

Reflection of plane waves at the initially stressed surface of a fiber-reinforced thermoelastic half space with temperature dependent properties

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Abstract In this paper, a model of two dimensional problem of generalized thermoelasticity for a fiberreinforced anisotropic elastic medium under the effect of temperature dependent properties is established. Reflection phenomena of plane waves in an initially stressed thermoelastic medium is studied in the context of two theories proposed by Lord-Shulman and Green-Lindsay. Using proper boundary conditions, the amplitude ratios and energy ratios for various reflected waves are presented. The phase speeds, reflection coefficients and energy ratios are computed numerically with the help of MATLAB programming and are depicted graphically to show the effect of initial stress and temperature dependent properties. It is found that there is no dissipation of energy at the boundary surface during reflection. A comparison between the two theories is also depicted in the present investigation.

Keywords Reflection · Anisotropic material · Fiberreinforced · Initial stress · Temperature dependent elastic modulus

Mathematics Subject Classification 74A15 · 80A20

1 Introduction

Weight reduction is often the principal consideration for selecting fiber reinforced polymers over metals and for many applications, they provide a higher material index than metals and therefore suitable for minimum mass design. Depending on the application, there are other advantages of using fiber reinforced composites, such as higher damping, no corrosion, parts integration, control of thermal expansion and so on. Fiberreinforced polymers have a great potential for replacing reinforced concrete and steel in bridges, buildings and other civil infrastructures. The principal reason for selecting these composites is their corrosion resistance, which leads to longer life and lower maintenance and repair costs. Another advantage of using fiber reinforced polymers for large bridge structures is their light weight, which means lower dead weight for the bridge, easier transportation from the production factory (where the composite structure can be prefabricated) to the bridge location, easier hauling and installation and less injuries to people in case of an earthquake . With lightweight construction, it is also possible to design bridges with longer span between the supports.

During the last few decades, fiber-reinforced theory has been successfully employed for modeling different processes and systems, specially in the area of engineering, mechanics and physics. Fiber-reinforced composites have many applications in commercial and industrial areas. Fiber-reinforced polymer composites

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are also used in building construction, furniture, power industry, oil industry, medical industry, aircraft, space, automotive, sporting goods etc. The elastic moduli for fiber-reinforced material were introduced by Hashin and Rosen (1964). Pipkin (1973) and Rogers (1975) did exciting works on the subject. Belfield et al. (1983) investigated the stress in elastic plates reinforced by fibers lying in concentric circles. Sengupta and Nath (2001) discussed the two-dimensional problem of surface waves in an anisotropic, fiber-reinforced solid elastic medium. Singh and Singh (2004) solved a two dimensional problem on reflection of plane waves at free surface of a fiber-reinforced elastic-half space.

Singh (2006) discussed the propagation of plane harmonic waves in a fiber-reinforced anisotropic thermoelastic medium. Othman and Atwa (2012) employed normal mode technique to study the propagation of plane waves in fiber-reinforced anisotropic thermoelastic half-space under the effect of magnetic field. Othman and Said (2012) studied the effect of rotation on two-dimensional problem of a fiberreinforced thermoelastic medium with one relaxation time. Othman and Said (2015) in another article analyzed the effect of rotation on a fiber-reinforced medium under generalized magneto-thermoelasticity with internal heat source. Micromechanical finite element analysis of effective properties of a unidirectional short piezoelectric fiber reinforced composite is presented by Panda and Panda (2015). Reflection of thermoelastic waves from insulated boundary of a fiber-reinforced half-space under influence of rotation and magnetic field was investigated by Elsagheer and Abo-Dahab (2016).

The conventional theory of thermoelasticity can be used in several particular problems, although this turns out to predict an infinite speed of thermal signals, which is physically unrealistic. Generalized theories proposed by Lord and Shulman (1967) and Green and Lindsay (1972) are two well known theories of thermoelasticity to overcome this deficiency. After that, providing sufficient basic modifications in governing equations, Green and Naghdi (1991, 1992, 1993) produced an alternative theory which was further divided into three different parts, referred to as GN theory of type I, II, III. Under Green–Lindsay theory, Darabseh et al. (2012) studied the transient thermoelastic response of a thick hollow cylinder made of functionally graded material under thermal loading.

The elastic modulus is an important physical property of materials reflecting the elastic deformation capacity of the material when subjected to an applied external load. In most of the investigations, the material properties are assumed to be constant. However, it is well known that the physical properties of engineering materials vary with temperature. At high temperature, the material characteristics such as modulus of elasticity, Poisson's ratio, coefficient of thermal expansion and the thermal conductivity are no longer constant, Lomakin (1976). Ezzat et al. (2001) solved a problem of generalized thermoelasticity with two relaxation times in an isotropic elastic medium with temperature-dependent mechanical properties. Aouadi (2006) examined the effect of temperature dependency of elastic modulus on the behavior of twodimensional solutions in micropolar thermoelastic medium. Othman and Kumar (2009) constructed the model of generalized magneto-thermoelasticity in an isotropic perfectly conducting elastic medium under the effect of temperature dependent properties. Kalkal and Deswal (2014) adopted normal mode technique to investigate the effect of phase lags on three-dimensional wave propagation with temperature-dependent properties. Othman and Said (2014) investigated the influence of magnetic field and temperature dependent properties on the plane waves in a fiber-reinforced thermoelastic medium in the context of three-phaselag theory and Green-Naghdi theory without energy dissipation.

Recent years have seen an ever growing interest in investigation of the problems related to initially stressed elastic medium, due to its numerous applications in various fields, such as earthquake engineering, seismology and geophysics. The earth is assumed to be under high initial stresses. The dynamic problem of an elastic medium under initial stress was solved by Biot (1965). The linear theory of thermoelasticity with hydrostatic initial stress for an isotropic medium was developed by Montanaro (1999). Abbas and Abd-Alla (2011) studied the two-dimensional problem of generalized thermoelasticity for a fiber-reinforced anisotropic thick plate under initial stress. Kumar et al. (2015) showed the effect of the initial stress on wave propagation in fiber-reinforced transversely isotropic thermoelastic medium. Deswal et al. (2016) studied the dynamical interactions of the thermal, elastic and diffusion fields under the fractional order generalized thermoelasticity theory with two-temperature and initial stress. Propagation of waves in an initially stressed generalized electro-microstretch thermoelastic medium with temperature dependent properties under the effect of rotation was investigated by Deswal et al. (2017). Yadav et al. (2017) analyzed the thermoelastic interactions in a homogeneous isotropic electro-microstretch semi-space caused by a mechanical source acting on an initially stressed surface.

In the present manuscript, we have studied the possibility of wave propagation in a fiber-reinforced initially stressed anisotropic thermoelastic medium with temperature dependent properties. The formulae for amplitude ratios and energy ratios corresponding to various reflected waves have been presented when a set of coupled waves strikes obliquely at boundary surface of the assumed model and their variations with angle of incidence are presented graphically. The phase speeds of various existing waves are computed and their variations are depicted graphically against frequency. It has been verified that during reflection phenomena, the sum of energy ratios is equal to unity at each angle of incidence. Some comparisons have been made in figures to estimate the effects of initial stress and temperature dependent properties.

The present information may be useful in some possible experiment based problems on wave propagation in fiber-reinforced initially stressed anisotropic thermoelastic medium with temperature dependent properties under Lord–Shulman and Green–Lindsay models. The efforts of this research are focused on systematically studying the difference of theories and effect of considered parameters in generalized thermoelastic medium. Currently there is no publication available that is related to reflection phenomenon in a fiber-reinforced initially stressed anisotropic thermoelastic medium with temperature dependent properties under Lord–Shulman and Green–Lindsay models. Hence, to address this issue, we have solved a twodimensional problem in such type of medium.

2 Governing equations

In the context of Lord–Shulman (LS) and Green– Lindsay (GL) theories, the constitutive relations and field equations, after ignoring the body force for a fiber-reinforced thermoelastic anisotropic medium with initial stress are given as: (i) Constitutive relations [Belfield et al. (1983), Xiong and Tian (2016)]:

$$\begin{aligned} \sigma_{ij} &= -P(\delta_{ij} + \omega_{ij}) + \lambda e_{kk} \delta_{ij} \\ &+ 2\mu_T e_{ij} + \alpha (a_k a_m e_{km} \delta_{ij} + a_i a_j e_{kk}) \\ &+ 2(\mu_L - \mu_T) (a_i a_k e_{kj} + a_j a_k e_{ki}) \\ &+ \beta a_k a_m e_{km} a_i a_j - \beta_{ij} (\Theta + \tau_1 \dot{\Theta}) \delta_{ij}, \end{aligned}$$

$$(1)$$

where P is the initial pressure, σ_{ii} are the components of stress, e_{ii} are the components of strain, λ , μ_T are elastic constants, α , β , and $(\mu_L - \mu_T)$ are reinforced parameters, δ_{ij} is the Kronecker's delta, τ_1 is the thermal relaxation time, T is the absolute temperature, T_0 is the reference temperature chosen so that $|(T - T_0)/T_0| \ll 1$, Θ is temperature deviation from reference temperature i.e. $\Theta =$ $T - T_0$ and the components of vector \vec{a} are (a_1, a_2, a_3) , where $a_1^2 + a_2^2 + a_3^2 = 1$, $\beta_{11} =$ $(2\lambda + 3\alpha + 4\mu_L - 2\mu_T + \beta)\alpha_{11} + (\lambda + \alpha)\alpha_{22},$ $\beta_{22} = (2\lambda + \alpha)\alpha_{11} + (\lambda + 2\mu_T)\alpha_{22}, \ \alpha_{11}$ and α_{22} are coefficients of linear thermal expansion. The deformation tensor and ω_{ij} can be expressed in terms of the displacement u_i as

$$e_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i}), \tag{2}$$

$$\omega_{ij} = \frac{1}{2} (u_{j,i} - u_{i,j}).$$
(3)

(ii) Equation of motion

$$\sigma_{ji,j} = \rho \ddot{u}_i,\tag{4}$$

where ρ is the mass density.

(iii) The balance law of energy

$$q_{i,i} = \rho h - ST_0, \tag{5}$$

where S is the entropy per unit volume and h is heat source per unit mass.

(iv) The entropy linear equation

$$S = \frac{\rho C_E}{T_0} \Theta + \beta_{ij} e_{ij}, \tag{6}$$

where C_E is the specific heat.

(v) Heat conduction law

$$q_i + \tau_0 \dot{q}_i = -k_{ij} \Theta_{,i} \,, \tag{7}$$

where q_i are the components of heat flux vector, τ_0 is the thermal relaxation time and k_{ij} is the thermal conductivity. Elimination of *S*, q_i and e_{ij} from Eqs. (2) and (5)–(7) in the absence of heat source yields the following coupled heat equation for the two models (LS and GL) as

$$k_{ij}\Theta_{,ij} = \rho C_E \left(\frac{\partial}{\partial t} + \tau_0 \frac{\partial^2}{\partial t^2}\right)\Theta + T_0 \left(\frac{\partial}{\partial t} + \eta_0 \tau_0 \frac{\partial^2}{\partial t^2}\right)\beta_{ij}u_{i,j}, \qquad (8)$$

where η_0 is a unifying parameter, a comma followed by suffix denotes material derivative and a superposed dot denotes the derivative with respect to time *t*.

Moreover, the use of the relaxation times τ_1 in Eq. (1), τ_0 and unifying parameter η_0 in Eq. (8) makes these fundamental equations valid for the two different theories of thermoelasticity:

(i) Lord and Shulman's theory (1967)
$$\tau_1 = 0, \tau_0 > 0, \quad \eta_0 = 1.$$

(ii) Green and Lindsay's theory (1972)

$$\tau_1 > 0, \tau_0 > 0, \quad \eta_0 = 0.$$

Our aim is to examine the effect of the temperature dependent nature of the material. So we assume that [Othman and Said (2014)]

$$\begin{aligned} &(\lambda_1, \ \alpha_1, \ \beta_1, \ \beta_{1ij}, \ \mu_{L1}, \ \mu_{T1}) \\ &= \frac{1}{(1 - \alpha^* T_0)} (\lambda, \ \alpha, \ \beta, \ \beta_{ij}, \ \mu_L, \ \mu_T), \end{aligned}$$
(9)

where α^* is an empirical material constant.

3 Statement of the problem

We consider the problem of a fiber-reinforced anisotropic initially stressed half space with temperature dependent properties, initially at the uniform temperature T_0 . The rectangular cartesian co-ordinates are introduced having origin on the surface (x = 0)and x-axis pointing vertically downward into the half space, which is thus designated as $x \ge 0$. We restrict our analysis to a two dimensional problem in xy-plane. Thus all the field quantities are independent of the variable z.

The components of displacement vector $\vec{u} = (u_1, u_2, u_3)$ assume the form

$$u = u_1 = u(x, y, t), \quad v = u_2 = u(x, y, t), \text{ and } w$$

= $u_3 = 0.$ (10)

We choose the fiber direction as $\vec{a} = (1, 0, 0)$, so that the preferred direction is *x*-axis. Eqs. (1), (4) and (8) with the help of (2), (3), (9) and (10), take the form

$$\sigma_{11} = A_1 \frac{\partial u}{\partial x} + A_2 \frac{\partial v}{\partial y} - \alpha_0 \beta_{111} \left(1 + \tau_1 \frac{\partial}{\partial t} \right) \Theta - P,$$
(11)

$$\sigma_{22} = A_2 \frac{\partial u}{\partial x} + A_3 \frac{\partial v}{\partial y} - \alpha_0 \beta_{122} \left(1 + \tau_1 \frac{\partial}{\partial t} \right) \Theta - P,$$
(12)

$$\sigma_{12} = \left(\alpha_0 \mu_{L1} - \frac{P}{2}\right) \frac{\partial v}{\partial x} + \left(\alpha_0 \mu_{L1} + \frac{P}{2}\right) \frac{\partial u}{\partial y}, \quad (13)$$

$$\sigma_{21} = \left(\alpha_0 \mu_{L1} - \frac{P}{2}\right) \frac{\partial u}{\partial y} + \left(\alpha_0 \mu_{L1} + \frac{P}{2}\right) \frac{\partial v}{\partial x}, \quad (14)$$

$$\rho \frac{\partial^2 u}{\partial t^2} = A_1 \frac{\partial^2 u}{\partial x^2} + \left(A_2 + \alpha_0 \mu_{L1} + \frac{P}{2}\right) \frac{\partial^2 v}{\partial y \partial x} + \left(\alpha_0 \mu_{L1} - \frac{P}{2}\right) \frac{\partial^2 u}{\partial y^2}$$
(15)
$$-\alpha_0 \beta_{111} \left(\frac{\partial \Theta}{\partial x} + \tau_1 \frac{\partial \dot{\Theta}}{\partial x}\right),$$

$$\rho \frac{\partial^2 v}{\partial t^2} = A_3 \frac{\partial^2 v}{\partial y^2} + \left(A_2 + \alpha_0 \mu_{L1} + \frac{P}{2}\right) \frac{\partial^2 u}{\partial y \partial x} + \left(\alpha_0 \mu_{L1} - \frac{P}{2}\right) \frac{\partial^2 v}{\partial x^2} - \alpha_0 \beta_{122} \left(\frac{\partial \Theta}{\partial y} + \tau_1 \frac{\partial \dot{\Theta}}{\partial y}\right),$$
(16)

$$\begin{pmatrix} k_{11} \frac{\partial^2}{\partial x^2} + k_{22} \frac{\partial^2}{\partial y^2} \end{pmatrix} \Theta - \rho \ C_E \left(\frac{\partial}{\partial t} + \tau_0 \frac{\partial^2}{\partial t^2} \right) \Theta$$

= $T_0 \left(\frac{\partial}{\partial t} + \tau_0 \eta_0 \frac{\partial^2}{\partial t^2} \right) \left(\beta_{111} \frac{\partial u}{\partial x} + \beta_{122} \frac{\partial v}{\partial y} \right) \alpha_0,$ (17)

where $A_1 = (\lambda_1 + 2\alpha_1 + \beta_1 + 4\mu_{L1} - 2\mu_{T1})\alpha_0$, $A_2 = (\alpha_1 + \lambda_1)\alpha_0$, $A_3 = (\lambda_1 + 2\mu_{T1})\alpha_0$, $\alpha_0 = (1 - \alpha^*T_0)$.

To facilitate the solution, we introduce non-dimensional variables as follows:

$$(x', y', u', v') = \chi c_1(x, y, u, v), (t', \tau'_0, \tau'_1) = \chi c_1^2(t, \tau_0, \tau_1), \Theta' = \beta_{111} \frac{\Theta}{\rho c_1^2}, \quad P' = \frac{P}{\rho c_1^2}, \quad \sigma'_{ij} = \frac{\sigma_{ij}}{\rho c_1^2},$$
(18)

where

$$c_1^2 = \frac{A_1}{\rho}, \quad \chi = \frac{\rho C_E}{k_{11}}$$

Now, in terms of the non dimensional quantities defined in (18), Eqs. (15)–(17) along with some simplifications, provide the following relations (dropping the prime notation)

$$\frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2} + B_1 \frac{\partial^2 u}{\partial y^2} + B_2 \frac{\partial^2 v}{\partial y \partial x} - \alpha_0 \left(\frac{\partial \Theta}{\partial x} + \tau_1 \frac{\partial \dot{\Theta}}{\partial x} \right),$$
(19)

$$\frac{\partial^2 v}{\partial t^2} = B_2 \frac{\partial^2 u}{\partial y \partial x} + B_1 \frac{\partial^2 v}{\partial x^2} + B_3 \frac{\partial^2 v}{\partial y^2} - \alpha_0 B_4 \left(\frac{\partial \Theta}{\partial y} + \tau_1 \frac{\partial \dot{\Theta}}{\partial y} \right),$$
(20)

$$\frac{\partial^2 \Theta}{\partial x^2} + B_5 \frac{\partial^2 \Theta}{\partial y^2} = \frac{\partial \Theta}{\partial t} + \tau_0 \frac{\partial^2 \Theta}{\partial t^2} + B_6 \frac{\partial^2 u}{\partial x \partial t} + B_7 \frac{\partial^2 v}{\partial t \partial y} + B_8 \frac{\partial^3 u}{\partial t^2 \partial x} + B_9 \frac{\partial^3 v}{\partial t^2 \partial y},$$
(21)

where

$$B_{1} = \frac{2\alpha_{0}\mu_{L1} - P\rho c_{1}^{2}}{2A_{1}},$$

$$B_{2} = \frac{2\alpha_{0}\mu_{L1} + 2A_{2} + P\rho c_{1}^{2}}{2A_{1}},$$

$$B_{3} = \frac{A_{3}}{A_{1}}, \quad B_{4} = \frac{\beta_{122}}{\beta_{111}}, \quad B_{5} = \frac{k_{22}}{k_{11}}, \quad B_{6} = \frac{T_{0}\beta_{111}^{2}\alpha_{0}}{A_{1}\rho C_{E}},$$

$$B_{7} = B_{6}B_{4}, \quad B_{8} = \frac{\eta_{0}T_{0}\alpha_{0}\tau_{0}\beta_{111}^{2}}{A_{1}\rho C_{E}}, \quad B_{9} = B_{8}B_{4}.$$

4 Solution of the problem

Various types of waves generated in a homogeneous and anisotropic half space will be discussed in this section. To solve the Eqs. (19)–(21) analytically in the form of the harmonic travelling waves, we call the solution of the form:

$$(u, v, \theta) = (u^*, v^*, \theta^*) \exp\{\iota k(-x \cos\theta + y \sin\theta) - \iota \omega t\},$$
(22)

where k is the wave number, ω is the angular frequency having the definition $\omega = kV$, V being the phase velocity and the pair $(\cos\theta, \sin\theta)$ denotes the projection of wave normal onto the xy-plane.

Making use of expression (22), Eqs. (19)–(21) take the form

$$(k^2 D_1 + \omega^2) u^* + k^2 D_2 v^* + k D_3 \Theta^* = 0, \qquad (23)$$

$$k^{2}D_{2}u^{*} + (k^{2}D_{4} + \omega^{2})v^{*} + kD_{5}\Theta^{*} = 0, \qquad (24)$$

$$kD_6u^* + kD_7v^* + (k^2D_8 + D_9)\Theta^* = 0, \qquad (25)$$

where

$$D_{1} = -\cos^{2}\theta - B_{1}\sin^{2}\theta, \quad D_{2} = \cos\theta\sin\theta B_{2},$$

$$D_{3} = i\alpha_{0}\cos\theta + \tau_{1}\omega\cos\theta\alpha_{0},$$

$$D_{4} = -B_{1}\cos^{2}\theta - B_{3}\sin^{2}\theta,$$

$$D_{5} = -i\alpha_{0}B_{4}\sin\theta - \alpha_{0}B_{4}\tau_{1}\omega\sin\theta,$$

$$D_{6} = B_{6}\omega\cos\theta - i\cos\theta\omega^{2}B_{8},$$

$$D_{7} = iB_{9}\omega^{2}\sin\theta - B_{7}\omega\sin\theta,$$

$$D_{8} = -\cos^{2}\theta - B_{5}\sin^{2}\theta, \quad D_{9} = i\omega + \tau_{0}\omega^{2}.$$

The condition for the existence of non trivial solution of the homogeneous system of Eqs. (23)–(25) provides us the characteristic equation satisfied by *V* as

$$V^6 + AV^4 + BV^2 + C = 0, (26)$$

where

$$A = \frac{\omega^2 (E_1 E_9 + E_2 E_8 - E_4 E_6)}{E_2 E_9},$$

$$B = \frac{\omega^4 (E_1 E_8 + E_2 E_7 - E_4 E_5 - E_3 E_6)}{E_2 E_9},$$

$$C = \frac{\omega^6 (E_1 E_7 - E_3 E_5)}{E_2 E_9}, \quad E_1 = D_1 D_5 - D_2 D_3,$$

$$E_2 = \omega^2 D_5, \quad E_3 = D_2 D_5 - D_3 D_4,$$

$$E_4 = -\omega^2 D_3, \quad E_5 = -D_2 D_8,$$

$$E_6 = D_5 D_6 - D_2 D_9, \quad E_7 = -D_4 D_8,$$

$$E_8 = D_5 D_7 - D_4 D_9 - \omega^2 D_8, \quad E_9 = -\omega^2 D_9.$$

The roots of equation (26) give three values of V^2 which correspond to three coupled waves, namely, quasi-longitudinal (qP_1) , quasi-transverse (qP_2) and quasi-thermal (qP_3) propagating with velocities V_1, V_2 and V_3 respectively.

5 Reflection phenomena

Here, we shall investigate the reflection phenomena of a coupled plane qP_1 wave striking at the plane boundary of considered half-space, propagating with velocity V_1 and making an angle θ_0 with the normal to the surface. In order to satisfy the boundary conditions, we postulate that incident qP_1 wave generates three reflected coupled plane waves $qP_{1,2,3}$ of amplitudes $R_{1,2,3}$ propagating with phase speeds $V_{1,2,3}$ and making angles $\theta_{1,2,3}$ respectively with the normal as

Fig. 1 Geometry of the problem showing various reflected waves

shown in Fig. 1. The full structure of the wave field consisting of the incident and reflected waves can be defined as

$$(u, v, \theta) = (1, a_1, b_1) R_0 P_0^- + \sum_{i=1}^3 (1, a_i, b_i) R_i P_i^+$$
(27)

where $P_0^- = \exp\{ik_1(y\sin\theta_0 - x\cos\theta_0) - i\omega_1t\}, P_i^+ = \exp\{ik_i(y\sin\theta_i + x\cos\theta_i) - i\omega_it\}, a_i \text{ and } b_i(i = 1, 2, 3)$ are the coupling parameters between *u* and *v*, *u* and θ respectively. The expressions of the coupling parameters are given as

$$a_{i} = \frac{k_{i}^{2}(D_{1}D_{5} - D_{2}D_{3}) + \omega_{i}^{2}D_{5}}{\omega_{i}^{2}D_{3} - k_{i}^{2}(D_{2}D_{5} - D_{4}D_{3})},$$

$$b_{i} = -\frac{k_{i}^{2}D_{1} + \omega^{2} + k_{i}^{2}D_{2}a_{i}}{k_{i}D_{3}}.$$

To determine the amplitudes R_0 , R_1 , R_2 and R_3 , we postulate some boundary conditions at the surface x = 0. The appropriate boundary conditions of the problem can be written in mathematical form as

$$\sigma_{11} + P = 0$$
, $\sigma_{12} = 0$ and $\Theta = 0$ at $x = 0$. (28)

In order to satisfy the boundary conditions (28), the wave numbers k_1 , k_2 , k_3 and the incident and the reflected angles are connected by the relation $k_1 \sin \theta_0 =$ $k_1 \sin \theta_1 = k_2 \sin \theta_2 = k_3 \sin \theta_3$, which can also be expressed as (extended Snell's law)



$$\frac{\sin\theta_0}{V_1} = \frac{\sin\theta_1}{V_1} = \frac{\sin\theta_2}{V_2} = \frac{\sin\theta_3}{V_3}.$$
(29)

Using expressions (27) in boundary conditions (28) (after making non-dimensional), one can obtain a system of three non homogeneous equations in three unknowns, which can be written as

$$\sum_{i=1}^{3} b_{ij} Z_j = Y_i, \quad (i = 1, 2, 3)$$
(30)

where

$$b_{1j} = \{ lk_j(\cos \theta_j + n_1 a_j \sin \theta) - \alpha_0 b_j + l\alpha_0 \tau_1 \omega_j b_j \}, b_{2j} = (g_1 a_j \cos \theta_j + g_2 \sin \theta_j) lk_j, \quad b_{3j} = b_j, Z_j = \frac{R_j}{R_0}, \quad (j = 1, 2, 3)$$

and

$$Y_{1} = \{ \imath k_{1} (\cos \theta_{0} - n_{1}a_{1} \sin \theta_{0}) + \alpha_{0}b_{1} - \imath \omega_{1}\tau_{1}b_{1} \}, Y_{2} = \imath k_{1} (g_{1}a_{1} \cos \theta_{0} - g_{2} \sin \theta_{0}), \quad Y_{3} = -b_{1}, n_{1} = \frac{A_{2}}{A_{1}}, \ g_{1} = \left(\frac{\alpha_{0}\mu_{L1}}{A_{1}} - \frac{P}{2}\right), \ g_{2} = \left(\frac{\alpha_{0}\mu_{L1}}{A_{1}} + \frac{P}{2}\right).$$

6 Energy partition

In order to check the physical rightness of this problem, we must certify the energy balance during reflection at the boundary surface. Following [Achenbach (1973)], the instantaneous rate of work of surface traction is the product of the surface traction and the particle velocity. This scalar product is called the power per unit area denoted by P^* and is given by

$$P^* = (\sigma_{11} + P)\dot{u} + \sigma_{12}\dot{v}.$$
(31)

Let $\langle P_0^* \rangle$ denotes the average energy carried along incident wave, $\langle P_i^* \rangle$ (i = 1, 2, 3) denote the average energy carried along reflected coupled waves. The expressions for energy ratios E_i (i = 1, 2, 3) for reflected waves are given by

$$E_i = \frac{\langle P_i^* \rangle}{\langle P_0^* \rangle},$$
(32)

$$E_{1} = P' \left\{ \cos \theta_{1} + a_{1} \sin \theta_{1} n_{1} + \frac{(\iota \tau_{1} \omega_{1} - 1) \alpha_{0} b_{1}}{\iota k_{1}} + (g_{1} a_{1} \cos \theta_{1} + g_{2} \sin \theta_{1}) a_{1} \right\} |Z_{1}|^{2},$$
(33)

$$E_{2} = P' \left\{ \cos \theta_{2} + a_{2} \sin \theta_{2} \ n_{1} + \frac{(\iota \tau_{1} \omega_{1} - 1) \alpha_{0} \ b_{2}}{\iota k_{2}} + (g_{1} a_{2} \cos \theta_{2} + g_{2} \sin \theta_{2}) a_{2} \right\} \left(\frac{k_{2}}{k_{1}} \right) |Z_{2}|^{2},$$
(34)

$$E_{3} = P' \left\{ \cos \theta_{3} + a_{3} \sin \theta_{3} n_{1} + \frac{(\iota \tau_{1} \omega_{1} - 1) \alpha_{0} b_{3}}{\iota k_{3}} + (g_{1} a_{3} \cos \theta_{3} + g_{2} \sin \theta_{3}) a_{3} \right\} \left(\frac{k_{3}}{k_{1}} \right) |Z_{3}|^{2},$$
(35)

where

$$P' = \left\{ -\cos \theta_0 + a_1 \sin \theta_0 \ n_1 + \frac{(i\tau_1\omega_1 - 1)\alpha_0 \ b_1}{ik_1} + (g_2 \sin \theta_0 - g_1a_1 \cos \theta_0)a_1 \right\}^{-1}.$$

We note that these energy ratios depend on the elastic properties of the medium, angle of incidence and amplitude ratios.

7 Special cases

7.1 Case I: without temperature dependent property

If we assume that the parameters λ , μ_L , μ_T , α , β and β_{ij} are free from temperature dependent effect, i.e. $\alpha^* = 0$, then we shall be dealing with a half space problem in an initially stressed fiber-reinforced thermoelastic medium. Taking into consideration the above mentioned modifications, Eq. (30) will provide us the reflection coefficients for the corresponding problem. If we further neglect the initial stress from the medium, then the results of the relevant problem

coincide with those of Elsagheer and Abo-Dahab (2016) with appropriate changes in the boundary conditions after removing the rotation and magnetic effects.

7.2 Case II: without initial stress

If we neglect the presence of initial stress from the half space, then we shall be left with the problem of wave propagation and its reflection in fiber-reinforced thermoelastic medium with temperature dependent properties. For this purpose, we shall set P = 0. With this consideration, the corresponding reflection coefficients for incidence of a set of coupled waves can be obtained from the Eq. (30). If we further neglect the temperature dependence of parameters then the results of the relevant problem coincide with Singh (2006) with appropriate changes in the theory and boundary conditions.

8 Numerical results and discussions

With an aim to discuss the behavior of wave propagation through a fiber-reinforced, anisotropic initially stressed medium with temperature dependent mechanical properties in greater detail, a numerical analysis is carried out. For the purpose of numerical computation, the material constants of problem are taken [Singh (2006)] and [Othman (2014)] as:

$$\begin{split} \rho &= 2660 \text{ kg m}^{-3}, \quad \mu_{T1} = 1.89 \times 10^{10} \text{ N m}^{-2}, \\ \alpha_1 &= -1.28 \times 10^{10} \text{ N m}^{-2}, \\ \mu_{L1} &= 2.45 \times 10^{10} \text{ N m}^{-2}, \quad \lambda_1 = 7.59 \times 10^{10} \text{ N m}^{-2}, \\ \beta_1 &= 0.32 \times 10^{10} \text{ N m}^{-2}, \\ k_{11} &= 0.0921 \times 10^3 \text{ J m}^{-1} \text{ deg}^{-1} \text{ s}^{-1}, \\ k_{22} &= 0.0963 \times 10^3 \text{ J m}^{-1} \text{ deg}^{-1} \text{ s}^{-1}, \\ \alpha_{11} &= 0.017 \times 10^4 \text{ deg}^{-1}, \\ \alpha_{22} &= 0.015 \times 10^4 \text{ deg}^{-1}, \quad T_0 = 293\text{K}, \\ C_E &= 0.787 \times 10^3 \text{ J kg}^{-1} \text{ deg}^{-1}, \quad \tau_0 = 0.02s, \\ \tau_1 &= 0.03\text{s}, \quad \omega = 2 \text{ s}^{-1}. \end{split}$$

With these numerical values of parameters, we have evaluated the amplitude ratios and energy ratios corresponding to incident qP_1 wave at different angles of incidence varying from normal incidence to grazing incidence. We have examined the variations of amplitude ratios and energy ratios in the considered medium for three different cases. (i) Medium under initial stress and with temperature dependent properties (MISTD, $\alpha^* = 0.005$, P = 1, solid line) (ii) Medium under initial stress (MIS, P = 1, $\alpha^* = 0.0$, long dashed line) (iii) Medium with temperature dependent properties (MTD, $\alpha^* = 0.005$, P = 0.0, small dashed line). Figures 2, 3, 4 are plotted to observe the effects of temperature dependency of material constants and initial pressure on the profile of



Fig. 2 Effect of initial stress on the moduli of reflection coefficient Z_1 for temperature dependent and independent properties

reflection coefficients. In Figs. 5, 6, 7, we have examined the variation of amplitude ratios in a fiberreinforced initially stressed medium with temperature dependent properties under Lord–Shulman (LS, solid line) and Green–Lindsay (GL, long dashed line) models.The dependence of energy ratios of various reflected waves on angle of incidence is displayed in Fig. 8. Figures (9, 10, 11, 12) are plotted with the purpose to show the change in phase speeds with frequency. All the graphs except Figs. (5, 6, 7) are plotted for L–S theory only.

Figure 2 is plotted to display the variations of moduli of amplitude ratio Z_1 versus angle of

Fig. 3 Effect of initial stress on the moduli of reflection coefficient Z_2 for temperature dependent and independent properties

Fig. 4 Effect of initial stress on the moduli of reflection coefficient Z_3 for

independent properties

temperature dependent and



incidence. From the figure, we observe that values of $|Z_1|$ remain in the neighborhood of unity for all the cases in the entire range of angle of incidence. It can be noticed from the figure that the presence of initial stress has a slight increasing effect while temperature dependency of material constants has decreasing effect on the profile of amplitude ratio $|Z_1|$. Figure 3 depicts the variations of absolute values of Z_2 against angle of incidence. It can be noticed from the figure that the curve of $|Z_2|$ for MISTD case is upper than that for both MIS and MTD cases. This has happened due to the temperature dependency of material constants and the presence of initial stress

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in the medium. Hence, temperature dependent material constants and initial stress parameter have increasing effect. The variations of reflection coefficient $|Z_3|$ are illustrated in Fig. 4. The presence of temperature dependent material constants has an increasing impact on the profile of this reflection coefficient, while initial stress parameter has both increasing and decreasing impacts.

Figure 5 is drawn with the purpose to display a comparison of variation of reflection coefficient $|Z_1|$ versus angle of incidence for LS and GL theories. It is clear from the figure that the values of $|Z_1|$ for LS theory are found to be larger as compared to GL

theory. It is also evident from the plot that the reflection coefficient $|Z_1|$ has qualitatively similar behavior for LS and GL theories. However, dissimilarity lies on the ground of magnitude. The behavior of variation of reflection coefficient $|Z_2|$ against angle of incidence has been expressed in Fig. 6 for LS and GL theories. This reflection coefficient experiences a similar pattern of variations in both the theories. We observe from the figure that the values of $|Z_2|$ for GL theory are found to be large as compared to LS theory. In Fig. 7, we have plotted the curves to exhibit the variations of reflection coefficient $|Z_3|$ for both the theories. The figure shows that the values of $|Z_3|$ for LS



theory are smaller than the values for GL theory in the entire range except at one point. The reflection coefficients $|Z_3|$ enjoys a similar pattern of variations in both theories.

Figure 8 is plotted to analyze the variations of modulus of energy ratios of reflected waves with the angle of incidence θ_0 lying in the registered range of incident coupled wave moving with velocity V_1 . The curves of energy ratios $|E_2|$ and $|E_3|$ are plotted after mounting up their original values by 10¹⁵ and 10¹⁹ respectively. It is noticed from the figure that the values of $|E_1|$ and sum are almost equal to 1.0 *i.e.* maximum energy is carried along reflected qP_1 wave. Since the reflection coefficients $|Z_2|$ and $|Z_3|$ are found

to be very small, therefore the corresponding energy ratios $|E_2|$ and $|E_3|$ are also very small in the entire range of angle of incidence except at grazing incidence, where their values are zero. It has been verified that at each angle of incidence $\sum_{i=1}^{3} E_i \approx 1$. Thus we conclude that energy balance law is verified for each angle of incidence.

Figure 9 is drawn to exhibit the variations of modulus of speed V_1 with frequency. It is found from the figure that initial stress parameter has caused a very little impact, while the temperature dependency of material constants has strongly influenced the velocity V_1 . The presence of temperature dependency of



Angle of incidence (in degree)

Deringer





Fig. 10 (**a**, **b**, **c**) Variations of moduli of phase speed V_1 with frequency

material constants has a decreasing impact on the profile of V_1 , while initial stress parameter has both increasing and decreasing effects. For better presentation, the variations of phase speed V_1 for MISTD, MIS and MTD cases have also been shown separately in Figs. 10a–c respectively. The frequency dependency of $|V_2|$ is demonstrated graphically in Fig. 11. It can be noticed from the figure that the curve of $|V_2|$ for MISTD case is lower than that for MTD case. This is

due to the effect of initial stress parameter. From the numerical values, it can be observed that the presence of temperature dependency of material constants has both increasing and decreasing impacts on $|V_2|$. In Fig. 12, a graphical representation is given for the variations of absolute values of velocity V_3 with frequency. We have observed from the figure that the curve of $|V_3|$ for MISTD case is higher than that for MIS case and lower than MTD case. The little



differences between absolute values of phase speed in MISTD and MTD cases show the small effect of initial stress. The values of $|V_3|$ show continuously increasing behavior with increasing frequency. The presence of temperature dependency of material constants has significantly increased the magnitude of $|V_3|$.

9 Concluding remarks

In this paper, a mathematical treatment has been presented to discuss the phenomena of elastic wave propagation in a fiber-reinforced thermoelastic medium under initial stress and temperature dependent properties. The expressions giving the reflection coefficients and energy ratios have been presented graphically. From the analysis of the illustrations, we can arrive at the following conclusions:

- Numerical results show that the reflection coefficients of various reflected waves are significantly affected by initial stress parameter and temperature dependence of material constants.
- Temperature dependence of material constants has an increasing effect on reflection coefficient $|Z_2|$ and $|Z_3|$, while decreasing effect is observed on reflection coefficient $|Z_1|$.

- While studying the numerical results, it is observed that the maximum amount of the incident energy goes along the reflected wave corresponding to the reflection coefficient $|Z_1|$.
- The modulus values of reflection coefficients $|Z_2|$ and $|Z_3|$ corresponding to an incident coupled wave are found to be small for LS theory as compared to GL theory, whereas, reverse happens for the reflection coefficient $|Z_1|$.
- The numerical results reveal that sum of the modulus values of energy ratios is approximately unity at each angle of incidence, thus proving the law of conservation of energy.
- It is apparent from the Figs. 10, 11, 12 that the numerical values of phase speeds V_2 and V_3 have decreased due to the presence of initial stress, while increasing and decreasing effects are observed on phase speed V_1 . Presence of temperature dependent material constants decreases the numerical values of the phase speed V_3 and has both increasing and decreasing effects on the profile of phase speed V_2 .

Wave phenomenon in a thermoelastic medium is of great practical importance in various technological and geophysical circumstances. The propagation of waves along with other geophysical and geothermal data carries information about the structure and distribution of underground magnum. The wave propagation as part of exploration seismology helps in various economic activities like tracing of hydrocarbons and other mineral ores which are essential for various developmental activities like construction of dams, huge buildings, roads, bridges, the design of highways as well as foundation problems in soil mechanics. The introduction of initial stress and temperature dependent material constants to the generalized thermoelastic medium provides a more realistic model for these studies. The present theoretical results may provide interesting information for experimental scientists / researchers/ seismologists working on this subject.

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