



An Efficient Spline Collocation Method for a Nonlinear Fourth-Order Reaction Subdiffusion Equation

Haixiang Zhang¹ · Xuehua Yang¹ · Da Xu²

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Abstract

The nonlinear fourth-order reaction–subdiffusion equation whose solutions display a typical initial weak singularity is considered. A new analytical technique is introduced to analyze orthogonal spline collocation (OSC) method based on L1 scheme on graded mesh. By introducing a discrete convolution kernel and discrete fractional Grönwall inequality, convergence of the scheme is proved rigorously. This novel analytical technique can provide new insights in analyzing other time fractional fourth-order differential equations with weakly singular solutions.

Keywords Fourth-order time fractional equation · Finite difference method · Collocation scheme · Convergence

Mathematics Subject Classification 65N12 · 65N30 · 35K61

1 Introduction

In the paper, we consider the following nonlinear fourth-order reaction–subdiffusion equation with initial singularity

$$\begin{cases} \partial_t^\alpha u + \Delta^2 u = \Delta u + f(u) + g(\mathbf{x}, t), & \mathbf{x} \in \Omega, t \in (0, T]; \\ u = u_0(\mathbf{x}), & \mathbf{x} \in \Omega, t = 0; \\ u = \Delta u = 0, & \mathbf{x} \in \partial\Omega, t \in (0, T]. \end{cases} \quad (1.1)$$

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✉ Xuehua Yang
hunanshidayang@163.com

¹ School of Science, Hunan University of Technology, Zhuzhou 412007, China

² Department of Mathematics, Hunan Normal University, Changsha 410081, China

Here, $\Omega \subset \mathbb{R}^d$ ($d = 1, 2$). Its closure is denoted by $\bar{\Omega}$. We assume that Ω has smooth boundary $\partial\Omega$ or is convex. $u_0 \in C(\bar{\Omega})$, g is the given function, the nonlinear function $f(u)$ is smooth, and $\partial_t^\alpha u$ denotes the Caputo fractional derivative

$$\partial_t^\alpha u(\mathbf{x}, t) = \int_0^t \omega_{1-\alpha}(t-s) \frac{\partial u(\mathbf{x}, s)}{\partial s} ds, \tag{1.2}$$

where $\omega_{1-\alpha}(t-s) = \frac{(t-s)^{-\alpha}}{\Gamma(1-\alpha)}$, $0 < \alpha < 1, t > 0$.

The nonlinear equation (1.1) possesses the fractional sub-diffusion and fourth-order derivative terms simultaneously, which makes it distinctive compared to general time-fractional sub-diffusion equations. For sub-diffusion equations with weakly singular solutions, their accurate numerical simulations have been the topic of much recent research, see references [1–5]. Yan et al. [6] established an improved L1 method for time fractional PDEs with nonsmooth data, then Xing and Yan modified this method to get a more higher order scheme in [7]. More recently, there are certain papers concerned with fourth-order fractional differential equations [8–13] and nonlinear sub-diffusions [14–19]. Ji et al. [20] proposed a high order FDM for fourth-order fractional sub-diffusion equations with the Dirichlet boundary conditions. In particular, Qiao et al. [21–23] derived ADI orthogonal spline collocation method for simulating the solution of multi-term time fractional integro-differential equation. However, they ignored a detailed issue and made the theoretical results without initial singularity. This is precisely the starting point of our present work.

We now consider the regularity of the exact solution u of (1.1) by introducing a corresponding linear problem, that is, set $f(u) + g(x, t) = f(x, t)$ in (1.1). According to earlier work of Luchko [24] and Sakamoto and Yamamoto [25], set $\{(\lambda_j, P_j) : j = 1, 2, \dots\}$ be the eigenvalues and eigenfunctions for the following problem

$$-\Delta P_j = \lambda_j P_j, \quad \text{on } \Omega \text{ with the boundary conditions } P_j|_{\partial\Omega} = 0,$$

with the eigenfunctions normalised by requiring $(P_j, P_j) = 1$ for all j , where (\cdot, \cdot) denotes the inner product in $L^2(\Omega)$. It is well known that the eigenvalues satisfy

$$0 < \lambda_1 < \lambda_2 < \dots < \lambda_j \rightarrow \infty.$$

Since $\{P_j : j = 1, 2, \dots\}$ form an orthogonal basis in $L^2(\Omega)$, then from the earlier work of An and Liu [26, Page 3327], $P_j, j = 1, 2, \dots$, is also an eigenfunction for the following problem

$$\Delta^2 P_j - \Delta P_j = \hat{\lambda}_j P_j, \quad \text{on } \Omega \text{ with the boundary conditions } P_j|_{\partial\Omega} = \Delta P_j|_{\partial\Omega} = 0,$$

where the eigenvalues $\hat{\lambda}_j = \lambda_j(\lambda_j + 1), j = 1, 2, \dots$

By using a standard separation of variables scheme (see [24, Eq. (4.29)] or [25, Eq. (2.11)], and imitating the Eq. (2.2) in [27], we can get

$$u(x, t) = \sum_{j=1}^{\infty} [(u_0, P_j) E_{\alpha,1}(-\hat{\lambda}_j t^\alpha) + J_{j,\alpha}(E_{\alpha,\alpha}; t)] P_j(x), \quad x \in \bar{\Omega}, \quad t \in [0, T]. \tag{1.3}$$

where

$$J_{j,\alpha}(E_{\alpha,\alpha}; t) = \int_0^t s^{\alpha-1} E_{\alpha,\alpha}(-\hat{\lambda}_j s^\alpha) f_j(t-s) ds,$$

where $f_j(t - s) = (f(\cdot, t - s), P_j(\cdot))$, and the generalized two-parameter Mittag-Leffler function $E_{\alpha, \beta}(z)$ [[28], Section 1.2] is defined by

$$E_{\nu, \beta}(z) = \sum_{i=0}^{\infty} \frac{z^i}{\Gamma(\nu i + \beta)}, \quad \nu > 0, \beta > 0, \quad z \in \mathbb{R}.$$

Set $\mathcal{L}P_j = \Delta^2 P_j - \Delta P_j$, by using the framework of sectorial operators [25], we define following fractional power \mathcal{L}^γ ($\gamma \in \mathbb{R}$) of the operator \mathcal{L} with domain

$$D(\mathcal{L}^\gamma) = \left\{ \varphi \in L^2(\Omega) : \sum_{j=1}^{\infty} \hat{\lambda}_j^{2\gamma} |(\varphi, P_j)|^2 < \infty, \gamma \in \mathbb{R} \right\},$$

and

$$\|\varphi\|_{\mathcal{L}^\gamma} = \left(\sum_{j=1}^{\infty} \hat{\lambda}_j^{2\gamma} |(\varphi, P_j)|^2 \right)^{\frac{1}{2}}, \quad \gamma \in \mathbb{R}.$$

Similar to [29, Section 6.1] (cf. [27, Section 2]), one can apply (1.3) and the theory of sectorial operators to get the following regularity of the solution to (1.1).

Let ℓ be a non-negative integer. For all $t \in (0, T]$, assume that $u_0 \in D(\mathcal{L}^{\ell+2})$, $\frac{\partial^l f(\cdot, t)}{\partial t^l} \in D(\mathcal{L}^\ell)$ and $\|u_0\|_{\mathcal{L}^{\ell+2}} + \|\frac{\partial^l f(\cdot, t)}{\partial t^l}\|_{\mathcal{L}^{\ell+1}} \leq c_0$ for $l = 1, 2$, where c_0 is a constant independent of t . Then we can make the following assumptions about the exact solution u of (1.1).

For $p = 1, 2, t \in (0, T], \ell \in \mathbb{N}_0 = \{0, 1, \dots\}$, and a constant c_0 , we assume

$$\|u(\cdot, t)\|_\ell \leq c_0, \quad \left\| \frac{\partial^p u(\cdot, t)}{\partial t^p} \right\|_\ell \leq c_0(1 + t^{\alpha-p}), \tag{1.4}$$

where the notation $\|\cdot\|_\ell$ is norm in the standard Sobolev space $H^\ell(\Omega)$.

The paper is organized as follows. In Sect. 2, inspired by L1 formula, L1-OSC scheme is presented. A new theoretical technique for our scheme is presented in Sect. 3. In Sect. 4, some numerical results are given.

2 The Fully Discrete Scheme Based on Orthogonal Spline Collocation

We set $\delta_x : a = x_0 < x_1 < \dots < x_{N_x} = b, \delta = \delta_x \times \delta_y$ in Ω be quasi-uniform, δ_y is similar to δ_x . Let $h_l^x = x_l - x_{l-1}, h_k^y = y_k - y_{k-1}, h = \max(\max_{1 \leq l \leq N_x} h_l^x, \max_{1 \leq k \leq N_y} h_k^y)$.

For $1 \leq k \leq N_x$, denote

$$\mathcal{M}_r(\delta_x) = \{v | v \in C^1(\bar{I}), v|_{[x_{k-1}, x_k]} \in P_r, r \geq 3\},$$

where $\bar{I} = [0, 1]$, and P_r is the set of polynomials of degree $\leq r$. Let

$$\mathcal{M}_r^0(\delta_x) = \{v | v \in \mathcal{M}_r(\delta_x), v(a) = v(b) = 0\},$$

with $\mathcal{M}_r^0(\delta_y)$ defined similarly. Set $\mathcal{M}_r(\delta) = \mathcal{M}_r(\delta_x) \otimes \mathcal{M}_r(\delta_y)$ and $\mathcal{M}_r^0(\delta) = \mathcal{M}_r^0(\delta_x) \otimes \mathcal{M}_r^0(\delta_y)$.

We now define collocation points set in Ω : $A_r = \{\zeta = (\zeta_x, \zeta_y), \zeta_x \in A_x, \zeta_y \in A_y\}$, where $A_x = \{\zeta_x^{i,k}\}_{i,k=1}^{N_x, r-1}, \zeta_x^{i,k} = x_{i-1} + \lambda_k h_i^x, \{\lambda_k\}_{k=1}^{r-1}$ are the nodes of the $(r - 1)$ -point Legendre quadrature rule. A_y defined similarly.

Set $\{\omega_i\}_{i=1}^{r-1}$ be weights of the Legendre quadrature rule and $\sum_{i=1}^{r-1} \omega_i = 1$, for $\forall \phi, \varphi$ on $\mathcal{M}_r^0(\delta)$, we define the following discrete inner product and norm,

$$\langle \phi, \varphi \rangle = \sum_{i=1}^{N_x} \sum_{j=1}^{N_y} h_i^x h_j^y \sum_{k=1}^{r-1} \sum_{l=1}^{r-1} \omega_k \omega_l (\phi \varphi)(\zeta_x^{i,k}, \zeta_y^{j,l}), \quad \|\phi\|_{\mathcal{M}_r}^2 = \langle \phi, \phi \rangle. \quad (2.5)$$

Let $\|\cdot\|$ be the usual L^2 norm, the norms $\|\cdot\|_{\mathcal{M}_r}$ and $\|\cdot\|$ is equivalent on $\mathcal{M}_r^0(\delta)$, see [30].

By introducing an auxiliary variable $v = \Delta u$, we split (1.1) into the following equivalent coupled system:

$$\begin{aligned} \partial_t^\alpha u + \Delta v &= \Delta u + f(u) + g(\mathbf{x}, t), & (\mathbf{x}, t) \in \Omega \times (0, T], \\ \text{and } v(\mathbf{x}, t) - \Delta u(\mathbf{x}, t) &= 0, & (\mathbf{x}, t) \in \Omega \times (0, T]. \end{aligned} \quad (2.6)$$

To derive discrete-time L1-OSC schemes, for any $K \in \mathbb{Z}^+$, grading constant $\check{r} \geq 1$ and $1 \leq n \leq K$, let $T_\tau = \{t_n | t_n = T(n/K)^{\check{r}}\}$, $\tau_n = t_n - t_{n-1}$, and $\tau_n \leq C_0 T K^{-\check{r}}(n-1)^{\check{r}-1}$, see [27, Eq. (5.1)]. Denote

$$\phi^n = \phi(\cdot, t_n), \quad a_{n-j}^{(n)} = \frac{\tau_j^{-1}}{\Gamma(1-\alpha)} \int_{t_{j-1}}^{t_j} \frac{ds}{(t_n - s)^\alpha}, \quad j = 1, \dots, n,$$

then, $\partial_t^\alpha \phi$ on graded mesh can be approximated by L1 scheme

$$D_K^\alpha \phi^n = \sum_{i=1}^n a_{n-i}^{(n)} (\nabla_t \phi^i) = a_0^{(n)} \phi^n - \sum_{i=0}^{n-1} (a_{n-i-1}^{(n)} - a_{n-i}^{(n)}) \phi^i, \quad (2.7)$$

where $a_n^{(n)} = 0, \nabla_t \phi^i = (\phi^i - \phi^{i-1})$.

By the Lemma 5.1 of [27], we know

$$|D_K^\alpha \phi^n - \partial_t^\alpha \phi(t_n)| \leq C_0 n^{-\min\{\check{r}\alpha, 2-\alpha\}}. \quad (2.8)$$

We now introduce a sequence of discrete convolution kernels as follow

$$\begin{aligned} b_0^{(n)} &= \tau_n^\alpha \Gamma(2-\alpha), \quad 1 \leq n \leq K, \\ b_{n-j}^{(n)} &= \tau_j^\alpha \Gamma(2-\alpha) \sum_{i=j+1}^n (a_{i-j-1}^{(i)} - a_{i-j}^{(i)}) b_{n-i}^{(n)}, \quad 1 \leq j \leq n-1, \end{aligned}$$

By Lemma 2.1 of [2], we can obtain

$$\begin{aligned} 0 < b_{n-j}^{(n)} &\leq \tau_j^\alpha \Gamma(2-\alpha), \quad \sum_{j=k}^n b_{n-j}^{(n)} a_{j-k}^{(j)} = 1, \quad 1 \leq n \leq K, \\ \text{and } \sum_{j=k}^n b_{n-j}^{(n)} \omega_{1+m\alpha-\alpha}(t_j) &\leq \omega_{1+m\alpha}(t_n), \quad m \geq 1, \quad 1 \leq n \leq K. \end{aligned} \quad (2.9)$$

Thus, using (2.7) and Newton linearization formula, we can construct following fully discrete L1-OSC scheme: seek $\{u_h^n, v_h^n\} \in \mathcal{M}_r^0(\delta) \times \mathcal{M}_r^0(\delta)$, such that, for $n = 1, 2, \dots, K$

$$\begin{aligned} D_K^\alpha u_h^n + \Delta v_h^n &= \Delta u_h^n + f'(u_h^{n-1})(u_h^n - u_h^{n-1}) + f(u_h^{n-1}) + g_h^n \text{ on } \Lambda_r, \\ \text{and } v_h^n &= \Delta u_h^n \text{ on } \Lambda_r, \end{aligned} \quad (2.10)$$

where g_h^n is a fitted approximation to $g(\cdot, t_n)$. Also, for $\forall \chi, \psi \in \mathcal{M}_r^0(\delta)$, we have

$$\begin{aligned} \langle D_K^\alpha u_h^n, \chi \rangle &= \langle \Delta u_h^n - \Delta v_h^n, \chi \rangle + \langle f'(u_h^{n-1})(u_h^n - u_h^{n-1}) + f(u_h^{n-1}) + g_h^n, \chi \rangle, \\ \text{and } \langle v_h^n, \psi \rangle &= \langle \Delta u_h^n, \psi \rangle, \end{aligned} \tag{2.11}$$

which will be applied to subsequent convergence analysis. (2.10) with the discrete initial and boundary conditions is a linear elliptic problem for every time level, the existence and uniqueness of the solution $\{u_h^j\}_{j=1}^{K-1}$ can be guaranteed by the Lax–Milgram lemma if h is sufficiently small or K sufficiently large.

3 Theoretical Analysis

Lemma 1 [2] *If the nonnegative sequences $\{\zeta_1^n, \zeta_2^n, | 1 \leq n \leq K\}$ are bounded, set $\tilde{\kappa}$ be a positive constant independent of n and the nonnegative constants κ_j satisfying $0 < \sum_{j=0}^{n-1} \kappa_j < \tilde{\kappa}, 1 \leq n \leq K$. If the nonnegative sequence $\{v^n\}_{n=0}^K$ satisfies*

$$\sum_{i=1}^n a_{n-i}^{(n)} \nabla_t (v^i)^2 \leq \sum_{j=1}^n \kappa_{n-j} (v^j)^2 + v^n \zeta_1^n + (\zeta_2^n)^2, \quad 1 \leq n \leq K, \tag{3.12}$$

then when the maximum temporal step size satisfies $\tau_K \leq (2\Gamma(2-\alpha)\tilde{\kappa})^{-1/\alpha}$, for $1 \leq n \leq K$, it holds

$$v^n \leq 2E_\alpha(2\tilde{\kappa}\tau_n^\alpha) \left(v^0 + \max_{1 \leq k \leq n} \sum_{j=1}^k b_{k-j}^{(k)} \zeta_1^j + \sqrt{\Gamma(1-\alpha)} \max_{1 \leq k \leq n} \{t_k^{\alpha/2} \zeta_2^k\} \right).$$

To derive convergence, first, define $\{\widehat{U}, \widehat{V}\}: [0, T] \rightarrow \mathcal{M}_r^0(\delta) \times \mathcal{M}_r^0(\delta)$ as

$$\langle \Delta(u - \widehat{U}), \chi \rangle = 0, \quad \langle \Delta(v - \widehat{V}), \psi \rangle = 0, \quad \psi, \chi \in \mathcal{M}_r^0(\delta), \tag{3.13}$$

where u and v are the solution of (2.6).

Let $\rho = v - \widehat{V}$ and $\eta = u - \widehat{U}$, then from [31], we have the following estimates on ρ and η and its time derivatives.

Lemma 2 [31] *If $\frac{\partial^i u}{\partial t^i}, \frac{\partial^j v}{\partial t^j} \in L^p(H^{r+3})$, for $t \in [0, T], i, j = 0, 1, 2, p = 2, \infty$, then*

$$\begin{aligned} \left\| \frac{\partial^{\ell+i} \eta}{\partial x^{\ell_1} \partial y^{\ell_2} \partial t^i} \right\|_{\mathcal{M}_r} &\leq C_u h^{r+1-\ell} \left\| \frac{\partial^i u}{\partial t^i} \right\|_{H^{r+3}}, \\ \text{and } \left\| \frac{\partial^{\ell+j} \rho}{\partial x^{\ell_1} \partial y^{\ell_2} \partial t^j} \right\|_{\mathcal{M}_r} &\leq C_v h^{r+1-\ell} \left\| \frac{\partial^j v}{\partial t^j} \right\|_{H^{r+3}}, \end{aligned} \tag{3.14}$$

where the constants C_u and C_v are independent of h and the time step, and $0 \leq \ell = \ell_1 + \ell_2 \leq 4$.

Set

$$\begin{aligned} u(t_n) - u_h^n &= (u(t_n) - \widehat{U}^n) - (u_h^n - \widehat{U}^n), \quad 1 \leq n \leq K, \\ \eta^n &= u(t_n) - \widehat{U}^n, \quad \xi^n = (u_h^n - \widehat{U}^n), \quad 1 \leq n \leq K, \end{aligned} \tag{3.15}$$

and

$$\begin{aligned} v(t_n) - v_h^n &= (v(t_n) - \widehat{V}^n) - (v_h^n - \widehat{V}^n), \quad 1 \leq n \leq K, \\ \rho^n &= (v(t_n) - \widehat{V}^n), \quad \theta^n = (v_h^n - \widehat{V}^n), \quad 1 \leq n \leq K. \end{aligned} \tag{3.16}$$

Now we state our main results.

Theorem 1 *Suppose $u(\cdot, t_n)$ are the solutions of (2.6) with the regularity property (1.4), the nonlinear function $f \in C^2(\mathbb{R})$, and $u(\cdot, t) \in L^\infty(\mathbb{R}^d)$ for $t \in (0, T]$. Let u_h^n be the discrete solutions of (2.11). If the maximum temporal step size satisfies $\tau_K \leq (4\Gamma(2 - \alpha)\hat{\kappa}_+)^{-1/\alpha}$, where $\hat{\kappa}_+$ is defined in (3.27). Then*

$$\|u(t_n) - u_h^n\| \leq c_0(K^{-\min\{\tilde{r}\alpha, 2-\alpha\}} + h^{r+1}), \quad 1 \leq n \leq K, \tag{3.17}$$

provided u_h^0 is chosen so that $\|u^0 - \widehat{U}^0\| \leq c_0 h^{r+1}$.

Proof Since the estimates of η^n and ρ^n are known by Lemma 2, then we need only to estimate ξ^n and θ^n . First, for $1 \leq n \leq K$, taking $t = t_n$ in (2.6), and using (2.11), (3.13) and (3.15), we obtain

$$\begin{aligned} \langle D_K^\alpha \xi^n, \chi \rangle &= \langle \Delta \xi^n, \chi \rangle - \langle \Delta \theta^n, \chi \rangle + \langle D_K^\alpha \eta^n, \chi \rangle + \langle \phi^n + R^n, \chi \rangle, \quad \forall \chi \in \mathcal{M}_r^0(\delta), \\ \text{and } \langle \theta^n, \psi \rangle &= \langle \Delta \xi^n, \psi \rangle + \langle \rho^n, \psi \rangle, \quad \forall \psi \in \mathcal{M}_r^0(\delta), \end{aligned}$$

where

$$\begin{aligned} R^n &= D_K^\alpha u^n - \partial_t^\alpha u(x, t_n) + f(u^n) - (f'(u^{n-1})(u^n - u^{n-1}) + f(u^{n-1})), \\ \phi^n &= f(u^{n-1}) + (u^n - u^{n-1})f'(u^{n-1}) - (u_h^n - u_h^{n-1})f'(u_h^{n-1}) - f(u_h^{n-1}). \end{aligned}$$

Taking $\chi = \xi^n, \psi = \theta^n$ and adding, we attain

$$\begin{aligned} \langle D_K^\alpha \xi^n, \xi^n \rangle + \langle \theta^n, \theta^n \rangle &- \langle \Delta \xi^n, \xi^n \rangle \\ &= -\langle \Delta \theta^n, \xi^n \rangle + \langle \Delta \xi^n, \theta^n \rangle + \langle D_K^\alpha \eta^n + \phi^n + R^n, \xi^n \rangle + \langle \rho^n, \theta^n \rangle, \quad 1 \leq n \leq K. \end{aligned} \tag{3.18}$$

From [32, Eq. (3.4)] or [33, Eq. (2.3) in Lemma 2.1], for $\forall \varpi, \sigma \in \mathcal{M}_r^0(\delta)$, we have

$$-\langle \Delta \varpi, \sigma \rangle + \langle \Delta \sigma, \varpi \rangle = 0, \tag{3.19}$$

on using (3.19) with $\varpi = \theta^n, \sigma = \xi^n$, we have

$$-\langle \Delta \theta^n, \xi^n \rangle + \langle \Delta \xi^n, \theta^n \rangle = 0, \quad 1 \leq n \leq K,$$

then, (3.18) can be rewritten as

$$\begin{aligned} \langle D_K^\alpha \xi^n, \xi^n \rangle + \langle \theta^n, \theta^n \rangle &- \langle \Delta \xi^n, \xi^n \rangle \\ &= \langle D_K^\alpha \eta^n + \phi^n + R^n, \xi^n \rangle + \langle \rho^n, \theta^n \rangle, \quad 1 \leq n \leq K. \end{aligned} \tag{3.20}$$

From [32, Eq. (3.5)] or [33, Eq. (2.4) in Lemma 2.1], for $\forall \vartheta \in \mathcal{M}_r^0(\delta)$, there exists a positive constant c such that

$$-\langle \Delta \vartheta, \vartheta \rangle \geq c \|\nabla \vartheta\|^2 \geq 0, \tag{3.21}$$

on using (3.21) with $\vartheta = \xi^n$, then

$$-\langle \Delta \xi^n, \xi^n \rangle \geq \|\nabla \xi^n\|^2 \geq 0, \quad 1 \leq n \leq K. \tag{3.22}$$

By the proof of Lemma 4.1 in [34], we obtain

$$2 \langle D_K^\alpha \xi^n, \xi^n \rangle \geq \sum_{i=1}^n a_{n-i}^{(n)} \nabla_t (\|\xi^i\|_{\mathcal{M}_r}^2), \quad 1 \leq n \leq K. \tag{3.23}$$

Thus, combining (3.20), (3.22) and (3.23), and using Cauchy–Schwarz and Young inequalities, we have

$$\begin{aligned} & \frac{1}{2} \sum_{i=1}^n a_{n-i}^{(n)} \nabla_t (\|\xi^i\|_{\mathcal{M}_r}^2) + \|\theta^n\|_{\mathcal{M}_r}^2 \\ & \leq (\|D_K^\alpha \eta^n\|_{\mathcal{M}_r} + \|\phi^n\|_{\mathcal{M}_r} + \|R^n\|_{\mathcal{M}_r}) \|\xi^n\|_{\mathcal{M}_r} + \frac{1}{4} \|\rho^n\|_{\mathcal{M}_r}^2 + \|\theta^n\|_{\mathcal{M}_r}^2, \quad 1 \leq n \leq K. \end{aligned} \tag{3.24}$$

By the use of the first condition in (1.4), we obtain

$$\begin{aligned} & \|(u^{n-1} - u_h^{n-1}) f'(su^{n-1} + (1-s)u_h^{n-1})\|_{\mathcal{M}_r} \\ & \leq c_0 (\|\eta^{n-1}\|_{\mathcal{M}_r} + \|\xi^{n-1}\|_{\mathcal{M}_r}), \quad 1 \leq n \leq K, \\ & \|f'(u_h^{n-1})(u^n - u_h^n - (u^{n-1} - u_h^{n-1}))\|_{\mathcal{M}_r} \\ & \leq c_0 (\|\eta^n\|_{\mathcal{M}_r} + \|\xi^n\|_{\mathcal{M}_r} + \|\eta^{n-1}\|_{\mathcal{M}_r} + \|\xi^{n-1}\|_{\mathcal{M}_r}), \quad 1 \leq n \leq K, \end{aligned}$$

and

$$\begin{aligned} & \|(u^n - u^{n-1})(u^{n-1} - u_h^{n-1}) f''(su^{n-1} + (1-s)u_h^{n-1})\|_{\mathcal{M}_r} \\ & \leq 2K_0 c_0 (\|\eta^{n-1}\|_{\mathcal{M}_r} + \|\xi^{n-1}\|_{\mathcal{M}_r}), \quad 1 \leq n \leq K, \end{aligned}$$

where $K_0 = \max_{0 \leq n \leq K} \|u^n\|_{L^\infty} + 1$.

Since

$$\begin{aligned} \|\phi^n\|_{\mathcal{M}_r} &= \|f(u^{n-1}) - f(u_h^{n-1}) + (f'(u^{n-1}) - f'(u_h^{n-1}))(u^n - u^{n-1}) \\ & \quad + f'(u_h^{n-1})(u^n - u_h^n - (u^{n-1} - u_h^{n-1}))\|_{\mathcal{M}_r} \\ & \leq \|(u^{n-1} - u_h^{n-1}) \int_0^1 f'(su^{n-1} + (1-s)u_h^{n-1}) ds\|_{\mathcal{M}_r} \\ & \quad + \|(u^n - u^{n-1})(u^{n-1} - u_h^{n-1}) \int_0^1 f''(su^{n-1} + (1-s)u_h^{n-1}) ds\|_{\mathcal{M}_r} \\ & \quad + \|f'(u_h^{n-1})(u^n - u_h^n - (u^{n-1} - u_h^{n-1}))\|_{\mathcal{M}_r}, \quad 1 \leq n \leq K. \end{aligned}$$

Thus, using Lemma 2, we obtain

$$\begin{aligned} \|\phi^n\|_{\mathcal{M}_r} & \leq c_0 \|\xi^n\|_{\mathcal{M}_r} + (2c_0 + 2c_0 K_0) \|\xi^{n-1}\|_{\mathcal{M}_r} \\ & \quad + (3c_0 + 2c_0 K_0) h^{r+1} \|u\|_{H^{r+3}}, \quad 1 \leq n \leq K. \end{aligned} \tag{3.25}$$

By combining (3.24) and (3.25), we obtain

$$\begin{aligned} & \frac{1}{2} \sum_{i=1}^n a_{n-i}^{(n)} \nabla_t (\|\xi^i\|_{\mathcal{M}_r}^2) \\ & \leq (\|D_K^\alpha \eta^n\|_{\mathcal{M}_r} + \|R^n\|_{\mathcal{M}_r}) \|\xi^n\|_{\mathcal{M}_r} + (c_0 \|\xi^n\|_{\mathcal{M}_r} + (2c_0(1 + K_0)) \|\xi^{n-1}\|_{\mathcal{M}_r} \\ & \quad + (3c_0 + 2c_0 K_0) h^{r+1} \|u\|_{H^{r+3}}) \|\xi^n\|_{\mathcal{M}_r} + \frac{1}{4} \|\rho^n\|_{\mathcal{M}_r}^2 \end{aligned}$$

$$\begin{aligned} &\leq (2c_0 + c_0 K_0) \|\xi^n\|_{\mathcal{M}_r}^2 + (c_0 + c_0 K_0) \|\xi^{n-1}\|_{\mathcal{M}_r}^2 \\ &\quad + (c_1(3c_0 + 2c_0 K_0)h^{r+1} + \|D_K^\alpha \eta^n\|_{\mathcal{M}_r} + \|R^n\|_{\mathcal{M}_r}) \|\xi^n\|_{\mathcal{M}_r} + \frac{1}{4} \|\rho^n\|_{\mathcal{M}_r}^2, \quad 1 \leq n \leq K, \end{aligned}$$

which has the form of (3.12), then using the discrete fractional Grönwall inequality of Lemma 1, we obtain

$$\begin{aligned} &\|\xi^n\|_{\mathcal{M}_r} \\ &\leq 4E_\alpha(2\hat{k}_+ t_n^\alpha) \left(\|\xi^0\|_{\mathcal{M}_r} + \frac{\sqrt{\Gamma(1-\alpha)}}{4} \max_{1 \leq k \leq n} \{t_k^{\alpha/2} \|\rho^k\|_{\mathcal{M}_r}\} \right. \\ &\quad \left. + \max_{1 \leq k \leq n} \sum_{j=1}^k b_{k-j}^{(k)} (c_1(3c_0 + 2c_0 K_0)h^{r+1} + \|D_K^\alpha \eta^n\|_{\mathcal{M}_r} + \|R^n\|_{\mathcal{M}_r}) \right), \quad 1 \leq n \leq K, \end{aligned} \tag{3.26}$$

where

$$\hat{k}_+ = c_0(3 + 2K_0). \tag{3.27}$$

We now proceed to estimate the terms on the RHS of (3.26). By using the definition (2.7) and (2.9), we have

$$\begin{aligned} \sum_{j=1}^n b_{n-j}^{(n)} \|D_K^\alpha \eta^j\|_{\mathcal{M}_r} &\leq \sum_{j=1}^n b_{n-j}^{(n)} \sum_{k=1}^j a_{j-k}^{(j)} \|\nabla_t \eta^k\|_{\mathcal{M}_r} \\ &= \sum_{j=1}^n \|\nabla_t \eta^j\|_{\mathcal{M}_r}, \quad 1 \leq n \leq K. \end{aligned} \tag{3.28}$$

Moreover, by Lemma 2 and (1.4), we have

$$\begin{aligned} \sum_{j=1}^n \|\nabla_t \eta^j\|_{\mathcal{M}_r} &= \sum_{j=1}^n \left\| \int_{t_j}^{t_{j-1}} \frac{\partial \eta}{\partial s}(s) ds \right\|_{\mathcal{M}_r} \\ &\leq \sum_{j=1}^n \int_{t_j}^{t_{j-1}} \left\| \frac{\partial \eta}{\partial s}(s) \right\|_{\mathcal{M}_r} ds \leq C_0 h^{r+1} (t_n + t_n^\alpha/\alpha), \quad 1 \leq n \leq K. \end{aligned}$$

For the term R^n , $1 \leq n \leq K$, by using (2.8), we have

$$\begin{aligned} &\sum_{j=1}^n b_{n-j}^{(n)} \|D_K^\alpha u^j - \partial_t^\alpha u(x, t_j)\| \\ &\leq \sum_{j=1}^n b_{n-j}^{(n)} \omega_{1-\alpha}(t_j) \max_{1 \leq k \leq n} \frac{\|D_K^\alpha u^k - \partial_t^\alpha u(x, t_k)\|}{\omega_{1-\alpha}(t_k)} \\ &\leq \Gamma(1-\alpha) \max_{1 \leq k \leq n} t_k^\alpha \|D_K^\alpha u^k - \partial_t^\alpha u(x, t_k)\| \\ &\leq c_0 \Gamma(1-\alpha) T^\alpha N^{-\min\{\tilde{r}\alpha, 2-\alpha\}}, \quad 1 \leq n \leq K. \end{aligned} \tag{3.29}$$

Set $\tilde{R}^n = f(u^n) - f(u^{n-1}) - f'(u^{n-1})(u^n - u^{n-1})$, $1 \leq n \leq K$, it follows from the Taylor expansion with integral remainder

$$\tilde{R}^j = (u^j - u^{j-1})^2 \int_0^1 f''(s(u^j - u^{j-1}) + u^{j-1})(1-s) ds, \quad j \geq 1.$$

By the regularity conditions (1.4), we have

$$|\tilde{R}^1| \leq c_0 \left(\int_{t_0}^{t_1} |u'(t)| dt \right)^2 \leq C(\tau_1^2 + \tau_1^{2\alpha} / \alpha^2),$$

$$\text{and } |\tilde{R}^j| \leq c_0 \left(\int_{t_{j-1}}^{t_j} |u'(t)| dt \right)^2 \leq C(\tau_j^2 + t_{j-1}^{2\alpha-2} \tau_j^2), \quad 2 \leq j \leq K.$$

By (2.12) of [14], for $1 \leq n \leq K$, the expression $\sum_{j=1}^n b_{n-j}^{(n)} \leq \frac{t_n^\alpha}{\Gamma(1+\alpha)}$ is true, then,

$$\begin{aligned} \sum_{j=1}^n b_{n-j}^{(n)} \|\tilde{R}^j\| &\leq b_{n-1}^{(n)} \|\tilde{R}^1\| + \sum_{j=2}^n b_{n-j}^{(n)} \|\tilde{R}^j\| \\ &\leq c_0 \tau_1^\alpha \|\tilde{R}^1\| + c_0 t_n^\alpha \max_{2 \leq j \leq n} \|\tilde{R}^j\| \\ &\leq c_0 \tau_1^\alpha (\tau_1^2 + \tau_1^{2\alpha} / \alpha^2) + c_0 t_n^\alpha \max_{2 \leq j \leq n} (\tau_j^2 + t_{j-1}^{2\alpha-2} \tau_j^2), \quad 1 \leq n \leq K, \end{aligned}$$

thus,

$$\begin{aligned} \sum_{j=1}^n b_{n-j}^{(n)} \|\tilde{R}^j\| &\leq c_0 \tau_1^{3\alpha} + c_0 t_n^\alpha \max_{2 \leq j \leq n} (\tau_j^2 + t_{j-1}^{2\alpha-2} \tau_j^2) \\ &\leq c_0 \tau_1^{3\alpha} + c_0 \tau_n^2 \\ &\leq c_0 K^{-\min\{3\tilde{r}\alpha, 2\}}, \quad 1 \leq n \leq K. \end{aligned} \tag{3.30}$$

Notice that the conditions of theorem about ξ^0 , then, with the help of Lemma 2, for $1 \leq n \leq K$, we obtains

$$\begin{aligned} \|\xi^n\|_{\mathcal{M}_r} &\leq 4E_\alpha(2\hat{\kappa}_+ t_n^\alpha) ((c_1 \Gamma(1-\alpha) t_n^{\alpha/2} / 4 + \Gamma(1-\alpha) T^\alpha (3c_0 + 2c_0 K_0)) h^{r+1} \\ &\quad + (t_n + t_n^\alpha / \alpha) h^{r+1} + c_0 \Gamma(1-\alpha) T^\alpha K^{-\min\{\tilde{r}\alpha, 2-\alpha\}} + c_0 K^{-\min\{3\tilde{r}\alpha, 2\}}). \end{aligned}$$

Therefore, using triangle inequality, Lemma 2, and the equivalence of norms on $\mathcal{M}_r^0(\delta)$ complete the proof. □

Remark 1 The hypothesis $u(\cdot, t) \in L^\infty(\mathbb{R}^d)$ for $t \in (0, T]$ means there exists a constant $C_0 > 0$ such that $\|u\|_{L^\infty} \leq C_0$. This hypothesis is proper because the value of u is bounded in the real applications. For example, for the nonlinear term $f(u) = u(1-u)$ in problem (4.32), we have $f'(u) = 1-2u$, $f''(u) = -2$, and $\|1-2u\| \leq 1+2\|u\|_{L^\infty} \leq C_0$, $\|f''(u)\| = 2 \leq C_0$. For the nonlinear term $f(u) = u(1-u)(u-1)$ in problem (3.33), we have $f'(u) = -1+4u-3u^2$, $f''(u) = 4-6u$, and $\|-1+4u-3u^2\| \leq (1+3\|u\|_{L^\infty})(1+\|u\|_{L^\infty}) \leq C_0$, $\|4-6u\| \leq 4+6\|u\|_{L^\infty} \leq C_0$. This indicates the proposed L1-OSC method is able to ensure the unconditionally stable and convergence for problem (4.32) and problem (3.33) according to the proof of Theorem 1.

4 Numerical Experiments

We employ the space of piecewise Hermite cubics, $\mathcal{M}_3^0(\delta)$, to present our numerical results with graded mesh $t_n = T(n/K)^{\tilde{r}}$.

Table 1 Convergent results in time with $h = 1/100$ for Example 1 in the case $\alpha = \beta$

α, β	K	L^2	Rate	L^∞	Rate
$\alpha = \beta = 0.8$	64	1.2993e-05		1.8371e-07	
	128	5.9036e-06	1.1381	8.3478e-07	1.1380
	256	2.6312e-06	1.1659	3.7208e-08	1.1658
	512	1.1555e-06	1.1872	1.6340e-08	1.1872
	1024	5.0669e-07	1.1893	7.1656e-09	1.1892
	2048	2.2134e-07	1.1948	3.1302e-09	1.1948
$\alpha = \beta = 0.6$	64	1.9921e-06		2.8124e-06	
	128	8.7801e-07	1.1820	1.2405e-06	1.1809
	256	3.6697e-07	1.2586	5.1867e-07	1.2580
	512	1.4775e-07	1.3125	2.0887e-07	1.3122
	1024	5.8164e-08	1.3450	8.2239e-08	1.3447
	2048	2.2758e-08	1.3538	3.2179e-08	1.3537

Example 1 We consider the following fourth-order nonlinear subdiffusion equation with $(x, t) \in (0, 1) \times (0, 1]$,

$$\partial_t^\alpha u + \Delta^2 u = \Delta u + \frac{1}{2 + \cos(u)} + g(x, t), \tag{4.31}$$

subject to zero-valued boundary, and initial data and the source function $g(x, t)$ are given from the exact solution $u(x, t) = (\omega_{1+\beta}(t) + \omega_{2+\beta}(t)) \sin(\pi x)$, $\beta \in (0, 1)$ is the regularity parameter.

First, the temporal errors and rate of convergence are shown in Tables 1, 2 and 3 for $1/h = 100$ and $\check{\gamma} = 2 - \alpha/\alpha$. Table 1 considers the case of $\beta = \alpha = 0.6, 0.8$; Table 2 considers the case of $\alpha = 0.8$ fixed and β changing; Table 3 considers the case of $\beta = 0.8$ fixed and α changing. The orders of convergence displayed in Tables 1, 2 and 3 indicate that the rate of convergence is $K^{-(2-\alpha)}$, which match with our theoretical analysis in convergence Theorem.

Taking $K = \lfloor h^{\frac{4}{\alpha-2}} \rfloor$ and $\check{\gamma} = 2 - \alpha/\alpha$, we show the spatial errors and rate of convergence in Table 4. The $O(h^4)$ convergence are observed, again as predicted by convergence Theorem.

Example 2 We consider the following fourth-order fractional Fisher-type equation with $(x, t) \in (0, 1) \times (0, 1]$,

$$\partial_t^\alpha u + \Delta^2 u = \Delta u + u(1 - u) + g(x, t), \tag{4.32}$$

subject to zero-valued boundary, and initial data and the source function $g(x, t)$ are given from the exact solution $u(x, t) = \sin(\pi x)\omega_{1+\beta}(t)$, $\beta \in (0, 1) \cup (1, 2)$ is the regularity parameter.

The computational parameters are listed as follows.

- Table 5: $K = \lfloor h^{\frac{4}{\alpha-2}} \rfloor$, $\check{\gamma} = 2 - \alpha/\alpha$, $\beta = \alpha = 0.4, 0.6, 0.8$.
- Table 6: $1/h = 100$, $\check{\gamma} = 2 - \alpha/\alpha$, $\beta = \alpha = 0.4, 0.6, 0.8$.
- Figure 1: $1/h = 32$, $K = \lfloor h^{\frac{4}{\alpha-2}} \rfloor$, $\check{\gamma} = 2 - \alpha/\alpha$, $\beta = \alpha = 0.4$.

Table 2 Convergent results in time with $h = 1/100$ for Example 1 in the case of α fixed

$\alpha = 0.8$	β	K	L^2	Rate	L^∞	Rate
	$\beta = 0.6$	64	7.1847e-06		1.0157e-05	
		128	3.3258e-06	1.1112	4.7024e-06	1.1110
		256	1.4965e-06	1.1521	2.1161e-06	1.1520
		512	6.6019e-07	1.1806	9.3360e-07	1.1805
		1024	2.9012e-07	1.1862	4.1029e-07	1.1862
		2048	1.2686e-07	1.1934	1.7940e-07	1.1935
	$\beta = 0.4$	64	2.4744e-06		3.4964e-06	
		128	1.2008e-06	1.0431	1.6975e-06	1.0425
		256	5.4324e-07	1.1443	7.6807e-07	1.1441
		512	2.3416e-07	1.2141	3.3111e-07	1.2139
		1024	9.8478e-08	1.2496	1.3926e-07	1.2495
		2048	4.0251e-08	1.2908	5.6920e-08	1.2908

Table 3 Convergent results in time with $h = 1/100$ for Example 1 in the case of β fixed

$\beta = 0.8$	α	K	L^2	Rate	L^∞	Rate
	$\alpha = 0.6$	64	4.0712e-06		5.7522e-06	
		128	1.6718e-06	1.2841	2.3629e-06	1.2836
		256	6.7197e-07	1.3149	9.4996e-07	1.3146
		512	2.6428e-07	1.3463	3.7366e-07	1.3461
		1024	1.0243e-08	1.3674	1.4484e-07	1.3673
		2048	3.9568e-08	1.3722	5.5953e-08	1.3722
	$\alpha = 0.4$	64	5.3417e-07		7.5059e-07	
		128	2.4928e-07	1.0995	3.5132e-07	1.0952
		256	1.0173e-07	1.2930	1.4356e-07	1.2911
		512	3.8632e-08	1.3969	5.4557e-08	1.3958
		1024	1.4161e-08	1.4479	2.0007e-08	1.4473
		2048	5.1729e-09	1.4529	7.3106e-09	1.4524

- Figure 2: For the fixed $K = 8, 16, 32, 64, N = 16, 32, 64, 128, 256, \check{r} = 2 - \alpha/\alpha, \beta = \alpha = 0.4$.
- Figure 3: For the fixed $K = 32, 64, 128, 256, N = 16, 32, 64, 128, 256, \check{r} = 2 - \alpha/\alpha, \beta = \alpha = 0.6$.

From Tables 5 and 6, we find that the numerical results match with our theoretical analysis of convergence Theorem. In Fig. 1 we draw the error figure in $\max_{1 \leq k \leq K} \|u_h^k - u^k\|_{L^\infty}$ for $1/h = 32, K = \lfloor h^{\frac{4}{\alpha-2}} \rfloor, \check{r} = 2 - \alpha/\alpha, \beta = \alpha = 0.4$. We can conclude that our proposed L1-OSC method can approximate well for the solution.

Further, we confirm the unconditional convergence of our proposed method for different α . The L^2 errors are given in Figs. 2 and 3 for $\alpha = 0.4, 0.6$. We find that for a fixed K , the L^2 errors asymptotically tend to a constant, that is to say that, there is no time-step restrictions for our scheme dependent on the spatial mesh size h .

Table 4 Errors and convergence results in spatial direction for Example 1

α, β	K	L^2	Rate	L^∞	Rate
$\alpha = 0.4$	4	1.6739e-04		2.3670e-04	
$\beta = 0.4$	8	9.4310e-06	4.1497	1.3337e-05	4.1496
	16	5.7592e-07	4.0335	8.1443e-07	4.0335
	32	3.5838e-08	4.0063	5.0681e-08	4.0063
$\alpha = 0.3$	4	1.5694e-04		2.2193e-04	
$\beta = 0.6$	8	8.8537e-06	4.1478	1.2520e-05	4.1478
	16	5.4223e-07	4.0293	7.6678e-07	4.0293
	32	3.3822e-08	4.0029	4.7829e-08	4.0029
$\alpha = 0.6$	4	1.6229e-04		2.2950e-04	
$\beta = 0.6$	8	9.1480e-06	4.1490	1.2937e-05	4.1489
	16	5.5729e-07	4.0370	7.8810e-07	4.0370
	32	3.4660e-08	4.0071	4.9014e-08	4.0071
$\alpha = 0.4$	4	1.4785e-04		2.0907e-04	
$\beta = 0.8$	8	8.3808e-06	4.1409	1.1851e-05	4.1409
	16	5.1315e-07	4.0296	7.2567e-07	4.0296
	32	3.1969e-08	4.0046	4.5209e-08	4.0046

Table 5 L^2 norm convergent results in space with $K = \lfloor h^{\frac{4}{\alpha-2}} \rfloor$ for Example 2

	$1/h = 4$	$1/h = 8$	$1/h = 16$	$1/h = 32$	$1/h = 64$
$\alpha = 0.4$	1.0015e-04	5.5854e-06	3.3866e-07	2.0994e-08	1.3110e-09
order		4.1644	4.0438	4.0118	4.0012
$\alpha = 0.6$	9.9112e-05	5.4893e-06	3.3245e-07	2.0611e-08	1.2874e-09
order		4.1744	4.0454	4.0117	4.0009
$\alpha = 0.8$	9.4815e-05	1.2753e-06	3.2025e-07	1.9872e-08	1.2417e-09
order		4.1678	4.0420	4.0104	4.0004

Example 3 In the example, we consider the following fourth-order fractional Huxley-type equation (2.6) with $x = (x_1, x_2) \in (0, 1) \times (0, 1), t \in (0, 1]$.

$$\partial_t^\alpha u + \Delta^2 u = \Delta u + u(1 - u)(u - 1) + g(x, t), \tag{3.33}$$

subject to zero-valued boundary, and initial data and the function $g(x, t)$ are determined by the exact solution $u(x, t) = \sin(\pi x_1) \sin(\pi x_2) \omega_{1+\beta}(t), \beta \in (0, 1) \cup (1, 2)$ is the regularity parameter.

The computational parameters are listed as follows.

- Table 7: $K = \lfloor h^{\frac{4}{\alpha-2}} \rfloor, \check{r} = 2 - \alpha/\alpha$ for different α and β .
- Table 8: $1/h = 100, \check{r} = 2 - \alpha/\alpha$ for different α and β .
- Figure 4: For the fixed $K = 32, 64, 128, 256, N = 16, 32, 64, 128, 256, \check{r} = 2 - \alpha/\alpha, \beta = \alpha = 0.6$.
- Figure 5: For the fixed $K = 32, 64, 128, 256, N = 16, 32, 64, 128, 256, \check{r} = 2 - \alpha/\alpha, \beta = \alpha = 0.8$.

Table 6 Convergent results in time with $h = 1/100$ for Example 2

$\alpha = \beta$	K	L^2	Rate	L^∞	Rate
0.4	64	4.6475e-07		5.7092e-07	
	128	1.4953e-07	1.4366	2.1110e-07	1.4354
	256	5.3216e-08	1.4905	7.5164e-08	1.4898
	512	1.8456e-08	1.5278	2.6077e-08	1.5273
	1024	6.2145e-09	1.5704	8.7826e-09	1.5701
	2048	2.0506e-09	1.5996	2.8992e-09	1.5990
0.6	64	1.1713e-06		1.6527e-06	
	128	5.5454e-07	1.0787	7.8330e-07	1.0772
	256	2.3922e-07	1.2130	3.3807e-07	1.2122
	512	9.7865e-08	1.2893	1.3834e-07	1.2891
	1024	3.8713e-08	1.3380	5.4732e-08	1.3378
	2048	1.4814e-08	1.3859	2.0945e-08	1.3858
0.8	64	2.4747e-06		3.4902e-06	
	128	1.2233e-06	1.0165	1.7286e-06	1.0137
	256	5.9747e-07	1.0338	8.4459e-07	1.0333
	512	2.7537e-07	1.1175	3.8934e-07	1.1172
	1024	1.2387e-07	1.1525	1.7515e-07	1.1524
	2048	5.4761e-08	1.1776	7.7437e-08	1.1775

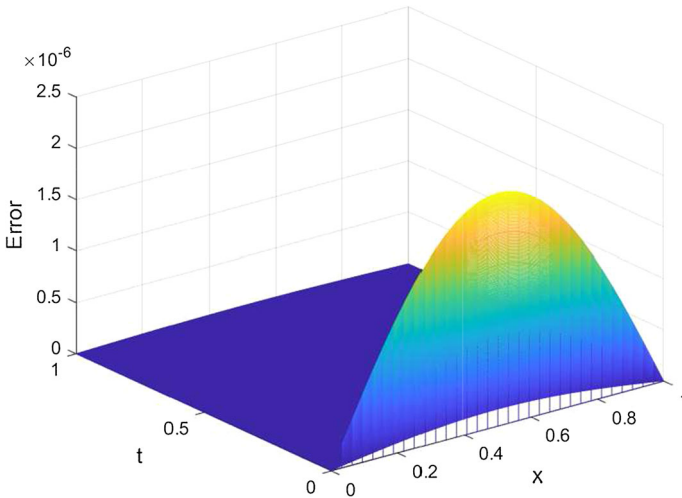


Fig. 1 The global error at $\alpha = 0.4$ in time and space for Example 2

The numerical errors and convergence orders are given in Tables 7 and 8, we find that the numerical results match with our theoretical analysis of convergence Theorem. Again, to further confirm the unconditional convergence of our proposed method for different α , the L^2 errors are shown in Figs. 4 and 5 for $\alpha = 0.6, 0.8$. The figures results present that for a fixed K , the errors in L^2 -norm asymptotically tend to a constant, which implies that there is no time-step restrictions for our proposed scheme dependent on the spatial mesh size h . Those results further confirm our theoretical analysis.

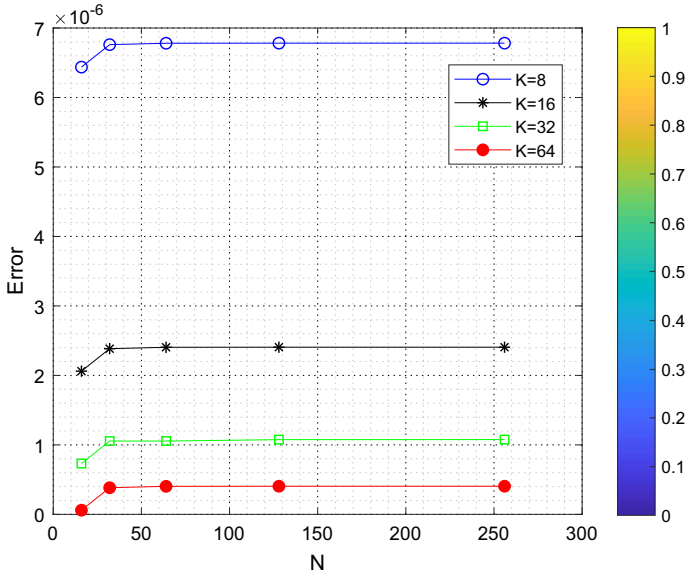


Fig. 2 The L^2 error at $\alpha = 0.4$ for Example 2

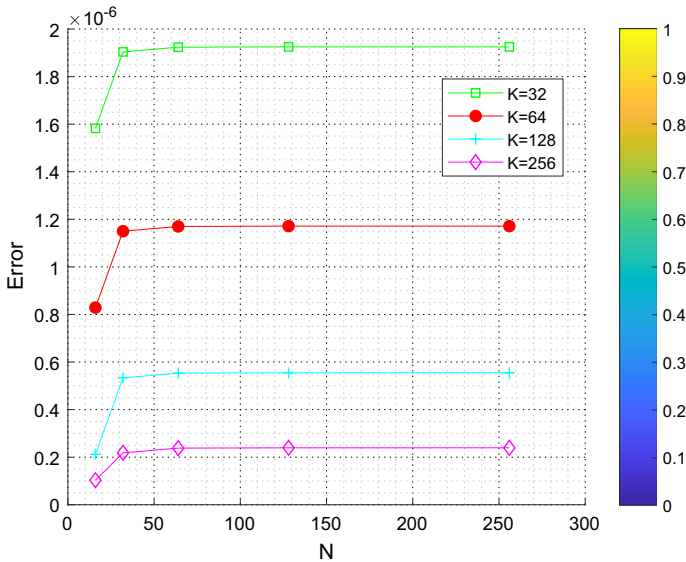


Fig. 3 The L^2 error at $\alpha = 0.6$ for Example 2

5 Conclusion

In order to effectively solve nonlinear fourth-order reaction–subdiffusion equation whose solutions display a typical initial weak singularity, we introduce the orthogonal spline collocation method to discrete the spatial variable and the L1-scheme on graded meshes to discrete the time-fractional Caputa derivative, the Newton linearized scheme to approxi-

Table 7 Errors and convergence results in spatial direction for Example 3

α, β	K	L^2	Rate	L^∞	Rate
$\alpha = 0.4$	4	9.8035e-05		1.3867e-04	
$\beta = 0.4$	8	5.4502e-06	4.1689	7.7089e-06	4.1690
	16	3.3019e-07	4.0449	4.6701e-07	4.0450
	32	2.0465e-08	4.0121	2.8945e-08	4.0121
$\alpha = 0.3$	4	7.9017e-05		1.1182e-04	
$\beta = 1.3$	8	4.4268e-06	4.1578	6.2636e-06	4.1580
	16	2.6684e-07	4.0522	3.7750e-07	4.0524
	32	1.6456e-08	4.0193	2.3277e-08	4.0195
$\alpha = 0.4$	4	6.9021e-05		9.7654e-05	
$\beta = 1.5$	8	3.9285e-06	4.1350	5.5571e-06	4.1353
	16	2.3952e-07	4.0358	3.3878e-07	4.0359
	32	1.4880e-08	4.0087	2.1045e-08	4.0088
$\alpha = 0.3$	4	9.9835e-05		1.4123e-04	
$\beta = 0.5$	8	5.5455e-06	4.1702	7.8445e-06	4.1702
	16	3.3520e-07	4.0482	4.7413e-07	4.0483
	32	2.0689e-08	4.0181	2.9263e-08	4.0181

Table 8 Convergent results in time with $h = 1/100$ for Example 3

α, β	K	L^2	Rate	L^∞	Rate
$\alpha = 0.4$	64	4.2999e-07		6.0365e-07	
$\beta = 0.4$	128	1.5543e-07	1.4680	2.1870e-07	1.4648
	256	5.4725e-08	1.5060	7.7112e-08	1.5039
	512	1.8869e-08	1.5362	2.6614e-08	1.5348
	1024	6.3337e-09	1.5749	8.9395e-09	1.5739
$\alpha = 0.3$	64	7.9131e-07		1.1323e-06	
$\beta = 1.3$	128	2.2979e-07	1.7839	3.2839e-07	1.7858
	256	6.4867e-08	1.8248	9.2597e-08	1.8264
	512	1.8380e-08	1.8193	2.6210e-08	1.8208
	1024	5.3147e-09	1.7901	7.5704e-09	1.7917
$\alpha = 0.8$	64	2.5202e-06		3.5502e-06	
$\beta = 0.8$	128	1.2978e-06	0.9575	1.8318e-06	0.9547
	256	6.1807e-07	1.0702	8.7315e-07	1.0690
	512	2.8146e-07	1.1348	3.9781e-07	1.1341
	1024	1.2583e-07	1.1615	1.7789e-07	1.1611
$\alpha = 0.6$	64	1.6530e-06		2.3297e-06	
$\beta = 0.5$	128	6.9077e-07	1.2588	9.7491e-07	1.2568
	256	2.8008e-07	1.3024	3.9559e-07	1.3013
	512	1.1066e-07	1.3397	1.5637e-07	1.3390
	1024	4.2888e-08	1.3675	6.0620e-08	1.3671

mate the nonlinear term. Based on the discrete fractional Grönwall inequality, the discrete fractional convolution kernel and the temporal–spatial OSC error splitting technology, the

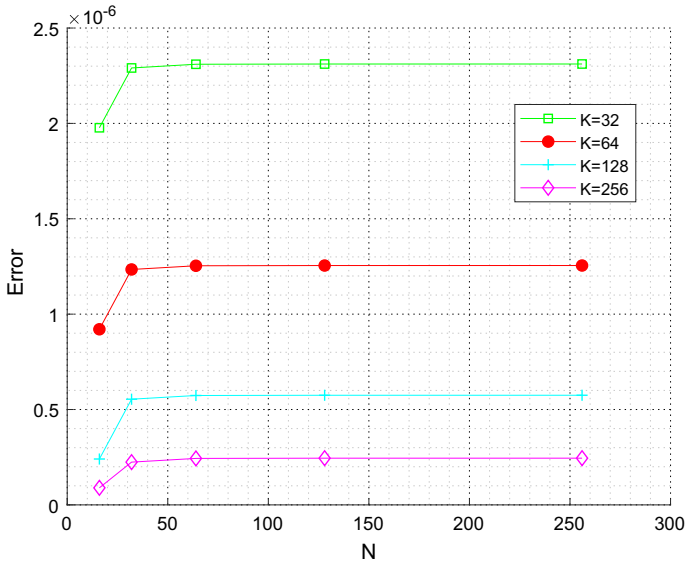


Fig. 4 The L^2 error at $\alpha = 0.6$ for Example 3

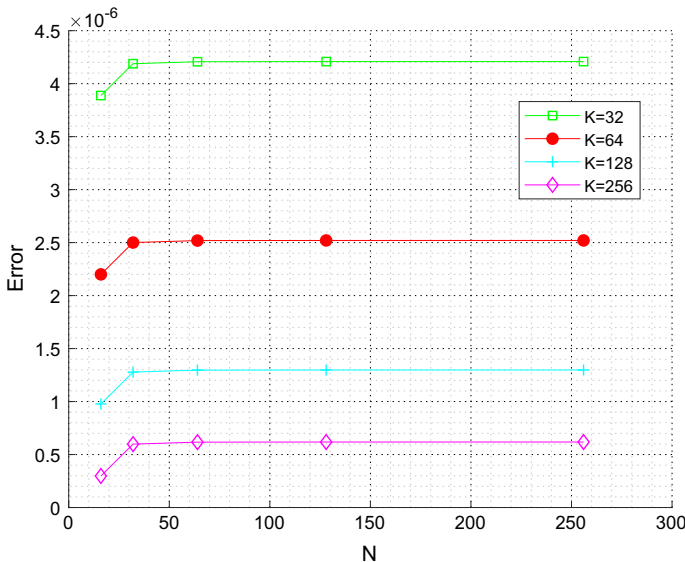


Fig. 5 The L^2 error at $\alpha = 0.8$ for Example 3

optimal convergence rate of the Newton linearized L1-OSC method are gained. Moreover the unconditional convergence results of our proposed L1-OSC method are proved with considering the initial singularity. Especially, there is no time step restrictions that depends on the size of the spatial mesh. Our analytical technique can provide new insights in analyzing other fourth-order fractional differential equations with weakly singular solutions.

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