



Classification of skin cancer from dermoscopic images using deep neural network architectures

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Abstract

A powerful medical decision support system for classifying skin lesions from dermoscopic images is an important tool to prognosis of skin cancer. In the recent years, Deep Convolutional Neural Network (DCNN) have made a significant advancement in detecting skin cancer types from dermoscopic images, in spite of its fine grained variability in its appearance. The main objective of this research work is to develop a DCNN based model to automatically classify skin cancer types into melanoma and non-melanoma with high accuracy. The datasets used in this work were obtained from the popular challenges ISIC-2019 and ISIC-2020, which have different image resolutions and class imbalance problems. To address these two problems and to achieve high performance in classification we have used EfficientNet architecture based on transfer learning techniques, which learns more complex and fine grained patterns from lesion images by automatically scaling depth, width and resolution of the network. We have augmented our dataset to overcome the class imbalance problem and also used metadata information to improve the classification results. Further to improve the efficiency of the EfficientNet we have used ranger optimizer which considerably reduces the hyper parameter tuning, which is required to achieve state-of-the-art results. We have conducted several experiments using different transferring models and our results proved that EfficientNet variants outperformed in the skin lesion classification tasks when compared with other architectures. The performance of the proposed system was evaluated using Area under the ROC curve (AUC - ROC) and obtained the score of 0.9681 by optimal fine tuning of EfficientNet-B6 with ranger optimizer.

Keywords EfficientNet · Deep convolutional neural network (DCNN) · Melanoma classification · Dermoscopic images

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1 Introduction

The most common and dangerous type of cancer in humans is skin cancer. Skin cancer can be broadly classified as melanoma and non-melanoma, where non-melanoma includes basal cell carcinoma and squamous cell carcinoma. Malignant melanoma is considered to be one of the most deadly forms of skin cancer and is exponentially increasing throughout the world. To reduce the mortality rate of skin cancer early diagnosis is very much crucial, since it bestows an elevated cure rate when detected and treated at an early stage.

Skin cancer is normally screened by clinicians through visual examination which is time consuming, error prone and is more subjective. Dermoscopy is a noninvasive imaging technique that eliminates the surface reflection of the skin which is able to capture illuminated and magnified images of skin lesions to increase the clarity of the spots. However, the detection of melanoma from dermoscopic images by the dermatologist achieved less than 80% accuracy in routine clinical settings [40]. To improve the efficiency and efficacy of skin cancer detection an automated diagnosis system is necessary to assist clinicians in order to enhance the decision making. For developing automated diagnostic tools, traditional Machine Learning (ML) algorithms are used to classify melanoma and non-melanoma. But it is very hard to achieve high diagnostic performance since ML algorithms require hand crafted features and also dermoscopic images have high intra-class and low inter-class variations [43].

Unbiased diagnosis is very important for any early detection and treatment of skin cancer diseases. During the recent years many researchers are focusing on Convolutional Neural Networks (CNNs) based methods since it provides significant improvement in prediction accuracy [15]. Many researchers are focusing on skin cancer classification using Deep Learning (DL) based methods because of its automatic feature engineering and self-learning capabilities. With deep neural networks high performance can be obtained at the cost of expanding the CNN wider, deeper and increasing resolution which leads the architecture to have additional parameters resulting in high computing power for training and testing. One of the most dynamic CNN architecture is EfficientNet which can be used to achieve high accuracy by exploiting compound scaling method. By compound scaling method the architecture can be enlarged by expanding depth, width, and resolution to obtain better accuracy with fewer computational resources than other models [38]. In general, classification of skin cancer is challenging, because of the presence of artifacts, image resolution disparity and less discriminating features between different types of cancer. Thus to alleviate these problems, EfficientNet architecture can be considered as an appropriate model, due to its compound scaling property, for skin cancer classification to strengthen the accuracy.

In this research work, we have proposed an automatic classification system for skin cancer using different deep neural networks based on transfer learning techniques. We have done extensive studies to identify the best classifier suitable for dermoscopic image classification using different deep neural networks such as Google Exception, DenseNet and different variants of EfficientNet models. ISIC-2019 and 2020 image datasets along with metadata information were used to train the DNN models and achieved best accuracy using EfficientNet. The main contribution of this work are as follows:

- A systematic method was investigated to classify skin cancer as melanoma and non-melanoma using various DCNN architectures.
- The issues pertaining to skin classification such as, different image resolutions and class imbalance problems observed in the dataset were addressed.

- EfficientNet architecture based on transfer learning was proposed which determines the hyper-parameters automatically resulting in improved accuracy.
- An ensemble architecture was also proposed to improve classification accuracy by combining both metadata and image features.
- The effectiveness of the proposed method was boosted using ranger optimizer which reduced the problem of hyper-tuning.

The rest of this paper is organized as follows, in Section 2 papers related to this research work are discussed, Section 3 describes the methodology, dataset and various DCNN architectures analysed in this study. Experimental results and analysis are outlined in Section 4 and finally conclusion and future work are presented in Section 5.

2 Related works

The extension of ML algorithms during recent years empowered researchers to develop many applications in the field of medical image analysis. Moldovanu et al. [30] segmented input images using threshold method and extracted a set of Gabor features and trained using a multilevel neural network. A framework for melanoma skin cancer detection using SVM model was proposed in [6] and trained with the help of optimized HOG features extracted from dermoscopic images. Dermoscopic score calculation with the help of ABCD (Asymmetry, Border, Color, and Diameter) features of the images used to separate benign lesions from melanoma was introduced by Kasmi et al. [20].

SVM classifier was used in [11] to train the model using combined global features and local patterns. Global features such as color and lesion shape were extracted using traditional image processing techniques whereas local patterns were extracted using DNN. Moura et al. [31] proposed a binary skin classification method using multiLayer perceptron by training the model using hybrid descriptors which combines the ABCD rule and the features from various pre-trained Convolutional Neural Networks (CNNs). A method for skin cancer localization and recognition using multilayered feed forward neural network was proposed in [22] after extracting the features using DenseNet201 and selecting most discriminating features by iteration-controlled Newton-Raphson (IcNR) method. Feature fusion approach using mutual information metric was proposed in [4], by extracting handcrafted features from ABCD rule and deep learning features from transfer learning.

Naem et al. [33] presented a deep learning techniques for melanoma diagnosis using CNN and provide a systematic review for the challenges on the basis of similarities and differences. They also discussed about the recent research trends, challenges and opportunities in the field of melanoma diagnosis and investigated the existing solutions. An end to end and pixel-wise learning using DCNN was proposed in [1]. The issues of multi-size, multi-scale, multi-resolution and low contrast images were handled by employing local binary convolution on U-net architecture was presented in [35]. A two stage segmentation method followed by classification was proposed in [19] which uses region-based Convolution Neural Network technique to crop the ROI and binary classification was done using ResNet152 architecture. A pre-trained model using transfer learning technique leveraged with AlexNet was presented in [2]. The training of deep learning models with best set-up of hyperparameters outperform the ensemble model of classification for different pre-trained models of ImageNet namely Xception, InceptionV3, InceptionResNetV2, NASNetLarge, ResNet101

were discussed in [7]. An optimized pipeline for seven different skin classes was proposed in [24] which learns pixel-wise features for segmentation with modified U-Net and classified using the features extracted from the DenseNet encoder. A methodology to improve the classification accuracy by combining the architectures based on the weighted output of the CNNs was studied in [13]. Fusing the classification output of the trained SVM after training the SVM with deep features from various pre-trained CNNs was proposed in [28]. The accuracy of the lower performing models has been improved by adding the metadata information along with the image features was proposed by Gessert et al. [12]. In general the accuracy of any DL model depends directly on hyper parameter tuning which is done manually by trial and error methods. Hence identifying appropriate parameters is crucial for any model to achieve high accuracy. So in this work we have proposed a method to automatically fine tune the models based on the hyper parameters obtained through compound scaling method introduced in EfficientNet model by Mingxing and Quoc [38].

EfficientNet model uses compounding-scaling method that expands in three dimensions such as scale, width and height of deep network with the help of large number of hyperparameters to obtain better accuracy. A deep learning model for the classification of remote sensing scenes using EfficientNet combined with an attention mechanism was proposed in [3]. The network learns to emphasize important regions of the scene and suppress the irrelevant regions. Deep learning networks such as EfficientNet and MixNet have been used for automated recognition of fruits in [10]. A transfer learning based approach using a pre-trained EfficientNet model was constructed to perform accurate classification of cucumber diseases with improved optimizer namely ranger which helps to obtain high accuracy was proposed in [45]. A bidirectional long short-term memory module which integrates the attention mechanism helps in accurate recognition of cow's motion behaviour [42]. The EfficientNet architecture was proposed in [29] to achieve binary and multiclass classification for Covid-19 diseases. A deep neural network based on Efficient-B5 using ISIC 2020 Challenge Dataset was discussed in [18]. EfficientNet deep learning architecture was used in [5] based on the transfer learning approach for plant leaf disease classification. Tuberculosis detection from X-ray chest images was proposed in [32] and was done based on transfer learning using pre-trained ResNet and EfficientNet models after enhancing the images using Unsharp Masking (UM) and High-Frequency Emphasis Filtering (HEF). An ensemble model for multi-label classification was proposed in [41] to detect the retinal fundus diseases by extracting features using Efficient net and the classification was achieved using neural network. Mahbod [27] proposed an algorithm that ensembles deep features from multiple pre-trained and fine-tuned DNNs and fused the obtained prediction values of different models. In the recent research it is evident that the EfficientNet models have been used in classification to improve the accuracy but it is noticed that very few researchers applied EfficientNet for skin lesion classification. Thus, we have proposed a new model for classifying skin cancer from dermoscopic images using EfficientNet model with ranger optimizer to achieve high accuracy.

3 Materials and methods

The motivation for carrying out this research is to investigate the performance of transfer learning techniques using different Deep Learning (DL) architectures for skin lesion classification from dermoscopic images.

3.1 Transfer learning

During the past decade the research community has made remarkable progress in the field of medical image analysis by utilizing DL architectures. The DL models achieve incredible accuracy as they try to learn the features automatically from the data in an incremental manner. The Convolutional Neural Networks (CNN) achieves high accuracy in the field of image classification. But training a CNN from scratch is not so easy since the accuracy of the classifier depends on the hyper-parameter tuning such as initial weights, number of epochs, learning rate, dropout, optimizers and also it requires high computational power and an extensive amount of labelled training data set. These problems can be leveraged using a transfer learning techniques. In transfer learning, the training time is reduced by the weights obtained from the pre-trained model which can be utilized as the initial weights to train the new similar problems. This method of reusing the pre-trained weights results in low generalization error. This is true in the case of general images since all transfer learning models have been built based on the general images where as this may not be true for specific images such as medical images.

To overcome these problems, researchers keep increasing the depth of the layers which results in vanishing gradient problem or increasing the layers breadth wise suffers from global optimization problem. So in this paper, we propose to explore an automatic method to classify two different types of skin cancer namely melanoma and non-melanoma from dermoscopic images using different transfer learning models. To investigate an efficient method for classification of skin cancer, using ISIC dataset we have used the state-of-the-art DCNN models such as DenseNet121, ResNet50, InceptionResNetV2 and variants of EfficientNet. We have analysed the results of all transfer learning models for classification in terms of both fine tuning and feature extraction and found EfficientNet performs better since it uses compound scaling method that expands the layers in all directions.

3.2 Dataset

In this work, we have used ISIC 2019 [8, 9, 39] and ISIC 2020 [34] dataset. ISIC 2020 dataset contains 33,126 dermoscopic images collected from multiple sites for training and the images are provided in both DICOM and JPEG format along with the metadata. The metadata contains patient_id, sex, age, and general anatomic site with its target value. The training set contains two classes of images, melanoma and non-melanoma with their ground truth while the test set contains 10,982 images with the contextual information. ISIC 2019 dataset contains 25,331 dermoscopic images provided in a JPEG format. ISIC 2019 dataset includes BCN_20000 dataset [9], HAM10000 [8] dataset and MSK Dataset [39]. The test set for ISIC 2019 dataset includes 8,238 images with embedded contextual data.

3.3 DenseNet model

The Densenet architecture is popular because the DenseNet model attenuates the vanishing-gradient problem, improves feature propagation, motivates feature reuse and reduces the number of parameters. In a dense convolutional neural network each layer is connected to every other layer as a feed forward pattern. Each layer in DenseNet accepts the feature maps of all preceding layers as additional input and passes on its own feature maps to all subsequent layers. Thus the n^{th} layer has n inputs of all preceding layers.

Generally, CNN tries to change the size of the feature map by down sampling layers. But DenseNet facilitates both down-sampling and feature concatenation by dividing the

network into multiple densely connected dense blocks. The feature map size inside the blocks remains the same. Outside the dense blocks convolution and pooling operations are performed to down sample and inside the dense block the size of the feature maps are same which helps to carry out concatenation.

We have used DenseNet121 which comprises 4 dense blocks with (6,12,24,16) layers in each. Each dense layer consists of 2 convolutional layers 1×1 and 3×3 . 1×1 layer is used to extract the features and the other layer used to bring down the feature depth. At the end of each dense layer a transition layer or block is added. The transition layer consists of a batch-norm layer, a 1×1 convolution followed by a 2×2 average pooling layer. The transition layer is used for changing the size of the feature maps. The last dense block is followed by a classifier at the end. Thus the DenseNet consists of 117 conv, 3 transition and 1-classification making the size of layers as 121.

3.4 ResNet50

ResNet50 supports residual learning which consists of a 50 layer residual network [16]. The ResNet architecture introduced skip connections, also called residual connections, which enables to train very deep networks and can boost the performance of the model by overcoming the vanishing gradient problem. The ResNet architecture is mainly composed of residual networks in which intermediate layers of a block learn a residual function with reference to the block input. The architecture of ResNet50 has 4 stages. The network takes the input in the multiples of 32 with 3 as channel width. Every ResNet architecture performs the initial convolution and max-pooling using 7×7 and 3×3 kernel sizes. Each stage has 3 residual blocks containing 3 layers, at each stage the size of the input is reduced to half in terms of height and width but the channel width will be doubled. There are three layers 1×1 , 3×3 , 1×1 convolutions in each residual block. The 1×1 convolution layers are responsible for reducing and then restoring the dimensions. The 3×3 layer is left as a bottleneck with smaller input/output dimensions. Finally, the network has an average pooling layer followed by a fully connected layer.

3.5 InceptionResNet V2

InceptionResNet V2 [37] is a variant of Inception V3 model which takes some ideas from ResNet architectures [14, 17]. So the architecture is just the combination of the Inception V3 model and ResNet model. Residual blocks are added in the inception model to replace the filter concatenation stage. This makes this model produce all the benefits of the residual approach while maintaining the same computational efficiency. The architecture contains 164 layers with input image size of 299×299 . In this model every Inception block is followed by a filter expansion layer (1×1 convolution without activation) which is used for scaling up the dimension of the filter bank before the addition to match the depth of the input. In the case of InceptionResNet, batch normalization is used only on top of the traditional layers, but not on top of the summations. The InceptionResNet V2 architecture is more accurate than previous state of the art models.

3.6 EfficientNet model

EfficientNet has been proposed to improve accuracy and efficiency of CNN by applying a uniform scaling method to all dimensions i.e., depth, width and resolution of the network yet scaling down the model. In general, convNets scales down or up by adjusting either

- Determine the best values for α, β, γ by fixing $\psi = 1$ using grid search with the assumption that there are twice as many resources available.
- Using the determined α, β, γ values as constant, scale up the baseline network to create EfficientNet-B1 to B7 with different ψ values.

We have analysed and compared the classification results obtained using different transfer learning techniques. From the results obtained it is apparent that EfficientNet produced better results when compared to other methods.

3.7 System architecture and methodology

We perform different experiments using different deep learning techniques and analyze the performance. Besides using different architectures we have done extensive experiments using variants of EfficientNet. There are two major transfer learning technique such as fine tuning and feature extraction. We have analysed both the methods of transfer learning techniques with different deep learning architecture with various optimizers and found that EfficientNet-B6 along with ranger optimizer produced better results. The proposed architecture using feature extraction is depicted in Fig. 2 and fine tuning the EfficientNet is shown in Fig. 3.

4 Experimental results and analysis

This research work utilizes dermoscopic skin images and classifies them into two different skin cancers namely melanoma and non-melanoma based on the transfer learning techniques. We have used different networks such as DesneNet121, ResNet50, InceptionResnet V2 and variants of EfficientNet and analyzed their performance using classification accuracy in terms of Area Under the Receiver operating characteristic curve (AUC-ROC) using ISIC-2019 and 2020 dataset.

The Receiver Operator Characteristic (ROC) is a probability curve that plots the True Positive Rate (TPR) against False Positive Rate (FPR) for various threshold values. The Area Under the Curve (AUC) measures the entire two-dimensional area underneath the entire ROC curve. AUC is used to project an aggregate measure of performance over all possible classification thresholds.

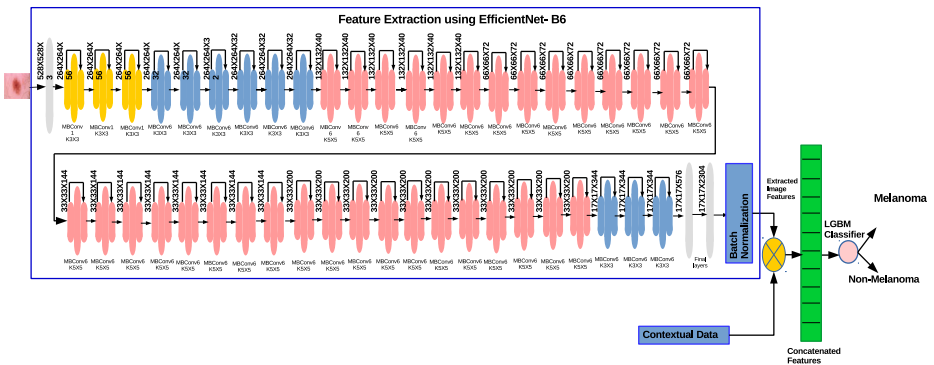


Fig. 2 Proposed feature extraction model using EfficientNet-B6

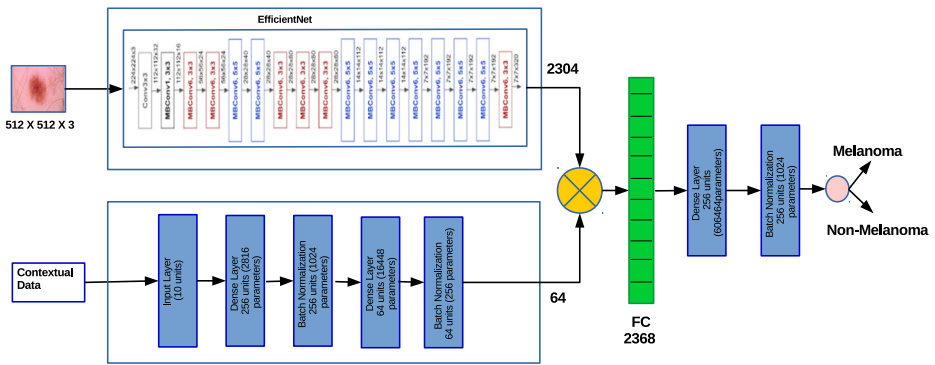


Fig. 3 Proposed fine tuning method using EfficientNet-B6

4.1 Experimental setup

The main objective of this study is to build an automatic system to categorise two types of cancer from dermoscopic images. We have used transfer learning techniques with different neural networks as a backbone and ascertain the performance of the classification models using different experiments as follows:

- The same CNN architectures are used as feature extractor with Light Gradient Boosting Machine (LGBM) Classifier.
- Fine Tuning the CNN architectures such as DenseNet121, ResNet50, InceptionResNet V2 and EfficientNet for training.
 - Analysed the efficacy of fine tuning method using optimizers, Adam and Ranger.

Feature extraction using CNN architectures To perform feature extraction on each dermoscopic image different CNN models were trained using pre-trained weights and feature representation vectors were obtained. Normally the deep learning architecture tries to extract generic features in initial layers while the later layers capture task specific features. So in this work we have extracted the features from the later layers. The extracted feature maps obtained from CNN are in high-dimensional space so we have down-sampled the feature maps by adding a global average pooling layer. Followed by a pooling layer, a drop out layer with 20% have been added to exclude the neurons during training which ensures the effectiveness of the data and prevents over-fitting. The extracted features from the images and contextual features are combined and trained using Light Gradient Boosting Machine (LGBM) classifier [21]. The LGBM classifier is a gradient boosting framework which works based on a decision tree algorithm. LGBM can handle the large size of data, takes lower memory to run and is called ‘Light’ because of its high speed. This algorithm results in better accuracy than any other boosting algorithms since this algorithm splits the tree leaf wise with best fit. The architecture of the proposed feature extraction model is presented in Fig. 2.

To train our models we have used 33,126 dermoscopic images with a learning rate of 0.001. The LGBM classifier is trained with the maximum tree depth of 6 and the number of leaves as 64. Also we have used stratified K-fold cross validation since the folds are selected in such a way that the mean response value is approximately equal in all the folds. This ensures that each fold contains approximately the same amount of the two types of class

Table 1 Feature Extraction Technique for different architecture using ISIC 2020 Dataset

Model Name	Image Size	No. of features*	Training AUC	Validation AUC	Testing AUC
Dense Net121	256X256X3	1024+3	0.9578	0.8512	0.8629
Res Net50	224X224X3	2048+3	0.9577	0.8279	0.8381
Inception ResNet V2	299X299X3	1536+3	0.9633	0.8359	0.8825
Efficient Net-B6	512X512X3	2304+3	0.9462	0.9100	0.9174

* Image features + contextual features

labels. Finally, the trained model is tested using 25331 images from the dataset. The results of the ISIC-2020 dataset is presented in Table 1.

From Table 1 it is evident that EfficientNet B6 produced 91% of AUC because the number of features extracted using EfficientNet is more when compared to other models. Hence EfficientNet have learnt more number of global discriminating features which helps to classify the images more precisely.

Fine tuning the CNN architectures Fine tuning is the method which unfreezes few of the top layers of the trained model and adds new classifier layers. The base model is then retrained along with the newly added layers which allows to fine tune the global features that is relevant to the specific task. To achieve better accuracy we have used both contextual and image information provided in the dataset. So we have developed two different architectures one for contextual data and other one for image data and concatenated the layers of the architectures. To train the contextual information we have used a simple neural architecture which consists of a dense layer followed by batch normalization and ReLu activation function. Next to train the image information a neural network architecture such as EfficientNet B0 to B7, DenseNet, InceptionResNet V2 and ResNet50 were used by unfreezing the top layers. The last layers of both the models were concatenated and fed into the dense layers with 384 neurons with ReLu activation function. Next a batch normalization layer is added to normalize the values and we have used a dropout of 20% which was chosen randomly to avoid over fitting. Finally a dense layer with softmax activation function consisting of a single neuron for binary classification is added at the top of the model. The architecture diagram of the proposed fine tuning method is presented in Fig. 3.

To analyse the efficacy of the proposed method we have implemented different architectures with Adam optimizer for ISIC 2020 dataset. The results of different architecture using Adam optimizer for ISIC-2020 dataset is depicted in Table 2. From the results it is evident that EfficientNet produced good accuracy when compared to other models. The EfficientNet architecture produced a promising results because the network architecture automatically scales the depth, width and resolution of the network and hence we have obtained a better

Table 2 Fine Tuning method for different architecture with Adam optimizer using ISIC 2020

Model Name	Image Size	Training AUC	Validation AUC	Testing AUC
Dense Net121	256X256X3	0.6472	0.7637	0.7414
ResNet50	224X224X3	0.66875	0.7627	0.7499
Inception ResNet V2	299X299X3	0.67913	0.7423	0.7423
EfficientNet-B6	512X512X3	0.7052	0.7369	0.7765

Table 3 Results of fine tuning the EfficientNet models using ISIC-2020 dataset

Model Name	AUC for Image Size 256X256	AUC for Image Size 384X384	AUC for Image Size 512X512
EfficientNet-B0	0.6622	0.7306	0.7732
EfficientNet-B1	0.6507	0.7265	0.7055
EfficientNet-B2	0.6873	0.6615	0.7064
EfficientNet-B3	0.6234	0.677	0.7663
EfficientNet-B4	0.6608	0.7655	0.7003
EfficientNet-B5	0.732	0.7266	0.73
EfficientNet-B6	0.7122	0.7208	0.7765
EfficientNet-B7	0.6615	0.7178	0.7642

AUC for this model. The neural network architectures presented in the table are trained with learning rate as 0.01, optimizer as Adam and trained the model for 100 epochs.

From the previous studies it is apparent that EfficientNet models produces high accuracy with few parameters and less training time. To study the performance of the proposed methodology, we have also conducted a few experiments with different size of input images such as 256×256 , 384×384 , 512×512 . The obtained results for EfficientNet with different images size for ISIC-2020 and combined data set of ISIC-2019 & 2020 datasets are presented in the Tables 3 and 4 respectively. From the table it is shown that EfficientNet produced good results when compared with other models and also the increase in images size gradually increases the accuracy. We have obtained 0.7765 and 0.9486 as AUC for ISIC-2020 and ISIC-2019 & 2020 datasets respectively, using EfficientNet-B6 with learning rate as 0.00001, optimizer as Adam and for 100 epochs.

Table 4 shows the AUC values of EfficientNet trained using the combined datasets. It shows that the EfficientNet-B6 and B7 achieved good results, but there are no much difference in the results though EfficientNet-B7 takes more training time than EfficientNet-B6. Hence we conclude that EfficientNet-B6 is the most suitable classifier for classifying melanoma and non-melanoma.

We have also estimated and analysed the execution time for the proposed methods using Tensorflow processing Unit (TPUs) for 100 epochs and results are presented in

Table 4 Fine Tuning results for EfficientNetB0 - B7 with different image size using ISIC-2019 & ISIC-2020 dataset

Model Name	AUC for Image Size 256X256	AUC for Image Size 384X384	AUC for Image Size 512X512
EfficientNet B0	0.9221	0.9313	0.9199
EfficientNet B1	0.9254	0.9368	0.9202
EfficientNet B2	0.9276	0.9313	0.9283
EfficientNet B3	0.9296	0.9355	0.9386
EfficientNet B4	0.9342	0.9324	0.9368
EfficientNet B5	0.9302	0.9374	0.9382
EfficientNet B6	0.9445	0.9483	0.9486
EfficientNet B7	0.9336	0.9375	0.9465

Table 5 Execution Time for EfficientNetB0 - B7 with different image size using ISIC-2019

Model Name	Execution Time for 256X256	Execution Time for 384X384	Execution Time for 512X512
EfficientNet-B0	2392.2	4456.9s	7276.6s
EfficientNet-B1	2618.5	5762.3s	7710.3s
EfficientNet-B2	2825.6	6256.4s	8274.3s
EfficientNet-B3	3137.8s	6713.6s	9101.0s
EfficientNet-B4	3702.0s	7136.4s	10761.8s
EfficientNet-B5	4646.7s	7955.2s	12954.4s
EfficientNet-B6	5056.1s	8655.2s	13213.5
EfficientNet-B7	6972.0s	9621.6s	14895.2

Table 6 Execution Time for EfficientNetB0 - B7 with different image size using ISIC-2020 & ISIC-2020 dataset

Model Name	Execution Time for 256X256	Execution Time for 384X384	Execution Time for 512X512
EfficientNet-B0	4192.1s	7463.6s	11385.1s
EfficientNet-B1	4348.5s	9352.2s	17045.1s
EfficientNet-B2	4523.0s	9623.4s	17389.7s
EfficientNet-B3	5012.3s	10856.6s	19991.5s
EfficientNet-B4	5864.6s	12148.5s	22040.1s
EfficientNet-B5	6772.0s	14096.2s	26146.2s
EfficientNet-B6	8034.7s	17644.1s	30256.5s
EfficientNet-B7	9795.2s	21946.7s	35178.4s

Table 7 Results of Fine Tuning EfficientNet-B6 architecture with various optimizers

Model Name	Image Size	Training AUC	Validation AUC	Testing AUC
EfficientNet-B6+SGD	384X384X3	0.8289	0.8865	0.8775
EfficientNet-B6+RMSprop	384X384X3	0.6112	0.5451	0.5370
EfficientNet-B6+Adam	384X384X3	0.9445	0.9483	0.9486
EfficientNet-B6+RAdam	384X384X3	0.8805	0.9202	0.9475
EfficientNet-B6+Ranger	384X384X3	0.90984	0.9475	0.9681

Table 8 Obtained AUC by Fine Tuning different architectures using ranger optimizer

Model Name	Image Size	Training AUC	Validation AUC	Testing AUC
DenseNet121	256X256X3	0.6470	0.7788	0.7449
ResNet50	224X224X3	0.63687	0.7656	0.7334
Inception ResNet V2	299X299X3	0.65785	0.6611	0.7502

Tables 5 and 6. From these tables it is obvious that increase in image size and complexity of the architecture increases the execution time. We believe that the setback of this work is that, the execution time is very high and this is because of the complexity of the EfficientNet architecture.

Choosing an appropriate optimizer and effectively tuning its hyper parameter controls the training speed and efficiency of the learned model. To choose a suitable optimizer for training the EfficientNet we have run some experiments by training EfficientNet-B6 with different optimizers and the results are discussed in Table 7. The results of Adam [23] and Rectified Adam (RAdam) [26] optimizers are somewhat close, but using RAdam optimizer leads to more stable training and converges quickly with good generalization. Also Adam produced lower loss than Rectified Adam which implies that Rectified Adam is generalizing better and at the same time because of lower loss, Adam may lead to over-fitting. From Table 7 it is evident that Ranger [25] optimizer produced higher accuracy than other optimizers because Ranger optimizer combines RAdam and lookahead [44] into a single optimizer. RAdam uses a dynamic rectifier to adjust Adam's adaptive momentum while lookahead reduces the task of hyper-parameter tuning and achieves faster convergence with minimal computational overhead. Therefore combining RAdam and lookahead provide advantages in different aspects of deep learning optimization and provide best results. From these experiments we find that using EfficientNet-B6 along with ranger optimizer produced better results by fine tuning very few hyper-parameters and less training time.

We have also tested the effect of using ranger optimizer with other architectures and the results are shown in Table 8. From Table 8 it is clear that ranger optimizer produced improved results when compared with other optimizers.

4.2 Comparison with the existing work

We have also compared the classification performance of our proposed work with other CNN models published recently. We observed that our proposed network achieved better AUC score of 0.9681 which is approximately 6% higher than the existing work presented in [18].

5 Conclusion and future work

This work aims to encourage the development of digital diagnosis of skin lesion and prospect the pertinence of a new CNN architecture, EfficientNet. We have proposed automated system for skin lesion classification which uses the dermoscopic images and meta data of patient information. The performance of the proposed method was evaluated using the datasets released by the popular challenges ISIC-2019 and ISIC-2020. The dataset contains different resolution images and also the dataset is highly imbalanced which may affect

the final results. To address these issues we have performed several experiments using two different transfer learning techniques such as feature extractor and fine tuning. In feature extractor technique the features from the later layers and the contextual data were combined and trained using LGBM classifiers. With this model we have obtained AUC score of 0.9174 for EfficientNet B6. To improve the results further, we have applied fine tuning method which concatenates the last layers of the pre-trained architecture and a simple neural network that takes contextual data as input. With this method we achieved better AUC score of 0.9681 for Efficient B6 with ranger optimizer which reduces the problem of hyperparameter tuning. We have also compared our results with the existing work and obtained a better score.

Declarations

Competing interests There are no relevant financial or non-financial competing interests to report.

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