# **Self-Adaptation in Collective Adaptive Systems**

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**Abstract** An adaptive system is currently on spot: collective adaptive system (CAS), which is inspired by the socio-technical systems. CASs are characterized by a high degree of adaptation, giving them resilience in the face of perturbations. In CASs, highest degree of adaptation is *self-adaptation*. The overarching goal of CAS is to realize systems that are tightly entangled with humans and social structures. Meeting this grand challenge of CASs requires a fundamental approach to the notion of self-adaptation. To this end, taking advantage of the categorical approach we establish, in this paper, a firm formal basis for modeling self-adaptation in CASs.

**Keywords** Adaptedness · Categorical approach · Collective adaptive system · Self-adaptation · Self-adaptive trait

# **1 Introduction**

The socio-technical structure of our community increasingly depends on systems, which are built as a collection of varied agents and are tightly coupled with humans and social interrelations. Their agents more and more need to be able to develop, cooperate and work all by themselves as a part of an artificial community. Hence, for such collective adaptive systems (CASs), one of major challenges is how to support self-adaptation in the face of changing interactions [\[7,](#page-7-0) [8\]](#page-7-1). In other words, how does a CAS understand

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relevant interrelations and then self-adapt to become better able to live in its interactions?

Dealing with this grand challenge of CASs requires a well-founded modeling and in-depth analysis on the notion of self-adaptation. With this aim, we develop a firm formal approach in which a collective of entities is able to selfadapt its configuration and self-optimize its performance in the face of changing interactions [\[9\]](#page-7-2).

CASs focus on self-adaptation in preference to build systems. In this view, we see that rigorously approaching to self-adaptation requests fundamental research in all aspects of the self-adaptation. As a novel development for the self-adaptation, we consider to formalize aspects of the self-adaptation taking advantage of categorical language, whose content is presented in this paper.

# **2 Outline**

The paper is a reference material for readers who already have a basic understanding of CAS and are now ready to know the novel approach for formalizing self-adaptation in CAS using categorical language.

Formalization is presented in a straightforward fashion by discussing in detail the necessary components and briefly touching on the more advanced components. Several notes explaining how to use the formal aspects, including justifications needed in order to achieve the particular results, are presented.

We attempt to make the presentation as self-contained as possible, although familiarity with the notion of selfadaptation in CAS is assumed. Acquaintance with the algebra and the associated notion of categorical language is useful for recognizing the results, but is almost everywhere not strictly necessary.

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The rest of this paper is organized as follows: Sections [3](#page-1-0) and [4](#page-1-1) present the notions of collective adaptive systems (CASs) and self-adaptation, respectively. In Section [5,](#page-1-2) formal aspects of self-adaptation in CASs are developed in detail. In Section [6,](#page-4-0) we briefly discuss our development. Finally, a short summary is given in Section [7.](#page-5-0)

## <span id="page-1-0"></span>**3 Collective adaptive systems (CASs)**

We define collective adaptive systems (CASs) as the following among various definitions that have been offered by different researchers:

**Definition 1** CASs are systems that consist of a collective of heterogeneous components, often called agents, that interact and adapt or learn.

Hence, CASs are characterized by a high degree of adaptation, giving them resilience in the face of perturbations. We see that, in CASs, highest degree of adaptation is *selfadaptation* and we are interested in approaches to this characteristic of CASs.

This definition is concerned with three major factors of CAS:

- *A collective of heterogeneous agents* is large enough to build up systems that are tightly entangled with humans and social structures. Their agents increasingly need to be able to evolve, collaborate and function as a part of an artificial society. More importantly, the agents interact dynamically, and their interactions are either physical or involving the exchange of information.
- *Interactions* are rich, non-linear and primarily, but not exclusively, with immediate neighbors. They can be recurrent, i.e. any interaction can feed back onto itself directly or after a number of intervening stages. CASs are dynamic networks of interactions
- *Self-adaptation* is the self-evolutionary process whereby a CAS becomes better able to live in its interactions.

#### <span id="page-1-1"></span>**4 Self-adaptation**

An interesting aspect of CASs is that it makes distinction between self-adaptation (i.e. system-driven personalization and modifications) and self-adaptability (i.e. user-driven personalization and modifications). *Self-adaptedness* is the state of being self-adapted, i.e. the degree to which a CAS is able to live and reproduce in a given set of interactions. A *self-adaptive trait* is an aspect of the developmental pattern of the CAS which enables or enhances the probability of that CAS surviving and reproducing.

Formally, let self-\* be the set of self- $\dot{\ }$ 's. Each self- to be an element in self-\* is called a *self-\* facet* [\[6\]](#page-7-3). That is,

$$
self - * = \{ self - \_\mid self - \_\text{is a self} - * facet \} \tag{1}
$$

Thus, self-adaptation is a facet of self-\*, that is, selfadaptation is a member of self-\*. In other words, using categorical language, this is written as  $1 \xrightarrow{\text{self-adaptation}}$  $\degree$ self-\*. CASs are self-adaptive in that the individual and collective behavior mutate and self-organize corresponding to interactions. Self-adaptation indicates that CAS is a mimicry of socio-technical systems.

#### <span id="page-1-2"></span>**5 Self-adaptation in CASs**

Self-adaptation is achieved when CASs are constructed. In this way, we start with considering CASs by categorical approach in this paper. CASs we want to abstract are intuitionally multiple partial morphism applications, such as

<span id="page-1-3"></span>
$$
s_0 \xrightarrow{\sigma_0} s_1 \xrightarrow{\sigma_1} s_2 \xrightarrow{\sigma_2} s_3 \cdots \tag{2}
$$

where

- All indexes  $i \in T$  (=  $\mathbb{N} \cup \{0\}$ ) refer to times,
- *s* is a self-adaptedness representing a state of CAS in the set, denoted by  $CAS$ , of states.  $s_i$  is the state  $s$  at the time *i*,
- *σ* is an interaction in the set, denoted by *Inter*, of interactions.  $\sigma_i$  is interaction  $\sigma$  at the time *i*, which makes change of the state  $s_i$  to become  $s_{i+1}$ .

The representation of Eq. [2](#page-1-3) can be understood as

... 
$$
s_2(s_1(s_0))) = ... s_2(s_1(\sigma_0)) = ... s_2(\sigma_1) = ... \sigma_2
$$
  
(3)

<span id="page-1-4"></span>The self-adaptation in Eq. [2](#page-1-3) can also be descriptively drawn as

$$
s_0() \sigma_0 \sigma_1 \sigma_2 \cdots \longrightarrow s_1(\sigma_0) \sigma_1 \sigma_2 \cdots \longrightarrow \sigma_0 s_2(\sigma_1) \sigma_2 \cdots
$$
\n(4)

<span id="page-1-5"></span>or, in another representation

$$
\xrightarrow{s_0} \sigma_0 \sigma_1 \sigma_2 \cdots \longrightarrow \sigma_0 \xrightarrow{s_1} \sigma_1 \sigma_2 \cdots \longrightarrow \sigma_0 \sigma_1 \xrightarrow{s_2} \sigma_2 \cdots
$$
\n(5)

Note that in Eqs. [4](#page-1-4) and [5,](#page-1-5) we want to represent the abovementioned self-adaptation of CAS based on interaction where each step of the self-adaptation is an application of unary partial morphism  $1 \frac{s_i}{s_i}$   $\geq$  CAS on  $1 \frac{\sigma_{i-1}}{s_i}$  Inter for all *i* in *T* .

The self-adaptation, in Eqs. [4](#page-1-4) and [5,](#page-1-5) describes selfevolutionary process of CASs including the self-adaptation steps to change *configurations* of the system.

**Definition 2** (**Configuration of CAS**) We define a configuration of CAS at a self-adaptation step to be a member of the set  $CAS \times Inter^{i \in T}$ , where *Inter*<sup>*i*∈*T*</sup> stands for

$$
Inter^{i \in T} = \underbrace{Inter \times Inter \times \dots \times Inter}_{itimes}
$$
 (6)

As we know, when we combine sets by multiplication, each set is a *factor* and the resulting set is the *product*. Hence, each set *Inter* is a factor of the resulting set *Inter*<sup>*i*∈*T*</sup>, *CAS* and *Inter*<sup>*i*∈*T*</sup> are two factors of the set  $CAS \times Inter^{i \in T}$ . The definition of multiplication of sets is very natural. Just remember that a product is not just a set, but a set with two morphisms as in

When i=2 then *Inter*<sup>2</sup> = {*< σ*<sub>1</sub>, *σ*<sub>2</sub> > |*σ*<sub>1</sub>, *σ*<sub>2</sub> ∈ *Inter*} is obtained by



• When i=3 then  $Inter^3 = \{ \langle \langle \sigma_1, \sigma_2 \rangle, \sigma_3 \rangle \}$  $|\sigma_1, \sigma_2, \sigma_3 \in Inter\}$  is obtained by



Specially, we have

- If i=0 then  $Inter^0 = \{\}$
- If i=1 then  $Inter^1 = Inter = {\sigma_1 | \sigma_1 \in Inter}$

We hope that these diagrams seem suggestive to readers. Our aim is to learn to use them as precise tools of understanding and reasoning, not merely as intuitive guides.

The self-adaptation paradigm, which we want to approach to, is based on mapping a configuration to another. Let us see the following examples

<span id="page-2-2"></span>**Example 1:** A specific self-adaptation can be specified by the following morphism:

$$
Self-A: (CAS \times Inter) \longrightarrow CAS \tag{7}
$$

(i.e., *Self* − *A* :  $(CAS \times Inter^1)$  →  $(CAS \times Inter^0)$ <br>or denoted by  $Set - ACAS \times Inter CAS$ ) or denoted by *Self* <sup>−</sup> *A(CAS* <sup>×</sup> *Inter, CAS)*)

<span id="page-2-3"></span>**Example 2:** Another specific self-adaptation can be specified by

$$
Self-A: (CAS \times Inter) \longrightarrow (CAS \times Inter) \tag{8}
$$

(i.e., *Self* − *A* :  $(CAS \times Inter^1)$  →  $(CAS \times Inter^1)$ )<br>or denoted by  $Set - ACAS \times Inter CAS \times Inter)$ or denoted by *Self* <sup>−</sup> *A(CAS* <sup>×</sup> *Inter, CAS* <sup>×</sup> *Inter)*) **Example 3:** Again, we can also specify another specific self-adaptation as

<span id="page-2-4"></span>
$$
Self-A: (CAS \times Inter^n) \longrightarrow (CAS \times Inter) \qquad (9)
$$

 $(i.e., Self - A : (CAS \times Inter^n) \longrightarrow (CAS \times Inter^1)$ or denoted by *Self* <sup>−</sup> *A(CAS* <sup>×</sup> *Intern, CAS* <sup>×</sup> *Inter)* and we can, in the completely same way, do for any other specific self-adaptation.

**Definition 3** (**Self-adaptation**) Generally, an arbitrary selfadaptation is specified by

$$
Self-A: (CAS \times Inter^{i \in T}) \longrightarrow (CAS \times Inter^{j \in T}) \text{ (10)}
$$

<span id="page-2-0"></span>Now, let us investigate the following corollaries.

**Corollary 1** (**Self-adaptation in CASs**) *Morphism Self-A in* Eq. [10](#page-2-0) *defines self-adaptation in* CASs

*Proof* This stems from Eq. [10](#page-2-0) and the fact that selfadaptation emerges through interactions in CASs.  $\Box$ 

Morphism *Self-A* is called a self-adaptation. Morphism *Self-A* in Eq. [10](#page-2-0) defines a set  ${Self - A_{k \in \mathbb{N}}}$  of mappings such that

<span id="page-2-1"></span>
$$
Self-A_{k\in\mathbb{N}} : (CAS \times Inter^{i\in T}) \longrightarrow (CAS \times Inter^{j\in T})
$$
\n(11)

**Corollary 2** (**Self-adaptive traits in CASs**) *Set* {*Self*− *<sup>A</sup>k*∈N} *in* Eq. [11](#page-2-1) *defines self-adaptive traits in* CASs*. Each mapping Self-Ak*∈<sup>N</sup> *is called a self-adaptive trait.*

*Proof* This originates as the result of the truth that selfadaptation is the set of self-adaptive traits.  $\Box$ 

For further well-founded investigation, we can construct a category of the sets of CAS configurations and establish *Self-A*-algebras as described in the following corollaries.

**Corollary 3** (**Category of the sets of CAS configurations**) *Sets of* CAS *configurations as in definition 2 define a category.*

*Proof* In fact, let **Cat(CAS)** be such a category of the sets of CAS configurations, whose structure is constructed as follows:

• Each set of configurations  $CAS \times Inter^{i \in T}$  defines an object.

That is,  $Obj(Cat(CAS)) = \{CAS \times Inter^{i \in T}\}.$ 

• Each *Self* <sup>−</sup> *A* defines a morphism. That is,  $Arc(Cat(CAS)) = {Self - A : (CAS \times A)$ *Inter*<sup>*i*∈*T*</sup>)(*CAS* × *Inter*<sup>*j*∈*T*</sup>)}.

It is easy to check that identity in Eq. [30](#page-6-0) and associativity in Eq. [31](#page-6-1) on all *Self* <sup>−</sup> *A*s are satisfied.  $\mathsf{\Pi}$ 

**Corollary 4** (*Self-A***-algebra(CAS)**) *Each morphism Self-A in the category* **Cat(CAS)** *defines an algebra, so-called Self-A-*algebra(CAS)*.*

*Proof* This stems from definition of T-algebra, see [Appendix,](#page-5-1) where functor  $T$  is defined such that  $T =$  $\bigcup \{Self - A\}$ . Note that the notation  $\bigcup$  stands for *disjoint* union or *coproduct*. *union* or *coproduct*.

With the result of corollary 4, we obtain a compact formal definition of CAS as in

**Definition 4** (**CAS**) Each *Self-A*-algebra(CAS) defines a CAS

Both *CAS* and *Inter* may be infinite. If both *CAS* and *Inter* are finite, then we have a finite CAS, otherwise we have an infinite CAS.

At this point we can extend the representation of CASs in Eq. [2](#page-1-3) to become *extended* CASs (ECASs) as follows

$$
s_0 \xrightarrow{\sigma_0 | x_0} s_1 \xrightarrow{\sigma_1 | x_1} s_2 \xrightarrow{\sigma_2 | x_2} s_3 \cdots \qquad (12)
$$

where

- All indexes *i* in *T*,  $s_i$  and  $\sigma_i$  are similar in meaning to the ones mentioned in Eq. [2](#page-1-3)
- $x_i$  is a real number that can be thought of as the *multiplicity* (or *weight*) with which the self-adaptation from  $s_i$  to  $s_{i+1}$  occurs.

Self-adaptation of ECASs in diagram [\(12\)](#page-3-0) can be separated into two complementary parts as follows:

$$
s_0 \xrightarrow{\sigma_0} s_1 \xrightarrow{\sigma_1} s_2 \xrightarrow{\sigma_2} s_3 \dots \quad (13)
$$

<span id="page-3-2"></span>and

$$
s_0 \xrightarrow{x_0} s_1 \xrightarrow{x_1} s_2 \xrightarrow{x_2} s_3 \dots \tag{14}
$$

On the one hand, diagram [\(13\)](#page-3-1) emphasizes  $1 \frac{\sigma_i}{\sigma}$  Inter for all *i* in *<sup>T</sup>*, in the self-adaptation. This allows us to discover conveniently sequence of  $\sigma_i$  as series of interactions. On the other hand, diagram [\(14\)](#page-3-2) gives rise to  $1 \frac{x_i}{x_i} \mathbb{R}$ , for all *i* in *<sup>T</sup>*, as weights of the series of interactions in the self-adaptation to support an evaluation of weight-based quantitative behaviors of the series of interactions.

<span id="page-3-3"></span>Some first steps of the self-adaptation in Eq. [12](#page-3-0) can also be descriptively drawn as



Diagram  $(15)$  is thought of as

For the first step,

*s*<sub>1</sub> ∈ {*s*<sub>1</sub>*,*1*,...,s*<sub>1*,n*</sub>} ⊂ *CAS* 

and

*x*<sub>0</sub> ∈ {*x*<sub>0</sub>*,*1*,..., x*<sub>0*,n*</sub>} ⊂ ℝ

For the second step,

$$
s_2 \in \{s_{2,1,1}, \ldots, s_{2,1,k}\} \cup \ldots \cup \{s_{2,n,1}, \ldots, s_{2,n,m}\} \subset CAS
$$

and

<span id="page-3-4"></span>
$$
x_1 \in \{x_{1,1,1}, \ldots, x_{1,1,k}\} \cup \ldots \cup \{x_{1,n,1}, \ldots, x_{1,n,m}\} \subset \mathbb{R}
$$

and the meaning of Eq. [12](#page-3-0) is viewed as the following morphism.

<span id="page-3-0"></span>
$$
Self-A: (CAS \times Inter) \longrightarrow (CAS \longrightarrow \mathbb{R})
$$
 (16)

The self-adaptation morphism *Self-A* in Eq. [16](#page-3-4) is nondeterministic and this can be explained as follows: *Self-A* assigns to each configuration in  $CAS \times Inter$  a morphism *CAS* → R that can be seen as a kind of *nondeterministic configuration* (or so-called *distributed configuration*) and specifies for every state  $s'$  in *CAS* a multiplicity (or weight) *Self-A*( $\lt s, \sigma >$ )(s<sup>'</sup>) in R.<br>This pondeterminism

This nondeterminism of self-adaptation makes extension in representation of the categorical models mentioned above. Let us see the following examples

<span id="page-3-1"></span>**Example 4:** A specific self-adaptation, which is specified by the following morphism, is an extension of Eq. [7:](#page-2-2)

$$
Self-A: (CAS \times Inter) \longrightarrow (CAS \longrightarrow \mathbb{R}) \tag{17}
$$

(i.e., Self-A:(CAS×Inter<sup>1</sup>) 
$$
\longrightarrow
$$
 ((CAS×Inter<sup>0</sup>)  $\longrightarrow$   
\n $\mathbb{R}$ )  
\nor denoted by Self $\rightarrow$  A ((CAS×Inter) (CAS $\rightarrow \mathbb{R}$ )))

or denoted by *Self*−*A* ((CAS × Inter), (CAS → R)))<br>**Example 5:** The model in Eq. 8 extended for self **Example 5:** The model in Eq. [8](#page-2-3) extended for selfadaptation is specified by

$$
Self-A: (CAS \times Inter) \longrightarrow ((CAS \times Inter) \longrightarrow \mathbb{R})
$$
\n
$$
(18)
$$

 $(i.e., Self-A:(CAS\times Inter<sup>1</sup>)\longrightarrow ((CAS\times Inter<sup>1</sup>)\longrightarrow$ R*)*

or denoted by *Self* <sup>−</sup> *A((CAS* <sup>×</sup> *Inter), ((CAS* <sup>×</sup>  $Inter) \longrightarrow \mathbb{R}$  $))$ 

**Example 6:** Again, we specify another specific selfadaptation as an extension of Eq. [9](#page-2-4) in

$$
Self-A: (CAS \times Inter^n) \longrightarrow ((CAS \times Inter) \longrightarrow \mathbb{R})
$$
\n
$$
(19)
$$

 $(i.e., Self - A : (CAS \times Inter^n) \rightarrow ((CAS \times$ *Inter*<sup>1</sup> $) \rightarrow \mathbb{R}$ 

or denoted by *Self* <sup>−</sup> *A(*−→ *(CAS* <sup>×</sup> *Intern), ((CAS* <sup>×</sup>  $Inter) \longrightarrow \mathbb{R}$  $))$ 

and, in the completely same way, we do for an arbitrary self-adaptation as in

**Definition 5** (**Self-adaptation**) Generally, an arbitrary selfadaptation is specified by

<span id="page-4-1"></span>
$$
Self - A : (CAS \times Inter^{i \in T}) \longrightarrow ((CAS \times Inter^{j \in T}) \longrightarrow \mathbb{R})
$$
\n
$$
(20)
$$

We have the following corollaries.

**Corollary 5** (**Self-adaptation in ECASs**) *Morphism Self-A in* Eq. [20](#page-4-1) *defines self-adaptation in* ECASs

*Proof* This stems from Eq. [20](#page-4-1) and the fact that selfadaptation emerges through interactions in ECASs. □

<span id="page-4-2"></span>Morphism *Self-A* in Eq. [20](#page-4-1) defines a set {*Self*<sup>−</sup> *Ak*∈N} of mappings such that

$$
\{Self - A_{k \in \mathbb{N}}\} : (CAS \times Inter^{i \in T}) \longrightarrow ((CAS \times Inter^{j \in T}) \longrightarrow \mathbb{R})
$$
\n
$$
(21)
$$

**Corollary 6** (**Self-adaptive traits in ECASs**) *Set* {*Self* <sup>−</sup> *Ak*∈N} *in* Eq. [21](#page-4-2) *defines self-adaptive traits in* ECASs*. Each mapping Self-A*<sub>*k*∈N</sub> *is called a self-adaptive trait.* 

*Proof* This originates as the result of the truth that selfadaptation is the set of self-adaptive traits.  $\Box$  **Corollary 7** (**Category of the sets of ECAS configurations**) *Category* **Cat(CAS)** *equipped with structure*  $(CAS \times Inter^{i \in T}) \rightarrow ((CAS \times Inter^{j \in T}) \rightarrow \mathbb{R})$ *defines a category* **Cat(ECAS)** *of the sets of* ECAS *configurations.*

*Proof* This result comes immediately from corollary 3.  $\Box$ 

**Corollary 8** (*Self-A***-algebra(ECAS)**) *Structure (CAS* <sup>×</sup> *Inter*<sup>*i*∈*T*</sup>  $\longrightarrow$  ((*CAS* × *Inter*<sup>*j*∈*T*</sup>)  $\longrightarrow$  R*) in the category* **Cat(ECAS)** *defines an algebra, so-called Self-A*algebra(ECAS)*.*

*Proof* This originates from definition on T-algebra in [Appendix,](#page-5-1) where functor  $T$  is defined such that  $T =$ {*Self* <sup>−</sup> *A*} (similar to corollary 4) with *Self-A* defined in Eq. [20.](#page-4-1)

With this result of corollary 8, we obtain a compact formal definition of ECAS as in

**Definition 6** (**ECAS**) Each *Self-A*-algebra(ECAS) defines an ECAS

Moreover, we have the following corollary to obtain a significant relationship between CASs and ECASs.

**Corollary 9** (**Relationship between CASs and ECASs**) CASs *are just of specific* ECASs*. In other words, using categorical language,*

*Proof* In fact, by the self-adaptation morphism in Eq. [20](#page-4-1) of ECASs, let *f* be the morphism  $f : (CAS \times Inter^{j \in T}) \longrightarrow$ R, *Conf* be *CAS* × *Inter*<sup>*j*∈*T*</sup> and the finite set Hence it follows that when  $\exists ! \bot \longrightarrow Conf : f(c) = 1$  but  $\forall c' \neq c : f(c') = 0$  (i.e., the set  $\mathbb{P}(Conf)$  is a singleton set of con $c$ :  $f(c') = 0$  (i.e., the set  $\mathbb{R}(Conf)$  is a singleton set of con-<br>figuration with weight of 1. Note that the notation  $\exists!$  is read figuration with weight of 1. Note that the notation ∃! is read as "exist only") then Eq. [20](#page-4-1) becomes the self-adaptation morphism of CASs as in Eq. [10.](#page-2-0) In other words, in the case, ECASs will become CASs.  $\Box$ 

#### <span id="page-4-0"></span>**6 Discussions**

The aim of this paper has been both to give an in-depth analysis as well as to present the new material on the notion of self-adaptation in both CASs and ECASs.

In the considered context, we apply the category theory, which deals in an abstract way with algebraic objects and relationships between them for specifying interaction behaviors in both CASs and ECASs. For modeling, analyzing and verifying the interaction behaviors, category theory is much better-approaching than other ones such as *process algebras* (or *process calculi*), FSM (Finite State Machine) or UML (Unified Modeling Language). In fact, the categorical approach becomes more powerful since process algebras and FSM are just of algebraic objects of category and UML is really a semi-formal approach. Categories were first described by Samuel Eilenberg and Saunders Mac Lane in 1945 [\[4\]](#page-7-4), but have since grown substantially to become a branch of modern mathematics. Category theory spreads its influence over the development of both mathematics and theoretical computer science. The categorical structures themselves are still the subject of active research, including work to increase their range of practical applicability.

## <span id="page-5-0"></span>**7 Conclusions**

In this paper, we have rigorously approached to the notion of self-adaptation in both CASs and ECASs from which formal aspects of the self-adaptation emerge.

We have investigated configuration of both CASs and ECASs at every self-adaptation step as a member in the set  $CAS \times Inter^{i \in T}$ , then self-adaptation as a morphism from a configuration to another and, moreover, self-adaptation as a set of self-adaptive traits. By that way we have discovered some significant properties of the self-adaptation.

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#### <span id="page-5-1"></span>**Appendix**

We recall some concepts from the category theory  $[1-5]$  $[1-5]$ used in this paper.

#### **What is a category?**

A category **C** can be viewed as a graph  $(Obj(\mathbf{C}),$ <br> $Arc(\mathbf{C})$ , s t) where *Arc(***C***), s, t)*, where

- $Obj(\mathbf{C})$  is the set of nodes we call *objects*,
- *Arc*(**C**) is the set of edges we call *morphisms* and<br>• *s*  $t : Arc(C) \longrightarrow Obi(C)$  are two mans called *s*
- $s, t : Arc(\mathbf{C}) \longrightarrow Obj(\mathbf{C})$  are two maps called *source* (or *domain*) and *target* (or *codomain*), respectively.

We write  $f: \mathcal{X} \longrightarrow \mathcal{Y}$  when f is in  $Arc(\mathbb{C})$  and  $s(f) = \mathcal{X}$ and  $t(f) = Y$ .

*Explanation on terminology* An object in the category is an algebraic structure such as a set. We are probably familiar with some notations for finite sets: {*Student A, Student B, Student C*} is a name for the set whose three elements are *Student A, Student B, Student C*. Note that the order in which the elements are listed is irrelevant.

A morphism *f* in the category consists of three things: a set  $X$ , called the source of the morphism; a set  $Y$ , called the target of the morphism and a rule assigning to each element *x* in the source an element *y* in the target. This *y* is denoted by  $f(x)$ , read "*f* of *x*". Note that the morphism is also called the *map*, *function*, *transformation*, *operator* or *arrow.* For example, let  $X = \{Student \, A, Student \, B, Stu$ *dent C*},  $\mathcal{Y} = \{Math, Physics, Chemistry, History\}$  and let *f* assign each student his or her favorite subject. The following internal diagram is an illustration.

{Student A Student B Student C}  
{
$$
Math
$$
  $Chemistry$   $History$   $Physics$  }  
(22)

This states that the favorite subject of the *Student C* is *History*, written by *f*(*Student C*)= *History*, while *Student A* and *Student B* prefer *Chemistry*. There are some important properties of any morphism

- From each element in the source {*Student A, Student B, Student C*}, there is exactly one arrow leaving.
- To an element in the target {*Math, Physics, Chemistry, History*}, there may be zero, one or more arrows arriving.

It is possible that the source and target of the morphism could be the same set. The following internal diagram is an example.

$$
\{Student A \qquad Student B \qquad Student C\}
$$
\n
$$
\{Student A \qquad Student B \qquad Student C\}
$$
\n
$$
\{Student A \qquad Student B \qquad Student C\}
$$
\n
$$
(23)
$$

and, in the case, the morphism is called an *endomorphism* whose representation is available as in

$$
{\{Student A \longrightarrow Student B \longleftarrow Student C\}}
$$
\n(24)

Associated with each object *X* in *Obj*(**C**), there is a mor-<br>phism  $1y \rightarrow Y$  called the *identity* morphism on phism  $1_\mathcal{X} = \mathcal{X} \longrightarrow \mathcal{X}$ , called the *identity* morphism on *X*, and to each pair of morphisms  $f : \mathcal{X} \longrightarrow \mathcal{Y}$  and  $g :$  $\mathcal{Y} \longrightarrow \mathcal{Z}$ , there is an associated morphism  $f$ ;  $g: \mathcal{X} \longrightarrow \mathcal{Z}$ , called the *composition* of *f* with *g*. The representations in

<span id="page-5-2"></span><sup>1</sup>Nguyen Tat Thanh University, Vietnam

Eq. [25](#page-6-2) include the external diagrams of identity morphism and composition of morphisms.

$$
\overbrace{\mathscr{X}}^{1_{\mathscr{X}}}\n\qquad \qquad \mathscr{X}\xrightarrow{f} \mathscr{Y}\xrightarrow{g} \mathscr{Z}\n\qquad \qquad (25)
$$

*Explanation on terminology* Here are the corresponding internal diagrams of the identity morphism.

Student A	Student B	Student C}
\n $\left\{\n \begin{array}{ccc}\n \text{Student } A & \text{Student } B \\  \text{Student } B & \text{Student } C\n \end{array}\n\right.$ \n		

Or

$$
\begin{array}{ccc}\n\bigcap & & & \bigcap & \\
\text{Student A} & & \text{Student B} & & \text{Student C}\n\end{array}
$$
\n(27)

<span id="page-6-3"></span>And here, the composition of morphisms is described in the internal diagram



Or, in the external diagram  $\mathscr{X} \xrightarrow{e} \mathscr{X} \xrightarrow{f} \mathscr{Y}$  By the diagram [\(28\)](#page-6-3), we can obtain answers for the question "What should each student support to his or her favorite classmate for subject?". In fact, the answers are such as " *Student A* likes *Student B*, *Student B* likes *Chemistry*, so *Student A* should support *Chemistry*", "*Student B* likes *Student C*, *Student C* likes *History*, so *Student B* should support *History*" and "*Student C* likes *Student B*, *Student B* likes *Chemistry*, so *Student C* should support *Chemistry*".

The composition of two morphisms *e* and *f* means that *e* and *f* are combined to obtain a third morphism  $\mathscr{X} \xrightarrow{e:f} \mathscr{Y}$ This is represented in the following internal diagram.



where, for example, *e*;  $f(Student B) = History$  is read as "the favorite subject of the favorite classmate of *Student B* is *History*".

<span id="page-6-2"></span>The following equation must hold for all objects  $\mathcal{X}, \mathcal{Y}$  in *Obj*(**C**) and morphism  $f : \mathcal{X} \longrightarrow \mathcal{Y}$  in  $Arc(\mathbb{C})$ :

<span id="page-6-0"></span>Identity: 
$$
1_{\mathcal{X}}; f = f = f; 1_{\mathcal{Y}}
$$
 (30)

$$
x \bigodot x \xrightarrow{f} y = x \xrightarrow{f} y = x \xrightarrow{f} y \bigodot 1_{y}
$$

The following equation must hold for all objects  $X, Y$  and  $\mathcal{Z}$  in  $Obj(\mathbb{C})$  and morphisms  $f: \mathcal{X} \longrightarrow \mathcal{Y}, g: \mathcal{Y} \longrightarrow \mathcal{Z}$ and  $h : \mathcal{Z} \longrightarrow \mathcal{T}$  in  $Arc(\mathbb{C})$ :

<span id="page-6-1"></span>Associativity: 
$$
(f; g); h = f; (g; h)
$$
 (31)  
\n
$$
\xrightarrow{f} \mathscr{Y} \xrightarrow{s} \mathscr{Z} \xrightarrow{h} \mathscr{T} = \mathscr{X} \xrightarrow{f} \mathscr{Y} \xrightarrow{g} \mathscr{Z} \xrightarrow{h} \mathscr{T}
$$
\n
$$
\xrightarrow{f; g}
$$

# **Isomorphism**

 $\mathbf{1}$ 

A morphism  $f: \mathcal{X} \longrightarrow \mathcal{Y}$  in the category **C** is an *isomorphism* if there exists a morphism  $g: Y \longrightarrow X$  in that category such that  $f$ ;  $g = 1_{\mathcal{X}}$  and  $g$ ;  $f = 1_{\mathcal{Y}}$ .



That is, if the following diagram commutes.



## **Element of a set**

For any set *A*,  $x \in A$  iff  $1 \xrightarrow{x} A$  (or  $x : 1 \longrightarrow A$ ) where 1 denotes a singleton set. Focus on one element of {*Math, Physics, Chemistry, History*}, say {*subject*}, and call this set "1". Let us see what the morphisms from 1 to {*Math, Physics, Chemistry, History*} are. There are exactly four of them.

$$
\begin{array}{ccc}\n\{subject\} & \{Math & Chemistry & History & Physics\} \\
\hline\nMath & & & & \\
\end{array}
$$
\n(34)

$$
{subject} \qquad {Math \qquad Chemistry \qquad History \qquad Physics} \qquad \qquad
$$

(35)

$$
\{Subject\} \qquad \{Math \qquad Chemistry \qquad History \qquad Physics\}
$$
\n
$$
History \qquad (36)
$$



By this way, we can write  $1 \longrightarrow N$  (or  $2 : 1 \longrightarrow N$ ) for  $2 \in \mathbb{N}, 1 \longrightarrow \mathbb{N}$  (or *i* : 1  $\longrightarrow \mathbb{N}$ ) for *i*  $\in \mathbb{N}$  and so on.

# **Functor**

Functor is a special type of mapping between categories. Functor from a category to itself is called an endofunctor. Note that the functors are also viewed as morphisms in a category, whose objects are smaller categories.

## **T-algebra**

Let **C** be a category, *A* an object in  $Obj(\mathbf{C})$ ,  $\mathbf{T} : \mathbf{C} \longrightarrow \mathbf{C}$ an endofunctor and *f* a morphism  $T(A) \rightarrow A$ ; then

T-algebra is a pair  $\langle A, f \rangle$ . *Obj* (**C**) is called a carrier of the algebra and T a signature of the algebra.

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