

A self recoverable dual watermarking scheme for copyright protection and integrity verification

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Abstract Dual watermarking implies embedding of robust as well as fragile watermarks into the same cover image. It facilitates integration of copyright protection and integrity verification into the same scheme. However, most of such existing state of art approaches either lacked the feature of tamper detection and original content recovery or provided an approximation using coarser block level approach. The proposed self recoverable dual watermarking scheme integrates all the aforementioned functionalities of copyright protection, tamper detection and recovery into one scheme. The scheme is independent of the order of embedding of robust and fragile watermarks as these are embedded in different regions of the cover image. It performs tamper detection and recovery, both at the pixel level. The scheme obtains recovery information for each 2×2 image block in just eight bits which are further encoded to only four bits via mapping table. This reduction in recovery bits allows efficient embedding of copyright information which is tested against comprehensive set of attacks. The scheme is found to be robust against noises, filtering, histogram equalization, rotation, jpeg compression, motion blur etc. Besides the normalized cross correlation value, the evaluation of the extracted copyright information is also being done using various objective error metrics based on mutual relation between pixels, their values and locations respectively. The imperceptibility and visual quality of the watermarked as well as recovered image is found to be satisfactorily high. Three major categories of images: natural, texture as well as satellite have been tested in the proposed scheme. Even minute alterations can be chalked out as the detection accuracy rate has been enumerated on pixel basis. The scheme can tolerate tampering ratios upto 50 percent though the visual quality of

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the recovered image deteriorates with increasing tampering ratio. Comparative results based on normalized cross correlation, probability of false acceptance, probability of false rejection and peak signal to noise ratio metrics validate the efficacy of the proposed scheme over other existing state of art approaches.

Keywords Self recoverable · Dual watermarking · Copyright protection · Integrity verification · Normalized cross correlation (NCC) · Probability of false rejection (PFR) · Probability of false acceptance (PFA) · Peak signal to noise ratio (PSNR)

1 Introduction

The advancement in technology has eased life with lots of amenities available at hand, accompanied with easy sharing and distribution of multimedia content across the internet. However, the rate of illegal distribution and malicious tampering increased exponentially through the easy and online availability of various softwares and tools. Hence, techniques securing the multimedia content like cryptography, digital signatures, steganography, watermarking etc are promoted and serve as active research areas. Each technique is designed for a specific purpose like cryptography is meant for delivering documents unreadable, steganography conceals the very existence of the message whereas watermarking assures the integrity of the multimedia content and proves the rightful ownership. Watermarking is basically a two phase technique. First phase involves watermark embedder that embeds a secret information into the cover image to obtain a watermarked image that is transmitted via internet. In the second phase, the watermark extractor extracts this secret information on the receiving end to proof the integrity of the content.

Based on the purpose, watermarking schemes can be mainly categorized as fragile, semi-fragile and robust watermarking schemes. Fragile watermarking aims for authenticity verification whereas robust watermarking is meant for proving the rightful ownership. Intermediate schemes between these two extremes are termed as semi-fragile watermarking schemes. Variation of these schemes called as dual watermarking schemes are gaining attention these days. Dual watermarks are combination of both, fragile as well as robust watermarks and could fetch benefits of both ownership assertion as well as integrity verification. Dual watermarking schemes can be broadly categorized into three main types: First type of schemes generate a dual watermark from the combination of fragile and robust watermarks and then embed it into the cover image as the typical watermarking scheme. If this watermark is tampered, then the whole purpose of its dual functionality is destroyed. Second kind of dual watermarking schemes follow a pipeline pattern while embedding of fragile and robust watermarks. The embedding and functionality of one watermark must not get affected by embedding of the other watermark. Third kind of dual watermarking schemes embed both fragile as well as robust watermarks into separate areas of the cover image. They are considered to be most versatile schemes as they become independent from any of the constraints of interference while embedding or functioning of the respective watermarks.

In literature, varied robust watermarking schemes have already been proposed [7, 12, 16, 17, 25, 31, 36] to maintain the integrity of the content. Copyright protection schemes for e-government document images based on discrete cosine transform (DCT) with zigzag space-filling curve (SFC) was proposed in [6], singular value decomposition (SVD) exploit-

ing luminance masking in [1, 4] where the singular values of the DCT transformed coefficients of the watermark was embedded into the left singular value of the host image. The genetic algorithm was utilized to find the optimum value of the scaling factor depending on the content of the image. A reversible watermarking scheme for authentication of relational databases has been proposed in [2] where exact original document was recovered even though 95 % tuples of watermarked data were deleted. Another svd based copyright protection scheme presented in [5] increased the reliability of the scheme by embedding the principal contents of the watermark into DCT and DWT domains. The robustness factor was also enhanced via incorporation of particle swarm optimization for finding suitable scaling factors. However, many malicious attacks could not be detected by such schemes. Hence, came the need of fragile watermarking schemes that could sense even minute manipulations.

Tamper assessment function was proposed in literature [13] in this respect. Various transform domain and quantization based schemes have been proposed to enhance the security of the scheme and prevent tampering [39]. A fragile watermarking scheme for authentication of H.264/AVC content having high sensitivity to video attacks was proposed in [3]. Minimum deterioration of perceptual quality was guaranteed by incorporation of spatiotemporal analysis. However, they failed against incidental manipulations [18, 22]. Thus, intermediate kind of schemes that could tolerate incidental distortions along with sensitivity to malicious attacks came into picture [23, 26]. Though a lot of schemes have already been proposed, but still a lot of improvement is needed. A integrity check authentication scheme has been presented in [28]. It detected the tampers but localization accuracy was compromised. In [29], the accuracy of tampered regions increased but it could not perform recovery of the altered regions. Hence, schemes with dual functionalities are more preferable nowadays. A scheme with both authentication as well as recovery was proposed in [33], but the security and visual quality was compromised for its sake. Secret keys are often used to enhance the security of the schemes [34]. If security of these schemes is compromised, then the whole algorithm fails. Hence, correlating the watermark with pixel values of the cover image and thereby, embedding coefficients in other regions would serve as safety enhancement against such distortions [33]. A dual watermarking utilizing both spatial as well as frequency domain has been proposed in [9]. Firstly, 5/3 wavelet transform of the cover image was calculated and a robust watermark was embedded into the middle frequency coefficients. Thereafter, LSB substitution was done in spatial domain to embed the fragile watermark. However, this scheme suffered from the limitation that the embedding of fragile watermark affected the extraction of the robust watermark. One such dual watermarking scheme based on DCT coefficient, separating the integer and decimal portions to embed the robust and fragile watermarks has been proposed in [18]. This ensured that the two watermarks doesn't affect each other. However, there was no means to recover the lost content. In this paper, a selfrecoverable dual watermarking scheme providing all the three functionalities of ownership assertion, tamper detection and recovery has been proposed. It minimized the storage requirements for embedding of recovery information to just four bits for each 2×2 sized image block and utilized the space for embedding of copyright information. The tamper detection and recovery are both performed at pixel level.

The rest of the paper is organized as follows: Section 2 describes the proposed approach in detail, experimental results with analysis are presented in Section 3. Conclusions along with the scope of future work has been concluded in Section 4 followed by references.

2 Proposed methodology

The proposed watermarking scheme consists of six main phases: generation and embedding of recovery information, embedding of copyright information, generation and embedding of authentication information, ownership verification via extraction of copyright information, tamper detection and recovery of tampered image.

Consider a gray scale cover image I having M rows and N columns where M and N are even. Then T represent the total number of pixels ($T = M \times N$). Let the intensity value of each pixel of the cover image be denoted by $P_n \in [0, 255]$ where $n = 1, 2, 3, \dots, T$.

The individual bit of P_n is denoted by $b(P_n, 8), b(P_n, 7), b(P_n, 6) \dots b(P_n, 1)$ and it can be represented in binary form as follows:

$$b(P_n, m) = \lfloor \frac{P_n}{2^{m-1}} \rfloor \text{mod} 2, m = 1, 2, 3, \dots, 8 \tag{1}$$

The decimal equivalent can be represented as:

$$P_n = \sum_{m=1}^8 b(P_n, m) 2^{m-1} \tag{2}$$

A principal content image I_c is formed from the cover image I by obtaining the major information content of the cover image via taking the five most significant bits (MSBs) of all pixels. All the phases of the proposed watermarking scheme will take this principal content image I_c as input for further processing.

A basic flow of the proposed scheme is depicted in Fig. 1. The principal content image serves as input on the sender end where generation and embedding of recovery, embedding of copyright information and generation and embedding of authentication information is done which produces the watermarked image (I_w) as output. This output image is transmit-

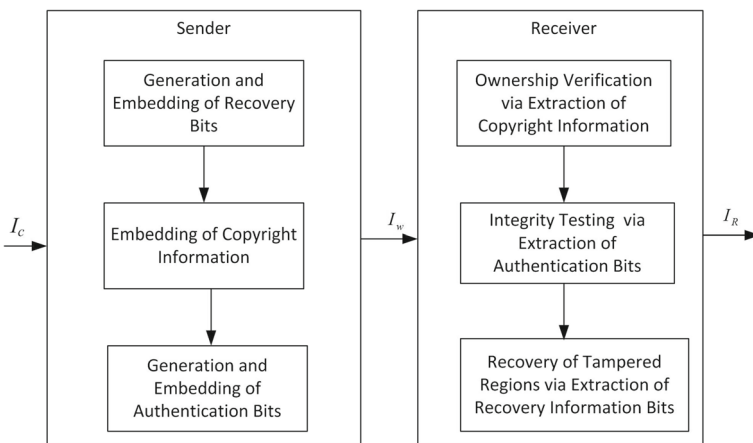


Fig. 1 Basic flow of the Proposed Scheme

ted to the receiver end where the ownership verification is done via extraction of copyright information. Then, its authenticity is checked and in case of tampering, a recovery image is obtained as output. The algorithmic flowchart of the proposed scheme has been depicted in Fig. 2 along with symbols, abbreviations and functions listed in Tables 1 and 2 respectively. The detailed approach is presented as follows:

2.1 Generation and embedding of recovery information

In this phase, the principal content image I_c of size $M \times N$ is divided into non overlapping blocks B_i of size 2×2 pixels each. A eight bit recovery information (R_{B_i}) is generated for each of the image blocks B_i . The method for recovery generation is done in the spatial domain whereas embedding is done in the frequency domain to maintain its robustness in case of tamper.

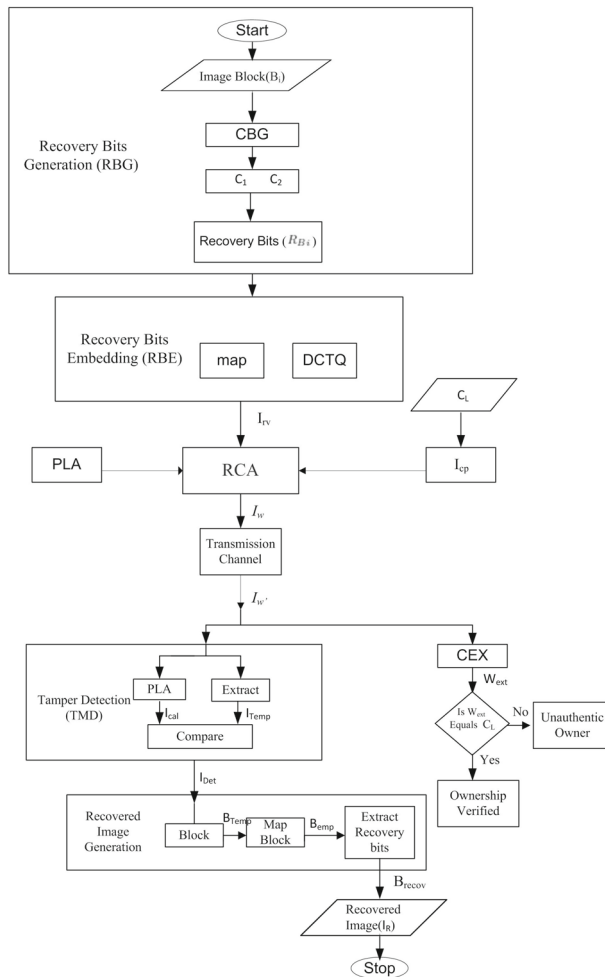


Fig. 2 Flowchart of the Proposed Scheme

Table 1 Symbols and abbreviations used in the flowchart

Symbol or Abbreviation Used	Significance
B_i	Image Block
C_1, C_2	Two Clusters of Block Pixels
RBG	Recovery Bits Generation
CBG	Cluster Based Generation
R_{B_i}	Recovery Bits of the Block (8 Bits)
RBE	Recovery Bits Embedding
D^j	Mapped Value
DCTQ	DCT based quantization
RCA	Recovery Copyright Authentication
PLA	Pixel Level Authentication
P_{xy}	Pixel Intensity Value
x, y	co-ordinate values of the pixel P_{xy}
M, N	Size of Cover Image
C_L	Copyright Logo
W_L	Bit sequence corresponding to C_L
CPE	Copyright Embedding
I_{cp}	Copyright Information Encoded Image
Ψ	Authentication Matrix of size $M \times N$ generated via PLA
I_w	Watermarked Image
I'_w	Suspected Watermarked Image
CEX	Copyright Information Extraction
W_{ext}	Extracted Watermark
TMD	Tamper Detection
I_{cal}	Calculated Authentication Bits Matrix of size $M \times N$
I_{Temp}	Extracted Authentication Bits Matrix of size $M \times N$
I_{Det}	Tamper Detected Image of size $M \times N$ where black regions signify untampered areas whereas white regions represent tampered ones
B_{Temp}	Tampered Blocks
B_{emp}	Contains Recovery Information
B_{recov}	Recovered Blocks
I_R	Recovered Image of size $M \times N$

The detailed methodology for the block recovery generation has been enlisted as follows:

1. Image Block Division: The principal content image I_c of size $M \times N$ is divided into non overlapping blocks B_i of size 2×2 pixels each where :

$$B_i = \begin{bmatrix} X_{p,q} & X_{p,q+1} \\ X_{p+1,q} & X_{p+1,q+1} \end{bmatrix} \quad (3)$$

where, $X_{p,q}$, $X_{p,q+1}$, $X_{p+1,q}$, $X_{p+1,q+1}$ represent the neighboring block pixels at $(p, q)^{th}$, $(p, q + 1)^{th}$, $(p + 1, q)^{th}$ and $(p + 1, q + 1)^{th}$ co-ordinates of I_c respectively.

Table 2 Functions used in the algorithms

Function Used	Significance
$length(C_i)$	returns the number of elements in C_i
$min(B_i)$	returns minimum element of the block B_i
$max(B_i)$	returns maximum element of the block B_i
map	returns mapped value of the input arguments according to the mapping table.
$Extract^u$	returns authentication bit from the u^{th} LSB position of the input argument
Compare	compares pixelwise values between the input arguments
Exor	Bitwise Exor of the input arguments
Block	finds tampered blocks corresponding to tampered pixel locations
MapBlock	maps tampered blocks with its corresponding recovery information embedded blocks

Hence, total number of such blocks formed T_b :

$$T_b = \frac{M \times N}{2 \times 2} \tag{4}$$

2. Block Recovery Generation: The recovery information is obtained for each block depending upon the content of the block, directly from the pixel values using the recovery bit generation (RBG) and cluster based generation (CBG) methods as Algorithm 1 and Algorithm 2.

Algorithm 1 RBG

INPUT: Image Block (B_i) of size 2×2

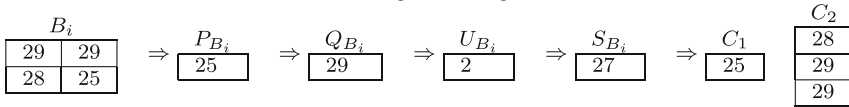
OUTPUT: R_{B_i} is a vector of size 1×8

Ensure:

- (1) $m_2 > m_1$
- (2) $length(C_i)$ returns the number of elements in C_i
- (3) C_1 and C_2 are two clusters containing elements of B_i in vector form
- (4) B_i^j denotes the j^{th} element of image block B_i

- 1: $\forall B_i, \text{ where } i = 1, 2, \dots, T_b$ ▷ For each 2×2 block of image
 - 2: $[C_1 \ C_2] \leftarrow CBG(B_i)$ ▷ Classify the block elements into two clusters C_1 and C_2
 - 3: $l_1 \leftarrow length(C_1)$ ▷ Count number of elements belonging to cluster C_1
 - 4: $l_2 \leftarrow length(C_2)$ ▷ Count number of elements belonging to cluster C_2
 - 5: $m_1 \leftarrow \sum_{i=1}^{l_1} C_1^i / l_1$ ▷ Compute mean of cluster C_1
 - 6: $m_2 \leftarrow \sum_{i=1}^{l_2} C_2^i / l_2$ ▷ Compute mean of cluster C_2
 - 7: $T_1 \leftarrow \lceil m_1 / 4 \rceil$ ▷ Reduce number of bits required to store mean value m_1
 - 8: $T_2 \leftarrow \lceil m_2 / 4 \rceil$ ▷ Reduce number of bits required to store mean value m_2
 - 9: $D \leftarrow T_2 - T_1$ ▷ Difference of the reduced mean values
 - 10: $R_{B_i}^{8-u} \leftarrow \lceil T_1 / 2^u \rceil \text{ mod } 2$ ▷ Storing binary equivalent of smaller mean value in the recovery vector
 - 11: where $u \leftarrow 0$ to 2
 - 12: $R_{B_i}^5 \leftarrow D$ ▷ Storing binary equivalent of difference value in the recovery vector
 - 13: **for** $j \leftarrow 1$ to 4 **do** ▷ Indicating cluster for each image block element
 - 14: **if** $B_i^j \in C_1$ **then**
 - 15: $R_{B_i}^{5-j} \leftarrow 0$
 - 16: **else**
 - 17: $R_{B_i}^{5-j} \leftarrow 1$
 - 18: **end if**
 - 19: **end for**
 - 20: **return** R_{B_i} ▷ Recovery vector of the image block
-

Example 2.1 Consider a block of cover image B_i of size 2×2 . The block elements are clustered into two clusters C_1 and C_2 using CBG Algorithm.



Algorithm 2 CBG

INPUT: Image Block (B_i) of size 2×2

OUTPUT: C_1 and C_2 composed of elements of B_i

Ensure:

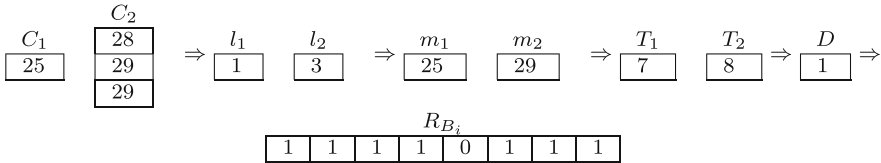
- (1) $min(B_i)$ returns minimum element of the block B_i
- (2) $max(B_i)$ returns maximum element of the block B_i

```

1:  $\forall B_i, \text{ where } i = 1, 2, \dots, T_b$  ▷ For each  $2 \times 2$  block of image
2:  $P_{B_i} \leftarrow min(B_i)$  ▷ Minimum element of block
3:  $Q_{B_i} \leftarrow max(B_i)$  ▷ Maximum element of block
4:  $U_{B_i} \leftarrow \lceil 0.5(Q_{B_i} - P_{B_i}) \rceil$  ▷ Semi Range of the block
5:  $S_{B_i} \leftarrow P_{B_i} + U_{B_i}$  ▷ Cluster Boundary for the block
6: for  $j \leftarrow 1$  to 4 do ▷ For each element of the image block
7:   if  $P_{B_i} \leq B_i^j < S_{B_i}$  then ▷ Range of Cluster  $C_1$ 
8:      $C_1 \leftarrow B_i^j$ 
9:   else
10:     $C_2 \leftarrow B_i^j$  ▷ Range of Cluster  $C_2$ 
11:   end if
12: end for
13: return  $C_1, C_2$  ▷ Clusters  $C_1$  and  $C_2$ 

```

Example 2.2 Recovery vector bits R_{B_i} for image block B_i is generated using RBG Algorithm.



After generation of eight bit recovery information for each image block through Algorithms 1 and 2, this generated information must be embedded into mapping blocks such that it could handle worst tampering scenarios. To achieve this goal of increasing chances of accurate localization and recovery, the extracted recovery information of a block is permuted using secret key prior to embedding in the corresponding mapping blocks. Random mapping of recovery information enhances the robustness against cryptanalysis as well as enhances the security of the scheme. Based on a secret key (K_1), a non convergent and non periodic logistic chaotic map, sensitive to the initial conditions is generated. The sequence is as follows:

$$z_{n+1} = \xi z_{n+1}(1 - z_n) \tag{5}$$

where $3.57 < \xi < 4$ and $0 < z_0 < 0.5$. The composition of secret key is as follows: $K_1 = (\xi, z_0)$. The generated chaotic sequence after binarization is sub divided into small series, each composed of eight bit binary information. The sub series is as follows: $y_i = (y_{i1}, y_{i2}, y_{i3}, y_{i4}, y_{i5}, y_{i6}, y_{i7}, y_{i8}), i = 1, 2, \dots, T_b$. The generated recovery information

bits is encoded after operating in exclusive-or mode with the chaotic sub series to obtain the final sequence as follows: $W = W_1, W_2, \dots, W_{T_b}$.

$$w_{i,j} = R_{B_{ij}} \oplus y_{ij} \tag{6}$$

where $1 \leq i \leq T_b, 1 \leq j \leq 8$.

3) Embedding position generation. The embedding of the encoded block recovery information is mapped randomly to another block using a sequence generated based on a secret key K_2 . A random sequence of length $T_b, r = (r_1, r_2, \dots, r_{T_b})$ is obtained using chaotic map in [20] as follows:

$$r_{n+1} = (1 + 0.3 \times (r_{n-1} - 1.08) + 379 \times r_n^2 + 1001 \times q_n^2) \bmod 3 \tag{7}$$

Here, q_n signifies the initial values q_0, r_0, r_1 of the logistic chaotic map [20]. The secret key $K_2 = (r_0, r_1, q_0)$ where $(r_0, r_1) \in (-1.5, 1.5), q_0 \in (0, 1)$. This random sequence $(r_1, r_2, \dots, r_{T_b})$ is sorted to obtain an ordered index sequence $(I_1, I_2, \dots, I_{N_b})$ used to select mapping block positions for embedding.

The recovery information is embedded in the frequency domain so as to increase its robustness against various tamperers while transmission and also enhance its imperceptibility. First of all, the eight recovery bits are converted pairwise into their decimal equivalents to obtain a four valued resulting vector holding values within range of 0 to 3. The mapping has been depicted in Fig. 3 for mapping recovery bits to their decimal equivalents. Thereafter, discrete cosine transform is calculated for each of the image blocks and each DCT coefficient value of the block pixels is quantized to a new modified value depending upon the recovery bits using DCT based quantization method ($DCTQ$) as Algorithm 4. Thereafter, inverse DCT is computed for each of the modified blocks to obtain the recovery embedded blocks to finally compose the watermarked image (I_{rv}). The detailed methodology of the recovery bit embedding (RBE) is described in Algorithm 3.

Recovery Bits Vector (R_{B_i})

$R_{B_i}^8$	$R_{B_i}^7$	$R_{B_i}^6$	$R_{B_i}^5$	$R_{B_i}^4$	$R_{B_i}^3$	$R_{B_i}^2$	$R_{B_i}^1$
Smaller Mean Value Bits (3 bits)			Difference Bit (1bit)	Four Bits for indicating belonging of each block pixel to which cluster ($C_1 \leftarrow 0$) ($C_2 \leftarrow 1$)			

Mapping Table

$R_{B_i}^k$	$R_{B_i}^{k+1}$	Mapped Value
0	0	0
0	1	1
1	0	2
1	1	3

Fig. 3 Mapping of Recovery Bits

Algorithm 3 RBE

INPUT: Image Block (B_i) of size 2×2 , Recovery Information Bits R_{B_i}

OUTPUT: Embedded Block B_{e_i} of size 2×2

Ensure:

- (1) $flag = 1$
- (2) D_j is the j^{th} element of D where D is a 1×4 vector containing mapped values according to the mapping table.
- (3) e is a matrix of size 2×2 .
- (4) map returns mapped value according to the mapping table.

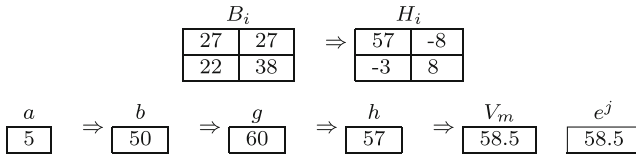
```

1:  $\forall B_i, \text{ where } i = 1, 2, \dots, T_b$                                  $\triangleright$  For each  $2 \times 2$  block of image
2:  $H_i \leftarrow \text{Discrete Cosine Transform of } B_i$                  $\triangleright$  Compute DCT of the block
3: where  $j \leftarrow 1$  to 4
4: while  $k \leq 8$  do
5:    $D^j \leftarrow \text{map}[R_{B_i}^k, R_{B_i}^{k+1}]$                      $\triangleright$  Map two consecutive bits of the Recovery Vector
6: end while
7: if  $H_i^j \leq 0$  then  $\triangleright$  Flag is initialized with negative sign if DCT coefficient is negative
8:    $flag \leftarrow -1$ 
9: end if
10:  $a \leftarrow \lfloor |H_i^j / 10| \rfloor$                                  $\triangleright$  Integer portion of the DCT coefficient after dividing by 10
11:  $b \leftarrow a * 10$                                          $\triangleright$  Lower bound of the DCT coefficient in multiples of 10
12:  $e^j \leftarrow \text{DCTQ}(D^j, b)$ 
13:  $e^j \leftarrow e^j * flag$                                  $\triangleright$  Modified DCT coefficient value
14:  $B_{e_i} \leftarrow \text{Inverse Discrete Cosine Transform of } e^j$   $\triangleright$  Modified block
15: return  $B_{e_i}$   $\triangleright$  Recovery embedded watermarked image( $I_{rv}$ ) is composed of these  $B_{e_i}$ 

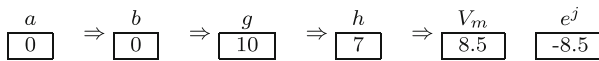
```

Example 2.3 Consider a block of cover image(B_i) of size 2×2 . The recovery bits $R_{B_i} = [11110111]$ is embedded using RBE and DCTQ Algorithm into the block B_i to obtain recovery information embedded block B_{e_i} .

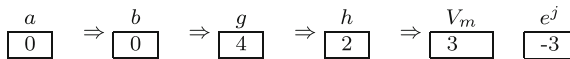
For $H_i^j=57$, and $D^j=3$, $flag=1$



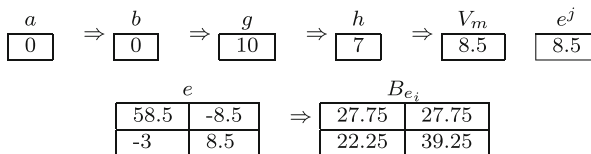
For $H_i^j=-8$, and $D^j=3$, $flag=-1$



For $H_i^j=-3$, and $D^j=1$, $flag=-1$



For $H_i^j=8$, and $D^j=3$, $flag=1$



Algorithm 4 DCTQ

INPUT: S is one of the elements of D and W is the lower bound of absolute DCT coefficient value of the Image Block (B_i) elements.

OUTPUT: V_m as modified absolute DCT coefficient value of the image block elements.

```

1: if  $S \leftarrow 0$  then
2:    $g \leftarrow W + 2$ 
3:    $h \leftarrow W$ 
4:    $V_m \leftarrow 0.5 * (g + h)$ 
5: end if
6: if  $S \leftarrow 1$  then
7:    $g \leftarrow W + 4$ 
8:    $h \leftarrow W + 2$ 
9:    $V_m \leftarrow 0.5 * (g + h)$ 
10: end if
11: if  $S \leftarrow 2$  then
12:    $g \leftarrow W + 7$ 
13:    $h \leftarrow W + 4$ 
14:    $V_m \leftarrow 0.5 * (g + h)$ 
15: end if
16: if  $S \leftarrow 3$  then
17:    $g \leftarrow W + 10$ 
18:    $h \leftarrow W + 7$ 
19:    $V_m \leftarrow 0.5 * (g + h)$ 
20: end if
21: return  $V_m$ 

```

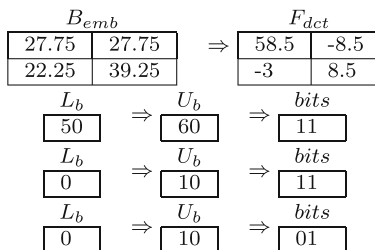
▷ Mapped consecutive recovery bits as 0
 ▷ Upper bound of Modified Coefficient
 ▷ Lower bound of Modified Coefficient
 ▷ Modified coefficient value
 ▷ Mapped consecutive recovery bits as 1
 ▷ Upper bound of Modified Coefficient
 ▷ Lower bound of Modified Coefficient
 ▷ Modified coefficient value
 ▷ Mapped consecutive recovery bits as 2
 ▷ Upper bound of Modified Coefficient
 ▷ Lower bound of Modified Coefficient
 ▷ Modified coefficient value
 ▷ Mapped consecutive recovery bits as 3
 ▷ Upper bound of Modified Coefficient
 ▷ Lower bound of Modified Coefficient
 ▷ Modified coefficient value
 ▷ Modified coefficient value

2.2 Embedding of copyright information

After obtaining the recovery information embedded cover image (I_{rv}), next comes the task of embedding the copyright information. Copyright logos (C_L) are in the form of binary watermarks containing total pixels as $\frac{M \times N}{4}$. The copyright logo is traversed in a sequential row by row manner to get an equivalent bit sequence W_L of the logo pixel values. Thereafter, corresponding to each bit of the sequence, a 2×2 block is generated according to the copyright embedding algorithm (CPE) as Algorithm 5 to obtain the copyright encoded image I_{cp} . The detailed algorithm is as follows:

Example 2.4 Consider a recovery information embedded block of cover image (B_{emb}) of size 2×2 . The extraction of recovery bits is done using the RIG Algorithm from it.

- For $F_{dct}^i = 58.5$,
- For $F_{dct}^i = -8.5$,
- For $F_{dct}^i = -3$,
- For $F_{dct}^i = 8.5$,



Hence, recovery bits vector is obtained as follows:

Algorithm 5 CPE

INPUT: W_L as watermark bit sequence of the copyright binary $\log_2(C_L)$ of length $\frac{M \times N}{4}$.

OUTPUT: I_{cp} is the encoded image with copyright information of size $M \times N$.

Ensure:

- (1) W_{L_i} is the i^{th} bit of W_L
- (2) R_i is an empty matrix of size 2×2

```

1: for  $i \leftarrow 1$  to  $\frac{M \times N}{4}$  do
2:   if  $W_{L_i} \leftarrow 0$  then
3:      $R_i \leftarrow \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix}$ 
4:   else
5:      $R_i \leftarrow \begin{bmatrix} 3 & 2 \\ 2 & 2 \end{bmatrix}$ 
6:   end if
7: end for
8: return  $I_{cp}$ 

```

▷ For all bits of the copyright \log_2

▷ When bit of copyright \log_2 is 0

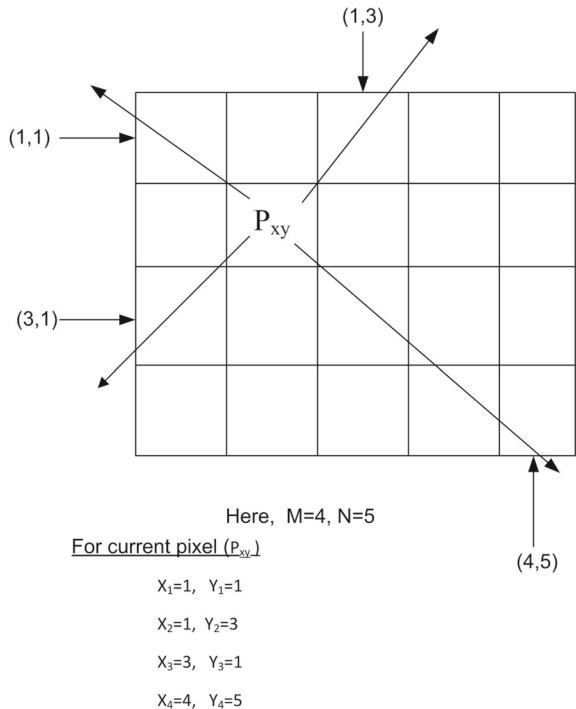
▷ When bit of copyright \log_2 is 1

▷ I_{cp} is composed of non overlapping blocks R_i

2.3 Generation and embedding of Authentication information

The authentication of the watermarked image is done at pixel level. An authentication bit is generated for each of the pixel depending upon its intensity value (P_{xy}) and position coordinates (row(x), column(y)) as shown in Fig. 4. The detailed algorithm for pixel level authentication (PLA) is enlisted in the Algorithm 6.

Fig. 4 Authentication Bit for a Pixel



Algorithm 6 PLA

INPUT: P_{xy} is the pixel intensity at x, y location, x, y as the pixel co-ordinates, M, N as size of cover image.

OUTPUT: ψ is the authentication matrix of size $M \times N$.

Ensure:

- rr is a vector of size 1×4 .
- α is a empty matrix of size 4×8 .
- A_s^i is composed of $A_s^1, A_s^2, A_s^3, A_s^4$ which are vectors of size 1×4
- β is a vector of size 1×4
- ψ is the authentication matrix of size $M \times N$
- ψ_{xy} denotes the authentication bit at x, y co-ordinate position

```

1:  $x_1 \leftarrow x$                                 ▷ Assign current x co-ordinate
2:  $y_1 \leftarrow y$                                 ▷ Assign current y co-ordinate
3: while  $x_1 \neq 1$  or  $y_1 \neq 1$  do                ▷ Keep traversing until  $x_1$  or  $y_1$  co-ordinate becomes 1
4:    $x_1 \leftarrow x_1 - 1$                             ▷ Decrement x co-ordinate by 1
5:    $y_1 \leftarrow y_1 - 1$                             ▷ Decrement y co-ordinate by 1
6: end while
7: if  $x_1 \neq 1$  then                                ▷  $rr_1$  is assigned co-ordinate value other than 1
8:    $rr(1) \leftarrow x_1$ 
9: else
10:   $rr(1) \leftarrow y_1$ 
11: end if
12:  $x_2 \leftarrow x$                                 ▷ Assign current x co-ordinate
13:  $y_2 \leftarrow y$                                 ▷ Assign current y co-ordinate
14: while  $x_2 \neq 1$  or  $y_2 \neq N$  do                ▷ Keep traversing until  $x_2$  is 1 or  $y_2$  co-ordinate becomes
    N
15:   $x_2 \leftarrow x_2 - 1$                             ▷ Decrement x co-ordinate by 1
16:   $y_2 \leftarrow y_2 + 1$                             ▷ Increment y co-ordinate by 1
17: end while
18: if  $x_2 \neq 1$  then                                ▷  $rr_2$  is assigned co-ordinate value other than 1 or N
19:   $rr(2) \leftarrow x_2$ 
20: else
21:   $rr(2) \leftarrow y_2$ 
22: end if
23:  $x_3 \leftarrow x$                                 ▷ Assign current x co-ordinate
24:  $y_3 \leftarrow y$                                 ▷ Assign current y co-ordinate
25: while  $x_3 \neq M$  or  $y_3 \neq 1$  do                ▷ Keep traversing until  $x_3$  is  $M$  or  $y_3$  co-ordinate
    becomes 1
26:   $x_3 \leftarrow x_3 + 1$                             ▷ Increment x co-ordinate by 1
27:   $y_3 \leftarrow y_3 - 1$                             ▷ Decrement x co-ordinate by 1
28: end while
29: if  $x_3 \neq M$  then                                ▷  $rr_3$  is assigned co-ordinate value other than  $M$  or 1
30:   $rr(3) \leftarrow x_3$ 
31: else
32:   $rr(3) \leftarrow y_3$ 
33: end if
34:  $x_4 \leftarrow x$                                 ▷ Assign current x co-ordinate
35:  $y_4 \leftarrow y$                                 ▷ Assign current y co-ordinate
36: while  $x_4 \neq M$  or  $y_4 \neq N$  do                ▷ Keep traversing until  $x_4$  is  $M$  or  $y_4$  co-ordinate
    becomes N
37:   $x_4 \leftarrow x_4 + 1$                             ▷ Increment x co-ordinate by 1
38:   $y_4 \leftarrow y_4 + 1$                             ▷ Decrement y co-ordinate by 1
39: end while
40: if  $x_4 \neq M$  then                                ▷  $rr_4$  is assigned co-ordinate value other than  $M$  or N
41:   $rr(4) \leftarrow x_4$ 
42: else
43:   $rr(4) \leftarrow y_4$ 
44: end if
45: for  $i \leftarrow 1$  to 4 do                            ▷ Binary equivalents of the binding neighbors
46:    $\alpha(i) \leftarrow \lfloor rr(i)/2^u \rfloor \text{mod} 2$ 
47:   where  $u \leftarrow 0$  to 4
48: end for                                            ▷  $\alpha(i)$  represents  $i^{th}$  row of  $\alpha$  with 8 columns
49: for  $j \leftarrow 1$  to 4 do                            ▷ Bitwise Exor of the Pixel intensity value with the binding
    neighbors
50:   $A_s^j \leftarrow \text{Exor}(\alpha_{4-u}^j, P_{xy_u})$ 
51:  where  $u \leftarrow 4$  to 0
52: end for
53:  $\beta \leftarrow (A_s^1 \wedge A_s^2 \wedge A_s^3 \wedge A_s^4) \triangleright \beta$  represents result of bitwise logical AND operation of all
     $A_s^j$ 
54:  $\psi_{xy} \leftarrow (\sum_{j=1}^4 \beta^j) \text{mod} 2$                 ▷ One bit authentication bit for the current pixel
55: return  $\psi$                                         ▷ Authentication matrix of size  $M \times N$ 

```

Example 2.5 Generation of authentication bit for Pixel P_{xy} using PLA Algorithm.

After obtaining the recovery information embedded image (I_{rv}), copyright information encoded image (I_{cp}) and the authentication matrix (ψ), all the three are coupled to obtain the final watermarked image (I_w) using the recovery copyright authentication (RCA) algorithm as Algorithm 7. The detailed procedure will follow.

Algorithm 7 RCA

INPUT: I_{rv} , I_{cp} , ψ are recovery embedded image, copyright information encoded image and authentication matrix of size $M \times N$.

OUTPUT: I_w is the watermarked image of size $M \times N$.

Ensure:

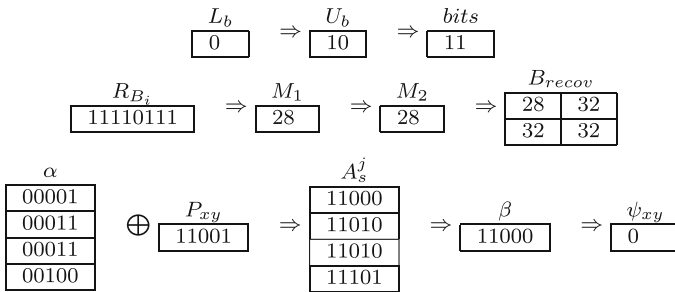
- (1) I_w is eight bit watermarked image of size $M \times N$.
- (2) B_1 is a vector of size 1×5 .
- (3) B_2 is a vector of size 1×2 .

```

1: for  $i \leftarrow 1$  to  $M$  do
2:   for  $j \leftarrow 1$  to  $N$  do
3:      $B_1 \leftarrow [I_{rv}(i, j)/2^u] \text{mod} 2$ 
4:     where  $u \leftarrow 0$  to 4
5:      $B_2 \leftarrow [I_{cp}(i, j)/2^v] \text{mod} 2$ 
6:     where  $v \leftarrow 0$  to 1
7:      $I_w(i, j)^p \leftarrow B_1$ 
8:     where  $p \leftarrow 8$  to 4
9:      $I_w(i, j)^q \leftarrow B_2$ 
10:    where  $q \leftarrow 3$  to 2
11:     $I_w(i, j)^r \leftarrow \psi(i, j)$ 
12:    where  $r \leftarrow 1$ 
13:  end for
14: end for
15: return  $I_w$ 

```

▷ Embedding into first five MSB's
▷ Embedding into 3rd and 2nd LSB's
▷ Embedding into 1st LSB's
▷ Watermarked Image



2.4 Ownership verification

The watermarked image (I_w) is transmitted to the receiver end. To proceed with the ownership assertion, the copyright information is extracted from the received watermarked image to obtain the copyright logo, called as extracted watermark logo (W_{ext}) using copyright extraction (CEX) algorithm as Algorithm 8. The rightful owner possesses the original watermark logo. If the extracted logo matches with the original one, he is proved to be the legitimate owner of the cover image. If there is a dispute, then he is the unauthorized owner and there may be a possibility of tampering of the content. To actually detect the tampered areas, one has to proceed with the TMD (Tamper Detection) algorithm as Algorithm 9.

Algorithm 8 CEX

INPUT: I_w

OUTPUT: W_{ext} is the extracted watermark logo of size $\frac{M \times N}{4}$.

Ensure:

- (1) B_w is 2×2 sized non-overlapping block of watermarked image I_w
- (2) W_{bsq} is vector of size $1 \times \frac{M \times N}{4}$
- (3) B_{dct} is vector of size 1×4
- (4) B_{dct}^i denotes the DCT value of the i^{th} pixel of the 2×2 non-overlapping block B_w .

- 1: $\forall B_w, \text{ where } w = 1, 2, \dots, T_b$ ▷ For all blocks of watermarked image
 - 2: $B_{dct} \leftarrow$ Discrete Cosine Transform of B_w ▷ Compute DCT of each block
 - 3: $S \leftarrow \sum_{i=1}^4 B_{dct}^i$ ▷ Sum of DCT coefficients of each block
 - 4: **if** $S = 2$ or $S = 6$ **then**
 - 5: $bit_{ext} \leftarrow 1$ ▷ Append the bit_{ext} bit to vector W_{bsq}
 - 6: **else**
 - 7: $bit_{ext} \leftarrow 0$ ▷ Append the bit_{ext} bit to vector W_{bsq}
 - 8: **end if** ▷ W_{ext} is the extracted watermark by reshaping vector W_{bsq} to image of size $\frac{M \times N}{4}$
 - 9: **return** W_{ext} ▷ Extracted Watermark
-

2.5 Tamper detection

The proposed scheme performs pixel level authentication for detecting the tampered regions of the suspected watermarked image. To chalk out the tampered regions, first of all the authentication bit is calculated for each pixel using the PLA algorithm. Also, the authentication information is extracted from the suspected watermarked image received. If there is a match between the extracted authentication bit and the calculated one, then it indicates the untampered pixel signified by black region. Otherwise, it belongs to the tampered region indicated by white regions in the tamper detected image (I_{Det}) respectively.

Algorithm 9 TMD

INPUT: I_w

OUTPUT: I_{Det} is the tamper detected image of size $M \times N$.

Ensure:

- (1) I_{Cal} is the empty matrix of size $M \times N$.
- (2) I_{Temp} is the empty matrix of size $M \times N$.
- (3) Extract is a function to extract the authentication bit from the u^{th} LSB position.
- (4) Compare is a function to compare pixelwise values.

- 1: $I_{Cal} \leftarrow$ Call PLA(I_w) ▷ Calculate Authentication Matrix for watermarked image using PLA Algorithm
 - 2: **for** $i \leftarrow 1$ to M **do**
 - 3: **for** $j \leftarrow 1$ to N **do**
 - 4: $I_{Temp}(i, j) \leftarrow$ Extract $^u(I_w(i, j))$ ▷ Extract the authentication bit from each pixel of the watermarked image
 - 5: where $u \leftarrow 1$
 - 6: **end for**
 - 7: **end for**
 - 8: $I_{Det} \leftarrow$ Compare(I_{Cal}, I_{Temp}) ▷ Compare the calculated authentication matrix with the extracted one ▷ Matching pixel is treated as true(0) ▷ Non Matching pixel is treated as false(1)
 - 9: **return** I_{Det} ▷ Tamper Detected Image with black and white regions indicating unaltered and altered portions of image
-

2.6 Recovery of tampered image

After the detection of tampered areas(tampered blocks) by using the pixel level authentication (PLA) algorithm, the recovery is to be done by mapping them to their corresponding recovery information embedded blocks. Thereafter, two bits recovery information is extracted from each of the DCT block coefficients to finally build up the eight bits recovery information of the block. From the retrieved recovery information, the block elements are build up to form the recovered block. The detailed algorithm of Recovery image generation (RIG) has been detailed in Algorithm 10.

Algorithm 10 Algorithm for RIG

```

INPUT:  $I_w, I_{Det}$ 
OUTPUT:  $I_R$  is the recovered image of size  $M \times N$ .
Ensure:
  (1)Block is a function to find tampered blocks corresponding to tampered pixel locations.
  (2)MapBlock is a function to map the tampered blocks with its corresponding recovery
  information embedded blocks.
  (3) $F_{dct}, B_{recov}$  are empty matrices of size  $2 \times 2$ .
  (4) $bits$  is a vector of size  $1 \times 8$  that will be reinitialized for each block contained in the
  set of blocks  $B_{emb}$ .

1:  $B_{Temp} \leftarrow Call\ Block(I_{Det})$   $\triangleright B_{Temp}$  contains all tampered blocks of  $I_w$ 
2:  $B_{emb} \leftarrow Call\ MapBlock(B_{Temp})$   $\triangleright B_{emb}$  contains all recovery information embedded
  blocks of  $B_{Temp}$ 
3:  $\forall B_{emb}$   $\triangleright$  For each recovery information embedded block
4:  $F_{dct} \leftarrow$  Absolute Value of Discrete Cosine Transform of  $B_{emb}$ 
5: for  $i \leftarrow 1$  to 4 do
6:    $L_b \leftarrow 10 * (\lfloor F_{dct}^i / 10 \rfloor)$   $\triangleright$  Lower bound of each absolute DCT coefficient of block (in
  multiples of 10)
7:    $U_b \leftarrow L_b + 10$   $\triangleright$  Upper bound of each absolute DCT coefficient of block (in
  multiples of 10)
8:   if  $L_b \leq F_{dct}^i < L_b + 2$  then  $\triangleright$  if DCT coefficient lies in range of lower bound and
  lower bound incremented by two
9:      $bits \leftarrow [0\ 0]$ 
10:   end if
11:   if  $L_b + 2 \leq F_{dct}^i < L_b + 4$  then  $\triangleright$  if DCT coefficient lies in range of lower bound
  incremented by two and four
12:      $bits \leftarrow [0\ 1]$ 
13:   end if
14:   if  $L_b + 4 \leq F_{dct}^i < L_b + 7$  then  $\triangleright$  if DCT coefficient lies in range of lower bound
  incremented by four and seven
15:      $bits \leftarrow [1\ 0]$ 
16:   end if
17:   if  $L_b + 7 \leq F_{dct}^i \leq U_b$  then  $\triangleright$  if DCT coefficient lies in range of lower bound
  incremented by seven and upper bound
18:      $bits \leftarrow [1\ 1]$ 
19:   end if  $\triangleright$  Append the bits variable for each of the block values
20: end for
21:  $M \leftarrow Extract^u(bits)$   $\triangleright$  Extract bits from eighth to sixth positions of  $bits$  vector
22: where  $u \leftarrow 8$  to 6
23:  $M_D \leftarrow (M, v)2^v$   $\triangleright$  Form the decimal equivalent mean value
24: where  $v \leftarrow 0$  to 2
25:  $D_c \leftarrow Extract^u(bits)$   $\triangleright$  Extract bit from fifth position of  $bits$  vector
26: where  $u \leftarrow 5$ 
27:  $M_2 \leftarrow (M_D + D_c) * 4$   $\triangleright$  Obtain the larger mean value as  $M_2$ 
28:  $M_1 \leftarrow M_D * 4$   $\triangleright$  Obtain the smaller mean value as  $M_1$ 
29: for  $i \leftarrow 1$  to 4 do  $\triangleright$  Depending on bits in positions one to four in  $bits$  vector form
  recovered block pixels
30:   if  $Extract^v(bits) \leftarrow 1$  then  $\triangleright$  If bit value is 1
31:      $B_{recov}(i) \leftarrow M_2$   $\triangleright$  Assign  $M_2$  as recovered pixel value
32:   else
33:      $B_{recov}(i) \leftarrow M_1$   $\triangleright$  Assign  $M_1$  as recovered pixel value
34:   end if
35: end for
36: return  $I_R$   $\triangleright$  Recovered image is composed of  $B_{recov}$ 

```

3 Experimental results and analysis

The proposed scheme has been simulated on a wide set of standard grayscale images using MATLAB 2013Ra. Variations of grayscale images has been tested upon, majorly categorized into three main kinds i.e. natural images, satellite images and texture images. Some of these grayscale images sized 512×512 has been shown in Fig. 5. To quantitatively evaluate the imperceptibility of the watermarked images, peak signal to noise ratio (PSNR) metric have been adopted with values enlisted in Table 3 and visual quality representation depicted in Fig. 6 respectively.

The Peak-Signal-to-Noise-Ratio (PSNR) metric is defined as follows:

$$PSNR = 10 \log_{10} \frac{255^2}{MSE} (dB) \quad (8)$$

$$MSE = \frac{1}{M1 \times M2} \sum_1^{M1} \sum_1^{M2} \|C'_{i,j} - C_{i,j}\| \quad (9)$$



Fig. 5 Cover Test Images

Table 3 PSNR Values for Different Types of Watermarked Images

Classification	Image	PSNR(dB)
Natural Images	Lena	29.13
	Barbara	28.11
	Cameraman	28.45
	Baboon	29.20
	Airplane	30.01
	Pepper	30.11
	Remote Sensing Images	Satellite Image 1
Satellite Image 2		29.23
Satellite Image 3		30.11
Texture Images	Bark	29.10
	Plastic Bubbles	30.11
	Brick Wall	29.34

**Fig. 6** Watermarked Test Images

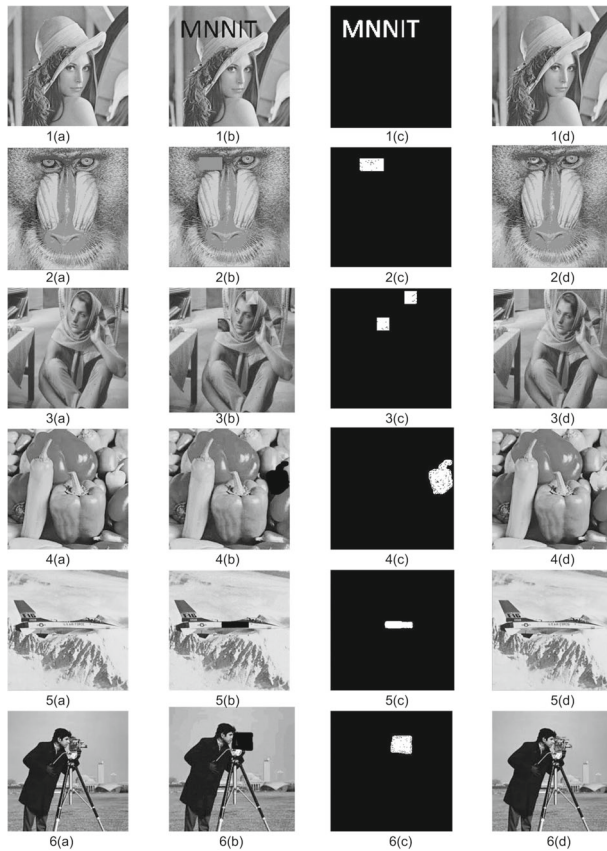


Fig. 7 Examples of Natural Images (a) Watermarked Images (b) Tampered Images (c) Tamper Detected Images (d) Recovered images

where, $C_{i,j}$ and $C'_{i,j}$ represents pixel value of original cover image and the watermarked image of size $M1 \times M2$.

PSNR values for the three categories of grayscale images has been tabulated in Table 3. Indistinguishability and imperceptibility attained for the above three categories of watermarked images is satisfyingly enough as indicated by the PSNR values. The dual functionalities of the proposed scheme have been evaluated using various available metrics and discussed in separate sections as follows:

3.1 Tamper detection and recovery

To evaluate the tamper detection and recovery efficiency of the proposed scheme, following metrics have been adopted:

1. Tampering Ratio(TR)

$$r_t = \frac{100N_T}{N} \% \tag{10}$$

where, N and N_T denotes the total number of blocks and the number of tampered blocks in the test cover image.

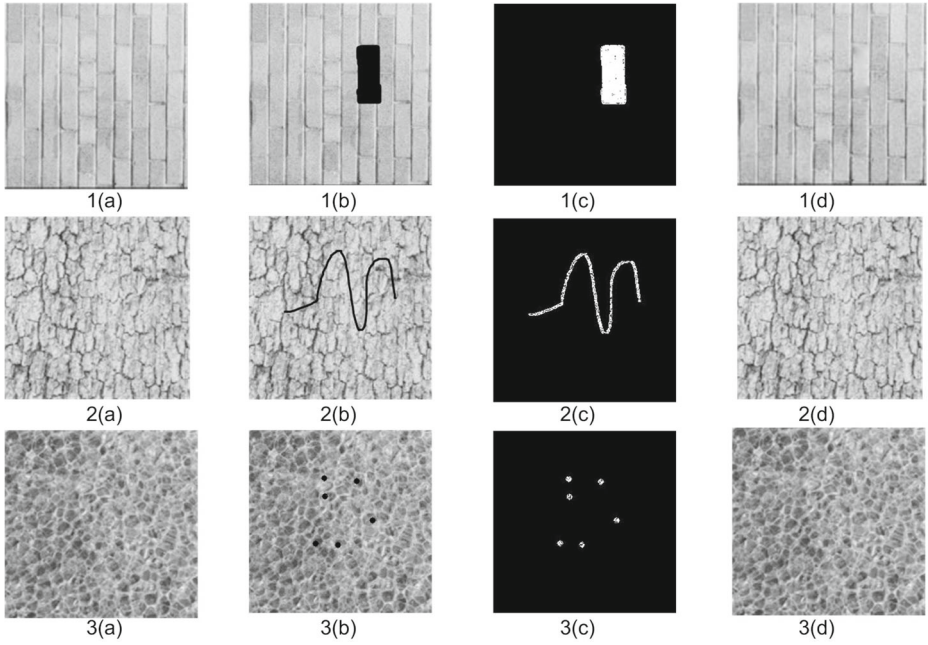


Fig. 8 Examples of Texture Images (a) Watermarked Images (b) Tamper Images (c) Tampered Detected Images (d) Recovered images

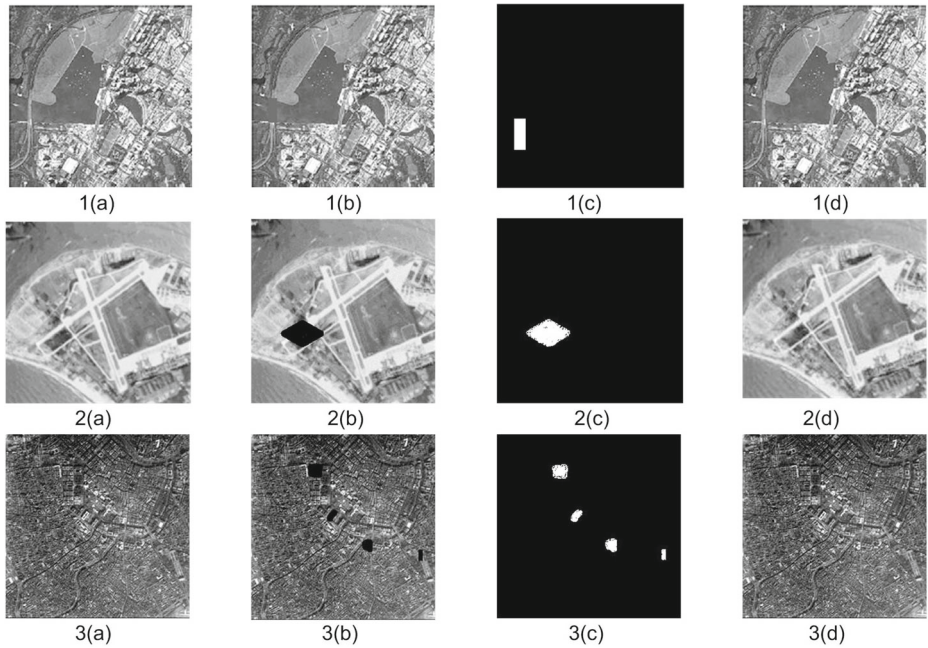


Fig. 9 Examples of Satellite Images (a) Watermarked Images (b) Tamper Images (c) Tampered Detected Images (d) Recovered images

Table 4 Results of Tamper Detection and Recovery for Natural Images

Cover Image	No. of Detected Pixels	Total Pixels Altered	Detection Rate
Lena	1988	2029	97
Baboon	812	823	98.6
Barbara	860	897	95.8
Pepper	1863	1902	97.94
Airplane	544	599	90.8
Cameraman	974	1016	95.86

2. Probability of False Rejection(PFR)

$$P_{fr} = \frac{100N_{ud}}{(N - N_T)}\% \quad (11)$$

where, N_{ud} , N and N_T denotes the number of valid blocks that are wrongly detected, the total number of blocks and the number of tampered blocks in the test cover image.

3. Probability of False Acceptance(PFA)

$$P_{fa} = \frac{100(N_T - N_{td})}{N_T}\% \quad (12)$$

where, N_{td} , N and N_T denotes the number of tampered blocks that are correctly detected, the total number of blocks and the number of tampered blocks in the test cover image.

To validate the efficiency of tamper detection and accurate localization of the proposed scheme for aforementioned three major categories of images: natural, texture and satellite, different attacks have been tested with few depicted in Fig. 7 for natural images, in Fig. 8 for texture images and in Fig. 9 for satellite images respectively. The detection of the altered regions have been done using Algorithm 9 and reflected by white regions in the tamper detected image (I_{Det}) whereas untampered ones signified by black regions. The level of accuracy is quite good. In the Figs. 7, 8 and 9, column representation is as follows: (a) the original image (b)the tampered image (c)the tamper detected image and (d)the recovered image. Different kind of attacks have been applied on the watermarked images like addition of text to the image, cropping some portion of the image, exchanging different image portions, removing some detailed sensitive information of the image etc. The tamper detection results along with recovery on pixel basis are tabulated in Tables 4, 5 and 6 for natural images, texture images and remote sensing images respectively.

Table 5 Results of Tamper Detection and Recovery for Texture Images

Cover Image	No. of Detected Pixels	Total Pixels Altered	Detection Rate
Brick Wall	2073	2115	98.01
Bark	1273	1350	94.64
Plastic Bubbles	902	226	92.47

Table 6 Results of Tamper Detection and Recovery for Remote Sensing Images

Cover Image	No. of Detected Pixels	Total Pixels Altered	Detection Rate
Satellite Image 1	550	560	98.21
Satellite Image 2	924	978	94.47
Satellite Image 3	700	753	92.96

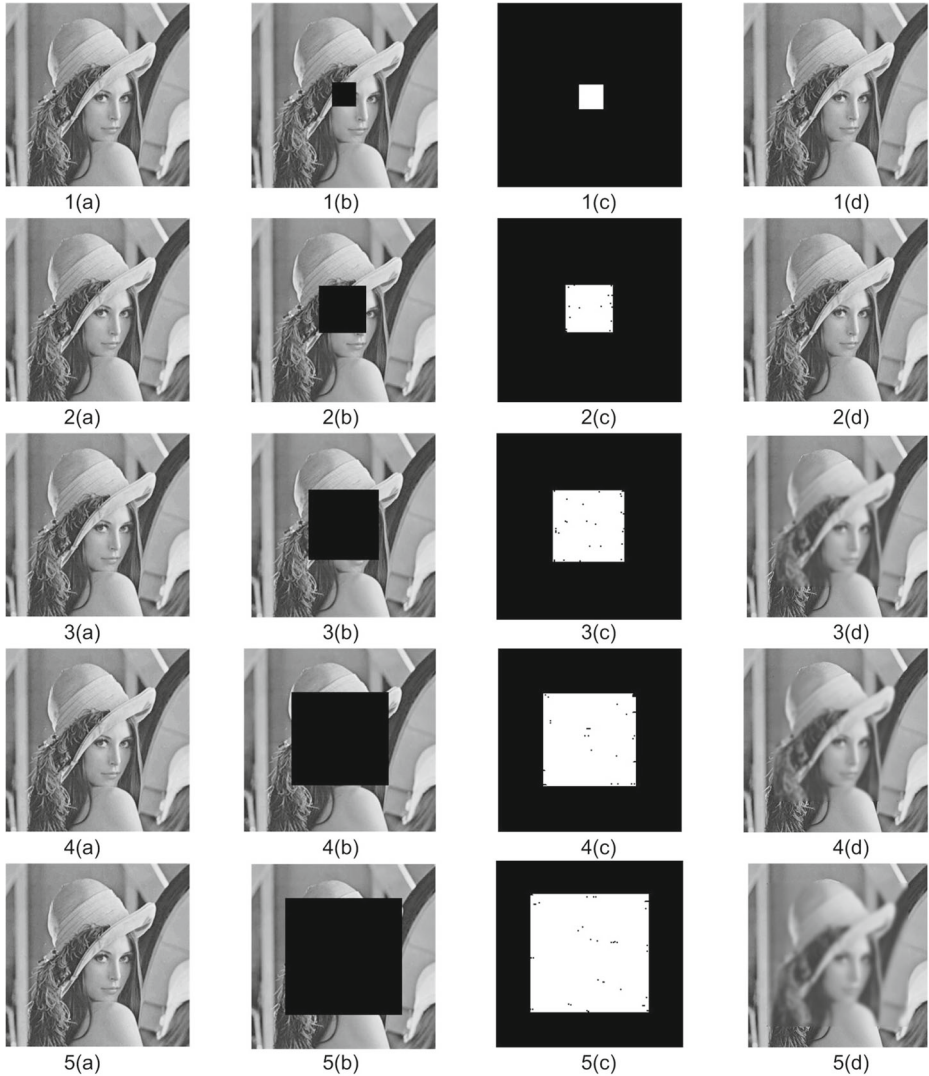


Fig. 10 Recovery for different Tampering Ratios(TR) (a)10 % (b) 20 % (c)30 % (d)40 % (d)50 %

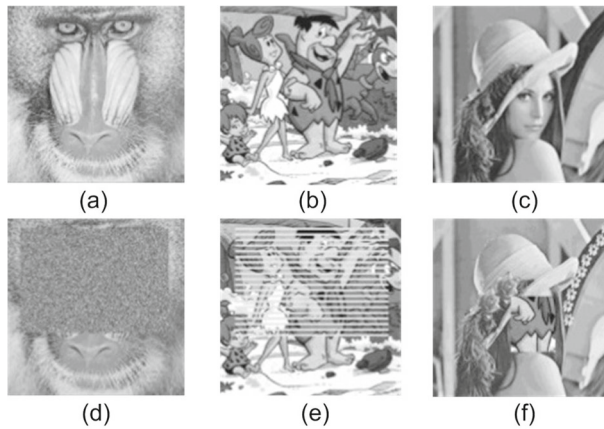


Fig. 11 (a)–(c)Watermarked Image,(d)–(f)Tampered Image

To further demonstrate the efficacy of the proposed scheme for recovery, the cover image is tampered with varying tampering ratios (TR) as shown in Fig. 10 for one of the test cover lena images. The scheme is able to recover the lost content even when major portions of the image are lost although the visual quality deteriorates with increasing tampering ratio.

To illustrate the efficacy of the proposed scheme over other state of the art algorithms, following tests were performed as depicted in Fig. 11. The details of the tests are as follows:

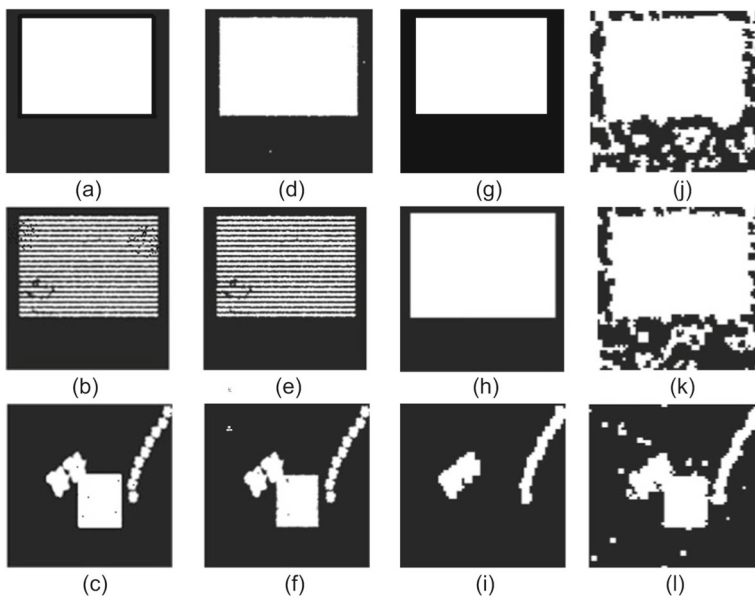


Fig. 12 Tamper Detection Results:(a)–(c)Proposed method, (d)–(f)[11], (g)–(i) [43],(j)–(l)[21]

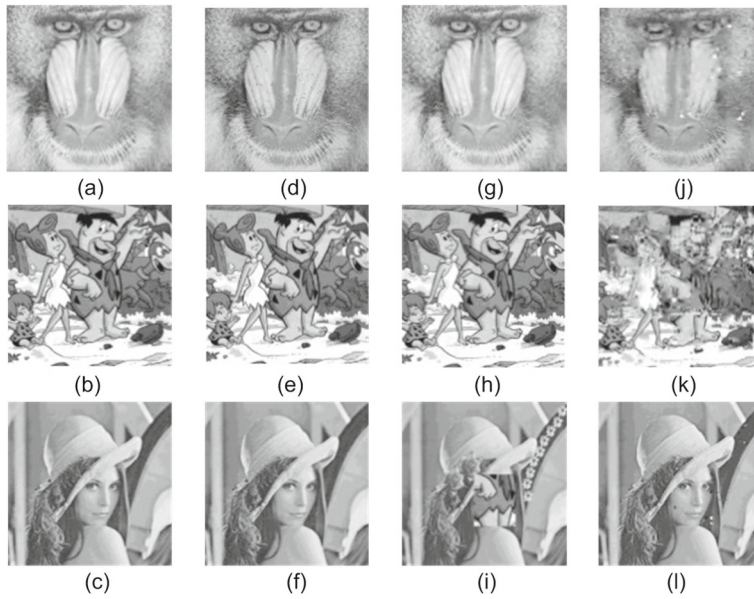


Fig. 13 Recovery Results:(a)–(c)Proposed method, (d)–(f)[11], (g)–(i) [43],(j)–(l)[21]

Table 7 Comparative Performance based on PFA

Tests	Tampering Ratio	our	[30]	[11]	[43]	[21]	[8]	[40]	[27]	[35]
1	48.07	0	0.3	0.01	0.00	0.93	0	0.1	0.28	0.05
2	26.48	0	0.05	1.50	0.00	2.34	0	0.11	0.34	0.07
3	13.58	0	0.01	1.31	57.56	1.48	0.01	0.09	0.36	0.08

Table 8 Comparative Performance based on PFR

Tests	Tampering Ratio	our	[30]	[11]	[43]	[21]	[8]	[40]	[27]	[35]
1	48.07	0.01	0	0.36	4.62	32.94	1.0	0.01	0.23	0
2	26.48	0.01	0.01	3.14	37.03	53.95	1.0	0.001	0.20	0
3	13.58	0.02	0.03	0.16	2.20	4.89	0.85	0	0.15	0

Table 9 Comparative Performance based on PSNR

Tests	Tampering Ratio	our	[30]	[11]	[43]	[21]	[8]	[40]	[27]	[35]
1	48.07	16.01	18.2	24.79	23.95	20.74	18	17.5	12	12
2	26.48	21.08	20	28.72	21.78	16.13	19.5	19.0	13.7	15.9
3	13.58	22.02	20.2	36.81	18.31	32.42	21.5	20.0	16	18.7

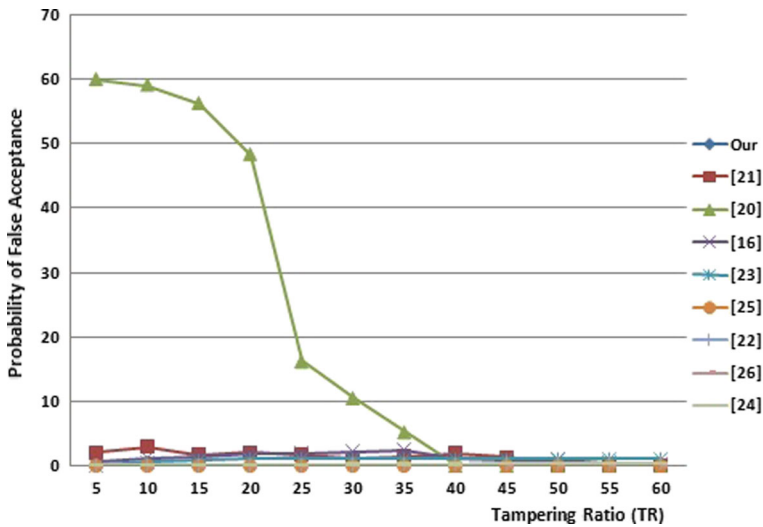


Fig. 14 Variation of Probability of False Acceptance(PFA) with Tampering Ratio(TR)

Test1: A rectangular portion(300 × 420) of the watermarked baboon image is tampered [11(d)].

Test2: Watermarked Flinstones image is tampered by drawing 20 rectangles, filled with a random integer $\in [200, 223]$ [11(e)].

Test3: The watermarked Lena image is tampered by pasting portion of the watermarked Flinstones image on it(collage attack) besides placing few small flowers and two large ones on it [11(f)].

The tamper detection efficacy of the proposed scheme is found to be quite good as pixel level authentication is done to chalk out the tampered pixels. Authentication bit for

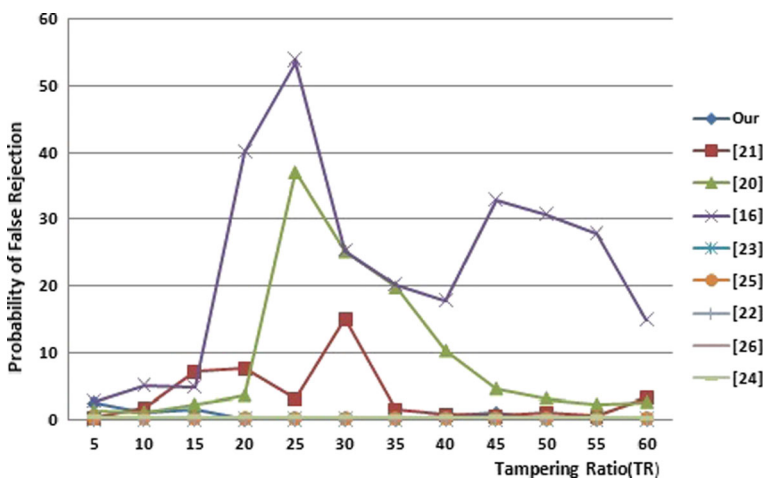


Fig. 15 Variation of Probability of False Rejection(PFR) with Tampering Ratio(TR)

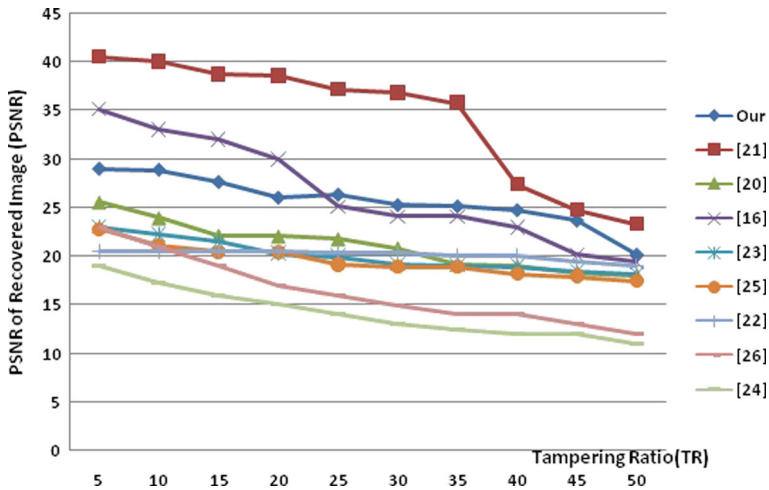


Fig. 16 Variation of PSNR of Recovered Image with Tampering Ratio(TR)

each pixel is generated based on pixel intensity value, its location co-ordinates and boundary intersecting neighbors as shown in Fig. 4. The recovery of the altered regions is done via extracting the recovery information bits from the corresponding mapped block and rebuilding the lost content from it. The comparative results for accuracy of localization and recovery are presented in Figs. 12 and 13. Schemes [21] and [11] were able to localize the collage attack in test 3 approximately. However, [43] was not even able to detect the collaged blocks.

The probability of false acceptance (PFA), probability of false rejection (PFR) and PSNR metric values are evaluated for variable degree of alterations on the cover test images. Comparative results are tabulated in Tables 7, 8 and 9 and presented graphically in Figs. 14, 15 and 16. The PFR and PFA values of the proposed scheme are quite close to the ideal value zero in most of the analytical analysis. The imperceptibility of the recovered image decreases with the increasing tampering ratios.

3.2 Robustness test results

The proposed scheme provides the feature of copyright protection too. Different binary logos have been used as test watermarks. Some are shown in Fig. 17. The robustness of the scheme is tested against comprehensive set of image processing attacks. Some are enlisted

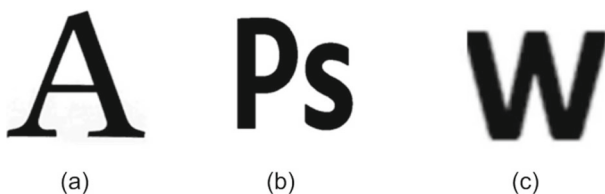






















Fig. 17 Copyright Logos

Table 10 Robustness test results

Attacked Watermarked image	Attack Types with parameters	Extracted Watermark	NCC value
	Salt & Pepper Noise (var=0.05)		0.98
	Histogram Equalization		0.96
	Rotation(60)		0.89
	Speckle Noise (var=0.05)		0.91
	Motion Blur		0.83

in Tables 10 and 11. The similarity of the extracted watermark with respect to the original one has been evaluated using the normalized cross correlation (NCC) metric value. The comparative results with other existing state of art approaches are tabulated in Tables 12 and 13. The evaluation of the extracted watermark has been further extended by using the

Table 11 Robustness test results

Attacked Watermarked image	Attack Types with parameters	Extracted Watermark	NCC value
	Weiner Filter		0.76
	Resizing 512 → 128 → 512		0.85
	Average Filter		0.88
	Unsharp Masking		0.90
	Median Filter		0.86

various available error metrics. It is based on mutual relation between pixels, their values and their locations respectively.

Let us assume that W_{emb} is the embedded watermark and W_{ext} is the extracted binary watermark. The total number of true positive, false positive, true negative and false

Table 12 Comparative Performance based on NCC

Attacks	our	[32]	[37]	[14]	[15]	[10]	[24]	[41]	[38]
Rotation	0.89	0.63	0.92	0	0	0	0.83	0.98	0.98
Noise Addition	0.98	0.75	0.99	0.82	0.87	0.89	0.76	0.98	0.95
Median Filtering	0.86	0.89	0.92	0.85	0.82	0.75	0.93	0.98	0.98
Blurring	0.88	0.77	0.86	0.79	0.78	0.79	0.92	0.98	0.99
Sharpening	0.96	0.81	0.98	0.82	0.93	0.89	0.81	0.98	0.99
Resizing	0.85	0.98	0.93	0.91	0.90	1	0.88	0.98	0.98

negative pixels with respect to W_{emb} and W_{ext} are indicated by N_{TP} , N_{FP} , N_{TN} and N_{FN} respectively [19, 42]. Some of the objective error metrics are defined as follows:

3.2.1 Precision

$$Precision = \frac{N_{TP}}{N_{TP} + N_{FP}} \tag{13}$$

For identical images value of Precision will be 1.

3.2.2 Recall/Sensitivity

$$Recall = \frac{N_{TP}}{N_{TP} + N_{FN}} \tag{14}$$

For identical images the value of recall will be 1.

3.2.3 F-Measure

$$FM = \frac{2 \times Recall \times Precision}{Recall + Precision} \tag{15}$$

For identical images the value of F-Measure will be 1.

Table 13 Comparison with other methods

Parameters	our	[8]	[40]	[35]	[27]	[30]
Security	High	Low	Low	Low	High	High
Localization Accuracy	High	Low	High	High	Medium	Medium
Recovery Quality	High	Medium	Medium	Medium	Medium	Medium
Robustness to JPEG	High	Low	Low	Low	Medium	High
Robustness to Gaussian	High	Low	Low	Medium	Low	High
Robustness to Rotation	High	Low	Low	Medium	Low	High

Table 14 Various Objective Measures for Extracted Binary Watermark against Various Attacks

Attacks	Objective measures	Precision	Recall	F-measure	SSIM	Specificity	BCR	BER	Geometric Accuracy	NRM	DRD	MPM (x1000)
Salt & Pepper Noise		0.9807	0.9756	97.42	0.9672	0.9692	0.9823	0.1094	0.830	0.0981	0.1966	893
Hist Eq.		0.8827	0.9126	95.12	0.9591	0.8915	0.8974	0.1594	0.897	0.1561	0.1939	816
Rotation		0.6677	0.8834	85.32	0.8569	0.7153	0.7819	0.2940	0.7543	0.3945	0.2871	501
Speckle Noise		0.7394	0.8936	87.52	0.8641	0.7955	0.7873	0.2291	0.7969	0.3297	0.2274	619
Motion Blur		0.7036	0.7247	84.42	0.8175	0.7736	0.7771	0.3964	0.7194	0.3359	0.3610	539
Weiner Filter		0.6237	0.7486	81.84	0.7402	0.7127	0.7962	0.3610	0.7910	0.3501	0.4820	489
Resizing		0.7496	0.7946	80.18	0.7907	0.7739	0.7583	0.2804	0.7631	0.3063	0.3492	703
Average Filter		0.7530	0.7949	82.86	0.8063	0.7946	0.8296	0.2075	0.8040	0.2595	0.2795	731
Unsharp Masking		0.8593	0.9074	90.73	0.9198	0.8983	0.8252	0.1793	0.8582	0.2069	0.1852	802
Median Filter		0.8183	0.8747	85.66	0.8280	0.8915	0.8811	0.1972	0.813	0.2684	0.2974	761
JPEG Compression		0.6749	0.7048	81.13	0.8379	0.8184	0.8709	0.2789	0.8163	0.3178	0.2804	691
Cropping		0.7456	0.7381	81.54	0.7913	0.7754	0.3682	0.7821	0.897	0.2699	0.2890	472
Laplacian Filter		0.7494	0.8671	87.84	0.8621	0.8071	0.7793	0.2904	0.891	0.2190	0.2395	673
Gaussian Noise		0.7183	0.8370	83.71	0.8591	0.8063	0.7961	0.2854	0.727	0.2842	0.2745	892

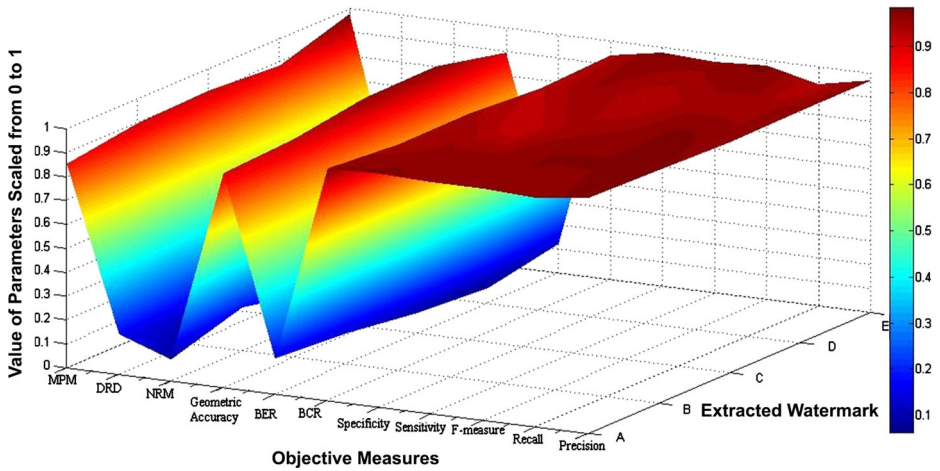


Fig. 18 Objective Parameters for Extracted Watermark Against Salt & Pepper Noise Attack

3.2.4 Structural Similarity Index (SSIM)

SSIM is a Human Visual System (HVS) based evaluation metric used to measure image quality.

$$SSIM(x, y) = \frac{(2\mu_x\mu_y + c_1)(2\sigma_{xy} + c_2)}{(\mu_x^2 + \mu_y^2 + c_1)(\sigma_x^2 + \sigma_y^2 + c_1)} \tag{16}$$

Where $\mu_x, \mu_y, \sigma_x^2, \sigma_y^2$ and σ_{xy} are the average, variance and covariance for x and y respectively. The SSIM index value ranges from -1 and 1, with value 1 is case of two identical data sets.

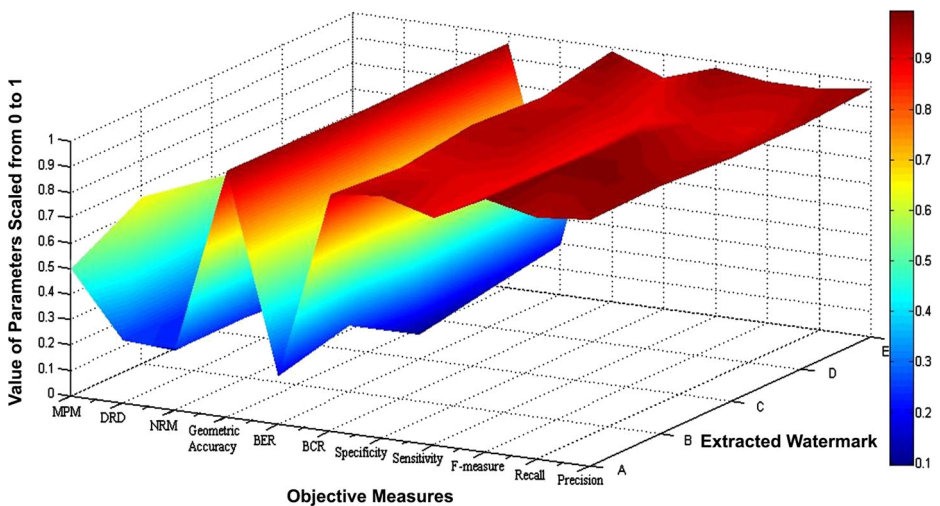


Fig. 19 Objective Parameters for Extracted Watermark Against Histogram Equalization Attack

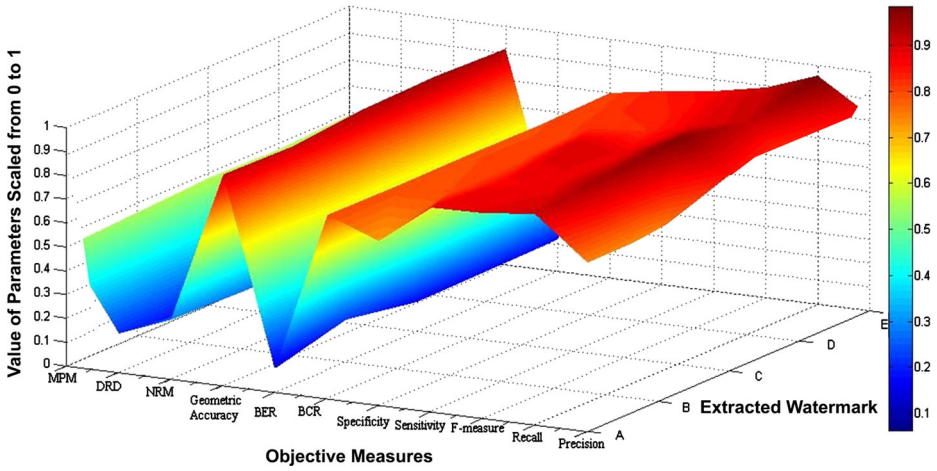


Fig. 20 Objective Parameters for Extracted Watermark Against Rotation Attack

3.2.5 *Specificity*

$$Specificity = \frac{N_{TN}}{N_{TN} + N_{FP}} \tag{17}$$

For identical images value of Specificity will be 1.

3.2.6 *Balanced Classification Rate (BCR)/Area Under the Curve (AUC)*

$$BCR = 0.5 \times (Specificity + Sensitivity) \tag{18}$$

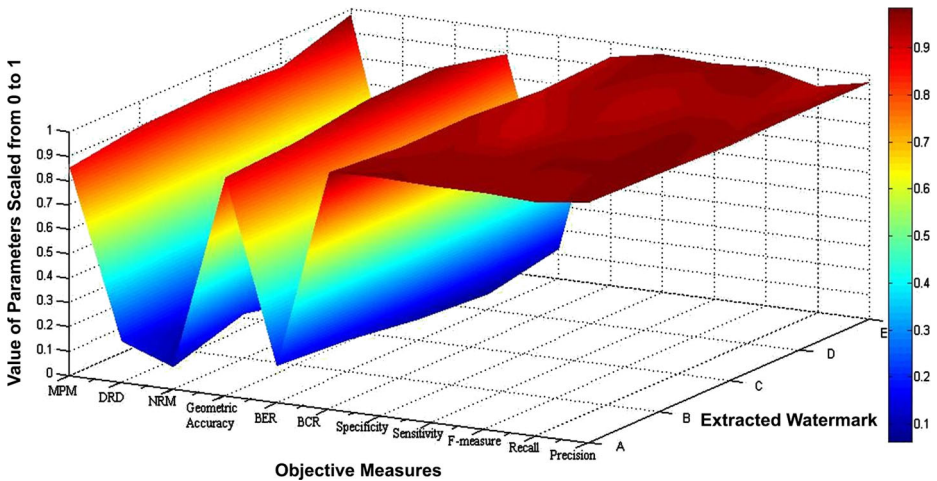


Fig. 21 Objective Parameters for Extracted Watermark Against Speckle Noise Attack

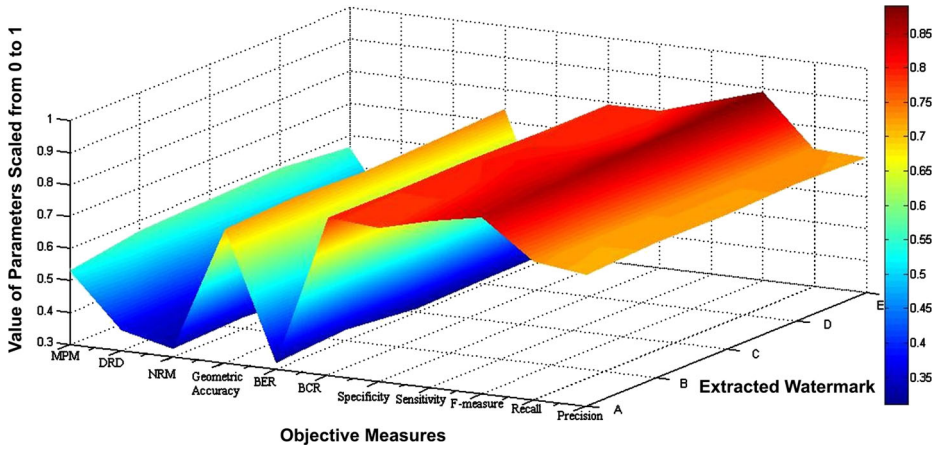


Fig. 22 Objective Parameters for Extracted Watermark Against Motion Blur Attack

For identical images the value of BCR/AUC will be 1.

3.2.7 Balanced Error Rate (BER)

$$BER = 100 \times (1 - BCR) \tag{19}$$

For identical images the value of BER will be 0.

3.2.8 Negative Rate Matrix (NRM)

The NRM is based on the pixel wise mismatch between the *I* and *G*.

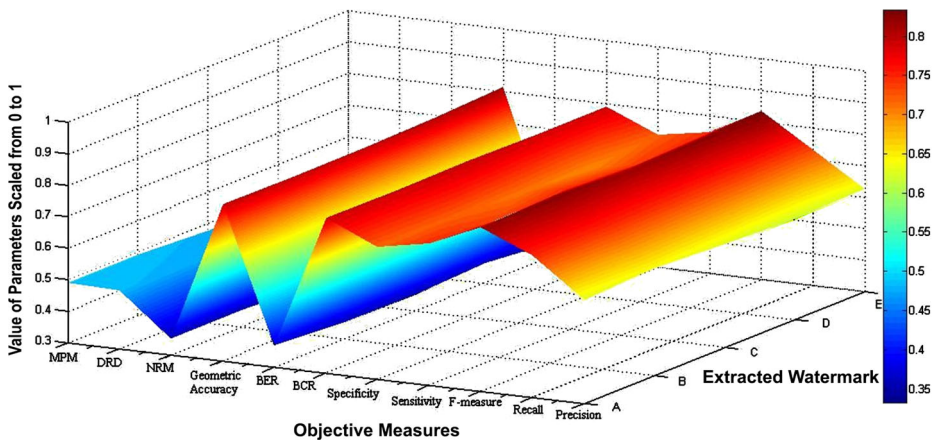


Fig. 23 Objective Parameters for Extracted Watermark Against Weiner Filter Attack

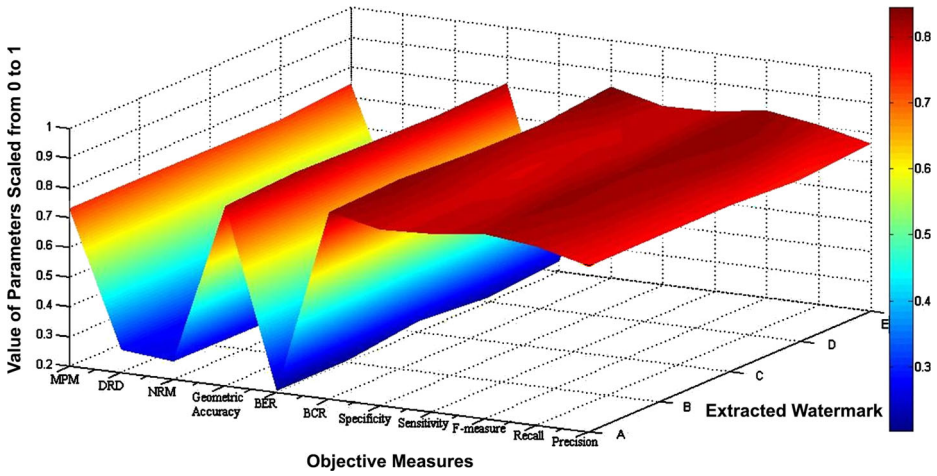


Fig. 24 Objective Parameters for Extracted Watermark Against Average Attack

$$NRM = \frac{NR_{fn} + NR_{fp}}{2} \tag{20}$$

where

$$NR_{fn} = \frac{N_{FN}}{N_{FN} + N_{TP}} \tag{21}$$

$$NR_{fp} = \frac{N_{FP}}{N_{FP} + N_{TN}} \tag{22}$$

For identical images value of NRM will be 0.

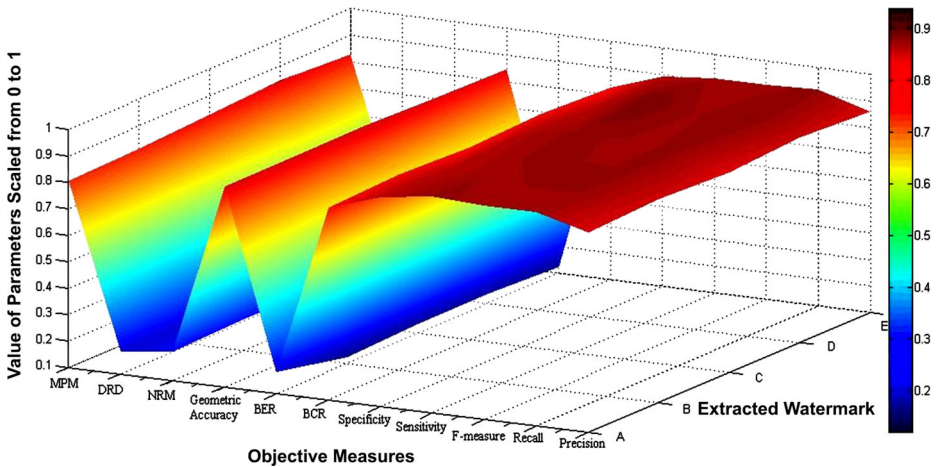


Fig. 25 Objective Parameters for Extracted Watermark Against Unsharp Masking Attack

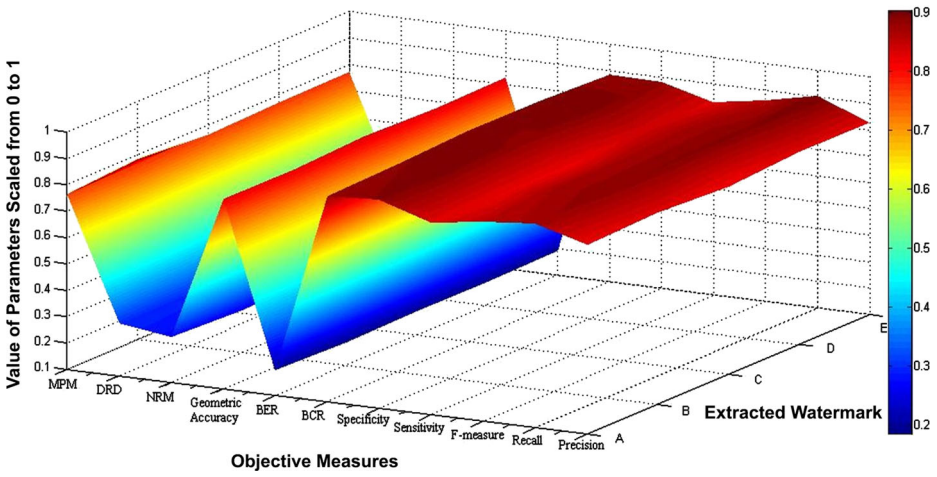


Fig. 26 Objective Parameters for Extracted Watermark Against Median Fiter Attack

3.2.9 Distance-Reciprocal Distortion Measure (DRDM)

Let W_m is the weight matrix and i_c and j_c are the center pixel.

$$W_m(i, j) = \begin{cases} 0, & \text{if } i_c = j_c \\ \frac{1}{\sqrt{(i-i_c)^2+(j-j_c)^2}}, & \text{otherwise} \end{cases} \tag{23}$$

This matrix is Normalized by.

$$W_{Nm}(i, j) = \frac{W_m(i, j)}{\sum_{i=1}^m \sum_{j=1}^m W_m(i, j)} \tag{24}$$

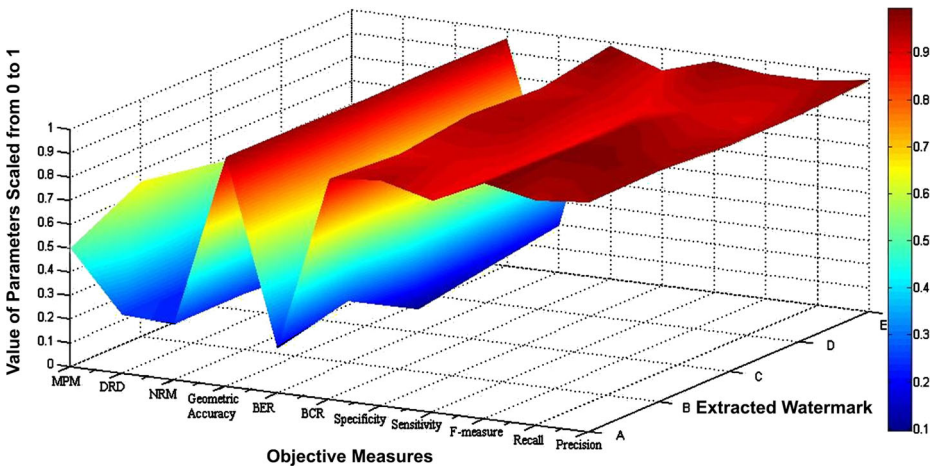


Fig. 27 Objective Parameters for Extracted Watermark Against JPEG Compression Attack

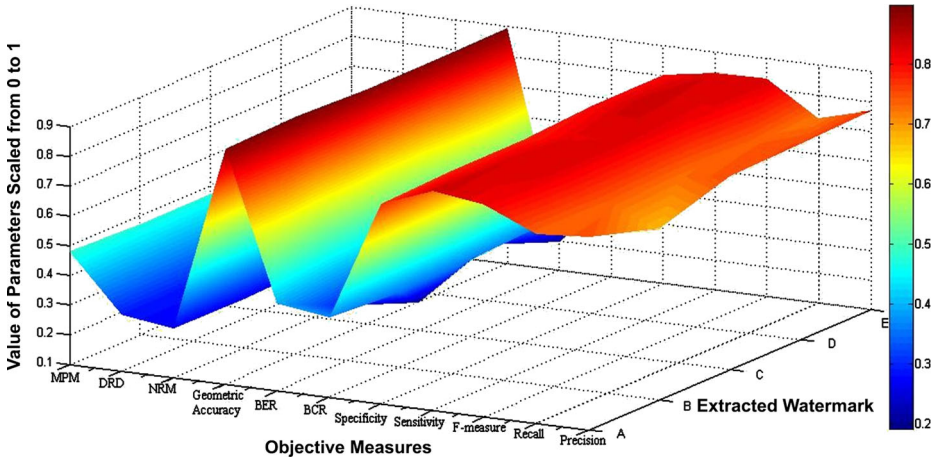


Fig. 28 Objective Parameters for Extracted Watermark Against Cropping Attack

Now

$$DRD_k = \sum_{i,j} [D_k(i, j) \times W_{Nm}(i, j)] \tag{25}$$

Where D_k is given by $(B_k(i, j) - g[(x, y)_k])$. Thus DRD_k equals to the weighted sum of the pixels in the block B_k of the original image.

$$DRD = \frac{\sum_{k=1}^s DRD_k}{NUBN} \tag{26}$$

Where NUBN is the nonuniform blocks in $F(x, y)$.

For identical Image DRDM will be 0.

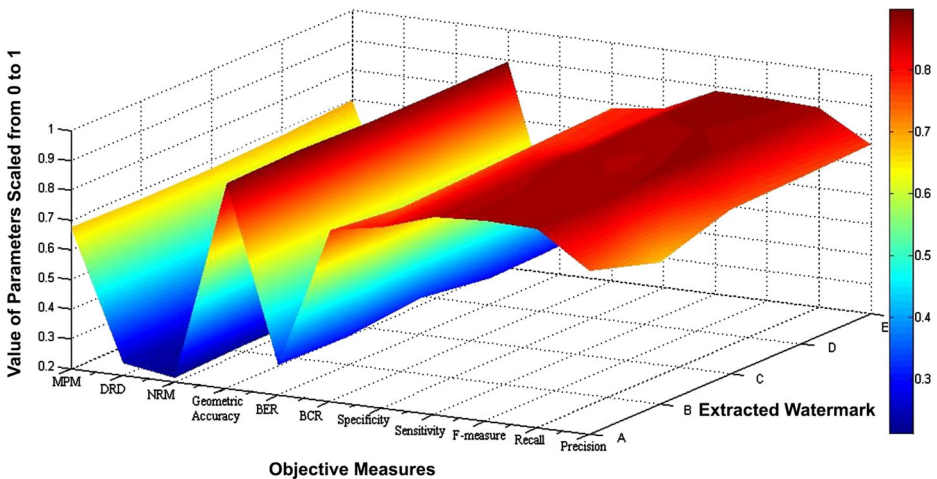


Fig. 29 Objective Parameters for Extracted Watermark Against Laplacian Filter Attack

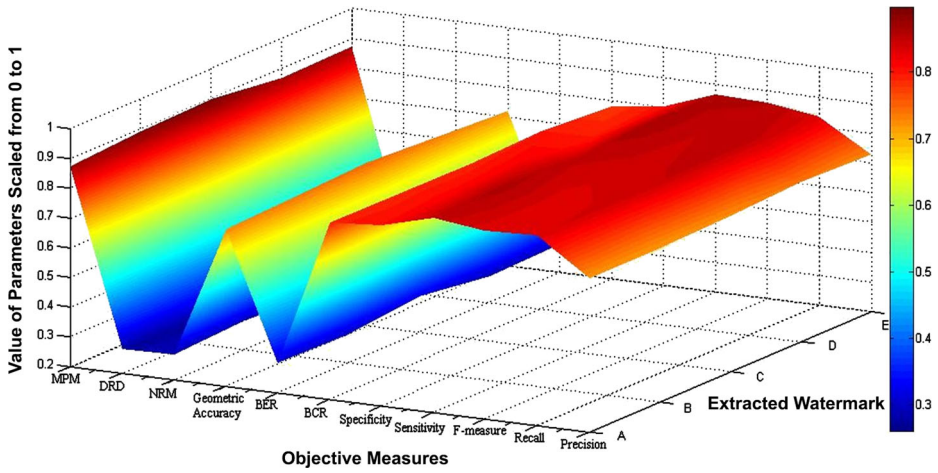


Fig. 30 Objective Parameters for Extracted Watermark Against Gaussian Noise Attack

3.2.10 Misclassification Penalty Metric (MPM)

$$MP = \frac{1}{2}(MP_{fn} + MP_{fp}) \tag{27}$$

where

$$MP_{fn} = \frac{\sum_{j=1}^{N_{fn}} d_{fn}^j}{D} \tag{28}$$

Represents the sum of distances of all false negatives.

$$MP_{fp} = \frac{\sum_{j=1}^{N_{fp}} d_{fp}^j}{D} \tag{29}$$

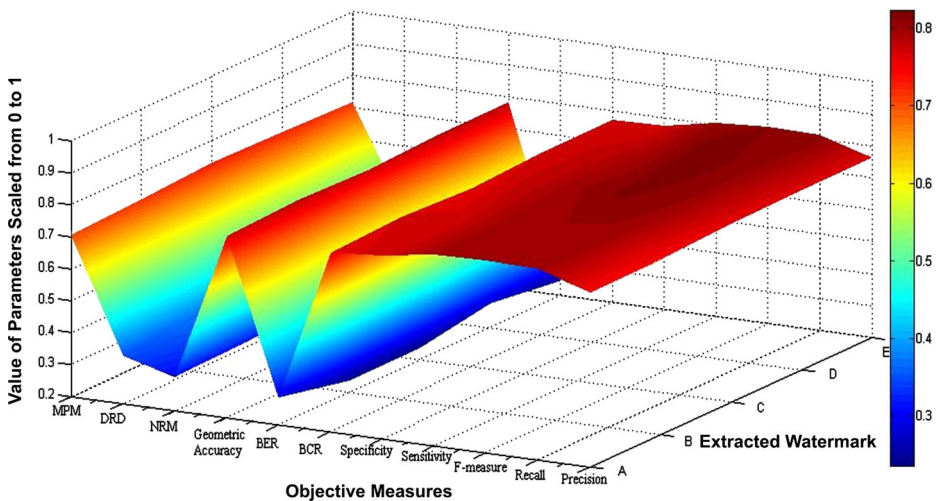


Fig. 31 Objective Parameters for Extracted Watermark Against Resizing Attack

Represents the sum of distances of all false positives.

For identical images the value of MPM will be 100.

The objective parameters for the extracted watermark tested against the comprehensive set of attacks has been tabulated in Table 14 and their respective 3D graphs has been depicted in Figs. 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30 and 31 respectively.

4 Conclusion and future scope

A dual watermarking scheme incorporating both features of ownership assertion as well as integrity check has been proposed here. Recovery information of each 2×2 sized non-overlapping block was reduced to just eight bits which were further encoded to obtain only four bits and embedded in the mapping block of the cover image. The reduction in storage requirements for recovery bits was utilized for efficiently embedding the copyright information, thus adding the feature of robustness in the scheme. The scheme performed well against comprehensive set of attacks like noises, filtering, histogram equalization, rotation, jpeg compression etc. The pixel level tamper detection of the scheme could chalk out the altered areas accurately for all the three major categories of natural, texture as well as satellite images. The random chaotic mapping of blocks enhanced the efficacy of the scheme against tampers even upto 50 %. Evaluation of extracted watermark logo via variety of suitable error metrics further added to its advantages, with satisfiable PSNR values for both watermarked as well as recovered images.

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