

Existence and Stability of Pseudo Almost Periodic Solution for Neutral Type High-Order Hopfield Neural Networks with Delays in Leakage Terms on Time Scales

Yongkun Li¹ · Li Yang² · Bing Li¹

Published online: 28 October 2015
© Springer Science+Business Media New York 2015

Abstract Using the exponential dichotomy of linear dynamic equations on time scales, a fixed point theorem and the theory of calculus on time scales, we obtain some sufficient conditions for the existence and global exponential stability of pseudo almost periodic solutions for a class of neutral type high-order Hopfield neural networks with delays in leakage terms on time scales. Our results show that the continuous-time neural network and its discrete-time analogue have the same dynamical behaviors. Finally, we give a numerical example and simulation to illustrate the feasibility of our results. Results of this paper are completely new even if the time scale $\mathbb{T} = \mathbb{R}$ or \mathbb{Z} .

Keywords Pseudo almost periodic solution · High-order Hopfield neural networks · Exponential stability · Time scales

1 Introduction

Neural networks are widely applied in signal processing, pattern recognition, static image processing, associative memory, and combinatorial optimization. In such applications, it is major importance to ensure that the designed neural network is stable [1, 2]. Since high-order Hopfield neural networks (HHNNs) have stronger approximation property, faster convergence rate, great stronger capacity and higher fault tolerance, HHNNs have been extensively applied in psychophysics, robotics, adaptive pattern recognition and image processing. Hence, HHNNs have been widely studied in recent years. For instance, in [3–6], authors studied the absolute stability, robust stability, global asymptotic stability and exponential

✉ Bing Li
bli123@126.com

¹ Department of Mathematics, Yunnan University, Kunming 650091, Yunnan, People's Republic of China

² School of Statistics and Mathematics, Yunnan University of Finance and Economics, Kunming 650221, Yunnan, People's Republic of China

stability of HHNNs, respectively; in [7], by using coincidence degree theory and Lyapunov functional, authors studied the existence and global exponential stability of periodic solutions for delayed HHNNs, respectively; in [8], the author obtained sufficient conditions on the existence and exponential stability of anti-periodic solutions for HHNNs; in [9, 10], by using a fixed point theorem, Lyapunov functional method and differential inequality techniques, authors obtained sufficient conditions on the existence and exponential stability of almost periodic solutions for HHNNs.

In fact, it is natural and important that systems will contain some information about the derivative of the past state to further describe and model the dynamics for such complex neural reactions [11], many authors investigated the dynamical behaviors of neutral type neural networks. For example, authors in [12–17] studied the stability for different classes of neutral type neural networks; authors in [18] obtained some sufficient conditions for the existence of periodic solutions for neutral type cellular neural networks with delays; authors in [19–21] studied almost periodic solutions of several classes of neural networks with neutral delays.

On the other hand, very recently, a leakage delay, which is the time delay in the leakage term of the systems and a considerable factor affecting dynamics for the worse in the systems, is being put to use in the problem of stability for neural networks (see [22, 23]). Such time delays in the leakage term are difficult to handle but has great impact on the dynamical behavior of neural networks. Therefore, it is meaningful to consider neural networks with time delays in leakage terms. For example, authors of [24–27] studied the stability of some classes of neural networks with leakage delays; authors of [28] studied the equilibrium point of two classes fuzzy neural networks with delays in leakage terms; authors of [29] studied the global attractive periodic solutions of BAM neural networks with continuously distributed delays in the leakage term; authors of [30, 31] studied almost periodic solutions of a classes of neural networks with leakage delays.

Also, as we all know that both continuous time and discrete time neural networks have equal importance in various applications. But it is troublesome to study the dynamical properties for continuous and discrete time systems, respectively. Hence, the theory of time scales, which was initiated by Hilger [32] in his Ph.D. thesis to contain both difference and differential calculus in a consistent way, has recently received a lot of attention from many scholars. By choosing the time scale to be the set of real numbers and the set of integers, results on time scales yield results concerning with differential equations and difference equations, respectively. Besides, results on time scales can also be extended to other types of equations, for example, q -difference equations. Therefore, it is significant to study the dynamical behaviors of neural networks on time scales. For instance, in [33], authors studied periodic solutions of BAM neural networks on time scales; in [34], authors studied almost periodic solutions of neural networks on time scales.

In reality, almost periodicity is much universal than periodicity. And the concept of the pseudo-almost periodicity on time scales, which is the central question in this paper, was introduced by Li and Wang [35] in 2012, as a natural generalization of the well-known almost periodicity. However, to the best of our knowledge, there is no paper published on the pseudo almost periodic of high-order Hopfield neural networks with variable delays in leakage terms on time scales.

Motivated by the above, in this paper, we consider the following neutral type high-order Hopfield neural networks with variable delays on time scales:

$$\begin{aligned}
 x_i^\Delta(t) &= -c_i(t)x_i(t - \tau_i(t)) + \sum_{j=1}^n a_{ij}(t)f_j(x_j^\Delta(t - \delta_{ij}(t))) \\
 &\quad + \sum_{j=1}^n \sum_{l=1}^n b_{ijl}(t)g_j(x_j(t - \sigma_{ijl}(t)))g_l(x_l(t - \zeta_{ijl}(t))) + I_i(t), \quad t \in \mathbb{T}, \quad (1.1)
 \end{aligned}$$

where \mathbb{T} is an almost periodic time scale, $i = 1, 2, \dots, n$, n corresponds to the number of units in a neural network; $x_i(t)$ corresponds to the state vector of the i th unit at the time t ; $c_i(t)$ represents the rate with which the i th unit will reset its potential to the resting state in isolation when disconnected from the network and external inputs; $a_{ij}(t)$ and $b_{ijl}(t)$ are the first-order and second-order connection weights of the neural network; $\tau_i(t) > 0$ with $t - \tau_i(t) \in \mathbb{T}$ denotes time delay in the leakage term; $\delta_{ij}(t) \geq 0$, $\sigma_{ijl}(t) \geq 0$, $\zeta_{ijl}(t) \geq 0$ correspond to the transmission delays and satisfy $t - \delta_{ij}(t) \in \mathbb{T}$, $t - \sigma_{ijl}(t) \in \mathbb{T}$, $t - \zeta_{ijl}(t) \in \mathbb{T}$; $I_i(t)$ denote the external inputs at time t ; f_j and g_j are the activation functions of signal transmission, $j = 1, 2, \dots, n$.

Remark 1.1 If we take $\mathbb{T} = \mathbb{R}$, then (1.1) reduces to the following form

$$\begin{aligned}
 x'_i(t) &= -c_i(t)x_i(t - \tau_i(t)) + \sum_{j=1}^n a_{ij}(t)f_j(x'_j(t - \delta_{ij}(t))) \\
 &\quad + \sum_{j=1}^n \sum_{l=1}^n b_{ijl}(t)g_j(x_j(t - \sigma_{ijl}(t)))g_l(x_l(t - \zeta_{ijl}(t))) \\
 &\quad + I_i(t), \quad i = 1, 2, \dots, n, \quad t \in \mathbb{R}; \quad (1.2)
 \end{aligned}$$

if we take $\mathbb{T} = \mathbb{Z}$, then (1.1) reduces to the following form

$$\begin{aligned}
 x_i(k + 1) - x_i(k) &= -c_i(k)x_i(k - \tau_i(k)) + \sum_{j=1}^n a_{ij}(k)f_j(x_j(k + 1 - \delta_{ij}(k + 1))) \\
 &\quad - x_j(k - \delta_{ij}(k)) \\
 &\quad + \sum_{j=1}^n \sum_{l=1}^n b_{ijl}(k)g_j(x_j(k - \sigma_{ijl}(k)))g_l(x_l(k - \zeta_{ijl}(k))) \\
 &\quad + I_i(k), \quad i = 1, 2, \dots, n, \quad k \in \mathbb{Z}. \quad (1.3)
 \end{aligned}$$

To the best of our knowledge, there is no paper published on the existence and exponential stability of pseudo almost periodic solutions for (1.2) and (1.3).

Our main purpose of this paper is to study the existence and global exponential stability of pseudo almost periodic solutions for (1.1). Our results of this paper are completely new even if the time scale $\mathbb{T} = \mathbb{R}$ or \mathbb{Z} . Our results show that the existence and exponential stability of almost periodic solutions for system (1.1) not only depends on the delays in the leakage term, but also depends on the neutral terms in the network. Our results also show that the continuous-time neural network (1.2) and its discrete-time analogue (1.3) have the same dynamical behaviors, which provides a theoretical basis for the numerical simulation of continuous-time neural network system (1.2).

For convenience, we denote $[a, b]_{\mathbb{T}} = \{t \mid t \in [a, b] \cap \mathbb{T}\}$. For a bounded function $f : \mathbb{T} \rightarrow \mathbb{R}$, denote $f^+ = \sup_{t \in \mathbb{T}} |f(t)|$, $f^- = \inf_{t \in \mathbb{T}} |f(t)|$. We denote by \mathbb{R} the set of real numbers, by

\mathbb{R}^+ the set of positive real numbers, by \mathbb{E}^n a real Banach space with the norm $\|\cdot\|$, by D a subset of \mathbb{E}^n and by $BC(\mathbb{T} \times D, \mathbb{E}^n)$ the set of all \mathbb{E}^n -valued bounded continuous functions.

The initial condition of (1.1) is the following

$$x_i(s) = \varphi_i(s), \quad x_i^\Delta(s) = \varphi_i^\Delta(s), \quad s \in [-\theta, 0]_{\mathbb{T}},$$

where $\theta = \max \left\{ \max_{1 \leq i \leq n} \tau_i^+, \max_{(i,j)} \{\delta_{ij}^+, \sigma_{ijl}^+, \zeta_{ijl}^+\} \right\}$, $\varphi_i \in C^1([-\theta, 0]_{\mathbb{T}}, \mathbb{R})$, $i = 1, 2, \dots, n$.

This paper is organized as follows: In Sect. 2, we introduce some notations and definitions and state some preliminary results which are needed in later sections. In Sect. 3, we establish some sufficient conditions for the existence of pseudo almost periodic solutions of (1.1) and prove that the pseudo almost periodic solution is globally exponentially stable. In Sect. 4, we give an example to illustrate the feasibility of our results obtained in previous sections.

2 Preliminaries

In this section, we introduce some definitions and state some preliminary results.

Definition 2.1 [36] Let \mathbb{T} be a nonempty closed subset (time scale) of \mathbb{R} . The forward and backward jump operators $\sigma, \rho : \mathbb{T} \rightarrow \mathbb{T}$ and the graininess $\mu : \mathbb{T} \rightarrow \mathbb{R}_+$ are defined, respectively, by

$$\sigma(t) = \inf\{s \in \mathbb{T} : s > t\}, \quad \rho(t) = \sup\{s \in \mathbb{T} : s < t\} \quad \text{and} \quad \mu(t) = \sigma(t) - t.$$

Lemma 2.1 [36] Assume that $p, q : \mathbb{T} \rightarrow \mathbb{R}$ are two regressive functions, then

- (i) $e_0(t, s) \equiv 1$ and $e_p(t, t) \equiv 1$;
- (ii) $e_p(t, s) = \frac{1}{e_p(s, t)} = e_{\ominus p}(s, t)$;
- (iii) $e_p(t, s)e_p(s, r) = e_p(t, r)$;
- (iv) $(e_p(t, s))^\Delta = p(t)e_p(t, s)$.

Lemma 2.2 [36] Let f, g be Δ -differentiable functions on T , then

- (i) $(v_1 f + v_2 g)^\Delta = v_1 f^\Delta + v_2 g^\Delta$, for any constants v_1, v_2 ;
- (ii) $(fg)^\Delta(t) = f^\Delta(t)g(t) + f(\sigma(t))g^\Delta(t) = f(t)g^\Delta(t) + f^\Delta(t)g(\sigma(t))$;

Lemma 2.3 [36] Assume that $p(t) \geq 0$ for $t \geq s$, then $e_p(t, s) \geq 1$.

Definition 2.2 [36] A function $p : \mathbb{T} \rightarrow \mathbb{R}$ is called regressive provided $1 + \mu(t)p(t) \neq 0$ for all $t \in \mathbb{T}^k$; $p : \mathbb{T} \rightarrow \mathbb{R}$ is called positively regressive provided $1 + \mu(t)p(t) > 0$ for all $t \in \mathbb{T}^k$. The set of all regressive and rd-continuous functions $p : \mathbb{T} \rightarrow \mathbb{R}$ will be denoted by $\mathcal{R} = \mathcal{R}(\mathbb{T}, \mathbb{R})$ and the set of all positively regressive functions and rd-continuous functions will be denoted by $\mathcal{R}^+ = \mathcal{R}^+(\mathbb{T}, \mathbb{R})$.

Lemma 2.4 [36] Suppose that $p \in \mathcal{R}^+$, then

- (i) $e_p(t, s) > 0$, for all $t, s \in \mathbb{T}$;
- (ii) if $p(t) \leq q(t)$ for all $t \geq s, t, s \in \mathbb{T}$, then $e_p(t, s) \leq e_q(t, s)$ for all $t \geq s$.

Lemma 2.5 ([36]) If $p \in \mathcal{R}$ and $a, b, c \in \mathbb{T}$, then

$$[e_p(c, \cdot)]^\Delta = -p[e_p(c, \cdot)]^\sigma$$

and

$$\int_a^b p(t)e_p(c, \sigma(t))\Delta t = e_p(c, a) - e_p(c, b).$$

Lemma 2.6 [36] *Let $a \in \mathbb{T}^k, b \in \mathbb{T}$ and assume that $f : \mathbb{T} \times \mathbb{T}^k \rightarrow \mathbb{R}$ is continuous at (t, t) , where $t \in \mathbb{T}^k$ with $t > a$. Also assume that $f^\Delta(t, \cdot)$ is rd-continuous on $[a, \sigma(t)]$. Suppose that for each $\varepsilon > 0$, there exists a neighborhood U of $\tau \in [a, \sigma(t)]$ such that*

$$|f(\sigma(t), \tau) - f(s, \tau) - f^\Delta(t, \tau)(\sigma(t) - s)| \leq \varepsilon|\sigma(t) - s|, \quad \forall s \in U,$$

where f^Δ denotes the derivative of f with respect to the first variable. Then

- (i) $g(t) := \int_a^t f(t, \tau)\Delta\tau$ implies $g^\Delta(t) := \int_a^t f^\Delta(t, \tau)\Delta\tau + f(\sigma(t), t)$;
- (ii) $h(t) := \int_t^b f(t, \tau)\Delta\tau$ implies $h^\Delta(t) := \int_t^b f^\Delta(t, \tau)\Delta\tau - f(\sigma(t), t)$.

In the following, we recall some definitions, notations and basic results of almost periodicity and pseudo almost periodicity on time scales. For more details, we refer the reader to [35,37].

Definition 2.3 [37] A time scale \mathbb{T} is called an almost periodic time scale if

$$\Pi := \{\tau \in \mathbb{R} : t \pm \tau \in \mathbb{T}, \forall t \in \mathbb{T}\} \neq \{0\}.$$

In this paper, we restrict our discussion on almost periodic time scales.

Definition 2.4 [37] Let \mathbb{T} be an almost periodic time scale. A function $f(t) : \mathbb{T} \rightarrow \mathbb{R}^n$ is said to be almost periodic on \mathbb{T} , if for any $\varepsilon > 0$, the set

$$E(\varepsilon, f) = \{\tau \in \Pi : |f(t + \tau) - f(t)| < \varepsilon, \forall t \in \mathbb{T}\}$$

is relatively dense, that is, for any $\varepsilon > 0$, there exists a constant $l(\varepsilon) > 0$ such that each interval of length $l(\varepsilon)$ contains at least one $\tau \in E(\varepsilon, f)$ such that

$$|f(t + \tau) - f(t)| < \varepsilon, \quad \forall t \in \mathbb{T}.$$

The set $E(\varepsilon, f)$ is called the ε -translation set of $f(t)$, τ is called the ε -translation number of $f(t)$, and $l(\varepsilon)$ is called the inclusion of $E(\varepsilon, f)$.

Definition 2.5 [37] Let \mathbb{T} be an almost periodic time scale. A function $f \in C(\mathbb{T} \times D, \mathbb{E}^n)$ is said to be almost periodic in t uniformly for $x \in D$, if for any $\varepsilon > 0$ and for each compact subset $S \subset D$, there exists a constant $l(\varepsilon) > 0$ such that each interval of length $l(\varepsilon)$ contains at least one $\tau \in E(\varepsilon, f)$ such that

$$|f(t + \tau, x) - f(t, x)| < \varepsilon, \quad \forall t \in \mathbb{T}, \quad x \in S.$$

In the following, we introduce some notations

$$AP(\mathbb{T} \times D)_n = \{f \in C(\mathbb{T} \times D, \mathbb{E}^n) : f \text{ is almost periodic in } t \text{ uniformly for } x \in D\},$$

$$AP(\mathbb{T})_n = \{f \in C(\mathbb{T}, \mathbb{E}^n) : f \text{ is almost periodic}\},$$

$$PAP_0(\mathbb{T})_n = \left\{ f \in BC(\mathbb{T}, \mathbb{E}^n) : f \text{ is } \Delta - \text{measurable such that} \right. \\ \left. \lim_{r \rightarrow +\infty} \frac{1}{2r} \int_{t_0-r}^{t_0+r} |f(s)| \Delta s = 0, \text{ where } t_0 \in \mathbb{T}, r \in \Pi \right\},$$

$$PAP_0(\mathbb{T} \times D)_n = \left\{ f \in BC(\mathbb{T} \times D, \mathbb{E}^n) : f(\cdot, x) \in PAP_0(\mathbb{T}) \text{ for each } x \in D \text{ and} \right. \\ \left. \lim_{r \rightarrow +\infty} \frac{1}{2r} \int_{t_0-r}^{t_0+r} \|f(s, x)\| \Delta s = 0 \text{ uniformly for } x \in D, \right. \\ \left. \text{where } t_0 \in \mathbb{T}, r \in \Pi \right\}.$$

Definition 2.6 [35] Let \mathbb{T} be an almost periodic time scale. A function $f \in C(\mathbb{T} \times D, \mathbb{E}^n)$ is said to be pseudo almost periodic in t uniformly for $x \in D$, if $f = g + \varphi$, where $g \in AP(\mathbb{T} \times D)_n$ and $\varphi \in PAP_0(\mathbb{T} \times D)_n$. We denote by $PAP(\mathbb{T} \times D)_n$ the set of all such functions.

Definition 2.7 [35] Let \mathbb{T} be an almost periodic time scale. A function $f \in C(\mathbb{T}, \mathbb{E}^n)$ is said to be pseudo almost periodic, if $f = g + \varphi$, where $g \in AP(\mathbb{T})_n$ and $\varphi \in PAP_0(\mathbb{T})_n$. We denote by $PAP(\mathbb{T})_n$ the set of all such functions.

Definition 2.8 [35] Let $X \in \mathbb{R}^n$ and $A(t)$ be a $n \times n$ matrix-valued function on \mathbb{T} , the linear system

$$X^\Delta(t) = A(t)X(t), \quad t \in \mathbb{T} \tag{2.1}$$

is said to admit an exponential dichotomy on \mathbb{T} if there exist positive constants $k_i, \alpha_i, i = 1, 2$, projection P and the fundamental solution matrix $X(t)$ of (2.1) satisfying

$$|X(t)PX^{-1}(s)| \leq k_1 e_{\ominus\alpha_1}(t, s), \quad s, t \in \mathbb{T}, t \geq s, \\ |X(t)(I - P)X^{-1}(s)| \leq k_2 e_{\ominus\alpha_2}(s, t), \quad s, t \in \mathbb{T}, t \leq s,$$

where $|\cdot|$ is a matrix norm on \mathbb{T} , that is, if $A = (a_{ij})_{n \times m}$, then we can take $|A| = \left(\sum_{i=1}^n \sum_{j=1}^m |a_{ij}|^2 \right)^{\frac{1}{2}}$.

Lemma 2.7 [35] Suppose that $A(t)$ is almost periodic and $g \in PAP(\mathbb{T})_n$, (2.1) admits an exponential dichotomy, then the following system:

$$X^\Delta(t) = A(t)X(t) + g(t)$$

has a unique bounded solution $X \in PAP(\mathbb{T})_n$ and $X(t)$ is expressed as follows

$$X(t) = \int_{-\infty}^t X(t)PX^{-1}(\sigma(s))g(s)\Delta s - \int_t^{+\infty} X(t)(I - P)X^{-1}(\sigma(s))g(s)\Delta s,$$

where $X(t)$ is the fundamental solution matrix of (2.1).

Lemma 2.8 [37] *Let $c_i(t) > 0$ and $-c_i(t) \in \mathcal{R}^+, \forall t \in \mathbb{T}$. If*

$$\min_{1 \leq i \leq n} \left\{ \inf_{t \in \mathbb{T}} c_i(t) \right\} = \tilde{m} > 0,$$

then the linear system

$$x^\Delta(t) = \text{diag}(-c_1(t), -c_2(t), \dots, -c_n(t))x(t) \tag{2.2}$$

admits an exponential dichotomy on \mathbb{T} .

Definition 2.9 Let $x^*(t) = (x_1^*(t), x_2^*(t), \dots, x_n^*(t))^T$ be a pseudo almost periodic solution of (1.1) with initial value $\varphi^*(s) = (\varphi_1^*(s), \varphi_2^*(s), \dots, \varphi_n^*(s))^T$. If there exist positive constants λ with $\ominus\lambda \in \mathcal{R}^+$ and $M > 1$ such that such that for an arbitrary solution $x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T$ of (1.1) with initial value $\varphi(s) = (\varphi_1(s), \varphi_2(s), \dots, \varphi_n(s))^T$ satisfies

$$\|x - x^*\| \leq M\|\varphi - \varphi^*\|e_{\ominus\lambda}(t, t_0), \quad t_0 \in [-\theta, \infty)_{\mathbb{T}}, t \geq t_0.$$

Then the solution $x^*(t)$ is said to be globally exponentially stable.

3 Main Results

In this section, we state and prove our main results.

Let $\mathbb{X}^* = \{f|f, f^\Delta \in PAP(\mathbb{T}, \mathbb{R}^n)\}$ with the norm $\|f\|_{\mathbb{X}^*} = \max\{\|f\|_1, \|f^\Delta\|_1\}$, where $\|f\|_1 = \max_{1 \leq i \leq n} f_i^+, \|f^\Delta\|_1 = \max_{1 \leq i \leq n} (f_i^\Delta)^+$. Then \mathbb{X}^* is a Banach space. Let $\varphi^0(t) = (\varphi_1^0(t), \varphi_2^0(t), \dots, \varphi_n^0(t))^T$, where $\varphi_i^0(t) = \int_{-\infty}^t e_{-a_i}(t, \sigma(s))I_i(s)\Delta s, i = 1, 2, \dots, n$ and L be a constant satisfying $L \geq \max\{\|\varphi^0\|_{\mathbb{X}^*}, \max_{1 \leq j \leq n} \{|f_j(0)|\}, \max_{1 \leq j \leq n} \{|h_j(0)|\}, \max_{1 \leq j \leq n} \{|g_j(0)|\}\}$.

Theorem 3.1 *Suppose that*

- (H₁) $c_i \in C(\mathbb{T}, \mathbb{R}^+)$ with $-c_i \in \mathcal{R}^+$ is almost periodic and $a_{ij}, b_{ijl}, I_i \in C(\mathbb{T}, \mathbb{R}), \tau_i, \delta_{ij}, \sigma_{ijl}, \zeta_{ijl} \in C(\mathbb{T}, \mathbb{R}^+)$ are pseudo almost periodic, where $i, j, l = 1, 2, \dots, n$;
- (H₂) $f_j, g_j \in C(\mathbb{R}, \mathbb{R})$ and there exist positive constants N_j, L_j, H_j such that $|g_j(u)| \leq N_j, |f_j(u) - f_j(v)| \leq L_j|u - v|, |g_j(u) - g_j(v)| \leq H_j|u - v|$, where $u, v \in \mathbb{R}, j = 1, 2, \dots, n$;
- (H₃) $\max_{1 \leq i \leq n} \left\{ \frac{\theta_i}{c_i^-}, (1 + \frac{c_i^+}{c_i^-})\theta_i \right\} \leq \frac{1}{2}, \max_{1 \leq i \leq n} \left\{ \frac{\gamma_i}{c_i^-}, (1 + \frac{c_i^+}{c_i^-})\gamma_i \right\} < 1$, where $\theta_i = c_i^+ \tau_i^+ + \sum_{j=1}^n \left(a_{ij}^+ (L_j + \frac{1}{2}) + \sum_{l=1}^n b_{ijl}^+ N_l (H_j + \frac{1}{2}) \right), \gamma_i = c_i^+ \tau_i^+ + \sum_{j=1}^n \left(a_{ij}^+ L_j + \sum_{l=1}^n b_{ijl}^+ (N_j H_l + H_j N_l) \right), i = 1, 2, \dots, n$,

then (1.1) has a unique pseudo almost periodic solution in $\mathbb{X}_0 = \{\varphi \in \mathbb{X}^ | \|\varphi - \varphi^0\|_{\mathbb{X}^*} \leq L\}$.*

Proof For any given $\varphi \in \mathbb{X}^*$, we consider the following system:

$$x_i^\Delta(t) = -c_i(t)x_i(t) + F_i(t, \varphi) + I_i(t), \tag{3.1}$$

where

$$\begin{aligned}
 F_i(t, \varphi) &= c_i(t) \int_{t-\tau_i(t)}^t \varphi_i^\Delta(s) \Delta s + \sum_{j=1}^n a_{ij}(t) f_j(\varphi_j^\Delta(t - \delta_{ij}(t))) \\
 &\quad + \sum_{j=1}^n \sum_{l=1}^n b_{ijl}(t) g_j(\varphi_j(t - \sigma_{ijl}(t))) g_l(\varphi_l(t - \zeta_{ijl}(t))), \quad i = 1, 2, \dots, n.
 \end{aligned}$$

Since $\min_{1 \leq i \leq n} \{ \inf c_i(t) \} > 0, t \in \mathbb{T}$, it follows from Lemma 2.8 that the linear system

$$x_i^\Delta(t) = -c_i(t)x_i(t), \quad i = 1, 2, \dots, n$$

admits an exponential dichotomy on \mathbb{T} . Thus, by Lemma 2.7, we obtain that system (3.1) has exactly one pseudo almost periodic solution as follows

$$x_i^\varphi(t) = \int_{-\infty}^t e_{-c_i}(t, \sigma(s)) (F_i(s, \varphi) + I_i(s)) \Delta s, \quad i = 1, 2, \dots, n.$$

For $\varphi \in \mathbb{X}^*$, then $\|\varphi\|_{\mathbb{X}^*} \leq \|\varphi - \varphi_0\|_{\mathbb{X}^*} + \|\varphi_0\|_{\mathbb{X}^*} \leq 2L$. Define the following operator

$$\Phi : \mathbb{X}^* \rightarrow \mathbb{X}^*, \quad (\varphi_1, \varphi_2, \dots, \varphi_n)^T \rightarrow (x_1^\varphi, x_2^\varphi, \dots, x_n^\varphi)^T.$$

First we show that for any $\varphi \in \mathbb{X}^*$, we have $\Phi\varphi \in \mathbb{X}^*$. Note that

$$\begin{aligned}
 |F_i(s, \varphi)| &= \left| c_i(s) \int_{s-\tau_i(s)}^s \varphi_i^\Delta(\vartheta) \Delta \vartheta + \sum_{j=1}^n a_{ij}(s) f_j(\varphi_j^\Delta(s - \delta_{ij}(s))) \right. \\
 &\quad \left. + \sum_{j=1}^n \sum_{l=1}^n b_{ijl}(s) g_j(\varphi_j(s - \sigma_{ijl}(s))) g_l(\varphi_l(s - \zeta_{ijl}(s))) \right| \\
 &\leq c_i^+ \tau_i^+ \|\varphi\|_{\mathbb{X}^*} + \sum_{j=1}^n a_{ij}^+ \left(|f_j(\varphi_j^\Delta(s - \delta_{ij}(s))) - f_j(0)| + |f_j(0)| \right) \\
 &\quad + \sum_{j=1}^n \sum_{l=1}^n b_{ijl}^+ N_l \left(|g_j(\varphi_j(s - \sigma_{ijl}(s))) - g_j(0)| + |g_j(0)| \right) \\
 &\leq \left(c_i^+ \tau_i^+ + \sum_{j=1}^n a_{ij}^+ L_j \right) \|\varphi\|_{\mathbb{X}^*} + \sum_{j=1}^n a_{ij}^+ |f_j(0)| \\
 &\quad + \sum_{j=1}^n \sum_{l=1}^n b_{ijl}^+ N_l H_j \|\varphi\|_{\mathbb{X}^*} + \sum_{j=1}^n \sum_{l=1}^n b_{ijl}^+ N_l |g_j(0)| \\
 &\leq 2L \left[c_i^+ \tau_i^+ + \sum_{j=1}^n \left(a_{ij}^+ \left(L_j + \frac{1}{2} \right) + \sum_{l=1}^n b_{ijl}^+ N_l \left(H_j + \frac{1}{2} \right) \right) \right].
 \end{aligned}$$

Therefore, we have

$$\begin{aligned}
 |(\Phi(\varphi - \varphi^0))_i(t)| &= \left| \int_{-\infty}^t e_{-c_i}(t, \sigma(s)) F_i(s, \varphi) \Delta s \right| \\
 &\leq \int_{-\infty}^t e_{-c_i}(t, \sigma(s)) |F_i(s, \varphi)| \Delta s \\
 &\leq 2L \int_{-\infty}^t e_{-c_i}(t, \sigma(s)) \sum_{j=1}^n \left[c_i^+ \tau_i^+ + \sum_{j=1}^n \left(a_{ij}^+ \left(L_j + \frac{1}{2} \right) \right. \right. \\
 &\quad \left. \left. + \sum_{l=1}^n b_{ijl}^+ N_l \left(H_j + \frac{1}{2} \right) \right) \right] \Delta s \\
 &\leq \frac{2L\theta_i}{c_i^-}, \quad i = 1, 2, \dots, n.
 \end{aligned}$$

On the other hand, for $i = 1, 2, \dots, n$, we have

$$\begin{aligned}
 \left| \left(\Phi(\varphi - \varphi^0) \right)_i^\Delta(t) \right| &= \left| \left(\int_{-\infty}^t e_{-c_i}(t, \sigma(s)) F_i(s, \varphi) \Delta s \right)_t^\Delta \right| \\
 &= \left| F_i(t, \varphi) - c_i(t) \int_{-\infty}^t e_{-c_i}(t, \sigma(s)) F_i(s, \varphi) \Delta s \right| \\
 &\leq |F_i(t, \varphi)| + |c_i(t)| \int_{-\infty}^t e_{-c_i}(t, \sigma(s)) |F_i(s, \varphi)| \Delta s \\
 &\leq 2L\theta_i \left(1 + \frac{c_i^+}{c_i^-} \right).
 \end{aligned}$$

In view of (H_3) , we have

$$\|\Phi\varphi - \varphi^0\|_{\mathbb{X}^*} \leq 2L \max_{1 \leq i \leq n} \left\{ \frac{\theta_i}{c_i^-}, \left(1 + \frac{c_i^+}{c_i^-} \right) \theta_i \right\} \leq L,$$

that is, $\Phi\varphi \in \mathbb{X}_0$. Next, we show that Φ is a contraction. For $\varphi = (\varphi_1, \varphi_2, \dots, \varphi_n)^T$, $\psi = (\psi_1, \psi_2, \dots, \psi_n)^T \in \mathbb{X}_0$, for $i = 1, 2, \dots, n$, denote by

$$\begin{aligned}
 G_i(s, \varphi, \psi) &= c_i(s) \int_{s-\tau_i(s)}^s (\varphi^\Delta(\theta) - \psi^\Delta(\theta)) \Delta\theta \\
 &\quad + \sum_{j=1}^n a_{ij}(s) (f_j(\varphi_j^\Delta(s - \delta_{ij}(s))) - f_j(\psi_j^\Delta(s - \delta_{ij}(s))))
 \end{aligned}$$

and

$$\begin{aligned}
 K_i(s, \varphi, \psi) &= \sum_{j=1}^n \sum_{l=1}^n b_{ijl}(s) (g_j(\varphi_j(s - \sigma_{ijl}(s))) g_l(\varphi_l(s - \zeta_{ijl}(s))) \\
 &\quad - g_j(\psi_j(s - \sigma_{ijl}(s))) g_l(\psi_l(s - \zeta_{ijl}(s)))).
 \end{aligned}$$

Note that, for $i = 1, 2, \dots, n$,

$$\begin{aligned}
 |G_i(s, \varphi, \psi)| &= \left| c_i(s) \int_{s-\tau_i(s)}^s (\varphi^\Delta(\theta) - \psi^\Delta(\theta)) \Delta\theta \right. \\
 &\quad \left. + \sum_{j=1}^n a_{ij}(s) (f_j(\varphi_j^\Delta(s - \delta_{ij}(s))) - f_j(\psi_j^\Delta(s - \delta_{ij}(s)))) \right| \\
 &\leq \left(c_i^+ \tau_i^+ + \sum_{j=1}^n a_{ij}^+ L_j \right) \|\varphi - \psi\|_{\mathbb{X}^*}
 \end{aligned}$$

and

$$\begin{aligned}
 |K_i(s, \varphi, \psi)| &= \left| \sum_{j=1}^n \sum_{l=1}^n b_{ijl}(s) (g_j(\varphi_j(s - \sigma_{ijl}(s))) g_l(\varphi_l(s - \zeta_{ijl}(s))) \right. \\
 &\quad \left. - g_j(\psi_j(s - \sigma_{ijl}(s))) g_l(\psi_l(s - \zeta_{ijl}(s)))) \right| \\
 &\leq \sum_{j=1}^n \sum_{l=1}^n b_{ijl}^+ \left[|g_j(\varphi_j(s - \sigma_{ijl}(s)))| |g_l(\varphi_l(s - \zeta_{ijl}(s))) - g_l(\psi_l(s - \zeta_{ijl}(s)))| \right. \\
 &\quad \left. + |g_j(\varphi_j(s - \sigma_{ijl}(s))) - g_j(\psi_j(s - \sigma_{ijl}(s)))| |g_l(\psi_l(s - \zeta_{ijl}(s)))| \right] \\
 &\leq \sum_{j=1}^n \sum_{l=1}^n b_{ijl}^+ (N_j H_l + H_j N_l) \|\varphi - \psi\|_{\mathbb{X}^*}.
 \end{aligned}$$

Then, we have

$$\begin{aligned}
 |(\Phi\varphi - \Phi\psi)_i(t)| &= \left| \int_{-\infty}^t e_{-c_i}(t, \sigma(s)) (G_i(s, \varphi, \psi) + K_i(s, \varphi, \psi)) \Delta s \right| \\
 &\leq \int_{-\infty}^t e_{-c_i}(t, \sigma(s)) \left(c_i^+ \tau_i^+ + \sum_{j=1}^n (a_{ij}^+ L_j \right. \\
 &\quad \left. + \sum_{l=1}^n b_{ijl}^+ (N_j H_l + H_j N_l)) \right) \Delta s \|\varphi - \psi\|_{\mathbb{X}^*} \\
 &\leq \frac{\gamma_i}{c_i} \|\varphi - \psi\|_{\mathbb{X}^*}, \quad i = 1, 2, \dots, n
 \end{aligned}$$

and

$$\begin{aligned}
 |(\Phi\phi - \Phi\xi)_i^\Delta(t)| &= \left| \left(\int_{-\infty}^t e_{-c_i}(t, \sigma(s)) (G_i(s, \varphi, \psi) + K_i(s, \varphi, \psi))^\Delta \right)_i \right| \\
 &= \left| G_i(t, \varphi, \psi) + K_i(t, \varphi, \psi) \right. \\
 &\quad \left. - c_i(t) \int_{-\infty}^t e_{-c_i}(t, \sigma(s)) (G_i(s, \varphi, \psi) + K_i(s, \varphi, \psi)) \Delta s \right| \\
 &\leq |G_i(t, \varphi, \psi)| + |K_i(t, \varphi, \psi)| \\
 &\quad + |c_i(t)| \int_{-\infty}^t e_{-c_i}(t, \sigma(s)) |G_i(s, \varphi, \psi) + K_i(s, \varphi, \psi)| \Delta s \\
 &\leq \left(1 + \frac{c_i^+}{c_i} \right) \gamma_i \|\varphi - \psi\|_{\mathbb{X}^*}, \quad i = 1, 2, \dots, n.
 \end{aligned}$$

By (H_3) , we have that $\|\Phi\varphi - \Phi\psi\| < \|\varphi - \psi\|$. Hence, Φ is a contraction. Therefore, Φ has a fixed point in \mathbb{X}_0 , that is, (1.1) has a unique pseudo almost periodic solution in \mathbb{X}_0 . This completes the proof of Theorem 3.1. \square

Theorem 3.2 *Let (H_1) - (H_3) hold. Then the pseudo almost periodic solution of system (1.1) is globally exponentially stable.*

Proof According to Theorem 3.1, we know that (1.1) has a pseudo almost periodic solution $x(t) = (x_1(t), x_2(t), \dots, x_n(t))^T$ with the initial condition $\varphi(s) = (\varphi_1(s), \varphi_2(s), \dots, \varphi_n(s))^T$. Suppose that $y(t) = (y_1(t), y_2(t), \dots, y_n(t))^T$ is an arbitrary solution of (1.1) with the initial condition $\psi(s) = (\psi_1(s), \psi_2(s), \dots, \psi_n(s))^T$. Denote $u(t) = (u_1(t), u_2(t), \dots, u_n(t))^T$, where $u_i(t) = y_i(t) - x_i(t)$, $i = 1, 2, \dots, n$. Then it follows from (1.1) that

$$\begin{aligned} u_i^\Delta(t) &= -c_i(t)u_i(t - \tau_i(t)) + \sum_{j=1}^n a_{ij}(t)(f_j(y_j^\Delta(t - \delta_{ij}(t))) - f_j(x_j^\Delta(t - \delta_{ij}(t)))) \\ &+ \sum_{j=1}^n \sum_{l=1}^n b_{ijl}(t)(g_j(y_j(t - \sigma_{ijl}(t)))g_l(y_l(t - \zeta_{ijl}(t))) \\ &- g_j(x_j(t - \sigma_{ijl}(t)))g_l(x_l(t - \zeta_{ijl}(t))))), \quad i = 1, 2, \dots, n. \end{aligned} \tag{3.2}$$

The initial condition of (3.2) is

$$\psi_i(s) = \varphi_i(s) - \psi_i(s), \quad \psi_i^\Delta(s) = \varphi_i^\Delta(s) - \psi_i^\Delta(s), \quad s \in [-\theta, 0]_{\mathbb{T}}, \quad i = 1, 2, \dots, n.$$

Rewrite (3.2) in the form

$$\begin{aligned} u_i^\Delta(t) &= -c_i(t)u_i(t) + c_i(t) \int_{t-\tau_i(t)}^t u_i^\Delta(s)\Delta s \\ &+ \sum_{j=1}^n a_{ij}(t)(f_j(y_j^\Delta(t - \delta_{ij}(t))) - f_j(x_j^\Delta(t - \delta_{ij}(t)))) \\ &+ \sum_{j=1}^n \sum_{l=1}^n b_{ijl}(t)(g_j(y_j(t - \sigma_{ijl}(t)))g_l(y_l(t - \zeta_{ijl}(t))) \\ &- g_j(x_j(t - \sigma_{ijl}(t)))g_l(x_l(t - \zeta_{ijl}(t))))), \quad i = 1, 2, \dots, n. \end{aligned} \tag{3.3}$$

Then, for $i = 1, 2, \dots, n$ and $t \geq t_0$, $t_0 \in [-\theta, 0]_{\mathbb{T}}$, we have

$$\begin{aligned} u_i(t) &= u_i(t_0)e_{-c_i}(t, t_0) + \int_{t_0}^t e_{-c_i}(t, \sigma(s)) \left\{ c_i(s) \int_{s-\tau_i(s)}^s u_i^\Delta(\vartheta)\Delta\vartheta \right. \\ &+ \sum_{j=1}^n a_{ij}(s)(f_j(y_j^\Delta(s - \delta_{ij}(s))) - f_j(x_j^\Delta(s - \delta_{ij}(s)))) \\ &+ \sum_{j=1}^n \sum_{l=1}^n b_{ijl}(s)(g_j(y_j(s - \sigma_{ijl}(s)))g_l(y_l(s - \zeta_{ijl}(s))) \\ &\left. - g_j(x_j(s - \sigma_{ijl}(s)))g_l(x_l(s - \zeta_{ijl}(s)))) \right\} \Delta s. \end{aligned} \tag{3.4}$$

For $\omega \in \mathbb{R}$, let $\Gamma_i(\omega)$ and $\Theta_i(\omega)$ be defined by

$$\Gamma_i(\omega) = c_i^- - \omega - \exp\{\omega \sup_{s \in \mathbb{T}} \mu(s)\} \left(c_i^+ \tau_i^+ \exp\{\omega \tau_i^+\} + \sum_{j=1}^n a_{ij}^+ L_j \exp\{\omega \delta_{ij}^+\} \right. \\ \left. + \sum_{j=1}^n b_{ijl}^+ N_l H_j \exp\{\omega \sigma_{ijl}^+\} + \sum_{j=1}^n b_{ijl}^+ N_j H_l \exp\{\omega \zeta_{ijl}^+\} \right)$$

and

$$\Theta_i(\omega) = c_i^- - \omega - \left(c_i^+ \exp\{\omega \sup_{s \in \mathbb{T}} \mu(s)\} + c_i^- - \omega \right) \left(c_i^+ \tau_i^+ \exp\{\omega \tau_i^+\} \right. \\ \left. + \sum_{j=1}^n a_{ij}^+ L_j \exp\{\omega \delta_{ij}^+\} + \sum_{j=1}^n b_{ijl}^+ N_l H_j \exp\{\omega \sigma_{ijl}^+\} + \sum_{j=1}^n b_{ijl}^+ N_j H_l \exp\{\omega \zeta_{ijl}^+\} \right),$$

where $i = 1, 2, \dots, n$. In view of (H_3) , for $i = 1, 2, \dots, n$, we have

$$\Gamma_i(0) = c_i^- - \left(c_i^+ \tau_i^+ + \sum_{j=1}^n a_{ij}^+ L_j + \sum_{j=1}^n b_{ijl}^+ (N_l H_j + N_j H_l) \right) > 0,$$

and

$$\Theta_i(0) = c_i^- - (c_i^+ + c_i^-) \left(c_i^+ \tau_i^+ + \sum_{j=1}^n a_{ij}^+ L_j + \sum_{j=1}^n b_{ijl}^+ (N_l H_j + N_j H_l) \right) > 0.$$

Since $\Gamma_i(\omega), \Theta_i(\omega)$ are continuous on $[0, +\infty)$ and $\Gamma_i(\omega), \Theta_i(\omega) \rightarrow -\infty$, as $\omega \rightarrow +\infty$, so there exist $\omega_i, \omega_i^* > 0$ such that $\Gamma_i(\omega_i) = \Theta_i(\omega_i^*) = 0$ and $\Gamma_i(\omega) > 0$ for $\omega \in (0, \omega_i), \Theta_i(\omega) > 0$ for $\omega \in (0, \omega_i^*), i = 1, 2, \dots, n$. By choosing a positive constant $a = \min \{\omega_1, \omega_2, \dots, \omega_n, \omega_1^*, \omega_2^*, \dots, \omega_n^*\}$, we have $\Gamma_i(a) \geq 0, \Theta_i(a) \geq 0, i = 1, 2, \dots, n$. Hence, we can choose a positive constant $0 < \alpha < \min \{a, \min_{1 \leq i \leq n} \{c_i^-\}\}$ such that

$$\Gamma_i(\alpha) > 0, \Theta_i(\alpha) > 0, \quad i = 1, 2, \dots, n,$$

which implies that

$$\frac{\exp\{\alpha \sup_{s \in \mathbb{T}} \mu(s)\}}{c_i^- - \alpha} \left(c_i^+ \tau_i^+ \exp\{\alpha \tau_i^+\} + \sum_{j=1}^n a_{ij}^+ L_j \exp\{\alpha \delta_{ij}^+\} \right. \\ \left. + \sum_{j=1}^n b_{ijl}^+ (N_l H_j \exp\{\alpha \sigma_{ijl}^+\} + N_j H_l \exp\{\alpha \zeta_{ijl}^+\}) \right) < 1$$

and

$$\left(1 + \frac{c_i^+ \exp\{\alpha \sup_{s \in \mathbb{T}} \mu(s)\}}{c_i^- - \alpha} \right) \left(c_i^+ \tau_i^+ \exp\{\alpha \tau_i^+\} + \sum_{j=1}^n a_{ij}^+ L_j \exp\{\alpha \delta_{ij}^+\} \right. \\ \left. + \sum_{j=1}^n b_{ijl}^+ N_l H_j \exp\{\alpha \sigma_{ijl}^+\} + \sum_{j=1}^n b_{ijl}^+ N_j H_l \exp\{\alpha \zeta_{ijl}^+\} \right) < 1,$$

where $i = 1, 2, \dots, n$. Let

$$M = \max_{1 \leq i \leq n} \left\{ \frac{c_i^-}{c_i^+ \tau_i^+ + \sum_{j=1}^n \left(a_{ij}^+ L_j + \sum_{l=1}^n b_{ijl}^+ (N_j H_l + H_j N_l) \right)} \right\}.$$

It follows from (H_3) that $M > 1$. Thus, we can obtain that

$$\begin{aligned} \frac{1}{M} < \frac{\exp\{\alpha \sup_{s \in \mathbb{T}} \mu(s)\}}{c_i^- - \alpha} \left(c_i^+ \tau_i^+ \exp\{\alpha \tau_i^+\} + \sum_{j=1}^n a_{ij}^+ L_j \exp\{\alpha \delta_{ij}^+\} \right. \\ \left. + \sum_{j=1}^n b_{ijl}^+ (N_l H_j \exp\{\alpha \sigma_{ijl}^+\} + N_j H_l \exp\{\alpha \zeta_{ijl}^+\}) \right). \end{aligned}$$

Moreover, we have that $e_{\ominus\alpha}(t, t_0) > 1$, where $t \in [-\theta, t_0]_{\mathbb{T}}$. Hence, it is obvious that

$$\|u\|_{\mathbb{X}^*} \leq M e_{\ominus\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad \forall t \in [-\theta, t_0]_{\mathbb{T}}.$$

We claim that

$$\|u\|_{\mathbb{X}^*} \leq M e_{\ominus\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad \forall t \in (t_0, +\infty)_{\mathbb{T}}. \tag{3.5}$$

To prove this claim, we show that for any $p > 1$, the following inequality holds

$$\|u\|_{\mathbb{X}^*} < p M e_{\ominus\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad \forall t \in (t_0, +\infty)_{\mathbb{T}}, \tag{3.6}$$

which implies that, for $i = 1, 2, \dots, n$, we have

$$|u_i(t)| < p M e_{\ominus\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad \forall t \in (t_0, +\infty)_{\mathbb{T}} \tag{3.7}$$

and

$$|u_i^\Delta(t)| < p M e_{\ominus\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad \forall t \in (t_0, +\infty)_{\mathbb{T}}. \tag{3.8}$$

By way of contradiction, assume that (3.6) does not hold. Firstly, we consider the following two cases.

Case 1 (3.7) is not true and (3.8) is true. Then there exists $t_1 \in (t_0, +\infty)_{\mathbb{T}}$ and $i_0 \in \{1, 2, \dots, n\}$ such that

$$\begin{aligned} |u_{i_0}(t_1)| &\geq p M e_{\ominus\alpha}(t_1, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad |u_{i_0}(t)| < p M e_{\ominus\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad t \in (t_0, t_1)_{\mathbb{T}}, \\ |u_k(t)| &< p M e_{\ominus\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad \text{for } k \neq i_0, \quad t \in (t_0, t_1]_{\mathbb{T}}, \quad k = 1, 2, \dots, n. \end{aligned}$$

Therefore, there must be a constant $\alpha_1 \geq 1$ such that

$$\begin{aligned} |u_{i_0}(t_1)| &= \alpha_1 p M e_{\ominus\alpha}(t_1, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad |u_{i_0}(t)| < \alpha_1 p M e_{\ominus\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \\ &t \in (t_0, t_1)_{\mathbb{T}}, \\ |u_k(t)| &< \alpha_1 p M e_{\ominus\alpha}(t_1, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad \text{for } k \neq i_0, \quad t \in (t_0, t_1]_{\mathbb{T}}, \quad k = 1, 2, \dots, n. \end{aligned}$$

Note that, in view of (3.4), we have

$$\begin{aligned}
 |u_{i_0}(t_1)| &= \left| u_{i_0}(t_0)e_{-c_{i_0}}(t_1, t_0) + \int_{t_0}^{t_1} e_{-c_{i_0}}(t_1, \sigma(s)) \left\{ c_{i_0}^+ \int_{s-\tau_{i_0}(s)}^s u_{i_0}^\Delta(\vartheta) \Delta\vartheta \right. \right. \\
 &\quad + \sum_{j=1}^n a_{i_0j}(s)(f_j(y_j^\Delta(s - \delta_{i_0j}(s))) - f_j(x_j^\Delta(s - \delta_{i_0j}(s)))) \\
 &\quad + \sum_{j=1}^n \sum_{l=1}^n b_{i_0jl}(s)(g_j(y_j(s - \sigma_{i_0jl}(s)))g_l(y_l(s - \zeta_{i_0jl}(s))) \\
 &\quad \left. \left. - g_j(x_j(s - \sigma_{i_0jl}(s)))g_l(x_l(s - \zeta_{i_0jl}(s)))) \right\} \Delta s \right| \\
 &\leq e_{-c_{i_0}}(t_1, t_0)\|\varphi - \psi\|_{\mathbb{X}^*} + \alpha_1 p M e_{\ominus\alpha}(t_1, t_0)\|\varphi - \psi\|_{\mathbb{X}^*} \\
 &\quad \times \left| \int_{t_0}^{t_1} e_{-c_{i_0}}(t_1, \sigma(s))e_\alpha(t_1, \sigma(s)) \left\{ c_{i_0}^+ \int_{s-\tau_{i_0}(s)}^s e_\alpha(\sigma(s), \vartheta) \Delta\vartheta \right. \right. \\
 &\quad + \sum_{j=1}^n a_{i_0j}^+ L_j e_\alpha(\sigma(s), s - \delta_{i_0j}(s)) + \sum_{j=1}^n \sum_{l=1}^n b_{i_0jl}^+ (N_j H_l e_\alpha(\sigma(s), s - \zeta_{i_0j}(s)) \\
 &\quad \left. \left. + N_l H_j e_\alpha(\sigma(s), s - \sigma_{i_0j}(s))) \right\} \Delta s \right| \\
 &\leq e_{-c_{i_0}}(t_1, t_0)\|\varphi - \psi\|_{\mathbb{X}^*} + \alpha_1 p M e_{\ominus\alpha}(t_1, t_0)\|\varphi - \psi\|_{\mathbb{X}^*} \\
 &\quad \times \left| \int_{t_0}^{t_1} e_{-c_{i_0} \oplus \alpha}(t_1, \sigma(s)) \left\{ c_{i_0}^+ \tau_{i_0}^+ e_\alpha(\sigma(s), s - \tau_{i_0}(s)) \right. \right. \\
 &\quad + \sum_{j=1}^n a_{i_0j}^+ L_j e_\alpha(\sigma(s), s - \delta_{i_0j}(s)) + \sum_{j=1}^n \sum_{l=1}^n b_{i_0jl}^+ (N_j H_l e_\alpha(\sigma(s), s - \zeta_{i_0j}(s)) \\
 &\quad \left. \left. + N_l H_j e_\alpha(\sigma(s), s - \sigma_{i_0j}(s))) \right\} \Delta s \right| \\
 &\leq e_{-c_{i_0}}(t_1, t_0)\|\varphi - \psi\|_{\mathbb{X}^*} + \alpha_1 p M e_{\ominus\alpha}(t_1, t_0)\|\varphi - \psi\|_{\mathbb{X}^*} \left| \int_{t_0}^{t_1} e_{-c_{i_0} \oplus \alpha}(t_1, \sigma(s)) \right. \\
 &\quad \times \left\{ c_{i_0}^+ \tau_{i_0}^+ \exp \left\{ \alpha(\tau_{i_0}^+ + \sup_{s \in \mathbb{T}} \mu(s)) \right\} + \sum_{j=1}^n a_{i_0j}^+ L_j \exp \left\{ \alpha(\delta_{i_0j}^+ + \sup_{s \in \mathbb{T}} \mu(s)) \right\} \right. \\
 &\quad + \sum_{j=1}^n \sum_{l=1}^n b_{i_0jl}^+ (N_j H_l \exp \left\{ \alpha(\zeta_{i_0j}^+ + \sup_{s \in \mathbb{T}} \mu(s)) \right\} \\
 &\quad \left. \left. + N_l H_j \exp \left\{ \alpha(\sigma_{i_0j}^+ + \sup_{s \in \mathbb{T}} \mu(s)) \right\} \right\} \Delta s \right| \\
 &= \alpha_1 p M e_{\ominus\alpha}(t_1, t_0)\|\varphi - \psi\|_{\mathbb{X}^*} \left\{ \frac{1}{\alpha_1 p M} e_{-c_{i_0} \oplus \alpha}(t_1, t_0) + \exp \left\{ \alpha \sup_{s \in \mathbb{T}} \mu(s) \right\} \right. \\
 &\quad \times \left[c_{i_0}^+ \tau_{i_0}^+ \exp \left\{ \alpha \tau_{i_0}^+ \right\} + \sum_{j=1}^n a_{i_0j}^+ L_j \exp \left\{ \alpha \delta_{i_0j}^+ \right\} + \sum_{j=1}^n \sum_{l=1}^n b_{i_0jl}^+ (N_j H_l \exp \left\{ \alpha \zeta_{i_0j}^+ \right\} \right. \\
 &\quad \left. \left. + N_l H_j \exp \left\{ \alpha \sigma_{i_0j}^+ \right\} \right) \int_{t_0}^{t_1} e_{-c_{i_0} \oplus \alpha}(t_1, \sigma(s)) \Delta s \right] \Big\}
 \end{aligned}$$

$$\begin{aligned}
 &< \alpha_1 p M e_{\Theta\alpha}(t_1, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \left\{ \frac{1}{M} e_{-(c_{i_0} - \alpha)}(t_1, t_0) \right. \\
 &\quad + \exp \left\{ \alpha \sup_{s \in \mathbb{T}} \mu(s) \right\} \left[c_{i_0}^+ \tau_{i_0}^+ \exp \{ \alpha \tau_{i_0}^+ \} + \sum_{j=1}^n a_{i_0 j}^+ L_j \exp \{ \alpha \delta_{i_0 j}^+ \} \right. \\
 &\quad + \sum_{j=1}^n \sum_{l=1}^n b_{i_0 j l}^+ \left(N_j H_l \exp \{ \alpha \zeta_{i_0 j}^+ \} \right. \\
 &\quad \left. \left. + N_l H_j \exp \{ \alpha \sigma_{i_0 j}^+ \} \right) \frac{1}{-(c_{i_0} - \alpha)} \int_{t_0}^{t_1} (- (c_{i_0} - \alpha)) e_{-(c_{i_0} - \alpha)}(t_1, \sigma(s)) \Delta s \right] \Big\} \\
 &= \alpha_1 p M e_{\Theta\alpha}(t_1, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \left\{ \left[\frac{1}{M} - \frac{\exp \{ \alpha \sup_{s \in \mathbb{T}} \mu(s) \}}{c_{i_0}^- - \alpha} \left(c_{i_0}^+ \tau_{i_0}^+ \exp \{ \alpha \tau_{i_0}^+ \} \right. \right. \right. \\
 &\quad + \sum_{j=1}^n a_{i_0 j}^+ L_j \exp \{ \alpha \delta_{i_0 j}^+ \} + \sum_{j=1}^n \sum_{l=1}^n b_{i_0 j l}^+ \left(N_j H_l \exp \{ \alpha \zeta_{i_0 j}^+ \} \right. \\
 &\quad \left. \left. + N_l H_j \exp \{ \alpha \sigma_{i_0 j}^+ \} \right) \right] e_{-(c_{i_0} - \alpha)}(t_1, t_0) \right. \\
 &\quad + \frac{\exp \{ \alpha \sup_{s \in \mathbb{T}} \mu(s) \}}{c_{i_0} - \alpha} \left(c_{i_0}^+ \tau_{i_0}^+ \exp \{ \alpha \tau_{i_0}^+ \} + \sum_{j=1}^n a_{i_0 j}^+ L_j \exp \{ \alpha \delta_{i_0 j}^+ \} \right. \\
 &\quad \left. \left. + \sum_{j=1}^n \sum_{l=1}^n b_{i_0 j l}^+ \left(N_j H_l \exp \{ \alpha \zeta_{i_0 j}^+ \} + N_l H_j \exp \{ \alpha \sigma_{i_0 j}^+ \} \right) \right) \right] \Big\} \\
 &< \alpha_1 p M e_{\Theta\alpha}(t_1, t_0) \|\varphi - \psi\|_{\mathbb{X}^*},
 \end{aligned}$$

which is a contradiction.

Case 2 (3.8) is not true and (3.7) is true. Then there exists $t_2 \in (t_0, +\infty)_{\mathbb{T}}$ and $i_1 \in \{1, 2, \dots, n\}$ such that

$$\begin{aligned}
 |u_{i_1}^\Delta(t_2)| &\geq p M e_{\Theta\alpha}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad |u_{i_1}^\Delta(t)| < p M e_{\Theta\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad t \in (t_0, t_2)_{\mathbb{T}}, \\
 |u_k^\Delta(t)| &< p M e_{\Theta\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad \text{for } k \neq i_1, \quad t \in (t_0, t_2]_{\mathbb{T}}, \quad k = 1, 2, \dots, n.
 \end{aligned}$$

Hence, there must be a constant $\alpha_2 \geq 1$ such that

$$\begin{aligned}
 |u_{i_1}^\Delta(t_2)| &= \alpha_2 p M e_{\Theta\alpha}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad |u_{i_1}^\Delta(t)| < \alpha_2 p M e_{\Theta\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \\
 t &\in (t_0, t_2)_{\mathbb{T}}, \\
 |u_k^\Delta(t)| &< \alpha_2 p M e_{\Theta\alpha}(t, t_0) \|\varphi - \psi\|_{\mathbb{X}^*}, \quad \text{for } k \neq i_1, \quad t \in (t_0, t_2]_{\mathbb{T}}, \quad k = 1, 2, \dots, n.
 \end{aligned}$$

Note that, in view of (3.4), we have

$$\begin{aligned}
 |u_{i_1}^\Delta(t_2)| &= \left| -c_{i_1}(t_2) u_{i_1}(t_0) e_{-c_{i_1}}(t_2, t_0) + c_{i_1}(t_2) \int_{t_2 - \tau_{i_1}(t_2)}^{t_2} u_{i_1}^\Delta(s) \Delta s \right. \\
 &\quad \left. + \sum_{j=1}^n a_{i_1 j}(t_2) (f_j(y_j^\Delta(t_2 - \delta_{i_1 j}(t_2))) - f_j(x_j^\Delta(t_2 - \delta_{i_1 j}(t_2)))) \right)
 \end{aligned}$$

$$\begin{aligned}
 & + \sum_{j=1}^n \sum_{l=1}^n b_{i_1 j l}(t_2)(g_j(y_j(t_2 - \sigma_{i_1 j l}(t_2)))g_l(y_l(t_2 - \zeta_{i_1 j l}(t_2)))) \\
 & - g_j(x_j(t_2 - \sigma_{i_1 j l}(t_2)))g_l(x_l(t_2 - \zeta_{i_1 j l}(t_2))) \\
 & - c_{i_1}(t_2) \int_{t_0}^{t_2} e_{-c_{i_1}}(t_2, \sigma(s)) \left\{ c_{i_1}(s) \int_{s-\tau_{i_1}(s)}^s u_{i_1}^\Delta(\vartheta) \Delta\vartheta \right. \\
 & + \sum_{j=1}^n a_{i_1 j}(s)(f_j(y_j^\Delta(s - \delta_{i_1 j}(s))) - f_j(x_j^\Delta(s - \delta_{i_1 j}(s)))) \\
 & + \sum_{j=1}^n \sum_{l=1}^n b_{i_1 j l}(s)(g_j(y_j(s - \sigma_{i_1 j l}(s)))g_l(y_l(s - \zeta_{i_1 j l}(s)))) \\
 & \left. - g_j(x_j(s - \sigma_{i_1 j l}(s)))g_l(x_l(s - \zeta_{i_1 j l}(s))) \right\} \Delta s \Big| \\
 \leq & c_{i_1}^+ e_{-c_{i_1}}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \\
 & + \alpha_2 p M e_{\ominus\alpha}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \left(c_{i_1}^+ \int_{s-\tau_{i_1}(s)}^s e_\alpha(\sigma(s), \vartheta) \Delta\vartheta \right. \\
 & + \sum_{j=1}^n a_{i_1 j}^+ L_j e_\alpha(\sigma(t_2), t_2 - \delta_{i_1 j}(t_2)) \\
 & + \sum_{j=1}^n \sum_{l=1}^n b_{i_1 j l}^+ \left(N_j H_l e_\alpha(\sigma(t_2), t_2 - \zeta_{i_1 j}(t_2)) + N_l H_j e_\alpha(\sigma(t_2), t_2 - \sigma_{i_1 j}(t_2)) \right) \Big) \\
 & + c_{i_1}^+ \alpha_2 p M e_{\ominus\alpha}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \left\{ \int_{t_0}^{t_2} e_{-c_{i_1}}(t_2, \sigma(s)) e_\alpha(t_2, \sigma(s)) \right. \\
 & \times \left[c_{i_1}^+ \int_{s-\tau_{i_1}(s)}^s e_\alpha(\sigma(s), \theta) \Delta\theta + \sum_{j=1}^n a_{i_1 j}^+ L_j e_\alpha(\sigma(s), s - \delta_{i_1 j}(s)) \right. \\
 & \left. \left. + \sum_{j=1}^n \sum_{l=1}^n b_{i_1 j l}^+ \left(N_j H_l e_\alpha(\sigma(s), s - \zeta_{i_1 j}(s)) + N_l H_j e_\alpha(\sigma(s), s - \sigma_{i_1 j}(s)) \right) \right] \Delta s \right\} \\
 \leq & c_{i_1}^+ e_{-c_{i_1}}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \\
 & + \alpha_2 p M e_{\ominus\alpha}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \left(c_{i_1}^+ \tau_{i_1}^+ e_\alpha(t_2, t_2 - \tau_{i_1}(t_2)) \right. \\
 & + \sum_{j=1}^n a_{i_1 j}^+ L_j e_\alpha(\sigma(t_2), t_2 - \delta_{i_1 j}(t_2)) \\
 & + \sum_{j=1}^n \sum_{l=1}^n b_{i_1 j l}^+ \left(N_j H_l e_\alpha(\sigma(t_2), t_2 - \zeta_{i_1 j}(t_2)) + N_l H_j e_\alpha(\sigma(t_2), t_2 - \sigma_{i_1 j}(t_2)) \right) \Big) \\
 & + c_{i_1}^+ \alpha_2 p M e_{\ominus\alpha}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \left\{ \int_{t_0}^{t_2} e_{-c_{i_1} \oplus \alpha}(t_2, \sigma(s)) \right. \\
 & \times \left[c_{i_1}^+ \tau_{i_1}^+ e_\alpha(\sigma(s), s - \tau_{i_1}(s)) + \sum_{j=1}^n a_{i_1 j}^+ L_j e_\alpha(\sigma(s), s - \delta_{i_1 j}(s)) \right.
 \end{aligned}$$

$$\begin{aligned}
 & + \sum_{j=1}^n \sum_{l=1}^n b_{i_1 j l}^+ \left(N_j H_l e_\alpha(\sigma(s), s - \zeta_{i_1 j}(s)) + N_l H_j e_\alpha(\sigma(s), s - \sigma_{i_1 j}(s)) \right) \Big] \Delta s \Big\} \\
 & \leq c_{i_1}^+ e_{-c_{i_1}}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} + \alpha_2 p M e_{\ominus\alpha}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \left(c_{i_1}^+ \tau_{i_1}^+ \exp\{\alpha \tau_{i_1}^+\} \right. \\
 & + \sum_{j=1}^n a_{i_1 j}^+ L_j \exp\{\alpha \delta_{i_1 j}^+\} + \sum_{j=1}^n \sum_{l=1}^n b_{i_1 j l}^+ \left(N_j H_l \exp\{\alpha \zeta_{i_1 j}^+\} + N_l H_j \exp\{\alpha \sigma_{i_1 j}^+\} \right) \Big) \\
 & \times \left(1 + c_{i_1}^+ \exp\{\alpha \sup_{s \in \mathbb{T}} \mu(s)\} \int_{t_0}^{t_2} e_{-c_{i_1} \oplus \alpha}(t_2, \sigma(s)) \Delta s \right) \\
 & < \alpha_2 p M e_{\ominus\alpha}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \left\{ \frac{c_{i_1}^+}{M} e_{-c_{i_1} \oplus \alpha}(t_2, t_0) + \left(c_{i_1}^+ \tau_{i_1}^+ \exp\{\alpha \tau_{i_1}^+\} \right. \right. \\
 & + \sum_{j=1}^n a_{i_1 j}^+ L_j \exp\{\alpha \delta_{i_1 j}^+\} + \sum_{j=1}^n \sum_{l=1}^n b_{i_1 j l}^+ \left(N_j H_l \exp\{\alpha \zeta_{i_1 j}^+\} + N_l H_j \exp\{\alpha \sigma_{i_1 j}^+\} \right) \Big) \\
 & \times \left. \left(1 + c_{i_1}^+ \exp\{\alpha \sup_{s \in \mathbb{T}} \mu(s)\} \int_{t_0}^{t_2} e_{-c_{i_1} \oplus \alpha}(t_2, \sigma(s)) \Delta s \right) \right\} \\
 & \leq \alpha_2 p M e_{\ominus\alpha}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*} \left\{ \left[\frac{1}{M} - \frac{\exp\{\alpha \sup_{s \in \mathbb{T}} \mu(s)\}}{c_{i_0}^- - \alpha} \left(c_{i_0}^+ \tau_{i_0}^+ \exp\{\alpha \tau_{i_0}^+\} \right. \right. \right. \\
 & + \sum_{j=1}^n a_{i_0 j}^+ L_j \exp\{\alpha \delta_{i_0 j}^+\} + \sum_{j=1}^n \sum_{l=1}^n b_{i_0 j l}^+ \left(N_j H_l \exp\{\alpha \zeta_{i_0 j}^+\} \right. \\
 & + \left. \left. \left. N_l H_j \exp\{\alpha \sigma_{i_0 j}^+\} \right) \right) \right] c_{i_1}^+ e_{-(c_{i_0} - \alpha)}(t_2, t_0) \right. \\
 & + \left. \left(1 + \frac{c_{i_1}^+ \exp\{\alpha \sup_{s \in \mathbb{T}} \mu(s)\}}{c_{i_0}^- - \alpha} \right) \left(c_{i_0}^+ \tau_{i_0}^+ \exp\{\alpha \tau_{i_0}^+\} + \sum_{j=1}^n a_{i_0 j}^+ L_j \exp\{\alpha \delta_{i_0 j}^+\} \right. \right. \\
 & + \left. \left. \sum_{j=1}^n \sum_{l=1}^n b_{i_0 j l}^+ \left(N_j H_l \exp\{\alpha \zeta_{i_0 j}^+\} + N_l H_j \exp\{\alpha \sigma_{i_0 j}^+\} \right) \right) \right\} \\
 & < \alpha_2 p M e_{\ominus\alpha}(t_2, t_0) \|\varphi - \psi\|_{\mathbb{X}^*},
 \end{aligned}$$

which is also a contradiction. By above two cases, for other cases of negative proposition of (3.6), we can obtain a contradiction. Therefore, (3.6) holds. Let $p \rightarrow 1$, then (3.5) holds. We can take $\ominus\lambda = \ominus\alpha$, then $\lambda > 0$ and $\ominus\lambda \in \mathcal{R}^+$. Hence, we have

$$\|u\|_{\mathbb{X}^*} \leq M \|\varphi - \psi\|_{\mathbb{X}^*} e_{\ominus\lambda}(t, t_0), \quad t \in [-\theta, \infty)_{\mathbb{T}}, \quad t \geq t_0,$$

which means that, the pseudo almost periodic solution $x(t)$ of (1.1) is globally exponentially stable. This completes the proof of Theorem 3.2. □

Remark 3.1 According to (H_3) , we see that the existence and exponential stability of almost periodic solutions for system (1.1) not only depends on the delays in the leakage term, but also depends on the neutral terms in the network.

Remark 3.2 Since conditions (H_1) – (H_4) do not impose any further restrictions on time scale \mathbb{T} except that \mathbb{T} is an almost periodic time scale, our results show that under conditions (H_1) – (H_4) the continuous time network (1.2) and its corresponding discrete time network (1.3) have the same dynamical behaviors.

4 Numerical Example

In this section, we present an example to illustrate the feasibility of our results obtained in Sect. 3.

Example 4.1 Let $n = 3$. Consider the following neural networks system on almost periodic time scale \mathbb{T} :

$$\begin{aligned}
 x_i^\Delta(t) = & -c_i(t)x_i(t - \tau_i(t)) + \sum_{j=1}^3 a_{ij}(t)f_j(x_j^\Delta(t - \delta_{ij}(t))) \\
 & + \sum_{j=1}^3 \sum_{l=1}^3 b_{ijl}(t)g_j(x_j(t - \sigma_{ijl}(t)))g_l(x_l(t - \zeta_{ijl}(t))) + I_i(t), \quad t \in \mathbb{T}, i = 1, 2, 3
 \end{aligned}
 \tag{4.1}$$

where

$$\begin{aligned}
 f_1(u_1) = g_1(u_1) &= 0.25 \sin u_1, & f_2(u_2) = g_2(u_2) &= 0.2 \sin u_2, & f_3(u_3) = g_3(u_3) &= 0.15 \sin u_3, \\
 a_{11}(t) &= 0.1 + 0.05 \cos t, & a_{12}(t) &= 0.25 + 0.01 \cos \sqrt{2}t, & a_{13}(t) &= 0.15 + 0.01 \cos \sqrt{3}t, \\
 a_{21}(t) &= 0.03 + 0.02 \cos \frac{4}{3}t, & a_{22}(t) &= 0.05 + 0.02 \cos \frac{1}{4}t, & a_{23}(t) &= 0.06 + 0.01 \cos \frac{1}{4}t, \\
 a_{31}(t) &= 0.04 + 0.02 \cos \frac{4}{3}t, & a_{32}(t) &= 0.05 + 0.01 \cos \frac{1}{4}t, & a_{33}(t) &= 0.05 - 0.02 \cos \frac{1}{4}t, \\
 c_1(t) &= 0.04 + 0.01 \sin \frac{1}{5}t, & c_2(t) &= 0.23 + 0.02 \sin \frac{1}{3}t, & c_3(t) &= 0.25 + 0.03 \sin \frac{1}{3}t, \\
 I_1(t) &= 0.03 + 0.02 \sin \sqrt{3}t, & I_2(t) &= 0.04 + 0.01 \cos \frac{3}{4}t, & I_3(t) &= 0.03 + 0.01 \cos \frac{3}{4}t, \\
 b_{111}(t) &= b_{222}(t) = b_{333}(t) = b_{123}(t) &= 0.12 + 0.01 \sin \sqrt{2}t, \\
 b_{112}(t) &= b_{212}(t) = b_{312}(t) = b_{313}(t) &= 0.25 + 0.05 \cos \frac{4}{3}t, \\
 b_{113}(t) &= b_{213}(t) = b_{323}(t) = b_{331}(t) &= 0.15 + 0.02 \sin \sqrt{2}t, \\
 b_{121}(t) &= b_{122}(t) = b_{131}(t) = b_{132}(t) &= 0.14 + 0.02 \sin \sqrt{2}t, \\
 b_{133}(t) &= b_{211}(t) = b_{311}(t) = b_{221}(t) &= 0.35 + 0.05 \sin \frac{3}{4}t, \\
 b_{231}(t) &= b_{232}(t) = b_{322}(t) = b_{332}(t) &= 0.14 + 0.02 \sin \sqrt{2}t, \\
 b_{223}(t) &= b_{233}(t) = b_{321}(t) &= 0.35 + 0.05 \sin \frac{3}{4}t, \\
 \tau_1(t) &= 0.04 \sin \pi t, & \tau_2(t) &= 0.05 \cos \left(\pi t + \frac{\pi}{2} \right), & \tau_3(t) &= 0.06 \sin 2\pi t.
 \end{aligned}$$

By calculating, we have

$$L_1 = H_1 = N_1 = 0.25, \quad L_2 = H_2 = N_2 = 0.1, \quad L_3 = H_3 = N_3 = 0.15,$$

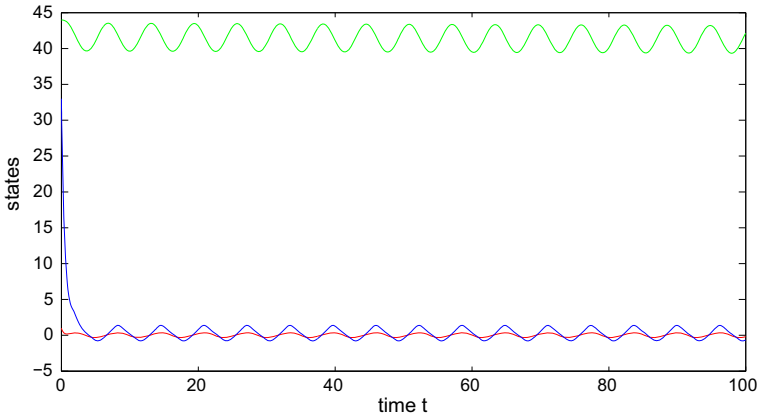


Fig. 1 Responds of continuous situation

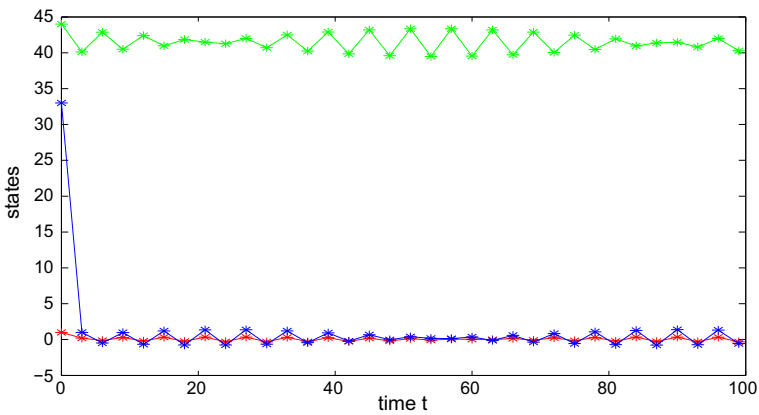


Fig. 2 Responds of discrete situation

$$\begin{aligned}
 &a_{11}^+ = 0.15, \quad a_{12}^+ = 0.26, \quad a_{13}^+ = 0.16, \quad a_{21}^+ = 0.05, \quad a_{22}^+ = 0.07, \quad a_{23}^+ = 0.07, \\
 &a_{31}^+ = 0.06, \quad a_{32}^+ = 0.06, \quad a_{33}^+ = 0.07, \quad I_1^+ = 0.05, \quad I_2^+ = 0.05, \quad I_3^+ = 0.04, \\
 &c_1^+ = 0.05, \quad c_1^- = 0.03, \quad c_2^+ = 0.25, \quad c_2^- = 0.21, \quad c_3^+ = 0.28, \quad c_3^- = 0.22, \\
 &b_{111}^+ = b_{222}^+ = b_{333}^+ = b_{123}^+ = 0.13, \quad b_{112}^+ = b_{212}^+ = b_{312}^+ = b_{313}^+ = 0.3, \\
 &b_{113}^+ = b_{213}^+ = b_{323}^+ = b_{331}^+ = 0.17, \quad b_{121}^+ = b_{122}^+ = b_{131}^+ = b_{132}^+ = 0.16, \\
 &b_{133}^+ = b_{211}^+ = b_{311}^+ = b_{221}^+ = 0.4, \quad b_{231}^+ = b_{232}^+ = b_{322}^+ = b_{332}^+ = 0.16, \\
 &b_{223}^+ = b_{233}^+ = b_{321}^+ = 0.4, \quad \tau_1^+ = 0.04, \quad \tau_2^+ = 0.05, \quad \tau_3^+ = 0.06.
 \end{aligned}$$

We can verify that all assumptions in Theorem 1 and Theorem 2 are satisfied. Therefore, we have that (4.1) has a pseudo almost periodic solution, which is globally exponentially stable.

Remark 4.1 Our results about system (4.1) can not be obtained from previously known results in literatures. Especially, for both the cases of $\mathbb{T} = \mathbb{R}$ and $\mathbb{T} = \mathbb{Z}$, (4.1) always has a pseudo almost periodic solution, which is globally exponentially stable (see Figures 1,2).

Acknowledgments This work is supported by the National Natural Sciences Foundation of People's Republic of China under Grant 11361072

References

1. Rakkiyappan R, Chandrasekar A, Lakshmanan S, Park JH (2015) Exponential stability for Markovian jumping stochastic BAM neural networks with mode-dependent probabilistic time-varying delays and impulse control. *Complexity* 20(3):39–65
2. Rakkiyappan R, Chandrasekar A, Lakshmanan S, Park JH (2014) Exponential stability of Markovian jumping stochastic Cohen-Grossberg neural networks with mode-dependent probabilistic time-varying delays and impulses. *Neurocomputing* 131:265–277
3. Dembo A, Farotimi O, Kaillath T (1991) High-order absolutely stable neural networks. *IEEE Trans Circuits Syst* 38:57–65
4. Liao XF, Yu JB (1998) Robust stability for interval Hopfield neural networks with time delays. *IEEE Trans Neural Netw* 9:1042–1046
5. Xu BJ, Liu XZ, Liao XX (2003) Global asymptotic stability of high-order Hopfield type neural networks with time delays. *Comput Math Appl* 45:1729–1737
6. Xu BJ, Liu XZ, Liao XX (2006) Global exponential stability of high order Hopfield type neural network. *Appl Math Comput* 174:98–116
7. Xiang H, Yan KM, Wang BY (2006) Existence and global exponential stability of periodic solution for delayed high-order Hopfield-type neural networks. *Phys Lett A* 352(4–5):341–349
8. Ou CX (2008) Anti-periodic solutions for high-order Hopfield neural networks. *Comput Math Appl* 56:1838–1844
9. Yu YH, Cai MS (2008) Existence and exponential stability of almost-periodic solutions for high-order Hopfield neural networks. *Math Comput Model* 47:943–951
10. Xiao B, Meng H (2009) Existence and exponential stability of positive almost periodic solutions for high-order Hopfield neural networks. *Appl Math Model* 33(1):532–542
11. Park JH, Park CH, Kwon OM, Lee SM (2008) A new stability criterion for bidirectional associative memory neural networks of neutral-type. *Appl Math Comput* 199:716–722
12. Rakkiyappan R, Balasubramaniam P (2008) New global exponential stability results for neutral type neural networks with distributed time delays. *Neurocomputing* 71:1039–1045
13. Rakkiyappan R, Balasubramaniam P (2008) LMI conditions for global asymptotic stability results for neutral-type neural networks with distributed time delays. *Appl Math Comput* 204:317–324
14. Liu J, Zong G (2009) New delay-dependent asymptotic stability conditions concerning BAM neural networks of neutral type. *Neurocomputing* 72:2549–2555
15. Samli R, Arik S (2009) New results for global stability of a class of neutral-type neural systems with time delays. *Appl Math Comput* 210:564–570
16. Samidurai R, Anthoni SM, Balachandran K (2010) Global exponential stability of neutral-type impulsive neural networks with discrete and distributed delays. *Nonlinear Anal* 4:103–112
17. Rakkiyappan R, Balasubramaniam P, Cao J (2010) Global exponential stability results for neutral-type impulsive neural networks. *Nonlinear Anal Real World Appl* 11:122–130
18. Li YK, Zhao L, Chen X (2012) Existence of periodic solutions for neutral type cellular neural networks with delays. *Appl Math Model* 36:1173–1183
19. Bai C (2008) Global stability of almost periodic solutions of Hopfield neural networks with neutral time-varying delays. *Appl Math Comput* 203:72–79
20. Xiao B (2009) Existence and uniqueness of almost periodic solutions for a class of Hopfield neural networks with neutral delays. *Appl Math Lett* 22:528–533
21. Wang K, Zhu Y (2010) Stability of almost periodic solution for a generalized neutral-type neural networks with delays. *Neurocomputing* 73:3300–3307
22. Li X, Cao J (2010) Delay-dependent stability of neural networks of neutral type with time delay in the leakage term. *Nonlinearity* 23:1709–1726
23. Balasubramanian P, Nagamani G, Rakkiyappan R (2011) Passivity analysis for neural networks of neutral type with Markovian jumping parameters and time delay in the leakage term. *Commun Nonlinear Sci Numer Simulat* 16:4422–4437
24. Balasubramanian P, Kalpana M, Rakkiyappan R (2011) Global asymptotic stability of BAM fuzzy cellular neural networks with time delay in the leakage term, discrete and unbounded distributed delays. *Math Comput Model* 53(5–6):839–853

25. Duan L, Huang LH (2013) Global exponential stability of fuzzy BAM neural networks with distributed delays and time-varying delays in the leakage terms. *Neural Comput Appl* 23(1):171–178
26. Liu BW (2013) Global exponential stability for BAM neural networks with time-varying delays in the leakage terms. *Nonlinear Anal Real World Appl* 14(1):559–566
27. Rakkiyappan R, Chandrasekar A, Lakshmanan S, Park Ju H, Jung HY (2013) Effects of leakage time-varying delays in Markovian jump neural networks with impulse control. *Neurocomputing* 121:365–378
28. Li X, Rakkiyappan R, Balasubramanian P (2011) Existence and global stability analysis of equilibrium of fuzzy cellular neural networks with time delay in the leakage term under impulsive perturbations. *J Frankl Inst* 348:135–155
29. Peng SG (2010) Global attractive periodic solutions of BAM neural networks with continuously distributed delays in the leakage terms. *Nonlinear Anal Real World Appl* 11(3):2141–2151
30. Zhang H, Shao JY (2013) Almost periodic solutions for cellular neural networks with time-varying delays in leakage terms. *Appl Math Comput* 219(24):11471–11482
31. Li YK, Li YQ (2013) Existence and exponential stability of almost periodic solution for neutral delay BAM neural networks with time-varying delays in leakage terms. *J Frankl Inst* 350(9):2808–2825
32. Hilger S (1990) Analysis on measure chains—a unified approach to continuous and discrete calculus. *Results Math* 18:18–56
33. Li YK, Chen X, Zhao L (2009) Stability and existence of periodic solutions to delayed Cohen–Grossberg BAM neural networks with impulses on time scales. *Neurocomputing* 72:1621–1630
34. Gao J, Wang QR, Zhang LW (2014) Existence and stability of almost-periodic solutions for cellular neural networks with time-varying delays in leakage terms on time scales. *Appl Math Comput* 237:639–649
35. Li YK, Wang C (2012) Pseudo almost periodic functions and pseudo almost periodic solutions to dynamic equations on time scales. *Adv Differ Equ* 1:1–24
36. Bohner M, Peterson A (2001) *Dynamic equations on time scales, an introduction with applications*. Birkhäuser, Boston
37. Li YK, Wang C (2011) Uniformly almost periodic functions and almost periodic solutions to dynamic equations on time scales, *Abstr Appl Anal* 2011, Article ID 341520, 22 pp