

# Volume Growth and On-diagonal Heat Kernel Bounds on Riemannian Manifolds with an End

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## Abstract

We investigate heat kernel estimates of the form  $p_t(x, x) \ge c_x t^{-\alpha}$ , for large enough t, where  $\alpha$  and  $c_x$  are positive reals and  $c_x$  may depend on x, on manifolds having at least one end with a polynomial volume growth.

Keywords Manifolds with ends · Heat kernel · Isoperimetric inequality

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# 1 Introduction

Let *M* be a complete connected non-compact Riemannian manifold and  $p_t(x, y)$  be the *heat kernel* on *M*, that is, the minimal positive fundamental solution of the heat equation  $\partial_t u = \Delta u$ , where  $\Delta$  is the Laplace-Beltrami operator on *M*. In this paper, we investigate the long time behaviour of  $p_t(x, x)$  for  $t \to +\infty$ ,  $x \in M$ . Especially, we are interested in lower bounds for large enough *t* of the form

$$p_t(x,x) \ge c_x t^{-\alpha},\tag{1.1}$$

where  $\alpha$  and  $c_x$  are positive reals and  $c_x$  may depend on x.

Let  $V(x, r) = \mu(B(x, r))$  be the volume function of M where B(x, r) denotes the geodesic balls in M and  $\mu$  the Riemannian measure on M. It was proved by A. Grigor'yan and T. Coulhon in [7], that if for some  $x_0 \in M$  and all large enough r,

$$V(x_0, r) \le Cr^N \tag{1.2}$$

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where C and N are positive constants, then

$$p_t(x, x) \ge \frac{c_x}{(t \log t)^{N/2}},$$
 (1.3)

which obviously implies (1.1).

It is rather surprising that such a weak hypothesis as (1.2) implies a pointwise lower bound (1.3) of the heat kernel. In this paper we obtain heat kernel bounds assuming even weaker hypotheses about M. We say that an open connected proper subset  $\Omega$  of M is an *end* of M if  $\partial \Omega$  is compact but  $\overline{\Omega}$  is non-compact (see also Section 2). One of our aims here is to obtain lower bounds for the heat kernel assuming only hypotheses about the intrinsic geometry of  $\Omega$ , although a priori it was not obvious at all that such results can exist.

One of the motivations was the following question asked by A. Boulanger in [1] (although for a more restricted class of manifolds). Considering the volume function in  $\Omega$  given by

$$V_{\Omega}(x,r) = \mu(B(x,r) \cap \Omega),$$

Boulanger asked if the heat kernel satisfies (1.1) provided it is known that

$$V_{\Omega}(x_0, r) \le C r^N, \tag{1.4}$$

for some  $x_0 \in \Omega$  and all *r* large enough.

A first partial answer to this question was given by A. Grigor'yan, who showed in [10], that if (1.4) holds and  $\overline{\Omega}$ , considered as a manifold with boundary, is *non-parabolic*, (and hence, N > 2 in Eq. 1.4 by [5]) then Eq. 1.3 is satisfied. More precisely, denoting by  $p_t^{\Omega}(x, y)$  the heat kernel in  $\Omega$  with the Dirichlet boundary condition on  $\partial \Omega$ , it was proved in [10] that, for all  $x \in \Omega$  and large enough t,

$$p_t^{\Omega}(x,x) \ge \frac{c_x}{(t\log t)^{N/2}},$$
(1.5)

which implies (1.3) by the comparison principle.

From a probabilistic point of view, the estimate (1.5) for non-parabolic  $\Omega$  is very natural if one compares it with (1.3), since the non-parabolicity of  $\overline{\Omega}$  implies that the probability that Brownian motion started in  $\Omega$  never hits the boundary  $\partial \Omega$  is positive (see [[12], Corollary 4.6]). Hence, one expects that the heat kernel in  $\overline{\Omega}$  and the heat kernel in  $\Omega$  with Dirichlet boundary condition are comparable.

The main direction of research in this paper is the validity of the estimate (1.1) in the case when  $\overline{\Omega}$  is parabolic and the volume function of  $\Omega$  satisfies (1.4). We prove (1.1) for a certain class of manifolds M when  $\overline{\Omega}$  is parabolic as well as construct a class of manifolds M with parabolic ends where (1.1) does not hold.

In Section 2 we are concerned with positive results. One of our main results -Theorem 2.6, ensures the estimate (1.1) when  $\overline{\Omega}$  is a *locally Harnack* manifold (see Section 2.2 for the definition). In order to handle difficulties that come from the parabolicity of the end, we use the method of *h*-transform (see Section 2.1). For that we construct a positive harmonic function *h* in  $\Omega$  and define a new measure  $\tilde{\mu}$  by  $d\tilde{\mu} = h^2 d\mu$ . Thus, we obtain a weighted manifold ( $\overline{\Omega}, \tilde{\mu}$ ). We prove that this manifold is non-parabolic, satisfies the polynomial volume growth and, hence, the heat kernel  $\tilde{p}_t^{\Omega}$  of  $(\Omega, \tilde{\mu})$  satisfies the lower bound (1.5). Then a similar lower bound for  $p_t^{\Omega}$  and, hence, for  $p_t$ , follows from the identity

$$p_t^{\Omega}(x, x) = h^2(x)\widetilde{p}_t^{\Omega}(x, x)$$

(see Lemma 2.3). Note that the techniques of *h*-transform for obtaining heat kernel estimates was used in [17] and [16] although in different settings (see also [[15], Section 9.2.4] and [22]).

In Section 3 we present a technique for obtaining *isoperimetric inequalities* on warped products of weighted manifolds. We say that a function J on  $[0, +\infty)$  is a *lower isoperimetric function* for  $(M, \mu)$  if, for any precompact open set  $U \subset M$  with smooth boundary,

$$\mu^+(U) \ge J(\mu(U)),$$
 (1.6)

where  $\mu^+$  denotes the perimeter with respect to the measure  $\mu$  (see Section 3 for more details).

The isoperimetric inequality on *Riemannian products* was proved in [19]. We develop further the method of [19] to deal with warped products. The main result here is stated in Theorem 3.3. Given two weighted manifolds  $(M_1, \mu_1)$  and  $(M_2, \mu_2)$  consider the weighted manifold  $(M, \mu)$  such that  $M = M_1 \times M_2$  as topological spaces, the Riemannian metric  $ds^2$  on M is defined by

$$ds^2 = dx^2 + \psi^2(x)dy^2,$$

with  $\psi$  being a smooth positive function on  $M_1$  and  $dx^2$  and  $dy^2$  denoting the Riemannian metrics on  $M_1$  and  $M_2$ , respectively and measure  $\mu$  on M is defined by  $\mu = \mu_1 \times \mu_2$ . Assume that the function  $\psi$  is bounded and  $(M_1, \mu_1)$  and  $(M_2, \mu_2)$  admit continuous lower isoperimetric functions  $J_1$  and  $J_2$ , respectively. Then we prove in Theorem 3.3 that  $(M, \mu)$  admits a lower isoperimetric function

$$J(v) = c \inf_{\varphi,\phi} \left( \int_0^\infty J_1(\varphi(t)) dt + \int_0^\infty J_2(\phi(s)) ds. \right),$$

for some positive constant c > 0 and where  $\varphi$  and  $\phi$  are generalized mutually inverse functions such that

$$v = \int_0^\infty \varphi(t) dt = \int_0^\infty \phi(s) ds$$

In Theorem 3.6 we construct a *weighted model manifold with boundary*  $(M_0, \tilde{\mu})$  (see Section 3.2 for the definition of this term), where  $M_0$  topologically coincides with  $[0, +\infty) \times \mathbb{S}^{n-1}$ ,  $n \ge 2$ , while the Riemannian metric on  $M_0$  is given by

$$ds^{2} = dr^{2} + \psi^{2}(r)d\theta^{2}, \qquad (1.7)$$

where  $d\theta^2$  is a standard Riemannian metric on  $\mathbb{S}^{n-1}$  and

$$\psi(r) = e^{-\frac{1}{n-1}r^{\alpha}},\tag{1.8}$$

with  $0 < \alpha \le 1$ , and obtain as a consequence of Theorem 3.3, that  $(M_0, \tilde{\mu})$  admits a lower isoperimetric function J such that for large enough v,

$$J(v) = \frac{cv}{(\log v)^{\frac{2-2\alpha}{\alpha}}},\tag{1.9}$$

for some positive constant c > 0.

In Section 4 we construct examples of manifolds M having a parabolic end  $\Omega$  with finite volume (in particular, satisfying (1.4)) but such that the heat kernel  $p_t(x, x)$  decays *superpolynomially* as  $t \to \infty$ . In fact, the end  $\Omega$  is constructed by means of the aforementioned model manifold  $M_0$ , particularly,  $\overline{\Omega}$  topologically coincides with  $M_0$ . Our fourth main result -Theorem 4.3, says that for a certain manifold M with this end  $\Omega$  the following heat kernel estimate holds:

$$p_t(x,x) \le C_x \exp\left(-Ct^{\frac{\alpha}{2-\alpha}}\right),$$
 (1.10)

for all  $x \in M$  and large enough *t*. The estimate (1.10) follows from Theorem 4.2 where we obtain the upper bound of the heat kernel  $\tilde{p}_t$  of a weighted manifold  $(M, \tilde{\mu})$  after an appropriate *h*-transform. In this theorem we prove that

$$\widetilde{p}_t(x,x) \le C \exp\left(-C_1 t^{\frac{\alpha}{2-\alpha}}\right).$$
 (1.11)

In fact, this decay is sharp, meaning that we have a matching lower bound

$$\sup_{x \in M} \widetilde{p}_t(x, x) \ge c \exp\left(-C_2 t^{\frac{\alpha}{2-\alpha}}\right)$$

(see the remark after Theorem 4.2). The key ingredient in the proof of Theorem 4.2 is utilizing the lower isoperimetric function J on  $(\overline{\Omega}, \widetilde{\mu})$  given by Eq. 1.9, which then yields the heat kernel upper bound (1.11) by a well-known technique based on *Faber-Krahn inequalities* (see [[13], Proposition 7.1] and Proposition 4.1).

Even though we managed to give both positive and negative results for manifolds with parabolic end concerning the estimate (1.1), a gap still remains. Closing this gap seems to be interesting for future work, for example, it might be desirable to construct a manifold with parabolic end of infinite volume for which (1.1) does not hold.

**Notation** For any nonnegative functions f, g, we write  $f \simeq g$  if there exists a constant C > 1 such that

$$C^{-1}f \le g \le Cf.$$

## 2 On-diagonal Heat Kernel Lower Bounds

Let *M* be a non-compact Riemannian manifold with boundary  $\delta M$  (which may be empty). Given a smooth positive function  $\omega$  on *M*, let  $\mu$  be the measure defined by

$$d\mu = \omega^2 d$$
vol,

where dvol denotes the Riemannian measure on M. Similarly. we define  $\mu'$  as the measure with density  $\omega^2$  with respect to the Riemannian measure of codimension 1 on any smooth hypersurface. The pair  $(M, \mu)$  is called *weighted manifold*.

The Riemannian metric induces the Riemannian distance d(x, y),  $x, y \in M$ . Let B(x, r) denote the geodesic ball of radius r centered at x, that is

$$B(x, r) = \{x \in M : d(x, y) < r\}$$

and V(x, r) its volume on  $(M, \mu)$  given by

$$V(x, r) = \mu(B(x, r)).$$

We say that M is complete if the metric space (M, d) is complete. It is known that M is complete, if and only if, all balls B(x, r) are precompact sets. In this case, V(x, r) is finite.

The Laplace operator  $\Delta_{\mu}$  is the second order differential operator defined by

$$\Delta_{\mu} f = \operatorname{div}_{\mu}(\nabla f) = \omega^{-2} \operatorname{div}(\omega^{2} \nabla f).$$

If  $\omega \equiv 1$ , then  $\Delta_{\mu}$  coincides with the Laplace-Beltrami operator  $\Delta = \operatorname{div} \circ \nabla$ .

Consider the Dirichlet form

$$\mathcal{E}(u,v) = \int_M (\nabla u, \nabla v) d\mu,$$

defined on the space  $C_0^{\infty}(M)$  of smooth functions with compact support. The form  $\mathcal{E}$  is closable in  $L^2(M, \mu)$  and positive definite. Let us denote by  $\overline{\Delta}_{\mu}$  its infinitesimal generator. By integration by parts, we obtain for all  $u, v \in C_0^{\infty}(M)$ ,

$$\mathcal{E}(u,v) = \int_{M} (\nabla u, \nabla v) d\mu = -\int_{M} v \Delta_{\mu} u d\mu + \int_{\delta M} v \frac{\partial u}{\partial v} d\mu', \qquad (2.1)$$

where  $\nu$  denotes the outward unit normal vector field on  $\delta M$ . If  $u \in C^2 \cap \operatorname{dom}(\overline{\Delta}_{\mu})$  then  $\frac{\partial u}{\partial \nu} = 0$  on  $\delta M$  and  $\Delta_{\mu} u = \overline{\Delta}_{\mu} u$ , so that  $\overline{\Delta}_{\mu}$  can be considered as an extension of  $\overline{\Delta}_{\mu}$  with Neumann boundary condition on  $\delta M$ .

A function *u* is called *harmonic* in *M* if  $u \in C^2(M)$ ,  $\Delta_{\mu}u = 0$  in  $M \setminus \delta M$  and  $\frac{\partial u}{\partial v} = 0$ on  $\delta M$ . We call a function  $u \in C^2(M)$  superharmonic if  $\Delta_{\mu}u \leq 0$  in  $M \setminus \delta M$  and  $\frac{\partial u}{\partial v} \geq 0$ on  $\delta M$ . A subharmonic function  $u \in C^2(M)$  satisfies the opposite inequalities.

The operator  $\overline{\Delta}_{\mu}$  generates the heat semi-group  $P_t := e^{t\overline{\Delta}_{\mu}}$  which possesses a positive smooth, symmetric kernel  $p_t(x, y)$ .

Let  $\Omega$  be an open subset of M and denote  $\delta \Omega := \delta M \cap \Omega$ . Then we can consider  $\Omega$  as a manifold with boundary  $\delta \Omega$ . Hence, using the same constructions as above for  $\Omega$  instead of M, we obtain the heat semigroup  $P_t^{\Omega}$  with the heat kernel  $p_t^{\Omega}(x, y)$ , which satisfies the Dirichlet boundary condition on  $\partial \Omega$  and the Neumann boundary condition on  $\delta \Omega$ .

**Definition** Let *M* be a complete non-compact manifold. Then we call  $\Omega$  an *end* of *M*, if  $\Omega$  is an open connected proper subset of *M* such that  $\overline{\Omega}$  is non-compact but  $\partial\Omega$  is compact (in particular, when  $\partial\Omega$  is a smooth closed hypersurface).

If  $\delta\Omega$  is nonempty, we will assume that  $\delta\Omega \cap \partial\Omega = \emptyset$ .

In many cases, the end  $\Omega$  can be considered as an exterior of a compact set of another manifold  $M_0$ , that means,  $\Omega$  is  $M_0 \setminus K_0$  for some compact set  $K_0 \subset M_0$ . If  $(M, \mu)$  and  $(M_0, \mu_0)$  are weighted manifolds, with  $\omega^2$  being the smooth density of measure  $\mu$  and the measure  $\mu_0$  having smooth density  $\omega_0^2$ , then, in particular, we have  $\omega_0 = \omega$  on  $\Omega$ .

**Definition** We say that a weighted manifold  $(M, \mu)$  is *parabolic* if any positive superharmonic function on M is constant, and *non-parabolic* otherwise.

**Definition** Let  $(M, \mu)$  be a weighted manifold and  $\Omega$  be a subset of M. Then we define *the volume function* of  $\Omega$ , for all  $x \in M$  and r > 0, by

$$V_{\Omega}(x,r) = \mu(B_{\Omega}(x,r)),$$

where  $B_{\Omega}(x, r) = B(x, r) \cap \Omega$ .

**Definition** Let  $(M, \mu)$  be a weighted manifold. We say that  $\Omega \subset M$  satisfies the *polynomial volume growth condition*, if there exist  $x_0 \in \Omega$  and  $r_0 > 0$  such that for all  $r \geq r_0$ ,

$$V_{\Omega}(x_0, r) \le C r^N, \tag{2.2}$$

where N and C are positive constants.

**Theorem 2.1** ([10], Theorem 8.3) *Let M be a complete non-compact manifold with end*  $\Omega$ . *Assume that*  $(\overline{\Omega}, \mu)$  *is a weighted manifold such that* 

- $(\overline{\Omega}, \mu)$  is non-parabolic as a manifold with boundary  $\partial \Omega \cup \delta \Omega$ .
- $\Omega$  satisfies the polynomial volume growth condition (2.2) with N > 2.

Then for any  $x \in \Omega$  there exist  $c_x > 0$  and  $t_x > 0$  such that for all  $t \ge t_x$ ,

$$p_t^{\Omega}(x, x) \ge \frac{c_x}{(t \log t)^{N/2}},$$
(2.3)

where  $c_x$  and  $t_x$  depend on x.

Consequently, if  $(M, \mu)$  is a complete non-compact weighted manifold with end  $\Omega$  such that the above conditions are satisfied, we have for any  $x \in M$  and all  $t \ge t_x$ ,

$$p_t(x,x) \ge \frac{c_x}{(t\log t)^{N/2}}.$$
 (2.4)

#### 2.1 h-transform

Recall that any smooth positive function *h* induces a new weighted manifold  $(M, \tilde{\mu})$ , where the measure  $\tilde{\mu}$  is defined by

$$d\widetilde{\mu} = h^2 d\mu = h^2 \omega^2 d \text{vol}$$
(2.5)

and we denote, for all r > 0 and  $x \in M$ , by  $\widetilde{V}(x, r)$  the volume function of measure  $\widetilde{\mu}$ . The Laplace operator  $\Delta_{\widetilde{\mu}}$  on  $(M, \widetilde{\mu})$  is then given by

$$\Delta_{\widetilde{\mu}}f = h^{-2}\operatorname{div}_{\mu}(h^{2}\nabla f) = (h\omega)^{-2}\operatorname{div}((h\omega)^{2}\nabla f).$$

**Lemma 2.2** ([16], Lemma 4.1) Assume that  $\Omega \subset M$  is open and  $\Delta_{\mu}h = 0$  in  $\Omega$ . Then for any smooth function f in  $\Omega$ , we have

$$\Delta_{\widetilde{\mu}} f = h^{-1} \Delta_{\mu} (hf). \tag{2.6}$$

**Lemma 2.3** ([16], Proposition 4.2) Assume that h is a harmonic function in an open set  $\Omega \subset M$ . Then the Dirichlet heat kernels  $p_t^{\Omega}$  and  $\tilde{p}_t^{\Omega}$  in  $\Omega$ , associated with the corresponding Laplace operators  $\Delta_{\mu}$  and  $\Delta_{\mu}$ , are related by

$$p_t^{\Omega}(x, y) = h(x)h(y)\widetilde{p}_t^{\Omega}(x, y), \qquad (2.7)$$

for all t > 0 and  $x, y \in \Omega$ .

*Remark* In particular, if we assume that h is harmonic in M, we get that the heat kernels are related by

$$\widetilde{p}_t(x, y) = \frac{p_t(x, y)}{h(x)h(y)}$$
(2.8)

for all t > 0 and  $x, y \in M$ .

**Definition** Let  $\Omega$  be an open set in M and K be a compact set in  $\Omega$ . Then we call the pair  $(K, \Omega)$  a *capacitor* and define the capacity cap $(K, \Omega)$  by

$$\operatorname{cap}(K,\Omega) = \inf_{\phi \in \mathcal{T}(K,\Omega)} \int_{\Omega} |\nabla \phi|^2 d\mu, \qquad (2.9)$$

where  $\mathcal{T}(K, \Omega)$  is the set of test functions defined by

$$\mathcal{T}(K,\Omega) = \{ \phi \in C_0^\infty(\Omega) : \phi|_K = 1 \}.$$

Let  $\Omega$  be precompact. Then it is known that the Dirichlet integral in Eq. 2.9 is minimized by a harmonic function  $\varphi$ , so that the infimum is attained by the weak solution to the Dirichlet problem in  $\Omega \setminus K$ :

$$\begin{cases} \Delta \varphi = 0\\ \varphi|_{\partial K} = 1\\ \varphi|_{\partial \Omega} = 0.\\ \frac{\partial \varphi}{\partial \nu}|_{\delta(\Omega \setminus K)} = 0 \end{cases}$$

The function  $\varphi$  is called the *equilibrium potential* of the capacitor  $(K, \Omega)$ .

We always have the following identity:

$$\operatorname{cap}(K,\Omega) = \int_{\Omega} |\nabla \varphi|^2 d\mu = \int_{\Omega \setminus K} |\nabla \varphi|^2 d\mu = -\operatorname{flux}(\varphi), \quad (2.10)$$

where  $flux(\varphi)$  is defined by

$$\mathrm{flux}(\varphi) := \int_{\partial W} \frac{\partial \varphi}{\partial \nu} d\mu',$$

where W is any open region in the domain of  $\varphi$  with smooth precompact boundary such that  $K \subset W$  and  $\nu$  is the outward normal unit vector field on  $\partial W$ . By the Green formula (2.1) and the harmonicity of  $\varphi$ , flux( $\varphi$ ) does not depend on the choice of W.

**Definition** We say that a compact set  $K \subset M$  has locally positive capacity, if there exists a precompact open set  $\Omega$  such that  $K \subset \Omega$  and  $cap(K, \Omega) > 0$ .

It is a consequence of the local Poincaré inequality, that if  $cap(K, \Omega) > 0$  for some precompact open  $\Omega$ , then this is true for all precompact open  $\Omega$  containing *K*.

**Lemma 2.4** Let  $(M, \mu)$  be a complete, non-compact weighted manifold and K be a compact set in M with locally positive capacity and smooth boundary  $\partial K$ . Fix some  $x_0 \in M$ and set  $B_r := B(x_0, r)$  for all r > 0 and assume that K is contained in a ball  $B_{r_0}$  for some  $r_0 > 0$ . Let us also set  $\Omega = M \setminus K$ , so that  $(\overline{\Omega}, \mu)$  becomes a weighted manifold with boundary. Then there exists a positive smooth function h in  $\overline{\Omega}$  that is harmonic in  $\Omega$  and satisfies for all  $r \ge r_0$ ,

$$\min_{AB} h \le C \operatorname{cap}(K, B_r)^{-1},$$
(2.11)

for some constant C > 0. Moreover, the weighted manifold  $(\overline{\Omega}, \widetilde{\mu})$  is non-parabolic, where measure  $\widetilde{\mu}$  on  $\overline{\Omega}$  is defined by Eq. 2.5.

*Proof* For any  $R > r_0$ , let  $\varphi_R$  be the equilibrium potential of the capacitor  $(K, B_R)$ . It follows from Eq. 2.10, that

$$\operatorname{cap}(K, B_R) = -\operatorname{flux}(\varphi_R). \tag{2.12}$$

Note that  $\partial \Omega = \partial K$ . By our assumption on K, we have for all  $R > r_0$ ,

$$\operatorname{cap}(K, B_R) > 0$$

whence we can consider the sequence

$$v_R = \frac{1 - \varphi_R}{\operatorname{cap}(K, B_R)}.$$

By Eq. 2.12 this sequence satisfies

$$flux(v_R) = 1. \tag{2.13}$$

Let us extend all  $v_R$  to K by setting  $v_R \equiv 0$  on K. We claim that for all  $R > r > r_0$ ,

$$\min_{\partial B_r} v_R \le \operatorname{cap}(K, B_r)^{-1}.$$
(2.14)

For  $R > r > r_0$ , denote  $m_r = \min_{\partial B_r} v_R$ . It follows from the minimum principle and the fact that  $v_R \equiv 0$  on K, that the set

$$U_r := \{x \in B_R : v_R(x) < m_r\}$$

is inside  $B_r$  and contains K. Then observe that the function  $1 - \frac{v_R}{m_r}$  is the equilibrium potential for the capacitor  $(K, U_r)$ , whence

$$\operatorname{cap}(K, B_r) \le \operatorname{cap}(K, U_r) = \operatorname{flux}\left(\frac{v_R}{m_r}\right) = \frac{1}{m_r},$$

which proves (2.14).

Since  $v_R$  vanishes on  $\partial \Omega$ , the maximum principle implies that, for all  $R > r > r_0$ ,

$$\sup_{B_r\setminus K} v_R = \max_{\partial B_r} v_R. \tag{2.15}$$

Hence, we obtain from Eq. 2.15, the local elliptic Harnack inequality, and Eq. 2.14, that for every  $R > r > r_0$ ,

$$\sup_{B_r \setminus K} v_R \le C(r) \min_{\partial B_r} v_R \le C(r) \operatorname{cap}(K, B_r)^{-1},$$
(2.16)

where the constant C(r) depends only on r. Let us choose an increasing sequence  $\{R_k\}$  such that  $R_k > r_0$  and  $R_k \to \infty$ . Then  $\{v_{R_k}\}$  is a sequence of non-negative harmonic functions that by Eq. 2.16 is uniformly bounded in  $\overline{B_r \setminus K}$  for each fixed r. By the local properties of harmonic functions, the sequence  $\{v_{R_k}\}$  is also equicontinuous in  $\overline{B_r \setminus K}$  and, hence, has a subsequence that converges uniformly in  $\overline{B_r \setminus K}$ . Using a standard diagonal process with  $r = r_l \to \infty$ , we obtain a subsequence of  $\{v_{R_k}\}$  that converges locally uniformly in  $\overline{\Omega}$ . Denoting the limit by v, we see that v is non-negative and continuous in  $\overline{\Omega}$ , harmonic in  $\Omega$ , and  $v|_{\partial\Omega} = 0$ . It follows that v is, in fact, smooth in  $\overline{\Omega}$ .

By renaming the sequence  $\{R_k\}$ , we can assume that  $v_{R_k} \to v$  as  $k \to \infty$ . By the local properties of convergence of harmonic functions, we have  $\nabla v_{R_k} \to \nabla v$  where the convergence is also locally uniform in  $\Omega$ . It follows that, for any  $r > r_0$ ,

$$\int_{\partial B_r} \frac{\partial v}{\partial \nu} d\mu' = \lim_{k \to \infty} \int_{\partial B_r} \frac{\partial v_{R_k}}{\partial \nu} d\mu',$$

which together with Eq. 2.13 implies

flux(v) = 1.

Let us define the function h = 1 + v so that h is smooth and positive in  $\overline{\Omega}$  and is harmonic in  $\Omega$ . It follows from Eq. 2.14, that for all  $r > r_0$ ,

$$\min_{\partial B_r} h \le 1 + \operatorname{cap}(K, B_r)^{-1} \le (1 + \operatorname{cap}(K, B_{r_0})) \operatorname{cap}(K, B_r)^{-1}$$

which proves (2.11) with  $C = 1 + \operatorname{cap}(K, B_{r_0})$ .

Let us now show that the weighted manifold  $(\Omega, \tilde{\mu})$  is non-parabolic. For that purpose, consider in  $\overline{\Omega}$  the positive smooth function  $w = \frac{1}{h}$ . Then we have by Lemma 2.2, that function w satisfies in  $\Omega$ ,

$$\Delta_{\widetilde{\mu}}(w) = \Delta_{\widetilde{\mu}}\left(\frac{1}{h}\right) = \frac{1}{h}\Delta_{\mu}1 = 0.$$

so that the function w is  $\Delta_{\tilde{\mu}}$ -harmonic in  $\Omega$ . Observe that

$$\frac{\partial w}{\partial v} = -\frac{\partial h}{\partial v} \frac{1}{h^2},\tag{2.17}$$

where v denotes the outward normal unit vector field on  $\partial\Omega$ . Since v is non-negative in  $\Omega$  and v = 0 on  $\partial\Omega$ , we have  $\frac{\partial h}{\partial v} \leq 0$  on  $\partial\Omega$ , whence we get by Eq. 2.17,

$$\frac{\partial w}{\partial \nu} \ge 0 \quad \text{on } \partial \Omega.$$

Hence, we conclude that w is  $\Delta_{\tilde{\mu}}$ -superharmonic in  $\overline{\Omega}$ , positive and non-constant, which implies that  $(\overline{\Omega}, \tilde{\mu})$  is non-parabolic.

*Remark* Note that the function *h* constructed in Lemma 2.4 is  $\Delta_{\mu}$ -subharmonic in  $\overline{\Omega}$ . If we assume that the weighted manifold  $(\overline{\Omega}, \mu)$  is parabolic, we obtain that *h* is unbounded since a non-constant bounded subharmonic function can only exist on non-parabolic manifolds.

## 2.2 Locally Harnack Case

**Definition** The weighted manifold  $(M, \mu)$  is said to be a *locally Harnack manifold* if there is  $\rho > 0$ , called the *Harnack radius*, such that for any point  $x \in M$  the following is true:

(1) for any positive numbers  $r < R < \rho$ 

$$\frac{V(x,R)}{V(x,r)} \le a \left(\frac{R}{r}\right)^n \tag{2.18}$$

(2) Poincaré inequality: for any Lipschitz function f in the ball B(x, R) of a radius  $R < \rho$  we have

$$\int_{B(x,R)} |\nabla f|^2 d\mu \ge \frac{b}{R^2} \int_{B(x,R/2)} (f-\overline{f})^2 d\mu, \qquad (2.19)$$

where we denote

$$\overline{f} := \int_{B(x,R/2)} f d\mu := \frac{1}{V(x,R/2)} \int_{B(x,R/2)} f d\mu$$

and a, b and n are positive constants and V(x, r) denotes the volume function of  $(M, \mu)$ .

For example, the conditions (1) and (2) are true in the case when the manifold *M* has Ricci curvature bounded below by a (negative) constant  $-\kappa$  (see [3]).

**Definition** For any open set  $\Omega \subset M$ , define

$$\lambda_1(\Omega) = \inf_u \frac{\int_{\Omega} |\nabla u|^2 d\mu}{\int_{\Omega} u^2 d\mu},$$
(2.20)

where the infimum is taken over all nonzero Lipschitz functions u compactly supported in  $\Omega$ .

**Lemma 2.5** ([11], Theorem 2.1) *Let*  $(M, \mu)$  *be a locally Harnack manifold. Then we have, for any precompact open set*  $U \subset M$ ,

$$\lambda_1(U) \ge \frac{c}{\rho^2} \min\left(\left(\frac{V_0}{\mu(U)}\right)^2, \left(\frac{V_0}{\mu(U)}\right)^{2/n}\right),\tag{2.21}$$

where

$$V_0 = \inf_{x \in M} \{ V(x, \rho) : B(x, \rho) \cap U \neq \emptyset \}$$

and the constant c depends on a, b, n from Eqs. 2.18 and 2.19.

**Definition** We say that a manifold *M* satisfies the *spherical Harnack inequality* if there exist  $x_0 \in M$  and constants  $r_0 > 0$ ,  $C_H > 0$ ,  $N_H > 0$  and A > 1, so that for any positive harmonic function *u* in  $M \setminus \overline{B(x_0, A^{-1}r)}$  with  $r \ge r_0$ ,

$$\sup_{\partial B(x_0,r)} u \le C_H r^{N_H} \inf_{\partial B(x_0,r)} u.$$
(2.22)

**Assumption** In this section, when considering an end  $\Omega$  of a complete non-compact weighted manifold  $(M, \mu)$ , we always assume that there exists a complete weighted manifold  $(M_0, \mu_0)$  and a compact set  $K_0 \subset M_0$  that is the closure of a non-empty open set, such that  $\Omega$  is  $M_0 \setminus K_0$  in the sense of weighted manifolds. For simplicity and since we only use the intrinsic geometry of  $M_0$ , we denote by B(x, r) the geodesic balls in  $M_0$  and by V(x, r) the volume function of  $M_0$ .

**Theorem 2.6** Let  $\Omega$  be an end of a complete non-compact weighted manifold  $(M, \mu)$ . Assume that  $M_0$  is a locally Harnack manifold with Harnack radius  $\rho > 0$ , where  $M_0$  is defined as above, and that there exists  $x_0 \in M_0$  so that

- *M*<sup>0</sup> satisfies the spherical Harnack inequality (2.22).
- *M*<sup>0</sup> satisfies the polynomial volume growth condition (2.2).
- There are constants  $v_0 > 0$  and  $\theta \ge 0$  so that for any  $x \in M_0$ , if  $d(x, x_0) \le R$  for some  $R > \rho$ , it holds that

$$V(x,\rho) \ge v_0 R^{-\theta}.$$
(2.23)

Then, for any  $x \in M$ , there exist  $\alpha > 0$ ,  $t_x > 0$  and  $c_x > 0$  such that for all  $t \ge t_x$ ,

$$p_t(x,x) \ge \frac{c_x}{t^{\alpha}},\tag{2.24}$$

where  $\alpha = \alpha(N, \theta, n, N_H)$  and n is as in Eq. 2.18.

*Proof* Let us set  $B_r = B(x_0, r)$  and  $V(r) = V(x_0, r)$  and  $K_0$  be contained in a ball  $B_{\delta}$  for some  $\delta > 0$ . It follows from [20, Theorem 2.25] that  $K_0$  has locally positive capacity. Then by Lemma 2.4 there exists a positive smooth function h in  $\overline{\Omega}$  that is harmonic in  $\Omega$  and such that the weighted manifold  $(\overline{\Omega}, \widetilde{\mu})$  is non-parabolic, where measure  $\widetilde{\mu}$  is defined by Eq. 2.5. Now, our aim is to apply the estimate (2.3) in Theorem 2.1 to the weighted manifold  $(\overline{\Omega}, \widetilde{\mu})$ . For that purpose, it is sufficient to show that there are positive constants  $\widetilde{r_0}, \widetilde{C}$  and  $\widetilde{N} > 2$ such that for all  $r \ge \widetilde{r_0}$ ,

$$\widetilde{V}_{\Omega}(r) = \int_{B_r \cap \Omega} h^2 d\mu \le \widetilde{C} r^{\widetilde{N}}.$$
(2.25)

Firstly, by Eq. 2.11, there is a constant  $C_{\delta} > 0$  such that for all  $r \ge \delta$ ,

$$\min_{\partial B_r} h \le C_{\delta} \operatorname{cap}(K_0, B_r)^{-1}.$$
(2.26)

As *h* is harmonic in  $M_0 \setminus \overline{B_\delta}$ , the hypothesis (2.22) implies that there exists a constant  $C_H > 0$ , so that for every  $r \ge \max(r_0, A\delta)$ ,

$$\max_{\partial B_r} h \le C_H r^{N_H} \min_{\partial B_r} h.$$

Combining this with Eq. 2.26, we obtain for all  $r \ge \max(r_0, A\delta)$  with  $C_0 = C_H C_{\delta}$ ,

$$\max_{\partial B_r} h \le C_0 r^{N_H} \operatorname{cap}(K_0, B_r)^{-1}.$$
(2.27)

For any  $r \ge \delta$ , let  $\varphi_r$  be the equilibrium potential of the capacitor  $(K_0, B_r)$ . Since

$$\int_{B_r} |\nabla \varphi_r|^2 d\mu_0 = \operatorname{cap}(K_0, B_r)$$

and

$$\int_{B_r} \varphi_r^2 d\mu_0 \ge \mu_0(K_0).$$

we obtain

$$\lambda_1(B_r) \leq \frac{\int_{B_r} |\nabla \varphi_r|^2 d\mu_0}{\int_{B_r} \varphi_r^2 d\mu_0} \leq \frac{\operatorname{cap}(K_0, B_r)}{\mu(K_0)}$$

whence, together with Eq. 2.27, we deduce

$$\max_{\partial B_r} h \le C_0 \mu(K_0)^{-1} r^{N_H} \lambda_1(B_r)^{-1}.$$
(2.28)

Since  $M_0$  is a locally Harnack manifold, we can apply Lemma 2.5 and obtain from Eq. 2.21, that for all  $r \ge \delta$ ,

$$\lambda_1(B_r) \ge \frac{c}{\rho^2} \min\left(\left(\frac{V_0}{V(r)}\right)^2, \left(\frac{V_0}{V(r)}\right)^{2/n}\right),\tag{2.29}$$

where

$$V_0 = \inf_{x \in M_0} \{ V(x, \rho) : B(x, \rho) \cap B_r \neq \emptyset \}.$$

Note that the condition  $B(x, \rho) \cap B_r \neq \emptyset$  implies that  $d(x_0, x) \leq r + \rho$ . Thus, we obtain from the hypothesis (2.23), assuming  $r \geq \rho$ ,

$$V(x,\rho) \ge v_0(r+\rho)^{-\theta} \ge v_0 2^{-\theta} r^{-\theta}.$$

Therefore, we have for all  $r \ge \rho$ ,

$$V_0 \ge C_\theta r^{-\theta}$$

with  $C_{\theta} = v_0 2^{-\theta}$ . Hence, using the polynomial volume growth condition (2.2), we obtain from Eq. 2.29, that for all  $r \ge \max(r_0, \rho, A\delta)$ ,

$$\lambda_1(B_r) \ge C_1 \min\left(r^{-2(N+\theta)}, r^{-2(N+\theta)/n}\right),$$

where

$$C_1 = \frac{c}{\rho^2} \min\left(\left(\frac{C_\theta}{C}\right)^2, \left(\frac{C_\theta}{C}\right)^{2/n}\right),$$

so that by setting

$$\beta = 2 \max\left(N + \theta, \frac{N + \theta}{n}\right), \qquad (2.30)$$

we deduce for  $r \ge \max(r_0, \rho, A\delta, 1)$ ,

$$\lambda_1(B_r) \ge C_1 r^{-\beta}$$

Combining this with Eq. 2.28, we obtain for every  $r \ge \max(r_0, \rho, A\delta, 1)$ ,

$$\max_{\partial B_r} h \le C_2 r^{\beta + N_H},\tag{2.31}$$

where

$$C_2 = C_0 C_1^{-1} \mu_0 (K_0)^{-1}$$

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Hence, Eq. 2.31, the polynomial volume growth condition (2.2) and the maximum principle imply that for all  $r \ge \max(r_0, \rho, A\delta, 1)$ ,

$$\widetilde{V}_{\Omega}(r) = \int_{B_r \cap \Omega} h^2 d\mu \le V(r) \max_{\partial B_r} h^2 \le C_2^2 C r^{N+2(\beta+N_H)},$$

which proves (2.25) with  $\tilde{r}_0 = \max(r_0, \rho, A\delta, 1)$ ,  $\tilde{N} = 2(\beta + N_H) + N$  and  $\tilde{C} = C_2^2 C$ , and implies that the weighted manifold  $(\Omega, \tilde{\mu})$  has polynomial volume growth. Thus, the hypotheses of Theorem 2.1 are fulfilled and we obtain by Eq. 2.3, that for any  $x \in \Omega$ , there exist  $\tilde{t}_x > 0$  and  $\tilde{c}_x > 0$ , such that for all  $t \ge \tilde{t}_x$ ,

$$\widetilde{p}_t^{\Omega}(x,x) \ge \frac{\widetilde{c}_x}{(t\log t)^{\beta+N_H+N/2}},$$

where  $\beta$  is defined by Eq. 2.30. Since *h* is harmonic in  $\Omega$ , we therefore conclude by Eq. 2.7 that for any  $x \in \Omega$  and all  $t \ge \tilde{t}_x$ ,

$$p_t^{\Omega}(x,x) = h^2(x)\widetilde{p}_t^{\Omega}(x,x) \ge \frac{\widetilde{c}_x h^2(x)}{(t\log t)^{\beta+N_H+N/2}},$$

which yields (2.24) for all  $x \in M$  by using  $p_t^{\Omega} \leq p_t$  and by means of a local parabolic Harnack inequality (cf. [21])

*Remark* Note that it follows from the non-parabolicity of  $(\overline{\Omega}, \widetilde{\mu})$ , that  $4 \max(N + \theta, \frac{N+\theta}{n}) + 2N_H + N > 2$ .

### 2.3 End with Relatively Connected Annuli

**Definition** We say that a manifold M with fixed point  $x_0 \in M$  satisfies the relatively connected annuli condition (RCA) if there exists A > 1 such that, for any  $r > A^2$  and all x, y with  $d(x_0, x) = d(x_0, y) = r$ , there exists a continuous path  $\gamma : [0, 1] \to M$  with  $\gamma(0) = x$  and  $\gamma(1) = y$ , whose image is contained in  $B(x_0, Ar) \setminus B(x_0, A^{-1}r)$ .

*Remark* Note that, even though the condition (RCA) is formulated for the specific point  $x_0$ , it is equivalent to the (RCA) condition with respect to any other point  $x_1$  with possibly a different constant *A*.

*Example* Any *Riemannian model with a pole* (see Section 2.4) with dimension  $n \ge 2$  has relatively connected annuli.

**Corollary 2.7** Let  $\Omega$  be an end of a complete non-compact weighted manifold  $(M, \mu)$  and assume that  $M_0$  is a locally Harnack manifold with Harnack radius  $\rho > 0$ , where  $M_0$  is defined as above. Also assume that there exists  $x_0 \in M_0$  so that

- $M_0$  satisfies (RCA) with some constant A > 1.
- There exist constants L > 0 and C > 0 so that for all  $r \ge L$ ,

$$V(Ar) - V(A^{-1}r) \le C \log r,$$
 (2.32)

where we denote  $V(r) = V(x_0, r)$ .

• There exists a constant  $v_0 > 0$  such that for any  $y \in M_0$ ,

$$V(y, \rho/3) \ge v_0.$$
 (2.33)

Then, for any  $x \in M$ , there exist  $\alpha > 0$ ,  $t_x > 0$  and  $c_x > 0$  such that for all  $t \ge t_x$ ,

$$p_t(x,x) \ge \frac{c_x}{t^{\alpha}},$$

where  $\alpha = \alpha(n, v_0, \rho, C)$ .

*Proof* As before, we denote  $B_r = B(x_0, r)$ . Obviously, the hypothesis (2.33) implies the condition (2.23) with  $\theta = 0$ . Hence, to apply Theorem 2.6, it remains to show that  $M_0$  has polynomial volume growth as in Eq. 2.2 and  $M_0$  satisfies the spherical Harnack inequality (2.22). The polynomial volume growth condition (2.2) follows from Eq. 2.32.

Let us now prove that the spherical Harnack inequality (2.22) holds in  $M_0$ . Assume that  $r \ge L$  and cover the set  $B_{Ar} \setminus B_{A^{-1}r}$ , with balls  $B(x_i, \rho/3)$  where  $x_i \in M_0$  and A > 1 is as in (RCA). By applying a standard covering argument, there exists a number  $\tau(r)$  and a subsequence of disjoint balls  $\{B(x_{i_k}, \rho/3)\}_{k=1}^{\tau(r)}$  such that the union of the balls  $\{B(x_{i_k}, \rho)\}_{k=1}^{\tau(r)}$  cover the set  $B_{Ar} \setminus B_{A^{-1}r}$ . Hence, it follows from Eq. 2.32, that

$$\sum_{i=1}^{\tau(r)} V(x_i, \rho/3) \le V(Ar) - V(A^{-1}r) \le C \log r.$$
(2.34)

Then the hypothesis (2.33), combined with Eq. 2.34, implies that

$$\tau(r) \le \frac{C\log r}{v_0}.\tag{2.35}$$

For all  $r > A^2$ , let  $y_1$ ,  $y_2$  be two points on  $\partial B_r$  and  $\gamma$  be a continuous path connecting them in  $B_{Ar} \setminus B_{A^{-1}r}$  as it is ensured by (RCA). Now select out of the sequence  $\{B(x_{i_k}, \rho)\}_{k=1}^{\tau(r)}$ those balls that intersect  $\gamma$ . In this way, we obtain a chain of at most  $\tau(r)$  balls, which connect  $y_1$  and  $y_2$ . Now let u be a positive harmonic function in  $M_0 \setminus \overline{B_{A_0^{-1}r}}$ , where  $A_0 \ge A$ is such that any ball of this chain lies in  $M_0 \setminus \overline{B_{A_0^{-1}r}}$  for all  $1 \le i \le \tau(r)$  and  $r > A_0^2$ . Applying the local elliptic Harnack inequality to u repeatedly in the balls of this chain and letting  $y_1$ ,  $y_2$  such that  $\min_{\partial B_r} u = u(y_1)$  and  $\max_{\partial B_r} u = u(y_2)$ , we obtain

$$\max_{\partial B_r} u = u(y_2) \le (C_\rho)^{\tau} u(y_1) = (C_\rho)^{\tau} \min_{\partial B_r} u,$$

where  $C_{\rho}$  is the Harnack constant in all  $B(x_{i_k}, \rho)$ . Together with Eq. 2.35, this yields

$$\max_{\partial B_r} u \le r^{\frac{c}{v_0} \log C_{\rho}} \min_{\partial B_r} u$$

which proves the spherical Harnack inequality (2.22) with  $N_H = \frac{C}{v_0} \log C_{\rho}$ . Thus the hypotheses of Theorem 2.6 are fulfilled and we obtain from Eq. 2.24, that for any  $x \in M$ , there exist  $t_x > 0$ ,  $c_x > 0$  and  $\alpha > 0$  such that for all  $t \ge t_x$ ,

$$p_t(x,x) \ge \frac{c_x}{t^{\alpha}},$$

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where  $\alpha = \alpha(n, N_H)$ , which finishes the proof.

**Definition** As usual, for any piecewise  $C^1$  path  $\gamma : I \to M$ , where *I* is an interval in  $\mathbb{R}$ , denote by  $l(\gamma)$  the length of  $\gamma$  defined by

$$l(\gamma) = \int_{I} |\dot{\gamma}(t)| dt,$$

where  $\dot{\gamma}$  is the velocity of  $\gamma$ , given by  $\dot{\gamma}(t)(f) = \frac{d}{dt} f(\gamma(t))$  for any  $f \in C^{\infty}(M)$ .

**Corollary 2.8** Let  $\Omega$  be an end of a complete non-compact weighted manifold  $(M, \mu)$  and assume that for some  $\kappa \geq 0$ , we have

$$Ric(M_0) \ge -\kappa, \tag{2.36}$$

where  $M_0$  is defined as above. Suppose that there exists  $x_0 \in M_0$  so that

•  $M_0$  satisfies (RCA) with A > 1 and piecewise  $C^1$  path  $\gamma$  so that there is some constant c > 0 such that for all  $r > A^2$ ,

$$l(\gamma) \le c \log r. \tag{2.37}$$

• There are constants  $v_0 > 0$  and  $\theta \ge 0$  so that for any  $y \in M_0$ , if  $d(y, x_0) \le R$  for some R > 1, it holds that

$$V(y,\rho) \ge v_0 R^{-t}$$

Then, for any  $x \in M$ , there exist  $\alpha > 0$ ,  $t_x > 0$  and  $c_x > 0$  such that for all  $t \ge t_x$ ,

$$p_t(x,x) \ge \frac{c_x}{t^{\alpha}}$$

where  $\alpha = \alpha(c, \theta, \kappa)$ .

*Proof* The assumption (2.36) implies that  $M_0$  is a locally Harnack manifold. Hence we are left to show that  $M_0$  has polynomial volume growth as in Eq. 2.2 and satisfies the spherical Harnack inequality (2.22) to apply Theorem 2.6. Again we denote  $B_r = B(x_0, r)$  and  $V(r) = V(x_0, r)$ . By the Bishop-Gromov theorem, the hypothesis (2.36) implies that there exists a constant  $C_{\kappa} > 1$ , so that for any  $y \in M_0$  and R > 1,

$$V(v, R) < e^{C_{\kappa}R}$$

Together with the assumption (2.37), this yields that the polynomial volume growth condition (2.2) holds in  $M_0$ .

Let us now show that  $M_0$  satisfies the spherical Harnack inequality (2.22). Let A > 1 be as above and assume that  $r > A^2$ . Fix two points  $y_1$ ,  $y_2$  on  $\partial B_r$  and let  $\gamma$  be a continuous path connecting them in  $B_{Ar} \setminus B_{A^{-1}r}$  as is it ensured by (RCA). Then cover the path  $\gamma$  with balls  $\{B(x_i, \rho)\}_{i=1}^{\tau(r)}$ , where  $x_i \in M_0$  and  $\rho > 0$ . Now let u be a positive harmonic function in  $M_0 \setminus \overline{B_{A_0^{-1}r}}$ , where  $A_0 \ge A$  is such that  $B(x_i, \rho) \subset M_0 \setminus \overline{B_{A_0^{-1}r}}$  for all  $1 \le i \le \tau(r)$  and  $r > A_0^2$ . In this way, we obtain a chain of at most  $\tau(r)$  balls  $B(x_i, \rho)$ , which connect  $y_1$  and  $y_2$ . By Eq. 2.37, we deduce that

$$\tau(r) \le \frac{c}{\rho} \log(r). \tag{2.38}$$

Applying the local elliptic Harnack inequality to *u* repeatedly in the balls of this chain and letting  $y_1$ ,  $y_2$  such that  $\min_{\partial B_r} u = u(y_1)$  and  $\max_{\partial B_r} u = u(y_2)$ , we obtain

$$\max_{\partial B_r} u = u(y_2) \le (C_{\rho})^{\tau} u(y_1) = (C_{\rho})^{\tau} \min_{\partial B_r} u$$

where  $C_{\rho}$  is the Harnack constant in all  $B(x_i, \rho)$ . Together with Eq. 2.38, this yields

$$\max_{\partial B_r} u \leq r^{\frac{c}{\rho} \log C_{\rho}} \min_{\partial B_r} u,$$

which proves (2.22) with  $N_H = \frac{c}{\rho} \log C_{\rho}$ . Thus the hypotheses of Theorem 2.6 are fulfilled and we obtain by Eq. 2.24, that for any  $x \in M$ , there exist  $t_x > 0$ ,  $c_x > 0$  and  $\alpha > 0$  such that for all  $t \ge t_x$ ,

$$p_t(x,x) \ge \frac{c_x}{t^{\alpha}},$$

which finishes the proof.

#### 2.4 An Example in Dimension Two

Consider the topological space  $M = (0, +\infty) \times \mathbb{S}^1$ , that is, any point  $x \in M$  can be represented in the polar coordinates  $x = (r, \theta)$  with r > 0 and  $\theta \in \mathbb{S}^1$ . Equip M with the Riemannian metric  $ds^2$  given by

$$ds^2 = dr^2 + \psi^2(r)d\theta^2,$$

where  $\psi(r)$  is a smooth positive function on  $(0, +\infty)$  and  $d\theta^2$  is the normalized Riemannian metric on  $\mathbb{S}^1$ . In this case, *M* is called a *two-dimensional Riemannian model with a pole*.

*Remark* A sufficient and necessary condition, for the existence of this manifold is that  $\psi$  satisfies the conditions  $\psi(0) = 0$  and  $\psi'(0) = 1$ . This ensures that the metric  $ds^2$  can be smoothly extended to the origin r = 0 (see [9]).

We define the area function *S* on  $(0, +\infty)$  by

$$S(r) = \psi(r)$$

**Proposition 2.9** Let M be a two-dimensional Riemannian model with a pole. Suppose that for any A > 1, there exists a constant c > 0, so that for all large enough r,

$$\sup_{t \in (A^{-1}r,Ar)} \frac{S''_{+}(t)}{S(t)} \le c \frac{S''_{+}(r)}{S(r)}.$$
(2.39)

Also assume that there exists a constant N > 0 such that, for every large enough r,

$$\frac{S(r)}{r} + \sqrt{S_{+}''(r)S(r)} \le N\log(r).$$
(2.40)

Then the spherical Harnack inequality (2.22) holds in M.

*Proof* Fix some  $x_0 \in M$  and denote  $B_r = B(x_0, r)$ . Since any model manifold of dimension  $n \ge 2$  satisfies the (RCA) condition, there exists  $A_0 > 1$  such that for all  $r > A_0^2$  and any  $x_1, x_2 \in \partial B_r$ , there exists T > 0 and a continuous path  $\gamma : [0, T] \to M$  such that  $\gamma(0) = x_1$  and  $\gamma(T) = x_2$ , whose image is contained in  $B_{A_0r} \setminus B_{A_0^{-1}r}$ . Let us choose  $A > A_0$  so that there exists a constant  $\epsilon > 0$ , such that  $B(x, R) \subset B_{Ar} \setminus \overline{B_{A^{-1}r}}$ , for any  $x \in \gamma([0, T])$ , where  $R = \epsilon r$ . Let u be a positive harmonic function in  $M \setminus B_{A^{-1}r}$  and  $x_1, x_2 \in \partial B_r$  such that  $\max_{\partial B_r} u = u(x_1)$  and  $\min_{\partial B_r} u = u(x_2)$ . Thus, we have to show that there are constants  $N_H > 0$  and  $C_H > 0$ , so that if r is large enough, then

$$u(x_1) \le C_H r^{N_H} u(x_2). \tag{2.41}$$

Let  $x \in \gamma([0, T])$ . Recall from [15, Exercise 3.31], that the Ricci curvature *Ric* on *M* is given by

$$Ric = -\frac{S''}{S}.$$
 (2.42)

Hence, we obtain from Eq. 2.42,

$$Ric(x) \ge \inf_{t \in (A^{-1}r, Ar)} \left( -\frac{S''(t)}{S(t)} \right) \ge -\sup_{t \in (A^{-1}r, Ar)} \left( \frac{S''_+(t)}{S(t)} \right).$$

By Eq. 2.39, we get, assuming that r is large enough,

$$Ric(x) \ge -c \frac{S''_{+}(r)}{S(r)} =: -\kappa(r).$$
 (2.43)

Clearly, we can assume that  $|\gamma'(t)| = 1$ . We have

$$\int_0^T \frac{|\nabla u(\gamma(t))|}{u(\gamma(t))} dt \le \sup_{0 \le t \le T} \frac{|\nabla u(\gamma(t))|}{u(\gamma(t))} \int_0^T dt \le \sup_{0 \le t \le T} \frac{|\nabla u(\gamma(t))|}{u(\gamma(t))} d(x_1, x_2).$$

Again, since *M* has dimension n = 2, and as  $x_1, x_2 \in \partial B_r$ , we see that

$$d(x_1, x_2) \le S(r)$$

whence

$$\int_0^T \frac{|\nabla u(\gamma(t))|}{u(\gamma(t))} dt \le \sup_{0 \le t \le T} \frac{|\nabla u(\gamma(t))|}{u(\gamma(t))} S(r).$$

Applying the well-known gradient estimate (cf. [6]) to the harmonic function u in all balls B(x, R), we obtain,

$$\sup_{0 \le t \le T} \frac{|\nabla u(\gamma(t))|}{u(\gamma(t))} \le C_n \left(\frac{1 + R\sqrt{\kappa(r)}}{R}\right).$$

where  $\kappa(r)$  is given by Eq. 2.43 and  $C_n > 0$  is a constant depending only on *n*. Therefore, we deduce

$$\begin{split} \log u(x_1) - \log u(x_2) &= \left| \int_0^T \frac{d \log u(\gamma(t))}{dt} \right| \le \int_0^T \frac{|d u(\gamma(t))|}{u(\gamma(t))} \\ &= \int_0^T \frac{|\langle \nabla u, \gamma'(t) \rangle|}{u(\gamma(t))} dt \\ &\le \int_0^T \frac{|\nabla u(\gamma(t))|}{u(\gamma(t))} dt \\ &\le C_n \left( \frac{1}{\epsilon r} + \sqrt{\kappa(r)} \right) S(r), \end{split}$$

which is equivalent to

$$u(x_1) \le \exp\left(C_n\left(\frac{S(r)}{\epsilon r} + S(r)\sqrt{\kappa(r)}\right)\right)u(x_2)$$

Hence, we get by Eq. 2.43,

$$u(x_1) \le \exp\left(C_n\left(\frac{S(r)}{\epsilon r} + \sqrt{cS''_+(r)S(r)}\right)\right)u(x_2).$$

Finally, by Eq. 2.40, we deduce for large enough r,

$$u(x_1) \leq r^{C_n \max\left\{\sqrt{c}, \frac{1}{\epsilon}\right\}N} u(x_2),$$

which proves (2.41) with  $C_H = 1$  and  $N_H = C_n \max\left\{\sqrt{c}, \frac{1}{\epsilon}\right\} N$  and finishes the proof.

*Example* Let  $(M, \mu)$  be a two-dimensional weighted manifold with end  $\Omega$  and, following the notation in Theorem 2.6, suppose that  $M_0$  is a Riemannian model with a pole such that

$$S_0(r) = \begin{cases} r \log r, \ r \ge 2\\ r, \ r \le 1. \end{cases}$$

Let us show that  $M_0$  satisfies the hypotheses of Theorem 2.6 so that for any  $x \in M$ , there exist  $t_x > 0$ ,  $c_x > 0$  and  $\alpha > 0$  such that for all  $t \ge t_x$ ,

$$p_t(x,x) \ge \frac{c_x}{t^{\alpha}}.$$
(2.44)

Since  $S_0''(r) = \frac{1}{r}$  for  $r \ge 2$ , the inequality (2.39) is satisfied and also

$$\frac{S_0(r)}{r} + \sqrt{\max\{(S_0'')(r), 0\}S_0(r)} = \log r + \sqrt{\log r} \le 2\log r,$$

whence (2.40) holds and we get that  $M_0$  satisfies the spherical Harnack inequality (2.22). On the other hand, we have for  $r \ge 2$ ,  $-\frac{S_0''(r)}{S_0(r)} = -\frac{1}{r^2 \log r}$  so that it follows from Eq. 2.42 that  $M_0$  has non-positive bounded below sectional curvature. Hence,  $M_0$  is a locally Harnack manifold and, as it is simply connected, is a Cartan-Hadamard manifold which yields that the balls in  $M_0$  of have at least euclidean volume. Therefore, condition (2.23) holds as well and we conclude from Theorem 2.6 that  $(M, \mu)$  admits the estimate (2.44).

## **3** Isoperimetric Inequalities for Warped Products

**Definition** For any Borel set  $A \subset M$ , define its perimeter  $\mu^+(A)$  by

$$\mu^{+}(A) = \liminf_{r \to 0^{+}} \frac{\mu(A^{r}) - \mu(A)}{r},$$

where  $A^r$  is the *r*-neighborhood of A with respect to the Riemannian metric of M.

**Definition** We say that  $(M, \mu)$  admits the *lower isoperimetric function* J if, for any precompact open set  $U \subset M$  with smooth boundary,

$$\mu^+(U) \ge J(\mu(U)).$$
 (3.1)

For example, the euclidean space  $\mathbb{R}^n$  with the Lebesgue measure satisfies the inequality in Eq. 3.1 with the function  $J(v) = c_n v^{\frac{n-1}{n}}$ .

#### 3.1 Setting and Main Theorem

Let  $(M_1, \mu_1)$  and  $(M_2, \mu_2)$  be weighted manifolds and let  $M = M_1 \times M_2$  be the direct product of  $M_1$  and  $M_2$  as topological spaces. This means that any point  $z \in M$  can be written as z = (x, y) with  $x \in M_1$  and  $y \in M_2$ . Then we define the Riemannian metric  $ds^2$  on M by

$$ds^{2} = dx^{2} + \psi^{2}(x)dy^{2}, \qquad (3.2)$$

where  $\psi$  is a smooth positive function on  $M_1$  and  $dx^2$  and  $dy^2$  denote the Riemannian metrics on  $M_1$  and  $M_2$ , respectively. Let us define the measure  $\mu$  on M by

$$\mu = \mu_1 \times \mu_2 \tag{3.3}$$

and note that then  $(M, \mu)$  becomes a weighted manifold with respect to the metric in Eq. 3.2 (see Section 3.2 for an example).

Denote by  $\nabla$  the gradient on M and with  $\nabla_x$  and  $\nabla_y$  the gradients on  $M_1$  and  $M_2$ , respectively. It follows from Eq. 3.2, that we have the identity

$$|\nabla u|^{2} = |\nabla_{x}u|^{2} + \frac{1}{\psi^{2}(x)}|\nabla_{y}u|^{2}, \qquad (3.4)$$

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for any smooth function *u* on *M*.

**Definition** Let  $\varphi : (0, +\infty) \to (0, +\infty)$  be a monotone decreasing function. Then we define the generalized inverse function  $\phi$  of  $\varphi$  on  $(0, +\infty)$  by

$$\phi(s) = \sup\{t > 0 : \varphi(t) > s\}.$$
(3.5)

We will use the convention that the supremum of the empty set is zero. One can easily prove the following

**Lemma 3.1** The generalized inverse  $\phi$  of  $\phi$  has the following properties:

- (1)  $\phi$  is monotone decreasing, right continuous and  $\lim_{s\to\infty} \phi(s) = 0$ ;
- (2)  $\varphi$  is right continuous if and only if  $\varphi$  itself is the generalized function of  $\varphi$ , that is

$$\varphi(t) = \sup\{s > 0 : \phi(s) > t\};$$
(3.6)

(3) we have the identity

$$\int_0^\infty \varphi(t)dt = \int_0^\infty \phi(s)ds.$$
(3.7)

The following lemma is well-known.

**Lemma 3.2** Let U be a precompact open subset of a weighted manifold  $(M, \mu)$  with smooth boundary. Then

$$u^+(U) = \inf_{\{u_n\}} \limsup_{n \to \infty} \int_M |\nabla u_n| d\mu = \sup_{\{u_n\}} \liminf_{n \to \infty} \int_M |\nabla u_n| d\mu,$$

where  $\{u_n\}_{n \in \mathbb{M}}$  is a monotone increasing sequence of smooth non-negative functions with compact support, converging pointwise to the characteristic function of the set U.

The proof of the following theorem follows the ideas of Theorem 1 in [19], where an isoperimetric inequality is obtained for Riemannian products  $M = M_1 \times M_2$  of two Riemannian manifolds  $M_1$  and  $M_2$ .

**Theorem 3.3** Let  $(M_1, \mu_1)$  and  $(M_2, \mu_2)$  be weighted manifolds and let the weighted manifold  $(M, \mu)$  be defined as above, that is, the Riemannian metric on M is defined by Eq. 3.2 and measure  $\mu$  is defined by Eq. 3.3. Assume that there exists a constant  $C_0 > 0$ , such that for all  $x \in M_1$ ,

$$\psi(x) \le C_0. \tag{3.8}$$

Suppose that  $(M_1, \mu_1)$  and  $(M_2, \mu_2)$  have the lower isoperimetric functions  $J_1$  and  $J_2$ , which are continuous on the intervals  $(0, \mu_1(M_1))$  and  $(0, \mu_2(M_2))$ , respectively. Then  $(M, \mu)$  admits the lower isoperimetric function J, defined by

$$J(v) = c \inf_{\varphi,\phi} \left( \int_0^\infty J_1(\varphi(t)) dt + \int_0^\infty J_2(\phi(s)) ds. \right),$$

where  $c = \frac{1}{2} \min \left\{ 1, \frac{1}{C_0} \right\}$  and  $\varphi$  and  $\phi$  are generalized mutually inverse functions such that

$$\varphi \le \mu_1(M_1), \quad \phi \le \mu_2(M_2), \tag{3.9}$$

and

$$v = \int_0^\infty \varphi(t)dt = \int_0^\infty \phi(s)ds.$$
(3.10)

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*Proof* Let U be an open precompact set in M with smooth boundary such that  $\mu(U) = v$ . Let us define the function

$$I(v) = \inf_{\varphi,\phi} \left( \int_0^\infty J_1(\varphi(t))dt + \int_0^\infty J_2(\phi(s))ds. \right),$$
(3.11)

where  $\varphi$  and  $\phi$  are generalized mutually inverse functions satisfying (3.9) and (3.10). We need to prove that

$$\mu^+(U) \ge cI(v),$$

where *I* is defined by Eq. 3.11 and *c* is defined as above. Let  $\{f_n\}_{n \in \mathbb{N}}$  be a monotone increasing sequence of smooth non-negative functions on *M* with compact support such that  $f_n \to 1_U$  as  $n \to \infty$ . Note that by Lemma 3.2, it suffices to show that

$$\liminf_{n \to \infty} \int_{M} |\nabla f_n| d\mu \ge c I(v).$$
(3.12)

By the identity (3.4) and using (3.8), we have

$$|\nabla f_n|^2 = |\nabla_x f_n|^2 + \frac{1}{\psi(x)^2} |\nabla_y f_n|^2 \ge \frac{1}{2} \min\left\{1, \frac{1}{C_0}\right\}^2 \left(|\nabla_x f_n| + |\nabla_y f_n|\right)^2.$$

Together with Eq. 3.12, it therefore suffices to prove that

$$\liminf_{n \to \infty} \int_{M} |\nabla_{x} f_{n}| d\mu + \liminf_{n \to \infty} \int_{M} |\nabla_{y} f_{n}| d\mu \ge I(v).$$
(3.13)

Let us first estimate the second summand on the left-hand side of Eq. 3.13. For that purpose, consider for every  $x \in M_1$ , the section

$$U_x = \{ y \in M_2 : (x, y) \in U \}.$$

By Sard's theorem, the set  $U_x$  has smooth boundary for allmost all x. Considering the function  $f_n(x, y)$  as a function on  $M_2$  with fixed  $x \in M_1$ , we obtain by Lemma 3.2 for allmost all x,

$$\liminf_{n\to\infty}\int_{M_2}|\nabla_y f_n(x, y)|d\mu_2(y)\geq \mu_2^+(U_x).$$

Integrating this over  $M_1$  and using Fatou's lemma, we deduce

$$\liminf_{n \to \infty} \int_{M} |\nabla_{y} f_{n}| d\mu \ge \int_{M_{1}} \mu_{2}^{+}(U_{x}) d\mu_{1}(x).$$
(3.14)

The first summand on the left-hand side of Eq. 3.13 could be estimated analogously, but instead, we will estimate it using the assumption that  $(M_1, \mu_1)$  and  $(M_2, \mu_2)$  admit lower isoperimetric functions  $J_1$  and  $J_2$ , respectively. First, by Fubini's formula, we have

$$\int_{M} |\nabla_{x} f_{n}| d\mu = \int_{M_{1}} \int_{M_{2}} |\nabla_{x} f_{n}| d\mu_{2} d\mu_{1} \ge \int_{M_{1}} \left| \nabla_{x} \int_{M_{2}} f_{n}(x, y) d\mu_{2}(y) \right| d\mu_{1}(x).$$
(3.15)

Now let us consider on  $M_1$  the function

$$F_n(x) = \int_{M_2} f_n(x, y) d\mu_2(y).$$

Note that  $F_n(x)$  is a monotone increasing sequence of non-negative smooth functions on  $M_1$ , such that

$$F(x) := \lim_{n \to \infty} F_n(x) = \mu_2(U_x).$$
 (3.16)

Since  $F_n$  is smooth for all n, we deduce that the sets  $\{F_n > t\}$  have smooth boundary, so that we can apply the isoperimetric inequality on  $M_1$ , that is,

$$\mu_1^+\{F_n > t\} \ge J_1(\mu_1\{F_n > t\}).$$

Hence, we obtain, using (3.15) and the co-area formula,

$$\begin{split} \int_{M} |\nabla_{x} f_{n}| d\mu &\geq \int_{M_{1}} |\nabla_{x} F_{n}| d\mu_{1} = \int_{0}^{\infty} \mu_{1}^{\prime} \{F_{n} = t\} dt \\ &= \int_{0}^{\infty} \mu_{1}^{+} \{F_{n} > t\} dt \\ &\geq \int_{0}^{\infty} J_{1}(\mu_{1}\{F_{n} > t\}) dt. \end{split}$$

Passing to the limit as  $n \to \infty$ , we get by Fatou's lemma, using the continuity of  $J_1$ ,

$$\limsup_{n \to \infty} \int_{M} |\nabla_x f_n| d\mu \ge \int_0^\infty J_1(\mu_1 \{F > t\}) dt.$$
(3.17)

By the isoperimetric inequality on  $M_2$  with function  $J_2$  and by Eq. 3.16,

$$\mu_2^+(U_x) \ge J_2(\mu_2(U_x)) = J_2(F(x)),$$

whence combining this with Eqs. 3.14 and 3.17, we get

$$\limsup_{n \to \infty} \int_{M} |\nabla_x f_n| d\mu + \limsup_{n \to \infty} \int_{M} |\nabla_y f_n| d\mu \ge \int_0^\infty J_1(\mu_1 \{F > t\}) dt + \int_{M_1} J_2(F(x)) d\mu_1(x)$$
(3.18)

Let us set

$$\varphi(t) = \mu_1\{F > t\}$$

and note that  $\varphi$  is monotone decreasing and right-continuous. Let  $\phi$  be the generalized inverse function to  $\varphi$  defined by Eq. 3.5. Then we obtain by Eq. 3.6,

$$\sup\{s > 0 : \phi(s) > t\} = \mu_1\{F > t\},\tag{3.19}$$

which means that  $\phi$  and F are equimeasurable. Clearly,  $\varphi \le \mu_1(M_1)$ . Since  $F \le \mu_2(M_2)$ , which implies  $\varphi(t) = 0$  for all  $t > \mu_2(M_2)$ , we also obtain  $\phi \le \mu_2(M_2)$  by Eq. 3.5. By Eq. 3.7, the definition of  $\varphi$  and Fubini's formula,

$$\int_0^\infty \phi(t)dt = \int_0^\infty \varphi(t)dt = \int_{M_1} F d\mu_1 = \mu(U) = v$$

Hence, the pair  $\varphi$ ,  $\phi$  satisfies the condition in Eq. 3.10. Note that by Eq. 3.19,

$$\int_{M_1} J_2(F(x)) d\mu_1(x) = \int_0^\infty J_2(\phi(t)) dt,$$

whence we obtain for the right-hand side of Eq. 3.18,

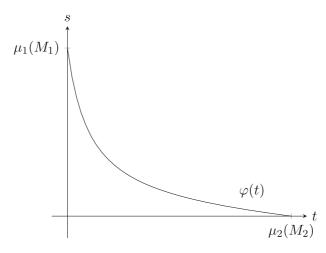
$$\int_{M_1} J_2(F(x)) d\mu_1(x) + \int_0^\infty J_1(\mu_1\{F > t\}) dt = \int_0^\infty J_2(\phi(t)) dt + \int_0^\infty J_1(\varphi(t)) dt \ge I(v),$$
  
which proves (3.13) and thus, finishes the proof (Fig. 1).

which proves (3.13) and thus, finishes the proof (Fig. 1).

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Let P > 0. Given two non-negative functions f on  $(0, +\infty)$  and g on (0, P) define the function h on  $(0, +\infty)$  by

$$h(v) = \inf_{\varphi,\phi} \left( \int_0^\infty f(\varphi(t)) dt + \int_0^\infty g(\phi(s)) ds. \right),$$



**Fig. 1** Function  $\varphi(t)$ 

where  $\varphi$  and  $\phi$  are generalized mutually inverse functions on  $(0, +\infty)$  such that

$$\int_0^\infty \varphi(t)dt = \int_0^\infty \phi(s)ds = v.$$
(3.20)

and with the condition that  $\phi < P$ . For fixed  $\varphi, \phi$ , where  $\varphi, \phi$  are as above, let us denote

$$S = \int_0^\infty f(\varphi(t))dt + \int_0^\infty g(\phi(s))ds.$$
(3.21)

**Lemma 3.4** Let f and g be continuous functions on the intervals  $(0, +\infty)$  and (0, P), respectively and suppose that g is symmetric with respect to  $\frac{1}{2}P$ . Also, assume that the functions  $\frac{f(x)}{x}$  and  $\frac{g(y)}{y}$  are monotone decreasing while the functions f and g are monotone increasing on the intervals  $(0, +\infty)$  and  $(0, \frac{P}{2})$ , respectively. Then, for any v > 0,

$$h(v) \ge \min\left(\frac{1}{6}h_0(v), \frac{1}{8}f\left(\frac{v}{P}\right)P\right),$$

where the function  $h_0$  is defined for all v > 0, by

$$h_0(v) = \inf_{\substack{xy=v\\x>0,\ 0< y\leq \frac{1}{2}P}} (f(x)y + g(y)x).$$
(3.22)

Remark A similar functional inequality was stated in [19, Theorem 2a] without proof.

In the following we denote by |A| the Lebesgue measure of a domain  $A \subset \mathbb{R}^2$ .

*Proof* Let  $\varphi$  be decreasing and right-continuous and  $\phi$  be its generalized inverse function satisfying (3.20) and let S be defined as in Eq. 3.21. We need to prove that

$$S \ge \min\left(\frac{1}{6}h_0(v), \frac{1}{8}f\left(\frac{v}{P}\right)P\right).$$
(3.23)

Let us first suppose that  $\varphi$  is strictly monotone decreasing and continuous on an interval  $(0, T) \subset (0, P)$  such that  $\lim_{t \to T} \varphi(t) = 0$  and  $\varphi((0, T)) = (0, +\infty)$ . Denote by  $\varphi$  the

inverse function of  $\varphi$  on  $(0, +\infty)$  and note that  $\phi$  is then also strictly monotone decreasing and continuous and satisfies  $\phi < T$ . Let us show that

$$S \ge \min\left(\frac{1}{6}h_T(v), \frac{1}{8}f\left(\frac{v}{T}\right)T\right),\tag{3.24}$$

where

$$h_T(v) = \inf_{\substack{xy=v\\x>0,\ 0 < y \le \frac{1}{2}T}} (f(x)y + g(y)x),$$

which will then imply (3.23) by an approximation argument.

For any  $p \in (0, T)$ , consider the domain

$$\Phi_p = \{(t,s) \in \mathbb{R}^2 : p \le t < T, \ 0 \le s \le \varphi(t)\}$$

and for any q > 0 the domain

$$\Psi_q = \{ (t, s) \in \mathbb{R}^2 : s \ge q, \ 0 \le t \le \phi(s) \}.$$

Since  $\phi$  is strictly monotone decreasing and continuous, there exists q > 0 such that  $|\Psi_q| = \frac{1}{3}v$ . Let us set  $p = \phi(q)$  and note that

$$v = \int_0^\infty \phi(s) ds = |\Phi_p| + |\Psi_q| + pq.$$
(3.25)

The proof will be split into two main cases.

Case 1. Let us assume that

$$|\Phi_p| \ge \frac{1}{3}v.$$

Then we obtain by Eq. 3.25 that  $p \leq \frac{1}{3q}v$ . By the monotonicity of  $\frac{g(y)}{y}$ , we therefore get

$$\int_0^\infty g(\phi(s))ds \ge \frac{1}{3}xg(y),$$

where x = 3q and  $y = \frac{1}{3q}v$  and similarly,

$$\int_0^\infty f(\varphi(t))dt \ge \frac{1}{3}f(x)y.$$

Hence, we obtain that

$$S \ge \frac{1}{3}h_0(v).$$

Case 2. Let us now assume that

$$|\Phi_p| < \frac{1}{3}v.$$

Then we can decrease p to p' such that  $|\Phi_{p'}| = \frac{1}{3}v$ . Set  $q' = \varphi(p')$  and note that this q' is larger than the q from Case 1, whence

$$|\Psi_{q'}| \le \frac{1}{3}v,$$

so that (3.25) implies

$$\frac{1}{3}v \le p'q' \le \frac{2}{3}v.$$

**Case 2a**. Assume further that  $p' \ge \frac{1}{4}T$ . It follows that

$$\int_0^\infty f(\varphi(t))dt \ge \frac{1}{3} \frac{f(q')}{q'} \iota$$

and since f is monotone increasing, we conclude

$$S \ge \frac{T}{8} f\left(\frac{v}{T}\right),$$

which proves (3.24).

**Case 2b.** Assume now that  $p' < \frac{1}{4}T$  and set  $q_0 = \varphi\left(\frac{1}{2}T\right)$ .

**Case 2b(i)**. Let us first consider the case when  $q_0 \le \frac{1}{2}q'$ . Using that g(y) is monotone increasing on  $(0, \frac{T}{2})$ , we obtain,

$$\int_0^\infty g(\phi(s))ds \ge \frac{1}{2}g(p')q'$$

Together with

$$\int_0^\infty f(\varphi(t))dt \ge f(q')p',$$

we deduce

$$S \ge \frac{1}{2}g(p')q' + f(q')p',$$

so that setting  $x = \frac{v}{p'}$  and y = p', yields

$$S \ge \frac{1}{6} (f(x)y + g(y)x) \ge \frac{1}{6} h_T(v).$$

**Case 2b(ii)**. Finally, let us consider the case when  $q_0 > \frac{1}{2}q'$ . Note that the condition that  $\frac{f(x)}{x}$  is monotone decreasing, implies that for any  $\lambda \in (0, 1)$ ,

$$f(\lambda x) \ge \lambda f(x)$$

Together with the monotonicity of f, we therefore obtain

$$\int_0^{T/2} f(\varphi(t))dt \ge f(q')\frac{T}{4},$$

which yields

$$S \ge f\left(\frac{v}{T}\right)\frac{T}{4},$$

and thus, proves (3.24) also in this case.

Now let us consider the general case, when  $\varphi$  is monotone decreasing and rightcontinuous and  $\phi$  being its generalized inverse function satisfying (3.20). Then consider an increasing sequence  $\{\varphi_n\}_n$  of functions which are positive, continuous, strictly decreasing functions on an interval  $(0, T_n) \subset (0, P)$  such that  $T_n \to P$ ,  $\varphi_n(t) \to \varphi(t)$  and  $v_n := \int_0^\infty \varphi_n(t) dt \to v$  for  $n \to +\infty$ . Letting  $\phi_n$  be the inverse function of  $\varphi_n$  on  $(0, T_n)$ for all n, we get by [8, Lemma 1.1.1], that for every continuity point  $s \in (0, +\infty)$  of  $\phi$ ,

$$\phi_n(s) \to \phi(s) \quad \text{as } n \to +\infty.$$

By the former case, we have the inequality (3.24) for all  $\varphi_n$ , that is,

$$\int_0^\infty f(\varphi_n(t))dt + \int_0^\infty g(\phi_n(s))ds \ge \min\left(\frac{1}{6}h_{T_n}(v_n), \frac{1}{8}f\left(\frac{v_n}{T_n}\right)T_n\right).$$
(3.26)

Now let  $q_1 = \varphi\left(\frac{P}{2}\right)$  and note that  $\phi_n(s) \le \frac{P}{2}$  for all *n* and  $s \ge q_1$ , whence using that *g* is monotone increasing on  $\left(0, \frac{P}{2}\right)$ , we obtain for all  $s \ge q_1$ ,

$$g(\phi_n(s)) \le g(\phi_{n+1}(s)).$$

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Hence, we obtain by the dominated convergence theorem, the monotone convergence theorem and the continuity of g,

$$\lim_{n \to \infty} \int_0^\infty g(\phi_n(s)) ds = \lim_{n \to \infty} \left( \int_0^{q_1} g(\phi_n(s)) ds + \int_{q_1}^\infty g(\phi_n(s)) ds \right) = \int_0^\infty g(\phi(s)) ds.$$

Using the monotonicity and the continuity of f, we get by the monotone convergence theorem,

$$\lim_{n \to \infty} \int_0^\infty f(\varphi_n(t)) dt = \int_0^\infty f(\varphi(t)) dt.$$

Hence, passing to the limit as  $n \to +\infty$  in Eq. 3.26, we conclude by the continuity of the right-hand side of Eq. 3.26, that inequality (3.23) holds, which finishes the proof.

**Corollary 3.5** In the situation of Theorem 3.3 suppose that

 $\mu_1(M_1) = \infty$  and  $\mu_2(M_2) < \infty$ 

and assume that  $\frac{J_1(x)}{x}$  and  $\frac{J_2(y)}{y}$  are monotone decreasing while the functions  $J_1$  and  $J_2$  are monotone increasing on the intervals  $(0, +\infty)$  and  $(0, \frac{1}{2}\mu_2(M_2))$ , respectively. Then the manifold  $(M, \mu)$  admits the lower isoperimetric function

$$J(v) = c \min\left(\frac{1}{6}J_0(v), \frac{1}{8}J_1\left(\frac{v}{\mu_2(M_2)}\right)\mu_2(M_2)\right),$$
(3.27)

where function  $J_0$  is defined for all v > 0, by

$$J_0(v) = \inf_{\substack{xy=v\\x>0,\ 0< y \le \frac{1}{2}\mu_2(M_2)}} (J_1(x)y + J_2(y)x),$$
(3.28)

and the constant c is defined as in Theorem 3.3.

*Proof* From Theorem 3.3, we know that  $(M, \mu)$  has the lower isoperimetric function cI, where I is defined by

$$I(v) = \inf_{\varphi,\phi} \left( \int_0^\infty J_1(\varphi(t)) dt + \int_0^\infty J_2(\phi(s)) ds. \right),$$

where  $\varphi$  and  $\phi$  are generalized mutually inverse functions satisfying  $\phi \le \mu_2(M_2)$  and the condition in Eq. 3.20. Since  $\mu_2(M_2)$  is finite, we can assume that the isoperimetric function  $J_2$  is symmetric with respect to  $\frac{1}{2}\mu_2(M_2)$ , because the topological boundaries of an open set and its complement coincide. Applying Lemma 3.4 to I with  $f = J_1$ ,  $g = J_2$  and  $P = \mu_2(M_2)$ , we obtain

$$I(v) \ge \min\left(\frac{1}{6}J_0(v), \frac{1}{8}J_1\left(\frac{v}{\mu_2(M_2)}\right)\mu_2(M_2)\right),$$

where function  $J_0$  is defined by Eq. 3.28, which implies that function J given by Eq. 3.27 is a lower isoperimetric function for  $(M, \mu)$ .

#### 3.2 Weighted Models with Boundary

Let us also consider the topological space  $M = \mathbb{R}_+ \times \mathbb{S}^{n-1}$ ,  $n \ge 2$ , where  $\mathbb{R}_+ = [0, +\infty)$ , so that any point  $x \in M$  can be written in the polar form  $x = (r, \theta)$  with  $r \in \mathbb{R}_+$  and

 $\theta \in \mathbb{S}^{n-1}$ . We equip *M* with the Riemannian metric  $ds^2$  that is defined in polar coordinates  $(r, \theta)$  by

$$ds^2 = dr^2 + \psi^2(r)d\theta^2$$

with  $\psi(r)$  being a smooth positive function on  $\mathbb{R}_+$  and  $d\theta^2$  being the Riemannian metric on  $\mathbb{S}^{n-1}$ . Note that *M* with this metric becomes a manifold with boundary

$$\delta M = \{ (r, \theta) \in M : r = 0 \}$$

and we call M in this case a *Riemannian model with boundary*. The Riemannian measure  $\mu$  on M with respect to this metric is given by

$$d\mu = \psi^{n-1}(r)drd\sigma(\theta),$$

where dr denotes the Lebesgue measure on  $\mathbb{R}_+$  and  $d\sigma$  denotes the Riemannian measure on  $\mathbb{S}^{n-1}$ . Let us normalize the metric  $d\theta^2$  on  $\mathbb{S}^{n-1}$  so that  $\sigma(\mathbb{S}^{n-1}) = 1$  and define the area function *S* on  $\mathbb{R}_+$  by

$$S(r) = \psi^{n-1}(r).$$

Given a smooth positive function h on M, that only depends on the polar radius r, and a measure  $\tilde{\mu}$  on M defined by  $d\tilde{\mu} = h^2 d\mu$ , we obtain that the weighted manifold  $(M, \tilde{\mu})$  has the area function

$$\tilde{S}(r) = h^2(r)S(r)$$

Then the weighted manifold  $(M, \tilde{\mu})$  is called a *weighted model* and we get that

$$d\widetilde{\mu} = \widetilde{S}(r)drd\sigma(\theta). \tag{3.29}$$

**Theorem 3.6** Let  $(M_0, \mu_0)$  be a model manifold with boundary. Assume that there exists a constant  $C_0 > 0$  such that for all  $r \ge 0$ ,

$$\psi_0(r) \le C_0.$$
 (3.30)

Assume also, that

$$\widetilde{S}_0(r) \simeq \begin{cases} r^{\delta} e^{r^{\alpha}}, \ r \ge 1, \\ 1, \quad r < 1, \end{cases}$$
(3.31)

where  $\delta \in \mathbb{R}$  and  $\alpha \in (0, 1]$ . Then the weighted model  $(M_0, \tilde{\mu_0})$  with area function  $\widetilde{S}_0$  admits the lower isoperimetric function J defined by

$$J(w) = \widetilde{c} \begin{cases} \frac{w}{(\log w) \frac{1-\alpha}{\alpha}}, & w \ge 2, \\ c'w^{\frac{n-1}{n}}, & w < 2, \end{cases}$$
(3.32)

where  $\tilde{c}$  is a small enough constant and c' is a positive constant chosen such that J is continuous.

*Proof* Let  $\nu$  be the measure on  $\mathbb{R}_+$  defined by  $d\nu(r) = \widetilde{S}_0(r)dr$ . Then (3.29) implies that measure  $\widetilde{\mu}_0$  has the representation  $\widetilde{\mu}_0 = \nu \times \sigma$ , where  $\sigma$  is the normalized Riemannian measure on the sphere  $\mathbb{S}^{n-1}$ . Obviously, we have by Eq. 3.31, that

$$\nu(\mathbb{R}_+) = \int_0^\infty \widetilde{S}_0(r) dr = +\infty.$$

Since  $\widetilde{S}_0$  is a positive, continuous and non-decreasing function on  $\mathbb{R}_+$ , we obtain from [2, Proposition 3.1], that  $(\mathbb{R}_+, \nu)$  has a lower isoperimetric function  $J_{\nu}(\nu)$  given by

$$J_{\nu}(v) = S_0(r),$$

where v = v([0, r)). Clearly, for small R, we have  $J_v(v) \simeq 1$ . For large enough R, we obtain

$$v = \int_0^R \widetilde{S}_0(r) dr \simeq R^{\delta + 1 - \alpha} e^{R^{\alpha}}.$$

This implies that for large v,

$$\log v \simeq R^{\alpha} + (\delta + 1 - \alpha) \log R \simeq R^{\alpha}$$

and thus,

$$J_{\nu}(v) = \widetilde{S}_{0}(R) \simeq R^{\delta} e^{R^{\alpha}} = R^{\alpha - 1} R^{\delta + 1 - \alpha} e^{R^{\alpha}} \simeq \frac{v}{(\log v)^{\frac{1 - \alpha}{\alpha}}},$$

which proves that

$$J_{\nu}(v) = c_0 \begin{cases} \frac{v}{(\log v)^{\frac{1-\alpha}{\alpha}}}, & v \ge 2, \\ c_1, & v < 2, \end{cases}$$

is a lower isoperimetric function of  $(\mathbb{R}_+, \nu)$  if  $c_0 > 0$  is a small enough constant and continuous for an appropriate choice of constant  $c_1 > 0$ . Note  $J_{\nu}$  is monotone increasing on  $\mathbb{R}_+$  and, since  $\alpha \in (0, 1]$ , the function  $\frac{J_{\nu}(\nu)}{\nu}$  is monotone decreasing. Let  $J_{\sigma}$  be the function defined by

$$J_{\sigma}(v) = c_n \begin{cases} v^{\frac{n-2}{n-1}}, & \text{if } 0 \le v \le \frac{1}{2}, \\ (1-v)^{\frac{n-2}{n-1}}, & \text{if } \frac{1}{2} < v \le 1. \end{cases}$$

It is a well-known fact that  $J_{\sigma}$  is a lower isoperimetric function for  $(\mathbb{S}^{n-1}, \sigma)$  assuming that the constant  $c_n > 0$  is sufficiently small. Since we assume that  $\psi_0$  satisfies the condition in Eq. 3.30, we can apply Corollary 3.5 and deduce that a lower isoperimetric function J of  $(M_0, \tilde{\mu}_0)$  is given by

$$J(w) = c \min\left(\frac{1}{6}J_0(w), \frac{1}{8}J_\nu(w)\right),$$
(3.33)

where  $J_0$  is defined by

$$J_0(w) = \inf_{\substack{uv=w\\u>0,\ 0 < v \le \frac{1}{2}}} (J_v(u)v + J_\sigma(v)u)$$

and the constant c > 0 is defined as in Theorem 3.3.

In order to estimate J in this case, let us consider the function K, defined for all w > 0, by

$$K(w) = \frac{J(w)}{w} = c \min\left(\frac{1}{6}K_0(w), \frac{1}{8}K_v(w)\right),$$
(3.34)

where  $K_0$  is given by

$$K_0(w) = \inf_{\substack{uv=w\\u>0,\ 0(3.35)$$

where  $K_{\nu}(u) = \frac{J_{\nu}(u)}{u}$  and  $K_{\sigma}(v) = \frac{J_{\sigma}(v)}{v}$ . Observe that, since  $K_{\sigma}$  is monotone decreasing,

$$K_0(w) \ge \inf_{0 < v \le \frac{1}{2}} K_{\sigma}(v) \ge K_{\sigma}\left(\frac{1}{2}\right)$$

Note that if  $w \ge 2$  and  $v \le \frac{1}{2}$ , then  $u = \frac{w}{v} \ge 4$ . Hence, we obtain that for  $w \ge 2$ ,

$$K_0(w) \simeq \text{const.}$$

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Substituting this into Eq. 3.34, we get, using that  $K_{\nu}$  is monotone decreasing,  $K(w) \simeq K_{\nu}(w)$  for  $w \ge 2$ , and whence

$$J(w) \simeq J_{\nu}(w) \simeq \frac{w}{(\log w)^{\frac{1-\alpha}{\alpha}}}, \quad w \ge 2.$$
(3.36)

Note that if  $w \le 2$ , the infimum is attained when  $u \le 2$  and the summands in Eq. 3.35 are comparable. Observe that this holds true when

$$v \simeq w^{rac{1}{2-rac{n-2}{n-1}}}$$

so that substituting this into Eq. 3.35, we deduce for  $w \leq 2$ ,

$$K_0(w) \simeq w^{-\frac{1}{n}}.$$

Hence, we obtain that for all  $w \leq 2$ ,

$$J_0(w) \simeq w^{\frac{n-1}{n}},$$

and therefore by Eq. 3.33,

$$J(w) \simeq w^{\frac{n-1}{n}}, \quad w \le 2$$

Combining this with Eq. 3.36, we conclude that the function J(w) defined by Eq. 3.32 is a lower isoperimetric function for the weighted model  $(M_0, \tilde{\mu_0})$ .

## 4 On-diagonal Heat Kernel Upper Bounds

Recall from Eq. 2.20, that for any open set  $\Omega \subset M$ , we define

$$\lambda_1(\Omega) = \inf_u \frac{\int_{\Omega} |\nabla u|^2 d\mu}{\int_{\Omega} u^2 d\mu},$$

where the infimum is taken over all nonzero Lipschitz functions u compactly supported in  $\Omega$ .

**Definition** We say that  $(M, \mu)$  satisfies a *Faber-Krahn inequality* with a function  $\Lambda$ :  $(0, +\infty) \rightarrow (0, +\infty)$  if, for any non-empty precompact open set  $\Omega \subset M$ ,

$$\lambda_1(\Omega) \ge \Lambda(\mu(\Omega)). \tag{4.1}$$

It is well-known that a Faber-Krahn inequality (4.1) implies certain heat kernel upper bounds of the heat kernel (see [4] and [14]).

**Proposition 4.1** ([14], Theorem 5.1) Suppose that a weighted manifold  $(M, \mu)$  satisfies a Faber-Krahn inequality (4.1) with  $\Lambda$  being a continuous and decreasing function such that

$$\int_0^1 \frac{dv}{v\Lambda(v)} < \infty. \tag{4.2}$$

Then for all t > 0,

$$\sup_{x \in M} p_t(x, x) \le \frac{4}{\gamma(t/2)},\tag{4.3}$$

where the function  $\gamma$  is defined by

$$t = \int_0^{\gamma(t)} \frac{dv}{v\Lambda(v)}.$$
(4.4)

**Definition** Let  $\{M_i\}_{i=0}^k$  be a finite family of non-compact Riemannian manifolds. We say that a manifold *M* is a *connected sum* of the manifolds  $M_i$  and write

$$M = \bigsqcup_{i=0}^{k} M_i \tag{4.5}$$

if, for some non-empty compact set  $K \subset M$  the exterior  $M \setminus K$  is a disjoint union of open sets  $E_0, \ldots, E_k$  such that each  $E_i$  is isometric to  $M_i \setminus K_i$  for some compact set  $K_i \subset M_i$ .

Conversely, we have the following definition.

**Definition** Let *M* be a non-compact manifold and  $K \subset M$  be a compact set with smooth boundary such that  $M \setminus K$  is a disjoint union of finitely many ends  $E_0, \ldots, E_k$ . Then *M* is called a *manifold with ends*.

*Remark* Let *M* be a manifold with ends  $E_0, \ldots, E_k$ . Considering each end  $E_i$  as an exterior of another manifold  $M_i$ , then *M* can be written as in Eq. 4.5.

Let  $(M = \bigsqcup_{i=0}^{k} M_i, \mu)$  be a connected sum of complete non-compact weighted manifolds  $(M_i, \mu_i)$  and *h* be a positive smooth function on *M*. As before, let us consider the weighted manifold  $(M, \tilde{\mu})$ , where  $\tilde{\mu}$  is defined by  $d\tilde{\mu} = h^2 d\mu$ . By restricting *h* to the end  $E_i = M_i \setminus K_i$  and then extending this restriction smoothly to a function  $h_i$  on  $M_i$ , we obtain weighted manifolds  $(M_i, \tilde{\mu}_i)$ , where  $\tilde{\mu}_i$  is given by  $d\tilde{\mu}_i = h_i^2 d\mu$ .

From now on, we always have  $\dim(M) = n$ .

**Theorem 4.2** Let  $(M, \tilde{\mu}) = \left(\bigsqcup_{i=0}^{k} M_i, \tilde{\mu}\right)$  be a weighted manifold with ends where  $M_0$  is a model manifold with boundary so that for all  $r \ge 0$ ,

$$\psi_0(r) \le C_0$$

and

$$\widetilde{S}_0(r) \simeq \begin{cases} r^{\delta} e^{r^{\alpha}}, \ r \ge 1, \\ 1, \qquad r < 1, \end{cases}$$

where  $0 < \alpha \leq 1, \delta \in \mathbb{R}$  and  $\widetilde{S}_0$  denotes the area function of a weighted model  $(M_0, \widetilde{\mu}_0)$ . Assume also that all  $(M_i, \widetilde{\mu}_i)$ , i = 1, ..., k, have Faber-Krahn functions  $\widetilde{\Lambda}_i$  such that

$$\widetilde{\Lambda_i}(v) \ge c_i \begin{cases} \frac{1}{(\log v)^{\frac{2-2\alpha}{\alpha}}}, v \ge 2, \\ v^{-\frac{2}{n}}, v < 2, \end{cases}$$

for constants  $c_i > 0$ . Then there exist constants C > 0 and  $C_1 > 0$  depending on  $\alpha$  and n so that the heat kernel  $\tilde{p}_t$  of  $(M, \tilde{\mu})$  satisfies

$$\sup_{x \in M} \widetilde{p}_t(x, x) \le C \begin{cases} \exp\left(-C_1 t^{\frac{\alpha}{2-\alpha}}\right), \ t \ge 1, \\ t^{-\frac{n}{2}}, \quad 0 < t < 1. \end{cases}$$
(4.6)

*Proof* It follows from Theorem 3.6, that  $(M_0, \tilde{\mu}_0)$  has the lower isoperimetric function J given by Eq. 3.32, that is

$$J(v) = \widetilde{c} \begin{cases} \frac{v}{(\log v)\frac{1-\alpha}{\alpha}}, v \ge 2, \\ c'v^{\frac{n-1}{n}}, v < 2, \end{cases}$$

where  $\tilde{c} > 0$  is a small enough constant and c' is a positive constant chosen such that J is continuous. Since J is continuous and the function  $\frac{J(v)}{v}$  is non-increasing, we obtain from [13, Proposition 7.1], that  $(M_0, \tilde{\mu_0})$  admits a Faber-Krahn function  $\tilde{\Lambda}_0$  given by

$$\widetilde{\Lambda}_0(v) = \frac{1}{4} \left( \frac{J(v)}{v} \right)^2 \simeq \begin{cases} \frac{1}{(\log v)^{\frac{2-2\alpha}{\alpha}}}, & v \ge 2, \\ v^{-\frac{2}{n}}, & v < 2. \end{cases}$$

We obtain from [18, Theorem 3.4] that there exist constants c > 0 and Q > 1 such that  $(M, \tilde{\mu})$  admits the Faber-Krahn function

$$\widetilde{\Lambda}(v) = c \min_{0 \le i \le k} \widetilde{\Lambda}_i(Qv).$$

Hence  $(M, \tilde{\mu})$  has a Faber-Krahn function  $\tilde{\Lambda}$ , satisfying

$$\widetilde{\Lambda}(v) \simeq \begin{cases} \frac{1}{(\log v)^{\frac{2-2\alpha}{\alpha}}}, & v \ge 2, \\ v^{-\frac{2}{n}}, & v < 2. \end{cases}$$
(4.7)

Observe that the Faber-Krahn function  $\tilde{\Lambda}$  satisfies condition (4.2). Thus, we can apply Proposition 4.1, which yields the heat kernel upper bound in Eq. 4.3. Hence, it remains to estimate the function  $\gamma$  from the right hand side of Eq. 4.3 by using (4.4). In the case when t > 0 is small enough, we get by Eqs. 4.4 and 4.7,

$$t = \int_0^{\gamma(t)} \frac{dv}{v\widetilde{\Lambda}(v)} = C' \int_0^{\gamma(t)} \frac{dv}{v^{1-\frac{2}{n}}} = C'\gamma(t)^{\frac{2}{n}},$$

which implies for some constant C'' > 0,

$$\gamma(t) = C'' t^{\frac{n}{2}}.$$

For large enough t on the other hand, we deduce

$$t = \int_0^{\gamma(t)} \frac{dv}{v\widetilde{\Lambda}(v)} \simeq \int_2^{\log(\gamma(t))} u^{\frac{2-2\alpha}{\alpha}} du \simeq \log(\gamma(t))^{\frac{2-\alpha}{\alpha}}.$$

Therefore,

$$\gamma(t) \simeq \exp\left(\operatorname{const} t^{\frac{\alpha}{2-\alpha}}\right),$$

where const is a positive constant depending on  $\alpha$  and n. Substituting these estimates for  $\gamma(t)$  into (4.3), we obtain the upper bound (4.6) for the heat kernel  $\tilde{p}_t$  of  $(M, \tilde{\mu})$  for small and large values of t. For the intermediate values of t, we deduce the upper bound (4.6) from the fact that the function  $t \mapsto \sup_{x \in M} \tilde{p}_t(x, x)$  is continuous.

*Example* In Theorem 4.2 one can take  $(M_i, \tilde{\mu}_i) = (\mathbb{H}^n, \mu_i), i = 1, \dots, k$ , where  $\mu_i$  is the Riemannian measure on the hyperbolic space  $\mathbb{H}^n$  since for all  $0 < \alpha \le 1$ , we have

$$\Lambda_{\mathbb{H}^{n}}(v) \simeq \begin{cases} 1, & v \ge 2, \\ v^{-\frac{2}{n}}, & v < 2 \end{cases} \ge c \begin{cases} \frac{1}{(\log v)^{\frac{2-2\alpha}{\alpha}}}, & v \ge 2, \\ v^{-\frac{2}{n}}, & v < 2. \end{cases}$$

*Remark* Let  $(M, \tilde{\mu})$  be the weighted manifold with ends, defined as in Theorem 4.2, so that  $\widetilde{S}_0(r) \simeq e^{r^{\alpha}} r^{\delta}$  for r > 1 and hence, for R > 1,

$$\widetilde{V}_0(R) = \int_0^R \widetilde{S}_0(r) dr \simeq \int_0^R e^{r^{\alpha}} r^{\delta} dr \simeq e^{R^{\alpha}} R^{\delta+1-\alpha}.$$

Then, we obtain from [7, Proposition 3.4] for large enough R,

$$\widetilde{\lambda_1}(\Omega_R) \leq 4 \left( \frac{\widetilde{S}_0(R)}{\widetilde{V}_0(R)} \right)^2 \leq \frac{C}{R^{2-2\alpha}},$$

where  $\Omega_R = \{(r, \theta) \in M_0 : 0 < r < R\}$ . Hence, setting  $R = R(t) = t^{\frac{1}{2-\alpha}}$ , [7, Proposition 2.3] yields the following lower bound for the heat kernel  $\tilde{p}_t$  in  $(M, \tilde{\mu})$  for large enough *t*:

$$\sup_{x} \widetilde{p}_{t}(x,x) \geq \frac{1}{\widetilde{\mu}(\Omega_{R})} \exp\left(-\widetilde{\lambda_{1}}(\Omega_{R})t\right) \geq \frac{C_{1}}{e^{R^{\alpha}(t)}R^{\delta+1-\alpha}(t)} \exp\left(-\frac{Ct}{R^{2-2\alpha}(t)}\right) \geq \frac{C_{1}}{e^{C_{2}t^{\frac{\alpha}{2-\alpha}}}},$$

which shows that the exponential decay in the upper bound given in Eq. 4.6 is sharp.

#### 4.1 Weighted Models with Two Ends

Let *M* be the topological space  $M = \mathbb{R} \times \mathbb{S}^{n-1}$ ,  $n \ge 2$ , that is, any point  $x \in M$  can be written in the polar form  $x = (r, \theta)$  with  $r \in \mathbb{R}$  and  $\theta \in \mathbb{S}^{n-1}$ . For a fixed smooth positive function  $\psi$  on  $\mathbb{R}$  consider on *M* the Riemannian metric  $ds^2$  given by

$$ds^2 = dr^2 + \psi^2(r)d\theta^2,$$

where  $d\theta^2$  is the standard Riemannian metric on  $\mathbb{S}^{n-1}$ . The Riemannian measure  $\mu$  on M with respect to this metric is given by

$$d\mu = \psi^{n-1}(r)drd\sigma(\theta),$$

where dr denotes the Lebesgue measure on  $\mathbb{R}$  and  $d\sigma$  the Riemannian measure on  $\mathbb{S}^{n-1}$ . As before, we normalize the metric  $d\theta^2$  on  $\mathbb{S}^{n-1}$  so that  $\sigma(\mathbb{S}^{n-1}) = 1$ . Then we define the area function S on  $\mathbb{R}$  by

$$S(r) = \psi^{n-1}(r).$$

Given a smooth positive function h on M, that only depends on the polar radius  $r \in \mathbb{R}$ , and considering the measure  $\tilde{\mu}$  on M defined by  $d\tilde{\mu} = h^2 d\mu$ , we get that the weighted model  $(M, \tilde{\mu})$ , has the area function

$$\widetilde{S}(r) = h^2(r)S(r).$$

The Laplace-Beltrami operator  $\Delta_{\mu}$  on *M* can be represented in the polar coordinates  $(r, \theta)$  as follows:

$$\Delta_{\mu} = \frac{\partial^2}{\partial r^2} + \frac{S'(r)}{S(r)}\frac{\partial}{\partial r} + \frac{1}{\psi^2(r)}\Delta_{\theta}, \qquad (4.8)$$

where  $\Delta_{\theta}$  is the Laplace-Beltrami operator on  $\mathbb{S}^{n-1}$ . If we assume that *u* is a radial function, that is, *u* depends only on the polar radius *r*, we obtain from Eq. 4.8, that *u* is harmonic in *M* if and only if

$$u(r) = c_1 + c_2 \int_{r_1}^r \frac{dt}{S(t)},$$
(4.9)

where  $r_1 \in [-\infty, +\infty]$  so that the integral converges and  $c_1, c_2$  are arbitrary reals.

**Theorem 4.3** Let  $(M, \mu) = (M_0 \sqcup M_1, \mu)$  be a Riemannian model with two ends, where  $M_0 = \{(r, \theta) \in M : r \ge 0\}$  is a model manifold with boundary such that for all  $r \ge 0$ ,

$$\psi_0(r) = e^{-\frac{1}{n-1}r^{\alpha}}$$

Also assume that  $(M_1, \mu_1)$  is a Riemannian model with

$$\int_{1}^{\infty} \frac{dt}{S_{1}(t)} < \infty, \tag{4.10}$$

and Faber-Krahn function  $\Lambda_1$ , so that

$$\Lambda_{1}(v) \ge c_{1} \begin{cases} \frac{1}{(\log v)^{\frac{2-2\alpha}{\alpha}}}, & v \ge 2, \\ v^{-\frac{2}{n}}, & v < 2, \end{cases}$$
(4.11)

for some constant  $c_1 > 0$ . Then there exist positive constants  $C_x = C_x(x, \alpha, n)$  and  $C_1 = C_1(\alpha, n)$  such that the heat kernel of  $(M, \mu)$  satisfies, for all  $x \in M$ , the inequality

$$p_t(x, x) \le C_x \begin{cases} \exp\left(-C_1 t^{\frac{\alpha}{2-\alpha}}\right), \ t \ge 1, \\ t^{-\frac{n}{2}}, \qquad 0 < t < 1. \end{cases}$$
(4.12)

*Proof* Observe that the assumption (4.10) yields that we can choose positive constants  $\kappa_1$  and  $\kappa_2$  so that the smooth function *h* on *M* defined by

$$h(r) = \kappa_1 + \kappa_2 \int_1^r \frac{dt}{S(t)}$$

is positive in M and satisfies  $h \simeq 1$  in  $\{r \le 0\}$ . Consider the weighted model with two ends  $(M, \tilde{\mu})$ , where  $\tilde{\mu}$  is defined by  $d\tilde{\mu} = h^2 d\mu$ . It follows from Eq. 4.11 that the weighted model  $(M_1, \tilde{\mu}_1)$  has the Faber-Krahn function  $\tilde{\Lambda}_1$  satisfying

$$\widetilde{\Lambda}_1(v) \ge \widetilde{c}_1 \begin{cases} \frac{1}{(\log v)^{\frac{2-2\alpha}{\alpha}}}, v \ge 2, \\ v^{-\frac{2}{n}}, v < 2, \end{cases}$$

for some constant  $\tilde{c}_1 > 0$ . Further, note that

$$h|_{M_0}(r) \simeq \begin{cases} r^{1-lpha} e^{r^{lpha}}, \ r \ge 1, \\ 1, \qquad 0 \le r < 1, \end{cases}$$

whence the area function  $\widetilde{S}_0$  of the weighted model with boundary  $(M_0, \widetilde{\mu}_0)$  admits the estimate

$$\widetilde{S}_0(r) \simeq \begin{cases} r^{2-2\alpha} e^{r^{\alpha}}, \ r \ge 1, \\ 1, & 0 \le r < 1. \end{cases}$$

Since also  $\psi_0 \leq 1$ , we can apply Theorem 4.2 and obtain that there exist constants C > 0 and  $C_1 > 0$  depending on  $\alpha$  and n so that the heat kernel  $\tilde{p}_t$  of  $(M, \tilde{\mu})$  satisfies

$$\sup_{x \in M} \widetilde{p}_t(x, x) \le C \begin{cases} \exp\left(-C_1 t^{\frac{\alpha}{2-\alpha}}\right), \ t \ge 1, \\ t^{-\frac{n}{2}}, \qquad 0 < t < 1. \end{cases}$$
(4.13)

Using that h is harmonic in M, we have by Eq. 2.8, for all t > 0 and  $x \in M$ , the identity

$$\widetilde{p}_t(x,x) = \frac{p_t(x,x)}{h^2(x)},$$

which together with Eq. 4.13 implies the upper bound (4.12) and thus, finishes the proof.  $\hfill\square$ 

*Remark* Consider the end  $\Omega := \{r > 0\}$  of the Riemannian model  $(M, \mu)$  from Theorem 4.3 and note that  $(\overline{\Omega} = \{r \ge 0\}, \mu|_{\{r \ge 0\}})$  is parabolic by [12, Proposition 3.1], whence the estimate (4.12) implies that we cannot get a polynomial decay of the heat kernel in M as it follows from Eq. 2.4 in Theorem 2.1, just by assuming the polynmial volume growth condition (2.2).

Remark Consider again the end  $\Omega := \{r > 0\}$  of the Riemannian model  $(M, \mu)$  from Theorem 4.3 and assume for simplicity that n = 2. Let  $M_0$  be defined as in Theorem 2.6, that is, there exists a compact set  $K_0 \subset M_0$  that is the closure of a non-empty open set, such that  $\Omega$  is isometric to  $M_0 \setminus K_0$ . Let us check which conditions from Theorem 2.6 are not satisfied in  $M_0$ . A simple computation shows that the area function  $S_0$  of the manifold  $M_0$  satisfies  $S_0''(r) \sim \alpha^2 e^{-r^{\alpha}} r^{2\alpha-2}$  as  $r \to +\infty$ , so that  $-\frac{S_0''(r)}{S_0(r)} \to 0$  as  $r \to +\infty$ . Together with the fact that on a compact set, the Gaussian curvature is non-negative, it then follows from Eq. 2.42 that the curvature on  $M_0$  is bounded below, which implies that  $M_0$ is a locally Harnack manifold. Obviously,  $S_0$  also satisfies the conditions (2.39) and (2.40) from Proposition 2.9, whence we obtain that on  $M_0$  the spherical Harnack inequality (2.22) holds. On the other hand, condition (2.23) in  $M_0$  fails, since for fixed  $\rho > 0$ , the volume  $V(x, \rho)$  decreases exponentially when  $r \to +\infty$  where  $x = (r, \theta) \in \Omega$ . Hence, we have that in general, we can not drop the condition (2.23) in Theorem 2.6 to get the polynomial decay (2.24) of the heat kernel in M.

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#### Declarations

**Conflict of Interests** The authors confirm that they do not have actual or potential conflict of interest in relation to this publication.

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