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Classification of generalized Wallach spaces

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Abstract In this paper, we present the classification of generalized Wallach spaces and discuss some related problems.

Keywords Generalized Wallach space · Compact homogeneous space · Symmetric space · Automorphism of a Lie algebra · Killing form · Riemannian metric · Einstein metric · Ricci flow

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1 Introduction and the main result

This paper is devoted to the classification of generalized Wallach spaces, a remarkable class of compact homogeneous spaces. These spaces were introduced in the paper [18], where they were called three-locally-symmetric spaces. Now we prefer to call them *generalized Wallach spaces* as in [20], because this term is less confusing and more informative. We begin with recalling some notations and definitions.

Let G/H be a compact homogeneous spaces with connected compact semisimple Lie group G and a compact subgroup H. Denote by \mathfrak{g} and \mathfrak{h} Lie algebras of G and H respectively. We suppose that G/H is almost effective, i. e. there are no non-trivial ideals of the Lie algebra \mathfrak{g} in $\mathfrak{h} \subset \mathfrak{g}$. Denote by $B = B(\cdot, \cdot)$ the Killing form of \mathfrak{g} . Since G is compact, B is negatively definite on \mathfrak{g} . Therefore, $\langle \cdot, \cdot \rangle := -B(\cdot, \cdot)$ is a positive definite inner product on \mathfrak{g} . Properties of B imply that $\langle \cdot, \cdot \rangle$ is bi-invariant, i. e. $\langle [Z, X], Y \rangle + \langle X, [Z, Y] \rangle = 0$ for all $X, Y, Z \in \mathfrak{g}$.

Let \mathfrak{p} be the $\langle \cdot, \cdot \rangle$ -orthogonal complement to \mathfrak{h} in \mathfrak{g} . It is clear that \mathfrak{p} is Ad(*H*)-invariant (and ad(\mathfrak{h})-invariant, in particular). The module \mathfrak{p} is naturally identified with the tangent space

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to G/H at the point eH, see e. g. [4, 7.23]. Every *G*-invariant Riemannian metric on G/H generates an Ad(*H*)-invariant inner product on p and vice versa [4, 7.24]. Therefore, it is possible to identify invariant Riemannian metrics on G/H with Ad(*H*)-invariant inner products on p. Note that the Riemannian metric generated by the inner product $\langle \cdot, \cdot \rangle |_{p}$ is called *standard* or *Killing*.

Remark 1 A linear subspace $q \subset p$ is ad(\mathfrak{h})-invariant if and only if it is Ad(H_0)-invariant, where H_0 is the unit component of the group H. Hence, these two notions are equivalent for connected H. It should be noted also, that the group H is connected provided that the space G/H is simply connected.

Suppose that a homogeneous space G/H has the following property: the module p is decomposed as a direct sum of three Ad(H)-invariant irreducible modules pairwise orthogonal with respect to $\langle \cdot, \cdot \rangle$, i. e.

$$\mathfrak{p} = \mathfrak{p}_1 \oplus \mathfrak{p}_2 \oplus \mathfrak{p}_3, \tag{1}$$

such that

$$[\mathfrak{p}_i,\mathfrak{p}_i] \subset \mathfrak{h} \quad \text{for} \quad i \in \{1, 2, 3\}.$$

Homogeneous spaces with this property are called generalized Wallach spaces.

Remark 2 The authors of [15,18] called these spaces *three-locally-symmetric*, since the condition (2) resembles the condition of local symmetry for homogeneous spaces (a locally symmetric homogeneous space G/H is characterized by the relation $[\mathfrak{p}, \mathfrak{p}] \subset \mathfrak{h}$, where $\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{p}$ and \mathfrak{p} is Ad(H)-invariant [4, 7.70]).

A detailed discussion on generalized Wallach spaces could be found in [20, pp.6346–6347] or [15], but we recall some important properties of these spaces for the reader's convenience.

There are many examples of these spaces, e. g. the manifolds of complete flags in the complex, quaternionic, and Cayley projective planes (a complete flag in any of these planes is a pair (p, l) where p is a point in the plane and l a line (complex, quaternionic or octonionic) containing the point p):

$$SU(3)/T_{\text{max}}$$
, $Sp(3)/Sp(1) \times Sp(1) \times Sp(1)$, $F_4/Spin(8)$

These spaces (known as *Wallach spaces*) are also interesting in that they admit invariant Riemannian metrics of positive sectional curvature (see [22]). The Lie group SU(2) $(H = \{e\})$ also could be considered as an example of generalized Wallach spaces. Note also that $SO(3)/(\mathbb{Z}_2 \times \mathbb{Z}_2)$ is the manifold of complete flags in the real projective plane. It is interesting that the above manifolds of complete flags have representations as so-called *Cartans isoparametric submanifolds*, see e. g. [21] for details.

Other examples of generalized Wallach spaces are some Kähler C-spaces such as

$$SU(n_1 + n_2 + n_3) / S(U(n_1) \times U(n_2) \times U(n_3)),$$

$$SO(2n) / U(1) \times U(n-1), \quad E_6 / U(1) \times U(1) \times Spin(8).$$

There are two more 3-parameter families of generalized Wallach spaces:

,

$$SO(n_1 + n_2 + n_3)/SO(n_1) \times SO(n_2) \times SO(n_3)$$

 $Sp(n_1 + n_2 + n_3)/Sp(n_1) \times Sp(n_2) \times Sp(n_3).$

Note that every generalized Wallach space admits a 3-parameter family of invariant Riemannian metrics determined by Ad(H)-invariant inner products

$$(\cdot, \cdot) = x_1 \langle \cdot, \cdot \rangle|_{\mathfrak{p}_1} + x_2 \langle \cdot, \cdot \rangle|_{\mathfrak{p}_2} + x_3 \langle \cdot, \cdot \rangle|_{\mathfrak{p}_3}, \qquad (3)$$

where x_1 , x_2 , x_3 are positive real numbers.

In [18], it was shown that every generalized Wallach space admits at least one invariant Einstein metric. This result could not be improved in general (e. g. SU(2) admits exactly one invariant Einstein metric). Later in [15], a detailed study of invariant Einstein metrics was developed for all generalized Wallach spaces. In particular, it is proved that there are at most four Einstein metrics (up to homothety) for every such space. A detailed discussion and the references related to all known results on Einstein invariant metrics on generalized Wallach spaces one can find in [20]. More detailed information on invariant Einstein metric on general homogeneous spaces could be found in [4–6,23,24].

In the recent papers [1,2], generalized Wallach spaces were studied from the point of view of the Ricci flow. Some results of these papers we will discuss in the last section.

Denote by d_i the dimension of \mathfrak{p}_i . Let $\{e_i^j\}$ be an orthonormal basis in \mathfrak{p}_i with respect to $\langle \cdot, \cdot \rangle$, where $i \in \{1, 2, 3\}, 1 \le j \le d_i = \dim(\mathfrak{p}_i)$. Consider the expression [ijk] defined by the equality

$$[ijk] = \sum_{\alpha,\beta,\gamma} \left\langle \left[e_i^{\alpha}, e_j^{\beta} \right], e_k^{\gamma} \right\rangle^2, \tag{4}$$

where α , β , and γ range from 1 to d_i , d_j , and d_k respectively, see [25]. The symbols [ijk] are symmetric in all three indices by the bi-invariance of the metric $\langle \cdot, \cdot \rangle$. Moreover, for spaces under consideration, we have [ijk] = 0 if two indices coincide. Therefore, the quantity

$$A := [123] \tag{5}$$

plays an important role. It easy to see that $d_i \ge 2A$ for all i = 1, 2, 3 (see [18] or Lemma 7 below). Hence the following constants

$$a_i = \frac{A}{d_i}, \quad i \in \{1, 2, 3\},$$
 (6)

are such that $(a_1, a_2, a_3) \in [0, 1/2]^3$. Note that these constants completely determine some important properties of a generalized Wallach space G/H, e. g. the equation of the Ricci flow on G/H, see [1,2]. Of course, not every triple $(a_1, a_2, a_3) \in [0, 1/2]^3$ corresponds to some generalized Wallach space. A complete description of suitable triples we will get together with the classification of generalized Wallach spaces.

Now we are ready to state the main result of this paper.

Theorem 1 Let G/H be a connected and simply connected compact homogeneous space. Then G/H is a generalized Wallach space if and only if it is of one of the following types:

- 1) G/H is a direct product of three irreducible symmetric spaces of compact type ($A = a_1 = a_2 = a_3 = 0$ in this case);
- The group G is simple and the pair (g, h) is one of the pairs in Table 1 (the embedding of h to g is determined by the following requirement: the corresponding pairs (g, t_i) and (t_i, h), i = 1, 2, 3, in Table 2 are symmetric);
- 3) $G = F \times F \times F \times F$ and $H = \text{diag}(F) \subset G$ for some connected simply connected compact simple Lie group F, with the following description on the Lie algebra level:

$$(\mathfrak{g},\mathfrak{h}) = (\mathfrak{f} \oplus \mathfrak{f} \oplus \mathfrak{f} \oplus \mathfrak{f}, \operatorname{diag}(\mathfrak{f}) = \{(X, X, X, X) \mid X \in f\}),\$$

where f is the Lie algebra of F, and (up to permutation) $p_1 = \{(X, X, -X, -X) | X \in f\}, p_2 = \{(X, -X, X, -X) | X \in f\}, p_3 = \{(X, -X, -X, X) | X \in f\} (a_1 = a_2 = a_3 = 1/4 in this case).$

The paper is divided into five sections. In Sect. 2 we discuss connections between generalized Wallach spaces and $\mathbb{Z}_2 \times \mathbb{Z}_2$ -subgroups in the automorphism groups Aut(g) of compact Lie algebras g. The second section is devoted to general structural results on generalized Wallach spaces G/H with connected H. In Sect. 4 we get a classification of generalized Wallach spaces G/H with simple G and connected H. In Sect. 5 we calculate the values of a_1, a_2, a_3 for all pairs in Table 1. Finally, in the last section we discuss properties of the set of points $(a_1, a_2, a_3) \in [0, 1/2]^3 \subset \mathbb{R}^3$ and Einstein invariant metrics on generalized Wallach spaces.

The **proof of Theorem** 1 follows immediately from Theorem 3, Theorem 4, and Proposition 2. The calculations of a_1 , a_2 , a_3 for all pairs in Table 1 are performed in Sect. 6.

When this paper was completed, the author saw the very recent paper [7], where (in particular) the classification of generalized Wallach spaces G/H with simple G was obtained.

2 Generalized Wallach spaces and involutive automorphisms

Let us consider connected compact homogeneous spaces G/H with the properties (1) and (2). We emphasize that we do not demand that the modules \mathfrak{p}_i are $\mathrm{Ad}(H)$ -irreducible now. The inclusion $[\mathfrak{p}_i, \mathfrak{p}_i] \subset \mathfrak{h}$ implies that

$$\mathfrak{k}_i := \mathfrak{h} \oplus \mathfrak{p}_i \tag{7}$$

is a subalgebra of \mathfrak{g} for any i, and the pair $(\mathfrak{k}_i, \mathfrak{h})$ is symmetric (it could be non-effective, of course). From (1) and (2) we easily get that $[\mathfrak{p}_j, \mathfrak{p}_k] \subset \mathfrak{p}_i$ for pairwise distinct i, j, k. Therefore,

$$[\mathfrak{p}_i \oplus \mathfrak{p}_k, \mathfrak{p}_i \oplus \mathfrak{p}_k] \subset \mathfrak{h} \oplus \mathfrak{p}_i = \mathfrak{k}_i, \quad \{i, j, k\} = \{1, 2, 3\},\$$

and all the pairs $(\mathfrak{g}, \mathfrak{k}_i)$ are also symmetric.

Let us consider involutive automorphisms

$$\sigma_i:\mathfrak{g}\mapsto\mathfrak{g},\quad i\in\{1,2,3\},$$

of the Lie algebra g, such that

$$\sigma_i|_{\mathfrak{k}_i} = \mathrm{Id}, \quad \sigma_i|_{\mathfrak{p}_i \oplus \mathfrak{p}_k} = -\mathrm{Id}_i$$

which do exist due to well known structure results (see e. g. [26, theorem 8.1.4]). It is easy to see that

$$\sigma_i \circ \sigma_i = \sigma_i \circ \sigma_i = \sigma_k$$

for pairwise distinct *i*, *j*, *k*. Keeping in mind that $\sigma_1 \circ \sigma_1 = \sigma_2 \circ \sigma_2 = \sigma_3 \circ \sigma_3 = \text{Id on } \mathfrak{g}$, we get the following

Proposition 1 The automorphisms σ_1 , σ_2 , and σ_3 generate a $\mathbb{Z}_2 \times \mathbb{Z}_2$ -subgroup in Aut(\mathfrak{g}), the group of automorphisms of the Lie algebra \mathfrak{g} . Every pair of these automorphisms is a set of generators of this group.

Now, let g be a compact semisimple Lie algebra and let Γ be a $\mathbb{Z}_2 \times \mathbb{Z}_2$ -subgroup in the group of automorphisms Aut(g) of g. Suppose that σ_1 and σ_2 are generators of Γ , and consider an inner product -B on g, where B is the Killing form of g. Since $\sigma_1 \circ \sigma_1 = \sigma_2 \circ \sigma_2 = \text{Id}$ and $\sigma_1 \circ \sigma_2 = \sigma_2 \circ \sigma_1$, we have **commutating normal operators** σ_1 and σ_2 on the Euclidean

Table 1	The pairs (g, h) corre	sponded to generalized Wallacl	h spaces G/H w	ith simple G				
z	ß	ť	d_1	d_2	d_3	<i>a</i> 1	<i>a</i> 2	<i>a</i> 3
1	so(k+l+m)	$so(k) \oplus so(l) \oplus so(m)$	kl	km	lm	$\frac{m}{2(k+l+m-2)}$	$\frac{l}{2(k+l+m-2)}$	$\frac{k}{2(k+l+m-2)}$
5	su(k+l+m)	$s(u(k) \oplus u(l) \oplus u(m))$	2kl	2km	2lm	$\frac{m}{2(k+l+m)}$	$\frac{l}{2(k+l+m)}$	$\frac{k}{2(k+l+m)}$
3	sp(k+l+m)	$sp(k) \oplus sp(l) \oplus sp(m)$	4kl	4km	4 <i>lm</i>	$\frac{m}{2(k+l+m+1)}$	$\frac{l}{2(k+l+m+1)}$	$\frac{k}{2(k+l+m+1)}$
4	$su(2l), \ l \ge 2$	n(l)	l(l - 1)	l(l + 1)	$l^{2} - 1$	$\frac{l+1}{4l}$	$\frac{l-1}{4l}$	<u>1</u>
5	$so(2l), \ l \ge 4$	$u(1) \oplus u(l-1)$	2(l-1)	2(l - 1)	(l-1)(l-2)	$\frac{l-2}{4(l-1)}$	$\frac{l-2}{4(l-1)}$	$\frac{1}{2(l-1)}$
9	<i>e</i> 6	$su(4) \oplus 2sp(1) \oplus \mathbb{R}$	16	16	24	$\frac{1}{4}$	1 4	16
7	e6	$so(8) \oplus \mathbb{R}^2$	16	16	16	$\frac{1}{6}$	$\frac{1}{6}$	$\frac{1}{6}$
8	e6	$sp(3) \oplus sp(1)$	14	28	12	<u>1</u> 4	<u>1</u> 8	$\frac{7}{24}$
6	e_7	$so(8) \oplus 3sp(1)$	32	32	32	<u>9</u>	<u>9</u> 2	<u>9</u>
10	еŢ	$su(6)\oplus sp(1)\oplus \mathbb{R}$	30	40	24	<u>9</u>	$\frac{1}{6}$	<u>5</u> <u>18</u>
11	e_7	so(8)	35	35	35	<u>5</u> <u>18</u>	<u>5</u> <u>18</u>	<u>5</u> <u>18</u>
12	e8	$so(12) \oplus 2sp(1)$	64	64	48	<u>5</u> 1	<u>5</u>	<u>15</u>
13	e8	$so(8) \oplus so(8)$	64	64	64	<u>15</u>	<u>15</u>	$\frac{4}{15}$
14	f_4	$so(5) \oplus 2sp(1)$	8	8	20	5 18	5 18	$\frac{1}{9}$
15	f_4	so(8)	8	8	œ	$\frac{1}{9}$	$\frac{1}{9}$	<u>1</u>

space $(\mathfrak{g}, -B)$. Moreover, since they are involutions, their eigenvalues are exactly 1 and -1. Therefore, these operator could be **diagonalized simultaneously**, see e. g. [11, 2.5.15].

Let us consider the following linear subspaces of g:

$$\mathfrak{h} = \{ X \in \mathfrak{g} \mid \sigma_1(X) = \sigma_2(X) = X \}, \mathfrak{p}_1 = \{ X \in \mathfrak{g} \mid -\sigma_1(X) = \sigma_2(X) = X \},$$
$$\mathfrak{p}_2 = \{ X \in \mathfrak{g} \mid \sigma_1(X) = -\sigma_2(X) = X \}, \mathfrak{p}_3 = \{ X \in \mathfrak{g} \mid -\sigma_1(X) = -\sigma_2(X) = X \}$$

It is clear that all these subspaces are pairwise orthogonal with respect to -B, \mathfrak{h} is a Lie subalgebra in $\mathfrak{g}, \mathfrak{g} = \mathfrak{h} \oplus \mathfrak{p}_1 \oplus \mathfrak{p}_2 \oplus \mathfrak{p}_3$, and $[\mathfrak{p}_i, \mathfrak{p}_i] \subset \mathfrak{h}, i \in \{1, 2, 3\}$. Therefore, we get a compact homogeneous space G/H with the properties (1) and (2), where G is a connected and simply connected Lie group with the Lie algebra \mathfrak{g} and H is a connected subgroup corresponding to the Lie subalgebra \mathfrak{h} . Hence we get the following

Theorem 2 There is a one-to-one correspondence between $\mathbb{Z}_2 \times \mathbb{Z}_2$ -subgroups in the automorphism groups $\operatorname{Aut}(\mathfrak{g})$ of compact semisimple Lie algebras \mathfrak{g} and connected and simply connected compact homogeneous spaces with the properties (1) and (2).

In order to classify all (connected and simply connected) generalized Wallach spaces, it is enough to classify "suitable" $\mathbb{Z}_2 \times \mathbb{Z}_2$ -subgroups in the group of automorphisms Aut(g) of compact semisimple Lie algebras g. Here, "suitable" means that the corresponding modules \mathfrak{p}_i are Ad(*H*)-irreducible or, equivalently (due to connectedness of *H*), ad(\mathfrak{h})-irreducible. We will realize this idea for generalized Wallach spaces *G*/*H* with simple *G* in Sect. 5. But in the general case we should get more detailed structural results in the next section.

3 On the structure of generalized Wallach spaces

Here we consider the structure of a generalized Wallach space G/H with connected H. Recall that the properties of a module $\mathfrak{q} \subset \mathfrak{p}$ to be $\mathrm{Ad}(H)$ -invariant and $\mathrm{ad}(\mathfrak{h})$ -invariant are equivalent for a connected group H. We will use notations as above. Since the Lie algebra \mathfrak{g} is semisimple, then we can decompose it into a ($\langle \cdot, \cdot \rangle$ -orthogonal) sum of simple ideals

$$\mathfrak{g} = \mathfrak{g}_1 \oplus \mathfrak{g}_2 \oplus \cdots \oplus \mathfrak{g}_s.$$

Let $\varphi_i : \mathfrak{h} \to \mathfrak{g}_i$ be the $\langle \cdot, \cdot \rangle$ -orthogonal projection. It is easy to see that all these projections are Lie algebra homomorphisms. We rearrange indices so that $\varphi_i(\mathfrak{h}) \neq \mathfrak{g}_i$ for i = 1, 2, ..., p and $\varphi_i(\mathfrak{h}) = \mathfrak{g}_i$ for i = p + 1, ..., s.

Since the Lie algebra \mathfrak{h} is compact, then we can decompose it into a ($\langle \cdot, \cdot \rangle$ -orthogonal) sum of the center and simple ideals

$$\mathfrak{h}=\mathbb{R}^l\oplus\mathfrak{h}_1\oplus\mathfrak{h}_2\oplus\cdots\oplus\mathfrak{h}_m$$

For i = 1, ..., m, we denote by a^i the vector $(a_1^i, a_2^i, ..., a_s^i) \in \mathbb{R}^s$, where $a_j^i = 1$, if $\varphi_j(\mathfrak{h}_i)$ is isomorphic to \mathfrak{h}_i , and $a_j^i = 0$, if $\varphi_j(\mathfrak{h}_i)$ is a trivial Lie algebra (there is no another possibility, because φ_j is a Lie algebra homomorphism). It is easy to see that $\sum_{i=1}^m a_j^i = 1$ for j = p + 1, ..., s, since $\varphi_j(\mathfrak{h}) = \mathfrak{g}_j$ is a simple Lie algebra. Denote also the number $\dim(\varphi_i(\mathbb{R}^l))$ by u_i for i = 1, ..., s, and put $u = \sum_{i=1}^s u_i, v_i = \sum_{j=1}^s a_j^i$ for i = 1, ..., m. It is clear that $u \ge l$ and $v_i \ge 1$ for all i.

Lemma 1 In the above notation, the following inequality holds:

$$p + u + \sum_{i=1}^{m} v_i - l - m = p + (u - l) + \sum_{i=1}^{m} (v_i - 1) \le 3.$$

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Proof For i = 1, 2, ..., p, every \mathfrak{g}_i contains at least one irreducible modules $\mathfrak{p}_j \subset \mathfrak{p}$, since $\varphi_i(\mathfrak{h}) \neq \mathfrak{g}_i$ and $\langle \cdot, \cdot \rangle$ -orthogonal complement to $\varphi_i(\mathfrak{h})$ in \mathfrak{g}_i is a subset of \mathfrak{p} . This gives at least p irreducible modules. Further, an $\langle \cdot, \cdot \rangle$ -orthogonal complement to \mathbb{R}^l in $\bigoplus_{i=1}^s \varphi_i(\mathbb{R}^l)$ is also a subset of \mathfrak{p} . It is clear that $\mathfrak{ad}(\mathfrak{h})$ acts trivially on this complement, hence we get exactly u - l one-dimensional irreducible submodules in it. Finally, for any i = 1, ..., m, an $\langle \cdot, \cdot \rangle$ -orthogonal complement to \mathfrak{h}_i in $\bigoplus_{j=1}^s \varphi_j(\mathfrak{h}_i)$ is also subset of \mathfrak{p} . In fact, we deal with compliment to $\mathfrak{diag}(\mathfrak{h}_i)$ in $\mathfrak{h}_i \oplus \mathfrak{h}_i \oplus \cdots \oplus \mathfrak{h}_i$ (v_i pairwise isomorphic summands). In this case we have exactly $(v_i - 1)$ ad(\mathfrak{h})-irreducible modules. Summing all numbers of irreducible submodules, we get the lemma.

Without loss of generality we may rearrange the indices so that $v_1 \ge v_2 \ge \cdots \ge v_{m-1} \ge v_m (\ge 1)$. Then we get the following

Corollary 1 In the above notation, the following inequality holds:

$$p \le 3$$
, $u - l \le 3$, $v_4 = 1$, $v_3 \le 2$.

Lemma 2 If two of the modules $\mathfrak{p}_1, \mathfrak{p}_2, \mathfrak{p}_3$ are subsets of \mathfrak{g}_i for some $i = 1, \ldots s$, then the third module is also a subset of \mathfrak{g}_i . In this case p = 1.

Proof Suppose, e. g. that $\mathfrak{p}_1, \mathfrak{p}_2 \subset \mathfrak{g}_i$, then $[\mathfrak{p}_1, \mathfrak{p}_2] \subset \mathfrak{g}_i \cap \mathfrak{p}_3$. If $[\mathfrak{p}_1, \mathfrak{p}_2] \neq 0$, then a nonempty module $\mathfrak{g}_i \cap \mathfrak{p}_3$ is $\mathrm{ad}(\mathfrak{h})$ -invariant, since this property have both \mathfrak{p}_3 and \mathfrak{g}_i (as an ideal in \mathfrak{g}). On the other hand, $\mathfrak{g}_i \cap \mathfrak{p}_3 \subset \mathfrak{p}_3$ and \mathfrak{p}_3 is $\mathrm{ad}(\mathfrak{h})$ -irreducible. Therefore, $\mathfrak{g}_i \cap \mathfrak{p}_3 = \mathfrak{p}_3$ and $\mathfrak{p}_3 \subset \mathfrak{g}_i$.

If $\mathfrak{g}_i \neq \varphi_i(\mathfrak{h}) + \mathfrak{p}_1 + \mathfrak{p}_2$, then we get $\mathfrak{p}_3 \subset \mathfrak{g}_i$ again, because an $\langle \cdot, \cdot \rangle$ -orthogonal complement to $\varphi_i(\mathfrak{h})$ in \mathfrak{g}_i is a subset of \mathfrak{p} .

Now, suppose that $[\mathfrak{p}_1, \mathfrak{p}_2] = 0$ and $\mathfrak{g}_i = \varphi_i(\mathfrak{h}) + \mathfrak{p}_1 + \mathfrak{p}_2$. Note that $[\varphi_i(\mathfrak{h}), \mathfrak{p}_1] \subset \mathfrak{p}_1$ $([Y, X] = [\varphi_i(Y), X] \subset \mathfrak{p}_1$ for every $Y \in \mathfrak{h}$ and every $X \in \mathfrak{p}_1 \subset \mathfrak{g}_i$, $[\mathfrak{p}_2, \mathfrak{p}_1] = 0$, and $[\mathfrak{p}_1, \mathfrak{p}_1] \subset \mathfrak{h} \cap \mathfrak{g}_i$, hence $[\mathfrak{g}_i, \mathfrak{p}_1] \subset [\mathfrak{p}_1, \mathfrak{p}_1] + \mathfrak{p}_1$ and $[\mathfrak{g}_i, [\mathfrak{p}_1, \mathfrak{p}_1]] \subset [\mathfrak{p}_1, [\mathfrak{p}_1, \mathfrak{p}_1] + \mathfrak{p}_1] \subset [\mathfrak{p}_1, \mathfrak{p}_1] + \mathfrak{p}_1 \subset [\mathfrak{p}_1, \mathfrak{p}_1] + \mathfrak{p}_1$ is a proper ideal in \mathfrak{g}_i , that is impossible.

The last assertion of the lemma is obvious.

Lemma 3 If A = 0, then G/H is locally a direct product of three irreducible symmetric spaces of compact type. A simply connected G/H with A = 0 is a direct product of three irreducible symmetric spaces of compact type.

Proof It is known that A = 0 if and only if the space G/H is locally a direct product of three compact irreducible symmetric spaces (see [15, Theorem 2]). Finally, we remind that complete (in particular, homogeneous) and simply connected locally symmetric space is a symmetric space, see e. g. [10, Theorem 5.6]. Hence we get the lemma.

Corollary 2 If $p \ge 2$, then A = 0, consequently, G/H locally is a direct product of three irreducible symmetric spaces of compact type.

Proof By Lemma 2 we get that one of the modules p_1 , p_2 , p_3 is in g_1 and the second one is in g_2 . Hence, $[p_1, p_2] = 0$ and A = 0. Now, it suffices to apply Lemma 3.

Lemma 4 If p = 1, then s = 1 and the Lie algebra $g = g_1$ is simple.

Proof Suppose the contrary, $s \ge 2$. Without loss of generality we may assume that $\mathfrak{p}_1 \subset \mathfrak{g}_1$. Then by Lemma 2, \mathfrak{p}_2 and \mathfrak{p}_3 are not subsets of \mathfrak{g}_1 . Hence, \mathfrak{p}_1 is an $\langle \cdot, \cdot \rangle$ -orthogonal

complement to $\varphi_1(\mathfrak{h})$ in \mathfrak{g}_1 . By definition of p, $\mathfrak{g}_i = \varphi_i(\mathfrak{h})$ for $2 \le i \le s$. Hence, $u_i = \dim(\varphi_i(\mathbb{R}^l)) = 0$ for $i \ge 2$, and $u = u_1 = \dim(\varphi_1(\mathbb{R}^l)) = l$. Since p = 1 and u = l we get $\sum_{i=1}^m (v_j - 1) \le 2$ by Lemma 1.

If $v_j = 1$ for j = 1, ..., m, then all $\mathfrak{g}_i = \varphi_i(\mathfrak{h})$ are ideals of \mathfrak{g} in \mathfrak{h} for $2 \le i \le s$, that is impossible due to the effectiveness of the pair $(\mathfrak{g}, \mathfrak{h})$.

Since $v_1 \ge v_2 \ge v_3 \ge \cdots \ge v_m \ge 1$, we should check the following possibilities: $(v_1, v_2) = (2, 1), (v_1, v_2) = (3, 1), \text{ and } (v_1, v_2, v_3) = (2, 2, 1).$ Note that all \mathfrak{h}_j with $v_j = 1$ are such that $\varphi_i(\mathfrak{h}_j)$ is trivial for $2 \le i \le s$, otherwise $\mathfrak{g}_i = \varphi_i(\mathfrak{h}_j) = \varphi_i(\mathfrak{h})$ are ideals of \mathfrak{g} in \mathfrak{h} .

The case $(v_1, v_2) = (2, 1)$ is impossible, because p in this case contains only two ad(h)-irreducible modules.

Let us consider the case $(v_1, v_2) = (3, 1)$. If $\varphi_1(\mathfrak{h}_1)$ is trivial, then $[\mathfrak{p}_1, \mathfrak{p}_2 \oplus \mathfrak{p}_3] = 0$ and A = 0, that is impossible due to Lemma 3. Hence, without loss of generality we may assume that $a_1^1 = a_2^1 = a_3^1 = 1$ and $a_i^1 = 0$ for $i \ge 4$. Then, $\mathfrak{p}_2 \oplus \mathfrak{p}_3$ should coincide with an $\langle \cdot, \cdot \rangle$ -orthogonal complement to diag (\mathfrak{h}_1) in $\varphi_1(\mathfrak{h}_1) \oplus \varphi_2(\mathfrak{h}_1) \oplus \varphi_3(\mathfrak{h}_1) \simeq 3\mathfrak{h}_1$. But $[\mathfrak{p}_1, \mathfrak{p}_2] \subset \mathfrak{g}_1$ (since \mathfrak{g}_1 is an ideal in \mathfrak{g}), that contradicts to $[\mathfrak{p}_1, \mathfrak{p}_2] \subset \mathfrak{p}_3$.

Finally, consider the case $(v_1, v_2, v_3) = (2, 2, 1)$. If $\varphi_1(\mathfrak{h}_1)$ or $\varphi_1(\mathfrak{h}_2)$ is trivial, then $[\mathfrak{p}_1, \mathfrak{p}_2] = 0$ or $[\mathfrak{p}_1, \mathfrak{p}_3] = 0$ which implies A = 0, that is impossible due to Lemma 3. Hence, without loss of generality we may assume that $a_1^1 = a_2^1 = 1$, $a_i^1 = 0$ for $i \ge 3$, $a_1^2 = a_3^2 = 1$, $a_i^3 = 0$ for other *i*. Further, without loss of generality, \mathfrak{p}_2 is an $\langle \cdot, \cdot \rangle$ -orthogonal complement to diag (\mathfrak{h}_1) in $\varphi_1(\mathfrak{h}_1) \oplus \varphi_2(\mathfrak{h}_1) \simeq 2\mathfrak{h}_1$ and \mathfrak{p}_3 is an $\langle \cdot, \cdot \rangle$ -orthogonal complement to diag (\mathfrak{h}_2) in $\varphi_1(\mathfrak{h}_2) \oplus \varphi_3(\mathfrak{h}_2) \simeq 2\mathfrak{h}_2$. As in the previous case, $[\mathfrak{p}_1, \mathfrak{p}_2] \subset \mathfrak{g}_1$, that contradicts to $[\mathfrak{p}_1, \mathfrak{p}_2] \subset \mathfrak{p}_3$. The lemma is proved.

Lemma 5 If p = 0, then either A = 0 or $(\mathfrak{g}, \mathfrak{h}) = (\mathfrak{f} \oplus \mathfrak{f} \oplus \mathfrak{f} \oplus \mathfrak{f}, \operatorname{diag}(\mathfrak{f}) = \{(X, X, X, X) | X \in f\})$ for a simple compact Lie algebra \mathfrak{f} . Moreover, up to permutation, we have $\mathfrak{p}_1 = \{(X, X, -X, -X) | X \in f\}$, $\mathfrak{p}_2 = \{(X, -X, X, -X) | X \in f\}$, $\mathfrak{p}_3 = \{(X, -X, -X, X) | X \in f\}$.

Proof Since p = 0, then $u_i = \dim(\varphi_i(\mathbb{R}^l)) = 0$ for all i, and u = 0 = l. Since p = 0 and u = l we get $\sum_{j=1}^{m} (v_j - 1) \le 3$ by Lemma 1. Since $\mathfrak{g}_i = \varphi_i(\mathfrak{h})$ for all i, then every \mathfrak{g}_i is isomorphic to some simple Lie algebra \mathfrak{h}_j .

If $v_j = 1$ for some j = 1, ..., m, then all \mathfrak{h}_j is an ideal of \mathfrak{g} in \mathfrak{h} (indeed, there is exactly one $i \in 1, ..., s$ with $a_i^j = 1$, hence $\mathfrak{g}_i = \varphi_i(\mathfrak{h}_j) = \varphi_i(\mathfrak{h})$), that is impossible due to the effectiveness of the pair ($\mathfrak{g}, \mathfrak{h}$). Therefore, $v_j \ge 2$ for all j = 1, ..., m. Since $\sum_{j=1}^m (v_j - 1) \le 3$, then we we should check the following possibilities: m = 3, m = 2 and m = 1.

If m = 3, then $v_1 = v_2 = v_3 = 2$. It is easy to see, that (up to permutation) \mathfrak{p}_1 is the $\langle \cdot, \cdot \rangle$ -orthogonal complement to diag(\mathfrak{h}_1) in $\varphi_1(\mathfrak{h}_1) \oplus \varphi_2(\mathfrak{h}_1) \simeq 2\mathfrak{h}_1$, \mathfrak{p}_2 is the $\langle \cdot, \cdot \rangle$ orthogonal complement to diag(\mathfrak{h}_2) in $\varphi_3(\mathfrak{h}_2) \oplus \varphi_4(\mathfrak{h}_2) \simeq 2\mathfrak{h}_2$ and \mathfrak{p}_3 is the $\langle \cdot, \cdot \rangle$ -orthogonal complement to diag(\mathfrak{h}_3) in $\varphi_5(\mathfrak{h}_3) \oplus \varphi_6(\mathfrak{h}_3) \simeq 2\mathfrak{h}_3$. Obviously in this case we have A = 0.

If m = 2, then either $(v_1, v_2) = (2, 2)$ or $(v_1, v_2) = (3, 2)$. The case $(v_1, v_2) = (2, 2)$ is impossible, because p in this case contains only two ad(\mathfrak{h})-irreducible modules. If $(v_1, v_2) =$ (3, 2), then $\mathfrak{p}_1 \oplus \mathfrak{p}_2$ is the $\langle \cdot, \cdot \rangle$ -orthogonal complement to diag(\mathfrak{h}_1) in $\varphi_1(\mathfrak{h}_1) \oplus \varphi_2(\mathfrak{h}_1) \oplus$ $\varphi_3(\mathfrak{h}_1) \simeq 3\mathfrak{h}_1$, and \mathfrak{p}_3 is the $\langle \cdot, \cdot \rangle$ -orthogonal complement to diag(\mathfrak{h}_2) in $\varphi_4(\mathfrak{h}_2) \oplus \varphi_5(\mathfrak{h}_2) \simeq$ $2\mathfrak{h}_2$. Since $[\mathfrak{p}_1 \oplus \mathfrak{p}_2, \mathfrak{p}_3] = 0$, we get A = 0 (in fact, it is easy to prove that this variant is impossible at all).

If m = 1, then we have $(\mathfrak{g}, \mathfrak{h}) = (s \cdot \mathfrak{h}_1, \operatorname{diag}(\mathfrak{h}_1))$, and G/H is a so-called Ledzer – Obata space, see [14, section 4] or [19]. It should be noted also that for any compact Lie group F, a Ledzer – Obata space $F^s/\operatorname{diag}(F)$ is diffeomorphic to the Lie group F^{s-1} [14, P. 453].

It is known that the module \mathfrak{p} decomposed in this case into the sum of s - 1 pairwise $ad(\mathfrak{h})$ -isomorphic irreducible summand, but such a decomposition is not unique, see [19]. Hence, s = 4 and $(\mathfrak{g}, \mathfrak{h}) = (\mathfrak{f} \oplus \mathfrak{f} \oplus \mathfrak{f} \oplus \mathfrak{f}, diag(\mathfrak{f}))$ for some simple Lie algebra $\mathfrak{f}(=\mathfrak{h}_1)$.

Clear that $\mathfrak{h} = \{(X, X, X, X) | X \in f\}$. Any $\mathrm{ad}(\mathfrak{h})$ -irreducible module in \mathfrak{p} has the form $\mathfrak{q} = \{(\alpha_1 X, \alpha_2 X, \alpha_3 X, \alpha_4 X) | X \in f\}$, where $\alpha = (\alpha_1, \alpha_2, \alpha_3, \alpha_4) \in \mathbb{R}^4$ is of unit length and satisfies $\alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 = 0$. Therefore, \mathfrak{p} could be decomposed into a sum of $\mathrm{ad}(\mathfrak{h})$ -irreducible and pairwise $\langle \cdot, \cdot \rangle$ -orthogonal modules only as follows (see details in [19]): $\mathfrak{p} = \mathfrak{p}_1 \oplus \mathfrak{p}_2 \oplus \mathfrak{p}_3$, where

$$\mathfrak{p}_{1} = \{ (\alpha_{1}X, \alpha_{2}X, \alpha_{3}X, \alpha_{4}X) \mid X \in f \}, \qquad \mathfrak{p}_{2} = \{ (\beta_{1}X, \beta_{2}X, \beta_{3}X, \beta_{4}X) \mid X \in f \}, \\ \mathfrak{p}_{3} = \{ (\gamma_{1}X, \gamma_{2}X, \gamma_{3}X, \gamma_{4}X) \mid X \in f \}, \qquad (\alpha, \alpha) = (\beta, \beta) = (\gamma, \gamma) = 1, \\ \alpha_{1} + \alpha_{2} + \alpha_{3} + \alpha_{4} = 0, \qquad \beta_{1} + \beta_{2} + \beta_{3} + \beta_{4} = 0, \qquad \gamma_{1} + \gamma_{2} + \gamma_{3} + \gamma_{4} = 0, \\ (\alpha, \beta) = (\alpha, \gamma) = (\beta, \gamma) = 0, \text{ where } (x, y) = x_{1}y_{1} + x_{2}y_{2} + x_{3}y_{3} + x_{4}y_{4}, \ x, y \in \mathbb{R}^{4} \}$$

Since $[\mathfrak{p}_i, \mathfrak{p}_i] \subset \mathfrak{h}$, i = 1, 2, 3, then $|\alpha_1| = |\alpha_2| = |\alpha_3| = |\alpha_4| = |\beta_1| = |\beta_2| = |\beta_3| = |\beta_4| = |\gamma_1| = |\gamma_2| = |\gamma_3| = |\gamma_4| = 1/2$. Therefore, up to permutation, $\alpha = (1/2, 1/2, -1/2, -1/2), \beta = (1/2, -1/2, 1/2, -1/2), \gamma = (1/2, -1/2, -1/2, 1/2)$. The lemma is proved.

From the previous results of this section we immediately get

Theorem 3 Let G/H be a generalized Wallach space with connected H. Then one of the following assertions holds:

- 1) G/H is locally a direct product of three irreducible symmetric spaces of compact type;
- 2) The group G is simple;
- 3) On the Lie algebra level, $(\mathfrak{g}, \mathfrak{h}) = (\mathfrak{f} \oplus \mathfrak{f} \oplus \mathfrak{f} \oplus \mathfrak{f}, \operatorname{diag}(\mathfrak{f}) = \{(X, X, X, X) | X \in f\}$) for a simple compact Lie algebra \mathfrak{f} and, up to permutation, we have $\mathfrak{p}_1 = \{(X, X, -X, -X) | X \in f\}$, $\mathfrak{p}_2 = \{(X, -X, X, -X) | X \in f\}$, and $\mathfrak{p}_3 = \{(X, -X, -X, X) | X \in f\}$.

Proposition 2 Let G/H be a generalized Wallach space such that $(\mathfrak{g}, \mathfrak{h}) = (\mathfrak{f} \oplus \mathfrak{f} \oplus \mathfrak{f}, \operatorname{diag}(\mathfrak{f}) = \{(X, X, X, X) \mid X \in f\})$ for a simple compact Lie algebra \mathfrak{f} and $\mathfrak{p}_1 = \{(X, X, -X, -X) \mid X \in f\}, \mathfrak{p}_2 = \{(X, -X, X, -X) \mid X \in f\}, \mathfrak{p}_3 = \{(X, -X, -X, X) \mid X \in f\}$. Then $A = \frac{1}{4} \operatorname{dim}(\mathfrak{f})$ and $a_1 = a_2 = a_3 = \frac{1}{4}$.

Proof Let e_i , $i = 1, ..., \dim(\mathfrak{f})$, be an orthonormal frame with respect to $-B_{\mathfrak{f}}$ (the minus Killing form of the Lie algebra \mathfrak{f}). Then $\frac{1}{2}(e_i, e_i, -e_i, -e_i), \frac{1}{2}(e_i, -e_i, e_i, -e_i)$, and $\frac{1}{2}(e_i, -e_i, -e_i), i = 1, ..., \dim(\mathfrak{f})$, forms $\langle \cdot, \cdot \rangle$ -orthonormal bases in \mathfrak{p}_1 , \mathfrak{p}_1 , and \mathfrak{p}_3 respectively. Therefore,

$$A = \sum_{i,j,k=1}^{\dim(\mathfrak{f})} \left\langle \left[\frac{1}{2} (e_i, e_i, -e_i, -e_i), \frac{1}{2} (e_j, -e_j, e_j, -e_j) \right], \frac{1}{2} (e_k, -e_k, -e_k, e_k) \right\rangle^2 \\ = \frac{1}{64} \sum_{i,j,k=1}^{\dim(\mathfrak{f})} \left\langle \left[(e_i, e_i, -e_i, -e_i), (e_j, -e_j, e_j, -e_j) \right], (e_k, -e_k, -e_k, e_k) \right\rangle^2 \\ = \frac{1}{64} \sum_{i,j,k=1}^{\dim(\mathfrak{f})} 16 \cdot (-B_{\mathfrak{f}} ([e_i, e_j], e_k))^2 = \frac{1}{4} \sum_{i,j=1}^{\dim(\mathfrak{f})} (-B_{\mathfrak{f}} ([e_i, e_j], [e_i, e_j]))$$

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$$= -\frac{1}{4} \sum_{i,j=1}^{\dim(\mathfrak{f})} (-B_{\mathfrak{f}}([e_i, [e_i, e_j]], e_j])) = -\frac{1}{4} \sum_{i=1}^{\dim(\mathfrak{f})} \operatorname{trace}(\operatorname{ad}(e_i) \cdot \operatorname{ad}(e_i)))$$
$$= -\frac{1}{4} \sum_{i=1}^{\dim(\mathfrak{f})} B_{\mathfrak{f}}(e_i, e_i) = \frac{1}{4} \dim(\mathfrak{f}).$$

Here we have used the definition of the Killing form: $B_{f}(X, Y) = \text{trace}(\text{ad}(X) \cdot \text{ad}(Y))$ and the fact that all operators ad(X) are skew-symmetric with respect to B_{f} .

Since dim(\mathfrak{p}_1) = dim(\mathfrak{p}_2) = dim(\mathfrak{p}_3) = dim(\mathfrak{f}), then $a_1 = a_2 = a_3 = 1/4$. Note also that this result follows also from more general calculations for an arbitrary Ledger – Obata space in § 4 of [19].

4 Generalized Wallach spaces and $\mathbb{Z}_2 \times \mathbb{Z}_2$ -symmetric spaces

Let Γ be a finite abelian subgroup of the automorphism group of a Lie group G. Then the homogeneous space G/H is called a Γ -symmetric space, if $(G^{\Gamma})_0 \subset H \subset G^{\Gamma}$, where the subgroup G^{Γ} consists of elements of G invariant with respect to Γ , and $(G^{\Gamma})_0$ is its unit component [16]. We get symmetric spaces for $\Gamma = \mathbb{Z}_2$ and k-symmetric spaces for \mathbb{Z}_k [27]. For the Klein four-group $\mathbb{Z}_2 \times \mathbb{Z}_2$, the above definition give us $\mathbb{Z}_2 \times \mathbb{Z}_2$ -symmetric spaces, which were studied in [3] and [13], In particular, a classification of these spaces for simple compact groups G were obtained in these two papers.

Another approach for this classification was applied in the paper [12]. On the Lie algebra level this classification is equivalent to the classification of $\mathbb{Z}_2 \times \mathbb{Z}_2$ -groups in the automorphism group Aut(g) for all simple compact Lie algebra g. It is clear that any $\mathbb{Z}_2 \times \mathbb{Z}_2$ -group are generated with two commuting involutive automorphisms of g.

By Theorem 2, every generalized Wallach spaces G/H with simple G is a $\mathbb{Z}_2 \times \mathbb{Z}_2$ symmetric space. Hence, we obtain **the following algorithm**. We should consider a complete list of $\mathbb{Z}_2 \times \mathbb{Z}_2$ -symmetric spaces. It is useful to deal with a such classification on the Lie algebra level, i. e. with the classification of simple compact Lie algebras \mathfrak{g} with $\mathbb{Z}_2 \times \mathbb{Z}_2$ groups Γ in Aut(\mathfrak{g}). A list of such objects is given e. g. in [12] (see Tables 3, 4 there). We reproduce it in our Table 2. We denote by \mathfrak{h} a Lie subalgebra of \mathfrak{g} consisted of fixed points of the corresponding group Γ . By \mathfrak{k}_1 , \mathfrak{k}_2 , and \mathfrak{k}_3 we denote symmetric subalgebras in \mathfrak{g} , that consist respectively of fixed points of involutions σ_1 , σ_2 , and $\sigma_3 = \sigma_1 \sigma_2$, such that σ_1 and σ_2 generate Γ . This information could be easily derived from Tables 2, 3, and 4 of the paper [12]. Of course, we consider these subalgebras up to permutation. Recall also that all the pairs (\mathfrak{k}_i , \mathfrak{h}), i = 1, 2, 3, are also symmetric.

Our final step is the following. For each line of Table 2, we should determine the "effective parts" ($\tilde{\mathfrak{k}}_i$, $\tilde{\mathfrak{h}}_i$) of the pairs (\mathfrak{k}_i , \mathfrak{h}), i = 1, 2, 3. This means that we need to eliminate nontrivial ideals of \mathfrak{g} from \mathfrak{h} . More precisely, let \mathfrak{a} be a maximal ideal of \mathfrak{k}_i in \mathfrak{h} , then $\tilde{\mathfrak{k}}_i$ (respectively, $\tilde{\mathfrak{h}}_i$) is a $B_{\mathfrak{g}}$ -orthogonal compliment to \mathfrak{a} in \mathfrak{k}_i (respectively, \mathfrak{h}), where $B_{\mathfrak{g}}$ is the Killing form of the Lie algebra \mathfrak{g} . Further, we should check that \mathfrak{p}_i , a $B_{\mathfrak{g}}$ -orthogonal compliment to $\tilde{\mathfrak{h}}_i$ in $\tilde{\mathfrak{k}}_i$ (or, equivalently, a $B_{\mathfrak{g}}$ -orthogonal compliment to \mathfrak{h} in \mathfrak{k}) is ad($\tilde{\mathfrak{h}}_i$)-irreducible (or, equivalently, ad(\mathfrak{h})-irreducible). We have the following obvious result

Lemma 6 Let $(\mathfrak{g}, \mathfrak{h})$ be a pair from Table 2. Then the following conditions are equivalent:

- 1) $(\mathfrak{g}, \mathfrak{h})$ corresponds to a generalized Wallach space G/H with connected H;
- 2) the modules p_i , i = 1, 2, 3, are ad(\mathfrak{h})-irreducible;
- 3) the symmetric pairs $(\tilde{\mathfrak{t}}_i, \tilde{\mathfrak{h}}_i)$, i = 1, 2, 3, are irreducible.

z	ß	þ	ŧı	Ê2	ŧ3
_	su(p+d)	$so(p) \oplus so(d)$	so(p+d)	so(p+d)	$s(u(p) \oplus u(p))$
5	su(2p)	(d)n	so(2p)	sp(p)	$s(u(p) \oplus u(p))$
3	su(2p + 2q)	$sp(p) \oplus sp(q)$	sp(p+q)	sp(p+q)	$s(u(2p) \oplus u(2q))$
4	su(p+q+r+s)	$s(u(p) \oplus u(q) \oplus u(r) \oplus u(s))$	$s(u(p+q) \oplus u(r+s))$	$s(u(p+r) \oplus u(q+s))$	$s(u(p+s) \oplus u(q+r))$
5	su(2p)	su(p)	$s(u(p) \oplus u(p))$	$s(u(p) \oplus u(p))$	$s(u(p) \oplus u(p))$
9	so(p+q+r+s)	$so(p) \oplus so(q) \oplus so(r) \oplus so(s)$	$so(p+q) \oplus so(r+s)$	$so(p+r) \oplus so(q+s)$	$so(p+s) \oplus so(q+r)$
7	so(2p)	so(p)	$so(p) \oplus so(p)$	$so(p) \oplus so(p)$	n(p)
8	so(2p + 2q)	$n(b) \oplus n(d)$	$so(2p) \oplus so(2q)$	(b+d)n	n(p+d)
6	so(4p)	sp(p)	u(2p)	u(2p)	u(2p)
10	sp(p)	so(p)	n(b)	n(b)	n(p)
11	sp(p+q)	$n(b) \oplus n(d)$	(b+d)n	(b+d)n	$sp(p) \oplus sp(q)$
12	sp(2p)	sp(p)	u(2p)	$sp(p) \oplus sp(p)$	$sp(p) \oplus sp(p)$
13	sp(p+q+r+s)	$sp(p) \oplus sp(q) \oplus sp(r) \oplus sp(s)$	$sp(p+q) \oplus sp(r+s)$	$sp(p+r) \oplus sp(q+s)$	$sp(p+s) \oplus sp(q+r)$
14	<i>e</i> 6	$2su(3) \oplus \mathbb{R}^2$	$su(6) \oplus sp(1)$	$su(6) \oplus sp(1)$	$su(6) \oplus sp(1)$
15	e6	$su(4) \oplus 2sp(1) \oplus \mathbb{R}$	$su(6) \oplus sp(1)$	$su(6) \oplus sp(1)$	$so(10)\oplus \mathbb{R}$
16	e6	$su(5) \oplus \mathbb{R}^2$	$su(6) \oplus sp(1)$	$so(10) \oplus \mathbb{R}$	$so(10)\oplus \mathbb{R}$
17	<i>e</i> 6	$so(8) \oplus \mathbb{R}^2$	$so(10)\oplus \mathbb{R}$	$so(10) \oplus \mathbb{R}$	$so(10) \oplus \mathbb{R}$
18	e6	$sp(3) \oplus sp(1)$	$su(6) \oplus sp(1)$	f_4	sp(4)
19	e6	$so(6)\oplus \mathbb{R}$	$su(6) \oplus sp(1)$	sp(4)	sp(4)
20	e6	so(9)	$so(10)\oplus \mathbb{R}$	f_4	f_4

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Table 2 continue	pe				
N	ß	(J	ŧı	ŧ2	ŧ3
21	66	$so(5) \oplus so(5)$	$so(10)\oplus \mathbb{R}$	sp(4)	sp(4)
22	εJ	$su(6) \oplus \mathbb{R}^2$	$so(12) \oplus sp(1)$	$so(12) \oplus sp(1)$	$so(12) \oplus sp(1)$
23	$e_{\mathcal{T}}$	$so(8) \oplus 3sp(1)$	$so(12) \oplus sp(1)$	$so(12) \oplus sp(1)$	$so(12) \oplus sp(1)$
24	eŢ	$so(10) \oplus \mathbb{R}^2$	$so(12) \oplus sp(1)$	$e_6 \oplus \mathbb{R}$	$e_6 \oplus \mathbb{R}$
25	$e_{\mathcal{T}}$	$su(6)\oplus sp(1)\oplus \mathbb{R}$	$so(12) \oplus sp(1)$	$e_6 \oplus \mathbb{R}$	su(8)
26	εı	$su(4) \oplus su(4) \oplus \mathbb{R}$	$so(12) \oplus sp(1)$	su(8)	su(8)
27	$e_{\mathcal{T}}$	f_4	$e_6 \oplus \mathbb{R}$	$e_6 \oplus \mathbb{R}$	$e_6 \oplus \mathbb{R}$
28	e_7	sp(4)	$e_6 \oplus \mathbb{R}$	su(8)	su(8)
29	Lə	so(8)	su(8)	su(8)	su(8)
30	<i>e</i> 8	$e_6 \oplus \mathbb{R}^2$	$e_7 \oplus sp(1)$	$e_{\mathcal{T}} \oplus sp(1)$	$e_{7} \oplus sp(1)$
31	68	$so(12) \oplus 2sp(1)$	$e_7 \oplus sp(1)$	$e_{\mathcal{T}} \oplus sp(1)$	so(16)
32	68	$su(8) \oplus \mathbb{R}$	$e_7 \oplus sp(1)$	so(16)	so(16)
33	<i>e</i> 8	$so(8) \oplus so(8)$	so(16)	so(16)	so(16)
34	f_4	$su(3) \oplus \mathbb{R}^2$	$sp(3) \oplus sp(1)$	$sp(3) \oplus sp(1)$	$sp(3) \oplus sp(1)$
35	f_4	$so(5) \oplus 2sp(1)$	$sp(3) \oplus sp(1)$	$sp(3) \oplus sp(1)$	so(9)
36	f_4	so(8)	so(9)	s 0(9)	so(9)
37	82	限2	$sp(1) \oplus sp(1)$	$sp(1) \oplus sp(1)$	$sp(1) \oplus sp(1)$

7	n	14
2	U	4

g	so(n)	sp(n)	su(n)	<i>8</i> 2	f_4	e ₆	<i>e</i> 7	<i>e</i> ₈
$\dim(\mathfrak{g})$ $B_{\mathfrak{g}}(\beta_m,\beta_m)$	$\frac{n(n-1)/2}{4(n-2)}$	$2n^2 + n$ $4(n+1)$	$n^2 - 1$ $4n$	14 16	52 36	78 48	133 72	248 120

Table 3 The values of dim(\mathfrak{g}) and $B_{\mathfrak{g}}(\beta_m, \beta_m)$ for compact simple Lie algebras \mathfrak{g}

Removing from Table 2 all pairs that do not satisfy the conditions of Lemma 6 we get the Table 1, that contains all possible $(\mathfrak{g}, \mathfrak{h})$ corresponding to generalized Wallach space with simple groups *G*.

Theorem 4 For any generalized Wallach space G/H with simple G and connected H, the pair $(\mathfrak{g}, \mathfrak{h})$ is in Table 2. A pair $(\mathfrak{g}, \mathfrak{h})$ from Table 2 generates a generalized Wallach space if and only if it is in Table 1.

Proof The first assertion we get immediately from Theorem 2. Let us prove the second assertion. We have to check all pairs from Table 2, using Lemma 6. For a list of irreducible symmetric pairs see e. g. [10] or [26].

Let us consider **line 1**. It is easy to see that the pairs $(\tilde{\mathfrak{k}}_1, \tilde{\mathfrak{h}}_1)$ and $(\tilde{\mathfrak{k}}_2, \tilde{\mathfrak{h}}_2)$ are irreducible symmetric, but the pair $(\tilde{\mathfrak{k}}_3, \tilde{\mathfrak{h}}_3) = (s(u(p) \oplus u(p)), so(r) \oplus so(q))$ is not. Hence the pair $(\mathfrak{g}, \mathfrak{h})$ does not generate a generalized Wallach space in this case.

Now, consider **line 2**. The pairs $(\tilde{\mathfrak{k}}_1, \tilde{\mathfrak{h}}_1)$, $(\tilde{\mathfrak{k}}_2, \tilde{\mathfrak{h}}_2)$, and $(\tilde{\mathfrak{k}}_3, \tilde{\mathfrak{h}}_3) = (su(p) \oplus su(p))$, diag (su(p)) are irreducible symmetric and we get line 4 in Table 1.

For line 3, the pairs $(\tilde{\mathfrak{t}}_1, \tilde{\mathfrak{h}}_1)$ and $(\tilde{\mathfrak{t}}_2, \tilde{\mathfrak{h}}_2)$ are irreducible symmetric, but the pair $(\tilde{\mathfrak{t}}_3, \tilde{\mathfrak{h}}_3) = (s(u(2p) \oplus u(2q)), sp(p) \oplus sp(q))$ is not.

For line 5, all the pairs $(\hat{\mathfrak{k}}_i, \hat{\mathfrak{h}}_i)$, i = 1, 2, 3, are not irreducible. The same is true for the lines 9 and 10.

Let us check line 6 in Table 2. In this case we have

$$\begin{aligned} (\mathfrak{g},\mathfrak{h}) &= (so(p+q+r+s), so(p) \oplus so(q) \oplus so(r) \oplus so(s)), \\ \mathfrak{k}_1 &= so(p+q) \oplus so(r+s), \quad \mathfrak{k}_2 &= so(p+r) \oplus so(q+s), \quad \mathfrak{k}_3 &= so(p+s) \oplus so(q+r). \end{aligned}$$

It is easy to see that the symmetric pair $(\mathfrak{k}_i, \mathfrak{h})$ is decomposed into the sum of two symmetric pairs provided that $p \cdot q \cdot r \cdot s \neq 0$. In order to get $ad(\mathfrak{h})$ -irreducible modules \mathfrak{p}_i , we should put s = 0 (without loss of generality). Then we get $(\mathfrak{k}_1, \mathfrak{h}_1) = (so(p+q), so(p) \oplus so(q))$, $(\mathfrak{k}_2, \mathfrak{h}_2) = (so(p+r), so(p) \oplus so(r))$, and $(\mathfrak{k}_3, \mathfrak{h}_3) = (so(r+q), so(r) \oplus so(q))$. We see that the modules \mathfrak{p}_i , i = 1, 2, 3, are $ad(\mathfrak{h})$ -irreducible for all $p, q, r \geq 1$ and s = 0. Hence we get line 1 of Table 1. Note that for p = q = r = 1 we get the Lie algebra $so(3) \simeq su(2) \simeq sp(1)$ that generate the group SU(2), a 3-dimensional generalized Wallach space.

Applying the same argument to **lines 4** and **13** in Table 2 we get lines 2 and 3 in Table 1. For **line 7**, the pair $(\tilde{\mathfrak{k}}_3, \tilde{\mathfrak{h}}_3) = (u(p), so(p))$ is not irreducible.

For **line 8**, the pairs $(\mathfrak{k}_2, \mathfrak{h}_2)$ and $(\mathfrak{k}_3, \mathfrak{h}_3)$ (that coincide with $(su(p+q), s(u(p) \oplus u(q)))$) are irreducible symmetric, the pair $(\mathfrak{k}_1, \mathfrak{h}) = (so(2p) \oplus so(2q), u(p) \oplus u(q))$ is irreducible only if q = 1 or p = 1. Hence, we get the line 5 in Table 1.

For line 11, the pair $(\mathfrak{k}_3, \mathfrak{h}_3) = (sp(p) \oplus sp(q), u(p) \oplus u(q))$ is not irreducible.

For **line 12**, the pair $(\mathfrak{k}_1, \mathfrak{h}_1) = (u(2p), sp(p))$ is not irreducible.

By the same manner we check **lines 13–37**, corresponding to exceptional Lie algebras g. We do not write all details here, because this is a direct and easy procedure. Recall the following isomorphisms between Lie algebras, which simplify the mentioned check: $sp(1) \simeq su(2) \simeq so(3)$, $sp(2) \simeq so(5)$, and $su(4) \simeq so(6)$.

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Note that the pairs in **lines 15, 17, 18, 23, 25, 29, 31, 33, 35**, and **36** generate generalized Wallach spaces (see lines 6–15 of Table 1). All other pairs $(\mathfrak{g}, \mathfrak{h})$ with exceptional \mathfrak{g} from Table 2 are such that at least one of the pairs $(\tilde{\mathfrak{t}}_i, \tilde{\mathfrak{h}}_i), i = 1, 2, 3$, is not irreducible symmetric. As a final result, we completes Table 1.

5 Calculation of a_1, a_2, a_3

Let G/H be a compact homogeneous space with semisimple G, then the Killing form B of the Lie algebra \mathfrak{g} is negatively defined, and \mathfrak{p} , the *B*-orthogonal complement to \mathfrak{h} in \mathfrak{g} , could be naturally identified with the tangent space of G/H at the point eH. Note that for any Riemannian invariant metric ρ on G/H, the isotropy representation $\tau : H \mapsto \text{End}(\mathfrak{p})$ of the isotropy group H is such that every $\tau(a) = \text{Ad}(a)|_{\mathfrak{p}}$ is orthogonal transformation. Moreover, the isotropy representation $d\tau : \mathfrak{h} \mapsto \text{End}(\mathfrak{p})$ of the isotropy algebra \mathfrak{h} is such that every $d\tau(f) = \text{ad}(f)|_{\mathfrak{p}}$ is a skew-symmetric.

For the inner product $\langle \cdot, \cdot \rangle|_{\mathfrak{h}} = -B|_{\mathfrak{h}}$ on \mathfrak{h} we can consider the Casimir operator *C* of the (restruction of the) adjoint representation of \mathfrak{h} on \mathfrak{p} . Let $\{e_0^j\}$ be an orthonormal basis in \mathfrak{h} with respect to $\langle \cdot, \cdot \rangle$, $1 \le j \le \dim(\mathfrak{h})$, then (see e. g. [4, 7.88])

$$C = -\sum_{1 \le j \le \dim(\mathfrak{h})} \operatorname{ad} \left(e_0^j \right) \Big|_{\mathfrak{p}} \circ \operatorname{ad} \left(e_0^j \right) \Big|_{\mathfrak{p}}.$$

For any $ad(\mathfrak{h})$ -irreducible submodule $\mathfrak{q} \subset \mathfrak{p}$, the operator *C* is proportional to the identity operator. If \mathfrak{p} is the sum of $ad(\mathfrak{h})$ -irreducible submodules \mathfrak{p}_i , then we have $C|_{\mathfrak{p}_i} = c_i \operatorname{Id}|_{\mathfrak{p}_i}$ for some constant c_i , that are called the Casimir constants. Since $ad(e_0^j)|_{\mathfrak{p}}$ is skew-symmetric, then

$$c_i = \sum_{1 \le j \le \dim(\mathfrak{h})} \left\langle [e_0^j, e], [e_0^j, e] \right\rangle \tag{8}$$

for an arbitrary unit (with respect to $\langle \cdot, \cdot \rangle = -B$) vector e in \mathfrak{p}_i . In particular, $c_i \ge 0$.

Now, we continue to study generalized Wallach spaces. Recall one important property of the numbers [ijk], see (4). According to lemma 1.5 in [25], we get the formula

$$\sum_{j,k} [ijk] = d_i(1 - 2c_i).$$

for all i = 1, 2, 3, where c_i is the corresponding Casimir constant, $d_i = \dim(p_i)$. Using the above consideration we can rewrite this equality as follows (see (5)):

$$2A = [ijk] + [ikj] = d_i(1 - 2c_i), \quad i \neq j \neq k \neq i.$$
(9)

Hence we get the following result (obtained in [18] and [15]).

Lemma 7 For a generalized Wallach space, we have $d_i \ge 2A$ for all i = 1, 2, 3. Moreover, the equality $d_i = 2A$ is equivalent to the condition $[\mathfrak{h}, \mathfrak{p}_i] = 0$.

Now, we give a convenient method for calculating c_i and A for generalized Wallach spaces G/H with simple G. Consider a connected Lie subgroup K_i in G with Lie algebra $\mathfrak{k}_i = \mathfrak{h} \oplus \mathfrak{p}_i$ as in (7). It is clear that the homogeneous spaces K_i/H and G/K_i are locally symmetric (see Sect. 3 and [4, 7.70]). If K_i does not act almost effectively on $M = K_i/H$, consider its subgroup \widetilde{K}_i acting on $M = K_i/H = \widetilde{K}_i/\widetilde{H}_i$ almost effectively (here we denote by \widetilde{H}_i the corresponding isotropy group). The pair of the corresponding Lie algebras $(\tilde{\mathfrak{k}}_i, \tilde{\mathfrak{h}}_i)$

is irreducible symmetric (see [4, 7.100]). A more direct and convenient way to produce the pair $(\tilde{\mathfrak{t}}_i, \tilde{\mathfrak{h}}_i)$ is the following: If \mathfrak{a} is a maximal ideal of \mathfrak{t}_i in \mathfrak{h} , then $\tilde{\mathfrak{t}}_i$ (respectively, $\tilde{\mathfrak{h}}_i$) is a $\langle \cdot, \cdot \rangle$ -orthogonal compliment to \mathfrak{a} in \mathfrak{t}_i (respectively, \mathfrak{h}).

If $\tilde{\mathfrak{k}}_i$ is a simple Lie algebra then its Killing form $B_{\tilde{\mathfrak{k}}_i}$ is proportional to the restriction of the Killing form *B* of \mathfrak{g} to $\tilde{\mathfrak{k}}_i$. Therefore, there exists a positive number γ_i with the property

$$B_{\tilde{\mathbf{t}}_i} = \gamma_i \cdot B \big|_{\tilde{\mathbf{t}}_i}.$$
 (10)

Lemma 8 In the notations as above, we have $c_i = \gamma_i/2$ and $A = d_i(1 - \gamma_i)/2$.

Proof Clearly, $\tilde{\mathfrak{k}}_i = \tilde{\mathfrak{h}}_i \oplus \mathfrak{p}_i$. Since for a locally symmetric space, the Casimir constant is equal to 1/2 (see [4, 7.93]), we may calculate c_i as follows. Consider any $\langle \cdot, \cdot \rangle$ -orthonormal basis $\{e_j^0\}$ in \mathfrak{h} , such that $e_j^0 \in \tilde{\mathfrak{h}}_i$ for $0 \le j \le \dim(\tilde{\mathfrak{h}})$ and $\langle e_j^0, \tilde{\mathfrak{h}}_i \rangle = 0$ for $j > \dim(\tilde{\mathfrak{h}})$. Obviously, $[e_j^0, e] = 0$ for all $e \in \mathfrak{p}_i$ and $j > \dim(\tilde{\mathfrak{h}})$. Therefore,

$$c_i = \sum_{0 \le j \le \dim(\mathfrak{h})} \left\langle [e_j^0, e], [e_j^0, e] \right\rangle = \sum_{0 \le j \le \dim(\tilde{\mathfrak{h}})} \left\langle [e_j^0, e], [e_j^0, e] \right\rangle$$

for every unit vector $e \in \mathfrak{p}_i$. Consider the vectors $f_j^0 = \frac{1}{\sqrt{\gamma_i}}e_j^0$, $1 \le i \le \dim(\tilde{\mathfrak{h}})$. They form an orthonormal basis in $\tilde{\mathfrak{h}}_i$ with respect to $-B_{\tilde{\mathfrak{k}}}$. Suppose that $\tilde{e} = \frac{1}{\sqrt{\gamma_i}}e$, where *e* is a vector of unit length with respect to $-B(\cdot, \cdot) = \langle \cdot, \cdot \rangle$. Then, the Casimir constant (= 1/2) of the adjoint representation of $\tilde{\mathfrak{h}}_i$ on \mathfrak{p}_i satisfies the following equality:

$$\begin{split} \frac{1}{2} &= \sum_{\substack{0 \le j \le \dim(\tilde{\mathfrak{h}})}} -B_{\mathfrak{k}_i}([f_j^0, \tilde{e}], [f_j^0, \tilde{e}]) \\ &= \sum_{\substack{0 \le j \le \dim(\tilde{\mathfrak{h}})}} \gamma_i \left\langle [f_j^0, \tilde{e}], [f_j^0, \tilde{e}] \right\rangle = \frac{1}{\gamma_i} \sum_{\substack{0 \le j \le \dim(\tilde{\mathfrak{h}})}} \left\langle [e_j^0, e], [e_j^0, e] \right\rangle = \frac{c_i}{\gamma_i}. \end{split}$$

Therefore, $\gamma_i = 2c_i$. Furthermore, since $2A = d_i(1 - 2c_i)$, we have $A = d_i(1 - \gamma_i)/2$. The lemma is proved.

Remark 3 Since $a_i = A/d_i$, i = 1, 2, 3, then $a_1 = a_2 = a_3$ if and only if $c_1 = c_2 = c_3$. Note that the last equality holds if and only if the Killing (the standard) metric on the space G/H is Einstein [4, 7.92]. Therefore, the equality $a_1 = a_2 = a_3$ means the same property.

The following formulas for the Killing forms of classical Lie algebra are well known:

$$B_{so(n)}(X, Y) = -(n-2) \operatorname{trace}(XY), \quad B_{sp(n)}(X, Y) = -2(n+1) \operatorname{trace}(XY),$$

 $B_{su(n)}(X, Y) = -2n \operatorname{trace}(XY).$

Hence, if we consider the inclusion $so(k+l) \subset so(k+l+m)$ with $X \mapsto diag(X, 0) =: X'$, then

$$B_{so(k+l)}(X, Y) = -(k+l-2)\operatorname{trace}(XY),$$

$$B_{so(k+l+m)}(X', Y') = -(k+l+m-2)\operatorname{trace}(X'Y') = -(k+l+m-2)\operatorname{trace}(XY),$$

and, consequently, $B_{so(k+l)} = \frac{k+l-2}{k+l+m-2} \cdot B_{so(k+l+m)}$. Using the same argument for other two type of classical Lie algebras and Lemma 8, we easily get the values of *A*, *a*₁, *a*₂, and *a*₃ for the spaces (see Table 1):

$$SO(k+l+m)/SO(k) \cdot SO(l) \cdot SO(m), \quad Sp(k+l+m)/Sp(k) \cdot Sp(l) \cdot Sp(m),$$

$$SU(k+l+m)/S(U(k) \cdot U(l) \cdot U(m)).$$

Let us consider the pair $(\mathfrak{g}, \mathfrak{h}) = (su(2l), u(l))$. In this case we have $\mathfrak{k}_1 = so(2l)$, $\mathfrak{k}_2 = sp(l)$, and $\mathfrak{k}_3 = s(u(l) \oplus u(l))$. From the standard inclusion $so(2l) \subset su(2l)$ we get $B_{so(2l)}(X, Y) = -(2l-2)$ trace(XY) and $B_{su(2l)}(X, Y) = -4l$ trace(XY), therefore, $\gamma_1 = \frac{l-1}{2l}$. By Lemma 8 we get $a_1 = \frac{l+1}{4l}$. Since $d_1 = l(l-1)$, $d_2 = l(l+1)$, and $d_3 = l^2 - 1$, then we get $A = (l^2 - 1)/4$, $a_2 = \frac{l-1}{4l}$, and $a_3 = 1/4$ (recall that $a_i d_i = A$). Note that $(\tilde{\mathfrak{k}}_3, \tilde{\mathfrak{h}}_3) = (su(l) \oplus su(l), \text{diag}(su(l)))$ in this case. In particular, $\tilde{\mathfrak{k}}_3 = su(l) \oplus su(l)$ is not a simple Lie algebra.

For all other cases in Table 1 we will apply Lemma 8 and the following method. Consider an inclusion $\mathfrak{k} \subset \mathfrak{g}$ of simple compact Lie algebras and try to determine a constant γ such that $B_{\mathfrak{k}} = \gamma \cdot B_{\mathfrak{g}}$, where $B_{\mathfrak{k}}$ and $B_{\mathfrak{g}}$ are the Killing forms of the Lie algebras \mathfrak{k} and \mathfrak{g} . Suppose that β_m (respectively, β'_m) is one of the roots of maximal length in the Lie algebra \mathfrak{g} (respectively, \mathfrak{k}). Then the formula

$$\gamma = \frac{B_{\mathfrak{k}}(\beta'_m, \beta'_m)}{j \cdot B_{\mathfrak{g}}(\beta_m, \beta_m)} \tag{11}$$

holds, where *j* means the Dynkin index of the Lie subalgebra \mathfrak{t} in \mathfrak{g} , see e. g. [8, pp. 38–40] for details. Note that the Dynkin index is a natural number and it was computed for all simple subalgebras of exceptional Lie algebras in [9] (see also [17]). The value $B_{\mathfrak{g}}(\beta_m, \beta_m)$ for simple Lie algebra are shown in Table 3 (this is a reproduction of Table 3 in [8]).

Let us use this algorithm for the pair $(\mathfrak{g}, \mathfrak{h}) = (so(2l), u(1) \oplus u(l-1))$. In this case $\mathfrak{k}_1 = su(l) \oplus \mathbb{R}, \mathfrak{k}_2 = su(l) \oplus \mathbb{R}$, and $\mathfrak{k}_3 = so(2l-2) \oplus \mathbb{R}$. Note that $(\tilde{\mathfrak{k}}_1, \tilde{\mathfrak{h}}_1) = (\tilde{\mathfrak{k}}_2, \tilde{\mathfrak{h}}_2) = (su(l), s(u(1) \oplus u(l-1)), (\tilde{\mathfrak{k}}_3, \tilde{\mathfrak{h}}_3) = (so(2l-2), u(l-1))$. Note also that the Dynkin index *j* for subalgebras su(l) and so(2l-2) in so(2l) is 1. Using Table 3, we get $\gamma_1 = \gamma_2 = \frac{l}{2(l-1)}$ and $\gamma_3 = \frac{l-2}{l-1}$. Therefore, by Lemma 8 we have $a_1 = a_2 = \frac{l-2}{4(l-1)}$ and $a_3 = \frac{1}{2(l-1)}$. Since $d_1 = d_2 = 2(l-1), d_3 = (l-1)(l-2)$, we also get A = (l-2)/2.

We list all (which will be needed) symmetric pairs $(\mathfrak{g}, \mathfrak{h})$ with exceptional \mathfrak{g} , with pointing of the Dynkin index *j* of some simple summands (*j* for \mathfrak{k} is shown as \mathfrak{k}^j) in subalgebras (see [9]):

$$\begin{array}{l} \left(e_{6}, su(6)^{1} \oplus su(2)\right), \quad \left(e_{6}, so(10)^{1} \oplus \mathbb{R}\right), \quad \left(e_{6}, sp(3)^{1} \oplus sp(1)\right), \quad \left(e_{6}, f_{4}^{1}\right), \\ \left(e_{6}, sp(4)^{1}\right), \quad \left(e_{7}, so(12)^{1} \oplus sp(1)\right), \quad \left(e_{7}, e_{6}^{1} \oplus \mathbb{R}\right), \quad \left(e_{7}, su(8)^{1}\right), \\ \left(e_{8}, e_{7}^{1} \oplus sp(1)\right), \quad \left(e_{8}, so(16)^{1}\right), \quad \left(f_{4}, sp(3)^{1} \oplus sp(1)\right), \quad \left(f_{4}, so(9)^{1}\right), \end{array}$$

This information, together with Table 2 and Table 3, the equality (11) and Lemma 8 allow us to calculate the values of A, a_1 , a_2 , and a_3 for all pairs in Table 1 with exceptional g.

Therefore, we get the numbers a_1 , a_2 , and a_3 for all pairs in Table 1.

6 The set of points (a_1, a_2, a_3) in $[0, 1/2]^3$ and Einstein metrics

Recall that the singular points of the normalized Ricci flow on a given homogeneous space are exactly invariant Einstein metrics. The authors of [1,2] studied local properties of the normalized Ricci flow for generalized Wallach spaces. It is remarkable that the normalized Ricci flow for these spaces could be represented as a planar dynamical system depended in addition on the constants a_1 , a_2 , and a_3 . Even not every triple $(a_1, a_2, a_3) \in [0, 1/2]^3$ corresponds to some generalized Wallach space, it is useful to study this dynamical system with all such triples. Let us consider one special algebraic surface $\Omega \subset \mathbb{R}^3$, defined by the equation $Q(a_1, a_2, a_3) = 0$, where

$$Q(a_1, a_2, a_3) = (2s_1 + 4s_3 - 1) \left(64s_1^5 - 64s_1^4 + 8s_1^3 + 12s_1^2 - 6s_1 + 1 + 240s_3s_1^2 - 240s_3s_1 - 1536s_3^2s_1 - 4096s_3^3 + 60s_3 + 768s_3^2 \right) - 8s_1(2s_1 + 4s_3 - 1)(2s_1 - 32s_3 - 1)(10s_1 + 32s_3 - 5)s_2 - 16s_1^2 (13 - 52s_1 + 640s_3s_1 + 1024s_3^2 - 320s_3 + 52s_1^2) s_2^2 + 64(2s_1 - 1)(2s_1 - 32s_3 - 1)s_2^3 + 2048s_1(2s_1 - 1)s_2^4,$$
(12)

and

$$s_1 = a_1 + a_2 + a_3$$
, $s_2 = a_1a_2 + a_1a_3 + a_2a_3$, $s_3 = a_1a_2a_3$.

Obviously, $Q(a_1, a_2, a_3)$ is a symmetric polynomial in a_1, a_2, a_3 of degree 12. The surface Ω was very important for the statement of Theorem 7 in [1], which provides a general result about the type of the non-degenerate singular points of the normalized Ricci flow for a generalized Wallach space with given a_1, a_2 , and a_3 .

In the rest of this section we deal only with points of the surface Ω in the cube $[0, 1/2]^3$. It should be noted that the position of a given point $(a_1, a_2, a_3) \in (0, 1/2]^3$ with respect to the surface Ω determines the number and some properties of Einstein invariant metrics on the corresponding generalized Wallach spaces. As it was pointed in Introduction, there are many papers devoted to the classification of Einstein metrics on generalized Wallach spaces. Here, we give some general exposition of Einstein metrics on generalized Wallach spaces in terms of the surface Ω .

We recall some important properties of Ω , see [1] for details. The points (0, 0, 1/2), (0, 1/2, 0), and (1/2, 0, 0) are all vertices of the cube $[0, 1/2]^3$, that are points of Ω . For $a_1 = 1/2$ and $a_2, a_3 \in (0, 1/2]$ points of Ω form a curve homeomorphic to the interval [0, 1] with endpoints $(1/2, 1/2, \sqrt{2}/4 \approx 0.3535533905)$ and $(1/2, \sqrt{2}/4 \approx 0.3535533905, 1/2)$ and with the singular point (a cusp) at the point $a_3 = a_2 = (\sqrt{5} - 1)/4 \approx 0.3090169942$. The same is also valid under the permutation $a_1 \rightarrow a_2 \rightarrow a_3 \rightarrow a_1$.

The plane $s_1 = a_1 + a_2 + a_3 = 1/2$ intersects the set $\Omega \cap [0, 1/2]^3$ exactly for points in the boundary of the triangle with the vertices (0, 0, 1/2), (0, 1/2, 0), and (1/2, 0, 0). For all other points in $\Omega \cap (0, 1/2]^3$ we have the inequality $s_1 = a_1 + a_2 + a_3 > 1/2$.

It is not difficult to show that (1/4, 1/4, 1/4) is the only point in $\Omega \cap [0, 1/2]^3$ satisfying the additional condition $s_1 = a_1 + a_2 + a_3 = 3/4$. It turns out that the point (1/4, 1/4, 1/4)is a singular point of degree 3 of the algebraic surface Ω (see Fig. 1). This point is an elliptic umbilic (in the sense of Darboux) on the surface Ω .

Now, we discuss a part of the surface Ω in the cube $(0, 1/2)^3$. Recall that Ω is invariant under the permutation $a_1 \rightarrow a_2 \rightarrow a_3 \rightarrow a_1$. It should be noted that the set $(0, 1/2)^3 \cap \Omega$ is connected. There are three curves ("edges") of *singular points* on Ω (i. e. points where $\nabla Q =$ 0): one of them has parametric representation $a_1 = -\frac{1}{2} \frac{16t^3 - 4t + 1}{8t^2 - 1}$, $a_2 = a_3 = t$, and the others are defined by permutations of a_i . These curves have a common point (1/4, 1/4, 1/4) (see Fig. 1). The part of Ω in $(0, 1/2)^3$ consists of three (pairwise isometric) "bubbles" spanned on every pair of "edges".

Another important observation is the following: the set $(0, 1/2)^3 \setminus \Omega$ has exactly three connected components. According to [1], we denote by O_1 , O_2 , and O_3 the components containing the points (1/6, 1/6, 1/6), (7/15, 7/15, 7/15), and (1/6, 1/4, 1/3) respectively. Note that $Q(a_1, a_2, a_3) < 0$ for $(a_1, a_2, a_3) \in O_1 \cup O_2$ and $Q(a_1, a_2, a_3) > 0$ for $(a_1, a_2, a_3) \in O_3$.



Fig. 1 The surface $\Omega \cap [0, 1/2]^3$

It is shown in [1] that the normalized Ricci flow for a generalized Wallach space with $(a_1, a_2, a_3) \in (0, 1/2)^3 \setminus \Omega$ has no degenerate singular point, as a planar dynamical system. By Theorem 7 in [1], for $(a_1, a_2, a_3) \in O_j$ the following possibilities for singular points (i. e. Einstein metrics) of this system can occur:

- (1) If j = 1 then there is four singular point, one of them is an unstable node and three other are saddles;
- (2) If j = 2 then there is four singular point, one of them is a stable node and three other are saddles;
- (3) If j = 3 then there are two singular points, that are saddles.

Now we describe the location of points $(a_1, a_2, a_3) \in \mathbb{R}^3$ determined by generalized Wallach spaces from Theorem 1. Recall that every such space determines not only one point (a_1, a_2, a_3) but also the points obtained by permuting the values a_1, a_2 , and a_3 .

For the spaces $SU(k + l + m)/S(U(k) \times U(l) \times U(m))$, $k \ge l \ge m \ge 1$, we have

$$a_1 = \frac{k}{2(k+l+m)}, \quad a_2 = \frac{l}{2(k+l+m)}, \quad a_3 = \frac{m}{2(k+l+m)},$$

and $a_1 + a_2 + a_3 = 1/2$. It is clear that all such points (a_1, a_2, a_3) are in the component O_1 . Moreover, the closure of the set of all such points coincides with the triangle in \mathbb{R}^3 with the vertices (0, 0, 1/2), (0, 1/2, 0), and (1/2, 0, 0). Indeed, the last assertion easily follows from considering of the barycentric coordinates in this triangle.

For the spaces $Sp(k + l + m)/Sp(k) \times Sp(l) \times Sp(m)$, $k \ge l \ge m \ge 1$, we get

$$a_1 = \frac{k}{2(k+l+m+1)}, \quad a_2 = \frac{l}{2(k+l+m+1)}, \quad a_3 = \frac{m}{2(k+l+m+1)},$$

and $a_1 + a_2 + a_3 < 1/2$. Hence, all such point are also in the component O_1 .

The case $SO(k + l + m)/SO(k) \times SO(l) \times SO(m)$, $k \ge l \ge m \ge 1$, is more interesting. We have

$$a_1 = \frac{k}{2(k+l+m-2)}, \quad a_2 = \frac{l}{2(k+l+m-2)}, \quad a_3 = \frac{m}{2(k+l+m-2)}.$$

For l = m = 1 we get $a_1 = 1/2$ and $a_2 = a_3 = \frac{1}{2k}$. Hence, $(a_1, a_2, a_3) \notin (0, 1/2)^3$. Then we may assume that $l \ge 2$ without loss of generality. Therefore, $k \ge l \ge 2$ and $k + l + m \ge 5$.

Note that $a_1 + a_2 + a_3 = \frac{k+l+m}{2(k+l+m-2)} = g(k+l+m)$, where $g(x) = \frac{x}{2(x-2)}$. Since the function $x \mapsto \frac{x}{2(x-2)}$ decreases for x > 2, then we get that the inequality $a_1 + a_2 + a_3 \le 3/4 = g(6)$ holds for all k, l, m with $k + m + l \ge 6$.

For $k + m + l \le 5$ we should check only the space $SO(5)/SO(2) \times SO(2) \times SO(1)$ with $a_1 = a_2 = 1/3$ and $a_3 = 1/6$. It is easy to see that the point (1/3, 1/3, 1/6) is in O_3 , because for all points in O_2 we have the inequality $a_i \ge 1/4$, i = 1, 2, 3.

If k + m + l = 6, then $a_1 + a_2 + a_3 = 3/4$. Recall that the plane $a_1 + a_2 + a_3 = 3/4$ intersects the surface $\Omega \cap (0, 1/2)^3$ exactly in the point (1/4, 1/4, 1/4) corresponding to the space $SO(6)/SO(2)^3$. All other points of this plane in the cube $(0, 1/2)^3$ are situated in the component O_3 . This is the case for $(a_1, a_2, a_3) = (3/8, 1/4, 1/8)$ corresponding to the space $SO(6)/SO(3) \times SO(2) \times SO(1)$.

For $k + m + l \ge 7$ we get $a_1 + a_2 + a_3 \le 7/10 = g(7) < 3/4$, and such points are either in $O_1 \cup O_3$ or in Ω . It is easy to see that there are infinitely many points of this type in O_1 . In order to find all triples in O_1 one should solve an inequality F(k, l, m) < 0 for natural k, l, m, where F is a polynomial of degree 12. We will not deal with this special problem here.

In any case, for the spaces $SO(k + l + m)/SO(k) \times SO(l) \times SO(m)$, there is no point (a_1, a_2, a_3) in the component O_2 .

Now, we determine the corresponding component O_i for all other generalized Wallach spaces. For this goal we may use all the ideas as above and one more simple observation: For $a_1 = a_2 = a_3 =: a$, the point (a_1, a_2, a_3) is in O_1 (respectively, O_2), if a < 1/4 (respectively, a > 1/4).

Simple calculations show that the spaces from lines 4, 7, 9, and 15 of Table 1 are such that $(a_1, a_2, a_3) \in O_1$.

Further, the spaces from **lines 5, 6, 8, 10, 12**, and **14** of Table 1 are such that $(a_1, a_2, a_3) \in O_3$. Due to the first of these examples (where we have 1 -parameter family of spaces), we conclude that there are infinitely many points (a_1, a_2, a_3) corresponding to generalized Wallach spaces in O_3 .

The spaces from the lines **11** and **13** of Table 1 satisfy the condition $(a_1, a_2, a_3) \in O_2$. It is interesting that there are only two generalized Wallach spaces with this property. These spaces give an affirmative answer to the question of Christoph Böhm on the existence of specific examples of generalized Wallach spaces with the property $(a_1, a_2, a_3) \in O_2$.

Note also that for a symmetric space G/H that is a product of three irreducible symmetric space, we have A = 0 and $(a_1, a_2, a_3) = (0, 0, 0)$. Finally, for all spaces $(F \times F \times F \times F)/\text{diag}(F)$, the equality $a_1 = a_2 = a_3 = 1/4$ holds, as well as for the space $SO(6)/SO(2)^3$. Recall that the point (1/4, 1/4, 1/4) is an an elliptic umbilic on the surface Ω .

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