



Remarks on double points of plane curves

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Abstract

We study the relation between the type of a double point of a plane curve and the curvilinear 0-dimensional subschemes of the curve at the point. An Algorithm related to a classical procedure for the study of double points via osculating curves is described and proved. Eventually we look for a way to create examples of rational plane curves with given singularities A_s .

Keywords Plane curves · Double points · Curvilinear schemes

1 Introduction

This note is dedicated to the study of double points of plane curves, either using their implicit equation or, in the case of rational curves, their parameterization. This is quite a classical subject in Algebraic Geometry; the aim of the present paper is to study the structure of a double point of a plane curve via the curvilinear 0-dimensional subschemes of the curve at the point, and to give, in the case of plane curves defined by their implicit equation, an algorithm which, following a classical procedure, allows to describe the structure of a double point. We work on the complex field.

We recall that a singularity of type A_s for a plane curve is a double point that can be resolved via r blow ups if $s = 2r - \varepsilon$, $\varepsilon = 0, 1$ and the desingularization yields two points if $\varepsilon = 1$ and only one if $\varepsilon = 0$. In the following, given a curve D smooth at a point Q , with mQ , or, if needed, $mQ|_D$, we denote the curvilinear 0-dimensional scheme of length m supported at Q and contained in D .

If $C \subset \mathbb{P}^2$ is a degree n integral rational curve, to give a parameterization means to see C as the projection of a rational normal curve $C_n \subset \mathbb{P}^n$ (see Sect. 3 for details). In Theorem 4.3 of [1] we show that the point P of C is a double point of type $A_{2r-\varepsilon}$ if and only if there is a 0-dimensional curvilinear scheme $X \subset C$ of length r , projection of a certain curvilinear scheme Y of length $2r$ on C_n (supported on two points if $\varepsilon = 1$, on one point if $\varepsilon = 0$) and X is “maximal” with respect to this property. In Sect. 2 of the present paper

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we generalize the result to any integral plane curve (Theorem 2.1). In the same section we study the intersection multiplicities of a plane curve C with a double point P with curves smooth at P (Proposition 2.2; this will be useful in the last section) and we give another characterization of A_s singularities through the possible length of the curvilinear schemes supported at P and contained in C .

In Sect. 3 we describe an algorithm which classifies double points on any plane curve; this algorithm is based on the classical method of studying the osculating curves (parabolas of degree r) to a curve at a double point. We give this algorithm in detail and also its justification since, although classically known, we find its main references (e.g. see [2]) a bit cumbersome in justifying the procedure.

In Sect. 4 we build an example illustrating the previous algorithm.

In Sect. 5 we give a brief summary of the techniques, introduced in [1], useful for studying singular points on a rational plane curve when the parameterization is known.

In Sect. 6, with [3], we build an example which illustrates how to build a plane rational curve with a double point of a chosen type using projection techniques, and how to use the techniques of Sect. 5 to study the singularities of a rational curve, given its parameterization.

2 Double points and curvilinear schemes

The following theorem is a generalization of [1], Theorem 4.3; its proof is essentially the same as in the rational case:

Theorem 2.1 *Let $C \subset \mathbb{P}^2$ be a curve with normalization $\pi : \tilde{C} \rightarrow C$ and let P be a double point for C . Then:*

- (1) P is an A_{2m-1} singularity if and only if
 - (a) $\pi^{-1}(P) = \{Q_1, Q_2\}$,
 - (b) $\pi(mQ_1|_{\tilde{C}} \cup mQ_2|_{\tilde{C}}) = X$, where X is a curvilinear scheme of length m contained in C ,
 - (c) m is the maximum integer for which (b) holds.
- (2) P is an A_{2m} singularity if and only if
 - (a) $\pi^{-1}(P) = \{Q\}$,
 - (b) $\pi(2mQ|_{\tilde{C}}) = X$, where X is a curvilinear scheme of length m contained in C ,
 - (c) m is the maximum integer for which (b) holds.

Proof It is known that a normal form for an A_s singularity is given by the curve $\Gamma_s \subset \mathbb{P}^2$ of equation: $y^2z^{s-1} - x^{s+1} = 0$ at the point $P = [0, 0, 1]$ (e.g. see [4, 5]), i.e. if C has an A_s singularity at P , then it is analytically isomorphic to Γ_s at P , and has the same multiplicity sequence as Γ_s at P . Hence we will work on these curves first.

Case (1): Let (C, P) be an A_{2m-1} singularity. Hence Γ_{2m-1} , in affine coordinates, is the union of the two smooth curves $\Gamma: \{y - x^m = 0\}$ and $\Gamma': \{y + x^m = 0\}$, while $p = (0, 0)$. The normalization of $\Gamma \cup \Gamma'$ is $\psi : \tilde{\Gamma} \cup \tilde{\Gamma}' \rightarrow \Gamma \cup \Gamma'$, where $\Gamma \cup \Gamma'$ is the union of two disjoint lines and the inverse image of p is given by two points, $q \in \tilde{\Gamma}$ and $q' \in \tilde{\Gamma}'$, so (a) is true. Since $\psi|_{\tilde{\Gamma}}: \tilde{\Gamma} \rightarrow \Gamma$ and $\psi|_{\tilde{\Gamma}'}: \tilde{\Gamma}' \rightarrow \Gamma'$ are two isomorphisms, it is clear that $\psi(mq|_{\tilde{\Gamma}}) = mp|_{\Gamma}$ and $\psi(mq'|_{\tilde{\Gamma}'}) = mp|_{\Gamma'}$.

Now let's notice that $\Gamma \cap \Gamma'$ is the curvilinear scheme Z whose ideal is (y, x^m) , hence $mp|_{\Gamma} = mp|_{\Gamma'} = Z$, and (b) is true. On the other hand, if we consider $\psi((m+1)q|_{\tilde{\Gamma}} \cup$

$(m + 1)q'|\bar{\Gamma}$), we get the scheme $(m + 1)p|_{\Gamma} \cup (m + 1)p|_{\Gamma'}$ which corresponds to the ideal (x^{m+1}, xy, y^2) , and this scheme is not curvilinear, so (c) holds.

Case (2): Let (C, P) be an A_{2m} singularity (hence (a) holds). We have that Γ_{2m} , in affine coordinates, is the irreducible curve $y^2 - x^{2m+1} = 0$, hence a parameterization (which is also a normalization) for it is $\phi : \mathbb{A}^1 \rightarrow \Gamma_{2m}$, where $\phi(t) = (t^2, t^{2m+1})$ and $p = (0, 0)$ is such that $\phi^{-1}(p) = q$. The ring map corresponding to ϕ is:

$$\tilde{\phi} : \frac{K[x, y]}{(y^2 - x^{2m+1})} \rightarrow K[t], \quad \bar{x} \mapsto t^2, \quad \bar{y} \mapsto t^{2m+1}.$$

The scheme $2mq|_{\mathbb{A}^1}$ corresponds to the ideal (t^{2m}) , and $\phi^{-1}((t^{2m})) = (y, x^m)$, hence (b) is true.

On the other hand, the scheme $2(m + 1)q|_{\mathbb{A}^1}$ corresponds to the ideal (t^{2m+2}) , and $\phi^{-1}((t^{2m+2})) = (x^{m+1}, xy, y^2)$, hence (b) is true.

To check that the “if” part of statements (1) and (2) holds, just consider that (1)(a), respectively (2)(a), determines if the singularity is of type A_{2h} , respectively A_{2h-1} , while (1)(b) and (1)(c), respectively (2)(b) and (2)(c), force h to be equal to m .

Now let us notice that, being Γ_s at p analytically isomorphic to C at P , when we consider Γ_s and C as analytic complex spaces, there exist open euclidean neighborhoods U of p and V of P such that $U \cap \Gamma_s$ and $V \cap C$ are biholomorphically equivalent. Since the statement is of local nature, this is enough to conclude. □

We denote the intersection multiplicity of two curves C and D at a point P by $i(C, D, P)$. The Proposition below relates the type A_s of a double point $P \in C$ with the value of $i(C, D, P)$ for a curve D smooth at P .

Proposition 2.2 *Let C be a plane reduced curve and $P \in C$ a double point of C . Let D be a plane curve, smooth at P . Then:*

- (i) *Assume P is an A_{2r-1} or an A_{2r} singularity. If $i(C, D, P) \leq 2r$, then it is an even number.*
- (ii) *If P is an A_{2r-1} singularity for C , there are curves D_1 and D_2 smooth at P such that $i(C, D_j, P) \geq 2r + 1$ for $j = 1, 2$ and $i(D_1, D_2, P) = r$.*
- (iii) *If P is an A_{2r} singularity for C , then $i(C, D, P) \leq 2r + 1$, and there exist curves smooth at P which attain the equality. If D_1, D_2 are curves such that $i(C, D_j, P) = 2r + 1$ for $j = 1, 2$, then $i(D_1, D_2, P) > r$.*
- (iv) *Let O be an A_s singularity for C , with $s = 2r - 1$ or $s = 2r, s \geq 2$, and suppose that the tangent of C at O is not the y -axis. Then any curve D , smooth at O and such that $i(C, D, O) \geq 2r + 1$, has a local analytic equation of the form*

$$y = \sum_{i=2}^{r-1} c_i x^i + c_r x^r + \sum_{i \geq r+1} c_i x^i$$

where $\sum_{i \geq r+1} c_i x^i$ is convergent, and c_2, \dots, c_r are fixed if $s = 2r$, while c_2, \dots, c_{r-1} are fixed and there are only two (different) possibilities for c_r if $s = 2r - 1$.

Proof The curve C at P is analytically isomorphic, at O , to the curve $y^2 - x^s = 0$, where $s = 2r$ if P is an A_{2r-1} singularity and $s = 2r + 1$ if P is an A_{2r} singularity. Since the intersection multiplicity of two curves is an analytic invariant, from now on we study the multiplicity intersection at O of each of these curves with a curve D smooth at O .

(i) If C and D meet transversally, $i(C, D, O) = 2$ so we are done.

If the tangent of D at O is $y = 0$, by the analytic implicit function Theorem (see for example [6], theorem 2.1.2.p.24), the curve D is locally given by an analytic equation $y = \sum_{i \geq 2} c_i x^i$. Denoting by $\omega(S)$ the order of a series S , the intersection multiplicity $i(C, D, O)$ is

$$\omega \left(\left(\sum_{i \geq 2} c_i x^i \right)^2 - x^s \right) \tag{*}$$

Since $\omega((\sum c_i x^i)^2) = 2\omega(\sum c_i x^i)$ is always even, if $i(C, D, O) \leq 2r$ we have that $\omega((\sum_{i \geq 2} c_i x^i)^2 - x^s)$ is even in both cases $s = 2r, 2r + 1$, hence statement $i)$ is proved. We have

$$\left(\sum_{i \leq 2} c_i x^i \right)^2 = \sum_{k \geq 4} \alpha_k x^k \quad \text{where} \quad \alpha_k = \begin{cases} 2 \sum_{j=2}^{\frac{k}{2}-1} c_j c_{k-j} + c_{\frac{k}{2}}^2 & \text{if } k \text{ even} \\ 2 \sum_{j=2}^{\frac{k-1}{2}} c_j c_{k-j} & \text{if } k \text{ odd} \end{cases}$$

Since $\omega(\sum_{k \geq 4} \alpha_k x^k)$ is always even, we have $\alpha_4 = \dots = \alpha_{2m} = 0 \Rightarrow \alpha_{2m+1} = 0$, and

$$\alpha_4 = \dots = \alpha_{2m} = \alpha_{2m+1} = 0 \iff c_2 = \dots = c_m = 0 \tag{†}$$

(ii) Let O be an A_{2r-1} singularity, i.e. $C : y^2 - x^{2r} = 0$, and assume $i(C, D, O) \geq 2r + 1$. Since $i(C, D, O) = \omega(\sum_{k \geq 4} \alpha_k x^k - x^{2r})$, we must have $\alpha_4 = \dots = \alpha_{2r-2} = 0$, this implying $\alpha_{2r-1} = 0$, and $\alpha_{2r} = 1$, hence $c_2 = \dots = c_{r-1} = 0$ and $c_r^2 = 1$. Hence there are two families of curves smooth at O and with intersection multiplicity $\geq 2r + 1$ with C at O , namely, those with a local equation of the form $y = x^r + \sum_{i \geq r+1} c_i x^i$ or $y = -x^r + \sum_{i \geq r+1} c_i x^i$. If D_1 is a curve of the first family and D_2 of the second, we have $i(D_1, D_2, O) = r$.

What we have seen implies that any two curves D_1, D_2 with $i(C, D_j, P) \geq 2r + 1$ are such that $i(D_1, D_2, P) \geq r$.

(iii) Let O be an A_{2r} singularity, i.e. $C : y^2 - x^{2r+1} = 0$, and assume $i(C, D, O) \geq 2r + 1$. Since $i(C, D, O) = \omega(\sum_{k \geq 4} \alpha_k x^k - x^{2r+1})$, we must have $\alpha_4 = \dots = \alpha_{2r} = 0$ and this implies $\alpha_{2r+1} = 0$, hence the coefficient of x^{2r+1} in the series $\sum_{k \geq 4} \alpha_k x^k - x^{2r+1}$ is always -1 , so that the order of the series has to be $2r + 1$; in other words, $i(C, D, O) = 2r + 1$. In this case (†) says that D has a local equation of the form $y = \sum_{i \geq r+1} c_i x^i$. Hence, if D_1, D_2 are two such curves, we find $i(D_1, D_2, O) > r$.

(iv) Let O be a double point for the curve C , and suppose that the tangent of C at O is not the y -axis. Let D_1, D_2 be any two curves smooth at O and such that $i(C, D_j, O) \geq 2r + 1$, $j = 1, 2$, and assume D_j is locally given by $y = \sum_{i \geq 2} c_{ij} x^i$, $j = 1, 2$.

If O is an A_{2r} singularity for C , $r \geq 1$, (iii) gives $i(D_1, D_2, O) > r$, i.e., $c_{i1} = c_{i2}$ for $i = 2, \dots, r$.

If O is an A_{2r-1} singularity for C , $r \geq 2$, the proof of (ii) gives $i(D_1, D_2, O) \geq r$, with $i(D_1, D_2, O) > r$ if D_1 and D_2 belong to the same family between the two families found in the proof, and $i(D_1, D_2, O) = r$ otherwise. Hence $c_{i1} = c_{i2}$ for $i = 2, \dots, r$ in the first case and $c_{i1} = c_{i2}$ for $i = 2, \dots, r - 1$ in the second case. \square

The following Theorem 2.3 gives a description of a double point P of a plane curve in terms of the curvilinear 0-dimensional subschemes of the curve supported at P .

Theorem 2.3 *Let C be a plane reduced curve and $P \in C$ a double point of C . Then P is an A_{2r} singularity if and only if no curvilinear scheme supported at P of length $> 2r + 1$ is contained in C . More precisely,*

- (i) P is an A_{2r-1} singularity for C if and only if for any $\ell \geq 1$ there is a curvilinear scheme supported at P of length ℓ contained in C ;
- (ii) P is an A_{2r} singularity if and only if for any $\ell \leq 2r + 1$ there is a curvilinear scheme supported at P of length ℓ contained in C , and no curvilinear scheme supported at P of length $> 2r + 1$ contained in C .

Proof The curve C at P is analytically isomorphic to the curve $\Gamma_s : y^2 - x^s = 0$ at O , where $s = 2r$ if P is an A_{2r-1} singularity and $s = 2r + 1$ if P is an A_{2r} singularity.

- (i) If P is an A_{2r-1} singularity, let $\ell \geq 1$, and consider the 0-dimensional curvilinear scheme Z of ideal $(y - x^r, x^\ell)$ supported at O ; Z has length ℓ and is contained in Γ_{2r} , since $y^2 - x^{2r} \in (y - x^r, x^\ell)$.
- (ii) If P is an A_{2r} singularity, let $1 \leq \ell \leq 2r + 1$, and consider the 0-dimensional curvilinear scheme Z of ideal (y, x^ℓ) supported at O ; Z has length ℓ and is contained in Γ_{2r+1} , since $y^2 - x^{2r+1} \in (y, x^\ell)$.

Now assume that a 0-dimensional curvilinear scheme Y of length $h \geq 2r + 2$ is contained in Γ_{2r+1} ; Y being curvilinear, there is a curve $D : g(x, y) = 0$ smooth at O and such that $Y \subset D$, so that $I_Y = (g) + (x, y)^h$. Since $Y \subset \Gamma_{2r+1}$, we have $y^2 - x^{2r+1} \in I_Y$, hence $(y^2 - x^{2r+1}, g) + (x, y)^h = (g) + (x, y)^h$; by 2.2 $i(\Gamma_{2r+1}, D, O) \leq 2r + 1$, so that:

$$2r + 1 \geq i(\Gamma_{2r+1}, D, O) = \dim (\mathbb{C}[x, y]/(y^2 - x^{2r+1}, g))_{(x,y)} \geq \dim (\mathbb{C}[x, y]/(y^2 - x^{2r+1}, g) + (x, y)^h)_{(x,y)} = \dim (\mathbb{C}[x, y]/(g) + (x, y)^h)_{(x,y)} = h$$

Hence a 0-dimensional curvilinear scheme of length $\geq 2r + 2$ cannot be contained in Γ_{2r+1} . \square

Remark 2.4 Notice that not all the 0-dimensional subschemes of C appearing in the statement of 2.3 are cut on C by a curve smooth at P , for example by 2.2 if the length is $\leq 2r$ then any such curve has an even intersection multiplicity with C , while clearly there are subschemes of odd length.

3 An algorithm for determining the type of a double point via implicit equation

What we will expose here is an algorithm to determine the nature of a double point on a plane curve C , given the implicit equation of C . The matter is classically known, but we prefer to give it here since it can be a bit "forgotten", especially for younger mathematicians, and also because our main reference ([2]) is a bit cumbersome when giving the justification of this procedure: for this reason we prefer to describe it in a more algorithmic way and to give a rather simple justification of it.

We work with a reduced algebraic curve $C \subset \mathbb{P}^2 = \mathbb{P}_{\mathbb{C}}^2$ of degree n , given by a homogeneous polynomial $F \in \mathbb{C}[x_0, x_1, x_2]_n$, and we suppose that the point $O = [0 : 0 : 1]$ is a double point for C . Let

$$F = \sum_{i+j+k=n} a_{ij} x_0^i x_1^j x_2^k.$$

where each $a_{ij} \in \mathbb{C}$, $i, j, k \in \{0, \dots, n\}$ and $k = n - i - j$.

Since what we want is to study the curve at O , we can work in the affine chart $\{x_2 \neq 0\}$, with affine coordinates $x = \frac{x_0}{x_2}, y = \frac{x_1}{x_2}$, so $O = (0, 0)$ and the affine curve is defined by the polynomial:

$$f(x, y) = \sum a_{ij}x^i y^j$$

The point O being a double point for C , we have $a_{00} = a_{10} = a_{01} = 0$ and $(a_{20}, a_{11}, a_{02}) \neq (0, 0, 0)$:

$$f(x, y) = a_{20}x^2 + a_{11}xy + a_{02}y^2 + a_{30}x^3 + a_{21}x^2y + a_{12}xy^2 + a_{03}y^3 + \dots$$

We make use of auxiliary curves Γ_Λ^t given by the equations :

$$\Gamma_\Lambda^t : y = \lambda_1x + \lambda_2x^2 + \dots + \lambda_t x^t$$

where $t \geq 1, \Lambda := (\lambda_1, \dots, \lambda_t) \in \mathbb{C}^t$. We look among them for curves osculating the curve C at O ; notice that the curve Γ_Λ^t is smooth at $(0, 0)$ and its degree is $\leq t$ (some of the λ_i 's can be zero).

We denote with $i(C, D, P)$ the intersection multiplicity of two curves C, D at the point P , and we set

$$R(C, \Gamma_\Lambda^t) := f(x, \lambda_1x + \lambda_2x^2 + \dots + \lambda_t x^t) \in \mathbb{C}[x]$$

so that $i(C, \Gamma_\Lambda^t, O)$ is the least degree assumed by x in $R(C, \Gamma_\Lambda^t)$.

The aim of the procedure is to establish the type A_s of the double point O . Here we illustrate how to get this result in several steps, before we give a formal algorithm to do that:

Step 1: Analysis via lines Γ_Λ^1 . Since $\Gamma_\Lambda^1 : y = \lambda_1x$ we have

$$R(C, \Gamma_\Lambda^1) = (a_{20} + a_{11}\lambda_1 + a_{02}\lambda_1^2)x^2 + (a_{30} + \dots + a_{03}\lambda_1^3)x^3 + \dots$$

The coefficient of x^2 is zero when

$$a_{20} + a_{11}\lambda_1 + a_{02}\lambda_1^2 = 0 \tag{*}$$

There are two cases:

Step 1a: If $a_{11}^2 - 4a_{20}a_{02} \neq 0$, then $(*)$ has two distinct roots $\lambda_{11}, \lambda_{12}$, so there are exactly two tangent lines $\Gamma_{(\lambda_{11})}^1, \Gamma_{(\lambda_{12})}^1$ for which $i(C, \Gamma_{(\lambda_{1j})}^1, O) \geq 3$ ($j = 1, 2$), *O is a double point A_1* (an ordinary node) for C and the analysis ends here.

Step 1b: If $a_{11}^2 - 4a_{20}a_{02} = 0$, then $(*)$ has one double root $\bar{\lambda}_1$, so there is only one tangent line $\Gamma_{(\bar{\lambda}_1)}^1$ for which $i(C, \Gamma_{(\bar{\lambda}_1)}^1, O) \geq 3$, namely $\Gamma_{(\bar{\lambda}_1)}^1 : y = -\frac{a_{11}}{2a_{02}}x$. Then O is a non-ordinary singularity.

We perform a linear change of coordinates so that the tangent at the double point O to the transformed curve, which we still call C , is $y = 0$, i.e. $\bar{\lambda}_1 = 0$; the equation of C then looks like:

$$C : f(x, y) = y^2 + a_{30}x^3 + a_{21}x^2y + a_{12}xy^2 + a_{03}y^3 + \dots \tag{**}$$

If we have $i(C, \Gamma_{(\bar{\lambda}_1)}^1, O) = 3$, i.e. if $a_{30} \neq 0$, then *O is an ordinary cusp A_2* , and the analysis ends here. Otherwise we go to step 2.

Step 2: Analysis via conics Γ_Λ^2 . We are assuming that C is given by $(**)$ with $a_{30} = 0$, that is, $i(C, \Gamma_{(\bar{\lambda}_1)}^1, O) \geq 4$. Consider the pencil of conics

$$\Gamma_\Lambda^2 : y = \bar{\lambda}_1x + \lambda_2x^2, \quad \Lambda = (\bar{\lambda}_1, \lambda_2)$$

all tangent to C at O ; since $\bar{\lambda}_1 = 0$, we get

$$\Gamma_{\Lambda}^2 : y = \lambda_2 x^2, \quad \Lambda = (0, \lambda_2)$$

$$R(C, \Gamma_{\Lambda}^2) = (a_{40} + a_{21}\lambda_2 + \lambda_2^2)x^4 + (a_{50} + a_{31}\lambda_2 + a_{12}\lambda_2^2)x^5 + \dots$$

The coefficient of x^4 is zero when

$$a_{40} + a_{21}\lambda_2 + \lambda_2^2 = 0 \tag{**}$$

There are two cases:

Step 2a: If the discriminant $a_{21}^2 - 4a_{40} \neq 0$, then there are exactly two osculating conics $\Gamma_{\Lambda_1}^2, \Gamma_{\Lambda_2}^2$ for which $i(C, \Gamma_{\Lambda_j}^2, O) \geq 5$ ($j = 1, 2$), so O is a double point A_3 (a tacnode), since the two conics separate the two branches of C at O . And the analysis stops here.

Step 2b: If $a_{21}^2 - 4a_{40} = 0$, **(**)** has a unique root $\bar{\lambda}_2 = -\frac{a_{21}}{2}$, so there is only one osculating conic $\Gamma_{\bar{\Lambda}}^2$ with $i(C, \Gamma_{\bar{\Lambda}}^2, O) \geq 5$, the one with $\bar{\Lambda} = (0, \bar{\lambda}_2)$.

If $i(C, \Gamma_{\bar{\Lambda}}^2, O) = 5$, i.e. $a_{50} + a_{31}\bar{\lambda}_2 + a_{12}\bar{\lambda}_2^2 \neq 0$, then O is a cusp A_4 , and the analysis ends here. Otherwise we go to step 3.

Step 3: Analysis via cubics Γ_{Λ}^3 . We are assuming that C is given by $(*)$ with $a_{30} = 0, a_{21}^2 - 4a_{40} = 0, 2\bar{\lambda}_2 + a_{21} = 0$ and $a_{50} + a_{31}\bar{\lambda}_2 + a_{12}\bar{\lambda}_2^2 = 0$, that is, $i(C, \Gamma_{\bar{\lambda}_2}^2, O) \geq 6$. Consider the pencil of cubics

$$\Gamma_{\Lambda}^3 : y = \bar{\lambda}_2 x^2 + \lambda_3 x^3, \quad \Lambda = (0, \bar{\lambda}_2, \lambda_3)$$

all having in common the tangent at O (i.e. the tangent $y = 0$ to C at O), and the osculating conic at O (i.e. the osculating conic $y = \bar{\lambda}_2 x^2$ to C at O). We get:

$$R(C, \Gamma_{\Lambda}^3) = (a_{40} + a_{21}\bar{\lambda}_2 + \bar{\lambda}_2^2)x^4 + (a_{50} + a_{31}\bar{\lambda}_2 + a_{12}\bar{\lambda}_2^2 + 2\bar{\lambda}_2\lambda_3 + a_{21}\lambda_3)x^5 + \dots$$

since the coefficients of x^4 and x^5 are 0, we have $i(C, \Gamma_{\Lambda}^3, O) \geq 6$.

The coefficient of x^6 is zero when

$$\lambda_3^2 + (2a_{12}\bar{\lambda}_2 + a_{31})\lambda_3 + a_{03}\bar{\lambda}_2^3 + a_{22}\bar{\lambda}_2^2 + a_{41}\bar{\lambda}_2 + a_{60} = 0 \tag{***}$$

We again have two cases:

Step 3a: If the discriminant $(2a_{12}\bar{\lambda}_2 + a_{31})^2 - 4(a_{03}\bar{\lambda}_2^3 + a_{22}\bar{\lambda}_2^2 + a_{41}\bar{\lambda}_2 + a_{60}) \neq 0$, there are exactly two osculating cubics $\Gamma_{\Lambda_1}^3, \Gamma_{\Lambda_2}^3$ for which $i(C, \Gamma_{\Lambda_j}^3, O) \geq 7$ ($j = 1, 2$), and O is a singularity A_5 (an oscnode).

Step 3b: If the discriminant $(2a_{12}\bar{\lambda}_2 + a_{31})^2 - 4(a_{03}\bar{\lambda}_2^3 + a_{22}\bar{\lambda}_2^2 + a_{41}\bar{\lambda}_2 + a_{60}) = 0$, **(***)** has a unique root $\bar{\lambda}_3$, so there is only one osculating cubic $\Gamma_{\bar{\Lambda}}^3$ with $i(C, \Gamma_{\bar{\Lambda}}^3, O) \geq 7$, the one with $\bar{\Lambda} = (0, \bar{\lambda}_2, \bar{\lambda}_3)$

If $i(C, \Gamma_{\bar{\Lambda}}^3, O) = 7$, then O is an A_6 cusp for C . Otherwise we go to Step 4 where we use quartics

$$\Gamma_{\Lambda}^3 : y = \bar{\lambda}_2 x^2 + \bar{\lambda}_3 x^3 + \lambda_4 x^4, \quad \Lambda = (0, \bar{\lambda}_2, \bar{\lambda}_3, \lambda_4)$$

and we go on in the same way. This process will end at some point (see the justification of the Algorithm: if O is an A_{2r-1} or an A_{2r} we will stop at Step r).

The procedure above is described in the following Algorithm 1. Notice that in the exposition above when the point is not a node we imposed $a_{02} \neq 0, a_{20} = a_{11} = 0$ to have that the double tangent at O is $y = 0$ so to simplify computations. This is not necessary, hence in the algorithm we just impose $a_{02} \neq 0$.

Algorithm 1 Study of the double points of a plane curve $C : \sum a_{ij}x_0^i x_1^j x_2^{n-i-j} = 0$

Input: $F = \sum a_{ij}x_0^i x_1^j x_2^{n-i-j} \in \mathbb{C}[x_0, x_1, x_2]_n, n > 0, P = [a, b, c], F(P) = 0.$

Output: State if P is a double point for C and its type: $A_m.$

1: *STEP 0*) Perform a linear change of coordinates so to have $P = [0, 0, 1]$; work in the affine chart $\{x_2 \neq 0\}$, with $f = \sum a_{ij}x^i y^j$, and $a_{00} = 0.$

If $(a_{10}, a_{01}) \neq (0, 0): P$ is a **simple point** for C , with tangent $a_{10}x + a_{01}y = 0.$ **STOP**

If $(a_{10}, a_{01}) = (0, 0)$ and $(a_{20}, a_{11}, a_{02}) = (0, 0, 0): P$ is a **point of multiplicity ≥ 3** for $C.$ **STOP.**

If $(a_{10}, a_{01}) = (0, 0)$ and $(a_{20}, a_{11}, a_{02}) \neq (0, 0, 0): P$ is a **double point** for $C:$ **go to Step 1.**

2: *STEP 1*) Perform a linear change of coordinates so to have $a_{02} \neq 0.$ Set $\Lambda := (\lambda_1)$ and consider

$$R(C, \Gamma_\Lambda^1) := f(x, \lambda_1 x) = (a_{20} + a_{11}\lambda_1 + a_{02}\lambda_1^2)x^2 + \dots$$

3: *STEP 1-a*) If $\Delta_1^2(\Lambda) := a_{11}^2 - 4a_{20}a_{02} \neq 0,$ then there exist $\lambda_{11} \neq \lambda_{12}$ with $i(C, \Gamma_{(\lambda_{11})}^1, P) \geq 3, i(C, \Gamma_{(\lambda_{12})}^1, P) \geq 3$ and P is a **double point** for C of type A_1 (ordinary node). **STOP.**

4: *STEP 1-b*) If $\Delta_1^2(\Lambda) = a_{11}^2 - 4a_{20}a_{02} = 0,$ then there is a unique $\bar{\lambda}_1$ with $i(C, \Gamma_{(\bar{\lambda}_1)}^1, P) \geq 3.$

Step 1-b1) If $i(C, \Gamma_{(\bar{\lambda}_1)}^1, P) = 3,$ then P is a **double point** for C of type A_2 (ordinary cusp). **STOP.**

Step 1-b2) If $i(C, \Gamma_{(\bar{\lambda}_1)}^1, P) \geq 4:$ **go to Step 2.**

For $r \geq 2,$ let

5: *STEP r*) Let $\Lambda = (\bar{\lambda}_1, \bar{\lambda}_2, \dots, \bar{\lambda}_{r-1}, \lambda_r)$ and

$$\Gamma_\Lambda^r : y = \bar{\lambda}_1 x + \bar{\lambda}_2 x^2 + \dots + \bar{\lambda}_{r-1} x^{r-1} + \lambda_r x^r$$

where the values $\bar{\lambda}_1, \dots, \bar{\lambda}_{r-1}$ come from Steps 1 – b₂, ..., (r – 1) – b₂. Let

$$R(C, \Gamma_\Lambda^r) := f(x, \bar{\lambda}_1 x + \bar{\lambda}_2 x^2 + \dots + \bar{\lambda}_{r-1} x^{r-1} + \lambda_r x^r)$$

We have $i(C, \Gamma_\Lambda^r, P) \geq 2r,$ so the least power of x appearing in $R(C, \Gamma_\Lambda^r)$ is $2r.$ Let Δ_r^{2r} be the discriminant of the second degree equation in λ_r obtained by forcing the coefficient of x^{2r} to be zero. Then

6: *STEP r-a*) If $\Delta_r^{2r} \neq 0,$ there exist $\lambda_{r1} \neq \lambda_{r2}$ such that, setting $\Lambda_j = (\bar{\lambda}_1, \bar{\lambda}_2, \dots, \bar{\lambda}_{r-1}, \lambda_{rj}),$ one has $i(C, \Gamma_{\Lambda_j}^r, P) \geq 2r + 1$ for $j = 1, 2,$ so P is a **double point** for C of type $A_{2r-1}.$ **STOP.**

7: *STEP r-b*) If $\Delta_r^{2r} = 0$ there is a unique $\bar{\lambda}_r$ such that, setting $\bar{\Lambda} = (\bar{\lambda}_1, \bar{\lambda}_2, \dots, \bar{\lambda}_{r-1}, \bar{\lambda}_r),$ one has $i(C, \Gamma_{\bar{\Lambda}}^r, P) \geq 2r + 1.$ *Step 1-b1*) If $i(C, \Gamma_{\bar{\Lambda}}^r, P) = 2r + 1$ then P is a **double point** for C of type $A_{2r}.$ **STOP.**

Step 1-b2) If $i(C, \Gamma_{\bar{\Lambda}}^r, P) \geq 2r + 2:$ **go to Step r + 1.**

Remark 3.1 In the algorithm, the curves Γ_Λ^r need not to have degree $r:$ some of the λ_i 's can be zero, or even all of them. For example, if $f(x, y) = y^2 - x^5,$ then $\Gamma_{(\bar{\lambda}_1)}^1 = \Gamma_{(\bar{\lambda}_1, \bar{\lambda}_2)}^2 = \{y = 0\};$ since $i(C, \Gamma_{(\bar{\lambda}_1, \bar{\lambda}_2)}^2, P) = 5$ this gives a verdict of A_4 singularity (actually this is the prototype of an A_4).

Remark 3.2 The curve C is assumed to be reduced, but it can be reducible, so it can happen that $i(C, \Gamma_\Lambda^r, P) = \infty,$ when Γ_Λ^r is a component of $C.$ For example, let $f(x, y) = y^2 - yx^2 =$

$y(y - x^2)$. The algorithm gives that $\Gamma_{(\bar{\lambda}_1)}^1$ is given for $\bar{\lambda}_1 = 0$, and $i(C, \Gamma_{(\bar{\lambda}_1)}^1, P) = \infty$; then in the next step, looking for $\Gamma_{\bar{\lambda}}^2$, we find two possibilities: $\Gamma_{(0,0)}^2$ and $\Gamma_{(0,1)}^2$, both yielding $i(C, \Gamma_{\bar{\lambda}}^2, P) = \infty$, giving a verdict of A_3 singularity (tacnode) for P .

Justification of Algorithm 1 procedure

The justification relies mainly on Proposition 2.2, as we will see.

Proposition 3.3 *In the Hypotheses of Algorithm 1 the following hold:
 Algorithm 1 stops at Step r-a if and only if P is an A_{2r-1} singularity for C;
 Algorithm 1 stops at Step r-b if and only if P is an A_{2r} singularity for C.*

Proof If P is an A_s singularity, $s \in \{2r - 1, 2r\}$, the statement follows directly by Proposition 2.2, (iv).

If the algorithm stops at the step $1 - a$, $\lambda_{11}, \lambda_{12}$ give the two distinct tangents of an A_1 singularity (ordinary node). If the algorithm stops at the step $1 - b$, $\bar{\lambda}_1$ gives the unique tangent $\Gamma_{\bar{\lambda}_1}^1$ with $i(C, \Gamma_{\bar{\lambda}_1}^1, P) = 3$ of an ordinary cusp A_2 .

So now suppose $r \geq 2$.

If the algorithm stops at the step $r - a$ the singularity cannot be an A_{2h-1} with $h < r$, because in that case, by Proposition 2.2(iv), the Algorithm should have given two different Λ_1, Λ_2 at step $h - a$, nor it can be an A_{2h} since in that case we should have $i(C, \Gamma_{\bar{\lambda}}^r, O) = 2h + 1 < 2r + 1$.

On the other hand, the singularity cannot be an A_s , $s \geq 2r$, otherwise we should have $\Gamma_{\Lambda_1}^r = \Gamma_{\Lambda_2}^r$, by Proposition 2.2(iv). Hence P is an A_{2r-1} singularity.

If the algorithm stops at the step $r - b$, the singularity cannot be an A_{2h} with $h < r$, because in that case we should have $i(C, \Gamma_{\bar{\lambda}}^r, P) \leq 2h + 1 < 2r + 1$, nor it can be an A_{2h-1} , $h \leq r$, since at step $h - a$ we should have got two different curves $\Gamma_{\Lambda_1}^h, \Gamma_{\Lambda_2}^h$.

On the other hand, the singularity cannot be an A_s , $s > 2r$, otherwise we should have that $i(C, \Gamma_{\bar{\lambda}}^r, P)$ is even by Proposition 2.2(i), and not $2r + 1$. Hence P is an A_{2r} singularity. \square

4 An example of the use of Algorithm 1

Let $C_n \subset \mathbb{P}^n$ be a rational normal curve projecting on a plane curve $\pi : C_n \rightarrow C$ and let $O_Q^r(C_n)$ denote the r -dimensional osculating space to C_n at the point $Q \in C_n$; recall that $O_Q^r(C_n)$ is the linear span in \mathbb{P}^n of the curvilinear scheme $(r + 1)Q \subset C_n$. In [1] we stated the lemma below without any proof, since we considered it as “common knowledge”:
 ([1], Lemma 4.2). Let $P \in C \subset \mathbb{P}^2$ be a double point on a rational curve of degree n , then:

- (1) *The point P is an A_{2m-1} , $2m - 1 < n$ if and only if the scheme $\pi^{-1}(P)$ is given by two distinct points $Q_1, Q_2 \in C_n$ and m is the maximum value for which $\pi(O_{Q_1}^{m-1}(C_n)) = \pi(O_{Q_2}^{m-1}(C_n)) \neq \mathbb{P}^2$.*
- (2) *The point P is an A_{2m} , $2m - 1 < n$, if and only if the scheme $\pi^{-1}(P)$ is given by the divisor $2Q \in C_n$ and m is the maximum value for which $\pi(O_Q^{2m-1}(C_n)) \neq \mathbb{P}^2$.*

When $m \geq 2$, we will have that the image $\pi(O_{Q_1}^{m-1}(C_n)) = \pi(O_{Q_2}^{m-1}(C_n))$, (respectively $\pi(O_Q^{2m-1}(C_n))$) is $T_P(C)$, the unique tangent line to C at P .

This lemma, which luckily enough is never used in [1], is actually wrong, but it sounded quite convincing not only for us, since neither the referee of [1] (which otherwise made a

quite thorough job), nor several colleagues with whom we talked about it during the making of the paper realized that it does not hold.

Here is the rationale which explains why the Lemma does not hold: assume $m > 1$ and that we are in case (1) (but analogous considerations may be done in case (2)); consider the linear spans, giving the osculating spaces: $\langle mQ_1 \rangle = O_{Q_1}^{m-1}(C_n)$, $\langle mQ_2 \rangle = O_{Q_2}^{m-1}(C_n)$. The Lemma states that the projection of these two osculating spaces to the curve C_n is not the whole of \mathbb{P}^2 , so it has to be the unique tangent line t to C at P ; but if this were true, the projection X of the two curvilinear schemes mQ_1, mQ_2 would be contained in a line (the tangent t), and this is not true in general, as the next example, which makes use of Algorithm 1 of Sect. 5, shows.

Example 4.1 Consider the quartic curve C given by the affine equation $y^2 - 2x^2y + x^4 + x^2y^2 = 0$. If we run Algorithm 1 on it, we find a unique tangent $y = 0$ in Step 1, a unique osculating conic $\Gamma : y = x^2$ in Step 2, and two distinct osculating cubics in Step 3:

$$D_1 : y = x^2 - ix^3, \quad D_2 : y = x^2 + ix^3$$

Hence Algorithm 1 gives that O is an oscnode for C (an A_5 double point, so here $m = 3$), and C , being a quartic with an oscnode, is rational, with two branches at O approximated by D_1 and D_2 . Let's denote by $C_4 \subset \mathbb{P}^4$ a rational normal curve which projects onto C .

We have $i(C, D_j, O) = 7$ for $j = 1, 2$ and $i(D_1, D_2, O) = 3$, in accord with Proposition 2.2(ii), and the length 3 curvilinear scheme X of Theorem 4.3 in [1], or of Theorem 2.1 where we take $\tilde{C} = C_4$, is given by $D_1 \cap D_2$, hence it is associated to the ideal $(y - x^2 - ix^3, y - x^2 + ix^3) = (y - x^2, x^3)$. Hence X is contained in the osculating conic Γ and not contained in the tangent line; but, according to Theorem 2.1, X is the projection of the curvilinear length 3 schemes $3Q_1$ and $3Q_2$ of $C_4 \subset \mathbb{P}^4$; so we conclude that $3Q_1$ and $3Q_2$ are not projected inside the tangent $y = 0$. □

5 Singular points on a rational plane curve via parameterization

In [1] we expose a way to determine the nature of a singularity on a rational plane curve C , given a parameterization of C , without using its implicit equation or the syzygies of the parameterization (e.g. as in [7]); in this section we recall a few results from [1].

Definition 5.1 Let $C \subset \mathbb{P}^2$ be a rational curve of degree $n \geq 3$, given by a map $\mathbf{f} = (f_0, f_1, f_2) : \mathbb{P}^1 \rightarrow C$, and assume that the parameterization (f_0, f_1, f_2) is proper, i.e. \mathbf{f} is generically 1:1 and the f_i 's do not have common zeroes. Let

$$f_j = a_{j0}s^n + a_{j1}s^{n-1}t + \dots + a_{jn}t^n, \quad j = 0, 1, 2$$

Consider the $(n - k + 4) \times (n + 1)$ matrices:

$$M_k = \begin{pmatrix} x_0 & x_1 & \dots & x_k & 0 & 0 & \dots & 0 \\ 0 & x_0 & x_1 & \dots & x_k & 0 & \dots & 0 \\ & & & \ddots & & & & \\ 0 & \dots & 0 & x_0 & x_1 & \dots & \dots & x_k \\ a_{00} & a_{01} & a_{02} & a_{03} & \dots & \dots & a_{0n-1} & a_{0n} \\ a_{10} & a_{11} & a_{12} & a_{13} & \dots & \dots & a_{1n-1} & a_{1n} \\ a_{20} & a_{21} & a_{22} & a_{23} & \dots & \dots & a_{2n-1} & a_{2n} \end{pmatrix}.$$

For $2 \leq k \leq n - 1$, we denote by $X_k \subset \mathbb{P}^k$ the scheme defined by the $(n - k + 3)$ -minors of M_k .

The following Proposition (see [1], Prop. 2.2) shows how the X_k 's are related to the k -uple points of C :

Proposition 5.2 *Let $C \subset \mathbb{P}^2$ be a rational curve of degree $n \geq 3$. The schemes X_k introduced in Definition 5.1 are either 0-dimensional or empty. Moreover:*

- $\forall k, 2 \leq k \leq n - 1, X_k$ is non-empty iff there is at least a singular point on C of multiplicity $\geq k$.
- Every singular point of C yields at least a simple point of X_2 and

$$\text{length} X_2 = \binom{n - 1}{2}$$

(notice that X_2 is never empty since $n \geq 3$).

There are several properties of the singularities of C which are quite immediate to check using the schemes X_k (see [1], Prop. 3.1 and Prop. 4.4); we report some of them in the following Proposition 5.3, where, if $P \in \text{Sing}(C)$, δ_P denotes the number $\delta_P = \sum_q \binom{m_q}{2}$ where q runs over all points infinitely near P , and C_2 is the conic $y^2 - 4xz = 0$.

Proposition 5.3 *Let $C \subset \mathbb{P}^2$ be a rational curve, given by a proper parameterization (f_0, f_1, f_2) , with $f_i \in K[s, t]_n$. Let C_2, X_2 be as defined before. Then:*

- C is cuspidal if and only if $\text{Supp}(X_2) \subset C_2$ (in this case, the number of singular points of C is exactly the cardinality of $\text{Supp}(X_2)$).
- C has only ordinary singularities if and only if the scheme X_2 is reduced and $X_2 \cap C_2 = \emptyset$.
- Let C have only double points as singularities and let $R \in X_2$ and $P \in \text{Sing}(C)$ be the point associated to R . Then $\text{length}_R(X_2) = \delta_P$.

The algorithms given in [1] describe how to use the scheme X_2 in order to study double points; in the next section we show an example of how to construct a desired curve with a double point of type A_m .

6 An example of the use of techniques of section 5

In this section, with the program CoCoA (see [3]), we build an example which illustrates how to build a plane rational curve with a double point of a chosen type using projection techniques, and how to use the results of section 5 to study the singularities of a rational curve, given its parameterization. This example also gives another counterexample to Lemma 4.2 in [1].

Example 6.1 In the first part of this example we construct a rational sextic $C \subset \mathbb{P}^2$ with an A_5 singularity P (an *oscnode*), and we show that it is a counterexample to [1] 4.2. In the second part we construct the scheme X_2 relative to our curve and we complete the study of the singular locus of the curve.

Part I We use Theorem 2.1 as a guide; hence, in order to obtain an A_5 singularity, we want to view our curve as the projection of a rational normal curve $C_6 \subset \mathbb{P}^6$, with center a linear space $\Pi \cong \mathbb{P}^3$, onto a plane $H \subset \mathbb{P}^6$, in such a way that two points Q_1 and Q_2 on C_6

have the same image P , and moreover the two curvilinear schemes $3Q_1, 3Q_2$ on C_6 have a curvilinear scheme $X \subset C$ of length three as their projection, with X not contained in a line. The idea is the following: let $Q_1 = [0, 0, 0, 0, 0, 0, 1]$, $Q_2 = [1, 0, 0, 0, 0, 0, 0]$, and let L be the line through them. The ideal $I_L^3 + I_{C_6}$ in $K[z_0, \dots, z_6]$ defines the required curvilinear scheme $3Q_1 + 3Q_2$. We want to project C_6 from a 3-dimensional space Π into a plane H , choosing Π in such a way that the projection $\pi : C_6 \rightarrow C$ is generically 1:1; Π does not intersect C_6 and intersects L at one point, so that $\pi(Q_1) = \pi(Q_2)$; it does not intersect the two osculating spaces $O_{Q_i}^2(C_6)$, so that $\pi(O_{Q_1}^2(C_6)) = \pi(O_{Q_2}^2(C_6)) = H$; the image of $3Q_1 + 3Q_2$ is a curvilinear scheme of length 3 contained in C ; $\pi(4Q_1 + 4Q_2)$ is not a degree 4 curvilinear scheme on C .

If we manage to do so, the curve $C = \pi(C_6) \subset H$ will have an A_5 singularity in $P = \pi(Q_i)$ by Theorem 2.1. Moreover, the image $\pi(O_{Q_i}^2(C_6))$, $i = 1, 2$, will not be contained in a line, contradicting Lemma 4.2 of [1].

In the following we describe the procedure by using the program CoCoA (see [3]):

Use R:= QQ[a, b, c, d, e, f, g];

This is the ring of coordinates of \mathbb{P}^6 .

IL:= Ideal(b, c, d, e, f)³;

This is the ideal of the “triple line” L through the points $A = [1, 0, 0, 0, 0, 0, 0]$ and $B = [0, 0, 0, 0, 0, 0, 1]$ in \mathbb{P}^6 .

IC6= Ideal(ac - b², ad - bc, ae - bd, bd - c², be - cd, ce - d², df - e², de - cf, ce - bf, af - be, ag - bf, bg - cf, cg - df, dg - ef, eg - f²);

IP:= IL+ IC6;

This is the ideal $I_L^3 + I_{C_6}$ of the curvilinear scheme $3A + 3B$, supported on C_6 .

Now we consider the space $\Pi \cong \mathbb{P}^3$ whose ideal is $(a + g, 3f - b - d, 9e + c - d)$; Π intersects L in a point and does not intersect the two osculating planes $O_A^2(C_6)$ (whose ideal is (d, e, f, g)) and $O_B^2(C_6)$ (whose ideal is (a, b, c, d)). We want to project with center Π on the plane with coordinates u, v, w , where $u = a + g, v = 3f - b - d, w = 9e + c - d$.

Use R:= QQ[a, b, c, d, e, f, g, u, v, w];

IS:= IP+Ideal(u - a - g, v - 3f + b + d, w - 9e - c + d);

IIS:=Saturation(IS,Ideal(a, b, c, d, e, f, g));

Elim(a..g,IIS);

Ideal(w², vw, v² - uw)

The projection of $3A + 3B$ is a scheme whose ideal $(w^2, vw, v^2 - uw)$ shows that it is supported at $P = [1, 0, 0]$, it has length 3 (it is generated by 3 independent conics), it is curvilinear (it is contained in a smooth conic) and is not on a line, hence we have a good candidate for an A_5 at P .

Let us check that P is not an A_7 , we will go through the same steps starting with the ideal I_L^4 :

IL4:= Ideal(b, c, d, e, f)⁴;

IP4:= IL+IC6;

IS4:= IP+Ideal(u - a - g, v - 3f + b + d, w - 9e - c + d)

IIS4:=Saturation(IS,Ideal(a, b, c, d, e, f, g));

Elim(a..g,IIS4);

Ideal(w², 9/28v²w, 9/28v³ - 9/28uvw)

The ideal we got is not the ideal of a curvilinear scheme, since the three curves defined by $w^2, 9/28v^2w$ and $9/28v^3 - 9/28uvw$ are not smooth at P , and it can be checked that it has length 5. Hence P is not an A_7 by Theorem 2.1.

We are left to check that the projection is generically 1:1; for this it is enough to find a smooth point of the plane curve C which comes from only one point of C_6 via π . Let us consider the point $R = [1, 1, 1, 1, 1, 1] \in C_6$:

```
Use R:= QQ[a, b, c, d, e, f, g, u, v, w];
IR:= Ideal(a - b, b - c, c - d, d - e, e - f, f - g);
IR1:= I+ Ideal(u - a - g, v - 3f + b + d, w - 9e - c + d);
IIR1:=Saturation(I1,Ideal(a, b, c, d, e, f, g));
Elim(a..g,I1);
Ideal(v - 1/9w, u - 2/9w)
```

This shows that R projects to the point $[1, 2, 9] \in C$. Now we consider the (4-dimensional) cone on Π with vertex $[1, 2, 9]$ and we intersect it with C_6 .

```
Use R:= QQ[a, b, c, d, e, f, g];
ICONO:= Ideal(9e + c - d - 27f + 9b + 9d, 18e + 2c - 2d - 9a - 9g);
IC6:= Ideal(ac - b^2, ad - bc, ae - bd, bd - c^2, be - cd, ce - d^2, df - e^2, de - cf, ce - bf, af - be, ag - bf, bg - cf, cg - df, dg - ef, eg - f^2);
I:= IC6+ICONO;
II:=Saturation(IP,Ideal(a, b, c, d, e, f, g));
Print II;
Ideal(a - g, b - g, c - g, d - g, e - g, f - g)
```

Hence the cone intersects C_6 only in R (simply), and so π is generically 1:1.

Part II The singularity of C at P is now known; let us complete the study of the curve C by checking what the other singularities are. Since the ideal of Π is $(a + g, 3f - b - d, 9e + c - d)$, the parametric equations of C are:

$$u = s^6 + t^6 \quad ; \quad v = -s^5t + 3st^5 - s^3t^3 \quad ; \quad w = 9s^2t^4 + s^4t^2 - s^3t^3$$

We want to study the scheme $X_2 \subset \mathbb{P}^2$, defined by the 7×7 minors of M_2 :

```
Use R:= QQ[x, y, z];
M:=Mat([[x, y, z, 0, 0, 0, 0], [0, x, y, z, 0, 0, 0], [0, 0, x, y, z, 0, 0], [0, 0, 0, x, y, z, 0], [0, 0, 0, 0, x, y, z], [1, 0, 0, 0, 0, 0, 1], [0, -1, 0, -1, 0, 3, 0], [0, 0, 1, -1, 9, 0, 0]]);
MM:=Minors(7,M);
IX2:=Ideal(MM);
```

This is the ideal of the scheme X_2 .

```
Hilbert(R/IX2);
```

```
H(0) = 1
H(1) = 3
H(2) = 6
H(t) = 10 for t ≥ 3
```

X_2 has length 10, as expected (C is a rational sextic).

```
IZ2:=Radical(IX2);
```

```
Hilbert(R/IZ2);
H(0) = 1
H(1) = 3
H(2) = 6
H(t) = 8 for t ≥ 3
```

X_2 has support at Z_2 which is made of 8 points, hence $\text{Sing}C$ is made of our A_5 supported on P plus 7 double points of type A_1 or A_2 ; to decide if they are nodes or cusps, we proceed as follows:

```
ICUSP:= IX2+Ideal(y^2 - 4xz);
Hilbert(R/ICUSP);
```

$$\begin{aligned} H(0) &= 1 \\ H(1) &= 3 \\ H(2) &= 5 \\ H(3) &= 7 \\ H(4) &= 4 \\ H(t) &= 0 \text{ for } t \geq 5 \end{aligned}$$

X_2 does not intersect the conic which is the locus of points parameterizing tangent lines of C_6 , hence the seven simple points are all ordinary nodes A_1 .

Data sharing not applicable to this article as no datasets were generated or analyzed during the current study.

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