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Constructal optimization of a vertical insulating wall based on a complex objective combining heat flow and strength

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For a vertical insulating wall, a product function of heat flow and strength with power weight is introduced as the complex optimization objective to compromise between insulating performance and mechanical performance. Under the global constraints of fixed external dimensions and safety requirements, the constructal optimization of the wall is carried out by taking the complex function maximization as the objective. It is shown that the maximum of the complex-objective function and its corresponding optimal internal structure design under a certain environmental condition can be obtained by allowing the internal structure of the wall to vary (evolve) freely. The validity, effectivity and applicability of the complex function are proved by the results and the power weight parameter in the range from 0.4 to 4 can compromise between the requirements of insulating and strength simultaneously and preferably. The constructal optimization with coequal attention to heat flow and strength and the corresponding results are discussed in detail. The optimal structure design and the corresponding performance analyses under various environmental conditions of application are presented. When the change of environment is greater and the total Rayleigh number is bigger, the insulating wall with large number of cavities should be employed. When the total Rayleigh number is small, the better performance can be obtained by reasonably employing the insulating wall with small number of cavities. The complex function has better self-adaptability, and the results in the recent literature are special cases of this paper.

constructal theory, insulating wall, multidiscipline, generalized thermodynamic optimization

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1 Introduction

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Since constructal theory was put forward by Bejan in 1996 [1], it has quickly become a continually developing hot spot of research [2–10]. Its research subjects involve many fields such as engineering [3,7,8], sociology [9], economics [11,12], material science [13], geophysics [14], biology [15], physics [16], etc. It is called constructal optimization that employs constructal theory to guide engineering design, i.e. to search the optimal internal structure, external shape and time rhythm of one thing by taking performance maximizaAnd the researches, which combine entransy dissipation extremum principle [18–54] and finite time thermodynamics $[55-67]$ with constructal theory $[1-17,68-95]$, are the new directions of this field. Recently, the research of constructal optimization mainly

tion as an objective with given global constraints [2–8,17].

focuses on various single-objective optimization problems, including time minimization [1,68], profit rate maximization [11], cost minimization [11,12], maximum temperature difference minimization [69–74], heat transfer rate maximization [75], fluid flow resistance minimization [76], heat flux maximization [77,78], path length minimization [79], exergy loss minimization [80], electrical resistance minimization [81], power maximization [82], entransy dissipation

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rate minimization [33,34,36,38,46,49,51–54], etc. The research of multi-objective optimization includes the optimization of convective heat transfer by taking fluid flow resistance minimization and thermal resistance minimization into account simultaneously [83,84] and various tree-shaped heat exchangers [85–87], the optimization of hot water pipe network by taking pumping power minimization and heat loss minimization into account simultaneously [88], the optimization of solid-gas chemical reactor by taking high density of chemical reaction and low pumping power into account simultaneously [89,90], etc. Especially, Lorente and Bejan [91] studied the constructal optimization of an insulating wall by combining heat transfer and strength, and exploited a new direction called multidisciplinary constructal optimization. Gosselin et al. [92] further studied the constructal optimization of a beam under thermal attack by combining heat transfer and strength. Gosselin and Silva [93] studied the nano-scale fluid flow problem by combing heat transfer and power dissipation. Gosselin and Bejan [94] optimized an electromagnet with high conductive material inserted by taking maximum temperature difference minimization as the objective with the fixed magnetic induction. Wei et al. [34,46,95] considered that the power dissipation of electromagnet increases with the increase of working temperature and that the mechanical strength of the solenoid decreases with the increase of the structure temperature, and optimized electromagnets by taking entransy dissipation rate minimization as the objective. Two different complex-objective functions characterizing the magnetic intensity and heat transfer performance of electromagnet synthetically were built. One was based on magnetic induction and maximum temperature difference and the other was based on magnetic induction and entransy dissipation rate. And the constructal optimization of compositive performance combining heat transfer and magnetic effect was conducted and compared by releasing the constraint of the fixed magnetic induction.

The precondition of engineering optimization is to choose a suitable objective function for different application purposes and situations. One may obtain different results, even widely divergent ones, when a different objective function is employed. In practical engineering, some multidisciplinary and multi-objective requirements are involved when an object pursues both its optimal performance and single-objective optimization which always attends to one thing and loses another. Ref. [91] analyzed the competitive relationship between insulating performance (overall thermal resistance) and mechanical performance (strength) of a special internal structure of an insulating wall, and optimized the internal structure by taking the overall thermal resistance as the optimization objective with the prescribed strength serving as an equation constraint. The corresponding optimal internal structures were presented. Its essential was single-objective optimization, and the mechanical performance was not optimized simultaneously in the process of the insulating performance optimization. For giving attention to insulating performance and mechanic performance simultaneously and perfectly, this paper introduces a product function of heat flow and strength with power weight as a complex performance index of a vertical insulating wall, and the constructal optimization of the insulating wall is conducted by taking the new index maximization as the objective, and the optimal internal structures which meet practical engineering requirements are obtained, i.e. the geometric structures with the maximum complex function are obtained by allowing the internal structure of insulating wall to vary (evolve) freely with some given global constraints.

2 Model

Insulating walls, such as energy-saving wall of architecture and refractory wall for high temperature have been used widely in engineering. Arranging cavities with air in an insulating wall is a classical and general measure for enhancing insulating effect. This measure can not only enlarge the thermal resistance of wall to reduce heat transfer rate (e.g. reducing the energy consumptions of heating or cooling system), but also to reduce the mass of solid materials and decrease the weight of wall, consequently the compositive benefits of reducing energy consumption and protecting environment are achieved. The insulating wall has been popularized emphatically because it accords with the sustainable ideal more suitably compared with complete solid wall. Consider the model of the vertical insulating wall shown in Figure 1 [91]. The height, width and thickness $(H \times W \times L)$ are fixed, *n* vertical air-filled cavities with equal thickness L_a slab the solid material into $n+1$ plies with equal thickness *L*s equidistantly. For characterizing the composite degree of the wall, the cavity volume fraction is defined as

$$
\Phi = nL_{\rm a}/L. \tag{1}
$$

And the solid material volume fraction becomes $1 - \Phi = (n+1)L_{\rm s}/L$.

The wall material is isotropy, and heat flows in one dimension which is perpendicular to the wall. The overall temperature difference Δ*T* between the two outboard planes of the wall is fixed. Because the thermal conductivity difference between general solid materials and air is very large (e.g. the ratio of the thermal conductivity of brick to that of air is $\lambda_s / \lambda_a \approx 20 >>1$ [91]), one has

$$
\Delta T \approx n \Delta T_{\rm a},\tag{2}
$$

where ΔT_a is the temperature difference between the two outboard planes of a cavity.

The practical A-A cross section of the insulating wall is shown in Figure 1(b), and there are transversal ribs, which

Figure 1 Insulating wall [91].

occupy considerably less material and space between plies. The main role of ribs is to connect the slabs into a whole. For the sake of simplification, the effects of transversal ribs on both insulating performance and mechanic performance of the wall are neglected in various calculation herein, and the staggered arrangement pattern of ribs is also simplified into serial arrangement pattern as shown in Figure 1(c).

3 Heat transfer and strength analysis

3.1 The overall heat transfer coefficient

The overall thermal resistance of insulating wall is the sum of the resistances of air and solid layers. Considering the effect of natural convection in air layers, the overall thermal resistance formula is

$$
R = \frac{nL_{\rm a}}{\lambda_{\rm a}HWNu} + \frac{(n+1)L_{\rm s}}{\lambda_{\rm s}HW},\tag{3}
$$

where *Nu* number expresses the relative heat transfer augmentation effect due to natural convection in a air space, i.e.

$$
Nu = \frac{q_{\text{actual}}}{q_{\text{conduction}}}.\tag{4}
$$

Based on comprehensive analysis and comparison, a cri-

teria correlation, $Nu = 0.364 \frac{L_a}{H} Ra_{H,\Delta T_a}^{1/4} (Nu \ge 2)$ [96,97], which has more extensive adaptability was chosen in ref. [91], and it was changed to adapt pure conduction case by employing the method presented in ref. [98], i.e.

$$
Nu = \left[1 + \left(0.364 \frac{L_{\rm a}}{H} Ra_{H,\Delta T_{\rm a}}^{1/4}\right)^m\right]^{1/m},\tag{5}
$$

where the dimensionless Rayleigh number $Ra_{H, \Delta T_a}$ = $g\beta H^3 \Delta T_a$ /(av), g is gravitational acceleration, β is coefficient of volumetric thermal expansion, α is thermal diffusivity, *v* is kinematic viscosity, and the parameter *m* is 3 [91].

The thermal resistance across a completely solid wall is $[L/(\lambda_k H W)],$ and the dimensionless overall resistance formula can be built by using it as reference scale,

$$
\tilde{R} = \frac{R}{L / (\lambda_s H W)}
$$

= $\frac{\lambda_s}{\lambda_a} \Phi [1 + (0.364 n^{-5/4} \Phi R a^*)^m]^{-1/m} + 1 - \Phi,$ (6)

where the global parameter Rayleigh number $Ra^* =$ $\frac{L}{H} Ra_{H,\Delta T}^{1/4}$, which characterizes the intensity of natural convection in cavity and reflects the different environmental

condition.

According to the correlation of heat transfer coefficient and thermal resistance, the overall heat transfer coefficient of the insulating wall including area information of heat transfer is the reciprocal $1/\tilde{R}$ of its thermal resistance, and the overall heat transfer coefficient of completely solid wall with the same dimensions is one. Therefore, the overall heat transfer coefficient difference between insulating wall and completely solid wall is $(1 - 1/\tilde{R})$, and the heat transfer rate reduced, which results from comparing the case of using insulating wall with that of using completely solid wall under the same temperature difference, is

$$
\tilde{Q} \sim (1 - 1/\tilde{R}) = f_1(n, \Phi, Ra^*).
$$
 (7)

 \tilde{Q} is the reduced heat loss or cooling load, and one has $\tilde{O} = (1 - 1/\tilde{R})$ when the temperature difference is the unit. Therefore, the overall heat transfer coefficient difference $(1 - 1/\tilde{R})$ essentially reflects the income of using insulating wall, and it can be employed to characterize the insulating performance of the wall. The larger $(1 - 1/\tilde{R})$ is, the less the heat transfer rate of insulating wall compared with that of completely solid wall under the same temperature difference is; the higher the income of using insulating wall is, the better the insulating performance is.

3.2 Strength

The mechanical strength is used as the mechanics index of the wall, i.e. its resistance to bend and buckle in the plane of Figure 1. It is controlled by the area moment of inertia of the horizontal wall cross section

$$
I_n = \int_{-L/2}^{L/2} x^2 W dx.
$$
 (8)

When the insulating wall is composed of solid materials completely, the mechanical strength of the wall approaches its maximum $I_0 = L^3 W/12$, and the dimensionless mechanical strength formula is built by using it as reference scale [91]

$$
\tilde{I}_n = \frac{I_n}{L^3 W / 12} = f_2(n, \Phi).
$$
 (9)

The dimensionless mechanical strength formulas of the wall with different cavity number are as follows:

$$
\tilde{I}_1 = 1 - \Phi^3, \quad \tilde{I}_2 = 1 - \frac{1}{3} \Phi - \frac{1}{3} \Phi^2 - \frac{1}{3} \Phi^3,
$$
\n
$$
\tilde{I}_3 = 1 - \frac{1}{2} \Phi - \frac{1}{3} \Phi^2 - \frac{1}{6} \Phi^3, \quad \tilde{I}_4 = 1 - \frac{3}{5} \Phi - \frac{3}{10} \Phi^2 - \frac{1}{10} \Phi^3,
$$
\n
$$
\tilde{I}_5 = 1 - \frac{2}{3} \Phi - \frac{4}{15} \Phi^2 - \frac{1}{15} \Phi^3, \quad \tilde{I}_6 = 1 - \frac{5}{7} \Phi - \frac{5}{21} \Phi^2 - \frac{1}{21} \Phi^3, \dots
$$
\n(10)

The requirement of optimal design for mechanical performance is that the larger the mechanical strength is, the better its performance is.

3.3 The complex function of product of heat flow and strength with power weight

The compositive goal of optimal design of insulating wall is to get a good insulating performance (which means $(1 - 1/\tilde{R})$ is as large as possible) as well as a good mechanical strength (which means *I* is as large as possible). But from eqs. (6) , (7) , (9) and (10) , there are competitions between the requirements of internal structure design (volume fraction Φ and cavity numbers *n*) for insulating performance and mechanical performance. As the followings, when Φ is fixed, the mechanical strength of the insulating wall is maximum when all the solid materials are arranged on both outboards of the insulating wall (i.e. *n*=1), and its mechanical performance is the optimum. However, at the same time, the cavity volume is the maximum. Large cavity can cause the development of natural convection, so that $(1 - 1/\tilde{R})$ decreases evidently and the insulating performance worsens. If the number *n* of cavities increases, though insulating performance improves, mechanical performance worsens. When *n* is fixed, the smaller Φ is, the better the mechanical performance is. But the relation between the insulating performance and the cavity volume fraction is nonmonotonic, and the insulating performance is affected by Ra^* . When Φ decreases, the insulating performance may improve or worsen.

The objectives competition between multidisciplines such as insulating and strength provides an opportunity to utilize constructal theory, i.e., getting a reasonable structure which gives attention to some requirements of every aspect by balancing several kinds of competition under the given global constraints.

In the multi-disciplinary and multi-objective optimization

problems, single-objective optimization always attends to one thing and loses another. To meet the requirements of various objectives, one of the methods used most commonly is to integrate incommensurate or incompatible multiple objective functions into one objective function. These methods include weighted sum method, ideal point method, cost-effectiveness analysis method, goal arrangement method and primary goal method, etc. [99]. For the optimization of heat engine, Yan [100] built an objective function $(\eta^{\lambda}P)$ of a product of efficiency and power with power weight. In order to characterize the compositive performance of an insulating wall combining insulating and strength, this paper introduces a complex function of a product of heat flow and strength with power weight, i.e.

$$
F = (1 - 1/\tilde{R})\tilde{I}_n^{\gamma},\tag{11}
$$

where γ is power weight parameter and its value can range from 0 to ∞ in theory.

Power weight γ reflects the attention degree given to insulating performance and mechanical performance of the insulating wall. And the larger γ is, the much more emphasis on strength is; the smaller γ is, the much more emphasis on insulating is. Constructal design is conducted by taking eq. (11) maximization as the objective in this paper, and the more reasonable insulating structure which gives attention to insulating and strength is obtained by allowing the internal structure of insulating wall to vary freely according to the model shown in Figure 1. When $\gamma = 0$, eq. (11) degenerates to an objective function only for insulating performance; when $\gamma \rightarrow \infty$, eq. (11) degenerates to an objective function only for mechanical performance; when $\gamma = 1$, eq. (11) is an objective function paying coequal attention to insulating and strength. In engineering design, sometimes the insulating performance needs to be given prominence, and sometimes the mechanical performance needs to be given prominence. Therefore, the value of γ can be chosen according to different requirements of practical application.

Ref. [91] studied the constructal optimization of an insulating wall combining heat transfer and strength, and exploited a new direction called multi-disciplinary constructal optimization. But its essential was single-objective optimization, and that method has some limitations. That is, ref. [48] is the optimization study taking the overall thermal resistance (eq. (6)) maximization as the objective with the constraint of a fixed strength (eq. (9)). Therefore, its essential is a multi-disciplinary optimization with one single-objective in which one objective served as an equation constraint and the other served as the optimization objective, and the mechanical performance was not optimized simultaneously when the insulating performance optimization was carried out. The results obtained were only localized in the constructal design of thermal resistance maximization with the fixed strength. The heat transfer rate reduced, which results from comparing the case of using insulating wall with the case of using completely solid wall, increases with the increase of the overall heat transfer coefficient difference between insulating wall and completely solid wall. Therefore, from the viewpoint of actual gains from using insulating wall, it can reflect more actual effectivity by employing $(1 - 1/\tilde{R})$ of the insulating wall to characterize the insulating performance in this paper than by employing \tilde{R} to characterize that in ref. [91]. More importantly, the multi-objective complex function introduced in this paper supplies a precondition for optimizing multi-disciplinary indexes simultaneously with releasing an equation constraint of one objective function, and this method avoids those limitations of single-objective optimization in ref. [91]. Complex function (eq. (11)) synthesizes the two indexes of insulating and strength essentially. The optimization employing this complex function can take the two requirements of insulating and strength into account simultaneously, and power weight γ endows flexibility and applicability to the complex function.

4 Optimization analysis

Safety is the fundamental requirement in every engineering design, so the strength of insulating wall must meet a lower limitation. $I_n \geq 0.5$ is employed in the optimization process herein. In the following text, the effect of power weight γ on the constructal optimization of the insulating wall will be analyzed and the constructal optimization giving coequal attention to insulating and strength will be studied. All the results obtained belong to the effective solution set of this optimization problem.

4.1 Effect of γ **on constructal optimization**

4.1.1 Effects of γ *on F*max−*Ra** *characteristic and the corresponding* $(1 - 1/\tilde{R})$ *and* \tilde{I}_n

Figure 2 shows the effect of power weight γ on F_{max} – Ra^*

Figure 2 Effect of γ on $F_{\text{max}} - Ra^*$ characteristic.

characteristic. As shown in the figure, the curves of F_{max} −*Ra*^{*} decrease with the increase of γ as a whole. For any γ , with the increase of Ra^* , F_{max} remains smooth with a small segment, then decreases quickly, and finally decreases slowly. With the increase of γ , the length of segment which decreases quickly extends and the length of segment which decreases slowly shortens.

Figures 3 and 4 show $(1 - 1/\tilde{R}) - Ra^*$ characteristic and *I*−*Ra*^{*} characteristic obtained with the method of this paper (solid line) and the method in ref. [91] (dashed line), respectively. From the solid lines shown in Figure 3, the curves of $(1 - 1/\tilde{R}) - Ra^*$ decrease with the increase of γ and this accords with the purpose of building the complex objective function combining heat flow and strength by taking exponent γ as a weight, and also proves the rationality of the complex function and the feasibility of the method herein. With the increase of Ra^* , each $(1 - 1/\tilde{R})$ curve keeps smooth with a small segment, then exhibits some staged decreasing segments. The reason that causes the staged phenomenon is that the numbers of cavities in insu-

Figure 3 Effect of γ on $(1 - 1/\tilde{R}) - Ra^*$ characteristic when *F* is at maximum. 1, γ =0.1; 2, γ =0.4; 3, γ =0.7; 4, γ =1; 5, γ =4; 6, γ =7; 7, *I*=0.7; 8, *I*=0.8; 9, *I*=0.9; 10, *I*=0.95.

Figure 4 Effect of γ on *I*−*Ra*^{*} characteristic when *F* is at maximum.

lating wall are discrete integers, not continuous real numbers, therefore its correlative function is discrete. The larger γ is, the larger the upward jump between two adjoining segments is, but the smaller the number of decreasing segments is. The larger Ra^* is, the lower the descending rate of each decreasing segment is. Comparing Figure 4 with Figure 3, one can find that *I*−*Ra** characteristics are reversed roughly to $(1 - 1/\tilde{R}) - Ra^*$ characteristics when *F* is at maximum, but the relation between $(1 - 1/\tilde{R})$ and *I* is not the absolutely reciprocal relation. The curve of *I*−*Ra** increases with the increase of γ . With the increase of Ra^* , each *I*−*Ra** curve remains smooth with a small segment, then exhibits some staged increasing segments. The larger γ is, the larger the downward jump between the two adjoining segments is, but the smaller the number of increasing segments is. The larger Ra^* is, the lower the increasing rate of each increasing segment is.

Synthesizing the analyses of Figures 2–4, one can draw a conclusion that the smaller γ is, the larger the range of application environment in which the function value is higher when the complex function maximization is taken as the objective. If γ is too small, though $(1 - 1/\tilde{R})$ is higher in the larger range of application environment and insulating performance of the wall is good, the corresponding *In* decreases too quickly (e.g. *In* corresponding to $\not=0.1$ decreases more largely than that corresponding to γ =0.4), and mechanical performance of the wall is too bad. If γ is too large, though I_n is higher in the larger range of application environment and mechanical performance of the wall is good, the corresponding $(1 - 1/\tilde{R})$ decreases more largely (e.g. $(1 - 1/\tilde{R})$ corresponding to $\not\equiv 4$ decreases more largely than that corresponding to $\not\equiv$ 1). Specially, in the range of high Ra^* , the insulating performance of the wall is too bad. Moreover, the increase of I_n corresponding to $\not=7$ is not obvious compared with that corresponding to $\not=4$. Therefore, γ ranging from 0.4 to 4 can give better attention to the requirements of insulating performance and mechanical performance. This also further approves the rationality and validity of the complex function eq. (11).

4.1.2 Effect of γ *on the best performance and corresponding structure when Ra** *is fixed*

Figure 5 shows the effect of γ on *F*max−Φ characteristic with $Ra^* = 20$ and 30. As shown in the figure, for any γ and Ra^* , with the increase of Φ , F_{max} increases in the beginning and then decreases. However, the larger γ is, the quicker the increase and decrease are, and the smaller the range of peak value with larger F_{max} is. It is shown that, for special environment, when γ is smaller, the higher value of objective function can be attained in the wider range of Φ ; however, when γ is larger, the range of Φ in which the objective function value is higher is reduced, and this indicates that the

corresponding precision demand upon structure design is more strict. Comparing the solid lines with the dotted lines in the figure, one can find that, when γ is fixed and Ra^* is smaller, F_{max} varies more gently with the increase of Φ , but the value of F_{max} is bigger.

Figures 6 and 7 show the Φ_{opt} −*n* and n_{opt} − Φ characteristics corresponding to the performance curves shown in Figure 5. As shown in Figure 6, when $\gamma \leq 1$ and for any Ra^* , with the increase of n , Φ_{opt} increases in the beginning and then decreases slowly; the smaller γ is, the bigger the increasing amplitude is, but all of the decreasing amplitude are small. When $\gamma > 1$, for any Ra^* , Φ_{opt} decreases with the increase of *n* monotonously. When *n* is small, Φ_{opt} corresponding to Ra^* =20 is bigger than that corresponding to Ra^* =30; the two Φ_{opt} tend to be the same with the increase of *n*, and when γ is larger, the two Φ_{opt} at the smaller *n* tend to be the same.

As shown in Figure 7, when γ is fixed, the range of n_{opt} with $Ra^* = 30$ is wider than that corresponding to $Ra^* = 20$. When γ <4, for any γ and Ra^* , with the increase of Φ , n_{opt} increases in the beginning and then decreases slowly. When

Figure 5 Effect of γ on $F_{\text{max}} - \Phi$ characteristic.

Figure 6 Effect of γ on ^Φopt−*n* characteristic.

Figure 7 Effect of γ on n_{opt} −Φ characteristic.

 $\gamma \geq 4$, $n_{opt} = 1$. For any Ra^* , the range of n_{opt} is reduced with the increase of γ . When Ra^* is fixed, the bigger γ is, the smaller the range of n_{opt} is. When Ra^* is bigger, the range of n_{opt} is reduced more slowly.

4.2 Optimization analysis when $\gamma = 1$

4.2.1 Comparative analysis between fixing n and releasing n

Figure 8 shows three-dimensional characteristic of *F*−Φ −*Ra** with *n*=3. As shown in *F*−Φ characteristic in the

Figure 8 Three-dimensional characteristic of *F*−Φ−*Ra** with *n*=3.

figure, for any Ra^* , with the increase of Φ , *F* increases in the beginning and then decreases slowly, and there exist the sole F_{max} and Φ_{opt} . Both Φ_{opt} and F_{max} decrease with the increase of *Ra*^{*}. $F_{opt}=0.24$ and $F_{max}=0.7041$ at $Ra^*=0$; Φ_{opt} =0.215 and F_{max} =0.6938 at Ra^* =30; F_{opt} =0.18 and *F*max=0.6544 at *Ra** =60. As shown in each *F*−*Ra** characteristic in the figure, when Φ <0.486, *F* holds the same roughly with the increase of Ra^* ; when $0.486 \le \Phi \le 0.639$, *F* decreases little with the increase of Ra^* . When Φ <0.11, the effect of Ra^* on *F* is not larger than 2.25%; when $Ra^* < 20$, the effect of Φ on *F* is not larger than 3.51%.

Based on the work shown in Figure 8, releasing the constraint of *n*, the three-dimensional characteristics of *F*−Φ−*Ra** with different *n* are calculated and analyzed. The three-dimensional characteristic of $F_{\text{max}} - \phi - Ra^*$ is shown in Figure 9. Comparing the rules shown in Figure 9 with those shown in Figure 8, one can find that, the bigger *F* can be attained by giving much more evolutional freedom degree of structure to the insulating wall, i.e. the bigger *F* can be attained by adding the freedom degree of cavity number *n*. Corresponding to different Ra^* , with the increase of Φ , F_{max} increases quickly in the beginning and then decreases slowly, and there also exists a sole maximum, i.e. Φ still has an optimization opportunity (Φ_{opt}) to approach a bigger *F*. Φ_{opt} and F_{max} both decrease with the increase of Ra^* . Φ_{opt} =0.365 and F_{max} =0.8315 at Ra^* =0; Φ_{opt} =0.215 and $F_{\text{max}} = 0.6941$ at $Ra^* = 30$; F_{max} increases by 18.09% and

Figure 9 Three-dimensional characteristic of $F_{\text{max}} - \phi - Ra^*$.

0.04%, respectively, compared with the results shown in Figure 8. Therefore the smaller Ra^* is, the more notable effect of releasing the constraint of *n* to increase *F* is. Comparing the F_{max} $-\phi$ characteristics corresponding to different Ra^* with each other, one can find that the maximum of F_{max} is reduced obviously with the increase of Ra^* in the beginning, and F_{max} gradually becomes smooth when $Ra^* > 16$. When Φ <0.15, F_{max} corresponding to different Ra^* keep unchanged roughly with the increase of Ra^* ; when $0.15 \le \Phi < 0.748$, with the increase of Ra^* , F_{max} corresponding to different Ra^* are reduced in the beginning, and then become gentle quickly; when $0.748 \le \Phi \le 0.793$, F_{max} corresponding to different Ra^* decrease with the increase of Ra^* , and the bigger Φ is, the larger the decreasing amplitude of F_{max} is. When $Ra^* > 30$ and $\Phi > 0.69$, F_{max} of various insulating walls are reduced sharply because the thermal resistance decreases obviously.

4.2.2 Comparative analysis between fixing Φ *and releasing* ^Φ

Figure 10 shows the three-dimensional characteristic of $F-n-Ra^*$ with Φ =0.13. As shown in the figure, $F-n$ characteristics are obviously different from *F*−Φ characteristics, and *F*−*n* characteristics corresponding to different *Ra** have different monotonicity. When *Ra** <15, *F* decreases with the increase of *n* and gradually becomes smooth; when $15 ≤ Ra^* ≤ 60$, with the increase of *n*, *F* increases in the beginning and then become gentle. These rules show that there are n_{opt} for different Ra^* with the fixed Φ , and n_{opt} increases with the increase of *Ra** . As shown in the figure, the *F*−*Ra** characteristics are different according to different *n*. When $n \leq 3$, *F* decreases with the increase of Ra^* , and the smaller n is, the larger the decreasing amplitude of F is; when $n>3$, F holds the same roughly with the increase of *Ra** .

Synthesizing the analyses of Figures 8 and 10, one can draw a conclusion that the different design requirements

Figure 10 Three-dimensional characteristic of $F - n - Ra^*$ with $\Phi = 0.13$.

(fixing *n* or Φ) have different effects on the complex function of $F_{\gamma=1}$. But whatever design requirement is employed, there is the optimal structure design (Φ_{opt} or n_{opt}). Therefore, the method presented herein is feasible, i.e. the structure paying coequal attention to insulating and strength can be obtained by allowing the internal structure of the wall to vary (evolve) freely, and the optimal structure may be different when the application condition $(Ra^*$ value) is different.

Based on the work of Figure 10, releasing the Φ constraint, the three-dimensional characteristics of *F*−*n*−*Ra** with different Φ are calculated and analyzed, and the three-dimensional characteristic of *F*max−Φ−*Ra** is obtained by comparison, as shown in Figure 11. Comparing Figure 10 with Figure 11, one can see that a larger value of *F* can be obtained by adding the evolutionary Φ degree of freedom for the internal structure of insulating wall. However, corresponding to different *n* and Ra^* , the effect of releasing the ^Φ constraint to improve *F* is different. The smaller *n* and *Ra** are, the more obvious the effect is. Therefore, the internal structure of the insulating wall with a smaller number of cavities has a more obvious effect on its performance. As shown in Figures 10 and 11, corresponding to different *Ra** , the characteristics of $F_{\text{max}}-n$ have different monotonicity; when $Ra^* \leq 16$, F_{max} decreases with the increase of *n*; when $16 < Ra^* \le 60$, with the increase of *n*, F_{max} increases quickly in the beginning, and then decreases slowly; however, when $n \ge 5$, F_{max} approaches to its stability, and the values of F_{max} are close to each other in this case. From F_{max} *-Ra*^{*} characteristic, one can see that when *n*<5, F_{max} decreases monotonously with the increase of *Ra** , and the smaller *n* is, the larger the decreasing amplitude of F_{max} is. When $n \ge 5$, F_{max} holds the same roughly with the increase of *Ra** . It indicates that the performance of the insulating wall with a smaller number of cavities is greatly affected by application environment; while the performance of the insulating wall with a larger number of cavities is

Figure 11 Three-dimensional characteristic of $F_{\text{max}}-n-Ra^*$.

little affected by application environment and its performance is more stable.

Synthesizing the analyses of Figures 9 and 11, one can draw a conclusion that the internal structure with better compositive performance combining insulating and strength can be obtained by releasing constraints of the internal structure of the insulating wall $(n \text{ and } \Phi)$ and allowing it to vary (evolve) freely along the direction of the complex function combining heat flow and strength maximization.

4.2.3 Analysis of optimal structure with double free variables n and ^Φ

Figures 12 and 13 show the three-dimensional characteristics of n_{opt} − Φ − Ra^* and Φ_{opt} − n − Ra^* $0 \leq R a^* \leq 60$, n_{opt} is located between 1 and 5; when $Ra^* \leq 16$ or $\Phi > 0.687$, n_{opt} is 1. As shown in the figure, for the fixed Φ , n_{opt} increases with the increase of Ra^* in a step way; and n_{opt} always reaches to a new higher step (i.e. adding a cavity) in a middle region of Φ . From $n_{\text{opt}}-\Phi$ characteristic, one can find that when $Ra^* > 16$, with the increase of Φ , n_{opt} always increases in the beginning, and then decreases to its initial value; the larger *Ra** is, the larger the increasing amplitude and decreasing amplitude of n_{opt} are. From ^Φopt−*Ra** characteristic shown in Figure 13, one can see that for the different n , Φ_{opt} roughly decreases with the increase of Ra^* ; and the smaller *n* is, the larger the decreasing amplitude of Φ_{opt} is; when $n \ge 5$, the decreasing amplitude of Φ_{opt} is small and Φ_{opt} is robust. From Φ_{opt} −*n* characteristic shown in Figure 13, one can see that when $Ra^* \le 17$ and $n \le 5$, Φ_{opt} decreases monotonously with the increase of *n*; when $Ra^* > 17$ and $n \le 5$, Φ_{opt} increases monotonously with the increase of *n*; when $n \le 5$, Φ_{opt} gradually approaches to its stability no matter what *Ra** is.

Synthesizing the analyses of Figures 11–13, one can find that the performance of insulating wall with a larger number of cavities is little affected by Ra^* , and its adaptability is better and the optimal internal structure is robust. Especially,

Figure 12 Three-dimensional characteristic of $n_{opt} - \phi - Ra^*$.

Figure 13 Three-dimensional characteristic of Φ_{opt} −*n*−*Ra*^{*}.

it has better performance for a higher value of *Ra** . Therefore, when the change of the application environment is obvious and *Ra** is high, it is suggested to use the insulating wall with a larger number of cavities. When Ra^* is small, the performance of insulating wall with a smaller number of cavities is better. However, its disadvantage is that its performance is affected by Ra^* more greatly and its adaptability is weak, and the differences of the optimal structures according to different Ra^* are also obvious. Therefore, when using the insulating wall with a smaller number of cavities, one should choose a reasonable structure of the insulating wall according to special application environment with a region of *Ra** to display the performance advantage of the insulating wall in a certain region of *Ra** . Therefore, in the practical engineering design or choosing insulating wall, one should synthetically take various factors such as design requirements and application environment into account.

4.3 Comparative analysis compared with the results of ref. [91]

From eqs. (6), (7), (9) and (10), both the strength \tilde{I}_n of the

insulating wall and the thermal resistance \tilde{R} of the insulating wall are the functions of n and Φ . The mechanics constraint is introduced by giving the equation constraint of the prescribed strength in ref. [91], and the internal structure of the insulating wall is optimized by taking \tilde{R} maximization as the objective. Comparing the solid lines (results of this paper) and the dashed lines (resulting from the method in ref. [91]) shown in Figures 3 and 4, one can find that when the value of $(1 - 1/\tilde{R})$ in the solid lines are higher than those in the dashed lines shown in Figure 3, then the values of *I* in the corresponding solid line are lower than those in the dashed line shown in Figure 4. For example, when $\gamma = 1$, comparing $(1 - 1/\tilde{R})$ obtained by the method of this paper with that obtained by the method in ref. [91] for *I*=0.9, with the increase of Ra^* , $(1-1/\tilde{R})$ goes through a process of low-high-low-high, and the corresponding *I* goes through a process of high-low-high–low. It illustrates that complex objective introduced in this paper has a well self-adaptability, that is, it can meet the lowest strength requirement in the practical engineering design. The complex objective can satisfy the two requirements of insulating and strength automatically and coordinately, and the maximum of complex objective can be obtained. However, the strength is fixed in ref. [91], and its essential is the optimal design for pursuing the optimal insulating ability meeting the fixed mechanical strength, and the objective is single in itself rather than compositive. The results obtained are only localized in the constructal design of thermal resistance maximization with the fixed strength (carrying the insulating performance optimization without optimizing the mechanical performance), and they are the optimization points for the given environment conditions and strength.

The paper synthetically considers the competitions between the insulating performance and mechanical performance and builds the complex function F (eq. (11)) of the product of heat flow and strength with power weight as the performance index for balancing the above competition. One can choose a reasonable power weight value γ in the engineering design, and the complex objective has a well applicability. About optimization method, this paper releases the equation constraint of strength employed in ref. [91] and consequently avoids the limitation of that optimization method. However, from the view of practical engineering design, an inequation constraint of strength $(I_n \geq 0.5)$ is given out and it is more reasonable. The result obtained in this paper is the constructal design of optimal region corresponding to the simultaneous optimization of both insulating performance and mechanical performance based on the requirement of engineering safety and in a wider calculation region (i.e. satisfying the requirement of the inequation constraint of strength), and it has a wider application region. By using the optimization method herein, one can obtain the optimal region design satisfying a lower

limit of strength, and the results obtained in ref. [91] are special cases of this paper.

5 Conclusion

In practical engineering, some multi-disciplinary and multi-objective requirements are involved when an object pursues its optimal performance and single-objective optimization always attends to one thing and loses another. For a vertical insulating wall, considering the competitive relationship between insulating performance and mechanical performance, this paper introduces a product function of heat flow and strength with power weight to serve as the complex performance index for balancing the competition of insulating and strength of the wall. Under the global constraints of fixed external dimensions and safety requirement, the constructal optimization of the wall is conducted by taking the complex function maximization as the objective, and the numerical results prove the rationality of the complex function and the feasibility of the optimization method herein.

The study about the effect of power weight on constructal optimization shows that, the smaller the power weight is, the larger the region of application environment with a higher objective value is. But if the power weight is too small or too large, the optimization cannot compromise insulating and strength preferably, and the range from 0.4 to 4 is appropriate for power weight. For special environment, when power weight is smaller, the higher objective function value can be attained in the wider range of cavity volume fraction; however, when power weight is larger, the range of cavity volume fraction in which the objective function value is higher is reduced, and this indicates that the corresponding precision demand of structure design is more strict.

When heat flow and strength are of coequality (power weight is one), the performance of insulating wall with a larger number of cavities is little affected by total Rayleigh number, and its adaptability is better and the optimal internal structure is robust. When total Rayleigh number is bigger, its performance is better. Therefore, when the change of environment is great and the total Rayleigh number is big, the insulating wall with large number of cavities should be employed. When the total Rayleigh number is small, the insulating wall with a smaller number of cavities is better. But the optimal structures according to different total Rayleigh number and the corresponding performance are affected by total Rayleigh number more greatly and its adaptability is weak. In practical engineering, one should choose a reasonable structure of the insulating wall according to special application environment with a region of total Rayleigh number to display its performance advantage in a certain region of total Rayleigh number.

Ref. [91] is the single-objective optimization study of

thermal resistance maximization with the constraint of strength equation, and the results obtained are the optimal points. This paper is multi-objective optimization study giving attention to the two requirements of insulating and strength, and the results obtained are the optimal regions and can provide some guidelines for multi-objective optimization in engineering design. The results in ref. [91] are special cases of this paper. This paper only studies the effect of power weight on constructal optimization of insulating wall, and the further study of the quantitative (qualitative) correlation between power weight parameter and the requirements of practical engineering will be conducted in the future.

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