

Handelman’s Positivstellensatz for polynomial matrices positive definite on polyhedra

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Abstract In this paper we give a matrix version of Handelman’s Positivstellensatz (Handelman in Pac J Math 132:35–62, 1988), representing polynomial matrices which are positive definite on convex, compact polyhedra. Moreover, we propose also a procedure to find such a representation. As a corollary of Handelman’s theorem, we give a special case of Schmüdgen’s Positivstellensatz for polynomial matrices positive definite on convex, compact polyhedra.

Keywords Handelman’s theorem · Pólya’s theorem · Schmüdgen’s theorem · Matrix polynomial · Polynomial matrix · Positivstellensatz · Positive definite · Standard simplex · Polyhedron

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1 Introduction

Let $\mathbb{R}[X] := \mathbb{R}[X_1, \dots, X_n]$ be the ring of polynomials in the variables X_1, \dots, X_n with real coefficients. Denote by Δ_n the standard n -simplex in \mathbb{R}^n , which is defined by

$$\Delta_n := \left\{ x = (x_1, \dots, x_n) \in \mathbb{R}^n \mid x_i \geq 0, \sum_{i=1}^n x_i = 1 \right\}.$$

Pólya [9] proved in 1928 that for a homogeneous polynomial $f \in \mathbb{R}[X]$, if $f(x) > 0$ for every $x \in \Delta_n$, then there exists a sufficiently large number N such that all coefficients of the polynomial $(X_1 + \dots + X_n)^N \cdot f$ are positive.

Powers and Reznick [10] gave an explicit bound for the number N , and applied it to give a constructive version of Handelman’s Positivstellensatz. More explicitly, let $P \subseteq \mathbb{R}^n$ be a convex, compact polyhedron with non-empty interior, bounded by linear polynomials $L_1, \dots, L_m \in \mathbb{R}[X]$. By choosing the sign of the L_i ’s, we may assume that

$$P = \{x \in \mathbb{R}^n \mid L_i(x) \geq 0, i = 1, \dots, m\}. \tag{1}$$

Theorem 1 (Handelman’s Positivstellensatz [4]) *For a polynomial $f \in \mathbb{R}[X]$, if $f(x) > 0$ for all $x \in P$, then f can be represented as*

$$f = \sum_{|\alpha| \leq M} f_\alpha L_1^{\alpha_1} \dots L_m^{\alpha_m}$$

for some $M \in \mathbb{N}$ and $f_\alpha \geq 0$ for all $\alpha = (\alpha_1, \dots, \alpha_m) \in \mathbb{N}^m$ such that $|\alpha| \leq M$.

Krivine [6] proved Handelman’s Positivstellensatz for a special polyhedron. Moreover, one can find a generalization of this Positivstellensatz in [11, Theorem 5.4.6] (or [8, Theorem 7.1.6]). A bound for the number M was given by Powers and Reznick [10], using the bound for the number N in Pólya’s Positivstellensatz.

Theorem 1 yields the following consequence.

Corollary 1 *For a polynomial $f \in \mathbb{R}[X]$, if $f(x) > 0$ for all $x \in P$, then f can be represented as*

$$f = \sum_{e=(e_1, \dots, e_m) \in \{0, 1\}^m} f_e^2 L_1^{e_1} \dots L_m^{e_m},$$

where $f_e \in \mathbb{R}[X]$ and $\deg(f_e^2) \leq M$.

This corollary is a special case of Schmüdgen’s Positivstellensatz [14] for convex, compact polyhedra which includes an explicit bound on the degrees of sums of squares coefficients f_e^2 .

Schmüdgen’s Positivstellensatz has many important applications, especially in solving polynomial optimization problems and moment problems for compact semi-algebraic sets. Therefore, as a special case of Schmüdgen’s Positivstellensatz, Handelman’s theorem for polynomials plays an important role in application.

A matrix version of Pólya's Positivstellensatz was given by Scherer and Hol [13], with applications e.g. in robust polynomial semi-definite programs. Schmüdgen's theorem for operator polynomials has been discovered by Cimprič and Zalar [3]. Positivstellensätze for polynomial matrices have been studied by some other authors, see for example in [1, 2, 7, 12]. *The main aim of this paper is to give a version of Handelman's Positivstellensatz for polynomial matrices with an explicit degree bound.*

We need to introduce some notations. For $t \in \mathbb{N}^*$, let $\mathcal{M}_t(R)$ denote the ring of square matrices of order t with entries from a commutative unital ring R . Denote by $\mathcal{S}_t(R)$ the subset of $\mathcal{M}_t(R)$ consisting of all symmetric matrices.

In this paper we consider mainly R to be the ring $\mathbb{R}[X]$ of polynomials in n variables X_1, \dots, X_n with real coefficients. Each element $\mathbf{A} \in \mathcal{M}_t(\mathbb{R}[X])$ is a matrix whose entries are polynomials from $\mathbb{R}[X]$, called a *polynomial matrix*. Each element $\mathbf{A} \in \mathcal{M}_t(\mathbb{R}[X])$ is also called a *matrix polynomial*, because it can be viewed as a polynomial in X_1, \dots, X_n whose entries from $\mathcal{M}_t(\mathbb{R})$. Namely, we can write \mathbf{A} as

$$\mathbf{A} = \sum_{|\alpha|=0}^d \mathbf{A}_\alpha X^\alpha,$$

where $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$, $|\alpha| := \alpha_1 + \dots + \alpha_n$, $X^\alpha := X_1^{\alpha_1} \dots X_n^{\alpha_n}$, $\mathbf{A}_\alpha \in \mathcal{M}_t(\mathbb{R})$, d is the maximum over all degree of entries of \mathbf{A} , and it is called the *degree of the matrix polynomial* \mathbf{A} . To unify notation, throughout the paper each element of $\mathcal{M}_t(\mathbb{R}[X])$ is called a *polynomial matrix*.

For any polynomial matrix $\mathbf{A} \in \mathcal{M}_t(\mathbb{R}[X])$ and for any subset $K \subseteq \mathbb{R}^n$, by $\mathbf{A} \succcurlyeq 0$ (resp. $\mathbf{A} \succ 0$) on K we mean that for any $x \in K$, the matrix $\mathbf{A}(x)$ is *positive semidefinite* (resp. *positive definite*), i.e. all eigenvalues of the matrix $\mathbf{A}(x)$ are non-negative (resp. positive).

For any polynomial matrices $\mathbf{A}, \mathbf{B} \in \mathcal{M}_t(\mathbb{R}[X])$, the notation $\mathbf{A} \succcurlyeq \mathbf{B}$ on K means that $\mathbf{A} - \mathbf{B} \succcurlyeq \mathbf{0}$ on K .

Suppose that we have a convex, compact polyhedron $P \subseteq \mathbb{R}^n$ with non-empty interior, bounded by linear polynomials $L_1, \dots, L_m \in \mathbb{R}[X]$, defined by (1). Let $\mathbf{F} \in \mathcal{S}_t(\mathbb{R}[X])$ be a polynomial matrix of degree $d > 0$. Assume $\mathbf{F} \succ \mathbf{0}$ on P . The main result of this paper is presented in Theorem 3 which is a matrix version of Handelman's Positivstellensatz, stating that there exists a number N_0 such that for all integer $N > N_0$ the polynomial matrix \mathbf{F} can be written as

$$\mathbf{F} = \sum_{|\alpha|=N+d} \mathbf{F}_\alpha L_1^{\alpha_1} \dots L_m^{\alpha_m},$$

where $\mathbf{F}_\alpha \in \mathcal{S}_t(\mathbb{R})$ are positive definite scalar matrices with $|\alpha| = N + d$.

The main idea in the proof of this theorem inherits from Powers and Reznick [10], using a matrix version of Pólya's Positivstellensatz [13] and the continuity of eigenvalue functions of the polynomial matrix \mathbf{F} on the entries of \mathbf{F} (by [16, Theorem 1]). As a corollary of this theorem, we give a special case of Schmüdgen's Positivstellensatz for polynomial matrices positive definite on convex, compact polyhedra. Furthermore, we give a procedure to find such a representation for the polynomial matrix \mathbf{F} .

2 Representation of polynomial matrices positive definite on simplices

In this section we consider a simple case where P is an n -simplex with vertices $\{v_0, v_1, \dots, v_n\}$ and let $\{L_0, L_1, \dots, L_n\}$ be the set of barycentric coordinates of P , that is, each $L_i \in \mathbb{R}[X]$ is linear and

$$X = \sum_{i=0}^n L_i(X)v_i, \quad \sum_{i=0}^n L_i(X) = 1, \quad L_i(v_j) = \delta_{ij}. \tag{2}$$

Let $\mathbf{F} \in \mathcal{S}_t(\mathbb{R}[X])$ be a polynomial matrix of degree $d > 0$. We can express \mathbf{F} as

$$\mathbf{F}(X) = \sum_{|\alpha| \leq d} \mathbf{A}_\alpha X^\alpha,$$

where $\mathbf{A}_\alpha \in \mathcal{M}_t(\mathbb{R})$.

Let us consider the *Bernstein–Bézier form* of \mathbf{F} with respect to P :

$$\tilde{\mathbf{F}}_d(Y) := \tilde{\mathbf{F}}_d(Y_0, \dots, Y_n) := \sum_{|\alpha| \leq d} \mathbf{A}_\alpha \left(\sum_{i=0}^n Y_i v_i \right)^\alpha \left(\sum_{i=0}^n Y_i \right)^{d-|\alpha|}. \tag{3}$$

It is easy to see that $\tilde{\mathbf{F}}_d(Y) \in \mathcal{S}_t(\mathbb{R}[Y])$ is a homogeneous polynomial matrix of degree d . Moreover, it follows from the relations (2) that

$$\tilde{\mathbf{F}}_d(L_0, \dots, L_n) = \mathbf{F}(X).$$

Following Scherer and Hol [13], for each multi-index $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$, let us denote

$$\alpha! := \alpha_1! \dots \alpha_n!; \quad D_\alpha := \partial_1^{\alpha_1} \dots \partial_n^{\alpha_n}.$$

With these notations, we can re-write \mathbf{F} as

$$\mathbf{F}(X) = \sum_{|\alpha| \leq d} \frac{D_\alpha \mathbf{F}(0)}{\alpha!} X^\alpha.$$

With the spectral norm $\|\cdot\|$, following Scherer and Hol [13], we define

$$C(\mathbf{F}) := \max_{|\alpha| \leq d} \frac{\|D_\alpha \mathbf{F}(0)\|}{|\alpha!|}. \tag{4}$$

Using these notations, we have the following representation of polynomial matrices which are positive on simplices.

Theorem 2 Let $P \subseteq \mathbb{R}^n$ be an n -simplex given as above and $\mathbf{F} \in \mathcal{S}_t(\mathbb{R}[X])$ a polynomial matrix of degree $d > 0$. Assume that $\mathbf{F} \succcurlyeq \lambda \mathbf{I}_t$ on P for some $\lambda > 0$. Let $C := C(\widetilde{\mathbf{F}}_d)$. Then for each $N > \frac{d(d-1)C}{2\lambda} - d$, \mathbf{F} can be represented as

$$\mathbf{F} = \sum_{|\alpha|=N+d} \mathbf{F}_\alpha L_0^{\alpha_0} \dots L_n^{\alpha_n},$$

where each $\mathbf{F}_\alpha \in \mathcal{S}_t(\mathbb{R})$ is positive definite.

Proof Let us denote by Δ_{n+1} the standard simplex in \mathbb{R}^{n+1} , i.e.

$$\Delta_{n+1} = \left\{ (y_0, \dots, y_n) \in \mathbb{R}^{n+1} \mid y_i \geq 0, \sum_{i=0}^n y_i = 1 \right\}.$$

Since $\mathbf{F}(x) \succcurlyeq \lambda \mathbf{I}_t$ for all $x \in P$, the Bernstein–Bézier form $\widetilde{\mathbf{F}}_d$ of \mathbf{F} with respect to P satisfies

$$\widetilde{\mathbf{F}}_d(y_0, \dots, y_n) \succcurlyeq \lambda \mathbf{I}_t, \forall (y_0, \dots, y_n) \in \Delta_{n+1}.$$

Then it follows from Pólya's theorem for polynomial matrices [13, Theorem 3], that for each $N > \frac{d(d-1)C}{2\lambda} - d$,

$$\left(\sum_{i=0}^n Y_i \right)^N \widetilde{\mathbf{F}}_d(Y) = \sum_{|\alpha|=N+d} \mathbf{F}_\alpha Y_0^{\alpha_0} \dots Y_n^{\alpha_n}, \quad (5)$$

where each $\mathbf{F}_\alpha \in \mathcal{S}_t(\mathbb{R})$ is positive definite. Substituting Y_i by L_i on both sides of (5), noting that

$$\widetilde{\mathbf{F}}_d(L_0(X), \dots, L_n(X)) = \mathbf{F}(X) \text{ and } \sum_{i=0}^n L_i(X) = 1,$$

we obtain the required representation for \mathbf{F} . □

3 Representation of polynomial matrices positive definite on convex, compact polyhedra

Throughout this section, let $P \subseteq \mathbb{R}^n$ be a convex, compact polyhedron with non-empty interior, given by (1). By [15], there exist positive numbers $c_i \in \mathbb{R}$ such that $\sum_{i=1}^m c_i L_i(X) = 1$. Replacing each L_i by $c_i L_i$ we may assume that

$$\sum_{i=1}^m L_i(X) = 1. \quad (6)$$

Moreover, it is easy to check that for each $i = 1, \dots, n$, there exist real numbers $b_{ij} \in \mathbb{R}$, $j = 1, \dots, m$ such that

$$X_i = \sum_{j=1}^m b_{ij} L_j(X).$$

Let us consider the $n \times m$ matrix $\mathbf{B} := (b_{ij})_{i=1, \dots, n; j=1, \dots, m}$. Then for $X = (X_1, \dots, X_n)$ and $L = (L_1, \dots, L_m)$, we have $X^T = \mathbf{B} \cdot L^T$. In other words, we have

$$X = L \cdot \mathbf{B}^T. \quad (7)$$

Denote $\mathbb{R}[Y] := \mathbb{R}[Y_1, \dots, Y_m]$, and consider the ring homomorphism

$$\varphi: \mathbb{R}[Y] \rightarrow \mathbb{R}[X], \quad Y_i \mapsto L_i(X), \forall i = 1, \dots, m.$$

It follows from (6) that $\sum_{i=1}^m Y_i - 1 \in \text{Ker}(\varphi)$. Hence we may assume that the ideal $I := \text{Ker}(\varphi)$ is generated by polynomials $R_1(Y), \dots, R_s(Y) \in \mathbb{R}[Y]$,

$$I := \text{Ker}(\varphi) = \langle R_1(Y), \dots, R_s(Y) \rangle,$$

where $\sum_{i=1}^m Y_i - 1$ is one of the R_i 's.

Note that the homomorphism φ induces a ring homomorphism

$$M_\varphi: \mathcal{M}_t(\mathbb{R}[Y]) \longrightarrow \mathcal{M}_t(\mathbb{R}[X]), \quad \mathbf{G} = (g_{ij}(Y)) \mapsto (\varphi(g_{ij}(Y))).$$

Lemma 1 *The homomorphism M_φ is surjective, and*

$$\mathcal{I} := \text{Ker}(M_\varphi) = \langle R_1(Y)\mathbf{I}_t, \dots, R_s(Y)\mathbf{I}_t \rangle,$$

where \mathbf{I}_t denotes the identity matrix in $\mathcal{M}_t(\mathbb{R}[Y])$.

Proof For each $g(X) = \sum_{|\alpha| \leq d} a_\alpha X^\alpha \in \mathbb{R}[X]$, denote

$$\tilde{g}(Y) := \sum_{|\alpha| \leq d} a_\alpha (Y \cdot B^T)^\alpha \left(\sum_{i=1}^m Y_i \right)^{d-|\alpha|} \in \mathbb{R}[Y]. \quad (8)$$

It is clear that \tilde{g} is homogeneous of degree d . Moreover $\varphi(\tilde{g}(Y)) = g(X)$. Hence φ is surjective. Then the surjectivity of M_φ follows from that of φ .

On the other hand, $\mathbf{G} = (g_{ij}(Y)) \in \text{Ker}(M_\varphi)$ if and only if $g_{ij} \in \text{Ker}(\varphi)$ for all $i, j = 1, \dots, t$. Hence for each $i, j = 1, \dots, t$ we have

$$g_{ij}(Y) = \sum_{k=1}^s a_{ijk}(Y) R_k(Y), \text{ for some } a_{ijk}(Y) \in \mathbb{R}[Y].$$

Then \mathbf{G} can be written as

$$\mathbf{G} = \sum_{k=1}^s R_k \mathbf{A}_k = \sum_{k=1}^s (R_k \mathbf{I}_t) \mathbf{A}_k,$$

where $\mathbf{A}_k = (a_{ijk}(Y)) \in \mathcal{M}_t(\mathbb{R}[Y])$ for each $k = 1, \dots, s$. It is equivalent to the fact that $\mathbf{G} \in \langle R_1 \mathbf{I}_t, \dots, R_s \mathbf{I}_t \rangle$. The proof is complete. \square

Let $\mathbf{F} = (f_{ij}) \in \mathcal{S}_t(\mathbb{R}[X])$ be a polynomial matrix of degree $d > 0$. Denote $\widetilde{\mathbf{F}} := (\widetilde{f}_{ij}) \in \mathcal{S}_t(\mathbb{R}[Y])$, where each \widetilde{f}_{ij} is defined by (8), which is a homogeneous polynomial of degree d .

Assume $\lambda(\mathbf{F})$ is an eigenvalue function of \mathbf{F} . It follows from [16, Theorem 1] that $\lambda(\mathbf{F})$ is a continuous function on $f_{ij}(X)$, $i, j = 1, \dots, t$. That is, there exists a continuous function $\Lambda: \mathbb{R}^{t \times t} \rightarrow \mathbb{R}$ such that $\lambda(\mathbf{F}) = \Lambda(f_{ij}(X))$. Denote $\widetilde{\lambda}(\widetilde{\mathbf{F}})(Y) := \Lambda(\widetilde{f}_{ij}(Y))$, which is actually an eigenvalue function of the polynomial matrix $\widetilde{\mathbf{F}}$.

Denote $R(Y) := \sum_{i=1}^s R_i^2(Y)$. With the notations given above, we have the following useful lemma.

Lemma 2 *Let $\mathbf{F} = (f_{ij}) \in \mathcal{S}_t(\mathbb{R}[X])$ be a polynomial matrix of degree $d > 0$. Let $\lambda(\mathbf{F})$ is an eigenvalue function of \mathbf{F} . If $\lambda(\mathbf{F}) > 0$ on P , then there exists a sufficiently large constant c such that $\widetilde{\lambda}(\widetilde{\mathbf{F}}) + cR > 0$ on the standard m -simplex Δ_m . More explicitly, this holds for $c > -m_1/m_2$, where m_1 is the minimum of $\widetilde{\lambda}(\widetilde{\mathbf{F}})$ on Δ_m and m_2 is the minimum of the polynomial R on the compact set $\Delta_m \cap \{y \in \mathbb{R}^m \mid \widetilde{\lambda}(\widetilde{\mathbf{F}})(y) \leq 0\}$.*

Proof The proof goes along the same lines as the proof of [10, Lemma 4], using continuity of the function $\widetilde{\lambda}(\widetilde{\mathbf{F}})$. \square

Applying this lemma, we have

Lemma 3 *Let $\mathbf{F} = (f_{ij}) \in \mathcal{S}_t(\mathbb{R}[X])$ be a polynomial matrix of degree $d > 0$. Denote $\widetilde{\mathbf{F}} := (\widetilde{f}_{ij}) \in \mathcal{S}_t(\mathbb{R}[Y])$. Assume $\mathbf{F} \succ \mathbf{0}$ on P . Then there exists a sufficiently large constant c such that $\widetilde{\mathbf{F}} + cR\mathbf{I}_t \succ \mathbf{0}$ on the standard m -simplex Δ_m .*

Proof Since \mathbf{F} is positive definite on P , its eigenvalue functions $\lambda_k(\mathbf{F})$, $k = 1, \dots, t$, are positive on P . It follows from Lemma 2 that for each k , there exists a sufficiently large constant c_k such that $\widetilde{\lambda}_k(\widetilde{\mathbf{F}}) + c_k R$ is positive on Δ_m . Let $c := \max_{k=1, \dots, t} c_k$. Then $\widetilde{\lambda}_k(\widetilde{\mathbf{F}}) + cR$ is positive on Δ_m for each $k = 1, \dots, t$. Note that, $\lambda_k(\mathbf{F})$, $k = 1, \dots, t$, are eigenvalues of the polynomial matrix $\widetilde{\mathbf{F}}$. Moreover, the eigenvalues of the matrix $\widetilde{\mathbf{F}} + cR\mathbf{I}_t$ are $\widetilde{\lambda}_k(\widetilde{\mathbf{F}}) + cR$, $k = 1, \dots, t$. It follows that $\widetilde{\mathbf{F}} + cR\mathbf{I}_t$ is positive definite on Δ_m . The proof is complete. \square

Note that $\overline{\mathbf{F}} := \widetilde{\mathbf{F}} + cR\mathbf{I}_t$ need not be homogeneous. However, by homogenization $\overline{\mathbf{F}}$ by $\sum_{i=1}^m Y_i$, we obtain a homogeneous polynomial matrix of the same degree as $\overline{\mathbf{F}}$. More explicitly, if we express $\overline{\mathbf{F}}$ as

$$\overline{\mathbf{F}} = \sum_{|\beta| \leq d} \overline{\mathbf{F}}_\beta Y^\beta, \quad \overline{\mathbf{F}}_\beta \in \mathcal{S}_t(\mathbb{R}),$$

then its homogenization by $\sum_{i=1}^m Y_i$ is

$$\bar{\mathbf{F}}^h = \sum_{|\beta| \leq d} \bar{\mathbf{F}}_\beta Y^\beta \left(\sum_{i=1}^m Y_i \right)^{d-|\beta|}. \tag{9}$$

$\bar{\mathbf{F}}^h$ is a homogeneous polynomial matrix of degree d . Moreover, $M_\varphi(\bar{\mathbf{F}}^h) = \mathbf{F}$, and $\bar{\mathbf{F}}^h$ is positive definite on Δ_m .

Now we can state and prove the following matrix version of Handelman’s Positivstellensatz.

Theorem 3 *Let $P, \mathbf{F}, \bar{\mathbf{F}}, \bar{\mathbf{F}}^h$ be given as above, with \mathbf{F} positive definite on P . Assume that $\bar{\mathbf{F}}^h \succcurlyeq \lambda \mathbf{I}_t$ on Δ_m for some $\lambda > 0$. Let $d := \text{deg}(\bar{\mathbf{F}})$ and $C := C(\bar{\mathbf{F}}^h)$. Then for each $N > \frac{d(d-1)C}{2\lambda} - d$, \mathbf{F} can be represented as*

$$\mathbf{F} = \sum_{|\alpha|=N+d} \mathbf{F}_\alpha L_1^{\alpha_1} \dots L_m^{\alpha_m}, \tag{10}$$

where each $\mathbf{F}_\alpha \in \mathcal{S}_t(\mathbb{R})$ is positive definite.

Proof Firstly, applying the matrix version of Pólya’s Positivstellensatz given in [13, Theorem 3] for $\bar{\mathbf{F}}^h$, observing that $d = \text{deg}(\bar{\mathbf{F}}^h)$. Then, applying M_φ , using the fact that $M_\varphi(\bar{\mathbf{F}}^h) = \mathbf{F}$ and $\varphi(\sum_{i=1}^m Y_i) = 1$. □

As a summary, we formulate the construction given above as a procedure to find a representation for the polynomial matrix $\mathbf{F} = (f_{ij}) \in \mathcal{S}_t(\mathbb{R}[X])$ positive definite on a convex, compact polyhedron $P \subseteq \mathbb{R}^n$ as follows:

- (1) Following [4] to find positive constants $c_i \in \mathbb{R}$ such that $\sum_{i=1}^m c_i L_i(X) = 1$. Constructing the c_i ’s comes down to find a positive solution to an under-determined linear system.
- (2) Solving the system of equations

$$X_i = \sum_{j=1}^m b_{ij} L_j(X), \quad i = 1, \dots, n,$$

to find the matrix $\widetilde{\mathbf{B}} = (b_{ij})_{i=1, \dots, n; j=1, \dots, m}$.

- (3) Using (8) to find $\widetilde{f}_{ij}, i, j = 1, \dots, t$.
- (4) Using Gröbner bases to find a basis $\{R_1, \dots, R_s\}$ for the kernel $\text{Ker}(\varphi)$ of the ring homomorphism φ .
- (5) Following the proof of Lemma 3 to find a sufficiently large c such that $\widetilde{\mathbf{F}} + c \mathbf{R}\mathbf{I}_t \succ \mathbf{0}$ on Δ_m .
- (6) Using (9) to construct the homogenization $\bar{\mathbf{F}}^h$ of $\bar{\mathbf{F}} := \widetilde{\mathbf{F}} + c \mathbf{R}\mathbf{I}_t$.
- (7) Following the proof of Lemma 4 below to find the positive number λ such that $\bar{\mathbf{F}}^h(y) \succcurlyeq \lambda \mathbf{I}_t$ for all $y \in \Delta_m$.

Lemma 4 Let $K \subseteq \mathbb{R}^m$ be a non-empty compact set, and $\mathbf{G} \in \mathcal{S}_t(\mathbb{R}[Y])$. Then there exists a number $c \in \mathbb{R}$ such that

$$\mathbf{G}(y) \succcurlyeq c\mathbf{I}_t, \text{ for all } y \in K.$$

In particular, if $\mathbf{G}(y) \succ 0$ for all $y \in K$, then we can choose a number $c > 0$ such that $\mathbf{G}(y) \succcurlyeq c\mathbf{I}_t$, for all $y \in K$.

Proof Let $\lambda_1(\mathbf{G}), \dots, \lambda_t(\mathbf{G})$ be (real-valued) eigenvalue functions of the polynomial matrix $\mathbf{G} \in \mathcal{S}_t(\mathbb{R}[Y])$. It follows from [16, Theorem 1] that $\lambda_i(\mathbf{G})$ are continuous functions. Since K is compact, let

$$c_i := \min_{y \in K} \lambda_i(\mathbf{G})(y), \quad i = 1, \dots, t.$$

Denote $c := \min_{i=1, \dots, t} c_i$. Since eigenvalue functions of $\mathbf{G} - c\mathbf{I}_t$ are $\lambda_i(\mathbf{G}) - c$, $i = 1, \dots, t$, it follows from the definition of c that

$$\lambda_i(\mathbf{G})(y) - c \geq \lambda_i(\mathbf{G})(y) - c_i \geq 0$$

for all $y \in K$ and for all $i = 1, \dots, t$. This implies that $\mathbf{G}(y) \succcurlyeq c\mathbf{I}_t$, for all $y \in K$. \square

(8) Using the formula (4) to find the number $C := C(\overline{\mathbf{F}}^h)$.

(9) Find a number $N > \frac{d(d-1)C}{2} \frac{1}{\lambda} - d$.

(10) Find the matrix coefficients of the polynomial matrix $(\sum_{i=1}^m Y_i)^N \overline{\mathbf{F}}^h \in \mathcal{S}_t(\mathbb{R}[Y])$, substituting Y_i by $L_i(X)$, we obtain the desired representation for \mathbf{F} .

We illustrate the procedure given above by the following example which is computed explicitly using MATLAB Version 7.10 (Release 2010a) and its add-on GloptiPoly 3 discovered by Henrion et al. [5].

Example 1 Let us consider the unit square centered at the origin

$$P := \left\{ (x, y) \in \mathbb{R}^2 \mid L'_1 = 1 + x \geq 0, L'_2 = 1 - x \geq 0, \right. \\ \left. L'_3 = 1 + y \geq 0, L'_4 = 1 - y \geq 0 \right\}.$$

Choosing $c_1 = c_2 = c_3 = c_4 = \frac{1}{4}$, we have $\sum_{i=1}^4 c_i L'_i(x, y) = 1$. Therefore, consider

$$L_1 := \frac{1}{4} + \frac{1}{4}x, \quad L_2 := \frac{1}{4} - \frac{1}{4}x, \quad L_3 := \frac{1}{4} + \frac{1}{4}y, \quad L_4 := \frac{1}{4} - \frac{1}{4}y \in \mathbb{R}[x, y],$$

we have $\sum_{i=1}^4 L_i = 1$.

It is easy to see that the matrix $\mathbf{B} = \begin{bmatrix} 2 & -2 & 0 & 0 \\ 0 & 0 & 2 & -2 \end{bmatrix}$ satisfies the equation

$$\mathbf{B} \cdot [L_1 \ L_2 \ L_3 \ L_4]^T = [x \ y]^T.$$

Let $\varphi: \mathbb{R}[y_1, y_2, y_3, y_4] \rightarrow \mathbb{R}[x, y]$ be the ring homomorphism defined by $\varphi(y_i) := L_i(x, y), i = 1, 2, 3, 4$. Using any monomial ordering in $\mathbb{R}[y_1, y_2, y_3, y_4]$ we can find a Gröbner basis for the kernel $\text{Ker}(\varphi)$ of φ :

$$\{R_1, R_2\} := \left\{ y_1 + y_2 - \frac{1}{2}, y_3 + y_4 - \frac{1}{2} \right\}.$$

Consider $R := R_1^2 + R_2^2$.

Now we consider the polynomial matrix

$$\mathbf{F} := \begin{bmatrix} -4x^2y + 7x^2 + y + 3 & x^3 + 5xy - 3x \\ x^3 + 5xy - 3x & x^4 + x^2y + 3x^2 - 4y + 6 \end{bmatrix}.$$

Eigenvalue functions of \mathbf{F} are

$$\lambda_1(\mathbf{F}) = 6x^2 - 4x^2y - 4y + 6; \quad \lambda_2(\mathbf{F}) = x^4 + x^2y + 4x^2 + y + 3.$$

For any $(x, y) \in P$ we have $\lambda_i(\mathbf{F})(x, y) \geq 2, i = 1, 2$. Hence $\mathbf{F}(x, y) \succcurlyeq 2\mathbf{I}_2$ for every $(x, y) \in P$.

With the matrix \mathbf{B} considered above, using the formula (8), we find $\tilde{f}_{ij}, i, j = 1, 2$, and then we obtain the polynomial matrix $\tilde{\mathbf{F}} = (\tilde{f}_{ij})$. We can compute exactly the eigenvalue functions $\lambda_1(\tilde{\mathbf{F}})$ and $\lambda_2(\tilde{\mathbf{F}})$ of $\tilde{\mathbf{F}}$ which satisfy

$$\min_{\Delta_4} \lambda_1(\tilde{\mathbf{F}}) = 1, \quad \min_{\Delta_4} \lambda_2(\tilde{\mathbf{F}}) = -2.$$

Moreover, $\min_{\Delta_4 \cap \{\lambda_2(\tilde{\mathbf{F}}) \leq 0\}} R(y_1, y_2, y_3, y_4) = 0.125$. Thus we can choose

$$c > -\frac{-2}{0.125} = 16, \text{ namely, } c = 17,$$

for which $\bar{\mathbf{F}} := \tilde{\mathbf{F}} + cR\mathbf{I}_2 \succ \mathbf{0}$ on Δ_4 .

Homogenizing $\bar{\mathbf{F}}$ by $\sum_{i=1}^4 y_i$ we obtain a homogeneous polynomial matrix $\bar{\mathbf{F}}^h = (\bar{f}_{ij}^h)$. Then we compute exactly the eigenvalue functions of the matrix $\bar{\mathbf{F}}^h$ which satisfy

$$\min_{\Delta_4} \lambda_1(\bar{\mathbf{F}}^h) = 1.9706, \quad \min_{\Delta_4} \lambda_2(\bar{\mathbf{F}}^h) = 1.5294.$$

It follows that $\bar{\mathbf{F}}^h \succcurlyeq 1.5294 \mathbf{I}_2$ on Δ_4 , and put $\lambda := 1.5294$.

Using the formula (4), we can find the number $C := C(\overline{\mathbf{F}}^h) = \frac{1044}{24} = \frac{87}{2}$.

Therefore, choosing $N = 167$, the polynomial matrix $(y_1 + y_2 + y_3 + y_4)^{167} \overline{\mathbf{F}}^h$ has positive definite coefficients.

Find the matrix coefficients of the polynomial matrix $(y_1 + y_2 + y_3 + y_4)^{167} \overline{\mathbf{F}}^h \in \mathcal{S}_t(\mathbb{R}[y_1, y_2, y_3, y_4])$, substituting y_i by $L_i(x, y)$, we obtain the desired representation for \mathbf{F} .

As a consequence of Theorem 3, we obtain the following matrix version of Schmüdgen's Positivstellensatz for convex, compact polyhedra.

Corollary 2 *Let $P, \mathbf{F}, \overline{\mathbf{F}}, \overline{\mathbf{F}}^h$ be given as above, with \mathbf{F} positive definite on P . Assume that $\overline{\mathbf{F}}^h \succcurlyeq \lambda \mathbf{I}_t$ on Δ_m for some $\lambda > 0$. Let $d := \deg(\overline{\mathbf{F}})$ and $C := C(\overline{\mathbf{F}}^h)$. Then for $N > \frac{d(d-1)C}{2} \frac{1}{\lambda} - d$, \mathbf{F} can be represented as*

$$\mathbf{F} = \sum_{e=(e_1, \dots, e_m) \in \{0, 1\}^m} (\mathbf{F}_e^T \mathbf{F}_e) L_1^{e_1} \dots L_m^{e_m}, \quad (11)$$

where $\mathbf{F}_e \in \mathcal{M}_t(\mathbb{R}[X])$ and the degree of each sum of squares $\mathbf{F}_e^T \mathbf{F}_e$ does not exceed $N + d$.

Proof The proof follows directly from Theorem 3, with the observation that any positive definite matrix $\mathbf{F}_\alpha \in \mathcal{S}_t(\mathbb{R})$ can be written as

$$\mathbf{F}_\alpha = \mathbf{G}_\alpha^T \mathbf{G}_\alpha,$$

where $\mathbf{G}_\alpha \in \mathcal{M}_t(\mathbb{R})$ is a non-singular matrix. □

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