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A two-grid finite element approximation for a nonlinear time-fractional Cable equation

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Abstract In this article, a nonlinear fractional Cable equation is solved by a two-grid algorithm combined with finite element (FE) method. A temporal secondorder fully discrete two-grid FE scheme, in which the spatial direction is approximated by two-grid FE method and the integer and fractional derivatives in time are discretized by second-order two-step backward difference method and second-order weighted and shifted Grünwald difference (WSGD) scheme, is presented to solve nonlinear fractional Cable equation. The studied algorithm in this paper mainly covers two steps: First, the numerical solution of nonlinear FE scheme on the coarse grid is solved; second, based on the solution of initial iteration on the coarse grid, the linearized FE system on the fine grid is solved by using Newton iteration. Here, the stability based on fully discrete two-grid method is derived. Moreover, the a priori estimates with second-order convergence rate in time are proved in detail, which is higher than the L1 approximation result with $O(\tau^{2-\alpha} + \tau^{2-\beta})$. Finally, the numerical results by using the two-grid method and FE method are calculated, respectively,

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and the CPU time is compared to verify our theoretical results.

Keywords Two-grid method · WSGD operator · Nonlinear time-fractional Cable equation · Finite element method · Error results

1 Introduction

Fractional partial differential equations (FPDEs), which have a lot of applications in the realm of science, mainly include space FPDEs [1–7], time FPDEs [8– 18] and space-time FPDEs [19-21]. The construction of numerical methods for FPDEs has attracted great attention of many scholars. For example, finite element (FE) methods have been successfully applied to solving many FPDEs in the current literatures. In [7], Roop gave FE method for fractional advection-dispersion equations on bounded domains in two dimensions. Feng et al. [20] studied FE method for diffusion equation with space-time-fractional derivatives. Ma et al. [22] used moving FE methods to solve space-fractional differential equations. Li et al. [23] gave some numerical theories on FE methods for Maxwell's equations. Liu et al. [24] proposed a mixed FE method for a fourthorder time FPDE with first-order convergence rate in time. Liu et al. [25] solved a time-fractional reactiondiffusion problem with fourth-order space derivative term by using FE method and L1 approximation. Jin et al. [26] used a FE method to solve the space-

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fractional parabolic equation and gave the error analysis. Zeng et al. [27] used FE approaches combined with finite difference method for solving the timefractional subdiffusion equation. Ford et al. [28] studied a FE method for time FPDEs and obtained optimal convergence error estimates. Bu et al. [29] discussed Galerkin FE method for Riesz space-fractional diffusion equations in two-dimensional case. Li et al. [30] applied FE method to solving nonlinear fractional subdiffusion and superdiffusion equations. In [31], Deng solved fractional Fokker–Planck equation with space and time derivatives by using FE method. Zhang et al. [32] implemented FE method for solving a modified fractional diffusion equation in two-dimensional case.

In this article, we will consider a two-grid FE algorithm for solving a nonlinear time-fractional Cable equation

$$\frac{\partial u}{\partial t} = -{}^{R}_{0}\partial^{\alpha}_{t}u + {}^{R}_{0}\partial^{\beta}_{t}\Delta u - \mathcal{F}(u) + g(\mathbf{x}, t), (\mathbf{x}, t) \in \Omega \times J,$$
(1)

which covers boundary condition

$$u(\mathbf{x},t) = 0, \, (\mathbf{x},t) \in \partial \Omega \times \bar{J},\tag{2}$$

and initial condition

$$u(\mathbf{x}, 0) = u_0(\mathbf{x}), \, \mathbf{x} \in \Omega, \tag{3}$$

where Ω is a bounded convex polygonal sub-domain of $R^d(d \leq 2)$, whose boundary $\partial \Omega$ is *Lipschitz* continuous. J = (0, T] is the time interval with the upper bound T. The source item $g(\mathbf{x}, t)$ and the initial function $u_0(\mathbf{x})$ are given known functions. For the nonlinear term $\mathcal{F}(u)$, there exists a constant C > 0such that $|\mathcal{F}(u)| \leq C|u|$ and $|\mathcal{F}'(u)| \leq C$. And ${}_0^R \partial_t^{\gamma} w(\mathbf{x}, t)$ is Riemann–Liouville fractional derivative with $\gamma \in (0, 1)$ given in Definition 1.

The fractional Cable equation [33–36], which reflects the anomalous electro-diffusion in nerve cells, is an important mathematical model. For the fractional Cable equation, we can find some numerical methods, such as finite difference methods [37–41], orthogonal spline collocation method [42], spectral approximations [43,44], finite element methods [45,46]. Chen et al. [37], Hu and Zhang [38], Yu and Jiang [39], Quintana-Murillo and Yuste [40] presented and ana-

lyzed some finite difference schemes to numerically solve the fractional Cable equation from different perspectives. Liu et al. [41], solved numerically the fractional Cable equation by using two implicit numerical schemes. Zhang et al. [42] proposed and analyzed the discrete-time orthogonal spline collocation method for the two-dimensional case of fractional Cable equation. Bhrawy and Zaky [43] presented a Jacobi spectral collocation approximation for numerically solving nonlinear two-dimensional fractional Cable equation covering Caputo fractional derivative. Lin et al. [44] developed spectral approximations combined with finite difference method for looking for the numerical solution of the fractional Cable equation. Recently, Zhuang et al. [45], Liu et al. [46] studied and analyzed Galerkin finite element methods for the fractional Cable equation with Riemann-Liouville derivative, respectively, and did some different analysis based on different approximate formula for fractional derivative. Here, we will consider a two-grid FE algorithm combined with a higher-order time approximation to seek the numerical solutions of nonlinear fractional Cable equation.

Two-grid FE algorithm was presented and developed by Xu [47,48]. Owing to holding the advantage of saving computation time, many computational scholars have used well the method to numerically solve integerorder partial differential equations(such as Dawson and Wheeler[49] for nonlinear parabolic equations; Zhong et al. [50] for time-harmonic Maxwell equations; Mu and Xu [51] for mixed Stokes–Darcy model; Chen and Chen [52] for nonlinear reaction-diffusion equations; Bajpai and Nataraj [53] for Kelvin–Voigt model; Wang [54] for semilinear evolution equations with positive memory) and developed some new numerical techniques based on the idea of two-grid algorithm (twogrid expanded mixed FE methods in Chen et al. [55], Wu and Allen [56], Liu et al. [57]; two-grid finite volume element method in Chen and Liu [58]). Until recently, in [59], the two-grid FE method was presented to solve the nonlinear fourth-order fractional differential equations with Caputo fractional derivative. However, the Caputo time-fractional derivative was approximated by L1 formula and the only $(2 - \alpha)$ -order convergence rate in time was arrived at in [59].

In this article, our main task is to look for the numerical solution of nonlinear fractional Cable equation (1) with initial and boundary condition by using two-grid FE method with higher-order time approximate scheme [60,61] and to discuss the numerical theories on stability and a priori estimate analysis for this method. Tian et al. [60] approximated the Riemann–Liouville fractional derivative by proposing a new higher-order WSGD operator and then discussed some finite difference scheme based on this operator. Considering this idea of WSGD operator, Wang and Vong [61] presented the compact difference scheme for the modified anomalous subdiffusion equation with α -order Caputo fractional derivative, in which the Caputo fractional derivative covering order $\alpha \in (0, 1)$ is approximated by applying the idea of WSGD operator, and an extension for this idea was also made to discuss a compact difference scheme for the fractional diffusion-wave equation. However, the theories of the FE methods based on the idea of WSGD operator have not been studied and discussed. In particular, the two-grid FE algorithm combined with the idea of the WSGD operator has not been reported in the current literatures. Here, we will study the two-grid FE scheme with WSGD operator for solving nonlinear fractional Cable equation, derive the stability of the studied method and prove a priori estimate results with second-order convergence rate, which is higher than time convergence rate $O(\tau^{2-\alpha} + \tau^{2-\beta})$ obtained by usual L1 approximation. Finally, we do some numerical computations by using the current method and standard nonlinear FE method, respectively, and find that our method in CPU time is more efficient than standard nonlinear FE method.

Throughout this article, we will denote C > 0 as a constant, which is free of the spatial coarse grid size H, fine step length h, and time mesh size τ . Further, we define the natural inner product in $L^2(\Omega)$ or $(L^2(\Omega))^2$ by (\cdot, \cdot) equipped with norm $\|\cdot\|$.

The remaining outline of the article is as follows. In Sect. 2, some definitions of fractional derivatives, lemmas on time approximations and two-grid algorithm combined with second-order scheme in time are given. In Sect. 3, the analysis of stability of two-grid FE method is made. In Sect. 4, a priori errors of two-grid FE algorithm are proved. In Sect. 5, some numerical results by using two-grid FE method and standard nonlinear FE method are computed and some comparisons of computing time are done. Finally, some remarking conclusions on twogrid FE algorithm proposed in this paper are shown in Sect. 6.

2 Fractional derivatives and two-grid FE method

2.1 Fractional derivatives and approximate formula

In many literatures, we can get the following definitions on fractional derivatives of Caputo type and Riemann– Liouville type. At the same time, we need to give some useful lemmas in the subsequent theoretical analysis.

Definition 1 The γ -order (0 < γ < 1) fractional derivative of Riemann–Liouville type for the function w(t) is defined as

$${}^{R}_{0}\partial^{\alpha}_{t}w(t) = \frac{1}{\Gamma(1-\gamma)}\frac{\mathrm{d}}{\mathrm{d}t}\int_{0}^{t}\frac{w(\tau)}{(t-\tau)^{\gamma}}\mathrm{d}\tau.$$
(4)

Definition 2 The γ -order ($0 < \gamma < 1$) fractional derivative of Caputo type for the function w(t) is defined by

$${}_{0}^{C}\partial_{t}^{\gamma}w(t) = \frac{1}{\Gamma(1-\gamma)}\int_{0}^{t}\frac{w'(\tau)}{(t-\tau)^{\gamma}}\mathrm{d}\tau,$$
(5)

where $\Gamma(\cdot)$ is Gamma function.

Lemma 1 [62] *The relationship between Caputo fractional derivative and Riemann–Liouville fractional derivative can be given by*

$${}^{R}_{0}\partial^{\gamma}_{t}w(t) = {}^{C}_{0}\partial^{\gamma}_{t}w(t) + \frac{w(0)t^{-\gamma}}{\Gamma(1-\gamma)}.$$
(6)

Lemma 2 For $0 < \gamma < 1$, the following approximate formula [60,61] with second-order accuracy at time $t = t_{n+1}$ holds

$${}_{0}^{R}\partial_{t}^{\gamma}w(\mathbf{x},t_{n+1}) = \sum_{i=0}^{n+1} \frac{p_{\gamma}(i)}{\tau^{\gamma}}w(\mathbf{x},t_{n+1-i}) + O(\tau^{2}),$$
(7)

where

$$p_{\gamma}(i) = \begin{cases} \frac{\gamma+2}{2}g_{0}^{\gamma}, & \text{if } i = 0, \\ \frac{\gamma+2}{2}g_{i}^{\gamma} + \frac{-\gamma}{2}g_{i-1}^{\gamma}, & \text{if } i > 0, \end{cases}$$

$$g_{0}^{\gamma} = 1, g_{i}^{\gamma} = \frac{\Gamma(i-\gamma)}{\Gamma(-\gamma)\Gamma(i+1)},$$

$$g_{i}^{\gamma} = \left(1 - \frac{\gamma+1}{i}\right)g_{i-1}^{\gamma}, i \ge 1.$$
(9)

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Lemma 3 For series $\{g_i^{\gamma}\}$ defined in Lemma 2, we have

$$g_0^{\gamma} = 1 > 0, \ g_i^{\gamma} < 0, (i = 1, 2...), \sum_{i=1}^{\infty} g_i^{\gamma} = -1,$$
(10)

Lemma 4 For series $\{p_{\gamma}(i)\}$ given by (8), the following inequality holds for any integer n

$$\sum_{i=0}^{n+1} |p_{\gamma}(i)| \le C.$$
(11)

Proof Noting that the notation (8), we have

$$\sum_{i=0}^{n+1} |p_{\gamma}(i)| = \frac{\gamma+2}{2}g_0^{\gamma} + \sum_{i=1}^{n+1} \left|\frac{\gamma+2}{2}g_i^{\gamma} + \frac{-\gamma}{2}g_{i-1}^{\gamma}\right|.$$
(12)

Applying triangle inequality and lemma 3, we arrive at

$$\sum_{i=0}^{n+1} |p_{\gamma}(i)| \leq \left(\frac{\gamma+2}{2}g_{0}^{\gamma} + \sum_{i=1}^{n+1} \left| -\frac{\gamma+2}{2}g_{i}^{\gamma} \right| + \sum_{i=1}^{n+1} \left| \frac{-\gamma}{2}g_{i-1}^{\gamma} \right| \right) \leq \left((\gamma+1)g_{0}^{\gamma} + \frac{\gamma+2}{2}\sum_{i=1}^{n+1} -g_{i}^{\gamma} + \frac{\gamma}{2}\sum_{i=1}^{n} -g_{i}^{\gamma} \right) \leq 2\gamma+2.$$
(13)

So, we get the conclusion of lemma.

Lemma 5 [60,61] Let $\{p_{\gamma}(i)\}$ be defined as in (8). Then for any positive integer L and real vector $(w^0, w^1, \dots, w^L) \in \mathbb{R}^{L+1}$, it holds that

$$\sum_{n=0}^{L} \left(\sum_{i=0}^{n} p_{\gamma}(i) w^{n-i} \right) w^{n} \ge 0.$$
 (14)

Remark 1 Based on the relationship (6) between Caputo fractional derivative and Riemann–Liouville fractional derivative, we easily find that the equality $_{0}^{R} \partial_{t}^{\gamma} w(t) =_{0}^{C} \partial_{t}^{\gamma} w(t)$ with w(0) = 0 holds. Further, it is not hard to know that the second-order discrete formula (7) in lemma 2 can also approximate the Caputo fractional derivative (5) with zero initial value.

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2.2 Two-grid algorithm based on FE scheme

To give the fully discrete analysis, we should approximate both integer and fractional derivatives. The grid points in the time interval [0, T] are labeled as $t_i = i\tau$, i = 0, 1, 2, ..., M, where $\tau = T/M$ is the time step length. We define $w^n = w(t_n)$ for a smooth function on [0, T] and $\delta_t^n w^n = \frac{w^n - w^{n-1}}{\tau}$.

Using the approximate formula (7) and two-step backward Euler approximation and then applying Green's formula, we find $u^{n+1} : [0, T] \mapsto H_0^1$ to arrive at the weak formulation of (1)–(3) for any $v \in H_0^1$ as Case n = 0:

$$\begin{pmatrix} \delta_t^1 u^1, v \end{pmatrix} + \sum_{i=0}^1 \frac{p_\alpha(i)}{\tau^\alpha} (u^{1-i}, v) + \sum_{i=0}^1 \frac{p_\beta(i)}{\tau^\beta} (\nabla u^{1-i}, \nabla v) + (\mathcal{F}(u^1), v) = (g^1, v) + (\bar{e}_1^1, v) + (\bar{e}_2^1, v) + (\Delta \bar{e}_3^1, v),$$
(15)

Case $n \ge 1$:

$$\begin{pmatrix} \frac{3}{2}\delta_{t}^{n+1}u^{n+1} - \frac{1}{2}\delta_{t}^{n}u^{n}, v \end{pmatrix} + \sum_{i=0}^{n+1} \frac{p_{\alpha}(i)}{\tau^{\alpha}}(u^{n+1-i}, v) + \sum_{i=0}^{n+1} \frac{p_{\beta}(i)}{\tau^{\beta}}(\nabla u^{n+1-i}, \nabla v) + (\mathcal{F}(u^{n+1}), v) = (g^{n+1}, v) + (\bar{e}_{1}^{n+1}, v) + (\bar{e}_{2}^{n+1}, v) + (\Delta \bar{e}_{3}^{n+1}, v),$$
(16)

where

$$\bar{e}_1^{n+1} = \begin{cases} \delta_t^1 u^1 - u(t_1) = O(\tau), & n = 0, \\ \frac{3}{2} \delta_t^{n+1} u^{n+1} - \frac{1}{2} \delta_t^n u^n - u_t(t_{n+1}) = O(\tau^2), & n \ge 1, \end{cases}$$
(17)

$$\bar{e}_2^{n+1} = O(\tau^2), n \ge 0,$$
 (18)

$$\overline{z}_3^{n+1} = O(\tau^2), n \ge 0.$$
⁽¹⁹⁾

For formulating finite element algorithm, we choose finite element space $V_h \subset H_0^1$ as

$$V_{h} = \{ v_{h} \in H_{0}^{1}(\Omega) \cap C^{0}(\overline{\Omega}) \mid v_{h}|_{e} \in Q_{m}(e), \\ \forall e \in \mathcal{K}_{h} \},$$
(20)

where \mathcal{K}_h is the quasiuniform rectangular partition for the spatial domain Ω . Then, we find $u_h^{n+1} \in V_h (n = 0, 1, ..., N_\tau - 1)$ to

Then, we find $u_h^{n+1} \in V_h (n = 0, 1, ..., N_\tau - 1)$ to formulate a standard nonlinear finite element system for any $v_h \in V_h$ as

Case
$$n = 0$$
:
 $\left(\delta_{t}^{1}u_{h}^{1}, v_{h}\right) + \sum_{i=0}^{1} \frac{p_{\alpha}(i)}{\tau^{\alpha}}(u_{h}^{1-i}, v_{h})$
 $+ \sum_{i=0}^{1} \frac{p_{\beta}(i)}{\tau^{\beta}}(\nabla u_{h}^{1-i}, \nabla v_{h})$
 $+ (\mathcal{F}(u_{h}^{1}), v_{h}) = (g^{1}, v_{h}),$
(21)

Case $n \ge 1$:

$$\begin{pmatrix} \frac{3}{2} \delta_t^{n+1} u_h^{n+1} - \frac{1}{2} \delta_t^n u_h^n, v_h \end{pmatrix} + \sum_{i=0}^{n+1} \frac{p_\alpha(i)}{\tau^\alpha} (u_h^{n+1-i}, v_h) + \sum_{i=0}^{n+1} \frac{p_\beta(i)}{\tau^\beta} (\nabla u_h^{n+1-i}, \nabla v_h) + (\mathcal{F}(u_h^{n+1}), v_h) = (g^{n+1}, v_h).$$
(22)

For improving the finite element discrete system (21)–(22), we consider the following two-grid FE system based on the coarse grid \mathfrak{T}_H and the fine grid \mathfrak{T}_h .

Step I: First, the following nonlinear system based on the coarse grid \mathfrak{T}_H is solved by finding the solution $u_H^{n+1}: [0, T] \mapsto V_H \subset V_h$ such that

Case
$$n = 0$$
:

$$\begin{pmatrix} \delta_t^1 u_H^1, v_H \end{pmatrix} + \sum_{i=0}^1 \frac{p_\alpha(i)}{\tau^\alpha} (u_H^{1-i}, v_H) + \sum_{i=0}^1 \frac{p_\beta(i)}{\tau^\beta} (\nabla u_H^{1-i}, \nabla v_H) + (\mathcal{F}(u_H^1), v_H) = (g^1, v_H),$$
 (23)

Case $n \ge 1$:

$$\begin{pmatrix} \frac{3}{2} \delta_t^{n+1} u_H^{n+1} - \frac{1}{2} \delta_t^n u_H^n, v_H \end{pmatrix} + \sum_{i=0}^{n+1} \frac{p_\alpha(i)}{\tau^\alpha} (u_H^{n+1-i}, v_H) + \sum_{i=0}^{n+1} \frac{p_\beta(i)}{\tau^\beta} (\nabla u_H^{n+1-i}, \nabla v_H) + (\mathcal{F}(u_H^{n+1}), v_H) = (g^{n+1}, v_H).$$
(24)

Step II: Second, based on the solution $u_H^{n+1} \in V_H$ on the coarse grid \mathfrak{T}_H , the following linear system on the fine grid \mathfrak{T}_h is considered by looking for U_h^{n+1} : $[0, T] \mapsto V_h$ such that

Case n = 0:

$$\left(\delta_t^1 U_h^1, v_h\right) + \sum_{i=0}^1 \frac{p_\alpha(i)}{\tau^\alpha} (U_h^{1-i}, v_h)$$

$$+\sum_{i=0}^{1} \frac{p_{\beta}(i)}{\tau^{\beta}} (\nabla U_{h}^{1-i}, \nabla v_{h}) + (\mathcal{F}(u_{H}^{1}) + \mathcal{F}'(u_{H}^{1})(U_{h}^{1} - u_{H}^{1}), v_{h}) = (g^{1}, v_{h}),$$
(25)

$$\frac{3}{2}\delta_{t}^{n+1}U_{h}^{n+1} - \frac{1}{2}\delta_{t}^{n}U_{h}^{n}, v_{h}\right) + \sum_{i=0}^{n+1}\frac{p_{\alpha}(i)}{\tau^{\alpha}}(U_{h}^{n+1-i}, v_{h}) + \sum_{i=0}^{n+1}\frac{p_{\beta}(i)}{\tau^{\beta}}(\nabla U_{h}^{n+1-i}, \nabla v_{h}) + (\mathcal{F}(u_{H}^{n+1}) + \mathcal{F}'(u_{H}^{n+1})(U_{h}^{n+1} - u_{H}^{n+1}), v_{h}) = (g^{n+1}, v_{h}),$$
(26)

where $h \ll H$.

Case $n \ge 1$:

Remark 2 In the solving system above, we can seek a solution $u_H^{n+1} \in V_H$ on the coarse grid \mathfrak{T}_H in the nonlinear system (23)–(24) and then get the solution $U_h^{n+1} \in V_h$ on the fine grid \mathfrak{T}_h in the linear system (25)–(26). We call the system (23)–(24) with (25)–(26) as two-grid FE system, which is more efficient than the standard nonlinear FE system (21)–(22). In the results of numerical calculations, we will see the CPU time used by two-grid FE scheme is less than that by standard nonlinear FE scheme.

In what follows, for the convenience of discussions on stability and a priori error analysis, we first give the following lemma.

Lemma 6 For series $\{w^n\}$, the following inequality holds

$$\left(\frac{3}{2}\delta_{t}^{n+1}w^{n+1} - \frac{1}{2}\delta_{t}^{n}w^{n}, w^{n+1}\right) \\ \geq \frac{1}{4\tau} [\Lambda(w^{n+1}, w^{n}) - \Lambda(w^{n}, w^{n-1})],$$
 (27)

where

$$\Lambda(w^n, w^{n-1}) \triangleq \|w^n\|^2 + \|2w^n - w^{n-1}\|^2.$$
(28)

In the next process, we firstly consider the stability for systems (23)–(24) and (25)–(26).

We first derive the stability based on two-grid FE algorithm.

Theorem 1 For the two-grid FE system (23)–(26) based on coarse grid \mathfrak{T}_H and fine grid \mathfrak{T}_h , the following stable inequality for $U_h^n \in V_h$ holds

$$\|U_h^n\|^2 \le C(\|U_h^0\|^2 + \|u_H^0\|^2 + \max_{0 \le i \le n} \|g^i\|^2), \quad (29)$$

Proof We first consider the results for the case $n \ge 1$. Setting $v_h = U_h^{n+1}$ in (26), and noting that the inequality (27), we have

$$\frac{1}{4\tau} \left[\Lambda(U_{h}^{n+1}, U_{h}^{n}) - \Lambda(U_{h}^{n}, U_{h}^{n-1}) \right] \\
+ \sum_{i=0}^{n+1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (U_{h}^{n+1-i}, U_{h}^{n+1}) \\
+ \sum_{i=0}^{n+1} \frac{p_{\beta}(i)}{\tau^{\beta}} (\nabla U_{h}^{n+1-i}, \nabla U_{h}^{n+1}) \\
= -(\mathcal{F}(u_{H}^{n+1}) + \mathcal{F}'(u_{H}^{n+1})(U_{h}^{n+1} - u_{H}^{n+1}), U_{h}^{n+1}) \\
+ (g^{n+1}, U_{h}^{n+1}).$$
(30)

Using Cauchy–Schwarz inequality and Young inequality, we easily get

$$\frac{1}{4\tau} \left[\Lambda(U_{h}^{n+1}, U_{h}^{n}) - \Lambda(U_{h}^{n}, U_{h}^{n-1}) \right] \\
+ \sum_{i=0}^{n+1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (U_{h}^{n+1-i}, U_{h}^{n+1}) \\
+ \sum_{i=0}^{n+1} \frac{p_{\beta}(i)}{\tau^{\beta}} (\nabla U_{h}^{n+1-i}, \nabla U_{h}^{n+1}) \\
\leq C \|u_{H}^{n+1}\| \|U_{h}^{n+1}\| + \|\mathcal{F}'(u_{H}^{n+1})\|_{\infty} (\|U_{h}^{n+1}\|^{2} \\
+ \|u_{H}^{n+1}\| \|U_{h}^{n+1}\|) + \|g^{n+1}\| \|U_{h}^{n+1}\| \\
\leq C (\|u_{H}^{n+1}\|^{2} + \|U_{h}^{n+1}\|^{2} + \|g^{n+1}\|^{2}). \tag{31}$$

Sum (31) for n from 1 to L and use (27) to get

$$\Lambda(U_h^{n+1}, U_h^n) + \tau^{1-\alpha} \sum_{n=1}^{L} \sum_{i=0}^{n+1} p_{\alpha}(i)(U_h^{n+1-i}, U_h^{n+1}) + \tau^{1-\beta} \sum_{n=1}^{L} \sum_{i=0}^{n+1} p_{\beta}(i)(\nabla U_h^{n+1-i}, \nabla U_h^{n+1})$$

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$$\leq C\tau \sum_{n=1}^{L} (\|u_{H}^{n+1}\|^{2} + \|U_{h}^{n+1}\|^{2} + \|g^{n+1}\|^{2}).$$
(32)

Set $v_h = U_h^1$ in (25) and use Cauchy–Schwarz inequality and Young inequality to arrive at

$$\begin{pmatrix} \delta_{t}^{1} U_{h}^{1}, U_{h}^{1} \end{pmatrix} + \sum_{i=0}^{1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (U_{h}^{1-i}, U_{h}^{1}) \\ + \sum_{i=0}^{1} \frac{p_{\beta}(i)}{\tau^{\beta}} (\nabla U_{h}^{1-i}, \nabla U_{h}^{1}) = -(\mathcal{F}(u_{H}^{1})) \\ + \mathcal{F}'((u_{H}^{1})(U_{h}^{1} - u_{H}^{1}), U_{h}^{1}) + (g^{1}, U_{h}^{1}) \\ \leq C(||u_{H}^{1}||^{2} + ||U_{h}^{1}||^{2} + ||g^{1}||^{2}).$$
(33)

From (33), it easily follows that

$$\begin{split} \|U_{h}^{1}\|^{2} + \tau^{1-\alpha} \sum_{i=0}^{1} p_{\alpha}(i)(U_{h}^{1-i}, U_{h}^{1}) \\ + \tau^{1-\beta} \sum_{i=0}^{1} p_{\beta}(i)(\nabla U_{h}^{1-i}, \nabla U_{h}^{1}) \\ \leq C\tau(\|u_{H}^{1}\|^{2} + \|U_{h}^{0}\|^{2} + \|U_{h}^{1}\|^{2} + \|g^{1}\|^{2}). \end{split}$$
(34)

Make a combination for (32) and (34) to get

$$\begin{aligned} \|U_{h}^{L}\|^{2} + \tau^{1-\alpha} \sum_{n=0}^{L} \sum_{i=0}^{n} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (U_{h}^{n-i}, U_{h}^{n}) \\ + \tau^{1-\beta} \sum_{n=0}^{L} \sum_{i=0}^{n} \frac{p_{\beta}(i)}{\tau^{\beta}} (\nabla U_{h}^{n-i}, \nabla U_{h}^{n}) \\ \leq C\tau \sum_{n=0}^{L} (\|u_{H}^{n}\|^{2} + \|U_{h}^{n}\|^{2} + \|g^{n}\|^{2}) + C\|U_{h}^{0}\|^{2}. \end{aligned}$$

$$(35)$$

Note that lemma 5 and use Cronwall lemma to get

$$\|U_h^L\|^2 \le C \|U_h^0\|^2 + C\tau \sum_{n=0}^L (\|u_H^n\|^2 + \|g^n\|^2).$$
(36)

For the next estimates, we have to discuss the term $||u_H^n||^2$.

In (23) and (24), we take u_H^1 and u_H^{n+1} for v_H , respectively, and use a similar process of derivation to the $||U_h^L||^2$ to arrive at

$$\|u_{H}^{n}\|^{2} \le C(\|u_{H}^{0}\|^{2} + \max_{0 \le i \le n} \|g^{i}\|^{2})$$
(37)

Substitute (37) into (36) and note that $\tau \sum_{n=0}^{L} \leq T$ to get

$$\|U_{h}^{L}\|^{2} \leq C(\|U_{h}^{0}\|^{2} + \|u_{H}^{0}\|^{2} + \max_{0 \leq i \leq L} \|g^{i}\|^{2}), \quad (38)$$

which indicate that the conclusion (29) of Theorem 1 holds.

4 Error analysis based on two-grid algorithm

For discussing and deriving a priori error estimates based on fully discrete two-grid FE method, we have to introduce a Ritz projection operator which is defined by finding $\Psi_{\hbar}: H_0^1(\Omega) \to V_{\hbar}$ such that

$$(\nabla(\Psi_{\hbar}w), \nabla w_{\hbar}) = (\nabla w, \nabla w_{\hbar}), \forall w_{\hbar} \in V_{\hbar}, \qquad (39)$$

with the following estimate

$$\begin{aligned} \|w - \Psi_{\hbar}w\| + \hbar \|w - \Psi_{\hbar}w\|_1 &\leq C\hbar^{r+1} \|w\|_{r+1}, \\ \forall w \in H_0^1(\Omega) \cap H^{r+1}(\Omega), \end{aligned}$$
(40)

where \hbar is coarse grid step length H or fine grid size hand the norms are defined by $||w||_l = \left(\sum_{0 \le |\theta| \le l} \int_{\Omega} |D^{\theta}| \right)$

$$w|^2 d\mathbf{x}$$
)² with the polynomial's degree l

In the following contents, based on the given Ritz projection [63] and estimate inequality (40), we will do some detailed discussions on a priori error analysis.

Now we rewrite the errors as

$$u(t_n) - U_h^n = (u(t_n) - \Psi_h U^n) + (\Psi_h U^n - U_h^n) = \mathfrak{P}_u^n + \mathfrak{M}_u^n.$$

Theorem 2 With $u(t_n) \in H_0^1(\Omega) \cap H^{r+1}(\Omega)$, $U_h^n \in V_h$ and $U_h^0 = \Psi_h u(0)$, we obtain the following a priori error results in L^2 -norm

$$\|u(t_n) - U_h^n\| \le C[\tau^2 + (1 + \tau^{-\alpha})h^{r+1} + (1 + \tau^{-2\alpha})H^{2r+2}],$$
(41)

where C is a positive constant independent of coarse grid step length H, fine grid size h and time step parameters τ .

Proof Combine (26) and (7) with (39) to arrive at the error equations for any $v_h \in V_h$ and $n \ge 1$

$$\left(\frac{3}{2}\delta_t^{n+1}\mathfrak{M}_u^{n+1} - \frac{1}{2}\delta_t^n\mathfrak{M}_u^n, v_h\right) + \sum_{i=0}^{n+1}\frac{p_{\alpha}(i)}{\tau^{\alpha}}(\mathfrak{M}_u^{n+1-i}, v_h)$$

$$+\sum_{i=0}^{n+1} \frac{p_{\beta}(i)}{\tau^{\beta}} (\nabla \mathfrak{M}_{u}^{n+1-i}, \nabla v_{h})$$

$$= -\left(\frac{3}{2} \delta_{t}^{n+1} \mathfrak{P}_{u}^{n+1} - \frac{1}{2} \delta_{t}^{n} \mathfrak{P}_{u}^{n}, v_{h}\right)$$

$$-\sum_{i=0}^{n+1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (\mathfrak{P}_{u}^{n+1-i}, v_{h})$$

$$- (\mathcal{F}(u^{n+1}) - \mathcal{F}(u_{H}^{n+1})$$

$$+ \mathcal{F}'(u_{H}^{n+1}) (\mathfrak{M}_{u}^{n+1} + \mathfrak{P}_{u}^{n+1} - u^{n+1} + u_{H}^{n+1}), v_{h})$$

$$+ (\bar{e}_{1}^{n+1}, v_{h}) + (\bar{e}_{2}^{n+1}, v_{h}) + (\Delta \bar{e}_{3}^{n+1}, v_{h})$$

$$\doteq I_{1} + I_{2} + I_{3} + I_{4} + I_{5} + I_{6}.$$
(42)

In what follows, we need to estimate the terms I_j , j = 1, ..., 6. First we estimate the third term I_3 . For considering the nonlinear term, we use Taylor expansion to obtain

$$\mathcal{F}(u^{n+1}) - \mathcal{F}(u_H^{n+1}) = \mathcal{F}'(u_H^{n+1})(u^{n+1} - u_H^{n+1}) + \frac{1}{2}\mathcal{F}''(\chi^{n+1})(u^{n+1} - u_H^{n+1})^2,$$
(43)

where χ^{j} is a value between u^{j} and u_{H}^{j} .

Based on (43), we obtain

$$\mathcal{F}(u^{n+1}) - \mathcal{F}(u_{H}^{n+1}) + \mathcal{F}'(u_{H}^{n+1})(\mathfrak{M}_{u}^{n+1} + \mathfrak{P}_{u}^{n+1}) - u^{n+1} + u_{H}^{n+1}) = \mathcal{F}'(u_{H}^{n+1})(\mathfrak{M}_{u}^{n+1} + \mathfrak{P}_{u}^{n+1}) + \frac{1}{2}\mathcal{F}''(\chi^{n+1})(u^{n+1} - u_{H}^{n+1})^{2}.$$
(44)

So, we have

$$I_{3} = -(\mathcal{F}(u^{n+1}) - \mathcal{F}(u^{n+1}_{H}) + \mathcal{F}'(u^{n+1}_{H})(\mathfrak{M}^{n+1}_{u}) + \mathfrak{P}^{n+1}_{u} - u^{n+1} + u^{n+1}_{H}), v_{h})$$

$$\leq \frac{1}{2} \|\mathcal{F}'(u^{n+1}_{H})\|_{\infty} (\|\mathfrak{P}^{n+1}_{u}\|^{2} + \|\mathfrak{M}^{n+1}_{u}\|^{2}) + \frac{1}{4} \|\mathcal{F}''(\chi^{n+1})\|_{\infty} \|(u^{n+1} - u^{n+1}_{H})^{2}\|^{2} + (\frac{1}{2} \|\mathcal{F}'(u^{n+1}_{H})\|_{\infty} + \frac{1}{4} \|\mathcal{F}''(\chi^{n})\|_{\infty})\|v_{h}\|^{2}.$$
(45)

We now use Cauchy–Schwarz inequality with Young inequality to get

$$I_{1} = -\left(\frac{3}{2}\delta_{t}^{n+1}\mathfrak{P}_{u}^{n+1} - \frac{1}{2}\delta_{t}^{n}\mathfrak{P}_{u}^{n}, v_{h}\right)$$

$$\leq \left\|\frac{3}{2}\delta_{t}^{n+1}\mathfrak{P}_{u}^{n+1} - \frac{1}{2}\delta_{t}^{n}\mathfrak{P}_{u}^{n}\right\|\|v_{h}\|$$

$$\leq C\int_{t_{n-1}}^{t_{n+1}}\|\mathfrak{P}_{ut}\|^{2}ds + C\|v_{h}\|^{2},$$
(46)

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and

$$I_{4} + I_{5} + I_{6} = (\bar{e}_{1}^{n+1}, v_{h}) + (\bar{e}_{2}^{n+1}, v_{h}) + (\Delta \bar{e}_{3}^{n+1}, v_{h})$$

$$\leq C(\tau^{4} + ||v_{h}||^{2}).$$
(47)

By using lemma 4 with Cauchy–Schwarz inequality and Young inequality, we have

$$\begin{split} I_{2} &= -\sum_{i=0}^{n+1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (\mathfrak{P}_{u}^{n+1-i}, v_{h}) \\ &\leq \frac{1}{\tau^{\alpha}} \sum_{i=0}^{n+1} |p_{\alpha}(i)|| (\mathfrak{P}_{u}^{n+1-i}, v_{h})| \\ &\leq \frac{\alpha+2}{2\tau^{\alpha}} g_{0}^{\alpha} || \mathfrak{P}_{u}^{n+1} || || v_{h} || \\ &+ \frac{1}{\tau^{\alpha}} \sum_{i=1}^{n+1} \Big| \frac{\alpha+2}{2} g_{i}^{\alpha} + \frac{-\alpha}{2} g_{i-1}^{\alpha} \Big| || \mathfrak{P}_{u}^{n+1-i} || || v_{h} || \\ &\leq Ch^{r+1} || v_{h} || \Big(\frac{\alpha+2}{2\tau^{\alpha}} g_{0}^{\alpha} + \frac{1}{\tau^{\alpha}} \sum_{i=1}^{n+1} \Big| - \frac{\alpha+2}{2} g_{i}^{\alpha} \Big| \\ &+ \frac{1}{\tau^{\alpha}} \sum_{i=1}^{n+1} \Big| \frac{-\alpha}{2} g_{i-1}^{\alpha} \Big| \Big) \\ &\leq Ch^{r+1} || v_{h} || \Big(\frac{\alpha+1}{\tau^{\alpha}} g_{0}^{\alpha} + \frac{\alpha+2}{2\tau^{\alpha}} \sum_{i=1}^{n+1} - g_{i}^{\alpha} \\ &+ \frac{\alpha}{2\tau^{\alpha}} \sum_{i=1}^{n} - g_{i}^{\alpha} \Big) \\ &\leq C(\alpha) \tau^{-\alpha} h^{r+1} || v_{h} || \\ &\leq C(\alpha) \tau^{-\alpha} h^{2r+2} + C || v_{h} ||^{2}. \end{split}$$

In (42), (45)–(48), we take $v_h = \mathfrak{M}_u^{n+1}$ and make a combination for these expressions to get

$$\begin{split} &\frac{1}{4\tau} [\Lambda(\mathfrak{M}_{u}^{n+1},\mathfrak{M}_{u}^{n}) - \Lambda(\mathfrak{M}_{u}^{n},\mathfrak{M}_{u}^{n-1})] \\ &+ \sum_{i=0}^{n+1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (\mathfrak{M}_{u}^{n+1-i},\mathfrak{M}_{u}^{n+1}) \\ &+ \sum_{i=0}^{n+1} \frac{p_{\beta}(i)}{\tau^{\beta}} (\nabla \mathfrak{M}_{u}^{n+1-i}, \nabla \mathfrak{M}_{u}^{n+1}) \\ &\stackrel{=}{=} I_{1} + I_{2} + I_{3} + I_{4} + I_{5} + I_{6} \\ &\leq C(\tau^{4} + \tau^{-2\alpha}h^{2r+2}) + \frac{1}{2} \|\mathcal{F}'(u_{H}^{n+1})\|_{\infty} \|\mathfrak{P}_{u}^{n+1}\|^{2} \\ &+ \frac{1}{4} \|\mathcal{F}''(\chi^{n+1})\|_{\infty} \|(u^{n+1} - u_{H}^{n+1})^{2}\|^{2} \end{split}$$

$$+ (\|\mathcal{F}'(u_{H}^{n+1})\|_{\infty} + \frac{1}{4}\|\mathcal{F}''(\chi^{n})\|_{\infty} + 1)\|\mathfrak{M}_{u}^{n+1}\|^{2}.$$
(49)

Multiply (49) by 4τ and sum (49) for *n* from 1 to *L* to get

$$\begin{split} \Lambda(\mathfrak{M}_{u}^{L+1},\mathfrak{M}_{u}^{L}) \\ &+ 4\tau^{1-\alpha} \sum_{n=1}^{L} \sum_{i=0}^{n+1} p_{\alpha}(i)(\mathfrak{M}_{u}^{n+1-i},\mathfrak{M}_{u}^{n+1}) \\ &+ 4\tau^{1-\beta} \sum_{n=1}^{L} \sum_{i=0}^{n+1} p_{\beta}(i)(\nabla \mathfrak{M}_{u}^{n+1-i},\nabla \mathfrak{M}_{u}^{n+1}) \\ &\leq \Lambda(\mathfrak{M}_{u}^{1},\mathfrak{M}_{u}^{0}) + C\tau \sum_{n=1}^{L} (\tau^{4} + \tau^{-2\alpha}h^{2r+2}) \\ &+ C\tau \sum_{n=1}^{L} \|\mathcal{F}'(u_{H}^{n+1})\|_{\infty} \|\mathfrak{P}_{u}^{n+1}\|^{2} \\ &+ \tau \sum_{n=1}^{L} \|\mathcal{F}''(\chi^{n+1})\|_{\infty} \|(u^{n+1} - u_{H}^{n+1})^{2}\|^{2} \\ &+ \tau \sum_{n=1}^{L} (\|\mathcal{F}'(u_{H}^{n+1})\|_{\infty} \\ &+ \frac{1}{4} \|\mathcal{F}''(\chi^{n})\|_{\infty} + 1) \|\mathfrak{M}_{u}^{n+1}\|^{2}. \end{split}$$
(50)

Subtract (25) from (15), we have

$$\left(\delta_{t}^{1} \mathfrak{M}_{u}^{1}, v_{h} \right) + \sum_{i=0}^{1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (\mathfrak{M}_{u}^{1-i}, v_{h})$$

$$+ \sum_{i=0}^{1} \frac{p_{\beta}(i)}{\tau^{\beta}} (\nabla \mathfrak{M}_{u}^{1-i}, \nabla v_{h}) = -\left(\delta_{t}^{n+1} \mathfrak{P}_{u}^{1}, v_{h} \right)$$

$$- \sum_{i=0}^{1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (\mathfrak{P}_{u}^{1-i}, v_{h}) - (\mathcal{F}(u^{1}) - \mathcal{F}(u^{1}_{H})$$

$$- \mathcal{F}'(u^{1}_{H})(U^{1}_{h} - u^{1}_{H}), v_{h}) + (\bar{e}^{1}_{1}, v_{h}) + (\bar{e}^{1}_{2}, v_{h})$$

$$+ (\Delta \bar{e}^{1}_{3}, v_{h}).$$

$$(51)$$

In (51), we choose $v_h = \mathfrak{M}_u^1$ and use (45) and (48) to get

$$\begin{split} \|\mathfrak{M}_{u}^{1}\|^{2} &- \|\mathfrak{M}_{u}^{0}\|^{2} + \|\mathfrak{M}_{u}^{1} - \mathfrak{M}_{u}^{0}\|^{2} \\ &+ 2\tau^{1-\alpha} \sum_{i=0}^{1} p_{\alpha}(i)(\mathfrak{M}_{u}^{1-i}, \mathfrak{M}_{u}^{1}) \\ &+ 2\tau^{1-\beta} \sum_{i=0}^{1} p_{\beta}(i)(\nabla \mathfrak{M}_{u}^{1-i}, \nabla \mathfrak{M}_{u}^{1}) = -2\tau \end{split}$$

$$\times \left(\delta_{t}^{n+1} \mathfrak{P}_{u}^{1}, \mathfrak{M}_{u}^{1} \right)$$

$$-2\tau \sum_{i=0}^{1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (\mathfrak{P}_{u}^{1-i}, \mathfrak{M}_{u}^{1}) - 2\tau (\mathcal{F}(u^{1}) - \mathcal{F}(u_{H}^{1}))$$

$$- \mathcal{F}'(u_{H}^{1})(U_{h}^{1} - u_{H}^{1}), \mathfrak{M}_{u}^{1})$$

$$+ 2\tau (\bar{e}_{1}^{1}, \mathfrak{M}_{u}^{1}) + 2\tau (\bar{e}_{2}^{1}, \mathfrak{M}_{u}^{1}) + 2\tau (\Delta \bar{e}_{3}^{1}, \mathfrak{M}_{u}^{1})$$

$$\leq \tau \|\mathcal{F}'(u_{H}^{1})\|_{\infty} (\|\mathfrak{P}_{u}^{1}\|^{2} + \|\mathfrak{M}_{u}^{1}\|^{2})$$

$$+ \frac{\tau}{2} \|\mathcal{F}''(\chi^{1})\|_{\infty} \|(u^{1} - u_{H}^{1})^{2}\|^{2}$$

$$+ (\tau \|\mathcal{F}'(u_{H}^{1})\|_{\infty} + \frac{\tau}{2} \|\mathcal{F}''(\chi^{1})\|_{\infty})\|\mathfrak{M}_{u}^{1}\|^{2} + C\tau^{4}$$

$$+ C\tau^{-2\alpha}h^{2r+2} + \frac{1}{4}\|\mathfrak{M}_{u}^{1}\|^{2},$$

$$(52)$$

Simplifying for (52) and using triangle inequality, we have

$$\Lambda(\mathfrak{M}_{u}^{1},\mathfrak{M}_{u}^{0}) + 2\tau^{1-\alpha} \sum_{i=0}^{1} p_{\alpha}(i)(\mathfrak{M}_{u}^{1-i},\mathfrak{M}_{u}^{1}) + 2\tau^{1-\beta} \sum_{i=0}^{1} p_{\beta}(i)(\nabla \mathfrak{M}_{u}^{1-i},\nabla \mathfrak{M}_{u}^{1}) \leq C\tau h^{2r+2} + C\tau^{-2\alpha} h^{2r+2} + \frac{\tau}{2} \|(u^{1} - u_{H}^{1})^{2}\|^{2} + C\tau^{4}.$$
(53)

Combine (50) with (53) and note that $\mathfrak{M}_u^0 = 0$ to get $\Lambda(\mathfrak{M}_u^{L+1}, \mathfrak{M}_u^L)$

$$\begin{aligned} &+4\tau^{1-\alpha}\sum_{n=-1}^{L}\sum_{i=0}^{n+1}p_{\alpha}(i)(\mathfrak{M}_{u}^{n+1-i},\mathfrak{M}_{u}^{n+1}) \\ &+4\tau^{1-\beta}\sum_{n=-1}^{L}\sum_{i=0}^{n+1}p_{\beta}(i)(\nabla\mathfrak{M}_{u}^{n+1-i},\nabla\mathfrak{M}_{u}^{n+1}) \\ &\leq C\tau\sum_{n=1}^{L}(\tau^{4}+\tau^{-2\alpha}h^{2r+2}) \\ &+C\tau\sum_{n=1}^{L}\|\mathcal{F}'(u_{H}^{n+1})\|_{\infty}\|\mathfrak{P}_{u}^{n+1}\|^{2} \\ &+\tau\sum_{n=1}^{L}\|\mathcal{F}''(\chi^{n+1})\|_{\infty}\|(u^{n+1}-u_{H}^{n+1})^{2}\|^{2} \\ &+\tau\sum_{n=1}^{L}(\|\mathcal{F}'(u_{H}^{n+1})\|_{\infty} \\ &+\frac{1}{4}\|\mathcal{F}''(\chi^{n})\|_{\infty}+1)\|\mathfrak{M}_{u}^{n+1}\|^{2}+C\tau h^{2r+2} \\ &+\frac{\tau}{2}\|(u^{1}-u_{H}^{1})^{2}\|^{2}+C\tau^{4}. \end{aligned}$$
(54)

By using the Cronwall lemma and the relationship (22), we have for sufficiently small τ

$$\Delta(\mathfrak{M}_{u}^{L+1}, \mathfrak{M}_{u}^{L}) \leq C(\tau^{4} + \tau^{-2\alpha}h^{2r+2} + h^{2r+2}) + C\tau \sum_{n=0}^{L} \|(u^{n+1} - u_{H}^{n+1})^{2}\|^{2}.$$
(55)

For the next discussion, we need to give the estimate for the term $||(u^{n+1} - u_H^{n+1})^2||$.

Subtract (23), (24) from (15), (16), respectively, and use the Ritz projection (39) to arrive at the error equations under the coarse grid for any $v_H \in V_H$

Case n = 0:

$$\begin{pmatrix} \delta_{t}^{1} \mathfrak{D}_{u}^{1}, v_{H} \end{pmatrix} + \sum_{i=0}^{1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (\mathfrak{D}_{u}^{1-i}, v_{H}) \\ + \sum_{i=0}^{1} \frac{p_{\beta}(i)}{\tau^{\beta}} (\nabla \mathfrak{D}_{u}^{1-i}, \nabla v_{H}) = -\left(\delta_{t}^{1} \mathfrak{A}_{u}^{1}, v_{H}\right) \\ - \sum_{i=0}^{1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (\mathfrak{A}_{u}^{1-i}, v_{H}) \\ - (\mathcal{F}(u^{1}) - \mathcal{F}(u_{H}^{1}), v_{H}) + (\bar{e}_{1}^{1}, v_{H}) + (\bar{e}_{2}^{1}, v_{H}) \\ + (\Delta \bar{e}_{3}^{1}, v_{H}),$$
(56)

Case $n \ge 1$:

$$\begin{aligned} &\frac{3}{2} \delta_{t}^{n+1} \mathfrak{D}_{u}^{n+1} - \frac{1}{2} \delta_{t}^{n} \mathfrak{D}_{u}^{n}, v_{H} \Big) \\ &+ \sum_{i=0}^{n+1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (\mathfrak{D}_{u}^{n+1-i}, v_{H}) \\ &+ \sum_{i=0}^{n+1} \frac{p_{\beta}(i)}{\tau^{\beta}} (\nabla \mathfrak{D}_{u}^{n+1-i}, \nabla v_{H}) \\ &= -\left(\frac{3}{2} \delta_{t}^{n+1} \mathfrak{A}_{u}^{n+1} - \frac{1}{2} \delta_{t}^{n} \mathfrak{A}_{u}^{n}, v_{H}\right) \\ &- \sum_{i=0}^{n+1} \frac{p_{\alpha}(i)}{\tau^{\alpha}} (\mathfrak{A}_{u}^{n+1-i}, v_{H}) \\ &- (\mathcal{F}(u^{n+1}) - \mathcal{F}(u_{H}^{n+1}), v_{H}) + (\bar{e}_{1}^{n+1}, v_{H}) \\ &+ (\bar{e}_{2}^{n+1}, v_{H}) + (\Delta \bar{e}_{3}^{n+1}, v_{H}), \end{aligned}$$
(57)

where $\mathfrak{A}_{u}^{n} = u(t_{n}) - \Psi_{H}u^{n}, \mathfrak{D}_{u}^{n} = \Psi_{H}u^{n} - u_{H}^{n}.$

In (56) and (57), we take $v_H = \mathfrak{D}_u^1$ and $v_H = \mathfrak{D}_u^{n+1}$, respectively, and use a similar process of proof to the estimate for $||u^n - U_h^n||$ to get

$$\|u^{n+1} - u_H^{n+1}\| \le C(\tau^2 + \tau^{-\alpha}H^{r+1} + H^{r+1}).$$
 (58)

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Table 1 L^2 -errors with $\alpha = 0.01, \beta = 0.99$ and $\tau = 1/100$

Н	h	$\ u - U_h\ $	Order	CPU time (in seconds)
1/4	1/16	6.3566e-003	_	43.231369
1/5	1/25	2.6118e-003	1.9930	122.612277
1/6	1/36	1.2323e-003	2.0600	414.219975
1/7	1/49	6.3532e-004	2.1489	1810.428349
FE algorithm	h	$ u - u_h $	Order	CPU time (in seconds)
	1/16	6.4246e-003	_	49.760083
	1/25	2.6815e-003	1.9578	145.938800
	1/36	1.3025e-003	1.9803	488.617402
	1/49	7.0575e-004	1.9876	2112.565940

Substitute the above estimate inequality (58) into (55)

$$\Lambda(\mathfrak{M}_{u}^{L+1},\mathfrak{M}_{u}^{L}) \leq C(\tau^{4} + \tau^{-2\alpha}h^{2r+2} + h^{2r+2} + \tau^{-4\alpha}H^{4r+4} + H^{4r+4}),$$
(59)

which combine the triangle inequality with (40) to get the conclusion of Theorem 2. П

Remark 3 Based on the theorem's results, we obtain the temporal convergence rate with second-order result, which is free of fractional parameters α and β . Moreover, we can find that the time convergence rate by using second-order backward difference method and second-order WSGD scheme is higher than the one with $O(\tau^{2-\alpha} + \tau^{2-\beta})$ obtained by L1 approximation.

5 Numerical tests

In this section, we consider a numerical example in space-time domain $[0, 1] \times [0, 1]^2$ to verify the theoretical results of two-grid FE algorithm combined with second-order backward difference method and secondorder WSGD scheme. We now choose the nonlinear term $\mathcal{F}(u) = u^3 - u$ and the exact solution u(x, y, t) = $t^2 \sin(2\pi x) \sin(2\pi y)$ and then easily determine that the known source function in (1) is

$$g(x, y, t) = \left[2t - t^2 + \frac{2t^{2-\alpha}}{\Gamma(3-\alpha)} + 16\pi^2 \frac{t^{2-\beta}}{\Gamma(3-\beta)}\right]$$
$$\sin(2\pi x)\sin(2\pi y) + t^6\sin^3(2\pi x)\sin^3(2\pi y).$$

We now divide uniformly the spatial domain $[0, 1]^2$ by using rectangular meshes, approximate first-order integer derivative with two-step backward Euler method and discretize the fractional direvative with second-order scheme. Now we take the continuous

bilinear functions space V_h with $Q(x, y) = a_0 + a_1 x +$ $a_2y + a_3xy$.

For showing the current method in the this paper, we calculate some error results with convergence order for different fractional parameters α and β . In Table 1, by taking fractional parameters $\alpha = 0.01, \beta = 0.99$ and fixed temporal step length $\tau = 1/100$, we show some a priori errors in L^2 -norm and convergence orders for two-grid algorithm with coarse and fine meshes $H = \sqrt{h} = 1/4, 1/5, 1/6, 1/7$ and FE method with h = 1/16, 1/25, 1/36, 1/49. From Table 1, ones can see that the results with second-order convergence rate by using our method are stable and the CPU time in seconds for two-grid FE method is less than that by making use of the standard FE method. In Table 2, we use the same computing method and spatial meshes as in Table 1 and then obtain the errors and convergence rates when taking $\alpha = 0.5$, $\beta = 0.5$ and $\tau = 1/100$. The similar calculated results with $\alpha = 0.99$, $\beta = 0.01$ and $\tau = 1/100$ are also shown in Table 3. These numerical results shown in Tables 1, 2 and 3 also tell ones that compared to widely used L1 formula with $O(\tau^{2-\alpha} + \tau^{2-\beta})$, the WSGD scheme in this paper can get second-order convergence rate. For obtaining the second-order accuracy in time, we here use the secondorder backward difference method to approximate time direction. Compared to commonly used one-step backward Euler difference method, for getting the same calculated accuracy, the second-order backward difference method can reduce the number of iterations in time and save the calculating time. From the numerical results presented in Tables 1 and 2, ones can see that the convergence order of our method is slightly higher than that of the standard nonlinear FE method, while in Table 3, our method shows the similar con**Table 2** L^2 -errors with $\alpha = 0.5$, $\beta = 0.5$ and

$$\tau = 1/100$$

Н	h	$ u - U_h $	Order	CPU time (in seconds)
1/4	1/16	6.6252e-003	_	34.637650
1/5	1/25	2.7694e-003	1.9545	102.802120
1/6	1/36	1.3488e-003	1.9729	374.852060
1/7	1/49	7.3406e-004	1.9733	1745.224030
FE algorithm	h	$ u - u_h $	Order	CPU time (in seconds)
	1/16	6.6292e-003	-	37.660242
	1/25	2.7735e-003	1.9525	116.171144
	1/36	1.3529e-003	1.9687	448.280514
	1/49	7.3816e-004	1.9651	2189.299786
Н	h	$\ u-U_h\ $	Order	CPU time (in seconds)
1/4	1/16	6.9107e-003	-	53.860030
1/5	1/25	2.8841e-003	1.9581	153.053853
1/6	1/36	1.4003e - 003	1.9815	497.518498

7.5807e-004

6.9107e-003

2.8841e-003

1.4003e-003

7.5809e-004

 $||u - u_h||$

1/49

1/16

1/25

1/36

1/49

h

Table 3 L^2 -errors with $\alpha = 0.99$, $\beta = 0.01$ and $\tau = 1/100$

vergence rate to that of nonlinear FE method. These
phenomena indicate that compared to nonlinear FE
method, our method has advantages in solving the time-
fractional Cable equation covering the space-time par-
tial derivative term ${}_{0}^{R}\partial_{t}^{\beta}\Delta u$ with larger fractional para-
meter $\beta \in (0, 1)$.

1/7

FE algorithm

In Figs. 1, 2 and 3, by taking $\alpha = 0.99$, $\beta = 0.01$, $\tau = 1/100$ and $h = H^2 = 1/25$, we show the surfaces for the exact solution u, two-grid FE solution U_h and FE solution u_h , respectively. Ones easily see that both two-grid FE solution U_h based on coarse and fine meshes and FE solution u_h can approximate well the exact solution u. In particular, from the surface for errors $u - U_h$ and $u - u_h$ in Figs. 4 and 5, ones easily find that two-grid FE method holds the similar computational accuracy to that of standard nonlinear FE method.

In summary, from the computed error results and convergence rate in Tables 1, 2 and 3 and the surfaces shown in Figs. 1, 2, 3, 4 and 5, ones can know that with the similar computational accuracy to that for stan-

dard nonlinear FE method, our two-grid FE method is more efficient in computational time than the standard nonlinear FE method. Moreover, the current method combined with the second-order backward difference method and second-order WSGD operator can get a stable second-order convergence rate, which is independent of fractional parameters α and β and is higher than the convergence result $O(\tau^{2-\alpha} + \tau^{2-\beta})$ derived by L1 approximation.

1.9905

Order

1.9581

1.9815

1.9904

_

2040.087416

57.108134

163.841391

554.982539

2416.876270

CPU time (in seconds)

6 Some concluding remarks

In this article, we consider two-grid method combined with FE methods to give the numerical solution for nonlinear fractional Cable equations. First, we give some lemmas used in our paper; second, we give the approximate formula for fractional derivative and then formulate the numerical scheme based on two-grid FE method; finally, we do some detailed derivations for the stability of numerical scheme and a priori error



Fig. 1 Exact solution u



Fig. 2 Two-grid FE solution U_h



Fig. 3 FE solution *u_h*

analysis with second-order convergence rate in time and then compute some numerical errors and convergence orders to verify the theoretical results.



Fig. 4 Value for $u - U_h$



Fig. 5 Value for $u - u_h$

From the numerical results, ones easily see that twogrid FE method studied in this paper can solve well the nonlinear time-fractional Cable equation. Based on the point of view of calculating efficiency, compared to FE method, two-grid FE method can spend less time. Moreover, compared with the time convergence rate $O(\tau^{2-\alpha} + \tau^{2-\beta})$ obtained by usual L1 approximation, the current numerical scheme can arrive at secondorder convergence rate independent of fractional parameters α and β . Considering the mentioned advantages, in the future works, we will discuss the numerical theories of two-grid FE method for some space and space– time-fractional partial differential equations with nonlinear term.

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