represented by the following expression [\[31\]](#page-9-1).

$$
S(\lambda) = \frac{\Delta \lambda_{\text{peak}}}{\Delta n_s} \left(\frac{\text{nm}}{\text{RIU}}\right)
$$
 (5)

The full width at half maxima (FWHM) of the resonance peak afects the sensor's resolution, and too much sensor sensitivity leads to too much FWMH, which results in lower sensor resolution [[32\]](#page-9-2). For this, we choose the quality factor fgure of merit (FOM) to judge the transmission characteristics [[10\]](#page-8-8):

$$
FOM = \frac{S(\lambda)}{FWHM}
$$
 (6)

According to the above formula, the material's refractive index changes when the magnetic feld and temperature change, leading to a shift in the resonance wavelength. By observing the shift, we can calculate its sensitivity. The expression for calculating the sensitivity of the two is as follows [[10\]](#page-8-8):

$$
K_{ch}(T) = \Delta \lambda_{ch} / \Delta T K_{ch}(H) = \Delta \lambda_{ch} / \Delta H
$$
\n(7)

We can derive the sensitivity matrices for the temperature and magnetic feld channels using the following matrices:

$$
\begin{pmatrix}\n\Delta \lambda_1 \\
\Delta \lambda_2\n\end{pmatrix} = \begin{pmatrix}\n\frac{\lambda_{1T}}{\Delta T} & \frac{\lambda_{1H}}{\Delta H} \\
\frac{\lambda_{2T}}{\Delta T} & \frac{\lambda_{2H}}{\Delta H}\n\end{pmatrix}\n\begin{pmatrix}\n\Delta T \\
\Delta B\n\end{pmatrix} = \begin{pmatrix}\nK_{ch1}(T) & K_{ch1}(H) \\
K_{ch2}(T) & K_{ch2}(H)\n\end{pmatrix}\n\begin{pmatrix}\n\Delta T \\
\Delta H\n\end{pmatrix}
$$
\n(8)

where $\Delta\lambda_{ii}$ denotes the shift of the resonance wavelengths of the temperature and magnetic feld channels for temperature or magnetic feld changes, ∆Tand ∆H denote the changes in temperature and magnetic field, respectively, and $K_{chi(J)}$ denotes the sensitivity of the two channels to changes in temperature and magnetic feld.

We can get the temperature and magnetic feld sensitivity matrices by solving the inverse matrix of the above matrices [[10\]](#page-8-8):

$$
\begin{pmatrix}\n\Delta T \\
\Delta H\n\end{pmatrix} = \begin{pmatrix}\nK_{ch1}(T) K_{ch1}(H) \\
K_{ch2}(T) K_{ch2}(H)\n\end{pmatrix}^{-1} \begin{pmatrix}\n\Delta \lambda_1 \\
\Delta \lambda_2\n\end{pmatrix}
$$
\n(9)

In this simulation, we use the fnite element method in Comsol to perform the analysis. The perfectly matched layer (PML) frst absorbs the radiant energy of other light and allows for a stable transmission of energy in the core.

Figure [3](#page-3-0) shows the electric feld distribution. For the parameters, we chose the radius of the air holes as $r_1 = 1.5$ um, the radius of the air holes injected into the magnetic fluid as $r_2 = 1.5$ um, the thickness of the gold film covering it as $t_3 = 0.4$ µm, and the depth of the upper polishing depth and the depth of the lower polishing depth as

 $d_1 = 8.5$ μm and $d_2 = 3.0$ μm, respectively. The upper and
above polishing surfaces were coated with a 0.5 um gold lower polishing surfaces were coated with a 0.5 μm gold film $(t_1=0.5 \mu \text{m}, t_2=0.5 \mu \text{m})$. The spacing of adjacent air holes is $c = 6.3$ μm. Data analysis shows light can propagate independently in both cores, thus completing the detection.

We give plots of the dispersion relations of core (1) and core (2) in the X and Y directions, respectively, along with their loss spectra. As shown in Fig. [4](#page-3-1), observation of Fig. [4a](#page-3-1) reveals a clear loss peak in the Y-pol direction and the core mode intersects with the SPP mode out of the resonance wavelength, and there is no loss peak in the X-pol direction. Thus, for the fber core (1), we mainly study his Y-pol direction. Observing Fig. [4](#page-3-1)b, c, we can fnd that the core mode

Fig. 3 Electric feld distributions of the core 1: **a** Core mode in the direction of Y polarization at 800 nm; **b** core mode in the direction of X polarization at 800 nm; **c** resonance modes in the direction of Y polarization at 892 nm; **d** SPP modes in the direction of Y polarization at 890 nm; Electric feld distributions of the core 2: **e** core mode

in the direction of Y polarization at 800 nm; **f** resonance modes in the direction of X polarization at 700 nm; **g** SPP modes in the direction of Y polarization at 970 nm; **h** resonance modes in the direction of Y polarization at 970 nm. Arrows indicate polarized direction of electric felds

Fig. 4 a The dispersion relationship between core mode and SPP mode of core 1, together with the loss spectrum of X-pol and Y-pol.; **b** core 2 Dispersion relation between core mode and SPP modes in

Y-pol direction; **c** core 2 Dispersion relation between core mode and SPP modes in X-pol direction

and SPP mode in the X-pol and Y-pol directions are intersected at the resonance wavelength, and there are obvious loss peaks in both directions, so for the core (2), we mainly study his X-pol and Y-pol directions.

Results and Discussion

PML and scattering boundary conditions were introduced in the calculations to improve the accuracy of the results. The designed PCF-SPR sensor was analyzed using the control variable method and the resonance wavelength shift was measured using the wavelength modulation method, which enabled multiparameter measurements. Finally, the sensitivity of the measured parameters is calculated and discussed by data processing.

Refractive Index Sensitivity

Figure [5](#page-4-0)b shows the ftted curve between the liquid resonance wavelength and RI. The fitting equation in the figure, as well as the data, shows that the ft is good. According to the calculation, the refractive index's sensitivity is up to 20,000 nm/RIU.

Temperature Sensitivity and Magnetic Field Sensitivity

Figure [6b](#page-4-1) shows the fitted curve between resonance wavelength and temperature. Based on the ftted curve equations as well as the data, it can be seen that the ft is good. The linear sensitivity is calculated to be 5.3 nm/°C because it is needed to derive the linear sensitivity in the subsequent matrix. In addition, the increase in the refractive index leads to the red shift of the phase matching point between the SPW and the core fundamental mode, so the resonance wavelength is red-shifted.

Figures [6](#page-4-1) and [7](#page-5-0) show that the resonance wavelengths of the magnetic feld channel and the temperature channel are blue shifted when the temperature varies. This is due to the negative temperature coefficients of the MF and PDMS for both the magnetic feld channel and the temperature channel.

Fig. 5 a Variation of the loss spectrum with the refractive index of the liquid and **b** the results of the numerical ftting of the resonance wavelength as a function of the refractive index of the liquid

Fig. 6 a Variation of loss spectrum with temperature and **b** results of numerical ftting of resonant wavelength as a function of temperature

Fig. 7 a Loss spectrum of the magnetic field channel as a function of liquid temperature and **b** numerical fitting results of the resonance wavelength as a function of liquid temperature

After linear ftting, the linear sensitivity of the temperature channel was 5300 pm/°C; maximum sensitivity to temperature up to 9200 pm/°C; the sensitivity of the magnetic feld channel to temperature was 425.71 pm/°C.

Figure [8](#page-5-1) shows that the magnetic feld channel resonance wavelengths are red-shifted when the magnetic feld strength is varied between 20 and 550 Oe. According to Eq. [\(4\)](#page-2-1), it can be seen that the magnetic feld strength is positively correlated with the MF when the temperature is determined. Therefore, the resonance wavelength is red-shifted, and the linear sensitivity of the magnetic feld channel to magnetic feld variations is 116 pm/Oe with an *R*-squared of 0.99214. Moreover, the sensitivity of the temperature channel to magnetic feld variations is found to be 0 pm/°C by using Eq. [\(3](#page-2-2)).

The linear sensitivity of the temperature channel for temperature and magnetic feld changes is 5300 pm/°C and 0 p/°C, respectively. The linear sensitivity of the magnetic feld channel for temperature and magnetic feld changes is 425.71 pm/Oe and 116 pm/Oe, respectively. According to Eqs. ([9\)](#page-3-2) and ([10\)](#page-5-2), the temperature and magnetic feld sensitivity matrix is as follows:

$$
\begin{pmatrix} \Delta T \\ \Delta H \end{pmatrix} = \begin{pmatrix} -0.426 & 0.116 \\ -5.3 & 0 \end{pmatrix}^{-1} \begin{pmatrix} \Delta \lambda_1 \\ \Delta \lambda_2 \end{pmatrix} = \begin{pmatrix} 0 & -0.189 \\ 8.62 & -0.693 \end{pmatrix} \begin{pmatrix} \Delta \lambda_1 \\ \Delta \lambda_2 \end{pmatrix}
$$
\n(10)

Since few multi-parameter measurement structures are available, we compare them with some of the two-parameter structures, as shown in Table [1](#page-6-0). The table shows that the present design is better than some of the current designs

Fig. 8 a Variation of loss spectrum with external magnetic feld and **b** numerical ftting results of resonant wavelength as a function of magnetic feld

Table 1 Comparison of refractive index, temperature, and magnetic feld sensitivity with other SPR-based sensor structures

	S(T)	S(RI)	S(T)	S(RI)		S(MF)
Our	9.2 (nm $^{\circ}C^{-1}$)	Luan et al. [33] 6.18 (nm °C ⁻¹) 12,500 (nm/RIU) Weng et al. [34] 0.14 (nm °C ⁻¹) 561.43 (nm/RIU) Xiao et al. [9] 164 pm/Oe Yang et al. [35] 1.81 (nm $^{\circ}C^{-1}$) 2214.0 (nm/RIU) Akter et al. [36] 1.00 (nm $^{\circ}C^{-1}$) 20,000 (nm/RIU) Liu et al. [37] $20,000$ (nm/RIU)			Our	44 pm/Oe $116 \text{ pm}/\text{Oe}$

Fig. 9 Loss spectra of the three channels for different values of r_1 , r_2 , *c*, d_1 and d_2 . **a–c** Loss spectrum of core 1 and core 2 with different values of stomatal radius; **d–f** loss spectrum of core1 and core2 with

diferent values of stomatal spacing; **g–i** loss spectrum of core 1 and core 2 with diferent values of depths

Fig. 10 Loss spectra of temperature channel, refractive index channel and magnetic field channel for different values of t_1 , t_2 , and t_3 . (1) Loss spectra for diferent gold flm thicknesses in the temperature

channel; (2) loss spectra corresponding to diferent gold flm thicknesses for the refractive index channel; (3) loss spectra corresponding to diferent gold flm thicknesses for magnetic feld channels

of two-parameter structures in terms of temperature and refractive index. The sensitivity of the magnetic feld of the present work is also approximately equal to or better than that of other designs.

Infuence of Structural Parameters on Sensor Stability

The stability of the designed sensor has a signifcant impact on its performance. Diferent structural parameters may have different effects on the sensor performance. In this simulation, diferent radii of air holes, inter-hole distances and polishing depths are observed to determine whether the sensor is stable. Observations in Fig. [9](#page-6-1)a–i show that the resonance peaks increase with the increase of the aperture radius under the same environmental conditions. When the aperture radius increases, the fber core is squeezed horizontally, and more energy leaks into the metal interface, resulting in increased energy loss and an enhanced SPR efect.

Under the same analytical method, an increase in the air hole spacing or polishing depth squeezes the fber core to some extent, increasing the energy loss and strengthening the SPR effect. However, the resonance wavelength was almost constant, indicating that the sensors involved are relatively stable.

Efect of Gold Film Thickness on Sensing Characteristics

Since the metal flm afects the excitation of SPR, we investigated the efect of diferent polished surface gold flms and the thickness of the gold flm in the magnetic feld channel on the sensor's performance. Figure [10](#page-7-0) shows the simulation results. The fgure shows that the resonance wavelength position is red-shifted, and the energy loss is gradually reduced with the increase in the thickness of the gold flm. This is because less energy can be coupled to the SPW mode with the increase in thickness, resulting in lower losses. The refractive index of the SPW increases as the thickness of the gold flm increases. However, the refractive index of the core remains constant, so the matching point between the SPW and the core is red-shifted, and the resonance wavelength position is also red-shifted.

However, when the thickness is chosen, the level of loss and the width of the spectrum will also afect the sensor performance detection. Therefore, by observing the images of temperature and refractive index channels, it was found that the loss was too high for detection at a gold flm thickness of 40 nm. In addition, when the gold flm thickness is 60 nm, the signal-to-noise ratio is low, which may result in falsepositive responses [[37,](#page-9-7) [38\]](#page-9-8). Finally, the gold flm thickness was determined to be 50 nm for the temperature channel. Similarly, using the same analytical method, the gold flm thickness was chosen to be 50 nm for the refractive index channel and 45 nm for the magnetic feld channel because either the loss was too signifcant or the spectra were too broad for detection.

Conclusion

This study presents an SPR-PCF sensor that simultaneously measures refractive index, temperature, and ambient magnetic feld. Using dual-polished and single-channel flled magnetic fuids makes the deposition of metal flms and temperature-sensitive materials easier, thus reducing the difficulty of fabricating the sensor. The relative stability of the designed sensors also reduces their fabrication accuracy. The maximum sensitivity of the RI measurement is 20,000 nm/RIU when the RI of the fuid is 1.36 to 1.42. The sensing matrix is also given when the temperature detection range is 0° C to 50 $^{\circ}$ C, and the magnetic feld detection range is 20 to 550 Oe. Moreover, calculating the resolution of the refractive index is 4.5×10^{-6} , the resolution of temperature is 2.9×10^{-2} , and the resolution of magnetic field strength is 0.63. The sensor is highly integrated and more miniaturized, providing a new solution for sensor fabrication.

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Data Availability No datasets were generated or analysed during the current study.

Declarations

Ethics Approval Not applicable.

Consent to Participate All authors agree to participate in this investigation.

Consent for Publication All authors agree to participate in this article.

Competing Interests The authors declare no competing interests.

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