RESEARCH ARTICLE

Flood discharge prediction using improved ANFIS model combined with hybrid particle swarm optimisation and slime mould algorithm

Sandeep Samantaray¹ · Pratik Sahoo2 · Abinash Sahoo2 · Deba P. Satapathy2

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Abstract

Due to the disastrous socio-economic impacts of food hazards and estimated rise of its occurrences in the near future, there has been an increase in the importance of food prediction worldwide. Artifcial intelligence (AI) models have contributed signifcantly by giving cost-efective solutions for simulating physical processes of food events and improving accuracy in prediction over the last few decades. This paper presents a novel conjoint model to forecast river flood discharge (Q_{FD}) considering data from four gauging stations of River Brahmani, Odisha India. The developed hybridised metaheuristic algorithm, i.e. ANFIS-PSOSMA, improves exploration capability of Slime mould algorithm (SMA) by integrating it with particle swarm optimisation (PSO). Performance of novel hybrid model is assessed by utilising quantitative statistical measures like the coefficient of correlation (R^2) , Nash–Sutcliffe Model Efficiency (N_{SE}), root mean square error (RMSE), and mean absolute error (MAE). The proposed hybrid ANFIS model using optimisation algorithm provided the best performance values with N_{SE} of 0.9952, R^2 of 0.9946, RMSE of 0.0485, and MAE of 0.0265 during training and N_{SE} of 0.9736, R^2 of 0.9731, RMSE of 8.4236, and MAE of 4.3197 during testing at Jenapur gauging station, indicating the prospective of utilising the developed models in forecasting food discharge. The present study's importance lies in integrating several input parameters, and AI algorithms have been utilised for developing food prediction model. In addition, the attained results indicated that combining the optimisation algorithms with ANFIS enhanced its performance in modelling monthly flood discharge time series.

Keywords Flood discharge · Artifcial intelligence · ANFIS-PSOSMA · River Brahmani

Introduction

The pressure of population growth, industrialisation, upgraded living standards, and urbanisation has led to increased water requirements and consumption (Zhou et al. [2002\)](#page-27-0). Accurate and reliable food forecasts are vital, predominantly in food-afected regions. Unlike any other natural disaster, floods affect countless lives, property, infrastructure, and cause limitless destruction. An accurate food forecast with proper lead time can provide forward-thoughtful attentiveness to an impending flood event early enough to minimise food damage signifcantly. It is not possible to have complete protection from fooding; however, countless lives and vast amounts of money can be avoided by timely and precise predictions of the crests, magnitude, and duration of the food. The control of foods is essential to halting climate change. In order to adjust to a changing environment and climate, food management innovation is vital. Inefective flood management has serious repercussions. Each year,

fooding causes up to tens of billions of dollars worth of economic damage and hundreds of fatalities worldwide. Because of machine learning (ML) algorithm's strong authority in unravelling non-linear relationships, they have been broadly employed for solving environmental and hydrological problems (Fan et al. [2019](#page-25-0); Xiao et al. [2019;](#page-27-1) Yaseen et al. [2019](#page-27-2); Deo et al. [2016](#page-25-1)). Data-driven models (DDM) work on the basis of functional connections between input (e.g. independent) and target (e.g. dependent) variables (Liang et al. [2019](#page-26-0); Kim et al. [2019](#page-26-1)). In hydrological studies, DDM, using ML algorithms, has been extensively utilised and has revealed better prediction performances with lesser constraints compared to physical-based models (Mosavi et al. [2018](#page-26-2); Zia et al. [2015;](#page-27-3) Samantaray et al. [2022f\)](#page-26-3). Classic DDM for hydrological investigations comprises artifcial neural networks (ANN; McCulloch and Pitts [1943](#page-26-4)), support vector machines (SVM; Vapnik [1995](#page-27-4)), random forest (RF; Breiman [2001](#page-25-2)), and ANFIS (Jang [1993](#page-25-3)). ANN has been utilised in several hydrological processes, including river engineering, water resources management, and hydrology. In terms of accuracy and application, several ANN-based studies have demonstrated an effective method for flow forecast, precipitation prediction, and water quality prediction (Fan et al. [2019](#page-25-0); Huang et al. [2019](#page-25-4); Samantaray et al. [2022a;](#page-26-5) Ghose and Samantaray [2019](#page-25-5); Samantaray and Ghose [2019](#page-26-6); Samantaray et al. [2022b\)](#page-26-7). Several studies have reported application of ANN-based food prediction models using diferent meteorological parameters of the study region (Mandal et al. [2005](#page-26-8); Han et al. [2007](#page-25-6); Dawson et al. [2006](#page-25-7); Do Hoai et al. [2011](#page-25-8); Elsafi [2014](#page-25-9); Mitra et al. [2016](#page-26-9); Tsakiri et al. [2018](#page-27-5); Sahoo et al. [2022a](#page-26-10), [b\)](#page-26-11). Singh [\(2012](#page-27-6)) applied wavelet-based ANN model for predicting food events and compared it with existing statistical models. They found that WANN model predicted better flood values than statistical models. In another study, Dhunny et al. [\(2020\)](#page-25-10) studied the use of ANN model for flood prediction using 20,000 climatic datasets (minimum temperature, maximum temperature, rainfall, and humidity) that were gathered over the course of 2 years for Mauritius. They found ANN to be a good predictor for the specifed study region.

Although the ANN method is widely used, it may not produce extremely accurate results, which leads to instability. The inability of ANNs to accurately forecast changes in hydrological variables led to the development of ANFIS that can operate with non-linear relationships. Data pre-processing techniques are required to boost ANN performance. ANFIS is said to be a good amalgamation of ANN and FL. Even though ANN and ANFIS have a lot in common in their modelling stages, reports recommend that ANFIS usually has superior performance than ANN (Sahoo et al. [2022b](#page-26-11); Samantaray et al. [2022c](#page-26-12); Akrami et al. [2013](#page-25-11); El-Shafe et al. [2011\)](#page-25-12); hence, it appears to be a reasonable indication for focusing on ANFIS. It is known to be one of the most benefcial and has a satisfactory performance in modelling many hydrological and environmental phenomena (Kheradpisheh et al. [2015](#page-26-13); Mekanik et al. [2016](#page-26-14)).

Nayak et al. ([2005](#page-26-15)) explored the potential of ANFIS for forecasting food fow of Kolar river basin, India. In another study, Ullah and Choudhury ([2010](#page-27-7)) explored the usability of ANFIS in food discharge forecasting of Barak river basin. Both the studies concluded that ANFIS provided better results compared to the ANN model. Nguyen and Chua [\(2012](#page-26-16)) implemented ANFIS for daily water level forecasting of Lower Mekong River using water levels of 1 to 5 days ahead. Ghalkhani et al. [\(2013\)](#page-25-13) used ANN and ANFIS, for food routing based on diferent lag times in Madarsoo river basin, Iran. Applied models generated good results at the study location. Anusree and Varghese [\(2016](#page-25-14)) applied multiple nonlinear regression (MNLR), ANN, and ANFIS to predict daily fow with diferent input combinations at exit of Karuvannur river basin. The outcomes indicated that ANFIS predicted river fow more precisely than MNLR and ANN models. Tabbussum and Dar [\(2021\)](#page-27-8) applied ANN, ANFIS, and fuzzy logic techniques based on diferent training algorithms to forecast Q_{FD} inflowing Srinagar city at Padshahi Bagh station of Jhelum River. They found that ANFIS model utilising hybrid training algorithm generated best prediction outcomes.

While classic AI techniques are utilised to model diferent phenomena, they generally sufer from certain shortcomings, such as utilising local search techniques, getting trapped in local optima, high computing, and over-ftting (Kisi et al. [2018](#page-26-17); Peyghami and Khanduzi [2013\)](#page-26-18). ANN and ANFIS are two well-known methods utilised for stimulating diferent hydrological phenomena. Often, they produce satisfactory performance in modelling the events mentioned above; however, they sometimes face problems estimating flood discharge. It may be because the non-linear and non-stationary condition of flow makes its modelling difficult. Hence, it appears to be a good indication to develop modelling quality by diminishing the complications of classical models. But, even though ANFIS has several benefts, its training approaches undergo a few faws resulting in the incompetence of the models in some circumstances (Kisi et al. [2017](#page-26-19)). Finding an appropriate structure and its constraints in a neuro-fuzzy (NF) system is essential and also, the system's success depends on its training algorithm's accuracy and efficiency.

Several researches have been published on the successful use of genetic algorithm (GA) in combination with ANN and ANFIS models in predicting river fow discharge (Mukerji et al. [2009](#page-26-20); Chau et al. [2005;](#page-25-15) Wu and Chau [2006](#page-27-9)). In a similar manner, hybrid ANFIS model with diferent evolutionary algorithms (Firefy Algorithm (FA); ant colony optimisation (ACO); Whale Optimisation algorithm (WOA); Gray Wolf Optimisation (GWO); Salp Swarm algorithm (SSA); Harris Hawks Optimization (HHO); Butterfy Optimization

Algorithm (BOA); Black Widow Optimization Algorithm (BWOA)) have been successfully applied for modelling several hydrological variables like precipitation, temperature, solar radiation, evapotranspiration, runoff, drought, water table depth, and humidity (Tao et al. [2018;](#page-27-10) Yaseen et al. [2018](#page-27-11); Dehghani et al. [2019](#page-25-16); Seif et al. [2020;](#page-27-12) Penghui et al. [2020;](#page-26-21) Samantaray et al. [2022d,](#page-26-22) [e;](#page-26-23) Panahi et al. [2021](#page-26-24); Emami and Emami [2021;](#page-25-17) Mirboluki et al. [2022,](#page-26-25) Fadaee et al. [2022\)](#page-25-18). Azad et al. [\(2018](#page-25-19)) utilised ACO, GA, and PSO, to train ANFIS for estimating the river fow of Zayandehrood river basin, Iran. Among all considered models, ANFIS-PSO performed best and classical ANFIS performed worst. Yaseen et al. ([2019](#page-27-2)) investigated the potential of GA, PSO, and diferential evolution (DE) in tuning membership function (MF) of ANFIS for improving accuracy of streamfow forecasting in River Pahang, Peninsular Malaysia. Analysis of performance indicated that PSO improved the profciency of ANFIS more than DE and GA algorithms. Inyang et al. ([2020](#page-25-20)) applied k-means, self-organising maps (SOM), ANFIS-GA, and ANFIS-PSO models for predicting flood severity levels. ANFIS-PSO model with lowest error established to be superior compared to other applied models. Arya Azar et al. ([2021](#page-25-21)) evaluated ANFIS, least-squares support vector machine (LS-SVM), and ANFIS-HHO models for predicting evaporation utilising data related to Doroudzan dam located in central Iran. They reported that ANFIS-HHO model gave superior performance to LS-SVR and ANFIS models. Mohammadi et al. ([2021](#page-26-26)) investigated performance of single Non-Recorded Catchment Areas (NRECA), Hydrologiska Byråns Vattenbalansavdelning (HBV), SVM, ANFIS, GMDH (group method of data handling) models, and hybridised NRECA and HBV with ANFIS, SVM, and GMDH models in streamfow prediction considering precipitation and streamfow data of four stations in Indonesia. The results revealed that hybrid models performed better than single models, with hybrid GMDH model performing best among all. Haznedar and Kilinc ([2022\)](#page-25-22) developed a hybrid ANFIS-GA model to predict river flow from data collected from Zamanti and Körkün stations of River Seyhan, Turkey, and compared its results with traditional ANN and LSTM models. Their outcomes showed that projected ANFIS-GA technique was successful in predicting river fow more accurately. Malik et al. [\(2022](#page-26-27)) applied three machine learning models namely MLP, SVM, and ANFIS and their optimisation with PSO, SMA, and spotted hyena optimiser (SHO) algorithms to predict soil temperature at diferent depths for a semi-arid zone of Punjab, India. They found that SMA algorithm best optimised the ML models and can be applied for other regions across India.

The developed technique, called ANFIS-PSOSMA, works by constructing a group of solutions, each of which refers to arrangement from ANFIS model's parameters. The training set, representing 70% of total samples, is used to evaluate

each solution. The solution with the smallest ftness value is the best, which is found by calculating the RMSE. After that, PSO's operators are utilised for enhancing the existing population. This procedure is trailed by utilising SMA's operators to improve solutions till they attain the fnal condition. The preeminent arrangement of ANFIS, i.e. the preeminent solution, is assessed utilising a testing set representing 30% of the entire samples. To the best of the authors' understanding, this is the frst application of PSOSMA to improve prediction capability of ANFIS and implemented in a real dataset (i.e. flood discharge dataset of Brahmani River). Study fow chart with methodology is given in Fig. [1.](#page-3-0)

Study area

River Bramhani is the second longest river in Odisha and a major seasonal river in eastern India. The Brahmani is a signifcant seasonal river in the eastern Indian state of Odisha (Fig. [2\)](#page-4-0). The Sankh and South Koel rivers meet to form the Brahmani, which flows through the Sundargarh, Deogarh, Angul, Dhenkanal, Cuttack, Jajapur, and Kendrapara districts. The basin is located on the right by Mahanadi basin and on the left by Baitarani basin. It forms a sizable delta with the river Baitarani before draining into the Bay of Bengal at Dhamra. It is situated amid 20°30′10′′ and 23°36′42′′N latitudes and 83°52′55′′ and 87°00′38′′E longitudes. About 80% of the water of river Bramhani is used in irrigation. In the summer, the temperature may get as high as 47° C, while in the winter, it can get as low as 4 °C. In the state of Odisha, the basin is the primary source of water supplies for several towns and businesses as well as for agriculture. Having a total 39,313.50 km² catchment area, it spreads over Chhattisgarh (3.5% of basin area), Jharkhand (39.2% of basin area), and Odisha (57.3% of basin area) states. Flood is a common aspect in Baitarani basin.

Materials and methods

ANN

ANNs have been increasingly utilised in hydrological modelling, like streamflow modelling, rainfall-runoff modelling, and reservoir modelling (Othman and Naseri [2011](#page-26-28)). ANNs are parallelly dispersed processing systems having tendency of storing experiential information (Latt and Wittenberg [2014](#page-26-29)). ANN descend connotation from historical dataset, as opposed to physical aspects of a watershed (Cai et al. [2009](#page-25-23)). MLP is a broadly utilised ANN comprising of neurons called perceptron (Mukerji et al. [2009](#page-26-20)). In mathematical terms, MLP can be expressed by Eq. (1) (1) :

Fig. 1 Study flow chart with methodology

$$
y = f(\sum_{z=1}^{n} m_{z} x_{z} + b)s
$$
 (1)

where *y*—output; x_z —input vector ($z = 1 ... n$); f —transfer function; *m_z*—weight vector; *b*—bias. Basic architecture of ANN is shown in Fig. [3.](#page-5-0)

ANFIS

A NF system combines ideas of ANNs and fuzzy logic. Depending on training data, they change the types of membership fuzzy functions and inference fuzzy rules using an artifcial neural network's learning capability (Das et al. [2019;](#page-25-24) Sarkar et al. [2021\)](#page-27-13). Learning and logical inference benefts are therefore incorporated into a single system. ANFIS is one of the most widely utilised NF systems (Samantaray et al. [2022g](#page-26-30)). A multilayer neural network called ANFIS produces output variable's specifc value for identifed inputs depending on datasets (input–output vector) used during training.

The ability of ANFIS to accurately simulate non-linear links between input and output is a key characteristic. The implementation of an error propagation backward technique, either separately or in conjunction with approach of least squared error, is the foundation of ANFIS training. For describing ANFIS's structure, the system comprises two inputs (*x* and *y*), two Sugeno's type fuzzy if–then rules, and a single output (*y*):

Rule 1 : *if* $(x_1$ *is* C_1 *and* $(x_2$ *is* D_1 *thenf*₁ = $p_1x_1 + q_1x_2 + r_1$ *Rule* 1 : *if* $(x_1$ *is* C_2 $\big)$ *and* $(x_2$ *is* D_2 $\big)$ *thenf*₂ = $p_2x_1 + q_2x_2 + r_2$

where C_i and D_i —fuzzy sets, q , p , r —subsequent model parameters assessed during training phase. Five layers of the ANFIS structure are seen in Fig. [4.](#page-5-1)

The 1st layer comprises fuzzy MFs having output function for every node as shown in Eqs. (2) (2) and (3) (3) :

$$
O_i^1 = \mu_{C_i}(x), i = 1, 2
$$
\n(2)

$$
O_i^1 = \mu_{D_{i-1}}(x), i = 3, 4
$$
\n(3)

where μ —generalised Gaussian MF.

The 2nd layer calculates fring power of a rule utilising multiplication operator using Eq. [\(4](#page-3-4)):

$$
O_i^2 = w_i = \mu_{C_i}(x) \cdot \mu_{D_i}(x), i = 1, 2
$$
\n(4)

The 3rd layer normalises fring power of each rule, utilising ratio between firing power of ith node and addition of firing powers from all nodes $(Eq. (5))$ $(Eq. (5))$ $(Eq. (5))$. Non-adaptive nodes are present in the 3rd layer.

$$
O_i^3 = \overline{w_i} = \frac{w_i}{w_1 + w_2}, i = 1, 2
$$
 (5)

w_i − *i*th output from layer 2

Fig. 2 Study area depicting four selected gauge stations

Fig. 3 Architecture of ANN β_h β_1 $O₁$ £ $O₂$ O_n O_k f_i Input layer Hidden layer Output layer Layer 2 Layer 4 Layer 1 Layer 3 Layer 5 (First order Sugeno model) (MFs) (Firing strength) (Normalization) (Sum) C_1 $\overline{\text{w}_1}$ W_1 \prod N $C₂$ $\overline{W_1}$ Σ W_2 $\overline{W_2}$ Output D_1 $\overline{w_2}f_2$ $\mathbf \Pi$ N Ŋ $D₂$

The 4th layer utilises a nodal function for calculating the impact of *i* th rule concerning the output of the model (Eq. [\(6](#page-5-2))):

$$
O_i^4 = \overline{w_i} (p_i x + q_i y + r_i) = \overline{w_i} f_i
$$
 (6) PSO

where p_i , q_i , and r_i —parameter sets of node and w_i —normalised fring power of 3rd layer.

The 5th layer consists of a solitary non-adaptive node that computes ANFIS model's overall output utilising a summation system $(Eq. (7))$ $(Eq. (7))$ $(Eq. (7))$:

$$
O_i^5 = \sum_i \overline{w_i} f_i = \frac{\sum_i w_i f_i}{\sum_i w_i} \tag{7}
$$

 Kennedy and Eberhart [\(1995\)](#page-25-25) proposed a population-based meta-heuristic algorithm known as PSO algorithm for solving optimisation problems. The societal behaviour of cluster of "birds" (particles) inspired the two scientists for developing this optimisation technique. The behaviour of birds

Algorithm 1 PSO algorithm

- 1. Initialisation of swarm size, position, and velocity of all particles randomly
- 2. Compute the fitness of each swarm

3. **Do**

- 4. Compute fitness value of each particle
- 5. If fitness value is superior than *pbest* fix present value as new *pbest*

6. **End**

7. If fitness value is superior than *gbest* **then** select *gbest* as fitness value as among all

particles

8. **End**

- 9. Update position of each particle using Eq. 8
- 10. Compute velocity of each particle using Eq. 9

11. **End**

12. While minimum error criteria or maximum iterations are not reached

known as flocking is based on finding certain foodstuff for themselves. At frst, population (particle) is initialised by some arbitrarily produced location values. The preeminent position of every particle (*pbest*) is uninterruptedly stored locally in conjunction with the knowledge about global best particle (*gbest*). The position and velocity of all population are updated utilising Eq. [8](#page-6-0) and Eq. [9](#page-6-1) respectively.

$$
x_{i,n}^{j+1} = x_{i,n}^j + v_{i,n}^{j+1}
$$
 (8)

$$
v_{i,n}^{j+1} = w v_{i,n}^j + c_1 r_1 p_{i,n}^j - x_{i,n}^j + c_2 r_2 p_{g,n}^j - x_{i,n}^j
$$
(9)

where $x_{i,n}^j$ and $v_{i,n}^j$ —position and velocity of i^{th} particle respectively, *w*—inertial weight of current particle utilised for modifying subsequent group of particles, $p^j_{i,n}$ personal preeminent location having fitness cost (value) of *i*th particle

usually termed *pbest*, $p_{g,n}^{j}$ global preeminent particle position usually termed *gbest*, c_1 and c_2 —coefficient of acceleration utilised for handling exploration and exploitation ability respectively, r_1 and r_2 —equally dispersed arbitrary number between [0, 1]. All elements work together with one another to search for a best solution with their optimal ftness function. Basic architecture of PSO is shown in the following algorithm.

SMA

Because metaheuristic algorithms perform better than deterministic algorithms and use less processing power and time, they have gained popularity in several practical felds in recent years. In addition, certain deterministic algorithms are afected by local optima because they lack unpredictability in their latter stages. In contrast, random elements in MAs might cause the algorithm to search for all optimal solutions in the search space, successfully avoiding local optimum. Li et al. [\(2020\)](#page-26-31) developed a technique for creating wireless sensor networks that use two diferent slime mould tubular networks corresponding to two diferent regional routing algorithms.

Approach food

For replicating the contraction technique in this approach, following model equations are expressed (Eq. (10) (10)):

$$
\overrightarrow{Y(t+1)} = \begin{cases} \overrightarrow{Y_b(t)} + \overrightarrow{vb} \cdot (\overrightarrow{W} \cdot \overrightarrow{Y_A(t)} - \overrightarrow{Y_B(t)}), r < p \\ \overrightarrow{vc} \cdot \overrightarrow{Y(t)}, r \ge p \end{cases} \tag{10}
$$

where \vec{vb} —constraint utilised in $[-a, a]$, \vec{vc} —constraint values that vary from 1 to 0. $t - t_{th}$ iteration, \overrightarrow{Y}_b —discrete location of present best, \vec{Y} —position of present solution, \vec{Y} ^{*A*} and \overrightarrow{Y}_B —two randomly selected solutions, and \overrightarrow{W} —weight of current solution. *p* value is determined as follows (Eq. ([11\)](#page-7-1)):

$$
p = \tanh|S(i) - bestfitness|
$$
\n(11)

where $i \in 1, 2, 3, \ldots, n$, $S(i)$ —fitness function of present solution and *vb* is found using the following expression Eq. (12) :

$$
\overrightarrow{vb} = [-a, a], a = \operatorname{arctanh}(-(\frac{t}{\max_iter}) + 1)
$$
\n(12)

The \overline{W} is obtained based on subsequent Eq. ([13\)](#page-7-3):

$$
\overline{W(Smellindex(i))} = \begin{cases} 1 + r \cdot \log\left(\frac{bF - S(i)}{bF - wF} + 1\right), condition\\ 1 - r \cdot \log\left(\frac{bF - S(i)}{bF - wF} + 1\right), others \end{cases}
$$
\n(13)

where *r*—arbitrary value between [0, 1], *bF*—best-attained fitness values, *wF*—worst-attained fitness values, and *SmellIndex*—organised ftness values.

Wrap food

When food item is satisfed to extend to a location where the quantity of food is fragile, then the importance of that area diminishes, initiating investigators to move their observation towards other areas of food accessibility which are not as important as the food item. To update the locations, the following mathematical expression is used as depicted:

$$
\overrightarrow{Y^*} = \begin{cases}\n\text{rand.}(UB - LB) + LB, \text{rand} < z \\
\overrightarrow{Y_B(t)} + \overrightarrow{vb} \cdot \left(\overrightarrow{W} \cdot \overrightarrow{Y_A(t)} - \overrightarrow{Y_B(t)}\right), r < p \\
\overrightarrow{vc} \cdot \overrightarrow{Y(t)}, r \ge p\n\end{cases} \tag{14}
$$

where *UB* and *LB*—upper and lower boundaries, *rand* and *r* —arbitrary values between [0, 1], and *z* is a value of parameter between [0, 0.1].

Grabble food

vb—zone of arbitrary numbers between $[-a, a]$, *vc*^{\vec{c}} lies between [−1, 1]. Even though slime mould obtained an enhanced feed source, it still would extend organic material to seek other sites for a superior-class food source instead of investing all of it in a solitary region for discovering a more consistent nutrition source. The mechanism of SMA algorithm is represented in the following algorithm.

Proposed ANFIS‑PSOSMA model

The applied algorithm intends at improving the capability of ANFIS model for predicting Q_{FD} by finding its optimal constraints. This is obtained by utilising a novel metaheuristic algorithm called SMA. SMA is dependent on utilising PSO for generating initial population (frst generation) as it has the biggest impact on conjunction of solutions concerning optimum solution. The developed model namely ANFIS-PSOSMA, as shown in Algorithm 3, starts by constructing the network that comprises fve layers like the conventional ANFIS. After that, the input data is divided into two groups; frst set (70% of total data) is utilised for training the network and fnding optimal constraints and second set (30% of total data) is utilised for assessing superlative network built utilising PSOSMA. The subsequent procedure is to generate a group of arbitrary solutions and assess superiority of each one for determining best solution in accordance to training set.

Subsequently, solutions are updated utilising PSO operators, and updated population is delivered to SMA algorithm, which means until they reach at end conditions, operators of SMA will be utilised for updating solutions. The best solution of the preeminent ANFIS network is reverted from learning phase. After that, the testing set is utilised for evaluating performance of the best ANFIS model. Steps of ANFIS-PSOSMA model is demonstrated in Fig. [5.](#page-9-0)

Evaluating standards

*R*2 (Sridharam et al. [2021](#page-27-14); Chaudhury et al. [2022;](#page-25-26) Samantaray and Ghose [2022\)](#page-26-32), MAE (Singh et al. [2022;](#page-27-15) Jamei et al. [2022\)](#page-25-27), and RMSE (Wang et al. [2022](#page-27-16); Ehteram et al. [2019\)](#page-25-28) are standard assessment measures for determining the preeminent prediction model (Eq. (15) , Eq. (16) (16) (16) , and Eq. (17) (17) (17)). Furthermore, the N_{SE} (Patel et al. [2022](#page-26-33); Samani et al. [2022\)](#page-26-34) is also utilised to assess the power of the ANFIS-PSOSMA model (Eq. [\(18\)](#page-8-3)). For the

14. **Return** Prominent Fitness value, Y_b ;

selection of the best model in this research, the criteria is MAE and RMSE are to be minimum and N_{SE} , R^2 must be maximum.

$$
=R^{2}\left(\frac{\sum_{i=1}^{n}(O_{i}-\overline{O})(P_{i}-\overline{P})}{\sqrt{\sum_{i=1}^{n}(O_{i}-\overline{O})^{2}\sum_{i=1}^{n}(P_{i}-\overline{P})^{2}}}\right)^{2}
$$
(15)

$$
RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (P_i - O_i)^2}
$$
 (16)

$$
MAE = \frac{1}{n} \sum_{i=1}^{n} ||P_i - O_i|| \tag{17}
$$

$$
N_{SE} = 1 - \left[\frac{\sum_{i=1}^{n} (P_i - O_i)^2}{\sum_{i=1}^{n} (O_i - \overline{O})^2}\right]
$$
(18)

where

 P_i predicted value. O_i observed value. *P* mean predicted value \overline{O} mean observed value

The applied models based on different input combinations of meteorological components (precipitation (P_t) , temperature (T_t) , humidity (H_t) , infiltration (I_t) , evapotranspiration (ET_t)) are presented in Table [1](#page-11-0). The observed rainfall (P_t) , average temperature (T_t) , mean humidity (H_t), and mean evapotranspiration loss (E_t) data are collected from IMD (Indian Meteorological Department), Pune. Infiltration data is obtained from Soil Water Infiltration Global Database.

Statistical analysis (minimum, maximum, mean, standard deviation, and kurtosis) of considered hydrological parameters (precipitation, humidity, temperature, evapotranspiration loss, and infltration), for all datasets (training and testing) of all four stations, is conducted in Tables [2,](#page-11-1) [3,](#page-12-0) [4](#page-12-1), and [5.](#page-13-0) The obtained

Fig. 5 Steps of ANFIS-PSOSMA

results are presented in Table [6](#page-13-1). After monitoring the data quality, datasets were divided into training (70% of complete data) and testing (30% of complete data). The period from January 1990 to December 2010 was utilised to train the models, and from January 2011 to December 2019 to test them.

Results

The performance of three models were tested for predicting monthly Q_{FD} in both training and testing phases utilising different statistical assessment measures (Tables [6,](#page-13-1) [7](#page-14-0), [8,](#page-14-1) [9](#page-15-0), and [10](#page-15-1)). Based on the applied evaluation measures, it was witnessed that all applied models had good prediction capability $(R^2 > 0.7)$. The results of R^2 revealed that applied models are satisfactory; however, ANFIS-PSOSMA model generated the best Q_{FD} values, with the highest value of R^2 (0.9946), followed by ANFIS-SMA (0.9813), ANFIS-PSO (0.9748), ANFIS (0.9657), and ANN (0.9507) models in the training phase and in the testing phase, *R*² values of 0.9731, 0.9517, 0.9436, 0.9314, and 0.9176 in Jenapur station. Considering RMSE values, ANFIS-PSOSMA model had the lowest RMSE (0.0485) proving its best predictive power, followed by ANFIS-SMA (2.2532),

ANFIS-PSO (6.8964), ANFIS (13.8749), and ANN (30.9957) models. Moreover, N_{SE} criteria were categorised from highest prediction power to lowest providing similar to R^2 , as follows: ANFIS-PSOSMA (0.9952)>ANFIS-SMA (0.9818)>ANFIS-PSO (0.9755)>ANFIS (0.9662)>ANN (0.9513).

The statistical indices discussed above have very well evaluated the prediction capability of projected models. In addition to that, scatter plots and time-series plots are very much useful in assessing the efficiency of forecasting data against the observed data.

It is observed from the scatterplots (Fig. [6\)](#page-16-0) that all models achieved reasonable outcomes in terms of low and high Q_{FD} values. However, the values of R^2 (Fig. [6](#page-16-0)) showed that ANFIS-PSOSMA performed superiorly compared to other hybrid and conventional models. As shown in Fig. [6](#page-16-0)d, the outcomes attained from the fve models in the Jenapur station are more closely to 45° reference line than those of Jaraikela, Gomlai, and Tilga stations. Also, ANFIS-PSOSMA generated the best R^2 value (0.99468), which inferred superior prediction than other models. The scatter plots of Tilga, Jaraikela, and Gomlai stations are shown in Fig. [6a](#page-16-0)–c.

Performance of ANN, ANFIS, and ANFIS-SMA are further demonstrated in a more instinctive manner by plotting **Algorithm 3** Pseudo-code of ANFIS-PSOSMA

- 1. Select and input the dataset
- 2. State the total number of iterations (t_{max}) , maximum epochs, number of solutions (N), increase

rate, error goal, initial step, decrease rate.

- 3. Select input data and break into train (70%) and test (30%) data set
- 4. Employing FCM clustering to the proposed model
- 5. Fix the input dataset of membership function
- 6. Initial population is produced by PSO.
- 7. **While** (Stopping criteria is not satisfied) **do**
- 8. Improve the solution using the SMA constraints
- 9. Calculate the value of fitness function for present scenario.
- 10. **If** the fitness value is better than the previous one, **then**
- 11. Save the current value
- 12. **end if**

13. **end while**

14. Find the Result

15. Stop

observed versus predicted Q_{FD} in the form of hydrographs, as presented in Fig. [6.](#page-16-0) Monthly forecasting time series data for all models are illustrated in Fig. [6](#page-16-0) using data from 1 January 1990 to 31 December 2010 during training, whereas during the testing period uses data from 1 January 2011 to 31 December 2019. For all the stations considered in this study, ANFIS-PSOSMA model performed best for Q_{FD} forecasting,

as estimated Q_{FD} values were closer to corresponding actual values and followed similar trend in all sketches, as displayed in Fig. [6](#page-16-0). The time-series plots of Tilga, Jaraikela, Gomlai, and Jenapur stations are presented in Fig. [6a](#page-16-0)–d. Different from predictions from Jaraikela, Gomlai, and Tilga stations, predictions from Jenapur station can better forecast higher and lower flows. Among all the four stations

| Input combinations | Output | Scenario | Model name | | | | |
|--|----------|----------|------------------|--------------------|-------------------|------------------|---------------|
| | | | ANN | ANFIS | ANFIS-PSO | ANFIS-SMA | ANFIS-PSOSMA |
| P_{t} | Q_{FD} | | ANN1 | ANFIS1 | ANFIS-PSO1 | ANFIS-SMA1 | ANFIS-PSOSMA1 |
| P_t , T_t | | П | ANN ₂ | ANFIS ₂ | ANFIS-PSO2 | ANFIS-SMA2 | ANFIS-PSOSMA2 |
| P_t , T_t , H_t | | Ш | ANN3 | ANFIS3 | ANFIS-PSO3 | ANFIS-SMA3 | ANFIS-PSOSMA3 |
| P_t , T_t , H_t , I_t | | IV | ANN ₄ | ANFIS4 | ANFIS-PSO4 | ANFIS-SMA4 | ANFIS-PSOSMA4 |
| P_t , T_t , H_t , I_t , ET_t | | | ANN ₅ | ANFIS5 | ANFIS-PSO5 | ANFIS-SMA5 | ANFIS-PSOSMA5 |

Table 1 Model scenarios based on diferent input combinations

Table 2 Statistical parameters of applied data Tilga

| Statistical parameters | Training set (252) | Testing set (108) | Total data set (360) | Training set (252) | Testing set (108) | Total data set (360) | | |
|---------------------------|--------------------|---------------------|----------------------|--------------------|---------------------|----------------------|--|--|
| Precipitation | | | | Humidity | | | | |
| Min | $\boldsymbol{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | 58.54 | 59.5 | 58.54 | | |
| Max | 56.064 | 47.86 | 56.06 | 83.04 | 83.04 | 83.04 | | |
| Mean | 40.616 | 43.762 | 40.616 | 71.20175 | 71.0052 | 71.14559 | | |
| Kurt | 1.942 | 1.256 | 1.317 | -0.95765 | -0.99391 | -0.97411 | | |
| SD | 46.281 | 46.378 | 45.519 | 6.25959 | 6.59965 | 6.33928 | | |
| Skew | 1.334 | 1.128 | 1.208 | -0.0072 | 0.05259 | 0.00939 | | |
| Temperature | | | | Evapotranspiration | | | | |
| Min | 18.5 | 18.5 | 18.5 | 78.54 | 79.5 | 78.54 | | |
| Max | 33.5 | 32.63 | 33.5 | 116.88 | 126.88 | 126.88 | | |
| Mean | 27.50175 | 27.14895 | 27.4009 | 98.03508 | 98.5669 | 98.22505 | | |
| Kurt | -0.57584 | -1.03682 | -0.72528 | -0.7702 | -0.8359 | -0.79538 | | |
| SD | 3.3617 | 3.91405 | 3.51994 | 9.187584 | 9.89156 | 9.38803 | | |
| Skew | -0.50559 | -0.367 | -0.46928 | -0.01812 | 0.01391 | 0.01115 | | |
| Infiltration | | | | | | | | |
| Min | 4.276 | 14.469 | 4.276 | | | | | |
| Max | 11.478 | 21.638 | 21.638 | | | | | |
| Mean | 7.892 | 18.335 | 8.22 | | | | | |
| Kurt | 0.59 | 9.414 | 34.526 | | | | | |
| SD | 0.758 | 5.146 | 2.789 | | | | | |
| Skew | 0.889 | -1.634 | -3.9 | | | | | |

considering the fve applied models, the prediction accuracy of Jaraikela station is poor with the least R^2 value in both the training and testing stages.

Linear scale plot of actual vs. estimated Q_{FD} for applied models are demonstrated in Fig. [7](#page-20-0). The fgures demonstrate that predicted peak Q_{FD} are 459.179 $M³/s$, 454.666 $M³/s$, $444.198M³/s$, $433.496M³/s$, $414.187M³/s$ for ANFIS-PSOSMA, ANFIS-SMA, ANFIS-PSO, ANFIS, and ANN in contrast to actual peak of $465.274M³/s$ for Tilga station. The approximated peak discharges are $3736.342M^{3}/s$, $3705.635M³/s$, $3624.51M³/s$, $3541.109M³/s$, and 3344.36M³ /s for ANFIS-PSOSMA, ANFIS-SMA, ANFIS-PSO, ANFIS, and ANN against actual peak $3790.931M³/s$ for Jaraikela division. For Gomlai gauging station, actual Q_{FD} is 2859.61M³/s aligned with predicted Q_{FD}

2822.149M³/s, 2804.991M³/s, 2736.075M³/s, 2667.444M³/s, and 2547.626M³/s for ANFIS-PSOSMA, ANFIS-SMA, ANFIS-PSO, ANFIS, and ANN correspondingly. Similarly, for Jenapur, observed peak discharge is $4432.095M³/s$ with respect to predicted Q_{FD} 4371.819 M^3/s , 4326.168 M^3/s , $4242.401M³/s$, $4143.566M³/s$, and $3871.435M³/s$, for ANFIS-PSOSMA, ANFIS-SMA, ANFIS-PSO, ANFIS, and ANN respectively.

The results of boxplot are shown in Fig. [8](#page-23-0). The boxplot of ANFIS-PSOSMA model for Q_{FD} prediction was nearly close to the actual boxplot compared to other two hybrid models (ANFIS-SMA and ANFIS-PSO), whereas conventional ANFIS, and ANN underestimated Q_{FD} . In terms of quartile, minimum and median values of all considered models were capable of predicting Q_{FD} values closer to

| Statistical parameters | Training set (252) | Testing set (108) | Total data set (360) | Training set (252) | Testing set (108) | Total data set (360) |
|---------------------------|--------------------|-------------------|----------------------|--------------------|-------------------|----------------------|
| Precipitation | | | | Humidity | | |
| Min | $\boldsymbol{0}$ | $\boldsymbol{0}$ | $\mathbf{0}$ | 56.03 | 56.03 | 56.03 |
| Max | 64.3 | 52.709 | 64.3 | 84.06 | 82.83 | 84.06 |
| Mean | 38.558 | 31.384 | 30.91 | 71.9143 | 70.31995 | 71.45878 |
| Kurt | 1.103 | 3.953 | 2.218 | -0.61569 | -0.70499 | -0.6799 |
| SD | 1.303 | 1.854 | 1.629 | 6.21456 | 6.38536 | 6.28626 |
| Skew | 45.519 | 40.99 | 43.115 | -0.23484 | -0.03069 | -0.17763 |
| Temperature | | | | Evapotranspiration | | |
| Min | 15.998 | 15.811 | 15.81 | 75.63 | 75.63 | 75.63 |
| Max | 35.49 | 34.03 | 35.49 | 118.54 | 118.39 | 118.54 |
| Mean | 24.965 | 24.794 | 24.95 | 99.103 | 98.85047 | 98.8398 |
| Kurt | -0.908 | -0.898 | -0.926 | -0.60293 | -0.5028 | -0.65282 |
| SD | 4.867 | 4.896 | 4.798 | 9.42552 | 10.1193 | 9.71719 |
| Skew | -0.104 | -0.222 | -0.117 | -0.23999 | -0.40922 | -0.27184 |
| Infiltration | | | | | | |
| Min | 6.876 | 7.986 | 6.876 | | | |
| Max | 12.375 | 19.912 | 12.375 | | | |
| Mean | 7.268 | 16.859 | 11.69 | | | |
| Kurt | 6.761 | 7.975 | 5.253 | | | |
| SD | 1.141 | 16.71 | 25.309 | | | |
| Skew | -6.131 | -4.231 | -7.031 | | | |

Table 4 Statistical parameters of applied data Jaraikela

Table 7 Performance of ANFIS Station Scenario Training Testing Testing

Table 8 Performance of ANFIS-PSO

| Station | Scenario | Training | | | | Testing | | | |
|-----------|--------------|--------------|-------------|--------|------------|----------|-------------|--------|------------|
| | | $\rm N_{SE}$ | RMSE | R^2 | MAE | N_{SE} | RMSE | R^2 | MAE |
| Tilga | I | 0.9607 | 23.17 | 0.96 | 10.82 | 0.9352 | 44.02 | 0.9348 | 20.3796 |
| | \mathbf{I} | 0.9616 | 21.8631 | 0.9612 | 11.387 | 0.9373 | 43.5731 | 0.9369 | 20.1727 |
| | Ш | 0.964 | 16.587 | 0.9633 | 8.639 | 0.9392 | 42.59 | 0.9388 | 23.6611 |
| | IV | 0.9653 | 15.0067 | 0.9647 | 7.2147 | 0.9408 | 41.33 | 0.9403 | 22.9611 |
| | V | 0.966 | 14.2587 | 0.9655 | 6.8551 | 0.9421 | 40.168 | 0.9414 | 19.1276 |
| Jaraikela | I | 0.9527 | 29.0048 | 0.9522 | 15.59 | 0.927 | 46.2296 | 0.9266 | 26.4169 |
| | \mathbf{I} | 0.9552 | 27.2367 | 0.9547 | 12.7274 | 0.9295 | 45.4821 | 0.9289 | 21.0565 |
| | Ш | 0.9561 | 26.1785 | 0.9556 | 12.2329 | 0.9305 | 44.9832 | 0.9301 | 20.8255 |
| | IV | 0.9581 | 25.3517 | 0.9574 | 11.8465 | 0.9323 | 44.589 | 0.9317 | 20.643 |
| | V | 0.9602 | 23.5214 | 0.9596 | 10.9913 | 0.9386 | 43.1832 | 0.938 | 19.9922 |
| Gomlai | Ι | 0.9634 | 18.2291 | 0.9629 | 9.4943 | 0.9387 | 42.97 | 0.9381 | 23.8722 |
| | \mathbf{I} | 0.9642 | 16.3201 | 0.9638 | 8.5005 | 0.93979 | 42.1267 | 0.9392 | 23.4037 |
| | Ш | 0.9658 | 14.7962 | 0.9652 | 7.1135 | 0.94048 | 41.66 | 0.94 | 23.1444 |
| | IV | 0.9669 | 12.8412 | 0.9664 | 6.1736 | 0.94147 | 40.775 | 0.941 | 22.6527 |
| | V | 0.9688 | 12.3541 | 0.9683 | 5.9394 | 0.94323 | 39.5064 | 0.9426 | 18.8125 |
| Jenapur | I | 0.970 | 11.8459 | 0.9694 | 5.6951 | 0.9401 | 41.8904 | 0.9395 | 23.2724 |
| | \mathbf{I} | 0.9712 | 10.8746 | 0.9706 | 5.5767 | 0.9407 | 41.496 | 0.9402 | 23.0533 |
| | Ш | 0.973 | 9.0215 | 0.9723 | 4.6264 | 0.9416 | 40.621 | 0.941 | 22.5672 |
| | IV | 0.9734 | 8.8147 | 0.973 | 4.5203 | 0.9434 | 39.337 | 0.9427 | 18.7319 |
| | V | 0.9755 | 6.8964 | 0.9748 | 3.5366 | 0.9441 | 38.915 | 0.9436 | 18.5309 |

 N_{SE} RMSE R^2 MAE N_{SE} RMSE R^2 MAE

Tilga I 0.9514 30.2856 0.9509 16.2825 0.9207 47.902 0.9203 27.3725

Jaraikela I 0.9477 36.0045 0.9473 19.3572 0.9192 48.1883 0.9186 21.6091

II 0.9519 29.8129 0.9513 16.0284 0.9217 47.621 0.9211 27.212 III 0.9531 28.5436 0.9525 13.3381 0.9238 47.003 0.9234 26.8588 IV 0.9551 27.2367 0.9547 12.7200 0.9252 46.7884 0.9247 26.7362 V 0.9571 25.6895 0.9565 12.0044 0.9256 46.6901 0.9250 26.68

II 0.9492 34.5147 0.9485 18.5562 0.9205 48.0067 0.9198 21.5276 III 0.9501 33.4179 0.9495 17.9666 0.9208 47.8219 0.9204 27.3268 IV 0.9512 30.7128 0.9508 16.5122 0.9221 47.44 0.9216 27.1085 V 0.9522 29.0048 0.9518 15.5939 0.9238 47.1184 0.9231 26.9248

actual values with a substantial degree of precision, even though ANFIS-PSOSMA model performed best among all models.

Correspondingly, frequency analysis is done through a histogram plot (Fig. [9\)](#page-24-0) of actual and predicted data set. The *x*-axis presents Q_{FD} values, and the number of events

Table 9 Performance of ANFIS-SMA

Table 10 Performance of ANFIS-PSOSMA

was determined by the bin ranges of the histograms. From the above analysis, it is clearly found that ANFIS-SMA is more suitable than ANFIS and ANN approach. It can be concluded that after incorporating SMA to ANFIS models, there is a noticeable decrease in forecasting uncertainty resulting in the assessment of the prediction model.

Fig. 6 Scatter plots of actual vs. predicted food discharge using ANN, ANFIS, ANFIS-PSO, ANFIS-SMA, and ANFIS-PSOSMA models for **a** Tilga, **b** Jaraikela, **c** Gomlai, and **d** Jenapur stations

Fig. 6 (continued)

Fig. 6 (continued)

Fig. 6 (continued)

Fig. 7 Observed and computed stream flow for **a** Tilga, **b** Jaraikela, **c** Gomlai, and **d** Jenapur stations

Discussion

The applied models realise flood discharge prediction with a forecasting horizon. The performance criteria of hybrid ANFIS-PSOSMA is satisfactory (NSE=0.9952, $RMSE = 0.0485$ $R^2 = 0.9946$, $MAE = 0.0265$). The coefficient of determination (Fig. 6) illustrates that the developed model has adequately acquired the aspects of time series (Q_{FD}) of training data series. The predicted and observed Q_{FD} by ANFIS-PSOSMA model are nearly similar (Fig. [7\)](#page-20-0). The same situation is observed with the NSE (0.9952). A small deviation is observed in terms of the RMSE (0.0485) between the forecasted food discharge against the actual discharge. Hence, the proposed hybrid ANFIS-PSOSMA model has appropriately adjusted with variations in the input dataset (meteorological components) during the training period. The evaluation of generalisation capability, i.e. absence of overftting or underftting, is conducted with the testing dataset which has not been utilised in the training period. For each occurrence, testing results showed a good generalisation capability of the selected model. This reveals that there was neither overftting nor underftting during training. Also, it specifes perfect forecasts of food peaks. There was a slight deviation between predicted and observed food peaks, and hence, we can conclude that ANFIS-PSOSMA model has a better forecasting or prediction ability for food peaks. The major advantage of the developed holistic approach is automatic determination of ANFIS variables and arrangement of key standardisation samples for overcoming limitations of conventional ML in modelling real-world problems when series of sample values is huge. The PSO is utilised for modifying search operators of SMA for avoiding its limitations in determining preeminent solution because of its fragile exploitation capability. As a result, integration of PSO and SMA, i.e. PSOSMA, utilises benefts of both SMA and PSO, and it shows higher performance outcomes compared to original SMA and PSO.

The key drawback of this research is the assessment of fve applied ML approaches utilising data from a particular area. The proposed techniques can further be verifed by utilising additional data from other climatic conditions. Also, the prospective of hybridisation of PSOSMA technique with stochastic models, mainly models with exogenous input, necessities to be evaluated. In future works, integrating ANFIS-PSOSMA with ensemble modelling techniques (like Bayesian model averaging) or preprocessing methods (e.g.

Fig. 7 (continued)

Fig. 7 (continued)

Fig. 7 (continued)

EEMD or EMD) may be considered for improving models' effectiveness.

Conclusion

This research investigates the possibilities of modelling food extremes utilising the newly developed AI approaches for improving early food warning systems to mitigate the efect of food hazards in the future. The present study was conducted for improving the appropriateness of ANFIS model integrated with PSOSMA for estimating flood discharge. Analysis of outcomes revealed that ANFIS in combination with meta-heuristic algorithms has great potential in estimating Q_{FD} with high accurateness and can enhance performance of standalone ANFIS by evading from the possibility of being stuck in local optima. It also decreases the dependency on conditions of the specifed problem and improves search technique and capability of optimising complex problems. A good agreement was achieved amid observed and predicted values for simulated Q_{FD} in Bramhani River.

- Among all employed AI models, ANFIS-PSOSMA model provided superior accurateness compared to other models namely ANFIS-SMA, ANFIS-PSO, ANFIS, and ANN. Novel ANFIS-PSOSMA model gave best value of $R^2 = 0.9946$ than ANFIS-SMA (0.9813), ANFIS-PSO (0.9748), ANFIS (0.9657), and ANN (0.9507) models.
- Addition of evapotranspiration as input to models showed substantial enhancement; hence for building an excellent Q_{FD} prediction model, rainfall data should be taken into consideration. In terms of accuracy in predicting Q_{FD} , it appears that the employed hybrid models performed very well.
- Therefore, the hybrid ANFIS algorithm without the need for an innovative mathematical model is excellent for mimicking the non-linear restraints of obtained data and could be useful as a Q_{FD} estimation tool. To forecast Q_{FD} , identical algorithms with related model architectures could be taken and verifed worldwide.
- Provided that usage of better-quality datasets in ANN models will give more consistent results, however, accessibility of these high-quality hydro-climatic data series is one of the major limitations of these types of approaches. For future studies, efforts should be made for applying other appropriate EA and investigating their capability by comparing the models recommended in this work. Also, proposed EA techniques can be applied in other popular AI models that might face certain problems during training phase.

Fig. 8 Boxplot representation for proposed models for **a** Tilga, **b** Jaraikela, **c** Gomlai, and **d** Jenapur stations

Author contribution Sandeep Samantaray: conceptualisation, analysis, writing-original draft. Abinash Sahoo: formulation, analysis, validation, review, and editing. Pratik Sahoo: methodology, review, and editing. Deba Prakash Satapathy: supervision and validation.

Data availability The data for the current study are available on reasonable request from the corresponding author.

Declarations

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Consent for publication Not applicable.

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