



# Non-collision Orbits for a Class of Singular Hamiltonian Systems on the Plane with Weak Force Potentials

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## Abstract

We study the existence of non-collision orbits for a class of singular Hamiltonian systems

$$\ddot{q} + V'(q) = 0$$

where  $q : \mathbb{R} \rightarrow \mathbb{R}^2$  and  $V \in C^2(\mathbb{R}^2 \setminus \{e\}, \mathbb{R})$  is a potential with a singularity at a point  $e \neq 0$ . We consider  $V$  which behaves like  $-1/|q - e|^\alpha$  as  $q \rightarrow e$  with  $\alpha \in ]0, 2[$ . Under the assumption that 0 is a strict global maximum for  $V$ , we establish the existence of a homoclinic orbit emanating from 0. Moreover, in case  $V(q) \rightarrow 0$  as  $|q| \rightarrow +\infty$ , we prove the existence of a heteroclinic orbit “at infinity” i.e. a solution  $q$  such that

$$\lim_{t \rightarrow -\infty} q(t) = 0, \quad \lim_{t \rightarrow +\infty} |q(t)| = +\infty \quad \text{and} \quad \lim_{t \rightarrow \pm\infty} \dot{q}(t) = 0.$$

**Keywords** Hamiltonian systems · Homoclinic and heteroclinic orbits · Minimization methods

**Mathematics Subject Classification** 34C37 · 37C29

## 1 Introduction

In this paper we consider the second order Hamiltonian system

$$\ddot{q} + V'(q) = 0 \tag{HS}$$

where  $q : \mathbb{R} \rightarrow \mathbb{R}^2$  and  $V \in C^2(\mathbb{R}^2 \setminus \{e\}, \mathbb{R})$  has a singularity at a point  $e \neq 0$  such that

$$V(q) \sim -\frac{1}{|q - e|^\alpha} \quad \text{as } q \rightarrow e \text{ with } \alpha \in ]0, 2[. \tag{1}$$

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We will assume that  $V$  has a strict global maximum at  $q = 0$ . So 0 is an equilibrium point for (HS).

Our goal in the first part is studying the existence of nontrivial homoclinic solutions to 0 of (HS), i.e. solutions  $q$  of (HS) such that

$$q \neq 0 \quad \text{and} \quad \lim_{t \rightarrow \pm\infty} q(t) \equiv q(\pm\infty) = 0 = \dot{q}(\pm\infty).$$

We note that the order  $\alpha$  in (1) plays an important role and we consider the existence of homoclinic solutions of (HS) under weak force case ( $\alpha \in ]0, 2[$ ). This case has been studied in several works which deal via variational methods with the periodic problem. See, e.g., [1], [2], [5], [9], [15], [17]. Let us now define the strong force condition:

(SF) There exists a neighbourhood  $\Omega$  of  $e$  in  $\mathbb{R}^2$  and  $U \in C^1(\Omega \setminus \{e\}, \mathbb{R})$  such that

$$\begin{aligned} |U(q)| &\rightarrow \infty \quad \text{as } q \rightarrow e, \\ -V(q) &\geq |U'(q)|^2 \quad \text{for all } q \in \Omega \setminus \{e\}. \end{aligned}$$

Condition (SF) was introduced by Gordon [10]. For a potential  $V(q) \sim -\frac{1}{|q - e|^\alpha}$  as  $q \rightarrow e$ , (SF) is satisfied if and only if  $\alpha \geq 2$ . In fact, for  $\alpha \geq 2$  we can take  $U(q) = -2^{-1} \ln |q - e|$ . The major role of (SF) is the following property.

**Lemma 1.1** *Assume (SF) and  $V(q) \rightarrow -\infty$  as  $q \rightarrow e$ . Let  $a < b \in \mathbb{R}$  and  $(q_m) \subset H^1([a, b], \Omega \setminus \{e\})$  which converges weakly in  $H^1([a, b], \mathbb{R}^2)$  to  $q$  such that  $q(t_0) = e$  for some  $t_0 \in [a, b]$ . Then*

$$-\int_a^b V(q_m) dt \rightarrow +\infty$$

(and therefore  $\int_a^b \left[ \frac{1}{2} |\dot{q}_m|^2 - V(q_m) \right] dt \rightarrow +\infty$ ).

The proof of this lemma can be found in ([11], Lemma 2.1) or in [13]. As a consequence, if (SF) holds then functions with bounded energy are uniformly away from the singularity  $e$ . Therefore, in such case, a standard variational arguments in [13] provided the existence of a pair of homoclinic orbits that wind respectively around the singularity  $e$  in a positive and negative sense. These solutions were obtained by minimizing the energy functional

$$I(q) = \int_{\mathbb{R}} \left[ \frac{1}{2} |\dot{q}|^2 - V(q) \right] dt$$

on classes of sets with a fixed winding number around  $e$  (see also [6, 7] for multiplicity results). If this condition is dropped (weak force case), Rabinowitz [13] proved the existence of a “generalized” homoclinic solution of (HS) which may pass through the singularity.

In  $\mathbb{R}^N$  with  $N \geq 3$ , the existence of homoclinic solutions of (HS) was proved in [16] for strong force potentials (see also [8] in the case of time periodic potentials) and [3, 14] for weak force potentials like (1.1). In [3, 14], the authors introduced a strong force perturbed potential  $V_\varepsilon$  for  $\varepsilon \in ]0, 1[$  such that  $V_\varepsilon(q) = V(q) - \varepsilon/|q - e|^2$  near  $q = e$  and proved through a min-max method from Bahri-Rabinowitz [4] the existence of non-collision solutions for approximated differential problems. Then they passed to the limit as  $\varepsilon \rightarrow 0$  with the aid of appropriate estimates to obtain a generalized homoclinic solution. In [3] we studied the Morse index of approximated functionals at critical points to estimate the number of collisions. In particular we established the existence of non-collision homoclinic solution for  $\alpha \in ]1, 2[$  i.e.

$q(t) \neq e$  for all  $t \in \mathbb{R}$ , while in [14] this result is obtained by assuming that  $V(q)$  is radially symmetric near  $q = e$ .

The main purpose of Sect. 2 is to prove the existence of non-collision homoclinic orbits of (HS) in  $\mathbb{R}^2$  for weak force potentials. By exploiting the topology of the plane and using a minimization method, we first show the existence of a generalized homoclinic solution of (HS) as a limit of solutions of perturbed problems with boundary conditions. Then and for the regularity of this solution, we will use a Tanaka’s rescaling argument to prove some additional properties of approximated solutions near collisions, and we will prove how the generalized homoclinic solution obtained is actually a non-collision orbit in the case  $\alpha \in ]0, 2[$ .

In Sect. 3, we assume that  $V$  has another global maximum at infinity i.e.  $\lim_{|x| \rightarrow +\infty} V(x) = V(0)$  and we study the existence of a heteroclinic orbit “at infinity” i.e. a solution  $q$  of (HS) satisfying

$$q(-\infty) = 0, |q(+\infty)| = +\infty \text{ and } \dot{q}(\pm\infty) = 0.$$

The problem in  $\mathbb{R}^N$  was treated by Serra in [14] for regular potentials where  $V(q) \sim -a/|q|^b$  as  $|q| \rightarrow +\infty$  with  $a, b > 0$ . He also treated the case of singular potentials which behaves like (1) when  $N \geq 3$  and established the existence of non-collision orbits using some results from [15] on the analysis of collisions solutions of minimization problems. In the present paper we deal with the case  $N = 2$  and we will perturb  $V$  near  $e$  with a strong force term to get the existence of sequence  $(q_n)$  of heteroclinic orbits at infinity for perturbed problems. We obtain uniform estimates to show that  $(q_n)$  converges to a generalized solution. Some local properties of  $q_n$  near collisions and the fact that  $q_n$  is obtained via a minimization procedure permit us to obtain a non-collision heteroclinic solution at infinity.

## 2 Existence of Homoclinic Orbits

In this section, we consider the existence of a homoclinic solution of (HS) where the potential  $V$  satisfies the following assumptions:

- (V1)  $V \in C^2(\mathbb{R}^2 \setminus \{e\}, \mathbb{R})$  for some  $e \neq 0$ ;
- (V2)  $V(q) < V(0) = 0$  for all  $q \in \mathbb{R}^2 \setminus \{0, e\}$ ;
- (V3)  $V$  is of the form

$$V(q) = -\frac{1}{|q - e|^\alpha} + W(q),$$

with  $\alpha \in ]0, 2[$  and  $W$  is such that

$$|q - e|^{\alpha-\nu} W(q), |q - e|^{\alpha-\nu+1} W'(q) \text{ and } |q - e|^{\alpha-\nu+2} W''(q) \longrightarrow 0 \text{ as } q \rightarrow e$$

for some  $\nu \in ]0, \alpha[$ ;

- (V4) There are  $R > 2|e|$  and a function  $W_\infty \in C^1(\mathbb{R}^2, \mathbb{R})$  such that

$$|W_\infty(q)| \longrightarrow +\infty \text{ as } |q| \rightarrow +\infty \text{ and } -V(q) \geq |W'_\infty(q)| \text{ for } |q| \geq R.$$

**Remark 2.1** i) The condition (V3) remains valid when  $\nu = 0$ . In particular it involves that  $V \sim -1/|q - e|^\alpha$  near  $q = e$  with  $\alpha \in ]0, 2[$ .

ii) The condition (V4) concerns the behavior of the potential at infinity. It will be satisfied if for example  $V(q) \sim -a|q|^\beta$  as  $|q| \rightarrow +\infty$  where  $a > 0$  and  $\beta \geq -2$ .

Our main result of this section is

**Theorem 2.2** Assume (V1)-(V4).

- 1) If  $\alpha \in ]1, 2[$ , then (HS) possesses at least one non-collision homoclinic solution.
- 2) If  $\alpha \in ]0, 1]$ , then (HS) possesses a non trivial generalized homoclinic solution  $q$  having at most one collision. Moreover, if  $q(t_0) = e$  then  $q(t)$  is a collision brake orbit, i.e.  $q(t + t_0) = q(t_0 - t)$  for all  $t \in \mathbb{R}$ .

Here, similarly as in [4], [17] for the periodic problem, we define a generalized homoclinic solution as a continuous function  $q : \mathbb{R} \rightarrow \mathbb{R}^2$  such that

- (i)  $\dot{q} \in L^2(\mathbb{R}, \mathbb{R}^2)$  and  $I(q) < \infty$ ;
- (ii)  $D = \{t \in \mathbb{R}, q(t) = e\}$  is a set of measure 0;
- (iii)  $q \in C^2(\mathbb{R} \setminus D, \mathbb{R}^2)$  and satisfies (HS) on  $\mathbb{R} \setminus D$ ;
- (iv)  $\frac{1}{2}|\dot{q}(t)|^2 + V(q(t)) = 0$  for  $t \in \mathbb{R} \setminus D$ ;
- (v)  $q(t) \rightarrow 0$  and  $\dot{q}(t) \rightarrow 0$  as  $t \rightarrow \pm\infty$ .

If  $D = \emptyset$ ,  $q$  is a classical (non-collision) homoclinic solution.

**Remark 2.3** Since  $V$  is independent of  $t$ ,  $q(-t)$  is a homoclinic solution of (HS) whenever  $q(t)$  is a homoclinic solution.

The proof of Theorem 2.2. is divided in various steps. We shall construct a homoclinic solution of (HS) as a limit of solutions of approximate value problems. We started by modifying the potential  $V$  near  $e$ . For  $\varepsilon \in ]0, 1]$ , we define  $V_\varepsilon \in C^2(\mathbb{R}^2 \setminus \{e\}, \mathbb{R})$  such that  $V_1 \leq V_\varepsilon \leq V$  and

$$V_\varepsilon(q) = \begin{cases} V(q) - \frac{\varepsilon}{|q - e|^2} & \text{if } 0 < |q - e| \leq |e|/4, \\ 0 & \text{if } |q - e| \geq |e|/2. \end{cases}$$

Remark that  $V_\varepsilon(q) \sim -\frac{\varepsilon}{|q - e|^2}$  as  $q \rightarrow e$ . So  $V_\varepsilon$  satisfies the strong force condition.

Let  $(\varepsilon_n)_{n \in \mathbb{N}^*} \subset ]0, 1]$  be a non-increasing sequence converging to 0. We consider for each  $n \in \mathbb{N}^*$  the Dirichlet boundary value problem

$$\begin{cases} \ddot{q} + V'_{\varepsilon_n}(q) = 0 & \text{in } ]0, n[, \\ q(0) = q(n) = 0. \end{cases} \tag{D_n}$$

The corresponding functional is

$$I_{0,n}(q) = \int_0^n \left[ \frac{1}{2}|\dot{q}|^2 - V_{\varepsilon_n}(q) \right] dt \in C^1(\Lambda_n, \mathbb{R})$$

where

$$\Lambda_n = \{q \in H_0^1([0, n], \mathbb{R}^2); \quad q(t) \neq e, \forall t \in [0, n]\}.$$

Let  $\text{ind}_{z_0}(\gamma)$  denote the winding number of a closed curve in  $\mathbb{C}$  around a point  $z_0$ . That is

$$\text{ind}_{z_0}(\gamma) = \frac{1}{2i\pi} \int_\gamma \frac{dz}{z - z_0}$$

which is a integer representing the number of counterclockwise turns that  $\gamma$  makes around  $z_0$ .

A critical point of  $I_{0,n}$  will be found as a minimizer of  $I_{0,n}$  over the set

$$\Gamma_n^{\pm 1} = \{q \in \Lambda_n, \text{ind}_e(q) = \pm 1\}.$$

Clearly  $\Gamma_n^{\pm 1} \neq \emptyset$ , so we can define

$$c_n^{\pm 1} = \inf_{q \in \Gamma_n^{\pm 1}} I_{0,n}(q). \tag{2}$$

We remark that, since  $I_{0,n}(q) = I_{0,n}(q(n - \cdot))$  for all  $q \in \Lambda_n$ , then  $c_n^1 = c_n^{-1}$ .

**Proposition 2.4** 1) *There exist  $M_1, M_2 > 0$  such that*

$$0 < M_1 \leq c_n^1 \leq M_2, \quad \forall n \in \mathbb{N}^*. \tag{3}$$

2) *For every  $n \in \mathbb{N}^*$ , there is  $q_n \in \Gamma_n^1$  such that  $I_{0,n}(q_n) = c_n^1$ . Moreover  $q_n$  is a non trivial classical solution of  $(D_n)$ .*

**Proof** 1) Let  $q \in \Gamma_n^1$ . The fact that  $\text{ind}_e(q) = 1$  implies that  $\|q\|_{L^\infty([0,n], \mathbb{R}^2)} \geq |e|$ . Since  $q(0) = q(n) = 0$ , there exist  $s_q < t_q$  such that

$$|q(s_q)| = \frac{|e|}{3}, \quad |q(t_q)| = \frac{2|e|}{3} \quad \text{and} \quad \frac{|e|}{3} \leq |q(t)| \leq \frac{2|e|}{3} \quad \text{for all } t \in [s_q, t_q].$$

Using the Cauchy-Schwartz inequality, we have the general formula

$$\begin{aligned} \int_{t_1}^{t_2} \left[ \frac{1}{2} |\dot{u}|^2 - V(u) \right] dt &\geq \frac{|u(t_2) - u(t_1)|^2}{2(t_2 - t_1)} + (t_2 - t_1) \min_{t \in [t_1, t_2]} -V(u(t)) \\ &\geq |u(t_2) - u(t_1)| \sqrt{2 \min_{t \in [t_1, t_2]} -V(u(t))} \end{aligned} \tag{4}$$

where  $u \in H^1([t_1, t_2], \mathbb{R}^2)$ .

We denote  $c = \min_{\frac{|e|}{3} \leq |x| \leq \frac{2|e|}{3}} -V(x) > 0$ . Then from (4), we get

$$\begin{aligned} I_{0,n}(q) &\geq \int_{s_q}^{t_q} \left[ \frac{1}{2} |\dot{q}|^2 - V(q) \right] dt \\ &\geq \frac{|e|}{3} \sqrt{2c} = M_1. \end{aligned}$$

Thus by the arbitrariness of  $q$ , we obtain  $c_n^1 \geq M_1 > 0$  for any  $n \in \mathbb{N}^*$ .

In order to prove that  $c_n^1$  is bounded from above, let  $q \in \Gamma_1^1$  and define

$$v_n(t) = \begin{cases} q(t) & \text{if } t \in [0, 1], \\ 0 & \text{if } t \in ]1, n]. \end{cases}$$

Clearly  $v_n \in \Gamma_n^1$  and then

$$\begin{aligned} c_n^1 \leq I_{0,n}(v_n) &= \int_0^1 \left[ \frac{1}{2} |\dot{q}|^2 - V_{\varepsilon_n}(q) \right] dt \\ &\leq I_{0,1}(q). \end{aligned}$$

Therefore

$$c_n^1 \leq \inf_{q \in \Gamma_1^1} I_{0,1}(q) = M_2.$$

2) Let  $(u_m)$  be a minimizing sequence for  $c_n^1$ . We have from (3),  $(u_m)$  is bounded in  $H_0^1([0, n], \mathbb{R}^2)$ . It follows that along a subsequence  $(u_m)$  converge weakly in  $H_0^1([0, n], \mathbb{R}^2)$  and uniformly in  $[0, n]$  to a function  $q_n$ . Since  $\int_0^n -V_{\varepsilon_n}(u_m) dt$  is bounded independently of

$m$  and  $V_{\varepsilon_n}$  is a strong force, Lemma 1.1 shows that  $q_n \in \Lambda_n$ . Moreover we know that the winding number is continuous with respect to uniform convergence of curves. Therefore  $\text{ind}_e(q_n) = \lim_{m \rightarrow +\infty} \text{ind}_e(u_m) = 1$  and so  $q_n \in \Gamma_n^1$ . Using the lower semi continuity of  $I_{0,n}$ , we get  $I_{0,n}(q_n) \leq \liminf_{m \rightarrow +\infty} I_{0,n}(u_m) = c_n^1$ . That is  $I_{0,n}(q_n) = c_n^1$ . Now in a standard way, we can see that  $q_n$  is a critical point of  $I_{0,n}$  and then a nontrivial classical solution of  $(D_n)$ .  $\square$

As a consequence of Proposition 2.4, we get the following estimates:

**Lemma 2.5** (i) *There is a constant  $C > 0$  which is independent of  $n$  such that for any  $n \in \mathbb{N}^*$ ,*

$$\|\dot{q}_n\|_{L^2([0,n], \mathbb{R}^2)} \leq C; \quad \int_0^n -V(q_n)dt \leq C; \quad \|q_n\|_{L^\infty([0,n], \mathbb{R}^2)} \leq C.$$

(ii) *For every  $n \in \mathbb{N}^*$ , there is a constant  $h_n > 0$  such that*

$$\frac{1}{2}|\dot{q}_n(t)|^2 + V_{\varepsilon_n}(q_n(t)) = h_n, \quad \forall t \in [0, n].$$

Moreover,  $h_n = \frac{1}{2}|\dot{q}_n(0)|^2 = \frac{1}{2}|\dot{q}_n(n)|^2 \rightarrow 0$ .

Since  $q_n \in \Gamma_n^1$ , we have  $\max_{t \in [0,n]} |q_n(t)| > |e|/4$ . Otherwise we would have  $\text{ind}_e(q_n) = 0$ .

Then we can find numbers  $\tau_n^1, \tau_n^2 \in ]0, n[$  such that

$$|q_n(\tau_n^1)| = |q_n(\tau_n^2)| = |e|/4 \quad \text{and} \quad |q_n(t)| < |e|/4 \quad \text{if} \quad t \in [0, \tau_n^1[ \cup ]\tau_n^2, n].$$

Note that in [3], it was also proved the existence of approximated solution  $q_n$  of  $(D_n)$  in  $\mathbb{R}^N$  ( $N \geq 3$ ) such that

- \*  $\max_{t \in [0,n]} |q_n(t)| > \rho$  where  $\rho > 0$  is a constant;
- \*  $|\dot{q}_n(0)| \rightarrow 0$  and  $|\dot{q}_n(n)| \rightarrow 0$ .

Using the continuity theorem of solutions with respect to initials conditions, we can see in a similar way to Lemma 2.7 in [3],

$$\tau_n^1 \rightarrow \infty \quad \text{and} \quad n - \tau_n^2 \rightarrow \infty.$$

Next we define

$$\tilde{q}_n(t) = \begin{cases} q_n(t + \tau_n^1) & \text{if } t \in [-\tau_n^1, n - \tau_n^1], \\ 0 & \text{if } t \in \mathbb{R} \setminus [-\tau_n^1, n - \tau_n^1]. \end{cases} \tag{5}$$

Clearly  $|\tilde{q}_n(0)| = |e|/4$  and  $\tilde{q}_n$  verifies

$$\begin{aligned} \ddot{\tilde{q}}_n + V'_{\varepsilon_n}(\tilde{q}_n) &= 0 \quad \text{in } ]-\tau_n^1, n - \tau_n^1[, \\ \frac{1}{2}|\dot{\tilde{q}}_n|^2 + V_{\varepsilon_n}(\tilde{q}_n) &= h_n \quad \text{in } ]-\tau_n^1, n - \tau_n^1[. \end{aligned}$$

By (i) of Lemma 2.5, we can extract a subsequence -still denoted by  $\tilde{q}_n$ - which converges in  $C_{loc}(\mathbb{R}, \mathbb{R}^2)$  to some function  $\tilde{q} \in C(\mathbb{R}, \mathbb{R}^2) \cap L^\infty(\mathbb{R}, \mathbb{R}^2)$  with  $\dot{\tilde{q}} \in L^2(\mathbb{R}, \mathbb{R}^2)$ . Since  $-\tau_n^1 \rightarrow -\infty$  and  $n - \tau_n^1 \rightarrow +\infty$ , we can see  $\tilde{q}$  is a non trivial generalized homoclinic solution of (HS). The complete proofs to Lemma 2.5 and the last statements are omitted as they are similar to its analogues in [3].

In what follows, we focus our attention to study the regularity of  $\tilde{q}$ . First we state some further properties of  $\tilde{q}_n$  and  $\tilde{q}$  near the singularity.

Let  $t \in \mathbb{R}$  such that  $|\tilde{q}_n(t) - e| < |e|/4$ . From the definition of  $V_{\varepsilon_n}$ ,  $\tilde{q}_n(t)$  verifies

$$\ddot{\tilde{q}}_n + \alpha \frac{\tilde{q}_n - e}{|\tilde{q}_n - e|^{\alpha+2}} + W'(\tilde{q}_n) + 2\varepsilon_n \frac{\tilde{q}_n - e}{|\tilde{q}_n - e|^4} = 0, \tag{6}$$

$$\frac{1}{2} |\dot{\tilde{q}}_n|^2 - \frac{1}{|\tilde{q}_n - e|^\alpha} + W(\tilde{q}_n) - \frac{\varepsilon_n}{|\tilde{q}_n - e|^2} = h_n. \tag{7}$$

Then

$$\begin{aligned} \frac{1}{2} \frac{d^2}{dt^2} |\tilde{q}_n(t) - e|^2 &= \langle \ddot{\tilde{q}}_n, \tilde{q}_n - e \rangle + |\dot{\tilde{q}}_n|^2 \\ &= \frac{2 - \alpha}{|\tilde{q}_n - e|^\alpha} - W'(\tilde{q}_n)(\tilde{q}_n - e) - 2W(\tilde{q}_n) + 2h_n \\ &= \frac{1}{|\tilde{q}_n - e|^\alpha} [2 - \alpha - |\tilde{q}_n - e|^\alpha W'(\tilde{q}_n)(\tilde{q}_n - e) - 2|\tilde{q}_n - e|^\alpha W(\tilde{q}_n) \\ &\quad + 2h_n |\tilde{q}_n - e|^\alpha]. \end{aligned}$$

By (V3) (see Remark 2.1 i)) and the fact that  $h_n \rightarrow 0$ , we can find  $0 < \delta < |e|/4$  such that for sufficiently large  $n$ ,

$$\frac{1}{2} \frac{d^2}{dt^2} |\tilde{q}_n(t) - e|^2 > 0 \quad \text{if } |\tilde{q}_n(t) - e| < \delta. \tag{8}$$

Similarly, if  $\tilde{q}(t) \neq e$  then  $\tilde{q}(t)$  satisfies (HS) and of energy 0. From this, we obtain

$$\frac{1}{2} \frac{d^2}{dt^2} |\tilde{q}(t) - e|^2 = \frac{1}{|\tilde{q} - e|^\alpha} [2 - \alpha - |\tilde{q} - e|^\alpha W'(\tilde{q})(\tilde{q} - e) - 2|\tilde{q} - e|^\alpha W(\tilde{q})].$$

Thus the property (8) holds also for  $\tilde{q}$ , i.e.

$$\frac{1}{2} \frac{d^2}{dt^2} |\tilde{q}(t) - e|^2 > 0 \quad \text{if } 0 < |\tilde{q}(t) - e| < \delta. \tag{9}$$

Taking into account the property (ii) of a generalized solution, (9) implies that the collisions times of  $\tilde{q}$  (if they exist) are isolated.

Now we suppose that  $\tilde{q}$  has a collision at  $t = \tilde{t}$  i.e.  $\tilde{q}(\tilde{t}) = e$  for some  $\tilde{t} \in \mathbb{R}$ . We will study the angle which describes  $\tilde{q}_n(t)$  around  $e$  when  $t$  is near  $\tilde{t}$ . In particular we will show that  $\tilde{q}_n$  have one self intersection if  $\alpha \in ]1, 2[$ .

Since  $\tilde{q}(t) \rightarrow 0$  as  $t \rightarrow \pm\infty$ , there exist  $\tau_1 < \tilde{t} < \tau_2$  such that

$$|\tilde{q}(\tau_1) - e| = |\tilde{q}(\tau_2) - e| = \frac{\delta}{2} \quad \text{and } 0 < |\tilde{q}(t) - e| < \frac{\delta}{2} \quad \forall t \in ]\tau_1, \tau_2[ \setminus \{\tilde{t}\}.$$

Thus for sufficiently large  $n$ , we have

$$|\tilde{q}_n(\tau_i) - e| \geq \frac{\delta}{4} \quad \text{for } i = 1, 2 \tag{10}$$

and

$$|\tilde{q}_n(t) - e| < \delta \quad \forall t \in [\tau_1, \tau_2]. \tag{11}$$

Let  $t_n \in [\tau_1, \tau_2]$  and  $\delta_n > 0$  such that  $\delta_n = |\tilde{q}_n(t_n) - e| = \min_{t \in [\tau_1, \tau_2]} |\tilde{q}_n(t) - e|$ .

Clearly  $\delta_n \leq |\tilde{q}_n(\tilde{t}) - e| \rightarrow |\tilde{q}(\tilde{t}) - e| = 0$ . So  $\delta_n \rightarrow 0$ . Moreover, up a subsequence, we have  $t_n \rightarrow \tilde{t}$ .

By (8), we have

$$\frac{d}{dt}|\tilde{q}_n(t) - e| < 0 \quad \forall t \in [\tau_1, t_n[, \tag{12}$$

$$\frac{d}{dt}|\tilde{q}_n(t) - e| > 0 \quad \forall t \in ]t_n, \tau_2]. \tag{13}$$

In the sequel we use a rescaling argument as in [17] and we introduce the function

$$x_n(s) = \delta_n^{-1} \left[ \tilde{q}_n \left( \delta_n^{\frac{\alpha+2}{2}} s + t_n \right) - e \right], \quad s \in \mathbb{R}.$$

Remark that

$$|x_n(0)| = 1 \quad \text{and} \quad (x_n(0), \dot{x}_n(0)) = 0. \tag{14}$$

Let  $l > 0$ . For sufficiently large  $n$ , since  $\delta_n^{\frac{\alpha+2}{2}} s + t_n \in [\tau_1, \tau_2]$  for  $s \in [-l, l]$ , we have from (11) and (6)-(7),

$$\ddot{x}_n(s) + \alpha \frac{x_n}{|x_n|^{\alpha+2}} + \delta_n^{\alpha+1} W'(\delta_n x_n + e) + \frac{2\varepsilon_n}{\delta_n^{2-\alpha}} \frac{x_n}{|x_n|^4} = 0 \quad \text{in } [-l, l], \tag{15}$$

$$\frac{1}{2}|\dot{x}_n|^2 - \frac{1}{|x_n|^\alpha} + \delta_n^\alpha W(\delta_n x_n + e) - \frac{\varepsilon_n}{\delta_n^{2-\alpha}} \frac{1}{|x_n|^2} = \delta_n^\alpha h_n \quad \text{in } [-l, l]. \tag{16}$$

We extract a subsequence still indexed by  $n$  such that

$$d = \lim_{n \rightarrow +\infty} \frac{\varepsilon_n}{\delta_n^{2-\alpha}} \in [0, +\infty] \tag{17}$$

exists. For  $d$  we need to show that

**Lemma 2.6** *The quantity  $d$  defined in (17) is a finite one.*

**Proof** On the contrary, we assume that  $d = +\infty$ . We will prove that  $\tilde{q}_n$  has a self intersection around  $e$  to find a contradiction. Let consider another rescaling of  $\tilde{q}_n$ :

$$y_n(s) = \delta_n^{-1} \left[ \tilde{q}_n \left( \varepsilon_n^{-\frac{1}{2}} \delta_n^2 s + t_n \right) - e \right], \quad s \in \mathbb{R}. \tag{18}$$

Since  $\varepsilon_n^{-\frac{1}{2}} \delta_n^2 = \left( \varepsilon_n^{-1} \delta_n^{2-\alpha} \right)^{\frac{1}{2}} \delta_n^{1+\frac{\alpha}{2}} \rightarrow 0$ , then for sufficiently large  $n$ , we have  $\varepsilon_n^{-\frac{1}{2}} \delta_n^2 s + t_n \in [\tau_1, \tau_2]$ ,  $\forall s \in [-l, l]$ . From (12)-(13), we get

$$\begin{aligned} \frac{d}{ds}|y_n(s)| &< 0 \quad \forall s \in [-l, 0[, \\ \frac{d}{ds}|y_n(s)| &> 0 \quad \forall s \in ]0, l]. \end{aligned}$$

As in [3], we can see that -up a subsequence-

$$y_n \longrightarrow \cos(\sqrt{2}s)e_1 + \sin(\sqrt{2}s)e_2 \quad \text{in } C_{loc}^2(\mathbb{R}, \mathbb{R}^2)$$

where  $(e_1, e_2)$  is an orthonormal basis of  $\mathbb{R}^2$ . Using polar coordinates, there exists a function  $\alpha_n \in C^2(\mathbb{R}, \mathbb{R})$  such that

$$y_n(s) = |y_n(s)| \left( \cos(\alpha_n(s))e_1 + \sin(\alpha_n(s))e_2 \right).$$



We take  $l > \sqrt{2}\pi$ . Since  $\dot{\alpha}_n \rightarrow \sqrt{2}$  uniformly on  $[-l, l]$ , then for sufficiently large  $n$ , there exist  $s_1 < 0 < s_2$  such that

$$\alpha_n(0) - \alpha_n(s_1) = \alpha_n(s_2) - \alpha_n(0) = 2\pi. \tag{19}$$

We may assume that  $1 < |y_n(s_1)| \leq |y_n(s_2)|$ . By continuity, there exists  $s_3 \in ]0, s_2]$  such that  $|y_n(s_1)| = |y_n(s_3)|$ . Since  $\dot{\alpha}_n > 0$ , it follows from (19) that

$$\begin{aligned} \alpha_n(s_3) - \alpha_n(s_1) &= \alpha_n(s_3) - \alpha_n(0) + \alpha_n(0) - \alpha_n(s_1) \\ &> 2\pi. \end{aligned}$$

This implies the existence of  $s'_1, s'_2 \in [s_1, s_3]$  such that  $y_n(s'_1) = y_n(s'_2)$  and  $\text{ind}_0 y_n|_{[s'_1, s'_2]} = 1$ . From (5) and (18), it follows the existence of  $t', t'' \in ]0, n[$  such that  $q_n(t') = q_n(t'')$  and  $\text{ind}_e q_n|_{[t', t'']} = 1$ . But this contradicts the fact that  $q_n$  is a minimum of  $I_{0,n}$  over  $\Gamma_n^1$ . Indeed, let consider the function

$$\underline{q}_n(t) = \begin{cases} q_n(t) & \text{if } t \in [0, n] \setminus [t', t''], \\ q_n(t' + t'' - t) & \text{if } t \in [t', t'']. \end{cases}$$

Then  $\underline{q}_n \in \Gamma_n^{-1}$  and  $I_{0,n}(\underline{q}_n) = I_{0,n}(q_n) = c_n^1 = c_n^{-1}$ . Therefore  $\underline{q}_n$  is a classical solution of  $(D_n)$ . By the uniqueness of the solution of ordinary differential equation, we deduce that  $\underline{q}_n = q_n$ : clearly this is a contradiction since  $\text{ind}_e(\underline{q}_n) = -1$  and  $\text{ind}_e(q_n) = 1$ .  $\square$

Since  $d < +\infty$ , by the continuity dependence of solutions on initial data and equation, we can see from (14)-(16) and (V3) the existence of an orthonormal basis  $(e_1, e_2)$  of  $\mathbb{R}^2$  such that

$$x_n(s) \rightarrow x_{\alpha,d}(s) \text{ in } C_{\text{loc}}^2(\mathbb{R}, \mathbb{R}^2)$$

where  $x_{\alpha,d}(s)$  is the solution of the initial value problem

$$\begin{cases} \ddot{x} + \frac{\alpha x}{|x|^{\alpha+2}} + 2d \frac{x}{|x|^4} = 0, \\ x(0) = e_1, \quad \dot{x}(0) = \sqrt{2(1+d)}e_2. \end{cases}$$

We use polar coordinates and write

$$\begin{aligned} \tilde{q}_n(t) - e &= |\tilde{q}_n(t) - e| \left( \cos(\tilde{\theta}_n(t))e_1 + \sin(\tilde{\theta}_n(t))e_2 \right), \\ x_{\alpha,d}(s) &= |x_{\alpha,d}(s)| \left( \cos(\theta_{\alpha,d}(s))e_1 + \sin(\theta_{\alpha,d}(s))e_2 \right), \end{aligned}$$

where  $\tilde{\theta}_n(s), \theta_{\alpha,d}(s) \in \mathbb{R}$  with  $\theta_{\alpha,d}(0) = 0$ . In [18] we observed the following properties for  $\theta_{\alpha,d}$

$$\dot{\theta}_{\alpha,d}(s) > 0 \quad \forall s \in \mathbb{R}, \tag{20}$$

$$\Delta\theta_{\alpha,d} = \lim_{s \rightarrow +\infty} (\theta_{\alpha,d}(s) - \theta_{\alpha,d}(-s)) = \frac{2\pi\sqrt{1+d}}{2-\alpha}. \tag{21}$$

We remark that  $\Delta\theta_{\alpha,d} > \pi \quad \forall \alpha \in ]0, 1]$  and if  $\alpha \in ]1, 2[$  then  $\Delta\theta_{\alpha,d} > 2\pi$ .

Let  $B_r(e)$  denote the open ball of radius  $r$  about  $e$ . We will give a estimate of  $\tilde{\theta}_n(t)$  when  $\tilde{q}_n(t) \in B_\mu(e) \setminus B_{L\delta_n}(e)$  for sufficiently small  $\mu > 0$  and large  $L > 1$  and  $n$ .

We have for  $t < t'$ ,

$$\begin{aligned} |\tilde{\theta}_n(t') - \tilde{\theta}_n(t)| &\leq \int_t^{t'} |\dot{\tilde{\theta}}_n(\tau)| d\tau \\ &= \int_t^{t'} \left| \frac{d}{dt} \frac{\tilde{q}_n(\tau) - e}{|\tilde{q}_n(\tau) - e|} \right| d\tau \end{aligned} \tag{22}$$

On the other hand, Tanaka [18] studied under the condition (V3) with  $e = 0$  the behavior of generalized periodic solutions of singular Hamiltonian systems in  $\mathbb{R}^N$ . In a neighborhood of the singularity, the generalized solution is a limit of classical solutions of perturbed problems with potentials  $V_\varepsilon$  as in our case, so we can apply some locally property of approximated solutions near a collision. More precisely, modifying the argument in Proposition 1.5 slightly, we can see that for any  $\eta > 0$  there exist constants  $\mu, S > 0$  and  $n_0 \in \mathbb{N}^*$  such that for  $n \geq n_0$ ,

$$\begin{aligned} \int_t^{t'} \left| \frac{d}{dt} \frac{\tilde{q}_n(\tau) - e}{|\tilde{q}_n(\tau) - e|} \right| d\tau &\leq \frac{\eta}{2} \text{ if } \tilde{q}_n(t), \tilde{q}_n(t') \in B_\mu(e) \text{ and} \\ \tau_1 < t < t' < t_n - S\delta_n^{\frac{\alpha+2}{2}} \text{ or } t_n + S\delta_n^{\frac{\alpha+2}{2}} < t < t' < \tau_2. \end{aligned} \tag{23}$$

Combining (22) and (23), we get

**Lemma 2.7** *For any  $\eta > 0$ , there are constants  $\mu \in ]0, \delta/4[$ ,  $S > 0$  such that for sufficiently large  $n$ , if  $\tilde{q}_n(t), \tilde{q}_n(t') \in B_\mu(e)$  and*

$$\tau_1 < t < t' < t_n - S\delta_n^{\frac{\alpha+2}{2}} \text{ or } t_n + S\delta_n^{\frac{\alpha+2}{2}} < t < t' < \tau_2,$$

then

$$|\tilde{\theta}_n(t') - \tilde{\theta}_n(t)| \leq \frac{\eta}{2}.$$

*End of the proof of Theorem 2.2.* 1) If  $\alpha \in ]1, 2[$ , there exists from (21)  $\eta > 0$  such that  $\Delta\theta_{\alpha,d} > 2\pi + \eta$ . For this  $\eta$ , we choose  $\mu \in ]0, \delta/4[$ ,  $S > 0$  and  $n$  sufficiently large as in Lemma 2.7.

From (21) again we can take  $S_1 > S$  such that

$$\theta_{\alpha,d}(S_1) - \theta_{\alpha,d}(-S_1) > 2\pi + \eta.$$

Then we obtain for sufficiently large  $n$ ,

$$\tilde{\theta}_n \left( t_n + \delta_n^{\frac{\alpha+2}{2}} S_1 \right) - \tilde{\theta}_n \left( t_n - \delta_n^{\frac{\alpha+2}{2}} S_1 \right) > 2\pi + \eta. \tag{24}$$

On the other hand, since  $|\tilde{q}_n(t_n \pm S_1\delta_n^{\frac{\alpha+2}{2}}) - e| \rightarrow |\tilde{q}(\tilde{t}) - e| = 0$ , we can assume that

$$|\tilde{q}_n \left( t_n \pm S_1\delta_n^{\frac{\alpha+2}{2}} \right) - e| < \mu.$$

We set  $t'_{1,n} = t_n - S_1\delta_n^{\frac{\alpha+2}{2}}$ . Then we have from (10)

$$|\tilde{q}_n(t'_{1,n}) - e| < \mu < \frac{\delta}{4} \leq |\tilde{q}_n(\tau_1) - e|.$$

Therefore there exists  $t_{1,n} \in ]\tau_1, t'_{1,n}[$  such that

$$|\tilde{q}_n(t_{1,n}) - e| = \mu.$$

Similarly we set  $t_{2,n} = t_n + S_1 \delta_n^{\frac{\alpha+2}{2}}$ . Since  $|\tilde{q}_n(t_{2,n}) - e| < \mu < \frac{\delta}{4} \leq |\tilde{q}_n(\tau_2) - e|$ , there exists  $t'_{2,n} \in ]t_{2,n}, \tau_2[$  such that

$$|\tilde{q}_n(t'_{2,n}) - e| = \mu.$$

Applying lemma 2.7 for  $t = t_{i,n}$  and  $t' = t'_{i,n}$  ( $i = 1, 2$ ), we obtain

$$|\tilde{\theta}_n(t'_{i,n}) - \tilde{\theta}_n(t_{i,n})| \leq \frac{\eta}{2} \quad \text{for } i = 1, 2. \tag{25}$$

It follows from (24)-(25),

$$\begin{aligned} \tilde{\theta}_n(t'_{2,n}) - \tilde{\theta}_n(t_{1,n}) &= \tilde{\theta}_n(t'_{2,n}) - \tilde{\theta}_n(t_{2,n}) + \tilde{\theta}_n(t_{2,n}) - \tilde{\theta}_n(t'_{1,n}) + \tilde{\theta}_n(t'_{1,n}) - \tilde{\theta}_n(t_{1,n}) \\ &> -\frac{\eta}{2} + 2\pi + \eta - \frac{\eta}{2} = 2\pi. \end{aligned}$$

That is  $\tilde{q}_n$  describes an angle greater than  $2\pi$  in going from  $\partial B_\mu(e)$  back to  $\partial B_\mu(e)$  which implies the existence of  $t''_{1,n}, t''_{2,n}$  with  $\tau_1 < t''_{1,n} < t''_{2,n} < \tau_2$  such that

$$\tilde{q}_n(t''_{1,n}) = \tilde{q}_n(t''_{2,n}) \quad \text{and } \text{ind}_e \tilde{q}_n|_{[t''_{1,n}, t''_{2,n}]} = 1.$$

Thus we deduce that  $q_n$  has a self intersection around  $e$  for sufficiently large  $n$ . As in the proof of Lemma 2.6, we get a contradiction and then we conclude that  $\tilde{q}$  is a non collision homoclinic solution of (HS).

2) In the case  $\alpha \in ]0, 1]$ , the angle which describes  $\tilde{q}_n$  near  $e$  is greater than  $\pi$  and  $\tilde{q}_n$  cannot have a self intersection. The fact that the collisions times of  $\tilde{q}$  are isolated and since  $\tilde{q}(t) \rightarrow 0$  as  $t \rightarrow \pm\infty$ , we get that the number of collisions of  $\tilde{q}$  is finite. Assume  $\tilde{q}(t)$  enters the singularity  $e$  and let

$$t_0 = \min\{t \in \mathbb{R}, \tilde{q}(t) = e\}.$$

Since (HS) is time reversible, the function

$$q(t) = \begin{cases} \tilde{q}(t) & \text{if } t \leq t_0, \\ \tilde{q}(2t_0 - t) & \text{if } t \geq t_0, \end{cases}$$

is a generalized homoclinic solution of (HS) and satisfies  $q(t + t_0) = q(t_0 - t)$  for all  $t$ . Moreover  $q$  has one collision in  $\mathbb{R}$ . The proof of Theorem 2.2 is finally complete.

**Remark 2.8** The assumption (V3) is far too restrictive in the case  $\alpha \in ]0, 1]$  and the existence of a generalized homoclinic solution with finite number of collisions and then a solution as in Theorem 2.2 2) still holds if we replace (V3) by

- (V'3) (i)  $V(q) \rightarrow -\infty$  as  $q \rightarrow e$ ;
- (ii) There exists a constant  $\delta \in ]0, |e|/4[$  such that

$$V(q) + \frac{1}{2}V'(q)(q - e) < 0 \quad \text{for } 0 < |q - e| \leq \delta.$$

We have kept (V3) in the case  $\alpha \in ]0, 1]$ , on the one hand to obtain a certain symmetry in the statements of Theorem 2.2, on the other hand the study of approximated solutions near collisions under (V3) will be useful in Sect. 3 to prove the existence of a non-collision heteroclinic orbit at infinity for every  $\alpha \in ]0, 2[$  (see Theorem 3.1 below).

### 3 Existence of Heteroclinic Orbits

In this section, the existence of non-collision heteroclinic orbits at infinity for (HS) will be established. Consider the problem

$$\begin{cases} \ddot{q} + V'(q) = 0, \\ q(-\infty) = 0, \quad |q(+\infty)| = +\infty, \\ \dot{q}(\pm\infty) = 0, \end{cases} \tag{P}$$

where  $V$  behaves like (1) near  $e$  and satisfies the assumptions (V1)-(V3) of Theorem 2.2.

The natural condition for  $V$  at infinity for (P) is  $\lim_{|q| \rightarrow +\infty} V(q) = 0$ . More precisely, we assume

$$(V'4) \quad V(q) \sim -\frac{a}{|q|^b} \quad \text{as } |q| \rightarrow +\infty \text{ for some } a > 0, b > 2.$$

When  $\alpha \in ]0, 1]$ , we need a further property of  $V$  near  $e$

(V5) there exists  $\phi \in C^2(]0, r[, \mathbb{R})$  for some  $r \in ]0, |e|/4[$  such that

$$V(q) = \phi(|q - e|) \quad \forall q \in B_r(e).$$

**Theorem 3.1** *Suppose (V1)-(V3), (V'4) and (V5)(only when  $\alpha \in ]0, 1]$ ). Then there exists at least one non-collision orbit of (P).*

We now pass to the proof of Theorem 3.1. Solutions of (P) can be found as critical points of the functional

$$I(q) = \int_{\mathbb{R}} \left[ \frac{1}{2} |\dot{q}|^2 - V(q) \right] dt$$

defined on the set

$$\Lambda_0^\infty = \{q \in H; \quad q(-\infty) = 0, \quad |q(+\infty)| = +\infty, \quad q(t) \neq e \quad \forall t \in \mathbb{R}\}$$

where

$$H = \left\{ q \in H_{loc}^1(\mathbb{R}, \mathbb{R}^N), \int_{\mathbb{R}} |\dot{q}|^2 dt < +\infty \right\}.$$

In [14] the case  $\alpha \geq 2$  (strong force case) has been studied and the existence of one classical solution of (P) has been found as a minimizer of  $I$  on  $\Lambda_0^\infty$ . In our situation where  $0 < \alpha < 2$ , we make a perturbation to the potential as in Theorem 2.2 and we consider for every  $n$  the problem

$$\begin{cases} \ddot{q} + V'_{\varepsilon_n}(q) = 0, \\ q(-\infty) = 0, \quad |q(+\infty)| = +\infty, \\ \dot{q}(\pm\infty) = 0. \end{cases} \tag{P_n}$$

Since  $V_{\varepsilon_n}$  is a strong force, we can use Lemma 1.1, and a standard compactness argument provides the existence of a classical (non-collision) solution  $q_n$  of  $(P_n)$  as a minimizer of the functional

$$I_n(q) = \int_{\mathbb{R}} \left[ \frac{1}{2} |\dot{q}|^2 - V_{\varepsilon_n}(q) \right] dt$$

on  $\Lambda_0^\infty$ , i.e.  $q_n \in \Lambda_0^\infty$  such that

$$I_n(q_n) = \inf_{q \in \Lambda_0^\infty} I_n(q). \tag{26}$$

By normalization, we can assume that

$$|q_n(0)| = \frac{|e|}{4} \quad \text{and} \quad |q_n(t)| < \frac{|e|}{4} \quad \forall t < 0.$$

Remark also that  $q_n$  has energy zero.

Now we observe that  $I_n(q_n) \leq \inf_{q \in \Lambda_0^\infty} I_1(q) = c_1 < +\infty$ . We deduce then the existence of a constant  $C > 0$  independent of  $n$  such that  $\|q_n\|_H \leq C$  and  $\int_{\mathbb{R}} -V(q_n)dt \leq C$ . Thus there is a subsequence still denoted by  $(q_n)$  and a function  $q \in H$  such that  $q_n$  converges weakly in  $H$  and uniformly in  $C_{loc}(\mathbb{R}, \mathbb{R}^2)$  to  $q$ . By Fatou's lemma  $\int_{\mathbb{R}} -V(q)dt \leq C$ , so the set of collisions  $D = \{t \in \mathbb{R}, q(t) = e\}$  is of measure 0. In a standard way, we can see that  $q \in C^2(\mathbb{R} \setminus D, \mathbb{R}^2)$ , satisfies (HS) and has energy zero in  $\mathbb{R} \setminus D$ , that is  $q$  is a generalized solution of (HS).

**Lemma 3.2**  $q(t) \neq e$  for all  $t \in \mathbb{R}$ .

**Proof** We prove by contradiction assuming  $q(\tilde{t}) = e$  for some  $\tilde{t} \in \mathbb{R}$ . From (V3) and the conservation of the energy,  $q$  satisfies the property (9) and then we can see that the collisions times of  $q$  are isolated. Moreover there is a sequence  $(t_n)$  such that  $t_n \rightarrow \tilde{t}$  and  $|q_n(t) - e|$  takes its local minimum at  $t = t_n$ .

As in Theorem 2.2 we define  $\delta_n = |q_n(t_n) - e|$  and  $d = \lim_{n \rightarrow +\infty} \frac{\varepsilon_n}{\delta_n^{2-\alpha}} \in [0, +\infty]$  (we extract a subsequence if necessary).

If we suppose that  $d = +\infty$ , we can see as in Lemma 2.6 that  $q_n$  has a self intersection i.e. there exist  $\sigma_1 < \sigma_2$  such that  $q_n(\sigma_1) = q_n(\sigma_2)$  and  $\text{ind}_e q_n|_{[\sigma_1, \sigma_2]} = 1$ . Here we consider the function

$$u_n(t) = \begin{cases} q_n(t + \sigma_1 - \sigma_2) & \text{if } t \leq \sigma_2, \\ q_n(t) & \text{if } t \geq \sigma_2. \end{cases}$$

Then  $u_n \in \Lambda_0^\infty$  and it is easy to see that  $I_n(u_n) < I_n(q_n)$ , which contradicts (26).

Therefore we get  $d < +\infty$ . In that case, there is a function  $x_{\alpha,d}$  such that after taking a subsequence still denoted by  $n$ ,

$$\delta_n^{-1} \left[ q_n \left( \delta_n^{\frac{\alpha+2}{2}} s + t_n \right) - e \right] \rightarrow x_{\alpha,d}(s) = |x_{\alpha,d}(s)| \left( \cos(\theta_{\alpha,d}(s))e_1 + \sin(\theta_{\alpha,d}(s))e_2 \right)$$

in  $C_{loc}^2(\mathbb{R}, \mathbb{R}^2)$  where  $(e_1, e_2)$  is an orthonormal basis of  $\mathbb{R}^2$  and  $\theta_{\alpha,d} : \mathbb{R} \rightarrow \mathbb{R}$  satisfies  $\theta_{\alpha,d}(0) = 0$  and the properties (20)-(21).

In polar coordinates, there exists  $\theta_n : \mathbb{R} \rightarrow \mathbb{R}$  such that

$$q_n(t) - e = |q_n(t) - e| \left( \cos(\theta_n(t))e_1 + \sin(\theta_n(t))e_2 \right).$$

For  $\alpha \in ]1, 2[$ , we have from (21)  $\Delta\theta_{\alpha,d} > 2\pi$ . Repeating the argument of Theorem 2.2, we get that  $q_n$  has a self intersection around  $e$  which is a contradiction as above.

For  $\alpha \in ]0, 1]$ , we will use (V5) to get a contradiction. Here  $\Delta\theta_{\alpha,d} > \pi$  and  $q_n$  cannot have a self intersection. However there exists  $L > 0$  such that  $\theta_{\alpha,d}(L) - \theta_{\alpha,d}(-L) > \pi$ . Setting  $\sigma_{1,n} = t_n - \delta_n^{\frac{\alpha+2}{2}} L$  and  $\sigma_{2,n} = t_n + \delta_n^{\frac{\alpha+2}{2}} L$ , for sufficiently large  $n$  we have

$$\begin{aligned} |q_n(t) - e| &\leq r, \quad \forall t \in [\sigma_{1,n}, \sigma_{2,n}], \\ \theta_n(\sigma_{2,n}) - \theta_n(\sigma_{1,n}) &> \pi, \\ \dot{\theta}_n(t) &> 0 \quad \forall t \in [\sigma_{1,n}, \sigma_{2,n}]. \end{aligned} \tag{27}$$

Let  $\sigma'_{1,n}, \sigma'_{2,n} \in [\sigma_{1,n}, \sigma_{2,n}]$  such that

$$\theta_n(\sigma'_{2,n}) - \theta_n(\sigma'_{1,n}) = \pi.$$

We consider the function  $\hat{q}_n$  defined by

$$\begin{aligned} \hat{q}_n(t) &= q_n(t) \quad \text{if } t \in \mathbb{R} \setminus [\sigma'_{1,n}, \sigma'_{2,n}], \\ \hat{q}_n(t) - e &= |q_n(t) - e| \left( \cos(-\theta_n(t) + 2\theta_n(\sigma'_{1,n}))e_1 + \sin(-\theta_n(t) + 2\theta_n(\sigma'_{1,n}))e_2 \right) \\ &\quad \text{if } t \in [\sigma'_{1,n}, \sigma'_{2,n}]. \end{aligned}$$

That is  $\hat{q}_n|_{[\sigma'_{1,n}, \sigma'_{2,n}]}$  and  $q_n|_{[\sigma'_{1,n}, \sigma'_{2,n}]}$  are axially symmetric with respect to the axis joining the two points  $q_n(\sigma'_{1,n})$  and  $q_n(\sigma'_{2,n})$ .

Clearly  $\hat{q}_n \in \Lambda_0^\infty$  and from (V5), since  $V$  is radially symmetric about  $e$  in  $B_r(e)$ , we get that  $I_n(q_n) = I_n(\hat{q}_n) = \inf_{q \in \Lambda_0^\infty} I_n(q)$ . It follows that  $\hat{q}_n$  is of class  $C^2$  and satisfies the equation

$\ddot{q} + V'_{\varepsilon_n}(q) = 0$ . By the uniqueness of solution of ordinary differential equation, we deduce that  $\dot{q}_n = \dot{\hat{q}}_n$ , which enters in contradiction with (27). Therefore we conclude that  $q(t) \neq e$  for all  $t \in \mathbb{R}$ . □

*End of the proof of Theorem 3.1.* To prove that  $q$  is a solution of (P), it remains to show that  $q(-\infty) = 0$ ,  $|q(+\infty)| = +\infty$  and  $\dot{q}(\pm\infty) = 0$ . Using the formula (4) and the fact that  $I(q) < +\infty$  one can see that  $|q(-\infty)|$  and  $|q(+\infty)|$  exist and they are 0 or  $+\infty$ . Since  $|q(t)| = \lim |q_n(t)| \leq |e|/4 \forall t \leq 0$ , then  $q(-\infty) = 0$ .

To show that  $|q(+\infty)| = +\infty$ , we suppose that  $|q(+\infty)| = 0$ . We will construct as in [12] a function  $Q_n \in \Lambda_0^\infty$  such that  $I_n(Q_n) < I_n(q_n)$ . Indeed, let  $\varepsilon \in ]0, |e|/16[$  and  $T_\varepsilon > 0$  such that  $q(T_\varepsilon) \in B_\varepsilon$  the open ball of radius  $\varepsilon$  about 0. For sufficiently large  $n$  we have  $q_n(T_\varepsilon) \in B_{2\varepsilon}$ . We consider the function  $Q_n \in \Lambda_0^\infty$  different from  $q_n$  for  $t < T_\varepsilon$  such that

$$Q_n(t) = \begin{cases} 0 & \text{if } t < T_\varepsilon - 1, \\ (t - T_\varepsilon + 1)q_n(T_\varepsilon) & \text{if } t \in [T_\varepsilon - 1, T_\varepsilon], \\ q_n(t) & \text{if } t \geq T_\varepsilon. \end{cases}$$

Since  $V_{\varepsilon_n} = V$  in  $B_{2\varepsilon}$  and  $V_{\varepsilon_n} \leq V$ , we have

$$I_n(Q_n) - I_n(q_n) \leq 2\varepsilon^2 + \max_{x \in B_{2\varepsilon}} -V(x) - \int_{-\infty}^{T_\varepsilon} \left[ \frac{1}{2} |\dot{q}_n|^2 - V(q_n) \right] dt. \tag{28}$$

On the other hand, since  $|q_n(0)| = |e|/4$  and  $|q_n(T_\varepsilon)| \leq 2\varepsilon < |e|/8$ , there are  $t_1 < t_2$  in  $[0, T_\varepsilon]$  such that

$$|q_n(t_1)| = \frac{|e|}{4}, \quad |q_n(t_2)| = \frac{|e|}{8} \quad \text{and} \quad \frac{|e|}{8} \leq |q_n(t)| \leq \frac{|e|}{4} \quad \text{for all } t \in [t_1, t_2].$$

By the formula (4), it holds that

$$\begin{aligned} \int_{-\infty}^{T_\varepsilon} \left[ \frac{1}{2} |\dot{q}_n|^2 - V(q_n) \right] dt &\geq \int_{t_1}^{t_2} \left[ \frac{1}{2} |\dot{q}_n|^2 - V(q_n) \right] dt \\ &\geq \frac{|e|}{8} \sqrt{2m_0} \end{aligned} \tag{29}$$

where  $m_0 = \min_{\frac{|e|}{8} \leq |x| \leq \frac{|e|}{4}} -V(x) > 0$ .

Then combining (28) and (29), we get  $I_n(Q_n) - I_n(q_n) < 0$  for sufficiently small  $\varepsilon$ , which contradicts (26). We conclude that  $|q(+\infty)| = +\infty$ .

From the conservation of energy and the fact that  $V(q(t)) \rightarrow 0$  as  $t \rightarrow \pm\infty$ , it follows that  $\frac{1}{2}|\dot{q}(t)|^2 = -V(q(t)) \rightarrow 0$  as  $t \rightarrow \pm\infty$ , that is  $\dot{q}(\pm\infty) = 0$ . The proof is complete.

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## Declarations

**Competing interests** The authors declare no competing interests.

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