RESEARCH PAPER

Comparative performance of eight ensemble learning approaches for the development of models of slope stability prediction

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Abstract

Slope engineering is a complex nonlinear system. It is difficult to respond with a high level of precision and efficiency requirements for stability assessment using conventional theoretical analysis and numerical computation. An ensemble learning algorithm for solving highly nonlinear problems is introduced in this paper to study the stability of 444 slope cases. Different ensemble learning methods [AdaBoost, gradient boosting machine (GBM), bagging, extra trees (ET), random forest (RF), hist gradient boosting, voting and stacking] for slope stability assessment are studied and compared to make the best use of the large variety of existing statistical and ensemble learning methods collected. Six potential relevant indicators, γ , C, φ , β , H and r_u , are chosen as the prediction indicators. The tenfold CV method is used to improve the generalization ability of the classification models. By analysing the evaluation indicators AUC, accuracy, kappa value and log loss, the stacking model shows the best performance with the highest AUC (0.9452), accuracy (84.74%), kappa value (0.6910) and lowest log loss (0.3282), followed by ET, RF, GBM and bagging models. The analysis of engineering examples shows that the ensemble learning algorithm can deal with this relationship well and give accurate and reliable prediction results, which has good applicability for slope stability evaluation. Additionally, geotechnical material variables are found to be the most influential variables for slope stability prediction.

Keywords Classification · Ensemble learning · Machine learning (ML) · Repeated cross-validation · Slope stability

1 Introduction

Due to the needs of economic development and the expansion of the scope of geotechnical engineering, as an essential environment for human survival, slopes are a crucial part of engineering construction, and research on their stability is constantly developing and advancing.

Slope stability evaluation is a crucial research aspect in slope engineering. However, the slope deformation and

 \boxtimes Bei Han hanbxie@bjut.edu.cn failure process is a very complex geological process. The factors that affect the slope stability are uncertain [\[27](#page-24-0)], so it is not easy to accurately evaluate slope stability with traditional theoretical analysis [[13\]](#page-24-0) and numerical calculations (such as the finite element method [\[20](#page-24-0)], discontinuous deformation analysis [[60,](#page-25-0) [61,](#page-25-0) [70\]](#page-25-0), virtual element method [\[33](#page-24-0), [48](#page-24-0)] and phase-field [\[65–67](#page-25-0)]). Slope engineering is an uncertain, nonlinear, dynamic and open complex system. Its stability is comprehensively affected by geological and engineering factors with randomness, fuzziness, variability and other uncertain characteristics. There is a highly nonlinear relationship between slope stability and influencing factors. Therefore, the inevitable slope stability research trend is to break through traditional deterministic thoughts and fully consider the uncertainty caused by various slope factors. Slope stability analysis can be regarded as a pattern recognition task [\[59](#page-25-0)]. Based on the slope information database [\[51](#page-24-0)], some scholars use machine learning (ML) $[35, 38, 50]$ $[35, 38, 50]$ $[35, 38, 50]$ $[35, 38, 50]$ $[35, 38, 50]$ to judge slope stability. Lu et al. $[36]$ $[36]$ used an artificial neural network (ANN) [[2\]](#page-23-0) to predict the failure of

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circular slopes, which showed that the ANN has obvious advantages compared with the maximum likelihood estimation (MLE) technique. Samui [[44](#page-24-0)] studied the application of a support vector machine (SVM) to predict slope stability. Sakellariou et al. [[43\]](#page-24-0) established a series of ANNs to predict the safety factor of the slope wedge failure mechanism and circular failure mechanism and evaluate their stability. Dickson et al. [\[9](#page-24-0)] introduced three ML algorithms to analyse the control of coastal cliff landslides. Yan et al. [[57\]](#page-25-0) studied the application of the Bayes discriminant analysis method in the stability prediction of open pit slopes. Zhou et al. [\[63](#page-25-0)] introduced six supervised learning methods to predict the stability of hard rock pillars, and the performance of these algorithms was compared and analysed. Cheng and Hoang [\[8](#page-24-0)] used a novel bee colony optimized support vector classifier to evaluate the slope collapse caused by a typhoon. Lee et al. [[29\]](#page-24-0) and Lin et al. [\[32](#page-24-0)] established a slope stability prediction model using an ANN. Based on ML, Hoang et al. [[23\]](#page-24-0) used the least squares support vector classification (LS-SVC) and firefly algorithm (FA) methods to study 168 slope cases. All the above artificial intelligence models can help us better understand the slope status, but each model has advantages and disadvantages. Due to the complexity of the problem, there are still some imperfections in these methods. Different algorithms have different sensitivities to the same type of data, and the classification accuracy of the same category under different algorithms will also vary. Each classifier has its limitations. The focus of slope stability evaluation research is the ML algorithm, which constantly looks for newer and more robust ML algorithms to establish slope stability evaluation models to achieve better prediction results. Therefore, it is necessary to find intelligent algorithms with high accuracy and strong applicability. Ensemble learning trains multiple algorithms to achieve complementary advantages and obtain better slope stability prediction results than the single algorithm.

Ensemble learning forms a more comprehensive 'strong learner' through the combination of multiple models. Ensemble learning can obtain more accurate prediction results, with better generalization performance and broader applications [\[10](#page-24-0), [11\]](#page-24-0). Ensemble learning has been successfully applied to character recognition [\[12](#page-24-0)], medical diagnosis [[62\]](#page-25-0), facial recognition [[21\]](#page-24-0) and seismic wave classification [\[46](#page-24-0)]. Lin et al. [[34\]](#page-24-0) applied four supervised learning algorithms (random forest (RF), gravitational search algorithm (GSA), SVM and naive Bayesian) to slope stability evaluation. They carried out a comparative analysis to prove that the performance of RF and GSA is better than other algorithms. Based on an updated database of case histories, Zhou et al. [[64\]](#page-25-0) proposed a prediction method for slope stability analysis using the gradient boosting machine (GBM) method. Qi and Tang [\[42](#page-24-0)] used FA to adjust the superparameters and verified and discussed the feasibility of six comprehensive methods (logistic regression (LR), RF, decision trees (DT), GBM, multilayer perceptron neural network and SVM) in slope stability prediction. Qi and Tang [\[41](#page-24-0)] proposed a slope stability evaluation algorithm, adaptive boosted decision trees (ABDT), quadratic discriminant analysis (QDA), SVM, ANN, Gaussian process classification (GPC) and Knearest neighbours (KNN) as individual classifiers and a weighted majority voting method as the combined classifier. The results show that the hybrid ensemble method greatly improves slope stability prediction performance. Previous studies have shown that ensemble learning can provide a feasible tool for constructing a slope stability discrimination system, which allows the classification of slope stability. However, there is no comprehensive comparison of classifier ensemble algorithms over the prediction of slope stability. To improve the prediction accuracy of nonlinear slope behaviour and establish a simple model that can be widely promoted, it is necessary to continue exploring an ensemble algorithm that is more suitable for analysing nonlinear slope behaviour.

Because of this, the primary purpose of this paper is to compare the applicability of different classifier ensemble algorithms in slope stability analysis. To achieve this goal, we developed a research method for comparing the performance of different classifier ensemble algorithms in Scikit-learn [\[40](#page-24-0)], including bagging, RF, AdaBoost, GBM, stacking, voting and extra trees (ET) and hist gradient boosting classifier (HGB). These ensemble learning algorithms are specifically selected because they are increasingly used in engineering, but they have not been thoroughly compared with each other. In Sect. 2, the ensemble learning algorithm is briefly introduced, and Sect. 3 analyses the slope dataset. In Sect. 4, these methods are applied to classify slope stability, and the results are discussed according to performance criteria. The conclusion of this study is presented in the final section.

2 Ensemble learning methods

Ensemble learning [[10\]](#page-24-0) is a process of effective fusion to form a strong classifier based on individual learners (as shown in Fig. [1\)](#page-2-0). According to the difference of the combination methods of base learners, ensemble learning can be divided into parallel topology structure (representing algorithm is bagging), serial topology structure (representing algorithm is boosting) and hybrid topology structure (representing algorithm is stacking). In this study, we consider several common ensemble learning algorithms in Scikit-learn. All these methods are increasingly being used and have efficient implementations; some of these methods

Fig. 1 Schematic diagram of ensemble learning

have been used in slope classification [\[58](#page-25-0), [64\]](#page-25-0) with good results; the resulting model allows rapid slope stability prediction. The following is only a brief introduction to each ensemble classification algorithm. For a more indepth discussion, please refer to the relevant literature [\[23](#page-24-0), [24](#page-24-0)].

2.1 Bagging

Bagging [[4\]](#page-23-0) is one of the simplest and most efficient ensemble learning algorithms. Figure 2 shows the structure diagram of bagging. First, m training samples are extracted from the original training samples. After the T-round extraction, T training sets can be obtained, and then the T

Fig. 2 Schematic diagram of bagging

training sets are used to train each 'weak learner'. Finally, each 'weak learner' result is combined according to the average or voting method. Each time the training set is extracted, all the features can be used for training, or some features can be randomly selected. There is no dependency among the 'weak learners', and they are all connected in parallel. Bagging can not only uniformly sample datasets but also realize parallel computing. For this reason, learners based on the bagging framework have better generalization ability and higher computing speed.

2.2 Random forest

Random forest (RF) is a method based on bagging and decision trees (DTs) [[19\]](#page-24-0). Unlike the traditional decision tree, RF randomly extracts n subsamples containing k attributes from the K attributes contained in N samples and then selects an optimal attribute from n subsamples for partitioning. RF combines the final prediction results based on the performance of multiple decision trees. RF can process high-dimensional data without feature selection and has strong adaptability to the dataset.

2.3 Boosting

Boosting [\[45](#page-24-0)] trains each 'weak learner' in an iterative manner. As shown in Fig. [3](#page-3-0), 'weak learner 1' is trained on the original training set 1 and adjusts the training sample distribution according to its prediction results to obtain training set 2. Train on training set 2 to obtain 'weak learner 2'. The above process is repeated until the termination condition is satisfied, and the final prediction result is the weighted sum of the results of each base learner.

Fig. 3 Schematic diagram of boosting

Boosting is a forward distributed boosting algorithm. Each calculation step is affected by the previous step, and the weight of the miscalculated samples increases to improve the overall predictive ability of the algorithm model.

Adaptive boosting [[17\]](#page-24-0) (AdaBoost) is the most typical. AdaBoost can combine several low-precision classifiers and automatically adjust the sample weights according to the classification effect to synthesize a strong classifier with higher precision. AdaBoost is sensitive to outliers and noisy data.

2.4 Gradient boosting machine

The gradient boosting machine (GBM) [\[18](#page-24-0)] is a boosting algorithm. The GBM algorithm searches for weak classifiers along the gradient descent direction and trains an additive model to combine all weak classifiers. The loss function is used to express the fitting degree between the test set and training set. The lower the loss function is, the higher the prediction accuracy and the more reliable the result. GBM includes GBDT (gradient boosting decision tree), XGBoost (extreme gradient boosting), LightGBM (light gradient boosting machine) and CatBoost (categorical boosting).

Hist gradient boosting (HGB) [[1](#page-23-0)], or histogram-based gradient boosting, is a boosting ensemble that uses feature histograms for fast and accurate selection of best splits. Light GBM inspires its implementation. HGB is more

efficient than GBM in terms of memory consumption and processing speed.

2.5 Stacking

The stacking algorithm [\[53](#page-25-0)] has the advantages of simple structure, high performance and strong classification ability. The stacking structure diagram is shown in Fig. [4](#page-4-0). The model of the first layer is called the base model, and the model of the second layer is called the meta-model. Using the predicted values of each model in the first layer as the input characteristics of the next layer, stacking has a stronger nonlinear expression ability than a single prediction model and can further reduce the generalization error. Based on the stacking algorithm, this paper uses GBM, RF, KNN, DT, SVC, LR, ET, bagging and Gaussian naive Bayes (GaussianNB) as the primary learners. LR is the secondary learner, and 10 times fivefold cross-training is used to avoid overfitting between the primary and second training models.

Stacking is a general method for achieving higher prediction accuracy by combining high-level models with low-level models. However, stacking generalization does not consider the data distribution and is suitable for standard datasets other than unbalanced data.

Bagging, boosting and stacking algorithms improve machine learning performance by merging multiple models. Bagging reduces model variance, boosting reduces

Fig. 4 Stacking schematic diagram

model deviation and stacking improves model prediction results.

2.6 Voting

The voting ensemble (majority vote set) is a machine learning model set that combines the predictions of several other models. Voting prediction classification methods include hard voting and soft voting. The hard vote set summarizes the votes from the clear class labels of other models and predicts the class with the most votes. A soft voting set includes the sum of predicted probabilities of the class labels and predicting the class label with a greater probability addition. Regardless of the machine learning model, the voting ensemble can be used and considered a meta-model. The voting method is fast and straightforward. It only requires the prediction results of the established model on the test dataset without retraining.

2.7 Extra trees

Extra trees (ET) [\[47](#page-24-0)] and RF have a similar structure. Unlike RF, ET uses the entire dataset to train each decision tree to utilize all samples fully. In addition, when ET trains T decision trees, N input features are randomly selected to form T subdatasets. In node partitioning, the subdataset is selected at random by the partition threshold of each characteristic, and the feature with the best partition effect is selected as the optimal partition attribute according to the specified threshold. According to the theory of 'errorambiguity decomposition', the greater the difference between 'weak learners' and the higher the prediction accuracy of each 'weak learner', the better the integration effect. The size of the ET decision tree is generally larger than that of RF, but the variance in the model is minor.

3 Database and variables

3.1 Parameter analysis

When establishing the classification model, the factors affecting slope stability are selected first. The principles of feature selection are as follows: (a) the meaningful features are selected from the given feature set to train the model to reduce the dimension disaster problem; (b) the complexity of the learning process is simplified by removing some features that are not related to the subsequent learning process. At present, gravity γ , cohesion C, internal friction angle φ , slope angle β , slope height H and pore water ratio r_u have extensive use in slope stability prediction. According to the training, the results are good, and the data can easily be obtained [[58\]](#page-25-0). It should be noted that according to engineering experience, the stability of the slope is also affected by other factors, such as the structure type of rock and soil, joints and the relationship between

Fig. 5 Box plot of each variable for slope cases

the joint surface and slope angle. However, it is difficult to obtain the values of these indicators accurately. The results indicated that slope stability could be well predicted without considering these indices [[64\]](#page-25-0).

3.2 Case data and preliminary analysis

From a performance point of view, measurements and comparisons have been made for the ensemble learning algorithm, 444 engineering examples of slopes were collected directly from the literature [\[5](#page-23-0)[–7](#page-24-0), [14–16](#page-24-0), [22,](#page-24-0) [26,](#page-24-0) [30](#page-24-0), [31,](#page-24-0) [36](#page-24-0), [37](#page-24-0), [49,](#page-24-0) [51](#page-24-0), [54–56](#page-25-0), [68,](#page-25-0) [69](#page-25-0)], and all the data are from these studies without any processing. A detailed description of the data is provided in Appendix. As shown in Fig. 5, the box diagram describes all the input features used in the slope stability prediction model. From these figures, the range and average distribution of all input features can be found directly. Except for β , most variables have noncentre medians to the boxes. This indicates an asymmetric distribution of these variables. Additionally, except for φ and β , there are several outliers in all input features.

There are two types of slope stability in the dataset: stable (S, 224 cases) and unstable (F, 220 cases). The variable correlation matrix is shown in Fig. [6.](#page-6-0) There is a pairwise relationship between the correlation coefficients of the variables related to slope stability. The red lines outside the diagonal are regression lines, which reflect the degree of linear correlation between variables. The diagonal of the figure is the marginal frequency distribution of each parameter. The red lines on the diagonal represent the empirical probability density curves. The numbers in the upper panels indicate the correlation between the two variables. The red stars ('***', '**', '*;, '.', ') $\lt =$ $\gt p$ values (0, 0.001, 0.01, 0.05, 0.1, 1). As shown in Fig. [6](#page-6-0), the correlation is rather poor with most variables ($R < 0.5$). There is a significant correlation between γ and φ $(R = 0.73)$, β ($R = 0.74$), a significant correlation between β and φ ($R = 0.70$), and a moderate correlation between γ and H ($R = 0.49$). r_u is negatively correlated with γ $(R = -0.20)$ and φ $(R = -0.24)$.

Furthermore, it is evident that the dataset is widely distributed and that the distribution of the variable is nonsymmetrical. Principal component analysis (PCA) summarizes and visualizes the collected slope data and explains its variance–covariance structure. As shown in Table [1](#page-6-0), the contribution rate of PC1 is the highest, 52.26%, and the contribution rate of PC6 is the lowest, only 3.65%. PCA allows us to visualize the classification capabilities of the slope dataset on a two-dimensional plane. According to the PCA results (as shown in Fig. [7a](#page-7-0)), the components of the first and second dimensions were visualized (Fig. [7b](#page-7-0)). As shown in Fig. [7b](#page-7-0), the data distribution regions of the two types of slope states on the first two components are relatively close, with overlapping areas. In addition, some indicators with significant skewness will affect the classification results of slope stability, as shown in Fig. [1](#page-2-0). To avoid the interference of large

Fig. 6 Scatter matrix of the six variables of slope stability

Table 1 PCA model for illustration of the slope data: component matrix and scores

Principal component	Variable				Variance	Variance ratio	Cumulative ratio		
(PC)	$\gamma(kN/m^3)$	C (kPa)	φ ^{(\circ})	β ^{(\circ})	H(m)	r_{μ}		$(\%)$	$(\%)$
PC ₁	0.5098	0.3462	0.4888	0.4787	0.3498	-0.1723	3.1430	52.26	52.26
PC ₂	0.0609	0.0459	-0.0232	0.1310	0.1968	0.9684	0.9517	15.82	68.08
PC ₃	-0.1933	0.6583	-0.3151	-0.3700	0.5346	-0.0852	0.7262	12.07	80.15
PC ₄	-0.0440	0.6645	-0.0079	0.1405	-0.7258	0.0996	0.6976	11.60	91.75
PC ₅	0.1132	-0.0507	-0.7675	0.6150	0.0579	-0.1181	0.2767	4.60	96.35
PC ₆	-0.8272	0.0207	0.2685	0.4677	0.1518	-0.0367	0.2193	3.65	100

fluctuation data on the model performance, when the difference in the order of magnitude of each control factor is too large or the same control factor is discrete, it is necessary to standardize the sample data. This article uses the Quantile Transformer function for data normalization.

Ideally, for the sake of precise classification, each value of all features can only have one class label (stable or failure) in the diagram. Slope stability is classified according to different indicators as shown in Fig. [8](#page-8-0). It can be observed from this figure that, in some events, the same indicator's value corresponds to both types of slope states. The possible reason is that the data are not linearly separable and it is difficult to define boundaries of feature values.

4 Development of slope stability assessment model

4.1 Data pre-processing

To form and control the performance of the classifiers, as shown in Fig. [9,](#page-9-0) a stratified and random sampling method is used to split the dataset into training datasets (90%) and test datasets (10%). The tenfold cross-validation (CV) and grid search method are adopted to obtain optimal parameters of the ensemble learning models. In the process of tenfold CV, the training is divided into random tenfold training, nine of which are trained by the ensemble learning model, and the remaining training is used as the

(b) a biplot of the first two components

Fig. 7 Visualization of PCA results

verification set to verify the model's performance. The training and testing process is repeated 10 times, and 10 different subsets are used as testing sets. Therefore, the overall performance of the ensemble learning algorithm on

Fig. 8 Slope stability concerning each indicator

the training set is calculated by simply averaging the 10 training results.

4.2 Model performance evaluation

For slope stability classification problems, receiver operating characteristic (ROC) curves [[3\]](#page-23-0), log loss, accuracy and kappa coefficients [\[28](#page-24-0)] are the main indicators for evaluating the performance of classifiers. The ROC curve is a good comprehensive evaluation index without considering the sample distribution, making a credible performance evaluation of the algorithm results. The area under the curve (AUC) is enclosed by the ROC curve and the coordinate axis. AUC represents the probability that a positive sample is more likely to be predicted as a positive class than a negative sample to be a positive sample, which is often used to measure the classification performance of a classifier on unbalanced data. Different AUC values reflect different classification effects [\[3](#page-23-0), [25\]](#page-24-0): 0.900–1.00 represents outstanding discrimination, 0.800–0.900 represents excellent discrimination, and 0.700–0.800 represents acceptable discrimination.

Fig. 9 Ensemble learning model for predicting slope stability

Log loss is a performance metric used to evaluate the probability of members of a given class. The log loss can be given using Eq. 1.

$$
\log \log \left(\frac{1}{n} \sum_{i=1}^{n} \sum_{j=1}^{m} y_{ij} \log (p_{ij}) \right) \tag{1}
$$

where n represents the total number of samples and m is the number of types of slope stability. When sample i belongs to class j, y_{ij} is 1; otherwise, y_{ij} is 0. Furthermore, p_{ij} represents the probability of sample *i* belonging to class j. For a binary classification problem, the log loss function is as follows:

$$
-\log \log = -\sum_{i=1}^{n} (y_i \log (p_i) + (1 - y_i) \log (1 - p_i)) \qquad (2)
$$

Accuracy is defined as the percentage of the number of samples correctly classified relative to the total number of samples selected for validation, and Eq. 3 calculates the precision. The accuracy can reflect the overall classification accuracy to a certain extent but cannot directly reflect the different classes' prediction results. The kappa coefficient is a comprehensive classifier evaluation index [[63\]](#page-25-0) mainly used to reflect the proportion of error reduction compared with random classification. Equation 4 is the expression of kappa.

$$
\text{Accuracy} = \left(\frac{1}{n}\sum_{i=1}^{r} z_{ii}\right) \times 100\%
$$
\n
$$
\left(\frac{1}{n}\sum_{i=1}^{r} z_{ii}\right) \times 100\%
$$

Kappa =
$$
\left[n \sum_{i}^{r} z_{ii} - \sum_{i} (z_{i+}z_{+i}) \right] / n^2 - \sum_{i} (z_{i+}z_{+i}) \tag{4}
$$

where r represents the number of categories to be classified by the confusion matrix. z_{ii} is the value of row i and column i of the confusion matrix, the number of samples correctly classified; z_{i+} and z_{+i} represent the sums of row i and column i, respectively, of the confusion matrix.

The distribution range of the kappa coefficient is $[- 1, 1]$, where -1 represents the worst classification effect, 0 represents the classification performance of the classifier equal to the random classifier and 1 represents the best classification performance. Different kappa coefficients reflect different classification effects: 0.810–1.000 (perfect), 0.610–0.800 (substantial), 0.410–0.600 (moderate), 0.210–0.400 (poor), 0.000–0.200 (slight) and $- 1.000 - 0.000$ (total disagreement). Generally, 0.4 is taken as the threshold of the kappa coefficient [\[63](#page-25-0)].

Method	Turning parameters	Optimal value	AUC	Sensitivity	Specificity
GBM	n estimators = $[10, 50, 100, 500]$	100	0.9199	0.8421	0.9130
	learning rate = $[0.0001, 0.001, 0.01, 0.1, 1.0]$	0.1			
	subsample = $[0.5, 0.7, 1.0]$	1.0			
	$max_{\text{depth}} = [20, 33, 65]$	7			
Bagging	n_{t} trees = [10, 50, 100, 500, 1000, 5000]	100	0.9291	0.7895	0.8696
	max _samples = [0.1, 0.3, 0.5, 0.7, 0.9,1]	1			
	max_f eatures = 2,3,4,5	3			
AdaBoost	$n_{estimators} = [10, 50, 100, 500]$	500	0.9199	0.8421	0.8261
	learning rate = $[0.0001, 0.001, 0.01, 0.1, 1.0]$	1.0			
ET	$min_samples_split = [13, 35, 38, 48, 59, 60, 67, 70]$	6	0.9519	0.8947	0.9565
	$max_{\text{features}} = [13, 20, 60, 61]$	3			
	n_{t} trees = [10, 50, 100, 500, 1000, 5000]	100			
RFC	$max_samples = [0.2, 0.4, 0.6, 0.8, 1]$		0.9268	0.7894	0.8696
	$max_{\text{features}} = [13, 20, 60, 61]$	3			
	n trees = $[10, 50, 100, 500, 1000]$	100			
HGB	None	None	0.8970	0.7368	0.9130
Voting	None	None	0.9588	0.8421	0.9565
Stacking	None	None	0.9382	0.8421	0.9565

Table 2 Tuning parameters of each model for an optimal classification

4.3 Model development and parameter optimization

This paper studies the applicability of eight common ensemble learning algorithms (GBM, AdaBoost, bagging, ET, RF, HGB, voting and stacking) in slope stability classification. Most classifiers (GBM, AdaBoost, bagging, ET and RF) contain parameters that need to be adjusted. The 'gridsearchcv' function in sklearn performs a tuning parameter grid for many classification problems, which allows a single consistent environment to train each ensemble learning method and tune their related parameters. After evaluating the optimal parameters, the final slope stability prediction models are established using the entire training dataset. To optimize the critical parameters of each integrated training model and obtain the best discrimination performance, a tenfold reputation of CV is used to select the 'optimal' value of the adjustment parameter. As a binary classification problem, slope stability is a trade-off between sensitivity and specificity. AUC represents the model's ability to distinguish between positive (stable) and negative (failure) categories. Therefore, the AUC is used to evaluate the performance of the parameters in the repeated tenfold CV process. Table 2 shows the hyperparameter settings and prediction results of the ensemble learning algorithms in the current research.

5 Results and discussion

5.1 Discriminant results and performance analysis

To compare the performance of different classification algorithms, the KNN, LR, GaussianNB, MLPClassifier (MLPC) and SVM methods are also used for slope stability classification. The prediction results of the model are shown in Fig. [10.](#page-11-0) The AUC of SVM is 0.898, LR is 0.752, KNN is 0.934, GaussianNB is 0.695, MLPC is 0.839, RF is 0.967, GBM is 0.961, ET is 0.966, AdaBoost is 0.961, bagging is 0.965 and HGBC is 0.959. It is worth noting that the AUC determines the classifier's performance greatly, and 1.0 represents the ideal performance. The ROC curves of ensemble learning (RF, GBM, ET, AdaBoost, bagging and HGB) are slightly more approximated to the left and upper axes than the other models. Their AUC values were above 0.90, slightly higher than those of KNN, and significantly higher than those of SVM, LR and MLPC. It also shows that ensemble learning is more suitable for slope stability prediction, and GaussianNB has the lowest prediction performance. The AUC value of the ensemble learning model constructed by the average predicted value of SVM, LR, KNN, GaussianNB, MLPC, RF, GBM, ET, AdaBoost, bagging and HGB is 0.961. These facts convincingly demonstrate that ensemble learning has a good ability to predict slope stability.

Fig. 10 ROC curves of the thirteen classifiers on the testing set

According to the visual comparison, one can easily observe the performance of all the ensemble learning classification methods, as shown in Figs. [11](#page-12-0) and [12](#page-13-0). The boxplots in Fig. [11](#page-12-0) report the performance of eight classifiers on a repeated tenfold CV procedure with average AUC, accuracy, log loss and kappa. Since these models use the same dataset, it is meaningful to analyse the differences between the calculated results. The distinction of the upper and lower quartiles in the stacking classifier is smaller than that of the other methods, indicating that the accuracy variance is relatively low in different iterations (see Fig. [11](#page-12-0)). Figure [12](#page-13-0) shows that the average AUC of each ensemble classifier in slope stability prediction is between [0.8992–0.9452]. The stacking model has the highest AUC, with an AUC of 0.9452, followed by the GBM method $(AUC = 0.9293)$, RF method $(AUC = 0.9210)$ and ET method $(AUC = 0.9180)$. According to the consistency scale, the AUCs of all modelling techniques used in the model evaluation test set are excellent. As shown in Fig. [11](#page-12-0), the accuracy and kappa value of stacking have the closest quartile range. The quartile range of the ROC value of GBM is the closest, but there are some outliers. The average value of log loss of each ensemble classifier in slope stability prediction falls into [0.3282–0.6860]. The lowest log loss is the stacking model, and the log loss is 0.3282, followed by the RF method ($log loss = 0.3776$) and ET method ($log loss = 0.3894$). Smaller $log loss$ is better, with 0 representing a perfect log loss. AdaBoost performed relatively worse, with a log loss of 0.6860.

The average accuracy of the ensemble classifiers in slope stability prediction falls into the range of [82.07–84.74%]. Obviously, the accuracy of the stacking model is the highest (accuracy $= 84.74\%$), and then the ET (accuracy = 83.53%), bagging (accuracy = 83.07%) and GBM $(accuracy = 82.81\%)$ models rank successively. Voting achieves the lowest average accuracy (82.07%). For the eight ensemble learning techniques, the performance (in terms of average kappa) falls into the range of (0.6377–0.8474). The kappa values of all ensemble learning models are above 0.4. The stacking predictor achieves the highest kappa (0.6910), followed by ET, bagging and

Fig. 11 Boxplot distributions of the training set in terms of 'AUC', 'log loss', 'accuracy' and 'kappa' for eight ensemble methods resulting from repeated tenfold CV procedure

Fig. 12 ROC curves for the ensemble models Fig. 12 ROC curves for the ensemble models

Fig. 13 Variable importance plot generated by the GBM, ET and RF classifiers

GBM, with average kappa rates of 0.6703, 0.6590 and 0.6545, respectively.

According to the concordance scale, the kappa of the training set and test set of eight ensemble learning classification techniques in model calibration data is medium to substantial. It is clear that the kappa and accuracy of each ensemble learning classification algorithm are basically the same, but kappa is usually smaller than accuracy. The reason is that kappa can more comprehensively reflect the error information of the model, while accuracy only considers the diagonal element error in the confusion matrix and ignores the element error on the nondiagonal line.

The results show that ensemble learning models have good performance in predicting slope stability, which is feasible and reliable. We can observe the following facts. Compared with a single classifier, the stacking ensemble classifier has a relatively higher average AUC (0.9452), average accuracy (84.74%) and kappa average (0.6910) and a relatively lower average log loss (0.3282) on the testing set, indicating that its prediction performance is relatively higher, but the calculation intensity is high, and it takes the longest time to train; stacking has better generalization performance than voting. This research indicates that using a classifier ensemble, rather than searching for the ideal single classifier, may be more helpful for slope stability prediction.

5.2 Relative variable impact

Determining the sensitivity of the factors affecting slope stability is very important for evaluating slope stability and the design of support structures. A relative importance score is used in this study, and this is based on optimal ensemble learning (GBM, ET and RF) to study the sensitivity. The methods are selected according to their excellent performance on the test set. The variable importance ranking is obtained by averaging the tenfold CV feature selection results of RF, ET and GBM. Figure 13 shows the normalized score of variable importance. γ (score = 0.2309), C (score = 0.2007) and φ (score = 0.2003) are the most sensitive factors to slope stability, which indicates the importance of slope material variables. The correlation matrix of the variables is consistent with these results (Fig. [6\)](#page-6-0), the component matrix and scores, and the litera-ture results [\[52](#page-24-0)]. Therefore, the values of the material γ , C and φ in artificial slopes must be reasonably and accurately selected based on specific indoor and field tests. In treating landslides, geomaterials' cohesive force and internal friction angle should be improved [[39\]](#page-24-0). The importance scores of β and H are 0.1449 and 0.1395, respectively, indicating that geometric variables also affect slope stability. Optimizing these two variables in practical design is a feasible method for ensuring slope stability. It can also be found that the sensitivity of r_u (0.0837) is not as good as that of the first five features.

6 Conclusions

Ensemble learning algorithms (GBM, AdaBoost, bagging, ET, RF, HGB, voting and stacking) are introduced in this study to study the stability of 444 slope cases. Six potential relevant indicators, γ , C, φ , β , H and r_u , serve as indicators for prediction, and the generalization ability of the classification models is improved using the tenfold CV method. According to the analyses, the following conclusions are presented:

- 1. The ROC curves of ensemble learning algorithms are closer to the left and top axes than other algorithms. The AUC of ensemble learning models is more than 0.900, slightly higher than KNN, SVM, LR and MLPC. The AUC value of the ensemble learning model constructed by the average predicted value of SVM, LR, KNN, GaussianNB, MLPC, RF, GBM, ET, AdaBoost, bagging and HGBC is 0.961. Ensemble learning algorithms have an excellent ability to predict slope stability.
- 2. The stacking model has a higher AUC, higher accuracy and kappa value, and lower log loss. It can be used as a

Table 3 Slope stability prediction database

NO	r (kN/m ³)	C (kPa)	φ (°)	β (°)	H(m)	$r_{\rm u}$	Status	Location
$\mathbf{1}$	18.68	26.34	15	35	8.23	$\boldsymbol{0}$	Failure	Congress street, open cut slope, Chicago, USA
2	16.5	11.49	0	30	3.66	0	Failure	Brightlingsea slide, UK
3	18.84	14.36	25	20	30.5	0	Stable	Unknown
4	18.84	57.46	20	20	30.5	0	Stable	Unknown
5	28.44	29.42	35	35	100	0	Stable	Case 1: open-pit iron ore mine, India
6	28.44	39.23	38	35	100	0	Stable	Case 2: open-pit iron ore mine, India
7	20.6	16.28	26.5	30	40	0	Failure	open-pit chromite mine, Orissa, India
8	14.8	$\boldsymbol{0}$	17	20	50	0	Failure	Sarukuygi landslide, Japan
9	14	11.97	26	30	88	0	Failure	Case 1: open-pit iron ore mine, Goa, India
10	25	120	45	53	120	0	Stable	Mercoirol open-pit coal mine, France
11	26	150.05	45	50	200	0	Stable	Marquesade open-pit iron ore mine, Spain
12	18.5	25	$\boldsymbol{0}$	30	6	0	Failure	Unknown
13	18.5	12	$\boldsymbol{0}$	30	6	0	Failure	Unknown
14	22.4	10	35	30	10	0	Stable	Case 1: Highvale coal mine, Alberta, Canada
15	21.4	10	30.34	30	20	0	Stable	Case 2: Highvale coal mine, Alberta, Canada
16	22	20	36	45	50	0	Failure	Case 1: open-pit coal mine, Newcastle coalfield, Australia
17	22	0	36	45	50	0	Failure	Case 2: open-pit coal mine, Newcastle coalfield, Australia
18	12	$\boldsymbol{0}$	30	35	4	0	Stable	Unknown
19	12	$\boldsymbol{0}$	30	45	8	0	Failure	Unknown
20	12	0	30	45	4	0	Stable	Unknown
21	12	0	30	45	8	0	failure	Unknown
22	23.47	$\boldsymbol{0}$	32	37	214	0	Stable	Pima open-pit mine, Arizona, USA
23	16	$70\,$	20	40	115	0	Failure	Case 1: Wyoming, USA
24	20.41	33.52	11	16	10.67	0.35	Stable	Seven Sisters Landslide, UK
25	19.63	11.97	20	22	12.19	0.405	Failure	Case 1: The Northolt slide, UK
26	21.82	8.62	32	28	12.8	0.49	Failure	Selset Landslide, Yorkshire, UK
27	20.41	33.52	11	16	45.72	0.2	Failure	Saskatchewan dam, Canada
28	18.84	15.32	30	25	10.67	0.38	Stable	Case 2: The Northolt slide, UK
29	18.84	$\boldsymbol{0}$	20	20	7.62	0.45	Failure	Sudbury slide, UK
30	21.43	$\boldsymbol{0}$	20	20	61	0.5	Failure	Folkestone Warren slide, Kent, UK
31	19.06	11.71	28	35	21	0.11	Failure	River bank side, Alberta, Canada
32	18.84	14.36	25	20	30.5	0.45	Failure	Unknown
33	21.51	6.94	30	31	76.81	0.38	Failure	Unknown
34	14	11.97	26	30	88	0.45	Failure	Case 2: open-pit iron ore mine, Goa, India
35	18	24	30.15	45	20	0.12	Failure	Athens slope, Greece
36	23	0	20	20	100	0.3	Failure	Open-pit coal mine Allori coalfield, Italy
37	22.4	100	45	45	15	0.25	Stable	Case 1: open-pit coal mine, Alberta, Canada
38	22.4	10	35	45	10	0.4	Failure	Case 2: open-pit coal mine, Alberta, Canada
39	20	20	36	45	50	0.25	Failure	Case 3: open-pit coal mine, Newcastle coalfield, Australia
40	20	20	36	45	50	0.5	Failure	Case 4: open-pit coal mine, Newcastle coalfield, Australia
41	20	0	36	45	50	0.25	Failure	Case 5: open-pit coal mine, Newcastle coalfield, Australia
42	20	$\boldsymbol{0}$	36	45	50	0.5	Failure	Case 6: open-pit coal mine, Newcastle coalfield, Australia
43	22	0	40	33	8	0.35	Stable	Case 1: Harbour slope, Newcastle, Australia
44	24	$\boldsymbol{0}$	40	33	8	0.3	Stable	Case 2: Harbour slope, Newcastle, Australia
45	20	0	24.5	20	8	0.35	Stable	Case 3: Harbour slope, Newcastle, Australia
46	18	5	30	20	8	0.3	Stable	Case 4: Harbour slope, Newcastle, Australia
47	22	29	15	18	400	$\boldsymbol{0}$	Failure	Qing River area landslide, China
48	23	24	19.8	23	380	$\boldsymbol{0}$	Failure	Qing River area landslide, China
49	22	40	30	$30\,$	196	0	Stable	Qing River area landslide, China
50	22.54	29.4	20	24	210	0	Stable	Qing River area landslide, China
51	22	21	23	30	257	0	Failure	Qing River area landslide, China
52	23.5	10	27	26	190	0	Failure	Qing River area landslide, China
53	22.5	18	20	20	290	0	Stable	Qing River area landslide, China

Table 3 (continued)

Table 3 (continued)

Table 3 (continued)

NO	r (kN/m ³)	C (kPa)	φ (°)	β (°)	H(m)	$r_{\rm u}$	Status	Location
160	24.96	40	45	53	120	$\boldsymbol{0}$	Stable	Circular critical failure mechanism
161	18.46	4	$\boldsymbol{0}$	30	6	$\boldsymbol{0}$	Failure	Circular critical failure mechanism
162	22.38	3.35	35	30	10	0	Stable	Circular critical failure mechanism
163	21.98	6.65	36	45	50	$\boldsymbol{0}$	Failure	Circular critical failure mechanism
164	18.8	5.1	30	25	10.6	0.38	Stable	Circular critical failure mechanism
165	18.8	4.8	25	31	76.8	0.38	Failure	Circular critical failure mechanism
166	21.47	2.3	30	30	88	0.45	Failure	Circular critical failure mechanism
167	13.97	4	26	45	20	0.12	Failure	Circular critical failure mechanism
168	17.98	8	30	45	15	0.25	Failure	Circular critical failure mechanism
169	22.38	33.3	45	45	10	0.4	Stable	Circular critical failure mechanism
170	22.38	3.35	35	45	50	0.25	Failure	Circular critical failure mechanism
171	19.97	6.65	36	45	50	0.25	Failure	Circular critical failure mechanism
172	19.97	6.65	36	45	50	0.5	Failure	Circular critical failure mechanism
173	20.96	15	25	49	12	0.3	Stable	Circular critical failure mechanism
174	20.96	10	35	40	12	0.4	Stable	Circular critical failure mechanism
175	19.97	13.35	30	30	15	0.3	Stable	Circular critical failure mechanism
176	17.98	15	25	25	14	0.3	Stable	Circular critical failure mechanism
177	18.97	10	35	35	11	0.2	Stable	Circular critical failure mechanism
178	19.97	13.35	40	40	10	0.2	Stable	Circular critical failure mechanism
179	18.83	8.25	21	21	37	$0.5\,$	Stable	Circular critical failure mechanism
180	18.83	3.45	21	34	37	0.3	Failure	Circular critical failure mechanism
181	18.77	8.35	10	25	50	0.2	Failure	Circular critical failure mechanism
182	18.77	6.65	10	25	50	0.3	Failure	Circular critical failure mechanism
183	19.08	3.35	10	25	50	0.4	Failure	Circular critical failure mechanism
184	18.77	6.65	20	30	50	0.3	Failure	Circular critical failure mechanism
185	19.08	3.35	20	30	50	0.4	Failure	Circular critical failure mechanism
186	21.98	6.65	22	20	180	$\boldsymbol{0}$	Failure	Circular critical failure mechanism
187	21.98	6.65	22	20	180	0.1	Failure	Circular critical failure mechanism
188	22	10	35	45	10	0.403	Failure	Left bank accumulation body of Xiaodongjiang hydropower station, China
189	20	20	36	45	30	0.503	Failure	Longxi landslide of Longyangxia hydropower station, China
190	20	0.1	36	45	50	0.29	Failure	Chana landslide of Longyangxia hydropower station, China
191	20	0.1	36	45	50	0.503	Failure	Canal slope of Baoji gorge with Wei River diversion project, China
192	22	0	40	33	8	0.393	Stable	Yellowstone landslide in the Three Gorges of the Yangtze River, China
193	24	0	40	33	8	0.303	Stable	Baiyian landslide in the Three Gorges reservoir area, China
194	20	$\boldsymbol{0}$	24.5	20	8	0.35	Stable	Baihuanping landslide in the Three Gorges reservoir area, China
195	18	$\boldsymbol{0}$	30	33	8	0.303	Stable	Gaojiazui landslide in the Three Gorges reservoir area, China
196	27	43	35	43	420	0.29	Failure	Songshan ancient landslide at Lechangxia hydropower station, China
197	27	50	40	42	407	0.29	Stable	Back channel landslide in the Three Gorges reservoir area, China
198	27	35	35	42	359	0.29	Stable	Jipazi landslide in the Three Gorges reservoir area, China
199	27	37.5	35	37.8	320	0.29	Stable	Jiuxianping Landslide in the Three Gorges reservoir area, China
200	27	32	33	42.6	301	0.29	Failure	Heishe landslide, China
201	27	32	33	42.2	239	0.29	Stable	Liujiawuchang landslide in the Three Gorges reservoir area, China
202	27.3	14	31	41	110	0.29	Stable	Majiaba landslide in the Three Gorges Reservoir Area, China
203	27.3	31.5	29.703	41	135	0.293	Stable	Sandengzi landslide in the Three Gorges Reservoir Area, China
204	27.3	16.2	28	50	90.5	0.29	Stable	Yaqianwan landslide in the Three Gorges Reservoir Area, China
205	27.3	36	$\mathbf{1}$	50	92	0.29	Stable	No.3 landslide of Sanbanxi hydropower station, China
206	27.3	10	39	41	511	0.29	Stable	Shijiapo landslide, China
207	27.3	10	39	40	470	0.29	Stable	Tanggudong landslide, China
208	25	46	35	47	443	0.29	Stable	Tianbao landslide, China
209	25	46	35	44	435	0.29	Stable	Shipingtai landslide of Xiaoxi hydropower station, China
210	25	46	35	46	432	0.29	Stable	Dongyemiao landslide, China
211	26	150	45	30	230	0.29	Stable	Hongtupo landslide, China
212	18.5	25	$\boldsymbol{0}$	30	6.003	0.29	Failure	Lianziya landslide in the Three Gorges reservoir area, China

Table 3 (continued)

NO	r (kN/m ³)	C (kPa)	φ (°)	β (°)	H(m)	$r_{\rm u}$	Status	Location
213	18.5	12	$\boldsymbol{0}$	30	6.003	0.29	Failure	No. 6 landslide of Jishixia hydropower station, China
214	22	10	35	30	10	0.29	Stable	No.7 landslide of Tianshengqiao second cascade hydropower station, China
215	21	10	30.343	30	30	0.29	Stable	Kualiangzi landslide, China
216	22	10	36	45	50	0.29	Failure	No.1 landslide of Jishixia hydropower station, China
217	22	20	36	45	30	0.29	Failure	Daxi landslide, China
218	12	0.03	30	35	4	0.29	Failure	Right Bank landslide of Zihong reservoir, China
219	12	$\boldsymbol{0}$	30	45	8	0.29	Failure	Zhongyangcun landslide, China
220	12	$\boldsymbol{0}$	30	35	4	0.29	Stable	Zhaojiatang landslide, China
221	31.3	68	37	49	200.5	0.29	Failure	Yangdagou landslide of Xunyang hydropower station, China
222	20	30	36	45	50	0.29	Failure	Sujiaping Landslide, China
223	19.6	21.8	29.5	37.8	40.3	0.25	Stable	Maidipo Landslide, China
224	23.1	25.2	29.2	36.5	61.9	0.4	Stable	Maoping Landslide, China
225	23.8	31	38.7	47.5	23.5	0.31	Stable	Shaling Landslide, China
226	22.3	20.1	31	40.2	88	0.19	Stable	Niugunhan Landslide, China
227	23.5	25	20	49.1	115	0.41	Stable	Xieliupo Landslide, China
228	23	20	20.3	46.2	40.3	0.25	Stable	Zhaojiatang Landslide, China
229	21.5	15	29	41.5	123.6	0.36	Stable	Touzhaigou Landslide, China
230	23.4	15	38.5	30.3	45.2	0.28	Failure	Shenzhen reservoir diversion tunnel landslide, China
231	19.6	17.8	29.2	46.8	201.2	0.37	Stable	Taipingyi hydropower station diversion tunnel landslide, China
232	22.1	45.8	49.5	45.8	49.5	0.21	Stable	Bawangshan Landslide, China
233	18.82	25	14.6	20.32	50	0.4	Failure	Jiangxi Qiyi Reservoir, China
234	20	20	36	45	50	0	Failure	Unknown
235	27	40	35	47.1	292	$\boldsymbol{0}$	Failure	Unknown
236	25	46	35	50	284	0	Stable	Unknown
237	31.3	68	37	46	366	$\boldsymbol{0}$	Failure	Unknown
238	25	46	36	44.5	299	0	Stable	Unknown
239	27.3	10	39	40	480	0	Stable	Unknown
240	25	46	35	46	393	0	Stable	Unknown
241	25	48	40	49	330	0	Stable	Unknown
242	31.3	68.6	37	47	305	0	Failure	Unknown
243	25	55	36	45.5	299	$\boldsymbol{0}$	Stable	Unknown
244	31.3	68	37	47	213	$\boldsymbol{0}$	Failure	Unknown
245	26.49	150	33	45	73	0.15	Stable	Three Gorges hydropower project, China
246	26.7	150	33	50	130	0.25	Stable	Three Gorges hydropower project, China
247	26.89	150	33	52	120	0.25	Stable	Three Gorges hydropower project, China
248	26.57	300	38.7	45.3	80	0.15	Failure	Three Gorges hydropower project, China
249	26.78	300	38.7	54	155	0.25	Failure	Three Gorges hydropower project, China
250	26.81	200	35	58	138	0.25	Stable	Three Gorges hydropower project, China
251	26.43	50	26.6	40	92.2	0.15	Stable	Three Gorges hydropower project, China
252	26.69	50	26.6	50	170	0.25	Stable	Three Gorges hydropower project, China
253	26.81	60	28.8	59	108	0.25	Stable	Three Gorges hydropower project, China
254	27.8	27.8	27	41	236	0.1	Stable	Dingjiahe phosphorus mine, China
255	27.1	22	18.6	25.6	100	0.19	Failure	Guilin-Liuzhou highway, China
256	21.2	$\boldsymbol{0}$	35	23.75	150	0.25	Failure	Xiaolangdi reservoir, China
257	21.2	$\boldsymbol{0}$	35	23.75	150	0.25	Failure	Xiaolangdi reservoir, China
258	21.2	$\boldsymbol{0}$	35	23.75	150	0.25	Stable	Xiaolangdi reservoir, China
259	21.2	$\boldsymbol{0}$	35	23.75	150	0.25	Stable	Xiaolangdi reservoir, China
260	22.3	$\boldsymbol{0}$	40	26.5	78	0.25	Stable	Xiaolangdi reservoir, China
261	18.6	$\boldsymbol{0}$	32	26.5	46	0.25	Stable	Jingzhumiao reservoir, China
262	18.6	$\boldsymbol{0}$	32	21.8	46	0.25	Stable	Jingzhumiao reservoir, China
263	18.8	9.8	21	19.29	39	0.25	Failure	Yuecheng reservoir, China
264	21.2	$\boldsymbol{0}$	35	18.43	73	0.25	Stable	Yuecheng reservoir, China
265	17.2	10	24.25	17.07	38	$0.4\,$	Stable	Gushan reservoir, China

Table 3 (continued)

Table 3 (continued)

Table 3 (continued)

NO	r (kN/m ³)	C (kPa)	φ (°)	β (°)	H(m)	$r_{\rm u}$	Status	Location
372	17.3	39	30	50	26	0.2	Stable	$09 + 530$
373	17.3	37.9	30	45	29	0.37	Stable	$11 + 950$
374	17.5	38.5	29	50	33	0.2	Stable	$12 + 870$
375	17.5	39.2	29.7	55	31	$\boldsymbol{0}$	Stable	$13 + 780$
376	17.8	39.8	31.3	45	32	0.34	Stable	$15 + 530$
377	17.3	39	30	48	30	0.03	Stable	$15 + 770$
378	18.3	57.2	38.6	38	31	0.64	Stable	$18 + 460$
379	17.4	5	43.5	58	29	0.05	Failure	$19 + 900$
380	17.8	14	44.2	65	31	0.07	Failure	$19 + 970$
381	17.4	0	43.7	60	26	0.4	Failure	$20 + 140$
382	19.8	57.5	41.3	62	23	0.19	Stable	$24 + 170$
383	20.5	6.5	12.5	42	70	$\boldsymbol{0}$	Failure	Yuan-Mo Highway
384	21.4	7.1	16.7	44	70	$\mathbf{1}$	Failure	Yuan-Mo Highway
385	21.5	9.5	11.5	40	75	$\boldsymbol{0}$	Failure	Yuan-Mo Highway
386	20.6	6.7	9.4	45	30	$\boldsymbol{0}$	Failure	Yuan-Mo Highway
387	20.9	9.7	18.5	39	38	$\mathbf{1}$	Failure	Yuan-Mo Highway
388	21.4	9.4	21.8	30	106	$\mathbf{1}$	Failure	Yuan-Mo Highway
389	19.9	6.8	19.4	30	80	$\mathbf{1}$	Failure	Yuan-Mo Highway
390	20.2	14.9	18.5	40	70	$\mathbf{1}$	Failure	Yuan-Mo Highway
391	19	9	15.2	45	27	$\boldsymbol{0}$	Failure	Yuan-Mo Highway
392	19.7	16.4	21.4	30	55	$\mathbf{1}$	Failure	Yuan-Mo Highway
393	21.2	7.8	22.4	45	25	$\mathbf{1}$	Failure	Yuan-Mo Highway
394	19.9	7.4	15.6	44	30	$\mathbf{1}$	Failure	Yuan-Mo Highway
395	19.9	7.1	21.2	30	55	$\boldsymbol{0}$	Failure	Yuan-Mo Highway
396	22.2	10.7	25.2	35	45	$\mathbf{1}$	Failure	Yuan-Mo Highway
397	21.8	7.2	17.8	40	34	$\mathbf{1}$	Failure	Yuan-Mo Highway
398	21.8	7.2	17.8	42	41	$\mathbf{1}$	Failure	Yuan-Mo Highway
399	21.96	34.77	14.15	28	60	$\boldsymbol{0}$	Stable	Yuan-Mo Highway
400	21.96	34.77	14.15	24	115	$\boldsymbol{0}$	Stable	Yuan-Mo Highway
401	22.93	32.33	19.73	30	50	$\mathbf{1}$	Stable	Yuan-Mo Highway
402	22.15	19.47	13.29	28	110	$\mathbf{1}$	Stable	Yuan-Mo Highway
403	23.4	20	9	36.5	50	$\boldsymbol{0}$	Stable	Yuan-Mo Highway
404	21.8	18.05	9.72	30	40	$\boldsymbol{0}$	Failure	Yuan-Mo Highway
405	23.98	32.77	17.28	40	100	$\boldsymbol{0}$	Failure	Yuan-Mo Highway
406	20.57	24.8	15.53	40	50	$\mathbf{1}$	Stable	Yuan-Mo Highway
407	21.2	24.88	17.29	44	52	$\boldsymbol{0}$	Failure	Yuan-Mo Highway
408	22.15	5	19	45	40	1	Failure	Yuan-Mo Highway
409	21.8	18.05	9.72	35	40	$\boldsymbol{0}$	Failure	Yuan-Mo Highway
410	23.75	36.78	22.63	42	43	$\mathbf{1}$	Failure	Yuan-Mo Highway
411	20.98	23.59	$20\,$	45	65	$\boldsymbol{0}$	Failure	Yuan-Mo Highway
412	22.6	24.06	14.04	26	190	$\mathbf{1}$	Stable	Yuan-Mo Highway
413	22.29	27.54	10.1	40	$70\,$	$\boldsymbol{0}$	Stable	Yuan-Mo Highway
414	22.1	24.67	16.2	40	70	$\mathbf{1}$	Stable	Yuan-Mo Highway
415	20.25	32.4	11.99	45	36	$\mathbf{1}$	Failure	Yuan-Mo Highway
416	20.8	15.57	8.74	29.7	35	$\mathbf{1}$	Failure	Yuan-Mo Highway
417	21.17	15.44	16	33	$32\,$	$\mathbf{1}$	Failure	Yuan-Mo Highway
418	22.94	33.77	23.29	27	170	$\mathbf 1$	Stable	Yuan-Mo Highway
419	22.95	46.49	25.11	30	42	$\mathbf 1$	Stable	Yuan-Mo Highway
420	21.92 21.42	19.4	15.5	35	80 30	$\mathbf 1$	Failure Stable	Yuan-Mo Highway
421 422	20.8	28.9 40.25	16.2 19.39	40 45	123	$\mathbf{1}$	Failure	Yuan-Mo Highway
423	20.1	34.61	24.69	$22\,$	94	$\mathbf{1}$ $\boldsymbol{0}$	Stable	Yuan-Mo Highway Yuan-Mo Highway
424	19.19	19.69	17.68	34	43	$\mathbf{1}$	Failure	
								Yuan-Mo Highway

Table 3 (continued)

valuable tool for predicting slope stability, especially in cases that very easily fail and classes with very low stability followed by ET, RF, GBM and bagging models. However, the stacking model has a large number of calculations and long training time, so it is necessary to combine the super learner function in practical applications to improve the computational efficiency.

- 3. The importance scores of 0.2309, 0.2007 and 0.2003 obtained by the prediction variables more influence slope stability, of which are geotechnical material variables (γ , C and φ).
- 4. The relationship between slope stability and influencing factors is a high-dimensional complex nonlinear relationship, which is challenging to address by traditional modelling methods. The analysis of engineering examples shows that the ensemble learning algorithm can deal with this relationship well and achieve accurate and reliable prediction results, which has good applicability for slope stability evaluation. For future work, the introduction of samples and parameters that play an essential role can be added to develop an ensemble learning algorithm and improve its generalization and reliability, such as rainfall, earthquakes, human activities and other external or trigger factors.

Appendix

See Table [3](#page-15-0).

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