**ORIGINAL PAPER**



# **Flood risk mapping for the lower Narmada basin in India: a machine learning and IoT‑based framework**

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## **Abstract**

Floods have a signifcant economic, social, and environmental impact in developing countries like India. Settlements in food hazard zones increase food risk due to a lack of information and awareness. The present study proposed a machine learning-based framework to identify such food risk zones for the lower Narmada basin in India. Flood hazard factors like elevation and slope of the terrain, distance from main river network, drainage density, annual average rainfall of the area, and land-use land-cover (LULC) characteristics, as well as food vulnerability factors like population density, agricultural production, and road– river intersections, were used as predictors in the random forest algorithm to predict the flood depth in the region. Initially, the flood depth obtained from the hydrodynamic model was used as a predict and to train the model and determine the weightage of each predictor. The RandomizedSeachCV technique was used to optimize hyperparameters of the random forest algorithm. The obtained results from variable importance of random forest show that the elevation of the terrain, LULC characteristics, distance from the main river network, and rainfall are the major contributors to cause food risk in the area. Furthermore, the possibility of using the IoT-based sensor to develop the real-time food risk mapping framework is described. The developed flood risk map can assist policymakers, stakeholders, and citizens in developing guidelines, taking preventive measures, and avoid unnecessary settlements in food risk zones.

**Keywords** Flood risk · Machine learning · Random forest · Hazard · Vulnerability

#### **Abbreviations**

- CV Cross-validation
- DEM Digital elevation model<br>DT Decision tree
- Decision tree
- GIS Geographic information system<br>HD Hydrodynamic
- Hydrodynamic
- IoT Internet of things

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# **1 Introduction**

Floods are one of the most destructive natural disasters worldwide, causing death, damaging infrastructure, disrupting transportation and communication, and afecting people's livelihood (Mohapatra and Singh [2003](#page-18-0); Teng et al. [2017;](#page-18-1) Khosravi et al. [2018;](#page-17-0) Yadav and Mangukiya [2021](#page-19-0)). In developing countries like India, foods cause an enormous scale impact on the nation's socioeconomic condition (Mohapatra and Singh [2003](#page-18-0); National Disaster Management Authority [2008](#page-18-2)). The consequences, on the other hand, are not always negative. Floods can provide long-term environmental benefts to areas that have been ravaged by drought (Balica et al. [2013;](#page-17-1) Teng et al. [2017](#page-18-1)). Floods are caused by continuous high-intensity rainfall in a specific area for an extended period (Dhar et al. [1981](#page-17-2); Kumar et al. [2013](#page-18-3); Ramkar and Yadav [2021\)](#page-18-4). Global climate change and anthropogenic activities such as land-use patterns and deforestation have recently increased the frequency and duration of high-intensity rainfall and caused foods in the arid and semiarid river basin (Li et al. [2015;](#page-18-5) Papaioannou et al. [2016](#page-18-6); Mangukiya and Yadav [2021](#page-18-7); Yadav and Mangukiya [2021\)](#page-19-0).

Flood risk assessment is becoming increasingly important in today's world for proper food management (Merz et al. [2014](#page-18-8); Manfreda and Samela [2019](#page-18-9)). Many researchers have made systematic efforts to identify flood risk zones and map inundation areas (Chen et al. [2011;](#page-17-3) Masood and Takeuchi [2012](#page-18-10); Balica et al. [2013](#page-17-1); Zehra and Afsar [2016;](#page-19-1) Kabenge et al. [2017;](#page-17-4) Ntajal et al. [2017;](#page-18-11) Darabi et al. [2019;](#page-17-5) Abdrabo et al. [2020;](#page-17-6) Ramkar and Yadav [2021](#page-18-4)). Flood risk indicates the probability of devastating impact and is determined as a product of hazard and vulnerability (Sayers et al. [2002;](#page-18-12) Winsemius et al. [2013](#page-19-2)). Geo-morphological and geo-environmental factors determine the likelihood of a food hazard at a specifc location (Khosravi et al. [2016](#page-17-7)). The potentially vulnerable factors of the flood are humans and exposed economic elements (Jato‐Espino et al. [2019](#page-17-8)). Diferent researchers have used various factors to determine food risk based on area-specifc characteristics (Darabi et al. [2019;](#page-17-5) Ramkar and Yadav [2021](#page-18-4)). The elevation and slope of the terrain, drainage density, distance from the river, rainfall distribution, and soil and land-use land-cover (LULC) characteristics are most widely used as food hazard factors, while population density and characteristics, industrial and agricultural zone, and exposed transportation network are most commonly used as vulnerable food factors (Balica et al. [2013;](#page-17-1) Khosravi et al. [2018;](#page-17-0) Darabi et al. [2019;](#page-17-5) Ramkar and Yadav [2021](#page-18-4)).

Flood risk mapping frameworks include various cloud models, analytical hierarchy process (AHP) combined with multi-criteria decision making (MCDM) approach, weighted comprehensive evaluation techniques, artifcial intelligence and machine learning-based approach, and GIS-based methods (Wan et al. [2017;](#page-19-3) Pham et al. [2021;](#page-18-13) Liu et al. [2021](#page-18-14); Ramkar and Yadav [2021](#page-18-4)). Depending on the interpretation factors of the food event, statistical models are also used for food risk mapping (Sanyal and Lu [2005](#page-18-15)). The machine learning (ML) approach has recently increased among all methods due to its ability to assess the existing nonlinear relationship between evaluation factors and food risk level (Ma et al. [2019](#page-18-16); Darabi et al. [2019](#page-17-5); Costache [2019](#page-17-9); Li et al. [2019;](#page-18-17) Eini et al. [2020](#page-17-10); Pham et al. [2021](#page-18-13); Liu et al. [2021](#page-18-14)). Random forest (RF), the classifcation and regression treesbased ML algorithm, is well suited for multivariate prediction (Breiman [2001](#page-17-11)). The RF algorithm is widely used in ecological environment monitoring because it efficiently solves nonlinear problems (Carvalho et al. [2018\)](#page-17-12). The study of food risk mapping based on RF, on the other hand, is limited and still has a scope to explore for large river basins. Lai et al.  $(2015)$  $(2015)$  and Wang et al.  $(2015)$  $(2015)$  have developed a flood risk mapping and assessment framework based on the RF algorithm for Jiangxi Province's river basin, China, and concluded that the RF-based outcomes have more reliability than support vector machines (SVMs) algorithm. Similarly, Feng et al. ([2015\)](#page-17-13) have also concluded that the RF algorithm outperformed the artifcial neural network (ANN) and the maximum likelihood method for food risk assessment. The efficiency of the various ML algorithms is also affected by the regionspecifc data characteristics. However, the RF-based methods have a high tolerance for outliers and noise, avoiding overftting. The RF, as a result, outperformed the most commonly used ML algorithms in terms of computational efficiency, accuracy, scalability, and robustness (Liu et al. [2021\)](#page-18-14).

Flood risk mapping and assessment on the Indian river basin are limited due to data scarcity in observed stage-discharge data, satellite imagery of the fooded area, and observed food depth of historical food events (Mangukiya and Yadav [2021;](#page-18-7) Yadav and Mangukiya [2021;](#page-19-0) Ramkar and Yadav [2021](#page-18-4)). Thus, the objective of the present study is to propose a possible framework for food risk mapping in lower Narmada basin in India based on available observed and remote sensing datasets. The main challenge in using remote sensing datasets is the heterogeneity of the data source. The available data from diferent sources have various scales, including a mix of unstructured and structured data (Pollard et al. [2018](#page-18-19); Towe et al. [2020](#page-19-5)). To extract useful information and make a decision based on this heterogeneous data, a defnite approach is required for integration and subsequent analyses. In the present study, a machine learning-based approach is adopted to analyze food risk in the region. The RF algorithm was used to train the model. Additionally, the hyperparameters of the RF algorithm were optimized using the 'Randomized-SearchCV' method. The food risk map was created using the weightage obtained from the RF feature importance parameter. Furthermore, the possibility of using the IoT-based sensor to develop the real-time food risk mapping framework is described. The proposed methodology and created food risk map can help policymakers, stakeholders, and citizens in developing guidelines and frameworks, take preventive measures, and avoid unnecessary settlements in flood risk zones.

## **2 Study area and data**

#### **2.1 Study area**

The Narmada River is the ffth largest and sixth longest river of India. The Narmada Basin covers an area of 98,796  $km^2$  and is located between longitudes 72°38′–81°43′ E and latitudes 21°27′–23°37′ N. The lower plain of the basin is bounded by Sardar Sarovar Dam and the coastal region covering  $8730 \text{ km}^2$  area mainly in the districts of Narmada, Bharuch, and parts of Vadodara which is more vulnerable to food. The lower Narmada basin has experienced numerous foods, including severe fooding in 1970, 1973, 1984, 1990, 1994, and 2013. Because of that reason, the lower plain of the coastal region is selected as a study area for the present study (Fig. [1](#page-3-0)). The upper hilly regions of the basin receive higher annual rainfall (1400–1650 mm), which causes foods in the downstream area even though it is a semiarid zone. The temperature in the lower part is infuenced by the sea and varies from 10 to 40 °C in diferent seasons. The primary LULC class of the lower Narmada basin is agriculture cropland (61%), dense vegetation and forest (21%), and urban land (8%).

## **2.2 Data description and processing**

The required data for the present study were collected from an open-source database and government reports as described in Sects. [2.2.1](#page-3-1) and [2.2.2.](#page-6-0) Nine factors were considered for preparing the food risk map, including food hazard causing factors and food vulnerability causing factors. The spatial database of these factors was created and integrated with GIS software for use as input to the ML algorithm.

#### <span id="page-3-1"></span>**2.2.1 Flood hazard factors**

Six diferent factors, namely elevation of the terrain, percentage change in slope of the terrain, distance from the main river network, drainage density of the area, annual average rainfall distribution of the area, and land-use land-cover characteristics of the area, were considered as food hazard factors for the study.



<span id="page-3-0"></span>Fig. 1 Location map of the study area. The highlighted lower part of the basin is frequently affected urban food areas

**2.2.1.1 Elevation of the terrain** The Shuttle Radar Topography Mission (SRTM) Digital Elevation Model (DEM) of 1-arc second resolution for the study area was downloaded from the United States Geological Survey (USGS) Earth Explorer portal ([https://earthexplorer.](https://earthexplorer.usgs.gov/) [usgs.gov/\)](https://earthexplorer.usgs.gov/). The downloaded DEM was mosaicked together for watershed delineation in ArcGIS v10.8 software. Finally, the DEM was clipped to the extent of the delineated watershed for lower Narmada basin and used for the analysis (Fig. [2a](#page-4-0)). The terrain elevation ranges from 0 to 860 m, with a mean and standard deviation of 159.35 and 122.28 m.

**2.2.1.2 Percentage change in slope of the terrain** The slope of the terrain affects the speed of draining water and inundation time of the area. The waterlogging of an area can be caused



<span id="page-4-0"></span>**Fig. 2** Flood hazard factors: **a** elevation, **b** percentage change in slope, **c** distance from the main river network, **d** drainage density, **e** average annual rainfall distribution, and **f** LULC characteristics of the study area

by a fat or low slope, whereas a steep or high slope can result in quick water drainage (Franci et al. [2016](#page-17-14)). The DEM was used to calculate the percentage change in slope of the terrain using the 'Slope' tool of 'Spatial analyst toolbox' in ArcGIS v10.8. The percentage slope of the area ranges from 0 to 185.3%, with a mean and standard deviation of 7.43 and 9.98%, respectively (Fig. [2b](#page-4-0)). The Sardar Sarovar dam is located in the southeast part of the basin, which has a higher slope, whereas the southwest part of the basin has a lower slope, making this area more flood-prone.

**2.2.1.3 Distance from the main river network** The area closer to the river channel has a high hazard when the water overtops the bank of the river. The hazard of the food decreases with the increase in distance from the main river network (Khosravi et al. [2016](#page-17-7)). The DEM was used to delineate the river network by keeping the satellite image as a reference. The 'Euclidean distance' tool of 'Spatial analyst toolbox' in ArcGIS v10.8 was used to calculate and prepare the distance map from the delineated river network. The Bharuch and Ankleshwar (two major cities of the study area) are located at the downstream end, with high food hazards due to less distance from the river channel (Fig. [2](#page-4-0)c).

**2.2.1.4 Drainage density of the area** The ratio of the river network's total length to the river's total drainage area is defned as the drainage density of the area. The higher drainage density value represents the exemplary river network which can take less time to drain the rainfall water. The less water travel time can result in draining a larger area simultaneously, increasing the peak of the food and ultimately increasing the area's food hazard. The delineated river network was used to calculate the drainage density of the area using the 'Line density' tool of the 'Spatial analyst toolbox' in ArcGIS v10.8. The drainage density of the study area ranges from 0 to 0.88 km per square kilometers of the area, with a mean and standard deviation of 0.[2](#page-4-0)8 and 0.17 km/km<sup>2</sup>, respectively (Fig. 2d).

**2.2.1.5 Annual average rainfall distribution of the area** The amount of rainfall directly indicates the intensity of food hazards. The gridded rainfall dataset of 0.25° resolution was downloaded from the India Meteorological Department (IMD, Pune) website. The annual average rainfall distribution of the area was calculated by inverse distance weighting method using 'IDW' tool of 'Spatial analyst toolbox' in ArcGIS v10.8. The rainfall in the lower Narmada basin ranges from 977 to 1944 mm, with a mean and standard deviation of 1489 and 215 mm, respectively (Fig. [2](#page-4-0)e). The middle part of the basin receives a higher amount of rainfall which drains into the downstream area and causes the food.

**2.2.1.6 Land‑use land‑cover characteristics** The distribution of rainfall water into various hydrological processes such as runoff, infiltration, baseflow, and interflow is governed by the LULC characteristics of the area (Dwarakish and Ganasri [2015\)](#page-17-15). The urban and built-up, agricultural, and barren land results in a higher runoff, increasing flood hazards, while the dense vegetation and forest land result in lesser runof. The LULC map of the study area was prepared from the Landsat8 satellite imagery of 30 m resolution downloaded from the USGS Earth Explorer Portal. The 'Maximum likelihood classifcation' tool of the 'Image Classifcation toolbox' in ArcGIS v10.8 was used to train and classify the LULC features of the study region. A large number of training samples of various classes (spread throughout the study area) were provided using Google Earth photographs as a background to categorize LULC characteristics in fve classes: dense vegetation, urban and built-up area, barren land, agricultural land, and water bodies. Because the LULC characteristics of the study

area do not change signifcantly over time, the LULC map from 2021 was used as a static food hazard factor in this study. The major LULC characteristic of the study area is agricultural land (61%), followed by dense vegetation  $(21\%)$ , urban and built-up area (8%), barren land (7%), and water bodies (3%) (Fig. [2f](#page-4-0)).

#### <span id="page-6-0"></span>**2.2.2 Flood vulnerability factors**

Three factors, namely population density of the area as social factor, agricultural production per unit area as economic factor, and road–river intersection points per unit area as physical transportation factor, were considered vulnerable food factors for the study (Balica et al. [2013;](#page-17-1) Shivaprasad Sharma et al. [2017\)](#page-18-20).

**2.2.2.1 Population density** Flood causes signifcant social loss and damage and impacts the economy and infrastructure. For considering social loss, population density is one of the critical factors (Nasiri et al. [2016;](#page-18-21) Yang et al. [2018\)](#page-19-6). The sub-district-wise population data were collected from the Census of India 2011. This population data was given as input in ArcGIS v10.8 to prepare the population density map (Fig. [3a](#page-6-1)). The density of population in the study area ranges from 31 to 775 persons per square kilometer. The downstream end



<span id="page-6-1"></span>**Fig. 3** Flood vulnerable factors: **a** sub-district-wise population density, **b** average annual crop production, and **c** road–river intersection point density map of the study area

of the basin, where two major cities (Bharuch and Ankleshwar) are located, has a higher population density.

**2.2.2.2 Agricultural production** India is an agricultural country. More than 80% of the rural Indian population depends on agriculture and its allied activities as the primary source of livelihood. Thus, the area's agricultural production is an important economic factor to be considered vulnerable (Chen et al. [2018\)](#page-17-16). The district-wise average annual crop production data were collected from an official government report published by the Directorate of Agriculture, Gujarat State (Directorate of Agriculture [2011](#page-17-17)), and the website of the Farmer Welfare and Agriculture Development Department, Madhya Pradesh State, India ([http://](http://mpkrishi.mp.gov.in/) [mpkrishi.mp.gov.in/](http://mpkrishi.mp.gov.in/)). This data was digitized in ArcGIS v10.8 to prepare the agricultural production map of the study area (Fig. [3](#page-6-1)b). The annual crop production of the study area ranges from 1159 to 7345 kg per unit hectare area.

**2.2.2.3 Road–river intersection density** The transportation links are necessary for rescue work and providing essentials to food-afected people. Any damage to transportation facilities can isolate the area and increase the food impact. For the present study, the road and river network intersections are considered vulnerable factors as most of the transportation in the study area takes place by road network. The road network of the study area was downloaded from the DIVA-GIS portal and corrected and validated using Google's hybrid satellite image. The intersection points of the road network and delineated river network were identifed using the 'Intersect' tool of 'Analysis toolbox' in ArcGIS v10.8. The density of the intersection point was calculated using the 'Point density' tool of the 'Spatial analyst toolbox' in ArcGIS v10.8 (Fig. [3c](#page-6-1)).

# **3 Methodology**

The objective of the present study is to prepare a flood risk map for the lower Narmada basin, which can be helpful for deciding the food prevention and mitigation strategies and social benefts. The lower Narmada basin has received a historic food in the year 1994. As the surveyed data of the food depth and inundation map are not available, the frst step of the methodology involves the development of the hydrodynamic model to prepare the food inundation map of the region. The developed food inundation map, along with nine food hazards and vulnerable factors, was then used to train the model and predict the weightage of the predictors using the RF algorithm (Table S1, Supplementary Material). The hyperparameters of the RF were optimized with the RandomizedSearchCV method to obtain the best results. Finally, the food risk map was prepared by using the weightage of each predictor. Figure [4](#page-8-0) shows the schematic representation of the methodology adopted in the present study.

## **3.1 Hydrodynamic model**

The two-dimensional (2D) hydrodynamic (HD) model was developed for the lower Narmada basin using the Hydrologic Engineering Center's River Analysis System (HEC-RAS v6.1) software. In the absence of the surveyed bathymetry data, the SRTM DEM was given as input for bathymetry data. The discharge data from the Garudeshwar weir (peak



<span id="page-8-0"></span>**Fig. 4** Schematic representation of the proposed framework for food risk mapping. The dataset consists of food hazard and vulnerability factors as predictors and food inundation map as predictand was given as input to the RF model for obtaining weightage of each factor to prepare food risk maps

discharge 32,056 cumec) for 2013 were provided as the upstream boundary condition. The river's normal slope was given as a downstream boundary condition to simulate the HD model. The roughness coefficient for the bathymetry was subsequently changed to calibrate the HD model by comparing simulated food depth with the observed water level at the Bharuch gauging station. The calibrated model was then used to develop the historic food map of the year 1994. The discharge data from the Garudeshwar weir (with peak discharge 60,642 cumec) for 1994 was given as a boundary condition to obtain the food depth in the region. The developed food inundation map (Fig. [5](#page-9-0)) was given as input to the RF algorithm.

#### **3.2 Random forest algorithm**

RF is the most widely used ensemble machine learning algorithm because of its ability to solve a broad range of regression and classifcation problems. It was proposed by Breiman ([2001\)](#page-17-11). It also includes critical hyperparameters and heuristics for optimizing them. RF is an extension of bagging (bootstrap aggregation) of decision trees. To develop a decision tree (DT) model, RF collects random samples of fxed numbers from the dataset by bootstrap sampling technique. After generating the DT model from one random sample, the sample dataset was again put back. So, the sample collected to develop one DT is likely to be collected again for developing another DT. These ensure that each random sample's content is diferent, which results in the variation in each of the developed DT models in the forest. The fnal results were obtained by taking the mean of the results from all individual DT models of the forest.

Taking the example of the present food risk study, the RF assumes that M numbers of food risk factors cause the food depth in the particular location. Firstly, the samples were split randomly into two datasets: training (70%) and testing (30%). The RF will randomly choose the sample from the training dataset to build a DT and put the sample back in the training dataset. Secondly, the Mtest (Mtest≤*M*) numbers of food risk factors will be randomly selected from the M numbers. Each DT will be developed by a random sample from the training dataset with random Mtest numbers of food causing factors, and the tree would grow to the maximum depth. The mean squared error (MSE) (Eq. [1\)](#page-10-0) will be



<span id="page-9-0"></span>**Fig. 5** Simulated food depth corresponding to peak discharge of the year 1994 from the Garudeshwar weir. 65% of the inundation area has a food depth of more than 3 m

calculated at each tree node for splitting the sample into two branches of the tree. In the end, the importance of each food risk factor for building the DT will be stored. This process will be repeated to develop N numbers of decision trees (Ntree). Finally, the developed Ntree will be aggregated to build a random forest, and the mean of the results from Ntree will be obtained as a fnal result of this random forest.

#### **3.3 Optimization of hyperparameter**

The RF algorithm can be set up with diferent hyperparameters; among them, the number of trees in the forest (Ntree or *n*\_estimators) and the number of features selected for splitting at each node (Mtest or max\_features) are most important. The maximum depth of the DT (max\_depth), the number of data samples required at a node before the split (min\_samples\_split), and the number of data samples needed in a leaf to allow the split (min\_samples\_leaf) are also optimized in the literature for better results. These hyperparameters can be optimized using two diferent methods: grid search and randomized search cross-validation. The grid search method iteratively runs all possible combinations of the hyperparameters defned by users, which is time-consuming and necessitates more computation resources. The randomized search method, on the other hand, chooses hyperparameter combinations at random from a predefned subset. As a result, the randomized search method does not necessitate a large amount of computation resources and is also less time-consuming (Paper [2020\)](#page-18-22). Also, the randomized search method greatly simplifes

analysis without signifcantly sacrifcing optimization. Due to this reason, in the present study, diferent combination value of the hyperparameters was evaluated using random search cross-validation (RandomizedSeachCV) method to fnd out the optimized value. The RandomizedSearchCV method will randomly take the value of hyperparameter from the defned grid and evaluate each combination of values by many iterations with *K*-fold cross-validation (CV). In *K*-Fold CV, the training dataset will be split into *K* number of groups or folds of equal size. Then the model will be iteratively ftted on '*K*−1' folds and tested on the *K*th fold (James et al. [2021\)](#page-17-18). The results of each of the folds will be averaged to obtain fnal validation metrics. The performance of the diferent combinations of the hyperparameters was evaluated using statistical indices, i.e., mean squared error (MSE) (Eq. [1](#page-10-0)), mean absolute error (MAE) (Eq. [2](#page-10-1)), root mean squared error (RMSE) (Eq. [3\)](#page-10-2), and coefficient of determination  $(R$ -square)  $(Eq, 4)$  $(Eq, 4)$ .

<span id="page-10-0"></span>
$$
MSE = \frac{\sum_{i=1}^{N} (y_{\text{act},i} - y_{\text{pred},i})^2}{N}
$$
 (1)

<span id="page-10-2"></span><span id="page-10-1"></span>
$$
\text{MAE} = \frac{\sum_{i=1}^{N} (y_{\text{pred},i} - y_{\text{act},i})}{N} \tag{2}
$$

<span id="page-10-3"></span>RMSE = 
$$
\sqrt{\frac{\sum_{i=1}^{N} (y_{\text{act}, i} - y_{\text{pred}, i})^2}{N}}
$$
 (3)

$$
R^{2} = \left\{\frac{\sum_{i=1}^{N} (\bar{y}_{\text{act}}) (y_{\text{pred}, i} - \bar{y}_{\text{pred}})}{\sqrt{\sum_{i=1}^{N} (y_{\text{act}, i} - \bar{y}_{\text{act}})^{2}} \cdot \sqrt{\sum_{i=1}^{N} (y_{\text{pred}, i} - \bar{y}_{\text{pred}})^{2}}\right\}^{2}
$$
(4)

where *N* is the number of data points,  $y_{\text{act}}$  is the actual flood depth,  $y_{\text{pred}}$  is the predicted flood depth by the RF,  $\bar{y}_{\text{act}}$  and  $\bar{y}_{\text{pred}}$  is the average of actual and predicted flood depth, respectively.

#### **3.4 Preparation of food risk map**

The food risk is the degree of exposure to an undesirable event caused by the combination of natural food hazard factors with those who are particularly vulnerable to this disaster. In the present study, six food hazard factors and three vulnerable food factors are considered. The factors were divided into fve classes (Table S2, Supplementary material) for the development of food hazard and food vulnerable maps using Jenks natural breaks classifcation method (Jenks [1967](#page-17-19)). The weightage of each food hazard and vulnerable factor obtained by RF was used to prepare the food hazard and vulnerable raster using the 'weighted overlay' tool of 'Spatial analyst toolbox' in ArcGIS v10.8. The food risk raster was prepared by multiplying food hazard and vulnerable raster using the 'raster calculator' tool of 'Spatial analyst toolbox' in ArcGIS 10.8. Finally, the food risk raster was reclassifed into four classes to prepare the food risk map indicating the level of risk at a particular location. Because the values of classes 1 and 2 in flood risk raster do not vary significantly,

both classes were combined together and considered as high-risk zone, whereas the study region in class 5 is primarily mountain ranges with a very low likelihood of fooding and was considered as a no-risk zone.

# **4 Results and discussion**

The present study involves nine predictor factors to prepare a risk map. The calibrated and validated food inundation map simulated using HEC-RAS v6.1 was used as a predictand to train the RF model. Together, all ten datasets were projected to a unifed coordinate system of 'WGS 1984 Universal Transverse Mercator (UTM)'. The dataset was then resampled to a grid resolution of  $30 \times 30$  m using ArcGIS v10.8. These resampled and projected data were then given as input to train the RF model.

#### **4.1 Results of random forest model**

The RF package developed by the 'scikit-learn' in python language was implemented to build the RF model for developing a food risk map in the present study. The hyperparameter of the RF model was optimized by evaluating combination values from the developed grid (Table [1\)](#page-11-0) using the RandomizedSeachCV method. Together, there were 640 diferent settings which were evaluated by 300 iterations using the threefold CV method. More number of the iterations can evaluate more settings from the grid, and more CV folds can reduce the probability of overftting, but it also increases the run time of the model. As a food can be an instantaneous event, a larger run time should be avoided so that the model can predict the result before the actual event. Keeping this in view, the best hyperparameter combination setting was obtained as: *n*\_estimators=1000, max\_depth=100, max\_features  $=$  'sqrt', min\_samples\_leaf  $=$  2, and min\_samples\_split  $=10$ . The performance of the model with the best hyperparameter setting was evaluated by statistical indices, and found as: MAE=0.34 m, MSE=0.54 m<sup>2</sup>, RMSE=0.74 m, and *R*-square=0.98. The predicted flood depth by the RF model using the test dataset was compared with the actual flood depth in Fig. [6.](#page-12-0) As the model is trained and tested on a high-resolution grid dataset (over 600,000 grid points), the predicted food depth shows the false prediction on some grid points due to homogeneity of the predictor factors in those grid points. But overall, the higher kernel density (Rosenblatt [1956;](#page-18-23) Parzen [1962](#page-18-24)) was achieved on the equipotential line ( $y_{\text{act}} \cong y_{\text{pred}}$ ) in the graph.

Hyperparameter	Settings
Number of DT in RF (Ntrees or $n$ estimators)	[100, 500, 800, 1000]
Maximum depth of DT (max depth)	['none', 20, 50, 100, 200]
Number of features to selected for split (max features)	['auto', 'sqrt']
Number of data samples needed in a leaf to allow the split (min_samples_leaf)	[1, 2, 5, 10]
Number of data samples required at a node before the split (min_samples_split)	[2, 5, 10, 20]

<span id="page-11-0"></span>**Table 1** Grid of hyperparameter settings for optimization



<span id="page-12-0"></span>**Fig. 6** The Gaussian Kernel density plot for comparing actual food depth with predicted food depth by the RF model. The higher point density was achieved at the equipotential line (1:1) of the plot

#### **4.2 Flood risk map**

The food risk map was prepared by using the weightage obtained by the feature importance value of the RF model. The food hazard raster was prepared by the 'weighted overlay' tool of ArcGIS v10.8 by multiplying the percentage weightage of each food hazard causing factor. Similarly, the vulnerable food raster was prepared by multiplying the percentage weightage of each vulnerable food factor. Finally, the food risk map was prepared by multiplying food hazard and vulnerable raster using the 'raster calculator' tool of ArcGIS v10.8. The obtained percentage weightage from the RF model for all factors is shown in Fig. [7](#page-12-1), and the developed flood risk map is shown in Fig. [8.](#page-13-0) The elevation and LULC characteristics of the region were given the highest importance (29 and 27%) in food hazard factors by the RF model. The distance from the main river channel and rainfall also has signifcant importance (17 and 15%) in causing the food hazard. These



<span id="page-12-1"></span>**Fig. 7** The feature importance (weightage) of food hazard and vulnerability factors obtained from the RF model. The blue bar indicates the food hazard factors, while the orange bar indicates the food vulnerability factors



<span id="page-13-0"></span>**Fig. 8** The developed food risk map of the study area by multiplying the food hazard and vulnerability map. The lower urban area of the basin is prone to high food risk, while the upper mountainous area is prone to low or no flood risk

results exceptionally would be helpful to decide the development policy in the region. The restrictions and guidelines could be applied for the development near the river banks to reduce the food hazard. The RF model gave the region's population density and crop production the highest importance (44 and 30%) in food vulnerable factors. The major cities in the study area are located at the bank of the river, which is more vulnerable to a food event. The majority of the study area is used for agricultural activities. Many agricultural farms are located even on the delta part of the river due to the higher productive capacity of the land, which makes it more vulnerable to food. Due to the region's lower elevation and relatively higher rainfall statistics, the study area was considered very high vulnerable by the National Flood Vulnerability Assessment System developed by the Indian geo-platform of the Indian Space Research Organization (ISRO) (Fig. [9\)](#page-14-0). The ISRO's food vulnerability map is developed using a multi-criteria evaluation technique considering the factors such as probable maximum precipitation obtained by IMD gridded rainfall data, runoff potential obtained by LULC and soil texture, drainage density, and slope of the terrain. The developed food risk map indicates that Bharuch and Ankleshwar, located in the downstream area, are at high risk due to higher population density and lesser distance from the main river. The majority of the study area, including the sub-district of the Jhagadia, Sinor, Rajpipla, and Sankheda, are at moderate risk due to high rainfall distribution and lower elevation of the region. This result indicates the requirement of a proper storm-water drainage system in a particular area to reduce the food risk. The region's northern and southern



<span id="page-14-0"></span>**Fig. 9** Flood vulnerability map developed by National Flood Vulnerability Assessment System, Indian geoplatform of ISRO using multi-criteria evaluation technique. *Source* <https://bhuvan-app1.nrsc.gov.in/nfvas/#>

east parts are at low or no risk zone due to their higher elevation and slope, which quickly drains the water from these regions.

In the present study, the developed food risk map may have various sources of uncertainty, including uncertainty in the given input data and weighing scheme of the proposed ML algorithm. The SRTM DEM is used as the elevation of the terrain, which may contain measurement errors, and this can propagate to other factors such as the slope of the terrain, which is derived from the elevation map. The ground-based survey data would be useful in overcoming this limitation. Natural variability, such as changes in river pathways and LULC, may need to be updated on a regular basis to deal with the uncertainty of these factors. The dynamic factor such as annual rainfall may include measurement errors that must be addressed. However, while developing the food risk map, the ranks are assigned based on the diferent class values of these factors, which may account for minor uncertainties in the input data. The ML model and its parameter uncertainty play a critical role in the output from the model. However, the RF model is an ensemble ML algorithm, which may reduce the uncertainty in the output.

#### **4.3 Integrated ML and IoT‑based framework for real‑time food risk mapping**

The present study demonstrates that the remote sensing dataset can be utilized for food risk assessment and mapping studies in the data scare region. The critical challenge in using remote sensing-based big data is to develop an integrated analysis approach that can extract useful information from heterogeneous data. The traditional method of food risk prediction based on the hydrodynamic model or empirical relationships has its limitation in terms of data integration and utilization. Also, these methods require high computation time for simulating large high-resolution datasets. To overcome this limitation, the ML approach is demonstrated in the present study to develop the integrated framework for food risk mapping. The developed food risk map for the lower Narmada basin using the RF model shows that the rainfall distribution of the region is one of the crucial factors which is dynamic for the prediction of food risk maps. These also indicate the possibility of exploring more such dynamic hydrological process variable factors (such as soil

moisture condition, evaporation, and atmospheric variables), which can infuence the food risk in the region.

The IoT-based sensor network for measuring rainfall and soil moisture datasets can be constructed in the region to collect real-time data. Also, the monitoring stations can be developed to gather information related to food depth or hazard conditions from the recently developed new paradigm of social IoT (combining the social network with IoT). The dataset collected from the IoT network can be integrated with the remote sensing dataset using a GIS platform or cloud-based services to prepare the unifed dataset. The traditional method may not extract helpful information from such dynamic and diversifed data. The ML approach, such as the RF model, can be trained and calibrated based on historical data and can be used to extract useful information from the real-time heterogeneous data. However, because the majority of IoT-based devices are low-end, high-end computational resources are required to accomplish such processing. Furthermore, because the ML algorithms detect changes in the given input data and produce the desired output, IoT would be useful to provide real-time input and generate real-time output using ML. Based on the ML model results, the real-time food risk map can be developed and published with the help of web-based services (Fig. [10\)](#page-15-0).

The IoT network, along with weather forecast data, can also help prepare the early warning system. The IoT network will collect ground-based datasets such as soil moisture and streamfow, which are critical factors in generating foods. The weather forecast, such as precipitation, can be given as input to the ML model for generating future food risk scenarios. The dataset collected from the IoT network and weather forecast can be clustered based on the spatial location. The region-wise thresholds for risk level can be defned based on historical experiences. The warning system can be set up to send an alert message to authorities and stakeholders when the IoT-based data and weather forecast surpasses the



<span id="page-15-0"></span>**Fig. 10** Proposed framework for developing real-time food risk map using integrated IoT-based sensors and ML algorithm. The real-time data from the IoT-based network and static factors will be given as input to the ML algorithm to prepare a flood risk map

threshold. However, the accuracy of such food risk forecast will directly depend on the accuracy of the input data. As weather forecasts can be uncertain sometimes, the decision should be made based on historical experiences. In the absence of food risk, the constructed IoT sensor network can be helpful to monitor the region's irrigation requirement, as the majority of the study area has an agricultural land-use pattern. Such a multi-use of the dataset can result in long-term economic and social benefts for the initially invested resources.

# **5 Conclusions**

The present study prepared the food risk map for the lower Narmada basin using a machine learning algorithm based on available observed and remote sensing-based heterogeneous data. The methodology described in the present study could be helpful in the datascares region to predict the food risk. The traditional methods for food risk prediction, such as hydrodynamic modeling and empirical relationships, has limitations in utilizing the heterogeneous and diversifed dataset. The ensemble machine learning algorithm such as RF can be helpful to extract the information from remote sensing-based heterogeneous data in food risk mapping. The cross-validation method can be helpful to improve the performance of the model and fnd the balance between run time and accuracy of the model. The results from the present study indicate that the elevation, distance from the main river, land-use land-cover characteristics, and rainfall are the more signifcant food hazard factors. The population density and agricultural production are more exposed and vulnerable to the food hazard. The developed food risk map based on the feature importance of the food hazard and vulnerable factors shows that the two major cities (Bharuch and Ankleshwar) are at high food risk, and four sub-districts (Jhagadia, Sinor, Rajpipla, and Sankheda) are at medium food risk in the lower Narmada basin. As rainfall is a dynamic and signifcant food risk predictor, the IoT-based sensor network for measuring rainfall and other hydrological process variables can help prepare a real-time food risk map of the region. The proposed IoT-based framework and machine learning-based methodology to extract helpful information from heterogeneous data would be benefcial for government officials and policymakers to take necessary actions to reduce flood risk in the lower Narmada basin.

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**Data availability** The data used to support the fndings of this study are available from the corresponding author upon request.

## **Declarations**

**Confict of interest** The authors declare that they have no known competing fnancial interests or personal relationships that could have appeared to infuence the work reported in this paper.

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